



Brief communication: Stalagmite damage by cave-ice flow quantitatively assessed by fluid-structure-interaction simulations

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Abstract. Mechanical damage to stalagmites is commonly observed in mid-latitude caves. Former studies identified thermoelastic ice expansion as a plausible mechanism for such damage. This study builds on these findings and investigates the role of ice flow along the cave bed as a possible second mechanism for stalagmite damage. Utilizing fluid-structure interaction models based on the finite element method, forces created by ice flow are simulated for different stalagmite geometries. The resulting effects of such forces on the structural integrity of stalagmites are analyzed and presented. Our results suggest that structural failure of stalagmites caused by ice flow is possible, albeit unlikely.

1 Introduction

Naturally occurring, mechanical damage to speleothems such as stalactites and stalagmites is common in mid-latitude caves (s. Fig. 1). Deformation by ice present in such caves during cold periods of the Pleistocene has been identified as a main cause for the observed damage on speleothems, especially stalagmites, which grow upward from the cave floor (e.g. Gilli, 2004; Orvošová et al., 2012). In a recent study, Spötl et al. (2023) used numerical modelling combined with laboratory measurements to quantitatively assess which processes in former ice-filled caves led to speleothem damage. The results show that internal deformation within a cave ice body due to ice flow under gravity cannot fracture stalagmites, even on steep slopes. In contrast, thermoelastic stresses within an ice body due to temperature changes reach values partly exceeding the tensile strength of stalagmites. In this contribution we expand on the analysis of Spötl et al. (2023) by (a) examining not only the external forces exerted by ice flow but also their internal effect within stalagmites, and (b) including also smaller stalagmite dimensions. Structural failure of stalagmites caused by ice flow was investigated using a fluid structure interaction (FSI) model (e.g. Sigrist, 2015).

2 Methods

In order to be consistent with the study of Spötl et al. (2023), we chose to model the same ice domain with $-7 \leq x \leq 14$ m, $-3.5 \leq y \leq 3.5$ m and the stalagmite location at $x = y = 0.0$ m (cf. Fig. 3 in Spötl et al., 2023). However, we examined two ice thicknesses ($h_{\text{ice}} = 1.0$ and 2.0 m), two slope angle values ($\beta_{\text{ice}} = 10$ and 40°), three stalagmite diameters ($d_s = 0.15, 0.25$



and 0.4 m), two stalagmite heights ($h_s = 0.5$ and 1.0 m) as well as full-slip and no-slip conditions at the cave base. In total, 14 different configurations which are summarized in Tab. 2 were examined. The cave walls (sidewalls of the ice domain) were assumed to be no-slip boundary conditions and the ice surface is a stress-free boundary, allowing for free movement of ice. Stalagmites were modelled as cylinders with a fixed diameter d_s , except for configurations 13 and 14, which exhibit a conical shape ($d_s^{\text{base}} = 0.25$ m and $d_s^{\text{top}} = 0.1$ m). Our numerical mesh contains typically 100.000 tetrahedral elements with mesh element sizes varying between 0.3 m far away from the stalagmite to 0.02 m within the stalagmite.

2.1 FSI Model

We assumed the deformation of ice to be fluid like, with a non-Newtonian rheology following Glen's flow law (e.g. Glen, 1955). Driven by gravity, the cave ice flows downslope and exerts forces on the stalagmite's outer surface. The structural response of the stalagmite to these external forces was modelled as linearly elastic. Using the chosen FSI model approach we simulated both, the forces exerted by ice deformation (fluid) and the response of the stalagmite (solid structure) to these forces with a finite-element model. A summary of the relevant model parameters is given in Tab. 1.

We developed this simulation strategy using the open-source software *Elmer FEM* (e.g. Malinen and Råback, 2013), which includes well established FSI routines (e.g. Järvinen et al., 2008). To include the non-linear flow behaviour of ice in our model, we used *Elmer/Ice* (e.g. Gagliardini et al., 2013), which builds upon *Elmer FEM*.

Elmer FEM applies a partitioned approach to solving FSI problems, thus solving the equations governing non-linear fluid flow and elastic structural response with two different numerical solvers. Forces are coupled at the fluid-structure boundary (stalagmite outer surface) and the model iterates until a balance between fluid stress and elastic response of the solid is found.

3 Results

Solutions from the FSI simulations were analyzed for maximum (principal) tensile stresses σ_{max} in the stalagmite to identify cases where its tensile strength ($4.3 \pm 1.5 \times 10^6$ Pa; Spötl et al., 2023) is exceeded. According to Rankine's theory (Rankine, 1857) this would result in structural failure of the stalagmite. Typically, the maximum tensile stresses were found to be caused by bending of the stalagmite and occurred at the upstream side of its base in vertical direction (s. Fig. 2). The results of the simulations are summarized in Tab. 2.

Using the mean value of the reported tensile strength for stalagmites, we found that configurations 04, 06, 08, configurations 09 (s. Fig. 3) to 12, as well as configuration 14 would likely fail (indicated by bold face simulation numbers in Tab. 2). For moderately sloping caves ($\beta_{\text{ice}} = 10^\circ$), only configurations exhibiting full-slip conditions at the ice-cave base interface (no bed friction) indicate failure (simulations 04, 06, 08, and 14). In case of steep sloping caves ($\beta_{\text{ice}} = 40^\circ$), all investigated configurations (simulations 09 to 12) exhibit maximum tensile stresses significantly exceeding the stalagmite's tensile strength.

We also investigated the effect of ice temperature, as all our simulations assume temperate ice (cf. *A* in Tab. 1). However, reducing the ice temperature to -5.0° C only results in a reduction of the maximum tensile stress of less than 0.5 % relative to the temperate case.



55 Ice thickness h_{ice} , and thereby how much ice overflows the stalagmite, significantly affects σ_{max} . Comparing simulations 05 ($h_{ice} = 2\text{m}$) and 07 ($h_{ice} = 1\text{m}$) reveals a reduction of σ_{max} by about 45 % in case of no-slip conditions. In case of full-slip conditions (simulations 06 and 08), however, only a small reduction of σ_{max} by about 8 % for the same 50% reduction in h_{ice} is observed.

The stalagmite geometry is found to significantly influence the observed maximum tensile stresses. This is especially true for the stalagmite base diameter d_s , and by extension its section modulus $S = \frac{\pi d_s^3}{32}$. Even though a reduction of d_s reduces the surface area exposed to ice flow, σ_{max} for simulations 03 and 04 ($d_s = 0.25\text{m}$) is nearly three times higher than for simulations 01 and 02 ($d_s = 0.4\text{m}$) due to a disproportionate reduction of S . Given the same ice thickness of $h_{ice} = 2\text{m}$, small stalagmites ($d_s = 0.15\text{m}$ and $h_s = 0.5\text{m}$; simulations 05 and 06) are more prone to failure than larger stalagmites ($d_s = 0.4\text{m}$ and $h_s = 1\text{m}$; simulations 01 and 02). Conically shaped stalagmites (configurations 13 and 14) exhibit comparable, albeit slightly lower, maximum tensile stresses than cylindrical stalagmites (configurations 03 and 04).

For our simulations we assumed ice frozen to the stalagmite and thus a direct force coupling on the ice-stalagmite interface. Therefore, the modelled ice flow can potentially exert tensile forces on the downslope side of the stalagmite. By comparing the maximum principle tensile stress σ_{max} on the downslope ice-stalagmite interface with reported values for ice tensile strength ($0.7 - 3.1 \times 10^6\text{Pa}$ (Petrovic, 2003)), we identified two configurations (configurations 10 and 12) for which failure of the ice itself would likely occur. For these configurations the reported maximum σ_{max} values are definitely an overestimation and thus have to be considered with caution.

High shear stresses within the stalagmite could also lead to structural failure, hence we report maximum absolute values of the base shear stress $|\tau_{zx}|$ in Tab. 2. However, maximum $|\tau_{zx}|$ amounts to less than 30 % of maximum σ_{max} for all investigated configurations. We therefore consider it unlikely that the stalagmite will fail due to the presence of shear stresses.

75 4 Discussion and conclusion

Ice caves exhibit complex geometries which comprise galleries, chambers and shafts. In addition, the floor of chambers and galleries is typically covered by coarse debris including variably large and angular blocks. These topographic intricate features render free sliding (i.e. full-slip) interface conditions between the ice and the cave bed highly unlikely in reality. Most importantly, cave ice bodies are typically frozen to their substrate. They owe their existence to the strong cooling of the rock mass surrounding the cave as a consequence of strong (winter) cooling by air flow or the presence of permafrost (e.g. Luetscher, 2022).

Any zones of full-slip would get compensated by ice being required to flow around and/or over complex bed topographies. Hence we consider our results with basal full-slip conditions (simulation numbers 02, 04, 06, 08, 10, 12, and 14) as highly unlikely upper end member cases for ice cave conditions. Conditions close to the no-slip simulations are regarded as most likely.



We found large tensile stresses on the upslope (i.e. upstream) side of stalagmites to be the main cause for structural failure. In contrast, a large influence of shear stresses near the stalagmite base is ruled out due to their comparatively small magnitude of less than 30 % of the observed tensile stresses.

Our results suggest that only in steep sloping caves with large ice bodies (e.g. 14 m of cave ice, 2 m thick, upslope of a stalagmite), forces exerted by ice flow can become large enough to damage moderately large stalagmites. Only in one case with
90 no-slip conditions (simulation number 09) we find a configuration in which a moderately large stalagmite would be damaged.

This study confirms that vertical uplift of stalagmites due to thermoelastic stresses induced by expanding ice, as previously reported (Spötl et al., 2023), is still the most likely physical explanation for wide-spread damage to speleothems in mid-latitude caves during the cold periods of the Pleistocene. Even though our results rule out lateral ice flow as a main damage mechanism,
95 which was previously often assumed, in extreme conditions (i.e. steep sloping, large, ice filled caves) however, large tensile stresses caused by ice flow can occur in stalagmites, which ultimately can also cause structural damage.

Code availability. All fluid structure interaction simulations in this contribution were carried out with the *Elmer FEM* and *Elmer/Ice* software packages, which can be accessed online under <http://elmerfem.org> and <http://elmerice.elmerfem.org/>

Author contributions. CS and AHJ conceived the study. AHJ performed the numerical simulations and together with PH analyzed the results.
100 All authors contributed to writing the paper.

Competing interests. The contact author has declared that none of the authors has any competing interests.

Acknowledgements. This research was funded in part by the Austrian Science Fund (FWF), grants P318740 and P358770.



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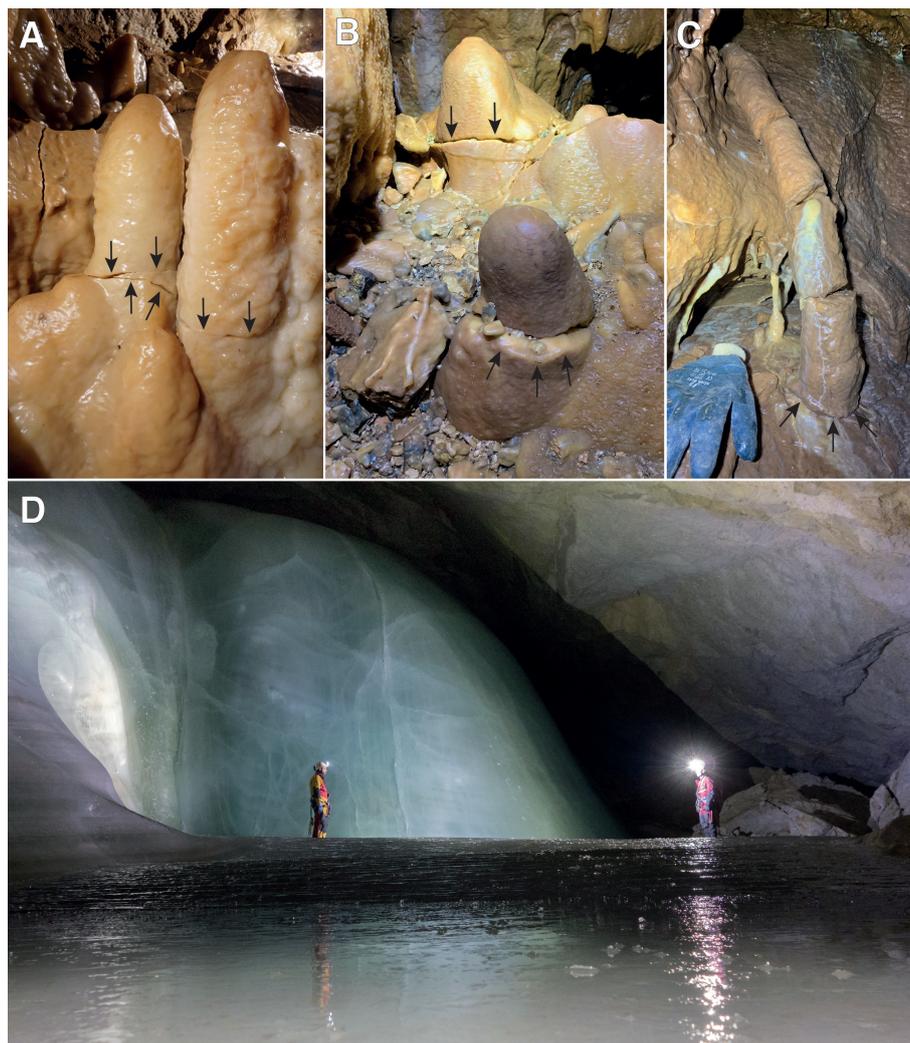


Figure 1. A-C: Examples of stalagmites damaged by ice during the last glacial period. A: Two parallel stalagmites detached from their base along subhorizontal cracks (arrows), Obir Caves, Austria. Width of image 0.4 m. B: Two conical stalagmites sheared off their base (arrows). While the specimen in the back was only detached from its base, the top part of the stalagmite in the front was also displaced a few centimeters laterally and slightly rotated. Shatter Cave, Mendip Hills, UK. Width of image 0.5 m. C: Cylindrical stalagmite detached from its substrate (arrows), broken into four pieces and leaning towards the cave wall. Shatter Cave, Mendip Hills, UK. Blue glove for scale. D: Example of a modern ice cave with floor ice and thick ice deposits on the slope in the background. Feuertal Eishöhle, Austria. Images: C. Spötl (A-C), H. Zeitlhofer (D).

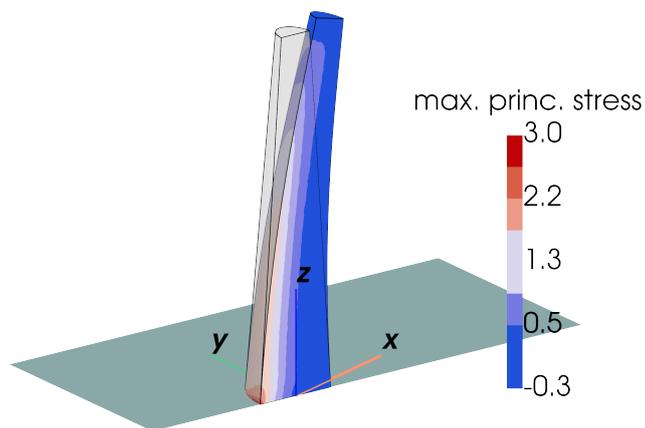


Figure 2. Maximum principal stress σ_{\max} for the conical stalagmite of simulation 13 in 10^6Pa (displacements are scaled by a factor of 1000). Red colours on the upstream face indicate tensile stresses ($\sigma_{\max} > 0$). The z -axis of the coordinate system is aligned vertically upward against gravity, while the x -axis aligns with the downstream direction of the ice flow.

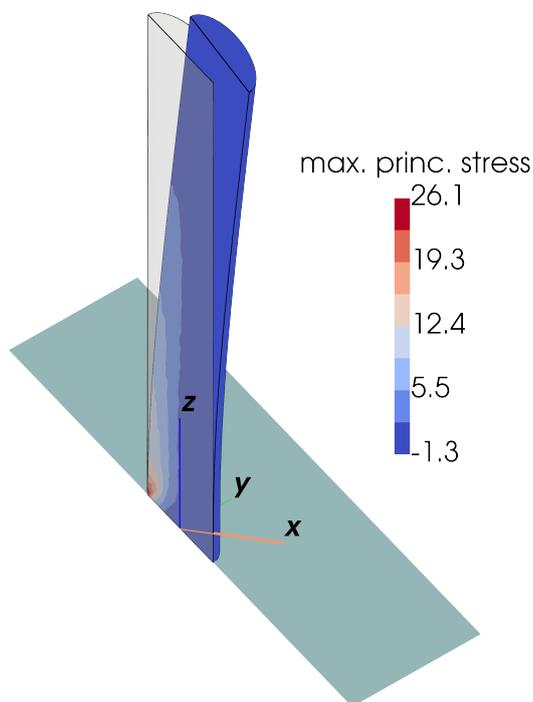


Figure 3. Maximum principal stress σ_{\max} in the stalagmite pertaining to simulation 09 in 10^6Pa (displacements are scaled by a factor of 100). This simulation indicates stresses significantly exceeding the tensile strength of the stalagmite on its upstream side. The x -axis points in the downstream direction of the ice flow.



Table 1. Model parameters

Symbol	Value	Units	Description
A	2.4×10^{-24}	$\text{Pa}^{-3} \text{s}^{-1}$	Glen's flow law parameter for temperate ice
n	3	-	Glen's flow law non-linearity number
E_i	9.5×10^9	Pa	Young's modulus for ice
E_s	6.41×10^{10}	Pa	Young's modulus for stalagmite
g	9.81	m s^{-2}	gravitational acceleration
ν_i	0.33	-	Poisson ratio for ice
ν_s	0.27	-	Poisson ratio for stalagmite
ρ_i	910	kg m^{-3}	Density of ice
ρ_s	2670	kg m^{-3}	Density of stalagmite material

Table 2. Maximum principal stress max. σ_{\max} and maximum shear stress max. $|\tau_{zx}|$ for all simulations. β_{ice} is the cave slope angle, h_{ice} the ice thickness, h_s the stalagmite height, d_s the stalagmite diameter. Boundary conditions at the ice bed are listed as well. Bold simulation numbers indicate configurations for which the stalagmite would likely break due to the arising tensile stresses. The configurations exhibiting a conical stalagmite shape are marked with an asterisk (*). For the simulations marked with a plus sign (+), maximum σ_{\max} on the downslope side of the stalagmite exceeds the tensile strength of ice (cf. Sect. 3).

Sim. №	β_{ice} °	h_{ice} m	h_s m	d_s m	base BC	max. σ_{\max} 10^6Pa	max. $ \tau_{zx} $ 10^6Pa
01	10	2	1	0.4	no-slip	1.22	0.273
02	10	2	1	0.4	slip	3.53	0.789
03	10	2	1	0.25	no-slip	3.55	0.745
04	10	2	1	0.25	slip	11.1	2.36
05	10	2	0.5	0.15	no-slip	2.73	0.588
06	10	2	0.5	0.15	slip	15.1	3.27
07	10	1	0.5	0.15	no-slip	1.51	0.325
08	10	1	0.5	0.15	slip	13.9	3.01
09	40	2	1	0.25	no-slip	26.1	6.58
10+	40	2	1	0.25	slip	86.9	22.2
11	40	2	0.5	0.15	no-slip	22.4	5.75
12+	40	2	0.5	0.15	slip	105	27.6
13*	10	2	1	0.25	no-slip	3.09	0.712
14*	10	2	1	0.25	slip	10.3	2.4