



1 A physical model for mean river discharge calculation:

² from riverside seismic monitoring experiments in a low-

3 flow river, China

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- 15 Abstract.

16 The dynamics of water flow and sediment transport in river systems play a crucial role in shaping river

- 17 morphology, in the planning and use of river infrastructure and the broader watershed management.
- 18 However, these characteristics are often challenging to measure comprehensively. On March 17, 2023,
- 19 we studied a low-flow river system (≤0.611 m³/s) within the boundaries of Yuancun in the Township of
- 20 Meishui. By synchronously monitoring the microseismic signals generated by the river and the river flow
- 21 velocity, we explored the relationship between these microseismic signals and the river discharge. During
- 22 each experiment, we used 3 to 4 three-component seismometers placed in close proximity to the
- 23 riverbank (at the distance of approximately 1 meter), with one device submerged underwater to record
- the microseismic signals caused by the flow. The signals exhibited a wide frequency range (2-50 Hz).
- 25 An analysis of the recorded microseismic signals and the flow data revealed an approximate linear
- relationship between the seismic noise in the 2-10 Hz bandwidth and the river flow. We used a least
- 27 squares regression model to invert the river flow from the 2-10 Hz microseismic signals and found that
- 28 the maximum relative error between the inverted flow and the measured values was 10.3%. The results
- 29 show that even at low flow rates, real-time monitoring of river processes is possible through continuous
- 30 time-frequency analysis of microseismic signals; this increases the potential for future applications of
- 31 seismic monitoring in real-time observation of hydrological evolution in river systems.





32 1 Introduction

33	The components of river monitoring usually include encompass river water level, flow velocity,
34	discharge, and sediment flux. Currently, there are two main approaches to river monitoring: one is the
35	hydrological monitoring system based on hydrological stations, and the other is the remote sensing
36	monitoring method, which has gradually developed with the maturity of remote sensing technology. Both
37	methods require the establishment of hydrological stations and the installation of measuring instruments,
38	which makes the monitoring process complex, time-consuming, and resource-intensive (Roth et al., 2016;
39	Cook et al.,2022; Larose et al.,2015). There is also a risk of the instruments being damaged and data
40	being lost during floods. In recent years, an increasing number of researchers have explored the
41	correlation between microseismic signal fluctuations and changes in river discharge and sediment flux,
42	demonstrating the potential of microseismic monitoring technology for hydrological studies (Turowski
43	et al., 2011). Since the early 1990s, when Govi et al. (1993) first deployed short-period seismometers in
44	river channels to record microseismic signals and investigate the relationship between these signals, river
45	discharge, and sediment transport, more researchers have begun to investigate the relationship between
46	microseismic signals and river hydrodynamics (Rickenmann et al., 2012). Schmandt et al. (2013) have
47	found that the sources of the microseismic signals could be related to water flow noise caused by
48	turbulence, sediments impinging on the riverbed, or acoustic waves generated by interactions between
49	water and the atmosphere. Díaz et al. (2014) conducted 36 months of continuous microseismic
50	monitoring of the Aragon River and identified three types of river-induced seismic events, each with
51	distinct characteristics related to floods caused by moderate rainfall, seasonal snowmelt, and severe
52	storms. This demonstrates that microseismic monitoring can not only aid in studying the hydrological
53	characteristics of rivers but also has significant potential in assessing hydrological hazards. Therefore,
54	continuous microseismic monitoring of ambient noise generated by rivers can provide valuable insights
55	into the study of the hydrological characteristics of rivers.

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57 Microseismic monitoring of rivers can provide a wealth of seismic data on the vibrations of river 58 sediments, and the interpretation of microseismic signals to infer hydrological parameters is one of the 59 essential tasks of microseismic monitoring in rivers. Roth et al. (2016) used broadband (5–480 Hz) 60 microseismic data, river discharge data, precipitation data, and bedload data from the Erlenbach River in





61	the Swiss Pre-Alps to propose a simple, empirically adjusted linear model for estimating bedload
62	transport rates. Their predictions showed a strong correlation with the transport rates determined by
63	calibrated seismic detectors in the river. Burtin et al. (2011) analyzed a braided river with a discharge
64	range of $1-5 \text{ m}^3$ /s at low water levels by simultaneously measuring river discharge, bedload, and seismic
65	signals during a limited summer period. Their analysis revealed that seismic signals in the $1-10$ Hz band
66	were most indicative of changes in the river water level, with seismic waves originating from turbulence.
67	This demonstrates that microseismic monitoring can be used to investigate hydrological characteristics
68	even at low discharge and can provide earlier indications of flow changes in the downstream main stem
69	of the river (Anthony et al., 2018; Gaeuman et al., 2014).

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71 Microseismic monitoring has practical applications in flood monitoring and early warning systems and 72 could also be used in the future to monitor geological disasters through seismic networks. Analysis and 73 prediction of geological hazards based on microseismic monitoring offers a significant advantage over 74 current methods based on hydrological monitoring stations and remote sensing. By analyzing the time-75 frequency characteristics of microseismic signals, floods can be identified and their evolution monitored. 76 Additionally, through inversion methods, hydrological data such as river discharge and sediment content 77 can be derived. Microseismic technology offers a new method for online monitoring of river dynamics 78 and flood early warning, which has enormous potential for the assessment of hydrological hazards.

79

80 This study focuses on the monitoring of tributaries with low discharge. The Jiuqu River in Yuan Village, 81 Meishui Township, Shangyu County serves as the research object, and through experimental field studies, 82 a microseismic monitoring system is deployed along the riverbank of the tributary to monitor the ground 83 vibrations caused by changes in the flow to stimulate the low-frequency microseismic signals, elaborate 84 and interpret the river microseismic signals by removing the noise of human activities, such as vehicles, 85 from the ambient noise, analyse the physical characteristics of the river microseismic signals, and construct a mathematical model using microseismic signals to invert river flow, predicting real-time river 86 87 flow (Viparelli et al., 2011), and providing a reference for monitoring and early warning of river flooding 88 and downstream river flow changes in the region.





89 2 Experiments

90 2.1 Experiment sites

The river studied in this study, the Jiuqu River, is a tributary of Meishui River, located in the territory of 91 92 Meishui Township in Shangyou County, China (Figure 1). Meishui Township is situated in a hilly and 93 mountainous area with an altitude of 200-300 m, and its relative height is 50-100 m. The exposed strata 94 are the Devonian and Carboniferous of the Late Paleozoic, and the lithology mainly consists of quartz 95 conglomerate, quartz sandstone, siltstone and dolomitic greywacke. It slopes from north to south, with a 96 gentle terrain, and belongs to the subtropical monsoon climate zone, with an average annual precipitation 97 of 1,235.6 mm. In this study, four monitoring experiments were conducted at four sections of the Jiuqu 98 River with different discharge. Current meters and seismic stations were installed on the riverbank to 99 measure the flow velocity and seismic ambient noise in each segment. For this experiment, we selected 100 a curved section of the Jiuqu River, approximately 1.4 kilometers long, with a river width ranging from 101 3 to 9 meters and a depth of 0.1 to 0.4 meters. The overall morphology of the river channel resembles 102 that of a drainage canal, with the riverbed consisting of gravel, fine sand, and pebbles. The gravel particle 103 size varies; the upstream section features smaller gravel particles, while the downstream section exhibits larger gravel particles (Aderhold et al., 2015). The maximum gravel size is $50 \times 36 \times 20$ cm, with an 104 105 average size of $13 \times 10 \times 5$ cm. Some segments of the riverbed contain silt. During the experiment, water 106 samples were taken to measure the sediment concentration, which was found to be approximately 0.5% 107 in the studied river section. Throughout the experimental period, the river's discharge was less than 5 108 m³/s, which classifyies it as a low-flow river (Figure 2).









Figure 1. The geophones at the four experimental sites. The red triangles represent the three base stations in test 1, the green triangles represent the four stations in test 2, the blue triangles represent the four stations in test 3, and the yellow triangles represent the four stations in test 4.

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Figure 2. Cross-sectional views of the river; a), b), c), and d) are cross-sectional views of the river at the first, second, third, and fourth experimental sites, respectively. The grey ovals represent river bottom pebbles, the

117 blue blocks represent river water, and the brown blocks represent river bottom sediment.

118 2.2 Seismic monitoring

- 119 Seismic ambient noise was collected from both the river sections and the nearby road areas. Seismic
- 120 instruments offer a variety of sensors with different characteristics, such as accelerometer, velocimeter





121	with different Eigenfrequency and useable frequency bands, making them suitable for specific
122	applications such as seismic imaging, monitoring, or civil engineering. The instruments can be broadly
123	categorized into two types: short-period seismometers and geophones, which are sensitive to high-
124	frequency bands ranging from 1 to 10 Hz up to 500 Hz. These instruments are well-suited for monitoring
125	most geomorphological seismic sources. Surface processes also generate low-frequency seismic waves,
126	requiring the use of broadband seismometers, which are sensitive to higher frequency signals as well.
127	Both broadband and most short-period seismometers typically record seismic signals in three-
128	dimensional configurations across orthogonal axes aligned vertically, north-south, and east-west,
129	facilitating the comparison of directional information from multiple stations. The use of three-component
130	instruments allows for greater data processing diversity compared to single-component instruments. For
131	instance, the polarity of seismic waves can be used to determine the source type and provide information
132	about the direction of wavefront incidence in localization problems (Burtin et al., 2014).

133

134 The seismic stations used in this experiment were four three-axis velocimeter stations (S45 triaxial velocimeter and SL06 recorder, SARA electronic instruments s.r.l., Italy), which was utilized to monitor 135 136 seismic signals generated by the river, with a sensitivity factor of 78 V/m/s. The sensor components of 137 the device were east-west (E), north-south (N), and vertical (Z). The natural frequency of these 138 instruments was 4.5 Hz, and we set the sampling frequency for all instruments to 200 Hz. A total of four 139 seismic stations were employed, one of which (Station 3) was an integrated velocimeters and data 140 collector (Velbox, SARA electronic instruments s.r.l., Italy). The other three stations were separate, each equipped with a SARA 24-bit A/D converter (SL06), connected to a 24-bit digitizer via the converter. 141 Each monitoring device was leveled using a spirit level and placed on a triangular support base to isolate 142 143 it from the ground. Real-time positioning of each monitoring device was conducted using GPS, and the power supply for the monitoring devices was provided by outdoor 12 V-60 A batteries shared between 144 145 different stations.







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147 Figure 3. Detailed location distribution map of the four stations in test2, where S2 was placed in the middle 148 of the river channel to be flooded, S4 was placed 1 m away from the river channel, S5 was placed 1.5 m away 149 from the river channel, and S3 was placed 1.5 m from the road.

- 150 During the research period on March 17, 2024, we conducted four experiments on the Jiuqu River in
- 151 Meishui Township, measuring seismic data from four river sections. Each experiment lasted for 20
- 152 minutes, during which 3 to 4 seismometers were installed approximately 1.5 meters from the riverbank
- 153 to monitor the seismic signals generated by the water flow. Since the river sections are located adjacent
- 154 to a road, vehicle and human activities occurred during the experiments. Therefore, in all four
- 155 experiments, the S3 (Station 3) was placed about 1 meter from the riverbank, near the road. This
- 156 configuration aimed to record microseismic signals generated by river activities while minimizing
- 157 interference from human activities.
- 158 For the second experiment, the detailed positions of the four stations and the microseismic signals
- 159 recorded by each station are illustrated in Figure 3. Given that the studied river sections are classified
- 160 as low-flow segments, the instruments were placed very close to the river channel. Specifically, S2 was
- 161 submerged in the middle of the river, S4 was located 1 meter from the riverbank, S5 was positioned 1.5
- 162 meters away, and S3 was situated 1.5 meters from the road (Figure 3).





- 163 By processing the signals recorded by the four stations and plotting the spectrograms, we found that the
- 164 dominant frequency range of the microseismic signals generated by the river was between 2 and 10 Hz.
- 165 In contrast, the noise frequencies generated by human activities and vehicle traffic concentrated
- 166 between 7 and 25 Hz (Figure 4). Moreover, the differences in the arrangement of the stations relative to
- 167 the river channel indicated that the stations were unable to monitor detailed microseismic signals at
- 168 greater distances from the riverbank. This limitation is primarily due to the nature of the studied river
- as a low-flow system, which does not produce sufficiently strong signals.







171 Figure 4. Seismic waveform and spectra recorded by seismometers, S2, S3, S4, and S5, at the test 2.

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173 2.3 River flow velocity measurement and discharge calculation

- 174 In the study, both the flow velocity and water depth of the river sections were measured. The flow
- 175 velocity was measured using a portable flow velocity meter (model LS1206B, Nanjing Jun Can
- 176 Instrument Equipment Company, China). To enhance the accuracy of the measured flow velocities,
- 177 vertical and horizontal sampling interval were set at 0.1 m and 1 m in a river section, respectively. In
- 178 the third experiment, a continuous flow velocity meter was employed to monitor flow velocity over a
- 179 period of twenty minutes.
- 180 Calculating river flow is typically achieved by determining the average flow velocity of the water
- 181 passing through the measured cross-sectional area. Additionally, flow can be directly measured using
- 182 appropriate devices or estimated using indirect methods such as empirical equations and mathematical
- 183 models. This study utilized a common flow calculation method, the velocity-area method (Herschy,
- 184 1993). The principle of this method involves dividing the river's cross-sectional width into several
- 185 slices based on the cross-section, then calculating the flow for each slice using its average slice velocity
- 186 and slice area, and finally summing these to obtain the total river flow. A schematic diagram of the
- 187 calculation is shown in Figure 5.
- 188





Figure 5. Schematic diagram of the velocity-area method for estimating river flows

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193 Calculate the width of the slice b_i :





194	$b_i = p_i p_0 - p_{i-1} p_0 \tag{1}$
195	Where $p_i p_0$ denotes the distance from the <i>i</i> th vertical measurement point to the start of the riverbank.
196	Calculate the depth of the slice d_i
197	$d_i = \frac{h_{i-1} + h_i}{2} \tag{2}$
198	Where h_{i-1} and h_i are the water level measured at the <i>i</i> -1 vertical measurement point and the <i>i</i> vertical
199	measurement point, respectively.
200	Multiplying the result of equation (1) with the result of equation (2) gives the slice area A_i :
201	$A_i = b_i d_i \tag{3}$
202	The most common methods for determining the mean slice velocity (mean vertical velocity) are the
203	vertical velocity profile method, the two-point method and the six-tenths depth method. Since only the
204	surface velocity of the river was measured in this experiment and that the study river is a low flow stream,
205	the linear relationship proposed by (Genç O et al., 2015) twas used for the calculation of the mean slice
206	velocity. The mean slice velocity u_i :
207	$u_i = 0.552\bar{u}_{wsi} \tag{4}$
208	Where \bar{u}_{wsi} denotes the slice-averaged water surface velocity and its value is:
209	$\bar{u}_{wsi} = \frac{v_{i-1} + v_i}{2} \tag{5}$
210	Where v_{i-1} and v_i are the surface flow velocity measured at the <i>i</i> -1 vertical measurement point and
211	the <i>i</i> vertical measurement point, respectively.
212	The slice flow rate for each slice q_i is obtained by combining equation (3) and equation (4):
213	$q_i = u_i A_i \tag{6}$
214	Final river flow Q obtained: $Q = \sum_{i=1}^{n} q_i$
215	(7)
216	Where <i>n</i> denotes the number of slices.
217	The profile data measured in the four experiments were processed by the above calculation process to
218	obtain the river flow rates of 0.444 m ³ /s, 0.611 m ³ /s, 0.512 m ³ /s, and 0.598 m ³ /s for tests 1, 2, 3, and 4, m^{1}
219	respectively.





220 3 Seismic ambient noise

221	Geophones can detect elastic waves generated by processes occurring on or near the Earth's surface,
222	which are emitted by the transmission of energy from objects impacting the ground, such as boulders
223	falling from slopes, pebbles bouncing on the riverbeds, or raindrops falling to the ground. The sources
224	of elastic waves generated by river processes can be quite complex and depend on the flow configuration
225	of the river. Possible sources include particle collisions during sediment transport, turbulence, bubble
226	explosions, friction between water flow and riverbed or riverbanks, and the propagation of gravity waves
227	or breaking waves on the river surface. The frequency range and physical characteristics of microseismic
228	signals produced by different river processes are distinct. By analyzing images such as time-frequency
229	analysis diagrams of microseismic signals, multiple overlapping seismic sources within different
230	frequency ranges can be distinguished, and the contributions of different river processes can be extracted,
231	thus enabling real-time monitoring of various river processes.

232

233 **3.1 Human noise**

234 Human activities can also cause seismic disturbances, such as industrial activities, vehicle noise, or 235 people walking near seismometers. Although noise from human activity is highly variable, some typical 236 time-frequency characteristics of noise from human activity can be highlighted. The river section studied 237 in this research is located next to a road. During the monitoring period, vehicles driving on the road may 238 generate signals that could affect the experiment, which is the main source of human activity during this 239 research period. To exclude the interference from human activity, we placed the base station S3 1.5 meters 240 away from the road in four experiments to monitor the human activities noise during the experimental period. Vehicles passing through the research section represent individual disturbances, which are of 241 242 short duration and mainly affect the frequency range from 2 to 40 Hz, with high signal amplitudes and 243 rapid attenuation of high-frequency signal amplitudes. The signal is more susceptible to attenuation with increasing distance, and is only recorded at nearby stations. As can be seen from the waveform of the 244 245 microseismic signal at the S3 base station in the second experiment, the microseismic signals generated 246 by passing vehicles are rarely coherent over the entire monitoring array (Figure 6). Therefore, the noise 247 from human activities is not the main source of seismic energy in this study and can be largely filtered







248 out with a bandpass filter.

249

Figure 6. Waveforms and spectrograms of microseismic signals generated by the river and vehicle travelling
in test2. Top: seismic signal emitted by vehicle recorded by S3 in test 2; bottom: seismic signal emitted by
river recorded S2 by in test 2, 20 meters away from S3.

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254

255 3.2 Still water flow

256 Except for the river section in the fourth experiment, which is located in a position with a steep slope and high water flow rate, the water flow in Test 1, Test 2 and Test 3, was relatively slow. Analyzing the 257 258 microseismic signals and their spectral characteristics produced by the rivers in Test 1, Test 2 and Test 3, 259 the seismic responses recorded by the monitoring stations in the three river sections share many 260 similarities. Throughout the entire monitoring period, the seismic signals exhibit a clear broadband 261 (2~50Hz) seismic response in both horizontal and vertical components. From the time-frequency analysis 262 and spectral plots of Test 1 (Figure 7), the energy of the microseismic signals is distributed across the 263 1~50 Hz frequency band, with most of the energy concentrated in the 2~16 Hz band. In Test 2, the energy of the microseismic signals is distributed across the 1~60 Hz frequency band, with most of the energy 264 265 concentrated in the 2~12 Hz band. In Test 3, the energy of the microseismic signals is distributed across 266 the 1~50 Hz frequency band, with most of the energy concentrated in the 2~10 Hz band. By performing 267 time-frequency analysis on the microseismic signals recorded by the monitoring stations closest to the river channel in the three experiments (namely S4, S2, and S4 stations) and calculating their Power 268 269 Spectral Density (PSD), the results plotted in the same graph show that for these three experiments the





270 energy distribution is mostly concentrated in the 2~15 Hz frequency range (Figure 8). 271 272 Previous studies showed that river flow and its variations tend to excite low-frequency seismic power (1-273 10 Hz), that there is a significant correlation between anomalous microseismic signals in the 2-10 Hz 274 band and river flow variations, and that the seismic power at 50 Hz has a linear relationship with the 275 measured sediment fluxes in the riverbed (Burtin et al., 2011; Gimbert et al., 2014; Tasi et al., 2012; Díaz 276 et al., 2014). The main frequency bands observed in this study are generally consistent with the 277 conclusions drawn by previous scholars, and there was no significant sediment transport process during 278 the experimental period. The seismic energy is mainly contributed by turbulence, so we can infer that the 279 low-frequency band of 2~10 Hz in the experimental spectrum is related to the turbulent flow process of 280 the river, and the changes in its energy reflect the changes in river flow rate.



281

Figure 7. Spectrograms of the microseismic signals generated by the river. a), b), c) River spectrograms of the

283 microseismic signals generated by the river at locations 1, 2 and 3 of the experiment, respectively (missing

284 data due to instrumental interruptions are in the red boxes).







285

Figure 8. Acceleration power spectral density plots of microseismic signals generated by rivers. The green curve represents the PSD curve of the water flow at the nearest base station S4 of the river in test 1, the blue curve at base station S2 in test 2, the orange curve at the base station S4 in test 3; the blue dashed box highlights the frequency band of maximum energy distributions of microseismic signals of tests 1, 2, 3.

291

292 **3.3 Turbulent river and sediment transport**

293	Geophones can detect elastic waves generated by processes occurring at or near the Earth's surface. These
294	elastic waves result from the transfer of energy produced by objects striking the ground. The sources of
295	elastic waves generated by river processes can be quite complex, depending on the flow configuration of
296	the river. These sources include particle collisions during sediment transport, water turbulence, bubble
297	explosions, and the propagation of gravity waves or breaking waves on the river's surface (Figure 9).
298	Sediment transport encompasses various particle movements, such as suspension, rolling, hopping, and
299	sliding (Boano et al.,2011).

- 300 These river processes induce vibrations in the riverbed, generating elastic waves that propagate through
- 301 the ground medium as vibrational signals. Within the range where the signal energy dissipates
- 302 completely, the deployed microseismic stations can receive these signals and record them as





303 corresponding voltage fluctuations.



Figure 9. Seismic noise generation by turbulent flow in rivers. The brown ovals represent gravel particles in the river, which generate microseismic signals as they move with the current, the white ovals represent microseismic signals generated by the explosion of air bubbles in the water.

308 309

310 During the research period, the fourth experiment was conducted in a section of the river channel with 311 large boulders that create a certain drop in the riverbed. The riverbed in this area is composed of gravel 312 and pebbles, with the largest gravel size measured at $50 \times 36 \times 20$ cm. The time-frequency analysis and 313 spectral plots from this location indicate that the energy of the microseismic signals is concentrated in two distinct frequency bands, namely 2~15 Hz and 35~50 Hz, with the maximum energy located in the 314 315 7~15 Hz band (Figure 10a). The time-frequency plot from Test 2 shows that in sections of the river 316 channel where the gradient is gentler, the energy of the microseismic signals is primarily concentrated in 317 the 2~12 Hz frequency band (Figure 10b). Research by Burtin et al. (2011) indicates that river flow and 318 its variations tend to excite low-frequency seismic power ($1 \sim 10$ Hz). Schmandt et al. (2013) found that 319 between 35~50 Hz, this band includes frequencies (15~45 Hz) previously identified as being excited by 320 sediment transport in river studies. Based on the data from this experimental study, it can be inferred that 321 the seismic energy in the fourth experiment mainly originates from the river and the flow of river water 322 driving a small amount of sediment transport to produce microseismic signals. The low-frequency band 323 of 2~15 Hz in the spectral plot is related to the river flow process, while the higher frequency band of 324 35~50 Hz is associated with the river's impact on the riverbed, a small amount of sediment transport, and 325 human activities (Barrière et al., 2015; Bagnold et al., 1966; Turowski et al., 2016). Since the river studied 326 in this research is a low-flow river system, with no significant sediment transport phenomena observed 327 during the experiment, a detailed exploration of the characteristics of microseismic signals generated by 328 sediment transport was not carried out.







329 330

331 Figure 10. Time-frequency diagrams of microseismic signals generated by rivers and their spectral 332 characteristics. a) is the time-frequency analysis and spectral characteristics of the river with a certain drop 333 of the river section at four places of the experiment; from the time-frequency analysis, it can be seen that the 334 energy of the microseismic signal is concentrated in the more obvious two frequency bands, respectively, 2~15 335 Hz, 35~50 Hz; b) is the time-frequency analysis and spectral characteristics of the river at two places of the 336 experiment in the gently sloping section of the river, and the microseismic signal is mainly concentrated in the 337 2~12 Hz frequency band. The red dashed box shows missing data caused by the instrumental interruption, 338 and the blue dashed box shows the frequency band where the energy of microseismic signals is mainly 339 distributed.

340 4 Seismic interpretation and river discharge calculation

341 4.1 Seismic data processing

342 Geophones receive signals generated by rivers and record them as corresponding voltage fluctuations.

- 343 These are then converted back into ground velocity based on the characteristics of the microseismic
- 344 instruments, allowing for the creation of the most primitive form of seismic waveforms produced by the
- 345 river signals, that is, the waveform or time series of ground velocity. The seismic amplitude of the time





- 346 series can provide information about the seismic signal, but some important features may be obscured 347 by input unrelated to the monitored event. Filter processing for specific frequencies can help to filter the 348 relevant parts of the signal. Transforming the signal to obtain the spectrum is a powerful tool for 349 quantifying the signal amplitude in the frequency domain. It allows for rapid characterization of the 350 signal and can be used with specific frequency filters to test and filter specific signals. However, in the 351 spectrum, the time information is not decomposed, and the fluctuations of the spectrum in the time series 352 are unknown. A common tool for characterizing seismic signals is time-frequency analysis, which 353 combines both aspects, allowing the amplitude or energy of microseismic signals to be quantified in both 354 the time domain and the frequency domain.
- 355

356 The Fourier transform is a classic method of time-frequency analysis. Using the Fast Fourier Transform 357 (FFT), continuous microseismic signals are divided into short segments, and a taper is applied to the 358 segments to obtain the spectral plot of the microseismic signal, thereby showing the distribution of 359 seismic energy in both time and frequency. To reduce the spectral variance typically caused by the simple 360 use of FFT and to quantify the energy produced by microseismic signals at a given frequency, we 361 calculated the Power Spectral Density (PSD) of the time series using Welch's overlapped segment method 362 (Welch, 1967). The time series is divided into several overlapping segments, and to avoid errors when the 363 signal is truncated, a Hamming window is used to window the segments, with a 1-second (200-sample) 364 window having a 50% overlap, thereby obtaining a discrete 1Hz frequency band.

365

366 4.2 The relationship between river discharge and seismic noise

367 By discussing the source of seismic waves in the fourth section, it can be concluded that the seismic 368 energy of the river in this study is mainly due to turbulence. The low-frequency band of 2~10 Hz in the 369 experimental spectrum is related to the turbulent process of the river, and the changes in seismic energy 370 reflect the changes in river flow. For verification, we selected data from the third experiment. During the 371 third experiment, while monitoring the microseismic activity of the river, we simultaneously conducted 372 continuous measurements of river flow velocity, measuring the average flow velocity at a distance of 373 1.35 m from the riverbank every minute. Based on the flow calculation formula in Section 2.3, we 374 obtained the average flow rate per minute. The microseismic signals were selected from the S4 station,





375 which had the highest signal-to-noise ratio. Using the method of estimating the average power spectral 376 density of the signal, we calculated the average seismic power at each frequency over a 1-minute period, 377 and then calculated the average seismic power of the microseismic signal in the 2~10 Hz band over a 1-378 minute period. This was converted into energy form and plotted on the same time axis as the flow rate 379 changes (Figure 11). It can be clearly seen from the figure that the fluctuations in the average seismic 380 power of the three components in the 2~10 Hz band recorded by the S4 station basically match the 381 fluctuations in the river flow at the same time, and the two have good consistency on the time scale. There are differences in the average seismic power of different components, but there are no obvious 382 383 differences in the response to changes in river flow. Among them, the average seismic power change of channel N is highly consistent with the change in river flow and can well reflect the fluctuations in river 384 385 flow. The above results indicate that there is a strong correlation between the recorded microseismic 386 signals in the 2~10 Hz band and river flow. Real-time monitoring of river processes can be achieved 387 through the analysis of the time-frequency diagram of continuous microseismic signals.





- 392
- 393

394 5 Results and discussion

395 This study employs a linear least squares regression model to quantify the relationship between the

seismic power spectral density (PSD) above the 1 Hz band and the river turbulence, without considering





397	the mechanical effects generated by the river process. The first 10 minutes of microseismic data from
398	each location during the experiment were used for regression; these regressions were then used to
399	calibrate the least squares model for flow prediction. The last 10 minutes of microseismic data from each
400	location during the experiment were then used for testing, ultimately resulting in a linear approximation
401	model for inferring river flow from microseismic data; the flow of the river section in the third experiment
402	was not inverted this time, as the microseismic data for this time window experienced anomalies due to
403	instrument issues, and could not be used for flow inversion. The total energy of the seismic waveforms
404	generated by multiple sources is the sum of the energies in the river processes of each river section.
405	Without considering the seismic energy generated by river sediment transport, the total seismic PSD is
406	the sum of the PSDs produced by water turbulence (P_Q) , passing vehicles (P_V) , and environmental noise
407	(P_N) . When constructing the linear least squares regression model, it is assumed that the PSD generated
408	by the first-order river turbulence process is linearly scaled with the variable representing the magnitude
409	of that process. Therefore, for any given time t, using the seismic PSD at each frequency band (P_f) , the
410	PSD generated by road vehicles (P_{yy}), the average power of station S3 at each frequency during periods
411	without human noise such as vehicles (P_{N}), and the constant linear coefficient af of flow at frequency f_{N}
412	the prediction equation for river flow $Q_{pred}(t)$ at time t is obtained:

413
$$Q_{pred}(t) = [P_f(t) - P_{vf}(t) - N_f]/a_f$$
(8)

414 The above equation provides the flow prediction for each frequency, which is solved using the least 415 squares method to maximize the consistency of predictions across the 1~100 Hz. The flow regression 416 coefficients corresponding to the highest turbulence signal-to-noise ratio geophones for each component (E, N, and Z) and each experiment site (Test 1, 2, and 4), calculated using the first 10 minutes of 417 microseismic data, are shown in Figure 12. The regression coefficient af encompasses both the coupling 418 419 between the flow measurement unit (m³/s) and the ground velocity signal produced by turbulence, as well as the attenuation of each microseismic signal between the source and the geophones (the Green's 420 421 function). This coefficient also represents the spectral contribution of the turbulence process to the 422 geophones signal, or the power per frequency transmitted by unit flow.









Figure 12. The flow regression coefficients and 95% confidence intervals for the river processes. (a), (b), and





425 (c) show the flow regression coefficients and 95% confidence intervals for the river processes on the E, N, and 426 Z components of the ground motion at base stations S4, S2, and S4 at test 1, 2, and 4, respectively. 427 428 429 After regressing the constant linear coefficient af of flow at frequency f using the first 10 minutes of 430 microseismic test data, the microseismic test data from the last 10 minutes is used to calculate the 431 predicted flow values at each experimental site using the aforementioned equation. Since the flow rate 432 calculation in this study is derived from the measured 1 minute average flow velocity, to ensure that the 433 predicted results match the measured data, the peak values of the flow-related turbulence coefficients af 434 (at frequencies of 4 Hz, 5 Hz, and 4 Hz) for the first, second, and fourth tests are substituted into the 435 equation to calculate the river flow predicted values at every 1 minute interval during the last 10 minutes. The predicted results are compared with the flow calculation results from Section 2.3, as shown in Figure 436 437 12. From the comparison chart of the two, it can be seen that the predicted flow values established by the 438 linear approximation model in this paper are close to the actual observed values, with the predicted flow 439 values fluctuating around the corresponding observed values. The average values of the predicted flow 440 values for the first, second, and fourth tests are $0.454 \text{ m}^3/\text{s}$, $0.548 \text{ m}^3/\text{s}$, and $0.537 \text{ m}^3/\text{s}$, respectively. The 441 average values of the predicted flow values indicate that the results predicted by the model in this study 442 are relatively accurate. However, the average absolute errors between the predicted flow values and the 443 measured values for the three tests are 0.030, 0.080, and 0.237, respectively. Moreover, from Figure 13, 444 it can be visually observed that there is a larger fluctuation between the predicted flow values and the 445 measured values for each minute of the fourth test. This may be due to the presence of large boulders in 446 the river section of the fourth test, which create a drop in water flow and impact the riverbed, generating 447 noise caused by sediment transport. Additionally, during the fourth test, there were trucks and excavators 448 operating about 150 meters away from the river section, which may have caused larger fluctuations in 449 the predicted flow values for each minute of the fourth test. During the entire data preprocessing stage, 450 all microseismic data were high-pass filtered to exclude the noise influence below 1 Hz, to reduce as much as possible environmental noise produced by vehicles, construction works, and other human 451 452 activities,. Therefore, in this test, there is still an error between the flow prediction results obtained by 453 inversion and the actual test results also due to the impact of the instruments' installation point, to the 454 river flow calculation method, and the instrumental errors itself. In the future, more accurate experimental 455 results could be obtained by starting from traditional flow refinement calculations and precise filtering





456 of river microseismic signals, increasing the number of microseismic stations, and building on the



457 proposed model to further refine the inversion analysis.





460 Figure 13. The plot of measured flow values against inverted flow predictions, (a). The scatter plot of mean 461 absolute error between flow predictions and measured values, (b). In figure (a), green represents measured 462 values and pink represents predicted values. In figure (b), blue represents Test1, pink represents Test2, green 463 represents Test4, straight line represents measured flow values and scatter represents predicted values. 464 465 The linear approximation model proposed in this study for flow inversion has a relative error within 466 467 10.3%, but it also has some limitations. First, in practical situations, there is a slight nonlinear relationship 468 between flow and seismic power, which the established model does not consider. This omission can affect 469 the accuracy of the model inversion, leading to a reduction in inversion accuracy during practical 470 application. Additionally, the linear approximation model proposed in this paper is built for the specific 471 river environment in question and can be generalized to similar river environments. However, for rivers 472 in different environments, other factors contributing to seismic power need to be considered.

473 6 Conclusion

474 The study analyzes the seismic records from 3 to 4 three-component seismometers deployed across four 475 sections of a low-flow river system in the village and combines measurements of flow velocity and cross-476 sectional area of the river sections to calculate its flow data. We found that the signals generated by the 477 river flow have a very wide frequency range (2~50Hz). Despite the presence of noise fields generated by 478 human activities throughout the research process, which are mainly high-frequency acceleration energy, 479 we cannot establish a correlation between high-frequency seismic power and river flow. In contrast, the 480 recorded microseismic signals in the 2~10 Hz band have a strong connection with river flow, approximately exhibiting a linear relationship. Moreover, the microseismic signals generated by 481 482 turbulence have frequencies lower than those produced by human activity noise and riverbed sediment 483 transport and can be separated using a bandpass filter. Even with low river flow, real-time monitoring of 484 the turbulence process can be achieved through the analysis of continuous microseismic signals time-485 frequency diagrams.

486

487 A linear least squares regression model was used to quantify the relationship between seismic power 488 spectral density (PSD) above the 1 Hz band and the river turbulence process, without considering the 489 mechanical effects generated by the river process. The first 10 minutes of microseismic data from each





490	location during the test were used for regression, and these regressions were then used to calibrate the
491	least squares model for flow prediction. The last 10 minutes of microseismic data from each location
492	during the experiment were then used for testing, ultimately resulting in a linear approximation model
493	for inferring river flow from microseismic data. The predicted average values obtained from the inversion
494	experiments for Tests 1, 2, and 4 are 0.454 $m^3/s,0.548\ m^3/s,$ and 0.537 $m^3/s,$ respectively, with the
495	maximum relative error between the predicted and measured values being 10.3%. By analyzing the
496	microseismic signals generated by vehicles and recorded at S3 in the third test and their spectral
497	characterization, the microseismic signals in the $2\sim7$ Hz band were retained by using a band-pass filter
498	to minimize the impact of vehicle-related signals. The 1 minute average seismic power in the $2{\sim}7~{\rm Hz}$
499	band on the time-frequency analysis map of the recorded microseismic signals was calculated by
500	estimating the average power spectral density (Welch) of the signals and converting it into energy form;
501	the calculated results were in good agreement with the 1 minute average flow rate measured in the field
502	in the time scale, and showed that the time-frequency analysis based on continuous microseismic
503	monitoring of the river can enable the monitoring of the river processes.
504	Author contributions. ZXY conducted the experiment, analyzed the experimental data and wrote the
505	manuscript. ZSZ and XW participated in the experiment. WYM, XB and Emanuele Intrieri provided
506	revision suggestions for the manuscript. FL guided the implementation of the experiment and revised the
507	content of the manuscript.

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