

1 Seismic data analysis for subglacial lake D2 beneath David Glacier, 2 Antarctica

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12 **Abstract.** Subglacial lakes beneath Antarctic glaciers are pivotal in advancing our understanding of cryosphere dynamics,
13 basal hydrology, and microbial ecosystems. We investigate the internal structure and physical properties of Subglacial Lake
14 D2 (SLD2), which is located beneath David Glacier in East Antarctica, using seismic data acquired during the 2021/22 austral
15 summer. The dataset underwent a comprehensive processing workflow, including noise attenuation, velocity analysis, and ~~pre-~~
16 ~~stack~~prestack time migration. ~~Migrated~~The migrated seismic sections revealed distinct reverse- and normal-polarity reflections
17 at the glacier–lake and lake–bed interfaces, respectively. We compared the synthetic seismogram generated through wave
18 propagation ~~modelling-based~~modeling on the basis of our structural interpretation of the migrated sections with the field data
19 to validate the subglacial lake structure inferred from the seismic data. This confirmed that the water column thickness
20 ranged from ~~around~~approximately 53 to 82 m and delineated the broader structure of the subglacial lake. ~~Also~~Additionally,
21 discontinuous reflections detected ~~on~~in seismic sections transverse to the ice flow were interpreted as scour-like feature
22 surfaces formed by ice movement. ~~Comparison~~A comparison with airborne ice-penetrating radar (IPR) data acquired in 2018
23 further supported the consistency of the ice thickness estimates. Notably, a steeply dipping bedrock boundary identified along
24 profile 21YY provided a more precise definition of the lateral extent of SLD2 than was possible using when IPR data alone
25 were used. Collectively, these findings enhance our understanding of subglacial lake environments and inform the selection of
26 future drilling sites for in situ sampling.

27 1 Introduction

28 Subglacial lakes beneath the Antarctic ~~Ice Sheet~~ice sheet are typically overlain by glaciers several kilometers thick and have
29 remained isolated from direct atmospheric and solar influences for millions of years, creating extreme environments
30 characterized by low temperatures (Thoma et al., 2010) and high pressures (Tulaczyk et al., 2014). With increasing scientific
31 interest, subglacial lakes have become a focal point for studies related to the Antarctic paleoclimate, as inferred from lake

32 sediments, as well as investigations into microbial life in polar ecosystems (Bell et al., 2007, 2011; Bentley et al., 2009;
33 Christner et al., 2014; Engelhardt et al., 1990; Priscu and Christner, 2003; Rose, 1979; Wingham et al., 2006). Subglacial lakes
34 in Antarctica are generally categorized as either stable or active. Approximately 80% of subglacial lakes in Antarctica are
35 classified as stable subglacial lakes. These closed systems do not exhibit significant surface elevation changes and where
36 subglacial water remains largely isolated, with minimal exchange due to slow and stable recharge and discharge cycles. The
37 remaining 20% are classified as active subglacial lakes, which exhibit surface elevation changes due to episodic water drainage
38 and refilling events (Livingstone et al., 2022).~~Additionally, these lakes influence glacier dynamics by reducing basal friction,~~
39 ~~facilitating ice flow, and potentially accelerating calving events~~ Such active lakes can reduce basal friction as they expand,
40 thereby facilitating glacier flow and, in some cases, accelerating calving processes, ultimately influencing glacier dynamics
41 (Bell et al., 2007; Stearns et al., 2008; Winsborrow et al., 2010). Characterizing subglacial lakes is essential for understanding
42 cryospheric processes, reconstructing past climate conditions, and assessing the potential for life in isolated, extreme
43 environments.

44 The sampling of subglacial lake water, sediments, and microbial communities is critical to address these scientific objectives.
45 However, successful sampling requires careful selection and characterization of the drilling site. Airborne ice-penetrating radar
46 (IPR) surveys are commonly employed at regional scales to detect potential subglacial lakes ~~suitable locations~~ suitable for drilling
47 (Christianson et al., 2012; Lindzey et al., 2020; Yan et al., 2022). However, due to signal attenuation in water, IPR surveys are
48 limited in resolving the internal structure of subglacial lakes. To overcome this limitation, seismic surveys have been conducted
49 at potential subglacial lake candidates identified from IPR surveys. During such surveys, P-waves propagate through the water
50 column and are partially reflected at the lake–bed interface because of contrasts in acoustic impedance. Analyzing these
51 reflected waves enables detailed delineation of the water column and underlying substrate, thereby informing optimal drilling
52 locations (Brisbourne et al., 2023; Filina et al., 2008; Horgan et al., 2012; Woodward et al., 2010).

53 As such, numerous studies have utilized seismic surveys to investigate the characteristics of subglacial lakes, including
54 Subglacial Lake Ellsworth, Subglacial Lake Whillans, and Subglacial Lake CECs. Subglacial Lake Ellsworth, located beneath
55 2,930–3,280 m of glacial ice in West Antarctica, was the subject of a seismic survey during the austral summer of 2007–08.
56 This survey revealed spatially variable ice thickness and a lake water column ranging from 52 to 156 m, which guided the
57 identification of an optimal drilling location (Smith et al., 2018; Woodward et al., 2010). Subglacial Lake Whillans lies beneath
58 approximately 800 m of ice. Seismic observations conducted during the 2010/11 field season revealed water columns
59 extending over a 5 km segment of the survey profile, with a maximum thickness of less than 8 m. The glacier bed was
60 predominantly composed of soft sediments, and localized zones with shallow water columns (< 2 m) were also identified
61 (Horgan et al., 2012). Subsequent drilling in the summer of 2012/13 confirmed the presence of microbial life in both the water
62 and sediment samples (Christner et al., 2014). Subglacial Lake CECs (SLCECs), located beneath 2653 m of ice at the Rutford–
63 Institute–Minnesota Divide in West Antarctica, were investigated through seismic surveys conducted in the 2016/17 and
64 2021/22 seasons. These surveys revealed a maximum water column thickness of 301.3 ± 1.5 m and clastic sediments up to 15

65 m thick covering the lakebed. While the lake center was relatively flat, significant topographic variability was observed near the lake margins (Brisbourne et al., 2023).

We have initiated subglacial lake research beneath David Glacier, the closest major glacier to Jang Bogo Station in East Antarctica. Satellite altimetry has identified six subglacial lakes in this region (Smith et al., 2009; Wright and Siegert, 2012). During the 2016/17 austral summer, an airborne IPR survey was conducted over the region encompassing Subglacial Lake D1 (SLD1) and Subglacial Lake D2 (SLD2) (Lindzey et al., 2020). A subsequent high-resolution IPR survey was carried out during the 2018/19 field season, focusing solely on SLD2 (Frémand et al., 2023; Ju et al., 2024b5). The combined results of the two surveys revealed moderately enhanced radar bed echoes relative to the surrounding area, specularity values (>0.4), a depressed basal elevation (≤ -350 m), and a low hydraulic gradient ($\leq 0.84^\circ$), collectively indicating a high potential for the presence of subglacial water beneath SLD2. Seismic Building upon these observations, Ju et al. (2025) subdivided the previously identified single subglacial water body at SLD2, as detected by ICESat altimetry, into three smaller subglacial lakes: SLD2-A, SLD2-B, and SLD2-C. Among these, SLD2-A represents the largest areal extent, and targeted seismic surveys were employed conducted over this area to investigate the structure of obtain high-resolution information on the lake further depth and basal structure. In the 2019/20 season, an initial seismic campaign identified the glacier thickness and suggested the presence of the lake; however, the data quality was compromised by surface crevasse noise and a lack of adequate fold coverage, limiting detailed interpretation. A refined seismic survey with 8-fold coverage was conducted during the 2021/22 season to address these issues.

In this study, we present a detailed analysis of the physical and structural properties of SLD2-A using seismic data acquired during the 2021/22 campaign. We first describe the seismic data processing workflow, including noise attenuation, amplitude correction, and pre-stack/prestack time migration. The final results reveal seismic reflections corresponding to the glacier--lake and lake--bed interfaces. Subsequently, the seismic interpretation is subsequently validated through a comparison with synthetic seismograms, and a quantitative analysis is performed to determine the key structural characteristics of SLD2-A, including the ice thickness, water column thickness, and basal structure of the lake.

88 2 Subglacial Lake D2 Beneath David Glacier in Antarctica

89 2.1 David Glacier

David Glacier, located in Victoria Land, East Antarctica, originates from the Dome C and Talos Dome regions and flows seaward through the Drygalski Ice Tongue (Fig. 1). The mass balance of the glacier/glaciers from 1979 to 2008 has been estimated at 7.5 ± 0.4 Gt yr⁻¹ (Rignot et al., 2019), while the mean ice discharge over the more extended period from 1979 to 2017 was reported to be approximately 9.7 Gt yr⁻¹ (Frezzotti et al., 2000; Rignot et al., 2019). These estimates suggest that ice discharge exceeds net accumulation, indicating a negative mass balance and implying that David Glacier has contributed to global sea level rise According to Smith et al. (2020), satellite altimetry observations from ICESat-1 and ICESat-2 (20032019) indicate that the grounded portion of David Glacier experienced a mass gain of 3 ± 2 Gt yr⁻¹, whereas the adjacent ice shelves

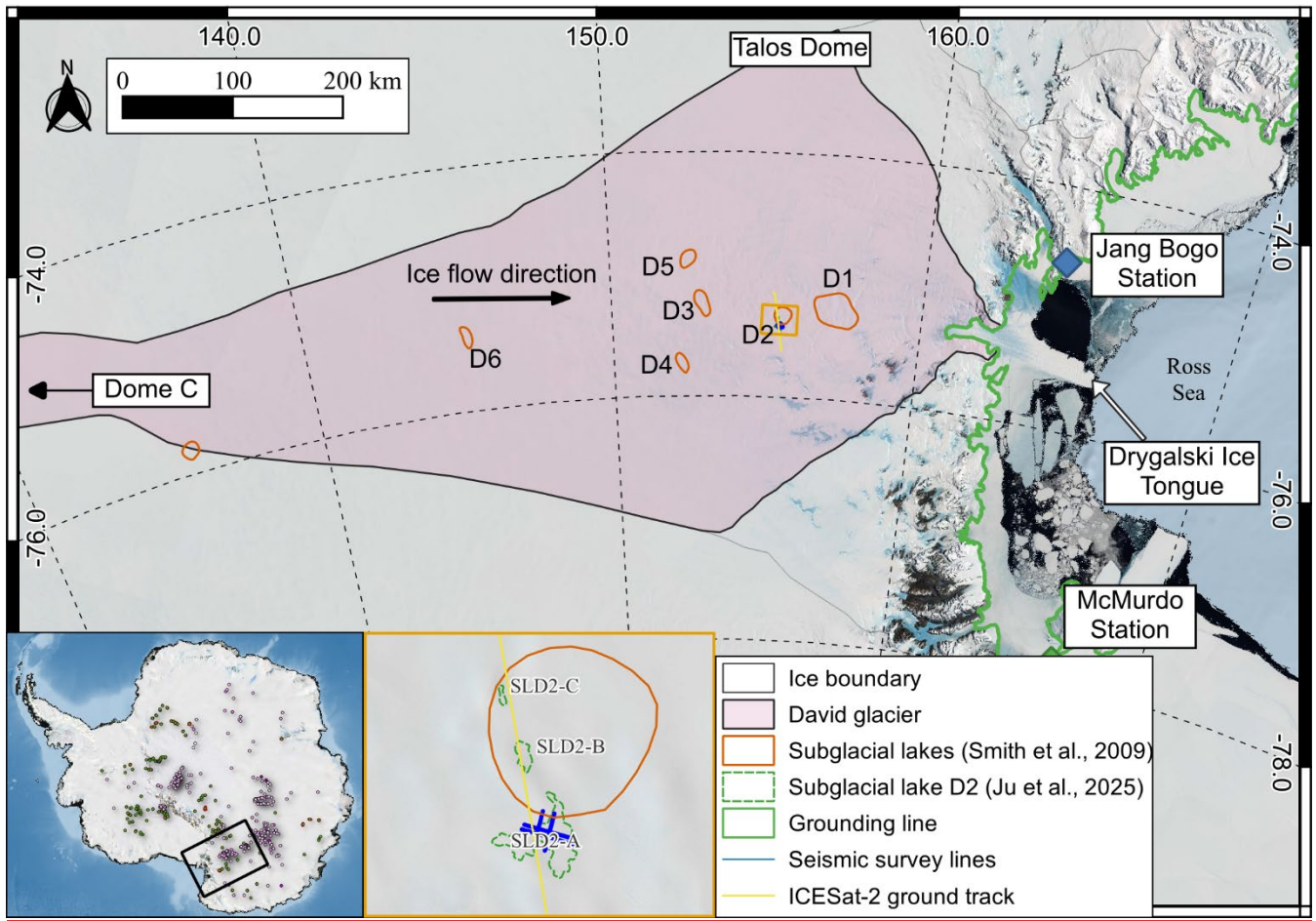


Figure 1: Locations of subglacial lakes D1–D6 in the David Glacier region, Victoria Land, Antarctica (EPSG: 4326–WGS84).

2.2 Subglacial Lake D2

~~Subglacial lakes in Antarctica are generally categorized as either stable or active. Approximately 80% of subglacial lakes in Antarctica are classified as stable subglacial lakes. These closed systems do not exhibit significant surface elevation changes, and where subglacial water remains largely isolated, with minimal exchange due to slow and stable recharge and discharge cycles. The remaining 20% are classified as active subglacial lakes, which exhibit surface elevation changes due to episodic water drainage and refilling events (Livingstone et al., 2022).~~

Among the six subglacial lakes (D1–D6) identified beneath David Glacier via satellite altimetry (Smith et al., 2009; Wright and Siegert, 2012), SLD2 was observed to have experienced a drainage event between 2003 and 2008 ~~based on~~ the basis of ICESat altimetry data (Smith et al., 2009). Since the drainage event, a continuous increase in surface elevation over SLD2 has been observed, indicating water refilling, as detected from CryoSat-2 altimetry data (2013–2017) (Siegfried and Fricker, 2018)

and, more recently, from ICESat-2 observations (2019–2024) (Fig. 2). Figure 2 shows elevation changes relative to April 2019, indicating surface uplift through January 2022. After this period, the surface elevation remained stable in the region originally delineated as SLD2 (by Smith et al., (2009), whereas the seismic survey region experienced a decreased elevation trend was observed in the SLD2-A region (Ju et al., 2025). These patterns of elevation change strongly suggest that SLD2 is an active subglacial lake, with cyclic drainage and refilling likely contributing to the presence of subglacial sediments.

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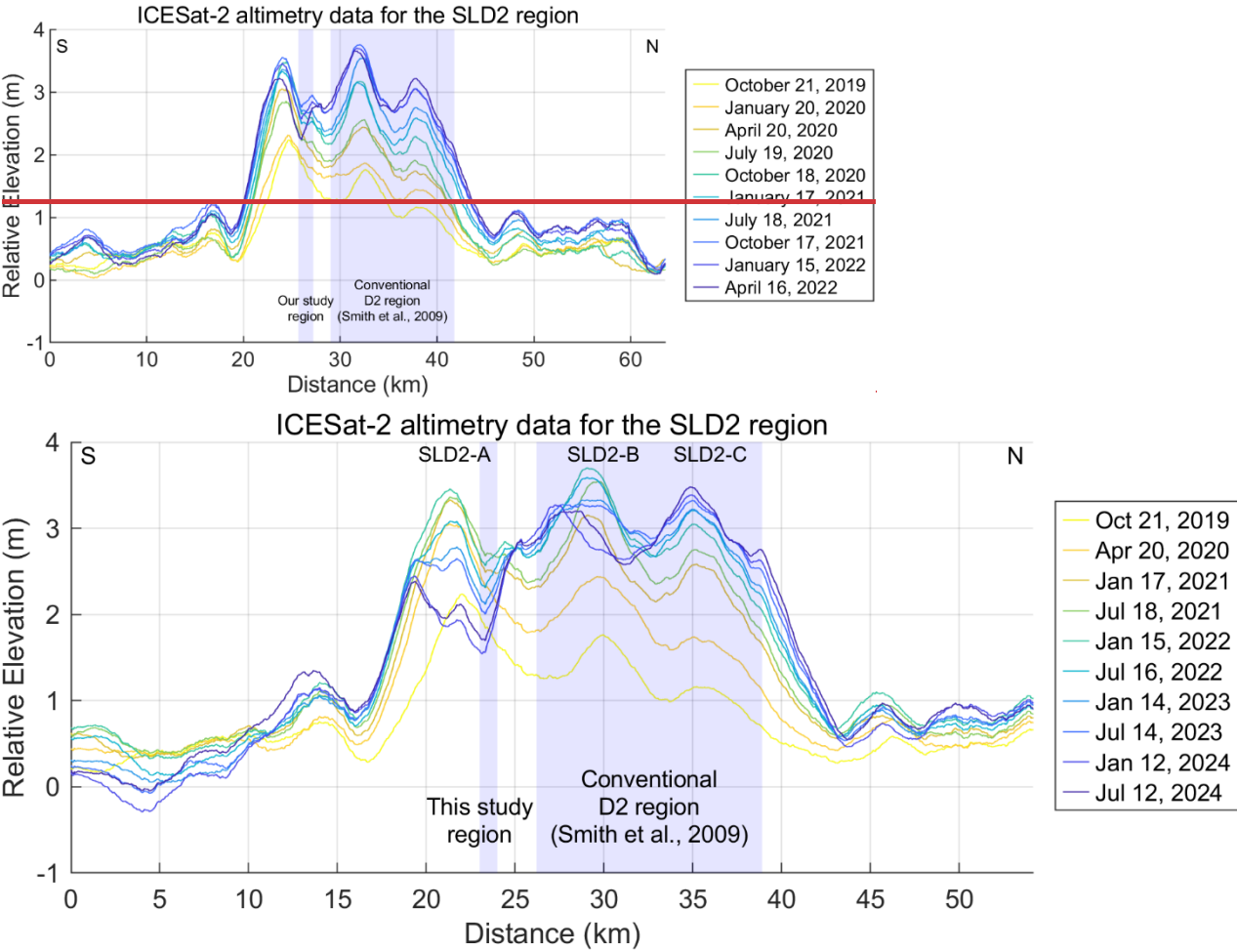
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Figure 2: Glacier surface elevation changes derived from ICESat-2 altimetry between 22 April 2019 and 12 July 2024. The X-axis corresponds to the 22 April 2019 dataset, and all subsequent elevation changes are referenced to this date. The light blue shaded region indicates the spatial overlap between the conventional SLD2 region identified by Smith et al. (2009) and our study region.

125

Airborne IPR surveys were conducted during the 2016/17 and 2018/19 austral summer seasons to better constrain the lake's extent and basal conditions. These surveys of SLD2, airborne IPR survey data from 2016/17 (Lindzey et al., 2020) and 2018/19 (Ju et al., 2025) field campaigns indicate that glacier surface elevations in the SLD2 region range from approximately 1820 to

128



129 1940 m, with ice thicknesses varying between 1685 and 2293 m. Furthermore, the observations of moderately enhanced radar
130 bed echoes relative to the surrounding area, elevated specularity values (>0.4), depressed basal elevations (≤ -350 m), the presence of a Bain-like topography, a lower hydraulic head than the surroundings, and low hydraulic gradients ($\leq 0.84^\circ$)
131 collectively suggest a high potential for the presence of subglacial water beneath SLD2. (~~Frémand et al., 2023~~; Ju et al., 2024b;
132 Lindzey et al., 2020).

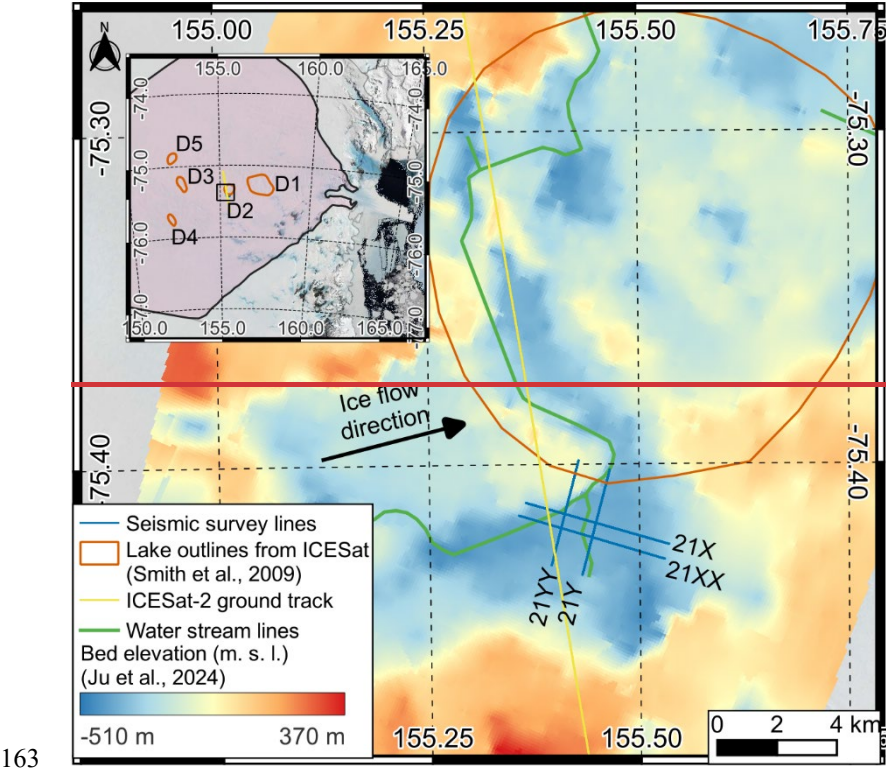
134 3 Method

135 3.1 Seismic survey

136 As previously noted, the internal structure and water column of subglacial lakes cannot be fully resolved using IPR alone
137 because of signal attenuation in water. Accordingly, a seismic survey was conducted within the candidate SLD2-A region
138 identified from IPR data to investigate the structure of the subglacial lake more precisely. ~~A~~
139 During the 2019/20 austral summer, a preliminary seismic survey was conducted during the 2019/20 austral summer over the
140 SLD2-A region to evaluate the potential presence of a subglacial lake and to obtain initial information on its structural
141 characteristics. Owing to limited field time and equipment constraints, the fold of coverage for all survey lines was restricted
142 to 1, and all shot points were aligned near surface crevasses. Consequently, the acquired seismic data were significantly
143 contaminated by strong linear coherent noise associated with crevasses, which severely degraded the signal quality of key
144 reflectors, particularly reflections from the subglacial lake–bedrock interface. In addition, explosives are deployed within
145 shallow boreholes (< 20 m depth), and owing to the absence of proper backfilling and the rapid timing of detonation, poor
146 coupling between the explosives and the borehole walls further reduces energy transmission efficiency, resulting in overall
147 low-quality reflection signals (Ju et al., 2024). As a result, due to the limitations of single-fold acquisition, stacking was not
148 feasible, resulting in a low signal-to-noise ratio (SNR) and the presence of dominant coherent noise, rendering the seismic
149 dataset unsuitable for quantitative structural interpretation. Nevertheless, the preliminary survey qualitatively confirmed both
150 the glacier thickness and beneath SLD2-A and suggested the presence of subglacial water, providing critical guidance for
151 baseline information that guided the methodology and survey design of the subsequent detailed ~~survey~~ seismic campaign
152 conducted during the 2021/22 season.

153 For the refined survey, seismic acquisition lines were planned using bed topography derived from the IPR and surface elevation
154 data from satellite altimetry. A total of four seismic lines were ~~deployed~~ acquired and designated 21X, 21Y, 21XX, and 21YY
155 (Fig. 3). Lines 21X and 21XX, oriented approximately 52° relative to the ice flow direction, are situated at an average surface
156 elevation of 1894 ± 13 m. Lines 21Y and 21YY, oriented approximately -30° in the ice flow direction, lie at an average
157 elevation of 1887 ± 16 m. All lines traverse regions of minimal topographic relief, with average surface slopes of approximately
158 0.5° , indicating a relatively flat and stable glacier surface. The lengths of the 21X/21XX and 21Y/21YY lines are
159 approximately 5 km and 3.5 km, respectively. Seismic acquisition for lines 21X and 21Y was conducted using 8-fold coverage

160 to increase the resolution, whereas lines 21XX and 21YY were acquired with 4-fold coverage due to time constraints during
161 the survey. The additional acquisition parameters are summarized in Table 1.
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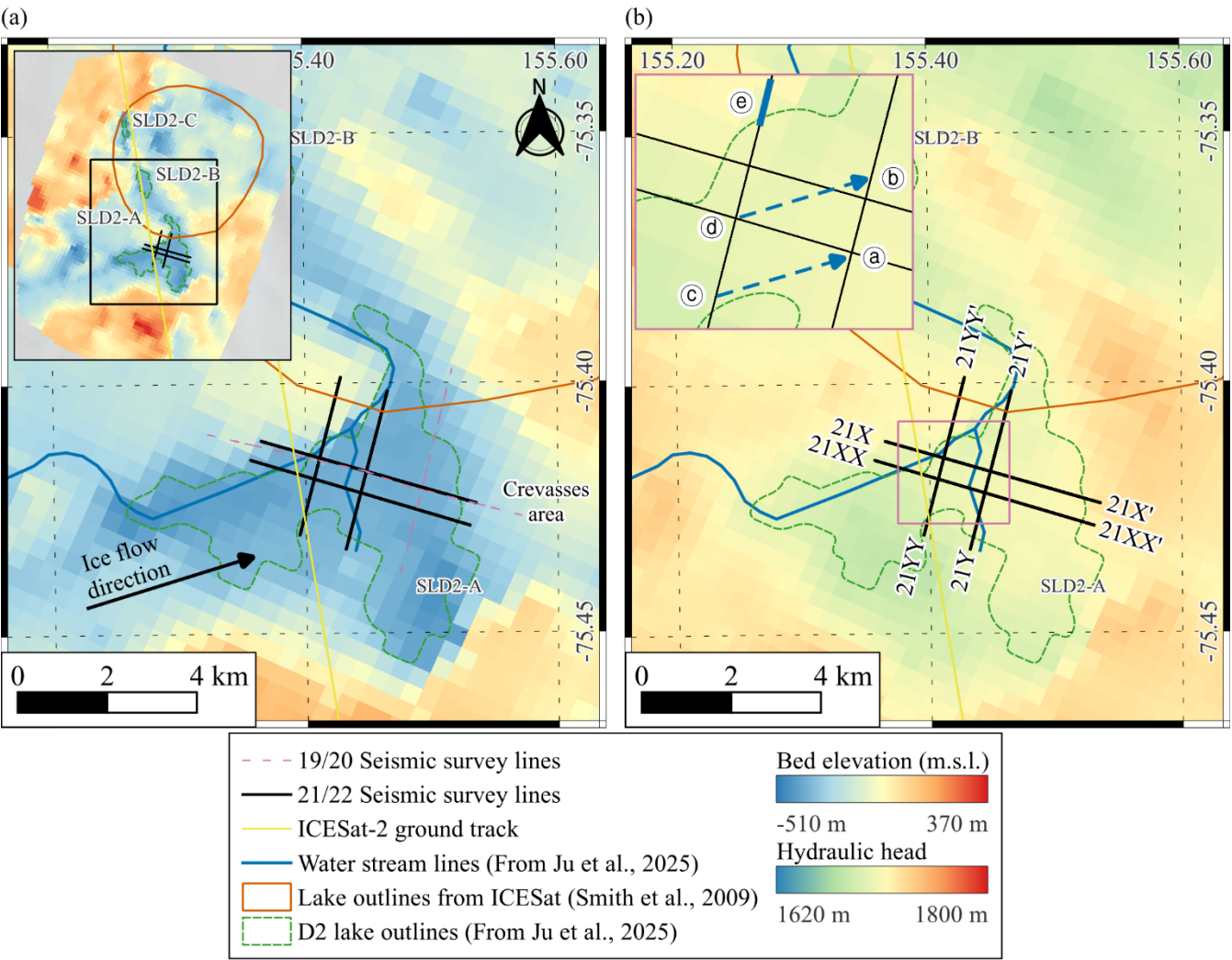


Figure 3: 21/22 Seismic survey layout (black lines) overlaid on (a) bed elevation and (b) hydraulic head data from IPR results (Ju et al., 20245).

Table 1: Parameters of the active-source seismic survey.

Survey Parameters		Survey lines			
		21X line	21Y line	21XX line	21YY line
Line length (km)		5	3.5	5	3.5
Fold		8	8	4	4
Shot interval (m)		90	90	180	180
Number of shots		56	40	28	20
Receiver channels				96	
Receiver interval (m)				15	
Recording time (s)				4	
Record peak frequency (kHz)				1	
Record sampling rate (ms)				0.25	
Survey time (days)				34	
Survey crew size			Hot water drilling (3), Seismic (6)		

Before the seismic survey, a ground-penetrating radar (GPR) survey was used to identify the firm transition zone at depths of approximately 20–22 m. To enhance seismic signal transmission, 1.6 kg of pentaerythritol tetranitrate (PETN) explosives were emplaced at depths of 25–30 m using hot water drilling techniques. A total of 144 shots were deployed across the four survey lines. Given the snow-covered glacier surface, Georods were used instead of conventional spike-type geophones to increase signal detection efficiency (Voigt et al., 2013). Each Georod houses four geophone elements in a 0.6 m-long cylindrical array, producing a single output by summing the inputs from all the elements. Compared with traditional geophones, this configuration improves coupling and detection performance in snow-dominated environments (Ju et al., 2024a). Figure 4 presents shot ~~gathers #31–40~~gather #27 from line 21X. ~~Orange arrows indicate the positions of the corresponding and~~ shot ~~points along the 21X profile. Within gather #7 from line 21Y. In~~ these shot gathers, ~~the velocity of the direct wave is estimated to be approximately 1800 m/s, and the refracted wave velocity is approximately 3800 m/s. First-arrival analysis of the direct wave indicates a normal polarity, confirming the source waveform polarity. A prominent negative polarity reflection is observed at a two-way travel time (TWT) of approximately 1.2 s is 2 s, interpreted as the glacier–lake interface, followed by. Approximately 25–30 ms later, a ghost reflection 20–30 ms later. A second with normal polarity appears. A subsequent reflection, observed at approximately 1.3 s TWT of 1.3 s, showing normal polarity, is attributed to the lake–bed interface. In some end, followed by its negative polarity ghost reflection 25–30 ms later. In shot gathers, such as shot-gather #33, linear 27, noise signals interfere with the glacier–lake interface signal originating from crevasses becomes apparent from approximately 2 s TWT. As the distance to the crevasses decreases, this noise increasingly overlaps with the primary reflection arrivals, complicating the interpretation.~~

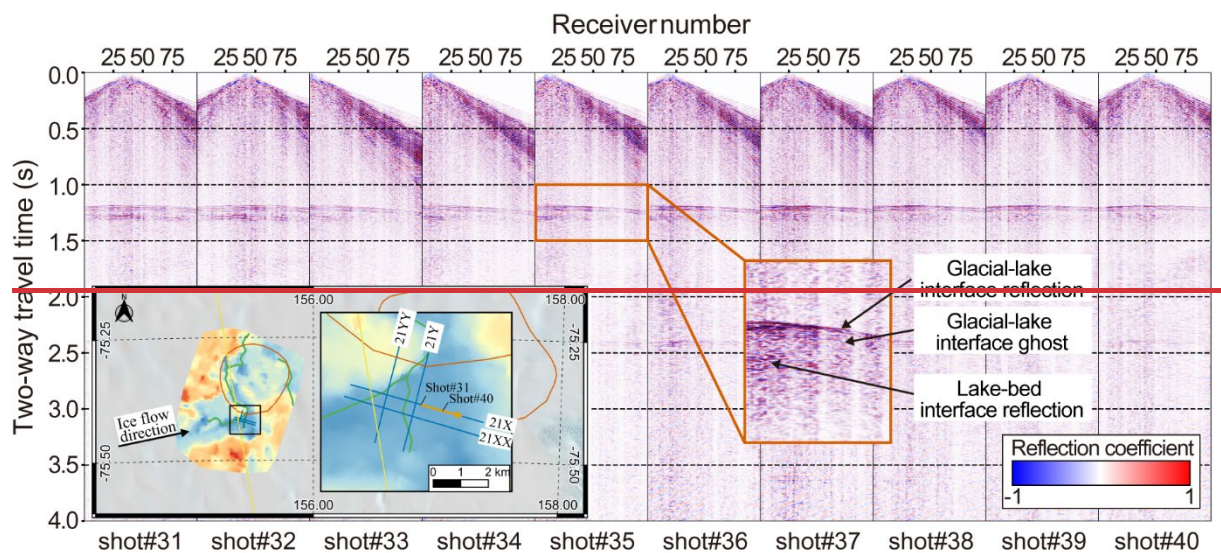


Figure 4: Raw shot gathers (#31–40) from line 21X, with data locations indicated by orange arrows.

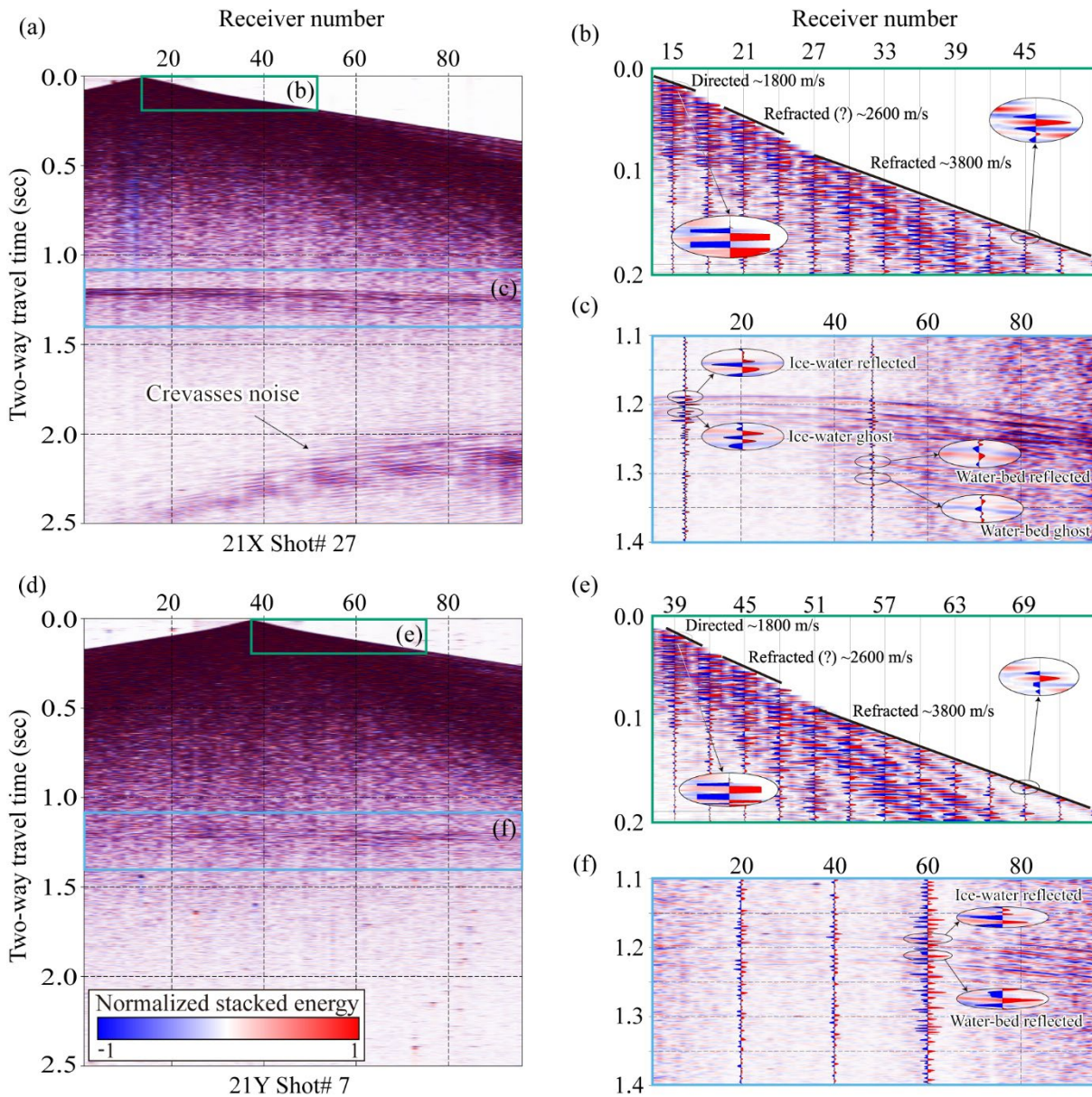


Figure 4: Raw shot records from seismic lines 21X (a) and 21Y (d). Panels (b) and (e) are zoomed-in views of the early arrival window (0.0–0.2 s) from panels (a) and (d), respectively, used to calculate the apparent velocities of the direct and refracted waves. These panels highlight that the first arrivals of both the direct wave (clipped for display) and the refracted wave exhibit positive polarity. The direct wave, propagating through the upper firn layer (0–25 m depth), shows an apparent velocity of direct waves, approximately 1800 m/s, while the refracted wave traveling through glacier ice has an apparent velocity of reflections approximately 3800 m/s. Panels (c) and (f) are zoomed-in views of the deeper arrivals (1.1–1.4 s) from panels (a) and (d), respectively. Reflections from the ice–water interface exhibit negative polarity, whereas those from the water–bed interface display positive polarity.

Raw shot records from seismic lines 21X (a) and 21Y (d). (b) Zoomed in view of the early arrivals (0.0–0.2 s) in panel (a), highlighting direct and refracted waves. (c) Zoomed in view of deeper arrivals (1.1–1.4 s) in panel (a). (e) Zoomed in view of the early arrivals (0.0–0.2 s) in panel (d). (f) Zoomed in view of deeper arrivals (1.1–1.4 s) in panel (d). In panels (b) and (e), the direct wave—

corresponding to the upper firn layer (0–25 m depth) propagates with an apparent velocity of approximately 1800 m/s, while the refracted wave through glacier ice exhibits an apparent velocity of about 3800 m/s. In panels (e) and (f), reflections from the ice–water interface exhibit negative polarity, while those from the water–bed interface show positive polarity.

3.2 Seismic data processing

Although seismic data acquired from glaciers share processing similarities with those of land-based surveys, glaciological factors, such as surface cracks, crevasses, and strong winds, introduce substantial noise that can degrade data quality (Johansen et al., 2011; Zechmann et al., 2018). Among these factors, linear noise generated by crevasses is particularly detrimental, often obscuring key reflections (Dow et al., 2013). Hence, the glacier seismic data underwent multiple data processing sequences focused on linear noise removal (Fig. 5). Acquisition geometry setup was performed added to the data using the raw data and geometry information. Multiple data processing and noise removal processes were then carried out to increase the signal-to-noise ratio (SNR).

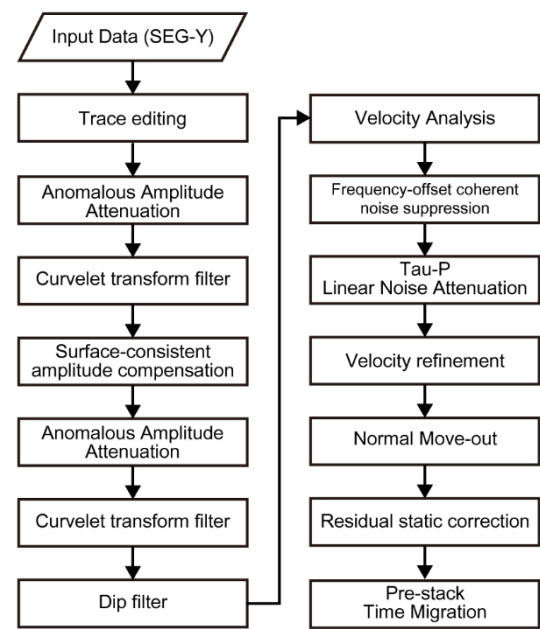


Figure 5: Schematic of the seismic data processing workflow based on the Omega geophysical data processing platform, (SLB), including noise attenuation, amplitude correction, velocity analysis, and pre-stack/prestack time migration.

The initial processing involved anomalous amplitude attenuation (AAA), implemented via a spatial median filter. This step targets outlier amplitudes within a defined frequency band, attenuating anomalous signals through interpolation across neighboring traces. A curvelet transform-based filter was subsequently applied to remove coherent noise. Curvelet decomposition enables the separation of signals based on the basis of dip angle and scale, allowing for the selective removal

228 of ground roll and other coherent noise components that differ in dip from true reflections (Oliveira et al., 2012). In this study,
 229 linear coherent noise at later arrival times (>2.0 s) was effectively removed using this method.

230 Surface-consistent amplitude compensation (SCAR) and surface-consistent deconvolution were employed to normalize the
 231 amplitude variability across shot gathers. These steps were followed by a second round of AAA and curvelet filtering to
 232 suppress artifacts introduced during the compensation and deconvolution stages. Dip filtering was also applied to eliminate
 233 spurious hyperbolic arrivals, which were manually identified and removed.

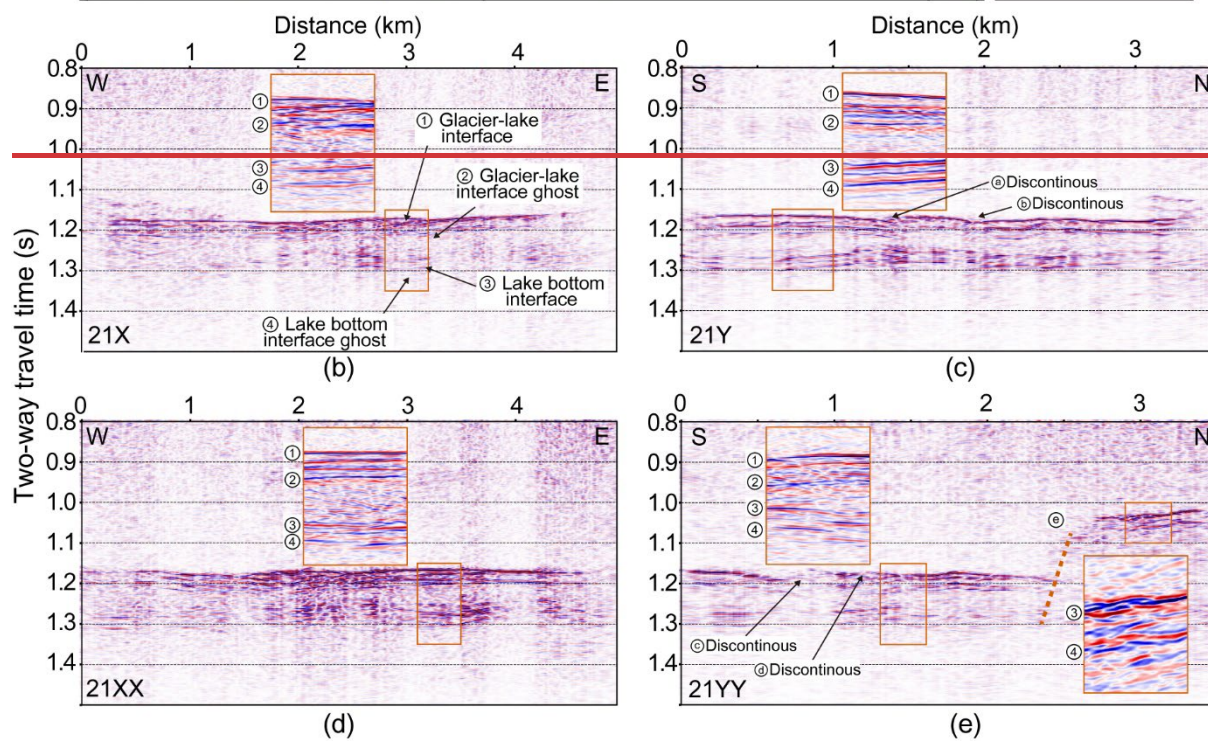
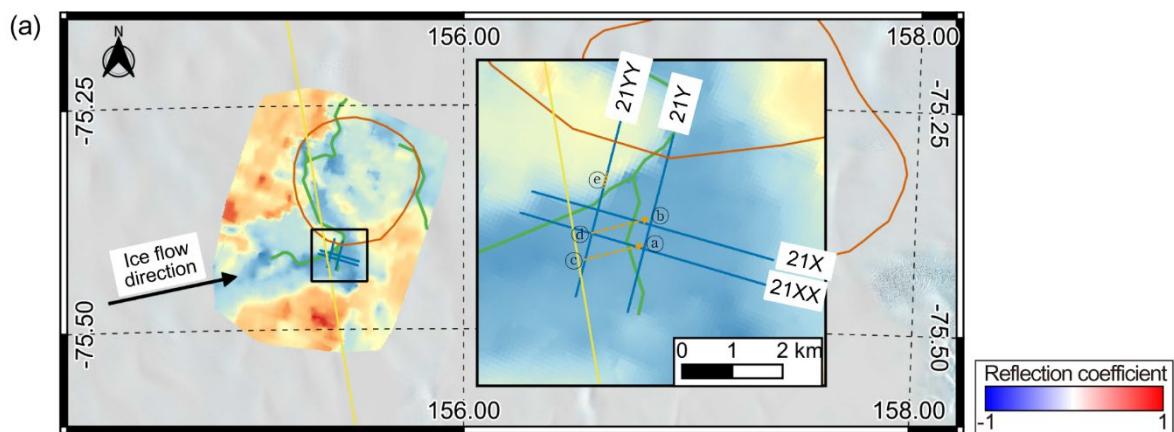
234 Velocity analysis was conducted at intervals of 40 common ~~mid-points~~midpoints to construct a migration velocity model.
 235 Frequency–offset coherent noise suppression (FXCNS) was used to attenuate linear-related noise, followed by Tau-p linear
 236 noise attenuation (LNA), effectively reducing the noise associated with crevasse scattering. The final processing steps included
 237 velocity model refinement, normal move-out (NMO) correction, and ~~pre-stack time migration (PSTM)~~prestack time migration
 238 (PSTM). The specific parameters employed for data processing, as well as the intermediate outcomes at each processing stage,
 239 are provided in the supplementary information (S1).

240 To increase imaging accuracy, a residual static correction was applied before migration using glacier surface elevation data.
 241 The final migrated seismic section was produced using Kirchhoff PSTM. The migrated data has^{ve} a center frequency of
 242 approximately 180 Hz. Assuming seismic wave velocities between 1395 m/s and 3800 m/s, the corresponding vertical
 243 resolutions, which are calculated using the quarter-wavelength criterion, range from approximately 2.01 m to 5.27 m. This
 244 resolution is adequate for imaging SLD2.

245 4 Seismic data processing results

246 Figure 6 presents the PSTM results for the four seismic survey lines. On line 21X (Fig. ~~6b6a~~), a strong, laterally continuous
 247 reflection with reverse polarity is observed at 0.3–4.8 km along the profile, and the two-way travel time (TWT) is
 248 approximately 1.~~49~~15–1.18 s. This reflection is interpreted as the glacier–lake interface (①). Approximately 25–30 ms below
 249 this horizon, a normal-polarity reflection (②) appears, likely representing a ghost signal associated with the primary glacier–
 250 lake reflection. A deeper normal-polarity reflection is observed within ~~2.5~~1.9–3.1 km at TWTs of 1.~~25–1.27~~–1.29 s (③),
 251 which is interpreted as the lake–bed interface. This is followed by a reverse-polarity reflection 25–30 ms later (④), which is
 252 presumed to be the corresponding ghost of the lake–bed interface.

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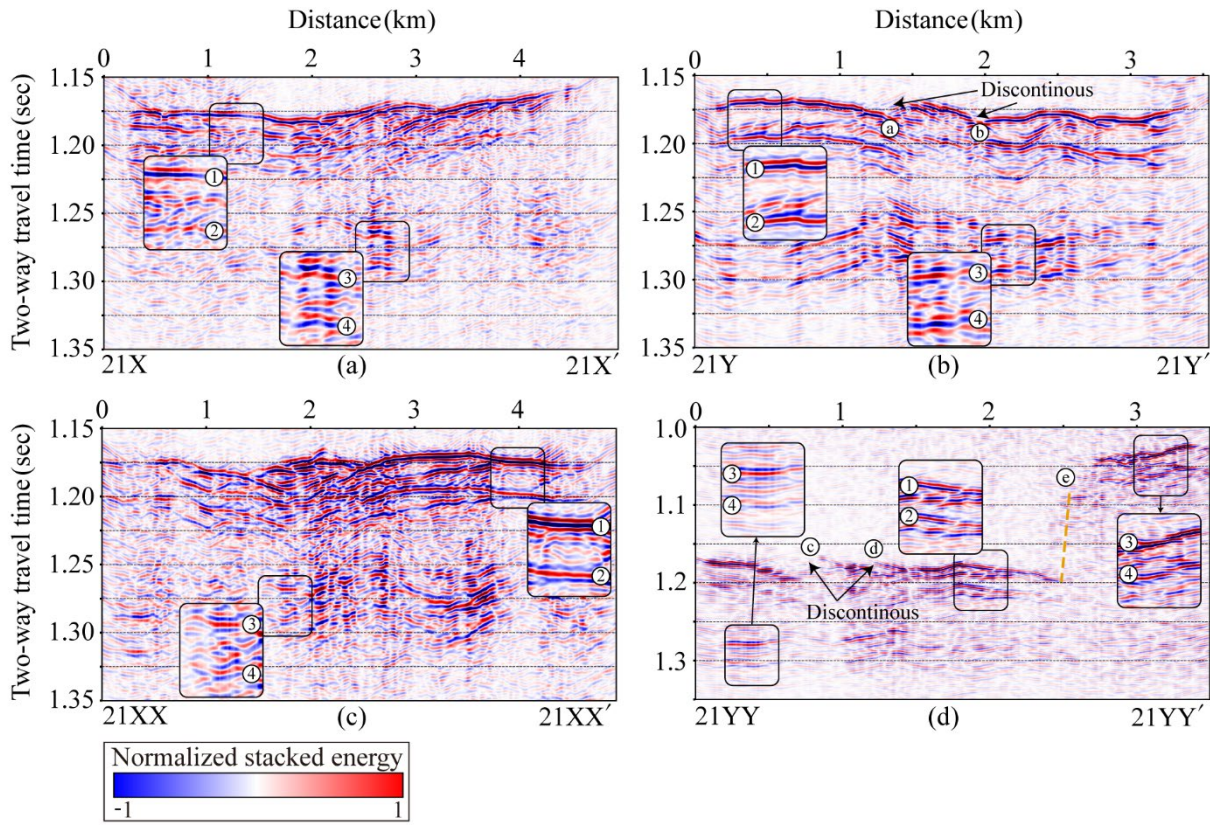


Figure 6: PSTM seismic sections for lines (ba) 21X, (eb) 21Y, (dc) 21XX, and (ed) 21YY prior to ghost removal. Ghost reflections appear 25–30 ms beneath the glacier–lake and lake–bed interfaces due to the 25 m source depth.

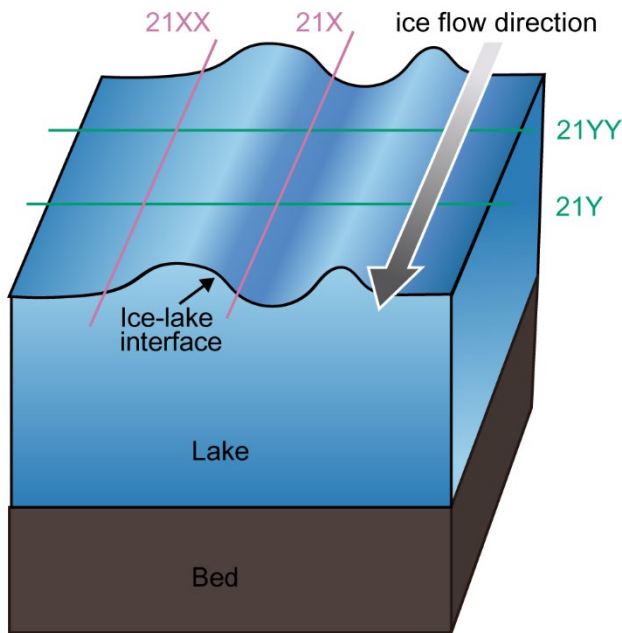
In line 21Y (Fig. 6e6b), similar features are observed. A reverse-polarity reflection, interpreted as the glacier–lake interface (①), is observed within 0.1–3.2 km at TWT 1.4917–1.18 s, with its ghost reflection (②), exhibiting which exhibits normal polarity, appearing and appears 25–30 ms later. A normal-polarity reflection within 0.1–3.2 km at a TWT of 1.26–1.2927 s is interpreted as the lake–bed interface (③), followed by a reverse-polarity ghost signal (④). Additionally, discontinuous reflections interpreted as subglacial scour-like features (SLF) are visible at approximately 1.43 km (a) and 1.9 km (b) along line 21Y at TWT 1.4918 s (black arrows in Fig. 6e6b). These features may be associated with glacial erosion of the underlying substrate.

In line 21XX (Fig. 6d6c), a reverse-polarity reflection, interpreted as the glacier–lake interface (①), is observed within 0–4.23 km at a TWT of 1.4917–1.2018 s. This reflection is followed 25–30 ms later by a normal-polarity reflection (②), which is considered the ghost of the primary glacier–lake interface. Further down the section, a normal-polarity reflection (③) within 1.9–4.2 km at a TWT of 1.2725–1.2928 s is interpreted as the lake–bed interface, followed by its ghost reflection (④) 25–30 ms later.

271 On line 21YY (Fig. 6e6d), the glacier-lake interface (①) is marked by a strong, flat, reverse-polarity reflection at 0–2.4 km
 272 and a TWT of 1.17–1.1920 s, followed by its normal-polarity ghost (②) 25–30 ms below. Lake-bed interface reflections (③)
 273 are observed within 0.42–2.4 km at TWTs of 1.27–1.3029 s, followed by a reverse-polarity ghost (④) 25–30 ms later. Within
 274 2.4–2.55 km and TWTs of 1.08–1.2717 s, no coherent reflection is visible due to the steeply dipping bed topography, as
 275 indicated by the dashed orange line in Fig. 6e6d. Within 2.55–3.54 km and a TWT of 1.0203–1.409 s, a stair-step-shaped
 276 reflection at the glacier-bed interface (③) is identified, followed by its reverse-polarity ghost (④). Additionally, similar to
 277 observations on line 21Y, discontinuous reflections interpreted as ~~seour~~SLF surfaces appear at 0.7 km (C) and 1.2 km (D)
 278 along line 21YY at TWT 1.1918 s (black arrows in Fig. 6ed).

279 The discontinuous reflection signals identified on lines 21Y and 21YY are spatially aligned along the ice flow direction when
 280 projected laterally (Fig. 6a3, dashed orangeblue arrow). This alignment suggests that the observed discontinuities correspond
 281 to a subglacial ~~seour~~SLF surface formed by glacial motion. The ~~seour-feature~~SLF is visible predominantly on lines 21Y and
 282 21YY, which are oriented more perpendicularly to the ice flow direction, thereby enhancing the expression of lateral subglacial
 283 variability. In contrast, lines 21X and 21XX are more parallel to the ice flow, resulting in a foreshortened view of the subglacial
 284 structures and a relatively flat appearance in the seismic sections (Fig. 7).

285



286

287 **Figure 7: Conceptual diagram illustrating the orientation of seismic survey lines relative to subglacial structures and the ice flow**
 288 **direction, explaining the appearance of structural features in each line.**

289

290 **5 Comparison between field data and synthetic seismograms**

291 The depth estimation of subsurface structures from PSTM sections is subject to errors arising primarily from inaccuracies or
292 uncertainties in the seismic velocity model. An inaccurate velocity model may result in erroneous positioning of reflection
293 events, leading to misinterpretation of stratigraphic horizons (Herron, 2000; Yilmaz, 2001). Such limitations are typically
294 mitigated through well-tie analysis, wherein seismic horizons are calibrated against borehole data. However, in the case of
295 SLD2, no borehole data ~~is~~are currently available.

296 We validate the processed field data by performing a comparative analysis with synthetic seismograms to address this
297 constraint. The forward modeling algorithms based on the staggered grid finite difference method in the time domain were
298 used (Graves et al., 1996). The velocity model for this seismic modeling is constructed by structural information given by the
299 seismic migration sections, integrating published values of P-wave velocities for firn, glacial ice, and subglacial water. P-wave
300 velocities in firn vary from 1525 to 3800 m s⁻¹ because density increases with depth (Kirchner and Bentley, 1979; Picotti et
301 al., 2015; Qin et al., 2024). Glacial ice has an average P-wave velocity of approximately 3800 ± 5 m s⁻¹ at -2 ± 2 °C (Kohnen,
302 1974), while subglacial water has a velocity of ~~roughly~~approximately 1396 ± 2 m s⁻¹ at -1.75 ± 0.25 °C, with a salinity less
303 than 1 PSU (practical salinity units) (Thoma et al., 2010; Tulaczyk et al., 2014). Additionally, ~~in~~on line 21YY, the reflection
304 polarity at the ice–bedrock interface is appears as normal, indicating polarity, which indicates an increase in the acoustic
305 impedance. In other words, this suggests that the P-wave velocity of the bedrock is ~~faster~~higher than that of the overlying
306 ~~glacial~~ice. Therefore, the bedrock P-wave velocity was set to 4000 m s⁻¹. Using this information, a layered P-wave velocity
307 model comprising firn, glacial ice, subglacial lakes, and bedrock was developed (Fig. 8). Forward modeling was then
308 conducted using the Ricker wavelet, with acquisition parameters matching those used in the field survey (Table 2). ~~The same~~
309 ~~seismic processing sequence~~We applied ~~to~~just the field data (Section 3.2, Fig. 5) was subsequently applied ~~to~~migration step in
310 ~~case of~~ the synthetic dataset ~~to produce a PSTM image for comparison, as it is free of noise.~~

312 **Table 2: Parameters of the synthetic model.**

Synthetic modeling parameters			
Model size	3.5 km (distance) x 3 km (depth)		
Source	Ricker wavelet (zero–phase), 60 Hz		
	25 m depth, 90-m interval		
Receiver	0 m depth, 15-m interval, 96 channel		
Grid spacing	0.5-m		
Sampling interval	0.1 ms		
Layer parameters	Thickness (m)	Velocity (m/s)	Density (g/cm ³)
Firn	100	1,525–3,800	0.3–0.917
Ice	1,887–2,221	3,800	0.917
Water	0–82±1.3	1,396	1.017
Bed	723–1,113	4,000	2.1

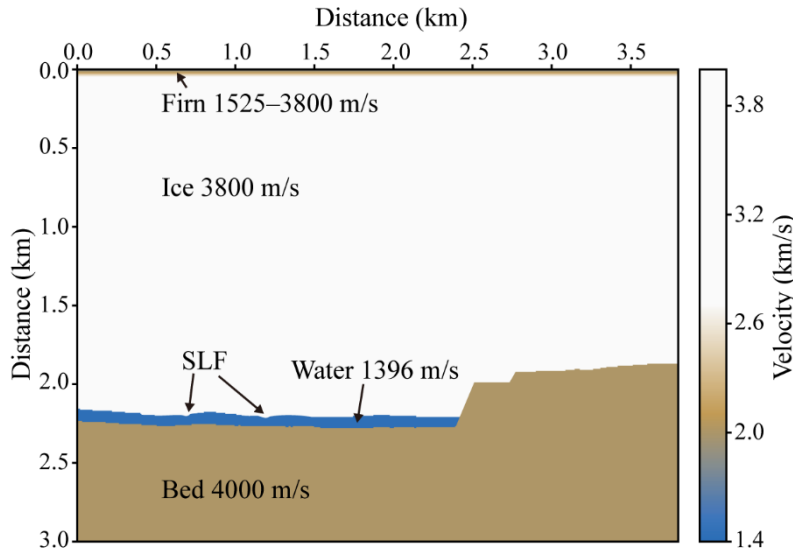
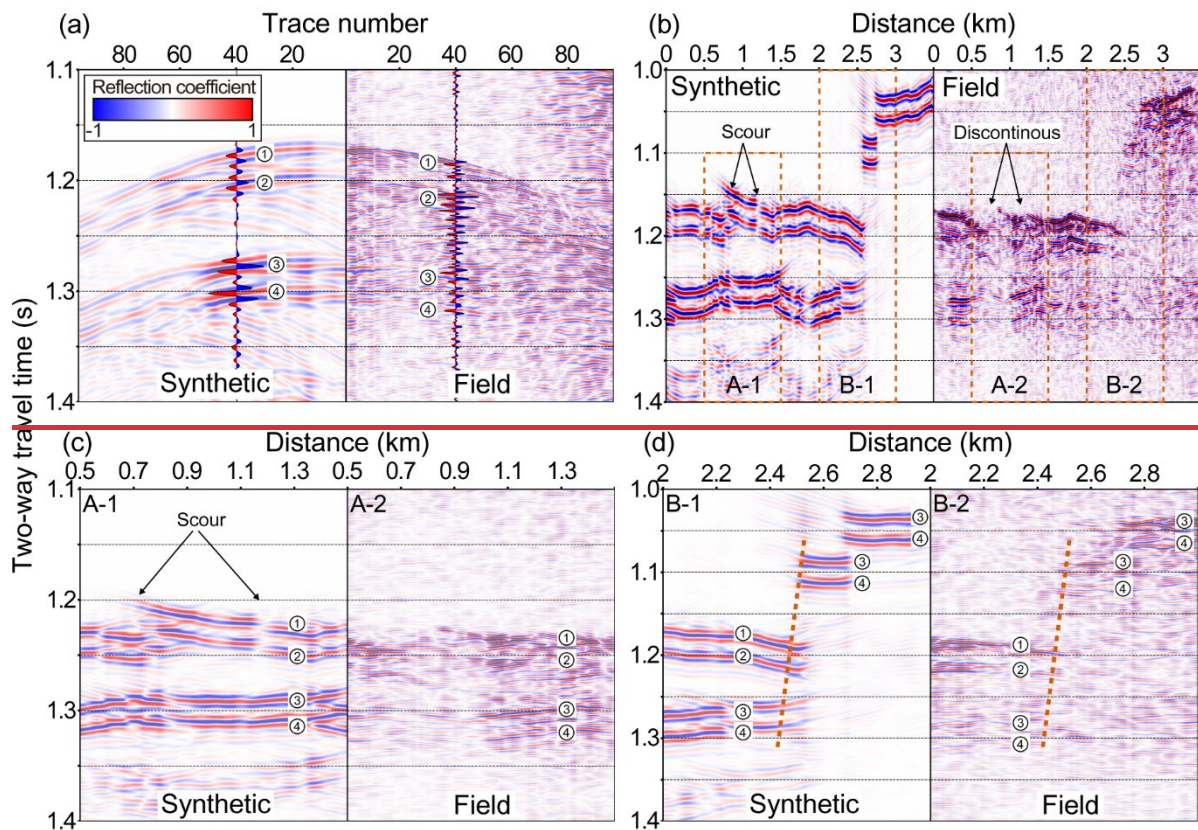


Figure 8: P-wave velocity model used in forward modeling for line 21YY. The upper ~100 m represents firn with velocities ranging from 1525 to 3800 m s⁻¹ (Kirchner and Bentley, 1979; Picotti et al., 2015; Qin et al., 2024). The ice below this depth has a velocity of 3800 ± 5 m s⁻¹ (Kohnen, 1974), and the subglacial water layer has a velocity of 1396 ± 2 m s⁻¹ (Thoma et al., 2010; Tulaczyk et al., 2014).

Figure 9a compares the shot gather from the synthetic dataset (left) and the corresponding gather from seismic data line 21YY (right) at the same location. A prominent reflection at a TWT of 1.17 s is observed in both datasets, corresponding to the glacier–lake interface (①). This reflection results in a high impedance contrast and reverse polarity due to the P-wave velocity difference between glacial ice and water. These features are consistent with previous observations at glacier–lake interfaces (Atre and Bentley, 1993; Brisbourne et al., 2023; Horgan et al., 2012; King et al., 2004; Peters et al., 2007; Woodward et al., 2010). A secondary reflection with normal polarity appears approximately 28 ms after the primary event (②) and is interpreted as a surface ghost reflection. This time delay corresponds to a ~~generating~~ seismic source depth of approximately 25 m, which is consistent with previous seismic analyses (Brisbourne et al., 2023; Schlegel et al., 2024). That is, assuming an average P-wave velocity of 1800 m s⁻¹ within the top 25 m, the TWT of the ghost reflection matches the expected delay:

$$\text{TWT}_{\text{ghost}} = \frac{2 \times 25 \text{ m}}{1800 \text{ m/s}} \approx 28 \text{ ms.}$$



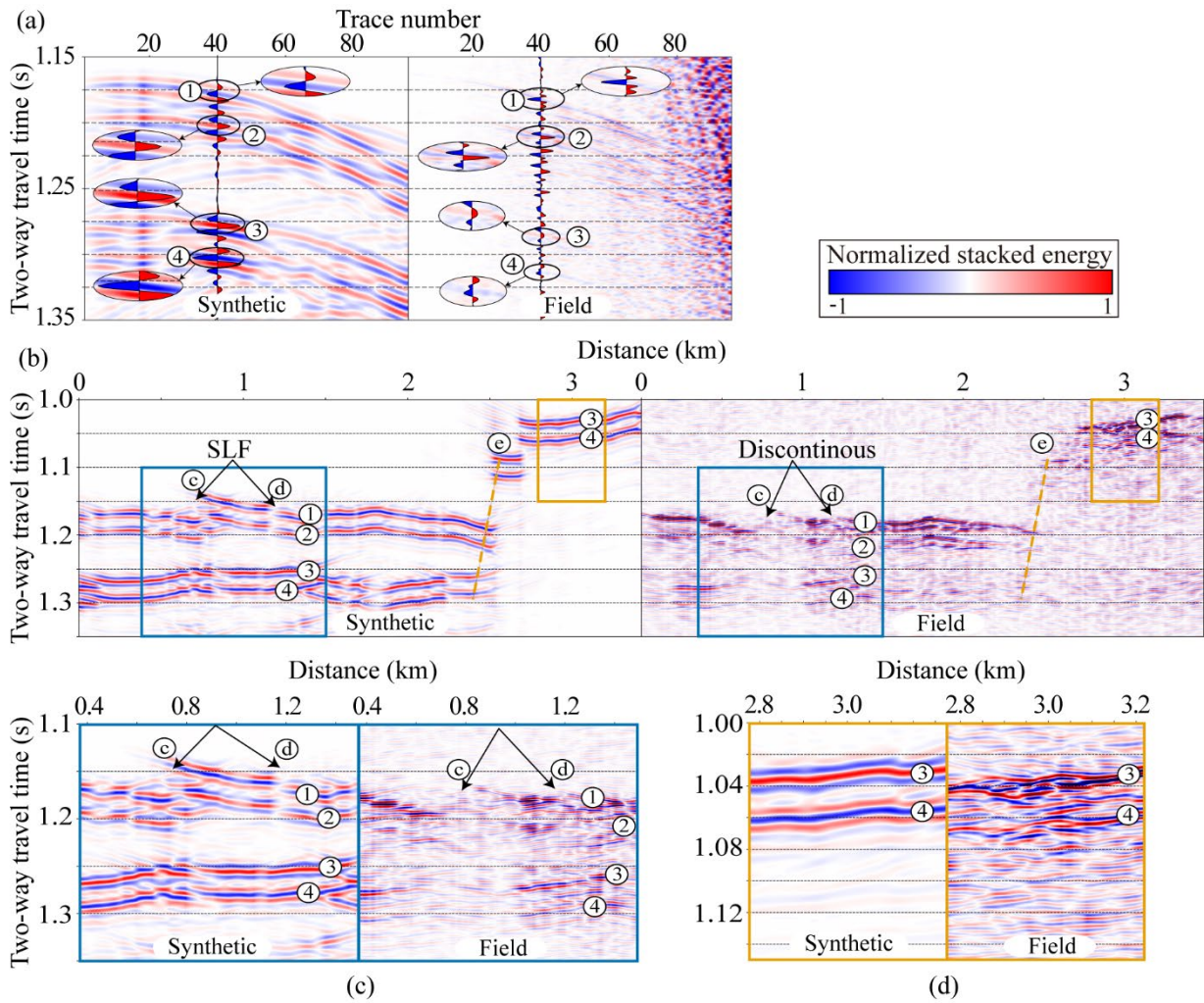


Figure 9: Comparison of synthetic and field seismic data. (a) Shot gather at the same location for synthetic (left) and 21YY field data (right). (b) PSTM images comparison between the synthetic model and the 21YY line. (c) Enlarged views of discontinuous reflections (A-1: synthetic, A-2: field). (d) Comparison of dipping bed reflections (B-1: synthetic, B-2: field), showing shadow zones and steep basal topography.

Furthermore, considering that the acoustic impedance of air is approximately zero ($Z_{air} \approx 0$) and that of ice is Z_{ice} , the reflection coefficient (RC) for an upgoing wave at the air–ice interface can be approximated as follows:

$$RC = \frac{Z_{air} - Z_{ice}}{Z_{ice} + Z_{air}} \approx -1. \quad (1)$$

This implies that the polarity of the ghost reflection at the surface is reversed relative to the downgoing primary wave (Krail and Shin, 1990; Robinson and Treitel, 2008).

Figure 9b compares the PSTM sections of the synthetic model (left) and the field data from line 21YY (right). Unlike the field data, the synthetic dataset is free from ambient noise and features a precise source–receiver geometry, resulting in clearer

delineation of subsurface reflections and facilitating structural interpretation. The synthetic and field PSTM sections exhibit four principal reflection events (①–④) at identical TWTs. Reflections ① and ④ are characterized by reverse polarity, whereas ② and ③ display normal polarity, which is consistent across both datasets. Discontinuous reflections observed in the synthetic model are interpreted as indicative of a subglacial ~~seour~~SLF surface.

Figure 9c provides a magnified comparison of regions ~~A-1~~(synthetic) and ~~A-2~~(field), ~~focusing with a focus~~ on discontinuous features. Although the discontinuous reflections and associated low impedance at 0.7 km and 1.2 km (TWT = 1.4918 s) in the field data (~~A-2~~) are challenging to resolve, the ~~seour~~SLF surface beneath the glacier is imaged in the synthetic section (~~A-1~~).

Figure 9d presents a magnified comparison of regions ~~B-1~~(synthetic) and ~~B-2~~(field) to examine reflections from a dipping bed. Within 2.4–2.55 km and TWTs of 1.0408–1.2717 s, reflections are temporally dispersed, resulting in a shadow zone where coherent signals are absent. From 0.24–2.4 km, a reversed-polarity reflection (①) is observed, whereas from 2.55–3.04 km, a normal-polarity reflection (③) is present. The latter is interpreted as the glacier–bed interface. The dashed line traces the steeply dipping bed geometry, delineating the lake margin, with an estimated dip angle of approximately 52°. The resulting shadow zone is likely caused by the lateral scattering of seismic energy along the steep slope. The comparison of synthetic PSTM sections confirms that the velocity model used for seismic imaging appropriately represents the structures of glacial and subglacial lakes.

To further validate the interpretation, ice thickness estimates from the seismic data were compared with those derived from airborne IPR surveys along four seismic lines (Fig. 10) (~~Frémand et al., 2023;~~ Ju et al., 2024b5). Given the lack of spatial coincidence between seismic and IPR profiles, kriging-based two-dimensional interpolation (Isaaks and Srivastava, 1989) was applied to the IPR dataset to estimate the ice thickness at seismic line locations. The uncertainties associated with the IPR and seismic datasets are ± 20.98 m and ± 5.27 m, respectively, resulting in a combined uncertainty of ± 24.05 m. The root mean square error (RMSE) between the two datasets is calculated as ± 29.4 m, exceeding this expected uncertainty range. This discrepancy is attributed primarily to smoothing effects introduced by interpolation in the IPR data, particularly between 1.7 and 2.6 km along line 21YY, within the light blue shaded area in Fig. 10, where seismic data reveal a significantly steeper basal slope. When this localized region is excluded, the RMSE is reduced to ± 24.8 m, approximating the combined uncertainty. Thus, apart from localized artifacts, the seismic and IPR datasets exhibit strong agreement. This consistency supports the mutual reliability of both methods and validates their integrated application for subglacial lake characterization. Despite localized differences, the overall ice thickness estimates from both datasets are in strong agreement, and this cross-validation reinforces the robustness of the seismic interpretation and affirms the consistency between the two geophysical approaches.

As additional supporting evidence for the ~~eis~~ interpretation, a steeply dipping (approximately 52°) bedrock boundary observed along the 21YY line is consistently identified in both the seismic PSTM profile (Figure 9d) and the IPR-derived ice thickness graph (Figure 10), indicating a similar topographic transition in both datasets. This boundary is interpreted as a structural margin delineating the lateral extent of SLD2 and likely functions as a hydrological barrier. The structural congruence observed in both seismic and radar data underscores the effectiveness of integrating these datasets to delineate the boundaries of subglacial lakes, particularly in regions characterized by complex basal topography.

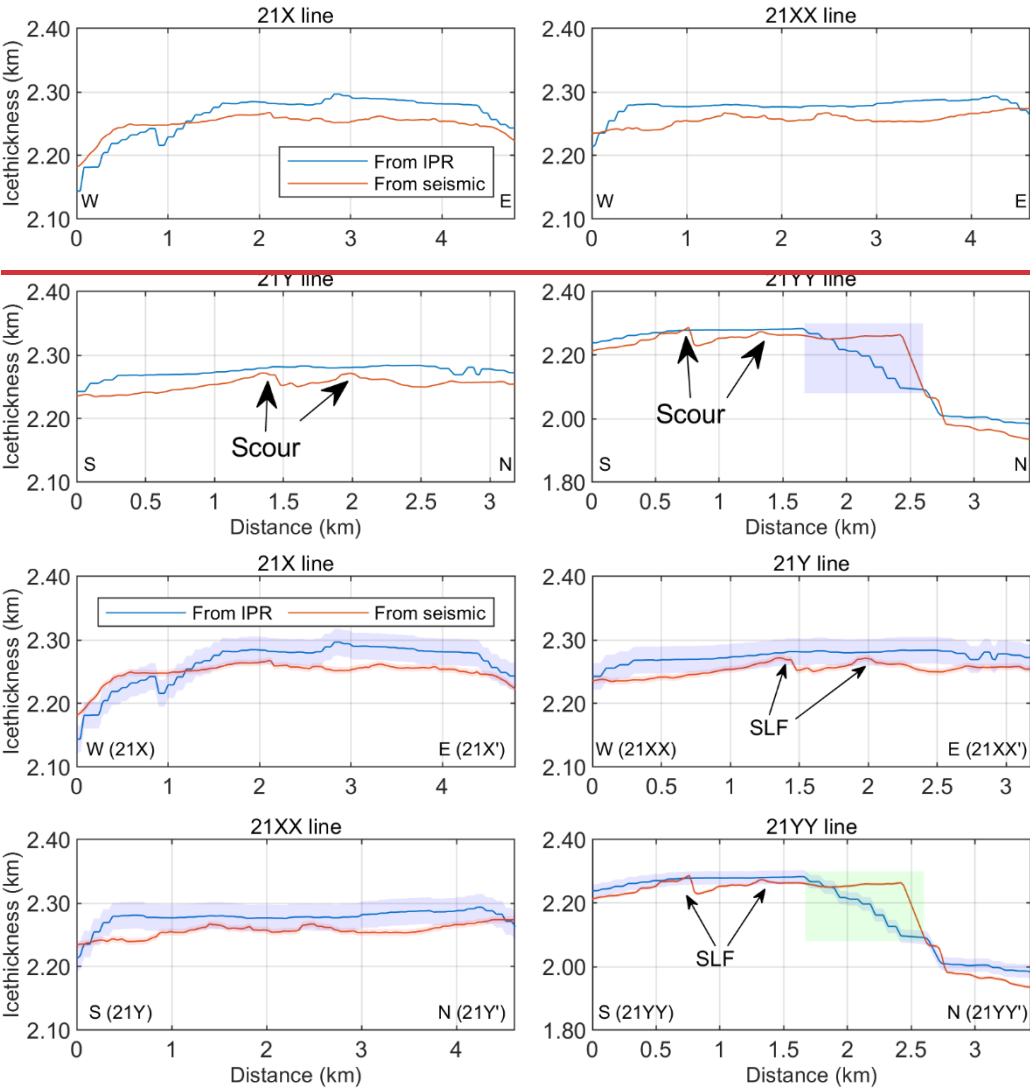


Figure 10: A comparison of ice thickness estimates derived from seismic and kriging-interpolated IPR data (Frémand et al., 2023; Ju et al., 2024b) along the four seismic survey lines reveals high overall consistency between the two datasets, despite localized discrepancies. The light blue shaded region in the 21YY line represents areas where interpolation contributes to the divergence between the two measurement approaches. The light blue envelope represents the uncertainty bounds associated with the IPR-derived estimates, while the light red envelope indicates uncertainty bounds for the seismic-derived estimates.

388 6 Conclusion

389 Since 2016, the [Korea Polar Research Institute \(KOPRI\)](#) has conducted a series of geophysical investigations to study SLD2
390 beneath David Glacier, beginning with airborne IPR surveys. In 2021, a seismic survey was carried out to characterize the
391 internal structure and water column of SLD2. The seismic data revealed strong, laterally continuous reflections with reverse
392 polarity at the glacier–lake interface, whereas normal-polarity reflections were observed at the glacier–bed and lake–bed
393 interfaces.

394 A velocity model was constructed on the basis of seismic interpretation, and synthetic seismic data were generated through
395 wave propagation modeling. A comparison between synthetic and field PSTM sections demonstrated strong agreement in the
396 timing and polarity of major reflection events at the glacier–lake and lake–bed interfaces, confirming the validity of the velocity
397 model. This model estimated the ice thickness and lake water column height to be 2250–2300 m and 53–82 m, respectively.
398 These thickness estimates are in close agreement with independent IPR measurements acquired in 2018; [\(Ju et al., 2025\)](#),
399 further supporting the reliability of the seismic interpretation.

400 In lines 21Y and 21YY, discontinuous reflections were observed near the glacier base. The discontinuous signals are
401 interpreted as ~~seour~~SLF surfaces formed by basal erosion. Structural alignment across multiple survey lines reveals that these
402 features are oriented in the direction of ice flow, supporting the interpretation of glacial erosion processes at the bed.

403 This study demonstrates the utility of seismic surveys for the structural characterization of subglacial lake environments. The
404 integrated analysis of seismic and synthetic data provides quantitative constraints on the geometry of SLD2 ~~beneath David~~
405 ~~Glacier. It offers critical insights for future research and logistical planning, including potential subglacial drilling operations.~~
406 ~~A beneath David Glacier. This study offers critical insights for future logistical planning, including potential subglacial drilling~~
407 ~~operations. Ultimately, this study identifies the area within a 1 km radius of S 75.422°, W 155.441° as a suitable candidate~~
408 ~~site for clean hot-water drilling, given its wide spatial extent, minimum estimated water depth exceeding approximately 50 m,~~
409 ~~and absence of contamination from surface field camps. The site is therefore considered highly appropriate for future~~
410 ~~exploration of active subglacial lakes. Furthermore, we plan to conduct follow-up studies incorporating advanced processing~~
411 ~~techniques such as deghosting, amplitude variation with offset (AVO) analysis, and the development of a refined velocity~~
412 ~~model that accounts for detailed firn-layer properties. These technical advancements are expected to enhance the resolution~~
413 ~~and precision of seismic imaging and contribute to a deeper understanding of the subglacial environment in future~~
414 ~~investigations.~~

415 Data availability

416 ~~The ICESat-2 data used in this study are available from the National Snow and Ice Data Center (NSIDC).~~ The seismic data
417 and ICESat-2 laser altimetry ~~datasets~~data used ~~in this study~~ are ~~also~~ available ~~through~~from the Korea Polar Data Center
418 (KPDC) ~~upon request~~ at <https://dx.doi.org/doi:10.22663/KOPRI-KPDC-00001177>. The maps related to Antarctica were
419 created using the Quantarctica dataset version 3.2 (Matsuoka et al., 2018).

420 **Author contributions**

421 HJ: Writing—original draft, investigation, methodology, conceptualization. SGK: Writing—original draft, methodology,
422 conceptualization, supervision. YC: Writing – original draft, data processing, modeling. SP: Data processing methodology.
423 MJL: Writing – original draft. HK: Hot-water drilling. KK: Investigation. YK: Investigation. JIL: Project administration,
424 Funding acquisition.

425 **Competing interests**

426 The authors declare that they have no known competing financial interests or personal relationships that could have appeared
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434 ~~**Additional information.**~~

435 We name Subglacial Lake D2 Subglacial Lake Cheongsuk (SLC). The name Cheongsuk has a significant meaning, as it is the
436 pen name of Dr. Yeadong Kim, the founder of the ~~Korea Polar Research Institute (KOPRI)~~ and former president of the
437 Scientific Committee on Antarctic Research (SCAR). Dr. Kim personally led the IPR and seismic surveys of Subglacial Lake
438 Cheongsuk and coauthored this paper.

439

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