



The comparative role of physical system processes in Hudson Strait ice stream cycling: a comprehensive model-based test of Heinrich event hypotheses

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Abstract. Despite their recognized significance on global climate and extensive research efforts, the mechanism(s) driving Heinrich Events remain(s) a subject of debate. Here, we use the 3D thermo-mechanically coupled Glacial Systems Model (GSM) to examine Hudson Strait ice stream surge cycling as well as the role of 3 factors previously hypothesized to play a critical role in Heinrich events: ice shelves, glacial isostatic adjustment, and sub-surface ocean temperature forcings. In contrast to all previous modeling studies examining HEs, the GSM uses a transient last glacial cycle climate forcing, global visco-elastic glacial isostatic adjustment model, and sub-glacial hydrology model. The results presented here are based on a high-variance sub-ensemble retrieved from North American history matching for the last glacial cycle.

Over our comparatively wide sampling of the potential parameter space (52 ensemble parameters for climate forcing and process uncertainties), we find two modes of Hudson Strait ice streaming: classic binge-purge versus near continuous ice streaming with occasional shutdowns and subsequent surge onset overshoot. Our model results indicate that large ice shelves covering the Labrador Sea during the last glacial cycle only occur when extreme calving restrictions are applied. The otherwise minor ice shelves provide insignificant buttressing for the Hudson Strait ice stream. While sub-surface ocean temperature forcing leads to minor differences regarding surge characteristics, glacial isostatic adjustment does have a significant impact. Given input uncertainties, the strongest controls on ice stream surge cycling are the poorly constrained deep geothermal heat flux under Hudson Bay and Hudson Strait and the basal drag law. Decreasing the geothermal heat flux within available constraints and/or using a Coulomb sliding law instead of a Weertman-type power law leads to a shift from the near-continuous streaming mode to the binge-purge mode.



1 Introduction

20 Heinrich Events (HEs) offer a near unique opportunity to explore a coupled ice-climate-ocean instability that operates on the order of centuries to millennia. HEs are generally attributed to large armadas of icebergs drifting from Hudson Strait across the North Atlantic (40° - 55° N) while depositing sediment layers of Ice-Rafted Debris (IRD). At least six of these Heinrich Layers have been identified between 60 kyr BP (before present) and 15 kyr BP, but there is evidence for earlier events (Table 6.3 in Bradley, 2014, and references therein). Heinrich Layers are usually characterized by high detrital carbonate concentration, 25 low abundance of organic carbon and terrigenous lipids, and high magnetic susceptibility (Hemming, 2004). Mineralogical inferences from IRD records indicate a Hudson Strait/Hudson Bay provenance, but there is also evidence for Icelandic and European source regions for at least 2 HEs (Grousset et al., 1993; Gwiazda et al., 1996; Hemming, 2004). HEs generally coincide with the coldest phases of the Dansgaard-Oeschger (DO) cycles, followed by a sharp temperature increase (e.g., Hemming, 2004; Clement and Peterson, 2008; Hodell et al., 2010). Marine records indicate a weakening of the Atlantic 30 Meridional Overturning Circulation (AMOC) and an increase in sub-surface ocean temperatures leading up to HEs (Marcott et al., 2011, and references therein).

Despite over 50 years of research, the exact mechanism behind HEs remains unclear. The proposed hypotheses include an internally driven binge-purge model (MacAyeal, 1993; Payne, 1995; Calov et al., 2002), an ice shelf buildup-collapse mechanism (Hulbe, 1997; Hulbe et al., 2004), and an underwater melt-driven grounding line retreat modulated by glacial 35 isostatic adjustment (GIA, Bassis et al., 2017). However, an extensive study simultaneously investigating the relative role of each proposed HE hypothesis is still missing. Furthermore, previous model-based tests of HE-related Hudson Strait surge cycling have not addressed uncertainties in key potentially relevant processes and inputs. These include the deep geothermal heat flux under Hudson Strait, glacio-isostatic adjustment, and the form of the basal drag law employed.

Here we run sensitivity experiments with the 3D thermo-mechanically coupled glacial systems model (GSM, Tarasov et al., 40 2024, in preparation) and a high-variance (with respect to ensemble parameters and ice sheet configuration) ensemble-based approach to determine the role that relevant physical system processes play in HEs. A challenge in this context is the robust modeling of ice stream cycling associated with 2 of the 3 hypotheses discussed herein. This challenge is largely due to the abrupt changes with ice stream activation/de-activation, resulting in potentially high sensitivity to the implementation and discretization of the relevant dynamical equations (Hank et al., 2023). As a step towards addressing this, we use Minimum 45 Numerical Error Estimates (MNEEs) as a threshold for the numerical significance of model results.

In particular, we address the following research questions.

Q_1 *What are the characteristics of Hudson Strait ice stream surges and how do they depend on the geothermal heat flux and basal drag law?*

Given the critical role of basal temperature and basal drag on ice stream cycling, we examine the to-date unassessed 50 effect of various GHF input fields and different basal sliding laws on Hudson Strait ice stream surge characteristics.

Q_2 *Can the sudden reduction of the buttressing effect of ice shelves trigger Hudson Strait ice stream surging?*



A 2°C increase in the sub-surface ocean temperature has been shown to cause a 6 fold increase in the ice shelf basal melt rates in front of Hudson Strait ($\sim 6 \text{ m yr}^{-1}$ to $35\text{-}40 \text{ m yr}^{-1}$) in simulations with an ocean/ice-shelf model (Marcott et al., 2011). Such an increase can significantly degrade the buttressing effect of a confined ice shelf and, thereby, potentially trigger ice stream activation or surging. To test this scenario, forced ocean warming experiments are carried out with forcing timing set to that of the HE record (timing based on average of Table 6.3 in Bradley (2014), “HE shelf forcing”).

Q₃ Can a sudden breakup of fringing ice shelves along the Canadian coast explain the IRD records (without the need for surges)?

HEs occurred during extremely cold climates. Hulbe et al. (2004) propose that these cold conditions led to the formation of fringing ice shelves along the Canadian coast. A sudden disintegration of the ice shelves would provide a source for Canadian-source icebergs (Hulbe, 1997) and could potentially explain the IRD records found in ocean sediment cores from the North Atlantic.

Q₄ How does sub-surface ocean warming affect HEs?

In the HE mechanism proposed by Bassis et al. (2017), a glacial isostatic uplifted bed topography at the Hudson Strait mouth protects the retreated ice sheet front from sub-surface ocean warmings (SSOWs) attributed to Dansgaard–Oeschger events (DO events). The ice sheet grows, eventually depressing the bed topography. Once the bed topography is depressed below the upper limit of the SSOW, the ice sheet front is vulnerable to ocean forcing. Due to a retrograde sloping bed, the ice sheet rapidly retreats during the next SSOW, allowing the bed topography to rise and isolate the ice sheet front from ocean forcing.

Due to the numerous differences in the model setup (e.g., model domain considered, grid discretization near the grounding line, GIA model, calving and sub-shelf melt implementations, and the lack of ice thermodynamics in Bassis et al. (2017)), we do not aim to directly replicate the experiments in Bassis et al. (2017). Instead, we examine the role of SSOW in a HE context by applying a sub-surface ocean temperature increase for every DO event.

Q₅ What is the role of GIA in a HE context?

Due to its effect on, e.g., relative sea level changes and ice sheet mass balance, GIA has long been known to have a significant impact on ice sheet evolution (e.g., Tarasov and Peltier, 1997). It also plays a central role in the HE hypothesis of Bassis et al. (2017). We assess the impact of GIA representation, associated earth model uncertainties, and GIA absence on Hudson Strait ice stream surge cycling.

2 Methods

2.1 Modeling approach

All experiments within this study are conducted with the glacial systems model (GSM Tarasov and Peltier, 1999, 2007; Pollard and DeConto, 2012; Tarasov et al., 2024, in preparation). The GSM is initialized from ice-free conditions at 122 kyr BP and



is run to present day with a maximum ice dynamics time step size of 1 yr (automatically decreased to meet CFL constraint or when the matrix solver fails to converge). The reference setup has a horizontal grid resolution of $\Delta_{lon} = 0.5^\circ$, $\Delta_{lat} = 0.25^\circ$
85 (finer horizontal grid resolutions are currently computationally unfeasible in the context of this study as the GSM is not parallelizable). The topography and sediment cover of the entire model domain are shown in Fig. S1.

Modeling sensitivities and numerical requirements for a model configuration that had reduced grid resolution dependence in an ice stream surge cycling context were determined based on an slightly earlier version of the GSM (Hank et al., 2023). The inclusion of basal sliding at sub-freezing temperatures, a basal hydrology representation, and the dampening effect of a
90 bed thermal model on basal-temperature changes significantly affect the surge characteristics. To account for these modeling aspects, the GSM version used within this study is run with a resolution-dependent basal temperature ramp, a local basal hydrology model (Drew and Tarasov, 2023), and a 4 km deep bed thermal model.

Additionally, the GSM incorporates, among other components, an asynchronously coupled global visco-elastic GIA solver (Tarasov and Peltier, 1997) and an asynchronously coupled geographically-resolved energy balance climate model (Deblonde et al., 1992). Instead of a constant climate forcing (e.g., Roberts et al., 2016) or only varying the ocean forcing (e.g., Alvarez-Solas et al., 2013; Bassis et al., 2017), we apply a transient last glacial cycle climate forcing. Furthermore, we use a 20 member
95 high-variance ensemble (with respect to ensemble parameters and ice sheet configuration) instead of just a single parameter vector to partly address potential non-linear dependencies of model results on ensemble parameters.

2.2 Ensemble parameter vectors

100 The source ensemble is from a North American history-matching for 52 GSM parameters (Tarasov et al., in preparation, Tarasov and Goldstein, 2021). For the experiments herein, ~ 15000 coarse resolution ($\Delta_{lon} = 1^\circ$, $\Delta_{lat} = 0.5^\circ$) GSM runs from the history matching are initially sieved for total North American ice volume (V_{tot}) and area (A_{tot}) at specific time steps, the last time the center of Hudson Bay (lat = $61.25^\circ N$, lon = $84.5^\circ W$) became free of grounded ice ($t_{ice,HB}$), the southernmost ice extent between $94.7^\circ W$ and $80.3^\circ W$ (lat_{ice}), and the southernmost ice extent at $69.7^\circ W$ (lat_{ice,Q}). The exact
105 sieves are $V_{tot,110} > 0.29 \cdot 10^7 \text{ km}^3$, $V_{tot,100} < (V_{tot,110} - 0.15 \cdot 10^7 \text{ km}^3)$, $V_{tot,60} > 0.6 \cdot 10^7 \text{ km}^3$, $V_{tot,30} < (V_{tot,20} - 0.1 \cdot 10^7 \text{ km}^3)$, $A_{tot,20} > 12 \cdot 10^3 \text{ km}^2$, $9.0 \text{ kyr BP} > t_{ice,HB} > 7.8 \text{ kyr BP}$, lat_{ice} < $39^\circ N$, and lat_{ice,Q} < $45.6^\circ N$ (Tarasov, 2024, in preparation). The numbers in the sub-scripts indicate the time step in kyr BP.

For the remaining ~ 10000 runs, we use a peak prominence algorithm to determine surges (*SciPy* version 1.6.3, Virtanen et al., 2020). This is similar to the approach used in (Hank et al., 2023). However, due to the more realistic model domain
110 used herein, not every increase in mid-Hudson Strait ice flux corresponds to a decrease in Hudson Strait ice thickness and vice versa. Since we are most interested in ice flux changes, the algorithm is applied directly to mid-Hudson Strait ice flux (minimum threshold of 0.0035 Sv) instead of the mean Hudson Strait ice thickness time series (as in Hank et al., 2023). We use mid-Hudson Strait ice flux instead of, e.g., the ice flux across the Hudson Strait grounding line, as it is less noisy and a more reliable indicator of large-scale surges. 2 different sieves are then applied to the surge characteristics. The runs pass if at
115 least one of the following conditions is met:



1. $3 \leq \#surges \leq 10$, $0.2 \text{ kyr} \leq \text{mean surge duration}$, $5.0 \text{ kyr} \leq \text{mean periodicity} \leq 11.0 \text{ kyr}$ (for surges between 100 kyr BP and 15 kyr BP), and/or
2. $3 \leq \#surges \leq 10$ (for surges between 65 kyr BP and 10 kyr BP).

The second sieve is added to increase the number of runs that show surges within the period set by HE proxy records (e.g., Hemming, 2004). The bounds for the mean duration and period are based on the literature HE estimates in Table 1.

The remaining ~ 200 runs are re-submitted at a finer horizontal grid resolution ($\Delta_{\text{lon}} = 0.5^\circ$, $\Delta_{\text{lat}} = 0.25^\circ$). As for the coarse resolution runs, we apply the peak prominence algorithm to mid-Hudson Strait ice flux to determine surges. Since we are now most interested in surges that could explain the IRD layers observed in the North Atlantic (rather than simply sieving for runs that show surges), we reject surges for which any of the following conditions is fulfilled:

1. change in mid-Hudson Strait ice flux $< 0.0025 \text{ Sv}$ (previously 0.0035 Sv , across black vertical line (*HS*) in Fig. 2)
2. surge duration $> 3 \text{ kyr}$ (maximum estimated duration of 2.3 kyr in Hemming, 2004)
3. change in Hudson Strait ice volume $> -5 \cdot 10^3 \text{ km}^3$ (only within area outlined by the *Hudson Strait mask* in Fig. 2)

As there is no proxy record for directly inferring the change in mid-Hudson Strait ice flux or Hudson Strait ice volume during HEs, the above thresholds were chosen after testing various values. They led to the most consistent (with respect to the surge mode across all runs) detection of surges while ensuring that mid-Hudson Strait ice flux increases and Hudson Strait ice volume decreases.

Based on the remaining surges in the fine resolution runs, we hand-pick a high variance (with respect to the surge characteristics) sub-ensemble of 10 runs with less than 3 surges and 10 runs with with more than 2 surges (between 100 kyr BP and 10 kyr BP). The ensemble members that show ≤ 2 surges at the fine resolution (but > 2 surges at the coarse resolution) are considered as *likely to surge* and are included to test if, e.g., the repetitive removal of the buttressing effect of an ice shelf can cause ice stream surge cycling in Hudson Strait.

2.3 Model description

The GSM uses hybrid shallow shelf/ice physics based on the ice dynamical core originally developed by Pollard and DeConto (2012). The hybrid ice dynamics are activated once the shallow-ice approximation basal velocity within a grid cell exceeds 30 m yr^{-1} over soft sediments and 200 m yr^{-1} over hard bedrock. The default basal drag law for our experiments is a Weertman-type power law,

$$\mathbf{u}_b = C_b |\boldsymbol{\tau}_{b,W}|^{n_b-1} \boldsymbol{\tau}_{b,W}, \quad (1)$$

where \mathbf{u}_b is the basal sliding velocity, $\boldsymbol{\tau}_{b,W}$ the basal stress, and n_b the bed power strength. In contrast to the version used in Hank et al. (2023), n_b has separate hard and soft bed values (see $n_{b,\text{soft}}$ in Table S1). To indirectly account for sub-temperate sliding, the basal sliding coefficient C_b is calculated according to

$$C'_b = (1 - F_{\text{warm}}) C_{\text{froz}} + F_{\text{warm}} C_{\text{warm}}, \quad (2)$$



where C'_b is the basal sliding coefficient in an intermediate calculation step and F_{warm} the estimated warm-based fraction of a grid cell (Hank et al., 2023). C_{froz} is the fully cold-based (needed for numerical regularization) and C_{warm} the fully warm-based sliding coefficient (depending on the bed properties; C_{rmu} and C_{fslid} in Table S1). C_b is further affected by the effective pressure N_{eff}

$$C_b = C'_b \cdot \min \left[10; \max \left[0.5; \frac{N_{\text{eff,Fact}}}{N_{\text{eff}} + N_{\text{eff,min}}} \right] \right], \quad (3)$$

where $N_{\text{eff,Fact}}$ is the effective-pressure factor (ensemble parameter, Table S1). $N_{\text{eff,min}} = 10$ kPa enforces that N_{eff} never falls below the set threshold. The effective pressure itself is calculated according to

$$N_{\text{eff}} = g\rho_{\text{ice}}H \cdot \left(1 - \min \left[\frac{h_{\text{wb}}}{h_{\text{wb,Crit}}}; 1.0 \right] \right)^{3.5}, \quad (4)$$

where $g = 9.81 \text{ m s}^{-2}$ is the acceleration due to gravity, $\rho_{\text{ice}} = 910 \text{ kg m}^{-3}$ the ice density, H the ice thickness, h_{wb} the basal water thickness, and $h_{\text{wb,Crit}}$ an estimated effective bed roughness scale (ensemble parameter in Table S1, see also Drew and Tarasov, 2023).

To determine the effects of the choice of basal drag law on surge characteristics, we also run experiments with a Coulomb sliding law

$$\tau_{b,C} = \max[1 \text{ kPa}; N_{\text{eff}}C_c \tan(\Theta_t)], \quad (5a)$$

or in a much more numerically stable regularized form:

$$\tau_{b,C} = \max \left[1 \text{ kPa}; N_{\text{eff}}C_c \tan(\Theta_t) \left(\frac{u_b^2}{u_b^2 + UV_{C,\text{reg}}} \right)^{1/6} \right], \quad (5b)$$

where C_c is a variable drag coefficient (ensemble parameter, Table S1), Θ_t the elevation-dependent till friction angle, and $UV_{C,\text{reg}}$ a regularization parameter (Tarasov et al., 2024, in preparation). To account for possible Weertman-type sliding when Coulomb drag is high, the basal shear stress used in the GSM when the Coulomb drag option is activated is set to

$$\tau_b = \min[\tau_{b,W}; \tau_{b,C}]. \quad (6)$$

The calculation of the ice flux across the grounding line in the GSM is independent of the choice of sliding law for the rest of the ice sheet. In the reference setup (Weertman-type power law only, Eq. 1), the basal shear stress at the grounding line $\tau_{b,GL}$ follows Eq. 6. To determine the implications of this grounding line ice flux implementation on surge characteristics, we also run experiments with $\tau_{b,GL} = \tau_{b,W}$.

2.4 Geothermal heat flux

The deep geothermal heat flux (GHF) input used in the GSM is constant in time but varies spatially (left panel in Fig. 1). It provides the lower boundary flux condition for a 4 km deep bed thermodynamic model fully embedded in the ice thermodynamic



175 solver. The default GHF input field is from Davies (2013) and represents an upper bound of the literature estimates. However, GHF data in Hudson Bay and Hudson Strait are sparse, and the estimated values differ significantly (Fig. S2 and, e.g., Pollack et al., 1993; Shapiro and Ritzwoller, 2004; Goutorbe et al., 2011; Lucazeau, 2019; Cuesta-Valero et al., 2021). To determine the sensitivity of model results to the GHF, we weigh the default GHF field GHF_{def} against a modified input GHF_{mod} (right panel in Fig. 1 given the lower regional values in Blackwell and Richards, 2004))

$$\text{GHF} = w_{\text{GHF}} \cdot \text{GHF}_{\text{def}} + (1 - w_{\text{GHF}}) \cdot \text{GHF}_{\text{mod}}, \quad (7)$$

180 where w_{GHF} is the weight ranging from 0 to 1. The reference GSM setup uses $w_{\text{GHF}} = 1$. We run sensitivity experiments for $w_{\text{GHF}} = [0, 0.2, 0.4, 0.6, 0.8]$ applied to both Hudson Bay and Hudson Strait as well as $w_{\text{GHF}} = 0$ applied separately to Hudson Strait (Fig. S3) and Hudson Bay (Fig. S4). When only considering grid cells affected by the GHF modifications (Fig. 1), the w_{GHF} values for the combined Hudson Bay and Hudson Strait experiments correspond to a mean GHF of $\text{GHF}_{\text{ave}} \approx [15, 26, 37, 48, 59] \text{ mW m}^{-2}$ ($\text{GHF}_{\text{ave}} \approx 70 \text{ mW m}^{-2}$ for reference setup). Additionally, we determine the effects of a smaller
 185 GHF when applied to a larger area (Fig. S5).

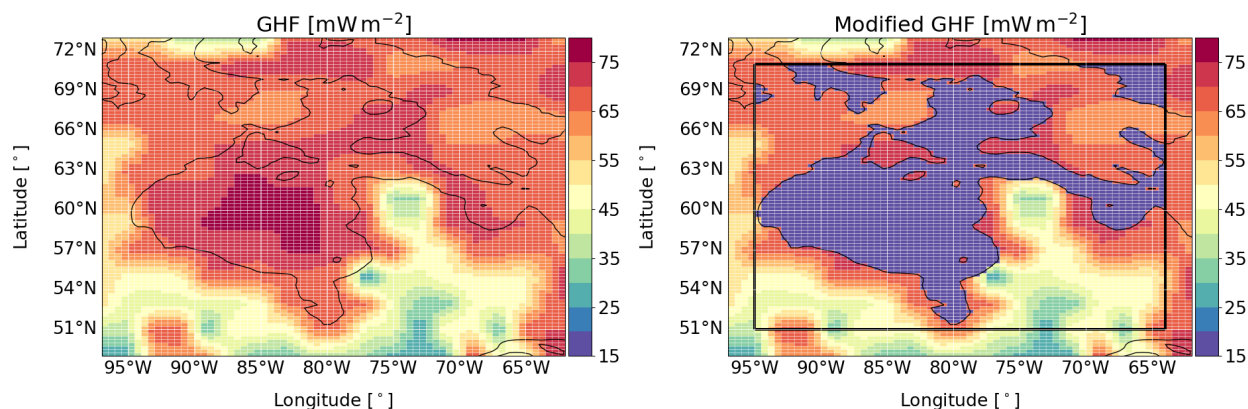


Figure 1. GSM input geothermal heat flux (GHF) applied at 4 km depth. The left panel shows the default input field (Davies, 2013), whereas the right panel shows the modified map used for the GHF sensitivity experiments (Sec. 2.4). In the modified field, we set $\text{GHF} = 15 \text{ mW m}^{-2}$ for all grid cells below present-day sea level and within the black square.

2.5 Ocean temperature forcing and marine mass loss processes

This section describes both the default and additional ocean temperature forcings employed herein. The additional forcings are only used in specific experiments to determine the effects of ice shelves (HE ocean forcing, Sec. 2.5.1) and sub-surface ocean warmings attributed to DO events in a HE context (Sec. 2.5.2).

190 The default ocean temperature T_{ocean} in the GSM is based on the summer weighted ocean temperature field $(0.5 \cdot (T_{\text{ave,Jul:Oct}} + T_{\text{ave,Jan:Dec}}))$ derived from the TraCE deglacial simulation run with the Community Climate System



Model Version 3 (CCSM3, Liu et al., 2009). Using a glacial index approach, the ocean temperature chronology is interpolated between full glacial (last glacial maximum) and present day conditions for all other time slices (Tarasov et al., 2024, in preparation). Within a limited *ocean forcing area* (Fig. 2) and below the upper depth limit of d_{OF} , the 2 types of additional
 195 ocean temperature forcing described below (T_{HE} and T_{DO}) are added to the background ocean temperature for grid cells with floating ice.

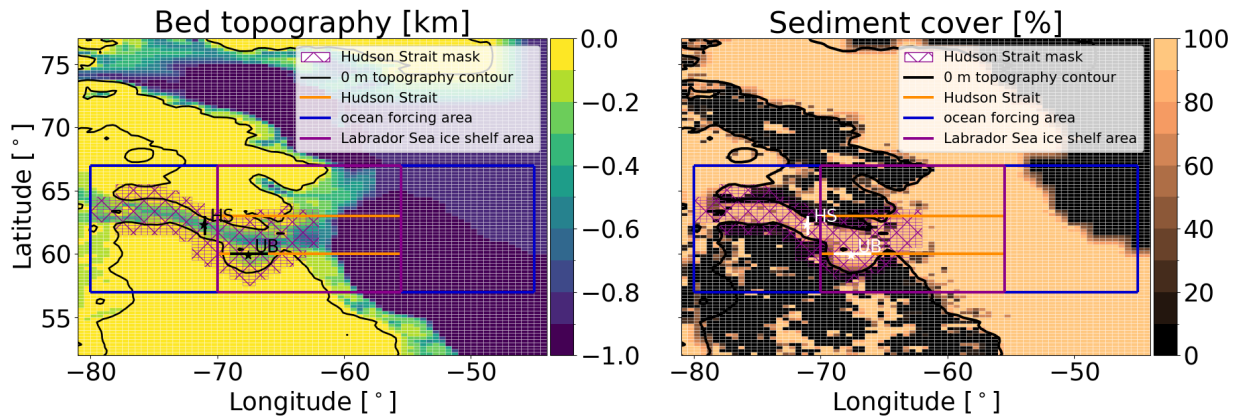


Figure 2. GSM input present-day bed topography and sediment cover. The black (left) and white (right) asterisks and lines indicate the location of Hudson Strait (*HS*) and Ungava Bay (*UB*) ice thickness calculation and flux gate, respectively. The *Hudson Strait mask* is used to determine Hudson Strait ice volume, mean and max basal ice velocity, and warm-based area. The black contour line shows the present-day sea level (coastline) used in the GSM. The *Hudson Strait* area is used to calculate Hudson Strait ice shelf area, ice shelf volume, and the backstress exerted by the floating ice on the Hudson Strait ice stream. The *ocean forcing area* outlines the region affected by the ocean temperature increases discussed in Sec. 2.5. Finally, the magenta box outlines the area within which the Labrador Sea ice shelf area and volume are calculated. To prevent ice sheet growth beyond a stub North-West Greenland, the surface elevation in the corresponding area has been set to well below sea level.

The ocean temperature at the relevant depth is then used to calculate the sub-shelf melt M_{SSM} and terminus face melt M_{face} . The GSM determines M_{SSM} based on a parametrization of buoyant meltwater plumes (Lazeroms et al., 2018) and parameter ranges set so that computed melt brackets present-day observations (e.g., Depoorter et al., 2013; Enderlin and Howat, 2013; Alley et al., 2015). For a floating ice grid cell, the sub-shelf melt is given by:
 200

$$M_{SSM} = (C_{SSM} + d \cdot A_{WF} \cdot (f_{SGWF})^{0.39}) \cdot T_{ocean,SSM} \cdot F_{slope}(SL) \cdot f_{SSM,slope} \quad (8)$$

and $0 \text{ m}_{\text{yr}}^{-1}$ otherwise. C_{SSM} is the scaled ensemble parameter for the sub-shelf melt (Table S1), f_{SGWF} the basal meltwater flux into the sub-shelf melt convection cell, A_{WF} is a scaling coefficient for the meltwater dependence, and d is the depth. $T_{ocean,SSM}$ is the ocean temperature at the depth of the ice shelf base and $f_{SSM,slope}$ is an overall scaling coefficient (Tarasov et al., 2024, in preparation). F_{slope} is a nonlinear function of the maximum lower ice surface slope SL (across the grid cell interfaces with adjacent ice).
 205



Face melt is determined only at the marine ice margin. It is calculated according to

$$M_{\text{face}} = \left(C_{\text{face}} \cdot H_{\text{eff}} + d \cdot A_{\text{WF}} \cdot (f_{\text{SGWF}})^{0.39} \right) \cdot T_{\text{ocean,face}}, \quad (9)$$

where C_{face} is the scaled ensemble parameter for the face melt (Table S1). $T_{\text{ocean,face}}$ is the ocean temperature adjacent to the ice face. This is set with the assumption that face melt water consists of equal parts of local water and shelf water. H_{eff} is the effective terminal ice thickness defined as $H_{\text{eff}} = \max[0.95 \cdot H; 200 \text{ m}]$.

Calving in the GSM is based on a crevasse propagation parameterization (Pollard et al., 2015). To account for the impact of land-fast perennial sea ice, calving is inhibited when the mean 2 m summer (JJA) temperature falls below -2.0°C (Tarasov et al., 2024, in preparation). However, calving has no temperature control once the ice shelf extends beyond the continental shelf break (present-day depth $> 860 \text{ m}$).

2.5.1 Ice shelf removal

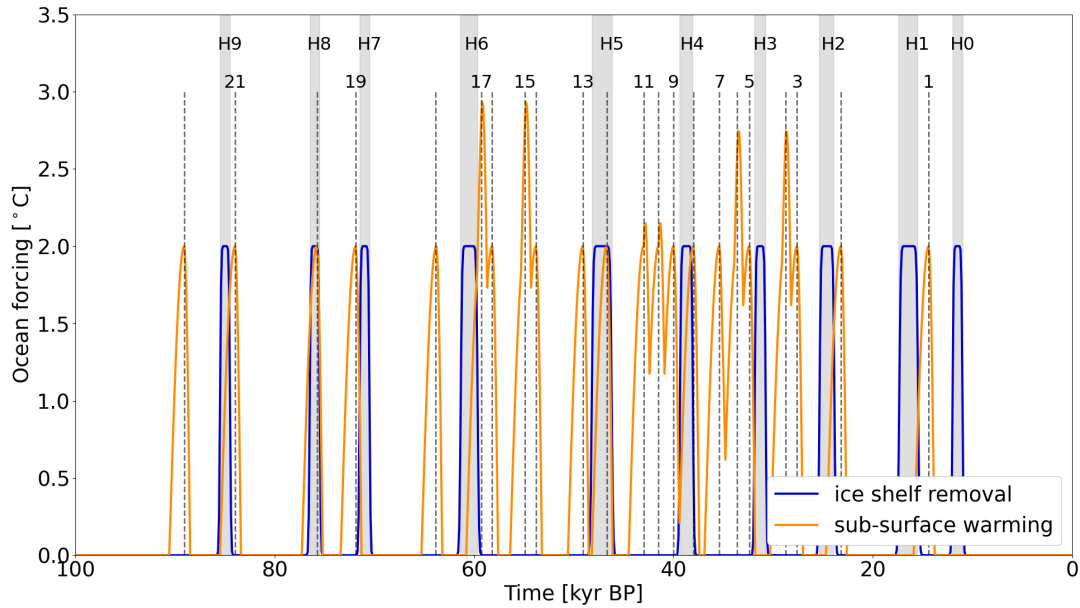


Figure 3. 2°C ocean temperature forcing used to remove the ice shelves (entire water column) and for the sub-surface ocean warming (below depth $d_{\text{OF}} = 250 \text{ m}$ in reference setup). The shaded grey areas represent the timing of HEs based on the average of Table 6.3 in Bradley (2014). The vertical dashed lines indicate the timing of DO events based on peaks in the NGRIP $\delta^{18}\text{O}$ time series (Bazin et al., 2013; Veres et al., 2013).

For experiments testing the impact of floating ice removal near Hudson Strait, an increase in the ocean temperature is imposed during HEs (Fig. 3). The ocean forcing is applied to either the entire water column ($d_{\text{OF}} = 0 \text{ m}$) or to an upper ocean forcing limit of $d_{\text{OF}} = 250 \text{ m}$. To calculate the HE shelf forcing, we first define a rectangular function for the i 'th HE according



220 to

$$T_{\text{HE},i} = \begin{cases} T_{\text{max,HE}} & \text{if } t_{\text{HE},i,\text{start}} \leq t \leq t_{\text{HE},i,\text{end}} \\ 0 & \text{otherwise,} \end{cases} \quad (10)$$

where $T_{\text{max,HE}} = [1, 2, 3]^\circ\text{C}$ are the maximum ocean temperature increases tested (amplitudes based on Gibb et al., 2014). To test for a potential warm bias of the GSM ocean temperatures, we also run a reverse experiment with a maximum ocean temperature decrease $T_{\text{max,HE}} = -2^\circ\text{C}$ during HEs. t is the time ranging from 0 to 100 kyr with a 100 yr increment, and $t_{\text{HE},i,\text{start}}$ and $t_{\text{HE},i,\text{end}}$ are the start and end time of the i 'th HE. The timing and duration of HEs are based on the average of Table 6.3 in Bradley (2014). For HEs without an estimated duration, we use 1 kyr (centered around the HE time estimate). To get a more gradual ocean temperature increase and decrease, we convolute $T_{\text{HE},i}$ with a Gaussian function of the form

$$y_{\text{Gauss},i,\text{tmp}} = \exp\left(\frac{-x_{\text{Gauss},i}^2}{2}\right) \quad (11a)$$

$$y_{\text{Gauss},i} = \frac{y_{\text{Gauss},i,\text{tmp}}}{\max(y_{\text{Gauss},i,\text{tmp}})} \cdot T_{\text{max,HE}}, \quad (11b)$$

230 where $x_{\text{Gauss},i}$ ranges from -10π to 10π over the duration of the i 'th HE and is 0 otherwise. The convoluted time series of the i 'th HE is then

$$T_{\text{HE},i,\text{conv}} = \begin{cases} T_{\text{HE},i} * y_{\text{Gauss},i} & \text{if } t_{\text{HE},i,\text{start}} \leq t \leq t_{\text{HE},i,\text{end}} \\ 0 & \text{otherwise.} \end{cases} \quad (12)$$

The final HE shelf forcing time series is obtained by adding the contributions of all individual HEs.

$$T_{\text{HE}} = \sum_i T_{\text{HE},i,\text{conv}}. \quad (13)$$

235 Since individual HEs do not overlap, the maximum ocean temperature increase does not exceed $T_{\text{max,HE}}$.

2.5.2 Sub-surface ocean warming

Similar to the preceding ice shelf removal experiments, the sub-surface warming preceding DO events is implemented as ocean temperature anomalies (OTAs, Fig. 3). The specification of the OTAs are based on proxies from marine cores in the North Atlantic and the Nordic Seas at mid depths (Rasmussen and Thomsen, 2004; Marcott et al., 2011). In the reference setup, the maximum increase of sub-surface (below depth $d_{\text{OF}} = 250$ m) temperatures of a single OTA is set to $T_{\text{max,DO}} = 2^\circ\text{C}$, but experiments are conducted for different sub-surface warming depths ($d_{\text{OF}} = [100, 500]$ m) and maximum temperature increases ($T_{\text{max,DO}} = [1, 3]^\circ\text{C}$). The OTAs last for a total of $t_{\text{D,tot}} = 2200$ yr, with an $t_{\text{Inc}} = 1600$ yr long temperature increase and $t_{\text{Dec}} = 600$ yr decrease. According to Rasmussen and Thomsen (2004), rapid DO warmings occur when the water column destabilizes and the warm sub-surface water rises to the surface. Since the warm sub-surface water is then mixed with the cold surface water (decreasing the sub-surface temperature), we align the maximum temperature increase of the OTAs with the DO

245



event time estimates (Fig. 3). Following the above, the OTA attributed to the i 'th DO event is calculated according to

$$T_{DO,i} = \begin{cases} T_{\max,DO} \cdot \sin\left(\frac{\pi}{2} \frac{t_{\text{Inc}} - (t - t_{DO,i})}{t_{\text{Inc}}}\right) & \text{if } t_{DO,i} \leq t \leq t_{DO,i} + t_{\text{Inc}} \\ T_{\max,DO} \cdot \sin\left(\frac{\pi}{2} \frac{t_{\text{Dec}} - (t_{DO,i} - t)}{t_{\text{Dec}}}\right) & \text{if } t_{DO,i} - t_{\text{Dec}} \leq t < t_{DO,i} \\ 0 & \text{otherwise,} \end{cases} \quad (14)$$

where $t_{DO,i}$ is the time of the i 'th DO event. Note that due to the implementation of the OTAs in Eq. 14, the values of $T_{DO,i}$ at $t_{DO,i} + t_{\text{Inc}}$ and $t_{DO,i} - t_{\text{Dec}}$ are 0°C . For a time step of 100 yr, the actual duration of increased sub-surface water temperature is, therefore, $t_D = 2000$ yr. Following Bassis et al. (2017), the contributions of overlapping OTAs are added

$$T_{DO} = \sum_i T_{DO,i} \quad (15)$$

Therefore, T_{DO} can exceed $T_{\max,DO}$ (Fig. 3).

2.5.3 Bounding experiments

To increase confidence in our model results and bound the effects of ocean forcings in a HE context (Sec. 2.5.1 and 2.5.2), we run additional experiments with more extreme scenarios. For all experiments within this section, the ocean forcing is applied to the whole water column ($d_{OF} = 0$ m) and for all grid cells within the *ocean forcing area* (Fig. 2, not only the grid cells with floating ice). The experiments are:

BE₁: DO event ocean forcing ($T_{DO}, T_{\max,DO} = 2^\circ\text{C}$)

BE₂: HE shelf forcing ($T_{HE}, T_{\max,HE} = 2^\circ\text{C}$)

260 BE₃: -2°C ocean forcing applied after 100 kyr BP

BE₄: no calving after 100 kyr BP

BE₅: HE shelf forcing ($T_{HE}, T_{\max,HE} = 2^\circ\text{C}$) with -2°C ocean forcing applied outside of HEs and after 100 kyr BP

BE₆: HE shelf forcing ($T_{HE}, T_{\max,HE} = 2^\circ\text{C}$) with no calving outside of HEs and after 100 kyr BP

Experiments BE₁ and BE₂ examine the effect of the ocean forcing restriction to grid cells with floating ice. Experiment BE₃ aims to decrease sub-shelf melt, face melt, and calving to enable the growth of larger ice shelves. In the more extreme experiment BE₄, the growth of larger ice shelves is enabled by inhibiting calving entirely. Experiments BE₅ and BE₆ target the collapse of larger ice shelves, with experiment BE₆ being the more extreme scenario.

2.6 Run comparison

Ensemble members with ≤ 2 and > 2 surges are generally analyzed separately. For runs with > 2 surges, percentage differences in surge characteristics (number of surges, mean surge duration, mean period between surges, mean increase in Hudson



Strait ice flux, and mean Hudson Strait ice volume change during a surge) for every sensitivity/reference run pair are computed individually and then averaged over all runs. MNEEs are computed by imposing stricter (than default) numerical convergence criteria in the ice dynamics solver. As in Hank et al. (2023), the final MNEEs (shaded grey regions in Fig. 6) are the maximum percentage difference for the metric in question of a setup with stricter numerical convergence and a setup with stricter numerical convergence with increased maximum iterations for the outer Picard loop (from 2 to 3, solving for the ice thickness) and the non-linear elliptic SSA (Shallow-Shelf Approximation) equation (from 2 to 4, solving for horizontal ice velocities). These MNEEs are then used as a threshold to determine if a change in model configuration leads to numerically significant differences in the surge characteristics. Differences smaller than the MNEEs should be interpreted as model response not resolvable given the numerical sensitivities.

For runs with ≤ 2 surges, the percentage differences in surge characteristics are large due to the small number of surges or impossible to determine for reference runs with #surges = 0. Therefore, we use alternative approaches (e.g., kernel density and time series plots) to determine the effects of physical system processes for the ≤ 2 #surges sub-ensemble.

3 Results

3.1 Hudson Strait ice stream surges

The Hudson Strait ice stream is active for most of the last glacial cycle when using the default GHF map (e.g., Fig. 4). This is contrary to the pattern of long quiescent intervals interspersed by short-lived surges proposed by, e.g., MacAyeal (1993); Payne (1995); Calov et al. (2002). Instead, the surges are preceded by a reduction (e.g., surges S0, S7 to S9 for parameter vector 1 shown in Fig. 4) or complete de-activation (S1 to S6) of the Hudson Strait ice stream. Depending on the background ice flux before the surge, the following ice flux increase occurs either rapidly (S0 to S7) or more gradually (S8 and S9). As per our criteria (Sec. 2.2), all identified surges have a decrease in Hudson Strait ice volume. The change is especially pronounced for surges preceded by a complete de-activation of the Hudson Strait ice stream. Times of complete Hudson Strait ice stream de-activation generally coincide with increased buttressing (shown as fraction of the grounding line longitudinal stress, Fig. 4). The decreased ice shelf volume indicates that this is due to a decrease in the longitudinal stress rather than an increase in the back stress. Therefore, the changes in buttressing are a consequence of the small Hudson Strait ice flux and not the cause. Instead, the de-activation of the Hudson Strait ice stream is caused by a decrease in the warm-based area (Fig. 4).

The more gradual increases in Hudson Strait ice flux (S8 and S9) are linked to surges in Ungava Bay (Fig. 4 and S6). Due to the rapid increase in ice flux in Ungava Bay, these surges are still in line with the concept of rapid surge onset, although the resultant increase in Hudson Strait ice flux is more gradual.

Some of the detected surges show an increase in Hudson Strait ice flux without a significant change in the effective pressure or the warm-based area in Hudson Strait (e.g., S1 to S3 in Fig. S7). During these surges, ice transport from Hudson Bay and Foxe Basin through Hudson Strait (and other outlets) towards the ice sheet margin increases (e.g., Fig. S8). The increased downstream ice transport and consequential increase in driving stress eventually increase the ice flux in Hudson Strait itself. Therefore, these surges originate further upstream and are initiated by ice and climate dynamics outside of Hudson Strait.

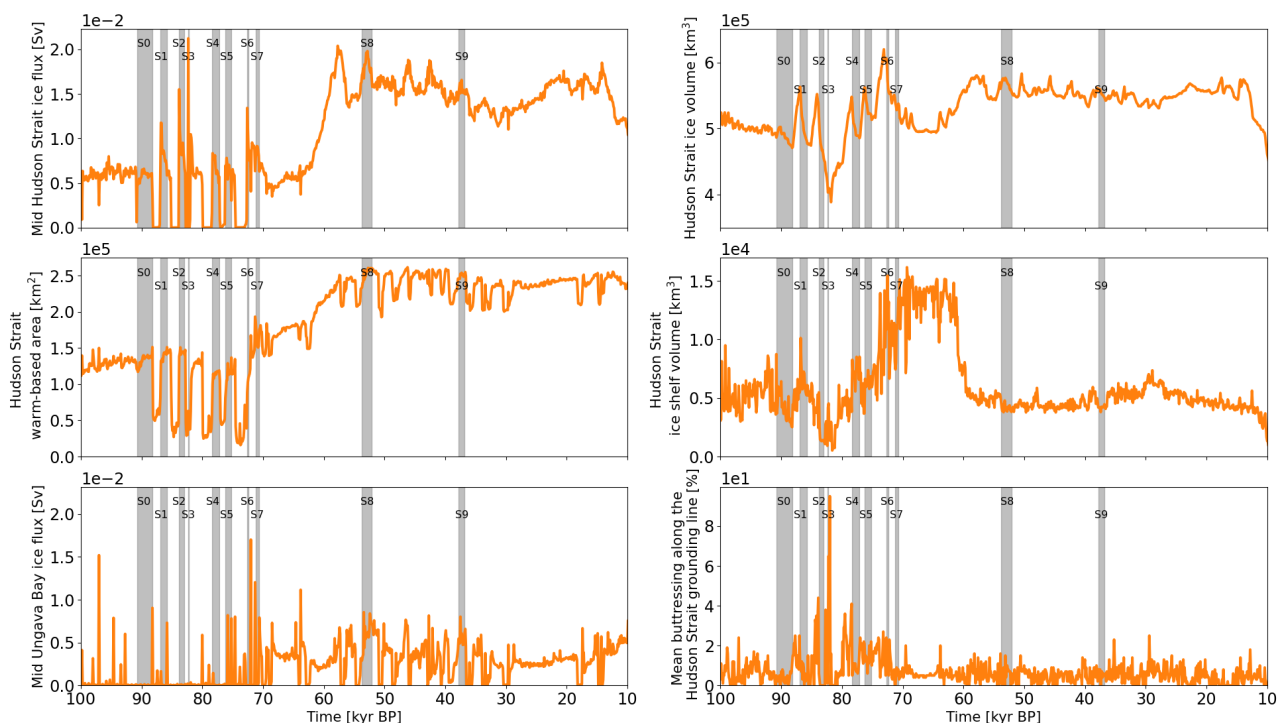


Figure 4. Time series of parameter vector 1. The shaded grey areas and black numbers mark Hudson Strait ice stream surges as determined by the automated detection algorithm (Sec. 2.2). Hudson Strait ice flux is determined at the flux gate marked with *HS* in Fig. 2. The Hudson Strait ice volume and warm-based area are calculated within the *Hudson Strait mask* (Fig. 2). The Hudson Strait ice shelf volume is determined within the *Hudson Strait* area (Fig. 2). The mean buttressing along the Hudson Strait grounding line (only within *Hudson Strait* area in Fig. 2) is given as fraction of the grounding line longitudinal stress $\left(\frac{\tau_{xx}}{\tau_f}\right)^{\frac{n}{m_s+1}}$ in Pollard and DeConto (2012)). The last panel shows the northward Ungava Bay ice flux determined at the flux gate marked with *UB* in Fig. 2. Note that the automated detection algorithm does not identify all smaller increases in mid-Hudson Strait ice flux (e.g., between 50 and 40 kyr BP) due to the additional requirement of a Hudson Strait ice volume decrease of at least $5 \cdot 10^3 \text{ km}^3$ (Sec. 2.2).

Surges, particularly those preceded by a complete de-activation of the Hudson Strait ice stream, tend to occur before
 305 65 kyr BP (e.g., Fig. 4). The absence of complete cessation of ice streaming during marine isotope stage 3 (MIS3, ~ 57 to 27 kyr BP, Lisiecki and Raymo, 2005) when using the default deep GHF map is due to increased basal temperatures. This is a result of the growing ice volume and, thereby, thicker ice and larger supply of warm-based upstream ice. The increased basal temperatures also lead to longer surges with reduced ice volume change (Fig. S9).

To get a better understanding of the physical mechanism behind Hudson Strait surges, we analyze surge S1 of parameter
 310 vector 1 in greater detail (Fig. 5 and video 01 of Hank, 2023). At 87.5 kyr BP, the ice sheet in Hudson Strait is warm-based, enabling basal melting. Basal water thicknesses reach up to 10 m (upper limit of local sub-glacial hydrology model), leading to small effective pressures and, consequently, high basal ice velocities. Due to a combination of cold ice advection from further



upstream and/or from the ice stream margins, thinning of the ice stream, and flattening of the ice sheet surface (hence reduced gravitational driving), the basal temperature eventually falls below the pressure melting point. The basal water refreezes and the effective pressure increases by an order of magnitude, increasing the basal drag (87.0 kyr BP). The ice streaming ceases, allowing the ice thickness to increase.

Due to increased insulation from the cold surface temperatures (thicker ice sheet) and heat contribution from the deformation work, the upstream basal temperature increases (video 02 of Hank, 2023). Once the basal temperature is close to the pressure melting point, basal sliding contributes further heat and the warm-based area starts to extend downstream (video 02 of Hank, 2023). Basal melting then leads to the build-up of a sub-glacial water layer, decreasing the effective pressure and enabling high basal ice velocities. Due to the built-up ice, Hudson Strait ice flux initially increases beyond the pre-ice stream de-activation values before gradually returning to similar ice fluxes, and completing the cycle (86.1 kyr BP).

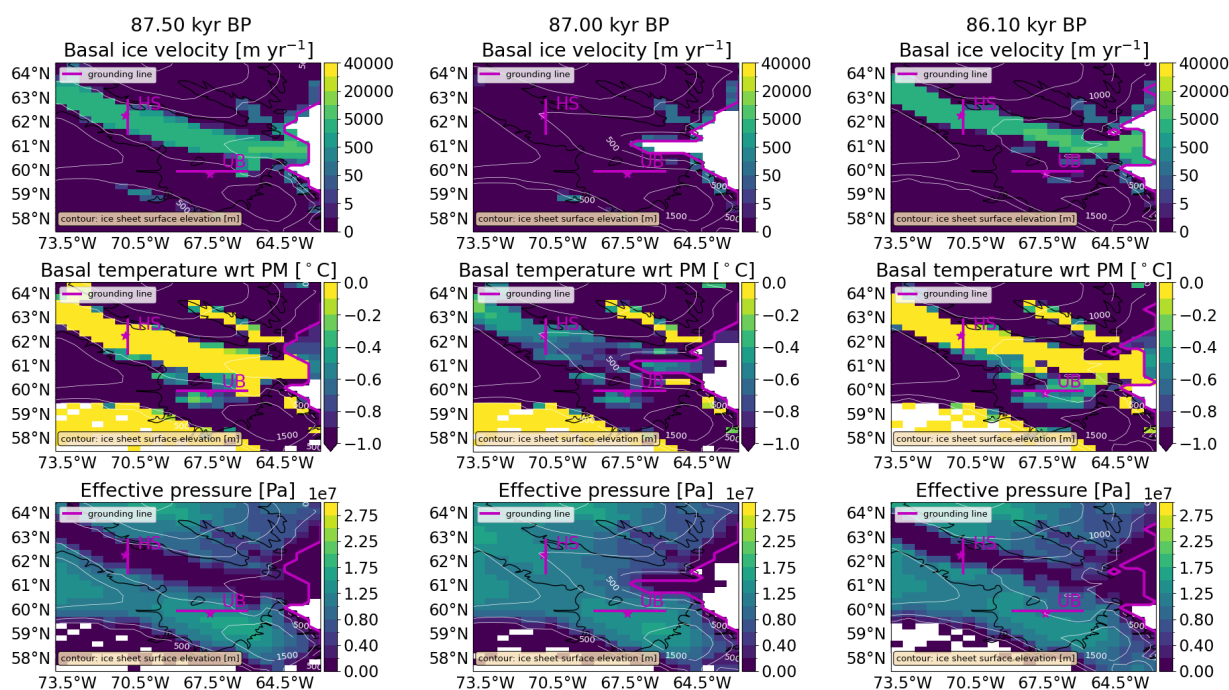


Figure 5. Basal ice velocity, basal temperature with respect to the pressure melting point, and effective pressure for surge S1 of parameter vector 1 (Fig. 4). The 3 time slices show the active ice stream before the surge (87.5 kyr BP), the quiescent period (87.0 kyr BP), and the surge at its maximum ice flux (86.1 kyr BP). The black contour is the present-day coastline provided by *cartopy* (Met Office, 2010 - 2015).

Overall, the mean surge characteristics of the reference setup for the sub-ensemble with more than 2 surges are in agreement with HE estimates in the literature (Table 1). However, the predominance of complete de-activation surges (generally the surges with the largest ice volume change) prior to 65 kyr BP is a major discrepancy (Fig. S9). One inferential caveat is that proxy records can provide only indirect bounds on Hudson Strait ice flux and ice volume change. A comparison to other ice



sheet modeling studies (e.g., Schannwell et al., 2023) is not straightforward, as the considered metrics vary significantly (e.g., Hudson Strait area). Using an intermediate mid-Hudson Strait ice flux during a surge (0.01 Sv, e.g., Fig. 4) and the mean surge duration (1.4 kyr, Table. 1) yields an ice volume discharge of $\sim 44 \cdot 10^4 \text{ km}^3$. This value is well within the range set by modeling and proxy estimates in the literature ($3 \cdot 10^4$ to $946 \cdot 10^4 \text{ km}^3$, Roberts et al., 2014, and references therein).

| Metric | reference setup (mean \pm SD) | literature HE estimate |
|---------------------------------|--|--|
| number of surges | 5.4 ± 2.5 | 6 to 10 (Table 6.3 in Bradley, 2014) |
| period | $13.6 \pm 8.8 \text{ kyr}$ | 4 to 15 kyr, mean = $8.0 \pm 2.7 \text{ kyr}$ (Table 6.3 in Bradley, 2014) |
| duration | $1.4 \pm 0.4 \text{ kyr}$ | 0.2 to 2.3 kyr (Hemming, 2004) |
| Hudson Strait ice flux increase | $4.9 \pm 2.0 \cdot 10^{-3} \text{ Sv}$ | - |
| Hudson Strait ice volume change | $-3.6 \pm 2.3 \cdot 10^4 \text{ km}^3$ | - |

Table 1. Surge characteristics of the reference setup compared to literature estimates. Only runs with #surges > 2 (between 100 kyr BP and 10 kyr BP) are considered. The literature HE estimates are also based on the time between 100 kyr BP and 10 kyr BP. As the automated detection algorithm determines the increase in mid-Hudson Strait ice flux (not the total flux) and the change in Hudson Strait ice volume (not the total discharge), we refrain from providing literature estimates for these two metrics here. Refer to the text for a comparison of the ice volume discharge.

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Due to the inclusion of a resolution-dependent basal temperature ramp (Hank et al., 2023), the differences in surge characteristics between the coarse resolution runs (horizontal grid resolution of $\Delta_{\text{lon}} = 1.0^\circ$, $\Delta_{\text{lat}} = 0.5^\circ$) and the reference runs ($\Delta_{\text{lon}} = 0.5^\circ$, $\Delta_{\text{lat}} = 0.25^\circ$) are generally within the MNEEs (Fig. 6). While finer (than the reference setup) horizontal grid resolutions are currently unfeasible in the context of this study, given the results of resolution response testing of surge cycling down to 3.125 km horizontal grid resolution in Hank et al. (2023), the differences in surge characteristics for finer resolutions are also expected to be within the MNEEs.

335

3.2 Geothermal heat flux

Since the Hudson Strait ice stream is active for most of the last glacial cycle and the GHF is poorly constrained in this area, a lower GHF could increase the time of ice stream inactivation. Therefore, we examine the effect of smaller average Hudson Bay/Hudson Strait GHFs (GHF_{ave}) on the surge characteristics. Sensitivity experiments are run for $\text{GHF}_{\text{ave}} \approx [15, 26, 37, 48, 59] \text{ mW m}^{-2}$ (Sec. 2.4).

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In general, decreasing the GHF in Hudson Strait and Hudson Bay leads to a decrease in the basal temperature, a smaller warm-based area, and, consequently, a decrease in mid-Hudson Strait ice flux. For small enough GHFs (15 mW m^{-2}), 9 parameter vectors have fully transitioned from an almost continuously active Hudson Strait ice stream to the classic binge-purge surge mode (e.g., Fig. 7). The exact transition point depends on the parameter vector in question but generally requires a Hudson Strait/Hudson Bay $\text{GHF}_{\text{ave}} \leq 37 \text{ mW m}^{-2}$ ($w_{\text{GHF}} = 0.4$). The #surges > 2 and #surges ≤ 2 sub-ensembles both show

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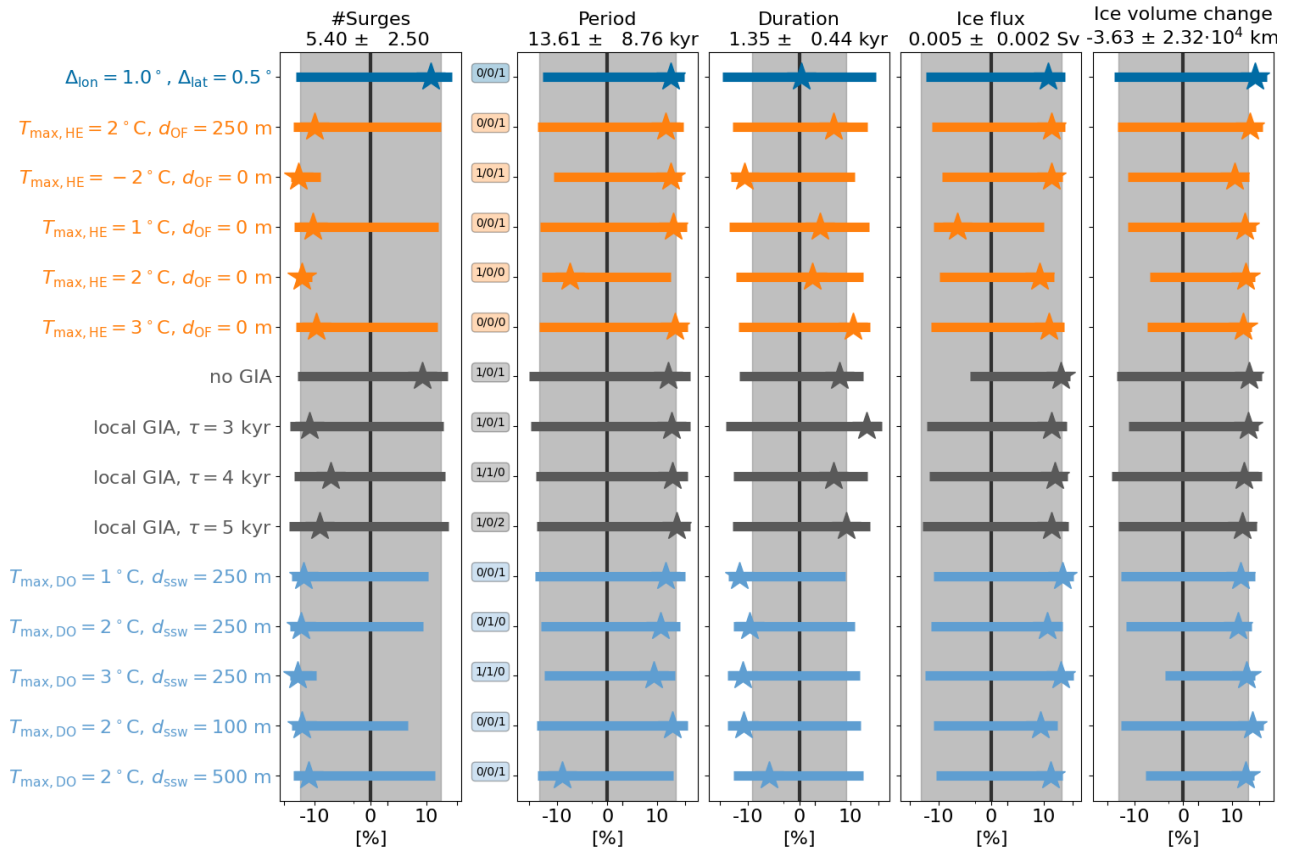


Figure 6. Percentage differences in surge characteristics compared to the reference setup for the > 2 #surges sub-ensemble. The shaded regions represent the MNEEs. The different colours provide visual alignment of the individual model setups. The stars and horizontal bars are the > 2 #surges sub-ensemble mean percentage differences and standard deviations, respectively. The three numbers between the first and second column show the number of crashed runs, the number of runs without a surge, and the number of runs with only one surge in the comparison setup. The x-axes are logarithmic. The model setups, from top to bottom, are: $\Delta_{lon} = 1^\circ$, $\Delta_{lat} = 0.5^\circ$ horizontal grid resolution, Heinrich Event shelf forcing ($T_{max,HE} = 2^\circ\text{C}$, $d_{OF} = 250\text{ m}$), whole water column Heinrich Event shelf forcing with $T_{max,HE} = [-2, 1, 2, 3]^\circ\text{C}$ (Sec. 2.5.1), no GIA model, local GIA model that is simply a damped-return to isostatic equilibrium with relaxation time constant $\tau = [3, 4, 5]$ kyr, DO event sub-surface ocean forcing with $T_{max,DO} = [1, 2, 3]^\circ\text{C}$ and $d_{OF} = [100, 250, 500]$ m (Sec. 2.5.2).

significant increases in the number of surges and mean Hudson Strait ice volume change for decreasing GHFs (Fig. S11 and S12, Table 2). On the other hand, the mean surge duration significantly decreases for smaller GHFs. Therefore, the colder basal temperatures and increased Hudson Strait ice volume lead to stronger and more rapid surges (e.g., Fig. 7).

350 A key feature of the binge-purge mode is the increase of strong Hudson Strait surges during MIS3 compared to the number of surges for the near continuous ice streaming mode (e.g., Fig. 7, S9, and S10). This is in closer correspondence with the actual IRD record.

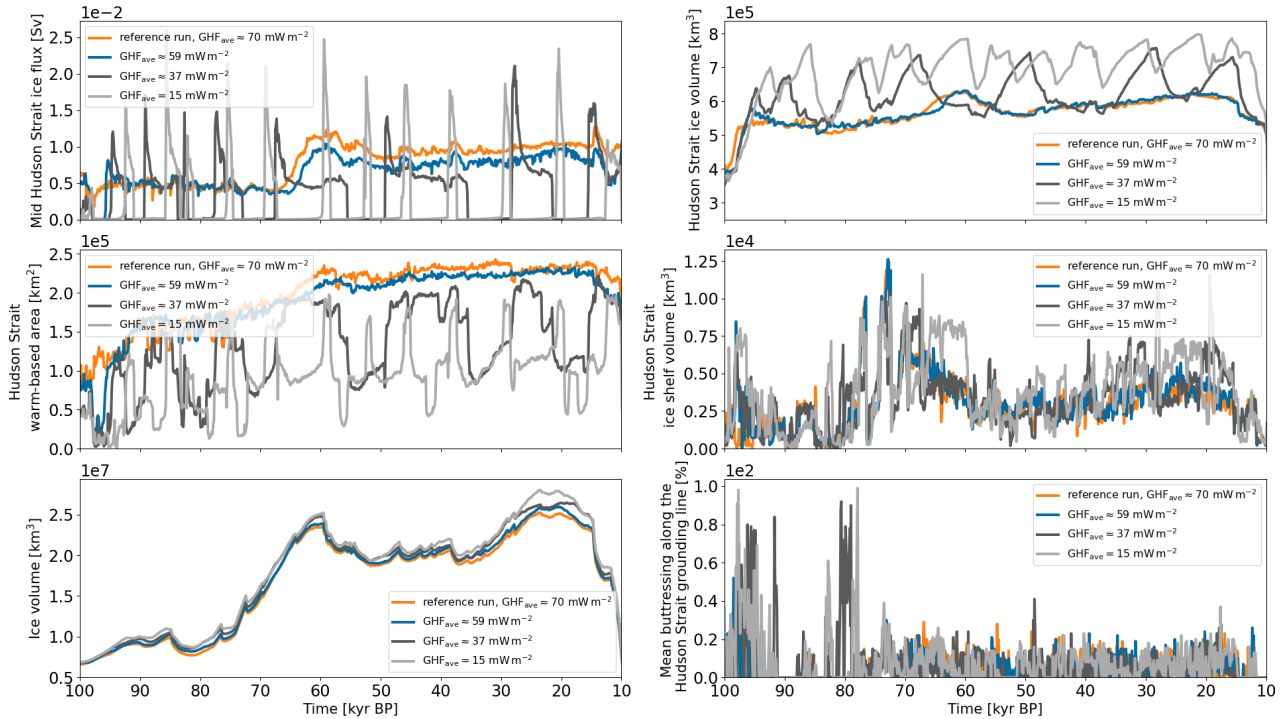


Figure 7. Time series of parameter vector 18 for different GHFs. The Hudson Strait ice stream surges are not highlighted for clarity. The bottom left panel shows the overall North American ice volume. Otherwise as Fig. 4.

| Metric | reference setup (mean \pm SD) | GHF _{ave} = 15 mW m ⁻² (mean \pm SD) | regularized Coulomb sliding law (mean \pm SD) |
|---------------------------------|--|--|--|
| number of surges | 5.4 \pm 2.5 | 10.6 \pm 5.3 | 52.4 \pm 18.8 |
| period | 13.6 \pm 8.8 kyr | 10.7 \pm 5.5 kyr | 1.6 \pm 0.5 kyr |
| duration | 1.4 \pm 0.4 kyr | 0.7 \pm 0.3 kyr | 0.3 \pm 0.2 kyr |
| Hudson Strait ice flux increase | 4.9 \pm 2.0 \cdot 10 ⁻³ Sv | 23.0 \pm 13.0 \cdot 10 ⁻³ Sv | 27.8 \pm 8.8 \cdot 10 ⁻³ Sv |
| Hudson Strait ice volume change | -3.6 \pm 2.3 \cdot 10 ⁴ km ³ | -6.6 \pm 1.1 \cdot 10 ⁴ km ³ | -4.1 \pm 1.3 \cdot 10 ⁴ km ³ |

Table 2. Surge characteristics for 3 different setups: the reference setup, a setup with the GHF in Hudson Bay and Hudson Strait set to 15 mW m⁻² (Sec. 2.4), and a setup using a combination of the default Weertman-type power law (Eq. 1 and regularized Coulomb sliding law (Eq. 5b and 6). Only runs with #surges > 2 (between 100 kyr BP and 10 kyr BP) are considered (10 for the reference setup, 13 for GHF_{ave} = 15 mW m⁻², 7 for the regularized Coulomb sliding law).

Separately modifying the GHF in Hudson Strait and Hudson Bay indicates that the GHF modification in Hudson Strait generally has a larger impact than modifications in Hudson Bay (Fig. S13 and S14). However, GHF modifications in both regions are required to obtain continuous binge-purge surge cycling. GHF modifications applied to a larger region (Fig. S5,



based on Blackwell and Richards (2004)) lead to similar conclusions (Fig. S15). Therefore both types of Hudson Strait ice stream surge cycling are consistent within available GHF constraints.

Our analyses below are based on the GSM default GHF map. However, similar conclusions are obtained when applying $\text{GHF}_{\text{ave}} = 25 \text{ mW m}^{-2}$ to Hudson Bay and Hudson Strait (Fig. S16, S17, S31, and S32). Any differences in model response are outlined in the specific sections.

3.3 Basal sliding law

As it is unclear which sliding law should be used in a surge cycling context, we examine the impact of using a (regularized) Coulomb sliding law (Eq. 5) in combination with the default Weertman-type power law (Eq. 1 and 6). Generally, the Coulomb sliding law experiments are numerically more unstable, leading to only 6 successfully completed runs for the Coulomb (Eq. 5a, 14 runs crashed) and 7 for the regularized Coulomb sliding law (Eq. 5b, 13 runs crashed). Additionally, the remaining runs show an average increase in the model run time of $\sim 447.5\%$ and $\sim 32.5\%$ for the Coulomb and regularized Coulomb sliding law, respectively.

The limited number of successful runs and increase in model run time hinder determining the effects of a Coulomb sliding law, especially in the case without regularization (Fig. S18 and S19). Therefore, the analysis below only examines the regularized Coulomb sliding law. However, both forms of Coulomb basal drag law lead to a noisy (large number of peaks in short succession) mid-Hudson Strait ice flux time series (Fig. 8), posing a challenge for the automated peak prominence detection algorithm (with potential overestimation of the number of surges and overlap of surges). While smoothing the mid-Hudson Strait ice flux time series and/or adding an additional requirement (e.g., minimum time difference between detected peaks) would likely minimize these issues, it would also lead to a loss of information and obscure the comparison to the other setups. Therefore, we continue the analysis without these changes.

The most significant impact of using the regularized Coulomb sliding law is a shift to the classic binge-purge surge cycling (e.g., Fig. 8). While a change in surge mode also occurs for a lower GHF, using the regularized Coulomb sliding law leads to more frequent binge-purge surges (Table 2, Fig. 8 and 9). This conclusion holds even when considering an overestimation of the detected surges due to the noisy mid-Hudson Strait ice flux time series when using the regularized Coulomb sliding law. All successful regularized Coulomb sliding law runs show surges, even those with parameter vectors that have a continuous ice stream in the $\text{GHF}_{\text{ave}} = 15 \text{ mW m}^{-2}$ experiment (e.g., Fig. S20).

Due to the large increase in the number of surges, the mean period for the regularized Coulomb sliding law is well below the literature estimates (Table 1 and 2). Given the differences in the basal sliding law, an assessment of whether the two different basal sliding laws (Weertman and Coulomb) are implemented with scale-matched parameter values would be ambiguous. However, the regularized Coulomb and $\text{GHF}_{\text{ave}} = 15 \text{ mW m}^{-2}$ ensembles have comparable ranges for Hudson Strait ice flux increases, while the latter has larger mean Hudson Strait ice volume changes during surges (primarily due to the longer surge duration, Table 2). Furthermore, our chosen basal drag coefficient ensemble parameters cover typical ranges (Table S1).

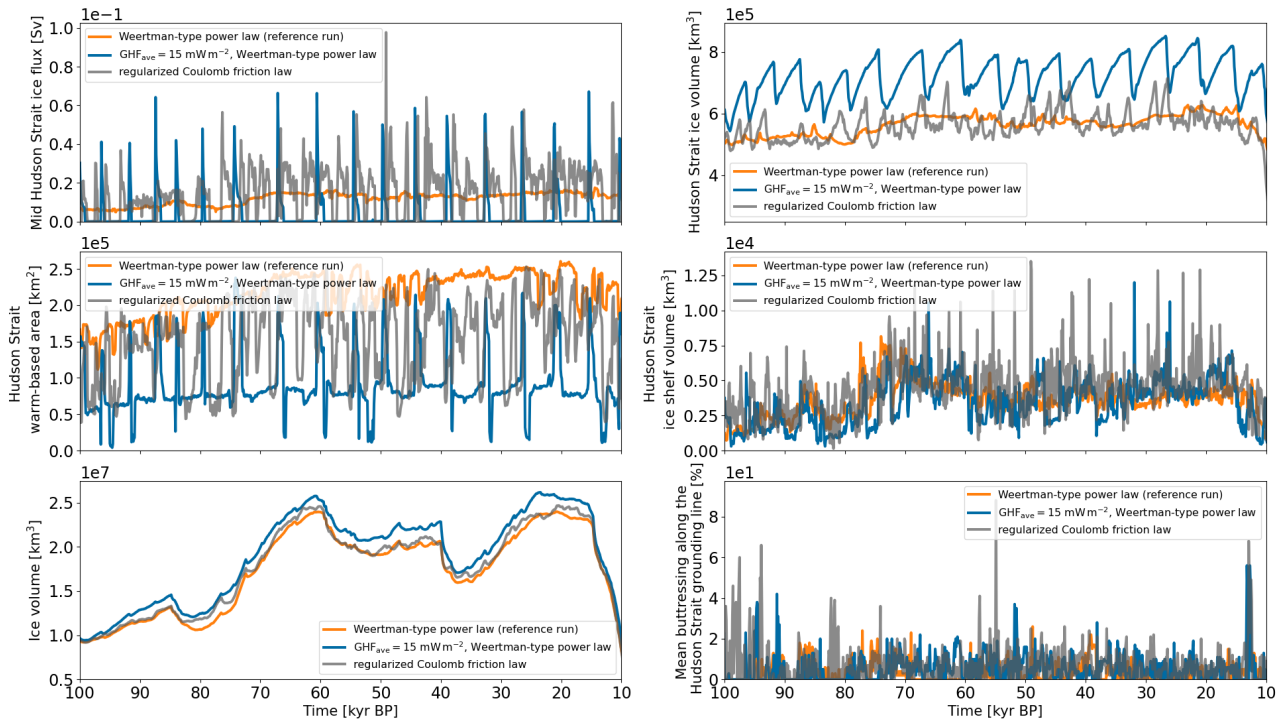


Figure 8. Time series of parameter vector 16 for different sliding laws (Weertman-type power law exponent is 2) and geothermal heat fluxes. The bottom left panel shows the overall North American ice volume. Otherwise as Fig. 4.

Only using the Weertman-type power law to calculate the ice flux across the grounding line ($\tau_{b, GL} = \tau_{b, W}$ instead of Eq. 6) and otherwise the reference setup (Eq. 1) has no significant effect on the surge characteristics (Fig. S18 and S19). Therefore, 390 uncertainties in the appropriate grounding line ice flux treatment are not critical.

Due to the numerically more unstable runs, the large increase in model run time, and the surge detection issues, we refrain from repeating all sensitivity experiments within this study with a (regularized) Coulomb sliding law.

3.4 Ice shelf removal

The hypothesized ice shelf collapse trigger for surge initiation is contingent on a large enough ice shelf to provide adequate 395 buttressing of the Hudson Strait ice stream. However, the maximum area covered by an ice shelf across all reference runs is $\sim 0.5 \cdot 10^5$ and $\sim 1.0 \cdot 10^5$ km² (Fig. 11) of *Hudson Strait* (total area of $\sim 2.6 \cdot 10^5$ km², Fig. S21) and the *Labrador Sea ice shelf area* (total area of $\sim 8.7 \cdot 10^5$ km², Fig. 10), respectively (both areas outlined in Fig. 2). The mean ice shelf cover never exceeds $0.4 \cdot 10^5$ km² in the *Labrador Sea ice shelf area*. These rather small ice shelves have only limited potential to buttress the Hudson Strait ice stream.

400 Given system uncertainties, we examine the change in ice shelf area when decreasing the ocean temperature by 2°C (entire water column, BE₃ in Sec. 2.5.3) and inhibiting calving in the *ocean forcing area* (BE₄ in Sec. 2.5.3, area outlined in Fig. 2).

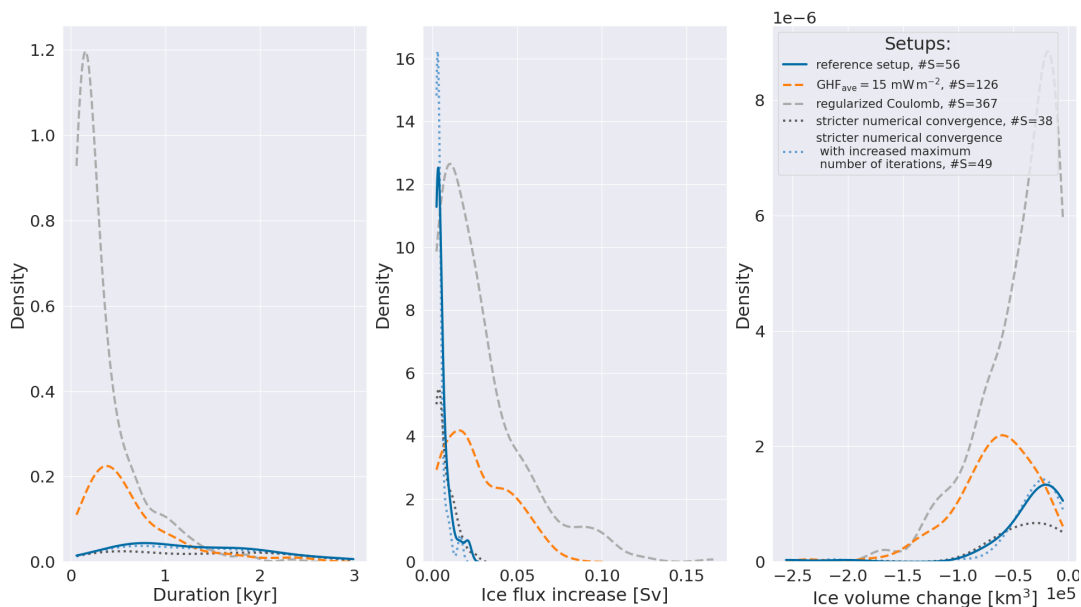


Figure 9. Kernel density plot for the whole ensemble (20 parameter vectors). The $\text{GHF}_{\text{ave}} = 15 \text{ mW m}^{-2}$ and MNEEs setups use the Weertman-type power law. Note that 2 runs crashed for the $\text{GHF}_{\text{ave}} = 15 \text{ mW m}^{-2}$ setup and 13 for the regularized Coulomb sliding law. Crashed runs are not considered here. #S indicates the total number of surges across all runs of the sub-ensemble. The density in each frame of the kernel density plot is scaled so that the sum of all individual integrals within this frame is 1.

Decreasing the ocean temperature leads only to a minor increase in Labrador Sea ice shelf cover (Fig. 12). When completely inhibiting calving, the Labrador Sea ice shelf cover increases by at least a factor of 4, at times covering all grid cells in the *Labrador Sea ice shelf area* not covered by grounded ice (maximum of $\sim 4.0 \cdot 10^5 \text{ km}^2$, Fig. 12). However, even with
 405 this extreme calving restriction, some parameter vectors show only minor Labrador Sea ice shelves (e.g., Fig. S28). This demonstrates the breadth of sub-shelf melt across our ensemble (maximum melt rates in BE_4 runs vary between $\sim 22 \text{ m yr}^{-1}$ (1.6°C ocean temperature) and $\sim 165 \text{ m yr}^{-1}$ (4.7°C ocean temperature)) and the resultant bound of process uncertainties.

To test the role of ice shelf buttressing (along with potential grounding line destabilization from submarine melt) in a Heinrich Event context, we apply different ocean temperature forcings (with default calving). In particular, we adjust the ocean
 410 temperature during HEs by a maximum temperature change $T_{\text{max,HE}} = 2^\circ\text{C}$ below 250 m of the sea level, and $T_{\text{max,HE}} = [-2, 1, 2, 3]^\circ\text{C}$ for the entire water column (Sec. 2.5.1 and 2.5.3). Except for the surge duration, none of these “HE shelf forcing” experiments significantly affects the surge characteristics of the > 2 #surges sub-ensemble (Fig. 6 as well as BE_2 and BE_5 in S29). Even at $T_{\text{max,HE}} = 3^\circ\text{C}$, there are only minor differences between the reference and HE shelf forcing runs (e.g., Fig. S22).

415 The ≤ 2 #surges sub-ensemble generally shows only small changes in the number of surges for the “HE shelf forcing” experiments (Fig. S23 as well as BE_2 and BE_5 in Fig. S30). The maximum difference (increase in the total number of surges in the sub-ensemble from 2 to 7) occurs for $T_{\text{max,HE}} = 1^\circ\text{C}$ and below depth $d_{\text{OF}} = 0 \text{ m}$. In comparison, the minimum increase

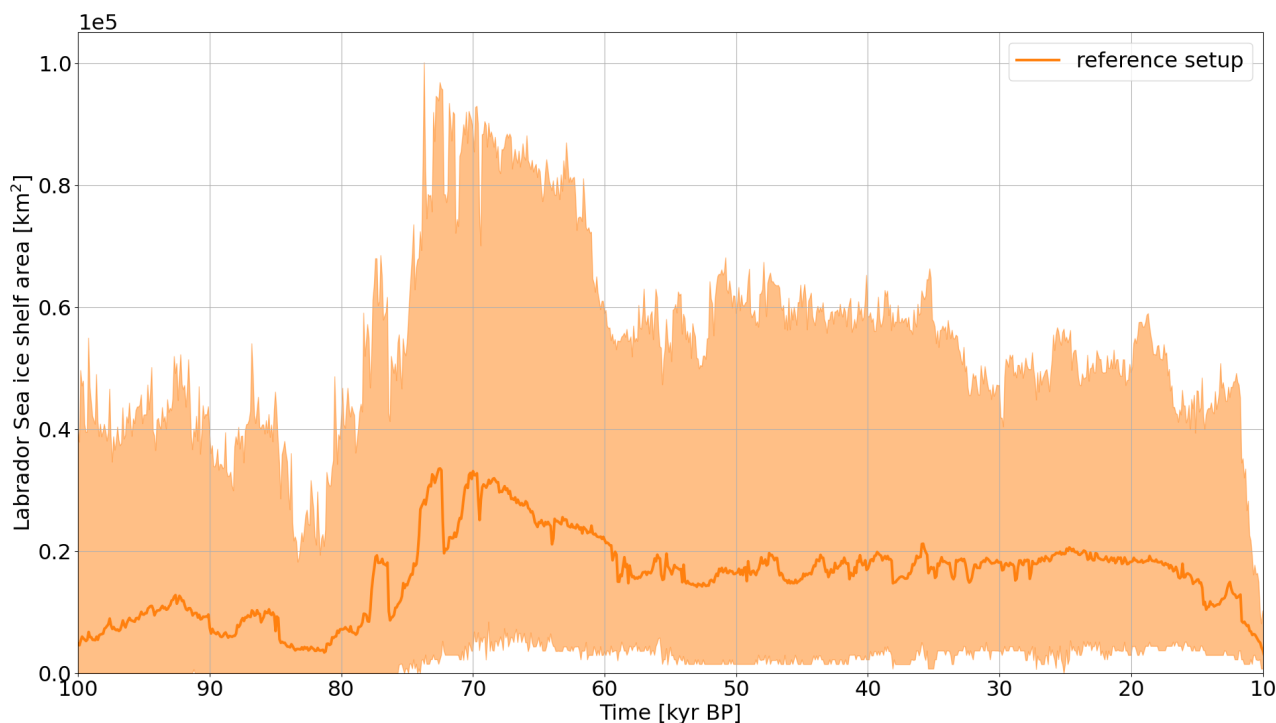


Figure 10. Labrador Sea ice shelf cover in the *Labrador Sea ice shelf area* outlined in Fig. 2 (total area of $\sim 8.7 \cdot 10^5 \text{ km}^2$). The thick line represents the mean of the 20 run ensemble. The shaded area marks the minimum and maximum of the ensemble. The maximum ice shelf area at 70 kyr BP is shown in Fig. 11.

in the total number of surges over the whole ≤ 2 #surges sub-ensemble (10 runs) for the GIA experiments is 10, and the MNEE experiments show a maximum difference of 2 (Fig. 16). Furthermore, the onset of the additional surges does not necessarily align with the ocean forcing (e.g., Fig. S24). The increase in surge number is a result of slightly different ice configurations rather than a direct response to the removal of the ice shelves and their potential buttressing.

During cold climatic conditions, the 2 m summer surface temperatures near the ice shelves stay below -2.0°C , allowing calving only where the ice shelf extends beyond the continental shelf break (e.g., Fig. S25, see Sec. 2.5 for details). To ensure the minor ice shelf sensitivity to ocean temperature changes during HEs is not solely a consequence of this calving restriction, we also run an experiment with a maximum ocean temperature forcing during HEs $T_{\text{max,HE}} = 3^\circ\text{C}$ applied to the whole water column ($d_{\text{OF}} = 0 \text{ m}$) and without any imposed restriction on calving within the *ocean forcing area* (Fig. 2). This has no significant effect (Fig. S26).

Therefore, the small effect of the ocean temperature forcing on surges of the Hudson Strait ice stream is a consequence of the relatively small ice shelf in front of Hudson Strait, providing insignificant buttressing. While the experiments with colder ocean temperatures (-2°C only during HEs and -2°C after 100 kyr BP) slightly increase the ice shelf cover, a complete calving shutdown is required to build up large ice shelves (e.g., Fig. 12). The larger ice shelves provide increased buttressing,

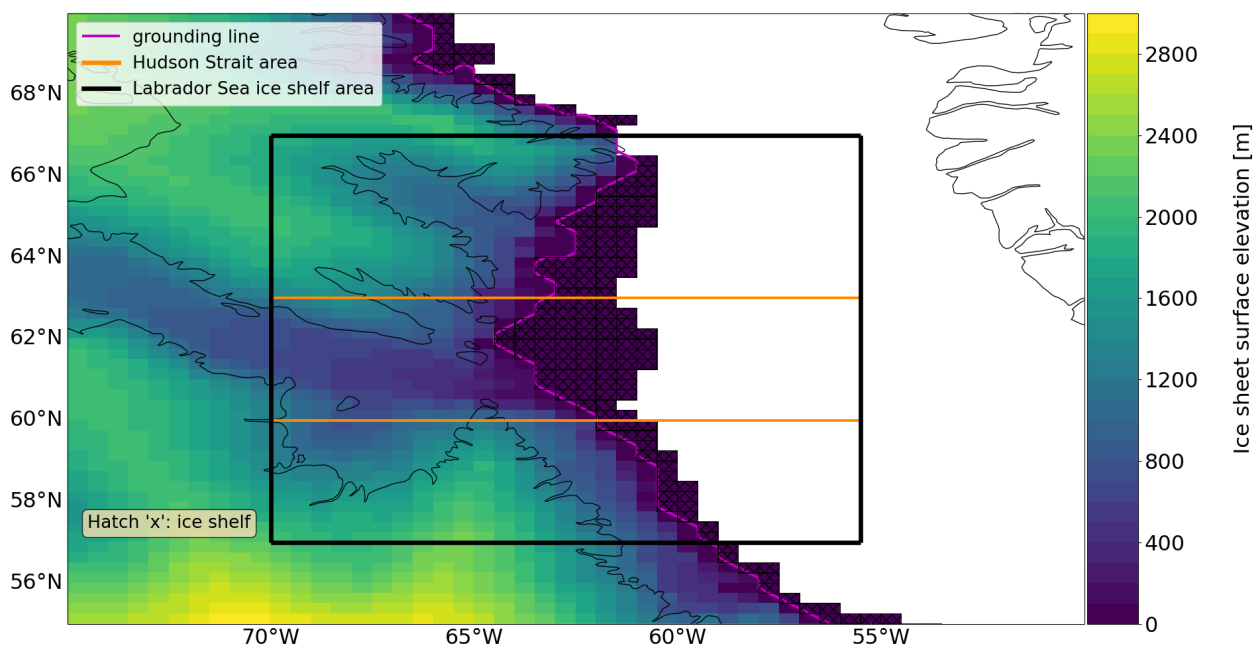


Figure 11. Ice sheet surface elevation at 70 kyr BP (time step closest to the maximum Hudson Strait ice shelf area; reference run in Fig. S22) for parameter vector 1.

leading to more gradual changes in mid-Hudson Strait ice flux, a more stable Hudson Strait ice volume, and consequentially fewer surges (Fig. S29 and S33).

Using the HE ocean forcing with a maximum temperature increase of $T_{\max, \text{HE}} = 2^\circ\text{C}$ and no calving outside of HEs and after 100 kyr BP (BE_6) leads to a rapid collapse of the large ice shelves during HEs (due to calving and warmer ocean temperatures, Fig. 13). The ice shelf disintegration increases Hudson Strait ice flux, decreasing Hudson Strait ice volume. While even in this extreme scenario, mid-Hudson Strait ice flux and Hudson Strait ice volume changes are relatively small (e.g., Fig. 13), the timing of at least 1 mid-Hudson Strait surge is directly affected by the ocean forcing and consequential reduction in buttressing for 10 (out of 20) parameter vectors.

440 3.5 Adding underwater warming pulses

As for the ocean forcing associated with HEs, the more frequent DO event sub-surface ocean warming has no significant effect on the surge characteristics, except for the surge duration (Fig. 6 and BE_1 in Fig. S29). Similarly, the ≤ 2 #surges sub-ensemble show minor changes in the number of surges when applying the DO event ocean forcing (Fig. 14 and BE_1 Fig. S30). The only exception is $T_{\max, \text{DO}} = 2^\circ\text{C}$, $d_{\text{OF}} = 250$ m, which increases the total number of surges across the sub-ensemble from 2 to 11 (spread across 3 runs, maximum increase of 4 surges per run). Considering that there are 22 ocean temperature increases

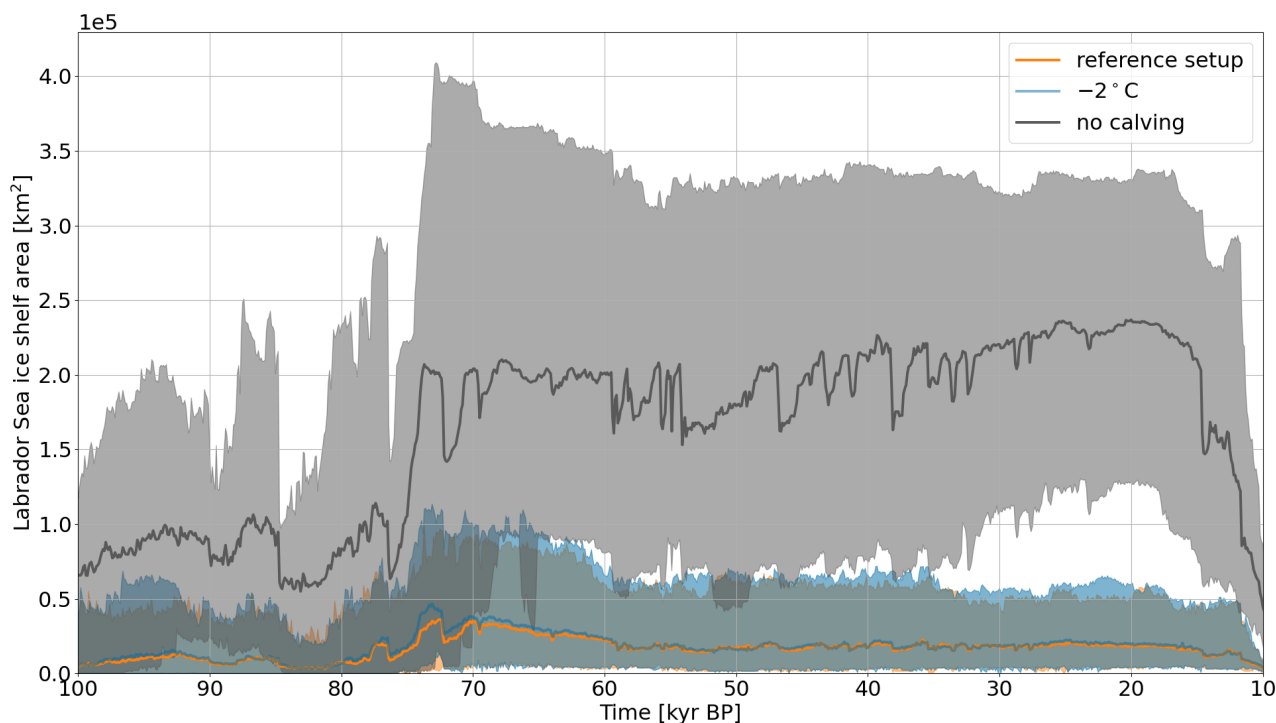


Figure 12. Labrador Sea ice shelf cover in the *Labrador Sea ice shelf area* for the reference setup compared to setups with 2°C colder ocean temperatures and without calving in the *ocean forcing area* (both areas outlined in Fig. 2). The thick line represents the mean of 18 runs (the runs for parameter vectors 8 and 15 crashed in both comparison setups and were not included). The shaded area marks the minimum and maximum of the remaining runs.

per run, this is still a rather small increase. Furthermore, the additional events do not necessarily align with increased ocean temperatures. As for the ice shelf removal experiments, the increase in surges is a consequence of small changes in the overall ice configuration, particularly in Hudson Strait, rather than a direct response to the ocean forcing itself (e.g., Fig. S27).

Therefore, the ocean forcing and the consequential increase in sub-shelf melt and face melt are insufficient to significantly affect the surge characteristics (number of surges, mean surge duration, mean period between surges, mean increase in Hudson Strait ice flux, and mean Hudson Strait ice volume change during a surge) or trigger new surges. However, sub-surface ocean warming can indirectly affect the overall timing of surges through changes in ice sheet evolution.

3.6 GIA

At first, we determine the effects of GIA on the overall ice sheet by comparing the reference setup to runs without GIA. On average, GIA leads to thicker ice sheets (Fig. 15). The bed depression caused by the weight of the ice sheet lowers the ice sheet surface elevation. Due to the atmospheric lapse rate and the Clausius–Clapeyron formula for saturation vapour pressure, accumulation generally increases for a decreasing surface elevation (except where orographic forcing is strong), allowing for

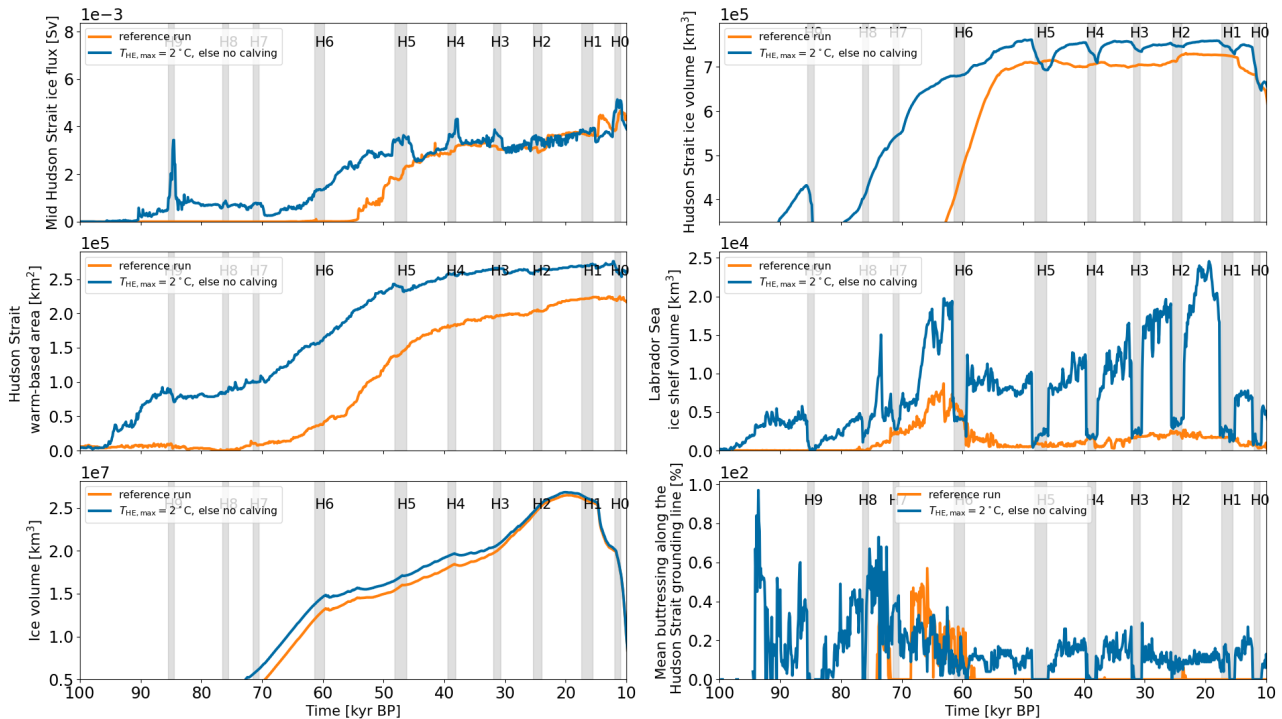


Figure 13. Time series of parameter vector 14 for the reference setup compared to the HE ocean forcing with a maximum temperature increase of $T_{max,HE} = 2^\circ\text{C}$ (shaded grey areas) and no calving outside of HEs and after 100 kyr BP (BE_6 in Sec. 2.5.3). The Labrador Sea instead of Hudson Strait ice shelf volume is shown. The bottom left panel shows the overall North American ice volume. Otherwise as Fig. 4.

a thicker ice sheet than without GIA (Fig. 15). Close to the ice sheet margin, a reduced ice sheet surface elevation has the potential to increase the ablation zone. However, the reduced ice sheet surface elevation could also lower the driving stress near the margin and decrease the ice flux to the ablation zone. While the bed topography under the ice sheet, including the marginal areas, is generally depressed (Fig. S34), the total melt tends to be slightly smaller with GIA (Fig. 15). It is difficult to disentangle the exact underlying cause as various processes affect surface melt. As this is not our primary focus, we defer exploring the nuanced effects of GIA on surface melt to future studies.

Before analyzing the effects of GIA on the surge characteristics, we determine the ice sheet's sensitivity to different earth rheology models. All 20 parameter vectors (full ensemble) were run with 9 different earth rheologies. The rheologies differ in the thickness of the Lithosphere (d_L), and the viscosity of the upper and lower mantle (η_{um} and η_{lm} , respectively). The sensitivity of the mean (across all 20 parameter vectors) North American ice volume to the earth rheology is generally small. The largest differences occur between 60 and 40 kyr BP, with a maximum difference of $0.3 \cdot 10^7 \text{ km}^3$ at ~ 50 kyr BP (Fig. S35). Similarly, the surge characteristics show minor sensitivities to a change in the earth rheology. However, a thinner Lithosphere and a smaller upper mantle viscosity tend to favour shorter surges (Fig. S36).

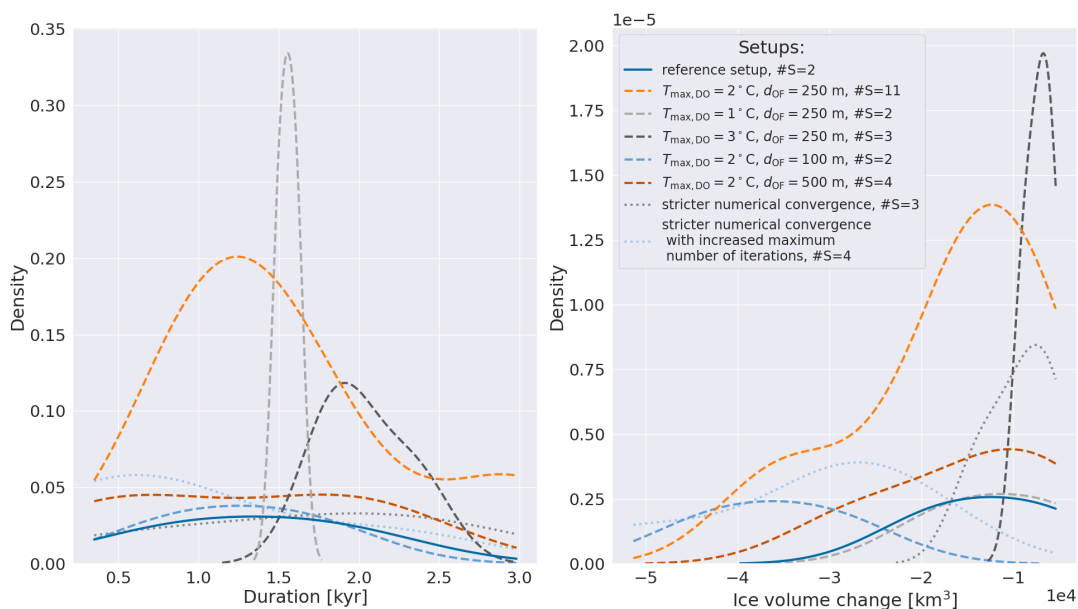


Figure 14. Kernel density plot for the ≤ 2 #surges sub-ensemble. The reference and MNEEs setups do not use an additional ocean forcing. #S indicates the total number of surges across all runs of the sub-ensemble.

The number of surges in runs with ≤ 2 surges (≤ 2 #surges sub-ensemble) increases significantly for all experiments with local GIA (a damped-return to isostatic equilibrium with relaxation time constant $\tau = [3, 4, 5]$ kyr) and without GIA (Fig. 16). This is likely due to a smaller North American and Hudson Strait ice volume and the resulting change in basal temperature (e.g., Fig. S37). The larger ice sheet in the reference setup (global GIA) leads to more stable basal temperatures and a continuously active Hudson Strait ice stream. On the other hand, the smaller ice sheet in runs with local GIA and without GIA leads to colder basal temperatures, reduced Hudson Strait warm-based area (Fig. S38), and at times complete de-activation of the Hudson Strait ice stream. As described in Sec. 3.1, this de-activation eventually leads to a surge.

For the > 2 #surges sub-ensemble, using local GIA leads to a similar response as completely deactivating GIA, except for the number of surges. The number of surges increases without GIA and decreases for all local GIA models, but the differences are smaller than the MNEEs (Fig. 6). The different response is caused by a change in ice configuration. For example, local GIA ($\tau = 4$ kyr) significantly reduces Hudson Strait ice volume before 80 kyr BP, leading to a smaller but more stable warm-based area (e.g., no rapid changes due to advection of cold ice) and consequentially a continuously active ice stream instead of activation/de-activation cycles (Fig. S39). Therefore, a change in ice stream behaviour can be caused by differences in Hudson Strait basal temperature due to glacial isostatically driven ice volume changes (e.g., decreased insulation due to a thinner ice sheet). The mean period, duration, increase in Hudson Strait ice flux, and mean ice volume change show an increase for experiments with local and without GIA, but most differences are smaller than the MNEEs.

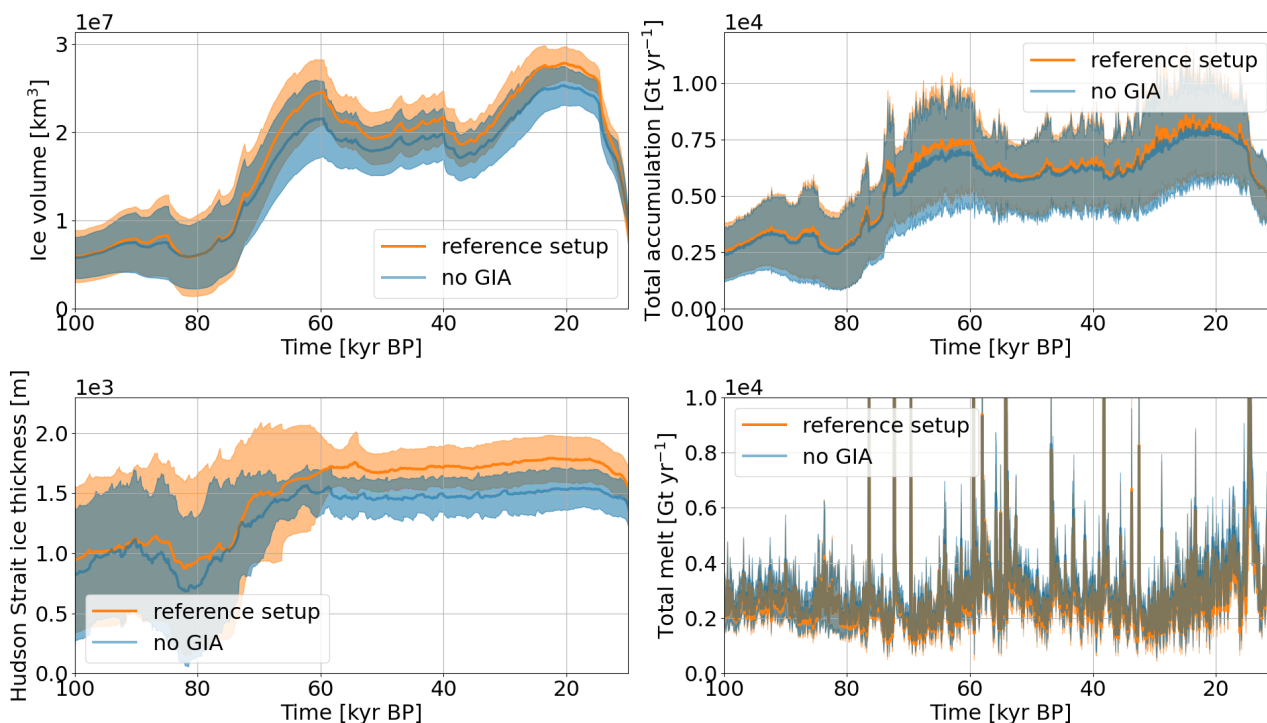


Figure 15. Ice sheet volume, total ice sheet accumulation, Hudson Strait ice thickness (Hudson Strait mask outlined in Fig. 2), and total ice sheet melt for the reference setup (global GIA model) and runs without GIA. The thick lines and shaded areas represent the mean and mean±standard deviation of 18 runs, respectively (the runs for parameter vectors 8 and 15 crashed in the comparison setup and were not included).

In summary, the GIA experiments with the default GHF indicate that the occurrence of Hudson Strait ice stream surges is sensitive to the overall North American ice configuration. The surge characteristics, however, show only minor changes. In contrast, the experiments with local GIA and without GIA lead to more significant changes for the classic binge-purge surge mode (Fig. S16 and S17). The surge duration decreases, while the number of surges, increase in mid-Hudson Strait ice flux, and Hudson Strait ice volume change increase. The different model response for high and low GHFs is due to the differences in thermal conditions at the ice sheet base (e.g., Fig. S13).

4 Discussion

Q₁ What are the characteristics of Hudson Strait ice stream surges and how do they depend on the geothermal heat flux and basal drag law?

The surge characteristics are sensitive to the applied GHF and sliding law. Use of either a regularized Coulomb sliding law (Eq. 5) in combination with the default Weertman-type power law (Eq. 1 and 6) or a lower GHF each lead to a

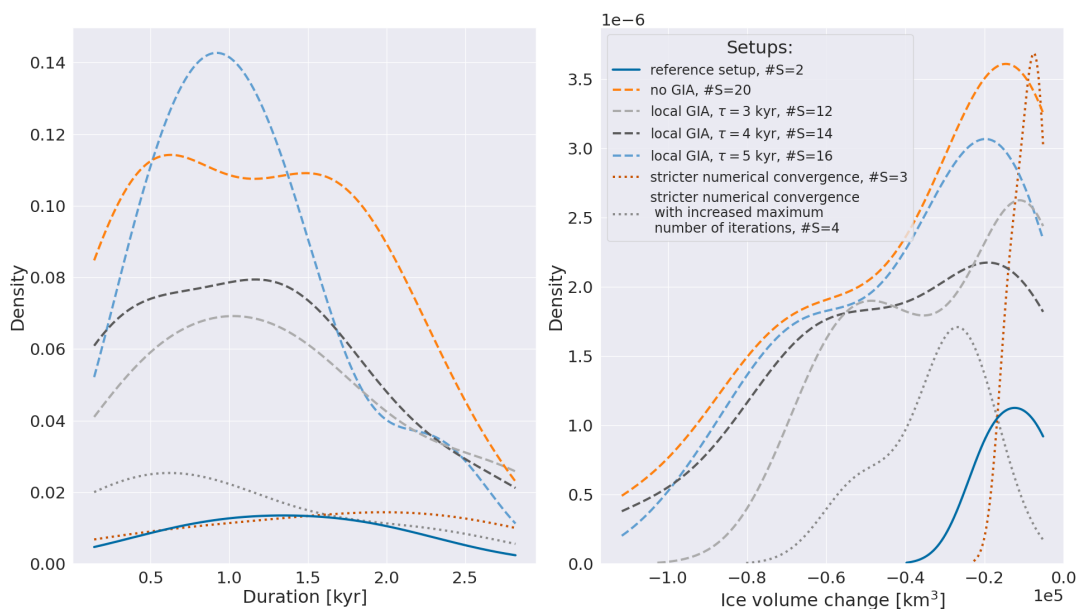


Figure 16. Kernel density plot for the ≤ 2 #surges sub-ensemble. The reference and MNEEs setups use a global GIA model. #S indicates the total number of surges across all runs of the sub-ensemble.

similar shift in surge mode (from nearly continuous Hudson Strait ice streaming to long quiescent periods interspersed with short surges) and surge characteristics (more surges, shorter duration, larger increase in mid-Hudson Strait ice flux, Table 2).

For the default GHF input field and Weertman-type power law, the Hudson Strait ice stream is almost continuously active throughout the last glacial cycle. Surges occur after a short quiescent period or as an increase above the background ice flux. Furthermore, the strongest surges (preceded by a complete de-activation of the Hudson Strait ice stream) occur before MIS3. While there is evidence for pre-MIS3 HEs (e.g., Table 6.3 in Bradley, 2014), HEs are usually associated with MIS3. The limited number of strong surges within MIS3 is a consequence of increased basal temperatures (increased insulation due to a thicker ice sheet), leading to a continuously active ice stream (no ice build-up before surge).

Geothermal heat flux

Decreasing the GHF in Hudson Bay/Hudson Strait below $\sim 37 \text{ mW m}^{-2}$ leads to a surge mode consistent with the originally proposed binge-purge mechanism (long quiescent periods interspersed with short surges, MacAyeal, 1993). Depending on the parameter vector, the surges can now occur continuously between ~ 110 and ~ 10 kyr BP (surges before 100 kyr BP are not considered in the surge characteristics). Critically, the binge-purge mode increases the number of strong surges during MIS3 (compared to the near continuous ice streaming mode), which is more in accord with the timing of Heinrich Layers in sediment cores (e.g., Hemming, 2004).



515 During a surge, both low and high GHF scenarios lead to a Hudson Strait ice flux and ice volume discharge consistent with literature estimates (Roberts et al., 2014, and references therein). As HEs are identified by IRD layers, the applied GHF must enable the entrainment of enough sediment. However, depending on the mechanism considered, sediment can be entrained for a cold-based (e.g., Meyer et al., 2019) as well as warm-based Hudson Bay/Hudson Strait (Drew, 2023). What ultimately controls the sediment discharge during a surge is the sediment availability. Furthermore, depending on the study and method used, GHF estimates in Hudson Bay and Hudson Strait vary between 20 and 80 mW m⁻² (e.g., Pollack et al., 1993; Shapiro and Ritzwoller, 2004; Blackwell and Richards, 2004; Davies, 2013; Lucazeau, 2019). 520 Therefore, both surge modes occur within GHF constraints and are consistent with proposed sediment entrainment mechanisms.

525 When using the default GHF, the GSM temperatures in the bed are colder or similar to borehole measurements south of Hudson Bay (Fig. S40 and S41). While these boreholes indicate a negative GHF gradient toward the North and older bedrock material tends to be colder (less radioactive decay), no deep boreholes are available in Hudson Bay and Hudson Strait. Therefore, better constraints on the GHF in Hudson Bay and Hudson Strait as well as inclusion of a fully coupled sediment model are required to better determine the most likely surge mode.

Basal sliding law

530 Similar to the effects of a lower GHF in Hudson Strait and Hudson Bay, using a regularized Coulomb sliding law leads to a shift to the binge-purge mode and a large increase in surges, including the number of strong surges during MIS3. While the increase in mid-Hudson Strait ice flux and Hudson Strait ice volume change during a surge are within literature estimates (Roberts et al., 2014, and references therein), the large increase in the number of surges and, therefore, the shorter periods are not (Table 1 and 2). This is in contrast to the lower GHF ensembles, rendering the regularized Coulomb sliding law experiments a less likely representation of the binge-purge mode.

535 *Q₂ Can the sudden reduction of the buttressing effect of ice shelves trigger Hudson Strait ice stream surging?*

540 In line with both proxy data indicating ice shelf free conditions during most of the last glacial cycle (Hillaire-Marcel et al., 1994; Hesse et al., 1999; De Vernal et al., 2000; Gibb et al., 2014) and other modeling studies (Schannwell et al., 2023), there is no significant Labrador Sea ice shelf in the GSM runs. This conclusion still holds even when running the GSM with a full North American and Greenland ice sheet configuration (instead of just the stub North-West Greenland shown in Fig. S1).

The relatively small ice shelves in front of the Hudson Strait terminus provide only minor buttressing and are barely affected by the applied ocean temperature forcing. Reducing the ocean temperature by -2°C leads to minor ice shelf growth. Even when completely inhibiting calving in front of Hudson Strait, not all parameter vectors yield ice shelves large enough to be buttressed against Greenland.



545 Ice shelf collapse in runs that have large ice shelves does lead to minor increases in mid-Hudson Strait ice flux. Our overall results indicate that buttressing ice shelves are likely not the main trigger of Hudson Strait ice stream surging but, depending on the parameter vector, can affect the timing of surges.

This is in contrast to the findings of Alvarez-Solas et al. (2013, Hudson Strait surge induced by collapse of buttressing ice shelf), which use fixed glacial climatic boundary conditions except for changes in the sub-surface ocean temperature. 550 However, the ice shelf in their simulation covers the entire area between Hudson Strait and Greenland, significantly increasing the buttressing and enabling a larger Hudson Strait ice volume (larger surges when removing the buttressing). As discussed above, this scenario is inconsistent with available marine records. Furthermore, this scenario is not supported by the bounding experiments within this study, especially given the range of sub-shelf melt rates across the ensemble.

555 *Q₃ Can a sudden breakup of fringing ice shelves along the Canadian coast explain the IRD records (without the need for surges)?*

Based on assumptions about the terrigenous material transported by floating ice during HEs (100 km³, Alley and MacAyeal, 1994), the debris concentration in basal glacier ice (5 to 35 %, Lawson et al., 1998), and the accreted ice thickness (1 % of total ice thickness), Hulbe et al. (2004) estimate that a minimum ice shelf volume of 2.8 · 10⁴ to 560 20 · 10⁴ km³ is required to explain the IRD records by disintegration of fringing ice shelves. The maximum Labrador sea ice shelf volume across all reference runs is 2.5 · 10⁴ km³ (12.6 · 10⁴ km³ when calving is completely inhibited in the *ocean forcing area* outlined in Fig. 2). Therefore, it is unlikely that the IRD layers found in the North Atlantic are solely a consequence of ice shelf disintegration. However, this conclusion neglects potential contributions of other source regions with similar geological material, such as the Boothia ice stream (Sanford and Grant, 1998; Hulbe et al., 2004; 565 Naafs et al., 2013). Future work, e.g. ice sheet modeling with a fully coupled sediment model, is required to determine the contributions of individual source regions.

Q₄ How does sub-surface ocean warming affect HEs?

In the idealized setup of Bassis et al. (2017), grounding line retreat driven by underwater melt and, in turn, modulated by GIA leads to pseudo-Hudson Strait surges. Although not exactly replicating the experiments of Bassis et al. (2017), 570 we examine the effect of sub-surface ocean warming in a HE context by applying sub-surface ocean forcings of different magnitudes at varying depths. In general, applying a similar sub-surface ocean forcing in the GSM does not significantly affect the surge characteristics and does not trigger new Hudson Strait surges. However, it can affect the timing of Hudson Strait surges. Depending on the melt coefficients and the ocean temperature (Sec. 2.5), sub-marine melt can reach up to 400 m yr⁻¹ in our simulations, indicating that the minor model response concerning surges is not an issue of insufficient sub-shelf melt. The different model response is likely a consequence of the less idealized model setup and the large 575 variety of physical system processes affecting the surges in the GSM that are not present in the modeling of Bassis et al. (2017, such as their lack of ice thermodynamics). Different implementations of GIA and calving along with different grid resolutions further contribute to the different results.



Q₅ What is the role of GIA in a HE context?

580 GIA leads to lower ice sheet surface elevations, increased accumulation, and consequently, larger ice sheets (Fig. 15).
The reduction in overall North American and Hudson Strait ice volume when using a local or no GIA model leads to, on
average, lower basal temperatures (Fig. S38) and fosters surges in runs that otherwise show a continuous Hudson Strait
ice stream.

585 Analyzing the surge characteristics with the default GHF shows a tendency towards longer and stronger surges for local
or no GIA. The differences are caused by the change in ice configuration but are generally on the same order of magnitude
as the MNEEs. Changes in the earth rheology used by the global GIA model have minor impact.

The classic binge-purge surge mechanism in the low GHF experiments is more sensitive to GIA. Due to the different
thermal conditions at the ice sheet base, the experiments with local or without GIA now lead to shorter but stronger
surges.

590 Due to its effect on the overall North American ice volume, the consequential change in basal temperatures in Hudson
Strait, and the limited range of ice sheet configurations for which Hudson Strait ice stream surges occur, global GIA plays
a critical role in modeling ice stream activation/de-activation cycles. These results are especially relevant for interpreting
HE modeling experiments that do not use a physically-based GIA scheme.

5 Conclusions

595 Within this study, we investigate Hudson Strait ice stream surges and determine the role of geothermal heat flux (GHF), basal
sliding laws, ice shelves, glacial isostatic adjustment (GIA), and sub-surface ocean temperature forcings in a HE context. The
model results are based on the first HE simulations with transient last glacial cycle climate forcing, global visco-elastic glacial
isostatic adjustment model, sub-glacial hydrology model, and high-variance sub-ensemble retrieved from North American
history matching for the last glacial cycle.

600 Consistent with proxy records, no large ice shelves develop in the Labrador Sea (unless extreme calving restrictions are
applied), leading to minor buttressing effects. Even when completely inhibiting calving in the Labrador Sea, the collapse
of large ice shelves leads to only a minor increase in mid-Hudson Strait ice flux. Except for the exact timing of surges, sub-
surface ocean warming does not significantly affect the surge characteristics. Due to its significant effect on the overall ice sheet
configuration, GIA can increase the number of Hudson Strait surges but does not significantly affect the surge characteristics.

605 Based on our results, Hudson Strait ice stream surge cycling is the most likely Heinrich Event mechanism, but ocean forcings
can affect the timing of surges and provide a means to synchronize HEs with the coldest phases of the Bond cycles. However,
the surge pattern is highly sensitive to the basal sliding law and the GHF in Hudson Bay and Hudson Strait. The GHF estimates
for this region vary by a factor of 4. While better constraints on the GHF are essential to determine the likelihood of the classic
binge-purge mechanism compared to a near continuous ice stream with pre-Heinrich Event shutdowns, the increased number
610 of strong surges during MIS3 in the binge-purge mode suggests that the deep GHF for Hudson Bay and Hudson strait is under



35 mW m^{-2} . Using a regularized Coulomb sliding law also leads to a shift to the binge-purge mode and increases the number of strong surges during MIS3. However, the overall large increase in surges leads to periods well below those inferred for HEs. In contrast, the period and duration of the reference and low GHF setup are in agreement with literature estimates.

615 A key caveat is the usual assumption that IRD flux is approximately proportional to ice flux (be it from Hudson Strait ice stream surge cycling or collapsing ice shelves). A follow-up submission with a fully coupled sediment model will evaluate the correlation between ice and sediment discharge and better link the glacial processes examined here to the IRD layers.

620 *Code and data availability.* Data is available upon request from the corresponding author. After acceptance for publication in CP, an archive of a representative sample of simulation output will be made available in a public archive. A recent version of the GSM code (as used for Hank et al., 2023) is available at <https://doi.org/10.5281/zenodo.7668472> (Tarasov et al., 2023). A description of the current version of the GSM will soon be submitted to GMD with a complete code archive.

Video supplement. Supplementary videos are available online at: <https://doi.org/10.5281/zenodo.10214928> (Hank, 2023).

625 *Author contributions.* KH prepared the experimental design, ran the model, and analyzed the results. Both authors contributed to the interpretation of the results and writing of the paper. LT provided the source parameter vector ensemble.

Competing interests. The authors have no competing interests.

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630 records in a Heinrich Event context.



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