



1 From climatology to hazard: environmental regimes and 2 tornado wind-speed exceedance in peninsular Spain and the 3 Balearic Islands

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14 **Abstract.** Tornadoes and waterspouts are infrequent but locally damaging hazards in the Iberian–Mediterranean
15 region, where uneven reporting and intensity uncertainty hamper their assessment. We compiled an updated
16 1992–2025 catalogue for peninsular Spain and the Balearic Islands by merging the national meteorological
17 agency's tornado records with a pan-European severe-weather database, harmonising event times to UTC and
18 removing duplicates, which yielded 1185 events: 567 tornadoes and 618 waterspouts. The record is temporally
19 heterogeneous, with a late-summer to autumn maximum and a marked diurnal split between morning
20 waterspouts and late-afternoon tornadoes; its rising counts appear to track reporting practices rather than any
21 climatic trend. Using 54 pre-event atmospheric-reanalysis (ERA5) parameters, we tested a six-region
22 geographical framework that proved only partially separable, so a simpler structure emerged: Ward clustering
23 of 50 km hexagonal cells resolves three broad regimes — shear-dominated in the west and southwest,
24 thermodynamically charged in the central-southeast, and weakly forced in the north and east. Adapting a
25 footprint-based occurrence-to-exceedance model, we derived the first regime-dependent wind-speed
26 exceedance estimates for the region. Notably, the least active regime holds four of the five Enhanced Fujita
27 Scale 3 (EF3) tornadoes and dominates exceedance at 180 and 220 km h⁻¹, so where tornadoes are most frequent
28 is not where the strongest winds are most likely. These results provide a first catalogue-based baseline for
29 regime-dependent tornado and waterspout hazard assessment in peninsular Spain and the Balearic Islands.

30 1 Introduction

31 Tornadoes and waterspouts are low-frequency but potentially damaging severe convective hazards in Europe.
32 Their climatological assessment is challenging because they are short-lived, spatially narrow phenomena whose
33 detection depends strongly on observation density, post-event documentation, and reporting practices. In recent
34 decades, European tornado climatologies have benefited from the development of severe-weather databases,
35 public reports, and reanalysis-based environmental studies, but reporting heterogeneity and intensity



36 uncertainty remain important limitations, particularly in regions where historical documentation is uneven
37 (Dotzek et al., 2009; Groenemeijer and Kühne, 2014).

38 Previous work has shown that the Iberian Peninsula and the Balearic Islands host a heterogeneous tornado and
39 waterspout climatology. Early national-scale compilations established this picture: Gayà (2011) characterised
40 the spatial, temporal, and intensity distribution of tornadoes, waterspouts, and convective windstorms across
41 Spain, and the national meteorological agency subsequently produced a systematic climatology for peninsular
42 Spain and the Balearic Islands from a 10-year sample for 2003–2012 (AEMET, 2015). More recent work has
43 focused on the environmental drivers most relevant to the present study. Rodríguez and Bech (2021) analysed
44 907 events for 1980–2018 and identified a broad northeast–southwest contrast in seasonality and environmental
45 ingredients, with northeastern events generally associated with higher CAPE and lower shear/helicity and a
46 relevant fraction of southwestern events occurring in high-shear, low-CAPE environments. Rodríguez and
47 Lemus-Canovas (2023) further showed that Iberian tornadic storms can be grouped into multiple synoptic
48 patterns, highlighting the diversity of large-scale configurations that may favour tornadogenesis.

49 Studies in other Mediterranean regions provide a useful analogue. Italian tornado studies have documented the
50 role of low-level shear, deep-layer shear, CAPE, storm-relative helicity, sea-surface temperature anomalies, and
51 coastal/orographic forcing in modulating tornado-prone environments (Ingrosso et al., 2020; Bagaglini et al.,
52 2021; Avolio and Miglietta, 2021). They are a useful reference for Spain, where the Mediterranean coast, the
53 Gulf of Cádiz, the Cantabrian coast, the Ebro valley, and major mountain systems can generate sharp spatial
54 contrasts in moisture, instability, and low-level convergence.

55 For wind-hazard assessment, climatology alone is insufficient. A catalogue can describe where and when
56 tornadoes and waterspouts have been reported, but exceedance analysis requires translating regional occurrence
57 into the probability that a given wind-speed threshold is exceeded at a representative point or across gridded
58 spatial units. Bridging that gap requires three connected elements: (i) an updated and internally consistent event
59 database; (ii) a spatial framework that groups areas with comparable tornado-prone environments; and (iii) a
60 physically traceable occurrence-to-exceedance model that accounts for tornado frequency, intensity, path
61 length, path width, and the distribution of wind speeds within the damage swath.

62 A useful framework for this transition was proposed by Balbi and Barbieri (2018), who developed a footprint-
63 based probabilistic approach for tornado hazard assessment in Argentina. The method links tornado occurrence
64 rates with intensity-dependent path geometry and the internal distribution of wind speeds within the tornado
65 footprint, allowing regional tornado climatology to be converted into wind-speed exceedance estimates. Such
66 an approach is particularly useful where direct point-impact observations are scarce, since it yields exceedance
67 probability curves, $EP(v, T)$, which express the probability of exceeding a wind-speed threshold v within a
68 given exposure period T . Here, we adapt this methodology to peninsular Spain and the Balearic Islands by
69 combining an updated tornado and waterspout catalogue, environmental regionalization, tornado-path
70 geometry, and a Poisson occurrence model.



The objectives of this study are to (1) present an updated 1992–2025 tornado and waterspout database for peninsular Spain and the Balearic Islands; (2) describe the main temporal, spatial, and intensity-related climatological features of the record; (3) assess whether the environmental information derived from ERA5 supports a meaningful regional organization of tornado-prone environments; and (4) develop a preliminary wind-speed exceedance framework, adapted from footprint-based probabilistic approaches, to estimate EP (v, T) curves and threshold-based exceedance maps over the study domain.

2 Data and Methods

2.1 Study area and event database

The study domain comprises peninsular Spain and the Balearic Islands. The Canary Islands, Ceuta, and Melilla were excluded to keep a physically coherent Iberian–Mediterranean domain.

The catalogue was built by merging SINOBAS (singular atmospheric observations in Spain, maintained by AEMET) and the European Severe Weather Database (ESWD, maintained by ESSL), a reference source for European severe-weather climatologies (Dotzek et al., 2009). The ESWD contribution includes QC1 and QC2 events. Only tornadoes and waterspouts were retained. Meanwhile, other vortex-like or convective-wind phenomena (dust devils, gust vortices, gust fronts) were excluded.

The 1992 start year satisfies the 30-year minimum recommended by the WMO for climatological analyses (WMO, 2017) — the 1992–2025 record spans 34 years — and coincides with the start of the ESWD data provided by ESSL, giving a common baseline across both sources.

Event times were harmonized to UTC before merging, since SINOBAS/AEMET records are in local time and ESWD records in UTC. Then, local times were converted using the corresponding standard or daylight-saving time, prior to duplicate detection and ERA5 extraction. Following previous Iberian work, reports were treated as duplicate candidates when within 50 km and 2 h of one another (Rodríguez and Bech, 2021).

After harmonization, filtering, and duplicate removal, the final database (updated to 15 December 2025) contains 1185 tornado and waterspout events for 1992–2025, of which 567 are tornadoes and 618 waterspouts. Intensity was harmonized into SD, <EF0, EF0, EF1, EF2, and EF3. The SD class (reports without a determined Fujita/EF intensity) is retained for occurrence climatology. However, its exclusion is tested in the hazard calculations because the regime is dominated by waterspouts, which are rarely rated over water, whereas the rated classes correspond essentially to land-based tornadoes.

Table 1: Number of events in the updated 1992–2025 database by reported Fujita/Enhanced Fujita category.
Counts include both tornadoes and waterspouts.

Intensity class	Number of events	Percentage
SD	701	59.2 %
<EF0	20	1.7 %
EF0	200	16.9 %
EF1	216	18.2 %



EF2	43	3.6 %
EF3	5	0.4 %
Total	1185	100.0 %

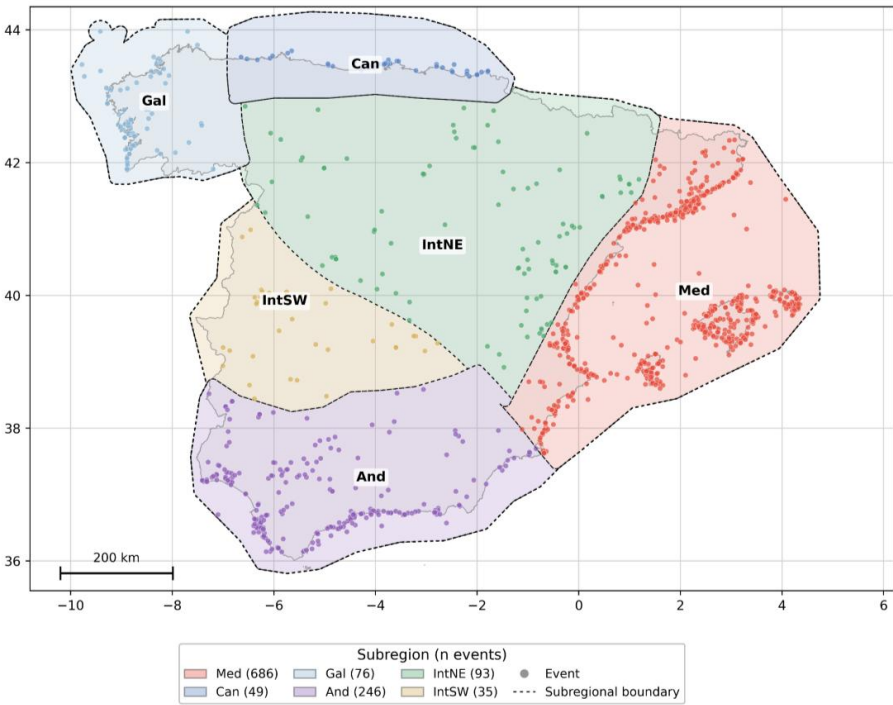
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103 **2.2 Climatological diagnostics and initial regional framework**

104 The climatological analysis covers annual counts and the monthly and diurnal distributions in local time (LT).
105 Because event times can be uncertain or rounded, the diurnal cycle was examined both with all records and
106 after filtering by temporal uncertainty; the main interpretation uses reports with uncertainty ≤ 1 h, with a stricter
107 ≤ 30 min comparison.

108 As an initial framework, the domain was divided into six a priori subregions: Mediterranean (MED), Interior
109 Northeast (IntNE), Andalusian/Gulf of Cádiz–Alborán (AND), Interior Southwest (IntSW), Cantabrian (CAN),
110 and Galician (GAL) (Fig. 1). This was not meant to define optimal clusters but to provide a physically motivated
111 baseline, refining the broad NE–SW contrast of Rodríguez and Bech (2021) and the synoptic diversity reported
112 by Rodríguez and Lemus-Canovas (2023), together with first-order controls on convective environments
113 (moisture sources, coastal–inland contrasts, orography, and the spatial density of reports). It is therefore treated
114 as a hypothesis to be tested against ERA5 information, not as an assumed optimum.

115



116

117 **Figure 1: Preliminary subregional framework for peninsular Spain and the Balearic Islands. Colours indicate the**
118 **six a priori subregions used in the analysis: Mediterranean (MED), Interior Northeast (IntNE), Andalusian/Gulf of**
119 **Cádiz–Alborán (AND), Interior Southwest (IntSW), Cantabrian (CAN), and Galician (GAL). Points indicate**



tornado and waterspout reports, and dashed lines indicate subregional boundaries. The map was generated using GeoPandas–Matplotlib from the subregional GeoJSON polygons, the event database, and official Spain–Balearic Islands geographical base layers.

2.3 ERA5 environmental predictors

Environments were characterized with ERA5 reanalysis (Hersbach et al., 2020). This reanalysis dataset provides hourly estimates of atmospheric variables on a $0.25^\circ \times 0.25^\circ$ horizontal grid. For each event, hourly profiles of temperature, humidity, and wind variables were extracted from 18 h before to 6 h after the reported event time. To reduce sensitivity to location, timing, and single-grid-point representativeness, each profile was defined as the spatial mean of the four ERA5 grid points forming the 2×2 grid-point box enclosing the event location.

From these source variables, 54 tornado-relevant parameters were computed using the open-source sounding-analysis package SHARPPy (Blumberg et al., 2017), including thermodynamic, kinematic, and composite indices such as CAPE, lifted indices, storm-relative helicity, effective bulk wind difference, energy-helicity indices, significant tornado parameters, and WMAXSHEAR-type diagnostics (Thompson et al., 2003, 2007; Taszarek et al., 2017). Their full definitions, layers, and primary references are listed in Table S1 in the Supplement.

For the exploratory full-window analysis, hourly series were summarized with event-relative values ($t = -6, 0, +6$ h) and simple descriptors (mean, maximum, minimum, and net change between -6 and $+6$ h), following the proximity-environment literature (Púčik et al., 2015; Taszarek et al., 2017) while adding a compact representation of the short-term evolution around each event (Ingrosso et al., 2020; Rodríguez and Bech, 2021).

With respect to the predictive and regionalization stages, only pre-event information was retained to avoid information leakage, i.e. the use of data not legitimately available before the event time (Kaufman et al., 2012), consistent with recent tornado machine-learning work using pretornadic predictors (Sessa and Trapp, 2025). The pre-event summaries were the value at $t = -6$ h, the pre-event mean, maximum, minimum, last value, first-to-last change, standard deviation, and linear slope.

2.4 Event-based environmental clustering and supervised separability

We first tested whether the six a priori regions emerged as natural groupings in the multivariate space. All predictors were standardized and reduced with PCA, representing each event in an orthogonal space retaining the dominant modes of variance (Jolliffe and Cadima, 2016). Furthermore, the number of components followed a cumulative-variance criterion, keeping those explaining ≈ 90 % of the total variance (up to 10 components).

The machine-learning methods were diagnostic tools, not operational predictors. Three unsupervised approaches were applied to the event-level PCA scores: DBSCAN, which finds dense groups and outliers without a preset number of clusters (Ester et al., 1996); a grid-based diagnostic on the PC1–PC2 plane to detect local density maxima (Wang et al., 1997); and Ward hierarchical clustering, which forms compact groups by minimizing within-cluster variance (Ward, 1963; Murtagh and Legendre, 2014).



156 Candidate solutions were screened before interpretation: a candidate was usable only if it produced at least two
157 non-noise clusters, retained sufficient coverage (low noise fraction, the share of unassigned events), and did not
158 collapse into one dominant cluster (low dominant-cluster fraction, the share of clustered events in the largest
159 cluster). These criteria were applied ahead of internal scores, which can be misleading when most events
160 become noise or when a partition is technically valid but nearly single-cluster (Hennig, 2015).

161 A supervised step then quantified whether the six regional labels were distinguishable from pre-event
162 predictors. This tested environmental separability, not forecast skill, since all cases are observed events.
163 Standardized, PCA-reduced predictors were evaluated with a dummy baseline that ignores the ERA5 predictors
164 and assigns the most frequent training-fold class, together with multinomial logistic regression, SVM-RBF
165 (Cortes and Vapnik, 1995), a decision tree (Breiman et al., 1984), and Gaussian naive Bayes (James et al.,
166 2021), under nested spatially grouped cross-validation with non-overlapping spatial blocks to limit spatial
167 leakage (Kohavi, 1995; Roberts et al., 2017). Because the classes are multiclass and imbalanced, performance
168 was summarized with Macro-F1, balanced accuracy and the Matthews correlation coefficient (MCC) (Sokolova
169 and Lapalme, 2009; Brodersen et al., 2010; Matthews, 1975; Gorodkin, 2004; Jurman et al., 2012). To combine
170 metrics defined on different ranges, the MCC was linearly normalized to the unit interval as $nMCC = (MCC +$
171 $1)/2$, following Chicco and Jurman (2020), and the three commensurable scores were aggregated into a single
172 composite score by an unweighted mean. Reducing several normalized performance metrics to a single index
173 for ranking is established practice in Earth-system model evaluation. Because such a single index can mask
174 trade-offs among the individual metrics (Gleckler et al., 2008), the composite is used only as a transparent,
175 parameter-free ranking criterion and the individual metrics are reported alongside it (Sect. 3.2). A dummy-
176 baseline skill score, $(\text{composite} - \text{dummy}) / (1 - \text{dummy})$, is reported in parallel.

177 **2.5 Objective spatial subregionalization**

178 The second stage shifted from event-level regimes to objective spatial regionalization, delineating spatial units
179 with similar pre-event signatures rather than imposing geographical boundaries (Zhang et al., 2016).

180 A regular hexagonal grid was generated over the domain; hexagons give a more uniform neighbourhood and
181 more compact geometry than square cells, favourable for spatial aggregation and connectivity analyses (Birch
182 et al., 2007; Majewski et al., 2002). Because ERA5 has a native spacing of 0.25° , the cell size was set
183 comparable to but slightly coarser than the reanalysis scale, with sensitivity tested at approximate hexagon sizes
184 of 35, 50, and 65 km.

185 Each event was assigned to its hexagon, and each occupied cell was summarized by the median of its events'
186 pre-event predictors, a robust statistic that limits the influence of extreme values where event counts per cell
187 are uneven (Huber and Ronchetti, 2009). Missing values were imputed feature-wise with the median, preserving
188 central tendency without adding extremes (Little and Rubin, 2019); the matrix was then standardized and PCA-
189 reduced before clustering.



190 Ward hierarchical clustering with a spatial-connectivity constraint was applied to the PCA scores, the constraint
191 preventing geographically fragmented regions. Candidate partitions were generated for $k = 2-6$ across the tested
192 hexagon sizes, with the six-region framework kept as a baseline.

193 Rather than selecting k automatically from a single internal criterion such as the gap statistic (Tibshirani et al.,
194 2001), candidates were compared under a common protocol: regional labels were predicted from pre-event
195 predictors and scored against a dummy baseline with a composite of Macro-F1, balanced accuracy, and
196 normalized MCC defined in Sect. 2.4, plus the dummy-relative skill score $(\text{model} - \text{dummy}) / (1 - \text{dummy})$,
197 which separates absolute performance from improvement over a trivial reference. Spatial cross-validation with
198 180 km blocks reduced inflation from spatial autocorrelation, and nested validation reduced optimistic bias
199 (Cawley and Talbot, 2010; Roberts et al., 2017).

200 The final partition was not chosen by a single score but by combining composite performance, skill, temporal
201 robustness, interpretability, parsimony, and suitability for the exceedance analysis.

202 **2.6 Occurrence, return period, and point-scale exceedance framework**

203 The probabilistic analysis was run over the official Spain-Balearic geographic domain clipped to the data. The
204 regionalization was derived from the combined tornado and waterspout sample, but the exceedance calculations
205 were restricted to tornadoes: waterspouts share physical drivers and improve the spatial coverage of ERA5
206 predictors, yet their overland wind speeds are not measurable from the catalogue. SD events were also excluded
207 from the class-specific footprint and exceedance calculation (Eqs. 2–4), as they cannot be assigned to a wind-
208 speed band without an arbitrary intensity distribution; in practice they correspond to amateur reports, distant
209 waterspout sightings, or cases without a damage survey (Doswell and Burgess, 1988).

210 Each tornado was assigned to a regime, and regime areas were obtained by dissolving the clipped hexagonal
211 partition in an equal-area projection. For each regime r and class k , the annual areal occurrence rate is given by
212 Eq. (1):

$$213 \quad \mu_{r,k} = \frac{N_{r,k}}{A_r n_y}, \quad (1)$$

214 where $N_{r,k}$ is the count, A_r the regime area, and n_y the number of years. This occurrence model was linked to
215 the footprint-based framework of Balbi and Barbieri (2018), in which climatology is translated into wind-speed
216 exceedance through occurrence rates, path geometry, and the internal distribution of damaging winds.

217 Path length and mean width were modelled by intensity class with Weibull distributions, fitted by maximum
218 likelihood where the class had at least 7 valid observations. In total, 52 catalogue events had usable path-
219 dimension information, distributed as SD ($N = 7$), EF0 ($N = 17$), EF1 ($N = 18$), and EF2 ($N = 7$), plus EF3 (N
220 $= 3$); no <EF0 report had usable dimensions. Local maximum-likelihood estimation (MLE) fits were obtained
221 for the four classes reaching the $N \geq 7$ threshold (SD, EF0, EF1, EF2). The SD fit was retained only as a path-



222 geometry diagnostic and was not propagated into the wind-speed exceedance calculation, because SD events
223 lack an assigned intensity class. Reported path dimensions are strongly rounded — typically given to the nearest
224 kilometre for length and as coarse round figures for width, rather than as precise survey measurements — so
225 the small EF1 and EF2 samples overlap substantially. For EF3, whose three usable reports fell below this
226 threshold, geometry instead followed the intensity–path relationships of Brooks (2004), scaled from the local
227 EF2 fit; $<EF0$ was scaled from EF0 with fixed ratio factors.

228 The expected footprint area $E[A_k]$ was estimated by Monte Carlo integration over the fitted path-length and
229 width distributions (Robert and Casella, 2010; Metropolis and Ulam, 1949). For each intensity class, $N = 200$
230 000 draws of path length and width were generated from the fitted Weibull distributions using a fixed seed for
231 reproducibility. The footprint area for each draw was computed as $L \times W$ and $E[A_k]$ taken as the sample mean
232 of these areas. The expected area exceeding a threshold v is given by Eq. (2):

$$233 \quad E[A_{exc,k}(v)] = E[A_k] f_k(v), \quad (2)$$

234 where $f_k(v)$ is the footprint fraction with local wind speed above v , taken from the area-variability matrix of
235 Balbi and Barbieri (2018), itself based on the NUREG/CR-4461 framework of Ramsdell and Rishel (2007);
236 within an EF band, $f_k(v)$ was linearly interpolated.

237 The annual exceedance rate and the probability of at least one exceedance in a time horizon T , under a Poisson
238 occurrence model, are given respectively by Eqs. (3) and (4):

$$239 \quad \lambda_r(v) = \sum_k \mu_{r,k} E[A_{exc,k}(v)], \quad (3)$$

$$240 \quad EP_r(v, T) = 1 - \exp[-\lambda_r(v)T]. \quad (4)$$

241 A homogeneous Poisson process was adopted because tornado occurrence within a regime over the 34-year
242 record can reasonably be treated as rare and approximately independent events with a locally constant rate,
243 consistent with standard practice in regional tornado-occurrence modelling (Jagger et al., 2015; Cheng et al.,
244 2015).

245 Fixed thresholds of 144, 180, and 220 km h⁻¹ were used as EF1-, EF2-, and EF3-like references (approximately
246 the lower bounds of each band), with continuous curves over a velocity grid. The exceedance probability is a
247 hazard metric conditional on each regime's observed climatology, not a deterministic forecast.

248 As a complementary occurrence metric, return periods were computed for a standard neighbourhood of radius
249 50 km centred on each hexagonal cell ($A_{50} = \pi 50^2$ km²) as $TR_{r,50}(v) = 1/\lambda_{r,50}(v)$. The neighbourhood return
250 period and the point-scale EP (v, T) are complementary but not interchangeable: the point-scale probability is
251 weighted by footprint area and increases with intensity, whereas the return period counts threshold-capable
252 events within A_{50} regardless of footprint. A regime with fewer but more intense tornadoes can therefore show
253 a longer return period yet a higher point-scale exceedance for the same threshold. The neighbourhood



formulation reflects the resolution of the hexagonal regionalization and matches the fixed-radius interpretation of operational severe-convective products.

Uncertainty was quantified by bootstrap resampling of years (1992–2025) with replacement, recomputing the regime rates per replicate (Efron and Tibshirani, 1993) and retaining the median and 5th–95th percentile range. Finally, threshold-based EP (v , T) maps were produced on the hexagonal grid, with hexagon rates smoothed by a Gamma–Poisson empirical-Bayes formulation whose prior mean equals the regime rate: $\hat{\lambda}_h = (n_h + \lambda_r T_0) / (T_h + T_0)$. A prior exposure $T_0 = 10$ years was adopted as an intermediate regularisation level, giving approximately $\approx 23\%$ weight to the regime prior and 77% to the observed count over the 34-year record. This regularisation reduces artificial zero estimates in empty cells where the corresponding regime rate is non-zero, while preserving most of the local spatial signal (Jagger et al., 2015; Cheng et al., 2015).

2.7 Computational implementation

All processing — harmonization, filtering, UTC standardization, duplicate detection, climatological diagnostics, ERA5 extraction, spatial processing, and the machine-learning analyses (PCA, clustering, supervised classification, cross-validation, metrics) — was implemented in Python with Jupyter notebooks (Kluyver et al., 2016), SHARPPy (Blumberg et al., 2017) for sounding-derived parameter computation and scikit-learn (Pedregosa et al., 2011), keeping the workflow reproducible. Ward clustering follows the minimum-variance criterion of Ward (1963) as clarified by Murtagh and Legendre (2014). ERA5 hourly profiles were downloaded and the 54 event-level parameters (Table S1) were computed using the HPC cluster of the “*Centro de Estudios Avanzados en Física, Matemáticas y Computación*” (CEAFMC), University of Huelva.

3 Results

3.1. Updated event catalogue and temporal occurrence patterns

The updated catalogue contains 1185 tornado and waterspout reports over peninsular Spain and the Balearic Islands for 1992–2025 after time harmonisation, filtering, and duplicate removal (Table 1). Annual counts show marked interannual variability rather than a simple monotonic behaviour (Fig. 2a). Specifically, the lowest annual totals are concentrated in the early part of the record, whereas larger totals occur mainly after the early 2000s, with particularly active years such as 2010 and 2018. Such an increase should be read with caution: European severe-weather databases are strongly affected by changes in reporting density, public awareness, documentation practices, and database consolidation (Dotzek et al., 2009; Gayà, 2011; Groenemeijer and Kühne, 2014). We therefore use the annual series to describe the observed record, not to infer a climatic trend in the physical occurrence of tornadoes or waterspouts.

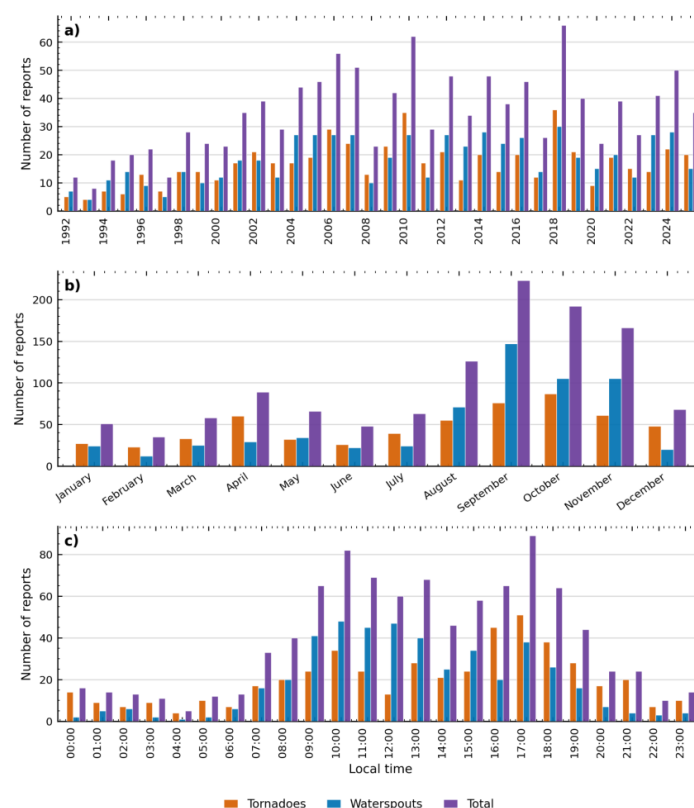
Analysis of the monthly distribution reveals a pronounced late-summer to autumn maximum is revealed, although events are reported throughout the year (Fig. 2b). The combined sample reaches its highest frequency in September and remains high in October and November, with an increase already evident in August. Waterspouts account for a large fraction of the late-summer and early-autumn maximum, especially in September, whereas tornado reports display a broader seasonal distribution, with enhanced activity in spring



289 and autumn and a marked maximum in October. This seasonal behaviour is consistent with the heterogeneous
290 Iberian and western Mediterranean setting, where coastal moisture sources, sea–land thermal contrasts,
291 orography, and synoptic forcing combine differently across regions (Rodríguez and Bech, 2021; Rodríguez and
292 Lemus-Canovas, 2023). The autumn maximum is also consistent with Mediterranean coastal environments,
293 where warm sea-surface conditions and early-season upper-level disturbances can favour deep moist convection
294 and low-level convergence (Ingrosso et al., 2020; Bagaglini et al., 2021; Avolio and Miglietta, 2021).

295 The filtered diurnal distribution further indicates that tornadoes and waterspouts have distinct timing
296 characteristics (Fig. 2c). Using only reports with temporal uncertainty equal to or lower than 1 h, the combined
297 sample is concentrated mainly from morning to late afternoon, with relative maxima around mid-morning and
298 late afternoon. Waterspouts show their highest frequencies from mid-morning to early afternoon, whereas
299 tornado reports peak later, mainly during the late afternoon. The contrast is physically plausible: land-based
300 tornado reports are more directly linked to the daytime development of boundary-layer instability, while
301 waterspouts and coastal convective vortices may also occur earlier over marine or near-coastal environments.
302 The stricter 30 min time-filtered sample preserves the same broad contrast between morning–early afternoon
303 waterspout activity and later tornado activity (Fig. S1c in the Supplement). By contrast, the unfiltered
304 distribution shows an anomalously strong noon peak, especially for waterspouts (Fig. S1a in the Supplement),
305 suggesting that records with uncertain or rounded times can distort the apparent diurnal cycle. For this reason,
306 the filtered records provide the basis for the interpretation of the diurnal climatology.

307



308

309 **Figure 2. Temporal distribution of tornado and waterspout reports in the updated catalogue for peninsular Spain**
 310 **and the Balearic Islands during 1992–2025. (a) Annual number of tornadoes, waterspouts, and combined events.**
 311 **(b) Monthly distribution aggregated over the full study period. (c) Diurnal distribution in local time using only**
 312 **reports with temporal uncertainty equal to or lower than 1 h. Orange, blue, and purple bars indicate tornadoes,**
 313 **waterspouts, and the combined sample, respectively.**

314 The record is thus strongly heterogeneous in time: interannual swings are large, activity peaks in autumn, and
 315 tornadoes and waterspouts differ in their daily timing. A single homogeneous temporal regime cannot represent
 316 the whole domain, which motivates the regional and environmental analyses that follow.

317 3.2. Event-level environmental separability of the initial subregional framework

318 The ERA5-derived environmental dataset provided a high-dimensional description of the pre-event conditions
 319 associated with the tornado and waterspout reports. The 54 tornado-relevant parameters listed in Table S1
 320 include thermodynamic, kinematic, and composite diagnostics, and were summarized using pre-event
 321 descriptors in order to avoid information leakage. We first used this predictor set to test whether the six a priori
 322 subregions defined in Sect. 2.2 were also distinguishable in the multivariate environmental space.

323 The projection of the event-level PCA scores onto the first two principal components shows substantial overlap
 324 among the six subregions (Fig. 3a). Although some broad spatial–environmental tendencies are apparent, the



325 regional labels do not form compact or well-separated clusters in the reduced environmental space. Events from
326 the Mediterranean region occupy a wide part of the diagram, while several inland and Atlantic-facing
327 subregions overlap strongly with one another. The overlap indicates that the initial geographical subdivision
328 captures part of the spatial organization of the record but does not correspond to six clearly separated
329 environmental classes.

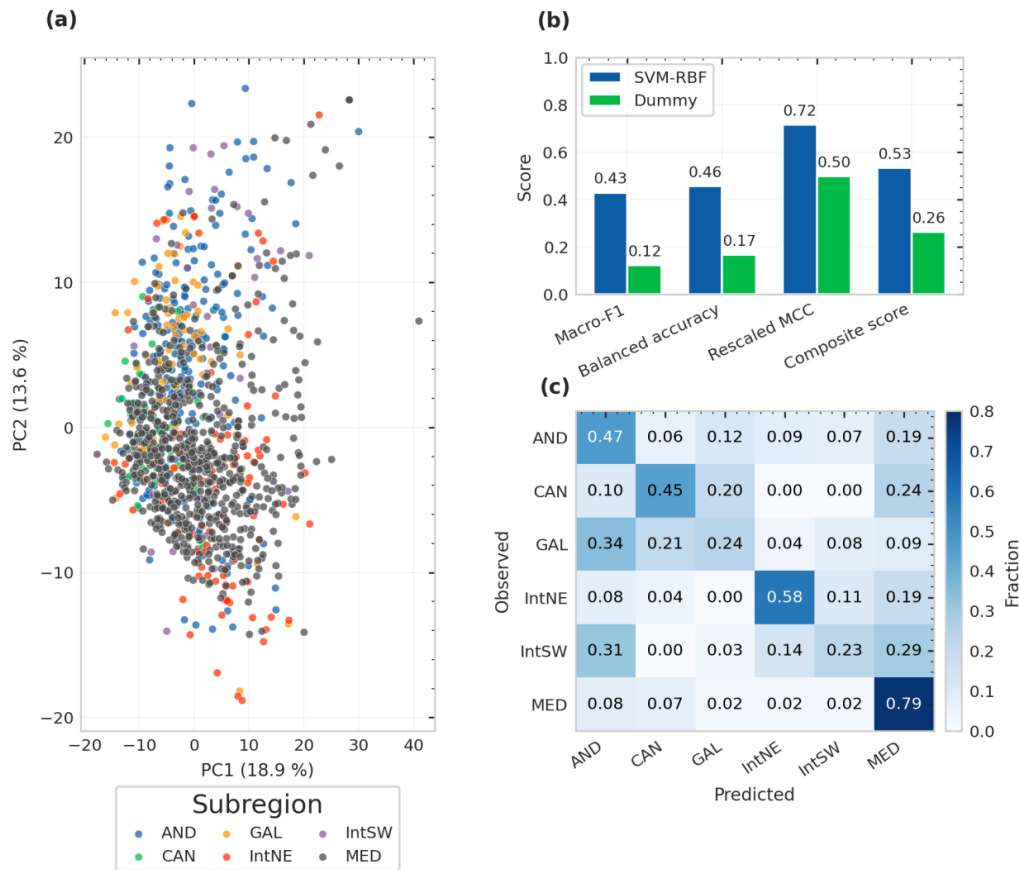
330 The supervised separability test confirms this interpretation. The best-performing classifier was the SVM-RBF
331 model, which obtained a composite score of approximately 0.54, compared with 0.26 for the dummy baseline
332 that ignores the ERA5 predictors (Fig. 3b). The model also outperformed the dummy reference in Macro-F1,
333 balanced accuracy, and rescaled MCC, indicating that the ERA5 predictors contain a non-random regional
334 signal. However, the absolute performance remained moderate, with Macro-F1 and balanced accuracy below
335 0.5. The six a priori regions are only partially recoverable from the pre-event environmental predictors.

336 The normalized confusion matrix further shows that this environmental separability is uneven across subregions
337 (Fig. 3c). The Mediterranean region was the most clearly identified class, with 79 % of observed Mediterranean
338 events classified correctly. Interior Northeast events also showed moderate separability, with 58 % correct
339 classification. By contrast, Galicia and Interior Southwest were poorly recovered, with correct-class fractions
340 of only about 24 % and 23 %, respectively. Both were frequently assigned to neighbouring or broader
341 environmental categories, especially Mediterranean, Andalusian/Gulf of Cádiz–Alborán, or Cantabrian classes.
342 The Andalusian/Gulf of Cádiz–Alborán and Cantabrian regions showed intermediate behaviour, with correct-
343 class fractions close to 45–47 %.

344 The comparison among classifiers supports the same conclusion (Fig. S2 in the Supplement). SVM-RBF
345 produced the highest composite score, followed closely by logistic regression, whereas Gaussian naive Bayes
346 and the decision tree performed less well. The relatively small separation between the two best models suggests
347 that the result is not driven by a single algorithmic choice. Instead, it reflects a moderate but incomplete
348 environmental organization of the six-region framework.



349



350

351 **Figure 3. Event-level environmental separability of the six a priori subregions. (a) Projection of tornado and**
352 **waterspout events onto the first two principal components of the standardized ERA5-derived environmental**
353 **predictor space, coloured by a priori subregion. (b) Performance of the best supervised classifier compared with a**
354 **dummy baseline using Macro-F1, balanced accuracy, normalized Matthews correlation coefficient (MCC), and the**
355 **composite score. The MCC was linearly rescaled to the [0, 1] interval before computing the composite score. (c)**
356 **Row-normalized confusion matrix for the best classifier, with observed subregions shown on the y axis and**
357 **predicted subregions on the x axis. Values indicate the fraction of events in each observed subregion assigned to**
358 **each predicted class.**

359 Unsupervised clustering of event-level PCA scores was then used as an additional diagnostic. DBSCAN, grid-
360 based clustering, and Ward hierarchical clustering were screened using simple validity criteria requiring at least
361 two non-noise clusters, sufficient event coverage, and no collapse into a single dominant cluster (Table S2 and
362 Fig. S3 in the Supplement). DBSCAN did not produce any valid candidate among the 90 tested configurations;
363 its best raw candidate retained most events but was dominated by a single non-noise cluster. The grid-based
364 method also produced no valid candidate among the 20 tested configurations; its best raw candidate identified
365 two dense groups but classified most events as noise, indicating poor event coverage. Ward clustering was the
366 only method that consistently produced valid, complete, and interpretable partitions, with all 30 tested
367 configurations passing the screening criteria. The rejection of DBSCAN and grid-based clustering was based



368 on basic validity diagnostics rather than on internal clustering scores alone: DBSCAN tended to collapse into
369 one dominant cluster, whereas the grid-based method retained only small dense subsets of the event space.

370 The four diagnostics agree: the six a priori subregions are a useful geographical hypothesis but too detailed to
371 capture the dominant environmental structure, which is better described by a smaller number of broader
372 regimes. That motivates the objective spatial regionalization developed next, where Ward clustering is applied
373 to hexagonal-cell signatures rather than to the six imposed regions.

374 **3.3. Objective spatial subregionalization**

375 The objective spatial regionalization was derived from Ward clustering applied to hexagon-level pre-event
376 environmental signatures. Among the tested hexagon sizes, the 50 km grid produced the highest composite
377 score, indicating the best compromise between spatial detail, event aggregation, and environmental separability
378 (Fig. 4a). The two-region solution achieved the highest absolute composite score, but it mainly reproduced the
379 first-order NE–SW contrast previously described for Iberian tornadic environments (Rodríguez and Bech,
380 2021). The three-region solution retained competitive performance while adding a geographically intermediate
381 third regime with its own distinct environmental signature and showed the strongest dummy-relative skill for
382 the tornado-only subset (Fig. 4b, c; the full per-metric breakdown by k is given in Fig. S4). Solutions with more
383 regions increased fragmentation without a clear compensating gain. The Ward 50 km $k = 3$ partition was
384 retained as the final objective regionalization.

385 The selected partition defines three spatially coherent regimes over peninsular Spain and the Balearic Islands
386 (Fig. 5). Regime 0 covers most of the northern and eastern sectors, including the Balearic Islands; regime 1 is
387 concentrated over the western and southwestern peninsula; and regime 2 forms a central-to-southeastern
388 transitional belt between them. The raw occupied-hexagon solution already shows this tripartite structure, while
389 the completed and officially clipped maps provide the continuous spatial support used in the subsequent
390 exceedance calculations (Fig. 5). The result refines, rather than replaces, the broad NE–SW environmental
391 contrast reported by Rodríguez and Bech (2021), and is consistent with the diversity of synoptic settings
392 documented for Iberian tornadic storms by Rodríguez and Lemus-Canovas (2023).

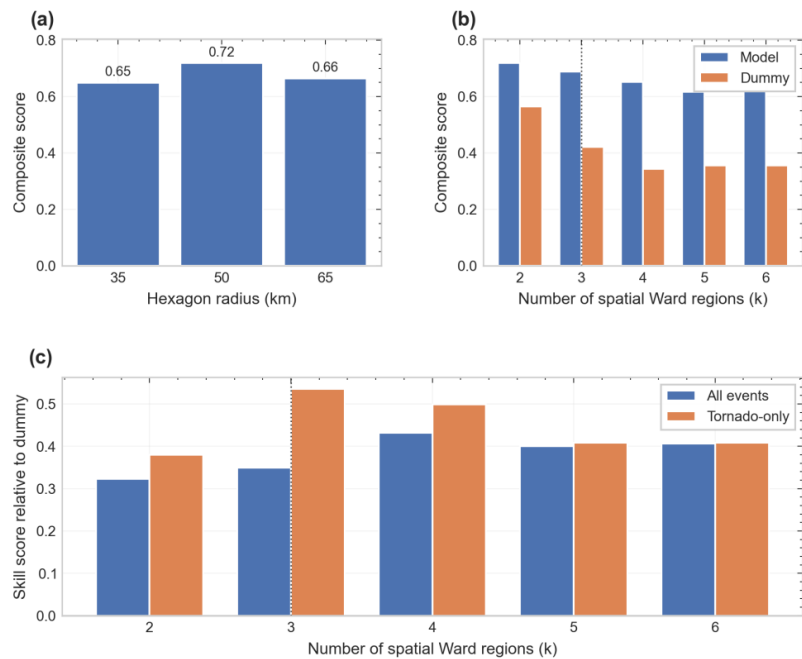


Figure 4. Comparative evaluation of candidate Ward spatial regionalizations. (a) Composite score for the tested hexagon sizes. (b) Composite score of Ward solutions with different numbers of regions ($k=2-6$), compared with the corresponding dummy baseline. (c) Skill score relative to the dummy baseline for the full event sample and the tornado-only subset. The final regionalization retained in this study corresponds to the 50 km, $k=3$ solution.

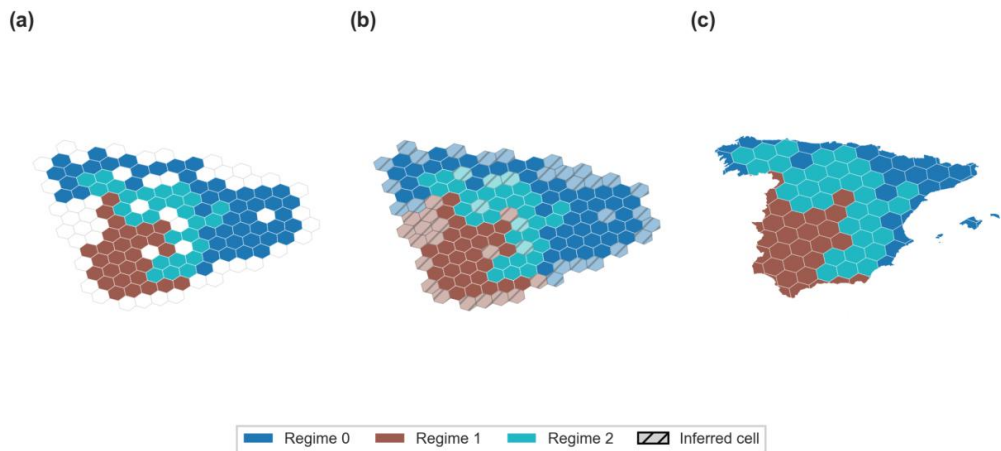


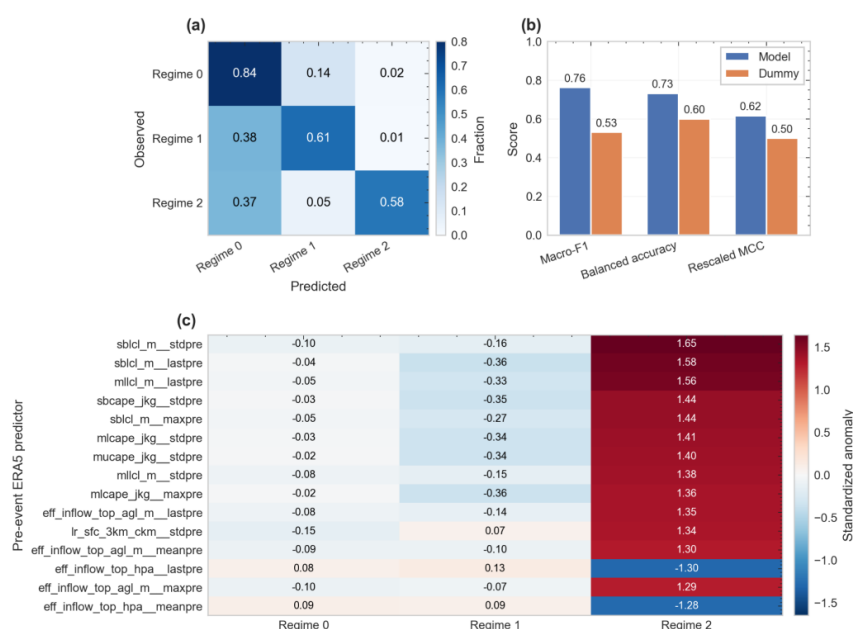
Figure 5. Construction of the final objective spatial regionalization. (a) Raw Ward 50 km $k=3$ partition for occupied hexagons only. (b) Full hexagonal partition after neighbour-based inference of labels for previously empty cells; inferred cells are indicated by hatching. (c) Final three-regime regionalization clipped to the official domain of peninsular Spain and the Balearic Islands.



The retained partition is also environmentally separable from event-level ERA5 predictors. For the full event sample, the supervised classifier outperformed the dummy baseline in Macro-F1, balanced accuracy, and rescaled MCC (Fig. 6b). The normalized confusion matrix shows that regime 0 is the most clearly recovered, with 84 % of its observed events correctly classified, whereas regimes 1 and 2 are recovered more moderately, at 61 % and 58 %, respectively (Fig. 6a). Critically, the confusion in both cases runs almost entirely toward regime 0 (38 % of regime 1 and 37 % of regime 2 events are misclassified as regime 0) and almost never between regimes 1 and 2 (1 % and 5 %, respectively). Regimes 1 and 2 are therefore well separated from each other, each partially overlapping only with the comparatively weak environmental signal of regime 0, rather than regime 2 sitting on a continuum between regimes 0 and 1.

Bootstrap resampling yielded a median composite score of 0.670, with a 5th–95th percentile range of 0.622–0.714 (Fig. S5 in the Supplement), consistent with the composite score obtained from the full sample and indicating that the retained partition's separability is not an artifact of any particular subset of years. The tornado-only validation reproduces the same pattern: the model again outperformed the dummy baseline (Macro-F1 0.66 vs. 0.17; balanced accuracy 0.67 vs. 0.23; normalized MCC 0.70 vs. 0.50), and the tornado-only confusion matrix closely mirrors the full-sample one, with regime 0 best recovered (75 %) and regimes 1 and 2 (70 % and 59 %) again confused mainly with regime 0 rather than with each other (Fig. S6 in the Supplement).

422



423

424 **Figure 6. Environmental separability and signature of the retained Ward 50 km k=3 regionalization. (a)**
425 **Normalized confusion matrix obtained when regional labels are predicted from event-level pre-event ERA5**
426 **predictors. (b) Model performance compared with the dummy baseline. (c) Standardized anomalies of the leading**



ERA5 predictors for each regime, showing the contrasting environmental signatures that define the final objective regionalization.

The environmental signatures of the three regimes are physically interpretable. The predictors with the largest combined range across the three regimes are dominated by thermodynamic and composite severe-weather diagnostics — CAPE-, LCL-, and effective-inflow-related variables — reflecting regime 2's outsized departure from the full-sample mean (Fig. 6c). Examining the leading predictors regime by regime reveals the full contrast (Fig. S7 in the Supplement): regime 0 shows generally negative standardized anomalies across a range of wind-, shear-, and composite-index predictors relative to the full event sample (Fig. S7a); regime 1 shows the strongest kinematic support of the three regimes, with pronounced positive anomalies in low- to mid-level wind and storm-relative-helicity variables (Fig. S7b); and regime 2 shows by far the largest anomalies of the three regimes, consistent with its dominance of the combined ranking in Fig. 6c (Fig. S7c). These contrasts are consistent with previous Iberian and Mediterranean studies showing that tornado-prone environments may arise from different combinations of instability, vertical shear, moisture, and synoptic forcing (Ingrosso et al., 2020; Bagagliini et al., 2021; Avolio and Miglietta, 2021; Rodríguez and Bech, 2021).

3.4. Occurrence, return period, and point-scale exceedance

By utilizing the Ward 50 km $k = 3$ environmental regionalization derived from the combined tornado and waterspout sample, the tornado-only exceedance analysis shows that the three regimes differ not only in total tornado occurrence, but also in how occurrence translates into wind-speed exceedance. Within the official clipped domain, regime 0 covers 132 734 km², regime 1 covers 152 244 km², and regime 2 covers 213 653 km². The corresponding domain-assigned tornado counts (all intensity classes, including SD) are 254, 189, and 74 events, respectively, implying total areal occurrence rates of approximately 5.6×10^{-5} , 3.7×10^{-5} , and 1.0×10^{-5} km⁻² yr⁻¹. Thus, regime 0 and regime 1 dominate the overall tornado occurrence signal, whereas regime 2 is less frequent but contains a proportionally larger contribution from the highest reported intensities.

Much of this amplification is driven by the fitted footprint geometry, which strongly increases the contribution of the most intense classes to exceedance at high wind-speed thresholds. The expected tornado footprint area increases from 0.09 km² for EF0 to 0.92 km² for EF1, 1.31 km² for EF2, and 11.50 km² for EF3. Consequently, the exceedance curves decrease rapidly with increasing wind-speed threshold, but not at the same rate in all regimes (Fig. 7a). For EF1-like winds, represented here by 144 km h⁻¹, the 30-year point-scale exceedance probability is highest in regime 0 (1.8×10^{-4}), followed by regime 1 (1.4×10^{-4}) and regime 2 (1.1×10^{-4} ; Fig. 7b). At 180 km h⁻¹, the ranking changes: regime 2 reaches the highest value (4.1×10^{-5}), followed by regime 0 (3.2×10^{-5}) and regime 1 (1.3×10^{-5}). At 220 km h⁻¹, the signal is concentrated in regime 2 (1.2×10^{-5}) and, to a lesser extent, regime 0 (5.0×10^{-6}), whereas regime 1 has no non-zero estimate because no EF3 tornadoes were recorded there in the analysed sample. This should not be interpreted as zero physical hazard, but as the direct consequence of the finite observed catalogue and the decision not to impose an arbitrary EF3 rate where none was observed. Accordingly, the 220 km h⁻¹ results rest on only five EF3 reports and on



the Brooks (2004) intensity–path scaling, which explains the very wide bootstrap intervals at this threshold and warrants cautious interpretation.

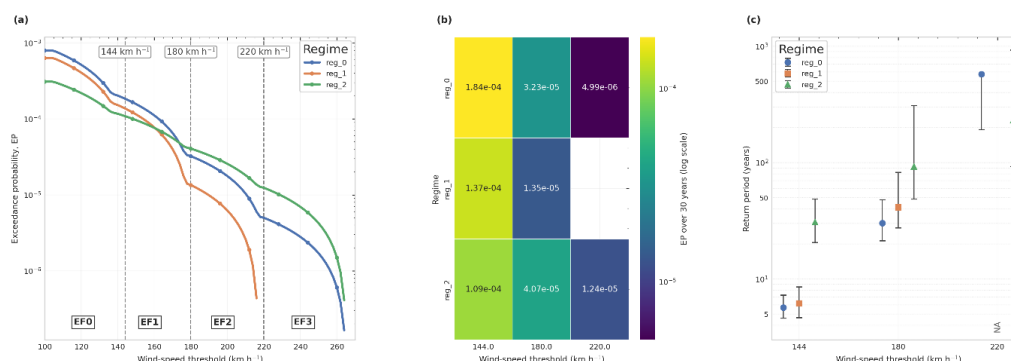


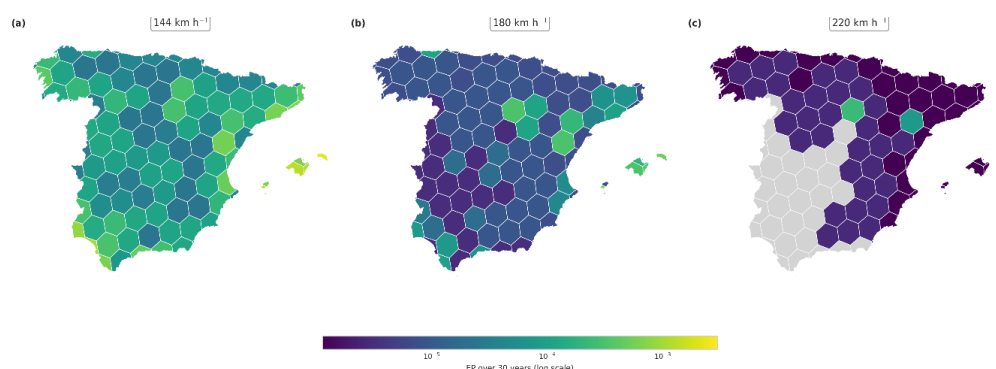
Figure 7. Regime-level tornado exceedance diagnostics computed for the Ward 50 km $k = 3$ regionalization derived from the combined tornado and waterspout sample. (a) Point-scale exceedance-probability curves $EP(v,T)$ for a 30-year time horizon as a function of wind-speed threshold. Vertical dashed lines mark the reference thresholds of 144, 180, and 220 km h⁻¹, approximately corresponding to EF1-, EF2-, and EF3-like wind speeds. (b) Fixed-threshold 30-year tornado exceedance probabilities by regime. Colours are shown on a logarithmic scale. (c) Bootstrap median return period for threshold-capable tornado occurrence within a 50-km neighbourhood. Points indicate the median and whiskers indicate the 5th–95th percentile range from annual bootstrap resampling.

Complementing this analysis, 50-km neighbourhood return-period estimates provide an occurrence-based view (Fig. 7c and Table S3 in the Supplement). For the 144 km h⁻¹ threshold, median return periods are short in regime 0 and regime 1, around 5.7 and 6.2 years, respectively, but increase to 30.8 years in regime 2. For 180 km h⁻¹, the median return periods increase to 30.2 years in regime 0, 41.2 years in regime 1, and 92.5 years in regime 2. For 220 km h⁻¹, only regime 0 and regime 2 produce finite median estimates, with values of 574.6 and 231.2 years, respectively; regime 1 remains undefined because of the absence of EF3 cases. The bootstrap intervals are particularly wide for the highest threshold, reflecting the strong sampling uncertainty associated with very few EF3 events.

To visualize how these regime-level differences project onto the spatial domain, empirical-Bayes hexagonal maps of point-scale $EP(v, T)$ are presented in Fig. 8. For 144 km h⁻¹, exceedance probabilities are spatially widespread, with local maxima mainly controlled by cells with stronger observed tornado occurrence. At 180 km h⁻¹, the signal becomes more localized and the contrast between regimes increases. At 220 km h⁻¹, exceedance probabilities are sparse and mainly confined to cells associated with the regimes where EF3 events were recorded. The filled-grid maps provide a continuous hazard surface over the official domain, while the observed-cell maps confirm where the estimates are directly supported by observed tornado records (Fig. S8 in the Supplement). Crucially, the most frequent tornado environments are not necessarily those producing the largest high-threshold exceedance probabilities: regime 0 and regime 1 dominate moderate-threshold occurrence, whereas regime 2 becomes disproportionately important for severe wind-speed exceedance.



491



492

493 **Figure 8.** Hexagon-level point-scale 30-year tornado exceedance probability for wind-speed thresholds of (a) 144,
494 (b) 180, and (c) 220 km h⁻¹. Estimates were obtained by applying the footprint-based point-scale exceedance model
495 to empirical-Bayes-smoothed hexagon-level tornado rates, shrunk toward the corresponding Ward-regime prior
496 with an equivalent prior exposure of 10 years. Colours are shown on a logarithmic scale. Grey cells indicate zero
497 estimates that cannot be represented on the logarithmic colour scale. The maps represent the filled official-domain
498 grid after propagating the final Ward-regime labels to previously empty cells.

499 The resulting probabilities should be interpreted as preliminary climatological hazard estimates conditional on
500 the 1992–2025 tornado catalogue, the adopted EF-scale wind thresholds, and the footprint-based exceedance
501 formulation of Ramsdell and Rishel (2007) and Balbi and Barbieri (2018). They are therefore not deterministic
502 forecasts, but a first spatially explicit translation of the updated Iberian tornado climatology into regime-
503 dependent wind-speed exceedance metrics.

504 4 Discussion

505 The updated catalogue reinforces a picture of strong temporal heterogeneity rather than a single dominant
506 regime. The September–November maximum, and in particular the waterspout-driven September peak, matches
507 the seasonal behaviour reported for the western and central Mediterranean, where warm late-summer sea-
508 surface temperatures and the first autumn upper-level troughs favour deep moist convection and low-level
509 convergence near the coast (Ingrosso et al., 2020; Bagaglini et al., 2021; Avolio and Miglietta, 2021). Land
510 tornadoes peak later in the year and later in the day than waterspouts, with a clear late-afternoon mode. The
511 split is physically reasonable: tornadoes over land depend on daytime heating of the boundary layer and the
512 destabilization that follows, whereas waterspouts form over a marine boundary layer that is far less sensitive to
513 the diurnal cycle and can develop under weak synoptic forcing through the morning. Rising counts after the
514 early 2000s are better read as improved reporting than as a physical trend, as has been stressed for European
515 severe-weather databases more generally (Dotzek et al., 2009; Groenemeijer and Kühne, 2014); we therefore
516 treat the annual series as descriptive.

517 The environmental analysis shows that the six a priori subregions are a useful geographical starting point but
518 not an environmental partition. Only the Mediterranean and, to a lesser degree, the Interior Northeast were well
519 recovered from the pre-event predictors, while Galicia and the Interior Southwest were largely absorbed into



neighbouring classes. The dominant structure is coarser: two regimes reproduce the northeast–southwest contrast already documented for Iberia (Rodríguez and Bech, 2021), and the retained three-regime solution refines it by isolating a third environmentally distinct regime located between the other two. We read the regimes as different ingredient combinations rather than as sharply bounded regions, which is consistent with the range of synoptic settings that Rodríguez and Lemus-Canovas (2023) associated with Iberian tornadic storms.

Each signature maps onto a known Iberian contrast. Regime 1, over the western and southwestern peninsula, is distinguished by enhanced low- to mid-level wind and shear with comparatively modest instability — the high-shear, low-CAPE setting repeatedly linked to Atlantic-facing and Gulf of Cádiz tornadoes (Rodríguez and Bech, 2018, 2021) and, more broadly, to environments that produce frequent but generally weak, short-lived tornadoes (Sherburn and Parker, 2014). Its high tornado count alongside the absence of EF3 cases fits that interpretation. Regime 2, a central-to-southeastern belt, instead shows by far the strongest anomalies of the three regimes, dominated by CAPE-, LCL-, and effective-inflow-related parameters, pointing to more strongly forced, supercell-favourable environments capable of occasional high-end tornadoes. Regime 0, covering the northern and eastern sectors and the Balearic Islands, shows comparatively muted anomalies across the wind- and shear-related predictors that distinguish regime 1, and carries the largest share of waterspouts; its low-shear character agrees with the milder northeastern environments of the binary contrast, although the strongest instability concentrates in regime 2 rather than across the whole northeast, a distinction the simple NE–SW split could not resolve.

A central result is that the most frequent tornado environments are not those that dominate the high-end wind hazard. Regimes 0 and 1 hold most of the tornadoes and control exceedance at 144 km h^{-1} , but at 180 and 220 km h^{-1} the hazard shifts to regime 2, which contains four of the five recorded EF3 tornadoes despite having the fewest events. The footprint-based framework makes this explicit: high-end point-scale exceedance scales with the expected damaged area of the most intense classes, and the EF3 footprint ($\approx 11.5 \text{ km}^2$) is more than an order of magnitude larger than the EF1 footprint ($\approx 0.9 \text{ km}^2$). The neighbourhood return periods and the point-scale exceedance probabilities consequently rank the regimes differently; this is not a contradiction but a direct effect of weighting events by footprint. For hazard purposes, event frequency alone is a poor proxy for severe-wind hazard, and an environment such as regime 2 warrants attention out of proportion to its event count.

Set against the previous national climatology, the results extend rather than overturn the earlier picture. The AEMET (2015) compilation for 2003–2012 recorded no EF3 tornado, whereas the longer 1992–2025 record used here includes five — a reminder of how sensitive the high-intensity tail is to catalogue length, and a reason to treat the 220 km h^{-1} estimates cautiously. This adaptation also represents, to our knowledge, the first spatially explicit translation of the Iberian tornado climatology into wind-speed exceedance, obtained by adapting the footprint approach of Balbi and Barbieri (2018) and the area-partition matrix of Ramsdell and Rishel (2007) to regime-dependent occurrence rates. The framework behaves coherently under the main sensitivity test:



555 excluding waterspouts shifts the point-scale exceedance probabilities but leaves the neighbourhood return
556 periods almost unchanged, which confirms that the threshold-capable occurrence signal is dominated by
557 tornadoes and is robust to how waterspouts over land are treated.

558 Several caveats qualify this interpretation. The exceedance estimates inherit the reporting heterogeneity of the
559 source databases and are conditional on the observed catalogue rather than predictive. Estimates for the most
560 intense classes rest on few events — five EF3 reports and only seven EF2 tornadoes with usable path dimensions
561 — so the EF2 and EF3 footprints carry large uncertainty and depend partly on the Brooks (2004) scaling and
562 on coarsely reported path lengths and widths. Recent reassessment work using the International Fujita scale in
563 Catalonia suggests that rating uncertainty is largest for weak tornadoes, whereas EF1 and stronger events show
564 fewer changes after rerating (Rodríguez et al., 2026). This does not remove the sampling uncertainty in our
565 high-threshold estimates, but it suggests that the largest classification ambiguities are concentrated mainly at
566 the weak end of the distribution, with more limited influence on the 180 and 220 km h⁻¹ exceedance estimates.
567 Waterspouts were retained for the climatological and environmental analyses but excluded from the hazard
568 calculation, since their overland wind speeds cannot be assigned reliably from the present record. The
569 regionalization was derived from the combined sample and then applied to the tornado-only hazard, an
570 approximation justified by shared environmental drivers but worth revisiting as more rated reports accumulate.
571 Finally, the ERA5 proximity approach describes the pre-event environment at the reanalysis scale and over a
572 2×2 average, smoothing the sharp coastal and orographic gradients that matter in a domain as varied as the
573 Iberian–Balearic region.

574 **5 Conclusions**

575 We assembled an updated 1992–2025 tornado and waterspout catalogue for peninsular Spain and the Balearic
576 Islands and used it to move from climatology toward a first regime-dependent assessment of wind-speed hazard.
577 The record of 1185 events is temporally heterogeneous, with a late-summer to autumn maximum and a clear
578 split between morning waterspouts and late-afternoon tornadoes; consistent with patterns documented for other
579 European severe-weather databases, its rising counts more plausibly reflect improved reporting practices than
580 a physical trend. The six geographically motivated subregions were only partially separable from the pre-event
581 ERA5 environments, and the dominant structure proved simpler: an objective Ward regionalization of 50 km
582 hexagonal cells resolves three broad regimes that refine, without replacing, the known northeast–southwest
583 contrast.

584 Each regime carries distinct environmental signatures — shear-dominated in the west and southwest,
585 thermodynamically charged in the central-southeast, and weakly forced in the north and east — and these
586 differences propagate into the hazard. The most informative result is a decoupling between occurrence and
587 severity: the regimes that produce most tornadoes are not those that dominate the high-end wind hazard. The
588 least active regime, the central-southeastern belt, concentrates the strongest instability-related environmental
589 signal and four of the five EF3 tornadoes, and therefore controls exceedance at 180 and 220 km h⁻¹. Occurrence
590 rate alone therefore underestimates where severe winds are most likely.



591 These estimates are preliminary and conditional on the observed catalogue, yet they offer a first spatially explicit
592 translation of the Iberian tornado climatology into wind-speed exceedance. Further progress will depend mainly
593 on the catalogue. Because tornadoes and their intensity are inherently difficult to document objectively — the
594 events are brief and narrow, many go unsurveyed, and the EF scale was not designed for European structures
595 — more accurate exceedance estimates require denser and more rigorous reporting. Standardized, reproducible
596 damage surveys that record path length, width, and rated intensity for as many events as possible (Rodríguez et
597 al., 2020), together with sustained community contributions to platforms such as SINOBAS, would tighten the
598 EF2–EF3 geometry that drives the severe end and keep both the database and the resulting exceedance maps
599 current. Higher-resolution or convection-permitting environmental information could further sharpen the
600 regional boundaries in a domain with strong coastal and orographic gradients, and applying the approach to
601 other Mediterranean regions would test how transferable the regime-dependent framework is.

602 **Code availability**

603 The code and reproducible workflow used in this study are archived on Zenodo at
604 <https://doi.org/10.5281/zenodo.21225731> (Agurto Barragán, 2026). The archived repository includes the
605 Python/Jupyter notebooks used for catalogue harmonization and filtering, ERA5 predictor extraction and
606 summarization, clustering and supervised-separability analyses, and regime-dependent occurrence and
607 exceedance calculations. It also includes the supporting Python source code, ERA5 download and preprocessing
608 scripts, figure-generation routines, documentation, and the computational environment specification.
609 Private/raw datasets and large derived outputs are not redistributed, in accordance with the repository data
610 policy and the access conditions of the original data providers.

611 **Data availability**

612 ERA5 reanalysis data are publicly available from the Copernicus Climate Data Store. SINOBAS tornado and
613 waterspout records are available through AEMET, and ESWD records are available through the European
614 Severe Storms Laboratory under their corresponding access, licensing, and quality-control conditions. The
615 processed datasets used internally for the analyses are not redistributed in the code repository, but the archived
616 workflow documents the processing steps required to reproduce the analyses from the authorized source data.

617 **Author contributions**

618 G.A. curated the database, performed the formal analysis (data harmonization, ERA5 predictor extraction,
619 clustering, classification, and exceedance calculations), and prepared the original draft. J.A.P., I.G.A. and
620 E.G.S.M.H. contributed to conceptualization, supervision, and review and editing. All authors contributed to
621 and approved the final manuscript.

622 **Competing interests**

623 The authors declare that they have no conflict of interest.



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630 the authors reviewed and edited the content as needed and take full responsibility for the content of the
631 publication.

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