

Response to reviewer1:

We would like to thank Reviewer 1 for their comments and suggestions. We have addressed them in the new version of the manuscript. Our responses are highlighted below in red following the reviewer comments.

Review comments for “Development and validation of satellite-derived surface NO₂ estimates using machine learning versus traditional approaches in North America”

The study focuses on a current important topic of estimating spatial surface NO₂ using high resolution satellite instruments such as TROPOMI. Authors use an RF based ML approach to derive surface NO₂ and compare these results with the ones derived using the traditional scaling approach, focusing on region of North America. An interesting approach of additionally including model data as training targets to include underrepresented remote areas seems to overcome the typical under-prediction issues of ML models in the background regions. This is clearly depicted in this study and is an interesting find that can help with accurate spatial predictions, not only over urban regions where stations are usually located, but also over rural and remote regions, highlighting the importance of integrating ML, satellite observation and model data. The findings of the study can be of interest to the scientific community working on air pollution.

While the manuscript is generally well-structured, scientifically sound, and includes relevant results and figures, there are a few minor issues to be addressed before it can be accepted for publication. In particular, some sentences would benefit from improved clarity and framing. I encourage the authors to carefully revise the manuscript, especially the sections highlighted below, to better communicate their findings. Furthermore, the manuscript is missing a more focused and detailed comparison between the ML-based and traditional approaches, which forms the main objective of the study.

We revised the manuscript as detailed below. As suggested, we included a more detailed comparison between the traditional and ML approach in the manuscript. See details below.

Specific comments

1. Line 55: Please mention the target spatial resolution of your model somewhere in the methodology.

This is done on L2 data, so the resolution is equal to the resolution of TROPOMI (~5x3.5 km²), additionally we would like to highlight that averaging this dataset (similar as to TROPOMI VCDs are averaged would improve the surface concentrations and reduce the noise). We included the following sentence in the manuscript:

“In this study, we use machine learning models to obtain surface concentrations for each TROPOMI observation (L2) on the same spatial resolution as the satellite observations themselves.”

2. Line 64: The changes in versions of TROPOMI through the years results in some differences between the TROPOMI NO₂ values for high pollution levels. Could you please explain why you choose this version when a harmonized reprocessed version is available?

Version 2 is the latest TROPOMI processing, we use a combination of reprocessed and OFFL (for newer data) which is the same version as RPRO.

3. Line 88: Figure 1 indicates the location of the model parameters as well. Why do you consider the model parameter points over ocean, if you are not predicting there? Will that not impact or introduce some noise into the model as the meteorological conditions over ocean are quite different than over land and hence these datasets can act as noise. Care must be taken to analyze any negative impact of this.

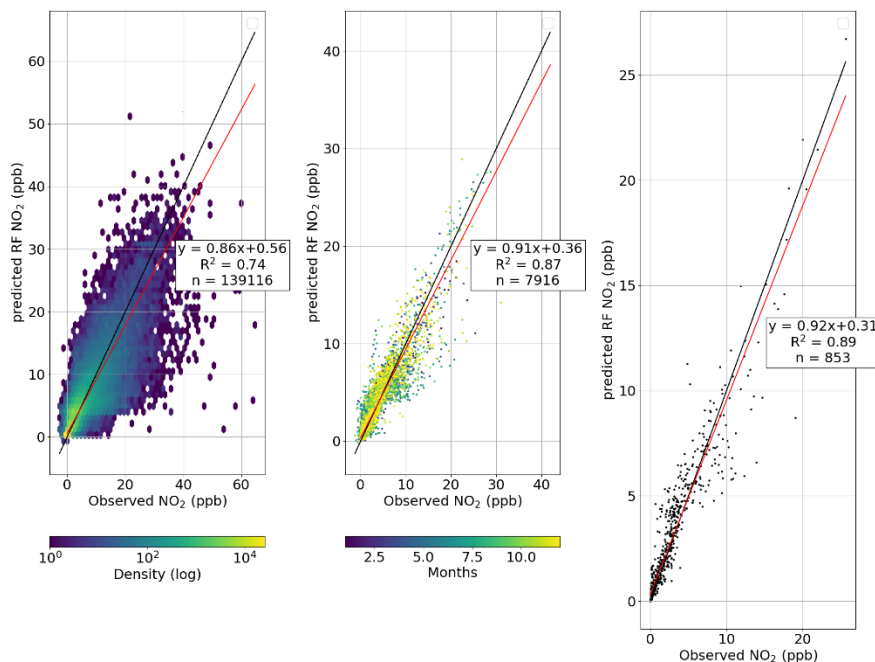
Thanks for pointing this out. Originally, we did not plan to remove the points over oceans, but we have limited ways to verify the random forest surface concentrations over water and were not certain if these RF surface concentrations represent the truth well. There is flexibility to keep the ocean points and evaluate at a later point.

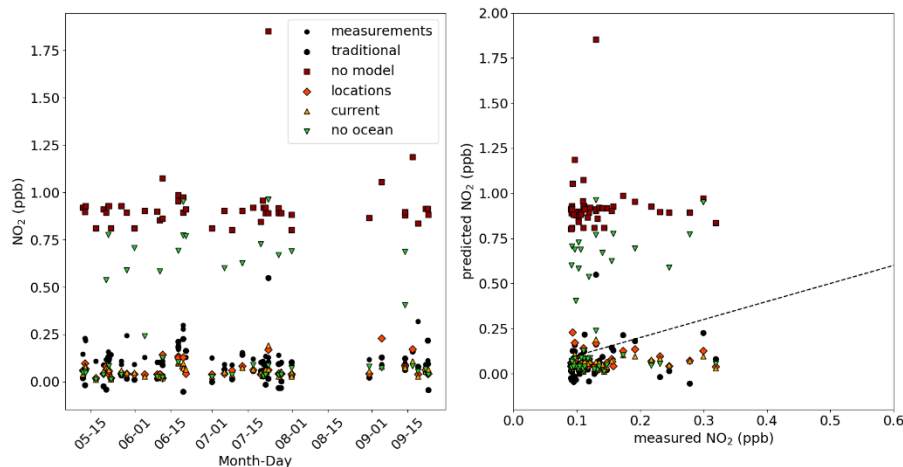
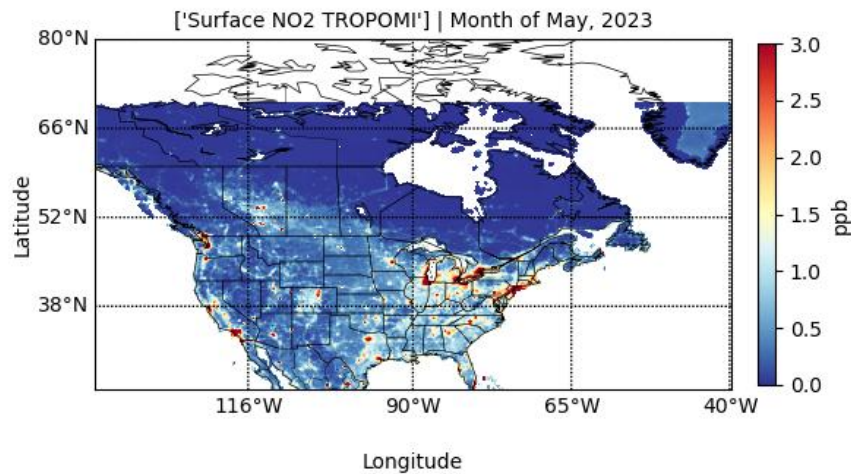
We did a test removing the synthetic stations over the ocean, see figures below. As a result, there are not enough “synthetic” background stations, and the values in rural/northern areas are worse. We created similar figures as Fig. 2, 4, and 5. With points over ocean removed for the training model. In Fig. 2 no significant difference is obvious (this is for all NAPS and AQS stations), however looking at rural stations such as the CAPMoN Pinehouse Lake location, as well as the map, removing the points over ocean performs worse. Alternatively, more “synthetic stations” could be added over land likely resulting in similar results as the original random forest model. Creating these additional datasets for additional “synthetic stations” over land requires a lot of work effort with limited improvement of the end result.

We included the following sentence in the manuscript: “While the surface concentrations are available for each TROPOMI observation, the learning–derived NO₂ surface concentrations over water are not shown here because their validity could not be verified in the absence of monitoring stations.

[....] A similar amount of synthetic background stations as NAPS stations is needed for the machine learning model to improve in background areas. ”

Below are the figures synthetic ocean stations removed.





4. Line 97: Citation required for Random Forest

We included the following citation here: Breiman et al., 2001, Random Forests, Machine Learning, 45, 5-32, <https://doi.org/10.1023/A:1010933404324>

5. Line 100: The logic behind the 0.1 threshold needs a one-liner explanation or a citation

We changed the sentence in the manuscript to:

“The selected hyperparameters are the ones that maximize the average R2 on both the training dataset and the unseen test data while ensuring that the difference between the testing and training R2 is small (indicating that the model has not overfit the training data and generalizes well to unseen data). There is no generally accepted definition of "small" so we chose a threshold of 0.1. At this location in the hyperparameter space, the test R2 value is not very sensitive to small changes in any of the hyperparameters.”

6. Line 123: Please mention a line or two on the data preparation part that includes how and to what resolution the input parameters were gridded or regridded to, since they all are in different spatial resolution? Were there any transformations applied on the datasets to deal with their general skewness? If yes, please mention.

We included the resolution of the dataset in Table 2.

7. In Table 2 caption, please indicate shortly what does the combination daily/midday mean. This helps a reader to gauge all the necessary information from the table, without having to search in the main text. Also, of relevance here is the spatial resolution of input parameters

These parameters change daily, technically all the time, but since TROPOMI only has one value per day at mid-day we take the mid-day point. While other parameters are constant, as indicated in the table. We included the following to make it clearer in the table caption:

“Some parameters are constant while others change hourly, however since TROPOMI only observes at mid-day, only coincident points with the TROPOMI observations are selected and indicated by "daily/mid-day" in the Table below.”

The table also includes now the spatial resolution of the input parameters.

8. Line 130: Why not ERA5-Land for meteorology such as wind and surface pressure which is available at higher spatial resolution than ERA5 and is more relatable to surface variations.

We would like to thank reviewer 1 for this suggestion of using ERA land which is at a higher resolution than ERA5. This is a good idea and we will update to this dataset in our future studies. For this study, however, we originally did not intend to remove the points over water and thus ERA-Land would have been insufficient. At this point including ERA land instead of ERA5 will be a big work effort and we would have to start from the beginning again. We also obtain NO₂ surface concentration information over water, but these were removed in this study because we did not have a way to verify its validity. Considering that the meteorological parameters such as the pressure and wind have very low importance (less than 0.05, see Fig. 3), we do not believe that including ERA5 land will have any significant impact on the machine learning model results. We included the following in the manuscript:

“ERA5 was chosen over ERA-Land (which has the advantage of a higher spatial resolution), because it is available for each TROPOMI observation, and surface concentrations over water could be obtained.”

9. Figure 2: The color scale for density is missing and needs to be added

Thanks for pointing this out. Figure 2 has been changed as suggested.

10. Line 185: How is the feature importance derived here? I suppose, in your case it's from the inbuilt feature importance function from random forest? Please mention this in the methods.

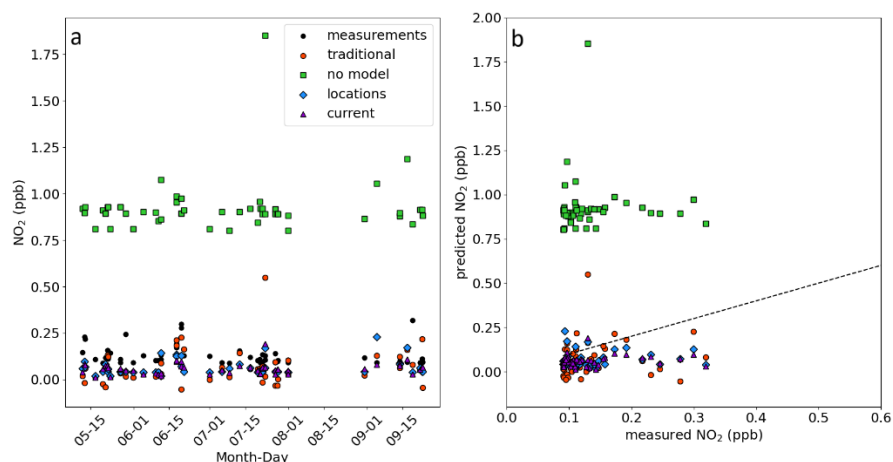
Yes, there is a built-in function that can be used for this. We have included the following in the manuscript: “The results of the feature importance (obtained through an in-built function of sklearn "feature_importances_") are shown in Figure 3 showing...”

11. Line 194: Do you mean “which results in remote areas predicting/computing much higher concentrations than there actually are”? Please check this sentence in terms of phrasing it right

We have corrected this sentence as suggested and included “computing”.

12. Line 205 and 208: Figure 4a and Figure 4b seem to be missing. There is only one figure 4. The black dots mentioned as part of Figure 4a are missing. Please check this result.

Thanks for pointing this out, we included Figure 4 a, somehow this went missing. Please find below the updated figure, which has also been updated in the manuscript:



13. Line 210: Please check the logical flow of this sentence and correct the same. The result is not communicated clearly. Also, it would be good to specify the direction of bias in certain discussions, i.e, positive or negative. Would recommend modifying the sentence into something like “This example highlights the high positive bias when only station measurements are used as random forest predictor. The RF model is unable to predict low concentrations due to lack of low concentration scenarios in the training data”

As suggested, we revised the sentence in the manuscript to:

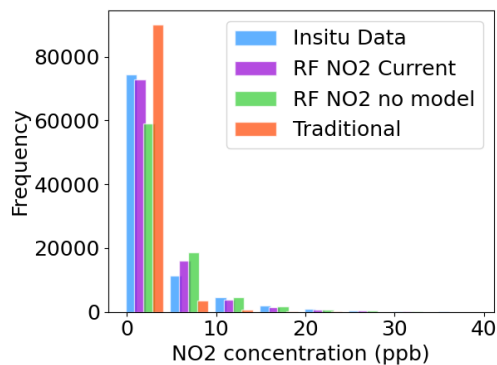
“This example highlights the high positive bias when only station measurements are used as random forest predictor. The RF model is unable to predict low concentrations due to lack of low concentration scenarios in the training data.”

14. Line 210: Does this mean that RF without model inputs, will generally not work well in background locations? How about during low NO₂ periods such as summer over urban regions? ML models usually overestimate low pollution levels and the inclusion of GEM-MACH model in your case, perhaps helps with the overall improvement in accuracy during low pollution levels (even over urban regions) and can also be generalized and stated as such in the study. This will be an important contribution and consider mentioning it after verification.

Yes, the RF does not work well (with just NAPS and AQS stations) in rural areas and background locations, as can be seen in Figs. 4 and 5. Typically the ML models will tend towards mean values and does not predict outliers well. We included the following in the manuscript:

“Generally, the random forest model does not do well predicting extreme concentrations (high and low surface concentrations). Using the additional surface concentrations from the GEM-MACH model helps the prediction in remote areas where surface concentrations are typically low (see further discussion in the next section and Fig. 6). [...] Furthermore, including these synthetic rural stations also helps improve the overall accuracy during low pollution levels, see Fig. 5, shown is the frequency (illustrated in 5ppb bins) of surface concentrations (compared to measurements “Insitu Data”), when synthetic stations are not included the surface concentrations are often overestimated for surface concentrations less than 10

ppb, significant improvement is shown when the synthetic GEM-MACH stations are included otherwise the RF surface concentrations are too high. The traditional method appears to have more frequent points on the lower end (0-5 ppb) compared to the actual measurements.”



15. Line 220: More comparative discussion between Fig 5a and Fig 5b should be included, as this is also the focus as per the title of the paper.

We included another figure showing the frequency of occurrences, including the traditional method, see comment above. We added the following to the manuscript:

“The traditional method appears to have more frequent points on the lower end (0-5 ppb) compared to the actual measurements, showing that the traditional scaling method tends to underpredict the true surface concentrations.”

Also, as suggested we elaborated the discussion on Fig 5 a and b, and included the following in the manuscript:

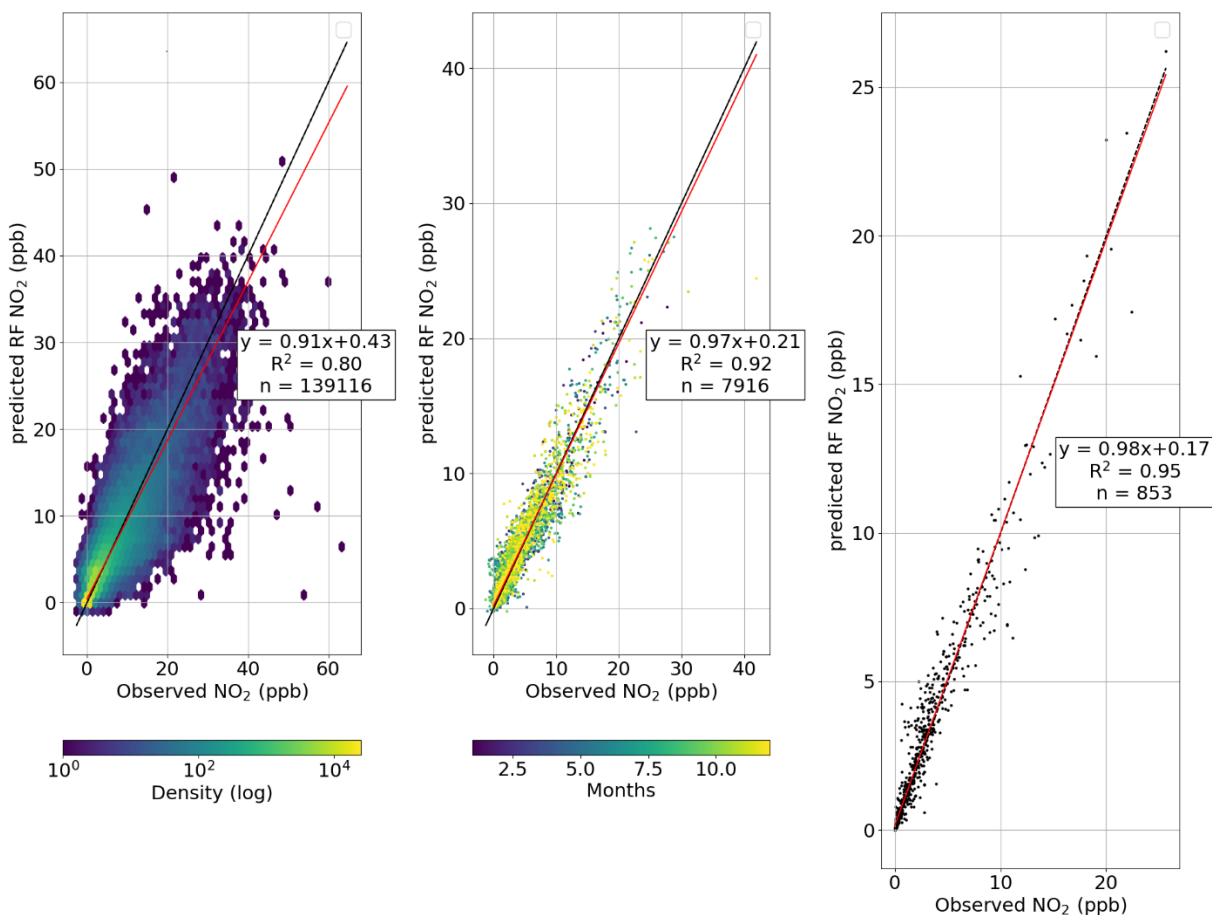
“...lower than the random forest estimated values, especially in sub-urban and urban areas. Compared to the station measurements the traditional method is typically under-predicting and the current version of the random forest model shows are more similar pattern to the actual measurements (see Fig. 5).”

16. Line 225-226. Please highlight in the map by overlaying correlation values or something similar to indicate the data filling capabilities of the model when latitude longitude is included as inputs. Yes, we can see the weird patterns at some locations, but which locations indicate the gap filling capacity is not clear or evident. Currently there is no statistical proof or indicator to show the same. Please consider adding a figure (may be a zoomed in version) or a table with correlation values to indicate this.

We added more details and included a Figure similar to Fig. 2 but also using the location in the training of the RF model:

“However, for specific measurement stations the correlation between the estimated and observed NO2 is much improved when using location information as input parameters the correlation is better when using the location information in the RF model $R^2=0.8$, see Fig. A1, whereas the current version of the

model only achieves $R^2=0.77$)...”



17. Line 240: What is the reason for less accuracy in the traditional approach here?

Relying on model profiles for the scaling, which relies on boundary layer height, emissions, winds... We included more details in the manuscript:

“This highlights the discrepancy of the traditional method that relies heavily on the model profiles and surface concentrations that are used for the scaling. The model profiles and surface concentrations are influenced by the location and magnitude of emissions in the GEM-MACH model, the accuracy of the winds and the boundary layer heights.”

18. Line 243: Looks like authors missed including something after “The observations and”. Please check this.

We revised the sentence and removed “and”.

19. Line 269-270: The authors state that the RF-based current approach performs better than relying on CTM output alone. Where is this conclusion referred to in your result?

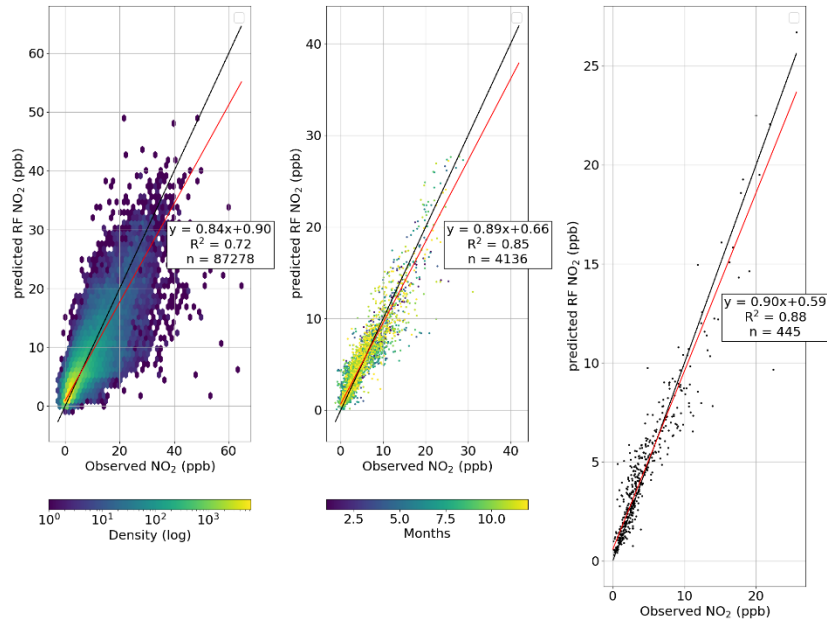
This was a typo, we meant to say:

“... which performs better than the traditional scaling method.”

20. Line 272-273: Does the RF version without the model as input capture these exceedances? It would be interesting to verify if the inclusion of model data is lowering these peak predictions?

No even when the model “stations” are excluded the exceedances are still not captured. There are just not enough exceedances in the training dataset. We included a figure in the appendix showing the random forest (same as Fig. 2) without the “model stations”. We also included the following sentence in the manuscript:

“This is the case for all RF tests performed in this study.”



Looking forward to seeing the revised version of this manuscript with the above changes. I thank the authors for the manuscript and wish them a good luck.

Thank you!