

1 Synergetic Retrieval from Multi-Mission Spaceborne Measurements
2 for Enhancement of Enhanced Aerosol and Surface Characterization

3
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20 **Abstract.** Atmospheric aerosol is one of the main drivers of climate change. At present time there are Currently, a number of
21 different satellites onin Earth orbit are dedicated to aerosol studies. Due to limited information content, the mainprimary aerosol
22 productsproduct of the most of satellite missions is AOD (Aerosol Optical Depth), while the accuracy of aerosol size and type
23 retrieval from spaceborne remote sensing still requires essentialimprovement. The combination ofCombining measurements
24 from different satellites essentiallyincreases their information content and, therefore, can provide new possibilities for retrieval
25 ofretrieving an extended set of both aerosol and surface properties.

26
27 A generalizedIn this paper, we present the physical basis and concept of the recently developed synergetic approach for aerosol
28 and surface characterization fromusing diverse spaceborne measurements (hereinafter SYREMIS (SYnergetic REtrieval from
29 Multi-MISSion instruments) approach). The approach was developed onimplemented in the basis of GRASP (Generalized
30 Retrieval of Atmosphere and Surface Properties) algorithm (SYREMIS/GRASP approach). The concept was applied andand
31 has been tested on two types of synergetic measurements: (i) synergy fromof polar-orbiting satellites (LEO+LEO synergy
32 combining Sentinel-5P/TROPOMI, Sentinel-3A/OLCI, and Sentinel-3B/OLCI instruments), (ii) synergy fromof polar--

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33 orbiting and geostationary satellites (LEO+GEO synergy). On based on Sentinel-5P/TROPOMI, Sentinel-3A/OLCI, Sentinel-
34 3B/OLCI, and Himawari-8/AHI instruments). On the one hand, such a synergetic satellite constellation extends the spectral
35 range of the measurements. On the other hand, it provides unprecedented global spatial coverage with high temporal resolution,
36 which is crucial for a number of climate studies.

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38 In this paper we discuss the physical basis and concept of the LEO+LEO and LEO+GEO synergies used in GRASP retrieval
39 and demonstrate. It is shown that the SYREMIS/GRASP approach allows facilitates the transition transfer of information content
40 from the instruments with the richest richer information content to the instruments those with lower one content. This results in
41 the substantial enhancements in aerosol and surface characterizations characterization for all instruments from within the
42 synergy.

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43 **1 Introduction**

44 Number of Many climate studies require the global extended aerosol and surface characteristics on the global scale, including
45 such properties such as Aerosol Optical Depth (AOD) and size distribution, Single Scattering Albedo (SSA), full surface Bi-
46 Directional reflectance Bidirectional Reflectance, Distribution Function (BRDF), etc. This is particularly relevant for the
47 generation of the high-quality aerosol and surface Essential Climate Variables (ECVs), characterizing which characterize the
48 Earth Earth's climate system, as well as for air-quality monitoring, aerosol emission and transport studies, etc. (Dubovik et al.,
49 2008, 2021b; Martin, 2008; Hollmann et al., 2013; IPCC, 2021; Chen et al., 2019, 2022a). In addition to the global scale, the
50 high temporal resolution of the extended aerosol properties is required for such important but challenging studies as aerosol-
51 cloud interactions, gas-to-particle transformation, and atmospheric aerosol dynamics etc. (Pöschl, 2005; Rosenfeld et al.,
52 2023; Vehkamäki and Riipinen, 2012).

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53
54 The global Global information about aerosol aerosols can be obtained from spaceborne measurements. Therefore, climate
55 studies are becoming more and more relying on the increasingly rely on high-quality aerosol characterization from space. At
56 present time, there are many different satellites on in Earth orbit dedicated to aerosol characterization. Nevertheless, due to
57 the their limited information content, the main primary aerosol product of most satellite missions is AOD (Remer et al., 2005;
58 Levy et al., 2013; Sayer, 2018b; Sogacheva et al., 2020), while the accuracy of the extended properties with high temporal
59 resolution still requires essential improvements improvement. To address this problem, several main requirements on the for
60 satellite measurements have been formulated from based on the general principles of light scattering theory and atmospheric
61 dynamics studies (Van der Hulst, 1957; Tsang et al., 1985; Bohren and Huffman, 1998; King et al., 1999; Mishchenko et al.,
62 2002; 2004; Hasekamp and Landgraf, 2007; Hasekamp et al., 2011, 2024; Lenoble et al., 2013; Dubovik et al., 2011, 2019;
63 Remer et al., 2024). In particular, such measurements should include:

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64 (i) ~~multi~~Multi-angular measurements in a wide range of scattering angles where the differences between ~~the~~ angular
65 dependence of aerosol and surface signals can be observed, and ~~the~~ angular sampling is ~~enough~~sufficient for aerosol
66 characterization;

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67 (ii) ~~measurements~~Measurements in a wide spectral range (preferably from ~~Ultra-Violet~~the Ultraviolet (UV) to ~~Short~~
68 ~~Wave~~Shortwave Infrared (SWIR) ranges) to take advantage of ~~the~~ different spectral dependence of aerosol and surface signals
69 and to observe spectral features of different aerosol species;

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70 (iii) ~~polarimetric~~Polarimetric measurements to ~~gain advantages of~~exploit differences in the polarization signatures of aerosol
71 and surface signals and ~~the~~ strong dependence of such measurements on microphysical properties of ~~aerosol~~aerosols;

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72 (iv) ~~frequent~~Frequent temporal measurements to account for the temporal variability of aerosol properties, as well as
73 differences in aerosol and surface conditions;

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74
75 ~~The conditions~~Conditions (i)-(iii) are substantially covered by Multi-Angular Polarimetric (MAP) spaceborne missions such
76 as, for example, POLDER-3/PARASOL mission, ~~which~~ ended in 2013 (Deschamps et al., 1994; Tanré et al., 2011), or ~~the~~
77 ~~new missions~~, like PACE (with HARP-2 and SPEX instruments ~~onboard on~~ board), MetOp-SG 3MI, and CO2M MAP, ~~etc.~~
78 (Dubovik et al., 2019; Hasekamp et al., 2019; ~~McBride et al., 2024; Werdell et al., 2024; Fu et al., 2025~~); Sienkiewicz et al.,
79 ~~2025~~). Nevertheless, each of ~~these~~spaceborne instruments ~~alone~~, including MAP, still has ~~a number of~~limitations related
80 to ~~their~~their spectral/spatial coverage, ~~spectral and spatial resolutions, etc. and/or resolution~~. Moreover, most ~~of the low~~polar-
81 orbiting satellites have a relatively low ~~frequency of the revisiting time~~frequency (a few times per day or less), which is ~~not~~
82 ~~enough to study~~insufficient for studying physical ~~and~~, chemical, ~~and~~ dynamic processes in the atmosphere with ~~the~~required
83 temporal resolution of one hour or even better.

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85 Strictly speaking, none of the currently operating and future aerosol-oriented satellite instruments alone ~~meets~~completely meet
86 ~~all the above-mentioned~~requirements (i)-(iv). The solution to this problem has been discussed for a long time
87 and is based on the synergetic retrieval of ~~the~~combined measurements from different sensors (Aires et al., 2012; Holzer-Popp
88 et al., 2008; Vanhellefont et al., 2014; Wang et al., 2014; Lee and Ahn, 2021). Indeed, ~~the~~different satellites dedicated to
89 atmospheric studies may have ~~different~~varying spectral coverage and resolution, ~~overpass~~observe the same ~~certain~~area on
90 Earth's surface ~~during on~~ the same day but at different times or ~~different~~relative positions. As a result, ~~being when~~ properly
91 collocated and combined, such measurements can provide multi-angular, multi-temporal measurements in an extended spectral
92 range, satisfying ~~the~~requirements (i)-(iv).

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94 Despite the known ~~recipe, the approach~~, a generalized synergetic retrieval ~~approach~~method applicable to diverse multi-
95 instrument L1 measurements (L1 synergy) has not ~~yet~~been developed ~~yet~~. The problem is ~~rather~~algorithmic ~~rather~~ than
96 engineering ~~since to gain advantages of~~. To ~~exploit~~the combined L1 synergetic measurements, the retrieval algorithm must
97 satisfy the following conditions;

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98 (v) The retrieval should be based on an advanced inversion approach and flexible forward models adaptable to the information
99 content of the measurements;

100 (vi) The retrieval should be able to account for diverse measurements with possibly, potentially, different calibration accuracy,
101 different spectral, and spatial resolution; resolutions;

102 (vii) The algorithm should be able to account for the multi-temporal (not collocated in time) measurements;

103
104 A number of advanced Many retrieval algorithms can fit themet requirements (v) and (vi), resulting in the synergetic
105 approaches for collocated in time satellite measurements, for example, Examples include the synergy of MERIS and
106 AATSR from the ENVISAT platform (North et al., 2008), the synergy of OCLIOLCI and SLSTR from the Sentinel-3 platform
107 (Henocq et al., 2018), and the PMAP synergetic algorithm for GOME-2, AVHRR, and IASI on the MetOp platform
108 (Grzegorski et al., 2021). Nevertheless, the correct treatment of the observations whichthat are not collocated in time is still
109 beyond the capacity forof most of the existing algorithms. Since theacrosol properties of aerosol do not change randomly in
110 time and space but rather show, showing temporal and spatial correlations due to atmospheric dynamic processes, accounting
111 for such temporal dependencies is crucial in the synergetic retrieval.

112
113 The temporal (as well as spatial) dependences between the characteristics of aerosol or surface are accounted for in Here, we
114 use the GRASP (Generalized Retrieval of Atmosphere and Surface Properties) algorithm with multi-temporal and multi-spatial
115 smoothness constraints (Dubovik et al. 2011, 2014, 2021a), which has emerged from the successful heritage of AERONET
116 retrieval developments (Dubovik and King, 2000; Dubovik et al., 2000, 2002; Dubovik, 2004) and pursues the idea of creating
117 a scientifically rigorous and versatile algorithm. As a result, GRASP has significantly extended capabilities and areas of
118 applicability. In particular, it can be applied to diverse remote sensing observations (passive, active, ground-based, satellite, in
119 situ, etc.), can simultaneously retrieve a large number of different atmospheric characteristics, and is well-optimized for
120 synergetic retrievals. This has been achieved by pursuing the following generalization principles:

- 121 - The two main modules of the algorithm, the “Forward model” and “Numerical Inversion,” are independent. This
122 allows for continuous development and extension of all functionalities of both modules without compromising
123 previously established applications.
- 124 - The “Forward model” provides consistent modeling of all observations to which GRASP can potentially be applied.
- 125 - The “Numerical Inversion” is general and flexible enough for inverting different observations and retrieving all
126 atmospheric and surface parameters that affect those observations.

127
128 GRASP relies on a statistical optimization approach based on the Multi-Term LSM (Least-Square-Method) (e.g., Dubovik et
129 al., 2021a). This approach, in contrast to the more common Optimal Estimation (Rodgers, 2000), emphasizes the use of
130 multiple a priori constraints. Indeed, the retrieval of most atmospheric parameters from remote sensing observations is an ill-
131 posed problem, and the use of a priori constraints is necessary for successful retrieval. However, such constraints can be very
132 different for various retrieved atmospheric characteristics (e.g., aerosol size distribution, vertical profile, index of refraction,

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133 surface reflectance parameters). A single constraining approach (such as the direct use of a priori estimates for each retrieved
134 parameter) is not optimal and is hardly possible in some situations. Using Multi-Term LSM allows resolution of this difficulty
135 by using different a priori constraints for diverse atmospheric characteristics. Moreover, using the same Multi-Term LSM
136 concept, the innovative multi-pixel concept has been implemented within the GRASP algorithm (Dubovik et al., 2011, 2021a).
137 Under this concept, the inversion is performed simultaneously on a group of observations (e.g., satellite observations
138 over different pixels in space and time). This allows for improved retrieval accuracy by applying additional a priori constraints
139 on the spatial and temporal variability of retrieved parameters. This concept is vital for the implementation of the multi-
140 platform retrieval because it enables synergetic retrieval of not fully coincident or not fully co-located observations.

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142 The GRASP algorithm has already been successfully applied to the observations from different spaceborne instruments.
143 Extended aerosol characterization with using the GRASP algorithm was demonstrated on with PARASOL measurements (Popp
144 et al., 2016; Chen et al., 2020; Schutgens et al., 2021). Application of the GRASP to the Sentinel-3A/OLCI instrument showed
145 a performance in AOD retrieval performance comparable to the MODIS dark target (DT) product (Chen et al., 2022b).
146 Nevertheless, the studies also showed a strong dependence of the quality of OLCI/GRASP/OLCI retrieval quality on a priori
147 information about surface BRDF and reduced quality of the retrieval of the extended properties like Angstrom Exponent
148 (AE_{sp}) and Single Scattering Albedo (SSA) (Chen et al., 2022b). Applying GRASP to Sentinel-5P/TROPOMI
149 measurements, it was shown demonstrated that the quality of the extended aerosol and surface characterization can be
150 significantly enhanced even from a single viewing instrument if the presented above conditions (ii), (iii-iv), (v), and (vii) are
151 fulfilled for the sensor and the retrieval algorithm (Litvinov et al., 2024; Chen et al., 2024a).

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153 The GRASP multi-pixel retrieval strategy has already been used in the different various synergetic approaches. In particular,
154 the synergetic approach from ground-based observations was developed for the sun-photometer and LIDAR ground-based
155 measurements (Lopatin et al., 2013, 2021; Dubovik et al., 2021a). The synergetic retrieval from combined ground-
156 based and satellite measurements was introduced and used to generate a surface reference database for validation of
157 the validating satellite surface retrieval (GROSAT/GRASP approach (Litvinov et al., 2020, 2022, 2024)). In (Litvinov et al.,
158 (2021) and (Chen et al., (2024b), the hybrid synergy with the GRASP algorithm gains advantages of the rich
159 information content of the TROPOMI measurements and the high spatial resolution of the PRISMA instrument (L2 to L1
160 hybrid synergy).

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162 In this paper, we present a novel generalized synergetic approach with implemented in the GRASP algorithm for retrieval of
163 multi-mission spaceborne measurements (hereinafter the SYREMIS/GRASP (SYnergetic REtrieval from Multi-MISSion
164 instruments) approach), which can be robustly applied to present and future satellite observations. The concept was developed
165 for the tested on two types of synergetic measurements: (i) synergy from of Low Earth Orbiting (LEO) (polar-orbiting) satellites
166 (LEO+LEO) and (ii) synergy of LEO and geostationary (GEO) satellites (LEO+GEO). The LEO+LEO synergy was

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167 implemented and tested on ~~the~~ combined measurements from Sentinel-5P/TROPOMI, Sentinel-3A/OLCI, and Sentinel-
168 3B/OLCI instruments (hereinafter ~~also~~ referred to ~~also~~ as S5P/TROPOMI, S3A/OLCI, S3B/OLCI). ~~The~~ LEO+GEO synergy
169 concept was applied to S5P/TROPOMI, S3A/OLCI, S3B/OLCI, and Himawari-8/AHI ~~sensors~~instruments.

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171 In this paper, first, we describe the main principles of the ~~developed~~ SYREMIS/GRASP synergetic approach. Then, based on
172 the validation results, the enhanced ~~possibilities~~capabilities of the synergetic approach will be demonstrated, and ~~theits~~ main
173 drivers ~~of the SYREMIS/GRASP synergetic approach~~ be discussed.

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175 **2. SYREMIS/GRASP synergetic concept**

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176 ~~The~~ SYREMIS/GRASP synergetic approach was developed for ~~the~~ currently operating polar-orbiting and geostationary
177 satellites: S3A/OLCI, S3B/OLCI, S5P/TROPOMI, and Himawari-8/AHI. ~~On~~Figure 1 schematically demonstrates the general
178 ~~concept of combining multi-instrument spaceborne measurements within the SYREMIS/GRASP synergy. On the~~ one hand,
179 such multi-mission measurements allowed ~~for~~ testing the approach on ~~the~~ actual aerosol events and ~~consideringevaluating~~ the
180 enhancement in aerosol characterization ~~relativelyrelative~~ to already validated GRASP ~~retrievalretrievals~~ from S3A/OLCI and
181 S5P/TROPOMI, and Himawari-8/AHI sensors alone (Chen et al., ~~20222022b~~, 2024a; Litvinov et al., 2024; Li et al., 2025).
182 ~~On the other hand, it allowed filling the~~ gaps in ~~the~~ detailed extended aerosol characterization, ~~existingwhich have existed~~
183 since the end of the POLDER-3/PARASOL mission in 2013 ~~tiltuntil~~ the beginning of ~~the~~ new polarimetric missions (HARP-
184 2 and SPEX ~~onboard ofon board~~ PACE, MetOp-SG 3MI, ~~etc.~~and others).

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186 ~~SYREMIS/GRASP synergetic satellites constellation extends the~~ In general, such combined L1 measurements provide several
187 ~~advantages crucial for aerosol/surface characterization (Table 1): (i) better spectral coverage (from the UV to SWIR spectral~~
188 ~~range of the measurements and provides unprecedented spatial and-); (ii) improved temporal coverage which is crucial for with~~
189 ~~a few measurements per day in the LEO+LEO synergy and hourly (or better) temporal resolution in the LEO+GEO synergy;~~
190 ~~(iii) enhanced global climate studies and air quality monitoring (Table 1). Moreover, coverage due to the combined~~
191 ~~measurements in the synergy; (iv) “pseudo-multi-angular” measurements incorporating single-view~~
192 ~~measurementsobservations~~ from all instruments in Table 1 ~~are~~, obtained at different illumination and observation
193 ~~geometrygeometries~~ (solar and viewing zenith angles, ~~azimuthalazimuth~~ angles). As a result, ~~thesuch~~ combined synergetic
194 measurements can be considered ~~as a~~ multi-angular ~~one~~, or, strictly speaking, pseudo-multi-angular, taking into account
195 different ~~measurement~~ times ~~of the measurements~~ for each observation angle.

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197 ~~The advantages of combined L1 measurements are beneficial, provided that all different observations are simultaneous and/or~~
198 ~~co-located. However, this is usually not the case for observations from different satellite platforms. Therefore, the benefit of~~

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information complementarity in different observations is not straightforward. The application of the aforementioned multi-pixel concept enabled overcoming this issue. Specifically, a group of observations, including measurements from different satellites, is inverted simultaneously under a priori constraints on temporal and spatial variability of various atmospheric and surface reflectance parameters. As will be shown below, applying these constraints allows the propagation of information in the interpretation of all observations from different satellites.

Table 1. Multi-mission constellation for prototyped synergetic retrieval

Platform / Instrument	Description	Level	Reference
S3A/OLCI	- Near-Polar orbiting	Level 1B	1*
and 3BS3B/OLCI	- Swath: ~1270 km	S3A/OL 1 ERR	
	- One observation angle per pixel	S3B/OL 1 ERR	
	- Equatorial crossing: ~10.00 a.m. local time		
	- Revisiting time: ~2 days near the equator		
	- Spatial resolution: ~300m		
	- Radiance measurements in the VIS and NIR spectral range		
S5P/TROPOMI	- Near-Polar orbiting	Level 1B	2*
	- Swath: ~2600 km		
	- One observation angle per pixel		
	- Equatorial crossing: ~13.30 local time		
	- Revisiting time: 1 day near the equator		
	- Spatial resolution: 5.5 x 3.5 km (UV, VIS, NIR range); 5.5 x 7 km (SWIR range)		
	- Hyperspectral measurements in the UV, VIS, NIR, SWIR spectral range		
Himawari-8/AHI	- Geostationary	L1 Gridded data (3*)	3*,4*
	- Coverage area: Asia		
	- One observation angle per pixel		
	- Spatial resolution: 2-5 km		

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	Temporal resolution: every 10 min		
	Radiance measurements in the VIS, NIR, and SWIR spectral range		

¹²: <https://sentinel.esa.int/web/sentinel/user-guides/sentinel-3-olci/data-formats>

^{2a}: <https://sentinels.copernicus.eu/web/sentinel/technical-guides/sentinel-5p/products-algorithms>

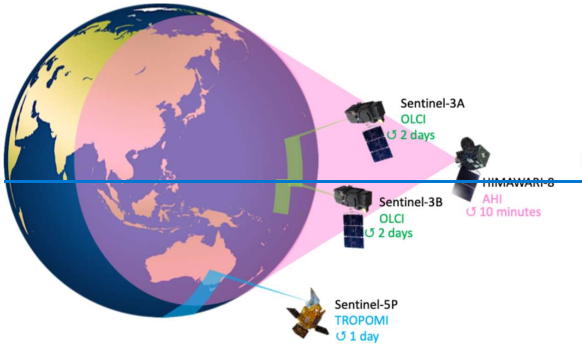
^{1*}: <https://user.eumetsat.int/resources/user-guides/sentinel-3-olci-level-1-data-guide>

^{2*}: <https://sentinels.copernicus.eu/data-products>

^{3*}: <https://www.eorc.jaxa.jp/ptree/userguide.html>

^{4*}: https://www.data.jma.go.jp/mscweb/en/himawari89/space_segment/sample_netcdf.html

Figure 1 demonstrates schematically the general concept of combining the multi-instrument spaceborne measurements in SYREMIS/GRASP synergy.



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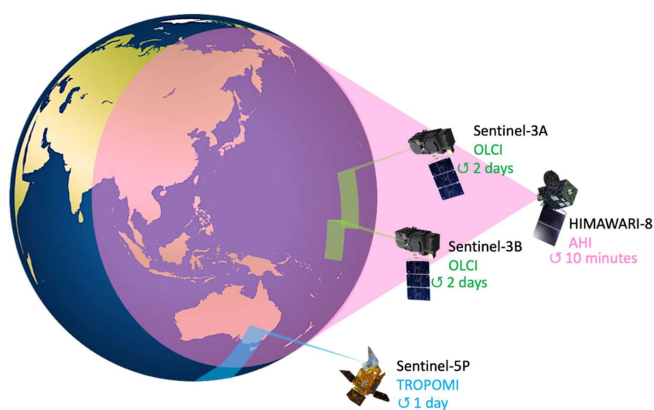


Figure 1: Schematic representation of the SYREMIS/GRASP multi-instrument measurements.

Figure 2 illustrates the SYREMIS/GRASP multi-instrument Level 1 (L1) synergetic processing chain for three different instruments: S3A/OLCI, S3B/OLCI, and S5P/TROPOMI (marked with different colors). For each instrument, the cubic layers symbolize the measurements on a certain day, which represent the observed radiance at measurement geometry (solar and observation zenith angles, azimuth angles difference), at selected spectral bands, and a given spatial resolution. All measurements from different instruments are cloud-screened, regridded to a consistent spatial resolution, and then merged into a spatial-temporal multi-pixel block, which is used as L1 input for the SYREMIS/GRASP forward run and inversion. The synergetic SYREMIS product contains retrieved aerosol and surface properties for all spectral bands, derived at the time of the merged L1 measurements.

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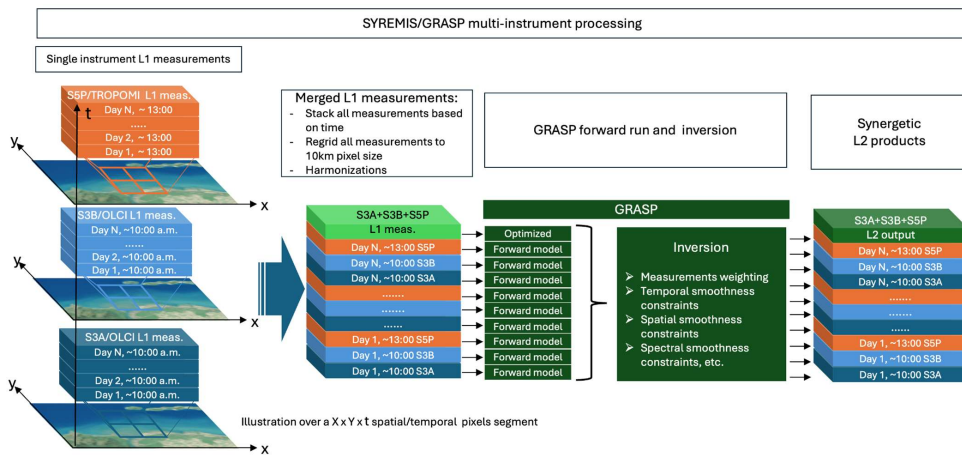


Figure 2: Illustration of SYREMIS multi-instrument processing chain.

Overall, the SYREMIS/GRASP synergetic concept is based on three main principles:–, which will be discussed in the next section:

- harmonization Harmonization and merging of L1 data from different instruments;
- “weightingWeighting” the used data sources (measurements and a priori constraints) according to their accuracies and information content and measurements accuracies;
- optimizationOptimization of GRASP forward models and retrieval setup.

2.1 SYREMIS/GRASP synergetic measurements harmonization

All satellites from Table 1 are very differentdiffer significantly in their measurement capabilities, including spectral range and spatial coverage, spatial resolution, revisiting time etc. To gain advantages ofexploit the extended information content of the synergy, the measurements from each instrument should be properly harmonized and merged. into a spatial-temporal multi-pixel group for simultaneous retrieval. In particular, this includes (i) spectral measurements harmonizationband selection within the synergy from different instruments; (ii) harmonization onof spatial resolution and gridding; (iii) cloud masking merging etc.

As a first step of the harmonization, the spectral bands which are more optimal for aerosol characterization were selected for LEO+LEO and LEO+GEO synergy (Table 2). The independentIndependent retrieval with the GRASP algorithm has been already been applied to each of the instrumentsinstrument in Table 1, using 9 spectral bands for the OLCI sensor, 10 for TROPOMI, and 6 bands for the AH1 instrument (Chen et al., 20222022b, 2024a; Litvinov et al., 2024; Li et al., 2025; Table

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1). These bands were also considered in the SYREMIS/GRASP synergy. In particular, 19 spectral measurements were included in the polar-orbiting LEO+LEO synergetic retrieval, and 24 bands in the LEO+GEO onesynergy (Table 2).

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All instruments from the synergetic satellite constellation have different spatial resolutions (Table 1). To apply properly the multi-pixel constraints in the GRASP algorithm, all measurements were re-gridded to the same spatial grid. Following the approach used in GRASP/TROPOMI/GRASP retrieval (Litvinov et al., 2024; Chen et al., 2024a), thean equidistant cylindrical projection and WGS84 coordinate system with the same spatial pixel resolution of 0.09° was used for all selected spectral bands, usingemploying a bilinear regridding method (<https://gdal.org/programs/gdalwarp.html>) (TablesTable 2).

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Table 2. Harmonized measurements from the SYREMIS synergy.

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	S3A/OLCI and S3B/OLCI	S5P/TROPOMI	Himawari-8/AHI
Wavelength selection	9 spectral bands: 412.5, 442.5, 490, 510, 560, 665, 753, 865, 1020 nm	10 spectral bands: 340, 367, 380, 416, 440, 494, 670, 747, 772, 2313 nm	6 spectral bands: 470.6, 510, 639.1, 856.7, 1610.1, 2256.8 nm
LEO+LEO synergy	19 spectral bands: 340, 367, 380, 412.5, 416, 440, 442.5, 490, 494, 510, 560, 665, 670, 747, 753, 772, 865, 1020, and 2313 nm		-
LEO+GEO synergy	24 spectral bands: 340, 367, 380, 412.5, 416, 440, 442.5, 470, 490, 494, 510, 560, 639.1, 665, 670, 747, 753, 772, 856.7, 865, 1020, 1610.1, 2256.8, and 2313 nm		
L1C Regridding method	0.09°, WGS84 coordinate system		
Cloud masking	IDEPIX	S5P NPP-VIIRS	Level 2 JAXA cloud product

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Since the measurements in the SYREMIS synergy are not collocated in time, the cloud masking was applied independently for each instrument. In particular, the cloud screening for TROPOMI in SYREMIS/GRASP processing is based on the S5P NPP-VIIRS cloud product, with aboutapproximately 500 m spatial resolution like it, as was done for GRASP/TROPOMI/GRASP processing (Litvinov et al., 2024; Chen et al., 2024a). SimilarlySimilar to OLCI/GRASP/OLCI,

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retrieval (Chen et al., 2022), IDEPIX cloud masking was applied to OLCI instruments. Himawari-8/AHI cloud screening is based on Level 2 cloud products (Letu et al., 2018, 2020).

2.2 “Weighting” observations for the multi-instrument synergistic retrieval

The GRASP multi-pixel concept is a key methodological approach in realizing multi-platform inversion. It is implemented within the Multi-Term LSM methodology, as described by Dubovik et al. (2011, 2021a). Following this approach, the retrieval is conducted not for each selected observed satellite pixel, but rather for a set of observations collected over different locations at different time moments (spatial-temporal multi-pixel dataset block, Figs. 2, 3).

Figure 3 illustrates an example of a spatial-temporal multi-pixel dataset block for 5x5 spatial pixels within a single selected day, filled with S3A/OLCI, S3B/OLCI, S5P/TROPOMI, and Himawari-8/AHI measurements in the synergy. As one can see, the single-day dataset block consists of data from different sensors, performing observations at different times during the same day: S3A/OLCI and S3B/OLCI make observations in the morning and can overlap spatially for some pixels; S5P/TROPOMI is the afternoon satellite; Himawari-8/AHI is in geostationary orbit, providing multiple observations during a day over the same area.

The multi-instrument measurements for the synergistic retrieval can be prepared in many possible combinations. A number of extensive case studies were performed to identify the most optimal retrieval setup for the synergy.

First of all, it was found out that merging close spectral measurements (for example, OLCI 442.5 nm and TROPOMI 440 nm, or OLCI 665 nm and TROPOMI 670 nm etc.) does not provide the best results. This can be explained by different accuracy of radiometric calibration and different bandwidth of the measurements in the synergy. Therefore, the final SYREMIS/GRASP synergistic data were prepared for 19 spectral measurements in LEO+LEO synergy and for 24 bands in LEO+GEO ones (Table 2). Accounting for the differences in the calibration and spectral bandwidth in GRASP algorithm is realized with application of the different requirements on the standard deviation of measurements fitting for the different spectral bands.

Second, extended standard deviation tests showed that proper “weighting” the multi-instrument measurements is crucial part of the SYREMIS/GRASP synergistic approach. In particular, it was found out that the “weight” of the TROPOMI measurements in the synergistic LEO+LEO and LEO+GEO retrieval should be stronger than the “weight” of the OLCI and AHI instruments. This can be explained by higher information content and better radiometric accuracy of TROPOMI measurements in comparison to other instruments in the synergy. Specifically, whenever close values of the standard deviation were applied to all instruments and all spectral bands, validation versus AERONET showed reduced performance in comparison with the single instrument retrieval (for example, in comparison with TROPOMI/GRASP results (Litvinov et al., 2024; Chen et al., 2024a). Application of the stronger requirements on the measurements fitting for the TROPOMI bands in

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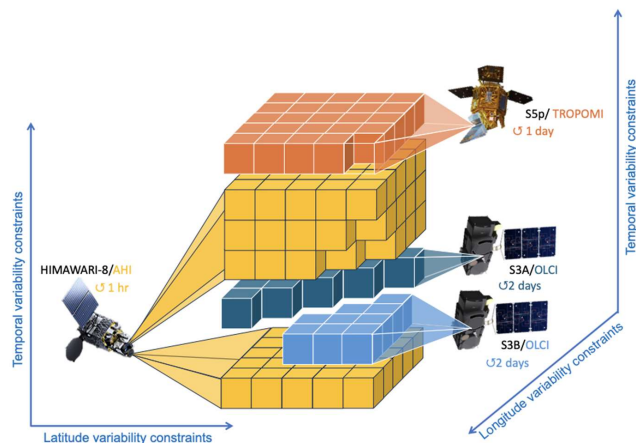


Figure 3: Illustration of applying a multi-pixel approach for S3A/OLCI, S3B/OLCI, S5P/TROPOMI, and Himawari-8/AHI multi-platform retrieval.

The balanced measurement “weighting” in the spatial-temporal multi-pixel dataset block (Figs. 2, 3) is crucial for synergetic retrieval. For example, as demonstrated in Litvinov et al. (2024) and Chen et al. (2024a), the S5P/TROPOMI instrument has the highest information content among all satellites from Table 1, allowing considerable enhancement of extended aerosol and surface characterization in comparison with OLCI and AHI instruments (Chen et al., 2022; Li et al., 2025). This fact was accounted for by “weighting” measurements from different instruments in the SYREMIS/GRASP retrieval.

The GRASP algorithm is based on the statistical optimization concept (e.g., Dubovik et al., 2021), where the contributions of different input data are balanced using known covariance matrices of each input dataset, including both satellite measurements and a priori data. Since those datasets are statistically independent ($C = I \sigma^2$, where C is the covariance matrix, I is the diagonal unity matrix, and σ^2 is the variance (σ is the standard deviation) (Appendix A; Dubovik et al. 2004, 2021a)), the weights (importance of the measurements) are driven by known (or assumed) standard deviations of uncertainties in each dataset: the smaller the standard deviation of measurement fitting required in the retrieval, the greater the “weight” of such measurements

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that can be assigned in the synergy. Within the framework of the Multi-Term LSM concept, the “weights” are quantitatively determined as ratios of σ_1^2 (variance of the first dataset) to σ_i^2 (variance of the i -th dataset). A detailed description of the data weighting Multi-Term LSM concept can be found in Dubovik et al. (2004) and Dubovik et al. (2021a), and a brief discussion is also provided in Appendix A.

Table 3 shows the weighting of different instruments used in the multi-instrument synergy inversion. It can be seen that the SSP/TROPOMI has the highest weight among other observations. At the same time, it is important to emphasize that, in general, the weights are defined with respect to both measurements and the a priori datasets used. This aspect is discussed in the next section and Appendix A.

In addition, it was discovered that exchanging of the a few measurements between the “weighting” groups provided better retrieval results vs AERONET. In particular, over land, the same standard deviation 0.001 as for the most of TROPOMI channels (Table 3) was assigned to OLCI bands 490 nm and 560 nm, whereas one TROPOMI band 494 nm was allocated to the OLCI bands “weighting” group with required standard deviation 0.05 (Table 3). Such bands inter-exchange was found to be useful to improve OLCI retrieval in the LEO+LEO synergy without loss in accuracy for SYREMIS/TROPOMI retrieval. It allows transferring information content from TROPOMI to OLCI and vice versa. The inter-exchange of selected bands between OLCI and AHI measurements also improved the consistency of the retrieval for all instruments in the LEO+GEO synergy (Table 4). The optimal “weighting” of the different measurements in LEO+LEO and LEO+GEO SYREMIS synergy, according to the applied requirements on the standard deviation, is presented in Tables 3 and 4.

Table 3. SYREMIS LEO+LEO synergy setup.

	Land	Ocean
SYREMIS/GRASP measurements “weighting” groups based on the requirement on the standard deviation of measurements fitting	0.001 (highest “weight”): –for 9 TROPOMI bands (340, 367, 380, 416, 440, 670, 747, 772, 2313 nm) –for 2 OLCI bands (490, 560 nm) 0.05 (lower “weight”): –for 1 TROPOMI band (494nm) –for 7 OLCI bands (412.5, 442.5, 510, 665, 753, 865, 1020 nm)	0.01 (highest “weight”): –for 9 TROPOMI bands (340, 367, 380, 416, 440, 670, 747, 772, 2313 nm) –for 1 OLCI band (490 nm) 0.02 (lower “weight”): –for 6 OLCI bands (510, 560, 665, 753, 865, 1020 nm) 0.1 (lower “weight”): –for 1 TROPOMI band (494nm) –for 2 OLCI bands (412.5, 442.5nm)
Surface variability	$\pm/- 6 h$	$\pm/- 0.5h$

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Temporal thresholds	Aerosol-scale height variability	$\pm 3h$	$\pm 0.5h$
Temporal smoothness constraints	Aerosol-concentration	0.0001 (relaxed-constraints)	0.0001 (relaxed-constraints)
	Aerosol-models-fractions	0.01	0.01
	Surface-BRDF-isotropic parameter	0.01	5.0
	Surface-BRDF-other parameters	0.005	A-priori information from ECMWF

Table 4. SYREMIS-GEO+LEO synergy-setup.

		Land
SYREMIS/GRASP-measurements “weighting” groups-based on the requirement on the standard deviation of measurements fitting		0.001 (highest “weight”): for 9 TROPOMI bands (340, 367, 380, 416, 440, 670, 747, 772, 2313 nm) for 2 OLCI bands (490,560 nm) 0.05 (lower “weight”): for 1 TROPOMI band (494nm) for 6 OLCI bands (412.5, 442.5, 665, 753, 865, 1020 nm) 0.01 (lower “weight”): for 4 AHI bands (471, 510, 639, 856.7nm) for 1 OLCI band (510 nm) 0.05 (lower “weight”): for 2 AHI bands (1610, 2256.8 nm)
Temporal thresholds	Surface-variability	$\pm 1h$
	Aerosol-scale height variability	$\pm 3h$
Temporal smoothness constraints	Aerosol-concentration	0.1
	Aerosol-models fractions	0.1
	Surface-BRDF	1.0

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345 **2.3 Forward models and retrieval setup for a priori constraints in the multi-instrument synergy**

346 Application of the GRASP retrieval algorithm independently to OLCI, TROPOMI, and AHI single-view instruments, as well

347 as to the multi-angular polarimetric PARASOL measurements, showed good performance of the so-called aerosol “models”

348 approach (Chen et al., 2020, 2022, 2024a; Dubovik et al., 2021a; Hasekamp et al., 2024; Litvinov et al., 2024). In

349 such this approach, the total single-scattering characteristics of aerosol aerosols are represented as the linear combinations of

350 the scattering characteristics of the preselected aerosol components, i.e., assuming an external mixture of four different aerosol

351 models: 1) fine absorbing, representing a climatological biomass burning aerosol model; 2) fine slightly absorbing,

352 corresponding to climatological sulfate aerosols with introduced minor absorption; 3) coarse component representing mainly

353 maritime aerosol type; and 4) coarse component for dust aerosol representation (Lopatin et al., 2021; Litvinov et al., 2024).

354 The state vector for such an aerosol model in the GRASP inversion consists of the following characteristics: aerosol scale

355 height, aerosol concentration, and aerosol model fractions (see, for example, the aerosol model parameters discussion in

356 Litvinov et al., 2024).

357

358 The surface reflectance in the GRASP retrieval is, usually, described by the spectrally constrained renormalized Ross-Li BRDF

359 model over land (Litvinov et al., 2010, 2011a, 2011b, 2024) and a modified Cox and Munk model with accounting for water

360 leaving reflectance (Cox and Munk, 1954; Litvinov et al., 2024). These aerosol and surface reflectance forward approaches

361 were found to be optimal also in the SYREMIS/GRASP synergetic retrieval for the satellite constellation from Table 1.

362

363 The strategic advantage of the GRASP inversion implemented via Multi-Term LSM statistically optimized fitting is that this

364 concept allows the use of multiple a priori constraints in the retrieval. Such a priori constraints can be applied to all aerosol

365 and surface characteristics and parameters (Dubovik et al., 2011, 2014, 2021a). In particular, the “single-pixel” a priori

366 smoothness constraints can be used for limiting variability (and avoiding unrealistic oscillations) of, for example, aerosol

367 column concentration, aerosol model fractions, spectral dependencies of surface BRDF parameters (the “in-pixel” smoothness

368 constraints in Eq. (13A)). In addition to the “single-pixel” constraints, the “inter-pixel” constraints were used within the so-

369 called “multi-pixel” retrieval when a large group of pixels was retrieved simultaneously and smoothness constraints (the “inter-

370 pixels” smoothness constraints in Eq.(13A)) can be used for limiting temporal or spatial variability of parameters retrieved in

371 different neighboring pixels (Dubovik et al., 2011, 2021a).

372

373 The successful applications of the GRASP algorithm to different satellites demonstrated the crucial role of the single- and

374 multi-pixels (or in-pixel and inter-pixel) smoothness constraints for stable and accurate characterization of both atmospheric

375 aerosol and surface (Dubovik et al., 2011, 2014; 2021a; Chen et al., 2022b; Litvinov et al., 2024). A brief summary of the

376 formal implementation of the “multi-pixel” retrieval is provided in Appendix A.

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In comparison to the single-instrument retrieval, the SYREMIS LEO+LEO and LEO+GEO synergies have much better diurnal temporal resolution of measurements, when the temporal difference between S3A/OLCI, S3B/OLCI, S5P/TROPOMI, and especially between Himawari-8/AHI measurements can vary from several minutes to several hours within one a single day. During this time aerosol. Moreover, the retrieval is performed on the data accumulated in the spatial-temporal blocks (Figs. 2 and 3) consisting of hundreds of satellite observations and covering about a month in the LEO+LEO and about two weeks in the LEO+GEO synergies (up to 150 and 200 temporal observations in the LEO+LEO and LEO+GEO synergies, respectively, Table 4). The temporal variability of aerosol and surface properties (in particular, aerosol concentration) can be different within a few minutes, hours, or from day to day. Moreover, the temporal variability of aerosol properties is usually stronger than the surface ones. Therefore, the importance of using a priori temporal constraints for aerosol and surface parameters within a few minutes to several days and weeks significantly increases in the LEO+LEO and LEO+GEO configurations.

GRASP limits the temporal variability of the retrieved parameters by applying the temporal a priori constraints, introduced as a priori estimates of the first derivatives with respect to time, approximated by finite differences (the differences between the parameters divided by the period over which they were observed (Dubovik et al., 2011, 2021a)). The estimates are assumed to be normally distributed values with zero means and the standard deviations assigned on the basis of the expected temporal variability of retrieved parameters. The use of limitations applied to the finite differences is a very convenient way to ensure flexibility in temporal constraints. Indeed, such constraints allow much larger variability for parameters corresponding to more distant in time observations compared to the parameters from observations that are very close in time (full description can be found in Dubovik et al., 2011, 2021a).

However, in cases when observations are nearly simultaneous or very close in time, the finite differences may have very large values that can produce an imbalance in practical fitting. To avoid such difficulties, “temporal thresholds” on aerosol and surface characteristics are used in the SYREMIS/GRASP. The temporal threshold allows for avoiding very large values of the finite differences in cases when the combined synergistic observations are close to each other in time. Specifically, the very small time difference in the denominator of the finite difference is replaced by the specified “temporal threshold” value, allowing stronger temporal constraints on the temporal variability of the retrieved parameters within the threshold. This approach was in particular useful for constraining BRDF parameters, defined by the intrinsic properties of the surface (surface type, reflecting properties, topology), which are very stable in time, and, as a rule, do not change essentially. At considerably during a day. The temporal thresholds applied to BRDF in the SYREMIS/GRASP approach allow using almost the same BRDF parameters for all synergetic measurements during the specified period. Similarly, the temporal thresholds are also useful for constraining the variability of aerosol model parameters (Table 4). Overall, in the SYREMIS/GRASP approach, different temporal thresholds were applied to different aerosol and surface properties, accounting for their different temporal dependence.

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412 When the time interval between measurements in the synergy exceeds the specified temporal threshold, the multi-pixel
413 temporal constraints (inter-pixel smoothness constraints on t-temporal variability in Eq. (13A)) in the SYREMIS/GRASP
414 account for the actual temporal interval between the measurements, as it was done in the single-instrument GRASP retrieval
415 (Dubovik et al., 2011, 2021a; Chen et al., 2022b; Litvinov et al., 2024; Li et al., 2025). In addition, some spatial multi-pixel
416 constraints were also used for aerosol, as described in Appendix A; however, these constraints played a rather minor role, as
417 they were applied only within 2 by 2 pixel areas.

418 **2.4 Remote sensing tests to optimize synergetic retrieval**

419 A priori knowledge about single-instrument information content and measurement accuracy provides a good starting point for
420 formulating the initial concept for the retrieval setups: instrument weighting, temporal, spatial, and spectral constraints in the
421 synergy. Nevertheless, practice shows that optimizing and tuning this initial synergetic retrieval setup by conducting a series
422 of remote sensing tests is usually desirable and necessary. In SYREMIS/GRASP, synergy optimization included several tests:
423 (i) validation of retrieved aerosol properties over a limited number of AERONET stations; (ii) intercomparison of surface
424 properties derived from synergetic ground-based and satellite measurements (based on the GROSAT/GRASP synergetic
425 approach (Litvinov et al., 2020, 2022, 2024)); and (iii) intercomparison of aerosol and surface synergetic retrieval with
426 reference products from space-borne measurements over small regions (~1000 km x 1000 km).

427
428 Test (i) for the LEO+LEO and LEO+GEO synergies was first performed over a few AERONET stations (Holben et al., 1998;
429 Giles et al., 2019) with different aerosol and surface properties (e.g., Mongu, Banizoumbou, Kanpur, Beijing) and then
430 extended to 30 stations worldwide (e.g., Chen et al., 2022b) for the selected limited period (March-May 2019). The retrieval
431 setups that showed the best AOD, AE, and SSA validation results were selected for further consideration. Test (ii) enabled
432 intercomparison of surface BRDF parameters derived from different instruments using the GROSAT/GRASP synergetic
433 approach, similar to Litvinov et al. (2022, 2024) and Chen et al. (2024a). Since these parameters are independent of
434 illumination/observation geometries, they can be intercompared for different space-borne sensors, allowing identification of
435 possible biases and their accounting for in the standard deviations of the uncertainties for each instrument (Section 2.2). In
436 Test (iii), MODIS and VIIRS (Levy et al., 2013; Sayer et al., 2018a; Schaaf and Wang, 2015) aerosol/surface products were
437 used for regional intercomparison with the SYREMIS/GRASP results.

438
439 The validation results against AERONET in Test (i) were evaluated using the following statistical characteristics: (i) Pearson
440 correlation coefficient (R); (ii) Root Mean Square Error (RMSE); (iii) the number of data points (N) in the validation; and (iv)
441 the number (and percentage) of data points satisfying the GCOS-based AOD criteria relative to AERONET. The GCOS-based
442 criteria for AOD are based on the AOD requirements from Global Climate Observing System (GCOS-245) and their adaptation
443 within the ESA aerosol-CCI project (Popp et al., 2016) for validation of AOD, derived from satellite measurements, against

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444 AERONET (de Leeuw et al, 2015): absolute difference in AOD is less than 0.04 or relative difference is less than 10%
445 (whichever is bigger).

447 The synergetic setup exhibiting the best validation statistical characteristics for aerosol and surface properties from Tests (i)
448 and (ii), and which qualitatively agreed with the well-established aerosol/surface products (Test (iii)), was selected as a baseline
449 approach for global synergetic retrieval.

451 The remote sensing tests, performed for the LEO+LEO and LEO+GEO synergies, showed that merging spectrally close
452 measurements (for example, OLCI 442.5 nm and TROPOMI 440 nm, or OLCI 665 nm and TROPOMI 670 nm) does not
453 provide the best results in Test (i). Therefore, the final SYREMIS/GRASP synergetic data were prepared using 19 spectral
454 measurements in the LEO+LEO synergy and 24 bands in the LEO+GEO synergy. The optimization test also showed the crucial
455 role of balanced “weighting” of the multi-instrument measurements within the SYREMIS/GRASP synergetic approach. As
456 discussed in Section 2.2 and Appendix A, instrument “weighting” in GRASP can be achieved through the standard deviation
457 of the measurement fitting, that defines weighting matrices in the GRASP multi-term LSM inversion scheme and, thus, the
458 weights (or importance) of different data involved in the inversion. It was found that application of stronger requirements on
459 the measurement fitting for the TROPOMI bands in the synergy resulted in much better validation results against AERONET
460 (Test (i)) (Fig. 4). This can be explained by TROPOMI’s higher information content (better spectral coverage and wider swath)
461 in comparison with other instruments within the synergy. Specifically, whenever comparable values of the standard deviation
462 were applied to all instruments and spectral bands, the validation against AERONET showed reduced performance relative to
463 single-instrument retrieval (for example, in comparison with the GRASP/TROPOMI results (Litvinov et al., 2024; Chen et al.,
464 2024a)). Therefore, in the SYREMIS/GRASP synergetic approach, a few weighting groups with different requirements for the
465 standard deviation of measurement fitting were associated with different instruments from the synergy (Table 3).

467 In addition, it was discovered that exchanging time, the changes in a few measurements between the weighting groups provided
468 better retrieval results against AERONET. In particular, over land, the same standard deviation of 0.001 as for most TROPOMI
469 channels (Table 3, group 'a') was assigned to OLCI bands 490 nm and 560 nm. Conversely, one TROPOMI band, 494 nm, was
470 allocated to the OLCI bands' weighting group with a required standard deviation of 0.05 (Table 3, group 'b'). Such band inter-
471 exchange was found to be useful for improving OLCI retrieval in the LEO+LEO synergy without loss of accuracy in the
472 SYREMIS/TROPOMI retrieval. This allows transferring information content from TROPOMI to OLCI and vice versa. The
473 inter-exchange of selected bands between OLCI and AHI measurements also improved the consistency of retrieval for all
474 instruments in the LEO+GEO synergy (Table 3). The optimal weighting of the different measurements used in the LEO+LEO
475 and LEO+GEO SYREMIS synergies, according to the applied requirements on the standard deviation, is presented in Table
476 3.

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478 [As one can see, the “weighting” of the LEO+GEO is much more complicated than that of the LEO+LEO synergy. In particular,](#)
479 [two additional groups of weights were added: group 'c' with '0.01', applied mainly to AHI instruments to account for diurnal](#)
480 [aerosol variability from geostationary measurements; and group 'd' with '0.05', to reduce the “weight” of SWIR AHI](#)
481 [measurements, that allowed improving the performance of the remote sensing tests.](#)

482
483 [The values of the “weights” in Table 3 are related to the specific inversion approach of the GRASP algorithm applied to the](#)
484 [instruments listed in Table 1. Moreover, due to the ill-posed character of the inversion, the “weighting” from Table 3 is not](#)
485 [unique even within the GRASP algorithm since other combinations of its values are possible with quite comparable retrieved](#)
486 [results. The values provided in Table 3 demonstrate a general tendency for the considered synergies: the “weight” of](#)
487 [SSP/TROPOMI measurements should be higher compared to other instruments.](#)

488
489 [Table 3. Instrument “weighting” in SYREMIS LEO+LEO and LEO+GEO synergy setup: example over land.](#)

LEO+LEO SYREMIS/GRASP measurements “weighting” groups based on the requirement on the standard deviation of measurements fitting	a). 0.001 (highest “weight”): - for 9 TROPOMI bands (340, 367, 380, 416, 440, 670, 747, 772, 2313 nm) - for 2 OLCI bands (490, 560 nm) b). 0.05 (lower “weight”): - for 1 TROPOMI band (494nm) - for 7 OLCI bands (412.5, 442.5, 510, 665, 753, 865, 1020 nm)
LEO+GEO SYREMIS/GRASP measurements “weighting” groups based on the requirement on the standard deviation of measurements fitting	a). 0.001 (highest “weight”): - for 9 TROPOMI bands (340, 367, 380, 416, 440, 670, 747, 772, 2313 nm) - for 2 OLCI bands (490, 560 nm) b). 0.05 (lower “weight”): - for 1 TROPOMI band (494nm) - for 6 OLCI bands (412.5, 442.5, 665, 753, 865, 1020 nm) c). 0.01 (lower “weight”): - for 4 AHI bands (471, 510, 639, 856.7nm) - for 1 OLCI band (510 nm) d). 0.05 (lower “weight”): - for 2 AHI bands (1610, 2256.8 nm)

490
491 [Besides satellite measurements’ “weighting”, GRASP “single-” and “multi-pixel” *a priori* constraints \(Section 2.3, Appendix](#)
492 [A\) also play a key role in the successful realization of the SYREMIS/GRASP approach. Overall, the spectral and spatial](#)
493 [constraints used in GRASP single-instrument retrieval \(Chen et al., 2022b; Litvinov et al., 2024; Li et al., 2025\) showed good](#)
494 [performance in the optimization tests and were subsequently used in synergy.](#)

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Due to the merging of measurements from different sensors, the synergetic L1 input data blocks have much better temporal resolution compared to any single instrument from the synergy (Figs. 2 and 3). This affects the optimal temporal constraints applied to aerosol and surface parameters within the SYREMIS/GRASP approach. Properly selected temporal thresholds and smoothness constraints substantially increase the number of pseudo-multi-angular measurements in the synergy, a factor crucial for BRDF parameter retrieval and the distinguishing of atmosphere and surface signals. The optimized temporal thresholds and smoothness constraints for aerosol and surface parameters in the SYREMIS/GRASP LEO+LEO and LEO+GEO synergies are presented in Table 4. As one can see, they account for known tendencies: surface BRDF temporal variability is generally smaller than the temporal variability of aerosol properties (stronger thresholds and constraints on the surface BRDF parameters than on the aerosol ones in Table 4); the temporal variability of the aerosol concentration is usually larger than that of the aerosol microphysics (size, chemistry/complex refractive index, non-sphericity etc.) or surface BRDF parameters may not be as fast, which results in stronger constraints on the aerosol model fraction parameter in the SYREMIS/GRASP approach (Table 4).

The temporal correlations of aerosol properties as well as surface BRDF parameters are accounted with the temporal constraints in the GRASP algorithm. The temporal thresholds applied to BRDF parameters in the SYREMIS approach considerably limit the variability of the BRDF parameters for all synergetic measurements during the specified period. They can change depending on pixel latitude due to different satellite overpass times at low and high latitudes. For the considered LEO+LEO synergetic satellite constellation, several hours (for example, +/-6 h) are sufficient to account for a stable surface within the day globally.

LEO+GEO synergetic measurements cover a wider range of observation/illumination geometries (solar and viewing zenith and azimuth angles) than LEO+LEO. It has already been demonstrated that different BRDF models used in remote sensing perform well only for limited geometries (the limitations of different BRDF models in remote sensing are studied, for example, in Litvinov et al. (2011a; 2011b)). Due to this known limitation of the BRDF models, the optimized temporal thresholds for the LEO+GEO synergy are relaxed to a few hours, and the constraints on temporal variability rely mainly on temporal smoothness constraints in the GRASP algorithm, allowing the retrieved properties to change smoothly in time.

Table 4. Example of SYREMIS LEO+LEO and LEO+GEO smoothness constraints over land.

	SYREMIS/GRASP LEO+LEO	SYREMIS/GRASP LEO+GEO
Maximum temporal dimension of the multi-temporal dataset block (Figs. 2 and 3)	~ 150 temporal measurements (about 1 month temporal period covered by the LEO+LEO temporal dataset block)	~ 200 temporal measurements (about 2 weeks temporal period covered by the LEO+GEO temporal dataset block)

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Temporal thresholds	Surface variability	Several hours (stronger than in LEO+GEO)	A few hours
	Aerosol scale height variability	A few hours	A few hours
Temporal smoothness constraints	Aerosol concentration	0.0001	0.1 (stronger than in LEO+LEO)
	Aerosol model fractions	0.01	0.1 (stronger than in LEO+LEO)
	Surface BRDF isotropic parameter	0.01 (stronger than for aerosol)	1 (stronger than in LEO+LEO)
	Other parameters of the surface BRDF	0.005 (stronger than for aerosol)	1 (stronger than in LEO+LEO)

Similar to Table 3, due to the ill-posed nature of the inversion problem, the values provided in Table 4, strictly speaking, are not unique, since quite similar retrieval performance of aerosol and surface properties can be obtained within a certain range of the constraints. Nevertheless, the chosen parameters are generally within the optimal range in the sense that they adequately reflect the tendencies in temporal dependencies of aerosol and surface properties, adapted to the information content in the LEO+LEO and LEO+GEO synergies.

Figure 4 shows the (Dubovik et al., 2011, 2021a). Correct selection of these constraints is one of the crucial elements of the synergy from the multi-instrument measurements when they are not coincident. To account for such temporal variability, different temporal thresholds and smoothness constraints were applied to different retrieval parameters. In particular, in the SYREMIS/GRASP processing the surface properties are considered to be the constant within ± 6 h over land and ± 0.5 h over ocean (“Temporal threshold on surface variability” in Tables 3 and 4). For the vertical distribution of aerosol concentration, the temporal threshold ± 3 h over land ± 0.5 h over ocean was applied (“Aerosol scale height variability” in Tables 3 and 4).

The temporal variability of aerosol and surface properties from day to day is controlled in SYREMIS/GRASP by adequately selected temporal smoothness constraints. Since the combined measurements from S3A/OLCI, S3B/OLCI, S5P/TROPOMI and Himawari-8/AHI contain more information about temporal variability than for each separated instrument, the temporal smoothness constraints were relaxed for the synergetic retrieval in comparison to those were used for the single instrument, for example, TROPOMI/GRASP and OLCI/GRASP (Tables 3, 4, (Litvinov et al., 2024; Cheng et al., 2022)). They are also more relaxed for LEO+GEO synergy than for LEO+LEO (Tables 3, 4).

Figures 2 and 3 show SYREMIS LEO+LEO retrieval results obtained before (Fig. 4(a)) and after (Fig. 4(b)) harmonization, instrument “weighting” and retrieval setup optimization. “single-” and “multi-pixel” setup optimization. The results are intercompared with AERONET AOD at 550 nm. In this and other validation figures below for AOD, AE, and SSA, AERONET

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Level 2.0 AOD and INV data were obtained from the NASA Goddard Space Flight Center AERONET website (<https://aeronet.gsfc.nasa.gov/>) (Holben et al., 1998; Dubovik and King, 2000; Dubovik et al., 2000; Giles et al., 2019).

In Fig. 4 (as well as in other similar validation plots below), the color of each data point indicates the AOD Probability Density Function (PDF) value (an increasing PDF value corresponds to a color gradient from blue to red). The straight dotted line represents an ideal one-to-one correspondence in AOD. The straight red line is the linear fit to the data distribution, with the slope and intercept marked in the top-left corner legend. The grey envelope surrounding the one-to-one line in the scatter plot indicates the AOD GCOS-based envelope discussed above: an absolute difference in AOD is less than 0.04, or a relative difference is less than 10% (whichever is bigger) (GCOS-2022; de Leeuw et al., 2015). Below the scatter plots, the PDF ('Probability' in Fig. 4) of the AOD difference (AOD(SYREMIS/GRASP) - AOD(AERONET) in Fig. 4) is provided for four AOD intervals (bins). "Total" (black color in Fig.4) corresponds to all AOD cases; "<0.2" (red): AOD<0.2; "[0.2,0.7]" (blue): AOD is between [0.2,0.7]; and ">0.7" (green in Fig.4): AOD>0.7 cases. In Fig. 4, the bias ('Avg'), standard deviation ('Std'), the total number of pixels in the validation (N), and the number and percentage of pixels satisfying GCOS-based requirements ('GCOS') are indicated as a legend at the top of the PDF plots.

Table 5 lists the AOD validation statistical parameters for the SYREMIS LEO+LEO synergy extracted from Fig. 4. In particular, after optimizing the retrieval settings, 'GCOS' (Total) improved from 34.2% to 47.9%; bias (Total) decreased from 0.04 to -0.02; the correlation coefficient improved from 0.89 to 0.9; and the RMSE decreased from 0.16 to 0.14. The biggest improvements are for the low AOD cases (AOD<0.2), containing the majority of validation pixels: 'GCOS' improved from 38.8% to 61%, and 'bias' decreased from 0.06 to 0.01. For moderate AOD (0.2 < AOD < 0.7), 'GCOS' improved from 25.2% to 26.3%, and 'bias' changed from 0.04 to -0.04. For high AOD (>0.7) cases, 'GCOS' remained flat around 35%, and 'bias' changed from -0.06 to -0.09. One can observe essentialsubstantial improvement in the retrieval-relativelyvalidation statistical characteristics, emphasized by the bold fonts in Table 5, relative to AERONET after properproperly accounting for the information content of the instruments, measurementsmeasurement accuracy, and adjustment of the retrieval approach to the synergetic multi-instrumentsinstrument constellation.

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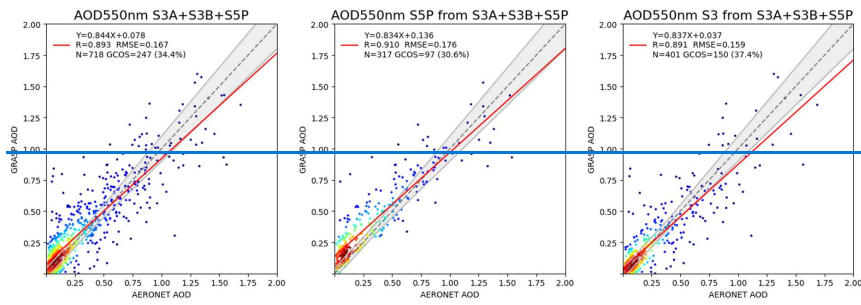
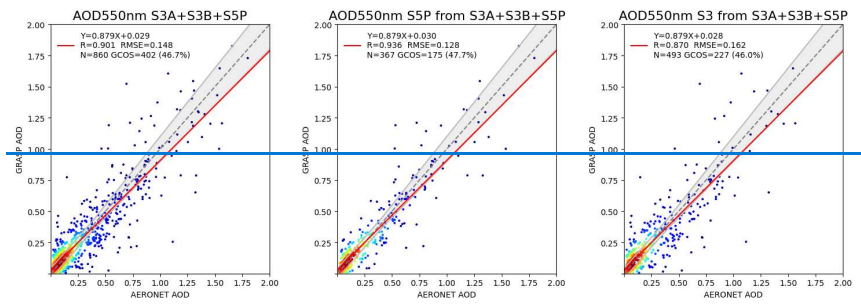


Figure 2: SYREMIS AOD retrieval before harmonization, instrument "weighting" and retrieval setup optimization: SYREMIS all instruments (left), SYREMIS/TROPOMI AOD extract (middle), SYREMIS/OLCI AOD extract (right).

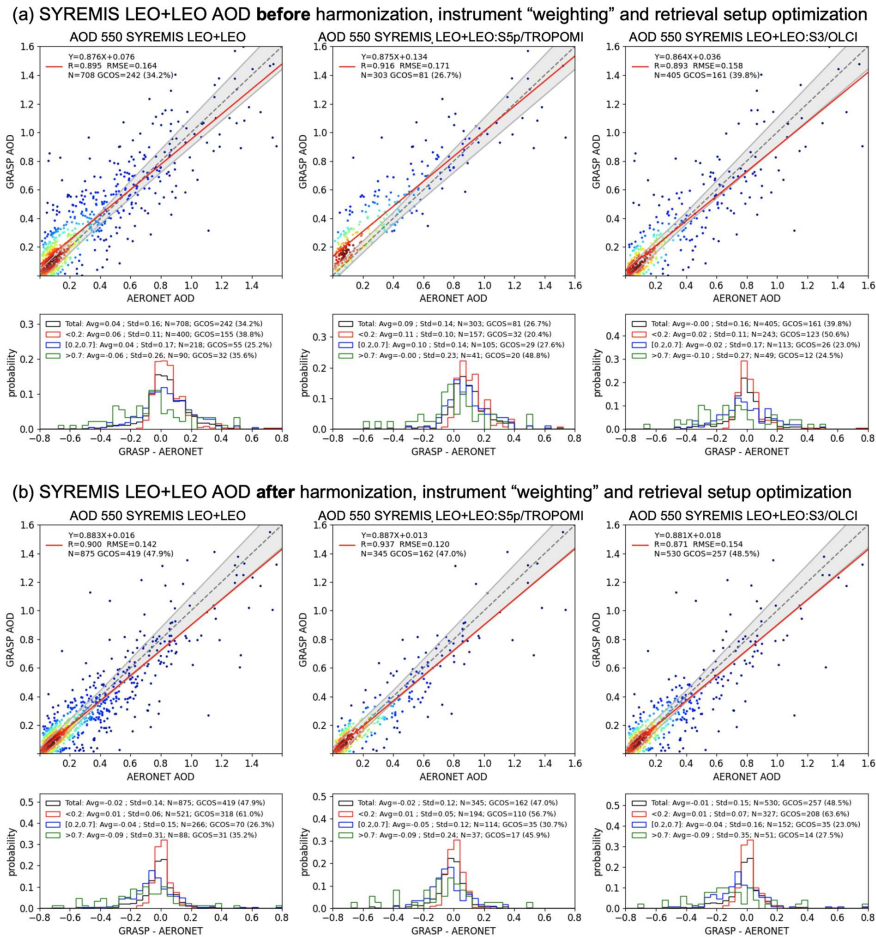


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Figure 3: The same as in Fig. 2 but after harmonization, instrument “weighting” and retrieval setup optimization (Table 3).



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Figure 4: Comparison of the SYREMIS LEO+LEO AOD retrieval before (Panel (a)) and after (Panel (b)) harmonization, instrument “weighting”, and setting optimization. Each panel contains validation of AOD 550nm versus AERONET AOD 550nm. In the scatter plot, the color of each datapoint indicates the two-dimensional probability density function (2D PDF) for AOD values (increasing PDF value corresponds to color gradient from blue to red). Below the scatter plot, the PDF AOD(SYREMIS) - AOD(AERONET) is provided for 4 AOD bins (see more details in Section 2.4). Left column of the panels: AOD product of all instruments in the synergy. Middle column of the

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588 panels: AOD product of S5p/TROPOMI extracted from the synergy. Right column of the panels: AOD product of
589 S3A/OLCI and S3B/OLCI extracted from the synergy.

590

591 Table 5. Summary of the SYREMIS LEO+LEO AOD accuracy statistics for the two tests ((a)“Before” and (b) “After”)
592 in Fig. 4. The statistical parameters in the column headers are the same as in Fig.4. “GCOS” and “Bias” are presented
593 for each AOD bin (“Total”, “AOD<0.2”, “0.2≤AOD≤0.7”, “AOD>0.7”), same as in Fig.4 histogram.

	GCOS (Total)	GCOS (AOD<0.2)	GCOS (0.2≤AOD≤ 0.7)	GCOS (AOD>0.7)	Bias (Total)	Bias (AOD<0.2)	Bias (0.2≤AOD≤ 0.7)	Bias (AOD>0.7)	R (Total)	RMSE (Total)
Fig 4 (a) ("Before")	34.2%	38.8%	25.2%	35.6%	0.04	0.06	0.04	-0.06	0.895	0.164
Fig 4 (b) ("After")	47.9%	61%	26.3%	35.2%	-0.02	0.01	-0.04	-0.09	0.90	0.142

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595 **3 Validation and inter-comparison of the synergetic product**

596 The validation of the SYREMIS/GRASP processing for LEO+LEO and LEO+GEO synergies was performed against
597 AERONET and intercompared with VIIRS and MODIS aerosol and surface products (Schaaf et al., 2002; Schaaf and Wang,
598 2015; Hsu et al., 203, 2019; Sayer et al., 2018a, 2018b). The validation criteria are described in Section 2.4 for the same as
599 was optimization remote sensing test and were used for the GRASP/TROPOMI/GRASP retrieval evaluation (Litvinov et al.,
600 2024; Chen et al., 2024a).

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602 **3.1 SYREMIS/GRASP LEO+LEO synergetic synergy performance versus AERONET**

603 Validation—The validation results from for the synergetic SYREMIS/GRASP LEO+LEO retrieval versus against the global
604 AERONET stations for March, April, and May 2019 are presented in Figs. 45-7 separately for (i). Figures 5(a)-7(a) show the
605 validation for all instruments in the synergy (SYREMIS/GRASP); (ii) for TROPOMI instrument- LEO+LEO). Figures 5(b)-
606 7(b) present the data associated with S5p/TROPOMI measurements (data extracted from the synergy at the time of TROPOMI
607 measurements, indicated as “SYREMIS LEO+LEO: S5p/TROPOMI” in Figs. 5(b)-7(b)). Figures 5(c)-7(c) contain the data
608 associated with S3/OLCI measurements (data extracted from the synergy (SYREMIS/TROPOMI) at the time of S3A/OLCI
609 and (iii) for OLCI instrument extracted from the synergy (S3B/OLCI measurements, indicated as “SYREMIS/OLCI-
610 LEO+LEO: S3/OLCI” in Figs. 5(c)-7(c)).

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To remove the outliers ~~offrom~~ the retrieval, ~~the~~ and ensure consistency in the presented results, a filtering similar to the GRASP/TROPOMI/GRASP quality assurance flag ~~was applied~~ (Litvinov et al., 2024) ~~was applied~~ in Figs. 5-7. In particular, over land, the validation was done for the pixels satisfying the following conditions: (i) the relative residual of fitting ~~iswas~~ less than 0.03 (3%); (ii) the standard deviation (σ_{AOD}) of AOD(865nm/670 nm) within the 3x3 ~~pixels~~ pixel window ~~iswas~~ less than 0.05, or the relative standard deviation $\sigma_{AOD}(865/670 \text{ nm})/AOD(865-670 \text{ nm})$ ~~was~~ less than 0.15; (iii) the number of valid pixels within the 3x3 pixel window was greater than or equal to 5. Over the ocean, the filtering conditions were relaxed, taking into account the overall smaller ~~the~~ total reflectance and global AOD values ~~in comparison~~ compared to the pixels over land: (i) the relative residual ~~iswas~~ less than 0.1; (ii) $\sigma_{AOD}(865/670 \text{ nm}) < 0.05$. For the Angstrom Exponent (AE_{Exp}) and SSA ~~the, an~~ additional filter was applied when only pixels with AOD(550 nm) ~~> 0.2~~ > 0.2 and AOD(550 nm) ~~> 0.3~~ > 0.3 , respectively, were used in the validation.

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In general, the synergetic SYREMIS/GRASP retrieval shows good correspondence to AERONET, with a high percentage of fulfilments (~54.3% over land and ~65% over ocean) of fulfillment of GCOS (Global Climate Observation System-based (GCOS-245, 2022)) requirements ~~and the value for AOD~~. The values of the statistical characteristics (Pearson correlation coefficient, Root Mean Square Error (RMSE), bias, etc.) ~~indicates~~ indicate the high quality of the retrieval ~~as shown in Figs. 45-7~~. All.

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The corresponding SYREMIS LEO+LEO AOD (550 nm) validation statistics are summarized in Table 6. As one can see, the SYREMIS all-instruments AOD (550 nm) retrievals (combining S5P/TROPOMI, S3A/OLCI, and S3B/OLCI, as presented in Figs. 5(a) and 5(d)) show good agreement with AERONET observations. Over land (Fig. 5(a)), the validation yields the correlation coefficient (R) of ~0.89, RMSE of ~0.094, and GCOS-based compliance fraction of 54.3%. Over the ocean (Fig. 5(d)), the R value is ~0.88, the RMSE is ~0.060, and the GCOS-based compliance fraction is 65.0%.

These AOD statistical characteristics are consistent with the validation results for all individual instruments extracted from the SYREMIS LEO+LEO retrievals, as shown in Figs. 5(b), 5(c) (for S5P/TROPOMI and S3/OLCI over land) and 5(e), 5(f) (for S5P/TROPOMI and S3/OLCI over ocean), respectively. Moreover, all retrieved extended characteristics (AOD, AE_{Exp} , SSA) are consistent for all instruments in the synergy. AE and SSA are also consistent with each other across all instruments in the synergy. Specifically, the validation results for AE and SSA from the SYREMIS LEO+LEO retrievals are presented in Figs. 6 (AE) and 7 (SSA), respectively, and summarized in Table 7. AE from the SYREMIS LEO+LEO (Figs. 6a and 6d), as well as from the TROPOMI (Figs. 6b and 6e) and OLCI (Figs. 6c and 6f) data extraction, demonstrates similarly good agreement with AERONET, with correlation coefficients (R) ranging from 0.70 to 0.80 and RMSE values of 0.45–0.48 over land. Over the ocean, R values range from 0.60–0.75 with RMSEs of 0.40–0.50. For the SYREMIS LEO+LEO (Figs. 7(a) and 7(d)), as well as for TROPOMI (Figs. 7(b) and 7(e)) and OLCI (Figs. 7(c) and 7(f)) data extraction, the SSA(550 nm) validations against

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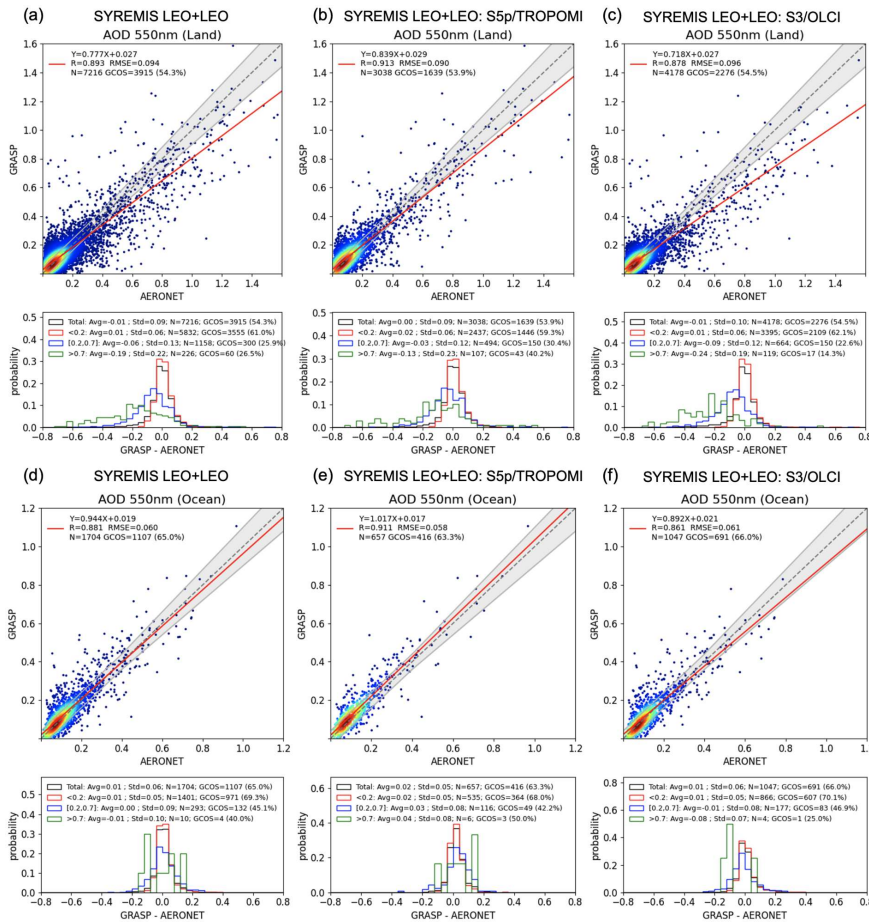
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645 AERONET show that the RMSEs are approximately 0.03–0.035 over land and 0.05–0.07 over ocean, indicating, in general,
 646 good agreement taking into account the limited available matchups of SSA under moderate and high AOD conditions.

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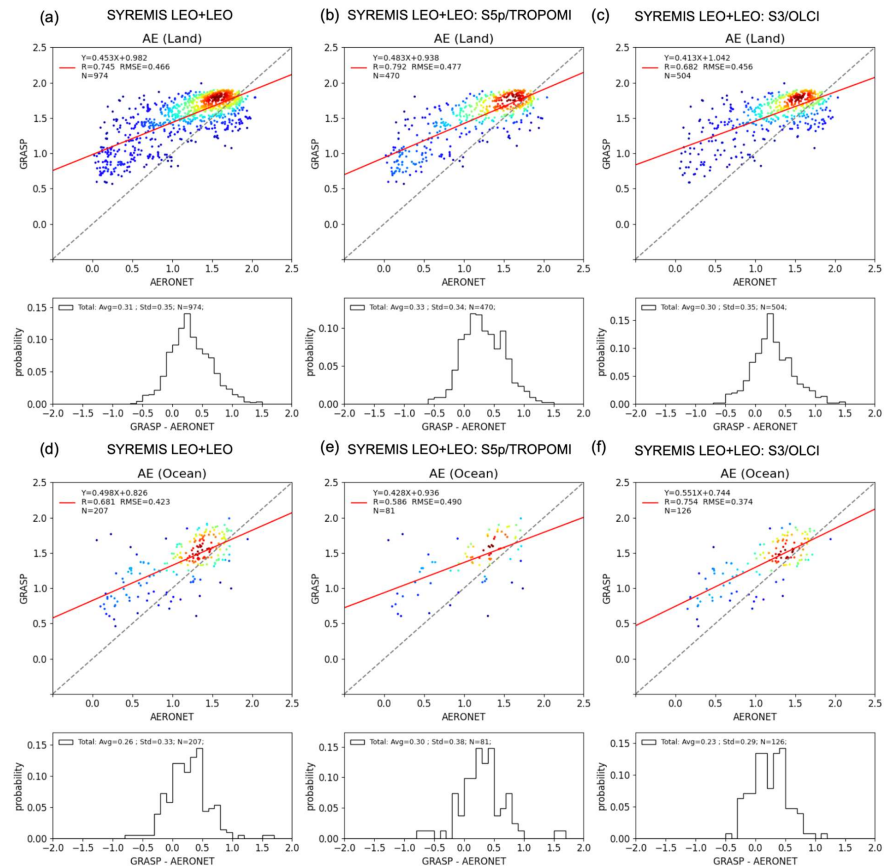
648 **Figure 5: Validation of AOD 550nm with global AERONET data over land and ocean for SYREMIS LEO+LEO synergy global**
 649 **processing in 2019 March, April, and May. Left column of panels: AOD product of all instruments in the synergy; middle column**
 650 **of panels: AOD product of TROPOMI extracted from the synergy; right column of panels: AOD product of S3/OLCI and**
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S3B/OLCI extracted from the synergy. The details of the scatter and PDF plots are explained in Fig. 4 and Section 2.4. The statistical metrics of each panel are summarized in Table 6.



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Figure 6: The same as in Fig. 5, but for Angstrom Exponent validation vs AERONET. Similar to AOD validation plots in Figs. 4 and 5, in the scatter plot, the color of each datapoint indicates the 2D probability density function value (increasing PDF value corresponds to color gradient from blue to red). In the legend in the top left corner of the scatter plots, the slope and intercept of the linear fit of the data points, the correlation coefficient R, and RMSE of the data points, and the number of data points N are indicated. Below each scatter plot, there is a corresponding histogram showing the error distribution, and in the legend over the top of the histogram, the bias between SYREMIS and AERONET AE ("Avg"), the standard deviation ("Std"), and the number of data points are indicated. The statistical metrics of each panel are summarized in Table 7.

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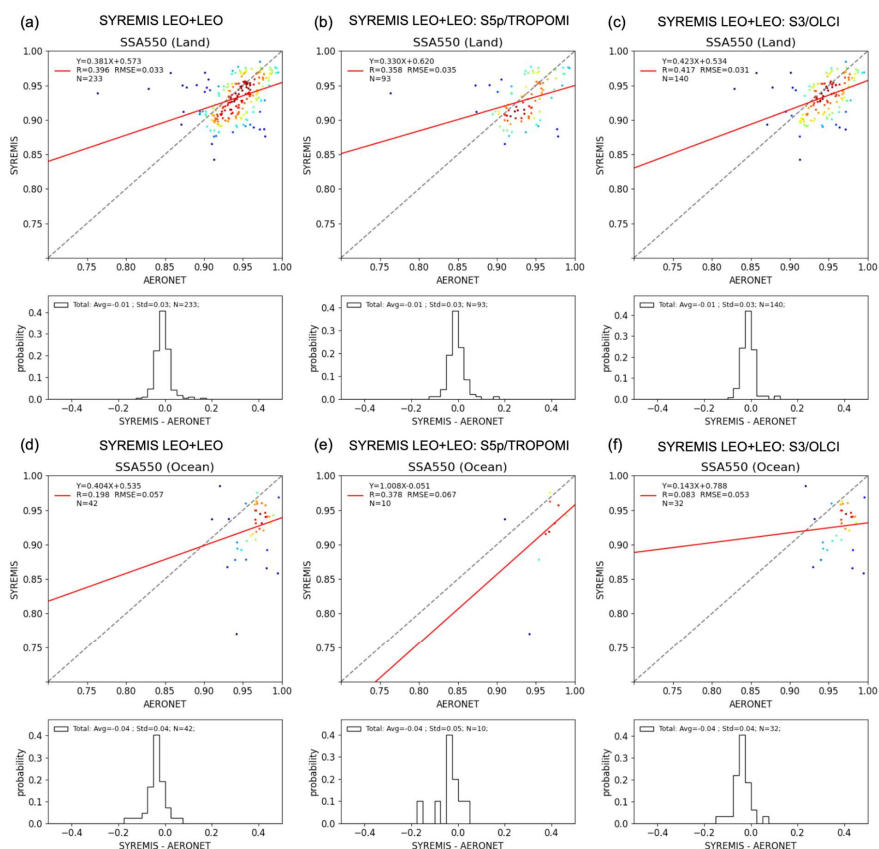


Figure 7: The same as in Fig.6 (AE) but for Single Scattering Albedo (SSA) 550 nm validation vs AERONET. The statistical metrics of each panel are summarized in Table 7.

Table 6. Summary of AOD 550nm validation statistics for the SYREMIS LEO+LEO global processing validation in Fig.5. Each row in the table corresponds to one validation plot in Fig.5.

AOD 550nm validation statistics									
SYREMIS LEO+LEO	GCOS (Total)	GCOS (AOD<0.2)	GCOS (0.2≤AOD)	GCOS (AOD>0.7)	Bias (Total)	Bias (AOD<0.2)	Bias (0.2≤AOD)	Bias (AOD>0.7)	R (Total)
									RMSE (Total)

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		2)	≤0.7)	1		1	≤0.7)	7)		
Fig. 5a (All, land)	54.3%	61%	25.9%	26.5%	-0.01	0.01	-0.06	-0.19	0.893	0.094
Fig. 5b (SSP, land)	53.9%	59.3%	30.4%	40.2%	0	0.02	-0.03	-0.13	0.913	0.09
Fig. 5c (S3, land)	54.5%	62.1%	22.6%	14.3%	-0.01	0.01	-0.09	-0.24	0.878	0.096
Fig. 5d (All, ocean)	65%	69.3%	45.1%	40%	0.01	0.01	0	-0.01	0.881	0.06
Fig. 5e (SSP, ocean)	63.3%	68%	42.2%	50%	0.02	0.02	0.03	0.04	0.911	0.058
Fig. 5f (S3, ocean)	66%	70%	46.9%	25%	0.01	0.01	-0.01	-0.08	0.861	0.061

Table 7. Summary of AE and SSA (550nm) validation statistics for the SYREMIS LEO+LEO global processing validation in Figs. 6 and 7. Each row in the table corresponds to one validation plot in Figs. 6 and 7.

AE validation statistics				SSA 550nm validation statistics			
SYREMIS LEO+LEO	Bias	R	RMSE	SYREMIS LEO+LEO	Bias	R	RMSE
Fig. 6a (All, land)	0.31	0.745	0.466	Fig. 7a (All, land)	-0.01	0.396	0.033
Fig. 6b (SSP, land)	0.33	0.792	0.477	Fig. 7b (SSP, land)	-0.01	0.358	0.035
Fig. 6c (S3, land)	0.3	0.682	0.456	Fig. 7c (S3, land)	-0.01	0.417	0.03
Fig. 6d (All, ocean)	0.26	0.681	0.423	Fig. 7d (All, ocean)	-0.04	0.198	0.057
Fig. 6e (SSP, ocean)	0.30	0.586	0.49	Fig. 7e (SSP, ocean)	-0.04	0.378	0.067
Fig. 6f (S3, ocean)	0.23	0.754	0.374	Fig. 7f (S3, ocean)	-0.04	0.083	0.053

3.2 SYREMIS/GRASP LEO+LEO inter-comparison with GRASP single instrument retrieval over AERONET

Figures 8-11 demonstrate the added value of the synergetic retrieval-by-approach, comparing SYREMIS/TROPOMI and SYREMIS/OLCI-A validation with the onerresults against AERONET of AOD, AE, and SSA, obtained from the

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SYREMIS/GRASP LEO+LEO retrieval and from the corresponding GRASP single-instrument retrieval (GRASP. Specifically, Figs. 8(a), 9(a), and 10(a) present the validation results from the SYREMIS LEO+LEO synergy associated with S5P/TROPOMI and GRASP/OLCI measurements (data extracted from the synergy at the time of TROPOMI measurements: “SYREMIS LEO+LEO: S5P/TROPOMI” in Figs. 8-10). Figs. 8(b), 9(b), and 10(b) show the validation obtained from the GRASP/TROPOMI single-instrument retrievals (Litvinov et al., 2024; Chen et al., 2024a). Overall, Figs. 10-13 present the validation for OLCI data extracted from the SYREMIS LEO+LEO synergy (“SYREMIS LEO+LEO: S3A/OLCI” in Figs. 11(a), 12(a), and 13(a)) and for the GRASP/OLCI-A single-instrument retrieval in Figs. 11(b), 12(b), and 13(b) (Chen et al., 2022). The corresponding intercomparison of validation statistics is summarized in Tables 8-11. In general, one can observe a higher number of retrievals passing the filtering criteria (mainly the residual filter criteria, Section 3.1) in the SYREMIS LEO+LEO products compared to the GRASP single-instrument retrievals, indicating increased quality of the retrieval in the synergy. This improvement may be attributed to enhanced aerosol-surface signal decoupling in the synergy, resulting in smaller spectral fitting residuals. In addition, the GRASP/TROPOMI single-instrument AOD (550 nm) retrieval exhibits some scatter, with an RMSE of 0.139 and a GCOS compliance fraction of 48.4% over land, as shown in Fig. 8b. These metrics are improved in the SYREMIS LEO+LEO: S5P/TROPOMI retrievals, which achieve an RMSE of 0.090 and a GCOS fraction of 53.9%, as shown in Fig. 8a. For the extended aerosol characteristics (AE and SSA), the SYREMIS LEO+LEO: S5P/TROPOMI retrievals show validation statistics that are generally comparable to those from the GRASP/TROPOMI single-instrument retrievals, as presented in Figs. 9 and 10, respectively. On the other hand, a clear improvement is observed for the SYREMIS LEO+LEO: S3A/OLCI aerosol data compared to the GRASP/OLCI-A single-instrument retrievals. Notably, the number of available AOD (550 nm) matchups with AERONET nearly doubles both over land and ocean (Figs. 11a and 11b). Additionally, the GCOS compliance fraction over land increases from 42.5% to 54.5% (Figs. 11a and 11b), similar to the SYREMIS LEO+LEO: S5P/TROPOMI. Although the validation statistics over the ocean show a slight decrease, as seen in Figure 11, the number of successful inversions increases by a factor of three (162 to 543), and more high-AOD values pass the filtering criteria with 64.5% high GCOS fulfillment, indicating enhanced sensitivity and broader retrieval capability in challenging conditions. For the extended aerosol characteristics (AE and SSA), as shown in Figs. 12 and 13, the validation results for the SYREMIS LEO+LEO: S3A/OLCI datasets are considerably improved in comparison with the single instrument GRASP/OLCI-A retrieval and reached a level comparable with those from the GRASP/TROPOMI single-instrument retrievals. These findings further support the conclusion that S5P/TROPOMI remains the dominant contributor to the information content in the SYREMIS LEO+LEO synergistic retrievals.

Summarizing intercomparison results, one can see slightly better performance of the SYREMIS LEO+LEO: S5P/TROPOMI AOD data extract in comparison with TROPOMI/GRASP. SYREMIS/TROPOMI AOD is better than the one derived from TROPOMI/GRASP retrieval, whereas AExp and SSA from the synergy are quite comparable with quality of TROPOMI/GRASP retrieval (Figs. 8-12 in (Litvinov et al., 2024)).

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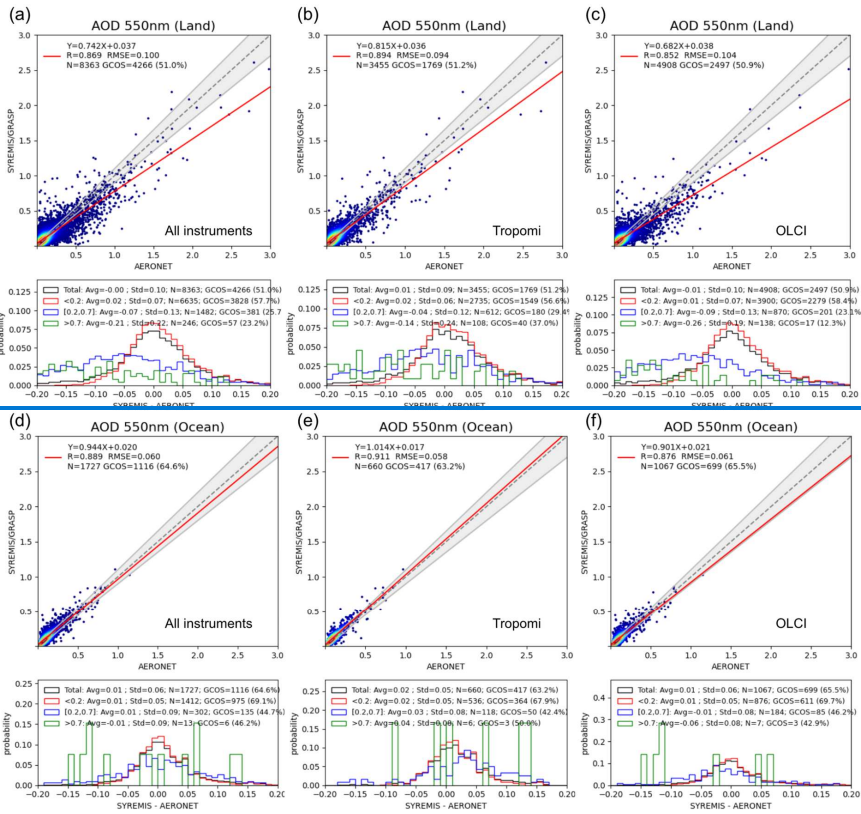
708 the GRASP/TROPOMI, while the extended properties (AE and SSA) are of similar quality in both (synergy and single-
709 instrument retrieval) cases. The biggest improvement is observed for the OLCI instrument, where the performance of all
710 retrieved parameters in SYREMIS LEO+LEO: S3A/OLCI data extract is essentially improved in comparison compared to the
711 independent single-instrument GRASP/OLCI-A retrieval (Figs. 6, 10, 11): AOD, AExp, SSA. In particular, all retrieved
712 characteristics from the synergy (AOD, AE, and SSA) are much better than those from the single OLCI/instrument
713 GRASP/OLCI-A retrieval. Moreover, and the number of pixels passed through the quality filter considerably increased. In
714 general, SSA from the SYREMIS LEO+LEO: S3/OLCI SSA retrieval reaches dataset is of the same quality as for from the
715 SYREMIS/LEO+LEO: S5P/TROPOMI and GRASP/TROPOMI with RMSE less than 0.05 (Litvinov et al., 2024; Chen et al.,
716 2024a), providing aligned retrieval for all instruments from the synergy.

717

718 The presented results clearly show that properly combining measurements from the S3A/OLCI, S3B/OLCI, and
719 S5P/TROPOMI, according to the information content and accuracy, the synergetic SYREMIS/GRASP approach
720 essentially considerably improves the retrieval of the extended aerosol characterization in comparison to the single instrument
721 retrieval. Overall it enables to transfer of information content from one instrument to another, which results in consistent aerosol
722 characterization from non-coincident diverse satellite measurements. As a result, the quality of the retrieval for all instruments
723 in the SYREMIS/GRASP LEO+LEO synergy is comparable to or better than the quality from the GRASP/TROPOMI/GRASP
724 single-instrument retrieval and much better than OLCI from the GRASP/OLCI single-instrument retrieval. This can be
725 explained by the fact that S5P/TROPOMI measurements provide a richer information content than S3/OLCI (bigger spectral
726 coverage, have a wider spectral range and swath) and is (consequently, better temporal resolution) than S3/OLCI. They are
727 also known for its their high radiometric accuracy (Ludewig et al., 2020; Tilstra et al., 2020). Therefore, the synergetic retrieval
728 allows the transition of the information content from one instrument to another. In addition, such synergy allows consistent
729 aerosol characterization from non-coincident diverse satellite measurements. In particular, SYREMIS/GRASP approach
730 provides diurnal variability of the extended aerosol properties from S3A/OLCI, S3B/OLCI and S5P/TROPOMI multiple
731 overpasses over the same geolocation. All these are crucial for atmosphere and surface signals differentiation and enhancement
732 of the retrieval as demonstrated in Litvinov et al., 2024 and Cheng et al., 2024a, and emphasized in the presented
733 SYREMIS/GRASP synergetic results.

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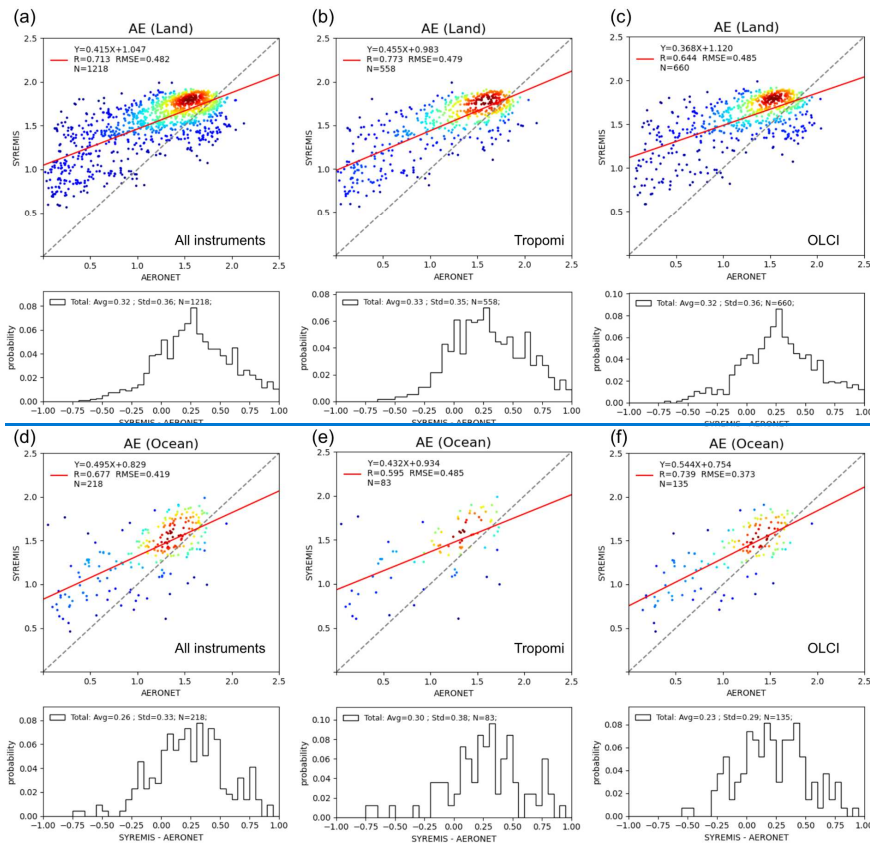
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Figure 5: The same as statistical metrics of each panel are summarized in Fig. 4 but for AExp Table 8.

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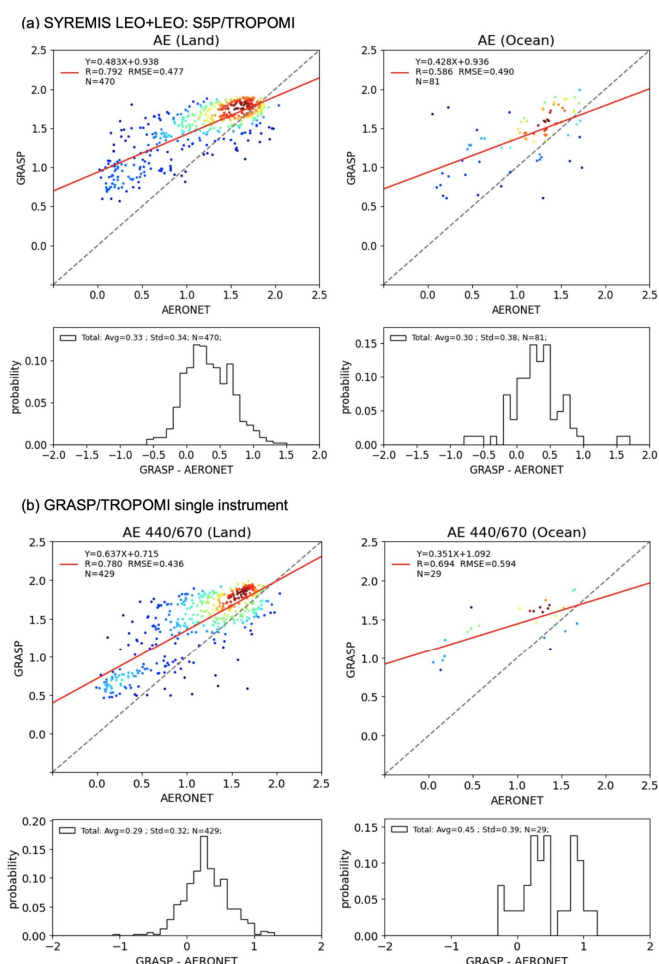


Figure 9: AE validation vs AERONET.

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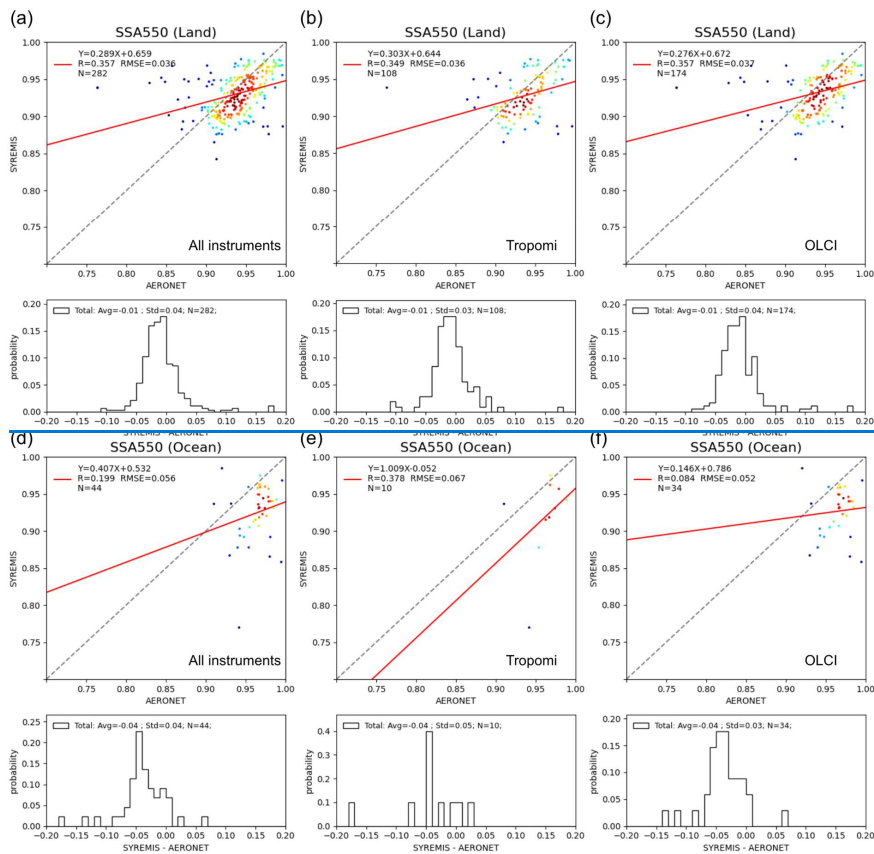


Figure 6: The same as in Fig. 4 but for SSA validation vs AERONET.

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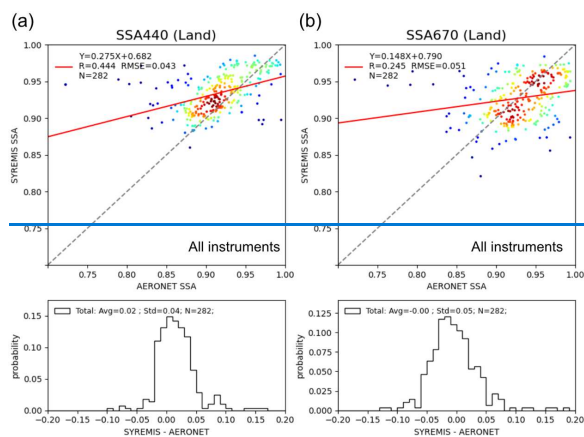


Figure 7: SSA 440 and 670nm validation vs AERONET over land for SYREMIS/GRASP from (a) SYREMIS LEO+LEO synergy, March, April, May 2019.

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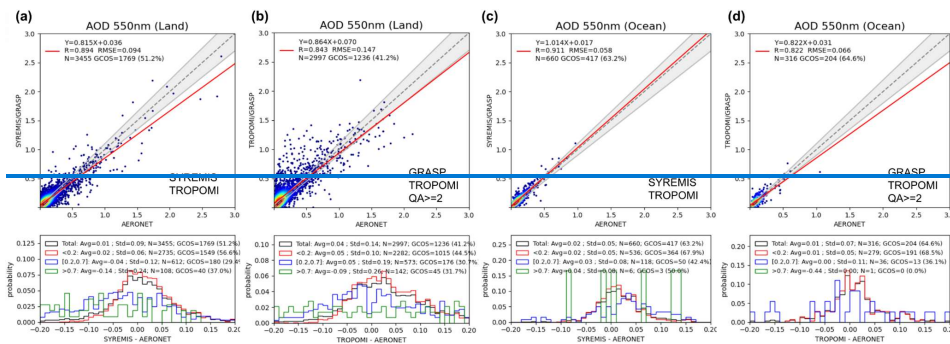


Figure 8: AOD (550) validation vs: TROPOMI and (b) GRASP/TROPOMI versus AERONET over land and ocean for SYREMIS/TROPOMI and TROPOMI in 2019 March, April, and May. The statistical metrics of each panel are summarized in Table 9.

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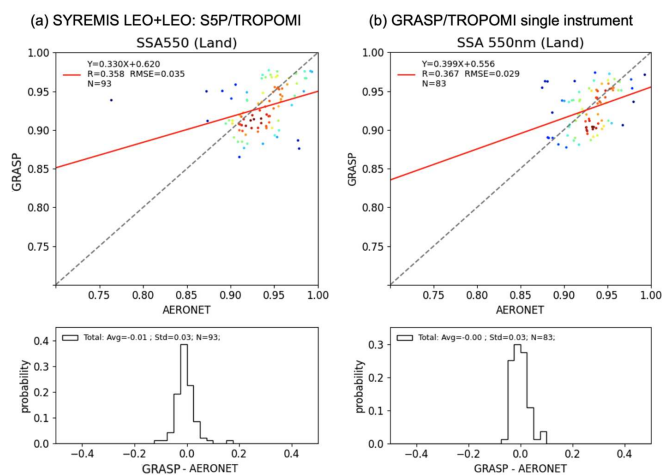


Figure 10: SSA validation from (a) SYREMIS LEO+LEO: TROPOMI and (b) GRASP/TROPOMI versus AERONET over land and ocean in 2019 March, April, and May. The statistical metrics of each panel are summarized in Table 9.

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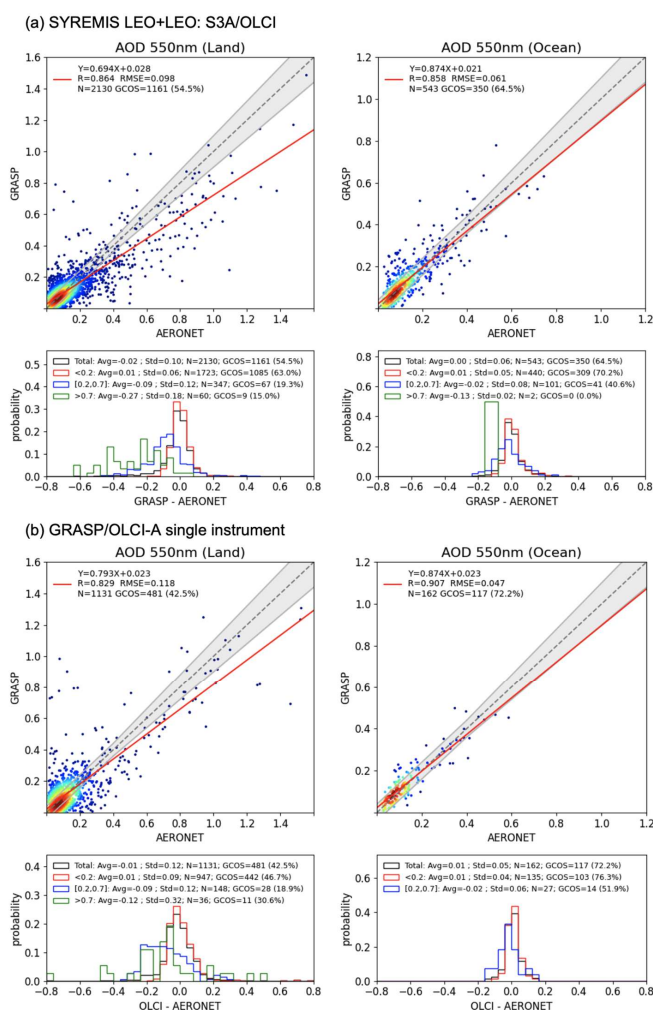


Figure 11: AOD validation from (a) SYREMIS LEO+LEO: S3A/OLCI and (b) GRASP (QA>=2) products, March, April, May 2019.

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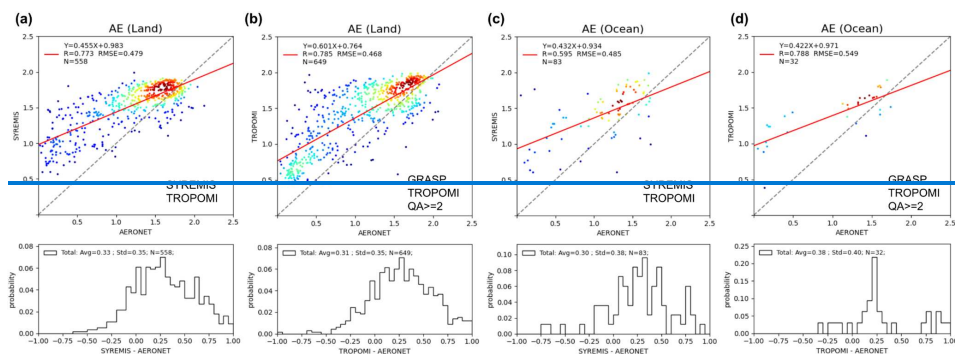


Figure 9: The same as in Fig. 8 but for AExp.

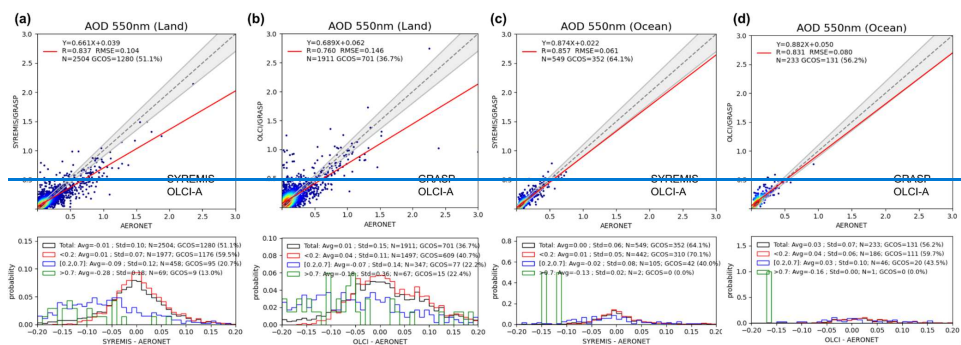


Figure 10: AOD(550) validation vs. SYREMIS/OLCI-A versus AERONET over land and ocean for SYREMIS/OLCI-A and OLCI-A/GRASP products in 2019 March, April, and May 2019. The statistical metrics of each panel are summarized in Table 10.

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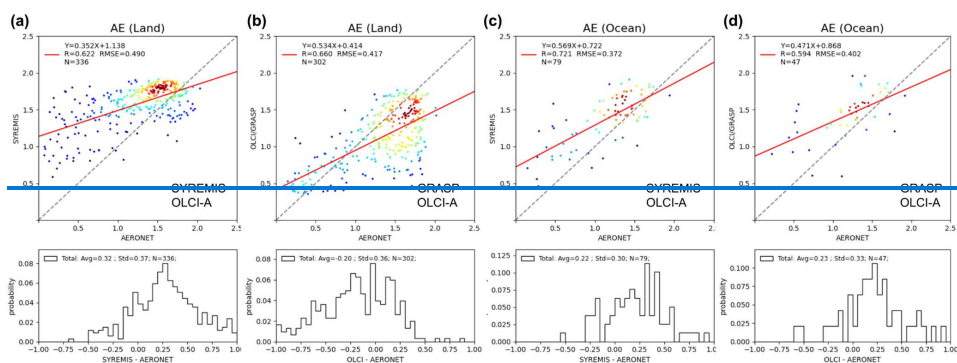
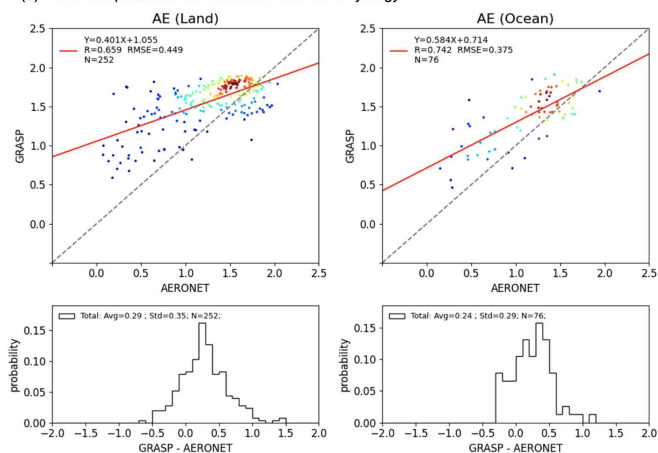


Figure 11: The same as in Fig. 10 but for AExp.

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(a) S3A/OLCI product from SYREMIS LEO+LEO synergy



(b) GRASP/OLCI-A single instrument

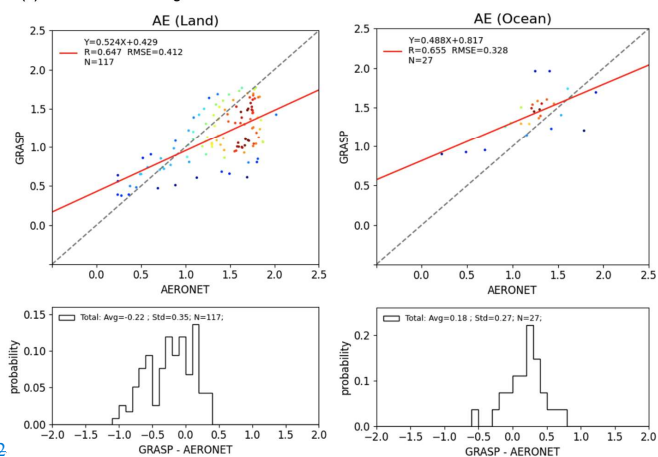


Figure 12: AE validation from (a) SYREMIS LEO+LEO: S3A/OLCI and (b) GRASP/OLCI-A versus AERONET over land and ocean in 2019 March, April, and May. The statistical metrics of each panel are summarized in Table 11.

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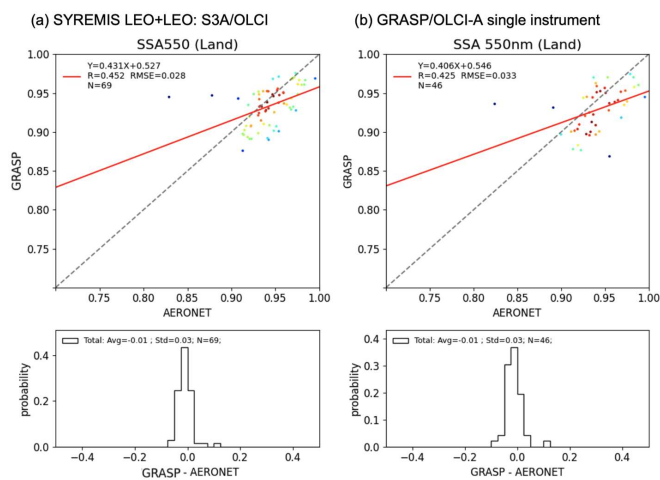


Figure 13: SSA validation from (a) SYREMIS LEO+LEO: S3A/OLCI and (b) GRASP/OLCI-A versus AERONET over land and ocean in 2019 March, April, and May. The statistical metrics of each panel are summarized in Table 11.

Table 8. Intercomparison of AOD (550 nm) AERONET validation statistics from SYREMIS LEO+LEO: S5P/TROPOMI and GRASP/TROPOMI single-instrument retrievals over land and ocean (Fig.8). The best performing metric is indicated in bold.

AOD 550nm validation statistics											
	N	GCOS (Total)	GCOS (AOD<0.2)	GCOS (0.2≤AOD<0.7)	GCOS (AOD>0.7, 1)	Bias (Total)	Bias (AOD<0.2)	Bias (0.2≤AOD<0.7)	Bias (AOD>0.7)	R (Total)	RMSE (Total)
SYREMIS LEO+LEO/TR OPMI, Land	3038	53.9%	59.3%	30.4%	40.2%	0	0.02	-0.03	-0.13	0.913	0.09
GRASP/TROP OMI, Land	2137	48.4%	52.8%	33%	35.8%	0.03	0.03	0.04	-0.09	0.869	0.139
SYREMIS LEO+LEO/TR OPMI, Ocean	657	63.3%	68%	42.2%	50%	0.02	0.02	0.03	0.04	0.911	0.058
GRASP/TROP OMI, Ocean	399	61.4%	64.2%	44.2%	0%	0.02	0.02	0.02	-0.08	0.85	0.062

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Table 9. Intercomparison of AE and SSA (550 nm) AERONET validation statistics from the SYREMIS LEO+LEO: S5P/TROPOMI and GRASP/TROPOMI single-instrument retrievals over land and ocean (Figs. 9 and 10). The best performing metric is indicated in bold.

AE validation statistics					SSA 550nm validation statistics				
	N	bias	R	RMSE		N	bias	R	RMSE
SYREMIS LEO+LEO/TROPOMI, Land	470	0.33	0.792	0.477	SYREMIS LEO+LEO/TROPOMI, Land	93	-0.01	0.358	0.035
GRASP/TROPOMI, Land	429	0.29	0.78	0.436	GRASP/TROPOMI, Land	83	0	0.367	0.029
SYREMIS LEO+LEO/TROPOMI, Ocean	81	0.3	0.586	0.49	=				
GRASP/TROPOMI, Ocean	29	0.45	0.694	0.594	=				

Table 10. Intercomparison of AOD (550 nm) AERONET validation statistics from SYREMIS LEO+LEO: S3A/OLCI and GRASP/OLCI single-instrument retrievals over land and ocean (Fig. 11). The best performing metric is indicated in bold.

AOD 550nm validation statistics											
	N	GCOS (Total)	GCOS (AOD<0.2)	GCOS (0.2≤AOD≤0.7)	GCOS (AOD>0.7)	Bias (Total)	Bias (AOD<0.2)	Bias (0.2≤AOD≤0.7)	Bias (AOD>0.7)	R (Total)	RMSE (Total)
SYREMIS LEO+LEO/OLCI-A, Land	2130	54.5%	63%	19.3%	15%	-0.02	0.01	-0.09	-0.27	0.864	0.098
GRASP/OLCI-A, Land	1131	42.5%	46.7%	18.9%	30.6%	-0.01	0.01	-0.09	-0.12	0.829	0.118
SYREMIS LEO+LEO/OLCI-A, Ocean	543	64.5%	70.2%	40.6%	0%	0	0.01	-0.02	-0.13	0.858	0.061
GRASP/OLCI-A, Ocean	162	72.2%	76.3%	51.9%	N/A	0.01	0.01	-0.02	N/A	0.907	0.047

Table 11. Intercomparison of AE and SSA (550 nm) AERONET validation statistics from the SYREMIS LEO+LEO: S3A/OLCI and GRASP/OLCI single-instrument retrievals over land and ocean (Figs. 12 and 13). The best performing metric is indicated in bold.

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AE validation statistics					SSA 550nm validation statistics				
	N	bias	R	RMSE		N	bias	R	RMSE
SYREMIS LEO+LEO/OLCI-A, Land	252	0.29	0.659	0.449	SYREMIS LEO+LEO/OLCI-A, Land	69	-0.01	0.452	0.028
GRASP/OLCI-A, Land	117	-0.22	0.647	0.412	GRASP/OLCI-A, Land	46	-0.01	0.425	0.033
SYREMIS LEO+LEO/OLCI-A, Ocean	76	0.24	0.742	0.375	=				
GRASP/OLCI-A, Ocean	27	0.18	0.655	0.328	=				

3.3 SYREMIS/GRASP LEO+GEO synergeticsynergy performance versus AERONET and intercomparison with LEO+LEO synergy

Validation of AOD, AExpAE, and SSA from the SYREMIS LEO+GEO synergy over all AERONET stations within Himawari-8/AHI full scan is presented in Figs. 12–14. Similarly to 14–16 and summarized in Tables 12 and 13. Similar to the LEO+LEO synergy, the results are presented for all instruments involved in the SYREMIS/GRASP synergy, as well as for the data extracted for each specific instrument: (SYREMIS LEO+GEO: S5P/TROPOMI, SYREMIS/ LEO+GEO: S3/OLCI (OLCI-A and OLCI-B) and SYREMIS/AHI. One can see very consistent, harmonized retrieval for different spectral bands and for all instruments. In particular, AOD, AExp and SSA retrievals are quite comparable for all instruments in the synergy, and SYREMIS LEO+GEO: Himawari-8/AHI). The retrievals of the AOD, AE, and SSA are highly comparable across all instruments in the synergy. For example, the AOD (550 nm) validation with AERONET shows the correlation coefficients around 0.92, the RMSE values near 0.15, and the GCOS-based fraction of approximately 40%. While the RMSE and GCOS-based fraction are slightly worse than the global SYREMIS LEO+LEO AOD (550 nm) validation results presented in Fig. 5, this difference can be attributed to the Himawari-8/AHI full scan region, which includes a higher proportion of high-AOD cases and thus poses more challenging retrieval conditions. Moreover, for all instruments AExp, AE (with RMSE < 0.3) and SSA (with RMSE < 0.505) are of the same similar quality as AExp to AE and SSA retrieved from GRASP/TROPOMI (Litvinov et al., 2024) and the SYREMIS LEO+LEO synergy (Figs. 5, 6). Being compared with SYREMIS LEO+LEO over the same AERONET stations, LEO+GEO synergy shows further improvement in AOD characterization (Fig. 56 and 7).

In general, the validation and inter-comparison results show that, similarly similar to the LEO+LEO synergy, richer information content from the S5P/TROPOMI “propagate” propagates to other instruments of the SYREMIS LEO+GEO synergy

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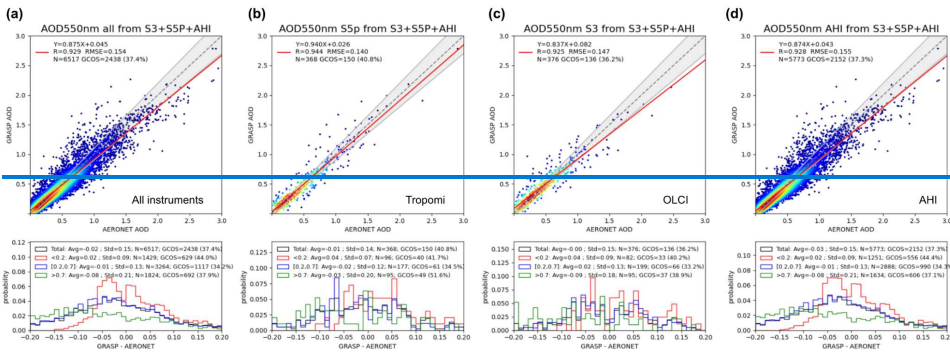
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(S3A/OLCI, S3B/OLCI, and Himawari-8/AHI), improving extended aerosol characteristics, for example, AExp such as AE and spectral SSA. At the same time, AOD is improved for all instruments in the SYREMIS LEO+GEO synergy, including S5P/TROPOMI, due to the additional spatial, temporal, and spectral information content in the synergetic measurements. Moreover, one of the crucial advantages of the LEO+GEO synergy is the high temporal resolution of the extended aerosol characterization (AOD, AExp, AE, SSA, etc.). In particular, the considered SYREMIS LEO+GEO synergy provides diurnal variability of aerosol with it is about ~1 hour~1 h temporal resolution, which allows for monitoring aerosol transport, air quality, and atmosphere can be used in atmospheric dynamics studies. The observed unique advantages in capturing the diurnal variability of aerosol optical-microphysical properties from the LEO+GEO SYREMIS product will be reported and discussed in a separate study.



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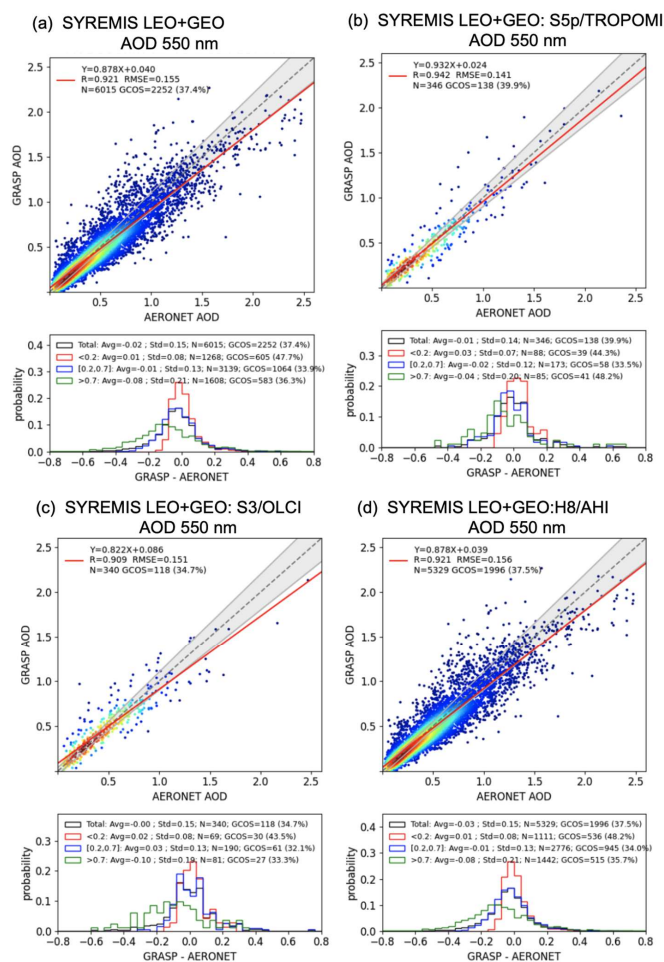


Figure 12: AOD55014: AOD 550nm validation against AERONET sites data over land for SYREMIS/GRASP LEO+GEO synergy-synergetic retrieval in 2019 March, April, and May 2019. (a): validation of AOD of all instruments in the synergy; (b): validation of AOD of S5p/TROPOMI extracted from the synergy; (c): validation of AOD of S3/OLCI extracted from the synergy; (d): validation of AOD of Himawari-8/AHI extracted from the synergy. The statistical metrics are summarized in Table 12.

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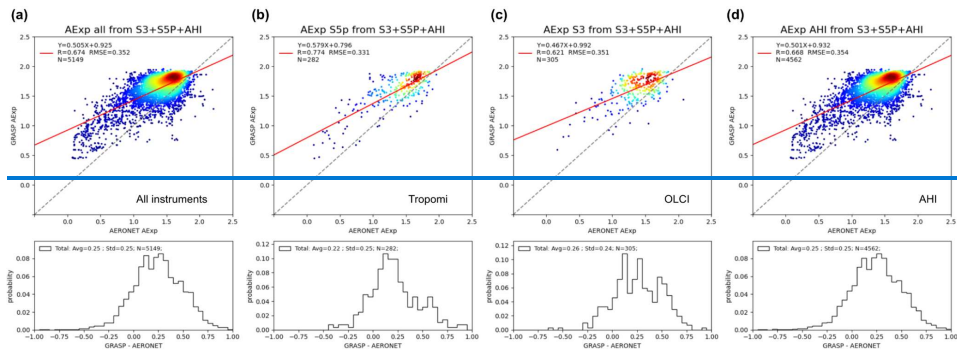
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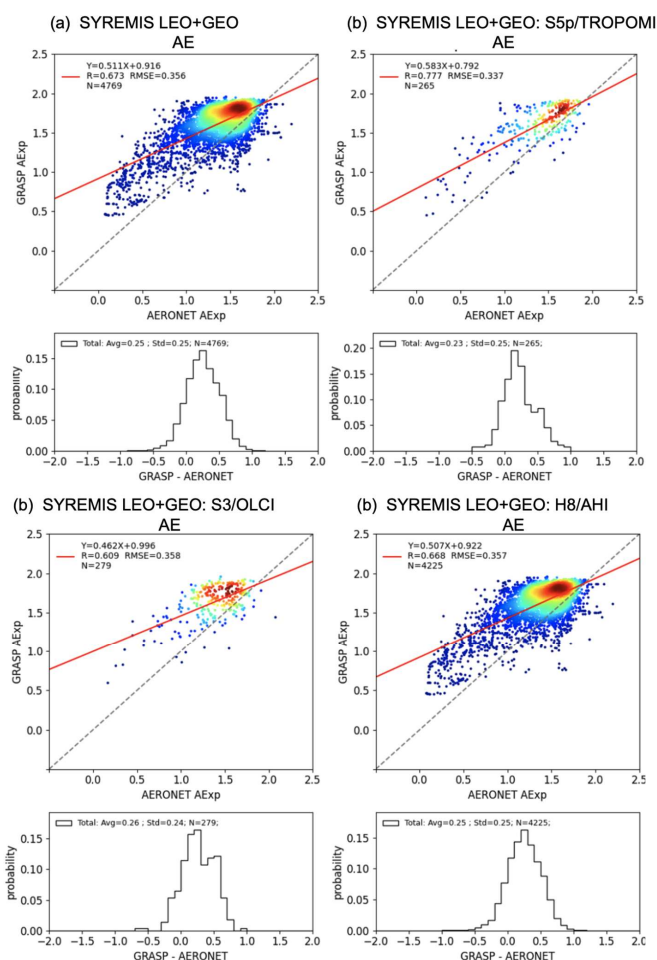


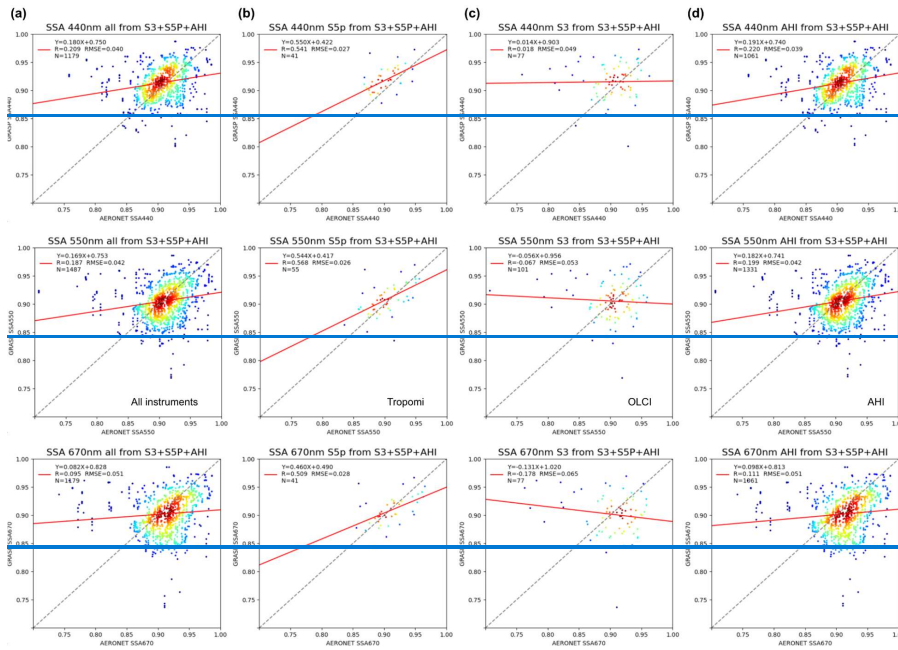
Figure 13: AExp15: Angstrom Exponent (AE) validation against AERONET sites data over land for SYREMIS/GRASP LEO+GEO synergy-synergetic retrieval in 2019 March, April, and May 2019. (a): validation of AE of all instruments in the synergy; (b): validation of AE of S5p/TROPOMI extracted from the synergy; (c): validation of AE of S3/OLCI extracted from the synergy; (d): validation of AE of Himawari-8/AHI extracted from the synergy. The statistical metrics are summarized in Table 13.

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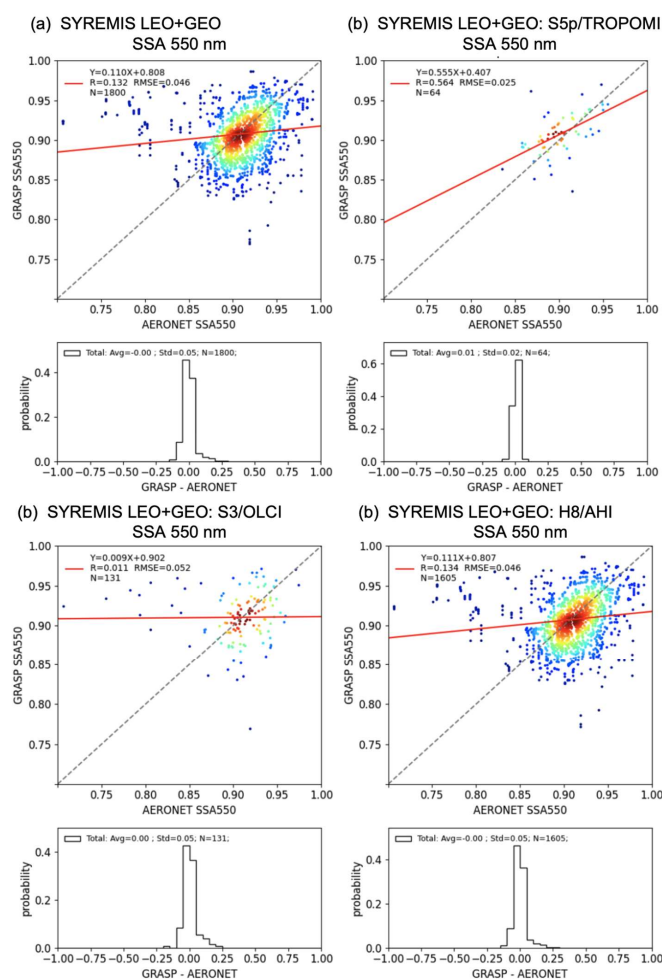


Figure 14-16: Single Scattering Albedo (SSA) 550nm validation against AERONET data over land for SYREMIS/GRASP LEO+GEO synergy-synergetic retrieval in 2019, March, April, and May-2019. (a): validation of SSA of all instruments in the synergy; (b): validation of SSA of S5p/TROPOMI extracted from the synergy; (c): validation of SSA of S3/OLCI extracted from the synergy; (d): validation of SSA of Himawari-8/AHI extracted from the synergy. The statistical metrics are summarized in Table 13.

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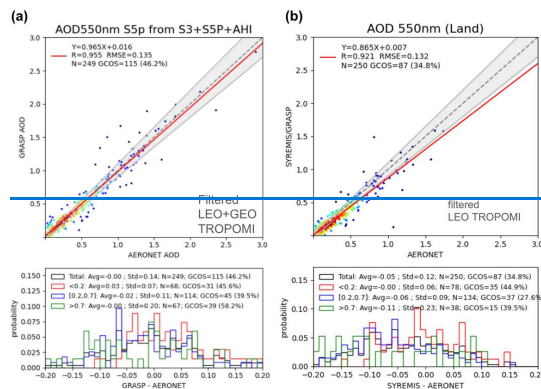


Figure 15: AOD550nm validation statistics for the same AERONET sites over land: SYREMIS/AOD vs SYREMIS/AOD LEO+GEO vs SYREMIS/AOD LEO+processing in Fig. 14. Each row in the table corresponds to one validation plot in Fig. 14.

AOD 550nm validation statistics									
SYREMIS LEO+GEO	GCOS (Total)	GCOS (AOD<0.2)	GCOS (0.2≤AOD ≤0.7)	GCOS (AOD>0.7)	Bias (Total)	Bias (AOD<0.2)	Bias (0.2≤AOD ≤0.7)	Bias (AOD>0.7)	R (Total)
Fig. 14a (All, land)	37.4%	47.7%	33.9%	36.3%	-0.02	0.01	-0.01	-0.08	0.921
Fig. 14b (S5p, land)	39.9%	44.3%	33.5%	48.2%	-0.01	0.03	-0.02	-0.04	0.942
Fig. 14c (S3, land)	34.7%	43.5%	32.1%	33.3%	0	0.02	0.03	-0.1	0.909
Fig. 14d (AHL, land)	37.5%	48.2%	34%	35.7%	-0.03	0.01	-0.01	-0.08	0.921
RMSE (Total)									
	0.155	0.141	0.151	0.156					

Table 13. Summary of Angstrom Exponent and Single Scattering Albedo validation statistics for the SYREMIS LEO-March, April, 2019+GEO processing in Figs. 15 and 16. Each row in the table corresponds to one validation plot in Figs. 15 and 16.

AE validation statistics				SSA 550nm validation statistics			
SYREMIS LEO+GEO	Bias	R	RMSE	SYREMIS LEO+GEO	Bias	R	RMSE

Fig. 15a (All, land)	0.25	0.673	0.356	Fig. 16a (All, land)	0	0.132	0.046
Fig. 15b (S5P, land)	0.23	0.777	0.337	Fig. 16b (S5P, land)	0.01	0.564	0.025
Fig. 15c (S3, land)	0.26	0.609	0.358	Fig. 16c (S3, land)	0	0.011	0.052
Fig. 15d (AHI, land)	0.25	0.668	0.357	Fig. 16d (AHI, land)	0	0.134	0.046

3.34 SYREMIS/GRASP aerosol and surface products global intercomparison

In this section, we present a preliminary intercomparison of aerosol and surface products global intercomparison.

Figures 16–18 show comparison of, obtained from the SYREMIS/GRASP synergetic retrieval, with GRASP results from S5P/TROPOMI, S3A/OLCI as well as with VIIRS, and MODIS aerosol and surface products (Hsu et al., 2013; 2019; Sayer et al., 2018; Schaaf et al., 2015a, 2015b; Chen et al., 2022; Litvinov et al., 2024). The comparison was a more detailed analysis of the global SYREMIS product will be performed in separate studies.

Figure 17 shows within 1 month (March, 2019) on the the global maps of the March 2019 monthly mean AOD at 550nm for the SYREMIS LEO+LEO: S5P/TROPOMI (TROPOMI data extraction from the synergy, indicated as SYREMIS/TROPOMI in Fig. 17), GRASP/TROPOMI (single-instrument GRASP retrieval from TROPOMI), VIIRS/DB, and their differences. The SNPP/VIIRS AERDB L2 VIIRS SNPP aerosol product (Hsu et al., 2013, 2019) was used in the intercomparison. All products were regridded to the same 0.2-degree global equi-rectangular grid for pixel-level collocated in time (to pixel-by-pixel comparison). To do this, the SYREMIS/TROPOMI and SYREMIS/OLCI pixels were extracted from SYREMIS LEO+LEO intercomparison.

Globally, SYREMIS/TROPOMI AOD values show good qualitative agreement with single-instrument GRASP/TROPOMI and VIIRS products. Nevertheless, the quantitative intercomparison (see the maps of the differences 'VIIRS/DB-SYREMIS/TROPOMI' and 'TROPOMI/GRASP-TROPOMI/SYREMIS' in Fig. 17) shows that the synergetic retrieval and then compared with corresponding pixels collocated in space and time from independent TROPOMI/GRASP, OLCI/GRASP, VIIRS and MODIS retrieval SYREMIS/TROPOMI AOD is lower than the GRASP/TROPOMI and VIIRS products over: (i) bright surfaces (e.g., over the Sahara and the Arabian Peninsula); (ii) the North Indian Subcontinent and the East coast of China, where AOD is quite large for all products; and (iii) the South polar regions, where AOD is very small for all products. In general, AOD products from the single instruments (GRASP/TROPOMI and VIIRS/DB) correspond to each other better than they correspond to the SYREMIS/GRASP AOD (see maps of the differences: 'VIIRS/DB-TROPOMI/GRASP'.

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'VIIRS/DB-SYREMIS/TROPOMI', and 'TROPOMI/GRASP - TROPOMI/SYREMIS' in Fig. 17). A more detailed analysis of the global aerosol characterization with the synergetic approach will be the subject of separate studies.

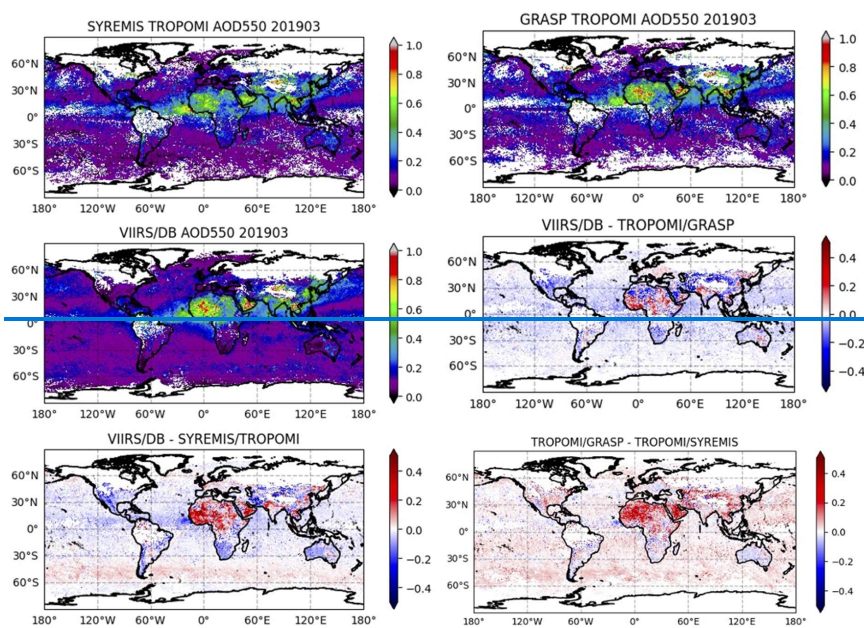
One can see from Fig. 16 that, overall, SYREMIS/GRASP AOD retrieval corresponds well to VIIRS, MODIS, TROPOMI/GRASP and OLCI/GRASP products. The SYREMIS/TROPOMI provides AOD values lower than VIIRS over Saharan and Arabian Peninsula, North Indian Subcontinent, East coast of China and South polar regions. In comparison to the TROPOMI/GRASP results, the SYREMIS/TROPOMI Figure 18 shows a little bit smaller AOD globally.

Figure 17 shows a very similar retrieval of the first (isotropic) BRDF parameter from the SYREMIS/TROPOMI relatively data extraction compared to the MODIS product. (the MODIS MCD43C1 Terra+Aqua BRDF Model Parameters Daily L3 Global 0.05Deg CMG product suite (Schaaf and Wang, 2015b) was used), regridded to the same 0.2-degree global equirectangular grid for pixel-to-pixel intercomparison. Depending on the region, the SYREMIS/GRASP can provide a brighter or darker surface in comparison compared to MODIS. In the blue spectral band, SYREMIS/TROPOMI BRDF1 (the isotropic Ross-Li BRDF parameter) values are generally lower than MODIS BRDF1 values in the Saharan desert, the Middle East, and Tibet, and higher than MODIS BRDF1 in other regions. In the red spectral band, the difference between SYREMIS/TROPOMI and MODIS BRDF1 shows an opposite spatial distribution. In Central Asia and Tibet, MODIS BRDF1 is higher than SYREMIS/TROPOMI BRDF1 in both the 'blue' and 'red' spectral bands. SYREMIS and MODIS BRDF maps differ in spatial completeness over the Amazon and high-latitude regions due to differences in their cloud/snow masks.

The biggest/largest difference in the surface retrieval emerging from the synergetic approach can be found in the second (volumetric) and third (geometric) Ross-Li BRDF parameters, describing which describe the angular profile of the surface reflectance. As can be seen from Fig. 1819, the values of these parameters derived by the SYREMIS/GRASP over bright surfaces (for example, e.g., over the Sahara) are essentially much higher than those ones from the MODIS BRDF product. This can be well clearly seen from the pixel-by-pixel comparison correlation in Fig. 4920. The stronger variability of the second and third BRDF parameters can be explained by the pseudo multi-angular measurements in the synergetic retrieval with much more angular information than from any of the single instruments with observation angle per measurements (MODIS, S5P/TROPOMI, S3A/OLCI or S3B/OLCI etc.). Due to this fact, SYREMIS synergy measurements provides much more information about the surface angular reflectance properties which results in better characterization of BRDF parameters representing surface angular dependence. In particular, the SYREMIS LEO+LEO accounts for S5P/TROPOMI, S3A/OLCI, and S3B/OLCI measurements within about one month, using temporal thresholds and "multi-pixel" temporal constraints of the GRASP algorithm (Table 4). This allowed for the accumulation of up to hundreds of synergetic measurements obtained at different observation/illumination geometries (zenith and azimuthal angles of the sun and satellites), which are accounted for in the GRASP multi-pixel LSM method (see Section 2). As a result, the synergetic retrieval of the angular features of BRDF (provided by the volumetric and geometric Ross-Li BRDF parameters) is expected to be much more comprehensive than any

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914 [single-instrument retrieval, including a multi-day MODIS Terra+Aqua combination. Similar to the global aerosol product,](#)
915 [synergetic surface BRDF retrieval on a global scale will be the subject of subsequent studies.](#)
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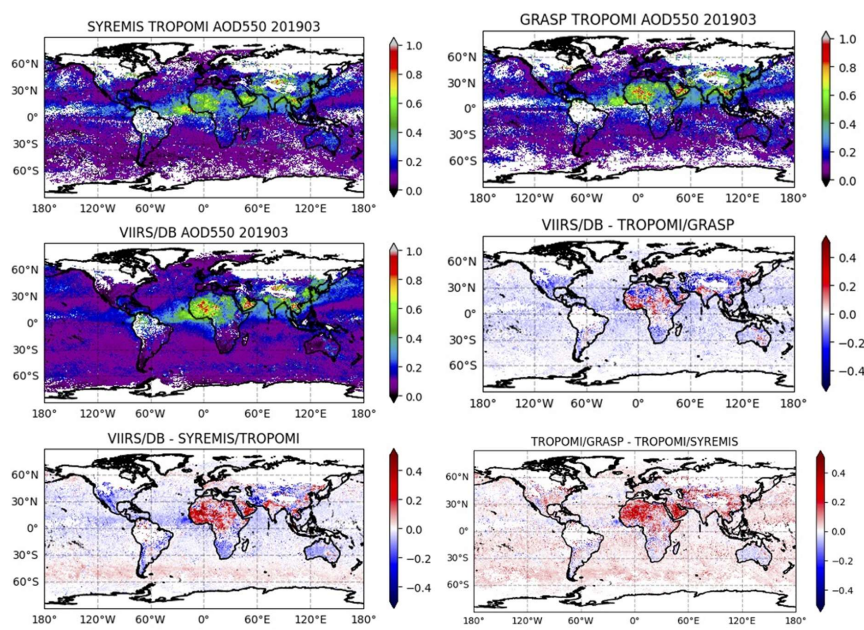


Figure 16:17: Global map of monthly mean AOD global map, TROPOMI/at 550nm of SYREMIS, TROPOMI/GRASP/TROPOMI/GRASP, and VIIRS/DB, in March 2019. The difference between the three products is also presented "VIIRS/DB-TROPOMI/GRASP", "VIIRS/DB- SYREMIS/TROPOMI", "TROPOMI/GRASP-TROPOMI/SYREMIS"

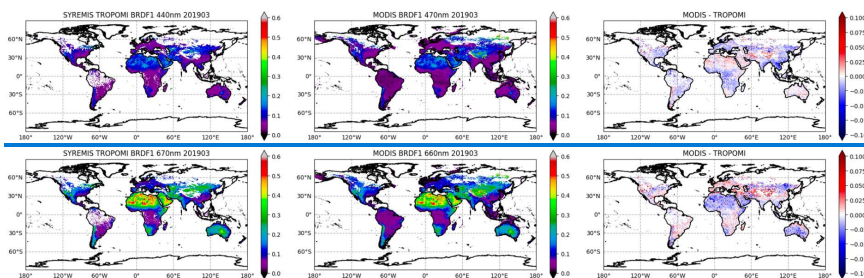


Figure 17: BRDF first parameter, SYREMIS: 440, 670, MODIS: 470, 660, March 2019

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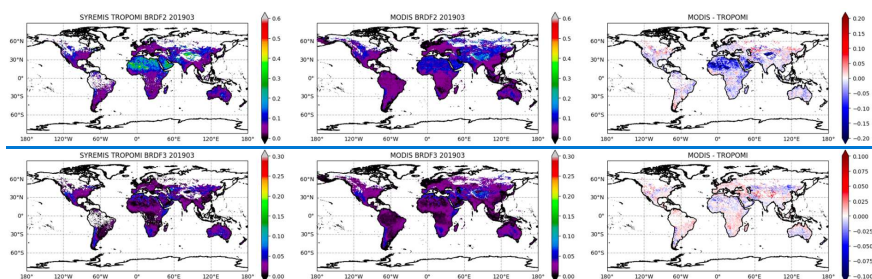
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(a) SYREMIS/TROPOMI vs MODIS BRDF1 (blue band)

(b) SYREMIS/TROPOMI vs MODIS BRDF1 (red band)

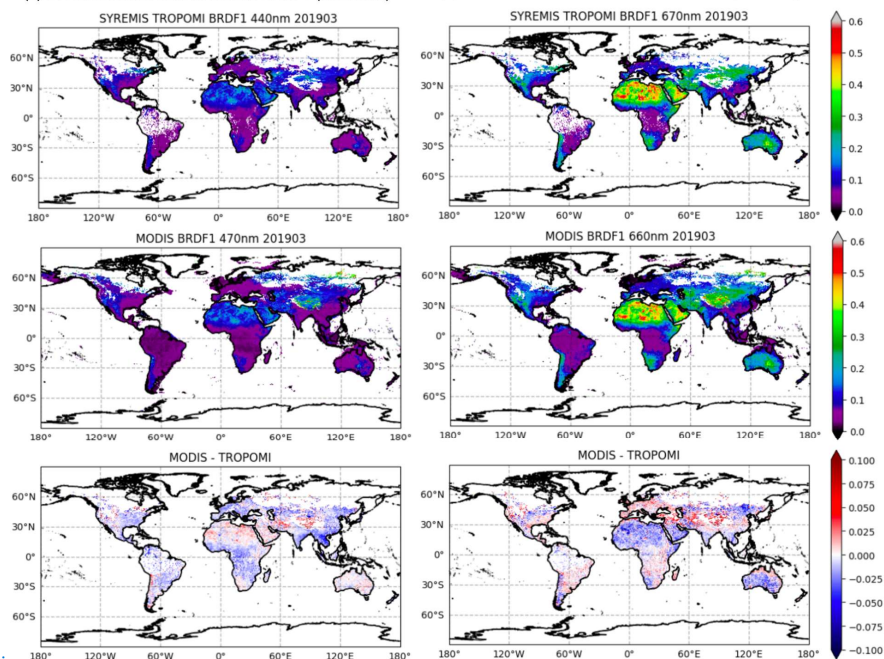


Figure 18:

Figure 18: Global intercomparison of SYREMIS/TROPOMI and MODIS Ross-Li BRDF 1st model parameter (isotropic) at "blue" band (440 and 470 nm) (a) and "red" band (670 and 660 nm) (b). The difference between the two products is presented as "MODIS-TROPOMI" at "blue" and "red" bands.

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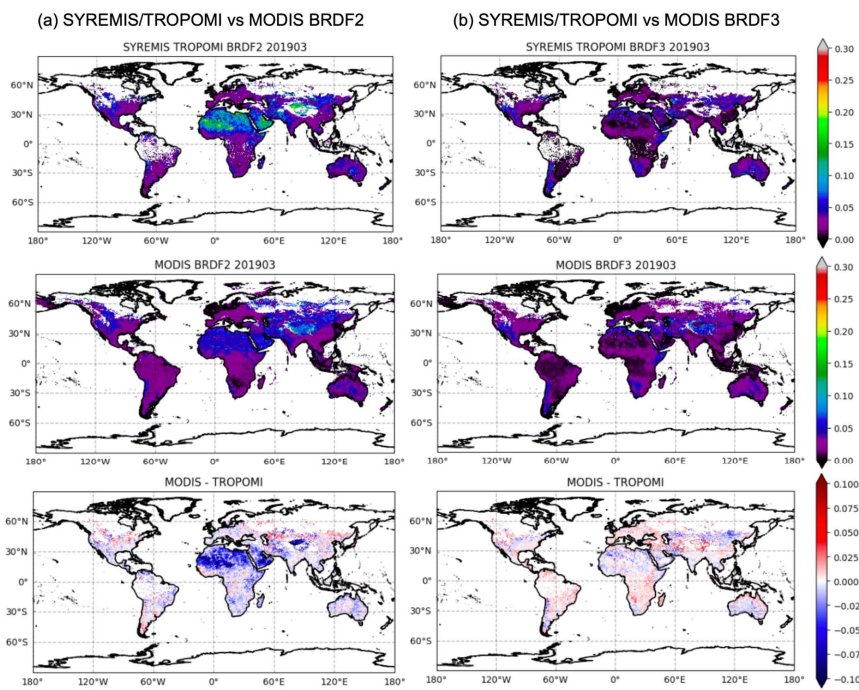


Figure 19: Global intercomparison of SYREMIS/TROPOMI and MODIS Ross-Li BRDF 2nd (volumetric) (a) and 3rd (geometric) (b) model parameters.

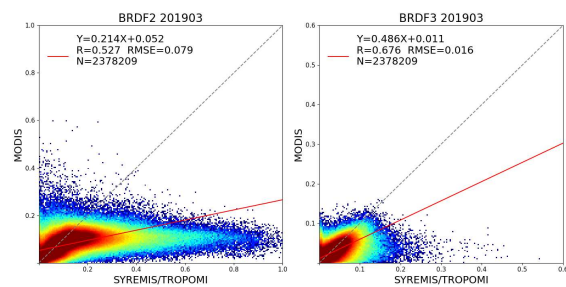


Figure 20: Correlation of global BRDF second and third parameters from between SYREMIS/TROPOMI and MODIS in March 2019. N is the number of pixels; R is the Pearson correlation coefficient.

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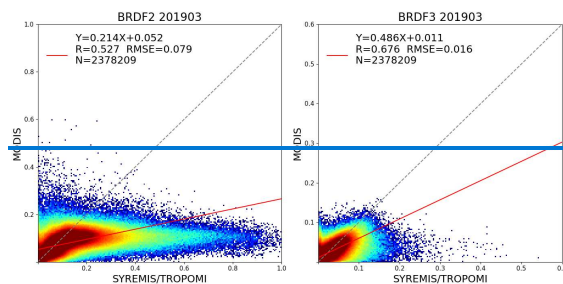


Figure 19: BRDF first, second and third parameters: SYREMIS/TROPOMI vs MODIS, March 2019.

4 Conclusions

In this paper, we presented an approach for SYnergetic REtrieval from Multi-MISSion instruments (SYREMIS-), which is based on the GRASP multi-instrument synergetic approach algorithm and was developed for the enhanced retrieval of aerosol and surface properties from the combined spaceborne instruments. It was. The approach was implemented and tested on (i) synergy from polar-orbiting satellites (the LEO+LEO synergy of the S5P/TROPOMI, S3A/OLCI and S3B/OLCI instruments) and (ii) synergy of polar-orbiting and geostationary satellites (the LEO+GEO synergy of the S5P/TROPOMI, S3A/OLCI, S3B/OLCI and Himawari-8/AHI sensors). The instruments). The synergetic concept of the SYREMIS/GRASP synergy approach is based on three main principles: discussed in this paper (e.g., Section 2); (i) harmonization of the multi-instrumentsinstrument L1 measurements, (ii) “weighting” the multi-instrumentsinstrument measurements, and (iii) optimization of the forward models and the retrieval setups.

After number of retrieval experiments with “weighting” the measurements from different sensors it was found out that the best SYREMIS/GRASP retrieval can be achieved when the “weight” of TROPOMI measurements in both LEO+LEO and LEO+GEO synergy is requested to be higher than the “weight” of OLCI and AHI instruments. TROPOMI is known by its good calibration and rich information content in terms of spectral measurements (from UV to SWIR spectral range) and wide swath. In particular, UV measurements provide sensitivity to the absorption properties of aerosol, wide spectral range are crucial for aerosol size and type characterization as well as for aerosol and surface signals differentiation (Litvinov et al., 2024). In the considered synergetic satellite constellation, TROPOMI has a richest information content and serves as a “driver” of the SYREMIS/GRASP retrieval. Nevertheless, it was demonstrated that the contribution of the other satellites in SYREMIS LEO+LEO and LEO+GEO synergy is not negligible since they essentially extend spectral, temporal and spatial coverage of TROPOMI instrument. Such synergetic multi-spectral and pseudo-multi-angular measurements are crucial for distinguishing between atmosphere and surface signals and improve essentially aerosol and surface BRDF characterization.

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960 Overall, it was demonstrated that by harmonizing multi-instrument measurements and properly balancing the “weights” of
961 measurements from different sensors, the SYREMIS/GRASP approach allows ~~transition-of-the~~for information transfer
962 between all instruments in the synergy. In combination with adjusted forward models and retrieval setups (spectral, spatial,
963 and temporal constraints on the aerosol/surface variability), this results in increased performance of AOD, aerosol size, and
964 absorption properties retrieval and more consistent surface BRDF characterization.

966 Performed remote sensing tests (e.g., Section 2.4) showed that the best SYREMIS/GRASP retrieval can be achieved when the
967 “weight” of TROPOMI measurements in both LEO+LEO and LEO+GEO synergies is higher than the “weight” of OLCI and
968 AHI instruments. TROPOMI is known for its good calibration and rich information content in terms of spectral measurements
969 (from the UV to SWIR spectral range) and wide swath (~2600 km). In particular, UV measurements provide sensitivity to
970 absorption properties; extended spectral coverage and a wide swath are crucial for aerosol size and type characterization, as
971 well as for aerosol and surface signal differentiation (Litvinov et al., 2024). As shown in Section 3, within the considered
972 synergetic satellite constellation, the TROPOMI instrument, providing the most information about aerosol and surface, serves
973 as a “driver” of the SYREMIS/GRASP retrieval. Nevertheless, it was also demonstrated that the contribution of the other
974 satellites in the SYREMIS LEO+LEO and LEO+GEO synergy is not negligible since they considerably extend the spectral,
975 temporal, and spatial coverage of the TROPOMI instrument (e.g., Section 3). This allows us to conclude that the
976 SYREMIS/GRASP approach, applied to synergetic multi-spectral, pseudo-multi-angular measurements from multi-mission
977 instruments, results in enhanced aerosol and surface BRDF characterization.

979 In particular, for all instruments from the LEO+LEO and LEO+GEO synergies, AOD performance against AERONET was
980 increased essentially. AExp, AE and SSA from the synergies were found to be comparable with the TROPOMI/GRASP single
981 instrument retrieval and essentially better than ~~from~~ of the same quality as previous OLCI/GRASP and AHI/GRASP
982 retrievals, (Section 3), supporting the conclusion that the information about aerosol size and absorption/scattering comes from
983 SSP/TROPOMI measurements mainly from the TROPOMI measurements.

985 SYREMIS/GRASP AOD inter-comparison with VIIRS and TROPOMI/GRASP shows similar global features, though the
986 noticeableobserved regional differences thatrequiresrequire further analysis. Global inter-comparison of the retrieved surface
987 properties showed good qualitative consistency of the SYREMIS/GRASP first BRDF parameter (isotropic Ross-Li parameter)
988 with the MODIS one, thoughparameter. Nevertheless, depending on the region, thea brighter or darker surface eanmay be
989 retrieved. The SYREMIS/GRASP also shows essential difference of differences in the volumetric and geometric Ross-Li
990 BRDF parameters in-comparisoncompared to the MODIS surface product.

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This can be explained by the fact that SYREMIS multi-instrument pseudo-multi-angular measurements provide more information about the angular dependence of surface reflectance angular-dependence-in-comparison-compared to the single instrument with one single-angle observations, as discussed in Section 3.4.

With properly applied temporal smoothness constraints, described in Section 2, the SYREMIS/GRASP retrieval allows deriving for the derivation of consistent temporal variation of aerosol properties with enhanced temporal resolution from all instruments within the synergy. In particular, the LEO+LEO synergy can provide consistent variability of extended aerosol properties several times per day, whereas the LEO+GEO synergy can essentially improve the improves temporal resolution to one hour or better. Such extended aerosol characterization with high temporal resolution is required in air quality studies, for monitoring aerosol transport, aerosol-cloud interaction, etc.

The developed SYREMIS/GRASP synergetic concept with approach is based on the fundamental principles of the multi-term LSM of the GRASP algorithm (e.g., Section 2 and Appendix A). Moreover, the formulated three main principles of the synergetic concept (e.g., Sections 2 and 3) are quite universal and can be extended to future spaceborne missions, including synergy with multi-angular, multi-spectral, polarimetric measurements. In such advanced synergy with spaceborne polarimeters, more complex aerosol models can be used, allowing. This is expected to allow further enhancement of the retrieval of aerosol microphysical and chemical properties retrieval-at-very-fine, as well as their temporal resolution.

Appendix A

The simultaneous solution for the selected data set corresponds to the solution of a joint system of equations that schematically can be represented as:

$$\begin{cases} f_1^* & f_1(a_1) + \Delta f_1^* \\ f_2^* & f_2(a_2) + \Delta f_2^* \\ f_3^* & f_3(a_3) + \Delta f_3^* \end{cases} = f(a) + \Delta f^* \quad (1A)$$

Here, the equations are written only for 3 pixels to illustrate the concept that can be extended to N_k pixels. f_k^* corresponds to measurements associated with pixel k , f_k measurements simulation performed for the state vector a_k . Evidently, solving the system of independent equations (Eq.(1A)) simultaneously or consequently does not make any difference since each equation corresponds to a different pixel that depends on independent parameters. This is especially evident if the function $f_j^* = K_j a_i$:

$$\begin{pmatrix} f_1^* \\ f_2^* \\ f_3^* \end{pmatrix} = \begin{pmatrix} K_1 & 0 & 0 \\ 0 & K_2 & 0 \\ 0 & 0 & K_3 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + \begin{pmatrix} \Delta f_1^* \\ \Delta f_2^* \\ \Delta f_3^* \end{pmatrix} = f(a) + \Delta f^* \quad (2A)$$

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However, this system can be complemented by the system representing a priori constraints that provides some dependence between parameters $\mathbf{a}_1$, $\mathbf{a}_2$ and $\mathbf{a}_3$:

$$\begin{cases} \mathbf{g}_t^* & \mathbf{g}_t(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3) + \Delta \mathbf{g}_t = \mathbf{g}_t(\mathbf{a}) + \Delta \mathbf{g}_t \\ \mathbf{g}_x^* & \mathbf{g}_x(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3) + \Delta \mathbf{g}_x = \mathbf{g}_x(\mathbf{a}) + \Delta \mathbf{g}_x \\ \mathbf{g}_y^* & \mathbf{g}_y(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3) + \Delta \mathbf{g}_y = \mathbf{g}_y(\mathbf{a}) + \Delta \mathbf{g}_y \end{cases} \quad (3A)$$

where the a priori functional constraints $\mathbf{g}_t$, $\mathbf{g}_x$ and $\mathbf{g}_y$ apply temporal and spatial dependencies between $\mathbf{a}_1$, $\mathbf{a}_2$, $\mathbf{a}_3$.

Solving two systems (Eqs.2A) and (3A)) simultaneously changes the solution compared to the consequent solution of Eq.(2A). Since both measurements $\mathbf{f}^*$ and a priori $\mathbf{g}^*$ data include random errors Δ , the joint system (Eqs.(2A) and (3A)) can be solved using Multi-Term LSM (Dubovik et al., 2021a) and corresponds to the minimum of the following quadratic form:

$$\begin{aligned} \Psi(\mathbf{a}) &= \sum_{i=1 \dots N_{pixel}} \Delta \mathbf{f}_i^T \mathbf{C}_i^{-1} \Delta \mathbf{f}_i + \sum_{k=t,x,y} \Delta \mathbf{g}_k^T \mathbf{C}_k^{-1} \Delta \mathbf{g}_k = \\ &\equiv \sum_{i=1 \dots N_{pixel}} \Psi_i(\mathbf{a}_i) + \sum_{k=t,x,y} \Psi_k(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3) = \sum_{i=1 \dots N_{pixel}} \Psi_i(\mathbf{a}_i) + \sum_{k=t,x,y} \Psi_k(\mathbf{a}) = \quad (4A) \\ &= \sum_{i=1 \dots N_{pixel}} \Psi_i(\mathbf{a}_i) + \Psi_{inter-pixel} \sim \min \end{aligned}$$

where $\Delta \mathbf{f}_i = \mathbf{f}_i^* - \mathbf{f}_i(\mathbf{a}_i)$ $\mathbf{C}$ is the covariance matrix, $\mathbf{C} = \mathbf{I} \sigma^2$, $\mathbf{I}$ is the diagonal unity matrix, σ^2 is the variance, and σ is the standard deviation of the dataset.

Since the solution is related to the minimum of a quadratic form and not related to the absolute value of this minimum, Eq.(4A) can be rewritten using weighting matrices:

$$\Psi(\mathbf{a}) = \sum_{i=1 \dots N_{pixel}} \gamma_i \Delta \mathbf{f}_i^T \mathbf{W}_i^{-1} \Delta \mathbf{f}_i + \sum_{k=t,x,y} \gamma_k \Delta \mathbf{g}_k^T \mathbf{W}_k^{-1} \Delta \mathbf{g}_k \sim \min, \quad (5A)$$

where $\mathbf{W}_i$ represent weighting matrices and γ_i represent so-called Lagrange multipliers, defined as

$$\mathbf{W}_i = \frac{1}{\{\mathbf{w}_i\}_{11}} \mathbf{W}_f = \frac{1}{\sigma_i^2} \mathbf{W}_f \text{ and } \gamma_i = \frac{\sigma_1^2}{\sigma_i^2} \text{ and } \gamma_k = \frac{\sigma_1^2}{\sigma_k^2}. \quad (6A)$$

The introduction of weighting matrices and Lagrange multipliers is a rather conventional approach (see discussion by Dubovik, 2004, Dubovik et al., 2021a) that is quite convenient since they allow explicitly expressing the weights (“importance”) of different data involved in the inversion.

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Thus, using a priori constraints $\mathbf{g}_k^*$ in Eq.(3A) allows for improving the accuracy of retrieval of multi-platform inversion. Formally, $\mathbf{g}_k^*$ are usually defined by assuming the derivatives of temporal or spatial dependencies of retrieved parameters to zeros, i.e. $\left(\frac{\partial^p a_n(x)}{\partial x^p}\right)^* \approx \Delta_x^* = 0_x^* + \Delta_x$, $\left(\frac{\partial^p a_n(y)}{\partial x^p}\right)^* \approx \Delta_y^* = 0_y^* + \Delta_y$ and $\left(\frac{\partial^p a_n(t)}{\partial x^p}\right)^* \approx \Delta_t^* = 0_t^* + \Delta_t$ (e.g. Dubovik et al., 2011, 2021a). Correspondingly, the multi-pixel constraints in Eq.(3A) are $\mathbf{g}_k^* = \mathbf{0}_k^* = \mathbf{S}_k \mathbf{a} + \Delta_k$, where $\mathbf{S}_k$ is the numerical equivalent of corresponding k-th derivatives, and it can be written:

$$\Psi_{inter-pixel} = \sum_{k=t,x,y} \mathbf{a}^T \gamma_k \Omega_k \mathbf{a}, \text{ where } \Omega_k = \mathbf{S}_k^T \mathbf{W}_k^{-1} \mathbf{S}_k. \quad (7A)$$

As shown before, the vector of retrieved parameters $\mathbf{a}$ includes the vectors of parameters retrieved for each pixel: $\mathbf{a}_1 = (\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3)$ and each vector $\mathbf{a}_0$ includes the following retrieved characteristics of aerosol and surface:

$$\mathbf{a}_i^T = (\mathbf{a}_1, \dots, \mathbf{a}_6)^T = (\mathbf{a}_{c_v}, \mathbf{a}_{comp}, \mathbf{a}_h, \mathbf{a}_{brdf,1}, \mathbf{a}_{brdf,2}, \mathbf{a}_{brdf,3})^T, \quad (8A)$$

where:

$$\mathbf{a}_{comp}^T = \left(\frac{\mathbf{a}_{c_{v1}}}{\mathbf{a}_{c_v}}, \frac{\mathbf{a}_{c_{v2}}}{\mathbf{a}_{c_v}}, \dots, \frac{\mathbf{a}_{c_{vn}}}{\mathbf{a}_{c_v}} \right)^T \quad (9A)$$

where $\mathbf{a}_{comp}$ represents the unknown vectors of aerosol compositions, $\mathbf{a}_{c_v}$ and $\mathbf{a}_h$ represent the unknown vectors corresponding to total aerosol volume concentration and aerosol scale height. Over land, $\mathbf{a}_{brdf,1}$, $\mathbf{a}_{brdf,2}$ and $\mathbf{a}_{brdf,3}$ represent the unknown vectors of the first, second, and third spectrally dependent surface Ross-Li BRDF parameters. Over ocean, $\mathbf{a}_{brdf,1}$, $\mathbf{a}_{brdf,2}$ and $\mathbf{a}_{brdf,3}$ represent the unknown vectors of the ocean isotropic albedo, the fraction of Fresnel reflection, and the mean square facet slope as described previously by Litvinov et al., (2024). The inter-pixel constraints are usually different for different retrieved characteristics and, therefore, “inter-pixel spatial and temporal smoothness matrices” $\gamma_k \Omega_k$ have the following diagonal structure:

$$\gamma_k \Omega_k = \begin{pmatrix} \gamma_{k,1} \Omega_{k,1} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \gamma_{k,2} \Omega_{k,2} & \dots & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \dots & \gamma_{k,n} \Omega_{k,n} \end{pmatrix} \quad (10A)$$

where Lagrange multiplier $\gamma_{k,n}$ and smoothness matrices Ω_k define inter-pixel constraints for each of retrieved characteristics: $\mathbf{a}_{c_v}$, $\mathbf{a}_{comp}$, $\mathbf{a}_h$, $\mathbf{a}_{brdf,1}$, $\mathbf{a}_{brdf,2}$, $\mathbf{a}_{brdf,3}$.

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It should also be noted that what the a priori in retrieval are not only about a priori known inter-pixel relationships of the retrieved characteristics but also about known a priori knowledge variability of parameters within the pixels. Moreover, in each pixel we may have observations from different satellites, for example, S3A/OLCI, S3B/OLCI, S5P/TROPOMI, HIMAWARI-8/AHI, with different spectral observations. Specifically, the system of equations corresponding to observations for each i-th pixel $f_i^* = f(a_i) + \Delta f_i$ in Eq.(2A), consists of several lines:

$$\left\{ \begin{array}{l} f_{i,1}^* = f_{i,1}(a_i) + \Delta f_{i,1} \\ f_{i,2}^* = f_{i,2}(a_i) + \Delta f_{i,2} \\ \dots \\ f_{i,N}^* = f_{i,N}(a_i) + \Delta f_{i,N} \\ f_{i,1}^a = f_{i,1}^a(a_i) + \Delta f_{i,1} \\ f_{i,2}^a = f_{i,2}^a(a_i) + \Delta f_{i,2} \\ \dots \\ f_{i,M}^a = f_{i,M}^a(a_i) + \Delta f_{i,M} \end{array} \right. \quad (11A)$$

where $f_{i,n}^*$ represent measurements from different instruments or from the same instrument but with different accuracy, and $f_{i,m}^a$ represent a priori data that usually defined as smoothness constraints defined as limitations on k-the derivatives, as $0_k^* = S_k a + \Delta_k$, or as direct a priori estimates $a_m^* = a_m + \Delta_{a,m}$, as suggested by Dubovik et al. (2011). Usually, in pixel a priori constraints are defined in the same way and with the same strength for all pixels. Therefore, the quadratic form $\Psi_{i,pixel}(a_i)$ corresponding to i-th pixel in Eq.(3A) can be written as the following:

$$\begin{aligned} \Psi_{i,} &= \sum_{n=1 \dots N_f} \gamma_{i,n} \Delta f_{i,n}^T W_{f_{i,n}}^{-1} \Delta f_{i,n} + \sum_{m=1 \dots M_\Delta} \gamma_{\Delta_{i,m}} a_{i,m}^T \Omega_{k,m} a_{i,m}^T = \sum_{m=1 \dots M_a} \gamma_{a,m} (\Delta a_{i,m}^*)^T W_{i,m}^{-1} \Delta a_{i,m}^* = \\ &= \sum_{n=1 \dots N_f} \gamma_{f_{i,n}} \Psi_{f_{i,n}} + \sum_{m=1 \dots 4} \gamma_{\Delta_{i,m}} \Psi_{\Delta_{i,m}} + \sum_{m=1 \dots 6} \gamma_{a_{i,m}} \Psi_{a_{i,m}} \end{aligned} \quad (12A)$$

Thus, based on Eq.(4A) and Eq.(12A), the multi-pixel solution for developed multi-platform retrieval is the value minimizing the following quadratic form:

$$\begin{aligned} \Psi(a) &= \sum_{i=1 \dots N_{pixel}} \Psi_i(a_i) + \Psi_{inter-pixel} = \\ &= \sum_{i=1 \dots N_{pixel}} \left[\sum_{n=1 \dots N_f} \gamma_{f_{i,n}} \Psi_{f_{i,n}} + \sum_{m=1 \dots 4} \gamma_{\Delta_{i,m}} \Psi_{\Delta_{i,m}} + \sum_{m=1 \dots 6} \gamma_{a_{i,m}} \Psi_{a_{i,m}} \right] + \sum_{k=t,x,y} a^T \gamma_k \Omega_k a \sim \min \end{aligned} \quad (13A)$$

As a result, the developed retrieval can be controlled by the following Lagrange multipliers ("weights"):

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- N_f weights $\gamma_{f_{lm}}$ determining the contribution of different instruments or different channels (those parameters are considered pixel-independent);
- up to 4 weights $\gamma_{\Delta_{i,m}}$ determining the contribution of in-pixel smoothness constraints for the vectors $\mathbf{a}_{brdf,1}, \mathbf{a}_{brdf,2}, \mathbf{a}_{brdf,3}$ representing some continues spectral functions or mixtures $\mathbf{a}_{comp}$.
- up to 6 weights $\gamma_{a_{i,m}}$ determining the contribution of in-pixel a priori estimates $\mathbf{a}_{lm}^*$ for vectors $\mathbf{a}_{c_v}, \mathbf{a}_{comp}, \mathbf{a}_h, \mathbf{a}_{brdf,1}, \mathbf{a}_{brdf,2}, \mathbf{a}_{brdf,3}$. It should be noted here that usually only one a priori in-pixel limitation (either smoothness constraints or a priori estimates) are used for the same parameter.
- up to 6 weights $\gamma_{x,m} = \gamma_{y,m}$ determining the contribution of a priori inter-pixel smoothness constraints on x,y horizontal variability of vectors $\mathbf{a}_{c_v}, \mathbf{a}_{comp}, \mathbf{a}_h, \mathbf{a}_{brdf,1}, \mathbf{a}_{brdf,2}, \mathbf{a}_{brdf,3}$;
- up to 6 weights $\gamma_{t,m}$ determining the contribution of a priori inter-pixel smoothness constraints on t- temporal variability of vectors $\mathbf{a}_{c_v}, \mathbf{a}_{comp}, \mathbf{a}_h, \mathbf{a}_{brdf,1}, \mathbf{a}_{brdf,2}, \mathbf{a}_{brdf,3}$;

It should be noted that all Lagrange parameters γ_i can be quantitatively determined as $\gamma_i = \frac{\sigma_i^2}{\sigma_i^2}$ (Eq.(6A)) from knowledge of measurements or a priori data covariance matrices. However, in practice, the knowledge of those covariance matrices is usually quite uncertain. Additionally, some assumptions of the methodology, e.g., dominance of the measurement errors over uncertainties of the used forward model, etc. (see discussion by Dubovik et al., 2021a). Therefore, in practical application of the methodology and one present here the “weights” γ_i are usually adjusted using sensitivity studies and tuning based on acquired experience in retrieval tests.

Code availability

The retrieval results presented in this paper were obtained with GRASP-OPEN software (<https://www.grasp-open.com>).

Data availability

The SYREMIS/GRASP datasets are available on request

Author contribution

PL provided the original concept of the multi-instrument synergetic approach, and together with CC performed original research, developments, and prepared the manuscript. OD provided consultancy on the GRASP algorithm adaptation to the synergetic retrieval and edited the manuscript. SZ provided validation results and visualization, and contributed to writing the

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manuscript. CM, LB, MD, and AL prepared satellite data for the SYREMIS/GRASP synergy, generated retrieval output. CL and AL provided consultancy on the GRASP algorithm application to the HIMAWARI/AHI instrument, and edited the manuscript. DF and TL provided support and development of the GRASP algorithm for the synergetic approach. CR, together with AD and DG, supervised the ESA SYREMIS project, discussed SYREMIS/GRASP results, and edited the manuscript.

Competing interests

Some authors are members of the editorial board of journal AMT.

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