

Regional CO₂ and CH₄ inversion system using WRF-Chem (v4.4)/DART (v9.8.0) and continuous high-precision observations over the Korean Peninsula

Doyoon Kwon¹, Bonhoon Koo¹, Jooyeop Lee¹, Jeongwon Kim¹, Jaehyung Ahn¹, Jinkyu Hong¹, Eri Saikawa², Alexander Avramov², Changsub Shim³, Je-Woo Hong³, Daegeun Shin⁴, Shanlan Li⁴, Sumin Kim⁴, and Sangwon Joo⁴

¹Department of Atmospheric Sciences, Yonsei University, Seoul, 03722, Republic of Korea

²Department of Environmental Sciences, Emory University, Atlanta, GA, 30319, USA

³Korea Environment Institute, Sejong, 30147, Republic of Korea

⁴National Institute of Meteorological Sciences, Jeju-do, 63568, Republic of Korea

Correspondence to: Jinkyu Hong (jhong@yonsei.ac.kr)

Abstract Quantifying greenhouse gas (GHG) emissions over complex terrain remains a significant challenge for conventional inversion systems due to the high sensitivity of tracer transport to surface heterogeneity. We develop a high-resolution dual-species ~~greenhouse gas (GHG)~~ top-down inversion framework by integrating the Weather Research and Forecasting model coupled with Chemistry (WRF-Chem v4.4) and the Data Assimilation Research Testbed (DART v9.8.0) in a cycling ensemble Kalman filter system. Built on community tools, the framework is designed to be portable and configurable, enabling ~~application~~applications to other regions, resolutions, and observing-system configurations (e.g., expanded surface networks and additional data streams). This framework jointly assimilates near-surface CO₂ and CH₄ concentrations to produce dynamically consistent updates of emissions. By employing a unified Eulerian framework that simultaneously updates meteorology and 3-D tracer fields, the system ~~preserves the physical~~is designed to maintain consistency between transport and concentrations, ~~effectively reducing and to reduce the risk that~~ transport ~~bias-related concentration errors are aliased into flux~~adjustments over the complex landscapes of the Korean Peninsula. To improve the simulation of ~~GHG~~-turbulent GHG dispersion in the atmospheric boundary layer over complex terrain, we incorporate surface heterogeneity parameterizations (roughness sublayer and canopy height) into the model physics in the inversion system. The system assimilates high-precision continuous *in situ* observations from three World Meteorological Organization/Global Atmosphere Watch (WMO/GAW) stations to constrain CO₂ and CH₄ emissions. Prior flux estimates include anthropogenic emissions (EDGAR v8.0), biogenic exchanges (the region-optimized VPRM), biomass burning (FINN v2.5 ~~data~~), and oceanic CO₂ exchanges (SeaFlux ~~data~~). A twin OSSE (Observation system simulation experiment) demonstrates that a denser observing network substantially enhances the detectability of regional emission signals and provides a robust pathway for significant uncertainty reduction. These results ~~underscore the framework's infrastructure readiness to serve as a practical design tool for future observing network expansion and to support high-fidelity sub-national MMRV assessments.~~, and oceanic CO₂ exchanges (SeaFlux). In a 2020 case study, the top-down estimates improve the agreement with ground observations, reducing root-mean-square errors by 30–60 % and

~~reducing~~lowering posterior mean bias ~~of to~~ 1–102 ppm (for CO₂) and 20–30–60 ppb (for CH₄) at the high-precision surface observation sites. Independent aircraft profiles provide external evaluation and indicate residual CH₄ discrepancies consistent with ~~background~~prior emissions and boundary condition uncertainties. Posterior adjustments suggest reduced CO₂ emissions over the Seoul Metropolitan Area and parts of the western coastal region and increased CH₄ emissions over inland agricultural source regions relative to the priors, highlighting priorities for follow-on evaluation of inventory components. Our posterior CO₂ total (620 ± 45 Mt yr⁻¹) is ~~broadly~~consistent with the Republic of Korea Biennial Transparency Report (ROK-BTR) estimate (624 Mt yr⁻¹) at the national scale, while the posterior CH₄ totals show weaker agreement with available bottom-up estimates total (54.7 ± 5.2 Mt CO₂eq yr⁻¹) exceeds the ROK-BTR estimate (35.5 Mt CO₂eq yr⁻¹) by 19.2 Mt CO₂eq yr⁻¹. consistent with the larger structural uncertainty in CH₄ source characterization and spatial allocation noted in previous studies. ~~Overall, the framework provides a reproducible, scalable pathway toward multi-platform (satellite, aircraft, shipborne) integration for regional to national GHG assessment. A controlled twin OSSE (Observation system simulation experiment), used as an idealized information-content diagnostic, shows that emission constraints strengthen with denser surface observations under perfect-model assumptions but remain strongly dependent on observing-network density and prior-emission uncertainty.~~

1 Introduction

Anthropogenic emissions of greenhouse gases (GHGs) originate predominantly from fossil fuel combustion, land-use change, agricultural practices, and waste management. These emissions are the principal drivers of contemporary climate change. Reliable and continuous monitoring of anthropogenic GHG emissions is essential for the development of effective climate mitigation strategies, compliance with international climate agreements, and the formulation of informed policy decisions (IPCC, 2021; Friedlingstein et al., 2025). Under the Paris Agreement, national inventories serve as the principal reporting mechanism, delineating Nationally Determined Contributions (NDCs) and facilitating periodic stocktakes (UNFCCC, 2015). These inventories are a standard method within the Measurement-, Monitoring-, Reporting-, and Verification (MMRV) framework and rely on bottom-up methodologies based on activity data and emission factors within a tiered framework established by the Intergovernmental Panel on Climate Change (IPCC) (Ogle et al., 2013). However, their accuracy is often limited by incomplete or outdated activity data, coarse spatio-temporal resolution, diffusive GHG emissions, and systemic delays in updating or reporting inventories (Rogelj et al., 2016; Pauw et al., 2018). Even nations with advanced inventories encounter challenges in capturing rapid emission changes, fine-scale spatial heterogeneity, and localized sources, which ~~undermines~~undermine the inventory credibility and comparability of inventories (Denison et al., 2019; Nisbet et al., 2019; WMO, 2025).

Top-down approaches, which are based on atmospheric inverse modeling or atmospheric data assimilation (DA), offer independent assessments of emissions by constraining surface fluxes through atmospheric concentration measurements

65 (Enting, 2002; Gurney et al., 2002; Weiss and Prinn, 2011; Oda et al., 2019; Janssens-Maenhout et al., 2020; Elguindi et al.,
2020; Mueller et al., 2021; Deng et al., 2022; WMO, 2025). These methodologies are increasingly incorporated into MMRV
frameworks (WMO, 2022; 2025). By reconciling observed atmospheric concentrations with emission fluxes, top-down
approaches can identify unreported or misrepresented emission sources, detect biases, and provide spatially explicit, policy-
relevant emission information (Mueller et al., 2021; Janssens-Maenhout et al., 2020). Recent advancements in observational
70 infrastructure, including dense atmospheric observation networks, satellite platforms, and airborne measurements, have
enabled top-down systems to resolve emission patterns at urban and sub-national scales, thereby enhancing the fidelity and
applicability of MMRV systems (Lauvaux et al., 2020; Byrne et al., 2023; Velasco et al., 2023).

Atmospheric inverse modeling frameworks for GHGs ~~typically employ either Lagrangian or Eulerian methodologies, differ~~
~~in how they numerically represent tracer transport. Lagrangian-based inversion frameworks track approaches release virtual~~
75 air parcels ~~backward from at~~ receptor sites, ~~offering computationally efficient and track their trajectories backward through~~
~~prescribed wind fields, reconstructing source-attribution-influence functions from the particle paths~~ (e.g., Henne et al., 2016;
Pisso et al., 2019; Sijkumar et al., 2023; Brunner et al., 2025; Bukosa et al., 2025). ~~However, they depend on external~~
~~meteorological fields and background GHG concentrations, which limits their capability to accurately represent complex~~
~~boundary-layer dynamics~~ Eulerian approaches instead solve the advection-diffusion continuity equation for tracer mixing
80 ratios on a fixed spatial grid. Within the Eulerian class, global offline systems advect tracers through reanalysis wind,
convective mass-flux, and boundary-layer depth fields supplied at each integration step, while regional online-coupled systems
such as WRF-Chem integrate the meteorological state and the tracer fields through a single numerical framework, applying
the same advection operators, turbulence closures, and planetary-boundary-layer scheme to both. Representation errors in
boundary-layer dynamics and sub-grid mixing have been documented across inversion configurations in which meteorology
85 and tracer transport are treated through separate numerical pipelines (Bréon et al., 2015; Lauvaux et al., 2016; Dekker et al.,
2017; Super et al., 2017; Gaudet et al., 2021; Nalini et al., 2022; Bukosa et al., 2025). ~~Conversely, Eulerian frameworks solve~~
~~advection-diffusion equations directly on fixed spatial grids, allowing for a physically consistent coupling of meteorology and~~
~~tracer transport, particularly when integrated with ensemble-based DA techniques such as the Ensemble Adjustment Kalman~~
~~Filter (EAKF) (Anderson, 2001, 2003; Kang et al., 2012; Gaudet et al., 2021). Notable examples of operational Eulerian~~
90 systems include the NOAA (National Oceanic and Atmospheric Administration) CarbonTracker (van der Velde et al., 2018)
and ECMWF (European Centre for Medium-Range Weather Forecasts)'s CAMS (Copernicus Atmosphere Monitoring Service)
global reanalysis (Agustí-Panareda et al., 2023); however, these systems typically operate at relatively coarse resolutions of
about 1° which limits their effectiveness in capturing fine-scale emission heterogeneity in urban or mountainous regions
(Gurney et al., 2002; Locatelli et al., 2013; Zhang et al., 2014; Feng et al., 2019; Gaudet et al., 2021) Online-coupled integration
95 yields temporal and sub-grid consistency between the resolved flow and the simulated GHG evolution, which is particularly
suited to ensemble-based DA techniques (Kang et al., 2012; Gaudet et al., 2021), including the Ensemble Adjustment Kalman
Filter (EAKF) (Anderson, 2001, 2003).

These ~~limitations~~considerations motivate the development and documentation of complementary high-resolution Eulerian DA frameworks that can ~~consistently~~explicitly represent mesoscale transport and boundary-layer mixing over heterogeneous surfaces and ~~exploit~~expanding can be extended to future dense observing systems. The Weather Research and Forecasting model coupled with Chemistry (WRF-Chem) provides high-resolution, online coupling of meteorology and chemistry, while the Data Assimilation Research Testbed (DART) offers ~~a robust~~an ensemble-based DA platform for dynamically updating meteorological and chemical states ~~resolution~~. Accordingly, ~~the~~ WRF-Chem coupled with the DART has been used in CO₂ concentration, regional meteorology and air quality studies (e.g., Mizzi et al., 2018; Ma et al., 2020; Zhang et al., 2021a). Previous studies have demonstrated the feasibility of coupling WRF-Chem with DART for ~~CO₂~~CO₂ flux inversion using satellite ~~XCO₂~~XCO₂ retrievals in an ensemble Kalman filter framework (Zhang et al., 2021a; 2021b; Jin et al., 2025).

While these studies establish feasibility, they have primarily focused on single-species (~~CO₂~~) estimation constrained by intermittent satellite sampling ~~was attempted~~, and the extent of independent flux evaluation (e.g., using independent *in situ*/aircraft constraints) and controlled ~~robustness tests (e.g., OSSE-style experiments and systematic sensitivity tests to key uncertainty settings)~~sensitivity testing remains relatively limited for robust flux-inversion assessment. Furthermore, applications to CO₂ and CH₄ regional inversions at kilometer-scale transport resolution remain limited particularly in complex-terrain environments where transport–flux aliasing and representativeness errors can be substantial. To our knowledge, a fully documented WRF-Chem/DART regional inversion framework that simultaneously targets ~~CO₂~~CO₂ and ~~CH₄~~CH₄ emissions and assimilates both *in situ* GHG observations and meteorological fields within a cycling dual-state configuration has not yet been documented in the literature. The present study fills this gap by providing a reproducible dual-species (CO₂/CH₄CO₂/CH₄) state-augmentation system, including with explicit configuration choices ~~(uncertainties, including uncertainty assumptions, localization/inflation, observation selection, boundary condition handling) and controlled OSSE demonstrations alongside, together with a real-data experiments application and a limited supplementary OSSE diagnostic.~~

Here we extend the WRF-Chem (v4.4) and DART (v9.8.0) framework to implement a 9-km dual-species inversion system that cycles meteorological DA while assimilating near-surface CO₂ and CH₄ observations, directly updating meteorology and 3-D tracer fields and estimating surface flux adjustments through ensemble cross-covariances. We further incorporate surface-heterogeneity-related physics and land information (e.g., roughness-sublayer and canopy-height adjustments) tailored to the Korean Peninsula, where complex topography, coastal circulations, clustered emissions, and monsoon seasonality pose challenges for conventional inventories and coarse-resolution inversions (e.g., Hong and Kim, 2011; Hong et al., 2019; Hong et al., 2020; Lee et al., 2021; Kim et al., 2024). ~~To demonstrate framework performance beyond a single real-data case, we conduct a controlled OSSE (Observation system simulation experiment) with synthetic observations to assess flux signal detectability and uncertainty reduction under increased network coverage, and we evaluate a~~ The main practical assessment is based on the 2020 real-data application, using concentration-space diagnostics, flux uncertainty reduction, independent aircraft observations, and intercomparisons with multiple emission~~emission~~ datasets. ~~Together, these assessments demonstrate the~~

~~utility of to evaluate~~ the framework's ~~relevance~~ for ~~policy support and effective (sub)future~~ national MMRV-oriented applications.

135 2 Description of CO₂ and CH₄ inversion framework

2.1 Atmospheric modeling system

Our GHG inversion framework integrates a regional Eulerian atmospheric chemistry model with an ensemble-based data assimilation system. Specifically, this framework employs the Weather Research and Forecasting model coupled with Chemistry (WRF-Chem v4.4; Grell et al., 2005) and the Data Assimilation Research Testbed (DART v9.8.0) (Anderson et al.,
140 2009) for sequential data assimilation. WRF-Chem solves the fully compressible, nonhydrostatic Eulerian equations on a fixed spatial grid, and simulates atmospheric dynamics, physical and chemical processes, and chemical transport within a unified framework.

In the inversion system, WRF-Chem generates ensemble forecasts by simulating meteorology with surface fluxes and atmospheric transport processes of GHGs. Given the long atmospheric lifetime of GHGs, they have been simulated as passive tracers in mesoscale models (Dekker et al., 2017; Super et al., 2017; Zhao et al., 2023). WRF-Chem includes the module to
145 simulate passive tracer transport of GHGs since WRF-Chem v3.4 (Beck et al., 2012). In WRF-Chem, distinct variables represent background, anthropogenic, biomass-burning, oceanic (CO₂ only), and biogenic components of CO₂ and CH₄. The model simulates their fluxes, transport, and diffusion processes driven by the meteorological field to obtain a three-dimensional concentration field on an hourly basis. The total concentrations are represented as the sum of the component variables,
150 facilitating comparison with observed concentrations. CO₂ and CH₄ are treated as ~~a~~-passive ~~tracer~~tracers for our regional application because the relative chemical lifetime of CH₄ against OH is on the order of years (about 9 years), whereas typical air-mass residence times across our regional domain are <1 day (Callewaert, 2024; Zhao et al., 2020). Therefore, the implied fractional loss is negligible compared to transport and emission uncertainties. In addition, large-scale chemical aging and seasonality are already reflected in the prescribed initial and lateral boundary conditions.

Our study area consists of a single model domain with 9-km horizontal spacing of 97 × 136 grid points and 51 terrain-following vertical levels stretching from the surface up to 50 hPa at the upper boundary (Fig. 1). The model employed specific physics parameterization schemes (Kim et al., 2024 and references therein), including the WSM-6 microphysics, Rapid Radiative Transfer Model for General Circulation Models (RRTMG) shortwave and longwave radiation schemes, the Yonsei University scale-aware Planetary Boundary Layer (PBL) scheme, Kain-Fritsch cumulus scheme, and the Unified Noah Land
160 Surface Model (LSM).

Notably, for better simulations of GHG transport over complex terrain, we used the revised WRF-Chem by replacing the default WRF canopy height with high-resolution (~~4 km~~ 1 km) spaceborne lidar-retrieved canopy height data (GLAS/ICESat) for a better representation of surface characteristics (Lee and Hong, 2016). To simulate realistic transport and dispersion of

GHG in the PBL, we further adapted roughness sublayer (RSL) parameterization of Lee et al. (2020), which incorporated the RSL function from the unified theory of Harman and Finnigan (2007, 2008) and Harman (2012), into the revised MM5 surface layer scheme (Jiménez et al., 2012) and Unified Noah land surface model LSM in WRF. Hereafter, we refer to this modified WRF-Chem v4.4 as ~~the~~ WRF-Chem GHG.

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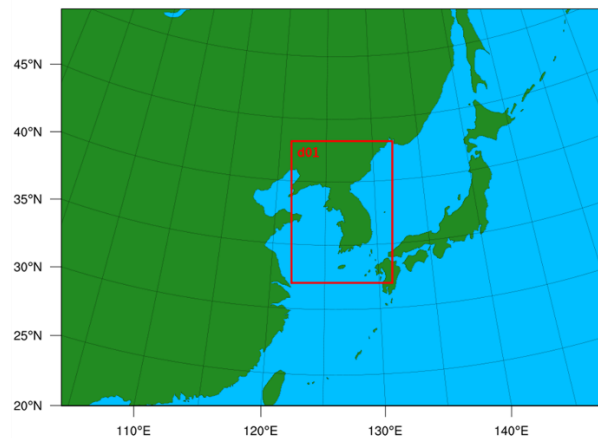


Figure 1. The WRF-Chem domain configuration used in this study.

2.2 DART data assimilation for GHG inversion

DART serves as a modular DA system designed to interface with various atmospheric models and observational datasets. The integration of WRF-Chem and DART enables the simultaneous assimilation of meteorological variables and chemical species through multivariate, dynamically consistent updates across the coupled system (Mizzi et al., 2016; Mizzi et al., 2018). The system operates as an ensemble of WRF-Chem forecasts, where each member represents a perturbed version of the state vector that accounts for both observational and model uncertainties. At each analysis cycle, ensemble perturbations are utilized to estimate a flow-dependent background error covariance, enabling the Ensemble Adjustment Kalman Filter (EAKF) to adjust both meteorological and tracer fields simultaneously in a dynamically balanced manner. This ensemble-based structure allows for uncertainty propagation, sequential updating of the background (prior) ensemble, and the maintenance of consistency between state variables during sequential assimilation. Hereafter, we refer to ~~the~~ WRF-Chem GHG coupled with DART as ~~the~~ WRF-Chem/DART.

Our work extends the DA system to facilitate the simultaneous assimilation of observed CO₂ and CH₄ concentrations with meteorological data at a spatial resolution of 9 km over the Korean Peninsula. The assimilated data include continuous *in situ* CO₂ and CH₄ concentrations, alongside standard meteorological observations from National Centers for Environmental Prediction (NCEP) automated data processing upper air and surface observations (PREPBUFR observations). Because meteorology is simulated and updated within the online WRF-Chem/DART cycling system (rather than prescribed as offline transport fields), the inversion does not rely on externally prescribed meteorological trajectories ~~and meteorological~~. Meteorological initial and boundary conditions (IC-/BCs hereafter) are provided from standard large-scale reanalysis products as in limited-area modeling.

We use an ensemble size of 20 members throughout the cycling assimilations in the WRF-Chem/DART system. The analysis directly updates the prognostic meteorological variables and 3-D tracer concentration fields each cycle, while emission adjustments are estimated as surface forcing parameters for the subsequent forecast, rather than being dynamically transported like tracer concentrations. This cycling approach helps preserve meteorology–transport–concentration consistency between the analyzed meteorology/tracer fields and the subsequent model transport in the ensemble forecasts. In the sequential EAKF framework, correcting the ~~prognostic~~ tracer concentration state at each analysis step (e.g., using the analysis field as the initial condition for the subsequent forecast) helps prevent the carry-over of transport-driven concentration biases and reduces the risk that these biases are aliased into inferred emission adjustments. As demonstrated in previous WRF-Chem/DART studies (Liu et al., 2017; Hsu et al., 2024), failure to correct the concentration state allows transport-driven biases to persist into subsequent forecast steps. The filter would then continuously interpret these persistent concentration residuals as evidence of flux errors, leading to the artificial amplification of emission estimates (over-adjustment) to compensate for accumulated biases. ~~By jointly updating the concentration state, the system effectively re-initializes the chemical conditions at each cycle, ensuring~~ For passive tracers such as CO₂ and CH₄, chemical loss is negligible at the cycling timescale, so transport-driven biases accumulate without meaningful attenuation. Similar concentration-state correction is applied in ensemble-based CO₂ flux estimation systems (Kang et al., 2011, 2012; Peng et al., 2015). By updating the concentration state at each cycle, the system ensures that emission adjustments are derived primarily from mismatches between model forecast and observation within the current assimilation window.

We implement this joint state–emission estimation using a state-augmentation approach in DART (Kang et al., 2011, 2012; Liu et al., 2017; Zhang et al., 2021a; Huang et al., 2022). The augmented state vector is defined as:

$$\mathbf{z} \equiv \mathbf{x} = [\mathbf{x}_{met}, \mathbf{x}_{chem}, \mathbf{x}_{flux}]^T \quad (1)$$

where $\mathbf{x}_{met}$ contains meteorological variables including zonal and meridional wind, temperature, specific humidity, and surface pressure (U, V, T, Q , and P_{sfc} respectively), $\mathbf{x}_{chem}$ contains three-dimensional CO₂ and CH₄ mixing ratios, and $\mathbf{x}_{flux}$ contains two-dimensional surface emission flux fields and is represented as time-indexed (e.g., hourly) flux fields that are

220 applied as external surface-forcing inputs to WRF-Chem during the subsequent forecast integration. At each analysis time, the deterministic EAKF updates the prior (background) augmented-state ensemble to the posterior ensemble:

$$\bar{\mathbf{z}}^u = \Sigma^u [(\Sigma^p)^{-1} \bar{\mathbf{z}}^p + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{y}^o] \quad (2)$$

$$\Sigma^u = [(\Sigma^p)^{-1} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H}]^{-1} \quad (3)$$

$$\bar{\mathbf{z}}_i^u = \mathbf{A}(\bar{\mathbf{z}}_i^p - \bar{\mathbf{z}}^p) + \bar{\mathbf{z}}^u, \quad i = 1, \dots, N \quad (4)$$

$$\mathbf{z}_i^u = \mathbf{A}(\mathbf{z}_i^p - \bar{\mathbf{z}}^p) + \bar{\mathbf{z}}^u, \quad i = 1, \dots, N \quad (4)$$

230 where $\bar{\mathbf{z}}^u$ and $\bar{\mathbf{z}}^p$ denote the posterior and prior ensemble means, respectively. The subscript i in $\bar{\mathbf{z}}_i^p$ and $\mathbf{z}_i^u$ indicates the i -th member of the prior/posterior ensembles, and N is the ensemble size. $\mathbf{y}^o$ is the observation vector including *in situ* CO₂/CH₄ and PREPBUFR meteorological observations, $\mathbf{R}$ is the observation-error covariance matrix, and $\mathbf{H}$ is the corresponding observation (forward) operator. Σ^p and Σ^u are the prior and posterior error covariance matrices, respectively. $\mathbf{A}$ is a transformation matrix satisfying $\Sigma^u = \mathbf{A} \Sigma^p \mathbf{A}^T$, consistent with the EAKF adjustment used here. Equations (2) and (3) provide
 235 a compact summary of the linear Kalman analysis in information form. In practice, DART implements the Ensemble Adjustment Kalman Filter (EAKF) as a deterministic, serial ensemble update in observation space, where each observation is assimilated sequentially using ensemble-estimated covariances with covariance localization. The ensemble adjustment matrix $\mathbf{A}$ in Eq. (4) is computed so that the posterior ensemble anomalies reproduce the localized posterior covariance in Anderson (2001, 2003), thereby avoiding the sampling noise associated with stochastic perturbations of observations. We refer to
 240 Anderson (2001, 2003) and Anderson et al. (2009) for the detailed mathematical and theoretical backgrounds for EAKF.

For *in situ* CO₂ and CH₄, we specify the observation error variance as $\sigma^2 = \sigma_{\text{meas}}^2 + \sigma_{\text{repr}}^2$, where σ_{meas}^2 is the measurement uncertainty reported for the WMO/GAW stations (Lee et al., 2019; Lee et al., 2023) and σ_{repr} is treated as a model–data mismatch term, not as an instrument error, and its magnitude is chosen to maintain stable cycling behavior and to avoid overfitting sparse point observations in a 9-km grid framework. Because σ_{meas}^2 is expected to be small for WMO/GAW-quality
 245 observations, σ_{repr} is treated as the primary contributor and is parameterized as a concentration-proportional term (as 5 % of the observed mole fraction) across all sites. This results in a relatively large effective error variance (typically ~20 ppm for ambient CO₂ and ~100 ppb of CH₄). This conservative parameterization is chosen not only to account for sub-grid variability but also to maintain analysis stability given the sparsity of the operational network. In data-sparse regions, relying too heavily on individual stations (via small observation errors) risks introducing spurious emission artifacts driven by local transport
 250 transients; a larger error specification mitigates this risk by ensuring that increments are driven only by persistent, robust signals. For PREPBUFR meteorological observations, we use the DART default observation error specifications based on the

NCEP operational error tables (e.g., rawin wind: 1.4–3.2 m s⁻¹, radiosonde temperature: 0.8–1.5 K, land station wind: 3.5 m s⁻¹, marine wind: 2.5 m s⁻¹, surface pressure: 1.0 hPa), which are platform- and pressure- (altitude) dependent.

Although the surface emission fluxes $\mathbf{x}_{flux}$ are not directly observed (i.e., $\mathbf{H}$ has no sensitivity to ~~flux elements~~ fluxes), they
255 are updated through the ensemble cross-covariances $\text{Cov}(\mathbf{x}_{chem}, \mathbf{x}_{flux})$. These flow-dependent covariances enable statistically
consistent flux adjustments that reduce concentration innovations, provided that physically plausible concentration–flux
relationships exist within the localization radius. ~~As noted above, these flux adjustments are estimated as time indexed forcing
parameters rather than being propagated as a dynamic prognostic state.~~ The updated emission fields are prescribed as static
260 ~~surface inputs that persist during the subsequent forecast window, rather than being advected as prognostic variables. Thus,
the emission corrections obtained at each analysis cycle propagate forward through the forecast into the next analysis cycle.~~
To suppress sampling error and spurious long-range correlations, we apply covariance localization using a Gaspari–Cohn
polynomial with a horizontal half-width of 0.025 rad ($\sim$ ~~450~~160 km) and a vertical normalization cutoff radius of 1.5 km,
constraining increments primarily to the lower troposphere and reducing under-sampling error (Gaspari and Cohn, 1999;
Anderson, 2012; Kang et al., 2012). Cross-species covariances are not applied; CO₂ and CH₄ tracers are updated independently.
265 To mitigate ensemble under-dispersion, we apply adaptive prior inflation in DART ($inf_factor = 2$). The inflation standard
deviation is initialized at 0.6 and damped by a factor of 0.9, with the maximum allowed change per cycle limited to 1.05.

Prior uncertainty is represented by applying Gaussian, multiplicative perturbations to the chemical initial state, lateral
boundary conditions, and anthropogenic emission fluxes when generating the forecast ensemble. For each ensemble member,
perturbation factors are drawn from normal distributions centered at unity, with 1 σ standard deviations of 5% for chemical
270 initial and lateral boundary conditions and 30% for anthropogenic fluxes. The former represents a pragmatic balance between
acknowledging residual uncertainty in the reanalysis inflow and preventing ensemble over-spreading that would overwhelm
regional increments, while the latter is chosen to span the inter-inventory discrepancies over the Korean Peninsula (see Section
~~76.4~~4 for details). The initial error configurations also align with those from previous studies (e.g. Zhang et al., 2021a, b).
Horizontal and vertical correlation lengths are specified as 200 km and ~~4km~~1 km, respectively.

275 Analyses are produced every six hours (00, 06, 12, 18 UTC) using observations within a ± 3 h window centered on the
analysis time; observations are rejected if they exceed three standard deviations of the background ensemble. The resulting
analyzed ensemble is then advanced with WRF-Chem to provide the background for the next cycle, updating the chemical and
meteorological initial conditions accordingly. To maintain dynamical consistency near the domain boundaries, the analysis
increments are propagated consistently into the lateral boundary tendencies used for the subsequent forecast, preventing
280 spurious discontinuities at the boundary interface. This is a numerical continuity treatment and does not constitute an
independent optimization of boundary inflow.

A controlled twin OSSE is provided in Supplement S2 as an auxiliary diagnostic of the implemented state-augmentation
machinery. The OSSE is not intended to demonstrate real-world robustness or operational flux accuracy. Instead, under
perfect-model assumptions, it evaluates how concentration innovations are transferred into emission increments through
285 ensemble-estimated concentration–flux covariances, and how this behavior differs between a dense synthetic network and the

present three-site network when a large prior-emission perturbation is imposed. Because the experiment excludes structural transport error, boundary-condition bias, and real-world representativeness errors beyond the prescribed stochastic component, its results are interpreted only at the regional to national scales supported by the synthetic observing networks.

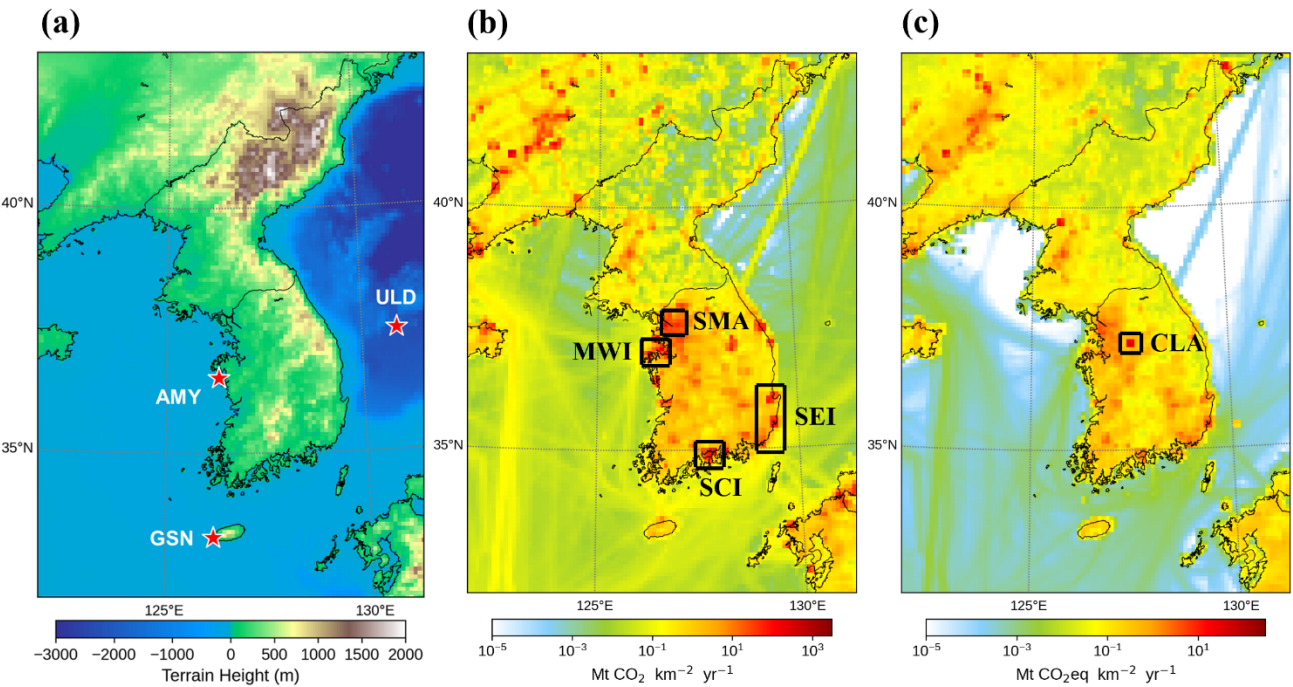


Figure 2. Locations of GHG monitoring stations (AMY, GSN, ULD) over terrain height (a) and annual anthropogenic emissions of CO₂ (b) and CH₄ (c) in the model domain in 2020 from EDGAR (v8.0). Main emission source regions in the model domain are boxed: (SMA: the (Seoul Metropolitan Area), MWI: (Mid-Western Industrial Area), SEI: South Eastern (Southeastern Industrial Area), SCI: (South Coast Industrial Area), and CLA: (Central Livestock Area).

3 Observation data of GHG concentrations and meteorological conditions for data assimilation

High-precision, continuous ground-based GHG measurements are essential for capturing high-frequency variability and providing constraints on regional enhancements near major source regions. To constrain CO₂ and CH₄ fields, the inversion framework assimilates *in situ* measurements of CO₂ and CH₄ concentrations from ~~World Meteorological Organization (WMO) Global Atmosphere Watch (GAW)~~ the WMO/GAW-affiliated monitoring stations at Anmyeondo (AMY), Gosan, Jeju Island (GSN), and Ulleungdo (ULD) operated by the Korea Meteorological Administration (KMA) (Fig. 2a). Depending on wind direction and atmospheric stability, ~~they sample~~these sites measure background inflow and downwind plumes from key

emission source regions (Fig. 2b and 2c). We therefore retain pollution events (no background selection) and rely on the coupled transport + localization to attribute information primarily within the dynamically connected influence region, and localization to attribute information primarily within these key source regions. ~~The new surface parameterizations adopted in this study improve wind simulations near the surface (e.g., Lee et al., 2015; Lee and Hong, 2016; Lim et al., 2019; Lee et al., 2020; Kim et al., 2024; Lee et al., 2024; Jo et al., 2025; WMO, 2025). For reference, we provide concise verification of modeled 10-m winds with Korea Meteorological Administration (KMA) ASOS observations at GSN and ULD and refer to Supplement (Fig. S1–S2 and Table S1).~~

Each site employs a harmonized measurement system based on cavity ring-down spectroscopy (CRDS, Picarro Inc., USA), paired with a custom cryogenic drying system jointly developed by KMA and the Korea Research Institute of Standards and Science. This setup ensures high-precision CO₂ and CH₄ measurements with minimal water vapor interference, critical for ensuring data quality under Korea’s seasonally variable meteorological conditions. Data are collected at 1-minute intervals, processed hourly into Level-2 quality-assured products. Here, Level-2 denotes QA/QC screening and calibration processing, distinct from ‘background-selected’ products that apply additional baseline selection. All stations are operated as GAW monitoring stations with documented QA/QC and are used here to constrain regional-scale enhancements rather than micro-scale local fluxes. It is worth noting that this Level-2 dataset excludes instrumental artifacts (e.g., calibration periods) but retains local and regional pollution events without applying background selection filters, ensuring that the high-concentration signals required for regional inversion are preserved. Further details on instrument calibration, QA/QC protocols, and traceability to international standards for CO₂ and CH₄ observations at WMO/GAW sites in Korea can be found in Lee et al. (2019) and Lee et al. (2023), respectively.

The new surface parameterizations adopted in this study improve wind simulations near the surface (e.g., Lee et al., 2015; Lee and Hong, 2016; Lim et al., 2019; Lee et al., 2020; Lee et al., 2023; Kim et al., 2024; Jo et al., 2025; WMO, 2025). For reference, we provide concise verification of modeled 10-m winds with KMA’s Automated Synoptic Observing System (ASOS) observations at Seosan (~32 km NNE of AMY), ULD, and GSN, complemented by a comparison against the marine meteorological observation buoy ~18 km east of ULD (Fig. S1–S2 and Table S1). At ULD (a steep volcanic island in open ocean, ~73 km² in area with a peak rising to ~984 m, comparable in extent to a single grid cell), the model exhibits relatively large wind errors that the grid cannot fully resolve; the buoy comparison shows substantially better model agreement with the surrounding marine wind field, while indicating a possible discrepancy related to local topographical representativeness rather than systematic regional transport bias.

In addition, we assimilate conventional meteorological observations from the NCEP PREPBUFR datasets. These include surface pressure, near-surface air temperature, wind speed and direction, and specific humidity, as well as sea surface temperature and upper-air wind observations (including satellite-derived winds, radiosonde soundings, and aircraft reports of winds, temperature, and humidity). Assimilating these data effectively constrains the meteorological state (winds, temperature, and humidity), thereby improving transport fidelity in the coupled WRF-Chem/DART system, consistently consistent with the previous applications (Mizzi et al., 2016; Mizzi et al., 2018; Pouyaei et al., 2023).

335 4 Initial and boundary conditions for meteorological variables and GHG concentrations

Meteorological initial and boundary conditions are obtained from the hourly ERA5 global reanalysis ~~hourly single level and pressure level~~ data at $0.25^\circ \times 0.25^\circ$ resolution (Hersbach et al., 2020; Hersbach et al., 2023a, 2023b). The initial and boundary conditions are preprocessed by the WRF Preprocessing System (WPS) to the model grid and then perturbed by the WRF Data Assimilation System (WRFDA) ~~based on~~, as described in previous studies (Barker et al., 2012; Mizzi et al., 2016; Liu et al., 340 2017; Zhang et al., 2021b).

Initial and boundary conditions of CO₂ and CH₄ are provided by the ECMWF CAMS global ~~greenhouse gas~~ GHG reanalysis (EGG4 hereafter) data (Inness et al., 2019; Agustí-Panareda et al., 2023). EGG4 applies 4D-Var data assimilation of *in situ* networks and satellite retrievals within the ECMWF's Integrated Forecast System (IFS Cycle 47R1) and currently covers the period of 2003–2020. The dataset provides atmospheric mixing ratios of CO₂ and CH₄, along with meteorological and 345 chemical variables on regular $0.75^\circ \times 0.75^\circ$ grid ~~on~~ 25 pressure levels and 60 hybrid σ -pressure vertical levels at 3-hourly intervals. EGG4 data as initial and lateral boundary conditions help ~~to~~ ensure that large-scale seasonal and regional variability and the growing season CO₂ drawdown ~~is~~ are represented in the background fields.

Previous evaluations indicate that EGG4 reanalysis data may exhibit systematic biases. Overall errors in CO₂ and CH₄ concentrations are within 10 ppm and 40 ppb near the Earth's surface (Agustí-Panareda et al., 2023). Validation of EGG4 data 350 against Total Carbon Column Observing Network (TCCON) measurement shows standard deviations of the difference of 1.18 ppm for XCO₂ and 11.3 ppb for XCH₄ (Wang et al., 2023). Notably, it has been reported that EGG4 data have a positive bias of CO₂ ~~concentration~~ concentrations in high-~~emission~~ regions, and its mean bias is about 7.46 ppm in Asia (Custódio et al., 2022). Regional biases can be systematic and location-dependent; for example, a negative bias of about 30 ppb in CH₄ concentration has been reported at the NOAA flask site in the ~~mid-western~~ midwestern industrial region (MWI) (Segato et al., 355 2025). We also note that even though EGG4 accounts for large-~~scale~~ CH₄ oxidation, ~~is~~ uses it relies on prescribed OH fields (or climatological loss rates) rather than interactive chemistry. ~~Consequently, this reliance on a~~ This parameterized sink can ~~contribute to introduce~~ systematic errors in CH₄ concentrations, ~~particularly~~ where the prescribed loss rates ~~do not reproduce~~ fail to capture local and temporal variability ~~of~~ in photochemical ~~loss properly~~ destruction (e.g., Zhao et al., 2020; Agustí-Panareda et al., 2023). We summarize these boundary-driven bias characteristics as diagnostic context to motivate our boundary- 360 condition uncertainty treatment and to aid the interpretation of residual baseline behavior discussed in Section 76.

5 Prior fluxes

5.1 Anthropogenic emissions

Within the domain, WRF-Chem simulates GHG transport and adds contributions from local surface emissions and sinks. Anthropogenic CO₂ and CH₄ emissions used as prior fluxes are regridded from the EDGAR global GHG emission inventory 365 version 8.0 (Crippa et al., 2023). EDGAR provides anthropogenic emissions data in accordance with IPCC-compliant

methodologies based on international activity data and emission factors (Janssens-Maenhout et al., 2019, Crippa et al., 2024). In EDGAR, the sectoral composition differs markedly between CO₂ and CH₄ over South Korea. CO₂ emissions are dominated by the power, energy, and industrial sectors (combustion and processes), with additional contributions from transport, fuel exploitation, and buildings (and minor contributions from remaining sources). In contrast, CH₄ emissions are dominated by agriculture and waste, followed by fuel exploitation, while other sectors are comparatively minor. It is also worth noting that wetland-like CH₄ emissions from rice paddies are categorized under the anthropogenic agricultural sector in EDGAR and are therefore included in our prior emissions. The inventory data used in this study, EDGAR₂, does not include natural wetland methane emissions and it is reported that annual CH₄ emission from natural wetlands in Korea is about 0.001 – 0.01 Tg CH₄ (Zhang et al., 2025). This is less than 0.5% of the national total anthropogenic CH₄ emissions.

Annual spatial distributions of CO₂ and CH₄ emissions across the domain are shown in Fig. 2. To consider temporal variability in CO₂ ~~emission~~emissions by human activities and disaggregate to hourly emissions, we apply the monthly and diel scaling ~~factor~~factors reported by the EDGAR and the gridded Temporal Improvements for Modelling Emissions by Scaling (TIMES) factors, respectively. These account for building heating/cooling usage patterns, traffic volume fluctuations, sectoral contributions (residential, commercial, transportation emission), and weekday-weekend differences at 0.25° × 0.25° resolutions (Nassar et al., 2013). Over ocean grid cells, EDGAR emissions are near zero except along major shipping lanes (if included in the selected EDGAR sectors). For CH₄ anthropogenic emissions, no diurnal TIMES disaggregation is applied; temporal variation is retained at the monthly level.

The spatial distribution of annual anthropogenic CO₂ and CH₄ emissions highlights the main source regions within the model domain (Fig. 2b and 2c). Strong CO₂ emissions in the Seoul Metropolitan Area (SMA) reflect aggregated contributions from power plants, traffic, and building emissions in the urban area. Industrial processes and power generation dominate emissions in the MWI and south and southeastern coast industrial corridors (SCI and SEI) over the Korean Peninsula (Fig. S3). CH₄ sources are generally coincident with strong CO₂ emission regions due to waste management in highly populated area but ~~exhibit~~exhibit more spatially confined peaks with hotspots over the high-density urban area (SMA) (wastewater and landfills), and central livestock area (CLA) (enteric fermentation and manure management) (Fig. S4).

5.2 Biomass burning emissions

Biomass burning emissions of CO₂ and CH₄ are taken from the Fire Inventory from the National Center for Atmospheric Research (NCAR) (FINN version 2.5). This dataset estimates biomass burning emissions using burned-area calculations, year-specific land cover and vegetation datasets, fuel loading and emission factors, and the use of multiple fire-detection satellites, such as MODerate resolution Imaging Spectroradiometer (MODIS) and Visible Infrared Imaging Radiometer Suite (VIIRS) (Schroeder et al., 2014). FINN provides emissions at 1 km spatial resolution and daily temporal resolution (Wiedinmyer et al., 2011; Callewaert et al., 2022; Wiedinmyer et al., 2023). The NCAR ~~(National Center for Atmospheric Research)~~ fire-emission preprocessing tool is used to subset the inventory over the modeling domain, regrid it to the model grid, and temporally

disaggregate it to hourly emissions for ~~the~~-WRF-Chem GHG simulations. Biomass burning emissions show strong spatial and seasonal variability in our domain (Fig. S5 for CO₂ and Fig. S6 for CH₄). Seasonal enhancements are primarily observed in spring (March–May), possibly related to agricultural residue burning and land-clearing practices. The total contribution of biomass burning emissions over the Korean Peninsula is negligible compared with anthropogenic emissions (< 0.1%) during the study period (2020).

5.3 Ocean CO₂ exchanges

Air-sea CO₂ exchange is obtained from the latest SeaFlux Ocean Carbon Dioxide Flux product (v2023.02) (Roobaert et al., 2018; Fay et al., 2021; Roobaert et al., 2019). This dataset combines five meteorological reanalysis data with six ocean surface CO₂ datasets, making a total of 30 combinations of the data products. These data provide monthly ocean CO₂ fluxes on a 1°×1° grid for 1990–2022. For this study, ensemble-mean monthly exchanges are used for oceanic CO₂ fluxes and prescribed as hourly fluxes (i.e., held constant throughout each month without sub-monthly or diurnal variability). Monthly distribution of oceanic CO₂ exchanges over East Asia shows that the Yellow Sea and nearby shelves exhibit seasonal reversals in oceanic CO₂ fluxes (i.e., net uptake during winter and spring and a source in summer) (Fig. S7) (Gregor and Fay, 2021). In contrast, the deeper East Sea acts as a persistent CO₂ sink. Although these patterns reflect known contrasts between shallow shelves and deep basins, the oceanic flux magnitude in our domain configuration is small relative to ~~the~~ dominant anthropogenic and terrestrial biogenic CO₂ sources and ~~sinks~~sinks.

5.4 VPRM-based estimation of terrestrial ecosystem fluxes

Terrestrial ecosystem carbon fluxes are estimated with the Vegetation Photosynthesis and Respiration Model (VPRM) coupled with ~~the~~-WRF-Chem- (Ahmadov et al., 2007; Mahadevan et al., 2008). VPRM simulates net ecosystem exchange (NEE) of CO₂ using meteorological drivers and satellite-derived surface indices, specifically the Enhanced Vegetation Index (EVI) and Land Surface Water Index (LSWI) from MODIS Terra surface reflectance 8-Day 500m product (MOD09A1). During model integration, VPRM computes Gross Primary Production (GPP) and ecosystem respiration (RES) and derives NEE as ~~RESP-NEE~~RES-GPP (negative NEE indicates net uptake in our sign convention) for eight land-cover categories using EVI, LSWI, 2 m air temperature, and ~~photosynthetically active radiation~~Photosynthetically Active Radiation (PAR) derived from downward shortwave radiation simulated by ~~the~~-WRF-Chem. Vegetation inputs (plant functional type, vegetation cover fraction, EVI, and LSWI) are derived from the 1-km SYNMAP global land cover data and MOD09A1 and are preprocessed using the VPRM preprocessor (Jung et al., 2006). VPRM-derived terrestrial CO₂ fluxes are sensitive to parameters linking EVI, LSWI, temperature, and radiation to GPP and RES (Hilton et al., 2013; Dayalu et al., 2018; Li et al., 2020). Because each vegetation type has distinct responses to environmental drivers, parameter calibration is critical to reduce NEE biases ~~with~~

plant function types across Plant Functional Types (PFTs), i.e., vegetation categories). In this study, we adopt a single parameter λ (maximum light use efficiency, PAR_0 : half-saturation value of PAR, α : temperature sensitivity of respiration, and β : basal respiration rate) applied uniformly across PFTs (vegetation categories) reported by Li et al. (2020), which has been validated for East Asian land-cover conditions to better capture seasonal and ecological variations across the Korean Peninsula.

Terrestrial biogenic CO₂ fluxes from the VPRM show strong seasonality driven by photosynthetic activity and temperature-dependent respiration (Fig. 3a). Croplands, deciduous, and mixed forests dominate in the model domain and contribute most to net carbon uptake during the growing summer season. Savanna and shrubland play minor roles in total uptake due to their limited areal extent. Monthly NEE shows clear net carbon uptake (negative values) in the summer growing season (May to September) with the strongest uptake (i.e., most negative NEE) in July when GPP exceeds RES, with relatively larger uncertainties in biogenic CO₂ fluxes. The monthly mean diurnal cycles of GPP, RES, and NEE further highlight that daytime GPP peaks in summer is mainly driven by higher incoming shortwave radiation and by more gradual, temperature-driven RES associated with the seasonal march progression of the summer monsoon (Fig. S8) (Hong et al., and Kim, 2011). For 2020, the integrated NEE over South Korea is -43 Mt CO₂ (5% of national anthropogenic GHG emissions) and broadly consistent with the national inventory estimate of the Land Use, Land Use Change and Forestry (LULUCF) sink (-39 Mt CO₂; Ministry of Environment, Republic of Korea, 2025), indicating that the VPRM biogenic fluxes reasonably represent the terrestrial carbon sink in this system.

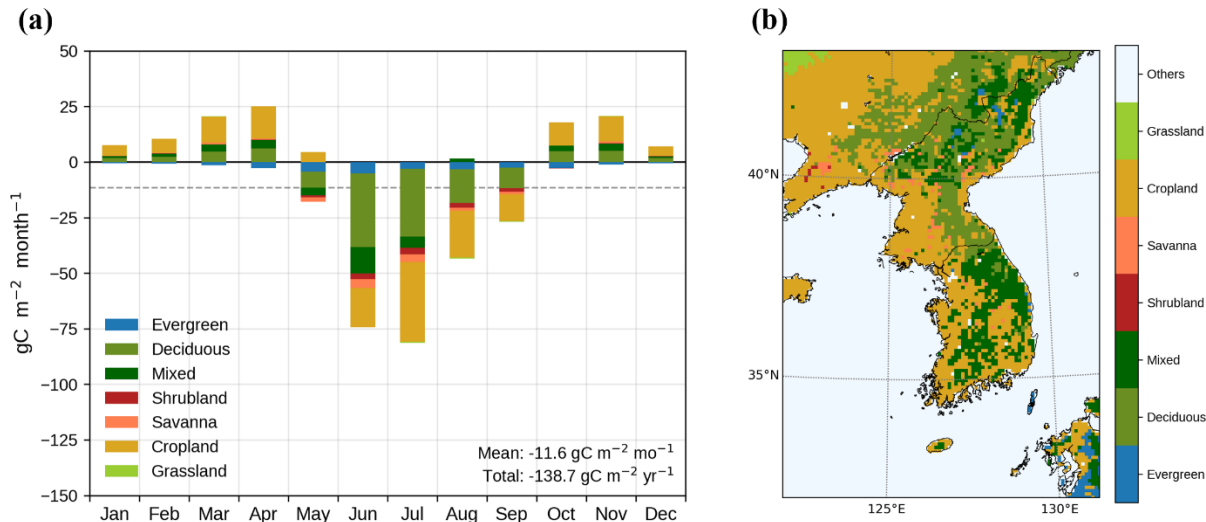


Figure 3. (a) Monthly net ecosystem exchange (NEE) contributions by vegetation class over the model domain in 2020. Bars show class totals (g C m⁻² month⁻¹), computed as spatial averages over grid cells of the corresponding vegetation type; negative values indicate net carbon uptake. (b) Spatial distribution of dominant vegetation classes used in WRF-Chem/VPRM; each grid cell is assigned the class with the largest vegetation fraction. Colors are consistent across panels.

6 Observation system simulation experiment (OSSE) with an expanded surface network

6.1 OSSE overview and experimental objectives

To provide a self-consistent proof of concept of the coupled WRF-Chem/DART top-down GHG estimation framework, we conduct an Observation System Simulation Experiment (OSSE) that evaluates the system's flux recovery capabilities under a controlled, idealized experimental setup. The OSSE is designed as a standard twin experiment in which synthetic observations are generated from a “truth” simulation and subsequently assimilated to assess whether the system can recover the imposed emission signal. Here we focus on CO₂ to provide a compact and interpretable illustration of flux recoverability; the same assimilation architecture is directly applicable to CH₄, and both species are demonstrated in Section 7 using operationally available WMO-GAW *in situ* observations in a real data application.

The twin experiment uses an expanded synthetic observing system comprising 50 surface sites, primarily concentrated over South Korea and located near major emission source regions. This hypothetical network is designed to test information gain under enhanced coverage, and to provide complementary evidence for how posterior constraints are expected to strengthen when observational coverage is substantially increased in a controlled twin setting. It is worth noting that this OSSE is a perfect model twin experiment: the same WRF-Chem configuration (physics, meteorological IC/BCs, and model operators) is used for both the nature run and the assimilation experiments, and the only imposed difference is the anthropogenic emission field.

6.2 Controlled twin experiment with a synthetically imposed missing power industry emission signal

The OSSE is conducted for the 2020.03.01–2020.03.17 period. Data assimilation cycle iterates every 6 hours, starting at 00 UTC on 2020.03.03 and continues for 14 days, following a 48-hour spin-up. The nature run (representing the “truth”) is generated with WRF-Chem using EDGAR CO₂ emissions for March 2020. This truth simulation is performed without data assimilation and provides dynamically consistent meteorology and tracer fields used to generate synthetic observations.

To define a clear and interpretable emission target for the OSSE, the corresponding inversion (prior) configuration uses EDGAR March 2020 CO₂ emissions with the power industry sector removed (“EDGAR without power industry”; Fig. 4a). This idealized “sector removal” setup therefore benchmarks whether the assimilation system can recover the missing emission contribution (the “true difference”) from concentration data under controlled, perfect model conditions. The removed EDGAR power industry sector accounts for 36.5% of domain total CO₂ emissions, increasing to 44.7% of emissions over South Korea, thereby imposing a substantial signal for the assimilation system to recover. By removing such a major component, the experiment imposes a substantial, spatially localized signal that is, in principle, detectable. This ensures the OSSE presents a strong signal recovery test rather than a weak signal detection problem.

Synthetic observations are generated by sampling hourly nature run CO₂ fields from 50 surface sites distributed across the model domain (shown as triangles in Fig. 4). The observation network in the OSSE is designed to cover strong CO₂ emission regions and maintain a minimum site spacing of approximately 30 km to increase sensitivity diversity while avoiding excessive

redundancy in South Korea. Hourly CO₂ concentrations from lowest model level of the nature run are interpolated to each site location to construct the synthetic time series. The observations are assimilated using the same temporal handling as the cycling system (e.g., hourly observations assimilated within ± 3 h window).

To emulate realistic measurement and representativeness uncertainty as in real applications, random observation error is introduced to each synthetic observation. These errors are assumed to be unbiased and Gaussian, specifically to match the real-data strategy described in Section 2.2: the error magnitude is dominated by the representativeness term and is parameterized as 5% of the sampled mole fraction. Ensemble perturbations for emissions and IC/BCs are generated following the exact strategy used in the real-data simulations. Furthermore, all other model inputs and ancillary datasets are kept identical to those in the real-data configuration to isolate the impact of observational density in a controlled twin setting.

6.3 Assimilation configuration for the OSSE

This OSSE is intentionally configured as a flux recovery capability test under perfect transport; meteorological variables are excluded from the augmented state to isolate the concentration-flux mapping and avoid conflating flux recoverability with transport uncertainty. The real-data experiments retain the full dual-state configuration. The assimilation step in the OSSE follows the WRF Chem/DART cycling framework described in Section 2: employing the EAKF with state augmentation to jointly estimate both GHG-tracer field and surface flux parameter. The augmented state includes (i) 3-dimensional CO₂-mixing ratios, and (ii) 2-dimensional anthropogenic flux scaling (or flux parameter) fields. The transport model configuration and meteorological IC/BCs are identical to those used in the synthetic truth generation.

Compared to the baseline real-data configuration, minor adjustments are made for the OSSE to ensure filter stability with the denser synthetic network: a minimum site spacing of approximately 30 km to increase sensitivity diversity while avoiding excessive redundancy. Specifically, the correlation length is set to 40 km and the localization half-width to 0.01 radians (~ 64 km) horizontally, deliberately avoiding over-tuning the system to the known truth. This configuration mimics a realistic operational capabilities assessment (where true error statistics are unknown) rather than a theoretically idealized scenario. This ensures that the evaluation isolates the impact of expanded network density, rather than the effects of perfect parameter optimization.

6.4 Emission estimation under a dense surface observational network

OSSE performance is evaluated against the known truth using diagnostics that target both emissions and concentration-space behavior. We examine: (1) the ability to recover the imposed emission signal (here, the missing power industry contribution) via comparison of posterior emission increments with the known “true difference”; (2) posterior uncertainty reduction for emission parameters. The OSSE demonstrates that the assimilation effectively recovers the spatial structure of the imposed emission signal. The posterior emission increment (post-prior) exhibits a distribution that is broadly consistent with the “true difference” associated with the excluded power industry emissions (compare Fig. 4b with Fig. 4a). The strongest adjustments occur in regions with the largest imposed emission differences and frequent downwind sampling by the expanded observing

network. Correspondingly, posterior emission uncertainty reductions, quantified by the decrease in ensemble spread (standard deviation) relative to the prior, are concentrated and strongest near the synthetic site clusters and major source regions, yielding a domain-wide mean reduction of 18.1% and a larger reduction of 34.1% over South Korea due to the concentrated observation sites (Fig. 4e). The percent-change increment highlights where posterior adjustments are large relative to the prior magnitude (Fig. 4d), although this metric should be interpreted with caution in areas where prior emissions are very small.

In addition to the spatial diagnostics, we examine the South Korea integrated CO₂ emission budget to quantify recovery of the imposed missing sector signal in the best-observed region. We report both the mean flux correction integrated over the OSSE period and the equivalent annualized rate. Over South Korea, the gap between the truth (“control”) and prior emissions is approximately -215 Mt yr^{-1} . After the 14-day OSSE cycling period, the posterior emission closes 103.2 Mt yr^{-1} of this gap (a recovery rate of 49.3%). Expressed as an increment ratio, the assimilation increases total CO₂ emissions of South Korea by 21.5% relative to the prior. These recovery rates should be interpreted as a conservative lower bound. The partial quantitative recovery reflects two primary constraints: the short duration of the total assimilation period (14 days) relative to typical flux convergence timescales (monthly to annual), and the use of an operationally representative, conservative filter configuration (assuming observation errors of $\sim 20 \text{ ppm}$). By avoiding idealized tuning—which would artificially maximize signal recovery in a perfect model setting with substantially lower error characteristics—we demonstrate that the expanded network successfully identifies the spatial structure and direction of the missing signal even under a cautious data assimilation setup. Thus, the results confirm robust signal detection capabilities, with the expectation that quantitative recovery would increase substantially over a longer period or with more optimized, situation-specific tuning.

Finally, it is important to note that the imposed power industry signal is highly heterogeneous and dominated by discrete large point sources. Accordingly, the OSSE should be interpreted as a test of whether the system captures the dominant, observation-constrained emission corrections, rather than a pixel-by-pixel reconstruction of individual point sources. In addition, because emission updates are formulated with a prior-proportional (multiplicative) error structure, recoverability is inherently limited where prior emissions are near zero; this also motivates a cautious interpretation of percent-change increments in low-emission grid cells (Fig 4d). Overall, the OSSE constitutes a stringent stress test, and the coherent recovery of the main spatial signal and the localized uncertainty reduction near the dense observing network support that the framework is performing as intended.

6.5 Implications

The controlled twin-experiment provides a compact technical illustration of framework behavior under substantially expanded observational coverage. Using a dense 50-site synthetic surface network, the system produces coherent analysis increments and substantially stronger, more spatially informative emission constraints over the well-sampled region, reflected in larger posterior uncertainty reduction. Importantly, this behavior is demonstrated under an intentionally demanding target signal defined by omission of the power industry sector, which is point-source-dominated and highly heterogeneous.

Crucially, these results were achieved using a standard, representative assimilation configuration rather than one hyper-tuned to the specific OSSE truth. The fact that the system successfully recovered the dominant spatial signals without requiring idealized, perfect model parameter optimization underscores the robustness of the dense network itself. It suggests that the reported information gains are driven by the improved observational coverage, rather than by artificial tuning advantages.

These results additionally underscore the framework's powerful potential as a practical tool for designing and exploiting denser regional observing systems, with the goal of better diagnosing inventory uncertainties and supporting iterative inventory characterization and refinement. This OSSE clarifies the expected direction and spatial structure of constraint gains as observational density increases, providing a controlled complement to the real data demonstrations that follow in the next section.

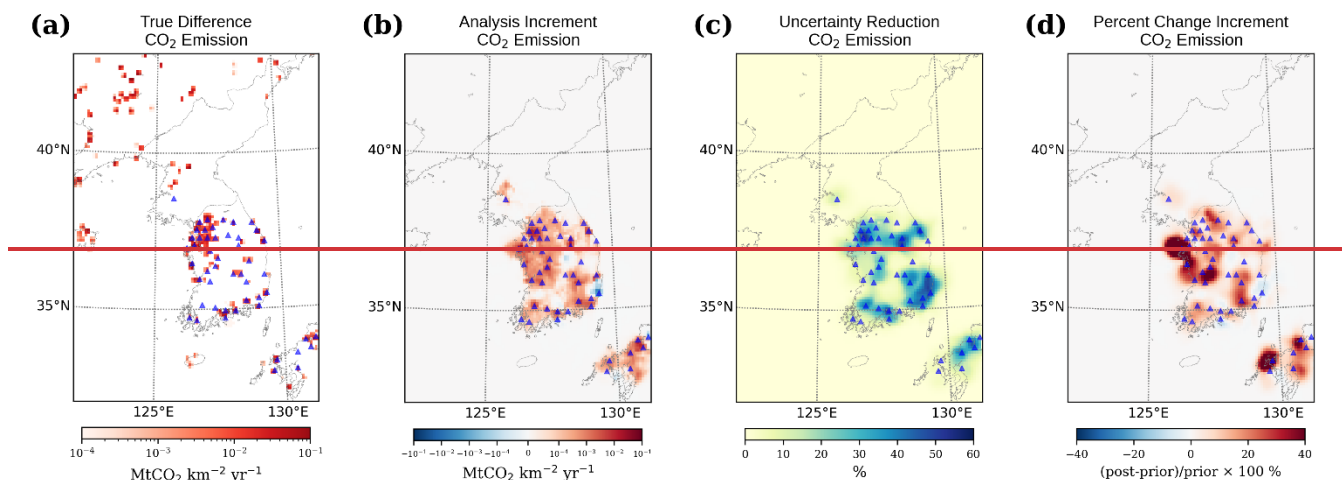


Figure 4. Temporal-mean OSSE diagnostics for CO₂ emissions using the expanded 50-site synthetic surface network over the OSSE DA cycling period (2020-03-03 00 UTC–2020-03-17 00 UTC). (a) Imposed target (“true difference” in CO₂ emissions), defined as EDGAR (full) minus EDGAR without the power industry sector. (b) Analysis increment (posterior minus prior) in CO₂ emissions from the OSSE inversion. (c) Posterior uncertainty reduction for CO₂ emissions expressed as the percent decrease in ensemble spread (standard deviation) relative to the prior. (d) Percent change increment in CO₂ emissions, computed as (posterior minus prior) divided by the prior. Triangles denote the locations of the 50 synthetic surface observation sites. All emission panels are shown in flux unit of Mt CO₂ km⁻² yr⁻¹. Red (blue) shading indicates an increase (decrease) in the posterior relative to the prior. Panels (a) and (b) are displayed on a logarithmic color scale to visualize the highly skewed, point-source-dominated imposed signal, and percent change increments in (d) are masked where prior emissions are below a small threshold to avoid spurious values.

6 Evaluation of the top-down estimates for 2020 case study

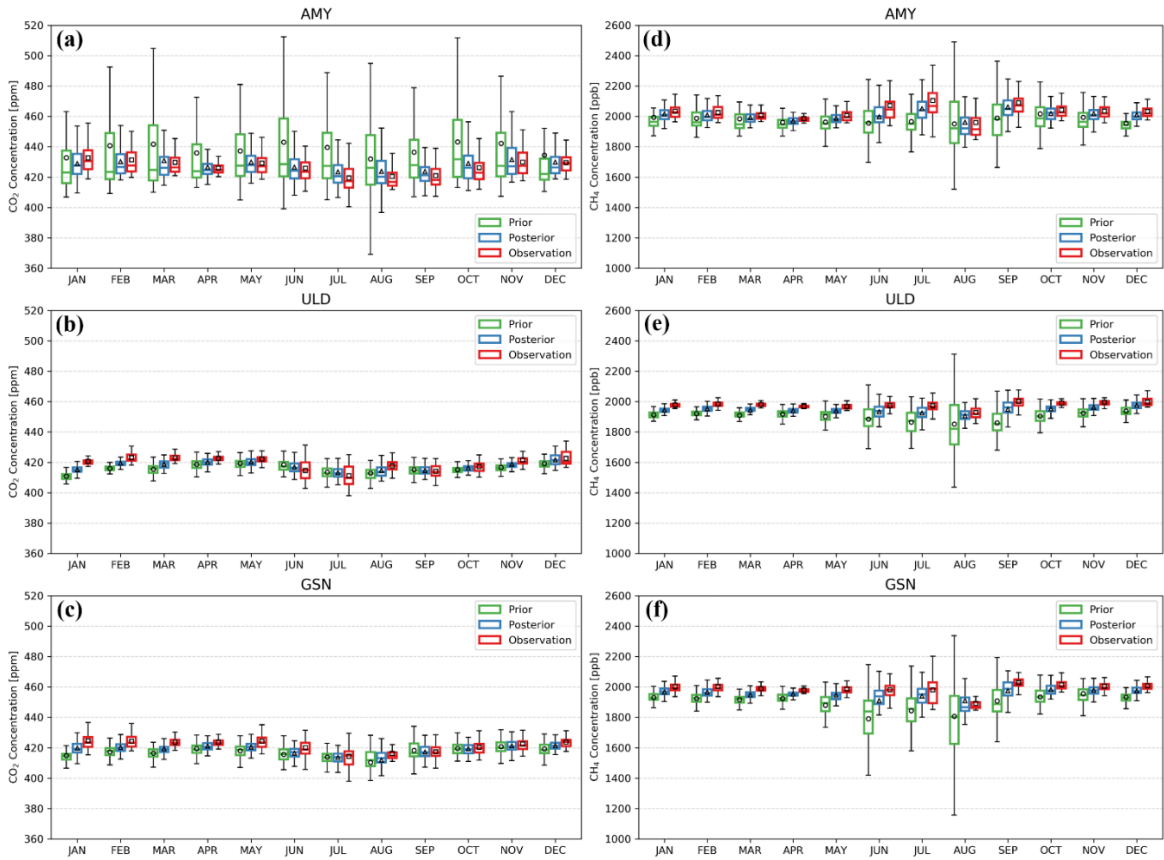
~~With the controlled proof of concept established in the previous section, we~~We now present a real-data demonstration to assess how the same cycling and analysis configuration performs under real observational constraints and inevitable model-data inconsistencies. We evaluated inversion results for 2020 using the WRF-Chem/DART system with full DA, in which both meteorological and GHG observations were assimilated. Each monthly run was initiated at 00 UTC on the last day of the preceding month, followed by a 24-hour spin-up prior to the start of assimilation. The controlled OSSE is provided separately in Supplement S2 as an auxiliary perfect-model diagnostic.

6.1 GHG concentrations at ground stations

Monthly distributions of prior, posterior, and observed CO₂ and CH₄ concentrations at the three WMO/GAW surface stations are summarized with box plots for comparison of seasonal variability and site-to-site statistics (Fig. 54 and Table 1). Prior CO₂ concentrations overestimate the *in situ* observations at the AMY by about 12 ppm but underestimate at the remote stations (ULD and GSN) by 2-3 ppm. Prior CH₄ concentrations underestimate at all ~~the~~stations especially with annual mean biases of -52 to -88 ppb and particularly large discrepancies during the summer season by 15 ppb. These biases are well matched consistent with the expected influence of uncertainties in the prescribed EGG4 boundary ~~data from the EGG4 fields~~. The top-down estimates of GHG concentrations show markedly improved agreement with observations relative to the prior, ~~thus demonstrating indicating~~ the efficacy practical effectiveness of the EAKF assimilation system in adjusting surface GHG concentrations reducing concentration-space mismatches. At the observation locations, the posterior estimates generally fall between the prior and the observations ~~and across~~. Across all sites and both species, posterior estimates consistently reduce MBE (mean bias error), and RMSE (root mean square error) (Table 1). Mean bias of posterior surface CO₂ and CH₄ concentrations are in the rangeranges of 1-2 ppm and 20-30 ppb, respectively. The drivers of these improvements vary by site. The largest error reduction for CO₂CO₂ occurs at AMY (10.9 ppm), reflecting the consistent with correction of ~~the~~a substantial prior ~~overestimation of local emissions from the positive concentration bias associated with~~ nearby industrial ~~'super cluster'~~ (coal power sources and petrochemical facilities) regional transport. In contrast, the largest improvement for CH₄ occurs at GSN (57 ppb), driven principally by the correction of the background bias and ~~the resolution of the latitudinal OH gradient which dominates this southernmost site compensation for the latitudinal CH₄ gradient inherited from the CAMS EGG4 boundary conditions~~. Note that the DA system does not directly modify OH fields; rather, it adjusts CH₄ concentrations to match observations. Error reductions are most pronounced in summer, consistent with corrections to low-biased boundary inflow for CH₄ and to underrepresented seasonal regional fluxes (e.g., anthropogenic and biogeochemical contributions) when seasonal gradients are largest.

Notable differences are evident in the skewness of the monthly distributions of observed CO₂ and CH₄ concentrations across the sites. At AMY, both prior and posterior CO₂ and CH₄ exhibit strong positive skews skewness and higher high variability (elongated upper whiskers in Fig. 5a4a and 5d4d), depending on wind around nearby large point sources (i.e., power and

605 industrial plants in the MWI). In contrast, GSN and ULD show more symmetric, compact distributions, suggesting weaker local source influence on these remote stations. All three stations exhibit a pronounced summertime dip in CH_4/CH_4 concentration, especially in August, consistent with enhanced OH-driven atmospheric oxidation under warm, humid, and high-radiation conditions (East et al., 2024). This seasonal signal feature is stronger at the lower latitude sites (AMY, GSN), where oxidation capacity becomes stronger. Similar dips appear also evident in the EGG4 data boundary fields used as lateral boundary forcing in WRF-Chem-GHG (see (Fig. S11-S11), indicating suggesting that the seasonal CH_4 decline is largely imposed by it primarily reflects large-scale features—seasonal background variability, potentially including enhanced summertime oxidative loss at hemispheric to continental scales, rather than regional chemical loss within the WRF-Chem domain.



615 **Figure 54.** Monthly boxplots of CO₂ (a–c) and CH₄ (d–f) concentrations at AMY (a,d), ULD (b,e), and GSN (c,f) in 2020. Prior (green), posterior (blue), and observations (red) are shown for each site. Boxes denote the interquartile range (25th–75th percentiles); horizontal lines indicate medians. Filled-symbols denote means (prior: circle; posterior: triangle; observation: square).

620 **Table 1. Mean bias error (MBE) and root-mean-square error (RMSE) of the top-down estimates to the observations at AMY, ULD, and GSN in 2020. Statistics are computed from 6-hourly averages.**

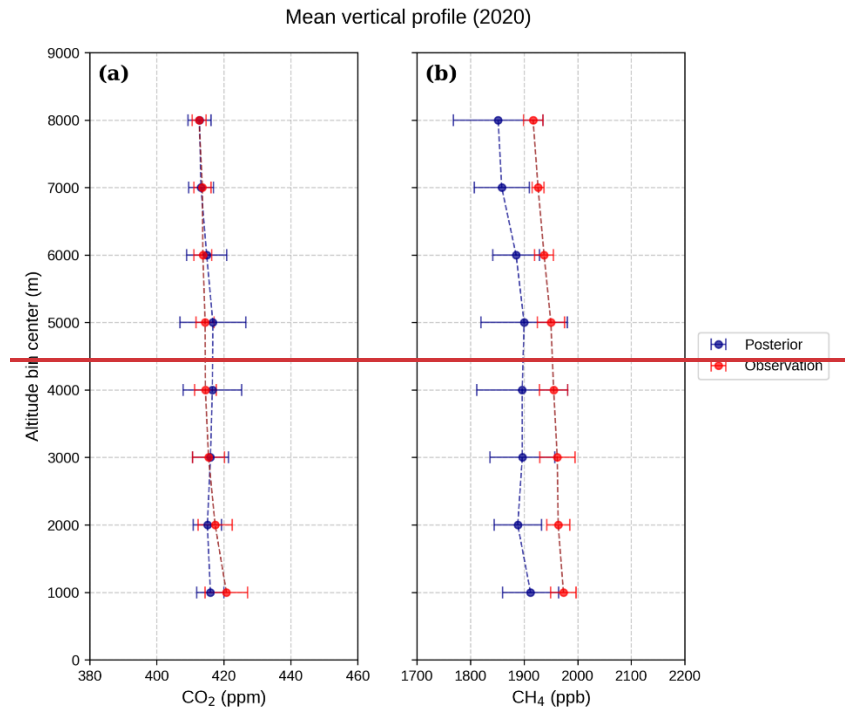
Station name	Latitude	Longitude	GHG variable	MBE	RMSE
AMY	36.53°N	126.32°E	Prior CO ₂	12.1 ppm	35.2 ppm
			Posterior CO ₂	1.2 ppm	13.9 ppm
			Prior CH ₄	-52 ppb	163 ppb
			Posterior CH ₄	-23 ppb	111 ppb
ULD	37.48°N	130.90°E	Prior CO ₂	-2.4 ppm	7.7 ppm
			Posterior CO ₂	-1.2 ppm	5.4 ppm
			Prior CH ₄	-72 ppb	124 ppb
			Posterior CH ₄	-30 ppb	60 ppb
GSN	33.29°N	126.16°E	Prior CO ₂	-3.4 ppm	10.0 ppm
			Posterior CO ₂	-2.3 ppm	7.4 ppm
			Prior CH ₄	-88 ppb	179 ppb
			Posterior CH ₄	-31 ppb	109 ppb

76.2 Validation against aircraft observations

625 To independently evaluate the performance of the inversion system, posterior CO₂ and CH₄ concentrations are compared with aircraft-based *in situ* observations collected over the Yellow Sea near the AMY station in 2020 using a Beechcraft King Air 350. The aircraft was equipped with a CRDS (G2401, Picarro Inc., USA) for measuring CO₂, CH₄, CO, and H₂O, at a sampling rate of 1.5 Hz. Sample air was dried upstream, and inlet ports were located near the front fuselage to minimize contamination. Typical operating altitudes reached 10 km with cruising speeds of 70–120 m s⁻¹, supporting both routine profiling and regional transport characterization. Ten vertical profile flights near the AMY were available in 2020 (not used in the data assimilation) 630 (Fig. S9). After quality control, the profiles were aggregated into 1 km altitude bins (± 500 m). Model fields were sampled along the flight track (time-matched and horizontally interpolated to the observation location) and averaged into the same altitude bins. For each bin, we computed mean observed concentrations and observational uncertainties (quadrature of sampling variability and reported measurement uncertainty) alongside the corresponding posterior values.

635 **Figure 6** **Figure 5** presents vertical profiles for CO₂ and CH₄ concentrations from both the inversion system and aircraft. Posterior CO₂ concentration is in good agreement with the observed profile with biases of 1-5 ppm even in the upper

640 troposphere, whereas the posterior CH₄ concentration profile shows a systematic negative bias of 40–50 ppb from the boundary layer to the mid-troposphere. We speculate that this persistent CH₄ bias ~~is a~~ likely reflects a combination of residual boundary condition bias in the prescribed CAMS EGG4 inflow mole fraction and under-~~presented~~represented coastal CH₄ sources in prior data over the Yellow Sea. The latter is consistent with the report that shallow shelves and coastal waters can be important CH₄ source regions (Weber et al., 2019; Lee et al., 2018). These results motivate further investigation of maritime CH₄ contributions in the regional prior/boundary treatment and highlight the value of additional observational constraints for improving CH₄ budgets over the Korean Peninsula.



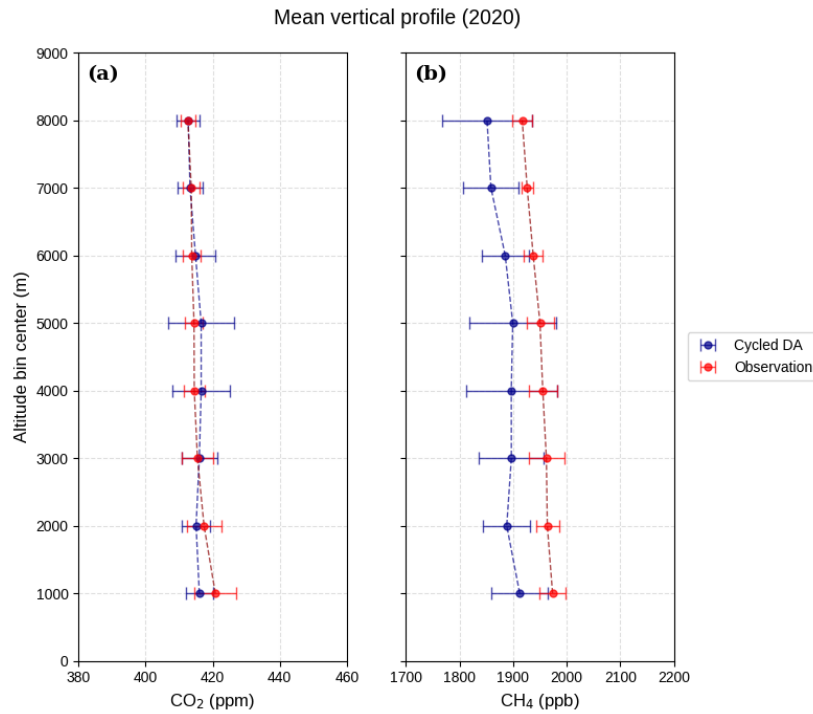


Figure 65. Mean vertical profiles of CO₂ and CH₄ from 10 CM-01 flights over South Korea in 2020. Profiles are aggregated into 1 km altitude bins (± 500 m). Symbols and error bars show mean concentrations and associated uncertainties per bin: observations (red) and **posterior/cycled DA** (blue). Observation uncertainties combine measurement precision and sampling variability.

76.3 Uncertainty reduction in concentrations and fluxes

Figures 7Figures 6 and 87 show the spatial distributions of ensemble spreads for CO₂ and CH₄ concentrations and the corresponding emission uncertainties, respectively, showing prior uncertainties (left panels) and uncertainty reductions after the DA (right panels). Unless noted, “**uncertainty reduction**” ~~denotes (posterior spread / is defined as $(1 - \sigma_{\text{post}} / \sigma_{\text{prior}} - \text{spread} = 1)$~~ $\times 100\%$ over grid cells: where σ_{post} and σ_{prior} denote the posterior and prior ensemble spread, respectively. Domain-averaged **flux/concentration** uncertainty over land decreases by 25-35 % for CO₂ and about 20 % for CH₄, with local reductions up to 50 % near the observation sites. Prior uncertainties in both concentrations and anthropogenic fluxes are elevated over strong source regions in ~~Seoul Metropolitan Area (SMA);SMA,~~ large-scale power plants along the MWI, and the southeastern industrial areas (SCI and SEI) for CO₂. Elevated uncertainties for CH₄ are observed in landfills around the SMA, and in rice cultivation ~~area and areas, as well as at~~ livestock farms ~~(around CLA)~~ (compare Fig. 2 with Fig. 6 and 7-and-8). Posterior uncertainties in GHG concentrations decrease substantially within an influence radius of about 90 km (e-folding distance) from all the stations. CH₄ uncertainty reduction reaches up to 40 % around the station and has a larger relative decrease than CO₂. This is consistent with the negative bias in CH₄ concentration discussed above. We also note that uncertainty reductions over

North Korea and China arise from weak cross-covariances at the range limit; these transboundary updates are not quantitatively interpreted in this study.

665 The spatial patterns of prior flux uncertainties closely resemble those for concentrations. Overall uncertainties for CO₂ emission decrease by about 7 % after the DA. CO₂ emission uncertainties decrease sharply within the influence radius of the AMY station along the western coasts, particularly for CO₂, where strong anthropogenic GHG sources are located (Fig. 87). Smaller reductions around ULD/GSN (< 5 %) reflect distance from major southeastern sources and prevailing winds. CH₄ emission uncertainties show a similar pattern with that of CO₂ except that the error reduction is relatively smaller than that of CO₂. Posterior flux uncertainty around ~~the~~ AMY shows a relatively smaller reduction in CH₄ compared to CO₂, primarily because major CH₄ sources are located more easterly than those of CO₂. These patterns suggest qualitative priorities for future network expansion (e.g., enhanced CO₂ coverage in the southeastern industrial corridor and CH₄ coverage over central inland hotspots), while noting that a formal network optimization is beyond the scope of this paper. Because the maps are annual means, transient spatial structures at individual cycles are smoothed out; therefore, Figs. 7–106–9 should be interpreted as 670 persistent features rather than cycle-to-cycle variability, with the strength of sub-national gradients remaining dependent on observational coverage.

The supplementary OSSE provides an idealized reference for this information-content limitation. Under perfect-model assumptions with a large prescribed prior-emission perturbation, the dense-network experiment shows stronger national-scale CO₂ emission recovery than the corresponding three-site experiment, whereas the three-site case exhibits much weaker recovery under otherwise matched filter settings. This contrast indicates that the modest domain-mean flux-uncertainty reduction in the 2020 real-data case is consistent with limited observational information content, while also depending on the prescribed error statistics, localization, and prior-emission uncertainty. Because the OSSE excludes transport-model error, boundary-condition bias, and realistic representativeness errors, it is used only as a diagnostic of information-content sensitivity, not as evidence of real-world robustness or grid-scale resolvability.

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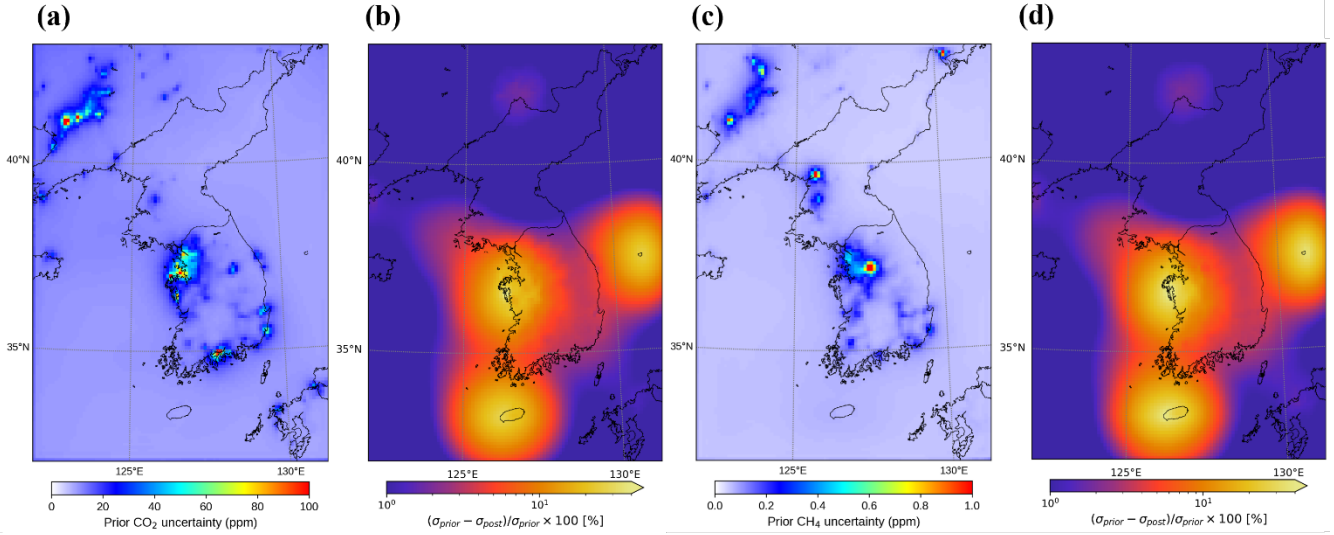


Figure 76. Annual prior concentration uncertainty (ensemble spread) (a,c) and its reduction after assimilation (b,d) for CO₂ (a,b) and CH₄ (c,d) in 2020.

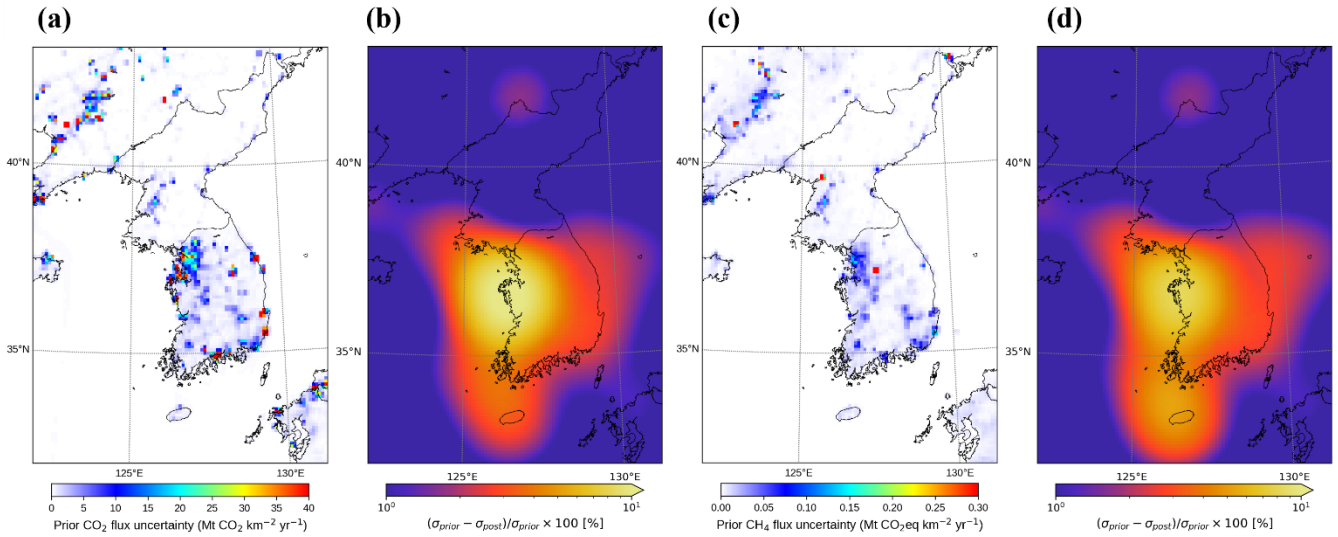


Figure 87. Annual prior flux uncertainty (a and c) and flux-uncertainty reduction (b and d) for CO₂ (a and b) and CH₄ (c and d) in 2020. Note that ocean-grid uncertainties are non-zero but appear small on the plotted scale because the prior spread is prescribed as a fractional perturbation and absolute oceanic flux magnitudes are much smaller than terrestrial sources.

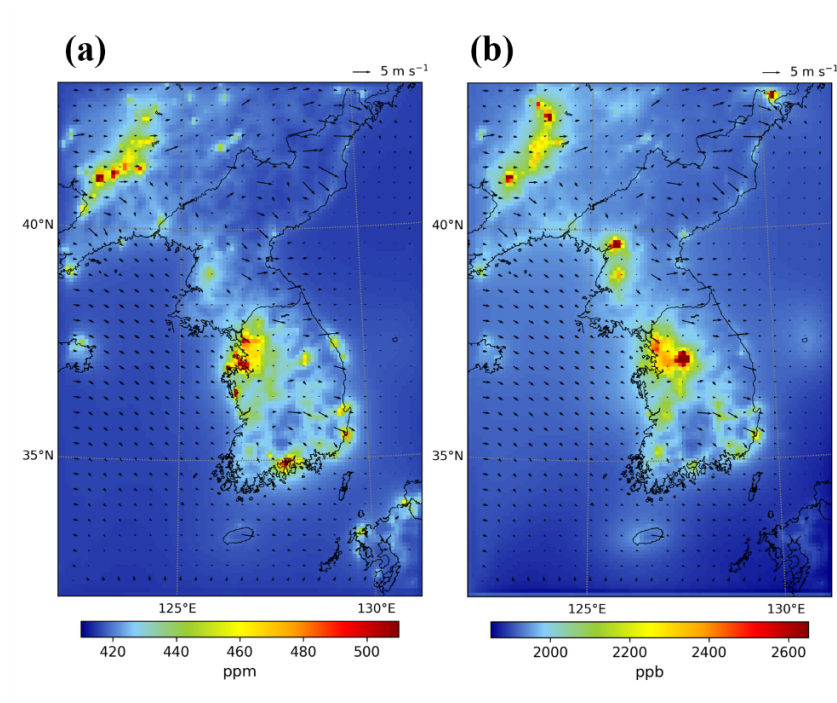


Figure 98. Annual mean surface posterior concentrations of CO₂ (a) and CH₄ (b) over the Korean Peninsula in 2020 from the WRF-Chem/DART inversion system. Wind vectors at 10 m illustrate prevailing flow conditions that shape annual concentration gradients.

76.4 Posterior fluxes and concentrations of CO₂ and CH₄

Figure 8 shows the spatial distribution of CO₂ and CH₄ concentrations from the inversion system. Posterior GHG concentrations capture large-scale gradients and regional enhancements induced by both long-range transport and upwind source regions. Elevated concentrations are clearly identified over key heavy industry and dense urban zones, specifically along the SMA, the west coast, and the southern industrial corridor (MWI, SCI, and SEI; Fig. 2b) for CO₂. In contrast, enhanced CH₄ concentrations are more closely associated with agricultural and waste-related source regions, including central-western Korea and the CLA region (Fig. 2c). When viewed alongside CAMS EGG4, both fields exhibit the broad synoptic structures, including persistent enhancements over the western Korean Peninsula and eastern China and the seasonal cycle of winter accumulation and summer dilution (Figs. S10–S13). However, this comparison is not used as an emission benchmark, because EGG4 does not solve for regional emissions in the same sense as the present inversion system; rather, it is used to illustrate differences in concentration-field representation between the coarse global boundary product and the high-resolution regional posterior. The structural differences between the two products primarily reflect differences in resolution and representation, highlighting the benefit of the high-resolution regional framework for sub-national patterns. While EGG4 depicts spatially smoother concentration fields characteristic of its coarser 0.75° global resolution (0.75° × 0.75°), the 9-

km posterior estimates ~~resolve~~represent sharper concentration gradients and more distinct ~~hotspots over major source regions~~
 715 ~~such as region signatures over~~ the SMA and MWI (Figs. 98 and S14a). Similarly, elevated CH₄ concentrations over the CLA
 are ~~resolved~~represented as more localized features in the posterior, whereas these appear as broader, more diffuse patterns in
 the global product- (Fig. S14b). These features are consistent with previous ~~studies based on satellite products of the GOSAT-~~
~~based studies over Korea that documented fine-scale urban-industrial heterogeneity in CO₂ and TROPOMI CH₄~~ (Shim et al.,
 2019; Moon et al., 2024), ~~which noted that coarse-~~. The 9-km framework resolution ~~global products tend to smooth out fine-~~
 720 ~~scale urban-industrial heterogeneity. These results illustrate a high-~~ is selected with future satellite-assimilation applications in
 view (e.g., TROPOMI CH₄ at ~7 km footprint), where sub-grid representation error directly affects the forward operator. The
 present three-station *in situ* configuration does not by itself demonstrate grid-scale emission constraints at this resolution
 regional inversion represent fine-scale spatial gradients and localized source-region signatures; however, retaining the 9-km
 transport framework facilitates future satellite-assimilation applications, provided that appropriate column observation
 725 operators, bias treatment, and representativeness-error specifications are ~~often averaged out at coarser global scales when it~~
~~combines local priors, mesoscale meteorology, and continuous in situ observations.~~implemented.

Figure 109 summarizes the posterior anthropogenic flux fields and the spatial distribution of flux adjustments (posterior
 minus prior). The overall spatial patterns of posterior CO₂ and CH₄ emissions remain similar to the priors, retaining the major
 hotspots over the Korean Peninsula (Fig. 2b and 2c), as expected, given the current observing network and the use of covariance
 730 localization. Spatially-~~varying~~ posterior adjustments are nonetheless produced to reduce concentration innovations at the
 observation sites. With the current observation configuration, these adjustments are best interpreted as regionally coherent
 corrections within the localization-supported influence region, while finer-scale structure remains strongly constrained by the
 prior and the assumed error statistics. Negative increments ~~of~~in CO₂ emissions are concentrated in densely populated and
 traffic-heavy regions (SMA and MWI) and positive increments ~~for CO₂ emission~~ are observed along the east coast and in the
 735 southeastern industrial corridor (i.e., SCI and SEI) (Fig. 10b9b). These patterns are broadly consistent with the ~~signs~~signs of
 the station-based concentration biases (Table 1) and suggest that ~~innovations at AMY (the positive bias) tend at AMY tends~~
 to project onto nearby western source regions as flux reductions, whereas ~~innovations the negative biases~~ at GSN and ULD
~~(negative bias)~~ can contribute to increased fluxes in the southern⁴ and eastern industrial regions through localized
 concentration-flux covariances. This behavior may also reflect sector-dependent structural uncertainties in the priors, given
 740 the strong contribution of heavy industry (steel, petrochemical, shipbuilding, and vehicle manufacturing) in SCI and SEI,
 relative to the more mixed urban/energy source ~~mix~~ in SMA/MWI. Positive increments for CH₄ emission are widespread
 across inland source regions associated with rice paddy, livestock facilities, landfills, and power-industry (Fig. 10d9d). Given
 the persistent negative CH₄ bias in the independent aircraft profiles (Section 76.2), we interpret these increases with caution
 because of the possibility for compensation for low-biased prescribed boundary mole fractions. At the same time, the spatial
 745 correspondence with known inland hotspots suggests that missing or underestimated sources in the prior may also contribute.
 Further work is therefore needed to disentangle boundary-condition bias, transport/representativeness error, and prior source

errors, including sensitivity tests using alternative boundary products and expanded observational constraints (e.g., additional *in situ* and upper-air measurements).

Figure 410 compares national-total anthropogenic CO₂ and CH₄ emissions for South Korea in 2020 from the posterior with multiple bottom-up inventories. For CO₂, the comparison encompasses Open-source Data Inventory for Anthropogenic CO₂ (ODIAC) (Oda et al., 2018), the Fossil Fuel Data Assimilation System (FFDAS) (Rayner et al., 2010), the Gridded Daily Fossil CO₂ Emissions Dataset (GRACED) (Dou et al., 2023), EDGAR, and the national total anthropogenic emissions (excluding the LULUCF sector) as reported in the Biennial ~~Transparent~~ Transparency Report of the Republic of Korea (ROK-BTR, hereafter). Because these products differ substantially in scope and construction (e.g., fossil-fuel-only versus IPCC-sector totals), proxy choice, point-source treatment, spatial disaggregation, native resolution, and sector attribution, we interpret the comparison as a consistency check under a harmonized scope (anthropogenic CO₂ excluding LULUCF) rather than as a validation target (Hutchins et al., 2017). Under the harmonized scope and spatial aggregation used here, EDGAR’s national-total anthropogenic CO₂ is most consistent with the ROK-BTR estimate among the bottom-up datasets considered. EDGAR is the closest to ROK-BTR (4% higher), whereas FFDAS, GRACED, and ODIAC ~~deviate more than EDGAR (show larger~~ deviations, ranging from about -31%, ~~to 10%~~, % to +10 %. In 2020, our posterior CO₂ total is broadly consistent with ROK-BTR at the national scale (Fig. 410). In contrast, posterior CH₄ total shows weaker agreement with the available bottom-up estimates, consistent with the larger structural uncertainty in CH₄ source characterization and spatial allocation noted in previous studies (e.g., Moon et al., 2024).

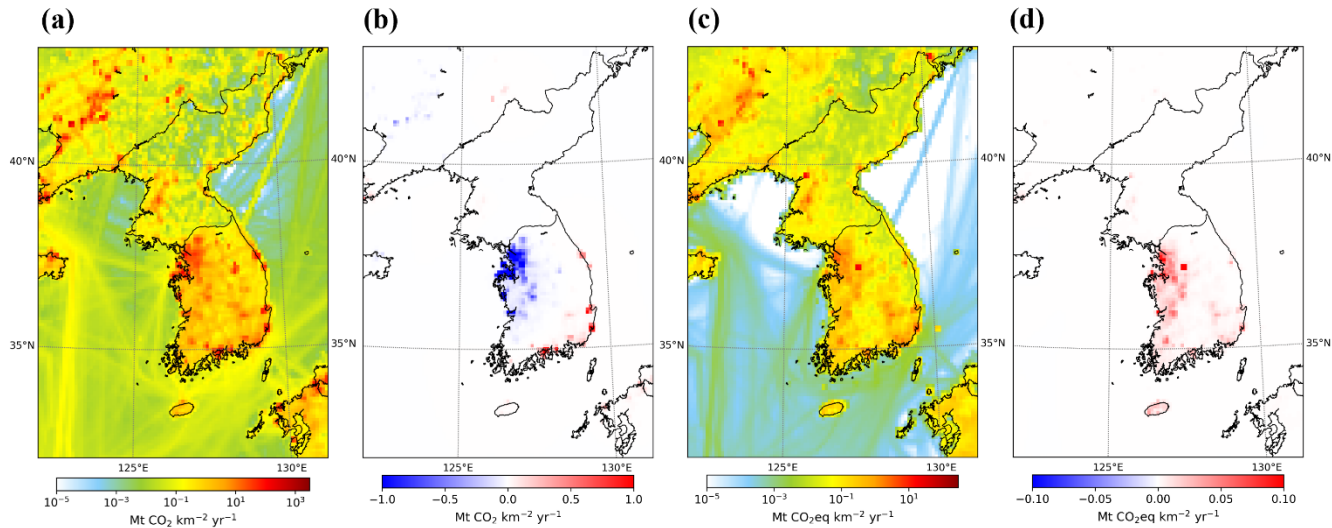


Figure 409. Annual-mean posterior surface fluxes (a and c) and assimilation increments (posterior minus prior) (b and d) for CO₂ (a and b) and CH₄ (c and d) from the WRF-Chem/DART system. Red (blue) shading indicates an increase (decrease) in the posterior relative to the prior.

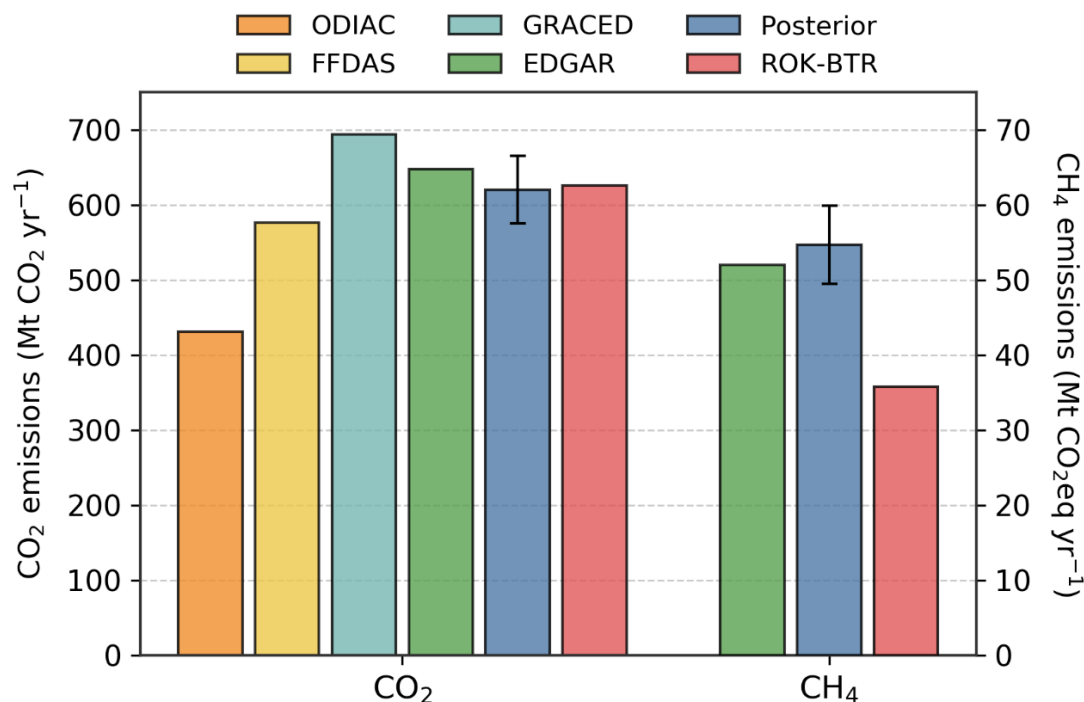


Figure 4-10. Annual total anthropogenic CO₂ and CH₄ emissions over South Korea in 2020 from multiple datasets. CO₂ comparisons include ODIAC, FFDAS, GRACED, EDGAR, ROK-BTR, and the posterior (six sources). CH₄ comparisons include EDGAR, ROK-BTR, and the posterior. Error bars denote posterior uncertainty. (FFDAS was scaled using the 2015–2020 gross emission growth rate from ROK-BTR because FFDAS is available only through 2015)

8.7 Summary and Conclusion

This study presents a high-resolution dual-species GHG (CO₂ and CH₄) inversion framework using the coupled WRF-Chem/DART system, which assimilates continuous high-precision *in situ* observations of GHG concentrations. The system provides transport-consistent and observation-constrained emission estimates and dynamically consistent temporal state updates through ensemble data assimilation. ~~By coupling meteorology and tracer transport and~~By updating both meteorological and tracer states within the cycling system, the framework ~~supports~~maintains internally consistent transport–concentration ~~flux adjustments relationships~~ over complex terrain. The incorporation of ~~precise~~continuous high-frequency *in situ* observations ~~further helps better representation of~~constrain near-surface gradients, ~~thereby enhancing and the associated~~ anthropogenic flux sensitivity.

This framework is designed to accommodate denser and more diverse observing systems (e.g., additional surface sites, tall towers, aircraft profiles, and satellite column retrievals) within the same data-assimilation framework; although extending to various types of observations may involve implementing the corresponding observation operators and specifying observation-error/representativeness settings (including bias treatment where applicable), together with network-dependent tuning (e.g., localization and observation error) as needed. A compact controlled twin experiment ~~with synthetic observations from~~

presented in Supplement S2, provides an expanded 50-site surface network illustrating idealized information-content diagnostic showing how emission constraints may strengthen as observational density increases, clarifying the expected direction and spatial structure of with denser surface observations under perfect-model assumptions, particularly when prior emission uncertainty reduction and informing iterative inventory refinement is large.

The cycling dual-state EAKF framework provides a more an integrated and internally consistent treatment of background errors and filter stability within a cycling joint state-parameter assimilation system for GHG concentrations and emissions, compared with footprint-based Lagrangian inversions. Because meteorology and 3-D tracer fields are advanced and analyzed within the same model, background-error covariances are represented in a flow-dependent manner by the evolving ensemble, rather than being prescribed a priori via static spatial correlations or fixed regularization operators that are often adopted in footprint-based approaches. In addition, the DART configuration provides an explicit, principled inflation framework to maintain physically plausible ensemble spread and to mitigate ensemble collapse during repeated cycling, offering a systematic handle on under-dispersion arising from unresolved transport/model errors and finite-ensemble sampling. By contrast, typical Lagrangian inversions typically manage under-dispersive behavior implicitly through tuning of prior error magnitudes, prescribed covariance structures, or regularization strength, without an inflation mechanism that is directly coupled to sequential filter dynamics. These advantages/capabilities come with trade-offs. Running an ensemble is computationally more expensive than footprint-based calculations, and posterior updates depend on the fidelity of the underlying meteorological and sub-grid physical parameterizations that govern transport and mixing.

In the 2020 real-data application, the system reduces mismatches with observed CO₂ and CH₄ at all high-precision sites and yields posterior uncertainty reduction in both concentrations and emissions. The posterior surface biases (1.2 ppm for CO₂ and 30 ppb for CH₄ over 2020) are smaller than those implied by the prescribed CAMS EGG4 IC/BC forcing at the surface observatory, indicating improved consistency with local observations under the cycling configuration. National totals are broadly consistent with the Republic of Korea inventory under ROK-BTR estimate (624 Mt yr⁻¹) at the defined scope, while showing regionally varying national scale. The posterior CH₄ total (54.7 ± 5.2 Mt CO₂eq yr⁻¹), however, exceeds the ROK-BTR estimate (35.5 Mt CO₂eq yr⁻¹) by 19.2 Mt CO₂eq yr⁻¹, which may reflect a combination of underestimated agricultural and waste-sector sources, residual boundary-condition bias, and structural uncertainty in CH₄ source characterization and spatial allocation. Regional adjustments relative to the prior are observed over densely populated, industrial, and agricultural areas for both species. Posterior increments suggest that prior CO₂ emissions may be overestimated over the Seoul Metropolitan Area and portions of the western coastal region, whereas CH₄ emissions may be underestimated over inland agricultural hotspots; CH₄ adjustments should be interpreted with caution, given the potential sensitivity to boundary-condition biases and maritime source representation. These results underscore/illustrate the potential value of top-down constraints for national-scale consistency checks and for guiding sub-national inventory refinement and for an aggregate-level consistency check/evaluation. To our knowledge, this study provides the first fully documented regional WRF-Chem/DART workflow for simultaneous CO₂ and CH₄ estimation within a cycling dual-state configuration at kilometer-scale resolution, combining *in situ* GHG assimilation with meteorological data assimilation. Overall,

this high-resolution dual-species WRF-Chem/DART inversion framework leveraging surface heterogeneity-aware parameterizations provides a ~~practical~~reproducible basis for spatially explicit emission analyses that can support future policy applications, operational monitoring development, and MMRV-oriented ~~verification~~evaluation at national and sub-national scales.

Code and Data availability

Model source code used in this study are archived on Zenodo under <https://doi.org/10.5281/zenodo.16939122> (Kwon et al., 2025a). Preprocessed data, model output, and model configurations used in this study are archived on Zenodo under <https://doi.org/10.5281/zenodo.16947463> (Kwon et al., 2025b). ERA5 is available after registration at <https://doi.org/10.24381/cds.adbb2d47> (pressure levels) (Hersbach et al., 2023a) and <https://doi.org/10.24381/cds.bd0915c6> (single level) (Hersbach et al., 2023b). CAMS EGG4 is available after registration at <https://doi.org/10.24381/cda4ed31> (Copernicus Atmosphere Monitoring Service, ~~2022~~2021). PREPBUFR is available at <https://doi.org/10.5065/Z83F-N512> (National Centers for Environmental Prediction, 2008). EDGARv8.0 is available at https://edgar.jrc.ec.europa.eu/dataset_ghg80 (Crippa et al., 2023). FFDAS is available at <https://ffdas.rc.nau.edu/Data.html> (Rayner et al., 2010). GRACED is available after registration at <https://carbonmonitor-graced.com> (Dou et al., 2023). ODIAC is available at <https://doi.org/10.17595/20170411.001> (Oda et al., 2015). FINNv2.5 is available after registration at <https://doi.org/10.5065/XNPA-AF09> (Wiedinmyer and Emmons, 2022). SeaFlux is available at <https://doi.org/10.5281/zenodo.5482547> (Gregor and Fay, 2021). Annual budget of CO₂ and CH₄ emissions in South Korea is available under <https://unfccc.int/documents/645637> (Biennial Transparency Report of Republic of Korea, 2025). EDGARv8.0, FFDAS, GRACED and the Republic of Korea's Biennial Transparency Report are also archived on Zenodo under <https://doi.org/10.5281/zenodo.17402804> (Kwon et al., 2025c). Access to the repositories archived on Zenodo will be provided upon request to the corresponding author.

Author contributions

DK, BK, ES, AA, CS, DS, SK, SJ, and JH conceptualized and designed the study. DK, BK, JL, JK, ES, and AA contributed to the implementation and development of the forward and inverse modeling framework. DS, SL, SK, and SJ were responsible for the WMO/GAW KMA observation program and the aircraft-based measurement. DK and JA performed preprocessing and visualization of the VPRM inputs and outputs. DK and BK collected and processed the remaining input datasets, conducted the model simulations, and carried out the analysis and visualization. DK, BK, and JH prepared the original draft. All authors reviewed and edited the manuscript.

Competing interests

One of the authors is a member of the editorial board of Geoscientific Model Development.

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