



Temperature sensitivity of snow viscoplasticity: evidence from controlled creep experiments

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Abstract. Snow is a warm, porous material whose densification under its own weight is highly temperature-dependent. Despite decades of research, reported activation energies for snow viscoplasticity remain highly scattered, ranging from 40 to 600 kJ mol⁻¹. We quantified the temperature dependence of snow viscoplasticity using in-tomograph creep experiments with a newly developed thermo-mechanical cell. This design allows accurate load and temperature control, micrometric displacement measurement, and microstructural evolution monitoring via X-ray tomography. To disentangle microstructural evolution and temperature effects on the compression rate, we used a state-of-the-art viscoplastic model. We conducted five experiments on centimetre-scale samples of decomposing and fragmented precipitation particles with initial densities ranging from 278 to 320 kg m⁻³ under an applied stress of 1.25 kPa. Each experiment comprised five temperature steps from -6 to -18°C, each lasting one day, and resulted in a mean final vertical strain of 4%. We show that the viscoplastic response follows a two-regime Arrhenius law, with activation energies $Q_h = 126 \pm 6$ kJ mol⁻¹ for temperatures above $-13 \pm 1^\circ\text{C}$ and $Q_l = 51 \pm 18$ kJ mol⁻¹ below. This temperature sensitivity matches that reported for polycrystalline ice but is greater than that used in detailed snow-pack models.

KEYWORDS: Snow mechanics; viscoplasticity; temperature; microstructure; settlement

1 Introduction

Snow is a porous material with a wide range of densities, from approximately 50 kg m⁻³ for new snow to about 500 kg m⁻³ at the end of the winter season in mid-latitude regions. On Earth, it exists close to its melting point, making it highly sensitive to temperature. Snow continuously undergoes metamorphism, including substantial compaction over time through viscoplastic deformation. This viscoplastic creep is strongly temperature dependent, varying by approximately two orders of magnitude between -45°C and 0°C (Yosida, 1955). Therefore, quantifying the temperature dependence of snow viscoplasticity is essential for accurately predicting snowpack evolution (Lehning et al., 2002; Vionnet et al., 2012; Simson et al., 2021), with direct implications for avalanche forecasting (Morin et al., 2020), hydrology (Barnett et al., 2008; DeBeer and Pomeroy, 2017), and palaeoclimatology (Barnola et al., 1987). Knowledge of this temperature sensitivity is also critical for extrapolating laboratory-derived densification laws (Brun et al., 1992; Védérine and Hagenmuller, 2025) to the wide range of natural condi-



tions encountered on Earth, from warm seasonal snow (Lejeune et al., 2019) to cold perennial snow with seasonal temperature
25 variations of up to 40°C (Morris and Wingham, 2014).

Dry snow can be regarded as a two-phase material composed of sintered ice crystals and air (Bader, 1939). Its compaction
results from the slow viscoplastic deformation of the ice skeleton and the associated reduction in pore volume (e.g., Yosida,
1955). Consequently, snow densification depends strongly on the spatial arrangement of ice crystals and on the mechanisms by
which they deform. The temperature dependence of snow compaction thus stems from these underlying mechanisms. Védrine
30 et al. (2024) showed that ice in snow does not deform in the same way as polycrystalline ice because of pore accommodation,
and that snow creep is mainly driven by basal glide. It therefore remains unclear whether the temperature sensitivity of snow
viscoplasticity is the same as that of polycrystalline ice, which has been studied far more extensively than snow.

The viscoplasticity of isotropic ice (secondary creep) or snow is commonly described by a power law of the form:

$$\dot{\epsilon} = \dot{\epsilon}_0(T) \left(\frac{\sigma}{\sigma_0} \right)^n, \quad (1)$$

35 where σ_0 is the reference stress, n is the stress exponent and $\dot{\epsilon}_0(T)$ is the temperature-dependent prefactor. For isotropic
polycrystalline ice, this relation corresponds to Glen's law (Glen, 1955). The temperature dependence of $\dot{\epsilon}_0(T)$ is generally
assumed to follow an Arrhenius relationship (e.g., Yosida, 1955; Glen, 1955):

$$\dot{\epsilon}_0(T) \propto \exp\left(-\frac{Q}{RT}\right), \quad (2)$$

where Q is the activation energy, $R = 8.3 \text{ J mol}^{-1} \text{ K}^{-1}$ is the universal gas constant, and T is the absolute temperature in
40 kelvin. Quantifying the temperature sensitivity of creep, therefore, primarily amounts to determining the activation energy Q .

Numerous studies have investigated the activation energy Q associated with the creep of polycrystalline ice, reporting values
ranging from 45 to 167 kJ mol^{-1} (e.g., Glen, 1955; Mellor and Smith, 1966; Mellor and Testa, 1969a; Ramseier, 1975) (Fig. 1).
An increase in activation energy at warmer temperatures, typically above -10°C , is commonly reported (e.g., Budd and Jacka,
1989; Morgan, 1991). For example, Mellor and Testa (1969a) identified an activation energy of 68.8 kJ mol^{-1} between -60°C
45 and -10°C , but did not identify a consistent Arrhenius law above -10°C , noting a stronger temperature dependence in this
warmer range. Similarly, Kirchner et al. (2001) reported $Q = 120 \text{ kJ mol}^{-1}$ above -8°C and $Q = 78 \text{ kJ mol}^{-1}$ below this
threshold. Other studies have reported similar trends, with activation energies of approximately 60 kJ mol^{-1} below -10°C and
130 kJ mol^{-1} above (Steinemann, 1954; Glen, 1955; Barnes et al., 1971).

Several experimental studies have also investigated the influence of temperature on snow creep (Bucher, 1948; Yosida, 1955;
50 Kirchner et al., 2001; Scapozza and Bartelt, 2003; Delmas, 2013; Schleef et al., 2014b; Li et al., 2024; Horlings et al., 2025)
(Fig. 1). Yosida (1955) reported activation energies of 87 and 99 kJ mol^{-1} for densities of 156 kg m^{-3} and 230 kg m^{-3} ,
respectively, independent of temperature over the range from -20°C to 0°C . Kirchner et al. (2001) derived a transition in the
activation energy near -6°C , with $Q = 56 \pm 2.6 \text{ kJ mol}^{-1}$ below this threshold and $Q = 260.6 \pm 38.6 \text{ kJ mol}^{-1}$ above. They
associated this transition with that observed for polycrystalline ice (see above). Scapozza and Bartelt (2003) reported activation
55 energies ranging from 66 to 426 kJ mol^{-1} , depending on temperature and sample density. They noted a general increase in
 Q with both temperature and porosity. Using a similar protocol, Delmas (2013) performed creep tests at two temperatures



To address these limitations, we propose a new experimental protocol designed to tightly control both temperature and
75 microstructure in order to quantify the temperature sensitivity of snow viscoplasticity. Quantifying the influence of tempera-
ture on strain rate requires measurable deformation, which induces densification and viscoplastic hardening. We developed a
thermo-mechanical cell that enables precise control of sample temperature and allows temperature to be varied during creep
tests. Sample deformation is monitored using laser displacement measurements, which provide sufficient accuracy without
requiring large strains, thereby limiting microstructural evolution. Microstructural changes are further monitored using X-ray
80 tomography. In addition, geometric hardening during the experiments is accounted for in the identification procedure using
a state-of-the-art snow creep model (Védrine and Hagenmuller, 2025). This approach allows us to isolate the temperature
dependence of the viscoplastic response from microstructural effects. Applying this protocol to five samples subjected to five
temperature steps, we derive a two-regime Arrhenius law relationship between strain rate and temperature. Finally, we compare
the resulting parametrisation with settlement laws implemented in snowpack models and discuss the implications for snowpack
85 modelling.

2 Materials and methods

2.1 Experimental setup of the sample environment

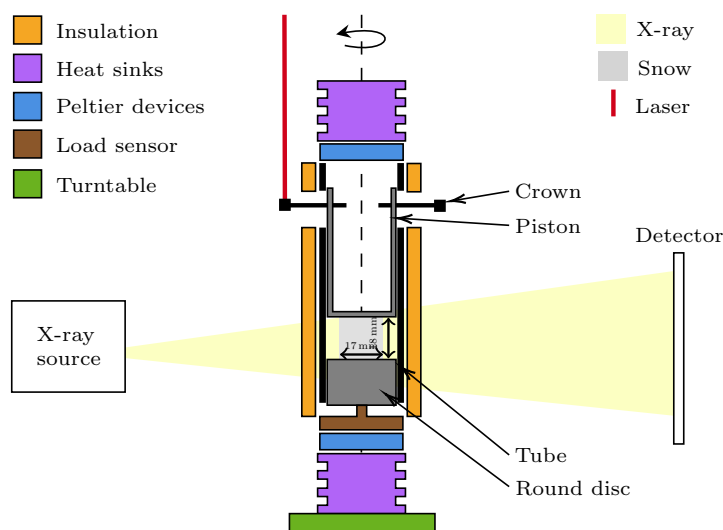


Figure 2. Scheme of the experimental setup.

The thermo-mechanical cell was designed for micro-CT measurements of snow settlement under controlled load and tem-
perature conditions. To this end, we drew inspiration from the *Snowbreeder 5* cell developed at the WSL-SLF (Wiese and
90 Schneebeli, 2017) and adapted the setup of Dick et al. (2026) for settlement analysis. In particular, we controlled the sample



temperature independently of the cold-room temperature, and we monitored the applied load to ensure that it remained constant throughout the tests.

The thermo-mechanical cell (Fig. 2) consists of an aluminium cylindrical tube with a diameter of 20 mm and a height of 90 mm. The wall thickness of the aluminium cell (0.5 mm) was chosen to allow X-rays to penetrate the cell and image the sample. A piston transmits the load to the sample. The mass of the piston and crown alone is $m = 28.79$ g. Because the piston is hollow, additional mass can be added to increase the applied load.

Two Peltier thermoelectric modules (TEC-14,7-3,9-34,0-70-30/0-R from Arctic TEC), referred to simply as Peltier units, are placed at the lower and upper ends of the cell, providing precise control of the sample temperature (Fig. 2). The Peltier modules are driven by a controller unit (TEC-1161-4A from MEERSTETTER). These Peltier modules ensure that temperature differences within the cell remain on the order of 10^{-3} K and provide an absolute temperature accuracy better than ± 0.5 K. Heat sinks and fans dissipate the heat produced by the Peltier units. The cell can be operated at temperatures up to ± 10 K relative to the ambient temperature. A thick insulating Styrofoam ring is added around the cell to ensure isothermal conditions. The Peltier units maintain temperature control during the experiment and prevent sample heating during scans. Temperature is measured at each Peltier module at 0.5 Hz.

Two additional measurements are integrated into the system:

- *Sample top displacement*: A laser sensor (OM30-P0100.HV.YUN from Baumer) mounted on the supporting frame measures the distance to a crown fixed to the piston applying the load to the snow sample. It is used to track the vertical displacement of the top of the snow sample. The crown design enables displacement tracking regardless of the cell orientation. The laser signal is transmitted via a 16-bit ADC acquisition card (MCCUSB234 from Digilent) to a computer located outside the cold room. The displacement data are recorded at a frequency of 0.2 Hz, with a measurement range of 15 mm and a resolution of $1 \mu\text{m}$. The vertical strain ε_{zz} is defined as:

$$\varepsilon_{zz} = \frac{h - h_i}{L} \quad (3)$$

where L is the sample height, and h and h_i are the current and initial laser distances, respectively.

- *Force measurement*: A miniature bottom load cell (LLB130 from FUTEK) is placed beneath the snow sample through a washer, allowing the force transmitted to the sample to be measured. It is used to ensure that a constant force is applied and to verify that the piston moves without frictional resistance. A driver (SM18-gage) amplifies the signal from the strain gauges, which is then sent to the same acquisition card as the laser displacement measurement. This sensor has a resolution of 0.1 g and, like the laser measurement, is recorded at a frequency of 0.2 Hz.

Because the cell rotates during tomographic acquisition, data are transmitted via a slip ring.



120 2.2 X-ray tomography

The evolution of the snow microstructure was monitored during the compression tests using an X-ray tomograph (DeskTom130, RX Solutions). Every 8 hours, a series of scans was acquired; each series consisted of one high-resolution scan (HR) and one low-resolution scan (LR). The HR scans captured an inner region (diameter of 10 mm and height of 10 mm) with a nominal voxel size of $11.23 \mu\text{m}$, and the LR scans covered the whole sample at a nominal voxel size of $27.44 \mu\text{m}$. The scan settings
125 for the different modalities are summarized in Table 1. The greyscale attenuation images were segmented into pore space and a continuous ice matrix (Hagenmuller et al., 2013).

Table 1. Acquisition parameters for tomographic imaging.

		LR	HR
X-ray source	Voltage (kV)	80	60
	Current (μA)	200	132
Detector	Averaged frames	3	2
	Frame rate (s^{-1})	5	1
	Number of projections	1000	1440
Scan trajectory	Voxel nominal size (μm)	27.44	11.23

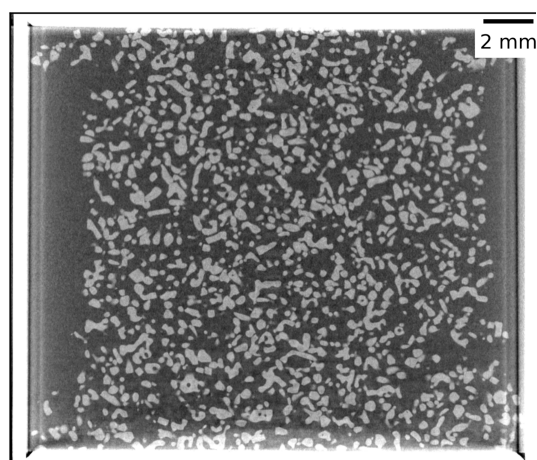


Figure 3. Vertical slice of the snow sample imaged in the thermo-mechanical cell using LR scans. The image is shown in grayscale.

To assess the consistency between the bulk deformation measured by laser and the deformation within the sample, axial strain was computed using Digital Volume Correlation (DVC) (Stamati et al., 2020) applied to low-resolution (LR) images. The analysis was conducted over a single region of interest (ROI) with dimensions of $10.3 \times 10.3 \times 10.3 \text{ mm}^3$.



130 2.3 Experimental protocol

Snow samples were prepared as follows. Natural snow was collected in the field and stored in styrofoam boxes in a cold room at a constant temperature of -20°C for several months, where it evolved into Decomposing and Fragmented precipitation particles (DF) through isothermal metamorphism. The snow particles were then sieved into a sample holder using a 1.6 mm sieve. The sample holder was cylindrical, with a diameter of 17 mm and a height of 17 mm, and was used to mould the snow samples. The diameter of the sample holder, 17 mm, was smaller than the 20 mm diameter of the cell tube, thereby creating unconfined conditions during the creep test and avoiding uncontrolled sidewall friction (Fig. 3). The samples were left to sinter for at least two weeks at -18°C before being placed into the cell tube.

We conducted creep tests with stepwise temperature variations to determine the temperature sensitivity of snow viscoplasticity. Temperature control was achieved using the Peltier modules. A stress of 1.25 kPa was applied to the snow sample, corresponding to the overburden stress exerted by a 0.45 m thick snow layer at the density used in the experiment. To limit lateral heat transfer, the cold room temperature was set to the average temperature of the experimental series. Each experiment lasted 5 days and consisted of 5 temperature steps, each lasting 1 day, with temperatures ranging from -6 to -18°C in 3°C increments. The first 8 hours of each experiment, corresponding to sample stabilisation (i.e., densification of the layer at the sample-piston interface and the establishment of steady-state conditions), were excluded from the analysis. This protocol was repeated on five snow samples with initial densities ranging from 278 to 320 kg m^{-3} ¹.

2.4 Snow viscoplastic model

The temporal evolution of the thickness e of a layer subjected to an overburden stress σ is related to the vertical strain rate through $\dot{\epsilon}_{zz} = \dot{e}/e$ (taken to be positive in compression). In its generic form (Védrine and Hagenmuller, 2025), the densification law can be expressed as a function of the solid fraction $\Phi = \rho/\rho_s$, where ρ is the snow density and $\rho_s = 917.15\text{ kg m}^{-3}$ is the density of ice:

$$\dot{\epsilon}_{zz}(T, \sigma) = \dot{\epsilon}_0(T) f(\sigma, \Phi), \quad f(\sigma, \Phi) = S_{\nu} \left(\frac{\sigma}{\sigma_{0,s} \Phi^m} \right)^n, \quad (4)$$

where S_{ν} is the boundary condition prefactor, equal to 1 here for free boundary conditions, n is the stress exponent, m is the solid-fraction exponent characterising the microstructure, and $\dot{\epsilon}_0(T)$ is the temperature-dependent prefactor. The latter is set to 1 s^{-1} at the reference temperature $T_0 = 263.15\text{ K}$, for which the reference stress of ice is $\sigma_{0,s} = 272\text{ MPa}$ (Jacka and Maccagnan, 1984). The stress exponent was set to $n = 2.2$ and the solid-fraction exponent to $m = 4$, based on experimental and modelling studies (Scapozza and Bartelt, 2003; Schleef et al., 2014a; Védrine and Hagenmuller, 2025).

The objective of the present study is to determine the temperature dependence of the prefactor $\dot{\epsilon}_0(T)$. To quantify the influence of temperature on strain rate, the sample must undergo measurable deformation; this inevitably induces densification and thus geometric hardening, i.e., an increase in the reference stress $\sigma_0 = \sigma_{0,s} \Phi^m$. As a result, even at constant temperature,

¹Note that, due to a technical issue, Samples 1 and 3 do not include a temperature step at -18°C .



160 the strain rate decreases during the test. To minimise geometric hardening, we apply a low overburden stress so that the microstructure remains only weakly deformed. Moreover, we use Eq. (4) to isolate the temperature prefactor $\dot{\epsilon}_0(T)$ by dividing the measured vertical strain rate $\dot{\epsilon}_{zz}$ by its mechanical component $f(\sigma, \Phi)$.

3 Results

3.1 Exemplary creep test

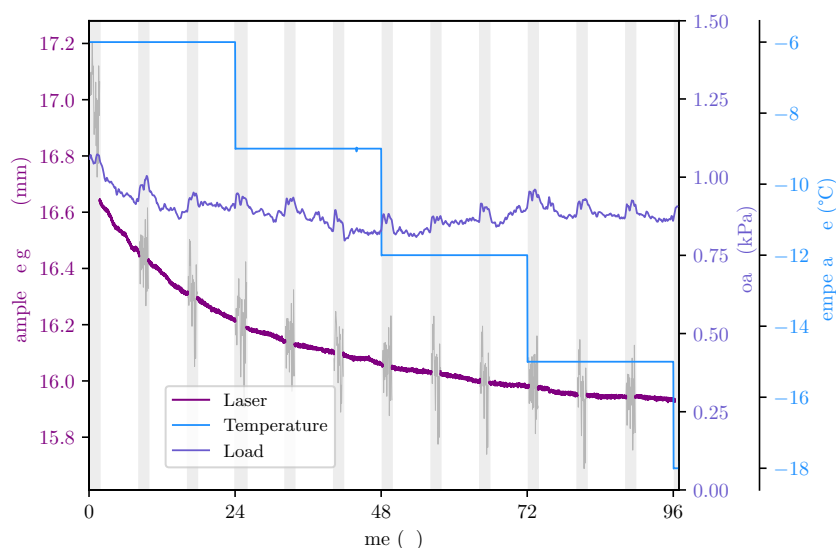


Figure 4. Temporal evolution of the sample height, the applied load, and the sample temperature for sample 1. Grey shaded areas indicate time intervals affected by X-ray tomographic scans.

165 We first show the results obtained on one sample (sample 1). The corresponding data for the other experimental series are provided in Appendix A1.

170 Figure 4 shows the temporal evolution of the sample height, applied load, and temperature. At each temperature step, an apparent change in the slope of the displacement curve is observed, reflecting a change in the strain rate. In addition, small displacement jumps occur at temperature transitions and are attributed to thermal expansion of the experimental cell. These jumps do not affect the subsequent analysis, as their magnitude is small and the analysis focuses on the derivative of the displacement (strain rate) obtained outside the scan periods. Because the applied load is small compared with the sensor measurement range (0–1 kg), the transmitted signal is weak and highly sensitive to the contact quality in the slip ring as well as to external perturbations. Nevertheless, we observe that the applied load remains nearly constant throughout the experiment, varying by less than 0.17 kPa, and is close to the nominal imposed load, which indicates that parasitic friction from the piston



175 or the washer is negligible. In the remainder of this study, the load applied to the sample is therefore assumed to be constant at 1.25 kPa (mass of the piston and crown divided by the sample cross-section).

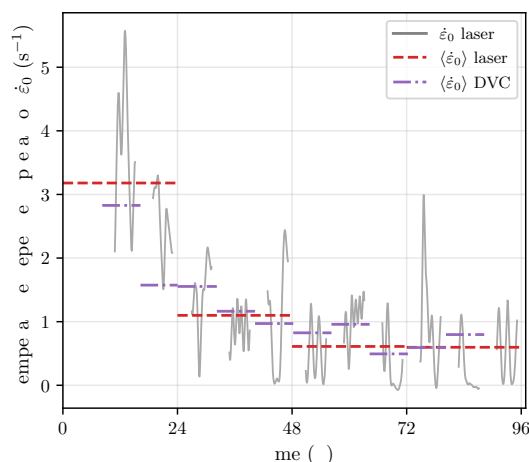


Figure 5. Temporal evolution of the strain rate prefactor $\dot{\epsilon}_0$, computed from laser displacement measurements and digital volume correlation (DVC).

To quantify the observed slope changes, the effects of densification and geometric hardening are first removed to isolate the temperature dependence of the deformation rate. Starting from the measured strain rate $\dot{\epsilon}$, the temperature-dependent prefactor $\dot{\epsilon}_0$ is computed and shown in Fig. 5. Despite significant fluctuations associated with experimental measurement noise, a systematic decrease in $\dot{\epsilon}_0$ is observed at each temperature step. Figures 5 and A4 show the temporal evolution of the strain rate prefactor $\dot{\epsilon}_0$, computed from both laser displacement measurements and DVC for all samples. The measurements are consistent with each other, indicating that the laser-based deformation accurately reflects the sample response despite the sample heterogeneities.

For each temperature plateau, the mean value of $\dot{\epsilon}_0$ is calculated and plotted as a function of inverse temperature $1/T$ (Fig. 6). On a logarithmic scale, $\dot{\epsilon}_0$ exhibits a linear dependence on $1/T$, consistent with an Arrhenius-type relationship, for which the slope equals $-Q/R$. The activation energy of sample 1 is thus estimated to be $Q_{S1} = 134 \pm 30 \text{ kJ mol}^{-1}$. Uncertainties here represent one standard deviation (68% confidence interval) derived from the covariance matrix, assuming Gaussian uncertainties in both temperature and strain rate.

We can compare the densification model (Eq. 4) with the measured vertical deformations using the previously calculated activation energy (Fig. 7). If temperature variations are neglected and the temperature is assumed to remain constant at its initial value, the deformation decreases more slowly and deviates from the experimental measurements. This comparison shows that the slowdown in deformation rate is primarily due to the decrease in temperature, as geometric hardening alone cannot account for the observed behaviour.

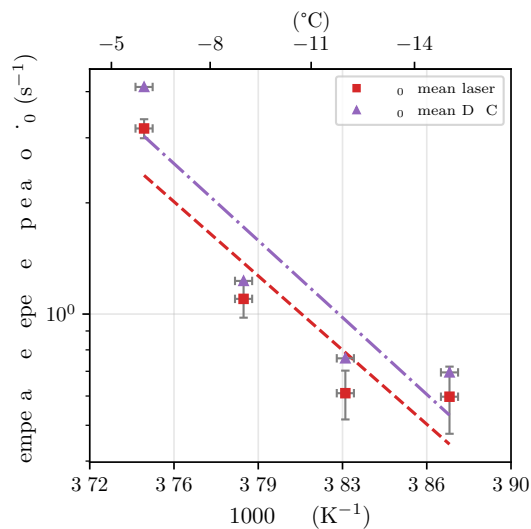


Figure 6. Mean values of the strain rate prefactor $\dot{\epsilon}_0$ as a function of temperature. The strain rate was computed from laser displacement measurements and digital volume correlation (DVC). Uncertainties in strain rate correspond to the standard deviation of the laser-derived measurements around the mean value shown in Fig. 5. Temperature uncertainty was estimated at $\pm 0.5^\circ\text{C}$.

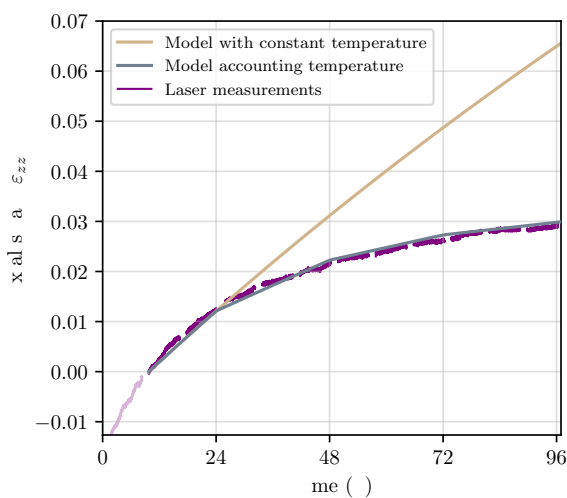


Figure 7. Strain versus time measured by the laser and predicted with the model Eq. 4 considering the measured temperature and a constant temperature equal to the initial temperature. The offset of the temperature prefactor is calibrated on the first temperature step. The first 8 hours (grey area) are excluded from the analysis.



3.2 Results for all experimental series

195 In this section, we analyse the full set of experimental results. At a given temperature, the temperature prefactor $\dot{\epsilon}_0$ varies by approximately 40% across the different experimental samples (Fig. A2). This dispersion is likely due to differences in second-order microstructural features that the mechanical model does not explicitly capture. In particular, samples 3 and 5 consistently exhibit higher values of $\dot{\epsilon}_0$ across the entire temperature range, whereas samples 1 and 4 show systematically lower values. Since our focus is on the temperature dependence, each sample series was first corrected for these second-order microstructural effects by subtracting the mean offset. Figure 8 shows the corrected scaled strain-rate prefactor as a function of inverse temperature for each sample. The data collapse onto a single master curve, indicating that all samples share a similar temperature dependence. We therefore use the complete dataset to characterise the viscoplastic response, accounting for the associated uncertainties.

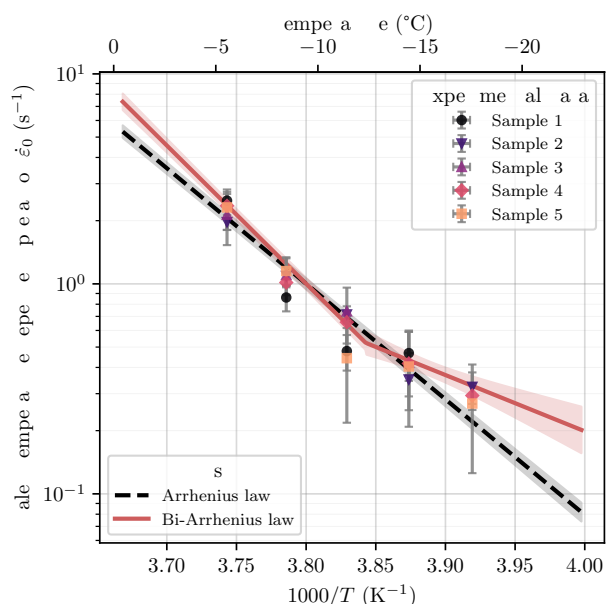


Figure 8. Scaled strain rate prefactor $\dot{\epsilon}_0$ as a function of inverse temperature for all studied samples, corrected for second-order microstructural effects.

Fitting a single Arrhenius law to all data yields an apparent activation energy of $Q = 105 \pm 6 \text{ kJ mol}^{-1}$. However, a simple Arrhenius formulation fails to capture the change in slope observed around -12°C , particularly for series 4 and 5. By fitting a two-regime Arrhenius law (Eq. 5) to the data, two activation energies are identified: $Q_h = 126 \pm 6 \text{ kJ mol}^{-1}$ and $Q_l = 51 \pm 18 \text{ kJ mol}^{-1}$, with a transition temperature of $T_c = -13 \pm 1^\circ\text{C}$. The activation energy associated with the low-temperature regime is subject to substantial uncertainty, owing to the large experimental scatter at low temperatures, where deformation rates are low. The two-regime Arrhenius law is statistically preferred according to the Akaike Information Criterion ($\delta AIC = -8$), indicating that the data support a transition between two temperature-dependent regimes.



$$\dot{\epsilon}_0(T) = \begin{cases} \exp\left[-\frac{Q_h}{R}\left(\frac{1}{T} - \frac{1}{T_0}\right)\right], & T > T_c, \\ \exp\left[-\frac{Q_l}{R}\left(\frac{1}{T} - \frac{1}{T_0}\right) + \frac{Q_l - Q_h}{R}\left(\frac{1}{T_c} - \frac{1}{T_0}\right)\right], & T \leq T_c. \end{cases} \quad (5)$$

3.3 Analysis of the evolution of microstructural properties and spatial heterogeneity

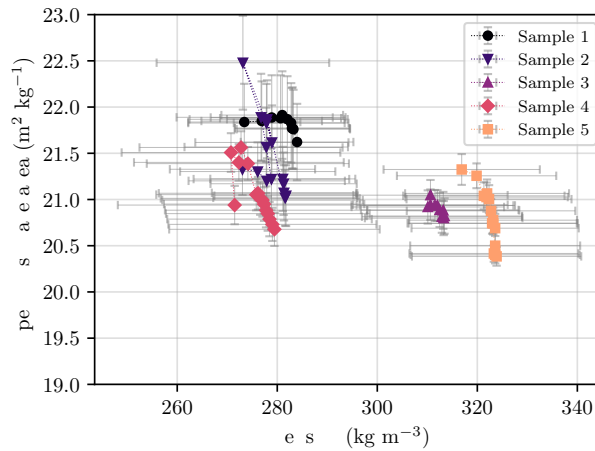


Figure 9. Evolution of specific surface area and density during the tests. Error bars represent the spatial heterogeneity within one sample (standard deviation between horizontal slices).

Tomographic scans were performed every 8 h during the tests to monitor the evolution of the microstructure. Figure 9 shows the evolution of the density and specific surface area (SSA) calculated over a $5.6 \times 5.6 \times 5.6 \text{ mm}^3$ volume. An increase in density was observed, whereas the SSA showed only a slight decrease. The microstructural variations are minimal during the experiment, with relative changes in density below 4% (less than 10 kg m^{-3}) and in SSA below 7% (less than $1.4 \text{ m}^2 \text{ kg}^{-1}$). The observed variation of the SSA is within the margin of error of tomographic image analysis (e.g., Hagenmuller et al., 2016). It confirms that the microstructure remained essentially unchanged during the compression tests, indicating a minimal effect on the mechanical properties.

220 4 Discussion

4.1 Robust identification of the temperature sensitivity of snow viscoplasticity

In this study, we isolated the effect of temperature on the viscoplastic response by (i) using the same snow sample throughout each test, (ii) limiting microstructural variations across temperature steps, and (iii) accounting for geometric hardening using the model proposed by Védérine and Hagenmuller (2025). This procedure enables robust identification of the temperature sensitivity



225 of snow viscoplasticity and disentangles it from microstructural effects. We discuss here how the choice of geometric hardening model and sample heterogeneity may affect the results.

Figure 10 illustrates the sensitivity of the identified activation energy to the parameters of the constitutive law. If the activation energy were estimated without accounting for geometric hardening ($n = 0$ and $m = 0$), a value of $Q = 116 \pm 7 \text{ kJ mol}^{-1}$ would be obtained, corresponding to a deviation of approximately 10%. This deviation remains relatively small because microstructural changes are intentionally limited. Nevertheless, it highlights the importance of decoupling the effects of geometric hardening and temperature. Furthermore, within the range of n and m typically reported for snow (Scapozza and Bartelt, 2003; Schleef et al., 2014a; Védérine et al., 2025), the sensitivity of Q to these parameters is low, resulting in a maximum deviation of 3%.

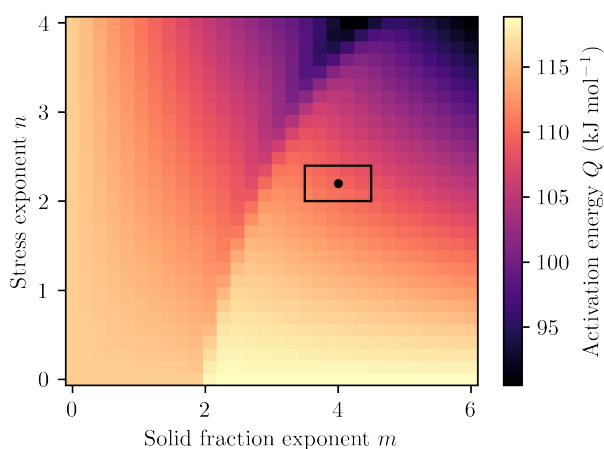


Figure 10. Activation energy estimated from the experimental measurements as a function of the model parameters m and n . The rectangle indicates the range of physically meaningful parameters ($m = 4 \pm 1$ and $n = 2.2 \pm 0.2$).

In our model, each sample was assumed homogeneous and characterised by its mean density. However, the tomographic scans reveal spatial heterogeneities within the samples (Fig. 9), which can lead to stress concentrations and higher strain rates (Fig. 8). Differences in microstructural heterogeneity between samples, as well as second-order microstructural parameters (Fig. 9), affect the mean strain-rate but not its temperature dependence. These effects can therefore be readily accounted for, allowing the influence of temperature to be isolated (Fig. 8). These results clearly demonstrate the necessity of using the same snow sample to identify the temperature sensitivity of snow viscoplasticity. If different samples are used at each temperature step, microstructural effects can no longer be disentangled from temperature dependence (e.g., Scapozza and Bartelt, 2003; Delmas, 2013; Li et al., 2024).



4.2 Comparison of the temperature dependence of snow viscoplasticity with previous studies

Our results ($Q_h = 126 \pm 6 \text{ kJ mol}^{-1}$ above $T_c = -13 \pm 1^\circ\text{C}$ and $Q_l = 51 \pm 18 \text{ kJ mol}^{-1}$ below) fall within the wide range of activation energies reported in the literature (Fig. 1) and confirm previous reports of two temperature regimes in snow (Kirchner et al., 2001; Scapozza and Bartelt, 2003). For example, Kirchner et al. (2001) observed an activation-energy transition near -6°C , with $Q = 56 \text{ kJ mol}^{-1}$ below this threshold and $Q = 260 \text{ kJ mol}^{-1}$ above. Scapozza and Bartelt (2003) reported an increase in activation energy from approximately 69 kJ mol^{-1} between -18°C and -11°C to about 120 kJ mol^{-1} between -12°C and -5°C for snow with a density of 430 kg m^{-3} . However, our activation energy estimates are substantially higher than those reported by Schlee et al. (2014b), who found an activation energy of $Q = 54 \text{ kJ mol}^{-1}$ between -13°C and -3°C . The very high activation energy values reported by Scapozza and Bartelt (2003) and Delmas (2013) are likely due to microstructural variability, because only two temperatures were used to determine the activation energy, which makes the estimated activation energy highly sensitive to differences in microstructure between samples.

4.3 A signature of microscale deformation mechanisms?

At first glance, the viscoplastic response of snow exhibits a temperature sensitivity similar to that reported for polycrystalline ice. In particular, the bilinear temperature dependence inferred from our data yields activation energies consistent with commonly reported values for ice creep. The high-temperature regime is characterised by an activation energy of $Q_h = 126 \pm 6 \text{ kJ mol}^{-1}$, in good agreement with values reported for polycrystalline ice, typically around 130 kJ mol^{-1} (e.g., Glen, 1955; Steinemann, 1954; Mellor and Testa, 1969b; Barnes et al., 1971). At lower temperatures, a second regime is observed, with $Q_l = 51 \pm 18 \text{ kJ mol}^{-1}$, close to the commonly used value of 69.1 kJ mol^{-1} for polycrystalline ice below -10°C (Mellor and Testa, 1969b).

However, this apparent similarity should be interpreted with caution. Védérine et al. (2024) demonstrated that deformation in snow is primarily governed by basal slip in the ice matrix. This result suggests that the temperature sensitivity of snow viscoplasticity may primarily be inherited from that of basal slip. Yet, the temperature sensitivity of basal slip at the single-crystal scale remains poorly constrained. The activation energy associated with basal slip has been reported to lie in the range $60\text{--}90 \text{ kJ mol}^{-1}$ (Okada et al., 1999; Meyssonier et al., 2009) at low temperatures ($\leq -10^\circ\text{C}$). Jones and Brunet (1978) investigated the temperature sensitivity of ice single crystals over the range -20°C to -0.2°C and reported an activation energy of $Q = 70 \pm 2 \text{ kJ mol}^{-1}$, independent of temperature. However, they observed that the stress exponent of basal slip, n_b , varied linearly with temperature, decreasing from $n_b = 2.07$ at -20°C to $n_b = 1.95$ at -0.2°C . Such temperature dependence of the stress exponent is commonly reported in single crystals (e.g., Spitzig and Keh, 1970; Wollgramm et al., 2016).

In our model, n was fixed at 2.2. However, when this relative temperature dependence of the exponent is taken into account ($n(T) = 2.15 - 7.26 \times 10^{-3}T$, assuming the same temperature dependence as for the basal slip system), we obtain a single effective activation energy of $Q = 73.5 \pm 6 \text{ kJ mol}^{-1}$ (Fig. A3) over the full temperature range. This value is consistent with the activation energy for basal slip determined by Jones and Brunet (1978). This result suggests that part of the apparent bilinear temperature dependence observed at the macroscopic scale may not reflect a true transition in activation energy, but rather the



275 effect of a temperature-dependent stress exponent. These results highlight the need for dedicated experimental and modelling
 studies to better constrain the temperature dependence of the stress exponent and its contribution to the apparent macroscopic
 temperature sensitivity of snow viscoplasticity.

4.4 Impact on snowpack model

We compare our model with the parametrisation of Brun et al. (1992) (BR92), implemented in the detailed snowpack model
 280 *Crocus*, and with the parametrisation of Kojima (1975) (K75) for fresh snow, implemented in the snowpack model *Snowpack*
 (Lehning et al., 2002). In the BR92 parametrisation, the temperature dependence is expressed as $e^{a_\eta(T_m - T)}$, with $a_\eta = 0.1 \text{ K}^{-1}$,
 where T_m is the melting temperature and T is the snow temperature in $^\circ\text{C}$. This expression corresponds to the first-order ex-
 pansion (close to 0°C) of the Arrhenius law with an activation energy of 62 kJ mol^{-1} , which is close to the value obtained for
 the low temperature regime but significantly lower than that obtained for the high temperature regime. In the K75 parametri-
 285 sation, the effects of density and temperature are coupled through a power law in the expression of the compactive viscosity,
 $\eta_{K75} = 7 \times 10^{-9} \rho^{(4.75 - T/40)}$, where ρ is the snow density and T is the temperature in $^\circ\text{C}$.

Figure 11 shows the strain rate predicted by the detailed snowpack models and our parametrisation for different densities:
 100, 200, and 400 kg m^{-3} . The BR92 model exhibits the weakest temperature sensitivity. At low densities, the K75 model is
 close to BR92, whereas at a density of 400 kg m^{-3} it shows a variation in strain rate between -30°C and 0°C that is similar
 290 to our parametrisation. Finally, only our parametrisation exhibits two distinct temperature regimes.

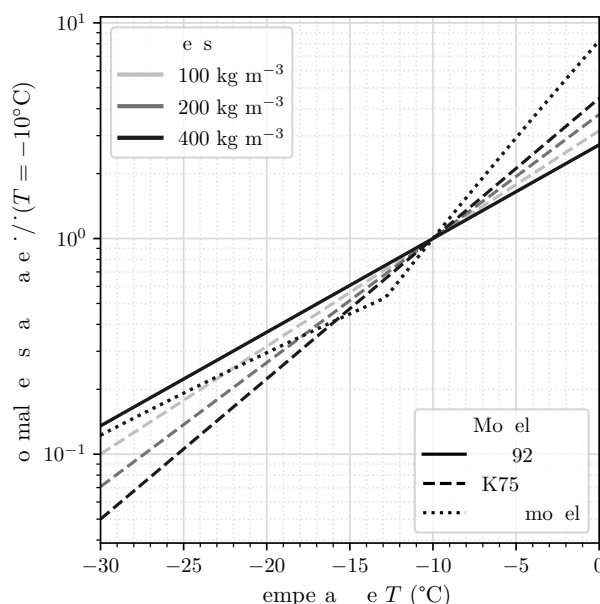


Figure 11. Normalized strain rate at -10°C predicted by the model of Brun et al. (1992) (BR92), Kojima (1975) (K75), and our parametrisation incorporating the two-regime Arrhenius law (Eq. 5) as a function of temperature for different snow densities.



Let us consider an isothermal snowpack 1 m thick with an initial density of $\rho = 100 \text{ kg m}^{-3}$. Figure 12 shows the evolution of snow height predicted by the different models at different temperatures. At low density and across all temperatures, our model predicts significantly higher strain rates than those obtained with the BR92 and K75 parametrisations, which yield nearly identical results in this regime. This behaviour is consistent with the commonly reported limitations of the BR92 formulation for fresh snow (Quéno et al., 2016). A clear sensitivity of snow compaction to temperature also emerges. After one hour, compared to a snowpack at -2°C , the snow height at -20°C decreases by 16%, 18%, and 23% for the BR92, K75, and our parametrisation, respectively. After one day, the influence of temperature and the differences in temperature sensitivity among the models become less pronounced. Overall, temperature mainly affects the characteristic timescale of compaction and, to a lesser extent, the long-term snowpack height. For example, after seven days, an isothermal snowpack at -20°C exhibits a snow height that is 25%, 42%, and 36% higher than that predicted at -2°C for the BR92, K75, and our parametrisation, respectively. These results underline that accurately capturing the temperature sensitivity of snow viscoplasticity is essential for predicting snowpack evolution.

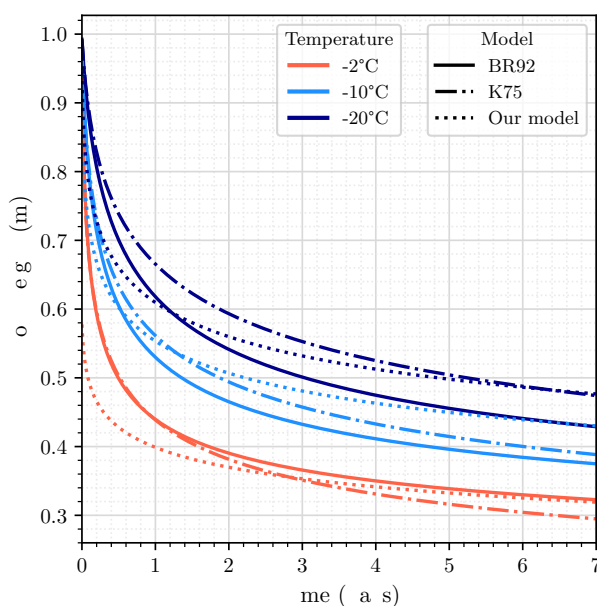


Figure 12. Evolution of snow height predicted using the parametrisations of Brun et al. (1992) (BR92), Kojima (1975) (K75), and our parametrisation incorporating the two-regime Arrhenius law (Eq. 5). Simulations are performed for a 1 m thick isothermal snowpack with an initial density of $\rho = 100 \text{ kg m}^{-3}$.

5 Conclusion and perspectives

We developed a new thermo-mechanical cell that enables precise temperature control during in-tomograph snow-creep experiments and allows the sample temperature to be varied during creep tests. Using this device, we performed five series of



experiments on samples with initial densities ranging from 278 to 320 kg m⁻³, each subjected to five temperature steps between -6°C and -18°C. By tracking the response of a single sample across successive temperature steps, we isolated the temperature dependence of snow viscoplasticity from microstructural variability by accounting for geometric hardening. The measured response is well described by a two-regime Arrhenius law, with a transition temperature of $T_c = -13 \pm 1^\circ\text{C}$, a high-temperature activation energy of $Q_h = 126 \pm 6 \text{ kJ mol}^{-1}$, and a low-temperature activation energy of $Q_l = 51 \pm 18 \text{ kJ mol}^{-1}$. Although the densification measured during the tests intentionally remained small (<4%), neglecting geometric hardening would lead to an apparent activation energy of $Q = 116 \text{ kJ mol}^{-1}$, corresponding to an error of about 10%.

These results provide a robust basis for extending snow densification laws over a wide temperature range and show that accurately capturing temperature sensitivity is essential for predicting snowpack evolution. Assuming a constant stress exponent, the identified behaviour closely resembles that reported for polycrystalline ice. However, when the temperature dependence of the stress exponent is taken into account, following the trend reported for basal slip by Jones and Brunet (1978), the data can also be described by a single effective activation energy of $Q = 73.5 \pm 6 \text{ kJ mol}^{-1}$, consistent with basal-slip creep. This suggests that part of the apparent bilinear temperature dependence observed at the macroscopic scale may reflect a temperature-dependent stress exponent rather than a true transition in activation energy. Dedicated experiments and modelling analyses are therefore still needed to better constrain the temperature dependence of the stress exponent and to clarify the respective roles of microscale deformation mechanisms in the macroscopic viscoplastic response of snow.

Code and data availability. All measurements are available at <https://doi.org/10.5281/zenodo.18824418> (Védrine et al., 2026), the tomographic data are available on request.

Video supplement. Videos of the compression experiments are available at <https://doi.org/10.5281/zenodo.18824418> (Védrine et al., 2026).



325 **Appendix A: Results for other creep tests**

A1 Displacement and load

Figure A1 shows the temporal evolution of the sample displacement and applied load for the Samples 2 to 5.

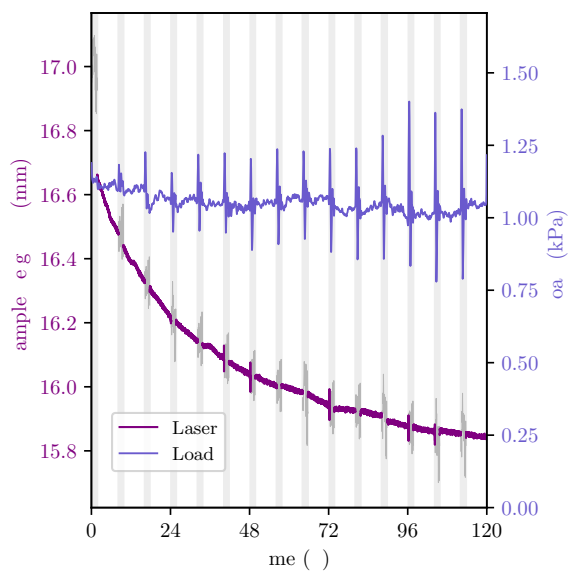
A2 Raw strain rate prefactor for all series

A3 Temporal evolution of the strain rate prefactor

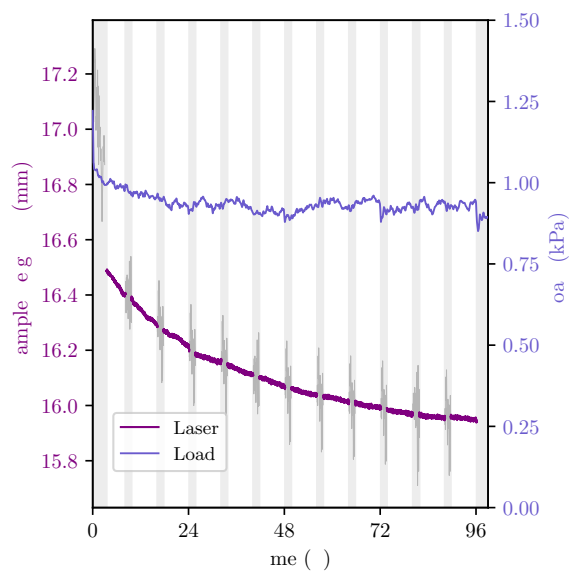
330 *Author contributions.* B.L., L.V. and P.H. developed CellCold. M.Brun, M.Bozon, L.V. and B.L. conducted the experiments and the data processing. L.V. and P.H. interpreted the results and wrote the paper with the input from all co-authors. P.H. and L.V. designed the study.

Competing interests. The authors declare that they have no conflict of interest.

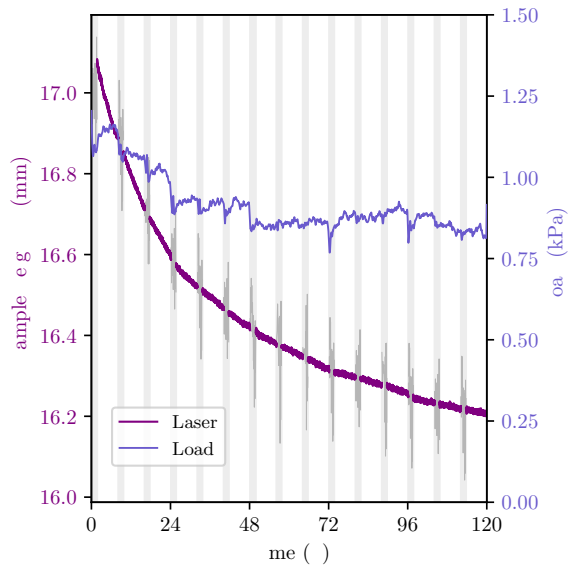
Acknowledgements. CEN is part of LabEx OSUG@2020 (ANR-15-IDEX-02). The tomography apparatus (TomoCold) was funded by INSU-LEFE, Labex OSUG (Investissements d'avenir-ANR10 LABX56) and CNRM. The laser sensor was funded by Région Auvergne-
335 Rhône-Alpes under the CPER MECASNOW program. The authors would like to thank the whole Col de Porte team for their warm welcome. We thank K. Fourteau and O. Dick for fruitful discussions.



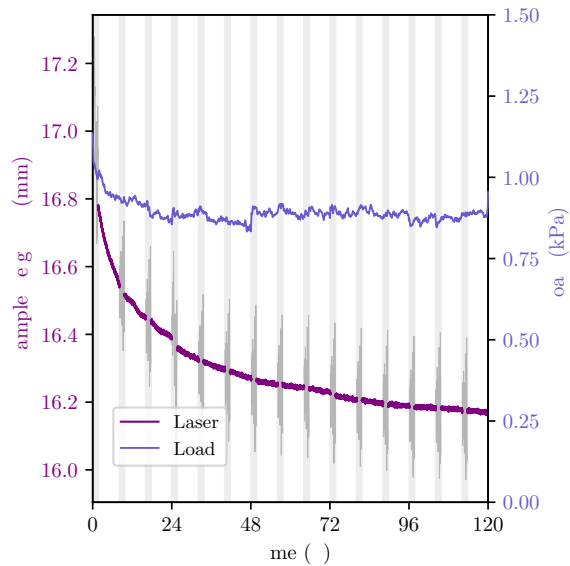
(a) Sample 2



(b) Sample 3



(c) Sample 4



(d) Sample 5

Figure A1. Temporal evolution of the sample height, the applied load, and the sample temperature for for the sample not shown in Fig. 4. Grey shaded areas indicate time intervals affected by X-ray tomographic scans.

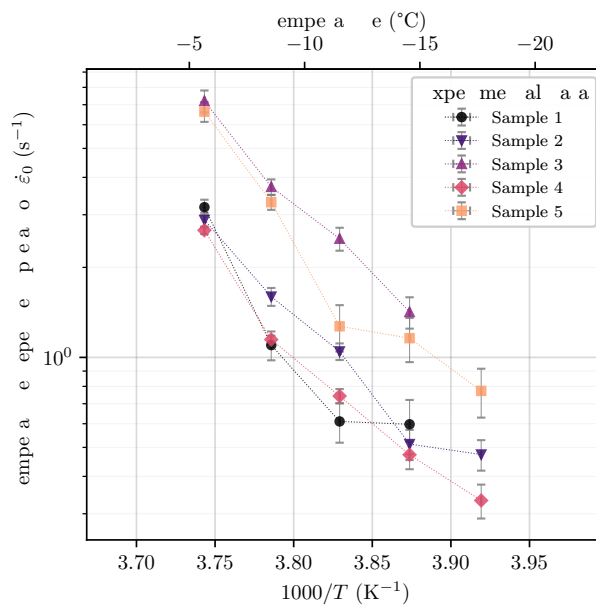


Figure A2. Strain rate prefactor $\dot{\epsilon}_0$ as a function of inverse temperature for all studied samples.

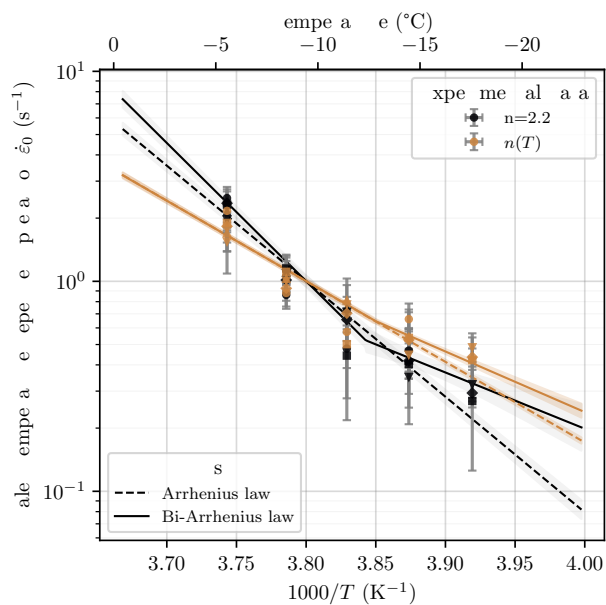


Figure A3. Scaled strain rate prefactor $\dot{\epsilon}_0$ as a function of inverse temperature for all studied samples considering a constant stress exponent and the stress exponent temperature sensitivity proposed by Jones and Brunet (1978).

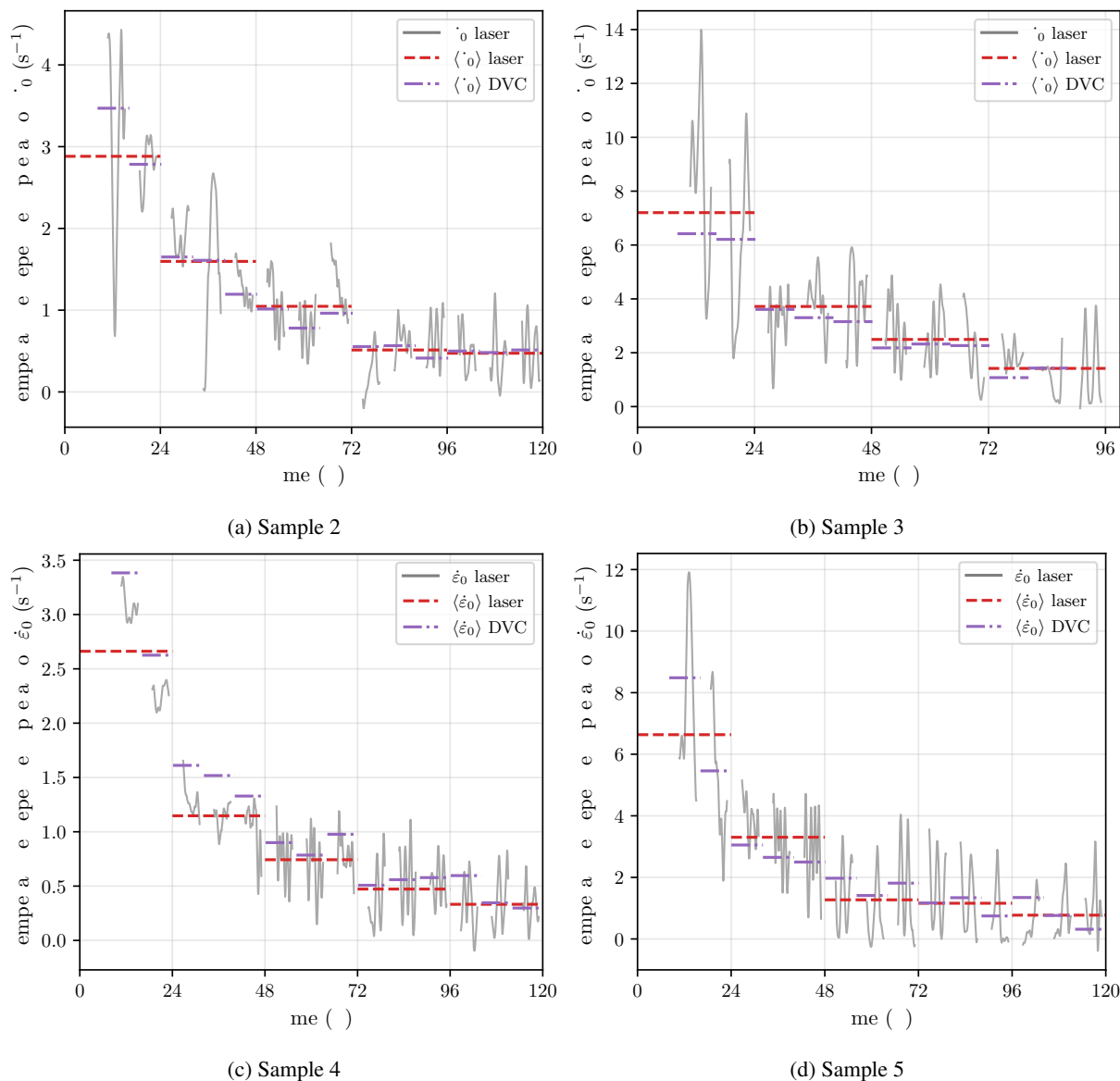


Figure A4. Temporal evolution of the strain rate prefactor $\dot{\epsilon}_0$, computed from laser displacement measurements and DVC.

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