



1 Stripe Patterns in Wind Forecasts Induced by Physics-Dynamics

2 Coupling on a Staggered Grid in CMA-GFS 3.0

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- 10 **Abstract.** An unphysical stripe pattern is identified in low-level wind field in China Meteorological
- 11 Administration Global Forecast System (CMA-GFS), characterized by meridional stripes in u-
- 12 component and zonal stripes in v-component. This stripe noise is primarily confined to the planetary
- boundary layer over land. The absence of noise in both surface static fields and pure dynamic-core
- 14 solutions proves that neither the dynamical core nor physical parameterizations alone can produce
- 15 wind stripe patterns. These results suggest that staggered-grid mismatch in physics-dynamics
- 16 coupling is likely the primary mechanism. Idealized two-dimensional experiments demonstrate that
- 17 combining one-dimensional dynamic-core advection and physics-based vertical diffusion on a
- staggered grid generates $2\Delta x$ -wavelength spurious waves when surface friction is non-uniform.
- 19 One-dimensional linear wave analysis further confirms that staggered-grid coupling between
- 20 dynamic advection and inhomogeneous damping forcing induces dispersion errors in wave
- 21 solutions. Sensitivity tests validate that eliminating grid mismatch in physics-dynamic coupling
- 22 removes this stripe noise. These findings collectively indicate that while staggered grids benefit the

dynamic core's numerical stability and accuracy, their inherent grid mismatch with physics

- 24 parameterizations requires specialized coupling strategies to avoid spurious noise. Potential
- 25 solutions to remedy this issue are discussed.

1. Introduction

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accuracy of circulation forecasts but also controls the spatiotemporal distributions of temperature, humidity, aerosols, and cloud microphysical properties through advection processes. Numerical weather prediction (NWP) systems simulate three-dimensional wind field evolution through numerical integration of atmospheric governing equations with multi-scale physical parameterizations. The momentum equations describe wind field evolution through three key forces: the pressure gradient force, Coriolis force, and nonlinear advection terms. The numerical discretization of advection terms is particularly important as it directly affects solution stability (Durran, 2010). Parameterized physical processes at subgrid scale significantly influence wind field predictions. Surface stress not only exerts substantial control over the wind intensity in both the near-surface and planetary boundary layers (PBL) through turbulent momentum transport (Blackadar, 1957; Stull, 1988), but also significantly influences the location of the surface westerlies and upper-level jets in the midlatitudes (Robinson, 1997; Chen et al., 2007). When flow encounters subgrid-scale orography, it excites gravity waves that propagate vertically, altering large-scale winds through momentum flux divergence (McFarlane, 1987; Kim et al., 2003; Kim and Doyle, 2005). Mesoscale topographic blocking and turbulent form drag modify low-level wind fields, which in turn affect global circulation patterns (Beljaars et al., 2004; Sandu et al., 2016). In addition to dynamics and physical processes, the consistency of dynamic-physics coupling is equally critical for overall model performance (Bauer et al., 2015; Gross et al., 2016; 2018). In NWP model, numerical noise typically stems from non-physical high-frequency oscillations induced by dynamical process discretization (Wurtele, 1961; Arakawa, 1966; Mesinger & Arakawa, 1976). Additionally, spatial grid mismatch in physics-dynamic coupling can generate computational noise (Chen et al., 2020). While consistent spatial grids between dynamical and physical processes are theoretically preferable for seamless coupling, practical implementations often employ differing horizontal and vertical grid configurations. For vertical discretization, two conventional grid arrangements are employed: (1) the Lorenz grid (Lorenz, 1960), collocating thermodynamic (temperature/moisture) and dynamic (wind) variables at half-levels, and (2) the Charney-Phillips (CP) grid (Charney & Phillips, 1957), staggering wind variables at half-levels while thermodynamic variables at full-levels. Chen et al. (2017) demonstrated that Lorenz-grid physics coupled with CPgrid dynamics generates non-physical computational modes in PBL scheme solutions. Chen et al.

The wind field, as a fundamental state variable in atmospheric dynamics, governs not only the

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(2020) confirmed that unified grid coupling significantly improves the stratocumulus representation and overall forecast skill while eliminating this spurious noise. These findings underscore that dynamic-physical coupling inconsistencies not only introduce numerical noise but also substantially degrade model performance. In global models, physical processes are typically computed in single columns, independent of horizontal grid configuration. Thus, horizontally distributed noise cannot originate from physical parameterizations if the underlying static physical data is noise-free. In two-dimensional rectangular grids, horizontal grid configurations are categorized into non-staggered (A-grid) and staggered (B grid to E grid) types, distinguished by their arrangement of wind components (u, v) and mass variables (height z or pressure p) (Arakawa and Lamb, 1977). Among these, the Arakawa C-grid – where mass variables are collocated at grid centers while velocity components are staggered at cell interfaces - exhibits optimal accuracy when the grid spacing resolves scales smaller than the Rossby radius of deformation (Batteen & Han, 1981; Xu & Lin, 1993; Randall, 1994). This superiority stems from its inherent conservation properties and reduced numerical dispersion in simulating geostrophic adjustment processes (Arakawa and Lamb, 1977; Randall, 1994). The Arakawa-C grid has been widely implemented as a preferred discretization framework in structured-grid NWP systems, including the Weather Research and Forecasting (WRF) Model's Advanced Research core (Skamarock et al., 2008) and operational systems such as the UK Met Office Unified Model (Walters et al., 2017), the NOAA Global Forecast System (GFS) (Sela, 2010), the Environment and Climate Change Canada (ECCC) Global Environmental Multiscale (GEM) model (Côté et al., 1998), and the China Meteorological Administration's (CMA) operational GRAPES system (Chen et al., 2008). Figure 1 illustrates the wind field distribution on an Arakawa C-grid, where the physicsparameterized winds are located at the central mass points while the dynamically computed winds are staggered at the cell interfaces. This inherent wind field grid mismatch is typically handled via two-step interpolation during physics-dynamics coupling. However, as demonstrated by Chen et al. (2020), the grid inconsistency during physics-dynamics coupling introduces spurious computational High-order horizontal diffusion (Xue, 2000) and filters (Shapiro, 1970, 1975; Raymond and Garder, 1988) are standard techniques for suppressing high-frequency computational noise in NWP models. These approaches were successfully implemented in the GRAPES model and effectively

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87 mitigated small-scale noise (Wang et al., 2008). Compared to CMA-GFS 2.4 (originally 88 GRAPES GFS V2.4), the new CMA-GFS 3.0 has removed fourth-order horizontal diffusion to improve small-scale system simulation capabilities (Shen et al., 2023). Following the upgrade to 89 90 CMA-GFS 3.0, stripe patterns became evident in the low-level wind fields—an issue absent in 91 previous versions. 92 This study systematically investigates the underlying causes of these stripe patterns in CMA-93 GFS 3.0, particularly examining physics-dynamics coupling mismatches as the probable source. 94 Section 2 details physics-dynamics coupling scheme on a staggered grid for the wind field 95 prediction in CMA-GFS 3.0 and characterizes the observed horizontal wind noise patterns. Section 3 identifies noise sources via idealized experiments and analytical wave solutions, revealing 96 97 fundamental discretization constraints in physics-dynamics coupling. Section 4 designs sensitivity 98 experiments to verify the origin of horizontal wind noise in CMA-GFS 3.0, conclusively attributing it to physics-dynamics coupling mismatches. Conclusions and discussions are presented in Section 99 100 5.

2. The wind prediction in the PBL in CMA GFS

2.1 Model description and physics-dynamic coupling in wind prediction

The CMA-GFS (formerly known as GRAPES_GFS) was developed based on a two-time-level semi-implicit semi-Lagrangian (SISL) non-hydrostatic dynamic core. Its development began in 2007, and the system became operational in late 2015 (Shen et al., 2020). The model employs a horizontal Arakawa C-grid on a regular latitude-longitude grid, combined with a vertical CP grid using a height-based terrain-following coordinate system (Chen et al., 2008).

Physics package includes the Rapid Radiative Transfer Model for GCMs (RRTMG) for longwave and shortwave radiation (Pincus et al. 2003; Morcrette et al. 2008), the double-moment microphysics and an explicit prognostic cloud cover scheme (Ma et al, 2018), the common land model (CoLM) (Dai et al. 2003), the subgrid-scale orographic (SSO) scheme including gravity wave drag (GWD) (Chen et al. 2016) and turbulence orographic form drag (TOFD) (Beljaar et al., 2004), the new Simplified Arakawa Schubert (NSAS) convection, and the new medium-range forecast (NMRF) for vertical diffusion (Han and Pan 2011). The implementation of vertical diffusion and





- 115 cloud physics schemes on the CP grid eliminated computational noise induced by physics-dynamics
- 116 coupling mismatches, leading to significant improvements in stratocumulus cloud simulations and
- overall forecast skill scores (Chen et al., 2020).

$$u = \frac{u_p, v_p}{i - 1/2, j}$$

$$i, j + 1/2$$

$$i, j = 1/2, j$$

$$i, j = 1/2$$

$$v$$

Figure 1. Wind configuration in Arakawa C grid; the subscript 'p' denotes the physics grid points

- In CMA-GFS's dynamical core, horizontal winds $u_{i\pm\frac{1}{2}j}$ and $v_{i,j\pm\frac{1}{2}}$ are staggered at cell
- interfaces, while physics-parameterized winds u_p and v_p are collocated at mass center (Figure 1).
- 122 In our coupling scheme, linear interpolation bridges the grid mismatch for physics-dynamics
- 123 coupling:

$$\begin{cases} P(u_{i,j}) = P\left(\frac{u_{i-\frac{1}{2},j} + u_{i+\frac{1}{2},j}}{2}\right) \\ P(v_{i,j}) = P\left(\frac{v_{i,j-\frac{1}{2}} + v_{i,j+\frac{1}{2}}}{2}\right) \end{cases}$$
(1)

- where P denotes the physics parameterization operator. When feeding physics tendencies back to
- the dynamical core, the coupling follows:

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$$\begin{cases}
\Delta u_{i+\frac{1}{2},j}^{P} = \frac{1}{2} [P(u_{i,j}) + P(u_{i+1,j})] \Delta t \\
\Delta v_{i,j+\frac{1}{2}}^{P} = \frac{1}{2} [P(v_{i,j}) + P(v_{i,j+1})] \Delta t
\end{cases}$$
(2)

126 where ΔV^P denotes the physics-induced wind increment to be fed back to the dynamic core.

127 However, such interpolation-based coupling schemes often fail to mitigate computational noise

induced by physics-dynamics grid mismatches (Chen et al. 2020).

As theoretically anticipated, lower-level winds of CMA-GFS 3.0 exhibit distinct stripe patterns.

130 We therefore systematically these anomalies in detail, first characterizing their spatiotemporal

structures, and then evaluating potential links to physics-dynamics coupling mechanisms.

2.2 Spatiotemporal distribution of wind forecast noise: a case study

In this case study—hereafter referred to as Exp_Ctrl—we utilize CMA-GFS 3.0 with a horizontal resolution of 0.25° (approximately 25 km at the equator) and 87 vertical levels extending up to 1 hPa. The simulation spans from 1200 UTC 1 July 2021, initialized with European Centre for Medium-Range Weather Forecasts (ECMWF) ERA5 reanalysis data (Hersbach et al., 2020; data available at https://cds.climate.copernicus.eu/datasets/). Hourly forecast fields are saved directly on the model's Arakawa C-grid at model levels throughout the 5-day simulation.

Global distribution of the wind field noise reveals pronounced land-sea contrasts, with predominant stripe patterns over land while relatively smooth over oceans. Figure 2 displays the 18-hour forecast (valid at 0600 UTC) of near-surface winds at the lowest model level over South Asia (88-113°E, 5-34°N), a region encompassing both land and ocean. Distinct stripe patterns dominate the wind field over land areas, where the u-component displays meridional stripes and the v-component exhibits zonal stripes. With the model's 0.25° resolution, these structures are clearly resolved with a wavelength of 0.5° ($2\Delta x$), demonstrating characteristic $2\Delta x$ wave properties.

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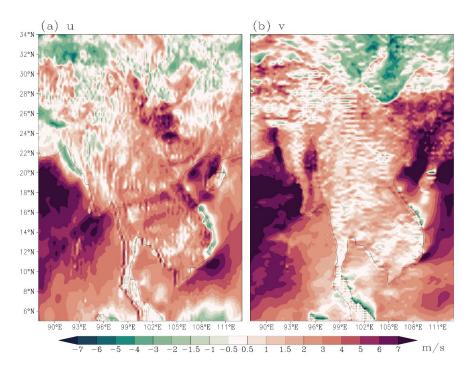


Figure 2. 18-hour forecast of (a) *u*- and (b) *v*- components at the lowest model level from CMA-GFS 3.0

Figure 3 displays vertical cross-sections of u- and v- components along 30°N and 100°E, respectively, for the region shown in Fig. 2. Pronounced $2\Delta x$ wave patterns are evident throughout the PBL in both components, whereas the wind field becomes markedly smoother in the free atmosphere above the PBL. The strongest $2\Delta x$ signatures are concentrated in the bottom of the PBL.



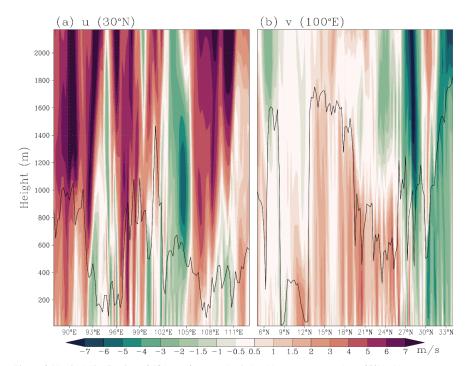


Figure 3 Vertical distribution of 18-hour forecasted winds: (a) u-component along 30°N; (b) ν -component along 100°E. Black solid lines denote the PBL height.

Figure 4 presents the 120-hour (5-day) evolution of surface-layer u- and v- components along the zonal and meridional transects shown in Fig. 3. The $2\Delta x$ oscillations exhibit continuous presence throughout the period while exhibiting diurnal amplitude modulation. This persistent noise pattern shows daytime intensification and nighttime weakening, suggests a potential linkage to the inherent diurnal cycle of the development of PBL.

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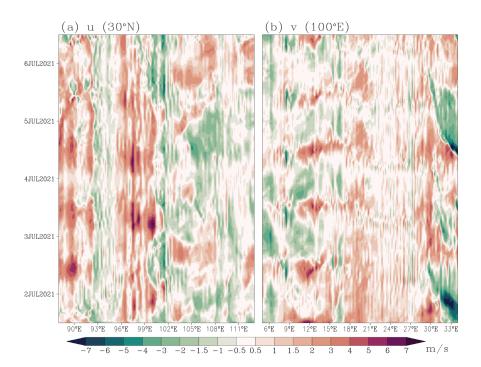


Figure 4. Temporal evolution of winds at the lowest model level (0-120 hours): (a) u-component along 30°N, (b) v-component along 100°E.

The vertical structure of low-level winds and their diurnal variations in the surface layer imply a connection between the stripe patterns and momentum-related physical processes, particularly turbulent transport within the PBL. However, the single-column design of physical schemes permits PBL diffusion to affect such horizontal wind noise solely via surface friction forcing. In the following section, we systematically examine the mechanisms for these $2\Delta x$ stripe patterns.

3. Tracing the cause of wind stripes predicted in CMA-GFS 3.0

3.1 Examination of associated surface static fields

The surface static fields directly governing surface friction in the wind field are surface inhomogeneity descriptors, principally characterized by subgrid orographic variability and aerodynamic roughness length. Figure 5 displays the spatial distributions of subgrid orography standard deviation and momentum roughness length across the domain shown in Fig. 2.





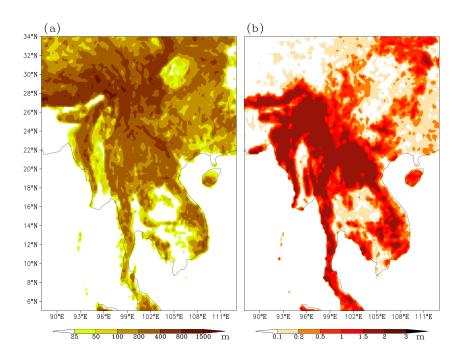


Figure 5. Horizontal distributions of (a) Standard deviation of sub-grid orography; (b) Roughness length over the study region (domain same as Fig. 2).

The complete absence of $2\Delta x$ noise in both static fields shown in Figure 5 contrasts sharply with the wind stripes observed in Fig. 2, definitively excluding surface parameters inhomogeneity as direct contributors to the noise generation. However, visual comparison with Fig. 2 demonstrates a distinct spatial correspondence between the stripe noise locations and the surface roughness distribution: the $2\Delta x$ noise patterns predominantly occur over areas with higher roughness, while remaining absent over smooth surfaces. The Andaman Islands, located between the Bay of Bengal and the Andaman Sea, generate localized surface inhomogeneity in this predominantly oceanic region. Consistent with this inhomogeneity, Fig. 2 exhibits obvious meridional stripes in the *u*-component precisely over this archipelago. These observations imply that although the surface inhomogeneity parameters themselves exhibit no stripe patterns—and thus cannot directly produce the wind stripes through physical processes—the spatial organization of $2\Delta x$ noise systematically correlates with surface inhomogeneity.

3.2 Dynamical Core Tests: Noise Assessment in Physics-off simulation

Section 3.1 demonstrated that the surface-friction-related static fields lack horizontal noise





patterns (Fig. 5), definitively excluding surface-mediated physical processes—which are computed in single columns—as possible sources of the observed $2\Delta x$ wind stripes. We now evaluate the dynamical core's potential contribution through a physics-free simulation using identical configuration described in section 2.2. Figure 6 displays 18-hour forecasts of near-surface u- and v-components over the same domain as in Fig. 2. The absence of surface friction yields stronger winds compared to the default physics-on simulation (Fig. 2), and more critically, the wind fields exhibit smooth distributions completely free of $2\Delta x$ stripes. This definitive evidence excludes the dynamical core as the source of the observed low-level wind noise.

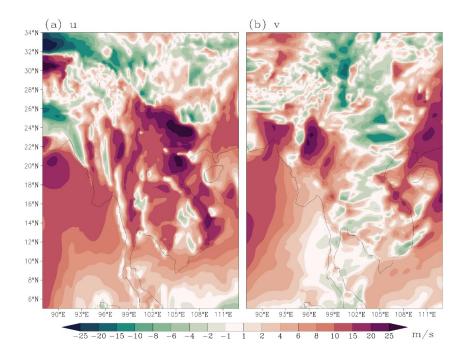


Figure 6. Same as Fig. 2, but for the physics-off experiment

Having definitively excluded both the dynamical core and physical parameterizations as direct sources of these horizontal noise patterns, the residual evidence points to the physics-dynamics coupling interface as the sole remaining candidate. As schematized in Fig. 1, CMA-GFS employs staggered grids between physics and dynamics components, requiring linear interpolation for wind field coupling. This inherent grid mismatch is now the most probable mechanism generating the observed $2\Delta x$ stripe noise. We proceed with idealized experiments and theoretical analysis to





- 207 examine whether the grid mismatch between physics and dynamics could induce the computational
- 208 noise.

209 3.3 Two-dimensional idealized test

- The governing equation for the idealized simulation combining one-dimensional horizontal
- 211 advection with vertical diffusion is

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -\frac{\partial \overline{u'w'}}{\partial z} \tag{3}$$

- 212 where u is flow speed and $\overline{u'w'}$ the turbulent vertical momentum flux. In Equation (3), the
- 213 nonlinear term $u \frac{\partial u}{\partial x}$ represents the dynamical advection process, while the right-hand side $-\frac{\partial \overline{u'w'}}{\partial z}$
- 214 represents the physical forcing process, specifically parameterized turbulent vertical transport. The
- 215 momentum flux can be expressed as:

$$\overline{u'w'} = -K\frac{\partial u}{\partial z} \tag{4}$$

where K(z) is the height dependent eddy diffusivity given by:

$$\begin{cases} K(z) = 0.5z \left(1 - \frac{z}{H}\right)^2, & z \le H \\ 0, & z > H \end{cases}$$
 (5)

- and H = 500m denotes the prescribed boundary layer height.
- The governing equation (3) is numerically solved using the discretization strategies and physical
- 219 configurations summarized in Table 1.

Table 1. Configuration for idealized simulation

$\Delta x = 25 \text{km}, \ N_x = 101 \text{points} \ (L = 2500 \text{km})$	
$\Delta z = 10 \text{m}, \ N_z = 100 \ \text{levels} \ (z_{\text{top}} = 1000 \text{m})$	
$u_0(x, z) = 10 \text{ m s}^{-1}$ (horizontally and vertically uniform)	
Pointing of the section of the secti	
Periodic conditions: $u(x = 0) = u(x = L)$	
Surface friction velocity: $u_* = \begin{cases} 1.0, & x = L/2 \\ 0.01, & \text{elsewhere} \end{cases}$	
Top: $\overline{u'w'}_{top} = 0$	
Time-splitting with explicit advection and fully implicit	





	diffusion.
Spatial discretization	Advection: First-order upwind scheme
	Vertical diffusion: Second-order central difference
The surface friction configura	ation in Table 1 creates deliberate localized forcing, enabling controlled
investigation of non-uniform	surface effects on wind noise generation mechanisms in the simulated
boundary layer flow.	
Based on the configurat	ions in Table 1, we conducted two contrasting idealized numerical
experiments:	
Ideal_Ctrl (Control Exp	periment):
Solves both hori	zontal advection and vertical diffusion terms at collocated grid points
(x_i)	
Ideal_Test (Test Experi	nent):
 Solves horizonta 	I advection at x_i
· Computes vertic	al diffusion at staggered grid points $(x_i + \Delta x/2)$, with surface friction
velocity (u_*) pres	scribed at corresponding staggered positions
 Couples solution 	s through linear interpolation between grids
The two experiments are	designed to isolate the impact of grid staggering on noise generation
under inhomogeneous surfac	be forcing. Both experiments are simulated for 24 hours (288 steps)
Figure 7 displays the spatio	-temporal distribution of the simulated u-wind from both cases. The
Ideal_Ctrl simulation (Fig. 7	(a) exhibits localized wind reduction at the surface forcing site, with
perturbations propagating d	ownstream smoothly, demonstrating physically consistent behavior
devoid of numerical noise. In	contrast, the Ideal_Test simulation (Fig. 7b) shows that additional $2\Delta t$
grid-scale waves emerge ne	ar the local surface friction anomaly, superimposed on the expected
frictional wind response. F	igure 7 (c-d) demonstrates that the influence of surface friction is
confined to the boundary lay	ver (below the 50th model level). Compared Fig.7 (d) with Fig. 7 (c)
the staggered coupling gene	erates $2\Delta x$ oscillation within the boundary layer at the point of non-
uniform surface friction an	d these spurious noise patterns propagate to adjacent grid points

primarily near the surface. The 6-hour simulated lowest level u-wind (Fig. 7e) confirms that these

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 $2\Delta x$ waves represent spurious numerical oscillations induced by dispersive energy propagation, which are most pronounced adjacent to the inhomogeneous surface forcing region. The Ideal_Test simulation results in Fig. 7 successfully reproduce both the distinctive $2\Delta x$ noise and their characteristic spatial distribution observed in CMA-GFS 3.0.

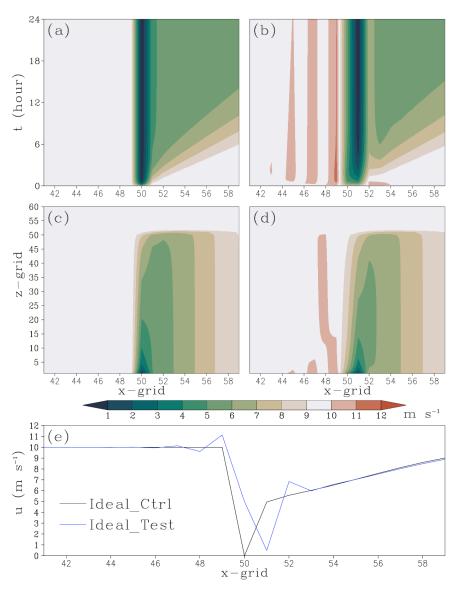


Figure 7. Idealized experiment results (domain: x-grid=41-59): (a-b) Temporal evolution of winds at the lowest model level in (a) Ideal_Ctrl and (b) Ideal_Test; (c-d) Vertical structure at 6 hour for (c) Ideal_Ctrl and (d) Ideal_Test; (e) 6-h wind at the lowest model level.





- 255 The idealized tests identify two primary noise sources: inconsistent advection-diffusion grid 256 staggering and inhomogeneous surface forcing. As demonstrated in Section 2.2, the stripe patterns 257 in wind fields of CMA-GFS 3.0 predominantly occur over landmasses or near islands. This strongly 258 indicates that wind stripe patterns in CMA-GFS 3.0 stem from inconsistent grid staggering in its 259 dynamical-physical coupling. When combined with non-uniform surface forcing, this grid
- 261 patterns.

262 3.4 Analysis of one-dimensional linear wave solution

For the one-dimensional linear damped wave equation:

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = -\alpha u, \qquad \alpha > 0 \tag{6}$$

mismatch triggers dispersive wave propagation—ultimately producing the observed $2\Delta x$ stripe

- where c is the phase speed, $-\alpha u$ the damping term and α the damping coefficient, the analytic
- solution takes the form:

$$u = u_0 e^{-\alpha t} e^{ik(x - ct)} \tag{7}$$

- here k is the wavenumber. Eq. (7) describes an exact, non-dispersive wave propagation where all
- 267 wavenumbers propagate at identical phase speed c.
- In Equation (6), the term $c \frac{\partial u}{\partial x}$ represents the advection term, while the damping term $-\alpha u$
- 269 acts as physical forcing. The numerical implementation employs a staggered grid configuration:
- 270 the advection term is discretized at the primary grid points (x), whereas the damping term is
- evaluated at half-grid offsets $(x \pm \Delta x/2)$ and then averaged—rather than being calculated directly
- 272 at x. This arrangement transforms Eq. (6) into the following modified form:

$$\frac{\partial u(x)}{\partial t} + c \frac{\partial u(x)}{\partial x} = -\frac{\alpha \left(x - \frac{\Delta x}{2}\right) u\left(x - \frac{\Delta x}{2}\right) + \alpha \left(x + \frac{\Delta x}{2}\right) u\left(x + \frac{\Delta x}{2}\right)}{2} \qquad \alpha > 0$$
 (8)

Using Taylor series expansion, the variable u at half-grid offsets can be written as:

$$u\left(x \pm \frac{\Delta x}{2}\right) = u(x) \pm \frac{\partial u}{\partial x}\Big|_{x} \frac{\Delta x}{2} + \frac{1}{2!} \frac{\partial^{2} u}{\partial x^{2}}\Big|_{x} \left(\frac{\Delta x}{2}\right)^{2} \pm \frac{1}{3!} \frac{\partial^{3} u}{\partial x^{3}}\Big|_{x} \left(\frac{\Delta x}{2}\right)^{3} + O(\Delta x^{4}) \tag{9}$$

- where the notation $\frac{\partial u}{\partial x}\Big|_{x}$ denotes the partial derivatives of u at location x. Substituting Eq. (9) into
- 275 Eq. (8) and systematically neglecting fourth-order terms ($O(\Delta x^4)$), the analytical solution to Eq. (8)
- 276 becomes:





$$u = u_0 e^{-\overline{\alpha}t} e^{ik(x-ct)} e^{-i\frac{k\Delta\alpha\Delta x}{2}t} e^{\frac{k^2\overline{\alpha}\Delta x^2}{8}t} e^{i\frac{k^3\Delta\alpha\Delta x^3}{48}t}$$

$$\tag{10}$$

- 277 where $\bar{\alpha} = \frac{\alpha\left(x + \frac{\Delta x}{2}\right) + \alpha\left(x \frac{\Delta x}{2}\right)}{2}$, $\Delta \alpha = \frac{\alpha\left(x + \frac{\Delta x}{2}\right) \alpha\left(x \frac{\Delta x}{2}\right)}{2}$. Eq. (10) exhibits three additional terms in its
- wave solutions compare to Eq. (8):
- 279 1) The term $e^{-i\frac{k\Delta\alpha\Delta x}{2}t}$ introduces a non-dispersive phase velocity modification.
- 280 2) The term $e^{\frac{k^2\alpha\Delta x^2}{8}t}$ enhances the wave amplitude (equivalently reducing damping).
- 281 3) The term $e^{i\frac{k^3\Delta\alpha\Delta x^3}{48}t}$ generates wavenumber-dependent phase modifications, a characteristic
- signature of dispersive wave propagation.
- 283 Compared to Eq. (7), the phase velocity in Eq. (10) combines non-dispersive and a dispersive
- 284 modifications as $c' = c + e^{-i\frac{k\Delta\alpha\Delta x}{2}t} + \frac{k^2\Delta\alpha\Delta x^3}{48}$.
- When α exhibits no spatial variation (hence $\bar{\alpha} = \alpha$ and $\Delta \alpha = 0$), Eq. (10) reduces to:

$$u = u_0 e^{-\alpha t} e^{ik(x-ct)} e^{\frac{k^2 \alpha \Delta x^2}{8} t}$$
(11)

- where only the amplitude-modifying term persists, producing exclusively damping reduction
- without any phase velocity modifications (neither non-dispersive shifts nor dispersive effects).
- Comparing Eqs. (7), (10) and (11) leads to the following conclusions:
- 289 1) The staggered-grid discretization scheme, where advection and damping terms are
- 290 computed at offset grid points, fundamentally modifies wave solutions when compared to
- 291 collocated approaches.
- 292 2) For spatially varying damping coefficients (α), this numerical framework introduces
- 293 coupled amplitude-phase distortions, including wavenumber-dependent propagation speeds
- 294 characteristic of dispersive systems.
- 295 3) In contrast, uniform α fields restrict the influence of staggered-grid effects solely to
- amplitude modulation, preserving the original non-dispersive wave kinematics.
- Idealized experiments and linear wave analysis identify wind stripe noise in CMA-GFS 3.0 as
- 298 requiring the coexistence of two independent factors: Physical forcing inhomogeneity (e.g.,
- 299 discontinuous surface friction) and dynamics-physics coupling on staggered grids. Critically, neither
- 300 factor alone can generate dispersion noise—their combined presence is strictly necessary. This
- 301 explains why stripes emerge preferentially over landmasses or near islands where sharp forcing

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from numerical dispersion noise.





gradients intersect with the model's inherent grid architecture (Fig. 2).

4. Confirming the origin of wind stripe patterns in CMA_GFS 3.0: sensitivity experiments

The preceding analysis demonstrates that low-level wind stripe noise over terrestrial region and 305 306 near islands in CMA-GFS 3.0 stems from horizontal grid mismatch in physics-dynamics coupling. 307 To validate this mechanism, we conduct a targeted sensitivity experiment (Exp Test) by implementing conformal grid alignment for coupled processes. 308 In Fig. 1, the physical-point *u*-component can be expanded as $u_p\left(x+\frac{\Delta x}{2}\right)=u(x)+O(\Delta x)$. In 309 Exp_Test, we retain solely the zeroth-order approximation, enforcing $u\left(x+\frac{\Delta x}{2}\right)=u(x)$. The 310 same treatment is applied to the v- component $\left(v\left(y+\frac{\Delta y}{2}\right)=v(y)\right)$, ensuring consistent dynamics-311 physics coupling for both horizontal velocity components. This conformal alignment ensures 312 313 dynamical and physical processes are computed at coincident grid points, eliminating the need for 314 interpolation-based coupling shown in Eqs. (1)-(2). The experimental configuration replicates the 315 Exp Ctrl setup described in Section 2.2, maintaining identical initial conditions and physical 316 parameterizations. Compared to the results from Exp Ctrl (Fig. 2), Exp Test maintains small-scale variability in 317 318 terrestrial wind fields while completely eliminating $2\Delta x$ stripe patterns (Fig. 8). The residual 319 inhomogeneity over land, as evidenced in Fig. 8, reflects authentic physical responses to subgrid 320 surface forcing inhomogeneity (e.g., topographic roughness, land-use variations), distinguishing it



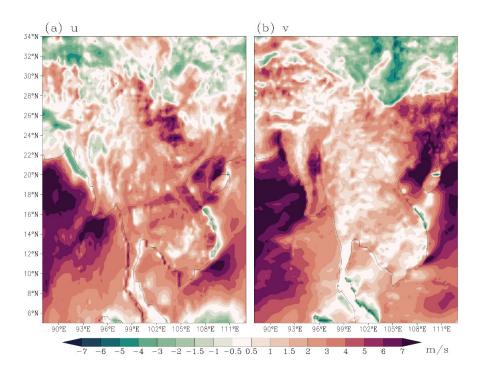


Figure 8 same as Fig. 2, but for $Exp_Test.$

Spectral analysis serves as a rigorous tool for quantifying energy distribution across frequencies. To diagnose the impacts of conformal dynamics-physics coupling on wind stripe patterns we conduct one-dimensional energy spectrum analysis separately for the *u*-component (zonal direction) and *v*-component (meridional direction). We selected the East Asian domain (70-145°E, 10-65°N) as a representative non-uniform surface region and the tropical Pacific (160°E-120°W, 20°S-20°N) as a typical uniform surface region for comparative analysis. The *u*- component was processed as a one-dimensional east-west oriented sequence for Fast Fourier Transform (FFT) analysis, while the *v*- component underwent identical treatment along the north-south axis. Through spectral analysis, the power spectral density (PSD) was estimated by computing the squared modulus of the FFT coefficients (Fig. 9).





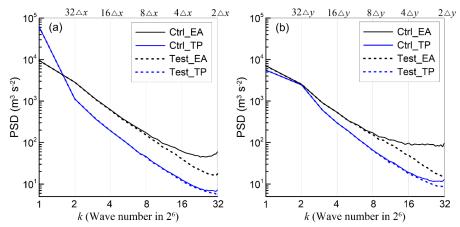


Figure 9. PSD of (a) *u*- and (b) *v*-components at 18 hour over tropical Pacific (TP: 160°E-120°W, 20°S-20°N) and East Asia (EA: 70°-145°E, 10°-65°N) domains for Exp_Ctrl and Exp_Test.

The key results of PSD investigation can be summarized as follows:

- 1) Over land, both u- and v- components in Exp_Ctrl demonstrate considerably strong energy at small scales (high wavenumbers), with no energy decay observed from 4Δx to 2Δx. In contrast, Exp_Test achieves significant suppression of small-scale energy, effectively mitigating high-frequency computational noise in terrestrial regions.
- Over oceanic regions, the near-surface wind power spectra exhibit remarkable consistency between Exp_Ctrl and Exp_Test. This spectral equivalence suggests that the horizontally homogeneous sea surface lacks the physical forcing inhomogeneity required to generate wind stripe patterns. The absence of surface inhomogeneity prevents the formation of computational noise in Exp_Ctrl, making Exp_Test's unstaggered dynamics-physics coupling configuration exerts no significant impact in these regions.
- 3) Terrestrial spectra exhibit distinct energy distributions between Exp_Ctrl and Exp_Test across scales ranging from 2Δx to 8Δx. This spectral difference indicates that when inhomogeneous surface forcing combined with staggered-grid dynamic-physical coupling, dominant 2Δx-scale perturbations emerge consistently while statistically significant oscillations develop at discrete larger scales (e.g., 4Δx).

Our sensitivity analysis confirms that the noise in CMA-GFS 3.0 originate specifically from the staggered-grid coupling between dynamic and physical processes over inhomogeneous surfaces. However, the noise-free Exp Test configuration artificially decouples the wind field from mass

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fields (e.g., temperature and moisture) spatially in physical processes, violating fundamental physical constraints. We emphasize that Exp_Test serves solely as a mechanistic diagnostic to isolate the noise source rather than a viable approach for operational model improvement.

5. Conclusion and discussion

The removal of fourth-order horizontal diffusion in CMA-GFS 3.0 (Shen et al., 2023), while enhancing small-scale system simulations, has inadvertently exposed underlying $2\Delta x$ stripe patterns in low-level wind fields that were previously suppressed by the horizontal diffusion scheme. The results of a case study demonstrate that these stripe patterns exhibits one-dimensional oriented distribution characteristics, with meridional alignment in u-component and zonal alignment in vcomponent. These stripes maintain continuous presence throughout the 120-hour period, with spatially predominant occurrence over land and near islands, while exhibiting diurnal amplitude modulation. We systematically elucidate the generation mechanism of these stripe patterns through a combination of numerical experiments and theoretical analysis. Through controlled experiments with the dynamic core alone (no physics) and examination of associated surface static fields, we conclusively exclude the possibility that either the dynamic numerics or physical parameterizations independently generate the observed $2\Delta x$ noise. This leaves physics-dynamics coupling as the sole plausible origin, consistent with our previous findings (Chen et al., 2020) that $2\Delta x$ computational modes may emerge specifically when dynamics and physics interact through staggered-grid coupling. Two-dimensional idealized experiments successfully reproduced $2\Delta x$ waves generated at inhomogeneous surface friction points when combining advection and friction on staggered grids. Linear wave theory analysis further revealed that this dispersion effect originates from the coupling between dynamic advection and physical forcing on staggered grids under non-uniform physical forcing. These mechanistic analyses indicate that the grid mismatch in dynamic-physical coupling is the fundamental cause of noise generation over inhomogeneous surfaces.

Sensitivity experiments confirm that when dynamic-physical grid consistency is maintained and interpolation coupling is avoided, the wind field noise can be completely eliminated. Spectral analyses reveal land-ocean contrasts: Over oceans, staggered-grid coupling shows negligible impacts due to surface homogeneity. Over land, grid mismatch in physics-dynamics coupling under





385 inhomogeneous surface elevates small-scale energy $(2\Delta x - 8\Delta x)$, generating broadband noise, while 386 unstaggered physics-dynamics coupling restores the energy spectrum to a reasonable decay curve 387 with decreasing scale. 388 Our results demonstrate that the stripe noise in low-level wind field of CMA-GFS 3.0 stems from grid mismatch in physics-dynamics coupling under non-uniform forcing conditions. These 389 390 findings offer critical insights for other NWP models employing similar grid configurations, 391 revealing potential numerical dispersion risks in physical-dynamics coupling on traditional staggered grids. 392 393 Building on these findings, we systematically evaluate potential solutions to mitigate wind-field noise in CMA-GFS 3.0. Since surface inhomogeneity is inherently present in NWP models, one 394 395 essential approach to noise reduction involves resolving the grid mismatch between physics 396 parameterizations and dynamical core. In latitude-longitude grid configurations, the Arakawa C-397 grid exhibits superior dispersion characteristics compared to unstaggered A-grid arrangements, 398 particularly in maintaining proper phase relationships for geostrophic adjustment processes. 399 However, adopting an A-grid configuration may introduce computational challenges in the 400 dynamical core that could degrade numerical accuracy. 401 It must be emphasized that grid configuration represents a fundamental architectural feature of 402 numerical modeling systems. As the cornerstone of model design, grid setup is determined at the 403 earliest development stage. Redesigning grids equates to building an entirely new model system, 404 making modifications to CMA-GFS's existing Arakawa C-grid configuration unfeasible. An 405 alternative approach would involve computing wind fields directly on the dynamics grid within 406 physical parameterizations. However, this strategy encounters substantial technical obstacles owing 407 to the inherently tight coupling between wind and temperature/moisture fields in physical processes, 408 especially when managing their interactions on staggered grids. Consequently, this method also 409 proves extremely difficult to implement in CMA-GFS. 410 A compromise solution involves employing higher-order horizontal diffusion or filtering which 411 is widely implemented in NWP models. Methods like high-order horizontal diffusion can effectively 412 eliminate $2\Delta x$ high-frequency noise while retaining most resolvable-scale energy. Specifically, as demonstrated by Xue (2000), 4th-order horizontal diffusion preserves about 80% of 4Δx-scale 413 spectral energy, and 6th-order diffusion achieves ~90% retention at this scale. However, one-414

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dimensional linear wave analysis shows that staggered grid coupling under non-uniform forcing not only produces dispersion effects but also alters wave amplitude and phase speed, and these systematic deviations cannot be corrected by simple noise-removal tools. Based on the conclusions of this study and the above discussion, we propose two recommendations: For the current CMA-GFS system, we recommend implementing high-order horizontal diffusion or similar treatment methods globally to eliminate low-level wind field noise, and systematically evaluating its impact on forecasts; In developing next-generation model frameworks, the coordination of dynamic-physical coupling should be a core design consideration to fundamentally prevent such issues. Data and code availability. The CMA-GFS 3.0 operational system code is proprietary to the China Meteorological Administration and cannot be publicly released. For inquiries about the model framework, contact the operational management department of CEMC or the author, Jiong Chen (cjiong@cma.gov.cn), for further assistance. The idealized test code for diagnosing stripe patterns, along with all analysis scripts and data used to generate the figures, is available at https://doi.org/10.5281/zenodo.15597504 (Chen et al., 2025). Author contributions. JC conducted the model simulations, designed the idealized experiments, performed the diagnostic analysis, and wrote the manuscript. YS first identified the stripe patterns in operational forecasts and excluded the dynamical core's contribution through controlled numerical tests. All other authors participated in result interpretation, provided critical feedback during manuscript revisions, and contributed to figure improvements. Competing interests. The contact author has declared that none of the authors has any competing interests. Acknowledgements. This research was supported by the NSFC Major Project (42090032) and

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