

Implementation of predicted rime mass in the bin microphysics scheme DESCAM 3D: ~~Heavy Snowfall~~ Evaluation for an idealized squall line system and a heavy snowfall event during ICE-POP 2018

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Abstract. Due to their wide variety of properties, the representation of ice particles in cold and mixed-phase clouds are challenging to represent for microphysical schemes. To improve their representation, this study evaluates the implementation of predicted rime mass distribution in the bin microphysics scheme DESCAM. Based on the ‘fill-in’ concept, the model allows a smooth transition in ice particle properties between unrimed and graupel particles. Consequently, the terminal velocity and collision kernels of ice particles were updated as a function of rime fraction. ~~These implementations are tested for~~ First, this study investigates the impact of the new implementation on cloud microphysics for an idealized squall-line system. The results show that large ice particles acquire substantial rime mass, enhancing their sedimentation and leading to earlier and more intense precipitation (+25%), while weakening the cold pool, reducing buoyancy, and slowing squall-line propagation. The second part of this study is dedicated to evaluating the new version of DESCAM against field observations from the ICE-POP 2018 campaign, focusing on a heavy snowfall event ~~observed that occurred from March 7–9 during the ICE-POP 2018 field campaign in the mountainous Pyeongchang region of the Korean Peninsula. This event consists of a deep cloud triggered by a low-pressure system, followed by a shallower cloud system formed by orographic lifting of marine air. We~~ 9. For this case, we found that the simulated rime mass fraction at ground simulated by DESCAM evolves similarly to the rime index measured by the MASC instrument. Furthermore, during the shallow cloud phase, the predicted rime implementation leads to an increase in ice particle number concentration and a decrease in mean particle size (from 1.5 to 1.0 mm). The new version of DESCAM leads to ~~The new DESCAM version also produces significant changes in the amount and spatial distribution of precipitation, with strong local variations exceeding 10 mm ;resulting in an increase of and a 6.5% in total precipitation amount. Accounting increase in total accumulation, which leads to a better agreement with field observations. Overall, accounting for predicted rime mass gives a better agreement improves consistency between the model and the ground-based observations of ground-based observations from~~ ICE-POP 2018.

1 Introduction

The formation of precipitating ice particles results from a complex combination of microphysical processes including vapor deposition, aggregation, and riming. Consequently, ice particles exhibit a wide variety of shapes (Kikuchi et al., 2013) depending on environmental conditions.

25 In mixed-phase clouds, riming occurs when precipitating ice particles collect supercooled liquid droplets down to -25°C (Tridon et al., 2022). As riming depletes supercooled liquid water, it significantly impacts the phase partitioning of mixed-phase clouds, which plays an important role on the Earth's radiation budget (Matus and L'Ecuyer, 2017; Korolev et al., 2017).

Riming of ice particles has been widely documented from various observations, including radars (Mason et al., 2018; Kneifel and Moisseev, 2020), in-situ aircraft (Waitz et al., 2022; Maherndl et al., 2024) or even ground based measurements (Praz
30 et al., 2017). During riming, small droplet tends to 'fill-in' the empty spaces within the structure of ice particles, increasing their density (Heymsfield, 1982; Seifert et al., 2019). Therefore, rimed ice crystals (i.e. graupel or hail) have a fastest terminal velocity (Vázquez-Martín et al., 2021) which explains their key role on precipitation. Indeed, several observational studies demonstrate the significant influence of riming on precipitation such as Grazioli et al. (2015) who showed its impact on precipitation flux, or Mitchell et al. (1990) who found that 30 to 40% of snow was formed by rime in Sierra Nevada. Similarly,
35 Moisseev et al. (2017) reported that riming accounted for 5% to 40% of snowfall in a frontal system in Finland. Furthermore, riming also plays an important role for secondary ice production (SIP) mechanisms (Korolev and Leisner, 2020) such as the Hallett-Mossop (rime splintering) process (Hallett and Mossop, 1974), fragmentation during thermal shock (King and Fletcher, 1976) or fragmentation due to graupel-graupel collisions (Takahashi et al., 1995; Grzegorzczak et al., 2023; Yadav et al., 2024).

A wide variety of modeling studies also reported the important role of riming of graupel particles on the precipitation
40 evolution and amount (Morrison and Milbrandt, 2011; McMillen and Steenburgh, 2015; Poirier et al., 2019; Li et al., 2019; Jin et al., 2019). In models, the habit of ice crystals is often represented by distinct categories (e.g., ice, snow, graupel, or hail) in most bulk microphysics schemes (e.g., WRF: Thompson et al., 2008; Morrison et al., 2009; Lim and Hong, 2010; ICON: Seifert and Beheng, 2006; Meso-NH: Vié et al., 2016; Pinty and Jabouille, 1998) or even bin microphysics schemes (e.g., HUCM: Khain et al., 2004; UPNB: Geresdi, 1998; Geresdi et al., 2014). One of the major difficulty when categorizing ice crystals is
45 to parameterize the transfer between the distinct ice categories (i.e., conversion or autoconversion rates), which is often set as a tuning parameter. In nature, ice particles have complex morphologies, necessitating a large number of categories and thus increase the number of uncertain conversion rates. Furthermore, as noted by Morrison and Grabowski (2008), categorizing ice particle types (e.g., ice and snow categories) is less straightforward than the distinction between cloud droplets and raindrops.

Instead of separating ice particles into categories, a new approach focuses on predicting their properties, allowing free evo-
50 lution along their history. The first implementations following this approach were introduced by Hashino and Tripoli (2007); Morrison and Grabowski (2008, 2010) in both bulk and bin schemes. The approach of Morrison and Grabowski (2010) considers the 'filling in' of crystal interstices during riming as introduced by the observations of Heymsfield (1982). It assumes that rime fills the ice particle interstices, increasing its mass while keeping it the same size. The 'fill-in' continues until the

interstices (such as the branches of dendrites or the faces of ice plates) are completely filled of rime. At this point, the ice crystal can be considered as a graupel for which additional rime increases both its mass and its size.

The ICE-POP 2018 campaign (International Collaborative Experiments for Pyeongchang 2018 Olympic and Paralympic Winter Games) took place during the 2018 winter Olympic Games over the mountainous region of Pyeongchang, located in the eastern part of the Korean peninsula. One of the main goal of this campaign was to investigate the ice particles properties of winter snowfall events using ground-based remote sensing instruments and microphysical probes (Jeoung et al., 2020; Gehring et al., 2020b; Kim et al., 2021; Gehring et al., 2021). Several snowfall events were investigated by Ko et al. (2022); Sunny Lim et al. (2020) in order to assess of the ability of the double moment 6-class (WDM6) scheme (Lim and Hong, 2010) to reliably predict the ice particles properties. Additionally, the ICE-POP 2018 observations were also used to evaluate the implementation of prognostic graupel and snow number concentration (Kwon et al., 2023) as well as predicted graupel volume mixing ratio (Park et al., 2024) in WDM6 scheme.

This study aims to evaluate the implementation of a predicted rime mass distribution in the bin microphysics scheme DESCAM (DEtailed SCAvening and Microphysics model, Flossmann and Wobrock, 2010; Planche et al., 2010) based on the approach of Morrison and Grabowski (2010). ~~Originally representing ice particles~~ Historically, DESCAM developments have mainly focused on cloud-aerosol interactions (Leroy et al., 2007) and their impacts on cloud and precipitation properties, including anvil characteristics in deep convective systems (Leroy et al., 2009), marine stratocumulus clouds (Flossmann and Wobrock, 2019), precipitation and drop size distributions (Planche et al., 2010; Kagkara et al., 2020), or even case studies in mountainous regions (Planche et al., 2013; Arteaga et al., 2020). Only a few developments have addressed the ice phase, for example the melting scheme of Planche et al. (2014), which is no longer used due to its high numerical cost. More recently, efforts have focus on the refinement of the ice phase microphysics of DESCAM, with the implementation of secondary ice production processes (Grzegorzczuk et al., 2025a, b, e). In previous versions, the ice particles in DESCAM were simply represented by a single predicted number distribution divided into 39 mass bins, ~~the present implementation will allow to refine the ice particle behavior within each bin of DESCAM, including~~ Building on these recent advances, we introduce rime mass prediction in DESCAM to better represent ice particle characteristics in each bin mass (i.e. size, fall speed, and collision kernels, as a function of rime mass. The benefits of this implementation will be).

To assess the model performance with the rime mass implementation, the new version of DESCAM is first evaluated in an idealized squall line simulation, focusing on microphysical properties, rime mass distribution, and precipitation. Secondly, the relevance and benefits of the rime mass implementation are assessed by comparing the ice DESCAM results for particle properties and precipitation outcomes predicted by DESCAM to observations of a heavy snowfall event observed during ICE-POP 2018.

This paper is structured as follows: Section 2 describes the implementation of the predicted rime mass distribution in DESCAM model. Section ~~?? presents the case study, including the numerical setup and the instrumentation used during the~~ 3 describes both case studies: section 3.1 gives the set-up for the idealized squall line, section 3.2 the one for the ICE-POP 2018 campaign including a description of instrumentation and measurements which were available. Section 4 presents the results of DESCAM simulations ~~and evaluates them against measurements from the ICE-POP 2018 campaign for the two different cases.~~

[Perspectives for future developments of the DESCAM microphysics are discussed in Section 5.](#) Finally, Section 6 summarizes

90 the main conclusions of the study.

2 Implementation of a rime distribution in DESCAM

2.1 DESCAM microphysics scheme

DESCAM (DEtailed SCAvening and Microphysics model, Flossmann and Wobrock, 2010; Planche et al., 2010) is a bin microphysics [scheme](#) currently included in the 3D cloud scale model of Clark (Clark et al., 1996; Clark, 2003). ~~It~~[In this dynamical framework, the subgrid scale mixing is calculated using a first-order turbulent kinetic energy \(TKE\) closure following Smagorinsky \(1963\) and Lilly \(1962\) formulation with the Blackadar \(1962\) mixing length. Surface atmosphere exchanges are represented using a Monin-Obukhov similarity scheme, with daytime dependent sensible and latent heat fluxes. Our microphysics scheme](#) predicts five distribution functions, each divided in 39 mass bins with namely, interstitial aerosol particles, liquid drops, ice particles as well as aerosol mass inside drop and ice particles.

100 The aerosol particle distribution of DESCAM ranges from 1 nm to 6 μm diameter, while liquid drops ranges from 2 μm to 13 μm diameter. Aerosol activation follows Köhler theory (Leroy et al., 2007). Liquid drops evolve through condensation, evaporation, and deactivation, as well as collision-coalescence, collision-breakup, and dynamical breakup. Aerosol-cloud interactions and liquid phase processes of DESCAM have been investigated by numerous studies (Flossmann et al., 1985; Flossmann, 1998; Planche et al., 2010, 2013; Flossmann and Wobrock, 2019; Arteaga et al., 2020; Kagkara et al., 2020).

105 The distribution of ice particles follows the same mass bins as for drops. The primary ice formation mechanisms, including heterogeneous and homogeneous ice nucleation, are implemented following Hiron and Flossmann (2015). Secondary ice production mechanisms including Hallett-Mossop process (Hallett and Mossop, 1974), fragmentation due to ice-ice collisions (Grzegorzczak et al., 2023; Yadav et al., 2024), and fragmentation of freezing drops (Phillips et al., 2018) were recently implemented by Grzegorzczak et al. (2025a). Ice particles are growing by vapor deposition, sublimation, riming and aggregation.
110 Several studies performed with DESCAM model also focused on cold microphysics processes (Leroy et al., 2009; Planche et al., 2014; Grzegorzczak et al., 2025b).

2.2 Ice particle size

In the original version of DESCAM (Flossmann and Wobrock, 2010), the size of the ice particles was fixed and calculated by the mass-diameter ($m - D$) relation:

$$115 \quad m = \alpha D^\beta \quad (1)$$

with D and m the ice particle diameter (in cm) and mass (in g), $\alpha = 0.0038$ and $\beta = 2.08$ are two coefficients obtained from the in situ aircraft observations of Fontaine et al. (2014). In order to improve this representation, a rime mass distribution is introduced in DESCAM for the last 27 bins of the 39 existing ones describing the ice particle number. Rime properties of the

small ice particles ($< 32 \mu\text{m}$) were ignored since the lower size threshold for ice particles at which droplet collection begins ranges from 35 to $200 \mu\text{m}$ (Wang and Ji, 2000). It is therefore supposed that small ice particles are not influenced by rime.

From the introduction of the rime mass distribution, the last 27 bins of the ice particles can be characterized in terms of rime mass fraction, defined as $\phi = \frac{m_r}{m}$ with m the total mass and m_r the rime mass of the ice particle. Based on the 'fill-in' consideration introduced by Heymsfield (1982), the diameter of ice particle D (in cm) is defined as

$$D = \max \left[\left(\frac{m(1-\phi)}{\alpha} \right)^{\frac{1}{\beta}}, D_{gr} \right] \quad (2)$$

with D_{gr} the graupel diameter (in cm) defined by $D_{gr} = \left(\frac{m}{\alpha_{gr}} \right)^{\frac{1}{\beta_{gr}}}$ with $\alpha_{gr} = 0.034$ and $\beta_{gr} = 2.59$ two coefficients taken from Heymsfield et al. (2018) and m the ice particle mass (in g). The α and β are the two coefficients previously defined for Eq. 1. When graupel particles are larger than 5 mm diameter, they are considered as hail, with $\alpha_{gr} = 0.111$ and $\beta_{gr} = 4.13$. The 'fill-in' concept considers that rime fills the interstices of ice particles without increasing their size. Consequently, in Eq. 2, the term $m(1-\phi)$ corresponds to the vapor-grown mass, which determines the particle size. Furthermore, as expressed by Eq. 2, when the particle diameter D reaches the graupel diameter D_{gr} , the 'fill-in' process ceases and the particle interstices are assumed to be fully filled by rime. At this stage, for any increase of rime mass, the ice particle will follow the $m - D$ relation of Heymsfield et al. (2018) for graupel particles

The previous considerations are illustrated by Fig. 1 which depicts the size (D) of the ice particles in DESCAM as a function of their total mass (m) and rime fraction (ϕ). In this figure, for a given mass, the particle size can vary by a factor of 2, highlighting the significant effect of riming on the ice particles properties.

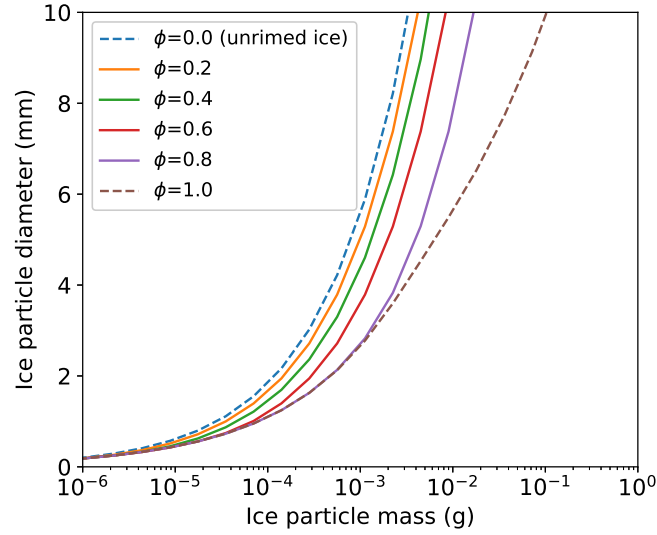


Figure 1. Mass - diameter relation of the ice particles in DESCAM depending on the rime fraction ϕ based on the 'fill-in' concept of Heymsfield (1982) and Morrison and Grabowski (2010).

In DESCAM, the density of ice particles can be diagnosed from the mass-diameter relationships presented in Fig. 1, resulting in rimed particles being denser than unrimed ones. Fully rimed particles, typically classified as graupel, exhibit densities of around 0.2 g cm^{-3} for millimeter-sized particles. This density is comparable to the graupel generated in the laboratory experiments of Grzegorzczak et al. (2023) under dry growth conditions (i.e., liquid water content of 0.7 g m^{-3} at $-20 \text{ }^{\circ}\text{C}$), meaning that fully rimed particles in DESCAM correspond to low-density graupel. This density results from the graupel mass-diameter relationship adopted from Heymsfield et al. (2018) (Table 3, "Graupel and small hail"). Future developments will focus on predicting ice particle density and accounting for wet growth to produce denser rimed particles, as discussed in Section 5.

2.3 Terminal velocity of ice particles

While the size of ice particles can change smoothly depending on their riming degree, their shape is not explicitly represented in DESCAM and is assumed to be spherical when shape is required in calculation. To calculate the terminal velocity of ice particles from their size and mass without supposing any predefined shape, a common approach relies on dimensionless numbers that describe the aerodynamics of ice particles. The Best number, X and the Reynolds number, Re were introduced by Abraham (1970) to describe the drag coefficient of a sphere and were extended by Böhm (1989) for ice particles. Based on the same considerations, different parameterizations have been proposed in the literature (Mitchell, 1996; Khvorostyanov and Curry, 2002, 2005; Mitchell and Heymsfield, 2005). The parameterization used in DESCAM is that of Heymsfield and

Westbrook (2010) which provides a modification of the Best number X and Reynolds number Re defined by:

$$Re = \frac{\delta_0^2}{4} \left[\left(1 + \frac{4\sqrt{X}}{\delta_0^2 \sqrt{C_0}} \right)^{\frac{1}{2}} - 1 \right] \quad (3)$$

155 with $C_0 = 0.35$ the inviscid drag coefficient, $\delta_0 = 8.0$ a dimensionless parameter and

$$X = \frac{\rho_a}{\nu^2} \frac{8mg}{\pi A_r} \quad (4)$$

with ρ_a the air density, ν the kinematic viscosity of air, m and D the ice particle mass and size and A_r the area ratio of the ice particle defined by $A_r = \frac{A}{(\pi/4)D^2}$ with A the projected area. To calculate A_r , Heymsfield et al. (2002) proposed the following relation $A_r = 0.29D^{-0.18}$ based on measurements in tropical cloud anvils where ice crystals are assumed to be
 160 unrimed. For graupel particles, the area ratio is calculated from the projected area of graupel $A_{gr} = 0.625D^2$ given in Morrison and Grabowski (2010) (cgs units). Contrary to ice particle size, the projected area and the area ratio of rimed ice crystals is not provided by the ‘fill-in’ concept. However, since Eq. 4 depend on A_r , a smooth transition between the area ratios of unrimed and graupel particles is needed. Therefore, the area ratio of rimed ice particle is assumed to evolve linearly between those of graupel and unrimed ice particles as follows:

$$165 \quad A_r^{rime} = A_r \left[1 - \left(\frac{D_{gr} - D}{D_{gr} - D_{\phi=0}} \right) \right] + \frac{A_{gr}}{(\pi/4)D^2} \left(\frac{D_{gr} - D}{D_{gr} - D_{\phi=0}} \right). \quad (5)$$

with D the $D_{\phi=0}$ the diameter of unrimed ice particles (cgs units).

From the previous considerations, Fig. 2 shows the terminal velocity (V) of ice particles as a function of their size and rime mass fraction (ϕ). This figure also shows the graupel terminal velocities based on the velocity-diameter ($V - D$) relationships of Lee et al. (2015) and Heymsfield et al. (2018) that can be compared with those calculated for DESCAM. For graupel particles
 170 smaller than 1 mm diameter, the predicted terminal velocity in DESCAM aligns closely with Lee et al. (2015), whereas for larger particles it is closer to Heymsfield et al. (2018). This could be explained by the fact that graupel can have different densities in nature while it is currently not the case in DESCAM scheme. A possible future perspective would be to predict the volume of rime, as proposed by ~~Morrison and Milbrandt (2015b)~~ [Morrison and Milbrandt \(2015a\)](#) which would allow rimed particles to have different densities and consequently gets rid of the fixed mass-diameter relation of graupel particles.

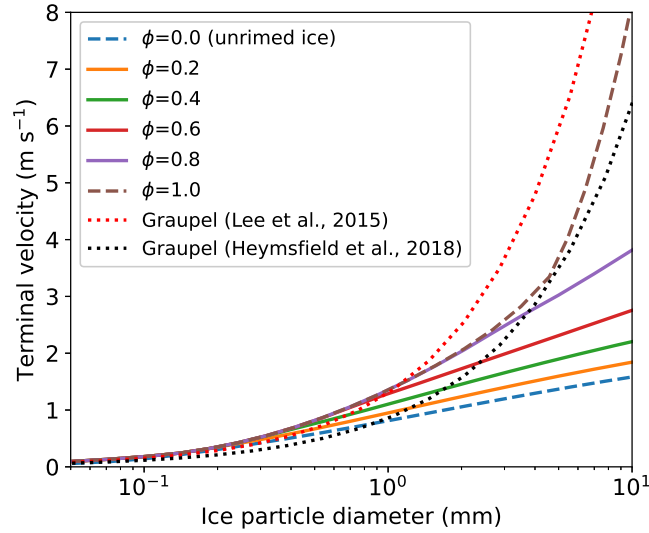


Figure 2. Terminal velocity of ice particles in DESCAM as a function of rime fraction ϕ , based on Heymsfield and Westbrook (2010) study. Dotted lines represent the graupel velocity-diameter ($V - D$) relationships from Lee et al. (2015) and Heymsfield et al. (2018).

2.4 Riming collision kernels

To represent the riming process in models, a key parameter is the collision kernels that quantify the rate at which two ice hydrometeors collide per unit time and volume. From the mass, size and terminal velocity of the ice particles presented in Fig. 1 and Fig. 2, the collision kernels for a drop of mass m_1 and an ice particle of mass m_2 with rime fraction ϕ are defined by:

$$K(m_1, m_2, \phi) = \frac{\pi}{4} (D_1 + D_2)^2 |V_1 - V_2| E_c(m_1, m_2, \phi). \quad (6)$$

with V_1 and V_2 the terminal velocity of liquid drop (derived from Beard, 1976) and ice particles, respectively. E_c is the collision efficiency of riming which depends on the particles properties. For unrimed ice particles collecting liquid drops ($V_2 > V_1$), E_c is derived from Wang and Ji (2000), while for graupel particles it follows the study of Cober and List (1993). For large liquid drops collecting ice particles ($V_1 > V_2$), the collision efficiencies are calculated from Lew et al. (1985). Therefore, for partly rimed particles, E_c is interpolated according to the particle size as done for A_r in Eq. 5.

The collision kernels are presented in Fig. 3a and Fig. 3b for unrimed and graupel particles. In both cases, the onset of riming occurs from drop or ice particles of around 100–200 μm diameter, as found by Lew et al. (1985) and Wang and Ji (2000). Fig. 3a shows an asymmetry in collision kernels due to the fact that drops fall faster than unrimed ice particles. In contrast, Fig. 3b shows a reduced asymmetry (except for large particles), as graupel particles have terminal velocities closer to those of liquid drops. This difference in terminal velocity also results in higher values of collision kernels for graupel compared to unrimed ice particles.

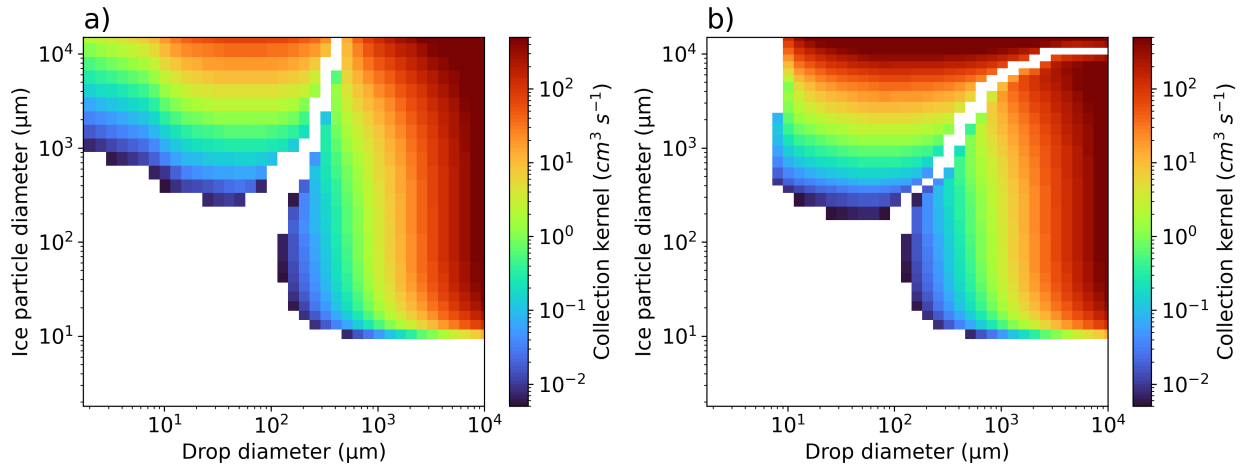


Figure 3. Riming collision kernels between liquid drops and ice particles, calculated using Eq. 6, that are implemented in DESCAM. Panel a) shows the kernels for unrimed ice crystals and panel b) presents those of graupel particles.

2.5 Aggregation collision kernels

Aggregation of ice particles is treated similarly to Eq. 6, taking into account the effects of rime on particle size and terminal velocity. As presented in a previous study (Grzegorzczuk et al., 2025a), the collection efficiency E_c for aggregation combines the collision efficiency, determined following the theoretical work of Böhm (1992), and the sticking efficiency (E_s), based on the studies of Connolly et al. (2012) and Karrer et al. (2021).

For both unrimed and rimed particles at temperatures warmer than -5 °C, as proposed in Karrer et al. (2021), E_s is assumed to increase linearly toward 1 as the temperature approaches 0 °C, reflecting the role of the sintering mechanisms due to the presence of a quasi-liquid layer on ice surfaces.

At temperatures below -5 °C, $E_s^{unrimed}$ follows the values reported by Connolly et al. (2012), reaching a maximum of 0.6 at -15 °C due to the interlocking of dendritic branches. We suppose that riming can reduce E_s near -15 °C because droplets may fill dendritic branches and limit interlocking. Accordingly, the sticking efficiency of fully rimed crystals at -15 °C is set to 0.15, corresponding to the average of the values reported at -10 °C and -20 °C by Connolly et al. (2012). The overall sticking efficiency can be expressed as a weighted average based on the rime fraction :

$$E_s(T, \phi) = (1 - \phi)E_s^{unrimed} + \phi E_s^{rimed} \quad (7)$$

It should be noted that the representation of aggregation and thus the assumptions made here regarding the effects of riming remains uncertain, as sticking efficiency has been investigated in a limited number of studies.

2.6 Budget equation for the rime mass distribution

210 The implementation of the rime mass distribution follows the same concepts and methodology as the track of aerosol mass inside ice particles and droplets developed and described by Flossmann and Wobrock (2010). The newly predicted rime mass distribution, is affected by various dynamical and microphysical processes:

$$\begin{aligned} \frac{\partial g_r(m)}{\partial t} = & \left(\frac{\partial g_r(m)}{\partial t} \right)_{dyn} + \left(\frac{\partial g_r(m)}{\partial t} \right)_{nucl} + \left(\frac{\partial g_r(m)}{\partial t} \right)_{rim} + \left(\frac{\partial g_r(m)}{\partial t} \right)_{agg/brk} \\ & + \left(\frac{\partial g_r(m)}{\partial t} \right)_{dep} + \left(\frac{\partial g_r(m)}{\partial t} \right)_{sub} + \left(\frac{\partial g_r(m)}{\partial t} \right)_{melt} \end{aligned} \quad (8)$$

The ~~the~~ left-hand term of Eq. 8 represents the total variation in rime mass $g_r(m)$ for an ice particle of mass m , due to the
 215 the sources and sinks generated by the microphysical processes. The effect of transport and sedimentation of ice particles is expressed by the ~~the~~ first term on the right-hand side of Eq. 8. As expressed by the second term on the right-hand side of Eq. 8, we also consider frozen drops generated by nucleation following Hiron and Flossmann (2015) method (i.e., condensation, immersion freezing, and homogeneous nucleation) as a source of rime. The third term represents the variation in rime mass caused by the collision of ice particles with liquid drops and is expressed as:

$$220 \quad \left(\frac{\partial g_r(m)}{\partial t} \right)_{rim} = g_d(m_1)g_i(m_2) \frac{K(m_1, m_2, \phi)}{m_2} + g_d(m_1)g_r(m_2) \frac{K(m_1, m_2, \phi)}{m_1}. \quad (9)$$

with g_i the total ice mass distribution, g_d the liquid drop mass distribution and $K(m_1, m_1, \phi)$ the riming collision kernel presented in Fig. 3. The first term of the right-hand part of Eq. 9 expresses the gain of newly formed rime mass for an ice particle of mass m due to the collision between drops of mass m_1 with ice particles of mass m_2 having a rime fraction ϕ . Furthermore, as ice crystals grow by riming, their total mass is transferred to larger bins. Consequently, the initial rime mass of
 225 the colliding ice particle (m_2) must also be redistributed into larger bins. This effect is taken into account by the second term of Eq. 9, which considers the transport of pre-existing rime mass. Since the mass gained from the collision (m_1, m_2) does not necessarily fit the defined mass bin m , the redistribution method of Bott (1998) for the stochastic collection equation is applied.

Although aggregation does not change the total rime mass, it can redistribute it across different bins, depending on the combined rime masses of the colliding particles (fourth right-hand part term of Eq. 8). The transport of rime due to the
 230 aggregation of two ice particles is treated similarly to riming (second term of the right-hand part of Eq. 9). Furthermore, when ice particles ~~does do~~ not stick but break, the rime mass fraction of the parent particle is kept constant. Additionally, the loss of rime mass due to fragmentation is considered.

Similarly to riming, when a particle gains mass through vapor deposition (fifth term of Eq. 8), it is necessary to transfer the rime mass of the initial particle into larger bins. Therefore, the gain or loss of rime mass is set to be proportional to the
 235 number of ice particles growing (or shrinking) to larger (or smaller) bin during vapor growth (or sublimation), as is detailed in Appendix A.

The sixth term of Eq. 8 represents the loss of rime mass through sublimation. Since there is no information about the surface properties of the ice particles (i.e. consisting of rime or vapor-grown ice), we assume that the particle rime fraction ϕ remains

constant during sublimation. As a result, the rime mass decreases in the same proportions as for the total ice mass. Finally, the
 240 last term of Eq. 8 expresses the sink of rime mass due to melting of ice particle (which is set to occur instantaneously, contrary
 to Planche et al., 2014).

To ensure the correct transport of rime mass through the binned distribution, numerical tests were conducted by using
 predefined rime mass distributions for each process included in Eq. 8 (with transport of sedimentation turn off). Similar tests
 of rime transport during depositional growth, aggregation and riming are presented in Morrison and Grabowski (2010) (their
 245 Figs. 1,2 and 4).

3 Simulation cases

3.1 Idealized squall line system

The first numerical experiment of this study examines the consequences of the predicted rime implementation in DESCAM
 for a large mesoscale convective system similar to the squall line that occurred on 20 June 2007 in Oklahoma and Kansas.
 250 A semi-idealized setup with 3D dynamics was applied as presented for an intercomparison study as part of the 2012 Eighth
 International Cloud Modeling Workshop (Muhlbauer et al., 2013). A detailed description of the model set-up and results of this
 intercomparison study are presented in Morrison and Milbrandt (2015a) (called hereafter MO15) and Morrison et al. (2015).

~~This study~~ We used the environmental temperature and moisture profiles described in Morrison et al. (2009) and Weisman and Klemp (19
 instead of the sounding given in MO15. The convective available potential energy ($CAPE = 2300 \text{ J kg}^{-1}$) is less pronounced
 255 than the one in MO15. This limits the extension of the cloud system in z and x direction compared to MO15 and helps to reduce
 the numerical cost of the simulations. The model domain is set to 382×128 points. The grid spacing is 1 km horizontally and
 250 m vertically. The melting level is located at a height of 4 km and the model top at 25 km. The horizontal wind profile has
 a shear of 0.0048 s^{-1} in the lowest 2.5 km altitude and zero shear above. The mean wind above 2.5 km is zero, which helps to
 keep the squall line near the center of the domain. A Rayleigh damper with damping coefficient of 0.003 s^{-1} is applied to the
 260 top 5 km. The upper and lower boundaries are free slip and rigid. Lateral boundary conditions are open.

As in MO15, convection is initiated in an uniform thermodynamic environment by applying a force to the u wind during the
 first hour of integration, providing convergence at low levels. The forcing term is prescribed as

$$\frac{\partial u}{\partial t} = \alpha \gamma \cos \left[\frac{\pi(x - x_c)}{2x_r} \right] \times \left[\cosh \left(\frac{2.5z}{z_r} \right) \right]^{-2} \quad (10)$$

where $\gamma = 1$ during the first 55 min of integration and then decreases linearly to $\gamma = 0$ at 60 min. In our study, $x_c = 192 \text{ km}$ is
 265 the center of the forcing, $x_r = 10 \text{ km}$, z is the height (in km), $z_r = 10 \text{ km}$ and $\alpha = 0.1 \text{ m s}^{-2}$ is the maximum forcing amplitude,
 and t the time in s.

To initiate 3D motion, random fluctuations perturbation of the potential temperature field are applied in a 25 km wide region
 with a maximum amplitude of $\pm 0.05 \text{ K}$ located next to the center x_c .

3.2 Heavy snowfall event during ICE-POP 2018

270 The second case study evaluates the relevance of the DESCAM implementations, by comparing the model results with
ground-based field observations. It focuses on the snowfall event that occurred between 7 and 9 March 2018, during the
passage of a low-pressure system over the Korean Peninsula during the ICE-POP 2018 campaign. This event is categorized
as "warm low" according to Kim et al. (2021), following the synoptic classification of Jeoung et al. (2020). The "warm low"
system forms over the southwestern part of the Korean Peninsula due to the abundant moisture supplies from the East China
275 Sea. This moisture leads to the development of precipitating cloud systems moving across the peninsula and producing heavy
snowfall. After the passage of the low pressure deep system, the wind in the upper layer shifts from southwest to northeast,
bringing in dry air. Consequently, a shallower cloud system forms exclusively in the lower layer. This system is mainly in-
fluenced by moisture from the East Sea, driven by sea-air interactions and orographic lifting along the eastern mountainous
coastal region. More details on this type of cloud system can be found in Kim et al. (2021).

280 3.3 Observations

3.2.1 Observations

Observations were conducted at several measurement supersites equipped with ground-based microphysical probes, wind
profilers, radars, and both fixed and mobile radiosounding stations. An overview of the instrumentation of the ICE-POP 2018
campaign can be found in Kim et al. (2021); Gehring et al. (2021, 2020b); Tsai et al. (2022). The present study mainly uses
285 the instrumentation of the MHS (Mayhills supersite; 37.6652° N, 128.6996° E; 789 m altitude) station. This site includes a
vertically pointing X-band radar and a W-band cloud Doppler radar, both providing radar reflectivity. A OTT Pluvio² rain
gauge is used to measure the rainfall accumulation and intensity and an OTT Parsivel² disdrometer (Tokay et al., 2014) is
used to determine the dominant type of precipitation (rain or snow). The Particle Imaging Package (PIP, Newman et al., 2009;
Pettersen et al., 2020) probe provides the size distribution of ice particles from 0.1 to 26 mm diameter. Complementary, a
290 multi-angle snowflake camera (MASC, Garrett et al., 2012) is used to obtain the morphological properties of the ice particles
following Praz et al. (2017) method, providing a rime index (ranging from 0 to 1) and a classification in 6 hydrometeors types.
In addition, three other disdrometers and rain gauges, deployed at YPO (Yongpyong Observatory; 37.6433°N, 128.6705°E;
772 m altitude), BKC (Bokwang-ri Community Center; 37.7381°N, 128.8058°E; 175 m altitude), and GWU (37.7709°N,
128.8669°E; 36 m altitude) are used in this study to provide the precipitation properties previously mentioned.

295 Fig. 4a-b shows the locations of the measurement sites mentioned previously, within the third (most refined) domain of
DESCAM model. The As visible from the topography cross section in Fig. 4c, the YPO and MHS sites are located in moun-
tainous regions while BKC and GWU are close to the coast (i.e. at lower altitudes).

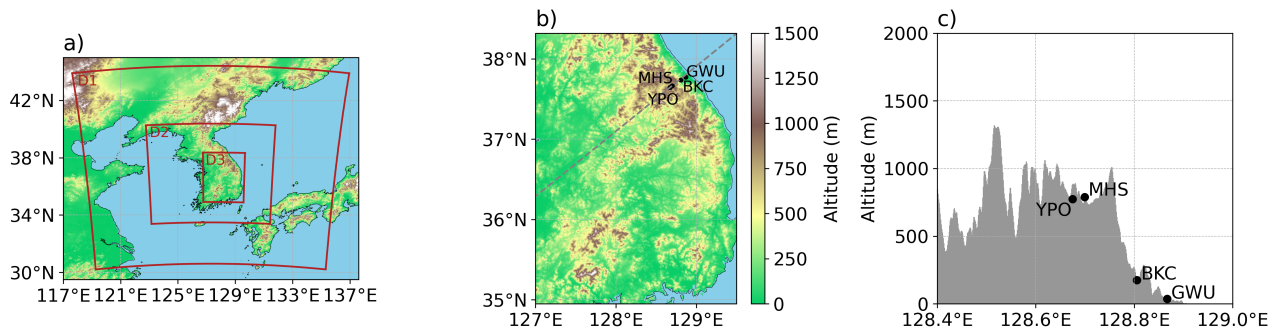


Figure 4. a) Location of the measurement sites of the ICE-POP 2018 campaign indicated in the innermost model domain. b) Nested model domains of DESCAM considered for the numerical experiments with 8 km (D1), 4 km (D2) and 1 km (D3) horizontal resolution. b) Location of the measurement sites of the ICE-POP 2018 campaign indicated in the innermost model domain. c) Topography and positions of the measurement sites along the transect indicated in panel b).

3.3 Numerical experiment

300 3.2.1 Numerical setup

In this study, the bin microphysics scheme DESCAM (see sections 2.1 and 2.2 for more details) included in the 3D dynamical frame of Clark et al. (1996); Clark (2003) is used. The numerical experiment consists of three nested domains shown in Fig. 4ba, composed of 193×193 , 193×193 and 258×386 grid points corresponding to horizontal resolutions of 8, 4 and 1 km, similar to the setup of Park et al. (2024). The vertical resolution is set to be grid is non-equidistant with around, with 82 vertical levels ranging from $\Delta z = 40$ m at ground level and $\Delta z = 230$ m at 9 km. The simulations are run for two days from March 7, 2018 at 00:00 UTC to March 9, 2018 at 00:00 UTC with a time step $\Delta t = 4$ s. The initial and boundary conditions of DESCAM are taken from ERA 5 ECMWF reanalysis (Hersbach et al., 2020). The aerosol particle size distribution is derived from the measurements of Yum et al. (2007) at Jeju Island (during March–April) and Park et al. (2021) at Baengnyeong Island, for air masses coming from the East China sea (classified as Type II and III in the aforementioned studies) which is where the cloud system forms. Therefore, the total aerosol particle concentration is set to 4500 cm^{-3} at ground and is assumed to decrease exponentially to 1500 cm^{-3} for altitudes above 3 km. We presumed-assumed that aerosol particles are composed of ammonium sulfate, as for this case study, the air masses mainly originated from the ocean (the East Sea for the shallow system and the China Sea for the deep system), although some influence from more polluted conditions cannot be excluded.

Two simulations were conducted using DESCAM. The first one, mentioned as the for each case study (i.e. squall line and ICE-POP): the "controlCTRL" simulation which disables the predicted rime scheme and follows the original configuration (i.e. Control version) of DESCAM before the new developments and the second one mentioned as "pRIME" simulation, which includes the recent implementations-implementation of the predicted rime described in Section 2.1, with the predicted rime mass distribution, the fill-in effect, and the rime dependency of ice particle terminal velocity and collision kernels. The second

simulation, called "no rime", disables the predicted rime scheme and follows the original configuration of DESCAM before
320 the new developments.

4 Results

The ability of

4.1 Idealized squall line system

325 Figure 5 presents a vertical and an horizontal cross section of total water content (TWC) at 5 km altitude from the pRIME simulation, illustrating the extent of the squall line at 02:30h of integration. This time was selected for the present analysis because the system remains quasi-steady between 02:00h and 04:00h, while differences in precipitation pattern arise after 02:30 indicate diverging cloud development. The squall line reaches up to 11.5 km altitude, and its anvil extends about 200 km in the x direction (Fig. 5a). The horizontal cross section (Fig. 5b) shows relatively continuous values along the y axis, which will be therefore averaged in the subsequent analyses.

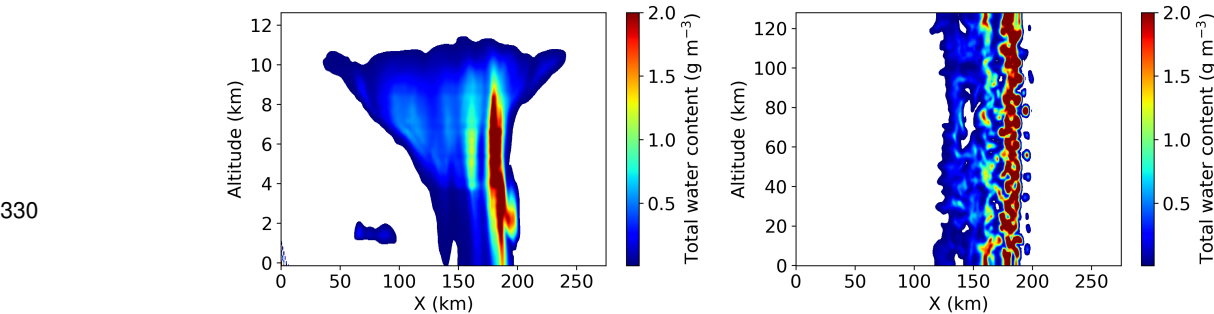


Figure 5. Total water content (TWC) of the squall line from the pRIME simulation at 02:30h (only values $> 0.01 \text{ g m}^{-3}$ are shown).
a) y-averaged vertical cross section and b) horizontal cross section at 5 km altitude.

To evaluate the effect of the ~~DESCAM (control simulation)~~ new prediction of rime scheme, averaged vertical profiles of the squall line system are presented by Fig. 6 at 2:30 h.

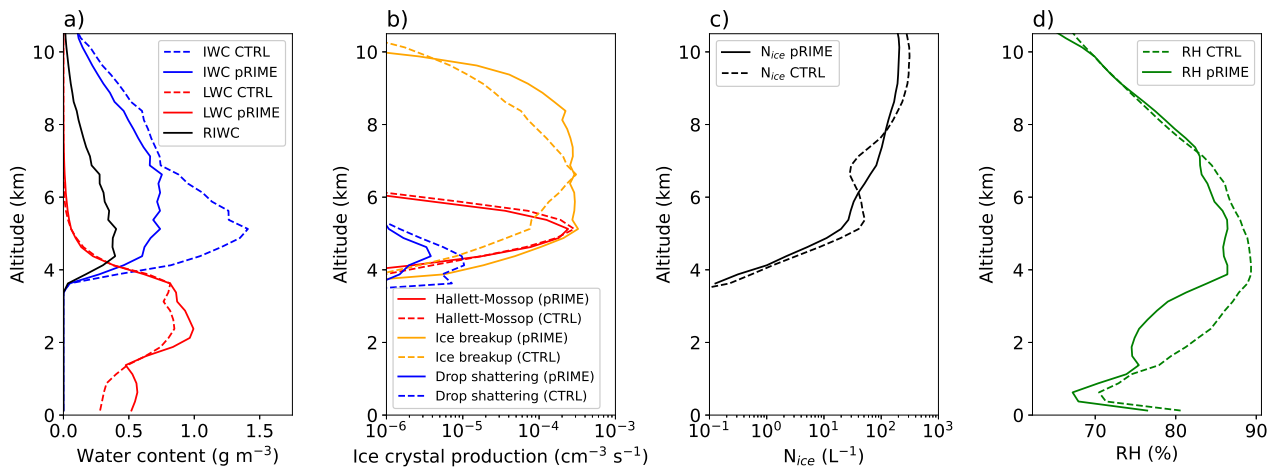


Figure 6. Vertical averaged profiles (for TWC > 0.01 g m⁻³ at 2:30 h) of cloud contents (a), rate of SIP processes (b), ice particle number concentration (c) as well relative humidity (d).

First, Fig. 6a shows that the ice water content (IWC) in the pRIME simulation is reduced by about a factor of two compared to CTRL while the liquid water content increases up to 0.2 g m⁻³ in the lower 4 km where $T > 0^{\circ}\text{C}$. The more pronounced presence of LWC in the warm phase of the cloud (below the melting layer) is also a results from the higher fall velocities as a consequence of the explicit rime prediction. Indeed, Fig. 6a shows that for the pRIME simulation, the mean Rime Ice Water Content (RIWC) reaches up to 0.45 g m⁻³, which represents approximately half of the IWC below 7 km.

In Fig. 6b, the production rate of ice particles from SIP processes shows that the ice collision breakup mechanism is stronger in the pRIME simulation, due to higher terminal fall velocities of rimed particles. The Hallett-Mossop process rate remains unchanged, while the drop shattering mechanism appears to decrease. Although SIP produces more ice particles in the pRIME simulation due to stronger ice breakup, the average ice particle number concentration in Fig. 6c is overall lower in pRIME, likely because faster sedimentation due to riming reduces their persistence within the cloud. An exception occurs near 7 km (i.e. -15°C) where N_{ice} in the pRIME simulation is higher due to the lower sticking efficiency of rimed particles (see Section 2.5 about aggregation).

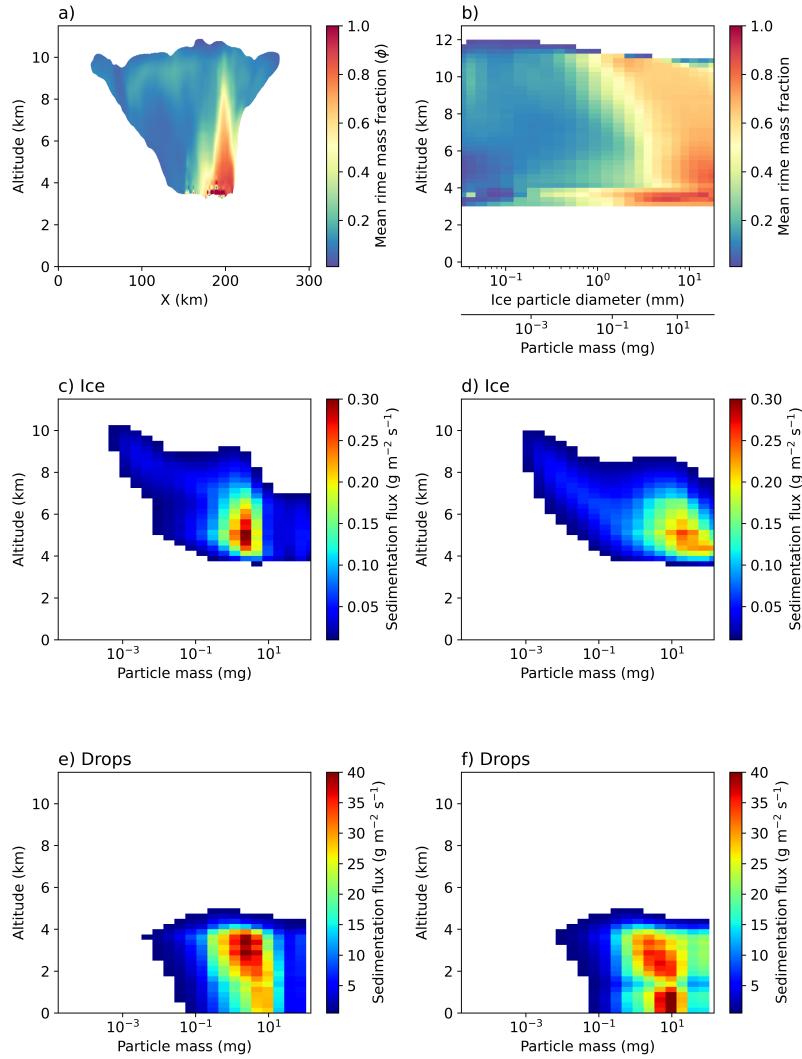


Figure 7. Vertical cross section of the mean rime mass fraction ϕ (y-direction averaged) a), mean rime mass fraction as function of the particle size and altitude b). Sedimentation flux of ice particle as function of ice particle size or mass and altitude for the CTRL c) and pRIME simulation d). Sedimentation flux of drops as function of their size and altitude for the pRIME c) and CTRL simulation d). All panels are averaged for TWC $> 0.01 \text{ g m}^{-3}$ at 2:30h.

To further analyze the rime mass implementation in DESCAM, Fig. 7a shows the y-averaged vertical cross section of the rime mass fraction (ϕ). It shows that for a large part of the squall line, ϕ exceeds 0.5, especially around the main convective core and up to 9 km altitude. The rime mass fraction even approaches 1 within the main convective core due to the strong presence of supercooled liquid water in this region.

Fig. 7b illustrates how the rimed ice is distributed across different ice particle sizes and masses (i.e. bins). At all altitudes, rime fraction increases with particle size (or mass), exceeding 50% for particles larger than 1 mm. This can be explained by the fact that large ice particles have higher collision kernels, which favor riming.

As the presence of rime on large ice particles increases their fall speed, Figs. 7c–d shows the sedimentation flux of ice particles as a function of their size and altitude for the CTRL and pRIME simulations. A clear shift of the sedimentation flux mode is observed across 4 to reproduce the observed cloud system evolution and intensity is evaluated in Section 4.2.1. The effect of 7 km altitude, from 5 mg (2 mm ice particles) in the CTRL simulation (Fig. 7c) to 20 mg (10 mm ice particles) in the pRIME simulation (Fig. 7d). This shift is consistent with the high ϕ values on large ice particles (Fig. 7b), which both increase their fall speed and promote growth to larger sizes by riming. Indeed, the presence of larger (i.e. more massive) ice particle in pRIME simulation is clearly visible in the mass size distribution (see Fig. B1a).

Similarly to Figs. 7c–d, Figs. 7e–f show the sedimentation flux of liquid drops. Below 4 km ($T > 0^\circ\text{C}$), the sedimentation flux of drops also shifts, with the peak moving from 3 mg (1.8 mm) drops in the CTRL to 10 mg (2.7 mm) drops in Rime. In addition, the flux of large drops > 20 mg (3.5 mm) increases significantly in the pRIME simulation. This shift toward larger drops coincides with the upward shift of ice particle sedimentation flux in the ice phase (see Fig. 7d), suggesting that it results from the melting of large rimed ice particles located just above the melting layer. This is further supported by the mass distribution of ice particles above the melting layer (Fig. B1a) and of drops just below it (Fig. B1b), which present similar differences between the CTRL and pRIME simulations.

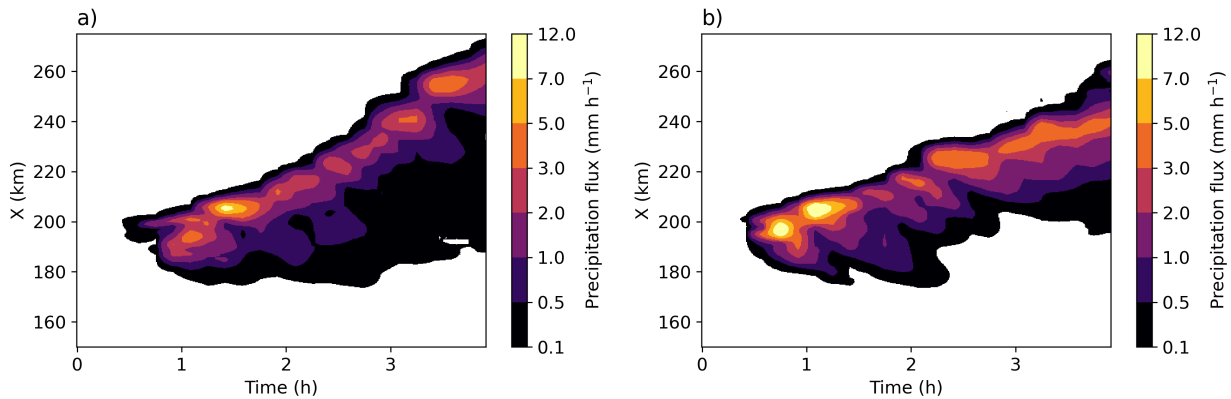


Figure 8. Temporal and spatial (y-averaged) evolution of precipitation rate larger than 0.1 mm h^{-1} for the CTRL a) and pRIME b) simulations.

The effect of the explicit rime prediction on the liquid phase properties of the squall line becomes also evident in the evolution of the precipitation rate presented in Fig. 8. The pRIME simulation (Fig. 8b) exhibits stronger and earlier precipitation rates compared to the predicted rime mass distribution on CTRL simulation (Fig. 8a). Overall, the pRIME simulation produces 25% more precipitation than CTRL. This increase is consistent with the shift and rise of the precipitation flux toward larger drops, resulting from the melting of rimed ice particles, as shown in Fig. 7.

Furthermore, the precipitation accumulation and evolution is examined in Section 4.2.1. Section 4.2.1 focuses on the analysis of ice particle properties (size, number, and rime content) to assess the relevance of the updated version of DESCAM. Finally, Section 4.2.1 investigates how the dynamical configuration influences the microphysical location of the precipitation maximum intensity also shifts from 2:30. At 4:00 h, the maximum in the pRIME simulation occurs at 240 km, compared to 260 km in CTRL. This suggests that the propagation of the squall line and therefore the convective properties of the ice-particles-cloud system can be influenced by the rime prediction.

A possible explanation lies in the differences in drop size distributions (DSD) between the two simulations. In the pRIME simulation, which produces more large drops and fewer small ones, evaporation in the cold pool is reduced (not shown here), consistent with a lower relative humidity below the melting layer in Fig. 6d. The weaker evaporation in the pRIME simulation reduces the cold pool cooling which is a key driver of squall line convection, leading to a weaker convective intensity and a more stationary cloud system as visible in Fig. 8. In contrast to that, the smaller droplets in the CTRL simulation enhance evaporation, produce larger and stronger cold pool, and consequently support more vigorous convection and faster squall-line propagation, as noted by Morrison et al. (2012). This effect observed here for the pRIME simulation was also reported by Van Weverberg et al. (2012) when including a predicted graupel category in a two-moment bulk scheme. Additionally, the influence of the drop size distribution and rimed particles on squall-line cold pool intensity has been also documented by Morrison and Milbrandt (2011).

A second factor contributing to the weaker convection of the squall line is the latent heat released within the ice phase. In the pRIME simulation, stronger sedimentation reduces the mass and number of ice particles compared to CTRL (see Fig. 6a and c), resulting in lower latent heat production from vapor deposition (not shown here). This weakens the buoyancy above 4 km and, as a feedback, can also reduce the strength of the cold pool and the propagation speed of the cloud system.

4.2 Cloud system intensity and evolution Heavy snowfall event during ICE-POP 2018

This section presents the evaluation of the DESCAM pRIME and CTRL simulations against ground-based measurements for a heavy snowfall case that occurred during the ICE-POP 2018 field campaign (see section 3.2).

4.2.1 Cloud system intensity and evolution

The Figure 9 shows the temporal evolution of the X and W band radar reflectivity at the MHS mountainous station is shown in Fig. 9 for both ground observations and the DESCAM control simulation, for observations in a) as well as DESCAM CTRL and pRIME simulations in b) and c), respectively. The modeled reflectivity is calculated using the Self-Similar Rayleigh-Gans Approximation (SSRGA) method (Hogan et al., 2017; Leinonen et al., 2017), that account for the internal structure of ice aggregates. The ice particle properties for this method follow the SSRGA-LS15-B0.2 configuration described by Tridon et al. (2019), that provides the best agreement with observed reflectivity measurements. As shown The radar observation in Fig. 9a and c, the radar observations show shows two distinct cloud systems with a deep system induced by the low pressure passage until 6:00 UTC (March 8), followed by a shallower one. The deep low pressure system produces precipitation at the surface from around 09:00 UTC, whereas in DESCAM both DESCAM simulations (Fig. 9b,d,c) the precipitation onset is delayed until

15:00 UTC. Nevertheless, the model accurately reproduces the observed weakening of reflectivity around 18 UTC, suggesting that the simulation does not exhibit a systematic delay but rather fails to reproduce the early development phase of the low pressure system between 09:00 and 15:00 UTC.

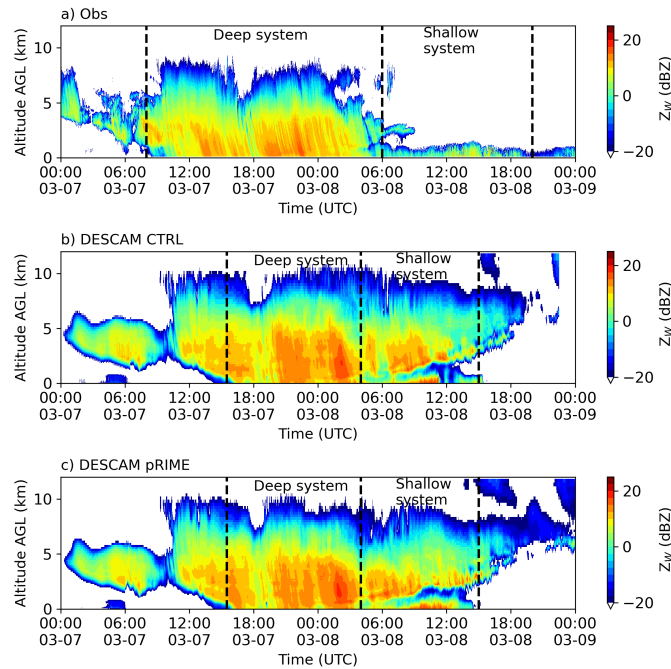


Figure 9. Time-height (above ground level) evolution of W-band radar reflectivity at the MHS station: a) ~~X-band~~ observations, b) DESCAM ~~X-band-control~~ CTRL simulation, c) ~~W-band-observations, and d)~~ DESCAM ~~W-band-control~~ pRIME simulation. Dashed lines indicate the limits of the different cloud systems.

Around 06:00 UTC (March 8), radar observations (Fig. 9a and e) show the transition of the deep low pressure system to a shallower one of around 2 km height above ground level. This system, as explained in Section ~~??~~3.2, corresponds to the dominance of an easterly low level flow following the low pressure system, inducing orographic lifting and the formation of low level clouds. In Fig. 9b and d, although the model reproduces simulations are reproducing the presence of a shallow system of 2 km height, it also generates both of them generate a second cloud layer above 2 km altitude, decoupled from the one below, that is absent in the observations. Therefore, the transition of these two cloud systems is less distinct in DESCAM than in the observations. Additionally, the shallow system starts slightly earlier in the simulation compared to the observations and consequently ends 5 hours earlier, around 15:00 UTC on March 8. The difference same conclusions applies for the X-band radar features also deployed at MHS (see Fig. S1 of Supplementary material). In addition, the differences between the X and W band radar reflectivities is are illustrated by the dual wavelength ratio reflectivity (DWR i.e. $Z_X - Z_W$) in Fig. ?? of Appendix BS3 of Supplementary material.

To further evaluate the intensity and vertical structure of radar reflectivity, Fig. 10 and 11 present the vertical frequency distribution of ~~observed and simulated reflectivity at X and W bands~~ the radar reflectivity for the two distinct cloud systems. For the deep system, ~~DESCAM control simulation both DESCAM simulations~~ (Fig. 10b and ~~d) shows c)~~ show high reflectivity frequencies near ~~20 dBZ (X-band) and 10 dBZ (W-band)~~ next to the surface, matching well the intensity of the observations (~~in~~ Fig. 10a ~~and e~~). Moreover, compared to the observations, the vertical decrease in reflectivity frequency is well captured ~~in the simulation for both X and W bands~~ by both simulations. As mentioned in Kim et al. (2021), the presence of higher reflectivity with decreasing altitude is due to the growth of snow aggregates. However, ~~in Fig. 10d, for the W-band~~ for both CTRL and pRIME, the modeled reflectivity extends to higher altitudes, reaching a maximum frequency of -12 dBZ at approximately 9 km, compared to 8 km in the observations.

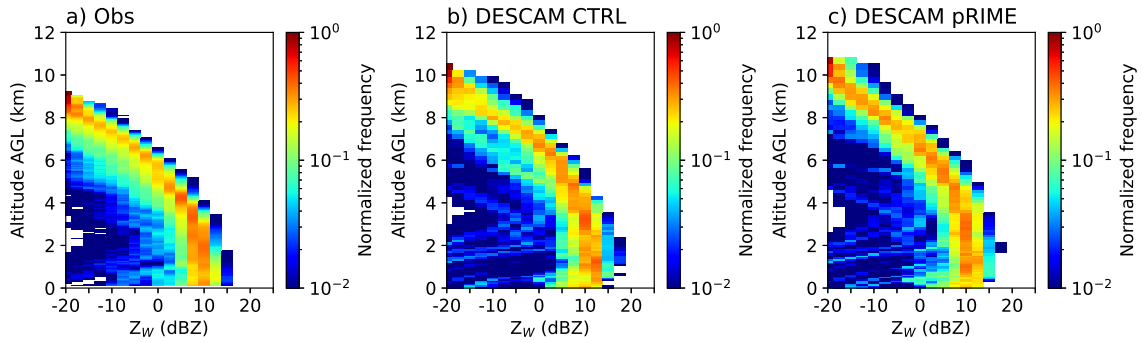


Figure 10. Frequency of W-band radar reflectivity as function of the altitude above ground level for the deep cloud system presented in Fig. 9 with: a) X-band-observations, b) X-band-DESCAM ~~control~~-CTRL simulation and c) W-band-observations and d) W-band-DESCAM ~~control~~-pRIME simulation.

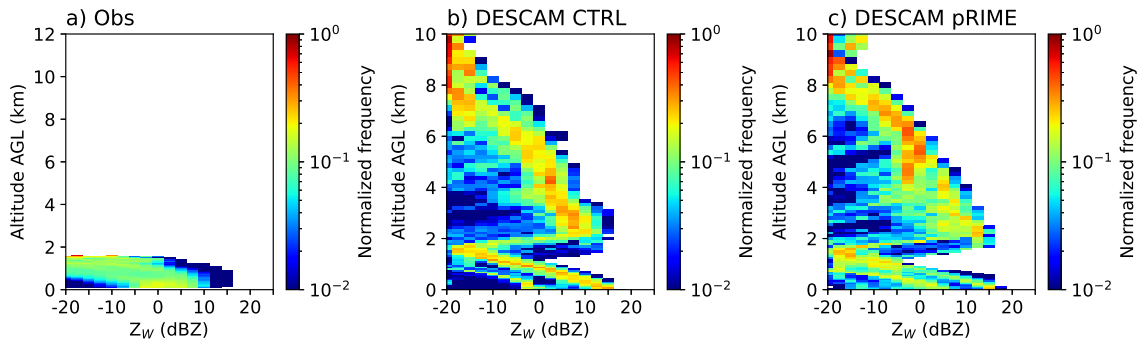


Figure 11. As Fig. 10 but for the shallow cloud system ~~presented in Fig~~ presented in Fig (i.e. after 9:00 UTC on March 8). 9.

For the shallow system, radar observations (~~in~~ Fig. 11a ~~and e~~) display reflectivity frequencies at the surface ranging from ~~0 to 15 dBZ for the X-band and -10 to 10 dBZ for the W band~~. In contrast, DESCAM CTRL (Fig. 11b ~~and d~~) overestimates

435 ~~the reflectivity intensity throughout the shallow layer, with a consistent positive bias of approximately) exhibits higher values~~
~~with a narrow surface reflectivity peak which consistently overestimates reflectivity by about +5 dB for both bands and for~~
~~altitudes lower than to +10 dB below 2 km height. Nevertheless, the~~. Compared to CTRL, the pRIME simulation shows more
variable reflectivity close to the ground (with -10 to 15 dBZ) which better matches the observations. This is due to rimed
440 ~~particles becoming smaller due the fill in hypothesis, reducing reflectivity while increasing variability depending on the rime~~
~~mass fraction. Overall, for higher altitudes, the~~ general vertical decrease in reflectivity up to 2 km is reasonably well captured
for both simulations.

Above 2 km, ~~substantial discrepancies emerge in~~ Fig. 11 ~~as the model continues to simulate show that both simulations~~
provide high reflectivity values (from ~~10-15~~ dBZ at 2 km down to -10 dBZ at 8 km), ~~similarly similar~~ as the structure of
the earlier deep system (Fig. 10). ~~In contrast, the observations show much weaker reflectivity~~ This represents a significant
445 ~~discrepancy, as the observations indicate no cloud~~ above 2 km. These differences suggest that the model may be prolonging
the presence of the upper portion of the deep system, leading to an upper cloud layer above the shallow system.

To further analyze the microphysics of the cloud system, Fig. 12 shows the W-band mean Doppler velocity for the obser-
vations and DESCAM ~~control~~ CTRL and pRIME simulation. During the deep cloud system, the observed Doppler velocity
near the ground is close to -1 m s^{-1} , which is accurately reproduced by ~~the model~~ both simulations, showing similar values
450 with only some peaks reaching around -1.3 m s^{-1} . Between 4 and 6 km altitude, radar observations (Fig. 12a) ~~shows show~~ an
increase in Doppler velocity up to -2 m s^{-1} . As mentioned in Gehring et al. (2020b) and Kim et al. (2021), this enhancement
may be attributed to a shear layer and therefore turbulence that leads to favor aggregation and riming. ~~However, this~~ This rise
in Doppler velocity also coincides with temperatures near -15°C , that ~~favor favors~~ dendritic growth and aggregation, poten-
tially resulting in larger and faster falling ice particles. However, as the DWR, which is sensitive to ice particle size, does not
455 significantly rise at this altitude (Fig. ~~??, Appendix B1 of supplementary material~~), the large Doppler velocities of Fig. 12a can
be more likely attributed to riming rather than aggregation.

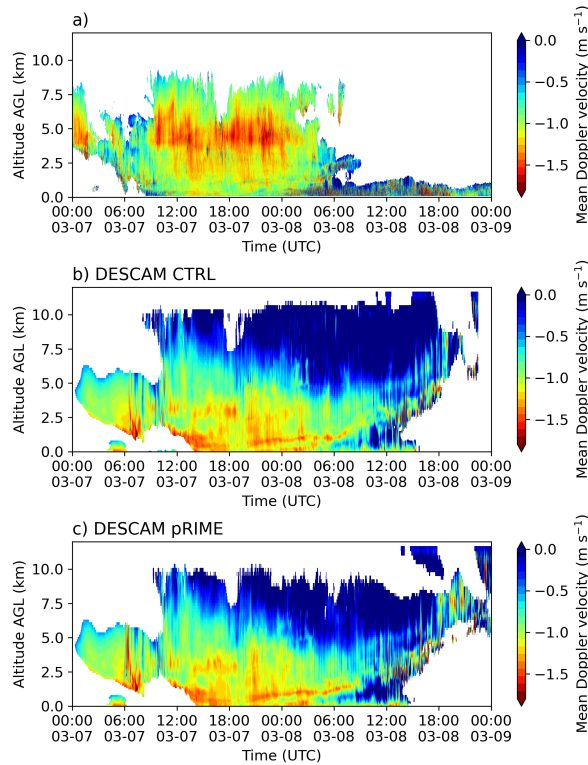


Figure 12. Mean Doppler velocity (defined positive upwards) at the MHS station for a) W-band radar observations in and b) DESCAM ~~control~~ CTRL simulation and c) DESCAM pRIME simulation. Data are presented for reflectivity values exceeding -20 dBZ (see ~~Figs~~Fig. 9e,d).

Regarding the control simulation For both simulations (Fig. 12b and c) the most notable increase in modeled velocity occurs near 1.5 km, within a transition layer between easterly and southwesterly airflows, where wind shear and thermal inversion are present. Close to 3.5 km, only a slight increase in Doppler velocity is provided by the model with much lower values than in the observations. Above 6 km, despite accurately representing radar reflectivity in Fig. 9, ~~DESCAM~~ both DESCAM simulations significantly underestimates the Doppler velocity compared to the observations. This discrepancy suggests that DESCAM may generate an excessive number of small ice particles in the upper cloud layers. Indeed, while these particles can produce reflectivity intensities comparable to the observations in Fig. 9, their low terminal velocity leads to an underestimated Doppler velocity in Fig. 12. The significant underestimation of DWR by-in the simulation compared to radar observations in Fig. ?? (Appendix B) S2 of supplementary material further confirms that DESCAM underestimates ice particle sizes near the cloud top.

In Fig. 12a, during the shallow cloud phase and below 2 km altitude, the observed Doppler velocities show a large variability, ranging from 0 to -2 m s^{-1} , whereas the modeled Doppler ~~velocities~~ velocity appear more uniform, with values around -1 m s^{-1} .

470 s^{-1} . ~~Additionally, in DESCAM CTRL. In contrast, near the ground, DESCAM pRIME exhibits stronger Doppler velocities (around -1.5 m s^{-1}), reflecting again the influence of the predicted rime in the shallow system.~~

~~Additionally, for the shallow system, in Fig. 12b and c, the modeled cloud layer above 4 km exhibits after 06:00 UTC (March 8) exhibits~~ relatively low Doppler velocities (-1 to 0 m s^{-1}) that are associated with significant reflectivity (Figs. 9b,d). This further indicates the presence of numerous small, and slowly precipitating ice particles, similarly to the results for the upper
475 levels of the deep system mentioned previously.

~~The~~ ~~We identified that the~~ overproduction of these small ice particles ~~likely originating originates~~ from a numerical artifact. ~~In-Indeed, in~~ the southwestern and northwestern corners of the outermost domain, mountainous terrain near the boundaries (Fig. 4ba) appears to influence incoming air masses by generating artificial updrafts at the upper levels of the domain. These updrafts lead to an ~~artificial~~ humidity enhancement at the western lateral boundary, triggering the production of a large number
480 of ice particles by heterogeneous and homogeneous ice nucleation. ~~It is important to note that this artificial upper cloud layer may contaminate the shallow cloud system through a seeder-feeder mechanism, potentially influencing its microphysical properties. A thorough evaluation of the microphysics of the shallow system against ICE-POP ground-based observations will be presented in the following sections.~~

4.3 Precipitation properties

485 4.2.1 Precipitation properties

The temporal evolution of accumulated precipitation at the four observation stations, based on Pluvio measurements and compared with DESCAM simulations, is shown in Fig. 13. As already observed for radar reflectivity (Fig. 9), the first phase of the cloud system is not represented by ~~the model, with precipitation beginning both simulations where precipitation starts at~~ around 15:00 UTC ~~in the simulation, which is (i.e. 3 hours later than in the observations).~~ After this delay, precipitation rate
490 from the ~~control simulation CTRL and pRIME simulations~~ becomes comparable to observations in the coastal regions (Fig. 13c,d), but remains slightly lower in the mountainous areas (Fig. 13a,b). Due to a later start, at the end of the deep system (04:00 UTC on March 8), the accumulated precipitation in ~~DESCAM control simulation both simulations~~ is less than half of the Pluvio measurements in mountainous areas (Fig. 13a,b) and about 5 mm lower in coastal areas (Fig. 13c,d).

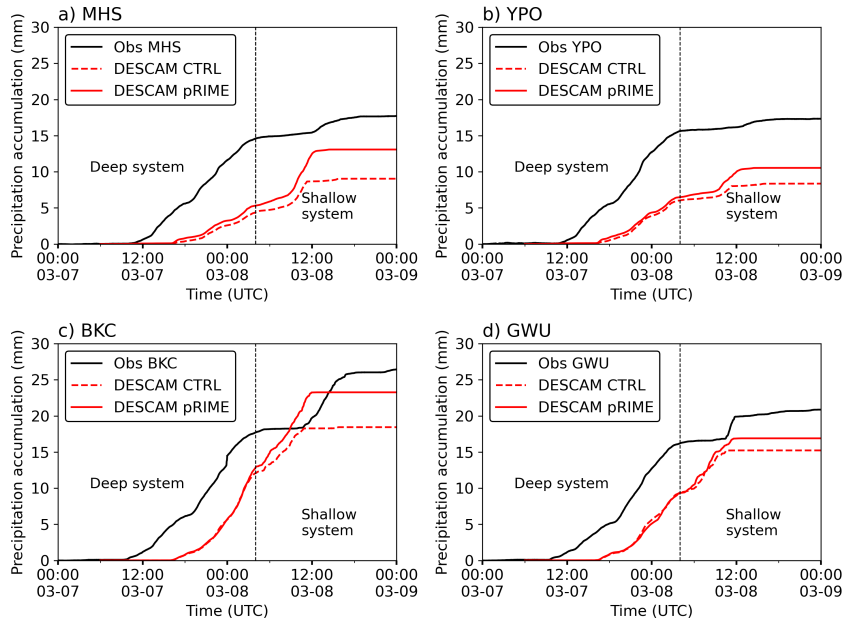


Figure 13. Temporal evolution of the precipitation accumulation at MHS, YPO, BKC, and GWU stations (see locations in Fig. 4). Black lines represent observations from the Pluvio rain gauge, while blue and the red lines show DESCAM simulation results a) - b) for mountainous stations and c) - d) for coastal stations. Plain and dashed lines represent DESCAM results for the ~~control~~ pRIME simulation and ~~no-rime~~ CTRL simulation, respectively. The black dashed line-lines indicate the limits of the different cloud systems.

495 Due to a delayed onset, the accumulated precipitation in the control simulation after the passage of the deep system (around 4 UTC on March 8) is roughly half of the observed total in mountainous areas, and about 5 mm lower in coastal regions.

For the shallow system, in the mountainous regions (Fig. 13a,b), DESCAM ~~control~~ simulation-simulations leads to more intense precipitation, that starts 3 hours earlier (at 09:00 UTC on March 8) compared to the observations (at 12:00 UTC on March 8). This aligns with the +5 dB-positive bias in the modeled radar reflectivity shown in Fig. 11 for the MHS station. This stronger modeled shallow system compensates the earlier underestimation of precipitation accumulation. At the coastal sites (Fig. 13c,d), DESCAM ~~control~~ pRIME simulation produces similar precipitation rate as the observed one while it starts immediately after the deep system, whereas observations show a distinct gap of 6 hours between the two events. Overall, at the end of the control simulation, DESCAM underestimates total precipitation accumulation by about 5 mm at all sites compared to the Pluvio observations.

505 In As expected from stronger Doppler velocities and lower reflectivity during the shallow system at ground, Fig. 13, the comparison between the control and no-rime simulation highlights the significant role of riming in demonstrates the important role of predicted rime on precipitation formation. Turning off the predicted rime scheme in CTRL results in a reduction of precipitation at all stations, with differences up to 5 mm (i.e. around 17% to 40%) at 00:00 UTC on March 9. These discrepancies are most notable at the end of the deep system and during the shallow phase that are i.e. periods when riming is

510 especially active. However, at the end of the pRIME simulation, DESCAM still underestimates total precipitation accumulation by about 5 mm at all sites compared to the Pluvio observations.

To further evaluate the precipitation characteristics simulated by DESCAM, Fig. 14 presents the temporal evolution of precipitation accumulation type (for > 0.1 mm accumulation within 3 hours) at the four observation stations. At the two mountainous stations MHS and YPO ~~mountainous stations~~ (Fig. 14a and ~~ed~~), Parsivel data indicate that ice particles dominate precipitation during the deep cloud system phase. ~~This observation is consistent with DESCAM results~~ Both DESCAM simulations (Fig. 14b~~and d~~), ~~which, c, e, f~~ also show predominantly ice precipitation, which is consistent with the observations. For the shallow cloud system, both observations and the model simulations show the occurrence of a small amount (~~i.e. less than 20%~~) of liquid precipitation. It should be noted that the presence of liquid precipitation is more pronounced in CTRL than in pRIME, probably because of higher consumption of water drops by rimed particles.

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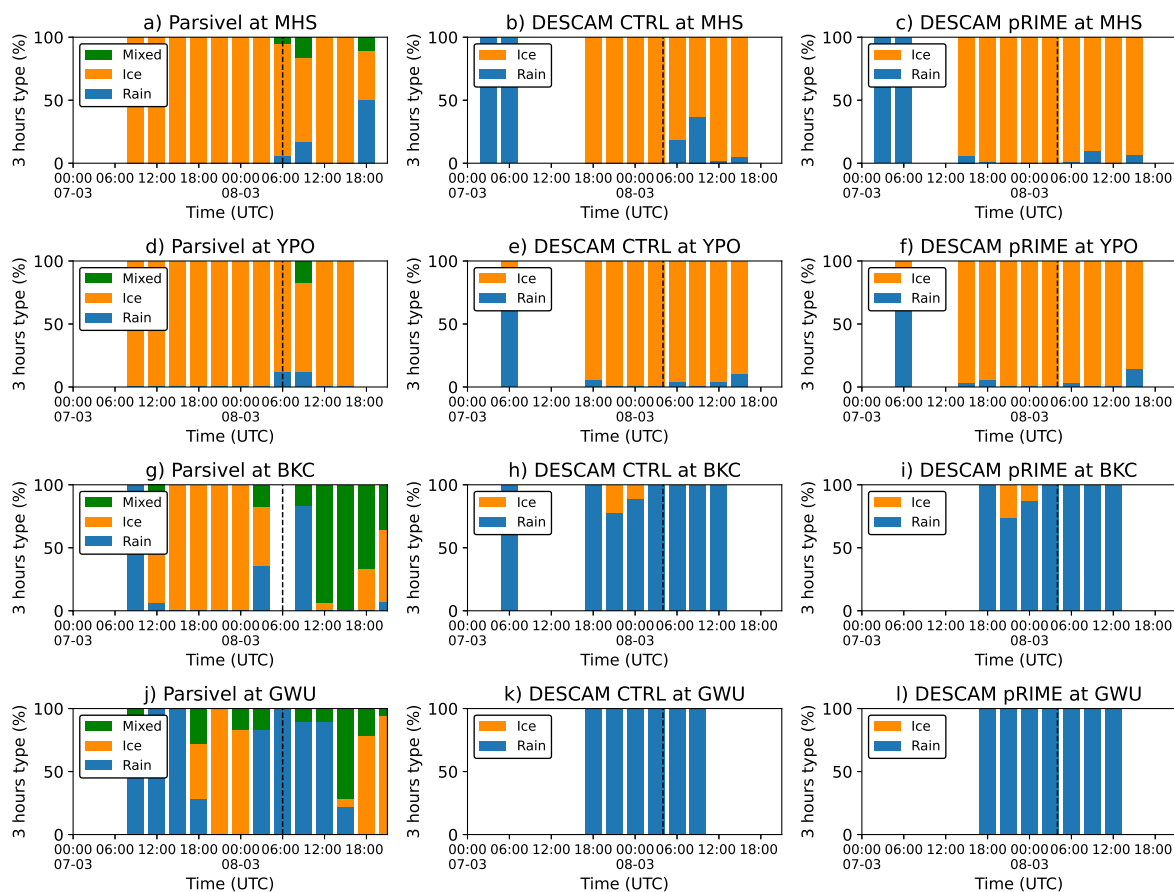


Figure 14. Temporal evolution of precipitation accumulation type (for > 0.1 mm within 3 hours) based at the MHS, YPO, BKC, and GWU stations observed by the Parsivel instrument (left column) and simulated by DESCAM for the CTRL (middle column) and pRIME (right column) for the control simulation. The 'mixed' particles describes melted or melting hydrometeors not identifiable as either rain or snow. The black dashed line indicate the limits between the deep and shallow cloud systems.

In contrast, for the BKC and GWU coastal stations, the model outputs (Fig. 14 ~~f and h~~ h, i, k, l) give almost exclusively liquid precipitation, with only a minor contribution from ice particles at BKC. However, the Parsivel observations in Fig. 14 ~~e and g~~ e and j show a significant part of ice precipitation during the deep system and a transition to mixed-phase (partially melted) particles during the shallow system.

This suggests that DESCAM may overestimate the altitude of the melting layer in coastal regions. Another possible cause of the liquid overestimation in DESCAM is maybe due to the assumption that ice particles melt instantaneously at the 0°C isotherm level (see 5 for this limitation). In reality, melting is gradual, potentially prolonging the presence of solid or mixed-phase particles, as suggested by the Parsivel observations.

Fig. 15 presents the spatial distribution of accumulated precipitation at the end of the simulation, for ice The precipitation fields from DESCAM pRIME and CTRL simulations (Fig. 15a), rain (Fig. 15b), and total precipitation (b) generally reproduce well the observed precipitation pattern and amount compared to the AWS (Automatic Weather Stations) rain product presented in Fig. 15c). As shown in Fig. 15b, ice precipitation is restricted to the mountainous coastal regions in the northeast region of the domain which is consistent with. Some differences still occur in the results presented in Fig. 14. It should be noted that the BKC station is located in the transition zone between areas dominated by ice and those dominated by rain southern part of the Korean Peninsula, where the simulations show more variability, with precipitation ranging from 15 to 30 mm, while the observations are more uniform, around 25 mm, with local peaks up to 40 mm. At the ICE-POP measurement sites, both simulations show higher precipitation than the AWS-based rain product, whereas Parsivel observations (Fig. 15a). The rest of the domain (especially in southwest) is largely influenced by liquid precipitation. Figure 15e also highlights that precipitation exceeds 30 mm in the southwest part of the domain, where the deep system comes from. 13) report substantially larger values. Because the rain product does not include Parsivel data of ICE-POP, the analysis of precipitation in this mountainous region should rely on Parsivel measurements provided in Fig. 13.

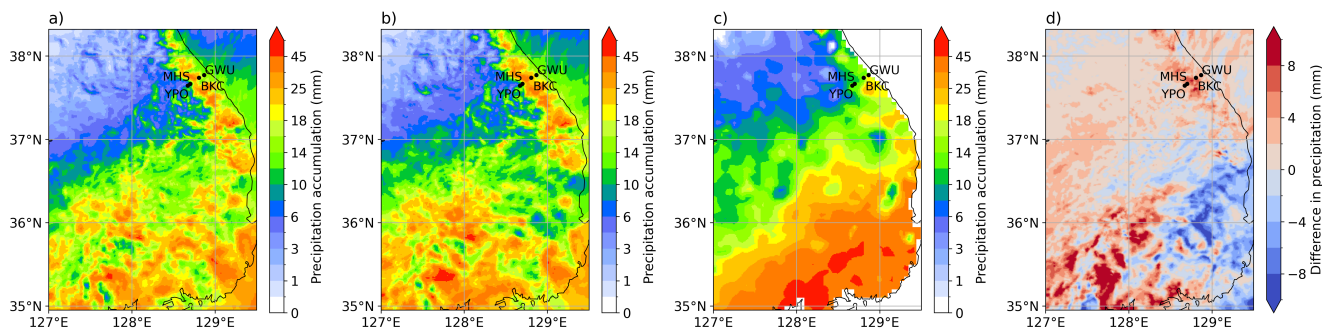


Figure 15. Precipitation accumulation from DESCAM control simulation (ice + rain) within the innermost domain at the end of the event (from 07 March 00:00 UTC to 09 March 9), for 00:00 UTC: a) liquid precipitation DESCAM CTRL, b) ice precipitation DESCAM pRIME, and c) total precipitation Rain accumulation product from Automatic Weather Stations (AWS) operated by the Korea Meteorological Administration (KMA) interpolated using the method of Cressman (1959) and d) difference between DESCAM pRIME in b) and DESCAM CTRL in a).

To further assess the impact of the predicted rime mass implementation, Fig ?? shows that it leads to a notable increase. Fig. 15d shows the differences in precipitation accumulation, with differences of up to 10 mm. This is particularly the case for the between the CTRL and pRIME simulations. In the southwestern part of the domain and the coastal mountainous regions close to the observation sites (consistent with Fig. rain accumulation rises by up to 10 mm in DESCAM pRIME, which lead to produce precipitation peak close to 40 mm, which better agree with the observations in Fig. 15c. Furthermore as visible in Fig. 15d and previously shown by Fig. 13, ice precipitation also rises by around 10 mm in the mountainous regions of the ICE-POP campaign. 13). Overall, the total precipitation mass in the third domain increases by approximately 6.5% in the control pRIME simulation. However, a local reduction is present in the southeastern part of the domain. This reduction could be explained

by the West to East movement of the deep system combined with the higher sedimentation velocities of rimed ice particles in the ~~control~~ CTRL simulation, that favors early precipitation in the western part of the domain. ~~Although the majority of precipitation during this event is liquid (except for the mountainous regions; see Fig. 15b) predicted rime in DESCAM also induces an important effect on the liquid precipitation amount. This highlights the important role of the representation of ice~~
 555 ~~particles properties in models which melt and contribute to liquid precipitation. The earlier and stronger liquid precipitation of~~
~~DESCAM pRIME is also supported by the idealized squall line simulation results presented previously in Fig. 8.~~

Difference between DESCAM control and no rime simulations for the total (liquid + ice) precipitation accumulation (at 00:00 UTC, on March 9). Positive (red) values indicate an increase in precipitation in the control simulation, while negative (blue) values indicate a decrease in the control simulations.

560 4.3 Ice particles properties

4.2.1 Ice particles properties

Fig. 16 ~~presents~~ shows the temporal evolution of ~~the~~ ice particle size distribution at the MHS station, ~~given~~ measured by the PIP probe (Fig. 16a) and ~~by DESCAM control simulation simulated by DESCAM CTRL~~ (Fig. 16b) ~~for particles larger than 100 μ m. In and pRIME~~ (Fig. 16b, ~~before 15:00 UTC (March 7), both c), with the corresponding mean particle diameter~~ (Fig. 16d).
 565 Both simulations produce small ice particles (< 1 mm) before the onset of precipitation whereas no ice particles are detected by the PIP (~~Fig. 16a~~) before 10:00 UTC. Furthermore, during the deep phase, ~~DESCAM control simulation both simulations~~ (Fig. 16b) ~~produces c)~~ provide a broader particle size distribution compared to observations, with a mean diameter fluctuating between 0.5 and 1.8 mm ~~-(Fig. 16d).~~ In contrast, ~~the PIP observations of in Fig. 16a d, the PIP observations~~ show a more steady mean diameter of around 0.8 mm. The ~~model two simulations~~ also displays a bimodal distribution before 00:00 UTC (March
 570 8) contrary to the PIP observations. These discrepancies suggest that the current representation of ice particle aggregation in DESCAM, ~~recently revised by Grzegorezyk et al. (2025a),~~ still requires further refinement.

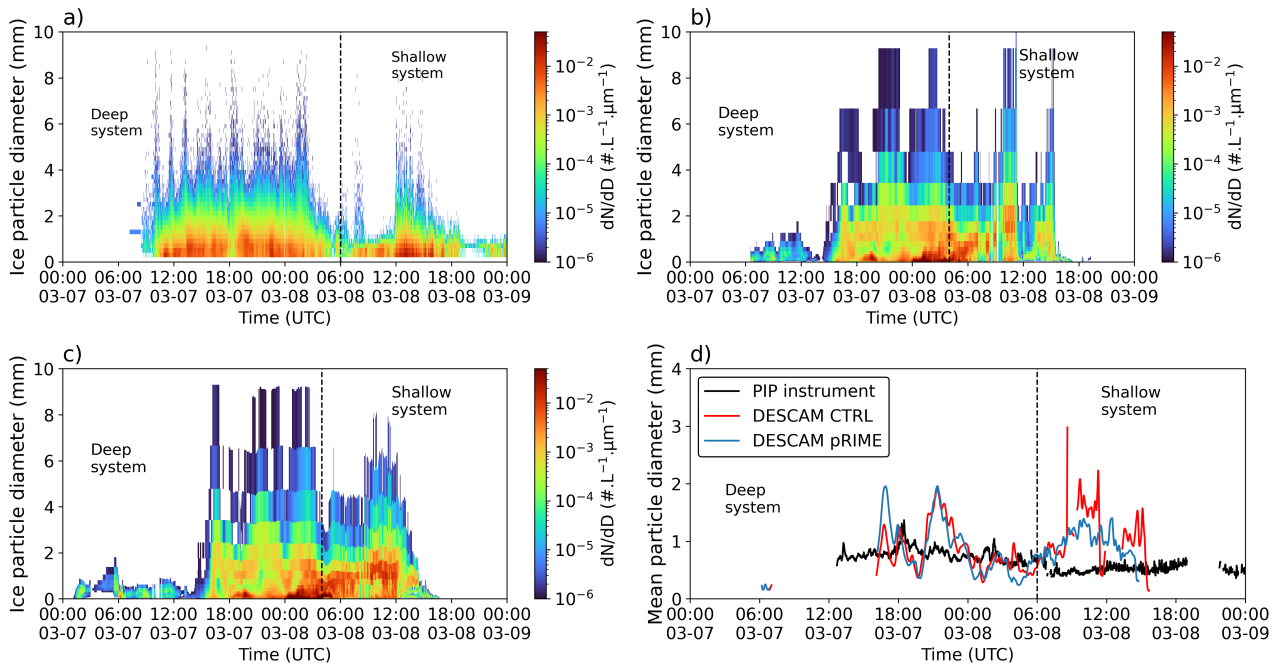


Figure 16. Temporal evolution of ground based ~~observation~~ observations of ice particle size distribution for a) from the PIP instrument at MHS and b) given by DESCAM ~~control~~ CTRL simulation and c) DESCAM pRIME simulation. Solid lines indicate the mean particle diameter. In panel b) Panel d), presents the black line represents the number-weighted number-weighted mean particle diameter for the control simulation, while the gray line corresponds the no-rime simulation. Only ice particle (considering particles larger than 100 μm are considered. The black dashed line indicate) for both simulations and the limits of the different cloud systems PIP observations.

In the shallow cloud phase, PIP measurements (in Fig. 16a-d), show smaller ice particle than in the deep system with a mean diameter around 0.5 mm. The control simulation, While the pRIME simulation overestimates the size of the ice particles with a mean diameter around 1 mm. Interestingly, the no-rime simulation, DESCAM CTRL generates even larger particles, of about 1.5 mm before 12:00 UTC (March 8). This shows that the implementation of the predicted rime distribution helps to mitigate the overestimation of large ice particles given by DESCAM CTRL.

The temporal evolution of the total number concentration of ice particles larger than 100 μm obtained from the PIP instrument and DESCAM ~~control and no-rime~~ CTRL and pRIME simulations is presented in Fig. 17. During the first part of the deep cloud system (i.e. between 15:00 and 00:00 UTC on March 7), both DESCAM simulations significantly underestimate the number of ice particles by around a factor two compared to observations. In contrast, during the second phase of the deep system (between 00:00 UTC and 06:00 UTC on March 8), both simulations, particularly the control, overestimate the particle number concentration, again by a factor of two.

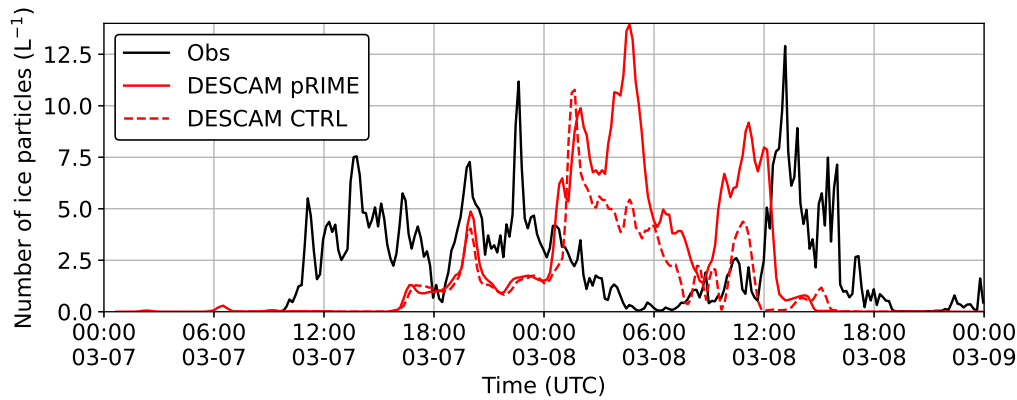


Figure 17. Temporal evolution of the number of ice particle (10-minute averaged) larger than $100\ \mu\text{m}$ at MHS station, observed by the PIP instrument (black line) and simulated by DESCAM, with the ~~control~~pRIME and ~~no-rime~~CTRL simulations shown in solid and dashed red lines, respectively.

During the shallow phase (from 06:00 UTC on March 8), the number of ice particles in the ~~control~~pRIME simulation aligns well with PIP observations, while the ~~no-rime simulation underestimates their concentration~~CTRL simulation underestimates it. These results further support that the predicted rime implementation leads to a more realistic representation of the ice particle properties during the shallow phase as seen for particle size in Fig. 16b. The effect of predicted rime in this case is opposite to that of the squall line system (Fig. 6c) where it reduced the ice particle number concentration.

To further investigate the riming properties of ice particles, Fig. 18a shows the temporal evolution of the riming index derived from MASC images (Praz et al., 2017), as well as the simulated rime mass fraction from DESCAM ~~control~~pRIME simulation. The rime mass fraction is defined as the ratio of rime mass to total ice mass of all particles larger than $100\ \mu\text{m}$ (i.e. approximately the detection threshold of the MASC). While the riming index and rime mass fraction are different parameters, ~~their temporal variation can be still compared~~we will still compare them in order to assess the model ability to represent the evolution of rime amount in ice particles. Figure 18b displays the number of particles, from the MASC images over 10-minute intervals, categorized in different hydrometeor types.

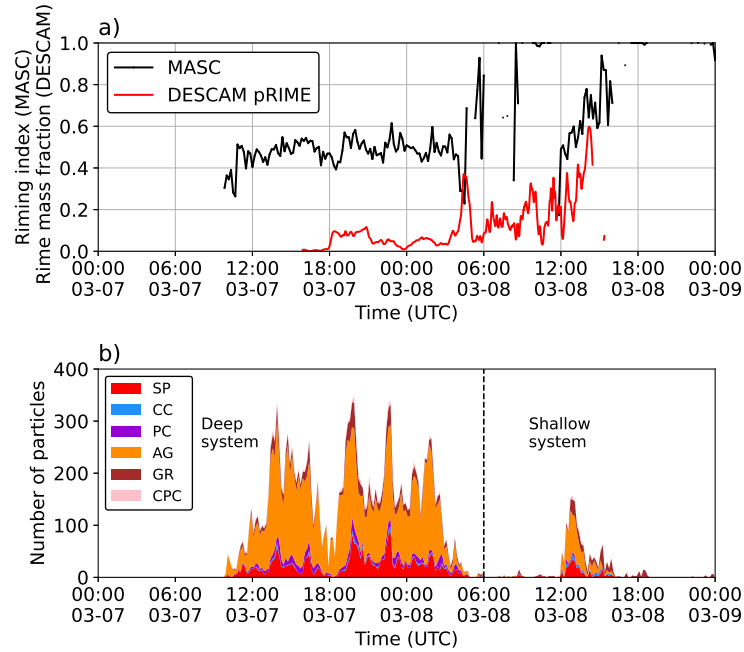


Figure 18. a) Evolution of the rime index retrieved from MASC observations, compared to the rime mass fraction from DESCAM simulation at MHS station [for \$> 0.1 \text{ L}^{-1}\$ ice particles](#). b) Number of particles (per 10-minute interval) for each hydrometeor species observed by MASC with: small particles (SP), columnar crystals (CC), planar crystals (PC), aggregates (AG), graupel (GR), and combinations of columnar and planar crystals (CPC). The rime index and hydrometeor classification are retrieved from Praz et al. (2017) method. The black dashed line ~~indicate~~[indicates](#) the limits of the different cloud systems.

~~In Fig. 18a, during~~ [During](#) the deep system (~~i.e. see Fig. 18a~~ [before 06:00 UTC](#)), the MASC riming index remains close to 0.5, along with the presence of rimed aggregates (AG) (Fig. 18b). In comparison, DESCAM gives a rime mass fraction of approximately 0.1, suggesting a possible underestimation of rime amount during the deep phase.

At the end of the deep system, a peak is obtained for the simulated rime mass fraction around 04:00 UTC on March 8, coinciding with peaks in the MASC riming index (from 04:00 to 9:00 UTC on March 8). A second, more pronounced increase occurs at the end of the shallow system at 14:00 UTC on March 8, with the MASC riming index reaching 0.9 and the simulated rime mass fraction increasing at 0.6. These consistent trends suggest that the predicted rime mass distribution implemented in DESCAM reproduces well the evolution of the riming properties of the ice particles.

The particle types classified from the MASC images (Fig. 18b), along with the ice particle total number concentration (Fig. 17a), reveal that the riming index ~~in~~ (Fig. 18a) increases as the total number of ice particles decreases, while the number of graupel (heavily rimed) particles observed with the MASC remains relatively constant. This suggests that a higher proportion of the remaining particles are rimed. DESCAM reproduces well this trend, particularly between 12:00 and 14:00 UTC on March 8 (Fig. 17a), when an increase in rime mass fraction coincides with a decrease in ice particle number concentration. Despite

that, it remains challenging to assess whether the amount of rime mass is accurately reproduced by DESCAM. Furthermore, even if the overall properties of the shallow system agree well with ground-based observations, a potential contamination by the artificial cloud layer produced by DESCAM (see Fig. 9) on the present results can not be ruled out.

4.3 Riming event

4.2.1 Riming event

To better understand the origin of the surge in rimed particle, Fig. 19 shows vertical cross sections from the DESCAM control pRIME simulation within the third domain. These cross-sections present the rime mass fraction, with some isotherms, relative humidity (RH), and the 2D wind field as well as liquid water content (LWC), and ice water content (IWC), relative humidity (RH), and the 2d wind field (along the dashed line of Fig. 4). They correspond to the deep system at 0018:00 UTC on March 8-7 (Fig. 19a,b,c,d) and to the shallow system at 14:00 UTC for the same day on March 8 (Fig. 19e,f,g,h).

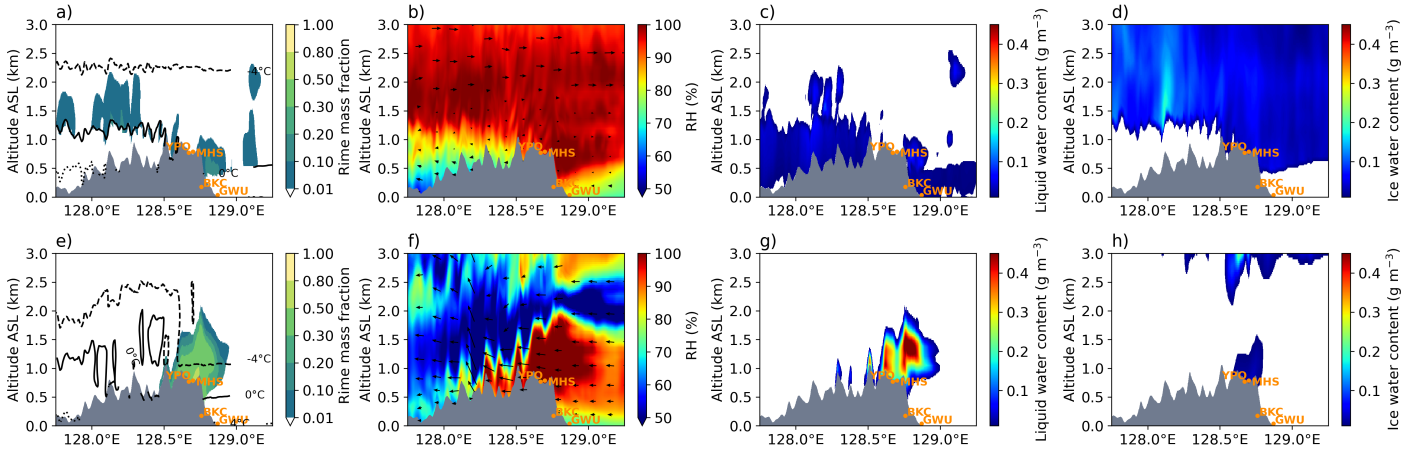


Figure 19. Vertical cross sections from DESCAM control-pRIME simulation (along the dashed line of Fig. 4, passing through the measurement sites) within the innermost domain. Panels a) and e) show for the rime-mass-fraction, with ice-water-content (IWC) and liquid-water-content (LWC) contours at 0.01 and 0.1 g m^{-3} , corresponding to the end of the deep system (at 18:00 UTC, on March 87 (top row) and the shallow system (at 14:00 UTC, on March 8 (bottom row), respectively. Panels b(a, e) and d) present show the rime mass fraction with isotherms, (b, f) relative humidity and the 2d wind field for the same time periods, (c, g) liquid water content (LWC), and (d, h) ice water content (IWC).

Fig. 19e-e highlights that, at the end of the shallow system, the rime fraction exceeds 0.5 at the and around the mountainous stations (YPO and MHS) the rime fraction generally exceeds 0.3, with maximum values close to 0.5, coinciding with high supercooled LWC ($> 0.1 \text{ g m}^{-3}$) and low IWC ($< 0.1 \text{ g m}^{-3}$) as visible in Fig. 19g,h. As shown in Fig. 19d,f, this cloud system seems to result from orographically induced updrafts lifting of humid marine air brought by the easterly flow. The relatively low cloud top and the surface temperatures just below 0 surface temperatures near $-2 \text{ }^{\circ}\text{C}$ (not-presented), driven by

a warm and humid air intrusion over the mountainous terrain (see the -4°C isotherm in Fig. 19e), promote the persistence of supercooled liquid water. This therefore favors the formation of rimed particles, as reflected in DESCAM-rime-mass-fraction (18a) Fig. 18e. The previous work of Kusunoki et al. (2005) has shown that terrain induced updrafts are promoting the presence of supercooled liquid water and thus increase the riming process efficiency. It-This was especially the case at-the-measurement points-of-for ICE-POP when northeasterly air flow becomes dominant, as mentioned by Kim et al. (2021).

In contrast, Fig. 19a,b depict the conditions during the deep cloud phase at 00:00 UTC (March 8). In this case, for the deep cloud system, Fig. 19b shows that northeasterly winds are restricted below 1.5 km, whereas above, due to a dominant southwesterly flow above, associated with the low-pressure system that transports snow aggregates over the mountainous regions. Consequently, temperatures above the mountain stations are colder than in the shallow system, as indicated by the -4°C isotherm in Fig. 19b. As a result, the amount-of-supercooled-LWC-for-supercooled LWC is lower in the deep system is reduced-compared-to (Fig. 19c, particularly near the mountainous sites, where-) than in the shallow system (Fig. 19g), while the IWC exceeds 0.1 g m^{-3} . Such-configuration-leads-to-a-lower-rime-mass-fraction-compared-to-This situation is therefore less favorable for riming than that of the shallow system (illustrated in Fig. 17).

640 5 Limitations and Perspectives for DESCAM

- **Ice particle density:** In the current implementation based on Morrison and Grabowski (2010), the size of rimed particles is constrained by a mass diameter (m - D) relation for graupel based on Heymsfield et al. (2018), which effectively limits ice density to graupel growing by pure dry growth. A future development would be to extend the predicted rime mass toward a prognostic treatment of ice particle density by introducing a prognostic rime volume, as proposed by Morrison and Milbrandt (2015a) and implemented in other microphysics schemes (e.g. Brdar and Seifert, 2018). Given that in DESCAM collision kernels and terminal velocities of ice particles are dependent on rime mass, implementing a prognostic density could be straightforwardly integrated into the model.
- **Melting:** A melting scheme considering the water ice ratio of melting ice particle was implemented in a former version of DESCAM 3D (Planche et al., 2014) but was later removed for computational efficiency, as it required approximately 30 additional prognostic variables relevant for a few vertical levels. However, several studies have highlighted the importance of ice particle continuous melting for both microphysical processes, precipitation and dynamics of convective cloud systems (Phillips et al., 2007; Cholette et al., 2019, 2023; Milbrandt et al., 2025). As DESCAM now aims to predict particle properties, the melting scheme of Planche et al. (2014) could be reintroduced and extended to account for particle density, which strongly influences melting behavior. However, this would first require a prognostic treatment of ice particle density mentioned in the previous point. Consequently, the scheme should be reformulated to depend on particle density from low density snow particles (Mitra et al., 1990) to heavily rimed particles (Theis et al., 2022). Additionally, shedding effects associated with large rimed particles should be considered (Rasmussen and Heymsfield, 1987a, b, c), as they are currently not represented.

- **Shape of particles:** Recent advances have also highlighted the possibility of predicting the habit of vapor-grown ice particles. This has been implemented in both bulk schemes (Jensen et al., 2017) and more detailed microphysics schemes (Welss et al., 2024). These studies show that predicting ice particle aspect ratios, which are influenced by environmental conditions, can significantly impact precipitation, as the terminal velocity of ice particles depends on their shape.
- **Challenges for ice particle properties prediction:** As several models advance toward predicting the ice particle properties, this requires more and more detailed information about ice microphysics. However, the behavior of ice particles depending on their shape, rime fraction, density, or melting state remains poorly understood. This is particularly true for aggregation since the sticking and collision efficiencies for different types of ice particle is not known. Similarly, while the fill-in hypothesis may apply when ice particles are much larger than droplets, its validity across different particle and droplet sizes remains unknown. Therefore, detailed investigations (e.g. laboratory studies) of ice particle behavior across different properties may help refine the microphysical representation of models. In addition, our study also highlights the difficulty of directly evaluating predicted ice particle properties in microphysics schemes from field measurements, since observations do not provide the predicted variables of models such as rime mass.

6 Conclusions

This study aims to evaluate the implementation of predicted rime mass by means of a budget equation within DESCAM bin microphysics scheme ~~by comparing the model outcomes to the ground-based in situ and radar observations during the ICE-POP 2018 field campaign.~~

~~The new implementation within DESCAM.~~ This implementation consists in a binned distribution, tracking the rime mass of ice particles throughout their evolution as initially presented by Hashino and Tripoli (2007) as well as by Morrison and Grabowski (2008, 2010). The approach used here is based on the "fill-in" concept that considers the filling of the interstitial spaces of ice particles by rimed droplets, increasing the particle mass without changing its size. This allows for ice particles to have a smooth and free transition between unrimed and graupel particles. From the predicted rime mass, the terminal velocity (based on Heymsfield and Westbrook, 2010) and collision kernels were refined and set to be dependant on the rime fraction.

~~To assess the effect of these new implementations, DESCAM was applied to simulate~~ First, an idealized case is used to examine the impact of predicted rime on cloud properties and precipitation for a convective squall line system. Second, the implementation is evaluated against ground-based in situ and radar observations for a heavy snowfall event ~~that was~~ observed during the ICE-POP 2018 field campaign over the Korean Peninsula ~~between (March 7-9, 2018. The model reproduced the two subsequent cloud systems observed during this event with, a deep system associated with a low pressure system, followed by a shallow orographic cloud field triggered by a moist marine easterly flow. Although the model missed the early part of the deep system, its intensity is similar to the observations in terms of radar reflectivity and precipitation rate~~ 2018). For the two cases, two simulations were conducted: pRIME considering the new implementations, and CTRL using the original DESCAM configuration.

For the squall line system, the explicit prediction of rime in the pRIME simulation strongly impacts cloud microphysics, precipitation, and system development. The simulations indicate that large ice particles acquire substantial rime mass, which leads to further promote their growth and enhances their sedimentation. As a result of stronger sedimentation, ice water content in the ice phase decreases, while liquid water increases below 4 km where $T > 0^{\circ}\text{C}$. In addition, the melting of the massive rimed ice particles also produces larger drops that fall faster, leading to an earlier onset of rainfall and an increase in total precipitation amount by 25%. Furthermore, ~~even if the shallow system intensity was occurring too early and its reflectivity was overestimated by +5 dB, both these discrepancies compensate the lack of precipitation accumulation due to the missed first part of the deep system. Another important bias of the model was also the formation of an upper cloud layer above 2 km altitude, likely caused by numerical humidity production at the outermost domain boundary conditions over mountainous regions, triggering ice nucleation processes.~~ presence of large drops leads to a reduction of evaporation in the cold pool that diminishes the latent heat release, weakening buoyancy and slowing squall-line propagation.

The results of the ICE-POP 2018 case show that DESCAM simulations were able to reproduce the two distinct cloud systems observed during the event: a deep system associated with a low-pressure system, followed by a shallow orographic cloud field triggered by moist easterly marine flow.

The evolution of the simulated rime mass fraction in pRIME at the MHS mountainous station successfully follows that of the riming index retrieved from the MASC instrument. This common evolution highlights the presence of rimed particles at the end of the deep system and during the shallow system. Our analysis indicates that riming events are associated with clouds generated by orographic lifting of easterly moist marine airflow, that promotes the presence of supercooled liquid water and favors riming.

The effect of the predicted rime implementation in pRIME is especially visible for shallow cloud phase, where the number concentration of ice particles at ground doubles, leading to a close agreement with the observations. This implementation also leads to ~~decrease the decrease of~~ the mean particle diameter from 1.5 mm to approximately 1 mm during the shallow phase, which is closer to the observed values around 0.5 mm diameter.

Regarding precipitation, ~~the new DESCAM version causes an increase as observed in the squall line simulation, DESCAM pRIME produces an overall increase. This increase reaches~~ up to 10 mm ~~in-for~~ both ice and liquid precipitation ~~over-in~~ the mountainous southwestern regions of the Korean Peninsula. In total, the precipitation amount increases by 6.5% ~~-Our (i.e. less than for the squall line). However while our~~ results underscore the important role of ~~ice particles representation for the production of ice and also liquid precipitation. However, the model predicted rime on precipitation, DESCAM pRIME~~ still overestimates the ice particle size and underestimates the accumulated precipitation by around 5 mm compared to ~~Pluvio measurements~~ observations. Therefore, even if aggregation was refined in Grzegorzczuk et al. (2025a), further improvements could be necessary, especially about the ice particle sticking efficiency which remains poorly documented. ~~Furthermore, discrepancies between the simulated dynamics and the real atmospheric conditions which cannot be fully ruled out in our model may also account for the differences observed between the simulations and the observations.~~

Even if this study demonstrates that the rime properties of ice particles have a substantial ~~effect and improve the simulated particle properties and precipitation amount of a snowfall event~~ effects for both cases, it also motivates further new model devel-

opments. Additional predicted variables, such as rime volume (Morrison and Milbrandt, 2015b)(Morrison and Milbrandt, 2015a), aspect ratio (Jensen and Harrington, 2015; Welss et al., 2024), or even water/ice ratio of ice particles (Planche et al., 2014; Cholette et al., 2019), could be integrated into DESCAM to better represent the ice particle properties. Predicting rime volume would eliminate the need of a fixed m–D relation for graupel while a predicted aspect ratio could improve the representation of vapor deposition and enables more detailed comparisons with observations. The discussed and upcoming implementations could be confronted against different types of observations (e.g. $\bar{r}$ -in situ aircraft measurements) and applied to different kinds of case studies.

Appendix A: Transport of rime mass during vapor growth of ice particles

The variation of rime mass g_r for a bin of mass m_2 due to vapor deposition is calculated by:

$$\left(\frac{\partial g_r(m_2)}{\partial t}\right)_{dep} = \frac{1}{n_i(m_1)} \left(\frac{\partial n_i(m_1)}{\partial t}\right)_{dep} \times g_r(m_1) - \frac{1}{n_i(m_2)} \left(\frac{\partial n_i(m_2)}{\partial t}\right)_{dep} \times g_r(m_2) \quad (A1)$$

with $\left(\frac{\partial n_i(m_1)}{\partial t}\right)_{dep}$ the positive gain of ice particle number for the m_2 bin and $\left(\frac{\partial n_i(m_2)}{\partial t}\right)_{dep}$ the loss of ice particle number in the m_2 bin due to growth by vapor deposition. Both terms depend on the size of the particles, humidity as well as the advection scheme of Bott (1989) which calculates the change of particle number between the bins. These growth rates are normalized by the initial number of ice particles to obtain the fraction of ice particles that is transported. This proportion is then multiplied by the rime mass g_r to track the rime properties of the ice particles.

Appendix B: Radar dual-wavelength ratio (DWR) Mass distribution of ice and liquid drops for the squall line case

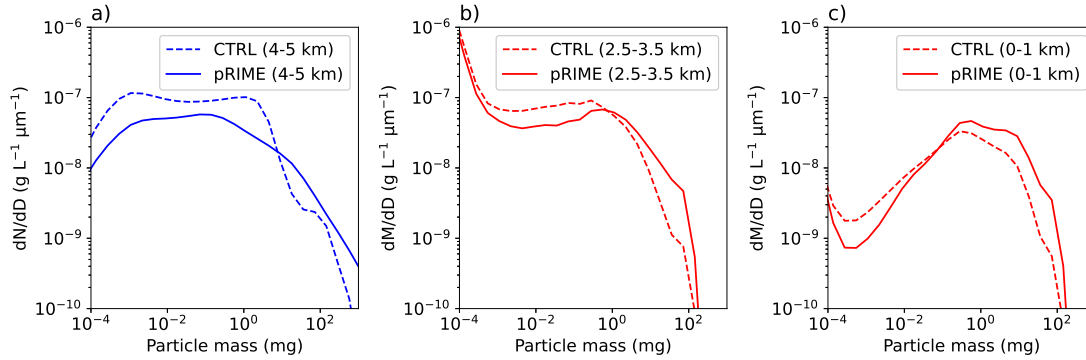


Figure B1. Radar dual-wavelength ratio-Averaged mass distributions at 2:30 h ($DWRTWC > 0.01 \text{ g m}^{-3}$) between: ice mass distribution above the X and W band melting layer (i.e. $Z_X4 - Z_W5 \text{ km}$) for in a) radar observations and, drop mass distribution below the melting layer (2.5 - 3.5 km) in b) DESCAM-control simulation and drop mass distribution averaged near the ground (0 - 1 km) in c). Only values corresponding to $Z_X > -3 \text{ dBZ}$ are shown.

Data availability. Parsivel, W-band radar, and MASC observations can be found via the PANGAEA repository: <https://doi.org/10.1594/PANGAEA.918315> (Gehring et al., 2020a). Additional observational datasets provided for the 2024 ICMW are available here: <https://zenodo.org/doi/10.5281/zenodo.17278661> (Grzegorzczak et al., 2025c). The first simulation of this study, the idealized squall line case, is available at <https://zenodo.org/records/18526033> (Grzegorzczak et al., 2026). The second simulation setup of DESCAM-3D for the ICE-POP case is available at <https://zenodo.org/doi/10.5281/zenodo.17854170> (Grzegorzczak et al., 2025d).

Competing interests. The authors declare no competing interest.

Author contributions. PG: Draft the original manuscript, conducted the run and analysis of the numerical simulations, analyzed the observational datasets, and contributed to the conceptualization of the study. WW and AC: Edited the manuscript, performed numerical simulations, and conceptualized the study. FT: Edited the manuscript and analyzed the observational datasets. GL and KK: Edited the manuscript and processed the observational data. KSSL: Edited the manuscript and conceptualized the case study. CP: Edited the manuscript, conceptualized the study, supervised the project and acquired the funding.

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