



# 1 **Microbial carbon use efficiency emerges from interactions be-** 2 **tween soil structure and life-history strategies**

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## 10 **Abstract**

11 Microbial carbon use efficiency (CUE) is believed to be a key regulator of the accumulation of persistent soil or-  
12 ganic carbon. Microbial processing of organic carbon in soil occurs in the pore network, the properties of which  
13 are known to affect microbial activity. However, the effects of interactions between pore architecture, and mi-  
14 crobial life-history strategies on carbon dynamics, and how these interactions are modulated by moisture re-  
15 gime, remain poorly understood.

16 Here, we use a spatially explicit model based on a cellular automaton, applied to realistic soil pore networks de-  
17 rived from X-ray tomographic images, to investigate how pore geometry and organic matter distribution shape  
18 microbial dynamics and CUE. The model explicitly represents r- and K-strategists that are either motile or im-  
19 mobile, and have different resource requirements for growth, maintenance and motility. The constraints imposed  
20 on substrate diffusion and the spatial domain in which motile bacteria can effectively disperse by the moisture  
21 regime are explicitly represented in the model, in order to capture how moisture regulate decomposer access to  
22 resources.

23 The simulations show that pore architecture has a significant effect on microbial CUE. Micropores promoted  
24 high CUE and a dominance of K-strategists by limiting substrate diffusion, reducing pore connectivity, and con-  
25 straining microbial access to spatially isolated resources. In contrast, macropores with high connectivity and  
26 greater substrate accessibility favor r-strategists, rapid biomass turnover and lower CUE. Motility emerges as  
27 advantageous in connected, carbon-rich macropores, but energetically unfavourable in confined or poorly con-  
28 nected micropores, where immobile strategies outperform motile ones.

29 Overall, our results indicate that microbial CUE is not an intrinsic property of life-strategies alone, but emerges  
30 from the interaction between microbial life-strategies and pore-scale physical constraints. This study suggests  
31 that soil structure influences microbial strategies by limiting resource availability and dispersal.

## 32 **Introduction**

33 Soil structure refers to the three-dimensional spatial arrangement of solid constituents and voids at different  
34 scales (Rabot et al., 2018). Soil pore space is directly linked to soil functions because it governs air/water  
35 transport and microbial colonization (Kravchenko et al., 2020; Schlüter et al., 2020), which are essential for de-  
36 termining the efficiency of microbial processes and the carbon cycle (Kravchenko and Guber, 2017; Schimel and  
37 Schaeffer, 2012). The size and connectivity of soil pores regulate nutrient diffusion and gas exchange, which can



38 profoundly affect the survival and colonization of microenvironments by microorganisms (Kravchenko and Gu-  
39 ber, 2017; Schlüter et al., 2022). In soil, microorganisms tend to selectively inhabit soil pores of different sizes  
40 (Li et al., 2024). It has been suggested that the properties of the pores in which microbial decomposers are active  
41 influence the rates of OM decomposition and, thus, its persistence (Kravchenko and Guber, 2017; Chenu et al.,  
42 2025); Maestrili et al., 2026). The fate of organic carbon (OC) depends largely on the capacity of the microor-  
43 ganisms present to use the OC and the spatial access they have to the OC (Lehmann et al., 2020; Shi et al., 2021).  
44 The decomposition of OC depends on the encounter between organic matter (OM) and decomposers or their de-  
45 composing enzymes. If this encounter is limited by the structural properties of the microbial environment, de-  
46 composition cannot take place, regardless of the properties of the OM (Dignac et al., 2017).

47 While pores with throat diameters  $< 1 \mu\text{m}$  are generally inaccessible to microbes, due to size exclusion, pores be-  
48 tween 1 and 10  $\mu\text{m}$  can be colonized by microorganisms, depending on their connectivity to the surrounding  
49 pore network. Larger pores ( $> 10 \mu\text{m}$ ) offer more space for microbial colonies and fungal hyphae. Previous stud-  
50 ies suggest that pore size and connectivity influence the distribution of microbial strategies, with fast-growing  
51 copiotrophs often associated with well-connected, resource-rich environments, and slow-growing oligotrophs  
52 dominating in more isolated or resource-limited conditions (Li et al., 2024). However, the extent to which inter-  
53 actions among the physical structure of the pore network, the spatial distribution of resources and the life-cycle  
54 strategies of microorganisms regulate microbial activity and carbon use efficiency is poorly understood. There is  
55 still a lack of mechanistic and spatially explicit understanding of how pore size, resource distribution, and mi-  
56 crobial life-history strategies jointly regulate microbial processing of resources and the resulting carbon dynam-  
57 ics.

58

59 The different microenvironments that occur in the pore network have been classified into according to, among  
60 others, resource availability (Li et al., 2024). The differences in conditions, naturally, exert selective pressures on  
61 the microbial communities which are more adapted to high or low levels of resource availability. The  $r/K$  selec-  
62 tion theory provides a simple and widely used framework for interpreting the dynamics and distribution of soil  
63 microorganisms (Fierer et al., 2007; Peng et al., 2022). While the  $r$ - and  $K$ -selection framework does not capture  
64 the full complexity of microbial life-history strategies (Reznick et al., 2002), it provides a simple and intuitive  
65 way to represent key ecological trade-offs. According to this classification scheme,  $r$ -strategists favour resource-  
66 rich conditions (copiotrophic species) but perform poorly when nutrient availability is low, while  $K$ -strategists  
67 grow more slowly but perform relatively better in resource-poor environments (oligotrophic species) (Fierer et  
68 al., 2007; Gao et al., 2025; Zheng et al., 2024). Therefore, the  $r/K$  selection theory is likely appropriate for this  
69 kind of system.

70

71 Motility is another trait that allows microorganisms to adapt to their microenvironment: the ability to move in the  
72 porous soil environment can confer a selective advantage under certain conditions. Although direct observations  
73 of microbial motility in unsaturated soils remain technically challenging due to the opacity and complexity of  
74 soil (Wang and Or, 2010), several studies indicate that soil moisture and pore network structure control microbi-  
75 al motility by regulating water film continuity and spatial connectivity within the pore space (Barton, 1997;  
76 Chang et al., 2009; Or et al., 2007; Young and Crawford, 2004). In particular, the presence of continuous water  
77 films is necessary for flagellar motility, which limits its expression in dry soils. As motility is energetically cost-



78 ly, its prevalence also appears to be modulated by the availability of organic carbon, an essential resource for  
79 microbial metabolism. Thus, carbon-rich environments, such as rhizospheres, tend to favour motile bacteria, as  
80 evidenced by higher levels of flagellar genes detected in these areas (Ramoneda et al., 2024). Conversely, in  
81 more resource-poor or arid environments, motility is often less prevalent. However, the role of pore-scale geom-  
82 etry particularly pore size distribution and connectivity in modulating the costs and benefits of motility remains  
83 poorly quantified. In particular, it is still unclear how physical constraints and spatial resource heterogeneity in-  
84 teract to determine when motility enhances microbial growth and carbon use efficiency.

85

86 The modelling of soil processes has made great strides due to the development of spatially explicit, mechanistic  
87 approaches that account for the physical structure of soil (Ray et al., 2017; Ritschel and Totsche, 2019; Rötzer et  
88 al., 2025; Zech et al., 2022). However, these models focus primarily on physical heterogeneity and do not always  
89 account for the functional diversity of microbial communities. The integration of realistic soil structure with ex-  
90 plicit microbial ecological dynamics remains a major challenge (Baveye et al., 2011; Otten et al., 2001; Pot et  
91 al., 2021). With some notable exceptions (Allison, 2005) approaches tend to separate these aspects: models fo-  
92 cused on microbial processes often consider homogeneous environments, while models that account for soil het-  
93 erogeneity generally ignore microbial traits and interactions (Panikov, 1999). This disconnection impairs our un-  
94 derstanding of the mechanisms underlying microbial carbon use in structured environments. Here, we use a cel-  
95 lular automaton framework which explicitly represents spatial structure and microbial interactions that are based  
96 on local rules, in order to determine how microbial traits affect C processing under different local environmental  
97 conditions.

98

99 The framework includes distinctive physiological traits for r- and K-strategists, different types of motility, re-  
100 source distributions and moisture regimes. The spatial structure of the environment was derived from X-ray  
101 tomographic images of soil.

102

## 103 **Material and methods**

### 104 **2.1 General principles of the cellular automaton**

105 A cellular automaton is a discrete mathematical model composed of a regular grid of cells, each of which can  
106 adopt a finite number of states. The system evolves over time in synchronous steps, where the future state of  
107 each cell is determined by its current state and that of its neighboring cells, according to a set of predefined tran-  
108 sition rules (Wolfram, 2002). In the context of this study, each cell represents a microscopic spatial unit in which  
109 explicit spatial interactions among microbial cells, as well as between microbial cells and organic substrates, can  
110 occur. The system is based on two coupled matrices of  $100 \times 100$  cells (pixels).

111

112 *The state matrix*, which identifies the nature of each grid cell in the automaton. Eight distinct cellular states are  
113 included, corresponding to different soil components or biological types: (1) solid phase of the soil, (2) air-filled  
114 porosity, (3) water-filled porosity, (4) carbon resources, (5) motile r-strategists, (6) immobile r-strategists, (7)  
115 motile K-strategists, and (8) immobile K-strategists (Table S1).



116 **The resource matrix**, which quantifies the amount of resources associated with each grid cell (when applicable).  
117 This matrix is used to monitor carbon flows in the system. This dual architecture makes it possible to model the  
118 system's structure and resources separately.

## 119 2.2 Construction of the state matrix

120 X-ray micro-tomographic images of a Luvisol (resolution 19  $\mu\text{m}$ ), obtained from the Soil Structure Library  
121 (<https://structurelib.ufz.de/lit/>) in the form of a TIFF image stack, were used to create the state matrix.

122

### 123 2.2.1 Soil images

124 Ten regions (100×100 pixels) were randomly selected from different images of the image stacks. If a region did  
125 not contain any usable pores (i.e., no empty space or, conversely, no solid matter), it was discarded and another  
126 one was extracted. The 10 image regions were thresholded using the Otsu method to separate pores and solid  
127 phases (Smet et al., 2018).

128

### 129 2.2.2 Optimization of pore connectivity

130 Since image resolution tends to obscure the narrower pores and reduce the connectivity of the porous network,  
131 we applied Bresenham's algorithm to the 10 thresholded images in order to establish connections between physi-  
132 cally close but unconnected pores (Bresenham, 1965). This method establishes connections based on the relative  
133 distance, spatial orientation, and surrounding configuration of the pores (Bresenham, 1965).

134

### 135 2.2.3 Pore classification and characterization

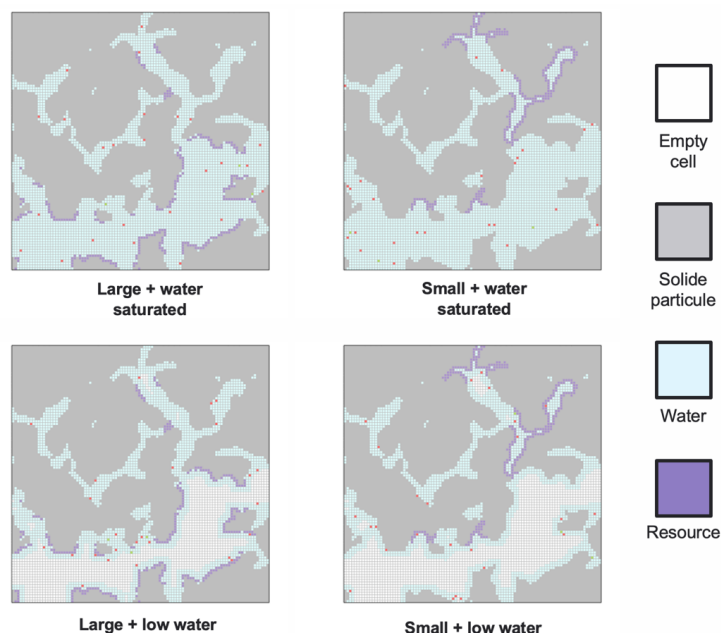
136 The classification and characterization of pores in the thresholded images consisted of a sequence of steps that  
137 began with a morphological erosion to extract the skeleton of the pore network. The pores were then classified  
138 based on the distance between each pixel of the skeleton and the nearest solid phase pixel. Pores for which the  
139 skeleton pixels were at a distance of less than 4 pixels (4 $\mu\text{m}$ ) were considered micropores (small, S). Other pores  
140 were classified as macropores (large, L). The images contained on average  $22.89 \pm 2.13\%$  macroporosity and  
141  $17.09 \pm 1.61\%$  microporosity.

142

### 143 2.2.4 Distribution of resources within the pore network

144 Resources were placed either in small or in large pores (Fig. 1). The resources were distributed so that the con-  
145 centration of resources in each pore size class was the same. The resources occupied 2.83% of the surface area of  
146 the 2D matrix, which is less than what is generally found in soil (5-25% soil volume, refs). However, all the re-  
147 sources were placed in the pore network and were therefore readily available to microbial decomposers, which is  
148 not the case in soil. Generally, <20% is readily available in soil (Bongiorno et al., 2019; Haynes, 2005; McLau-  
149 chlan and Hobbie, 2004). The amount of resources added therefore approximated the amount of readily available  
150 resources found in soils. For this study, each resource cell contained 100 resource units, but additional simula-  
151 tions examined the effect of varying the concentration of resource cells (Fig. S8)

152



153

154 **Figure 1 : Diagram showing the four initial conditions of moisture and resource distribution for a given matrix. The**  
 155 **isolated green and red pixels that are barely visible on the grids represent microbial cells randomly placed at the start**  
 156 **of each simulation.**

157 **2.2.3 Moisture management in matrices**

158 Each matrix was assigned a specific moisture level. Moisture was distributed throughout the pore space by add-  
 159 ing a layer of water pixels next to the solid surface. Further layers of moisture pixels were then added in succes-  
 160 sion until the desired moisture level was reached. This process is akin to morphological dilation and results in the  
 161 narrower pores being filled first. In addition, dilation ensures the connectivity of the pore network from the start  
 162 of the simulations without creating heterogeneity between large and small pores (Fig. 1).

163

164 **2.3 General automaton rules**

165 The cellular automaton model used here is based on a set of deterministic rules applied synchronously at each  
 166 simulation time step, modifying both the state matrix and the resource matrix. In each matrix, only water-filled  
 167 pore grid units, resources grid units and microbial cells can change state. Within a simulation, solid phase grid  
 168 units and empty pores are immutable and represent the inherent constraints of a particular matrix (Fig. 2).

169

170 The resource base of the system is defined at the start of the simulation in the form of resource elements, 100 of  
 171 which is assigned to each resource grid unit. The resource can diffuse from its initial locations in the matrix ac-  
 172 cording to a propagation model that follows Moore's neighbourhood (eight adjacent grid unit) (Zaitsev, 2017).  
 173 This diffusion occurs along concentration gradients, with resource spreading from resource-rich to resource-poor  
 174 zones. Mathematically, the change in the resource content of a resource grid unit at coordinates (x,y) is described  
 175 by the equation  $Resource_{x,y(i+1)} = Resource_{x,y(i)} - \Sigma Resource(i)$ , where i represents the current iteration. At  
 176 each iteration, only cells whose resource content exceeds a minimum threshold (diffusion threshold) can act as



177 donors, preventing very small resource quantities from spreading. The amount of resource transferred to each el-  
178 igible neighbor is not proportional to the concentration gradient but is instead capped by a fixed maximum value  
179 (diffusion rate). As a result, resource-rich cells lose a constant quantity of resource to each less concentrated  
180 neighboring cell, leading to a stepwise and locally asymmetric redistribution process. This mechanism produces  
181 a gradual homogenization of resource distribution across the matrix without reaching instantaneous equilibrium.

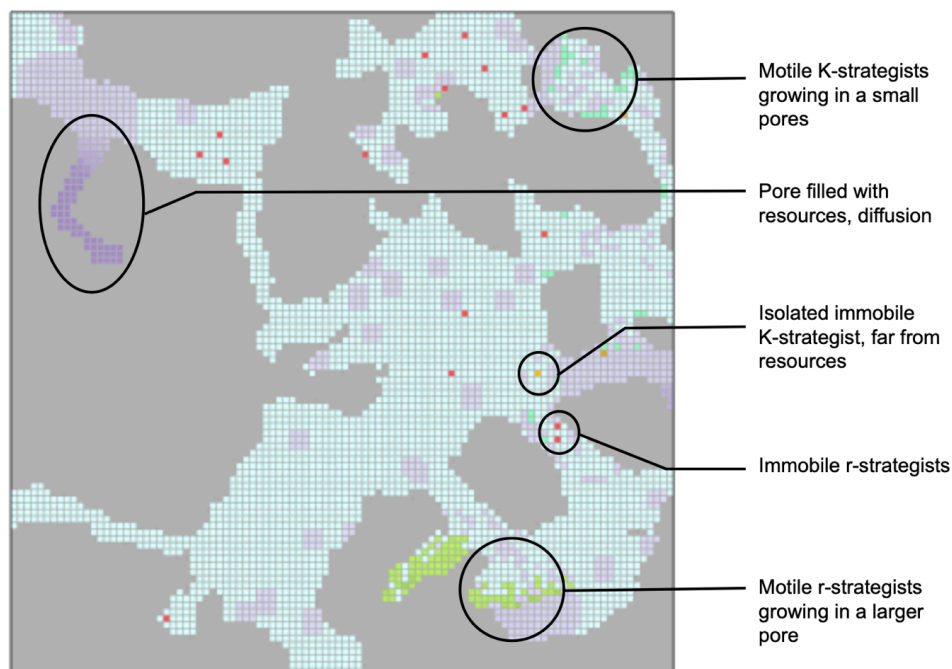
182

183 The different types of microbial cells (Table 1) transition between three states (growth, maintenance or death),  
184 depending on resource availability. The transitions are regulated by three critical resource thresholds. The  
185 maintenance threshold ( $S_d$ ) triggers a state of reduced metabolism when resources become scarce. During  
186 maintenance, cells do not move or reproduce. If the resource scarcity persists and falls below the mortality  
187 threshold ( $S_m < S_d$ ), the microbial cell dies and the remaining resource is transferred to the available resource  
188 pool. Conversely, the accumulation of resource above the reproduction threshold ( $S_r$ ) activates cell division, in  
189 which a new cell of the same type appears in any of the eight adjacent aqueous grid units. The parent cell invests  
190 a significant proportion of its resource (25 to 50% depending on the microbial strategy) in this process according  
191 to the formula  $\text{Resource}(\text{parent}, t+1) = \text{Resource}(\text{parent}, t) - [\text{Resource}(\text{descendant}) + C_r]$ , where  $C_r$  represents  
192 the fixed metabolic cost of reproduction (Table 1). The reproductive costs vary among microbial cell types, the  
193 cost being higher for K-strategists.

194

195 Motile cells can search for and exploit available resources within a configurable perception radius  $R$ . Motile cells  
196 move at a speed of one grid unit per iteration towards the nearest and most resource-concentrated resource grid  
197 unit within their perception radius. Due to the cost of motility, motile cells focus only on resources with a re-  
198 source content above a defined threshold equal to 5 resource elements (Table 1). The cost of motility ( $C_m$ ) is  
199 deducted for each move according to  $\text{Resource}(t+1) = \text{Resource}(t) - C_m$ . The inability of mobile cells to antici-  
200 pate obstacles, such as pore walls, when moving toward the nearest resources introduces a realistic constraint  
201 that limits their effectiveness in complex environments. Immobile cells rely entirely on the diffusion of resources  
202 to acquire the resource and matter necessary for maintenance and growth. This resource acquisition strategy is  
203 energetically more economical, due to the absence of motility costs.

204



205

206 **Figure 2 :** Image taken from one of the simulations showing strategists r and K present simultaneously in the matrix  
 207 (iteration 50). The different colors represent the various states of the cells: light blue for water, gray for the solid  
 208 phase of the soil, purple for resources (with the intensity of the purple indicating the concentration of resources),  
 209 green for mobile cells, and red/orange for immobile cells.

210

211 **Table 1 :** Different cell types present in the simulations, and the associated resource costs and thresholds

Cell type	Motility	Motility cost	Maintenance cost	Dormancy threshold	Mortality threshold	Reproduction cost (Cr)	Reproduction threshold
r-strategist cells	Mobile	1	1	60	30	55	100
	Immobile	0	1	60	30	55	100
K-strategist cells	Mobile	5	3	60	30	70	250
	Immobile	0	3	60	30	70	250

212

213 **2.3 Simulation runs**

214 Four initial matrices were generated for each of the 10 images previously extracted. Each initial matrix was generated with a combination of different moisture levels (saturation or low water) and resource distributions (resources were placed in either large pores or small pores). During the simulations, different microbial densities (low 23 bacterias, and high 56 bacterias) and microbial diversities (r, K and r+K) were applied (Fig. 2). Twenty  
 215  
 216  
 217  
 218  
 219 simulations of 200 iterations were then run on each matrix, resulting in a total of 400 simulations.



#### 220 **2.4 Sensitivity analysis of the model**

221 In addition to the simulations presented above, analyses were performed to establish the sensitivity of the model  
222 to (1) matrix moisture, (2) initial resource concentration, and (3) the parameters governing the r- and K-  
223 strategies. Details of the methods and results obtained for these additional simulations are presented in supple-  
224 mentary data.

225

#### 226 **2.5 Model parametrisation and realism**

227 At the beginning of the simulations, microbial biomass represented between 9.0% (low microbial density) and  
228 16.5% (high microbial density) of total soil organic carbon (SOC). These values were chosen as they are repre-  
229 sentative of the rhizosphere, a highly active soil compartment characterized by elevated microbial densities rela-  
230 tive to total organic carbon (Chunhua Lv, 2022; Zhao et al., 2022). Although microbial biomass is often reported  
231 to represent a smaller fraction of SOC in bulk soils, typically reaching up to ~6% in field measurements (He et  
232 al., 2021), estimates based on fumigation–incubation methods indicate microbial biomass carbon contents rang-  
233 ing from 300 to 1200 mg C kg<sup>-1</sup> in natural silt–clay soils (Franzluebbers et al., 1994; Jenkinson and Powlson,  
234 1976; Sparling and West, 1988), corresponding to approximately 1.5–12% of SOC in soils containing 1–2% total  
235 organic carbon. The values used in the present model therefore fall within, or slightly above, the upper range re-  
236 ported in the literature, consistent with a focus on the rhizosphere rather than bulk soil. Within the model, the use  
237 of relatively high initial microbial densities aimed to ensure the establishment and persistence of microbial popu-  
238 lations over the simulation period, while allowing a representative distribution of different functional types  
239 across heterogeneous microenvironments (pores of varying size and resource availability). Although the model  
240 assumes an identical total amount of carbon between pore types, the differential accessibility generated by diffu-  
241 sion constraints and spatial geometry conceptually reproduces empirical gradients. Cells were initially distribut-  
242 ed randomly in space to avoid imposing predefined spatial advantages among microbial types (mobile vs. immo-  
243 bile) and life-history strategies (r vs. K), thereby allowing differences in colonization dynamics to emerge from  
244 intrinsic traits and interactions.

245

246 In the model, the recycling rate of microbial biomass (cellular resource resource) was set to 100%, meaning that  
247 the entire resource content of dead cells was instantaneously transferred to the pool of assimilable resources.  
248 This assumption implies an immediate decomposition of cellular structures and the absence of a non-assimilable  
249 organic matter compartment. Empirical studies indicate that microbial biomass recycling efficiency in soils is  
250 much lower. Although microbes are able to feed on microbial necromass, recycling efficiencies rarely exceed  
251 12% (Kästner et al., 2021), and microbial necromass can constitute more than half of total soil organic carbon  
252 stocks (Liang et al., 2019). The use of a 100% recycling rate therefore does not aim to represent realistic micro-  
253 bial necromass processing, but rather reflects a deliberate structural simplification of the model. All cellular re-  
254 source is assumed to be potentially accessible to other microbes, corresponding to an idealized and instantaneous  
255 transformation of biomass into assimilable resources. As a consequence, the model accelerates carbon transfor-  
256 mation processes compared to real soil systems and likely overestimates the efficiency and speed of microbial  
257 biomass recycling. This limitation should be kept in mind when interpreting model outcomes.

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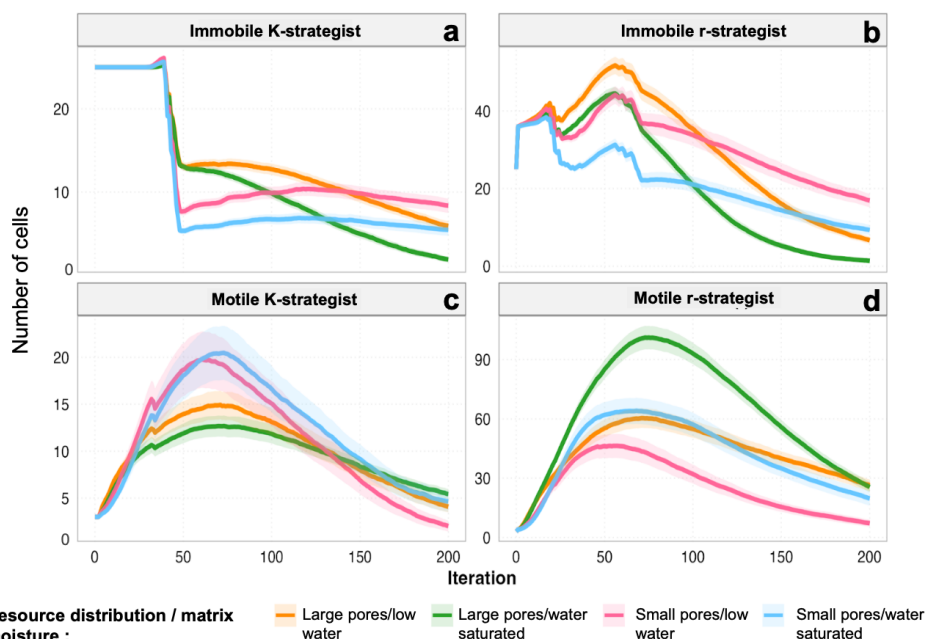
260 **2.6 Statistical analysis**

261 All statistical analyses were performed using R (R: The R Project for Statistical Computing, 2026). The demog-  
262 raphy of microbial populations, their use of resources for maintenance, growth and movement, and the temporal  
263 dynamics of resources were monitored for each simulation. Microbial carbon use efficiency (CUE) was calculat-  
264 ed according to the formula:  $CUE = \text{Resources assimilated (t)} / \text{Resources consumed}$ , with resources consumed =  
265 resources assimilated into biomass + resources released through breathing. This ratio made it possible to assess  
266 the influence of multiple factors on the metabolic efficiency of microbial communities: resource location, water  
267 regime, adaptive strategies and microbial motility. The CUE was calculated for the entire community of cells  
268 present in the matrix at each iteration, and then an average CUE for each simulation was also calculated from the  
269 25th iteration to the end of the simulation, to avoid taking into account the cell installation time during the first  
270 iterations, during which the CUE values were highly unstable.

271 **Results**

272 **3.1 Populations dynamics**

273 The population dynamics profiles of r- and K-strategists (Fig. 3) were similar regardless of the number of micro-  
274 bial cells initially present in the simulation (28 or 56). The mortality of immobile K-strategists was very high  
275 during the first 50 iterations (Fig. 3a) and was directly linked to their initial position in the matrix: if they were  
276 positioned too far from resources, the diffusion rates of resources were not sufficiently high to satisfy their ener-  
277 getic requirements for survival. Compared to immobile K-strategists, immobile r-strategists (Fig. 3b) reproduced  
278 more easily, due to their lower reproduction threshold. As a result, a small population peak was observed be-  
279 tween iterations 50 and 80 (Fig. 3b). Thereafter, resource limitation caused a decrease in population size as cell  
280 death rates surpassed reproduction rates. It is interesting to note that the largest immobile populations were found  
281 in the large pores. However, immobile populations persisted longer in small pores, especially at low moisture  
282 levels. The most unfavourable initial configuration for the persistence of immobile populations over time was  
283 when resources were in large, water-saturated pores.



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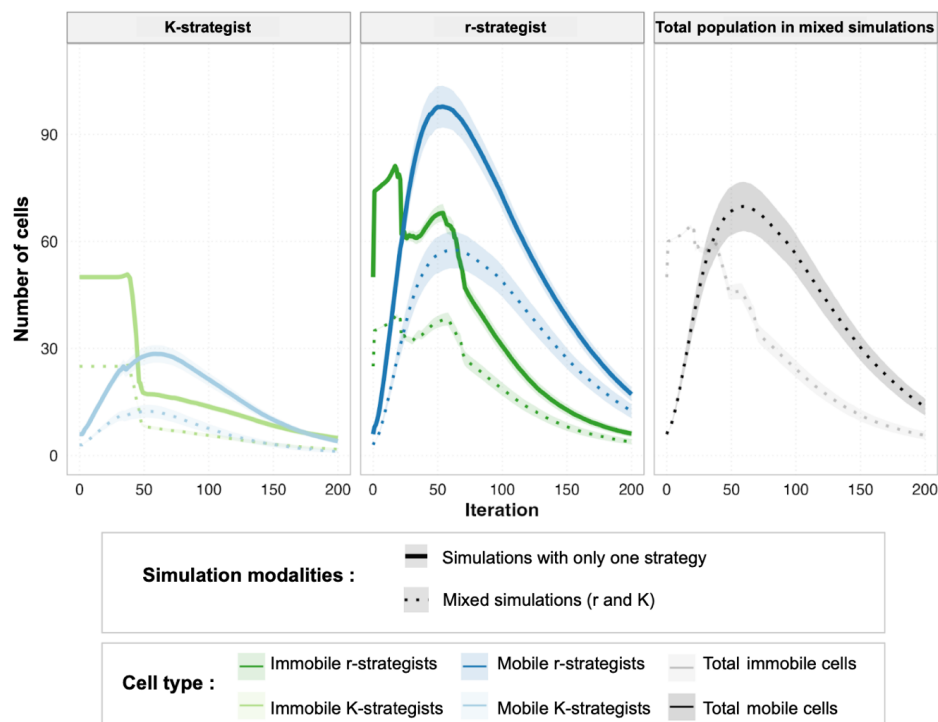
285 **Figure 3 : Number of motile and immobile cells with either r- or K-strategies in simulations with an initial population**  
 286 **size of 56 cells (50 immobile and 6 motile). The results of simulations with initial populations of 28 initial cells were**  
 287 **similar and are available in the supplementary data (Figure S1). The colours refer to the different initial matrix con-**  
 288 **figurations, where, resources were distributed in the large pores (orange and green) or in the small pores (pink and**  
 289 **blue). Matrices were either saturated with water (green and blue) or low water (pink and orange). Note that the y-axis**  
 290 **scales are different.**

291

292 The population dynamics of the motile populations showed an initial increase in size during the first 50 iterations  
 293 (Fig. 3), which was followed by a decrease, as the populations became resource limited. The results observed for  
 294 motile populations differed according to the life strategy: the population of r-strategists increased to over 100  
 295 cells/matrix while the populations of K-strategists remained more modest at fewer than 40 cells/matrix (Fig. 3c).  
 296 The populations of K-strategists reached a maximum when the resources were located in small pores, whereas r-  
 297 strategist populations thrived when resources were in large, water-saturated pores. Neither r- nor K- strategists  
 298 thrived in the other's preferred environments. The least favourable situation for motile r-strategists was when re-  
 299 sources were in small pores with low water content. In this scenario, the environment impeded motility, thus re-  
 300 ducing both the rate at which resources were acquired and the reproduction rate.



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**Figure 4:** Simulations showing the effects of competition between r- and K-strategists. K-strategists, r-strategists and total cell populations in which r-strategists (28 cells) and K-strategists (28) were present together in the same matrix. The solid lines show simulations without competition which correspond to situations with K strategists only (25 immobile and 3 motile) and r strategists only (25 motile and 3 immobile) respectively. The dashed lines show the results of simulations with competition, where r- and K-strategists were both present in the matrices. The grey curve in the third panel is the sum of the immobile K and r cells in the previous two panels. The black curve on the third panel is the sum of moving K and r strategists on the previous two facets.

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Simulations in which both r- and K-strategists were present together showed that competition affected both populations, whether they were motile or immobile, from approximately the 40<sup>th</sup> iteration onwards, resulting in decreases in population size (Fig.4). This was due to resources becoming more limited relative to the needs of the populations. The competitive interactions resulted in r-strategists dominating the matrix. The same general dynamics can be observed with a larger initial cell supply (56 r-strategists and 56 K-strategists) (Fig.S2).

### 3.2 Microbial carbon use efficiency

The CUE differed markedly among microbial strategies and initial community sizes (Fig.5). Overall, communities dominated by K-strategists exhibited higher CUE than either those dominated by r-strategists or mixed communities. The highest CUE values were observed in K-strategist communities with low initial cell densities. In contrast, r-strategist communities consistently showed a lower CUE under comparable conditions (Tukey:  $P < 0.001$ ).



323 Increasing the initial number of cells led to a decrease in CUE for both r- and K-strategist communities, indicat-  
 324 ing a negative effect of initial density on carbon use efficiency. Mixed communities composed of both r- and K-  
 325 strategists exhibited the lowest CUE values across all scenarios. Statistical support for these effects is provided  
 326 in Fig. S3.

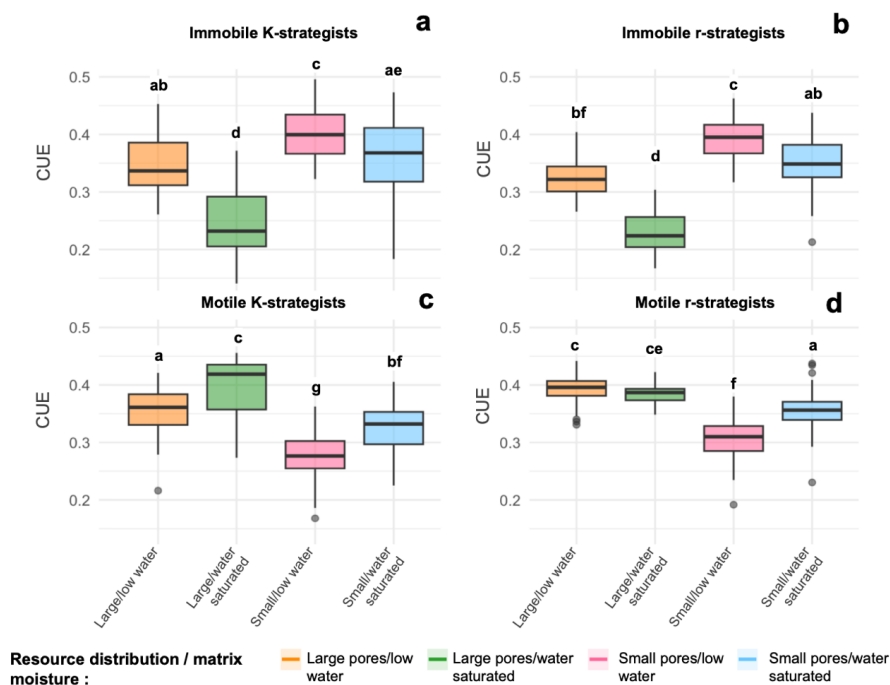
327

328 In addition to the effects of metabolic strategy and the initial cell numbers, the location of resources in specific  
 329 pores also had significant effects ( $F=101.53$ ;  $P<0.001$ ), as did microbial cell motility ( $F=138.89$ ;  $P<0.001$ ) and  
 330 their interaction ( $F=328.03$ ;  $P<0.001$ ).

331 Firstly, higher CUE values ( $0.40\pm 0.04$  for K cells and  $0.39\pm 0.04$  for r cells) were always obtained for immobile  
 332 cells under low water conditions. The next highest, but significantly lower (Tukey:  $P<0.001$ ), CUE values were  
 333 obtained when resources were in water saturated small pores ( $0.36\pm 0.07$  for K cells and  $0.35\pm 0.04$  for r cells).

334 When the resources were in large pores, immobile cells showed the lowest CUE, in particular under water-  
 335 saturated conditions ( $0.24\pm 0.04$  for K cells and  $0.23\pm 0.02$  for r cells).

336



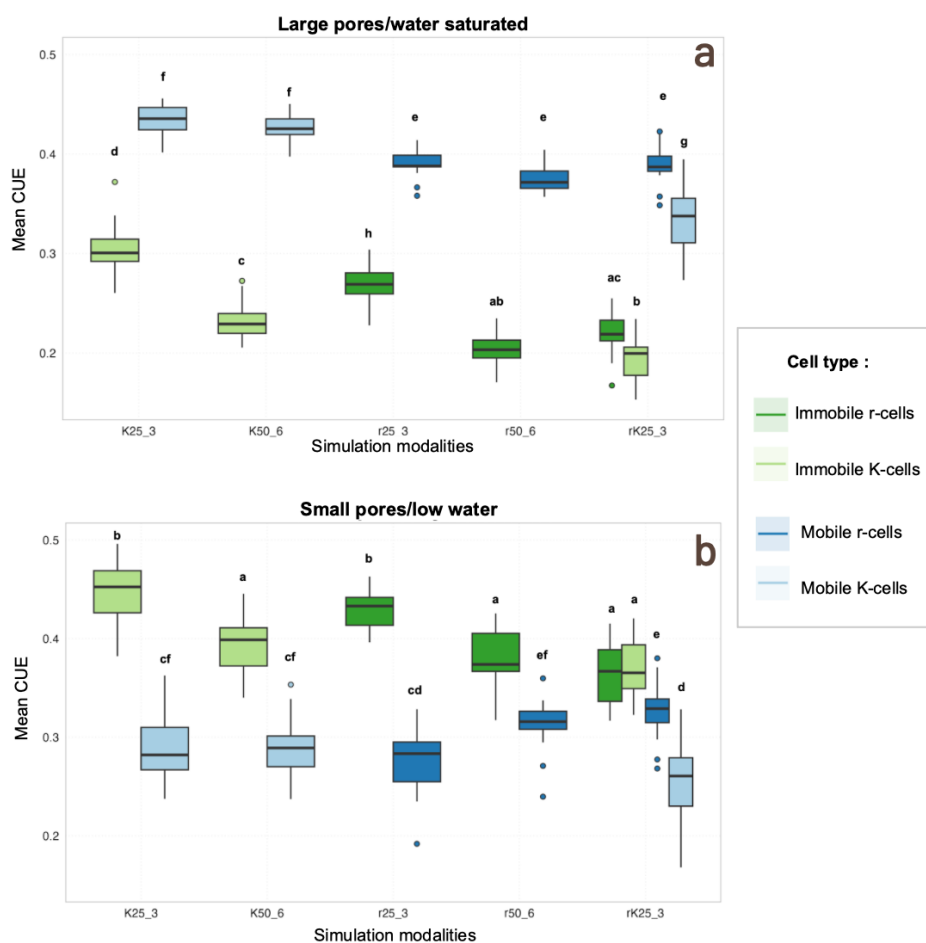
337

338 **Figure 5 : Panel graph showing average CUE for each different cell type.** Average CUE values were calculated from  
 339 the 25th iteration onwards, in order to avoid the uncertainty associated with the population fluctuations at the begin-  
 340 ning of the simulations. This analysis takes into account the 5 initial scenarios with r- and K-strategists separately for  
 341 the two initial cell densities (28 and 56), as well as the mixed scenario with r- and K-strategists present together in the  
 342 simulations. The colours used refer to the different initial matrix configurations. In orange and green, resources are  
 343 distributed in the large pores, and in pink and blue, resources are distributed in the small pores. Green and blue refer  
 344 to matrices saturated with water, and pink and orange to matrices with a one-pixel water film covering the solid phase  
 345 of the soil and the resources. Letters on the figure refer to statistical differences between groups (Tukey).

346 The motile cells with the largest CUE were observed in the large pores (Fig.5). In the case of motile K-  
 347 strategists, these are large, water-saturated pores (CUE =  $0.49\pm 0.05$ ), while in the case of motile r-  
 strategists,



348 large pores, whether water-saturated or not, are indifferently associated with the highest CUE (Tukey:  $P=0.50$ ).  
 349 Also in contrast to what was described for immobile cells, small pores are the most constraining for the CUE of  
 350 motile cells, with the lowest CUE particularly in small pores with low water content (CUE =  $0.28 \pm 0.04$  for K-  
 351 strategists and CUE =  $0.31 \pm 0.04$  for r cells).  
 352  
 353



354  
 355 **Figure 6 :** Graphical panel showing the mean CUE in all the different initial matrix configurations, resources distrib-  
 356 uted in large pores or small pores with or without water saturation. Colours refer to the different cell types present in  
 357 the matrices. K25\_3 and K50\_6 correspond to situations with K strategists only (25 immobile K cells and 3 motile K  
 358 cells or 50 motile K cells and 6 immobile K cells respectively). r25\_3 and r50\_6 correspond to situations with r  
 359 strategists only (25 immobile r cells and 3 motile r cells or 50 motile r cells and 6 immobile r cells respectively). rK25\_3  
 360 show the results of simulations with competition, where r and K cells have been added jointly to the matrices (25 im-  
 361 mobile K cells and 3 motile K cells with 25 motile r cells and 3 immobile r cells). The letters correspond to the statisti-  
 362 cal groups given by a Tukey analysis, for each panel graph, the groups have been calculated separately.

363 The simulations with both r and K strategists enabled us to determine the effect of competition between the dif-  
 364 ferent cell types on CUE. Increasing the initial cell density significantly reduced CUE, the strategy of the cells



365 also had a significant effect, with K-strategists having higher CUE values. The K-strategist cells were more sen-  
366 sitive to the presence of r-strategists. In contrast, the CUE of r-strategists was less sensitive to the presence of K-  
367 strategists in the matrices. This competitive effect is largely modulated by the initial conditions of the matrices,  
368 the size of the resource distribution pores, but also humidity (Fig.6).

369

370 The results show that the initial configurations of the matrix had different effects on the cells; the two most dis-  
371 tinct configurations were one in which the pore network was saturated with water, with resources distributed on-  
372 ly in the large pores (Fig. 6b), and one in which water was limited and resources were found only in the small  
373 pores. When the pore network was water-saturated and resources were only in large pores (Fig. 6b), motile cells  
374 r were not affected by increasing cell density in the initial state (Tukey:  $P=0.32$ ), nor by competition with motile  
375 cells K in the mixed situation (Tukey:  $P=0.99$ ). However, this was not the case for motile K-strategists, whose  
376 CUE was negatively affected when there were motile r-strategists in the matrix (Tukey:  $P<0.001$ ). In the case of  
377 immobile cells, r-strategists were affected at greater initial cell densities (Tukey:  $P<0.001$ ), regardless of  
378 whether these were r- or K-strategists (Tukey:  $P=0.36$ ). The CUE of immobile K-strategists was reduced when  
379 the initial number of K-strategists was high (Tukey:  $P<0.001$ ), and reduced further when in the presence of r-  
380 strategists (Tukey:  $P<0.001$ ).

381

382 When resource was in small pores in low water conditions (Fig. 6c), the CUE of r-strategists was unaffected by  
383 the increase in initial cell density (Tukey HSD:  $P=0.001$ ), and did not differ from the CUE of K-strategists (Tuk-  
384 ey:  $P=0.98$ ). The effects were different for motile K-strategists, whose CUE was not affected by high initial den-  
385 sities of K-strategists (Tukey:  $P=0.99$ ), but were affected when in the presence of motile r-cells (Tukey:  
386  $P<0.001$ ). As far as immobile cells are concerned, the effects were identical for both cell strategies, with the  
387 CUE lowered by higher initial cell densities, regardless of their identity.

388

## 389 Discussion

### 390 4.1 Accuracy of the collected data

391 The population dynamics observed for motile cells, which were characterized by rapid growth following re-  
392 source inputs, high turnover, and strong temporal fluctuations are consistent with rhizosphere population dynam-  
393 ics described in the literature (Darrah, 1991; Newman and Watson, 1977). We observed that microbial growth  
394 was limited by the supply of organic substrate, so an increase in microbial cell populations is associated with  
395 greater consumption of available resources in the environment, led to resource limitation and subsequently to the  
396 collapse of microbial populations. In the case of immobile cells, the population dynamics observed were more  
397 dependent on competition with motile cells for resources.

398

399 Although all cells are assumed to be the same size (1 pixel = 1  $\mu\text{m}$ ), they differ in their ability to accumulate re-  
400 sources, with K-strategists having higher reproduction thresholds. Consequently, these cells incur higher overall  
401 costs related to maintenance, motility and reproduction. To study the impact of these trade-offs, we ran supple-  
402 mentary simulations in which these costs were assigned arbitrarily so that we could observe the effect of simple  
403 variations allowing us to assess how differences in resource allocation influence microbial dynamics in a porous



404 space (Fig. S4). This modeling approach is consistent with theoretical predictions that the various costs associat-  
405 ed with cellular life (motility, maintenance, reproduction) are closely linked to cell size (Kempes et al., 2017). In  
406 particular, motility depends heavily on cell size, and below a critical volume, directed motility is assumed to be  
407 inefficient and therefore absent (Dusenbery, 1997). When occurring in small microorganisms, motility can repre-  
408 sent an energy cost comparable to, or even greater than, maintenance costs (Kempes et al., 2017).

409 Although few studies explicitly quantify the allocation of resources among these different expenditures, our pa-  
410 rameterization yields microbial carbon use efficiency (CUE) values ranging from 0.28 to 0.78, which corre-  
411 sponds to values reported in the literature (He et al., 2024; Jones et al., 2018; Schnecker et al., 2023). Note that  
412 the CUE values reported for oligotrophic communities (up to 0.72; Ma et al., 2023) exceed our estimates, which  
413 probably reflects the simplifications inherent to our approach.

414

#### 415 **4.2 Influence of pore size and connectivity on microbial access to and microbial utilization of carbon**

416 The model results suggest that the CUE of microorganisms is largely determined by the pore environment. It has  
417 already been shown that organic matter turnover varies across different soil pore sizes (Chenu et al., 2025; Li et  
418 al., 2024; Maestrali et al., 2026; Pfeiffer et al., 2001; Xia et al., 2022) because the microbes that dominate in  
419 these different pore sizes have strategies that are adapted to their microenvironment such as fluctuations in hu-  
420 midity (Ceriotti et al., 2022; Kravchenko et al., 2020), available space (Chenu et al., 2001; Gupta and Germida,  
421 1988), nutrient availability (Bouckaert et al., 2013) and predation pressure (Erktan et al., 2020; Wright et al.,  
422 1995). This study suggests that the geometry of the pores themselves selects the microbes capable of colonising  
423 the environment. Indeed, when confined in micropores, organic matter is physically protected not only through  
424 exclusion by pore size, but also due to pore tortuosity, which modulates both substrate diffusion and microbial  
425 access. In our simulations, we observed that even when motile cells were close to small pores, their effective ac-  
426 cess to resources was limited by the tortuosity of the pore network. Although motile bacteria are capable of de-  
427 tecting chemical gradients, the establishment and continuity of these gradients depend on the connectivity of the  
428 pores and the continuity of the water film. In highly tortuous or poorly connected pore networks, chemical gradi-  
429 ents can be weak, discontinuous, or spatially misleading, limiting the ability of motile cells to effectively reach  
430 nearby resource areas. For example, a flagellated bacterium may not effectively reach an organic matter particle  
431 located just a few micro-meters away if the accessible pathways are long or disconnected, whereas a non-motile  
432 bacterium already positioned nearby can exploit the resource via diffusion without incurring the energy cost of  
433 motility. These results are consistent with previous studies showing that tortuosity significantly influences bacte-  
434 rial mobility by increasing the complexity of the paths that bacteria must follow in porous media, thereby reduc-  
435 ing their effective diffusion and transport rates. Using magnetic resonance imaging, it has been shown that the  
436 swimming behavior of bacteria such as *Pseudomonas putida* is strongly impeded by the pore structure (Olson et  
437 al., 2005). Bacterial motility patterns, particularly path lengths and turning angles, interact with surface adhesion  
438 in porous media, further increasing apparent tortuosity and affecting bacterial movement (Narayanaswamy et al.,  
439 2009). Experimental and modeling studies demonstrate that smaller pores and more tortuous paths reduce the  
440 average free-swimming distances of bacteria, hindering their self-propulsion (Dehkharghani et al., 2023; Duffy  
441 et al., 1995).

442 This mechanistic framework demonstrates that physical constraints at the pore scale alone can shape microbial  
443 activity and carbon use efficiency, independent of microbial size variation.



444

445 This work reveals the water regime (low water or water-saturated) modulates the influence of pore size on mi-  
446 crobial communities. Under conditions with low water and organic matter in the macropores, motile cells  
447 achieve a higher CUE, suggesting that water creates connected pathways without completely restricting motility.

448 This configuration allows motile cells to access resources while experiencing fewer diffusional constraints: re-  
449 sources diffuse only in the available water film and are therefore less ‘diluted’ compared to a situation where  
450 pores are completely saturated with water. Our simulations suggest that r-strategist populations, characterized by  
451 their rapid growth, exploit this situation particularly well by efficiently colonizing accessible surfaces.

452

### 453 **4.3 Microbial motility as a competitive advantage depending on/across soil pore architecture**

454 The simulations suggest that motility does not universally confer a competitive advantage, but instead leads to  
455 contrasting outcomes depending on pore-scale environmental conditions. In well-connected, carbon-rich envi-  
456 ronments, motile cells benefit from increased access to spatially distributed resources, resulting in higher growth  
457 and competitive success. In contrast, in poorly connected or resource-limited environments, the energetic costs  
458 associated with motility reduce carbon allocation to growth, leading to lower CUE compared to immobile strate-  
459 gies. This trade-off reflects the additional biosynthesis, repair, and operating costs associated with flagellar mo-  
460 tility (Kempes et al., 2017), and is consistent with experimental observations showing reduced growth under car-  
461 bon limitation when motility is constitutively expressed (Lisevich et al., 2025). Here, we show that pore-scale  
462 physical constraints modulate this trade-off, determining when motility enhances or limits microbial efficiency.

463

464 The architecture of pore networks fundamentally alters microbial movement and the advantage of motility. In  
465 fully saturated macropores, bacteria can exhibit efficient ‘run-and-tumble’ movements with long ballistic trajec-  
466 tories (Zhang et al., 2024). In contrast, in micropores, physical confinement forces motile cells to adopt a less ef-  
467 ficient ‘swim-and-stop’ or ‘jump-and-trap’ movement, significantly eroding the advantages of motility. The  
468 chemotaxis machinery further amplifies these resource costs (for substrate detection, cilia or flagella movements,  
469 etc.), reducing the net CUE (van Albada et al., 2009; Hoffmann et al., 2017). In this context, the relationship be-  
470 tween motility and carbon distribution is crucial. As this study demonstrates, motile bacteria have maximum  
471 CUE when organic matter is located in macropores, where chemotactic movement towards carbon gradients is  
472 optimal. When organic matter is confined to micropores, the motility advantage decreases significantly because  
473 bacteria cannot physically access these areas. In direct contrast, in our simulations, sessile bacteria dominate in  
474 micropores, maximising CUE by minimising motility-related costs (13–19% of the cellular resource budget in  
475 our models) and redirecting resources towards stress tolerance and growth efficiency. Indeed, in low-  
476 connectivity environments, Jin and Sengupta, (2024) observe that passive dispersal (expansion through growth,  
477 attachment to motile vectors) can surpass active motility in resource efficiency, explaining the good performance  
478 of immobile microbes when organic matter is confined to micropores. Thus, since the prevalence of bacterial  
479 flagellar motility is strongly associated with soil carbon accessibility (Ramoneda et al., 2024), cell motility  
480 should be particularly associated with a copiotrophic lifestyle, which explains the large populations observed in  
481 the case of motile r-strategists with resource distribution in the largest pores. Ultimately, the environmental de-  
482 pendencies observed (pore size, moisture) suggest that microbial communities are evolving towards motility pat-  
483 terns optimised for their specific environments. Microbial motility is not universally advantageous, but rather



484 represents a finely tuned adaptation to the interaction between pore architecture, carbon heterogeneity and re-  
485 source trade-offs, with cascading effects on the carbon cycle at the ecosystem scale. Furthermore, under favour-  
486 able moisture conditions, active cell motility plays a key role in the early colonisation process: Bacterial com-  
487 munities with cellular motility are pioneers and often the first to colonise new surfaces, followed by other bacte-  
488 ria with other functional traits (Wang et al., 2025), leading to the colonisation of new microenvironments in the  
489 soil.

490

#### 491 **4.4 Influence of pore size on the selection of microbial strategies (r or K)**

492 The simulations show that pore architecture fundamentally structures microbial ecological strategies. It is known  
493 that micropores constitute preferential niches for oligotrophic taxa (Acidobacteriales, Frankiales, Firmicutes)  
494 specialised in the processing of complex carbon compounds (Li et al., 2024). These organisms have specific  
495 morphological adaptations, reduced cell sizes and filamentous shapes, that maximise nutrient absorption under  
496 resource-limited conditions (Chen et al., 2022).

497

498 Our simulations indicate that the environment, and in particular pore architecture, can strongly modulate the in-  
499 fluence of life cycle parameters on carbon use efficiency (CUE). While r and K strategies represent well-  
500 established ecological archetypes (Pianka, 1970; Li et al., 2024), the conditions under which they maximise CUE  
501 are not universal but depend heavily on pore size and cell motility. Using a spatially-explicit model, our study  
502 shows that in large pores, maintenance cost emerged as the dominant parameter, influencing CUE outcomes dif-  
503 ferently for motile and immobile cells (Fig. 5). In small pores, the reproduction threshold played a central role.  
504 These results indicate that the effect of each parameters cannot be dissociated from the environmental context:  
505 the same parameter can improve CUE under certain pore conditions while limiting it under others (such as re-  
506 production threshold). Similar results have been reported in microbial ecology, where the spatial heterogeneity  
507 of soil pores is recognised as a determining factor in microbial metabolic strategies (Nunan et al., 2020; Portell et  
508 al., 2018).

509

510 Carbon distribution in the soil pores network appears to be the main mechanistic link between pore size and the  
511 selection of microbial strategies. Chen et al., (2022) showed that carbon-rich rhizospheric soils favour copi-  
512 otrophs, while poor environments select oligotrophs, which accentuates contrasts in resource availability be-  
513 tween microsites. The microarchitecture of pores induces marked biogeochemical gradients over a few microme-  
514 tres: Li et al., (2024) measured significant variations in oxygen, water film thickness and diffusion between pore  
515 classes, with macropores exhibiting more dynamic physicochemical conditions, while micropores maintain more  
516 stable but resource-poor environments. This trade-off between stability and availability is a fundamental axis for  
517 sorting ecological strategies, with r-strategists exploiting large, variable but rich pores, and K-strategists special-  
518 ising in small, stable but limited pores. These spatio-temporal dynamics are also consistent with the phenomenon  
519 described by Zelenev et al., (2000) in the BACWAVE model, which simulated ‘bacterial waves’ generated by  
520 the movement of a nutrient pulse and translated into spatial waves of microbial growth and mortality along roots.  
521 Similarly, our model highlights a similar phenomenon where motile cells, particularly r-strategists, move along  
522 resource gradients formed on pore walls, producing wave-like dynamics of colonisation and consumption com-  
523 parable to those observed empirically in the rhizosphere.



524 Our cellular automaton succeeds in reproducing several well-documented mechanisms of soil microbial ecology,  
525 such as the trade-offs between r and K strategies, the contrasted dynamics between motile and immobile cells,  
526 and the strong selective role of pore architecture on CUE. This convergence between model outputs and empiri-  
527 cal knowledge highlights the potential of minimalistic, mechanistic approaches to capture emergent ecosystem  
528 patterns without requiring a high degree of parametrization. By making explicit the links between cellular traits,  
529 spatial constraints and carbon cycling, our framework provides a transparent testbed for exploring hypotheses  
530 that are difficult to address empirically at the microscale. Beyond confirming the relevance of r and K arche-  
531 types, our results pave the way for extending the model towards a broader trait-based framework, such as the Y-  
532 A-S triangle (Fig. S15) (Ho et al., 2013; Malik et al., 2020), in order to represent the continuum of microbial  
533 strategies observed in soils. This perspective opens promising avenues for coupling simple agent-based ap-  
534 proaches with empirical measurements, ultimately contributing to a better mechanistic understanding of how mi-  
535 crobial diversity and soil structure jointly shape the fate of carbon in terrestrial ecosystems.

536

537

## 538 **Conclusion**

539 This study employed a spatially explicit model to investigate how soil pore architecture, resource distribution,  
540 moisture and the life cycle characteristics of microorganisms jointly regulate microbial dynamics and carbon use  
541 efficiency. The results suggest that the physical structure is an active factor in microbial functioning, influencing  
542 both resource access and the outcome of ecological trade-offs.

543 Our results highlight that pore size and connectivity exert a dominant control over microbial carbon use efficien-  
544 cy (CUE), often surpassing the influence of intrinsic physiological parameters. In particular, heterogeneity at the  
545 pore scale determines whether traits such as motility confer a competitive advantage or become energetically  
546 detrimental. Motility emerges as a context-dependent strategy, beneficial in well-connected, resource-rich envi-  
547 ronments but disadvantageous under high spatial constraints or limited resource accessibility. Similarly, the per-  
548 formance of r- and K-strategies is not fixed but dynamically modulated by the spatial distribution of carbon and  
549 the physical accessibility imposed by pore networks. Beyond confirming established ecological patterns, our  
550 model reveals that microbial functioning cannot be understood without explicitly accounting for the interaction  
551 between spatial structure and trait trade-offs.

552 Our model supports the use of minimalist yet mechanistic approaches as powerful tools for bridging the gap be-  
553 tween pore-scale processes and the ecosystem-scale carbon cycle. However, several limitations must be  
554 acknowledged. The assumption of complete and instantaneous recycling of microbial biomass, as well as the  
555 simplified representation of microbial traits, likely leads to an overestimation of carbon turnover rates. Future  
556 developments should aim to incorporate more realistic representations of necromass dynamics, the effect of min-  
557 eral surfaces, and a broader continuum of microbial strategies. By explicitly linking pore geometry and microbial  
558 ecology, this work offers a new conceptual framework for improving our understanding of the carbon cycle at  
559 the fine scale.

560

561

562 **Code availability**



563

564 **Data availability**

565 The Python and R code used to run the cellular automaton is available on request. The data and the R code used  
566 for statistical analysis are also available on request.

567

568 **Author contributions**

569 MM: Conceptualisation, data curation, formal analysis, methodology, visualisation, writing ; XR: Conceptualisa-  
570 tion, methodology, validation, writing (review and editing); NN: Writing (review and editing), validation, super-  
571 vision; HW: Conceptualisation, validation ; NN: Writing (review and editing), validation, supervision; ASR : da-  
572 ta curation, formal analysis, visualisation.

573

574 **Competing interests**

575 The authors have no competing interests to declare.

576

577

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579 This article is part of the special issue “Advances in dynamic soil modelling across scales”. It is not associated  
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