

DAR-type model based on "long memory-threshold" structure: a competitor for daily streamflow prediction under changing environment

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Abstract. The non-stationarity, non-linearity, and time-varying fluctuations of streamflow have increased with changes in the environment, which makes accurate streamflow prediction more challenging. Furthermore, without incorporating long-term memory features could lead to biases in model parameter estimation, which would affect the accuracy of streamflow simulated by the model. The classical linear Autoregressive-Generalized Autoregressive Conditional Heteroskedasticity (AR-GARCH) model has a narrow parameter range, and the moment conditional requirements for parameter estimation are relatively strict, limiting its applicability and prediction accuracy of daily streamflow. A dual-threshold double autoregressive (DTDAR) model is proposed to simulate basin streamflow with non-linear and long-term memory characteristics. Using 15 hydrological stations in the Yellow River basin in China as the study site, the performances of DAR models are compared with AR-GARCH models to assess their applicability and predictive ability. The results indicate that the DAR-type models have a stronger predictive ability for daily streamflow than the AR-GARCH-type counterparts. Threshold models (DTDAR and TAR-GARCH) transform nonlinear problems into linear ones, enhancing prediction accuracy compared to single linear structural models (DAR, FDAR, AR-GARCH, and FAR-HARCH). They improve goodness-of-fit statistics for observed versus simulated streamflow, with R^2 increasing by 29.15% and 15.06% for DTDAR and TAR-GARCH, respectively, compared to DAR and FDAR, and by 25.53% and 15.53% compared to AR-GARCH and FAR-HARCH. Similarly, NSE values increase by 0.29 and 0.16 for DTDAR and TAR-GARCH versus DAR and FDAR, and by 0.24 and 0.15 versus AR-GARCH and FAR-HARCH. Compared to the normal distribution, the Student's t distribution for residuals is a better choice for predicting daily streamflow time series in the study area. This study has developed stochastic hydrological models capable of predicting credible basin streamflow.

1 Introduction

30 Under the impact of climate change and anthropogenic activities, the behavioural characteristics or responses of hydrological systems have become increasingly complex (Lyu et al., 2023; Ma et al., 2024; Matic et al., 2022; Sivakumar, 2009). The hydrological statistical method has gained wide attention in hydrological simulation and prediction due to its outstanding ability to describe the structure, function, and development trend of the system, and has become one of the hot issues in stochastic hydrology research (Can et al., 2012; Chen et al., 2021; Yang et al., 2022). Among popularly used stochastic models
35 in hydrologic research, the classic regression model is conceptually simple, practical and easy to implement.

Traditional regression models, including the autoregressive (AR) model, the moving average (MA) model, and their combined, ARMA model, are well-suited for modeling stationary time series but they have significant limitations. On the other hand, unlike the ARMA model, by adding a differencing step to smooth a time series, the differencing ARMA (known as ARIMA) model can be effective in modelling a non-stationary time series (Wang et al., 2019). However, both the ARIMA and ARMA
40 models have difficulties handling seasonality in a time series. The seasonal ARIMA (SARIMA) model is a preferred option to model monthly streamflow time series with annual cycles with seasonal variations (Adnan et al., 2019; Modarres, 2007). However, the “illegible” seasonal features in a daily streamflow series pose a challenge for us to effectively apply the SARIMA model. To overcome this problem, Guo et al. (2021a) used a seasonal standardization approach to preprocess daily streamflow time series, so that the influence of seasonality is removed or minimized for subsequent applications. Therefore in this study we
45 used the seasonal standardization method to eliminate the seasonal effect from daily streamflow time series.

In the last several decades, the conditional heteroscedastic behaviour (ARCH effect) of the mean model residual series has received increasing attention due to the changing environment (Guo et al., 2021b; Nazeri-Tahroudi et al., 2022; Wang et al., 2023a). The generalized Autoregressive Conditional Heteroscedasticity (GARCH) model has been often employed to improve the modelling accuracy of the AR-type model by eliminating the ARCH effect in the residuals (Fathian et al., 2019; Fathian
50 and Vaheddoost, 2021; Pandey et al., 2019; Zha et al., 2020). However, the AR-GARCH model, a typical regression model for streamflow forecasting, has a relatively cumbersome combined form than a single AR model, hindering its application. Compared with the AR-GARCH, the double autoregressive (DAR) model proposed by Ling (2007) is more concise in form, can describe the first- and second-order moments behaviour of time series simultaneously, and has been widely applied in economic studies (Hansen, 2021; Jiang et al., 2020; Li et al., 2019; Liu et al., 2018). In addition, the ARMA model requires
55 the autoregressive and moving average parameters to fall within the range of $-1 \sim 1$ but the sum is lower than 1, while the GARCH model restricts non-negative parameters and the sum (except for the constant) is below 1. In contrast, the definition range of the DAR model parameter is broader, with a first-order moment selection throughout the real number field and non-negative second-order moment constraints. However, the DAR model has yet been applied in hydrology, and its predictive ability has yet to be verified.

60 Dimitriadis and Koutsoyiannis (2015) found that long-term memory, the correlation between streamflow at present and the past, is very important for daily streamflow prediction. It has been reported that any time-varying volatility detected in daily

streamflow series could be attributed to long-term memory (Dimitriadis et al., 2021; Graves et al., 2017; Grimaldi, 2004), which may lead to a spurious ARCH effect in residuals of the pure AR model, rendering the constructed GARCH model deficient which can affect its predictive ability. Both the combined AR-GARCH model and the novel DAR model have problems reproducing the long-term persistency of a daily streamflow time series. Long-term memory has been mostly neglected in majority of past streamflow simulation and predictive studies. The research on long memory has began by Hurst (1951), and Mandelbrot and Wallis (1969). Hurst was pioneer in proposing the Hurst index (H , $H > 0.5$ indicates that a time series has long memory) to detect long-term memory. Although long-term memory has been first identified within the field of hydrology, for a long time, there was no efficient method that could effectively reproduce the long-term memory of daily streamflow widely accepted by most hydrologists. Granger (1978) proposed the concept of "fractionally differencing", which laid the foundation for the development of subsequent long-memory models (such as the ARFIMA model). Hosking (1981) followed up in the field of hydrology. Montanari et al (1996; 1997) advocated that the fractional difference model is the only method that can describe the daily streamflow time series with long-term persistence. Therefore, this study leads the way in hydrology by combining fractional differencing and time-varying fluctuation models to ensure the authenticity of the ARCH effect and reduce the risk of negatively affecting streamflow prediction accuracy due to insufficient information description. Hydrologic time series are highly nonlinear, as demonstrated in many studies (e.g., Delforge et al., 2022; Feng et al., 2022; Guo et al., 2021b; Miller, 2022; Yuan et al., 2021), resulting in significant challenges to modelling them using traditional mean capture and predict the nonlinearity in the mean behaviour of hydrological time series (Tong, 1983). Significant non-linearities were found in the projected annual mean runoff response to global warming in CMIP5 models, which could not be entirely explained by precipitation changes (Zhang et al., 2018). Similar non-linear behaviours are found in CMIP6 models over the Mississippi, Amazon, Yangtze, Niger, and Euphrates river basins, showing the need to reassess the assumption of linearity when estimating regional water cycle changes (Douville et al., 2021). Several recent studies (Fathian et al., 2019; Gharehbaghi et al., 2022; Huang et al., 2021; Kolte et al., 2023) have introduced a new, innovative combination model coupled with a nonlinear mean model, such as the artificial intelligence-GARCH, for hydrologic predictions. Guo et al. (2021b) combined the Self-Exciting TAR model with the GARCH model to predict groundwater depth and achieved satisfactory results. Unfortunately, the applicability of the TAR-GARCH model to hydrological time series is limited by restrictive parameter constraints. To address this limitation, this study proposes a dual-threshold DAR (DTDAR) model based on the novel DAR model, which provides thresholds for both the linear form of the first-order and the second-order moments, namely "dual-threshold", making it more versatile than the TAR-GARCH model. To the best of our knowledge, for the first time the DTDAR model is proposed to predict daily streamflow, which we believe will become a strong competitor for simulating many types of time series besides streamflow.

This study aims to improve the prediction accuracy of daily streamflow time series by constructing a novel model capable of simulating daily streamflow with seasonality, non-stationarity, long-term memory, nonlinearity, and time-varying volatility. Therefore, a FDTDAR model using the long memory-threshold structure of the aforementioned DAR model, with a seasonal normalization approach to account for the seasonality of the streamflow data. The assumption that the residual series follows

a Gaussian distribution is imposed in the model, even though the actual hydrologic time series may have tails that are either heavier or lighter than that of a Gaussian distribution. Therefore, a t-distribution shape is also considered in the model developed, which are called FDTDAR-n and FDTDAR-t, respectively. To test and to evaluate the prediction accuracy of the DTDAR model, in addition to the single DAR model, the classic AR-GARCH and TAR-GARCH models are also selected in this study.

2 Study area and data

2.1 Study Site

The site selected for this study (Figure 1) is the ionic Yellow River Basin of China, which has a main stream channel length of approximately 5464 km and a catchment area of about 795,000 km², ranking second largest river basin of China and the fifth largest in the world. The Yellow River that originates from the Bayan Har Mountains in Qinghai Province, Western China, flows through 9 provinces before discharging into the Bohai Sea. This study focuses on the streamflow data of 15 hydrologic stations located within the Yellow River Basin given data of these stations are reliable and of high quality. These stations (Figure 1) are located on the mainstream, which include Tangnaihai (TNH), Lanzhou (LZ), Xiaheyuan (XHY), Shizuishan (SZS), Toudaoguai (TDG), Fugu (FG), Longmen (LM), Tongguan (TG), Sanmenxia (SMX), Aishan (AS) and Lijin (LJ) and the largest tributary of the Yellow River, the Weihe River Basin (Zhangjiashan (ZJS), Xianyang (XY), Lintong (LT) and Zhuangtou (ZT)).

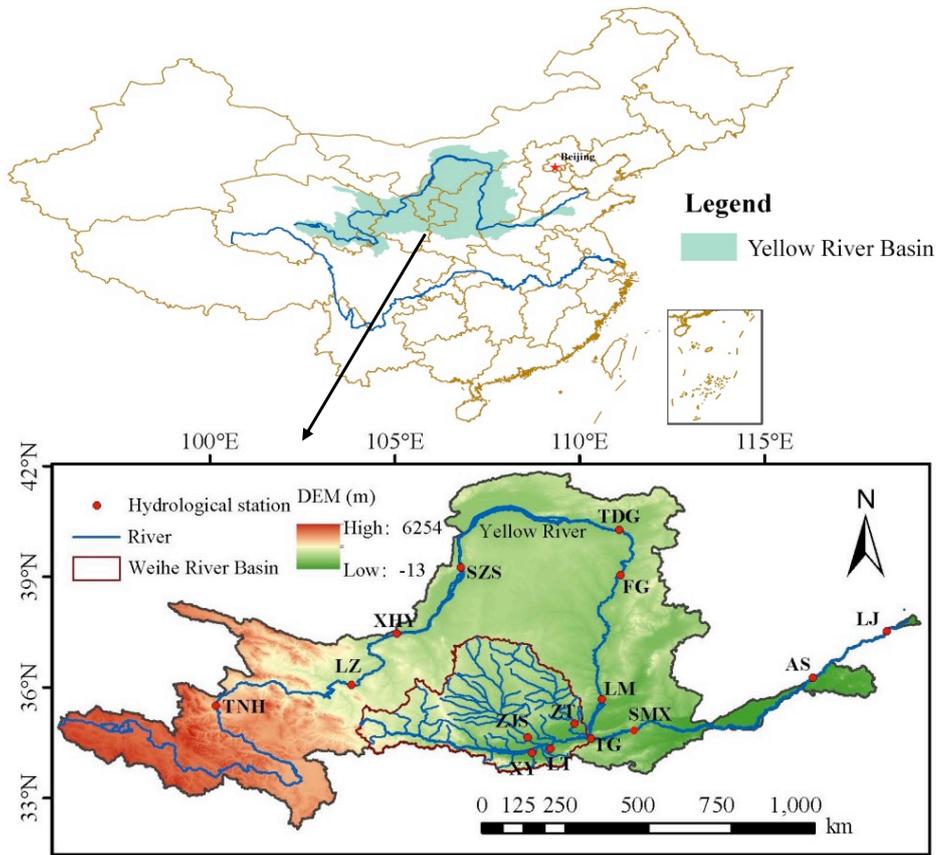


Figure 1: The Yellow River basin and locations of 15 hydrological stations.

2.2 Daily streamflow time series data

115 This study selects the measured daily streamflow time series from 15 hydrological stations in the Yellow River Basin (Table 1). Figure S1 shows the temporal variations of the daily streamflow time series for the 15 hydrologic stations. The last year's data of each station is used as the testing period to compare and to evaluate the prediction accuracy or the modelling capabilities of various models selected and calibrated using the streamflow data independent of the testing period, data that represent multiple characteristics of daily streamflow time series.

120 **Table 1: Basic Statistics of daily streamflow series for 15 stations.**

Stations	Abbreviation	Water system	Latitude/N	Longitude/E	Control area/km ²	Period
Tangnaihai	TNH	Yellow River	35.5	100.15	121972	2007.01.01- 2022.12.31

Lanzhou	LZ	Yellow River	36.06	103.82	222600	2009.01.01- 2022.12.31
Xiaheyan	XHY	Yellow River	37.45	105.05	254142	2007.01.01- 2021.12.31
Shizuishan	SZS	Yellow River	39.25	106.78	309146	2007.01.01- 2022.12.31
Toudaoguai	TDG	Yellow River	40.27	111.06	367898	2009.01.01- 2022.12.31
Fugu	FG	Yellow River	39.03	111.08	404000	2007.01.01- 2022.12.31
Longmen	LM	Yellow River	35.67	110.58	497552	2009.01.01- 2022.12.31
Tongguan	TG	Yellow River	34.6	110.3	682141	2007.01.01- 2022.12.31
Sanmenxia	SMX	Yellow River	34.82	111.37	688421	2007.01.01- 2022.12.31
Aishan	AS	Yellow River	36.25	116.3	749136	2007.01.01- 2022.12.31
Lijin	LJ	Yellow River	37.52	118.3	751869	2007.01.01- 2022.12.31
Zhangjiashan	ZJS	Jinghe	34.64	108.59	43216	2007.01.01- 2022.12.31
Xianyang	XY	Weihe River	34.32	108.7	46827	1985.01.01- 2022.12.31

Lintong	LT	Weihe River	34.43	109.2	97299	1985.01.01- 2007.12.31
Zhuangtou	ZT	Beiluohu	35	109.84	25154	2007.01.01- 2022.12.31

2.3 Daily streamflow time series characteristics

Before initiating the modeling procedure, it is essential to understand the inherent statistical properties of daily streamflow time series. The primary objective of this section is to conduct a comprehensive diagnostic analysis to evaluate four key characteristics of time series: long-term persistence, non-stationarity, ARCH effects, and nonlinearity (Figure 2). These features are critical in determining the suitability and effectiveness of various modeling approaches. Moreover, understanding their interconnections provides important theoretical support for the logical consistency and robustness of the subsequent modeling framework (Figure 2).

The daily streamflow time series exhibits seasonal characteristics due to the cyclical influence of the four seasons. Therefore, deseasonalization is a necessary preprocessing step before modeling, with details of the specific method presented in Section 3.1. In this section, the presence of long-term memory in the daily streamflow series is identified based on the Hurst exponent (H) calculated using the rescaled range (R/S) analysis method and the trend of the autocorrelation function (ACF), and the influence of seasonality on long-term memory is also assessed (Lo, 1991). On this basis, the stationarity of the series is evaluated using three unit root tests: the Augmented Dickey-Fuller (ADF), Phillips-Perron (PP), and Kwiatkowski-Phillips-Schmidt-Shin (KPSS) tests (Dickey and Fuller, 1981; Kwiatkowski et al., 1992; Peter and Perron, 1988). The null hypotheses of ADF and PP tests assume that the time series has a unit root, while the KPSS test considers the null hypothesis as the time series being a stationary process. Due to the tendency of unit root tests to favor the null hypothesis, to rigorously determine the non-stationarity of the daily streamflow time series, if any of the three methods indicates the presence of a unit root process, then the daily streamflow time series at that station is considered non-stationary. Stationarity is a fundamental prerequisite for a model construction. The method of achieving stationarity differs depending on the presence of long memory: non-long-memory series are differenced using integer orders, while long-memory series require fractional differencing. Subsequently, the Ljung-Box (LB) and Lagrange Multiplier (LM) tests are employed to detect the presence of ARCH effects, which is the most critical criterion in building a heteroscedastic model in this study (Ljung and Box, 1978). The ARCH effect reflects the limitations of linear regression models and highlights the necessity of characterizing the variations using a second-order moments. Some studies have suggested a close relationship between ARCH effects and long-term memory in hydrological time series, neglecting long-term memory may lead to spurious detection of ARCH effects (Wang et al., 2023b; Wang et al., 2023c). Therefore, in this section we compare the LB test results of two linear models: a standard integer-order autoregressive model and a long-memory autoregressive (FAR) model based on fractional differencing. Finally, the BDS test is applied to

examine whether the series exhibits nonlinear dynamics (Broock et al., 1996). Since most existing heteroscedastic models are constructed based on linear structures, if the series demonstrates significant nonlinearity, it may be necessary to improve the model expression accordingly.

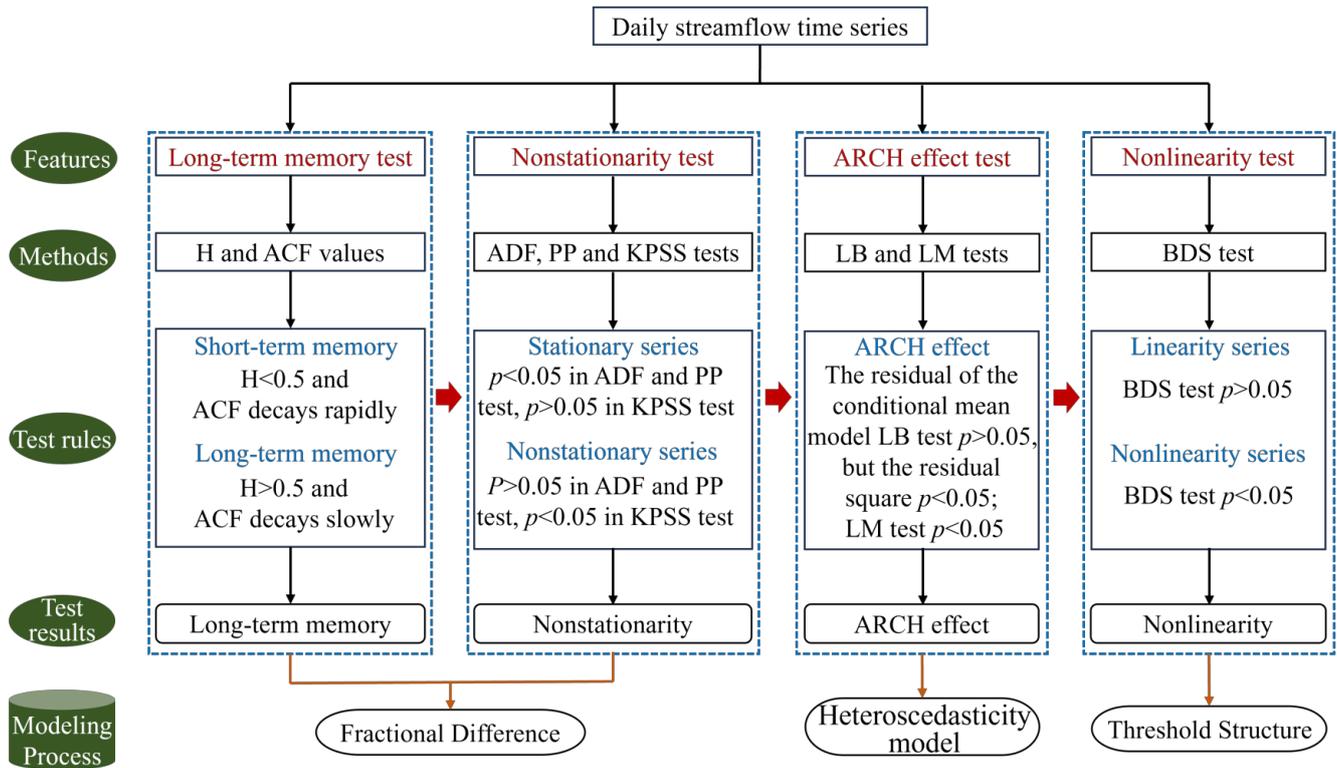
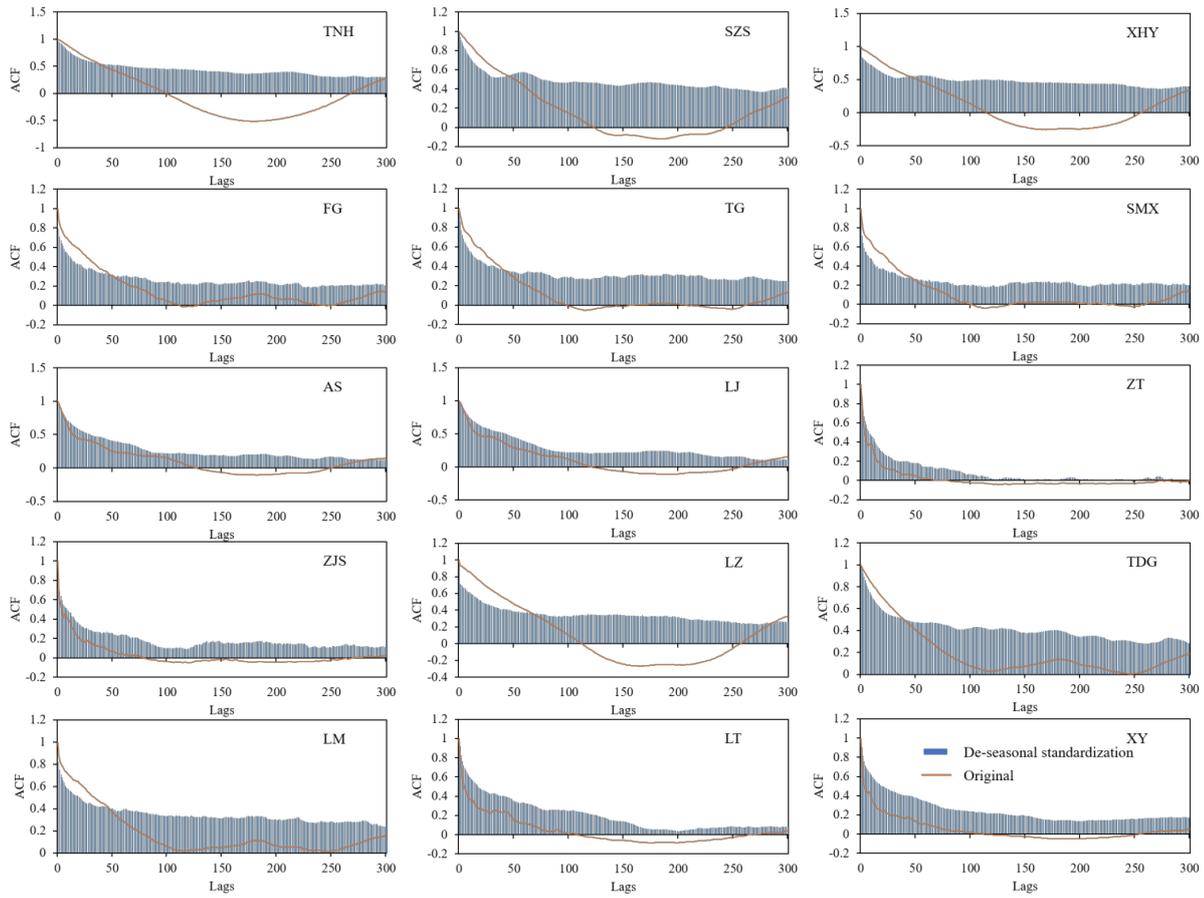


Figure 2: Characteristics tests designed to detect long-term memory, nonstationarity, ARCH effect and nonlinearity in daily streamflow time series.

The results of various diagnostic tests on the daily streamflow time series are presented in Figure 3, Figure S2, and Tables S1–S3. The autocorrelation function (Figure 3) and the Hurst exponent results (Table S1) indicate that the daily streamflow series exhibits long-term memory characteristics, but the strength of this memory can be weakened by seasonality. The results of the 3-unit root tests (Table S2) reveal that the series is non-stationary. Considering its long-memory properties, fractional differencing is adopted to achieve stationarity, which satisfies the model assumptions. Figure S2 shows the Ljung-Box (LB) test results for the residuals of two linear models. The residuals of both models exhibit no significant autocorrelation, indicating that the model structures are appropriate. However, the squared residuals display significant autocorrelation, reflecting the presence of ARCH effects. Moreover, the ARCH effect becomes more pronounced when long memory is taken into account. The LM test yields consistent results. The nonlinearity test results (Table S3) suggest that the daily streamflow time series exhibits significant nonlinear behavior, implying that the model structure in this study should be modified to accommodate nonlinear dynamics.



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Figure 3: Autocorrelation coefficient (ACF) of original and de-seasonalized daily streamflow time series, respectively.

The diagnostic results presented above provide critical insights into the statistical characteristics of the daily streamflow time series, including long-term memory, non-stationarity, heteroscedasticity, and nonlinearity. These findings form a solid foundation for selecting appropriate modeling strategies in the subsequent sections. Specifically, the detection of long-term memory and non-stationarity justifies the use of fractional differencing methods to ensure model validity. The presence of ARCH effects highlights the need for models capable of capturing time-varying volatility, while the identified nonlinear dynamics suggest that linear structural models may be insufficient. DAR-type models have emerged as strong competitors to the widely used heteroscedastic GARCH models, due to their simple mathematical formulation, ease of parameter estimation, and ability to accurately characterize real-world data. Based on the results of this section, the next section introduces an enhanced modeling framework (FDTDAR model) based on the DAR family, which integrates long-memory components, heteroscedasticity, and nonlinear dynamics to better capture the complex behavior of daily streamflow of Yellow River Basin.

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3 Methodology

3.1 De-seasonal standardization

For a given original daily streamflow time series, the mathematical expression for deseasonalization is as follows (Guo et al., 2021a):

$$\begin{cases} \mu^m = \frac{1}{N} \sum_{n=1}^N X_t^{(n,m)} \\ \sigma^m = \left[\frac{1}{N} \sum_{n=1}^N (X_t^{(n,m)} - \mu^m)^2 \right]^{0.5} \end{cases} \quad (1)$$

$$Y_t = \frac{X_t - \mu^m}{\sigma^m} \quad (2)$$

where $X_t^{(n,m)}$ ($n = 1, \dots, N; m = 1, \dots, M$) ($M=366$ in a leap year and 365 in a normal year) is the original daily streamflow time series of the m -th day in the n -th year, μ^m and σ^m are the mean and variance of the variable for each calendar day, respectively; Y_t ($t = 1, \dots, T$) represents the daily streamflow time series after removing seasonality, and the training period length is T .

3.2 FDTDAR model

As shown by the analysis in Section 2.3, the daily streamflow time series exhibits long-term memory, non-stationarity, conditional heteroscedasticity, and nonlinear characteristics. Therefore, these properties should be comprehensively considered in the model construction process. The model proposed in this study, referred to as the FDTDAR model (Fractionally differenced dual-threshold double autoregressive model), is an extension of the ordinary double autoregressive (DAR) model—a type of heteroscedasticity model. Specifically, the long memory characteristics of daily streamflow are modeled using the fractional difference method. On satisfying the stationarity characteristics, the threshold idea is then considered in the DAR model. In other words, in the process of characterizing the first-order moment and the second-order moment, the threshold is introduced to account for nonlinear changes of the daily streamflow series. This processing method is taken from the threshold autoregression (TAR) model. Therefore the proposed FDTDAR model is capable of accommodating the coexistence of multiple complex features in the daily streamflow series. The mathematical formulation of the model is presented as follows:

The fractional difference is used to describe the long-term memory of the daily streamflow series (Y_t) after removing the seasonal components. The specific mathematical form is expressed as:

$$y_t = (1 - L)^d Y_t \quad (3)$$

where y_t is the daily streamflow series after difference, d is the difference order, and $LY_t = Y_{t-1}$ is the lag operator. In order to facilitate the calculation, the binomial expansion of $(1 - L)^d$ is performed as follows:

$$(1 - L)^d = 1 - dL + \frac{d(d-1)L^2}{2!} - \frac{d(d-1)(d-2)L^3}{3!} + \dots \quad (4)$$

205 Eq. (4) shows that infinite data information before the observation point needs to be used in the difference process, which is practically impossible in the actual calculation, and a reasonable approximation is necessary. Therefore, Eq. (4) is substituted into Eq. (3) and sorted to obtain the difference formula used in this study. The specific structure is as follows:

$$y_t = \sum_{k=0}^t \omega_k \cdot Y_{t-k} \quad (5)$$

$$\omega_k = -\omega_{k-1} \frac{d-k+1}{k} \quad (6)$$

210 where the weight ω_k ($\omega_0 = 1$) means that the amount of information required for each data point is different, and k represents the time lag.

The long-memory DAR (FDAR) combines first-order moment and the second-order moment of time series, and its general structure is as follows (Ling, 2007):

$$y_t = \varphi + \sum_{i=1}^p a_i y_{t-i} + \varepsilon_t \sqrt{\alpha + \sum_{i=1}^p b_i y_{t-i}^2} \quad (7)$$

215 where y_t is the daily streamflow time series processed by a fractional difference (Eq. (5)). φ and α are constants, $a_1 \cdots a_p$ and $b_1 \cdots b_p$ are the coefficients of the FDAR model with the order p , ε_t represents the residual series with mean 0 and variance 1. Eq. (7) shows that the mathematical form used to describe the first-order and second-order moment characteristics of the time series in FDAR model are linear structures, that is $A = \varphi + \sum_{i=1}^p a_i y_{t-i}$ and $B = \omega + \sum_{i=1}^p b_i y_{t-i}^2$. Thus, both parts are assigned thresholds r_1 and r_2 to build the FDTDAR model, and the corresponding lag orders are d_1 and d_2 respectively. θ is
220 the set of model parameters. When $d_1 \neq d_2$, the mathematical form of the FDTDAR model is expressed as:

$$y_t = \begin{cases} \varphi_{11} + \sum_{i=1}^{p_{11}} a_{1i}^1 y_{t-i} + \varepsilon_t \sqrt{\alpha_{11} + \sum_{i=1}^{q_{11}} b_{1i}^1 y_{t-i}^2} & \text{if } y_{t-d_1} \leq r_1 \quad y_{t-d_2}^2 \leq r_2 \\ \varphi_{21} + \sum_{i=1}^{p_{21}} a_{1i}^2 y_{t-i} + \varepsilon_t \sqrt{\alpha_{21} + \sum_{i=1}^{q_{12}} b_{1i}^2 y_{t-i}^2} & \text{if } y_{t-d_1} > r_1 \quad y_{t-d_2}^2 \leq r_2 \\ \varphi_{12} + \sum_{i=1}^{p_{12}} a_{2i}^1 y_{t-i} + \varepsilon_t \sqrt{\alpha_{12} + \sum_{i=1}^{q_{21}} b_{2i}^1 y_{t-i}^2} & \text{if } y_{t-d_1} \leq r_1 \quad y_{t-d_2}^2 > r_2 \\ \varphi_{22} + \sum_{i=1}^{p_{22}} a_{2i}^2 y_{t-i} + \varepsilon_t \sqrt{\alpha_{22} + \sum_{i=1}^{q_{22}} b_{2i}^2 y_{t-i}^2} & \text{if } y_{t-d_1} > r_1 \quad y_{t-d_2}^2 > r_2 \end{cases} \quad (8)$$

where $\varphi_{11}, \varphi_{21}, \varphi_{12}, \varphi_{22}, \alpha_{11}, \alpha_{21}, \alpha_{12}$ and α_{22} are constants, represented by the set C ; the order of the model is $p_{11}, p_{21}, p_{12}, p_{22}, q_{11}, q_{12}, q_{21},$ and q_{22} , and the set is O ; $a_{11}^1 \cdots a_{1p_{11}}^1, a_{11}^2 \cdots a_{1p_{21}}^2, a_{21}^1 \cdots a_{2p_{12}}^1, a_{21}^2 \cdots a_{2p_{22}}^2$ and $b_{11}^1 \cdots b_{1q_{11}}^1, b_{11}^2 \cdots b_{1q_{12}}^2, b_{21}^1 \cdots b_{2q_{21}}^1, b_{21}^2 \cdots b_{2q_{22}}^2$ represent the first-order and second-order moment coefficients, respectively, which expressed
225 by the set E . When $d_1 = d_2 = d_0$, the threshold of FDTDAR (θ) model is $r_1 = r_2 = r_0$, and its general form is expressed as:

$$y_t = \begin{cases} \varphi_{10} + \sum_{i=1}^{p_1} a_{1i} y_{t-i} + \varepsilon_t \sqrt{\alpha_{10} + \sum_{i=1}^{q_1} b_{1i} y_{t-i}^2} & \text{if } y_{t-d_0} \leq r_0 \\ \varphi_{20} + \sum_{i=1}^{p_2} a_{2i} y_{t-i} + \varepsilon_t \sqrt{\alpha_{20} + \sum_{i=1}^{q_2} b_{2i} y_{t-i}^2} & \text{if } y_{t-d_0} > r_0 \end{cases} \quad (9)$$

where $\varphi_{10}, \varphi_{20}, \alpha_{10}$ and α_{20} are constants, $a_{11} \cdots a_{1p_1}, a_{21} \cdots a_{2p_2}, b_{11} \cdots b_{1q_1},$ and $b_{21} \cdots b_{2q_2}$ represent the coefficients of the model with orders p_1, p_2, q_1 and q_2 .

In fact, Li et al. (2016) proposed a similar form of Eq. (9) ($d_1 = d_2$) and further studied the quasi-maximum likelihood estimation of the model. The significant difference between this model and the TAR-GARCH model is that the former makes the dynamic behavior of the conditional variance visible by specifying it in the observation function. Daren and Huay-min (2004) investigated the structure of such models in general settings such as the strict stationarity and V-uniform ergodicity. The FDTDAR model we have proposed (Eq. (8)) is a further extension of previous works. The structure of this model is discussed in more details in Li et al. (2016) and Daren and Huay-min (2004).

235 3.3 Parameter estimation of FDTDAR model

The parameters of the FDTDAR model are estimated using the quasi-maximum likelihood estimation (QMLE) method, considering both the Gaussian distribution (FDTDAR-n) and the student's t distribution (FDTDAR-t) for the residuals.

(1) Gaussian distribution

Assume that the time series y_t is a sample from the FDTDAR model (taking Eq. (8) as an example), given an initial value $\{y_{t-p}, \dots, y_0\}$, where $p = \max\{p_{11}, p_{21}, p_{12}, p_{22}, q_{11}, q_{12}, q_{21}, q_{22}\}$. The conditional log-likelihood function is defined as:

$$Ln(\theta) = \sum_{t=1}^T l_t(\theta) = \sum_{t=1}^T \left[-\frac{1}{2} \log h_t(\theta) - \frac{[y_t - u_t(\theta)]^2}{2h_t(\theta)} \right] \quad (10)$$

where θ is the set of model parameters, $\theta = (C', E', r_1, r_2)' \equiv (C', A', B', r_1, r_2)'$. And $C' = (\varphi_{11}, \varphi_{21}, \varphi_{12}, \varphi_{22}, \alpha_{11}, \alpha_{21}, \alpha_{12}, \alpha_{22})'$, $A = (A_1, A_2, A_3, A_4)$, $A_1 = (a_{11}^1 \dots a_{1p_{11}}^1)$, $A_2 = (a_{11}^2 \dots a_{1p_{21}}^2)$, $A_3 = (a_{21}^1 \dots a_{2p_{12}}^1)$, $A_4 = (a_{21}^2 \dots a_{2p_{22}}^2)$; $B_1 = (b_{11}^1 \dots b_{1q_{11}}^1)$, $B_2 = (b_{11}^2 \dots b_{1q_{12}}^2)$, $B_3 = (b_{21}^1 \dots b_{2q_{21}}^1)$, $B_4 = (b_{21}^2 \dots b_{2q_{22}}^2)$. $u_t(\theta)$ and $h_t(\theta)$ represent the conditional mean and conditional variance of the FDTDAR model respectively. Their specific mathematical expressions are:

$$\begin{aligned} u_t(\theta) = & (\varphi_{11} + A'_1 Z_{1,t-1}) I(y_{t-d_1} \leq r_1, y_{t-d_2}^2 \leq r_2) \\ & + (\varphi_{21} + A'_2 Z_{2,t-1}) I(y_{t-d_1} > r_1, y_{t-d_2}^2 \leq r_2) \\ & + (\varphi_{12} + A'_3 Z_{3,t-1}) I(y_{t-d_1} \leq r_1, y_{t-d_2}^2 > r_2) \\ & + (\varphi_{22} + A'_4 Z_{4,t-1}) I(y_{t-d_1} > r_1, y_{t-d_2}^2 > r_2) \end{aligned}$$

(11)

$$\begin{aligned} h_t(\theta) = & (\alpha_{11} + B'_1 S_{1,t-1}) I(y_{t-d_1} \leq r_1, y_{t-d_2}^2 \leq r_2) \\ & + (\alpha_{21} + B'_2 S_{2,t-1}) I(y_{t-d_1} > r_1, y_{t-d_2}^2 \leq r_2) \\ & + (\alpha_{12} + B'_3 S_{3,t-1}) I(y_{t-d_1} \leq r_1, y_{t-d_2}^2 > r_2) \\ & + (\alpha_{22} + B'_4 S_{4,t-1}) I(y_{t-d_1} > r_1, y_{t-d_2}^2 > r_2) \end{aligned}$$

250 (12)

Where $Z_{1,t-1} = (1, y_{t-1}, \dots, y_{t-p_{11}})'$, $Z_{2,t-1} = (1, y_{t-1}, \dots, y_{t-p_{21}})'$, $Z_{3,t-1} = (1, y_{t-1}, \dots, y_{t-p_{12}})'$, $Z_{4,t-1} = (1, y_{t-1}, \dots, y_{t-p_{22}})'$; $S_{1,t-1} = (1, y_{t-1}^2, \dots, y_{t-q_{11}}^2)'$, $S_{2,t-1} = (1, y_{t-1}^2, \dots, y_{t-q_{21}}^2)'$, $S_{3,t-1} = (1, y_{t-1}^2, \dots, y_{t-q_{12}}^2)'$, $S_{4,t-1} = (1, y_{t-1}^2, \dots, y_{t-q_{22}}^2)'$. $I(\cdot)$ is an indicator function.

Given the initial value of the observation, the quasi-maximum likelihood estimate (QMLE) of the parameter θ can be defined
 255 by the following formula:

$$\hat{\theta} = \operatorname{argmax} \ln(\theta) \quad (13)$$

where $\hat{\theta}$ is the quasi-maximum likelihood estimator of parameter vector θ .

(2) Student's t distribution

The Gaussian Normal distribution is the most commonly used conditional distribution form in the DAR model. However, for
 260 the significant peak-tailed characteristics in hydrological time series, the heavy-tailed distribution of linear model residuals
 may be insufficient, and even the residual series obtained from volatility are required to be heavy-tailed. Therefore, the normal
 distribution assumption of the classic DAR model may not meet the modelling requirements of the hydrological time series.
 Therefore we introduce a skewed conditional distribution into the DAR model to enhance its ability to characterize the heavy-
 tail characteristics of the hydrologic time series.

265 The expansion of the conditional distribution in the classic ARCH model starts from the Student's t distribution. Regarding the
 ARCH model, Engle (1982, 1987, 1990, 1993) mentioned after extensive research that the conditional distribution of the
 volatility model can adopt a non-Gaussian form. Therefore, Bollerslev (1986) first used the student's t distribution to describe
 the distribution form of the residuals. This study used the student's t distribution to expand the conditional distribution of the
 DAR model.

270 Therefore, the student's t distribution is considered in the FDTDAR model, that is $\varepsilon_t \xrightarrow{i.i.d} t(0,1;k)$, where k is the degree of
 freedom of the student's t distribution. The most common probability density function of the student's t distribution is
 expressed as:

$$f(y_t, k) = \frac{\Gamma(\frac{k+1}{2})}{\sqrt{k\pi}\Gamma(\frac{k}{2})} \left(1 + \frac{y_t^2}{k}\right)^{-\frac{(k+1)}{2}} \quad (14)$$

where $\Gamma(\cdot)$ is the Gamma function. M_t is used to represent the scale parameter of the FDTDAR model, then the probability
 275 density function of the time series y_t is expressed as:

$$f(y_t | M_t) = \frac{\Gamma(\frac{k+1}{2})}{\sqrt{k\pi}\Gamma(\frac{k}{2})} \frac{1}{\sqrt{M_t}} \left[1 + \frac{(y_t - u_t)^2}{M_t k}\right]^{-\frac{(k+1)}{2}} \quad (15)$$

When the degrees of freedom $k > 2$, the mean of the residual series ε_t is 0, and the variance h_t is expressed as:

$$E(y_t^2) = \frac{M_t k}{k-2} \quad (16)$$

Therefore, for series y_t with variance h_t and freedom k , the scale parameter M_t can be written as:

$$280 \quad M_t = \frac{h_t(k-2)}{k} \quad (17)$$

The probability density function then becomes:

$$f(y_t|h_t) = \frac{\Gamma(\frac{k+1}{2})}{\sqrt{(k-2)\pi}\Gamma(\frac{k}{2})\sqrt{h_t}} \left[1 + \frac{(y_t-u_t)^2}{h_t(k-2)}\right]^{-\frac{(k+1)}{2}} \quad (18)$$

where the freedom degree k is to be estimated, the conditional log-likelihood function is:

$$\begin{aligned} 285 \quad Ln(\theta) &= \sum_{t=1}^T l_t(\theta) = \sum_{t=1}^T \ln[f(y_t|h_t)] \\ &= \sum_{t=1}^T \ln \left[\frac{\Gamma(\frac{k+1}{2})}{\sqrt{(k-2)\pi}\Gamma(\frac{k}{2})\sqrt{h_t}} \left[1 + \frac{(y_t-u_t)^2}{h_t(k-2)}\right]^{-\frac{(k+1)}{2}} \right] \\ &= -\frac{T}{2} \ln \left[\frac{\pi(k-2)\Gamma(\frac{k}{2})^2}{\Gamma(\frac{k+1}{2})^2} \right] - \frac{1}{2} \sum_{t=1}^T \ln h_t - \frac{k+1}{2} \sum_{t=1}^T \ln \left[1 + \frac{(y_t-u_t)^2}{h_t(k-2)}\right] \end{aligned} \quad (19)$$

where u_t and h_t are calculated by Eq. (11) and Eq. (12) respectively. If there exists a vector $\hat{\theta}$ such that $Ln(\theta)$ has the maximum value, then in the setting of maximum likelihood estimation, vector $\hat{\theta}$ is considered as the maximum likelihood estimator for the parameter vector θ , and it is determined by Eq. (13).

290 In this study, the quasi-maximum likelihood estimation under both residual distributions was implemented using the *nlminb* function in R version 4.4.1, which is an efficient numerical optimization tool. It returns the negative value of the likelihood function; therefore, the actual likelihood value used in the estimation is the negative of the function's output. For both residual distribution scenarios, the model orders ($p_{11}, p_{21}, p_{12}, p_{22}, q_{11}, q_{12}, q_{21},$ and $q_{22}; p_1, p_2, q_1$ and q_2) were exhaustively searched in the range of 0 to 10. The initial values of the parameters were determined based on the autocorrelation functions
295 at different lag orders up to the corresponding model order. Additionally, the *nlminb* function allows for setting constraints on parameter values, which were specified based on the theoretical requirements of the model. Specifically, the parameters associated with the first-order moments were allowed to vary over the entire real line, while the parameters related to the second-order moments were constrained to be greater than 0. The degrees of freedom of the student's t distribution are estimated jointly with the other model parameters, and a constraint of greater than 2 is imposed to ensure numerical stability.

300 3.4 Order determined of FDTDAR model

As expected, as the order increases, the FDTDAR model's ability to describe time series becomes stronger. However, the resulting larger parameter set adds higher complexity to the model structure which reduces the computational speed. Therefore, it is necessary to use a metric tool to determine the optimal order for the model. The evaluation of model quality generally depends on two aspects: the likelihood function value of parameter estimation and the number of unknown parameters in the
305 model. A larger likelihood function value and a greater number of parameters indicate superior model fitting. However, the risk of "overfitting" arises when the model performance at the calibration stage is excessively superior, which could potentially lead to a decrease in accuracy during the prediction stage.

The search for an optimal model order is essentially an optimization task aimed at balancing the two aspects mentioned above. In practical computations, we aim for a larger likelihood function value while minimizing the number of model parameters.

310 The Akaike Information Criterion (AIC) is an effective statistical estimator of prediction error in the context of model order determination. The formula of AIC based on the DTDAR model is:

$$AIC(p) = -2Ln(\hat{\theta}) + 2(p_{11} + p_{21} + p_{12} + p_{22} + q_{11} + q_{12} + q_{21} + q_{22} + 8) \quad (20)$$

During the order determination process, restrict the value of p within the range of 1 to 25 to select the minimum AIC value.

And p_{ij} ($i, j = 1, 2$) and q_{ij} ($i, j = 1, 2$) take values within $[1, p]$, $d_1 \in [1, \min(p_{ij})]$, $d_2 \in [1, \min(q_{ij})]$, $r_1 \in$
 315 $[\min(y_t), \max(y_t)]$, $r_2 \in [\min(y_t^2), \max(y_t^2)]$.

3.5 FTAR-GARCH model

To evaluate the performance of the proposed FDTDAR model, we compare it with the FTAR-GARCH model, a widely used long-memory heteroscedastic model that also incorporates threshold effects.

The TAR model (Tong, 1983) is based on the AR model by adding a threshold to achieve the nonlinear description of the time series mean behavior. The mathematical structure of a two-stage TAR model is written as:

$$y_t = \begin{cases} \omega_{10} + \sum_{i=1}^{p^1} \beta_i^1 y_{t-i} + e_t^1 & \text{if } y_{t-c} \leq \tau \\ \omega_{20} + \sum_{i=1}^{p^2} \beta_i^2 y_{t-i} + e_t^2 & \text{if } y_{t-c} > \tau \end{cases} \quad (21)$$

where ω_{10} and ω_{20} are constants, β_i^1 and β_i^2 represent the coefficients of model with orders p^1 and p^2 , the e_t^1 and e_t^2 are residuals with mean 0 and variance σ^2 , and c and τ express specified time delay and threshold, respectively. The conditional heteroscedasticity information in the residual series of the TAR model is captured by the GARCH (1,1) model (Bollerslev,

325 1986), and its specific form is as follows:

$$\sigma_t^2 = \omega + \nu e_{t-1}^2 + \theta \sigma_{t-1}^2 \quad (22)$$

$$e_t = \sigma_t \eta_t \quad \eta_t \sim N(0, 1) \quad (23)$$

where ω is a constant, ν and θ are coefficients of the GARCH model, σ_t^2 is the condition time-varying variance of the residual series.

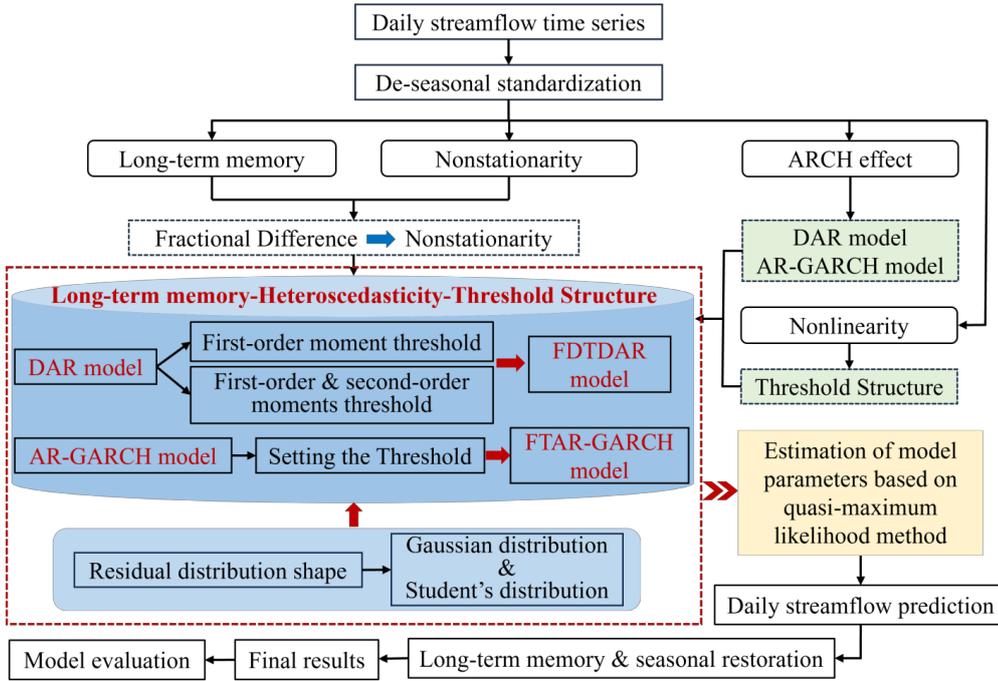
330 3.6 Comparative evaluation methods

Five indicators are used in this study to compare and evaluate the prediction performance of the models, namely Mean Absolute Error (MAE), Root Mean Squared Error (RMSE), Coefficient of determination (R^2), Nash-Sutcliffe efficiency coefficient (NSE), and Absolute Maximum Error (AME) (Dawson et al., 2007; Liu et al., 2020; Moriasi et al., 2007). The smaller the MAE and RMSE, and the closer the R^2 and NSE approaching 1 indicates that the model prediction performance is better. The
 335 interval forecasting performance was evaluated using the Average Interval Width (AIW) and Coverage Rate (CR) whose formulae are given in Wang et al. (2023b).

In addition, the DM (Diebold-Mariano) test is used to compare the accuracy of two models (model 1 and model 2), and its null hypothesis is that the prediction accuracy of model 1 is higher than that of model 2.

340 The residual diagnostics of the model were conducted using the autocorrelation function (ACF), by examining whether the residual autocorrelations at various lag times fall within the 95% confidence interval around 0. If ACF values lie within this interval, the residuals can be considered approximately white noise, indicating that the model has effectively captured the variation structure of the time series.

An overview of the process of building the model in this study is shown in Figure 4.



345 **Figure 4: Model building overview diagram**

4 Results

Figure 5 illustrates the presence order of the FDTDAR model at various hydrological stations. Under the assumption of normal distribution, the values of d_1 and d_2 in the FDTDAR model of TG, SMX, LM, LJ, and AS hydrological stations are different, while in the Student's t distribution, they are different for TG, SMX, LM, FG, and AS stations. Additionally, in the FDTDAR models with equal lag times (Eq. (9)), the value of d_0 is consistently 1, while in another form (Eq. (8)), the lag times (d_1 and d_2) have values of 1 or 2. Furthermore, the order of FDTDAR-n and FDTDAR-t models generally ranges from 1 to 5 days, except for ZT and LJ stations where the FDTDAR-t model order reaches 20.

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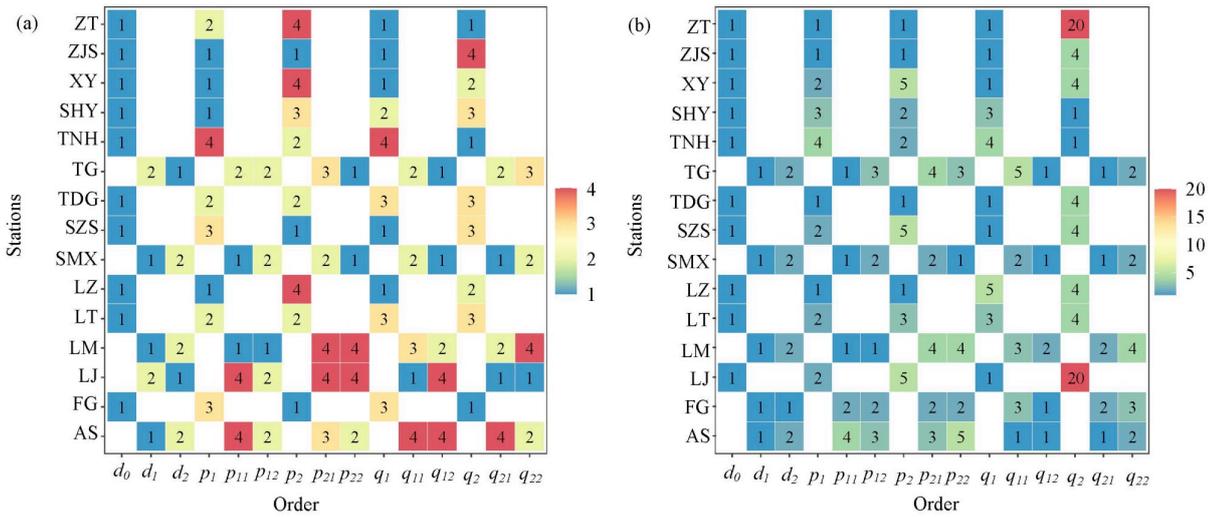


Figure 5: The order of FDTDAR model in 15 hydrological stations, where (a) and (b) represent the normal distribution and the student's t distribution respectively.

Overall, although the FDTDAR model based on Eq. (9) is chosen by the majority of stations, approximately one-third of the stations, mostly located in the mid to downstream areas of the basin, lean towards another pattern. Due to intensified climate change and enhanced human activities, the nonlinearity of daily streamflow time series may continue to grow. FDTDAR models with the same lag time essentially use a threshold at the mean level to simultaneously constrain the behavior of the first and second moments, which may be challenging in addressing the challenges brought about by nonlinear changes at the second-moment level in daily streamflow time series. Except for ZT and LJ stations, the complexity of the FDTDAR models under two residual distribution forms is generally consistent.

The thresholds for the FDTDAR model with different residual distributions at 15 hydrological stations are presented in Table 2. The inputs for each model are daily streamflow time series that have undergone seasonal standardization and fractional differencing. The thresholds for the FDTDAR models based on two residual distributions are identical for the TNH, XHY, SMX, ZJS, LM, and LT hydrological stations.

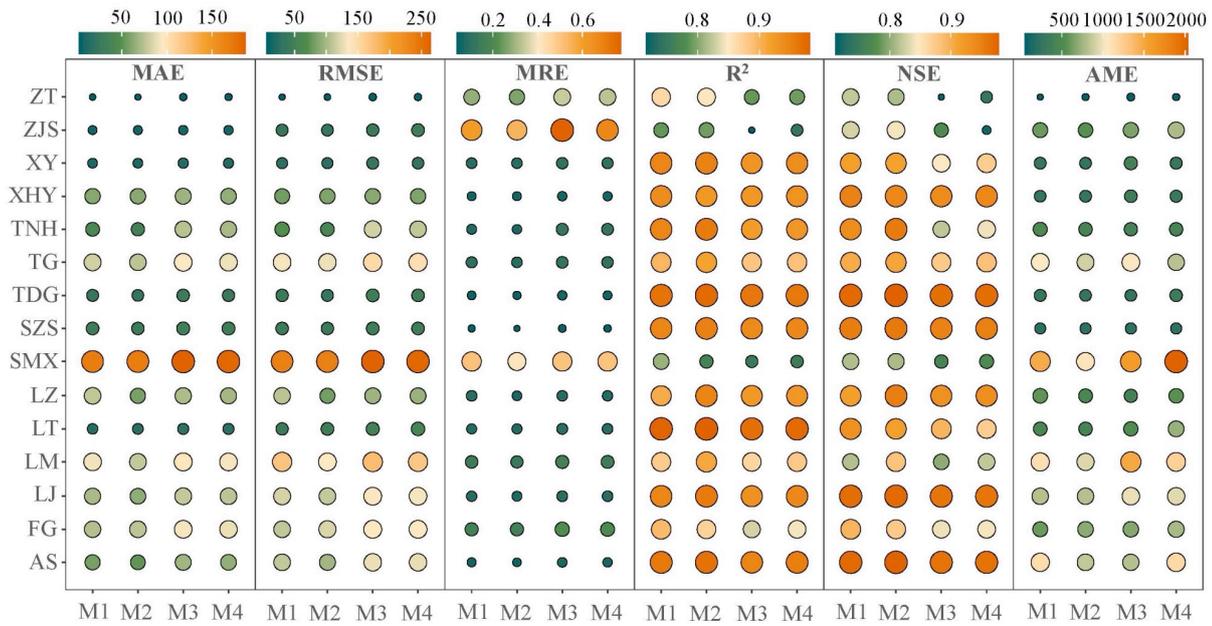
Table 2: Thresholds of FDTDAR model in 15 hydrological stations

Stations	Distributions	r_1	r_2	r_0	Stations	Distributions	r_1	r_2	r_0
TNH	n			-0.71	ZT	n			2.72
	t			-0.71		t			-1.28
SZS	n			-0.25	ZJS	n			1.41
	t			2.4		t			1.41
XHY	n			1.79	LZ	n			0.79

	t		1.79		t		1.79
FG	n		-0.69		TDG	n	-1.7
	t	-3.69	7			t	-0.7
TG	n	-3.2	2.56		LM	n	1.98 3
	t	3.04	10.1			t	1.98 3
SMX	n	-3.42	10.7		LT	n	1.47
	t	-3.42	10.7			t	1.47
AS	n	0.52	3		XY	n	1.54
	t	-1.76	4.63			t	2.09
LJ	n	-1.88	3				
	t		-1.88				

4.1 Comparison between FDTDAR and FTAR-GARCH models

Figure 6 compares the predictive performance of various long memory threshold models at 15 hydrological stations. For mainstream hydrological stations, higher levels of average error (MAE and MRE) and extreme error (RMSE and AME), and lower R^2 and NSE values, indicate poor predictive accuracy for the four models at the SMX station. From a model category perspective, it is observed that for most stations, the FDTDAR class models have smaller MAE, RMSE, MRE, and AME values than the FTAR-GARCH class models. Both model classes show similar predictive accuracy, with R^2 and NSE values above 0.85 at stations other than SMX. FDTDAR-type models are more influenced by the residual distribution shape, and the FDTDAR-t model has lower MAE, RMSE, and MRE values than the FDTDAR-n model. However, there is no significant difference in the three metrics for FAR-GARCH class models based on two distributions. In summary, FDTDAR models exhibit superior predictive ability in mainstream hydrological stations compared to FTAR-GARCH models, and the student's t distribution is more suitable than the normal distribution for describing the changing form of daily streamflow.



380 **Figure 6: Prediction evaluation indicators of long memory threshold models, where M1, M2, M3 and M4 are FDTDAR-n, FDTDAR-t, FTAR-GARCH-n and FTAR-GARCH-t models respectively.**

Furthermore, Figure 6 illustrates that, in the case of four tributary hydrological stations (ZT, ZJS, LT, and XY), the FDTDAR type models exhibit relatively lower values of MAE, RMSE, MRE, and AME, while simultaneously having higher R and NSE values compared to FTAR-GARCH models. The predictive results of FDTDAR and FTAR-GARCH models vary under
 385 different distribution assumptions, with the t-distribution yielding superior predictive performance. In short, FDTDAR models demonstrate strong predictive capabilities in the daily streamflow time series at tributary hydrological stations, and the t-distribution significantly result in better model predictions compared to the Gaussian normal distribution.

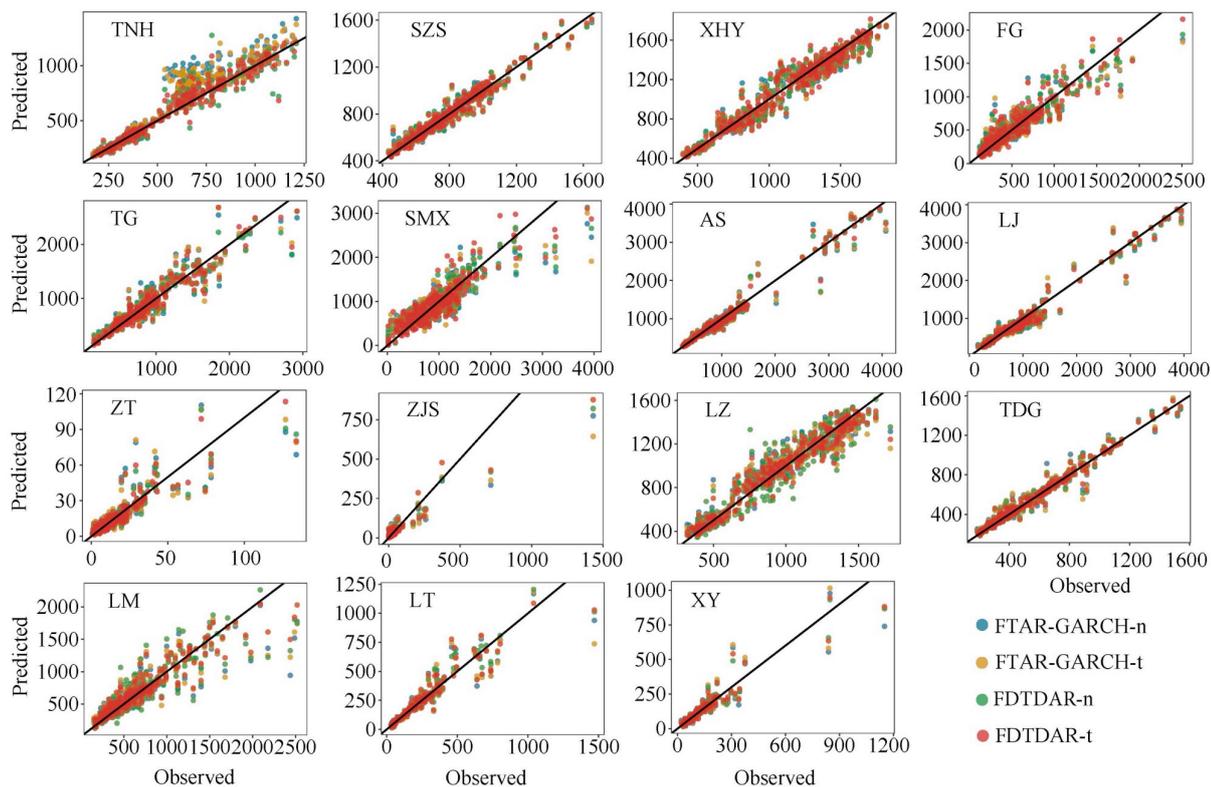
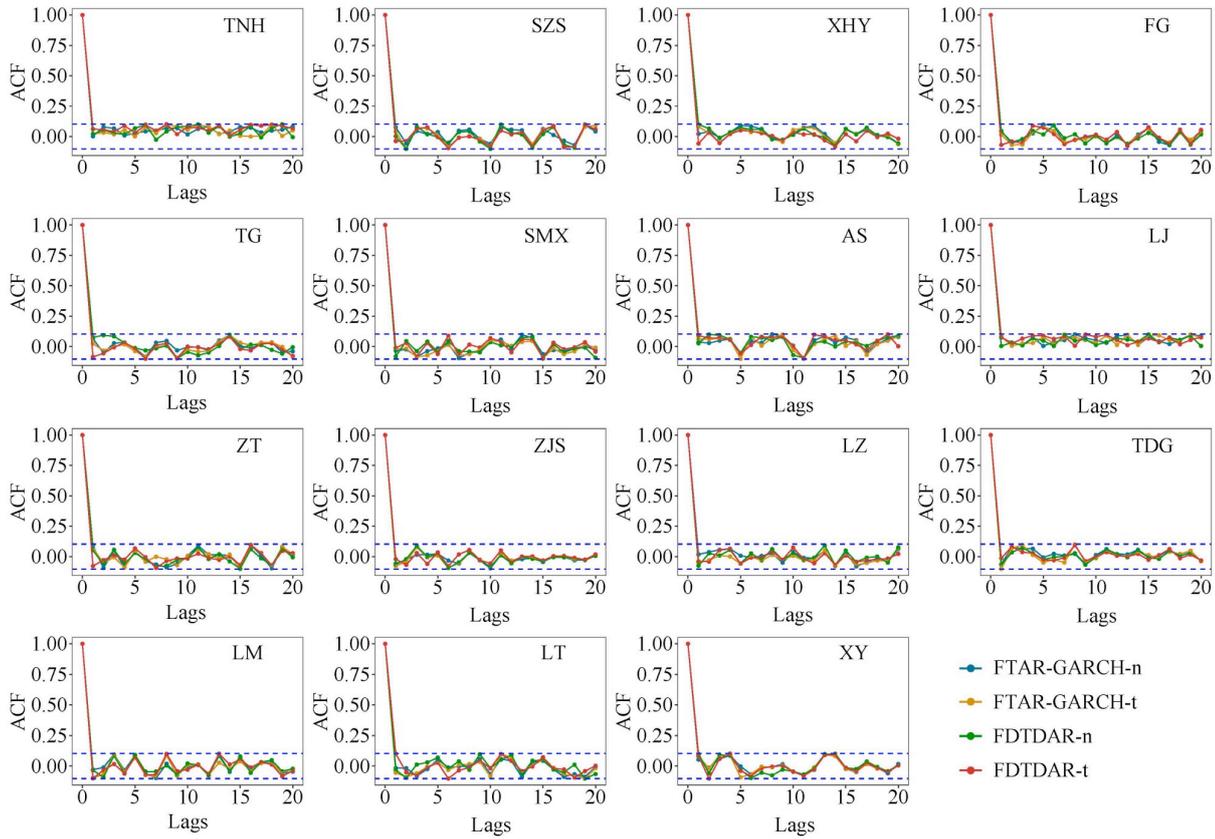


Figure 7: Scatterplots of predictions versus observations of FDTDAR and FTAR-GARCH models at 15 hydrological stations.

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Scatterplots between predictions versus observations of FDTDAR-n, FDTDAR-t, FTAR-GARCH-n, and FTAR-GARCH-t models reveal that for the majority of 15 hydrologic stations, more predictions of FDTDAR scatter closer to the 1:1 line than that of the FTAR-GARCH models (Figure 7). Using the assumption of student's t distribution, both FDTDAR and FTAR-GARCH models predict streamflow values that match better with observed daily streamflow compared to their counterparts assuming a normal distribution (FDTDAR-n and FTAR-GARCH-n models). This suggests that the FDTDAR models have stronger predictive capabilities for daily streamflow time series compared to the FTAR-GARCH models, and the student's t distribution improves the predictive performance and peak description ability of the models under the classical normal distribution assumption.

395



400 **Figure 8: The autocorrelation functions of residuals of FDTDAR and FTAR-GARCH models with respect to time lag in days at 15 hydrologic stations.**

Figure 8 shows that the ACF of the residual series from the long memory threshold FDTDAR and FTAR-GARCH models, based on two different residual distributions, are within the confidence intervals, indicating the absence of autocorrelation in the residual series. This implies that both model types effectively capture practical information in the daily streamflow time series, and the model predictions are reliable.

405

4.2 Effective evaluation of long-term memory threshold structure

This section compares the point and interval prediction performance of DAR-type and AR-GARCH-type models under three different structures (integer differencing, long memory, and long memory threshold) and two residual distribution assumptions. In comparing the point predictions, R^2 and NSE values are chosen to assess the prediction accuracy of the model while for the interval prediction comparison, average interval width (AIW) and containing ratio (CR) values are selected to assess the prediction uncertainty and the inclusion rate of observed values. Finally, the DM test is employed to identify the optimal prediction model structure and type for each hydrologic station.

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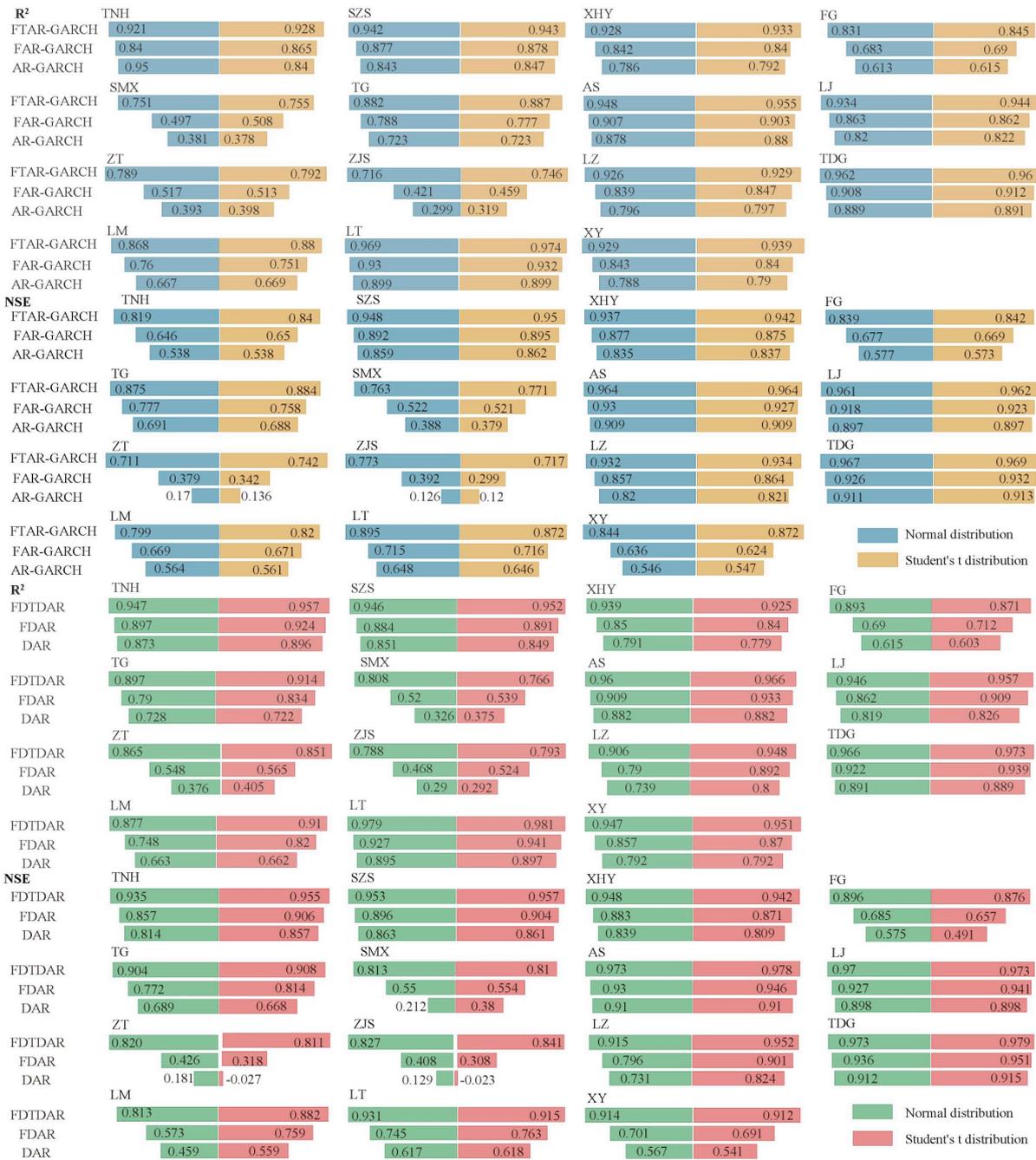


Figure 9: Comparison of prediction accuracy of DAR-type and AR-GARCH-type models based on three structures with two types of residual distributions.

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Figure 9 reveals that under the "long-term memory threshold" structure that considers nonlinear changes, both AR-GARCH-type and DAR-type models exhibit higher R² and NSE values than the two linear structures. Furthermore, the FAR-GARCH

and FDAR models, which account for long-term memory, significantly improve the NSE values of the classical AR-GARCH and DAR models based on integer differencing. This likely indicates that both the long-term memory and strong nonlinearity in the daily streamflow time series significantly influence the predictive performance of the models, and the long memory threshold structure is effective in improving the accuracy of daily streamflow predictions.

Figure 10 and Figure 11 show that the prediction interval width of DAR-type and AR-GARCH-type models with the "long memory-threshold" structure, that consider long-term memory and nonlinear changes, is significantly narrower than those of the "long memory" and "integer differencing" linear structures. However, different settings have minimal impact on the CR values of the models. This indicates that FDTDAR and FAR-TGARCH models could predict observed values more accurately with narrower prediction intervals, because the "long memory threshold" structure significantly improves the interval prediction performance of the models compared to the single "long memory" and "integer differencing" structures.

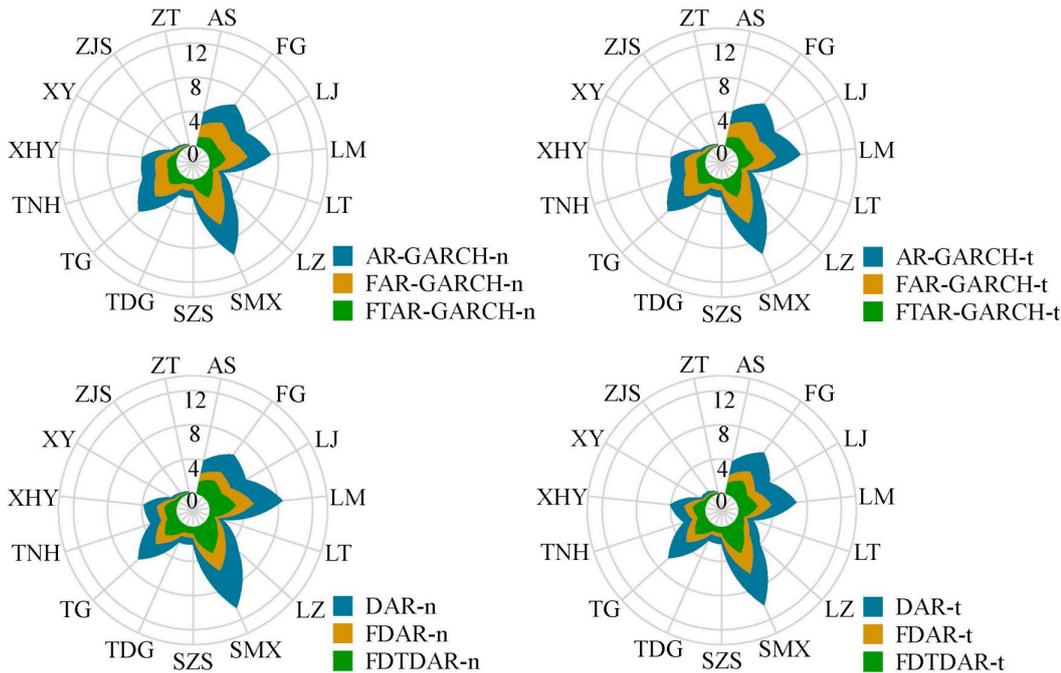
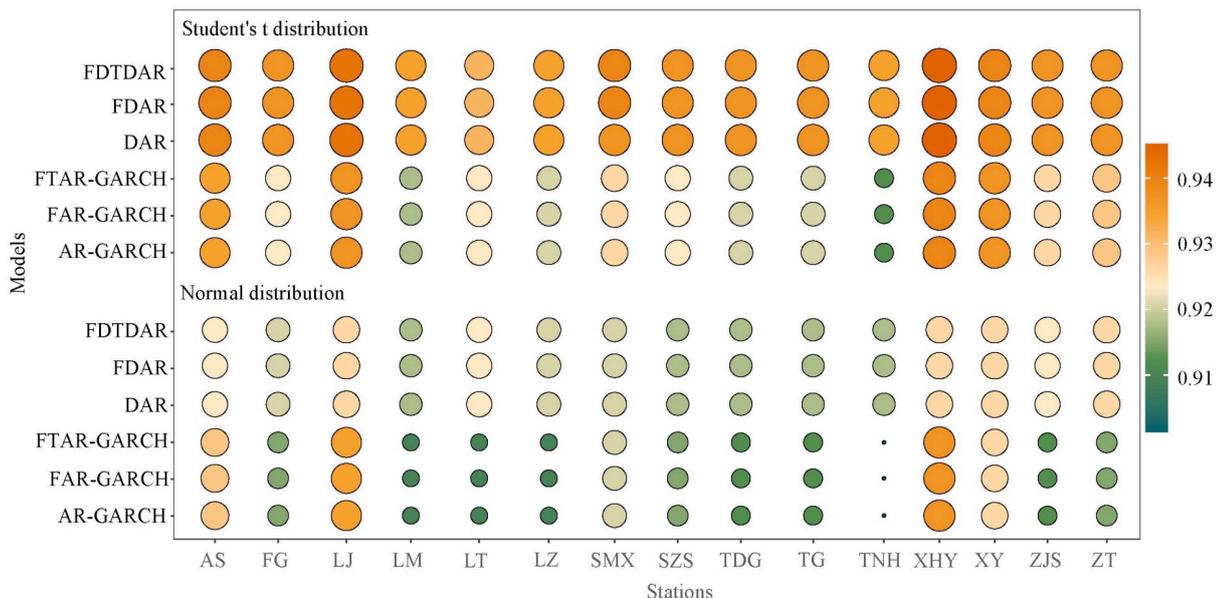


Figure 10: Comparison of AIW of DAR and AR-GARCH models based on three structures.



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Figure 11: Comparison of CR of DAR and AR-GARCH models based on three structures.

The comprehensive evaluation results of the predictive performance of DAR-type and AR-GARCH-type models under different structures are presented in Table 3. In the group of Linear vs. Nonlinear, the linear models are derived from the advantageous models in the difference group, while the two superior models in the residual distribution comparison groups come from the optimised models of each distribution. It can be observed that, except for the ZJS station, the long memory structure based on fractional differencing effectively enhances the predictive ability of the two types of models under traditional integer differencing. The p-values less than 0.05 indicate that the long-memory threshold structure significantly contributes to improving the prediction accuracy of the two type models (DAR and AR-GARCH) with linear changing characteristics (excluding the ZJS station). Additionally, the results of different residual comparison group indicate that TNH, SZS, LJ, LZ, TDG, and LM stations are more suitable for the t-distribution in DAR-type model, while in AR-GARCH-type, only TNH and XHY stations exhibit this preference.

440

Table 3. p -values of DM tests for DAR-type and AR-GARCH-type models under different structures (M1 vs. M2 shows that the original hypothesis of the DM test is that the prediction performance of M1 is better than M2).

Stations	DAR-type model					AR-GARCH-type model				
	Normal distribution		Student's t distribution			Normal distribution		Student's t distribution		
	Difference	Linear vs. Nonlinear	Difference	Linear vs. Nonlinear	n vs. t	Difference	Linear vs. Nonlinear	Difference	Linear vs. Nonlinear	n vs. t
	Integer vs. Fraction		Integer vs. Fraction			Integer vs. Fraction		Integer vs. Fraction		
TNH	0	0	0	0	0.01	0	0	0	0	0.01
SZS	0	0	0	0	0.02	0	0	0	0	0.16
XHY	0	0	0	0	0.96	0	0	0	0	0.02

FG	0	0	0	0	0.96	0	0	0	0	0.33
TG	0	0	0	0	0.33	0	0	0	0	0.21
SMX	0	0	0	0	0.55	0	0	0	0	0.36
AS	0	0	0	0	0.07	0	0.01	0	0	0.46
LJ	0	0	0	0	0	0	0	0	0	0.34
ZT	0	0	0	0	0.64	0	0	0	0	0.1
ZJS	0.07	0.08	0.08	0.08	0.92	0.1	0.09	0.06	0.08	0.89
LZ	0	0	0	0	0	0	0	0	0	0.32
TDG	0	0	0	0	0	0	0	0	0	0.27
LM	0	0	0	0	0	0	0	0	0	0.09
LT	0.01	0	0.01	0	0.93	0	0.02	0	0.01	0.79
XY	0.01	0.02	0	0.02	0.61	0	0.01	0	0.02	0.17

Further comparison was conducted on the preferred models of the two types at each station, with the null hypothesis (DM hypothesis) set as DAR-type model being superior to AR-GARCH-type. The optimal models for each station are determined, with TNH, SZS, LJ, LZ, TDG, and LM stations favouring the FDTDAR-t model, while the DAR-n model performing better at the ZJS station, and the remaining stations favor the FDTDAR-n model.

5 Discussions

5.1 Properties of daily streamflow time series

The daily streamflow time series of the Yellow River Basin, influenced by natural and human factors, exhibit seasonality, long-term persistence, non-stationarity, and time-varying volatility (ARCH effect), which play a crucial role in the performance of the DAR and AR-GARCH models examined in this study. However, the long-term persistence has been overlooked in most studies. The integer difference method is often used to address non-stationary issues to smooth the series (Myronidis et al., 2018; Yan et al., 2022), but it also eliminates the long-term memory information of daily streamflow, resulting in incomplete input information for the model and affecting the performance of the models at both the calibration and prediction stages. Some researchers (Mehdizadeh et al., 2019; O'Connell et al., 2016; Yang and Bowling, 2014) have also studied long-term persistence, demonstrating its importance in predicting the daily streamflow process. However, these researchers have not conducted the second-order moment components, making it impossible to prove whether the ARCH effect is due to the effect of long-term persistence. In recent years, an increasing number of researchers (Dimitriadis et al., 2021; Graves et al., 2017; Grimaldi, 2004) have reported that the detected ARCH effect in the classic AR model may be suspicious due to the lack of consideration of long-term memory, and the results of the further constructed time-varying fluctuation model are thought-provoking. This implies that the results obtained in existing studies on daily streamflow prediction by time series models may be biased due to an incomplete understanding of the characteristics of the research targets. Given the existing problems in the research, in addition to the seasonality and non-stationarity of the daily streamflow time series, this study also considers long-

465 term persistence and time-varying volatility, which has improved the prediction accuracy by correctly accounting for the ARCH effect.

In addition, time irreversibility is also an important property of streamflow time series, although it is insignificant in other hydrological cycle components (e.g., precipitation, evapotranspiration) (Vavoulogiannis et al., 2021). Stationary processes in statistics are typically reversible over time, but the nonlinearity of underlying dynamic procedures is reflected in time
470 irreversibility. River dynamics requires that the time irreversibility of streamflow sequences mainly depends on different triggering factors in the dynamic process which exhibits nonlinear changes. Typically, the increase in streamflow is largely caused by short-term meteorological drivers, which are inherently the dynamic characteristics of precipitation, while groundwater dynamics respond to the streamflow reduction process (Serinaldi and Kilsby, 2016). Table S3 demonstrates a clear evidence of the nonlinear nature of daily streamflow, supporting the existence of time irreversibility. Threshold regression
475 models such as TAR-GARCH and DTDAR have been successful in modeling the nonlinear characteristics of daily streamflow time series, and numerous studies have confirmed their effectiveness in solving nonlinear problems. Therefore, the modeling approach used in this study, incorporating long memory, thresholds, and time-varying fluctuations, is more suitable for describing daily streamflow time series.

5.2 DAR-type model vs. AR-GARCH-type model

480 From the perspective of the general capability of statistical models, both the DAR and the AR-GARCH models can account for the first- and second-order moment information of the daily streamflow time series, but the DAR model has a simpler model structure. One of the most significant differences between these models is that the second-order moment description of the GARCH model uses past conditional fluctuations, as well as past daily streamflow information, to estimate the current conditional variance. In contrast, the DAR model relies solely on past streamflow information. Previous period streamflow
485 values and conditional fluctuations reflect the fluctuation aggregation and long-term behavior characteristics of the time series respectively. Nevertheless, most of the literature (Guo et al., 2021b; Modarres and Ouarda, 2013b; Pandey et al., 2019) found that the classic GARCH model is insufficient in describing fluctuation and aggregation effects, which are generally significant in hydrological time series (Figure S1). Moreover, limited data availability in practice means that short-term volatility clustering is often prioritized over long-term volatility. To avoid long-term persistent interference, the daily streamflow time
490 series is processed with an effective fractional difference approach before being used as the model input. Taken together, these constraints result in better prediction performance and accuracy for the DAR-type models than for the AR-GARCH-type models.

5.3 Threshold regression model

Geosciences acknowledge that data are the only reliable source of information for developing models for hydrologic
495 predictions. The concepts of stationarity and non-stationarity are considered modeling options rather than properties of data because stochastic models are inherently mathematical models (Dimitriadis and Koutsoyiannis, 2018; Koutsoyiannis and

Montanari, 2015). However, model properties such as randomness, determinism, stationarity, and non-stationarity should always align with the data. Furthermore, stationarity is ergodic in practice, i.e., the selected sample data is representative of the entire stochastic process (Koutsoyiannis and Montanari, 2015). Meanwhile, the short-term behavior of hydrological predictions can allow model structure to be inferred from sample data. These provide evidence for the rationality of using data to build models and predict in this study. In regression analysis, the stability of coefficient estimates is usually studied, but the external forcing disturbances such as the effects of climate warming that cause “structural” changes in the streamflow time series cannot be avoided, which hinders the applicability of ordinary linear regression models.

Affected by multiple factors such as global climate change and human activities such as urbanization and deforestation, the nonlinearity of the basin hydrological system could have been enhanced. As early as the 1990s, Xia et al. (1997) had conducted in-depth and systematic research on nonlinear hydrological systems, and explored the nonlinear process of streamflow generation and transformation, as well as the nonlinear mechanism of streamflow formation and transformation from response units to watershed scales. He further proposed a new nonlinear model for streamflow simulation and prediction. In practice, the hydrological gain of streamflow magnitude generated by precipitation is closely related to highly nonlinear controlling factors (such as precipitation, underlying surface conditions, antecedent moisture conditions, soil moisture, etc.), resulting in non-stationary, and highly nonlinear streamflow generated by precipitation and other climatic factors such as wind, atmospheric humidity, evaporation, etc (Milly et al., 2008). Therefore, linear mechanism process models are difficult to simulate representative basin streamflow under an ever changing environment.

In view of the nonlinear changes in water resource systems (Wu et al. 2023), a series of multivariate analysis methods based on nonlinear relationships have been developed, where numerous conditioning factors are input into models to simulate streamflow (Song et al. 2022). These methods improve the simulation and prediction accuracy by comprehensively considering the influence of climate factors, soil properties, terrain conditions and vegetation types on streamflow (Tiwari et al. 2022). Regarding the land surface water balance, precipitation reaches the ground after being intercepted by vegetation leaves, and infiltrates through the soil or becomes surface streamflow. The water intercepted by the leaves and a portion of the water in the soil returns to the atmosphere through evaporation, and the soil moisture absorbed by vegetation for growth is transpired through the leaves, ultimately forming the cycle of atmospheric-land surface water. At present, coupled processes and data-driven multivariate models are developing rapidly, which can take into account the complex mechanisms of streamflow generations and further enhance the simulation and prediction accuracy of single-type models (Zhong et al. 2023).

The univariate method constructed in this study is based on various performance characteristics of streamflow time series, reducing the uncertainty of input factors by generalizing the rainfall-runoff process in a river basin, which should result in more practical and resilient applications statistical models in hydrology. The threshold concept is used to explain the nonlinear variations in the series, which can more accurately describe the linear variation process of daily streamflow time series within different threshold intervals, and has strong robustness and applicability. Moreover, the threshold model is effective in capturing the asymmetric effects of rising and falling limbs in daily streamflow hydrographs, offering higher flexibility in

530 mimicking time-varying, basin-scale rainfall-runoff processes compared to linear structure models, with a high potential for achieving more representative basin hydrologic predictions.

5.4 Limitations of FDTDAR models

535 Compared with modern machine learning models (such as long short-term memory (LSTM) networks or hybrid deep learning architectures), the DAR-type models focused on in this study offer a simpler and more interpretable approach to time series modeling. They are particularly advantageous in scenarios where domain interpretability, limited sample sizes, and computational efficiency are critical. Their transparent structure facilitates parameter estimation, theoretical analysis, and diagnostic evaluation, making them especially suitable for hydrological applications that typically involve noisy data, sparse observations, and operational constraints, thereby enhancing their robustness and reliability in real-world settings (Li et al., 2019; Ling, 2007).

540 However, as any other models, the proposed FDTDAR model also has inherent limitations. First, although it can effectively capture regime-switching behavior and certain nonlinear dynamics, it may fall short in modeling the complex and high-dimensional variations commonly present in large-scale hydrological or climate datasets. Second, the modeling capacity of the FDTDAR framework is constrained by the number of thresholds and lag terms that can be practically specified, which limits its structural flexibility compared with more adaptive, data-driven models such as LSTM. Third, the prediction performance of FDTDAR models often depends heavily on the correct setting of thresholds and lag structures. This adjustment process can be challenging in practice and often requires expert knowledge and extensive experience, or a large number of traversal trials, which may reduce the generalization ability of the model across different regions or datasets.

550 In contrast, machine learning models, particularly deep learning approaches, can learn complex patterns, nonlinearities, and long-term dependencies directly from the data without strong prior assumptions about model structure (van Cranenburgh et al., 2022). These models often demonstrate strong performance in many benchmark tasks. However, their “black-box” nature raises concerns about interpretability and transparency, which are critical in scientific and decision-making contexts such as hydrology (Beven, 2020; Hosseini et al., 2025). In addition, the high computational cost, demand for large training datasets, and sensitivity to hyperparameter tuning may restrict their applicability in resource-limited environments or real-time forecasting systems.

555 Given these trade-offs, this study focuses on DAR-type models as a theoretically sound and operationally tractable alternative to traditional AR-GARCH models. While the proposed FDTDAR framework strikes a balance between model simplicity and nonlinear expressiveness, we acknowledge that future research should include comprehensive comparisons with state-of-the-art machine learning models. Such efforts would help in further assessing the strengths and limitations of the proposed approach and explore the potential of hybrid frameworks that combine the interpretability of statistical models with the flexibility of machine learning techniques.

560 In terms of the model residuals, although the student’s t distribution used in this study effectively captures heavy tails, it does not account for potential asymmetry in the distribution of hydrological residuals. In real-world streamflow processes,

especially during flood or drought events, residuals may exhibit skewness in addition to heavy tails. Therefore, more flexible distributions, such as the skewed or generalized t-distributions, may offer a better fit for such cases. While these distributions were not explored in the present study, they represent a promising direction for future research aimed at enhancing the model's adaptability to extreme or asymmetric behavior.

6 Conclusions

The nonlinear changes of the daily streamflow time series driven by the external environment cannot be ignored, and the strong non-stationarity and volatility, as well as its long-term memory, together lead to an increase in the difficulty of streamflow prediction, which lead to major challenges to the traditional time series models. To address this issue, this study introduced a novel DAR model and further proposed the DTDAR model, which considered these critical features and added certain thresholds, for improving the accuracy of daily streamflow time series prediction. The main conclusions of this study can be summarized as follows:

- (1) The DAR model is a better alternative to the AR-GARCH model for predicting daily streamflow time series. Both the linear structure DAR and the threshold DTDAR models outperform the AR-GARCH and TAR-GARCH models in terms of predictive ability.
- (2) The nonlinear changes of the daily streamflow time series are reflected in multiple linear structures by adding the threshold, improving the accuracy of the single linear structure method. The NSE values of the DTDAR and TAR-GARCH models are higher than those of the DAR and AR-GARCH models by 0.056-0.229 and 0.032-0.431, respectively.
- (3) We demonstrated that using the t-distribution is a better choice than the traditional normal distribution in modeling residuals for predicting daily streamflow time series for both FDTDAR and FTAR-GARCH models.

Code and data availability. The seasonally normalized and fractionally differencing daily streamflow data in this study can be downloaded from <https://doi.org/10.6084/m9.figshare.26795140.v1>. The codes for calculating results and plotting figures is available upon request.

Author contributions. HW: conceptualization, methodology, software, formal analysis, data curation, writing – original draft, writing – review and editing, and visualization; SS: conceptualization, methodology, investigation, data curation, writing – review and editing, supervision, project administration, and funding acquisition; GZ: conceptualization, methodology, investigation, data curation, writing – review and editing, supervision, project administration, and funding acquisition; TG: Formal analysis and writing – review and editing; ZP: Formal analysis and writing – review and editing.

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