



Quantifying spatial uncertainty to improve soil predictions in data-sparse regions

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Abstract. Artificial Neural Networks (ANNs) are valuable tools for predicting soil properties using large datasets. However, a common challenge in soil sciences is the uneven distribution of soil samples, which often results from past sampling projects that heavily sample certain areas while leaving similar yet geographically distant regions under-sampled. One potential solution to this problem is to transfer an already trained model to other similar regions. Robust spatial uncertainty quantification is crucial for this purpose, yet often overlooked in current research. We address this issue by using a Bayesian deep learning technique, Laplace Approximations, to quantify spatial uncertainty. This produces a probability measure encoding where the model's prediction is deemed reliable, and where a lack of data should lead to a high uncertainty. We train such an ANN on a soil landscape dataset from a specific region in southern Germany and then transfer the trained model to another unseen but to some extent similar region, without any further model training. The model effectively generalized alluvial patterns, demonstrating its ability to recognize repetitive features of river systems. However, the model showed a tendency to favor overrepresented soil units, underscoring the importance of balancing training datasets to reduce overconfidence in dominant classes. Quantifying uncertainty in this way allows stakeholders to better identify regions and settings in need of further data collection, enhancing decision-making and prioritizing efforts in data collection. Our approach is computationally lightweight and can be added post-hoc to existing deep learning solutions for soil prediction, thus offering a practical tool to improve soil property predictions in under-sampled areas, as well as optimizing future sampling strategies, ensuring resources are allocated efficiently for maximum data coverage and accuracy.

1 Introduction

Machine learning (ML) has become an indispensable tool in scientific research, leading to significant advances in many fields, including soil science (Zhang et al., 2022b). Since the early 2000s, ML methods have been steadily integrated into soil mapping



20 (McBratney et al., 2003; Scull et al., 2003; Behrens et al., 2005). Over the past two decades, the use of ML in soil science has grown substantially, reflecting its increasing importance and effectiveness (Minasny and McBratney, 2016; Rentschler et al., 2022; Zhang et al., 2022a; Kebonye et al., 2023; Taghizadeh-Mehrjardi et al., 2024). However, new research challenges have emerged as ML methods become more widely used. One key challenge is improving model interpretability in order to promote scientific knowledge (Padarian et al., 2020). Chen et al. (2022) further added that future research should focus on making
25 the most of legacy datasets, using smarter sampling strategies, improving model accuracy and interpretability, and developing advanced mapping methods to create detailed and high-quality soil maps. In line with this, Bohn and Miller (2024) showed that locally enhanced, bottom-up oriented DSM approach has been shown to deliver higher accuracy compared to both conventional soil maps and global DSM products in many cases.

Using legacy datasets effectively means applying data from already sampled areas to predict conditions in similar but unsam-
30 pled regions. This extrapolation process has been discussed for many years. For example, Lagacherie et al. (1995) pointed out the need to develop self-learning systems that dynamically adapt predictions. Bui and Moran (2003) demonstrated that existing soil maps can be combined with environmental and geological data to extend their usefulness beyond their original boundaries. Additionally, Scull et al. (2005) showed with classification trees that this technique allows soil experts to focus field mapping on unique areas and efficiently extrapolate soil-landscape relationships, making it a valuable tool for soil surveys. Extrapo-
35 lation approaches also address the challenges of traditional soil mapping, which relies on cartographers manually surveying landscapes—a process that is both costly and time-consuming. These methods offer a particularly cost-effective solution for predicting soil classes in regions with limited data, helping to fill the gaps in soil maps and improving the efficiency of digital soil mapping (DSM) (Taghizadeh-Mehrjardi et al., 2022). For example, decision trees demonstrated a 46.00 % overall accuracy for extrapolating soil subgroups using digital mapping methods, making them a cost-effective option for areas with limited data
40 or challenging sampling conditions (Neyestani et al., 2021). Similarly, multinomial logistic regression and classification trees have been used successfully to extrapolate soil classes (Abbaszadeh Afshar et al., 2018; Lemercier et al., 2012; Grinand et al., 2008). To summarize, the increasing adoption of machine learning is driven not only by its relevance to soil science but also by its ability to significantly reduce the effort required for mapping, especially in large or hard-to-access areas (Hewitt, 1993; Grunwald et al., 2011; Stumpf et al., 2017).

45 More advanced methods, in particular Artificial Neural Networks (ANN), have proven effective for extrapolation in soil mapping. For instance, the study by de Arruda et al. (2016) demonstrated the potential of ANNs to produce digital soil maps, providing initial classifications for unexplored areas. Building on this, Coelho et al. (2021) introduced an innovative methodology that combined georeferenced soil profile point data and ANN models for extrapolation tasks. Responding to the growing demand for high-resolution soil maps in, for instance, precision agriculture, environmental management, and land-use plan-
50 ning, ANNs are becoming more and more popular due to their ability to process large amounts of data and provide predictions comparably fast (Haykin, 1998; Schmidhuber, 2015; Silveira et al., 2013). Brungard et al. (2015) demonstrated the superior accuracy of complex models containing neural networks in predicting soil taxonomy classes compared to simpler models. Similarly, Zhu (2000) highlighted the capability of ANNs in generating high-resolution soil maps.



Despite their advantages, one notable challenge is the lack of inherent interpretability (Heung et al., 2016). As “black box” models, ANNs make predictions through complex internal processes that are difficult to understand and interpret. Moreover, ANNs lack built-in uncertainty metrics, making it harder to assess their reliability and potentially leading to misinterpretations and therefore suboptimal decisions (Guo et al., 2017). They often produce overly confident predictions—sometimes reaching 100.00 % certainty—even when the input data is flawed or noisy (Breiman, 2001; Nguyen et al., 2015; Hein et al., 2019). In the context of DSM, this issue is compounded by the broader challenge of quantifying spatial uncertainty in soil maps (Hengl et al., 2017; Wadoux et al., 2020; Rau et al., 2024). For instance, while DSM research is growing in countries like India and Iran, uncertainty mapping remains insufficiently used. In India, only 34.00 % of DSM studies include uncertainty maps, while in Iran, fewer than 20.00 % address uncertainty (Zeraatpisheh et al., 2020; Dash et al., 2022). Typically, these maps then present just an overall accuracy expressed as a single statistical measure, often derived through cross-validation techniques that use a subset of the training data to estimate overall performance uncertainty (Wadoux et al., 2020). Although this approach offers some insight, it falls short, especially for applications involving unbalanced datasets. This gap has led to calls for more detailed uncertainty analysis (Meyer and Pebesma, 2022), particularly for tasks involving extrapolation to new areas because of poor uncertainty performance in such contexts (Grinand et al., 2008). Some recent studies have made strides in incorporating uncertainty quantification. For instance, Carvalho Monteiro et al. (2023) and van der Westhuizen et al. (2023) have demonstrated progress in quantifying uncertainties for Random Forests, while Saygin et al. (2023) have explored the use of ANNs. However, many of these methods rely on variance estimates, which fail to adequately address critical issues such as model overconfidence. This problem has emerged in the study by Schmidinger and Heuvelink (2023) that ANNs produce overly optimistic probabilistic predictions, resulting in low-reliability scores. Additionally, these approaches frequently neglect spatial uncertainty, an essential aspect of practical soil mapping (Li et al., 2023; Bao et al., 2024). These findings underscore the urgent need for methodological advancements that go beyond variance estimation to also tackle overconfidence together with spatial uncertainty (Rau et al., 2024). Such improvements are crucial to ensure that machine learning models for soil mapping provide both accurate and reliable predictions. In this study, we aim to address these challenges by applying an ANN model to predict soil units beyond the known training domain. To quantify model uncertainty at every pixel in the study area, we use the Last-Layer Laplace Approximation (LLLA) (Kristiadi et al., 2020). This approach enables us to identify and correct the overconfidence of ANNs and perform a spatial analysis of the model’s predictions and associated uncertainties. Furthermore, we assess the transferability of the ANN by improving its interpretability and reliability for soil mapping tasks. In doing so, this research contributes to a better understanding of the capabilities and limitations of ANNs in extrapolation and the spatial structure of different domains. Ultimately, our work aims to promote more robust, accurate, and insightful applications of DSM.



2 Material and Methods

2.1 Study area

This study investigates two regions in central Baden-Württemberg, Germany, near the city of Tübingen. The reference area is located northwest of the city, and the target area lies to the southwest, as shown in Figure 1 (A). These regions were chosen because they share similar geology, climate, and cultural development, making them suitable for comparative analysis. The reference area, named after the Goldersbach stream, covers 8.86 km² with an average elevation of 445.51 m above sea level, ranging from 325.31 m to 552.48 m. It represents the lower section of the upstream part of the Goldersbach River and its catchment. The main land use since the 19th century in this area is forestry and since 1972 it has been part of a nature park. The target area, named after the Bühlertalbach stream, is larger, covering 18.5 km² with an average elevation of 498.26 m above sea level, ranging from 388.86 m to 583.04 m. It includes the entire Bühlertalbach stream valley, from its upstream to downstream sections. Similar to the reference area, forestry is the main land use, and this area is extensively used for forest-related activities. Both areas have the same underlying geology, belonging to the Middle and Upper Keuper series, which consist of layers of sandstone, claystone, and marlstone, creating typical soil patterns of the Keuperbergland. The climate in both regions is cool temperate moist, with an average annual temperature between 8.3 °C and 8.7 °C and annual precipitation ranging from 740 mm to 770 mm. The target area was deliberately chosen to be larger, encompassing the entire catchment of the Bühlertalbach River. This strategic decision allows for the investigation of how predictions and findings extend beyond the upstream areas on which the reference area is based. By including the full catchment, this approach provides a broader and more comprehensive understanding of processes in similar but not equal landscapes.

2.2 Data

Figure 1 illustrates the distribution of soil units across the reference area (blue, subfigure (B)) and target area (red, subfigure (C)), with each number corresponding to a specific soil unit and its associated characterization. The classification of the soil types in these units follows the LGRB soil classification system, a local variant of the German soil classification KA5, which is structured around soil formation processes and properties (Ad Hoc-AG Boden, 2005). Within the reference area, there are eight distinct soil units, alongside an urban zone represented as unit 0. In contrast, the target area exhibits greater diversity, comprising 14 unique soil units. A comprehensive description of all these units is provided in Table 1, including their correspondence with the World Reference Base (WRB) soil classification system (WRB, 2022).

For international understanding, we use the WRB classification system. The soil unit maps, initially sourced from the *State Authority for Geology, Mineral Resources and Mining (LGRB)*, were provided in vector format. To facilitate our analysis, these polygons were converted into raster files using a rasterization process based on digital elevation grids. The original map scale of 1:50,000 was rasterized to produce a 10 m × 10 m resolution. To enhance the performance of the neural network and ensure detailed analysis, spatially dense covariate data were required for the entire region. For this purpose, digital elevation models (Figure 1 (A)) were used for both areas. These models offer a 10 m resolution and serve as the basis for calculating topographic indices, also at 10 m resolution. The variable selection was informed by local expert geographical knowledge, guided by

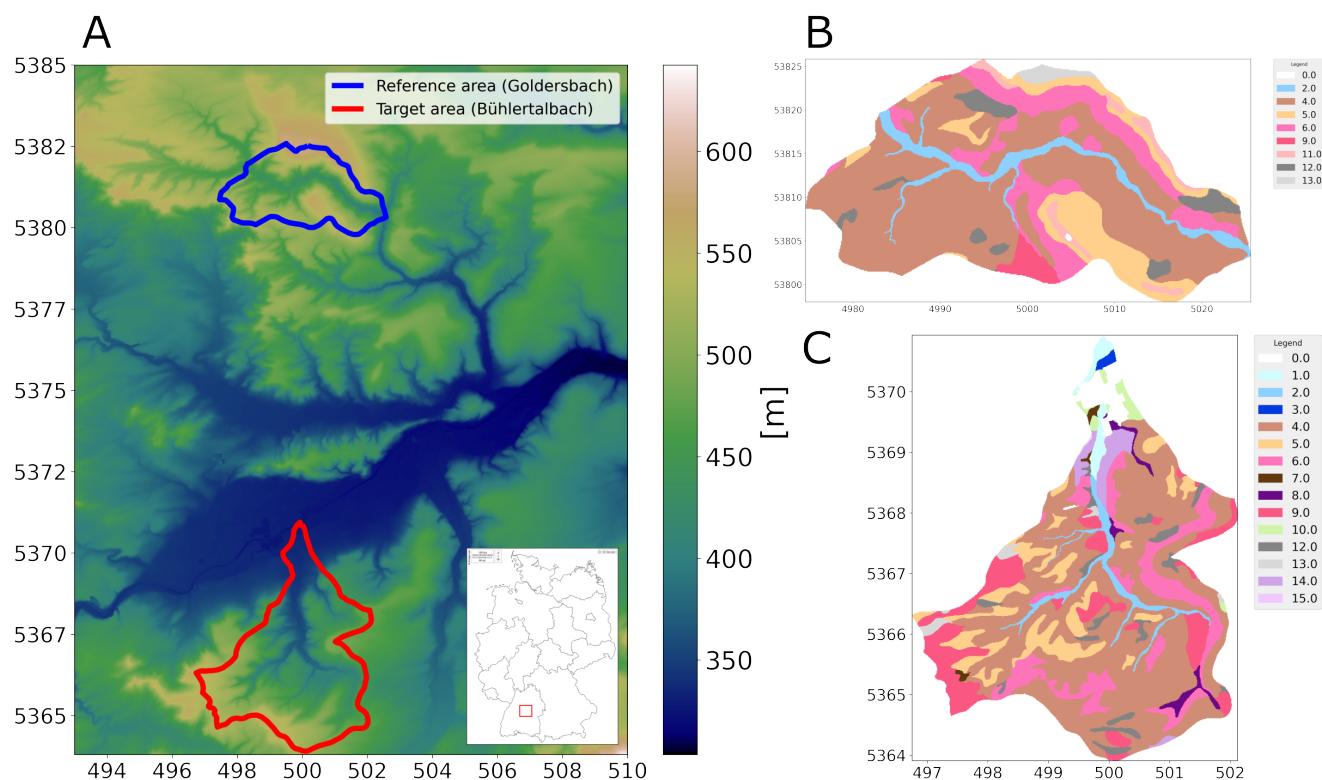


Figure 1. (A) Digital elevation model of the study area with the location of the study area in Germany, reference area in blue, target area in red, (B) and (C) Soil unit maps over the reference and target areas, created by the *State Authority for Geology, Mineral Resources and Mining (LGRB) Baden-Württemberg*.

commonly used proxies representing the SCORPAN model introduced by McBratney et al. (2003), which draws upon Jenny (1941). In addition, we included spectral indices based on satellite data from the *Copernicus Sentinel-2* program. Since 2017, *Sentinel-2* provides data in 13 spectral bands with a 5-day revisit time. For this study, we focused on the visible (R, G, B) and near-infrared bands, which have a 10 m resolution. Using these bands, we calculated indices such as the Normalized Difference Vegetation Index (NDVI) to measure vegetation cover. To ensure robust data representation and reduce the impact of outliers, we computed the median values of these indices for the time series of cloud-free images from March to May 2019. We also included geological maps, scaled at 1:50,000, provided by the *LGRB*. These maps were rasterized in the same way as the soil unit maps. Table 2 summarizes the indices and variables used for the ANN as covariates and their respective references. To compare the covariates in the reference and target areas, we applied the cosine similarity index, as outlined by Manning (2008). This method, which measures similarity on a scale from -1 (completely opposite) to 1 (identical), resulted in a mean value of 0.85 . Using this score confirmed a strong similarity between the areas. In addition, we collaborated with experts from the *LGRB*, whose extensive regional knowledge ensured the appropriate selection of study areas.



Class no.	Label	German Soil Classification	WRB-Classification	Detailed information
0	None	None	None	Ablation, order, settlement
1	A1	Brauner Auenboden, Auenbraunerde	Fluvisol, Cambisol	partly with gleying in the near subsoil, of alluvial sand and alluvial loam
2	A3	Auengley, Auenpseudogley-Auengley, Brauner Auenboden-Auengley	Fluvisol	from alluvial sand and alluvial clay
3	A7	Auenbraunerde, Auenparabraunerde	Cambisol	from older alluvial sediment
4	B2	Braunerde, Pelosol-Braunerde, Pseudogley-Braunerde	Cambisol	from solifluction soils, partly alluvial and flood loam
5	B4	Braunerde, Podsol-Braunerde	Arenosol	mostly podzolic, from sandstone, debris-rich fluvial soils and slope debris
6	D1	Pelosol, Braunerde-Pelosol, Pseudogley-Pelosol	Luvisol-Vertisol	from solifluction soils, subordinate from alluvial debris
7	K1	Kolluvium	Anthrosol	partly over Braunerde and Parabraunerde, from alluvial deposits over solifluction soils
8	K2	Pseudogley-Kolluvium, Gley-Kolluvium	Gleyic Anthrosol	from alluvial deposits
9	L2	Parabraunerde, Braunerde-Parabraunerde, Pseudogley-Parabraunerde	Luvisol	of loess loam and loess-loam-rich solifluction soils
10	L3	Parabraunerde, Pelosol-Parabraunerde, Terra fusca-Parabraunerde, Pseudogley-Parabraunerde	Luvisol	from solifluction soils and slope debris
11	N1	Ranker und Braunerde-Ranker	Leptosol-Cambisol	from sandstone
12	S1	Pseudogley, Braunerde-Pseudogley, Pelosol-Pseudogley	Planosol-Cambisol	from solifluction soils, partly Pleistocene alluvial debris
13	S2	Pseudogley, Parabraunerde-Pseudogley	Planosol-Luvisol	of loess loam and loess-loam-rich solifluction soils
14	Z1	Pararendzina, Pelosol-Pararendzina, Braunerde-Pararendzina	Leptosol-Vertisol	from solifluction soils and slope debris, partly from landslide masses
15	R3	Rendzina und Terra fusca-Rendzina	Leptosol	from river gravels

Table 1. Detailed description of the soil units



Environmental input data		Definition after
Topographic indices	Eastness, Elevation, Northness, Slope	Bauer et al. (1985)
	Diffuse radiation, Direct radiation, Slope discontinuities, Terrain classification index for lowlands	Bock et al. (2007)
	Relative height above the depth line, Soil moisture	Böhner and Köthe (2003)
	Catchment area	Freeman (1991)
	Plan curvature, Profile curvature	Heerdegen and Beran (1982)
	Convergence divergence index, Crest index for lowlands, Crest index for mountain areas, Culmination line for lowlands, Culmination line for mountain areas, Elevation below the culmination line for lowlands, Elevation below the culmination line for mountain areas, Horizontal distance to the depth line, Relative hill slope position for lowlands, Relative hill slope position for mountain areas, Relative altitude, Relief	Köthe and Bock (2006)
	Depth of closed surface depressions	Wang and Liu (2006)
Spectral indices	Brightness index, Colouration index, Hue index, Normalized difference vegetation index, Redness index, Saturation index	Hounkpatin et al. (2018)
Geological variable	Geological map	<i>Department 9: State Authority for Geology, Mineral Resources and Mining (LGRB)</i>

Table 2. Overview of the covariates for the neural network

2.3 Model design

130 Artificial Neural Networks (ANNs) originated in the field of image recognition, particularly for classification tasks (Goodfellow et al., 2016). These models are highly effective at identifying patterns and relationships in data, even without prior domain knowledge, and excel in handling large datasets. ANNs are composed of layers of neurons leveraging activation functions to learn complex patterns. The structure of an ANN can vary widely in terms of its architecture, the number and type of layers, their dimensions, and the activation functions used. Since our research prioritizes understanding uncertainty in machine
135 learning models applied to soil data rather than optimizing model performance, we opted for a straightforward design: a fully connected multilayer perceptron, as described in Table 3. For the hidden layers, we employed the rectified linear unit (ReLU) activation function, which is defined as:

$$\text{ReLU}(x) = \max(0, x)$$

where x is the input to a neuron (Fukushima, 1969; Glorot et al., 2011; Nair and Hinton, 2010). For training and validation,
140 we used data from the reference area, which includes 33 covariates (listed in Table 2) and soil unit labels. The reference area comprises eight distinct soil units, which the model aims to predict. To evaluate the model's performance, we tested it on the ground truth map of soil units from the target area (Figure 1 (C)). The training and validation dataset consisted of 142,569 data points, i.e. the number of raster cells, while the test dataset contained 378,214 data points. We used the architecture mentioned



above. Detailed descriptions of the tuning process can be found in Rau et al. (2024). The optimized hyperparameters derived from this process were successfully transferred and applied to the reference area, yielding excellent results. To enhance the model's robustness and prevent overfitting, we implemented an early stopping criterion. The training process was halted when the model's training accuracy, defined as the percentage of correctly predicted pixels, exceeded 95.00 %, and no significant improvement in test dataset accuracy was observed.

Layer	Number of neurons	Activation function
Input layer	33	ReLU
Layer 1	395	ReLU
Layer 2	510	ReLU
Layer 3	489	ReLU
Output Layer	9	Softmax

Table 3. Architecture of the Artificial Neural Network

2.4 Uncertainty measurement of ANNs with Last-Layer Laplace Approximation

For ANNs commonly the Softmax function in the output layer is used to convert raw scores into a probability distribution over the predicted classes. The Softmax function transforms the output of the previous layer into a vector of probabilities, essentially forming a distribution across input classes. The Softmax function is defined as follows:

$$\text{Softmax}(x_i) = \frac{\exp(x_i)}{\sum_j \exp(x_j)} \quad (1)$$

where x is the vector of raw score for all classes (Bridle, 1990; Goodfellow et al., 2016). These probability values can be interpreted as uncertainty about the classification output. A higher probability indicates greater certainty, while a lower value signifies uncertainty. In other words, the ANN has predicted a class with low uncertainty and is therefore very confident about the prediction. Nevertheless, relying solely on Softmax-derived uncertainty measures has limitations, particularly in regions where the ANN encounters data points far from its training distribution, as they do not account for the uncertainty in the model's parameters or structure (Hein et al., 2019; Guo et al., 2017). To address these limitations and quantify model uncertainty, we employ the Last-Layer Laplace Approximation (LLLA) following Daxberger et al. (2021). This method is based on Bayesian principles and provides a computationally efficient approach to estimate posterior uncertainties for neural network parameters. The LLLA approximates the posterior distribution of the weights as

$$p(\Theta | D) \approx \mathcal{N}(\Theta; \Theta_{MAP}, \Sigma) \quad \text{with} \quad \Sigma := (\nabla_{\Theta}^2 \mathcal{L}(\mathcal{D}; \Theta) |_{\Theta_{MAP}})^{-1}. \quad (2)$$

Here, Θ_{MAP} represents the maximum a posteriori estimate of the last-layer parameters, obtained by minimizing the negative log posterior $\mathcal{L}(\mathcal{D}; \Theta)$, typically the cross-entropy loss with an isotropic Gaussian prior. The LLLA method offers key



advantages: it is computationally efficient by focusing on the last layer (Kristiadi et al., 2020) and has the benefit that the point estimate (Θ_{MAP}) is unaffected by the uncertainty estimation, which simplifies development and tuning. We have shown that LLLA effectively identifies areas of high uncertainty, making it crucial for generating uncertainty maps in tasks like soil classification with uneven training data coverage (Rau et al., 2024).

170 3 Results & Discussion

3.1 Loss and accuracy of the ANN

In our study, we used a simple neural network architecture rather than a highly specialized one tailored to the soil classification extrapolation task. This decision reflects common scenarios where pre-built models are preferred due to their ease of use and quick deployment. Our goal was to assess and enhance the neural network's ability to extrapolate, and not to achieve the highest possible overall accuracy outperforming other state-of-the-art ANNs. For this reason, we focus on the spatial uncertainty at pixel level rather than the total uncertainty of the soil map, which is used in digital soil mapping (Wadoux et al., 2020). The study was therefore based on two different areas: a well-sampled reference area and a completely unsampled target area. This setup simulated a realistic challenge, where models are often required to make predictions in areas with limited or no prior information (Heuvelink and Webster, 2001). The results indicated that the model learned the training data effectively, achieving a low loss value of 0.01, a high training accuracy of 98.57 %, and a validation accuracy of 96.73 %. However, when applied to the target area, the test accuracy dropped significantly to 47.38 %. This decrease was expected since there was no area-specific tuning for the neural network and our target area is substantially larger than the reference area including the entire course of the river. The reference area can thus not fully represent the target area (Warrick, 2001). Compared with other studies in digital soil mapping that use neural networks for soil classification (e.g., Zhu (2000); Behrens et al. (2005); Boruvka and Penizek (2006); Bodaghabad et al. (2015); Neyestani et al. (2021)), our model performed at an average level, consistent with our expectations due to similar parent material and climate as well as cultural development of the areas over the last centuries. These initial findings emphasize the trade-offs between simplicity and predictive performance when using simple neural networks in soil mapping applications. While these are convenient and easy to deploy, their performance is often limited in data-sparse regions. This highlights the importance of complementing neural network predictions with uncertainty quantification to effectively identify data gaps.

3.2 Prediction of the ANN

The prediction of soil units across the target area reveals several notable patterns and challenges when we compare the ANN-predicted map in Figure 2 (A) with our ground truth derived from the *LGRB* in Figure 1 (C). Not all soil units were predicted, which is expected as certain soil units (in that case soil units 1, 3, 7, 8, 10, 14, and 15) were absent from the reference area. The ANN could not predict these soil units due to its lack of training data. This phenomenon is not uncommon in practice, as soil units in complex areas often remain untested in reality (Heuvelink and Webster, 2001). For example, units 1 and 3 belong



to floodplain soils, more precisely to Fluvisols after WRB, and are not included in the reference area. Similarly, soil unit 14, representing soils over the Gipskeuper formation, is also missing. The absence of certain soil units in the training dataset reveals how the neural network handles such cases and provides insight into the associated uncertainty. A detailed breakdown of the soil units is provided in Table 1.

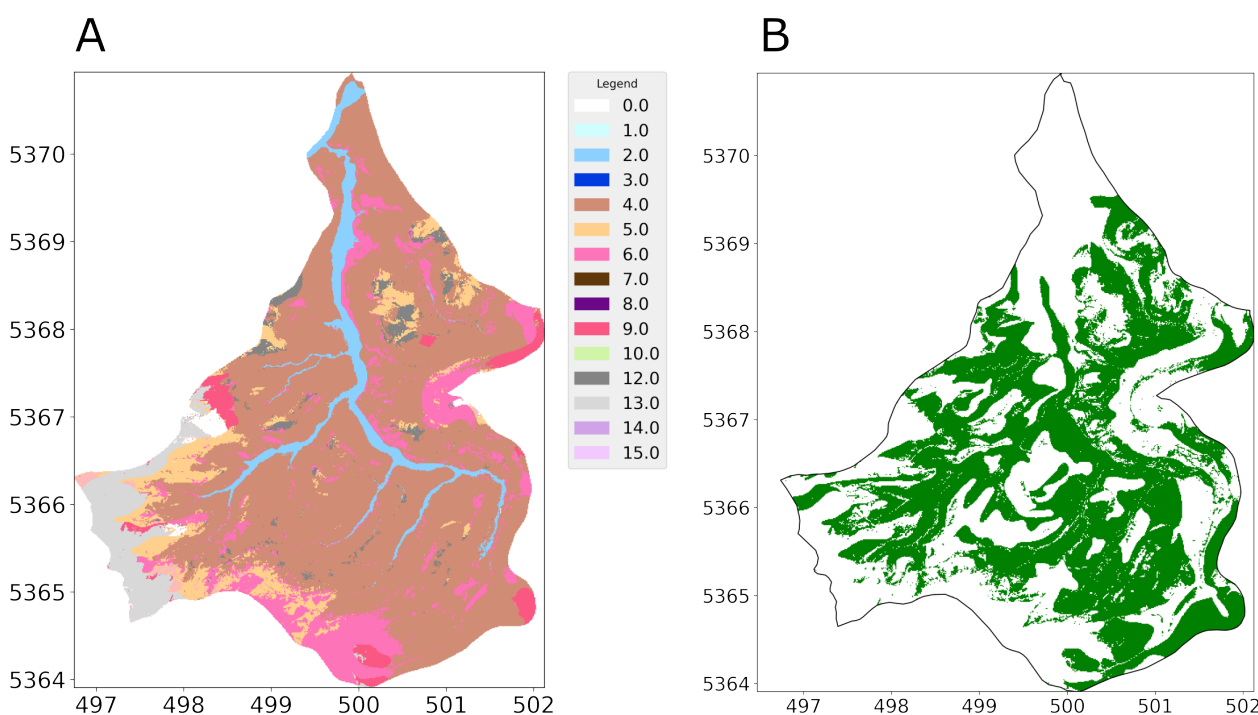


Figure 2. (A) Prediction map of the soil unit in our target area by the ANN, (B) Comparison of the prediction with the ground truth: green means a correct prediction of the soil unit

An overall evaluation of the predictions reveals that certain regions, particularly the northern and southwestern parts of the target area, were predicted wrong (Figure 2 (B)). Interestingly, these areas correspond to the upstream and downstream sections of the river, which were areas not well represented in the reference area. We can see that predictions were more accurate in the middle stream of the river, which closely aligns with the reference area, compared to the downstream and upstream regions. This is likely due to the increasing distance from the training data. A brief and selected breakdown of the prediction of the specific soil units is now given and can be followed with the comparison of the ground truth map in Figure 1 (C) with the prediction of the ANN in Figure 2 (A) and with the confusion matrix in Figure 3.

Unit 0, which represents the settlements, was completely misclassified and often predicted as unit 2 or more often as units 4 and 6. Because unit 0 is found in the river valley and extends towards the receiving stream, these predictions are not surprising. It is interesting to see what happens to soil units 1 and 3, both alluvial soil units, neither of which occur in the reference area. Soil



unit 1, a Fluvisol from alluvial sand and loam, was predicted as soil unit 2, which is the only Fluvisol in the reference area, also from alluvial sand and clay. Meanwhile, unit 3, classified as Cambisol, is often predicted as soil unit 4, representing Cambisol formed from alluvial deposits, which aligns with unit 3's characteristics as a floodplain Cambisol from older sediments. In conclusion, the model's predictions for units 1 and 3 demonstrate its ability to recognize and generalize alluvial patterns, even when specific soil units are missing from the reference data. These results suggest that floodplain soils maintain recognizable characteristics across regions, and the model effectively learns the repetitive patterns of river systems, such as floodplains and channel deposits, during training. Unit 4 is dominant in both the reference and target areas, as confirmed by the ground truth map. Its proportion increased from 51.09 % in the ground truth from the target area to 64.21 % in the prediction by the ANN. However, this soil unit was overestimated in the central region and underestimated in the south, demonstrating the importance of spatial analysis. This is also the case for soil unit 5. This soil unit was underestimated in the central region but correctly identified in the southwest and north. Overestimations occurred in the south, and misclassifications primarily involved unit 4. This can be explained by the fact that both represent the most common soil units in Germany and the domination of 4 in the training data (Amelung et al., 2018; Wiechmann, 2000). As a result, the neural network tends to predict them more often in the output (Johnson and Khoshgoftaar, 2019). Soil unit 6 was also underestimated overall but maintained its proportional representation due to false predictions along the southern margins. The colluvial soil units 7 and 8, were not part of the training set, so they were misclassified as 4 and 6, soil unit 7 specifically as unit 6 in the southwest and unit 4 in the north. Unit 9 was extremely accurately detected in four areas in the south, east, and west but was underrepresented overall. In the southwest, areas belonging to unit 9 were often predicted as unit 13, which is also a Luvisol from loess loam.

The model effectively recognizes familiar soil units, indicating that it successfully learns and applies process-based rules of soil formation, as demonstrated by the predictions for soil units 1 and 3. However, it shows a tendency to generalize soil units based on shared properties, as seen in the misclassification of soil unit 13 as unit 9 due to their similar origin as Luvisols from loess. This suggests the model is adept at identifying broad patterns but lacks sensitivity to regional nuances and finer distinctions between similar units. The substantial regional variability in the predictions highlights the need for spatial uncertainty analyses to improve accuracy and address the model's limitations in handling less common or unfamiliar soil units.

3.3 Confidence of the ANN

Based on the previous results, especially the large distribution of correctly and incorrectly predicted classes in a unit and a non-spatial accuracy of 47.38 %, we now analyze the uncertainty of the ANN prediction of every single soil unit before applying the LLLA. In the case of an ANN, besides cross-validation methods and other techniques, a common step is to evaluate the probability of the predicted class (Wadoux et al., 2020). This probability can be interpreted as the confidence of the model in its predictions, thus the degree of uncertainty of the model regarding the predictions per pixel (see Figure 4 (A)).

Notably, the highest confidence values, often reaching 100 %, are observed at the borders in the south, west, and north, as well as in the central region near the river. In contrast, the intermediate regions display a more diverse confidence distribution, though the values remain generally high. This trend is reflected in the mean confidence value, which stands at 96.22 %. When examining the relationship between confidence and prediction accuracy, it can be seen that in areas where the ANN performs

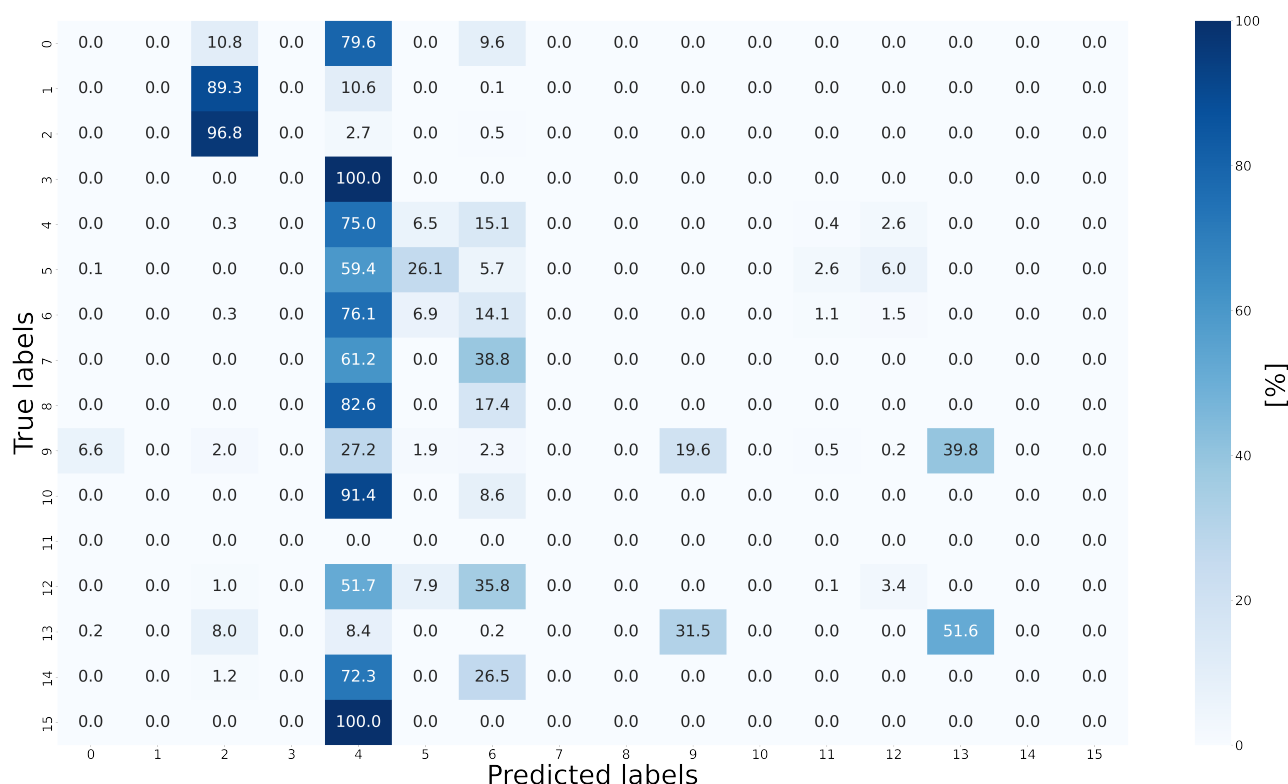


Figure 3. The confusion matrix of the ANN displays true vs. predicted classifications, with diagonal values indicating correct predictions and off-diagonal values showing misclassifications.

poorly, the confidence values paradoxically remain high. This indicates overconfidence in regions, which happens with ANNs when the training data does not represent the target area. For example, pixels where soil units are correctly predicted exhibit a mean confidence of 97.17 %, while incorrectly predicted pixels also demonstrate a high mean confidence of 95.36 %. This pattern underscores the ANN's tendency to assign high confidence to both correct and incorrect predictions, exacerbating the issue of overconfidence. Such behavior aligns with findings from previous studies, which have highlighted the tendency of ANNs to exhibit overconfidence in data-scarce regions (Kasiviswanathan et al., 2018; Hein et al., 2019; Rau et al., 2024).

Further analysis of the confidence distribution for each soil unit is presented using a violin plot in Figure 5. The blue curves represent the distribution of confidence values for each unit, focusing only on soil units present in the reference area, as these are the only ones the ANN can predict. The width of the plot indicates where confidence values are more frequent, and the shape shows the range of these values. For most soil units, there are sharp peaks around 100 %, which means that the ANN is overly confident in all units. However, soil units 11 and 12 stand out, as the ANN also shows high confidence here, but the shape is in a wider range. This analysis highlights the issue of overconfidence of ANNs: here the ANN is too confident, even in areas where it performs poorly. This overconfidence is especially apparent in regions far from the training data or underrepresented

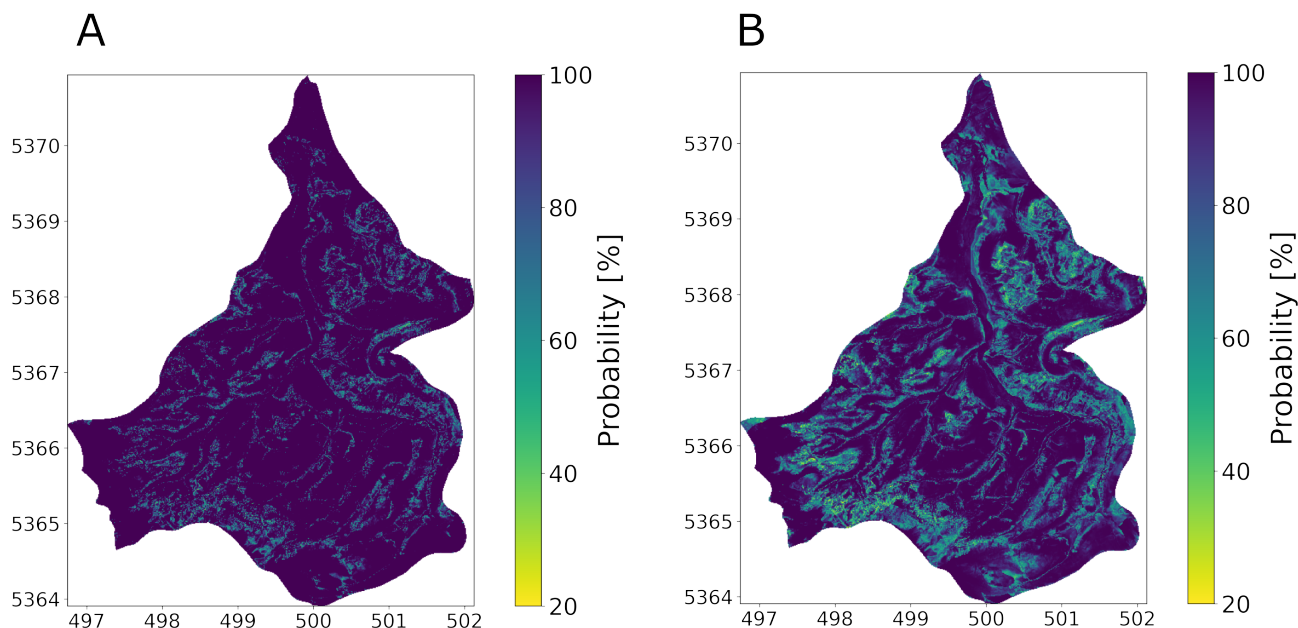


Figure 4. (A) probability of the soil unit in our target area predicted by the ANN calculated with the Softmax function, interpreted as the confidence of the ANN (B) probability after applying the LLLA, interpreted as the uncertainty of the ANN

areas. To improve the ANN's reliability, its ability to estimate its uncertainty needs to be enhanced. Further detailed analysis by soil units will be provided when comparing the ANN's predictions with those after applying the LLLA method as described in Section 2.4.

3.4 Uncertainty of the ANN from Last-Layer Laplace Approximation

As discussed in Section 2.4, the application of the LLLA method enabled us to generate uncertainty estimates for the model predictions, addressing the overconfidence issue typically associated with ANNs (Kristiadi et al., 2020). After applying LLLA, the model's adjusted confidence values are shown in Figure 4 (B), where lighter colors indicate higher uncertainty. Some areas, like the western edge and the river region, showed almost no change, but overall, the average confidence dropped from 96.22 % to 88.66 %. This decrease shows that the LLLA method helped adjust the ANN's confidence to be more realistic. When looking at areas where the ANN made correct predictions, the mean confidence decreased by 5.97 %, so just minor adjustments are needed. A larger reduction can be observed in areas where the predictions are wrong. The mean confidence decreased more, by 9.00 %. This shows that LLLA was effective in reducing the model's overconfidence, especially where it previously made incorrect predictions. Considering spatial differences inside correctly predicted areas, confidence reductions mainly occur along the edges. The opposite is true for wrongly predicted areas, where larger reductions occur more in the

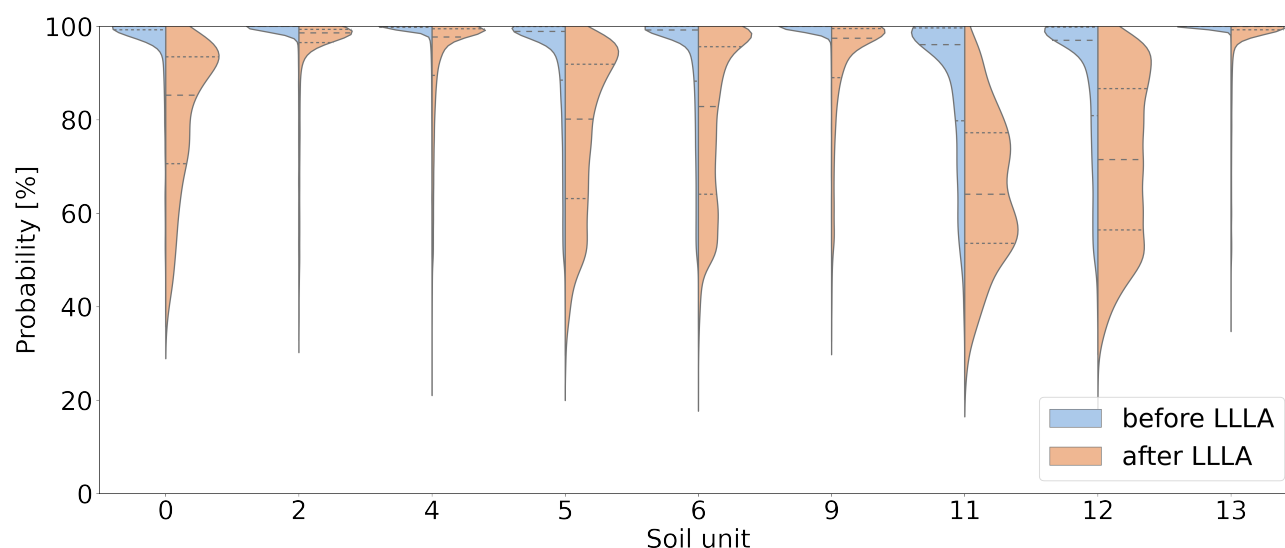


Figure 5. Distributions of the probability of predictions across the soil units (Blue: before LLLA; orange: after LLLA).

center, which is particularly apparent in the northern and southern regions. That indicates, that it is important to look at the spatial variability of the single soil units. A first insight is provided by the violin plot, where the orange-colored part shows the confidence after LLLA. It shows that the spread of confidence values has increased for some soil units, like units 0, 5, 6, 11, and 12. This suggests that LLLA made the model uncertainty more precise for these units. For other units, like 2, 4, 9, and 13, the confidence distribution stayed mostly the same. The highest points of confidence, called peaks, shifted for some units. For example, units 0, 5, and 6 still had high peaks, but units 11 and 12 showed much lower peaks after LLLA. For most other units, the peaks remained high, meaning the ANN stayed confident in its predictions for those units.

Examining the behavior of individual soil units gives further insights. For soil unit 0, which was completely misclassified, the confidence in the areas, where it was predicted, dropped significantly, and the same happened for areas where this soil unit was wrongly predicted. In contrast, soil unit 1, which was mostly misclassified as soil unit 2, maintained high confidence in the correct areas, except for one point in the north, where it was misclassified as soil unit 4. This pattern indicates that when the model predicted soil unit 2, a familiar and similar soil unit, it remained confident, whereas the misclassification to soil unit 4, a less related unit, triggered a higher uncertainty adjustment. This finding indicates that the model is capable of differentiating between plausible misclassifications and more significant errors. A similar pattern is observed with soil unit 3, which was often misclassified as soil unit 4, a closely related soil unit, where the confidence remained high after LLLA. The most extreme example of a plausible misclassification is soil unit 9, which was misclassified as unit 13 for a large area in the west. Notably, there was no reduction in confidence despite the large spatial error, suggesting that the LLLA method failed to detect the misclassification, likely because soil units 9 and 13 are very similar. This highlights a limitation of the LLLA



adjustment when soil units have closely overlapping characteristics, making it difficult for the model to recognize the need for uncertainty in such cases. Soil unit 2, which was well-predicted overall, maintained high confidence in both the correct areas and the false positive areas, where it was misclassified as soil unit 1. In the correct areas, it retained the highest confidence levels of all soil units, indicating that the ANN remained highly confident after the LLLA in its accurate predictions. The behavior of the LLLA for soil unit 4 is more complex. Recall that it was overestimated in the center and north and underestimated in the south. After applying LLLA, the confidence decreased significantly in the central areas, where it was wrongly predicted over soil units 5, 9, and 12, indicating that the model recognized uncertainty in those regions. However, in most of the other misclassified areas, with a small exception in the north, the model's confidence remained high, suggesting that it did not adjust sufficiently for those errors. This lack of uncertainty adjustment could be explained by the large proportion of soil unit 4 in the training data, leading the model to overtrust its predictions for this unit. The model seems to favor overrepresented units, even when faced with evidence of misclassification, which highlights the importance of balancing the training dataset to avoid overconfidence in dominant soil units (Kotzé and van Tol, 2023). The soil units 7 and 8, both absent from the training data, were misclassified as units 4 and 6. However, these misclassifications were detected extremely well by the LLLA adjustment. Initially, the model assigned high confidence to these areas, but after LLLA, the regions corresponding to soil unit 8 showed some of the lowest confidence values. This indicates that LLLA effectively identified areas of high uncertainty, particularly where the model faced unknown soil units, suggesting that the method is highly effective in detecting errors related to unfamiliar inputs. Soil unit 6 was underestimated overall, with false predictions along the southern margins. In the correct areas, where this unit should have been identified, LLLA significantly lowered the confidence, indicating that the model recognized the initial overconfidence. However, in the wrongly predicted areas, the confidence decrease varied spatially. In the south and east, the model remained highly confident, even where soil unit 6 was misclassified as unit 4, showing that LLLA had difficulties detecting the uncertainty of soil unit 4. This is another example of overtrusted predictions of the model in regions where dominant units like soil unit 4 were prevalent in the training set. Conversely, in the center and north, LLLA effectively detected the misclassification, leading to a clear reduction in confidence. In conclusion, the application of LLLA effectively addressed the overconfidence issue of the ANN by providing uncertainty estimates and adjusting confidence levels in both correct and incorrect predictions. The method successfully reduced confidence in misclassified areas, particularly for unknown soil units like 7 and 8, indicating its effectiveness in detecting unfamiliar inputs. However, the results also show regional variability in the uncertainty adjustments. For some soil units, such as unit 4, the model remained overconfident in dominant units, especially for units that were prevalent in the training data. This highlights a limitation of LLLA in handling closely related or overrepresented soil units, emphasizing the need for balanced training data to improve the model's uncertainty calibration and overall robustness. Nevertheless, compared to broader global approaches like Homosoils — where even the study by (Nenkam et al., 2022) acknowledged that model accuracy improved significantly when incorporating local data — LLLA provides a key advantage by offering spatially resolved uncertainty estimates. This allows for more localized and detailed insights into the reliability of predictions, making it a valuable tool for identifying regional variations in model performance and improving uncertainty calibration at finer scales.



4 Conclusion

325 This study explored the use of Artificial Neural Networks (ANNs) for extrapolation tasks in digital soil mapping (DSM) in
under-sampled regions and proposed a novel uncertainty quantification approach using Last-Layer Laplace Approximation
(LLLA). The uneven distribution of soil samples limits the reliability of models when extrapolating to new areas. Our research
addressed this issue by training an ANN on soil data from a reference area and applying it to a similar but unsampled target
area. The results showed that while the ANN could recognize familiar soil patterns, it often produced overconfident predictions,
330 particularly in regions outside the training domain. By applying the LLLA method, we successfully reduced the overconfidence
of the ANN and generated spatial uncertainty estimates. This approach provided more realistic confidence values and identified
regions where the model's predictions were less reliable. Importantly, LLLA was particularly effective in detecting areas
with unfamiliar soil units, reducing confidence in those regions and highlighting the need for further data collection. Our
findings underline the importance of uncertainty quantification in DSM, particularly when using machine learning models in
335 spatially diverse landscapes. While ANNs excel in recognizing patterns and extrapolating soil units, their inherent "black-box"
nature and tendency for overconfidence pose significant risks when models are deployed in new areas. The LLLA method
offers a practical, computationally lightweight solution to address these issues, making it a valuable tool for improving the
reliability of soil predictions. Future work should focus on improving the balance and representativeness of training datasets
to further enhance the accuracy of uncertainty estimates. Additionally, integrating spatial uncertainty maps into sampling
340 strategies can help optimize data collection, ensuring that scarce resources are allocated to regions where the model shows high
uncertainty. This approach will improve both the quality of soil maps and decision-making processes in land-use planning,
agriculture, and environmental management. In conclusion, our research demonstrates that combining ANNs with post-hoc
Bayesian uncertainty quantification techniques can significantly enhance the interpretability, reliability, and transferability of
digital soil mapping models. This advancement is essential for making machine learning models more robust and trustworthy
345 in practical applications, particularly in regions with sparse or uneven soil data.

Code availability. The code used to perform the analyses and generate the results presented in this study is available upon reasonable request
from the corresponding author.

Data availability. The datasets generated and/or analyzed during the current study are not publicly available but are available from the
corresponding author upon reasonable request.

350 *Author contributions.* Kerstin Rau: Conceptualization, Formal analysis, Methodology, Software, Data Curation, Writing - Original Draft.
Katharina Eggenberger: Software, Validation, Writing - Review & Editing. Frank Schneider: Software, Formal analysis, Writing - review &



editing. Michael Blaschek: Data curation, Writing – review & editing. Philipp Hennig: Supervision, Funding acquisition. Thomas Scholten: Writing - Review & Editing, Supervision, Funding acquisition.

355 *Competing interests.* The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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