

1 **Review article: Harnessing data-driven methods for climate multi-** 2 **hazard and multi-risk assessment**

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17 **Abstract.** In recent years, interest in data-driven methods, such as machine learning and multivariate statistics for multi-hazard
18 and multi-risk assessment has surged, due to their ability to integrate vast amounts of data in modelling complex non-linear
19 relationships between hazard and risk factors. This review explores data-driven methods in climate multi-hazard and risk
20 assessment, focusing on four themes: (i) data processing and collection; (ii) hazard identification, prediction and analysis; (iii)
21 risk assessment; and (iv) future risk scenarios under climate change. Key findings highlight the extensive use of machine
22 learning to combine Earth observations and climate data for downscaling and land use and land cover characterisation; the
23 application of deep learning for hazard prediction; the use of ensemble methods for risk assessment; and the growing emphasis
24 on explainable AI frameworks. Supervised machine learning approaches trained on historical impact data to project future
25 climate risks have also emerged as a significant research area. Future research in this area should focus on modelling multi-
26 hazard interactions, particularly triggering and cascading effects, integrating dynamic vulnerability and exposure factors, and
27 addressing uncertainties associated with using machine learning for extrapolation. Advancements in Earth observations and
28 textual data integration, alongside the development of open-access disaster catalogues, will also be crucial for improving multi-
29 risk assessments and supporting AI-driven early warning systems tailored to regional needs.

30 **1 Introduction**

31 The growing interconnectedness between socio-economic and natural systems, coupled with the escalating challenges
32 presented by climate change, has led to increased complexities in climate risk analysis. At the same time, a wider availability
33 of data on multiple risk drivers, including weather observations, Earth observations (EO), climate reanalyses and projections,
34 socio-economic indicators, and social media, coupled with advances in machine learning (ML) and statistical methods, are
35 increasing the potential of data-driven methodologies, which promise to revolutionise climate risk assessment (Kashinath et
36 al., 2021; Reichstein et al., 2019). To unlock the full potential of this data, it is crucial to develop and apply advanced methods
37 for processing, harmonizing, and integrating heterogeneous datasets. These efforts enable the generation of actionable insights
38 essential for effective multi-hazard and multi-risk assessments, by leveraging the accessibility of large datasets to be explored
39 with advanced ML and statistical techniques.

40 Complex dynamics characterize socio-environmental and climate risk: applications may underestimate impacts if they do not
41 take into account the compounding, cascading and amplifying interactions of hazards and their effect on vulnerability and
42 exposure factors. In fact, (i) compounding hazards (co-occurring in the same location and at the same time) can lead to impacts
43 which may be substantially higher than the sum of the single events taken in isolation (Arosio et al., 2020; Zscheischler et al.,
44 2018), (ii) the occurrence of one hazard itself can modify vulnerability or resilience of the system, exposing assets or
45 communities to higher risks, such as in the case of consecutive hazards (de Ruiter & van Loon, 2022), and (iii) impacts and
46 risks can propagate across multiple scales and sectors, extending far beyond the area initially hit and affecting whole systems
47 (Arosio et al., 2021; Pescaroli & Alexander, 2018), such as in the case of high-impact and low-probability events (Linkov et
48 al., 2022). For these reasons, the international community (Intergovernmental Panel on Climate Change (IPCC), 2023;
49 UNDRR, 2020) has recently pledged for a paradigm shift from single hazard towards a more comprehensive representation of
50 multiple and interconnected climatic risks (AghaKouchak et al., 2020; De Angeli et al., 2022; Gallina et al., 2020; Šakić
51 Trogrlić et al., 2024; Terzi et al., 2019; Tilloy et al., 2019; Ward et al., 2022). To achieve this shift, it is essential to develop
52 data-driven methodologies that can analyse and predict the interactions and dependencies between multiple hazards, enabling
53 a more accurate characterisation of their compounding and cascading effects.

54 To better navigate the many definitions surrounding multi-hazard risk concepts, this paper adopts the terminology used in
55 Zschau (2017), where *multi-layer single hazards* refers to applications focussing on more than one hazard, without considering
56 hazard interactions; *multi-hazard* focuses on hazards interaction; *multi-hazard risk* refers to applications considering risks in
57 a multi-hazard framework, without discussing interactions at vulnerability level, and finally *multi-risk* refers to the most
58 complex analysis comprising interactions at both hazard and vulnerability level.

59 The complex nature of multi-hazard events presents significant challenges to existing risk assessment methodologies, which
60 treat hazards and risks singularly and often struggle to handle the non-linear interactions and feedback loops between multiple
61 risk drivers (Tilloy et al., 2019). ML techniques have recently gained traction in climate science and risk analysis for their
62 ability to process and integrate large, heterogeneous datasets from sources such as weather observations, Earth observations,

63 climate reanalyses and projections, socio-economic indicators, and even social media. By learning from historical data, they
64 can uncover non-linear risk patterns and detect correlations across spatial and temporal scales, driving their growing use in
65 climate risk assessment (Reichstein et al., 2019; Zennaro et al., 2021).

66 Integrating these heterogeneous data sources can help in capturing multi-hazard interactions and characterise their impacts on
67 social, economic, and natural systems, especially thanks to the introduction of new Deep Learning (DL) architectures and
68 models, specialized in capturing both spatial and temporal non-linear interactions (S. Park et al., 2023). As ML models have
69 become more complex, attention has shifted toward making these models more interpretable and explainable (Carvalho et al.,
70 2019). This is especially important for applications focussing on risk, where it is crucial to quantify the contribution of each
71 input feature to the model's prediction, making it easier to assess how different risk variables impact the overall risk. In this
72 context, explainability frameworks improve the robustness of risk assessments and enhance trust in the model's outputs by
73 providing insights into how the model arrives at specific conclusions (S. Jiang et al., 2024; McGovern et al., 2019), supporting
74 transparency and accountability for stakeholders.

75 In addition to ML methods, this review briefly considers the role of copulas as multivariate statistical tools in multi-risk
76 assessment. Copulas enable explicit modelling of the dependence structure between variables, making them particularly
77 valuable for analysing compound events in which multiple hazards occur simultaneously or sequentially (see, for example,
78 Agrawal, 2022; Hochrainer-Stigler et al., 2019). They have, for instance, been used to characterise the joint occurrence of
79 droughts and heatwaves, yielding insights into their combined impacts on agriculture and water resources (see e.g. Ribeiro et
80 al., 2020). Although their application is more specialised than most ML approaches, copulas provide critical information about
81 inter-hazard dependencies, supporting a deeper understanding of compounding and interacting risks. Their inclusion in this
82 review therefore highlights their importance in contexts requiring precise statistical modelling of hazard interactions and
83 underscores how they complement broader ML-based strategies in climate-risk analysis. To advance this field, there is a critical
84 need for predictive frameworks that can leverage these advanced methods to forecast long-term future multi-hazard and multi-
85 risk scenarios, addressing uncertainties and guiding adaptive risk management strategies under changing climatic conditions.
86 To support implementation, the development of a wide range of open-source libraries (e.g., *scikit-learn*, *TensorFlow*, *Keras*,
87 *PyTorch*, *VineCopulas* (Claassen et al., 2024), etc.), allows users to implement, train, validate, and deploy models with
88 minimal programming expertise, making it possible for non-experts or domain specialists with limited knowledge to efficiently
89 apply advanced techniques to risk modelling. This democratization of tools reduces the technical barriers for researchers and
90 practitioners, enabling more interdisciplinary collaborations and accelerating the adoption of data-driven methods in climate
91 risk management (Rolnick et al., 2019).

92 This paper aims to provide a comprehensive review of data-driven methods, with a specific focus on ML approaches, for multi-
93 hazard and multi-risk assessment, exploring ongoing applications, current limitations and future perspectives, while also
94 addressing the use of copulas, a non-ML statistical method, to highlight its role in modelling dependencies in compound hazard
95 events. Unlike other recent reviews that have focused on ML (particularly DL) for specific hazards or sectors – such as extreme
96 events (Salcedo-Sanz et al., 2022), hydrology (Tripathy & Mishra, 2024), geophysics (S. Yu & Ma, 2021), wildfires (Jain et

97 al., 2020), and climate risk (Zennaro et al., 2021) – this paper takes a cross-cutting perspective on multi-hazard and multi-risk
98 assessment. By structuring the discussion around successive stages of risk analysis – data processing, hazard prediction, risk
99 assessment, and future scenarios – we connect climate risk and data-driven methods while also identifying critical gaps,
100 particularly in linking hazard interactions with vulnerability.

101 The review is structured as follows: Section 2 Methodology outlines the research questions, and the search methodology
102 employed. Section 3 Results and discussions summarises the literature review findings and discusses key insights related to
103 each of the research questions. Section 4 Conclusion provides a summary of the key insights and outlines the next steps for
104 research in this field. The Appendices provide an abbreviation dictionary as well as the summary tables of main articles
105 collected for each research question.

106 **2 Methodology**

107 This paper follows a systematic review process based on the Preferred Reporting Items for Systematic Reviews and Meta-
108 Analyses (PRISMA) methodology, which ensures a standardized, systematic, and transparent framework for analysing and
109 synthesizing existing literature (O’Dea et al., 2021). The method involves several steps, among which the main ones are:
110 defining of the research questions; developing a protocol detailing the search methodology (including database to search,
111 keywords, timeframe and selection criteria); collecting and screening relevant literature; synthesizing and interpreting the
112 findings. Such a stepwise process ensures a thorough search for relevant studies, consistent criteria for the selection of papers,
113 and clear documentation of the review process, therefore reducing the risk of bias and enhancing the robustness and
114 replicability of the analysis (Sarkis-Onofre et al., 2021).

115 **2.1 Research questions**

116 Each of the four research questions (Figure 1) is focussed on a specific topic and presents several sub-topics, offering a
117 structured framework to explore current applications, address challenges, and pinpoint future opportunities. These research
118 questions are:

- 119 1. Data: How can Machine Learning improve data collection and processing?
- 120 2. Multi-Hazard: How can Machine Learning and statistical tools be used to analyse extreme events, and model hazard
121 interactions?
- 122 3. Multi-Risk: How can Machine Learning applications integrate vulnerability and exposure in multi-risk analysis?
- 123 4. Future: How can Machine Learning and statistical tools be used to predict long-term future multi-hazard and multi-
124 risk?

125



Figure 1: Research questions and sub-themes

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128 The first research question examines how ML can help process diverse types of data, extracting and harmonising the
 129 information needed to analyse multi-hazard and multi-risk by addressing current gaps such as data sparsity, inconsistency
 130 across sources, and the lack of harmonised formats. This contributes to improving the quality and comparability of risk
 131 assessments by enabling integrated use of climate, EO, and textual datasets. In particular, the sub-themes are divided based on
 132 the type of data analysed:

- 133 I. Climate data (time series of geospatial climate data), which describe the characteristics of climate-related hazards
 134 across space and time. Preparing this data for multi-hazard and multi-risk applications often requires ML methods
 135 (i.e. feature engineering) to increase spatial and temporal resolution, harmonise and extend the time coverage of the
 136 datasets or correct for biases (Schneider et al., 2023).
- 137 II. EO, which can be used to characterise hazard, exposure and vulnerability layers and extract information on impacts
 138 (Ghaffarian & Emtehani, 2021; Novellino et al., 2024).
- 139 III. Textual data, such as newspapers or social media, which in the last years have been leveraged for extracting
 140 information on diverse impacts (Sodge et al., 2023).

141

142 The second research question investigates how ML and statistical tools improve the identification and modelling of hazard
 143 dynamics by capturing complex spatio-temporal patterns, compounding effects, and non-linear interactions that traditional
 144 approaches often overlook. This helps advance multi-hazard and multi-risk analysis by providing more accurate detection,
 145 classification, and modelling of extreme events. In particular, the key sub-themes are:

- 146 I. Analyse which methods can be used to identify, classify and cluster extreme events, producing spatio-temporal
 147 footprints of multi-hazard events (H. Yu et al., 2022).

148 II. The prediction of (multi-)hazard events, for example through early warning systems or seasonal predictions
149 (Bhowmik et al., 2023).

150 III. The analysis of hazard interactions, for example characterising joint distributions through copulas (Bevacqua et al.,
151 2021) or multi-hazard susceptibility maps (Pourghasemi et al., 2019).

152 The third research question concerns the application of ML for the integration of vulnerability and exposure into multi-risk
153 analysis addressing the current gap where vulnerability and exposure are often treated as static or secondary layers rather than
154 dynamic drivers of risk. This integration strengthens the ability of multi-risk assessments to capture how socio-economic
155 conditions and adaptation measures interact with hazards to shape overall risk. In particular, the key themes are:

156 I. Multi-hazard exposure and vulnerability assessments, integrating susceptibility mapping with information on specific
157 exposure layers, such as buildings and population (Rusk et al., 2022).

158 II. Modelling risk from past impacts data, often through supervised ML approaches that use hazard, vulnerability and
159 exposure indicators as predictors (Dal Barco et al., 2024).

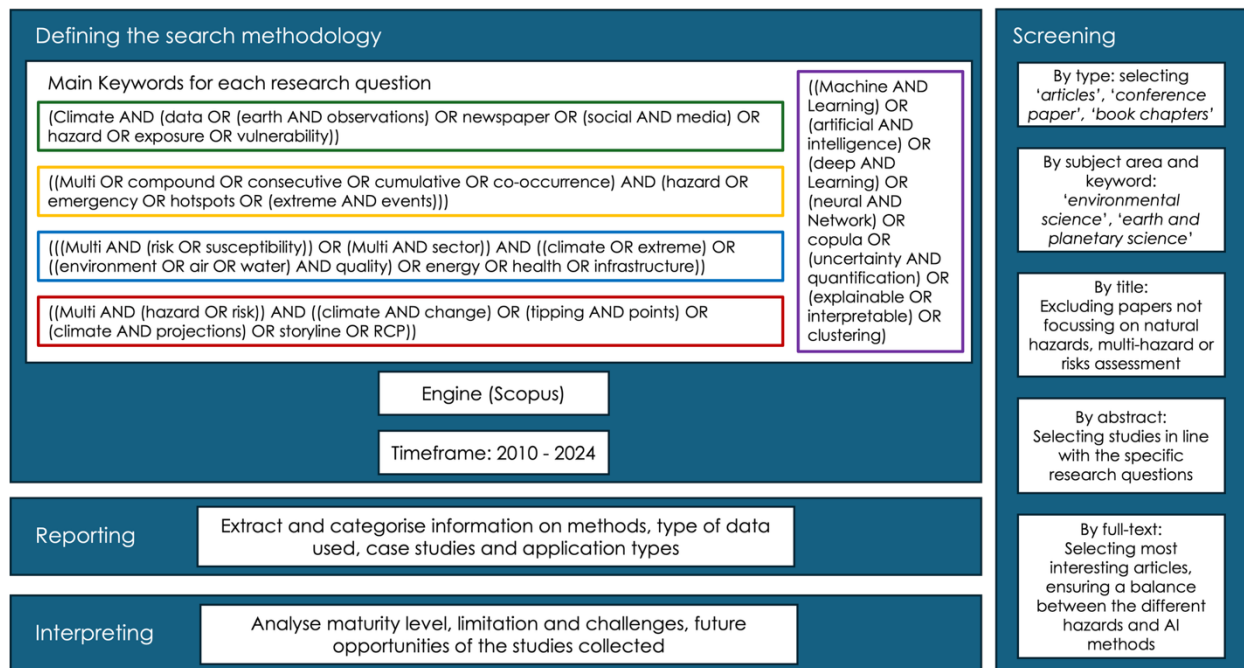
160 The fourth research question investigates the possible contribution of ML and statistical tools into the analysis of (long-term)
161 future multi-hazard and multi-risk, where uncertainty associated with the representation of future extremes in climate
162 projections further complicates risk modelling, highlighting a critical gap in existing approaches, which often fail to adequately
163 capture compound and cascading extremes under changing climate conditions This research question clarifies how ML can
164 enhance scenario building, improve uncertainty quantification, and support more robust long-term multi-risk assessments. In
165 particular, the key sub-themes are:

166 III. Modelling future multi-hazard trends and spatial patterns using statistical methods, in particular for compound and
167 consecutive events (Zscheischler et al., 2018).

168 IV. Assessing future impacts based on climate change projections, often using methods trained on historical data and
169 applied to ensembles of RCP projections (S. J. Park & Lee, 2020).

170 **2.2 Methodological framework: search methodology, screening, reporting and interpreting**

171 The search was performed on Scopus, focusing on articles published in English. Since the analysis focuses on ML applications
172 and multi-risk, the timeframe 2010 – 2024 was chosen because both areas of research are recent and other reviews have
173 addressed earlier periods, highlighting that most applications in ML and climate risk have been published only in the last few
174 years (Zennaro et al., 2021). For each research question, a dedicated search was performed. Each search string was generated
175 by the combination of a set of method-related keywords (e.g. those related to ML or statistical methods), common across all
176 questions, and a set of thematic keywords, specific to each research question (Figure 2).



177
178 **Figure 2: Literature review methodology**

179 After collecting articles for each research question, the papers were first filtered by following typologies: *'journal articles'*,
180 *'conference papers'*, and *'book chapters'*. Afterwards, for each research question, the papers were screened by title, then by
181 abstract, and finally by full text. The final screening selected 153 key papers to be analysed in the literature review. This
182 information was then summarised into tables, identifying the type of applications, the type of data used, the case study and the
183 methods used. Finally, for each research questions, the results were discussed to understand the maturity level of the
184 applications, their limitations and possible future developments.

185 **2.3 Limitations and scope of the review**

186 While this review follows the PRISMA guidelines for search strategy, screening, and reporting, a formal numerical quality
187 scoring of individual studies was not applied, consistent with standard practice in PRISMA-based reviews of computational
188 methods in geoscience and climate risk (e.g., Zennaro et al., 2021; Salcedo-Sanz et al., 2022; Ghaffarian et al., 2023). Instead,
189 quality and relevance were assessed qualitatively during full-text screening based on three criteria: methodological rigour
190 (evaluated through the presence and type of model validation, e.g., cross-validation, independent test sets, or benchmark
191 comparisons), relevance to the research questions, and diversity across data sources, geographical coverage, hazard types, and
192 ML approaches. The latter criterion was applied explicitly to avoid over-representation of any single method or region in the
193 final corpus, and is documented in Appendix B.

194 Another limitation concerns terminological consistency. Although this review adopts the Zschau (2017) framework to
195 reclassify papers during full-text screening, the terms multi-hazard, multi-risk, compound, and cascading are used with

196 considerable inconsistency across the reviewed literature, a well-documented feature of the field (Gill & Malamud, 2014;
197 Tilloy et al., 2019). Because paper selection was based on keyword matching against author-assigned terminology, the corpus
198 necessarily reflects this heterogeneity, and the thematic categories used in the synthesis should be understood as analytical
199 conveniences rather than sharp taxonomic boundaries.

200 Moreover, while this review focuses on ML and copula-based methods as the primary data-driven approaches for multi-hazard
201 and multi-risk assessment, it is important to acknowledge that several complementary quantitative frameworks exist and have
202 been the subject of dedicated reviews that fall outside the scope of the present work. Bayesian networks (BNs) provide a
203 probabilistic framework for multi-hazard causal modelling, capturing conditional dependencies between risk drivers through
204 directed acyclic graphs and propagating uncertainty in a transparent, interpretable way; they are particularly valuable in data-
205 sparse contexts where causal structure can be informed by expert knowledge, and their application to climate multi-risk
206 assessment has been reviewed in depth by Sperotto et al. (2017). Agent-based models (ABMs) simulate the adaptive behaviour
207 of individuals and institutions under hazard scenarios, making them suited to capturing dynamic vulnerability, evacuation
208 dynamics, and community resilience processes that purely data-driven models cannot represent; comprehensive reviews of
209 their application in disaster management are provided by Zhuo & Han (2020) and Anshuka et al. (2022). More broadly, the
210 full landscape of quantitative methods for modelling hazard interrelationships, including stochastic, empirical, and mechanistic
211 approaches, is systematically covered by Tilloy et al. (2019), providing a valuable complement to the ML-focused perspective
212 of the present review.

213 Finally, some considerations need to be taken on the geographical distribution of the 153 papers included in this review, which
214 reveal a marked concentration in a small number of regions. In terms of lead authorship, Europe (35.5%) and East Asia (27.0%)
215 together account for nearly two thirds of the corpus, followed by North America (21.1%), while the Global South is
216 substantially underrepresented: Africa, South America, and Oceania collectively contribute less than 5% of lead authors. A
217 similar pattern holds for co-authorship, though with a slight broadening of participation: South/SE Asia rises to 6.4% and
218 Middle East to 7.3%, suggesting that researchers from these regions participate more frequently as collaborators than as lead
219 investigators. The most pronounced shift occurs in the case study column: Global studies account for 14.9% of the corpus, and
220 South/SE Asia (10.6%), Middle East (6.8%), and Africa (5.0%) are more represented as study areas than as sources of
221 authorship, indicating that data-driven methods developed in high-income regions are frequently applied to, rather than
222 developed within, lower-income contexts. The full breakdown of lead author institution country, co-author countries, and case
223 study regions, together with a Sankey diagram illustrating the flows between these three dimensions, is provided in Appendix
224 B. These geographical imbalances should be borne in mind when interpreting the findings of this review, as the methods,
225 datasets, and risk priorities that dominate the literature inevitably reflect the institutional contexts in which the research was
226 produced.

227

228 **3 Results and discussions**

229 **3.1 Data**

230 **3.1.1 Climate datasets**

231 The application of ML methods to produce new, complete, or high-resolution hazard datasets (either from meteorological
232 observations, climate reanalyses or future projection) is quite established, and mainly focuses on data with sparse and irregular
233 measurements. A typical indicator which is derived with ML methodologies is soil moisture: in-situ measurements are usually
234 scarce and not uniformly distributed, satellite images (which will be discussed later) often presents temporal gaps and can only
235 provide information on the first layer and struggles in complex topographies and it presents a complex dynamic that is
236 influenced by many different drivers (similarly to multi-risk prediction) such as precipitation, temperature, evaporation,
237 topography and land use. For example, Kang et al. (2018) and O. & Orth, (2021) investigate the complex interactions at
238 different soil levels and temporal scales with a Long-Short Term Memory (LSTM) model that takes as inputs the topography,
239 vegetation and atmospheric conditions and predicts each soil moisture layer in succession, using ERA-5 reanalysis as
240 assessment endpoint. LSTM is widely applied to model the behaviour of other hydrological variables, such as snow, run-off
241 and river catchments. Entity-Aware LSTM was used for rainfall-runoff modelling by Kratzert et al., (2018); Kratzert, Klotz,
242 Shalev, et al., (2019), to include both static and dynamic inputs allowing the algorithm to explicitly differentiate the two
243 different types. Ghiggi et al. (2019) applies Random Forest (RF) regression to predict monthly runoff rates in the timeframe
244 1902-2020, based on antecedent precipitation and temperature from an atmospheric reanalysis, validating the results with in-
245 situ streamflow observations. Other research focuses on different variables and in particular investigate the irregular
246 distribution of sensors: Amato et al. (2020) introduces a multi-step methodology to interpolate irregularly distributed spatio-
247 temporal timeseries, first decomposing the signal and then learning stochastic spatial coefficients which can be spatially
248 modelled and mapped on a regular grid with Artificial Neural Networks (ANN), allowing the reconstruction of the complete
249 spatio-temporal signal.

250 ML methods have been applied also to climate reanalyses and models. Early applications, such as He et al. (2016), tested RF
251 regression to statistically downscale spatially precipitation data, using few covariates and demonstrating how this approach is
252 able to catch the non-linear relations between variables, minimising overfitting and collinearity issues between predictors.
253 However, the algorithm struggled with skewed datasets and even the final model, which is the combination of two different
254 RF models, trained respectively on high-precipitation and low-precipitation values, fails to detect the complex spatial and
255 temporal complexity of precipitation data, overestimating the intensity and spatial distribution of low precipitation and
256 underestimating high precipitation. Other applications are focussing on Deep Learning models: CNNs are used to downscale
257 many variables from future climate models (among which, air temperature, precipitation, 10-m wind speed, 2-m relative
258 humidity, downward shortwave radiation) (Lin et al., 2023). Generative models particularly Generative Adversarial Networks
259 (GAN) and diffusion models, are widely used for this task. GANs consist of two neural networks – a generator and a
260 discriminator - that are trained simultaneously in a competitive process. The generator attempts to create realistic fake data

261 that can fool the discriminator, while the discriminator works to distinguish between real and fake data. For example, specific
262 GANs based on Convolutional Neural Networks (CNNs) have been applied to post-process weather forecast outputs. These
263 models can enhance the resolution of precipitation data by a factor of ten, producing more realistic and spatially coherent
264 forecasts compared to the original input data (Harris et al., 2022). Diffusion models, on the other hand, learn to reverse a noise
265 process: first the model adds sequentially noise to input data, then the model learns how to predict the noise at each step, and
266 once trained, it can start with noisy data and work backwards, progressively removing the noise to generate a new, realistic
267 dataset. Diffusion models are related to variational inference, where the forward process defines a probabilistic trajectory from
268 data to noise, and the reverse process defines a generative path from noise back to data. Unlike other generative models like
269 GANs, which learn through a "discriminative" process (trying to fool a discriminator network), diffusion models learn through
270 this smooth diffusion and denoising process (Yeğin & Amasyalı, 2024). For example, diffusion models are applied to
271 downscale multiple climate models, also providing information on the uncertainty downscaling, by generating a large number
272 of ensemble members based on probability distribution sampling (Ling et al., 2024). DL approaches are often used to
273 downscale low-resolution future models to Convection Permitting (CP) climate models, where the main advantage of these
274 techniques is their reduced computational costs compared to the development of a CP climate models (Bretherton et al., 2022;
275 Clark et al., 2022). The role of Artificial Intelligence (AI) in climate predictions is discussed in Schneider et al. (2023). This
276 study advocates for the development of global models at 10–50 km resolution, harnessing AI and EO for the calibration and
277 development of higher-resolution regional simulations.

278 In recent years, there has been growing interest in hybrid modelling: approaches that combine data-driven ML methods with
279 physical or process-based models or constraints, as a way to benefit from both high flexibility and physical realism. Such
280 hybrid / physics-informed ML methods help address several limitations of pure data-driven models: they can enforce
281 conservation laws, reduce overfitting to noise, improve generalization especially under conditions outside the training domain,
282 and provide more interpretable insights into underlying drivers. For instance, He et al., (2023) integrates ML corrections into
283 a land-surface / atmospheric model using data assimilation, remote sensing LAI and soil moisture to improve climate
284 simulations. Similarly, Huynh et al., (2025) combines process-based hydrological flux models with neural networks to correct
285 for scale mismatches and to better capture spatial heterogeneity. Also, (S. Yu et al., 2024) provides benchmarks for ML
286 emulators that mimic nested high-resolution physical simulations. Despite their promise, hybrid models also face important
287 limitations. They often require substantial domain and physical knowledge to be formulated appropriately and to ensure
288 physical consistency (Willard et al., 2022). Moreover, coupling ML architectures with numerical process models can remain
289 computationally demanding, particularly for high-resolution simulations or large spatio-temporal domains (Reichstein et al.,
290 2019). Calibration and validation can also be complex, as balancing the contributions of the physical and data-driven
291 components often involves ad hoc or case-specific tuning (Read et al., 2019). Finally, interpretability may still be reduced
292 when the ML component acts as a black box, obscuring how physical constraints shape predictions (Kashinath et al., 2021).
293 These challenges are also relevant for hazard prediction, where process dynamics such as land–atmosphere feedback play
294 central roles and require models that are both physically credible and statistically robust. Thus, hybrid models represent an

295 emerging frontier at the interface of ML, process-based modeling, and data assimilation, particularly relevant for both climate
296 data reconstruction and hazard modelling and deserve explicit consideration in future reviews and benchmarking efforts.
297 Machine learning applications for climate and environmental datasets have greatly improved the reconstruction and
298 downscaling of variables from sparse and irregular observations. However, a critical yet often under-addressed aspect in this
299 field is uncertainty quantification (UQ), which is particularly relevant when these datasets are later used for hazard or risk
300 assessments (Beven, 2018). Uncertainty in ML-based models arises from multiple sources: Aleatoric uncertainty stems from
301 the intrinsic variability and noise in the underlying measurements, such as sensor errors, missing satellite observations, or
302 inconsistent temporal coverage; epistemic uncertainty originates from limited or biased training data and model structural
303 choices (Xu et al., 2022). Several probabilistic approaches have been explicitly designed to represent spatial data uncertainty
304 by learning distributions rather than deterministic predictions, mainly involving Bayesian Networks (BN) and Gaussian
305 Processes (GP) (Siddique et al., 2022). For example, Multi-fidelity Gaussian Processes with a 5/2 Matern kernel in particular,
306 were used to downscale precipitation data from ERA-5 over high mountain terrain. Multi fidelity models combine low-fidelity
307 observations (which are usually more numerous and less expensive to obtain) with high-fidelity ones. This makes the model
308 more suited than other state-of-the-art machine learning methods for smaller datasets and able to quantify and narrow the
309 uncertainty associated with the precipitation estimates, which is especially needed over ungauged areas and can be used to
310 estimate the likelihood of extreme events that lead to floods or droughts (Tazi et al., 2024). Andersson et al., (2023) applies
311 Convolutional Neural Processes (ConvNPs), to suggest informative sensor placements by finding sites that maximally reduce
312 prediction uncertainty, testing it for air temperature anomalies measurements in Antarctica. Convolutional Neural Processes
313 (ConvNPs) extend the probabilistic framework of Gaussian Processes by learning flexible, data-driven covariance structures
314 through neural networks. While traditional GPs provide robust uncertainty estimates but suffer from scalability and stationarity
315 constraints (M. Jiang et al., 2022), ConvNPs maintain a probabilistic foundation while scaling linearly with data size and
316 accommodating irregular spatial inputs (Garnelo et al., 2018). DeepSensor¹, a specific GitHub python package, was developed
317 to facilitate the application of Neural Processes in environmental sciences, especially for downscaling, interpolation, sensor
318 placement and data imputation. Monte Carlo Dropout (MCD) enhances epistemic uncertainty quantification in climate data
319 and was tested on neural networks for probabilistic medium-range weather forecasting (Garg et al., 2022). Deep generative
320 models such as diffusion or GAN frameworks can further approximate uncertainty by generating ensembles of plausible
321 realisations that sample the predictive probability space (Ling et al., 2024; Saha & Ravela, 2022). Despite these advances,
322 most studies still focus primarily on improving resolution and accuracy, while systematic approaches to quantifying and
323 propagating uncertainty through the modelling chain, from data to hazard and risk estimates, remain limited (Beven, 2018).
324 Addressing this challenge is crucial, as downstream risk assessments rely heavily on the reliability of the climate inputs that
325 feed them.

¹ <https://github.com/alan-turing-institute/deepsensor>

326 3.1.2 Earth observations

327 EO data, when combined with ML is increasingly recognised for its critical role in supporting actionable multi-hazard and
328 multi-risk assessment, as evidenced by new initiatives from ESA and NOAA's Centre for AI, where particular attention is
329 devoted to the use of EO for discovering impacts in remote areas and developing early warning systems.

330 Remote sensing images are used to improve climate datasets, for example increasing the spatial coverage in areas with sparse
331 measurements or providing real data to bias-correct/downscale modelled data. Multiple AI methods, such as Support Vector
332 Machine (SVM) (Ahmad et al., 2010; Jing et al., 2016a), Ridge Regression (Kang et al., 2018), RF (Han et al., 2023; Jing et
333 al., 2016b) and LSTM (Fang et al., 2017) are applied for developing soil moisture datasets.

334 EO provides consistent, near-real time observations of environmental conditions that are critical for early warning and hazard
335 characterisation. For instance, indicators such as vegetation stress (Miyoshi et al., 2020; Schiefer et al., 2020; Veras et al.,
336 2022), surface temperature anomalies can enable the early detection of droughts (Barrett et al., 2020), floods (Dasgupta et al.,
337 2022) or wildfires (Jain et al., 2020) especially in remote and data scarce areas. DL and Physics Informed Neural Networks
338 can leverage radar (e.g., Sentinel-1 SAR), to estimate water levels for flood forecasting (Dasgupta et al., 2022; Gierszewska
339 & Berezowski, 2024) or fused into predictive models that refine hazard forecasts for severe weather and anticipate cascading
340 impacts (Flora et al., 2021). Remote sensing plays a crucial role in hazard dataset development by helping mitigate bias that
341 may be inherited by ML-based risk models. These models are often trained on datasets calibrated with data from resource-rich
342 regions, where the majority of weather stations are located. As a result, they may struggle to generalize effectively to
343 underdeveloped areas, which are frequently the most vulnerable to extreme events (McGovern et al., 2019, 2022).

344 EO combined with ML is also used in assessing environmental quality, such as water quality (Sagan et al., 2020; Sit et al.,
345 2020). These applications mainly showcase simpler models, such as short neural networks and SVM (Nazeer et al., 2017),
346 Decision Trees (DT), RF, Cubist Regression and Extreme Gradient Boosting (XGBoost), due to their ease of implementation
347 and relative scarcity of ground measurement data (J. Liu et al., 2023). They focus on optically parameters, such as chlorophyll-
348 a, turbidity and suspended solids, but also others such as of nutrients and other non-optical parameter) can be predicted relying
349 on models integrating meteorological and hydrological variables (S. Chen et al. 2022).

350 A central application of EO is in supporting impact and damage assessments: change detection techniques that compare pre-
351 and post- event imagery are used to estimate physical impacts (T. Bai et al., 2023). This includes building damage (Y. Bai et
352 al. 2018), infrastructure collapse (Sublime & Kalinicheva 2019) due to earthquakes or tsunamis (Ji et al. 2018), but also flood
353 extent (Munawar et al., 2021), landslides (Lei et al., 2019) and wildfire scars (Bo et al., 2022; Tran et al., 2020). The main
354 challenges encountered in these applications are due to the return periods of satellites, which may limit their ability to detect
355 fast changing impacts; to the presence of clouds, which can hamper visibility especially during the occurrence of extreme
356 events likely to cause damages; and to changes in luminosity or season (Faiza et al., 2012).

357 Moreover, EO enables long-term recovery tracking and vulnerability/exposure monitoring, with applications using proxies
358 such as night-time lights to measure recovery trajectories (Kabiru et al., 2023; Qiang et al., 2020). For examples, studies have

359 used EO and ML to track how rapidly services return to urban slums post disaster, highlighting which population remain
360 exposed and underserved (Ghaffarian & Emtehani, 2021). Similarly, UNET-based CNNs are used to identify deprivation
361 pockets from satellite images and track during their recovery process (J. Wang et al., 2019), or to derive proxy indicators for
362 poverty from satellite night lights (Jean et al., 2016), in combination with transfer learning to overcome scarcity of labelled
363 data (S. J. Pan & Yang, 2010). At longer timescales, techniques like K-Nearest Neighbour (KNN), SVM, ANN and RF are
364 used to classify urban and rural land cover, detect land use changes or informal settlements (Adam et al., 2014; Yuh et al.,
365 2023; Zerrouki et al., 2019).

366 In summary, the integration of EO with ML and statistical techniques offers a powerful toolkit for multi-hazard and multi-risk
367 assessment, supporting early warning, targeted preparedness, rapid impact estimation, and recovery monitoring.

368 **3.1.3 Textual data**

369 In addition to remote sensing, textual data from sources such as social media and newspapers offer valuable information for
370 impact assessment. Natural Language Processing (NLP) algorithms can harness this textual data, facilitating applications
371 across various hazard types, including landslides, volcanoes, drought, earthquakes, floods, and wildfires. In general, the
372 procedure typically consists in several steps, in which the textual sources are first screened based on metadata (such as location
373 or the presence of disaster-related words in titles); then NLP or semantic algorithms (Angelov, 2020) are used to extract
374 keywords from the main text and convert the textual data into tabular/numeric; then a classification algorithm is applied to
375 choose between impact/no impact data or link the impacts to a specific sector or hazard. Additional steps may also involve the
376 retrieval of spatial information from textual data. Many different algorithms can be employed, with logistic/lasso regression
377 (Genkin et al., 2007), Naïve Bayes Classifiers (L. Jiang et al., 2016), KNNs (Shah et al., 2020) and ANNs (Nam et al., 2014),
378 being the most common. In the field of disaster mapping, SVM are tested by Asinthara et al. (2022), while Powers et al. (2023)
379 compares CNN and specific pre-trained language models; Koshy & Elango (2023) tests a multi-modal method leveraging text
380 and images from social media, employing the language models BERT; Mehrotra et al., (2022) test SVM, DT, RF, Adaboost,
381 Gradient Boosting, XGBoost, LSTM in combination with language models. Twitter (now X) was the main social media that
382 has been used to detect impacts, while newspaper articles have also been used, in particular for slow onset hazards, such as
383 droughts. For example, Sodoge et al. (2023) apply several NLP and ML methods to automatize the detection of drought impacts
384 from newspaper articles; the procedure classifies impacts into 25 classes, based on the sector (e.g., forestry, livestock, forestry,
385 transport etc.) by using different Supervised ML models (Naïve Bayes, Lasso Regression, RF, ANN). In general, rule-based
386 methods are preferred to ML models when the number of samples is limited (X. Liu et al., 2018).

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390 **Table 1. Data-related methods, gaps and opportunities.**

SECTION	METHODS	GAPS	OPPORTUNITIES
3.1.1 Climate datasets	<ul style="list-style-type: none"> • LSTM for soil moisture & hydrology; • RF for runoff/precipitation; • ConvNPs for sparse sensors; • ANNs for interpolation; • CNNs, GANs, diffusion models for downscaling; • GPs for uncertainty quantification 	<ul style="list-style-type: none"> • Struggles with sparse/irregular data; • Poor scalability (GPs); • Extremes misrepresented; • Limited uncertainty treatment 	<ul style="list-style-type: none"> • Hybrid ML–physics models; • Scalable probabilistic methods; • Better uncertainty quantification; • Generative models for projection ensembles
3.1.2 Earth observations (EO)	<ul style="list-style-type: none"> • SVM, RF, LSTM for soil moisture; • CNNs/autoencoders for land cover, impacts, disaster recovery; • Transfer learning; • ML for water quality (RF, ANN, XGBoost) 	<ul style="list-style-type: none"> • Bias toward data-rich regions for validation/testing; • Revisit gaps/ clouds limit detection; • False positives; • Weak multi-hazard integration 	<ul style="list-style-type: none"> • Robust models for missing/noisy data; • Near-real-time EO pipelines; • Integrate EO with socio-economic data; • Transfer learning for vulnerable regions
3.1.3 Textual data	<ul style="list-style-type: none"> • NLP + ML (Naïve Bayes, RF, SVM, CNN, BERT, LSTM); • Multimodal (text + images); • Rule-based for small datasets 	<ul style="list-style-type: none"> • Few labelled datasets; • Language/ cultural bias; • Imprecise spatial info; • Noisy social media inputs 	<ul style="list-style-type: none"> • Multilingual/ transfer learning; • Improved geolocation extraction; • Integrate with EO/sensor data; • Robust methods for noisy/misinformation-prone data

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393 This section contributes to the field of multi-hazard and multi-risk analysis by showing how ML applications to climate
 394 datasets, Earth observations, and textual data can overcome data sparsity and heterogeneity, thereby enabling the generation
 395 of more complete, high-resolution, and multi-source datasets that are essential for capturing hazard interactions and cascading
 396 risks.

397 3.2 Multi-hazard

398 3.2.1 Identify, classify and cluster

399 The initial step in conducting a comprehensive multi-risk assessment involves a thorough analysis of hazard factors, which is
 400 critical for effective climate risk evaluation and enhancing disaster preparedness. In this context, identifying various hazards,

401 classifying them into distinct categories, and extracting their spatio-temporal footprints through clustering techniques are
402 fundamental processes.

403 The identification of impacts from satellite images to discover hazard footprints, such as for landslides, earthquakes, floods
404 was discussed in the previous section because it is mainly an image processing task, where the goal is to identify differences
405 between two images. This section focuses on the identification of extreme events from climate datasets, which require specific
406 considerations on the typology of hazards and risk considered and is subject to different definitions and multiple interpretations.
407 The most common approach to identify multiple hazards from climate datasets is to use thresholds to identify univariate
408 extreme events and then combine them at a later stage into a multi-hazard database. In order to identify the thresholds, two
409 methods are applied: empirical thresholds (e.g., defining a max temperature over which an event is considered extreme) or
410 statistical thresholds (e.g., calculating a pixel-wise and/or day-wise percentile to identify events that exceeds a threshold that
411 can vary spatially and temporally). Empirical thresholds are usually fine-tuned to link extreme events to impacts on specific
412 sectors or local applications, and many applications focus on temperature extremes and health (Ray et al., 2021; X. Sun et al.,
413 2014). Statistical thresholds are preferred when analysing global trends and merging multi-hazard extremes because they allow
414 a more consistent and probabilistic robust comparison between different hazards. Percentiles can be easily adapted to model
415 spatial and temporal variations in data and are ideal for global application that cover multiple landscapes where a unique
416 empirical threshold cannot be univocally determined. For example, in Ionita et al. (2021), specific percentiles are used to
417 identify heatwaves and drought from temperature and SPI indicators respectively, before applying Empirical Orthogonal
418 Functions to investigate their drivers and their centre of actions over Europe; Similarly, Sutanto et al. (2020) is using
419 percentiles to identify heatwaves, droughts and wildfires from temperature, soil moisture and Fire Weather Index (FWI),
420 analysing spatial overlaps of the daily binary hazard maps to identify simultaneously occurrences of dry hazards and then
421 investigating cascading events by looking at different combinations of hazard sequences. Claassen et al. (2023), proposes a
422 methodology to identify multi-hazard events combining static footprints derived from the processing of satellite images (e.g.
423 for landslides, floods, tsunamis) with dynamic footprints (based on statistical percentiles) of climate hazards (e.g., heatwaves,
424 droughts, extreme precipitation, extreme wind, etc.), proposing a methodology to identify consecutive events using a specific
425 time lag and analysing the global distribution of the various multi-hazard events.

426 Return periods are another statistical technique used to identify extreme events, studying the likelihood of an event of a certain
427 magnitude occurring in a chosen timeframe (Liao et al., 2021). Return periods are most often applied in hydrology, when
428 dealing with flooding and storm surge events (G. Liu et al., 2020, 2023; Mattei et al., 2021; Zanini et al., 2020). These
429 applications fit a probability distribution (typically a Generalised Extreme Value Distribution, calculated over the number
430 exceeding of a threshold or over maxima) which allow for an estimation of the uncertainty of the threshold. Percentile
431 thresholds, returns periods and Generalised Extreme Value (GEV) distributions are also used conjunctly, such as in Orth et al.
432 (2022), where different hydrological hazards (floods, frost, heat waves, droughts, and storms) and their contrasting impacts
433 are analysed against multiple sectoral assessment endpoints (Gross Primary Productivity for vegetation, crop yields, human
434 mortality, damages to properties and public attention).

435 It is important to note that these approaches focus initially on univariate extremes, and only at a second stage, the identified
436 events are merged to produce multi-hazard events, checking for overlapping in time and space. This can lead to the
437 underestimation of compound joint-extreme events which arise as a combination of multiple indicators not individually
438 extreme.

439 Other approaches focus on identifying and classifying extreme events from climate reanalyses using DL, especially in case of
440 cyclones or other hazards that are characterised by the interaction of multiple atmospheric drivers. Y. Liu et al. (2016) was one
441 of the first to apply CNN based on AlexNet to detect and classify tropical cyclones, atmospheric rivers and weather fronts
442 from climate datasets, such as ERA-5, CAM5.1. One of the main challenges in this domain is the scarcity of labelled data for
443 training supervised ML models. This is discussed by Racah et al. (2016), who expanded the previous approach, developing a
444 semi-supervised CNN model to overcome the lack of labelled data and created an extreme weather dataset as benchmark. In
445 general, the skewness of datasets is another common challenge for identifying climate anomalies with supervised approaches:
446 often data on which the ML models are trained on present very few samples of conditions leading to impacts (Dal Barco et al.,
447 2024).

448 Other studies focus on the identification of the spatio-temporal footprints of the climate hazards, in particular with algorithms
449 such as Density Based Spatial Clustering Applications with Noise (DBSCAN, Ester et al., 1996), grouping single point
450 anomalies into clusters in time and space. These approaches are applied in single hazards, such as droughts (Cammalleri &
451 Toreti, 2023), heatwaves (J. Wang & Yan, 2021) or earthquakes (Di Martino et al., 2018). With regard to multi-hazards
452 applications, DBSCAN is used by Tilloy et al. (2022) to cluster compound precipitation and wind compound extreme events
453 in Great Britain and by H. Yu et al., (2022) to investigate droughts, heatwaves, cold-waves, extreme wind and extreme
454 precipitation in Eurasian Drylands, studying how the coordinates of the centroid of the clusters are shifting hot and dry events
455 to northern latitudes due to climate change.

456 **3.2.2 Hazard forecasting and prediction**

457 Before delving into more risk-based applications, it is worth noting that in the last few years, the application of DL models
458 such as Transformers (Vaswani et al., 2017), Graph Neural Networks (GNN) (Veličković et al., 2017) and Physics Informed
459 Neural Networks (Kashinath et al., 2021; Lütjens et al., 2021) has prompted a revolution in weather forecasting. Early
460 applications of AI models, primarily using RF and SVM, were largely aimed at replacing specific steps within numerical
461 weather forecasts. More recently, DL tools have gained prominence due to their ability to capture long-range dependencies,
462 handle complex and irregular data structures and integrate the solutions of equations of physical systems into a unified
463 framework, enabling DL to be successfully employed for modelling the whole medium range weather forecasting process (Bi
464 et al., 2022; Chen et al., 2023; Keisler, 2022).

465 Applications that focus on predicting or forecasting hazards are still mainly focussed on single hazard approaches. However,
466 some single hazard approaches were included in this review because their multi-variate approach includes the combination of
467 different static (as land use, topography, socio-economic data) and dynamic (e.g., atmospheric and marine data) parameters

468 and implicitly deal with multi-hazard interactions (e.g., a wildfire may be more probable when dry and hot conditions are
469 present, a drought can be influenced by temperature and soil moisture, etc.). For example, Haggag et al. (2021) propose an
470 ANN prediction model in a multi-hazard perspective, but then test it on past disaster records to predict only floods in Ontario
471 using indices for climate extremes inputs. Monte Carlo dropout techniques have been employed to quantify epistemic
472 uncertainty, for example in surge forecasts (Macdonald et al., 2025) and flood modelling (M. Nguyen et al., 2024).

473 One of the main algorithms applied to forecast hazards is LSTM: Kratzert, Klotz, Brandstetter, et al. (2019) apply adapted
474 LSTM to disentangle static and dynamic inputs and analyse both high and low extremes in river flows, considering climate
475 susceptibility and integrating static and dynamic inputs. Tiggeloven et al. (2021) propose a LSTM/CNN architecture to predict
476 global storm surge residuals based on atmospheric conditions, investigating how the model's performance varied based on
477 changes of the spatial area input into the convolutional model. With regard to vegetation, long-range temporal dependencies
478 from several climate variables are investigated with a LSTM model (Kraft et al., 2019). Many applications focus on forecasting
479 of air quality hazards, especially in urban areas: compared to other types of environmental impacts, such as water quality, the
480 network of air quality monitoring stations offers hourly data at a high spatial resolution, enabling the training of AI models to
481 dynamically forecast at short lead times. Applications include the short-term prediction of ozone levels in Kuwait (Freeman et
482 al., 2018), the development of a daily air quality index in Beijing and Guilin (Q. Wu & Lin, 2019), or the prediction of
483 concentration of micro particular matter in the air of Seoul (Chang-Hoi et al., 2021).

484 Another popular DL architecture is GNN, applied in weather forecasting (Keisler, 2022; Lam et al., 2022) and river
485 networks/flooding predictions (Bentivoglio et al., 2023; Kazadi et al., 2024; A. Y. Sun et al., 2021). The key advantage of
486 GNNs over CNNs is their ability to capture complex relationships in non-Euclidean data. While CNNs are limited by fixed
487 sliding windows and may miss correlations between adjacent pixels or non-adjacent zones, GNNs excel in modelling graph-
488 structured data, allowing for more accurate representations (Kipf & Welling, 2016). In particular, Kazadi et al. (2024) apply a
489 combination of GNN and Gated Recurrent Unit (GRU, a type of recurrent neural network), for spatio-temporal flood
490 prediction, accounting for spatially distributed precipitation data, as well as static features such as bathymetry and topography,
491 comparing its performances against a LISFLOOD-FP simulation of Hurricane Harvey (2017) in Houston, Texas and showing
492 improvements in terms of accuracy and faster training (100x) and testing (1000x) times. Similarly, Transformers are applied
493 for river flood prediction, outperforming other RNNs in terms of computational costs and performances, also increasing the
494 interpretability of the model (Castangia et al., 2023).

495 CNN, ANN, LSTM are still popular for drought and heat events, which are characterised by longer scale spatio-temporal
496 dynamics. For example, Bonino et al. (2024) compare the performances of CNN, LSTM and RF for the prediction of marine
497 heatwaves; Patil et al. (2023) employ CNN to predict drought in East Africa 3 or 4 season ahead, analysing the contribution
498 of different climate drivers at multiple spatial and temporal scales; ANN are used for forecasting drought risk at near real time
499 in India, using Artificial Neural Network models (Singh et al., 2021). Other algorithms (SVM, Random Forest, XGBoost,
500 Extra Trees) are still often applied to analyse low probability extreme events in specific locations, where the lack of data

501 constrains the training of Deep Neural Networks, such as the storm surge height caused by tropical cyclones in New York
502 (Ayyad et al., 2022).

503 **3.2.3 Modelling hazard interaction**

504 Recent work has applied interpretable ML frameworks to hazard modelling, aiming not only at prediction but also at identifying
505 key drivers. For instance, S. Jiang, Bevacqua, et al. (2022) and S. Jiang, Zheng, et al. (2022) used LSTMs to study river
506 flooding in Europe, combining feature attribution methods such as Expected Gradients (Erion et al., 2021) and Additive
507 Decomposition (Du et al., 2019) to disentangle the roles of snowmelt and precipitation. By running models across decades,
508 they revealed shifts in dominant flood drivers, with precipitation becoming increasingly important. Other studies have applied
509 gradient-based methods (A. Y. Sun et al., 2021), CNN heatmaps (Patil et al., 2023), attention mechanisms (Castangia et al.,
510 2023), and sensitivity analysis (Bentivoglio et al., 2023; Bonino et al., 2024; Kratzert, Klotz, Shalev, et al., 2019). These
511 advances improve interpretability, yet ML approaches remain limited by high data demands, sensitivity to training biases, and
512 the difficulty of generalising beyond observed conditions (Bentivoglio et al., 2023). Their strength lies in prediction and
513 uncovering nonlinear relationships, but the black-box nature of many models complicates causal modelling (Freeman et al.,
514 2018).

515 While most ML studies focus on univariate hazards, compound events require methods that capture joint extremes. Copulas
516 offer a flexible statistical framework to model dependence structures between variables, such as the co-occurrence of high
517 river discharge, intense rainfall, and coastal surges (Hao & Singh, 2016; Nelsen, 2006). By decoupling marginal distributions
518 from their dependence structure, copulas can assess joint probabilities of rare events with more precision than traditional
519 multivariate models (Tilloy et al., 2019) Applications include pair copulas for compound flooding in Italy (Bevacqua et al.,
520 2017), Joe copulas for concurrent river–coastal extremes (Sadegh et al., 2017), and copula-based Bayesian networks for flood–
521 drought interactions (Couason et al., 2018). However, several challenges remain: selecting appropriate copula families is non-
522 trivial (since different families imply different tail dependencies, yet many common families assume simplistic dependency or
523 exchangeability) (Oh & Patton, 2015); capturing joint tail dependence becomes increasingly difficult in high dimensions
524 (vines, mixtures, or hierarchical copulas may help but bring computational and inference burdens) (Simpson et al., 2020);
525 physical drivers (e.g. precipitation skew, changing climate forcings, watershed characteristics) are often only indirectly
526 represented through marginal or covariate models (Hochrainer-Stigler et al., 2019). Therefore, while copulas are powerful for
527 probabilistic risk quantification, they are less suited to dynamic forecasting or process-based understanding without additional
528 model structure or ensembles (Tootoonchi et al., 2022).

529 **Comparison and complementarities.**

530 ML and copula methods approach hazard interactions from distinct perspectives. ML excels at prediction and feature
531 discovery but struggles with transparency and extrapolation, while copulas provide interpretable dependence structures and
532 joint probability estimates but scale poorly with dimensionality and lack causal interpretability. ML can identify critical
533 hazard predictors and generate inputs, while copulas rigorously quantify their joint occurrence. Yet, few studies combine

534 these strengths; most rely on either predictive ML or probabilistic copulas in isolation. For example, an LSTM may forecast
535 river discharge under given precipitation and snowmelt conditions, while a copula model can then quantify the probability
536 that extreme discharge co-occurs with extreme rainfall or sea-level rise. Together, ML and copulas can provide a more
537 complete picture: ML enables forecasting and driver attribution, while copulas ensure rigorous treatment of dependence
538 structures and joint extremes (Sadegh et al., 2017; Tilloy et al., 2019). Combining both approaches offers a promising
539 pathway for advancing compound risk assessments. Some approaches, such as, T. Jiang et al., (2023) used a hybrid ML-
540 copula method to estimate the probability of consecutive drought events (in particular from meteorological to ecological
541 droughts), combining several ML classifiers (KNN, RF, SVM, ...) to estimate the propagation probability of meteorological
542 drought given its characteristics, and C-vine copulas to model conditional probability model of the paired meteorological
543 and ecological drought events. Closing this gap, for instance, by integrating ML-derived drivers into copula frameworks, or
544 benchmarking ML-learned dependencies against copula-based models, represents a promising but underexplored direction
545 for compound risk assessment.

546 **Susceptibility mapping**

547 Susceptibility in the context of natural hazards refers to the predisposition of an area to experience a specific hazard and
548 considers different factors (usually categorised into hazard or vulnerability in risk assessment), such as topography, geology,
549 hydrology, land use and vegetation and highlights “territorial characteristics”, disregarding the more dynamic and time-
550 dependent component of risks (Wubalem, 2022). The methodology for creating multi-hazard susceptibility maps using ML
551 usually consists in three steps: first, for each hazard, the susceptibility factors are identified; then, supervised ML techniques
552 are employed to create single hazards susceptibility maps, considering the different conditioning factors as predictors and the
553 areas impacted by the analysed hazards in the past as assessment endpoints; finally, the single hazard maps are combined to
554 produce the final multi-hazard susceptibility map. Eventually, feature importance techniques are applied as a fourth step to
555 extract the most susceptible factors for each hazard or multi-hazard combination.

556 ML has been applied extensively to derive multi-hazard susceptibility maps, which can identify areas prone to multiple disaster
557 and help disaster management planning. However, these applications are typically trained on average, static climatic conditions
558 and do not consider temporal interactions between risk factors (such as the cumulative impacts of a series of successive extreme
559 rain events, the duration of a heatwave or changes in vulnerability caused by wildfires). Moreover, the type of multi-hazard
560 events for which they are applied is often limited to wildfires, landslides, floods, and earthquakes (Abu El-Magd et al., 2021;
561 Ahmadi et al., 2021; Cao et al., 2020): in fact, these methods rely on the presence of catalogues of past clearly defined
562 hazard spatial footprint: for other climate hazards, such as extreme winds, hails, or heatwaves susceptibility is not investigated.
563 Furthermore, input data for susceptibility mapping are aggregated over long time frames, in order to ensure robustness of the
564 analysis. However, changes in vulnerability and exposure parameters occurring in the analysed periods, for example due to
565 newly implemented adaptation measures, are overlooked, potentially leading to overestimation (or underestimation) of areas
566 at risks.

567 The most common approach for integrating susceptibility parameters into multi-risk assessment is by producing multi-hazard
568 susceptibility mapping, where susceptibility to multiple hazard (including factors for hazard, such as yearly precipitation, but
569 also vulnerability parameters, such as slope) can provide a valuable point of reference for decision makers in sustainable land-
570 use planning or infrastructure development. A number of studies are focusing on mountainous regions, using a range of ML
571 models, including Logistic Regression, ANN, DT, SVM, RF, Boosted Regression Trees (BRT), or Generalised Linear Models
572 (GLM) (Javidan et al., 2021; Karakas et al., 2023; Kariminejad et al., 2022; H. D. Nguyen et al., 2023; Pourghasemi et al.,
573 2019, 2020; Pouyan et al., 2021; Yousefi et al., 2020) The multi-hazard combination usually covers floods, landslides,
574 avalanches and forest fires, which have clear footprints that can be used to train single hazard susceptibility, and integrate other
575 risks which can be assessed through already available risk maps, such as seismic risk maps at a later stage (Bordbar et al.,
576 2022). Different hazards are included by Piao et al. (2022), who test BRT, RF and Classification And Regression Trees (CART)
577 in the Gangwon-do region in South Korea (an area rich in forests and ecological diversity) to establish a multi-hazard
578 probability map for forest fires and droughts; in this study the multi-hazard interactions are investigated, considering drought
579 as an amplifying hazard for forest fires. Mandal et al. (2022) focus instead on coastal areas, in particular in West Bengal
580 (India), considering tropical cyclones, embankment breaching, storm and tidal surge, inundations, extreme rainfall, salinization
581 and erosion; RF and ANN are applied to produce multi-hazard susceptibility maps. Ullah et al. (2022) test a CNN to produce
582 flash floods, landslides and debris flow multi-hazard susceptibility mapping, comparing its performances with Logistic
583 Regression and KNN methods in terms of accuracy, coefficient of determination, Mean Absolute Error and Root Mean Squared
584 Error. The input data consist of field surveys, topography, hydrology, and environmental data, while the locations of historical
585 flash flood, debris flow and landslide locations are extracted from Google Earth images. The feature importance scores are
586 derived using a Random Forest model and are used to enhance the analysis of the multi-hazard maps. It is interesting to note
587 that in this case, the CNN layer is 1-dimensional and is not used to analyse the spatial context of the pixels, but it runs across
588 the 14 layers of predicting variables, producing an independent output pixel by pixel.

589 While the literature on this topic is quite established, most of these applications propose a multi-layer single hazard risk, rather
590 than a full multi-hazard or multi-risk approach: in fact, the single hazard maps are often combined linearly or via a matrix
591 considering combined risk categories, without elaborating further on the hazard interactions. Another common challenge in
592 the development of susceptibility maps is the skewness of the training dataset, which are characterized by a predominance of
593 areas with no damage. These greatly affects the training and testing of the models, and specific sampling procedures are often
594 applied, rather than relying on balancing weights when training the ML model. Most often, all the positive samples (e.g., where
595 some impact was recorded) are included; a buffer area is applied to the positive samples and subtracted from the whole dataset
596 to exclude areas near recorded impacts; a number of points of comparable magnitude to the positive ones is sampled from the
597 difference dataset to ensure that the final training dataset includes a balanced representation of impacted and non-impacted
598 areas. This is a key step of the susceptibility mapping and can potentially add biases to the model, if the selected samples are
599 not representative of the whole dataset or if there is a high autocorrelation. Spatial or temporal autocorrelation needs to be
600 considered when splitting between training, validation and test data: random splitting methods assume data is independent and

601 identically distributed. Specific techniques, such as spatio-temporal block cross validation (Zanetti et al., 2022) need to be
 602 considered to account for this. For example, a recent paper by Sweet et al. (2023) shows the impact of different validation
 603 techniques in a RF model for the prediction of agricultural yield, and their implications on performances and robustness of the
 604 interpretation of the model.

605 **Table 2: Multi-hazard related methods, gaps and opportunities.**

SECTION	METHODS	GAPS	OPPORTUNITIES
3.2.1 Identify, classify & cluster	<ul style="list-style-type: none"> • Thresholding (empirical & percentiles) to build multi-hazard catalogues; • Return periods & GEV; • CNNs (semi-/supervised) for extreme-weather object detection in reanalyses; • DBSCAN for spatio-temporal footprints and compound clusters. 	<ul style="list-style-type: none"> • Under-detection of joint (non-univariate) extremes when hazards are merged post-hoc; • Label scarcity & class imbalance for supervised DL; • Skewed datasets; • Sensitivity to spatial/temporal non-stationarity. 	<ul style="list-style-type: none"> • Unified pipelines that detect compound signatures directly (multivariate thresholds + clustering); • Semi-/self-supervised DL to mitigate label scarcity; • Robust cluster tracking of compound hotspots under change.
3.2.2 Hazard forecasting & prediction	<ul style="list-style-type: none"> • LSTM/CNN for hydrology, storm surge, drought-heat; • Transformers for floods; • GNN/GRU for river-network dynamics; • Classical ML (RF/SVM/XGB) for local extremes when data are limited. 	<ul style="list-style-type: none"> • High data demands; • Generalisation beyond observed regimes; • Limited interpretability; • Performance varies with spatial context and input windowing. 	<ul style="list-style-type: none"> • Physics-informed/graph-aware DL for better extrapolation; • Attention/attribution to expose drivers; • Global-to-local transfer learning; • Benchmarking vs. process models for trust.
3.2.3 Modelling hazard interactions	<ul style="list-style-type: none"> • Copulas (pair/vine/Joe) for joint extremes; • Copula-BNs for river-coastal compounding; • XAI on LSTMs/CNNs/Transformers (gradients, attention, sensitivity) to reveal drivers and shifts. 	<ul style="list-style-type: none"> • Copula family selection & tail-dependence in high dimensions; • ML black-box limits causal insight; • Difficulty linking physical drivers to dependence structures. 	<ul style="list-style-type: none"> • Hybrid ML-copula stacks (ML to predict/characterise events, copulas to quantify joint probabilities); • Benchmarking ML-learned dependencies against copula baselines; • Conditional vine copulas for multivariate models.
3.2.3 Susceptibility mapping (multi-hazard)	<ul style="list-style-type: none"> • Supervised ML (LR, GLM, RF, SVM, BRT, CART, ANN, CNN) to build single-hazard susceptibility maps, then combined into multi-hazard maps; 	<ul style="list-style-type: none"> • Often “<i>multi-layer single-hazard</i>” (weak interaction modelling); • Skewed datasets (few positive samples); 	<ul style="list-style-type: none"> • Spatio-temporal CV (block) to curb leakage; • Dynamic susceptibility that updates with sequences/adaptation;

	<ul style="list-style-type: none"> • Feature importance to rank drivers. 	<ul style="list-style-type: none"> • Sampling bias & autocorrelation; • Limited hazard breadth beyond fire/ landslide/ flood/ earthquake. 	<ul style="list-style-type: none"> • Explicit hazard interaction terms; • Extend beyond the typical geohazards
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607 This section contributes to the field of multi-hazard and multi-risk analysis by reviewing methods for identifying, classifying,
608 and clustering hazard events from diverse datasets, highlighting how threshold-based approaches, clustering algorithms, deep
609 learning models, and copulas can capture the spatio-temporal footprints and interactions of hazards, thereby advancing the
610 ability to detect, forecast, and model compound and cascading events.

611 3.3 Multi-risk

612 3.3.1 Modelling risk combining susceptibility, exposure and vulnerability

613 Many studies are found to focus on modelling risk by combining hazard maps, produced via ML-based susceptibility mapping,
614 with vulnerability and exposure layers. Single hazards such as wildfires, floods and landslides are often considered, and
615 buildings, population and infrastructures are the typically included exposure elements. Kotaridis & Lazaridou (2022) consider
616 flooding risk in Tuscany and applied a 2D CNN to produce an urban flooding susceptibility map. Differently from Ullah et al.
617 (2022) the CNN applied here makes use of the spatial context of each pixel, considering a 5x5 patch centred on a specific pixel
618 (an area of 50 x 50 m² since the pixel size is 10m), creating 20000 different samples from the initial map, each one with a
619 5x5x9 size, where the last number corresponds to the different predictors of the susceptibility mapping that are considered as
620 channels in the CNN architecture. Thus, not only the selection of the initial samples, but also the selection of the size of the
621 patch is a key hyperparameter to be considered: in this case, a cross validation is used to choose the best patch size. The
622 vulnerability maps are created dividing the land use into 5 classes, which are then multiplied with the hazard layer to calculate
623 the final risk map. Convolutional Neural Networks (CNNs) offer significant advantages over traditional algorithms in spatial
624 analysis due to their ability to process areas as 2D maps. This enables the model to leverage Max Pooling layers to capture and
625 simplify the spatial context of events. Unlike models that focus on individual point characteristics, CNNs can better model and
626 integrate the broader spatial relationships. For example, Zhao et al. (2020) test CNN for urban flood susceptibility too but
627 instead of producing separate maps for hazard and vulnerability, anthropogenic factors were used as predictors for the
628 susceptibility map. The study compares the performances of different ML models: a simple (with 1 convolutional layer) CNN
629 architecture, LeNet5 (Lecun et al., 1998), a slightly deeper CNN (with 2 convolutional layers), SVM and RF models. Different
630 input strategies are tested: a point based strategy that only considers input at a given site; a partial spatial strategy that considers
631 the surrounding pixels, flattening the 2D image to a 1D vector, thus losing partially the spatial context, but allowing the
632 neighbouring pixels to be fed to SVM and RF models as additional predictors; a patch strategy, similar to the one described
633 before for the CNN models, which granted the best performances. This study also discusses the use of Deep CNNs, which is

634 discouraged since the typical sample size and model is too small to tune the high number of parameters required by Deep
635 CNNs.

636 Rusk et al. (2022) analyse population risk in the Hindu-Kush and Himalaya region, producing a multi-hazard map for
637 landslides, floods and wildfire with the MaxEnt (Maximum Entropy) algorithm, which is then overlaid with population
638 distribution. The paper also produces a matrix of multi-hazard interactions, dividing them into three types: when hazards are
639 directly linked (e.g., flooding causing a landslide), when their linkage is mediated by an environmental condition (e.g., land
640 use changes caused by wildfires increasing the probability of a landslide), or when their linkage is mediated by infrastructure
641 or urban processes (e.g., a landslide damaging a dam, triggering a flood). However, a quantitative assessment of these multi-
642 hazard interactions is not provided and only the records of these events are used to complement the multi-risk map. A similar
643 approach is used in Austria (Fuchs et al., 2015), considering river flooding, torrential flooding and snow avalanches as hazards
644 and buildings as assets. In this case, buildings vulnerability is investigated, categorising them based on location, size, building
645 category and the construction period. The different urbanisation patterns, very high in mountainous terrain of the Hindu-Kush-
646 Himalaya (HKH) and quite low for Austria, influenced the final risk score assessment, with the HKH showing more areas at
647 higher risk (Rusk et al., 2022). Sammonds et al. (2023) analyse hurricane, flood and landslide risk on population, producing
648 single hazard susceptibility maps with statistical methods and discussing the vulnerability of population, considering gender,
649 age, and population density; the final multi-hazard hurricane risk is obtained as a product of the single hazard susceptibility
650 scores, overlaid with weights determined with Analytic Hierarchy Process (AHP), and the vulnerability score. Other
651 applications focus on Vietnam, where RF is applied to derive risk for buildings and population against multi-hazard
652 susceptibility maps for floods and wildfires (Luu et al., 2024). RF is applied to calculate single and multi-hazard susceptibility
653 maps for China for flooding, landslides, and debris flows and the railway infrastructure was overlaid to analyse present and
654 future risk, considering newly planned railway links (K. Liu et al., 2018). In general, a number of studies are found to apply
655 non-ML approaches, including multi-criteria decision-making and expert judgements methods to calculate susceptibility and
656 vulnerability layers, such as in Arvin et al. (2023), that focuses on infrastructure resilience in Iran, considering flooding,
657 landslides and earthquake as hazards, and 25 indicators at the county level and Khatakho et al. (2021), focussing on population
658 exposed to flooding, earthquakes and wildfires near Kathmandu (Nepal).

659 A critical limitation of the studies reviewed in this section is the static treatment of vulnerability. Most applications use fixed
660 proxies – building footprints, land-use classifications, census-derived population density – that do not evolve in response to
661 hazard occurrence, adaptation measures, or broader socio-economic change (Haer et al., 2019, de Ruiter & van Loon, 2022).
662 This static framing can substantially underestimate risk in contexts where vulnerability is shaped by governance failures,
663 structural inequalities, or rapid urban expansion (Ward et al., 2022; Šakić Trogrlić et al., 2024). A particularly underexplored
664 challenge in multi-hazard risk assessment is that vulnerabilities do not simply add up across hazards: they interact. Synergies
665 and asynergies between vulnerabilities mean that the combination of hazards can fundamentally alter how exposed elements
666 are affected. For instance, adaptation measures designed to reduce risk from one hazard may increase vulnerability to another,
667 and damage caused by a first hazard event can leave a system more vulnerable to a subsequent one (Albulescu & Armaş, 2024;

668 de Ruiter & van Loon, 2022). Stolte et al. (2024) further demonstrate through a global systematic review of urban vulnerability
669 that the drivers of vulnerability differ substantially across hazard types, and explicitly call for research into multi-hazard
670 vulnerability dynamics as a necessary step beyond the current dominant paradigm of treating multiple hazards in parallel rather
671 than in interaction. Despite growing conceptual recognition of this problem, it remains essentially unaddressed in the data-
672 driven literature reviewed in this study, where vulnerability interactions are neither modelled nor discussed. Social justice
673 dimensions also remain largely absent from the reviewed multi-risk literature: only few of the papers analysed explicitly
674 consider vulnerability dimensions such as gender, while the question of how ML-based risk maps might inherit biases from
675 historically underinvested impact datasets remains largely unaddressed (McGovern et al., 2022).

676 Another aspect to consider is uncertainty and its propagation across the risk modelling chain: attempts to propagate it formally
677 across the hazard–exposure–vulnerability–risk chain are rare even in single-hazard contexts: Kropf et al., (2022) introduced a
678 sensitivity and uncertainty analysis framework within the CLIMADA platform that varies hazard, exposure, and vulnerability
679 inputs simultaneously, and Dawkins et al. (2023) extended this to formally quantify uncertainty contributions from each
680 component, with an application using GAM for heat-stress risk assessment, but neither study addresses multi-hazard
681 interactions. However, no study in the reviewed corpus achieves end-to-end UQ in a multi-hazard risk context, propagating
682 uncertainty from input data through hazard modelling and ML or statistical methods to the final risk estimate.

683 **3.3.2 Modelling risk predicting impacts**

684 Another popular approach to model multi-risk with ML is to use impacts as a proxy and training supervised ML models on
685 past impacts. Examples of possible impacts are excess mortality for health risks, economic damages and monetary losses,
686 number of emergency signals or specific environmental indicators, such as ecological status. With regard to ML methodology,
687 approaches are similar to the ones applied for predicting hazard values, considering multiple predictors covering climate,
688 topography, land use and anthropogenic factors, but the final assessment endpoint, impact data, is very different from typically
689 hazard data, having a coarser resolution in time and space and resulting in much smaller datasets. Thus, most of the studies
690 focus on simpler and more interpretable ML methods like ensemble methods, rather than the DL approaches which are popular
691 for hazard prediction. Moreover, more attention is dedicated to the interpretation of the factors and the explainability of
692 methods (Ghaffarian et al., 2023), with most applications presenting some form of feature importance analysis, either as a
693 built-in feature of the model, such as for RF, or as a a-posteriori analysis with SHAP values. In this section, studies are grouped
694 based on the sectors and type of impact considered, considering health, food security and crops, environmental quality &
695 biodiversity, physical damages and economic losses.

696 **Health**

697 Studies focussing on environmental-health risks often analyse the combination of heat and air quality stressors and use excess
698 mortality as predicant variable. These applications aim at disentangling complex temporal patterns, consisting of a long-term
699 trend, driven by multiple (and often unknown) factors, and short-term peaks, mainly driven by summer heatwaves; moreover,
700 time-lags needs to be considered. Thus, statistical methods, such as Distributed Lag non-linear models have been widely

701 applied (Gasparrini, 2014) to model exposure lag-response of mortality to environmental stressors. More recently, RF has been
702 applied, analysing the role of humidity in urban mortality during heatwaves at the global scale (Guo et al., 2024) or predicting
703 heat-stroke occurrence in China (Y. Wang et al., 2019), while SVM is applied for analysing previous diseases, population
704 density and urbanisation (X. Wang et al., 2021). One of the most interesting papers, Boudreault et al., (2023) test 9 different
705 ML, DL and statistical methods (such as Generalised Additive Models – GAMs) in the Metropolitan City of Montreal,
706 considering weekly all-cause mortality as predictand and air temperature, humidity, wind, Particle Matter (PM) 2.5, Ozone
707 (O₃), Nitrogen Dioxide (NO₂), Sulphur Dioxide (SO₂), Carbon Monoxide (CO) as predictors. Among the methods tested,
708 Tree based methods (RF, XGBoost) usually perform better overall, while statistical methods (and GAM in particular) are more
709 accurate in predicting the mortality peaks; Deep Learning approaches, such as MLP and LSTM have instead the worst
710 performances. This is partially explained by the limited size of the dataset and the inclusion of non-climate causes in the
711 predictand, likely to cause overfitting in the DL models. Another study also focussing on Canada proposes an AI-based
712 framework to extrapolate vulnerability from health-heat relationship: Côté et al. (2024) test this approach considering two
713 steps: first, a model to predict daily mortality from mean temperature for 3 days, age, income and period of the year as
714 predictors and then a second model predicting annual mortality over aggregated areas with specific socio-economic and
715 environmental (air quality, vegetation, ...) characteristics. The model tested are AutoGluon (an automatic ML framework
716 allowing to train and test ML models without expert knowledge²), GP and Deep Gaussian Process (Deep GP). The results
717 shows that GP are able to model better the daily mortality trends, especially during extreme temperature, while AutoGluon is
718 slightly better for the annual analysis. GP with non-linear (e.g., 5/2 Matern Kernel (Y. Pan et al., 2021)) are in fact able to
719 better handle noise and small data samples (J. Wang, 2023), and their limit is their computational costs (M. Jiang et al., 2022);
720 on the other hand, the more complex Deep GP handed the worst outcomes, highlighting the challenges in tuning more complex
721 Deep GPs (Tazi et al., 2023). Other studies focus on predicting the influence of water quality parameters, such as turbidity, on
722 the risk of cholera disease outbreaks in Indian Coastal municipalities using a RF predictor (Campbell et al., 2020).

723 **Food security and crops**

724 The second group of reviewed studies focus on the nexus between food production, food security and migrations. For instance,
725 Busker et al., (2024) apply XGBoost to predict food insecurity in the Horn of Africa. This model, takes as input several factors,
726 integrating climatological variables, biological hazards, food and fuel prices, macroeconomic indicators, conflicts and
727 humanitarian assistance, aggregating data on the administrative units for which the assessment endpoint variable (food
728 security) was available. The model is tested for its ability to predict the onset of crises up to 12 months in advance,
729 demonstrating superior performance in agro-pastoral areas compared to croplands. SHAP values are employed to analyse the
730 key risk drivers. The findings of this study highlight its potential application in operational early warning systems, such as
731 FEWS NET.

² <https://auto.gluon.ai/stable/index.html>

732 Tárraga et al. (2024) also investigate the dynamic relationships between droughts, conflicts and food security, focussing on
733 their impact on population displacement. In this case, ML is not used to predict displacement, but causal discovery methods
734 are tested to retrieve its drivers within Somalia from 2016 to 2023. In particular, Granger Causality and Peter and Clark
735 Momentary Conditional Independence (PCMCI) are tested to generate plausible causal graphs of drought displacement,
736 showing limitations for Granger causality due to the high dimensionality and autocorrelation of the time series, while the
737 PCMCI method is able to disentangle the intertwined vulnerabilities and different leading times connecting drought impacts,
738 water and food security systems along with episodes of violent conflict. The reliability of the causal model depends on the
739 quality of training data and several assumptions are required, such as causal sufficiency (i.e., all possible driving variables of
740 drought displacement need to be considered in the analysis), no contemporaneous causal effects and causal stationarity. Note
741 that although causal sufficiency is valid, the associations between the other variables (e.g., SPEI, market prices, fatalities) may
742 be influenced by confounding factors rather than direct causality.

743 Different types of copulas (Normal, Student's t, Archimedean with different distributions) are tested to model risk by linking
744 bivariate return periods of temperature and precipitation to crop yields, analysing the impact of dry and hot, dry and cold, wet
745 and hot, wet and cold conditions (Zscheischler et al., 2017). Nested Archimedean copulas were used to model the tri-variate
746 dependence between maximum temperature and spring precipitation on crop yields, estimating the impact differences between
747 single and compound hazards, using combinations of heat and precipitation stress (Ribeiro et al., 2020).

748 **Environmental quality and biodiversity**

749 Numerous studies focus directly on environmental impacts, such as the influence of land use and urban planning on water
750 quality. For example, R. Wang et al., (2021) apply RF with SHAP values to model stream water quality and specific pollutants
751 based on four different urban planning scenarios in Texas. The model allows to correlate urban sprawl to water quality
752 degradation and was used to forecast environmental impacts under different urban development pattern scenarios. In Li et al.
753 (2022) the ensemble model XGBoost is used to predict water quality in beach locations in lake Eyre, paired with SHAP for
754 increased explainability. Other studies focus on ecosystem and biodiversity: for example, RF and Logistic regressions are
755 tested to predict forest loss in Borneo from topographical and anthropogenic variables (distance to urban areas, population,
756 etc.), highlighting the advantages of RF for modelling multi-scale spatial relationships between risk drivers (Cushman et al.,
757 2017). Similarly, in Islam et al. (2021), the spatio-temporal dynamics of wetlands in Bangladesh and their negative effects on
758 biodiversity are analysed using Decision trees, RF and SVM. RF and SVM are the best performing algorithms and in general,
759 the papers highlighted the role of remote sensing, for mapping wetlands variations in time. Species distribution is also
760 investigated, with many applications discussing the different spatial approaches for river network modelling. For example,
761 Schmidt et al. (2020) test the MaxEnt algorithm with two representations of rivers, highlighting how a high-resolution model
762 based on river reaches is better at discovering individual local habitat features, whereas lower resolution sub-catchment scale
763 models better account for more general drivers in fish distribution. Teichert et al. (2016) apply a RF model to identify the
764 dominant stressors for fish presence in estuaries, investigating the interactions among stressors evaluating ecological benefits
765 expected from reducing pressure. In particular, an RF model is trained to predict ecological status in 90 locations using 17

766 predictors describing the different stressors (urbanisation, flow changes, water pollution, oxygen depletion, etc.). Then,
 767 simulations are run to analyse the benefit of restorations comparing the difference between the baseline model and a model
 768 where the intensity of stressors was varied. The difference between single and multiple restoration action is analysed,
 769 highlighting the importance of combined restoration schemes and the non-linearity of their effects.

770 **Economic losses and physical damages**

771 This final category focus on studies modelling economic losses or physical impacts: Dal Barco et al. (2024) model the
 772 occurrence of impacts due to extreme weather events in the Veneto coastal municipalities, with a combination of two ML
 773 models: first a classifier (RF, SVM, ANN) is trained to predict the probability of daily impacts in coastal municipalities using
 774 meteorological data as predictors and a Boolean variable based on impact reports from the Regional Authorities as predictand;
 775 then a Linear Regression is used to predict the yearly occurrences of damages based on the outcome of the first model.
 776 However, the coarse resolution of the impact data, the biases in human collected impact catalogues, and the skewedness of the
 777 dataset can pose significant challenges to the training of a ML-model predicting direct physical impacts. Other studies focus
 778 on modelling tropical cyclones along the East Coast of the US with ANN: Pilkington & Mahmoud (2017) investigate the
 779 complex connections between all meteorological factors (wind, pressure, storm surge, and precipitation resulting in inland
 780 flooding) of a tropical cyclone and how those interact with the location of landfalls to produce a certain level of economic
 781 damage. The vulnerability and resilience of the different coastal locations are investigated essentially using the model to predict
 782 losses with varying meteorological factors taken from past historical events but switching their landfall location. Other
 783 approaches, such as Mukherjee et al. (2018) test SVM and RF to analyse impacts on the energy sector in the US caused by
 784 extreme weather events, leveraging the records of disruptions from outage data of the Department of Energy in the US and
 785 using as predictors a set of climatic and socio-economic variables aggregated at state level. In this study, two different models
 786 are trained, in order to account for the differences in the risk drivers between the more frequent energy disruptions and the
 787 extreme events, which are separated based on their quantile. Finally, other studies focus on the impacts on specific economic
 788 sectors, such as finance and tourism: Carannante et al. (2024) propose a pricing model for climate change risk, particularly
 789 physical risk, developing a type of climate risk-insured loan, based on a bioclimatic composite indicator developed with ML.
 790 In particular, a temporal dynamic RF (considering variables at different lag-times) is used to produce a monthly risk index,
 791 based on atmospheric variables (wind, precipitation, temperature) obtained mainly from remote sensing datasets, which is used
 792 to model impacts on beach resorts in Italy and inform the subsequent climate-risk loan mechanism.

793 **Table 3: Multi-risk related methods, gaps and opportunities.**

SECTION	METHODS	GAPS	OPPORTUNITIES
3.3.1 Risk via susceptibility + exposure + vulnerability	<ul style="list-style-type: none"> Overlay of single-hazard susceptibility (RF, SVM, ANN, BRT, CART, MaxEnt, CNN with patch context) with exposure (buildings, 	<ul style="list-style-type: none"> Vulnerability and exposure treated as static layers; modelling only direct impacts and risks; 	<ul style="list-style-type: none"> Dynamic vulnerability/exposure updates using EO and time-sequenced hazards; spatio-temporal block cross-validation;

	<p>population, infrastructure) and simple vulnerability layers;</p> <ul style="list-style-type: none"> • AHP/MCDM weighting; • feature importance/ SHAP to rank drivers. 	<ul style="list-style-type: none"> • Ignores cascading and indirect effects and their propagation across multiple spatial scales 	<ul style="list-style-type: none"> • interaction-aware fusion (graphs, learned weights); • extend to wind, hail, heat, storm surge; • probabilistic risk maps with uncertainty bands.
3.3.2 Predicting impacts	<ul style="list-style-type: none"> • Ensemble and hybrid ML approaches (RF, XGBoost, SVM, DL, copulas, causal ML) applied to health, food, environmental, and economic impacts; • explainable AI (SHAP) and probabilistic modelling for driver attribution. 	<ul style="list-style-type: none"> • Impact labels are sparse, coarse, biased, and confounded; • scale mismatches and aggregation blur signals; • extremes and tails poorly represented; • DL tends to overfit and transfer poorly across cities/regions/climates; • uncertainty quantification and causal attribution often limited. 	<ul style="list-style-type: none"> • Data & catalogues: build geocoded, event-level, cross-sector impact datasets and standardized labels (health, yields, biodiversity, losses); • Causal & lag-aware stacks: combine DLNM / explicit-lag models with ML and causal discovery to capture delayed and causal pathways; • Multi-source fusion & transfer: integrate EO, in-situ, socio-economic and market data; • use domain-adaptation/ transfer learning for cross-region generalization.

794

795 This section contributes to the field of multi-hazard and multi-risk analysis by examining how ML and statistical approaches
796 combine hazard, exposure, and vulnerability layers or directly predict impacts, highlighting opportunities and challenges in
797 capturing dynamic vulnerability, addressing data limitations, and improving the interpretability of risk models across health,
798 food security, environmental, economic, and infrastructure sectors.

799 3.4 Future

800 3.4.1 Predicting future hazards

801 Several studies focus on data-driven methods to predict long-term future multi-hazard and multi-risk scenarios. Zscheischler
802 et al. (2018) discuss the importance of compound events for future risk assessment and presents several approaches and
803 discusses the main challenges related to the use of future climate projections and weather simulations to analyse future
804 compound events. The role of bias correction and its connection to multi-hazard events and impact models is analysed: future
805 projections are often bias corrected to align the distribution of the modelled variables to the distribution of the observed ones,
806 in the reference timeframe. However, some issues can arise: the simplest approaches focus on adjusting the averages of the
807 variables and do not correct the tails of the distributions, thus modifying the behaviour of extreme events. Methods such as

808 quantile mapping, are needed to align the historical and future datasets before the application of any statistical or ML methods.
809 Sensitivity analysis can be performed to analyse how the model reacts to changes in inputs and the robustness of future
810 scenarios (Kim et al., 2023). Moreover, bias corrections are often univariate, and do not consider the effects on joint tail
811 distributions and consequently impact models based on these inputs are affected; multivariate bias correction models are then
812 encouraged (Sippel et al., 2016).

813 When dealing with the future of multi-hazard events, statistical methods are most often applied to identify hotspots and test
814 trends, similarly to the applications focussing on historical data. For example, Ridder et al. (2022) consider hot, dry, wet and
815 windy compound events by selecting cells which exceed the 99th percentile for wind and precipitation in the same day. Then
816 results are presented in changes in return period and annual event density, where the latter is a measure for how often an event
817 affects a region and how much of the region is affected, calculated from the number of grid cells affected. Similarly, Zhu et al.
818 (2023) investigate future compound wind and precipitation extreme at the global scale, analysing 14 CMIP6 models,
819 identifying compound events through the 95th percentile and discussing the sources of uncertainties via the HS09 statistical
820 method (Hawkins & Sutton, 2009) splitting between internal variability, model uncertainty and scenario uncertainty. Further
821 analyses discuss the spatial and temporal performances of future projections: Ridder et al., (2021) find good performances in
822 CMIP6 simulation for precipitation and wind compound extremes over North America, Europe and Asia, but poor
823 performances over Australia, probably linked to the limits in the modelling of tropical and extratropical cyclones and local
824 convection systems. Also, copulas are used to analyse spatial complementary patterns of compound events, such as in Ghanbari
825 et al. (2021), which analyse the joint return period of compound floods along the US coast, incorporating sea level rise and
826 peak river flows for future climate change risk scenarios with copulas. H. Wu et al., (2023, 2024), employ Vine copulas to
827 analyse hot & dry and pluvial & hot events in future scenarios, using a Single Model Initial Conditions Large Ensemble
828 (SMILE).

829 Bevacqua et al., (2023) stress the importance of SMILE for a robust analysis of future compound climate events. In fact, a
830 SMILE consists of many simulations from a single climate model, each starting from slightly different initial states (differently
831 from classical model ensembles, like CMIP6, which consists of many different runs from different models). Each realization
832 differs solely due to internal climate variability and ensures a better quantification of future uncertainties, and at the same time
833 it provides a much larger dataset to analyse statistically compound events. Multiple SMILEs can then be combined to identify
834 model differences and distinguish between internal climate variability and structural model differences. Sometimes, especially
835 when dealing with unprecedented, High-Impact, Low-Probability events, climate projections or even SMILE or statistical
836 weather generation are not sufficient: in these cases, storyline approaches are often used as alternative to explore future multi-
837 risk patterns (Moezzi et al., 2017; Shepherd et al., 2018). These approaches fit well within common practices in disaster risk
838 management, which consider event-based scenarios for emergency preparedness, allowing for interaction with local
839 stakeholders to evaluate the effectiveness of selected measures (Sillmann et al., 2021) and to explore low-likelihood and high
840 impact plausibility events (Bevacqua et al., 2021).

841 3.4.2 Modelling future impacts

842 A common approach to estimate future risks involves using future climate projections as input data for ML models that have
843 been trained on historical data of past impacts, similar to applications that focus on assessing current risks by leveraging past
844 impacts. For example, the study of future cyclone impacts in New York and New Jersey, is feeding four General Circulation
845 models as input for a SVM / AdaBoost risk model (Ayyad et al. 2023). Park & Lee (2020) test the performances of three
846 algorithms, K-NN, RF and SVM to analyse coastal risks in South Korea, considering rainfall, tides, topography and land use,
847 training the model on past floodings and then predicting future risks using monthly averages of rainfall and tidal values from
848 RCP 4.5 and 8.5 ensembles. Future risk scenarios are calculated aggregating the risk model outcomes for each decade from
849 2030s to 2080s. In a successive publication, Park et al. (2023) apply a similar ML methodology to investigate adaptation
850 strategies for coastal flooding: in this case, the ML model is trained on historical data with two different adaptation strategies,
851 seawalls or green spaces, and then the future adaptation models are implemented, either maintaining current adaptation
852 infrastructures or increasing one specific strategy. To ensure comparability between the adaptation scenarios, infrastructure
853 construction costs are standardized, guaranteeing that the two distinct adaptation pathways incurred equal expenses.

854 In general, it is considered good practice to use ensemble projections and values calculated over multiple years, in order to
855 increase the robustness of the future scenarios; however, some risk analyses focus on just a few selected years: Lim & Kim
856 (2022) test RF for future rainfall induced landslides, also analysing different adaptation pathways and considering an increase
857 in forested or urban areas. Instead of using monthly or daily values for the ML model, yearly values are used in the model, for
858 specific years (2050, 2092), which are considered significative for representing future scenarios. This approach is valuable for
859 analysing specific extreme events that may be overlooked when averaging across multiple models or years, and it reduces
860 computational demands. However, it carries the risk of biasing the analysis, as the selection of specific years may result in
861 outcomes that are not fully representative of the broader range of future scenarios. Bayesian Networks were tested by Pham et
862 al., (2023) in a multi-model chain approach combining ocean hydrodynamics models, wind-wave models, and shoreline
863 extraction models to analyse sea water quality impacts and shoreline erosion under different RCP projections (4.5 and 8.5).
864 Bayesian Networks are applied due to their ability to integrate heterogeneous data sources, including quantitative and
865 qualitative inputs and several data fusion steps to harmonise different spatial coverage, temporal resolutions and data formats,
866 with a final risk assessment conducted at municipality level and yearly/ decadal scale.

867 With regard to the water-food nexus, ML is being progressively employed as an alternative to process or statistical methods
868 for future crop yield estimation, showing increased performances and higher computational efficiency: Leng & Hall (2020)
869 test a RF model for annual yield prediction in the US for a 2° C global warming scenario; while Khan et al. (2024) select
870 Gradient Boosting to model the relationships between daily climate variables, hazard indicators, such as Consecutive dry days
871 (CDD) and crop production with CMIP6 data. Tabari & Willems (2023) carry out a global risk assessment from hot and dry
872 events, employing Copulas and integrating data from Shared Socio-economic Pathways (SSP) scenarios, future land use
873 patterns population and governance. ML methods are used also to predict the risk of increased conflicts due to climate stressors:

874 a RF classifier is applied by Hoch et al., (2021) to predict water-related conflicts in Africa using different SSP future
 875 projections, integrating socio-economic predictors (population, education, GDP, governance) and climate predictors
 876 (precipitation, evaporation, flood volume, soil water). The model is trained on historical data up to 2015 and tested with
 877 projections from 2016 to 2050. Future temperature-related mortality in different European regions is analysed by García-León
 878 et al., (2024) considering 4 scenarios of global warming (1.5 °C, 2°C, 3°C, 4°C) with an ensemble of CMIP5 models, analysing
 879 disparities between cold-related deaths and heat-related deaths and analysing the role of age, health infrastructure and climate
 880 change with a Distributed Lag Non-Linear model. In particular, different scenarios are discussed: present climate and present
 881 population, present climate with future population from EUROPOP 2019; future climate under different warming level with
 882 future population exposure.

883 Future risk patterns are also calculated implementing future multi-hazard susceptibility maps: for example, Rahman et al.,
 884 (2024) analyse future coastal multi-hazard risks in Bangladesh, implementing an LSTM algorithm, in combination with RF
 885 feature selection and a Genetic Algorithm (GA) optimiser. In particular, GA is used to identify optimal or near-optimal
 886 solutions, searching the space of LSTM parameters through a process of selection, crossover and mutation. The combination
 887 of the LSTM's ability to capture sequential patterns and long-term dependencies and GA's efficiency in navigating complex
 888 search spaces, is proved to achieve better convergence, avoid local minima, and optimise both the architecture and parameters
 889 of the LSTM model (Zamani et al., 2022). Other future multi-hazard susceptibility approaches include Ya et al., (2023), who
 890 analyse future risks in the Tibetan plateau considering climate and land use changes. Logistic Regression is used to produce
 891 susceptibility maps, while future climate scenarios were taken from CMIP6 future projections. In order to create future land
 892 use, this paper focus on PLUS, a RF-based model analysing the relationship between influencing factors and land use changes
 893 (Liang et al., 2021). Another approach for future land use is applied by Saha et al., (2021), which focuses on modelling cultural
 894 heritage site future multi-hazard susceptibility in the Sikkim state in India, considering different climate scenarios from CMIP5
 895 and land use from an empirical model (Dyna-CLUE) incorporating spatial logistic regression (W. Jiang et al., 2015). Bayesian
 896 Additive Regression Trees and Bayesian Generalised Linear models are applied to produce multi-hazard susceptibility maps,
 897 considering extreme rainfall, landslides and earthquakes. Another dynamical model, a Cellular Automata- Markov model
 898 (Clarke et al., 1997) is used to predict future land use changes in Iran to investigate flood risks, testing RF, XGBoost and
 899 Gradient Boosting as algorithms for producing susceptibility maps (Janizadeh et al., 2021).

900 **Table 4: Future related methods, gaps and opportunities.**

SECTION	METHODS	GAPS	OPPORTUNITIES
3.4.1 Predicting future hazards	<ul style="list-style-type: none"> • Bias correction for projections (incl. quantile mapping); • Hotspot/ trend detection via percentile thresholds (e.g., 95th–99th), return periods; • Uncertainty sources and propagation; • Vine copulas for joint tails; 	<ul style="list-style-type: none"> • Univariate bias correction can distort extremes/ joint tails; • Regional skill varies; • Limited direct detection of compound signals; 	<ul style="list-style-type: none"> • Adopt multivariate bias correction; • Combine SMILEs to separate internal variability vs. structural model differences;

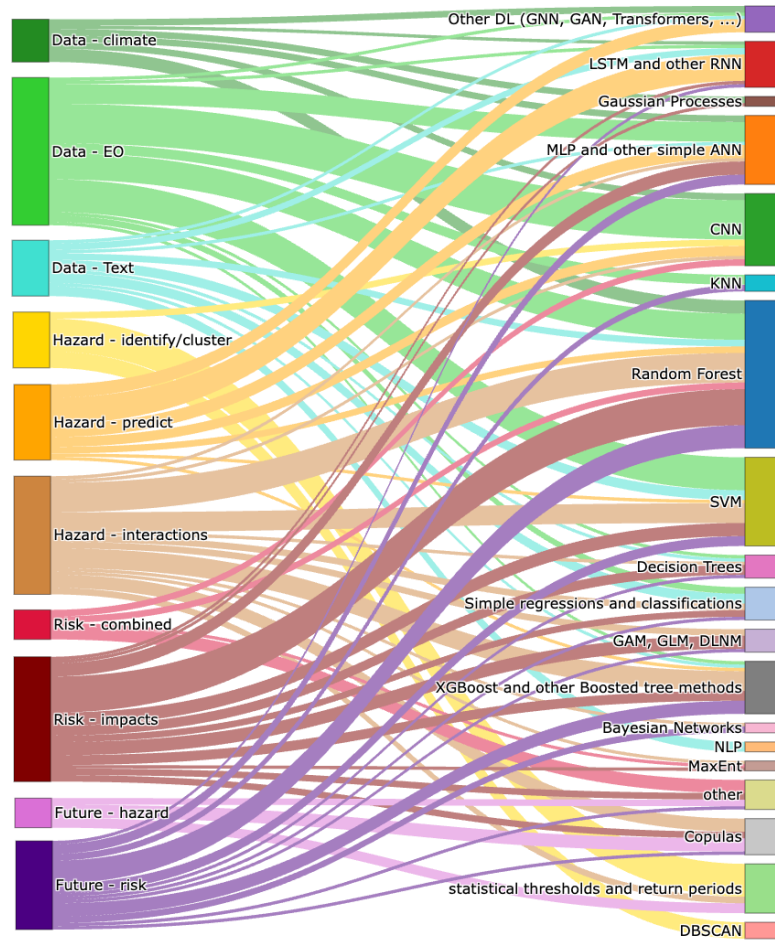
	<ul style="list-style-type: none"> • SMILE large ensembles; • Storyline event-based scenarios analysis. 	<ul style="list-style-type: none"> • Uncertainty treatment often partial. 	<ul style="list-style-type: none"> • Scale up vine copulas for compound events; • Embed storylines for preparedness.
3.4.2 Modelling future impacts	<ul style="list-style-type: none"> • Trained on historical impacts and applied to future ensembles; ensemble ML methods (RF, XGBoost, ...) for coastal risk, conflict risks, crop yield and adaptation scenarios; • Bayesian Networks for multi-model chains (hydrodynamics–waves–shoreline); • Distributed-lag models for future health impacts; • Future susceptibility integrating land use changes 	<ul style="list-style-type: none"> • Impact data often coarse, biased, and sparse; • Studies often rely on few years → low representativeness; • Causal discovery hinges on strong assumptions; • Biases due to scale mismatch in climate–exposure–impact data. 	<ul style="list-style-type: none"> • Use multi-model, multi-year ensembles and probabilistic models to quantify and propagate uncertainty; • Evaluate adaptation portfolios with standardized costs; • Integrate dynamic land use + socio-economic pathways (SSPs); • Uncertainty-aware learning, and open, geocoded impact datasets.

901

902 This section contributes to the field of multi-hazard and multi-risk analysis by reviewing how ML and statistical methods are
903 applied to predict future hazards and impacts, highlighting the importance of bias correction, climate ensembles, SMILEs, and
904 storyline methods, as well as the integration of socio-economic and land use projections. It emphasizes how these approaches
905 can improve the robustness of long-term risk scenarios, support adaptation planning, and guide strategies to address
906 uncertainties in future multi-risk patterns.

907 3.5 Limitations and future research directions

908 Figure 3 summarises the distribution of ML methods across the ten research sub-topics identified in this review, providing a
909 synthetic overview of the methodological landscape documented in the preceding sections. The figure reveals several patterns:
910 CNNs and DL architectures dominate Earth observation processing tasks; LSTM and sequence-based models concentrate in
911 hazard prediction, where temporal dynamics and memory effects are critical. Random Forest, ensemble methods, and simpler
912 regression approaches prevail in risk and impact assessments and future scenario analysis, consistent with their interpretability,
913 robustness to overfitting, and compatibility with tabular socio-environmental predictor sets. Statistical methods, including
914 copulas and return period approaches, appear primarily in compound event characterisation. Taken together, these patterns
915 confirm that data-driven methods have achieved meaningful penetration across the full multi-hazard risk assessment chain,
916 with distinct methodological communities converging on appropriate tools for each sub-problem. At the same time, the figure
917 shows that methods natively designed for multi-hazard interaction modelling, such as graph neural networks, remain marginal
918 across all sub-topics, and no architecture yet bridges the full modelling chain in an integrated way.



920
921 **Figure 3: Main methods used for each research topic**

922 These gaps point to the limitations of the current ML applications and open research directions relevant to the operational
 923 uptake of data-driven approaches in multi-hazard risk management. A first and fundamental limitation is climate non-
 924 stationarity, as highlighted in Section 3.4 Future: ML models trained on historical hazard records implicitly assume that the
 925 statistical relationships between predictors and outcomes will remain stable into the future. As Reichstein et al. (2025) argue
 926 in the context of early warning systems, relying on past norms and training distributions will prove inappropriate under non-
 927 stationary risk conditions, where projected increases in hazard frequency and severity, combined with shifting exposure and
 928 vulnerability, create conditions that fall outside the range of any historical training set. This is particularly acute for compound
 929 and cascading events, which are by definition rare in the historical record yet are precisely the configurations that climate
 930 change is projected to intensify.

931 A second limitation is the gap between hazard prediction and impact prediction. Most ML applications reviewed optimise for
 932 hazard or susceptibility metrics, but impact prediction requires integrating physical hazard outputs with dynamic exposure and

933 vulnerability data at sub-kilometre scales, a challenge that the reviewed papers largely sidestep by using static proxies. This
934 gap between technical model performance and actionable risk information represents one of the most important unresolved
935 challenges in translating ML-based risk assessment into operational decision-making (Tiggeloven et al., 2025, Reichstein et
936 al., 2025).

937 A third set of concerns relates to interpretability and trust. The black-box nature of deep learning models creates well-
938 recognised barriers to adoption in high-stakes regulatory and emergency management contexts, where stakeholders need not
939 only a prediction but a justification they can interrogate and contest. However, current XAI applications remain predominantly
940 proof-of-concept and are rarely integrated into operational early warning or risk assessment workflows (Ghaffarian et al.,
941 2023). Moreover, reproducibility and validation remain a persistent concern. In geoscientific applications, spatial
942 autocorrelation means that random train-test splits routinely inflate apparent model skill relative to genuinely independent
943 spatial holdouts (Sweet et al., 2023), and the reviewed literature shows limited adoption of spatially blocked cross-validation
944 or independent regional test sets. These limitations do not invalidate the contributions reviewed here, but they do underscore
945 the need for more rigorous validation protocols, realistic appraisal of out-of-sample performance, and explicit discussion of
946 the conditions under which ML approaches can be expected to generalise beyond their training contexts.

947 Another methodological gap identified by this review is the absence of end-to-end uncertainty quantification frameworks for
948 multi-hazard risk assessment. Current practice addresses UQ in fragments: aleatory uncertainty in input data is handled at the
949 start of the chain, epistemic uncertainty in ML models is occasionally addressed through Bayesian or ensemble methods at the
950 hazard stage, and copula-based approaches characterise joint uncertainty for statistically correlated hazard pairs, but these
951 efforts are rarely connected, and they do not extend to the full multi-hazard concept, which encompasses cascading and
952 triggered hazards beyond the reach of shared statistical distributions. A genuinely integrated framework would propagate both
953 aleatory and epistemic uncertainty continuously from input data through multi-hazard interactions, ML and statistical model
954 outputs, and exposure and vulnerability components, to the final risk estimate (Beven et al., 2018).

955 A further methodological consideration for future research is the development of data-driven frameworks that move beyond
956 static representations of vulnerability and exposure. The reviewed literature overwhelmingly treats these components as fixed
957 spatial layers, with limited engagement with their dynamic, socially differentiated, and governance-mediated dimensions.
958 Addressing this gap will require closer integration of ML and statistical methods with approaches capable of representing how
959 vulnerability evolves over time, including agent-based modelling, participatory data collection, and socially-informed
960 frameworks that explicitly account for adaptive behaviour, equity, and governance processes. Progress in this direction would
961 not only improve the realism of multi-risk assessments but also strengthen their relevance for policy and decision-making in
962 contexts where social vulnerability is itself a driver of risk (Cannon 2017; Bankoff and Hilhorst 2022).

963 Finally, the geographical distribution of the reviewed studies, visualised in the Sankey diagram in Appendix B, points to an
964 imbalance that is worth acknowledging explicitly. Europe, North America and East Asia together account for more than 80%
965 of lead authorships, while Africa and South America contribute less than 5%. This pattern partly reflects the Scopus, English-
966 only, 2010–2024 scope of the search strategy, which may systematically underrepresent research published in other languages

967 or in regional journals not indexed by Scopus. At the same time, the decoupling between authorship geography and case study
968 geography, with South/SE Asia, the Middle East, and Africa appearing more frequently as study areas than as sources of
969 authorship, suggests that data-driven methods are in several cases developed in data-rich institutional contexts and
970 subsequently applied to regions with different risk dynamics, data availability, and governance structures (Tiggeloven et al.,
971 2025). While drawing strong conclusions about data colonialism or algorithmic bias from a bibliometric analysis alone would
972 go beyond the scope of this review, these patterns do raise questions that the community should engage with: whether training
973 datasets and validation benchmarks are representative of the contexts in which models are ultimately deployed, and whether
974 the priorities shaping methodological innovation reflect the needs of the most exposed populations. Future work in this area
975 should pay closer attention to the transferability of data-driven multi-risk frameworks across different socio-economic and
976 data environments (Tiggeloven et al., 2025), and collaborative initiatives fostering locally-grounded research in currently
977 underrepresented regions would strengthen both the scientific robustness and the equity dimensions of the field (Naudé &
978 Viluesa, 2021).

979 **4 Conclusion**

980 This paper presents a comprehensive review of data-driven applications aimed at modelling and enhancing our understanding
981 of climate-related multi-hazard and multi-risk events. Based on the selection and in-depth analysis of 153 key papers, the
982 review addresses four research areas: (i) data processing and collection, (ii) hazard analysis, (iii) risk analysis, and (iv) future
983 risk scenarios, each divided into several sub-topics. The results highlight the strong connections between Earth observations
984 processing and ML techniques like CNN; on the other hand, RF, other ensemble methods and GAM are mostly applied for
985 risk impacts and future risk assessment, while LSTM, ANN and other DL approaches are most common for hazard prediction,
986 reflecting a growing trend toward leveraging sophisticated AI architectures for climate and hazards applications, and a focus
987 on simpler, more interpretable models for risk applications. Despite the current prevalence of single-hazard applications in ML
988 research, there is growing recognition of the importance of multi-risk strategies. Notable advancements include copula-based
989 compound event analyses and ML-driven multi-hazard susceptibility maps. Future research should prioritize a more
990 comprehensive understanding of multi-risk interactions – such as triggering, cascading, or amplifying effects – by considering
991 the interplay between hazard factors, vulnerability, and exposure dynamics, which are often overlooked or treated
992 independently in current studies. DL methods, with their capacity to capture complex, non-linear interactions across spatio-
993 temporal dimensions, offer promising avenues for progress, yet remain underexplored in operational multi-risk contexts.
994 However, these methods require high-resolution impact data, which remains a significant challenge due to limited availability,
995 inconsistency across regions, and issues of data quality and standardization. While EO and textual data can aid in generating
996 new multi-risk disaster catalogues, traditional sensor-based and human-curated disaster catalogues remain essential for
997 validation, representing a major bottleneck that constrains model validation, transferability, and ultimately the uptake of these
998 methods in practice. By addressing these methodological and data gaps, the field can move toward more robust, interpretable,

999 and actionable multi-risk assessments, ultimately strengthening the integration of machine learning into climate services that
1000 support adaptation, resilience, and disaster risk reduction.

1001 The gap between hazard prediction and impact prediction remains largely unresolved and bridging it will demand closer
1002 integration of data-driven model outputs with dynamic representations of exposure and vulnerability, including human
1003 behaviour, adaptive responses, and the social and governance dimensions that determine how risk is distributed across
1004 communities. Explainability is a further priority: XAI methods need to move beyond their current role as exploratory tools and
1005 be embedded into operational early warning and risk assessment workflows, where their ability to illuminate driver interactions
1006 and build stakeholder trust is most consequential. End-to-end uncertainty quantification across the full modelling chain remains
1007 absent and developing integrated frameworks that propagate both aleatory and epistemic uncertainty from inputs through
1008 multi-hazard interactions to the final risk estimate is one of the most important open methodological challenges for the field.

1009 Underlying all of these challenges is the problem of non-stationarity: as climate change intensifies hazard frequency and
1010 severity, shifts exposure and vulnerability, and increases the likelihood of compound and cascading configurations that fall
1011 outside any historical training set, the assumption that past conditions are a reliable guide to future risk becomes increasingly
1012 untenable, with direct consequences for the validity of ML-based projections of multi-risk evolution.

1013 Addressing these gaps, alongside the geographic and equity imbalances documented in this review, will require not only
1014 methodological innovation but also more inclusive research practices: collaborative frameworks that bring together physical
1015 scientists, social scientists, and communities in currently underrepresented regions, co-producing knowledge that is robust,
1016 transferable, and genuinely relevant to those most exposed to the evolving risks of a changing climate.

1017 **Author contribution**

1018 DMF: Conceptualisation, Methodology, Formal analysis, Investigation, Data curation, Visualisation, Writing – original draft.

1019 MS: Conceptualisation, Methodology, Validation, Writing – review and editing.

1020 MM: Conceptualisation, Data curation, Writing – review and editing.

1021 AC: Funding acquisition, Supervision, Conceptualisation, Writing – review and editing.

1022 ST: Funding acquisition, Supervision, Conceptualisation, Project administration.

1023 **Competing interest**

1024 The authors declare that they have no conflict of interest.

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