Analysis of a saline dust storm from the Aralkum Desert - Part 1: Consistency between multisensor satellite aerosol products

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Abstract. The Aralkum Desert poses a challenging environment for satellite aerosol retrieval due to its heterogeneous and dynamic surfaces and the lack of in situ constraints on region-specific aerosol properties. This study first surveys current satellite algorithms capable of detecting the dust presence, column burden, and vertical height over the Aral Sea basin, and documents the globally optimized algorithm assumptions on surface and aerosol properties that may contribute to inconsistent retrievals and misrepresent local conditions. Aerosol product inconsistencies and potential biases are further assessed via detailed comparisons of multiple UVAI, midvisible and thermal-infrared AOD, and ALH products in characterizing a saline dust event from Aralkum. The results indicate that: (1) UVAI products consistently delineate the dust plume extent when differences in dynamic range are accounted for. All products show large positive values over the Garabogazköl Gulf and northern Caspian Sea, due to absorption by shallow and turbid waters, highlighting the limitation of UVAI for dust detection over dry or ephemeral lakes. (2) Midvisible aerosol products from MODIS and VIIRS show strong agreement in total and coarse-mode AOD retrievals over the Caspian Sea, despite using different aerosol optical models. Over desert surfaces, all operational products misclassify fresh dust plumes as clouds and exhibit strong non-linear relationships in AOD retrievals. The NOAA EPS product retrieves significantly lower AOD than others, although the agreement improves when a dust optical model is used for retrieval. The MISR research algorithm produces higher, more consistent AOD and improved particle property retrievals compared to the MISR operational product. (3) Among four IASI infrared products, the LMD algorithm performs

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best in detecting dust plume features over both desert and water surfaces. (4) The EPIC AOCH product overestimates dust layer altitude in clean or low-AOD conditions, but exhibits good agreement with CALIOP in detecting elevated dust layers with well-defined upper boundaries. MISR height retrievals also align well with CALIOP and EPIC. On average, IASI infrared ALH retrievals over dust scenes are 0.4 km higher than EPIC. This study underscores the important insight of a synergistic, multisensor approach into the complementary strengths and potential biases of aerosol products, and calls for their appropriate application and careful interpretation when characterizing saline dust from the Aralkum Desert.

1 Introduction

Emerging from the desiccated basin of the former Aral Sea, the Aralkum Desert has evolved into one of the most active sources of wind-blown dust, with adverse impacts on biodiversity, agriculture, and human well-being across Central Asia (Orlovsky and Orlovsky, 2001; Xi and Sokolik, 2016). Aralkum stands out among the extensive dust sources in Asia, not only because of its anthropogenic origin but also due to the distinct chemical and mineralogical compositions of its erodible sediments. Figure 1 shows the spectral abundance of four mineral groups derived from the Earth Surface Mineral Dust Source Investigation (EMIT) instrument. EMIT reveals that Aralkum contains more abundant carbonate and sulfate minerals, but less iron oxides and clays than the nearby Karakum and Taklamakan deserts. Groll et al. (2019) confirmed that dust samples collected near Aralkum contained considerably higher sulfate and chloride content than those from sandy deserts. Given its distinct mineralogical compositions, Aralkum dust is expected to be more hygroscopic and less light-absorbing than typical desert dust (Sokolik and Toon, 1999). Indeed, ground lidar measurements in Tajikistan reported significantly lower extinction-to-backscatter or lidar ratios (23 sr at 532 nm) for salt dust compared to typical desert dust (44±9 sr) (Hofer et al., 2017).

Even within the desiccated Aral Sea bed, there is substantial variability in the physiochemical properties of erodible sediments. As the Aral Sea continued shrinking, sediment grain size became progressively smaller towards the basin's lowest point, while evaporate minerals began to precipitate following a typical sequence of calcite, gypsum/anhydrite, halite, and finally potassium and magnesium salts. Consequently, distinct spatial gradients in mineralogy, grain size, and soil texture have been observed in the exposed sediments. For instance, Jiang et al. (2021) reported increasing abundances of clay and evaporites minerals but decreasing abundance of carbonates and organic carbon, when moving from the older coastline towards the newly exposed seabed. Argaman et al. (2006) found that the highly erodible takyr soils dominate the outer rim of Aralkum, whereas the newly formed solonchak soils are more likely protected by salt crusts which create stable, coarse aggregates that are resistant to wind erosion.

Assessing the impacts of Aralkum-generated saline dust is greatly hindered by lack of in situ measurements of the physical and chemical properties of the erodible sediments (e.g., soil texture, mineralogical composition, crusting), and airborne particles (e.g., particle size distribution, shape, nonsphericity, chemical composition, mixing state, solubility). Particularly, the global network of ground-based sun/sky photometers, AERosol RObotic NETwork (AERONET), has no operating sites near Aralkum. The two operational sites in Central Asia—Issyk-Kul and Dushanbe—are located too far away to provide representative measurements of the saline dust from Aralkum (Semenov et al., 2005; Rupakheti et al., 2020). AERONET serves two

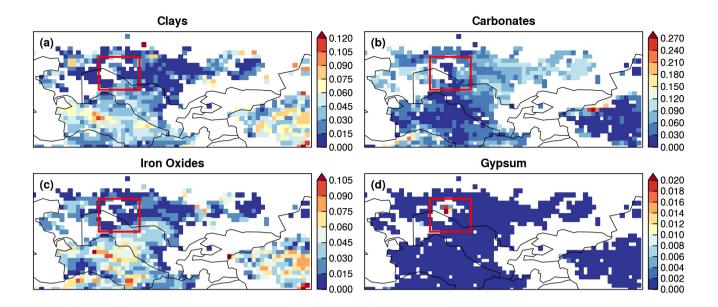


Figure 1. Aggregated spectral abundance of four mineral groups based on the Earth Surface Mineral Dust Source Investigation (EMIT) L3 product: (a) Clays (including chlorite, illite, muscovite, kaolinite, montmorillonite and vermiculite); (b) Carbonates (calcite and dolomite); (c) Iron Oxides (goethite and hematite); and (d) Gypsum. Boxed regions indicate the Aralkum Desert. Note that panel (d) uses a different color scale from others.

important purposes. First, it provides the climatological aerosol information needed to specify season- and region-dependent aerosol optical models used in passive satellite retrieval algorithms (Dubovik et al., 2002). Second, AERONET measurements are used as benchmark for validating satellite retrievals. Consequently, the a priori assumptions about aerosol microphysical properties in satellite algorithms may not accurately capture the distinct particle properties over Aralkum. The lack of ground truth also prevents an evaluation of satellite product performance for the region. In general, satellite algorithms are optimized for global performance, but may exhibit significant local biases when the local prevailing aerosol conditions deviate substantially from the algorithm assumptions on particle microphysical properties.

Dust event monitoring has relied on satellite retrievals over ocean basins frequently affected by continental dust outflow. For dust sources located deep within continental interiors, observing airborne dust from space is more challenging due to difficulty in separating the surface contribution from the top-of-the-atmosphere (TOA) radiance measurements. Central Asia comprises a range of dust sources with varying sediment abundance and erodibility, including sandy and hilly deserts, desert steppes, salt flats, and ephemeral or dry lakes (Xi and Sokolik, 2015a, b). These regions feature heterogeneous, dynamic surface properties and conditions (e.g., reflectivity, emissivity, land/water boundary, water turbidity), posing a major challenge for isolating aerosol signals from surface contributions. Currently, a number of techniques have been developed to facilitate aerosol retrievals over desert surfaces. However, data users may struggle with the product choice, not knowing the strengths and limitations of each product for their specific area of interest. To date, the performance of satellite aerosol products for

5 characterizing the Aralkum dust aerosol is poorly understood. It is also unclear whether these products are consistent with each other. In this regard, a multisensor approach is preferred over the use of a single product, and may provide potential insights about satellite product performance through the synergy of different observation techniques.

During 27–29 May 2018, a saline dust storm was triggered from the Aralkum Desert by an cold air outbreak, causing persistent haze, record high particulate concentrations, and salt deposition on agricultural areas (Xi, 2023). This manuscript documents the first part of a detailed investigation of this event, focusing on the consistency and synergy of multisensor aerosol products. A companion paper will focus on the large-scale atmospheric dynamics and model simulations of the event. In this paper, we first conduct a survey of current satellite techniques and algorithms capable of detecting the presence, column burden, and vertical height of airborne dust over the Aral Sea basin (Section 2). The survey focuses on the theoretical basis and a priori assumptions about aerosol and surface properties associated with satellite retrievals of Ultraviolet Aerosol Index (UVAI), midvisible and thermal-infrared Aerosol Optical Depth (AOD), and Aerosol Layer Height (ALH). In Section 3, we compare multiple UVAI, AOD (at both 0.55 and 10 μ m), and ALH products to investigate the cross-sensor and cross-algorithm consistency in observing the saline dust from Aralkum on 27–29 May 2018. To avoid confusion, we will refer to the midvisible $(0.55 \mu m)$ AOD simply as AOD, while specifying the wavelength as a subscript for other cases, e.g., AOD₁₀ for 10 μm AOD and $AOD_{0.68}$ for $0.68 \mu m$ AOD. Due to lack of validation data, we focus on assessing the consistency (or lack thereof) between different products rather than their performance or accuracy. Through a synergistic analysis of multisensor satellite products, we aim to highlight the complementary strengths of various techniques, uncover their inconsistencies and limitations, and emphasize the need for their appropriate application and interpretation over the Aralkum Desert. Section 4 summarizes the findings of this study.

2 Overview of Satellite Aerosol Retrievals over Deserts

85 **2.1** UVAI

UVAI was first discovered as a spectral residual quantity in the near-UV (330–380 nm) which measures the departure of observed spectral contrast from that of a pure molecular atmosphere (Herman et al., 1997). Significant changes in the spectral dependence of backscattered UV radiances were frequently associated with the presence of absorbing aerosols, such as dust, carbonaceous aerosols, and volcanic ash. This phenomenon provides a physical basis for UVAI, which yields large positive values for absorbing aerosols over ocean and land (including deserts and snow/ice-covered surfaces), as well as above clouds. This makes UVAI an excellent tracer for airborne dust (Prospero et al., 2002). Compared to a pure molecular atmosphere, dust particles reduce the spectral contrast of backscattered UV radiances by absorbing the Rayleigh scattered radiation from beneath the dust layer (Torres et al., 1998; de Graaf et al., 2005). UVAI depends on multiple factors—including AOD, ALH, absorption properties, and surface reflectivity—with higher ALH or more absorbing particles leading to larger UVAI (de Graaf et al., 2005).

In addition to absorbing aerosols, large positive UVAI may also result from non-aerosol geophysical effects such as sun glint, ocean color, and strong wavelength dependence of surface reflectivity (Herman et al., 1997). These effects, if misinterpreted as aerosol signals, can introduce biases in dust detection.

In the original UVAI definition, water clouds were treated as part of a spectrally independent Lambertian Equivalent Reflector (LER), resulting in small negative UVAI values. Torres et al. (2018) introduced a new approach that explicitly accounts for the Mie scattering effects of water clouds. This Mie-based approach yields near-zero UVAI over clouds, and exhibits a weaker angular dependence than the LER-based definition. Multidecadal UVAI records have been generated from spaceborne UV-visible spectrometers. In this study, we compare the UVAI products from Ozone Mapping and Profiler Suite (OMPS), TROPOspheric Monitoring Instrument (TROPOMI), and Earth Polychromatic Imaging Camera (EPIC), described below.

105 **2.1.1 OMPS**

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The OMPS Nadir Mapper is an imaging spectrometer onboard the Suomi National Polar-orbiting Partnership (SNPP) space-craft in a sun-synchronous orbit with an ascending node equatorial crossing time of 13:30. OMPS measures UV radiances from 300 to 380 nm with a nadir footprint of 50×50 km² and 110° across-track field of view, equivalent to a ground swath of 2800 km. The OMPS Nadir Mapper aerosol algorithm (NMMIEAI) reports the Mie-based UVAI at the 340/378.5 nm wavelengths (Torres, 2019a).

2.1.2 TROPOMI

TROPOMI is a nadir-viewing, push-broom-type grating spectrometer onboard the Copernicus Sentinel 5 Precursor (S5P) mission, which flies in close formation with SNPP (less than 5 min apart) in a sun-synchronous orbit with an ascending node equatorial crossing time of 13:30 (Veefkind et al., 2012). TROPOMI measures reflected and emitted radiation from the UV to shortwave infrared (SWIR) with a nadir footprint size of 3.5×7 km² and a 2,600 km swath width.

There are two separate UVAI products from TROPOMI, one developed by ESA (European Space Agency), and the other developed by NASA. The NASA version uses the TropOMAER algorithm which reports both LER- and Mie-based UVAI at 354/388 nm (Torres, 2021). The ESA version reports LER-based UVAI at three wavelength pairs: 354/388, 340/380, and 335/367 nm (Stein Zweers, 2022). The first two pairs were selected to continue the multidecadal heritage UVAI records, while the 335/367 nm pair was added to ensure compatibility with the future UVAI algorithm planned for the Sentinel-5 mission.

2.1.3 EPIC

EPIC is an imaging spectroradiometer onboard the Deep Space Climate Observatory (DSCOVR) spacecraft, which operates in a Lissajous orbit about Lagrange-1 point in the Earth-Sun system. This allows EPIC to view the sunlit disk of Earth every 60–100 minutes. EPIC measures reflected radiances in 10 channels from UV to near-infrared (NIR), with a ground resolution of 8 km at 443 nm and 16 km in other bands. The EPIC EPICAERUV algorithm reports both LER- and Mie-based UVAI at the 340/388 nm wavelengths (Torres, 2019b).

2.2 Midvisible AOD

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Inferring column-integrated aerosol properties from reflected visible-NIR observations is an ill-posed inverse problem due to limited information content to fully characterize the atmosphere-surface system. Midvisible AOD is generally the most readily-available parameter, and consequently algorithms must rely on a priori knowledge or assumptions of the aerosol size distribution, shape, and refractive index (known as aerosol optical models). A common strategy involves using radiative transfer codes to create look-up tables (LUTs) of TOA radiances for a set of predefined aerosol optical models, surface types, and solar/viewing geometries (e.g., Remer et al., 2013a). These LUTs are then used to match with measured TOA reflectances to derive optimal estimates of AOD and, in some cases, additional aerosol properties related to particle size and absorption. Aerosol retrieval using this strategy is highly sensitive to the aerosol optical models that are predefined in the algorithm and selected during the retrieval. Although these aerosol models are designed to represent season- and location-specific aerosol conditions as realistically as possible, satellite algorithms may still incorporate inconsistent or even contradictory models, especially for regions like Central Asia due to lack of observational constraints. In addition, satellite algorithms may fail to select the appropriate model during the retrieval, leading to mismatch between the assumed aerosol properties and the actual aerosol conditions. These factors can contribute to inconsistencies between retrieved AODs, including those from the same instrument.

We compare multiple AOD products from three polar-orbiting instruments onboard NASA's EOS and NOAA's JPSS satellites, including the Moderate Resolution Imaging Spectroradiometer (MODIS), Multi-angle Imaging Spectroradiometer (MISR), and Visible Infrared Imaging Radiometer Suite (VIIRS). MODIS and VIIRS employ three single-view aerosol algorithms—Dark Target (DT), Deep Blue (DB), and Enterprise Processing System (EPS)—and the time series-based Multi-Angle Implementation of Atmospheric Correction (MAIAC) algorithm. MISR utilizes two algorithms: an operational standard algorithm for generating routine global aerosol records, and a research algorithm designed to explore alternative retrieval methods and additional aerosol properties on a case-by-case basis.

Below, we briefly describe the MODIS, VIIRS, and MISR aerosol algorithms, focusing on the a priori assumptions about aerosol optical models and surface reflectances. Other algorithm components (e.g., screening of clouds/sun glint/snow, spectral fitting) are not discussed.

2.2.1 MODIS and VIIRS DT over-water algorithms

The DT algorithm includes different approaches for over-land and over-water retrievals. We focus on the over-water algorithm which is well suited for retrieving dust properties over the Caspian Sea. DT exploits the contrast of reflective aerosol layers against a dark background in the visible spectrum. Over water, the algorithm searches the LUT for the best fit of measured TOA reflectances at seven window bands from visible to SWIR, and obtains solutions for both AOD and fine mode fraction (FMF) (Tanré et al., 1997). The ambient aerosol scene is represented as a linear combination of one fine and one coarse mode weighted by FMF. DT considers nine aerosol optical models over water: four fine aerosol models, three sea salt models, and two coarse dust models, which are derived from long-term AERONET measurements near water bodies (Remer et al., 2005).

Each optical mode comprises spherical particles, with the main difference between the sea-salt and dust modes being the assumed complex refractive index. During the retrieval the algorithm evaluates each of the 20 combinations of fine and coarse modes, and addition to AOD and FMF, reports which combination of modes led to the best fit. Due to the nonsphericity of dust particles, the current DT algorithm is known to yield biased retrievals over dusty oceanic scenes (Zhou et al., 2020b). A spheroidal dust model will be implemented in the MODIS Collection 7 as well as future versions of VIIRS (Zhou et al., 2020a).

In the MODIS product suite, DT aerosol retrieval is performed at a nominal resolution of $10\times10 \text{ km}^2$. A higher-resolution product (DT3K) was later introduced at $3\times3 \text{ km}^2$ to capture small-scale aerosol features (Remer et al., 2013b). DT3K employs the same technique as DT, but using different pixel aggregation and quality assurance (QA) rules. The DT algorithm has been ported to VIIRS, which retrieves AOD at a nominal resolution of $6\times6 \text{ km}^2$ (Sawyer et al., 2020).

2.2.2 MODIS and VIIRS DB algorithms

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Inspired by the aerosol detection capability in the near-UV, the DB algorithm employs the 0.41 μ m or "deep blue" band, which has lower and more homogeneous surface reflectivity than the longer visible wavelengths (Hsu et al., 2004). Aerosols are represented by a spheroidal dust model and a spherical fine-dominated anthropogenic model, which employ various SSA values depending on locations and seasons. The surface reflectances are determined based on a pre-calculated database over bright surfaces (e.g., deserts, urban areas), and empirical relationships between visible and SWIR bands over vegetated surfaces (Hsu et al., 2013).

DB was initially implemented to fill the data gap over bright surfaces in the MODIS aerosol product. In the VIIRS product suite, DB has been expanded to all cloud-, snow- and ice-free land surfaces, and also performs retrieval over water using the Satellite Ocean Aerosol Retrieval (SOAR) algorithm (Hsu et al., 2019; Lee et al., 2024). SOAR considers four aerosol optical models: maritime, dust, fine-dominated, and mixed, each represented by a bi-modal distribution consisting of one fine and one coarse mode (Sayer et al., 2018). The dust model consists of one spherical fine mode and one spheroidal coarse mode, derived from AERONET measurements at Cape Verde (Lee et al., 2017).

2.2.3 VIIRS EPS algorithm

The EPS algorithm is developed for NOAA's next-generation polar-orbiting and geostationary meteorological satellites. Here we focus on the VIIRS EPS aerosol product described in Laszlo (2018) and more recently Laszlo and Liu (2022). Over water, EPS is based on the MODIS heritage and represents the aerosol column as a linear combination of one fine and one coarse mode weighted by FMF, selected from four fine-mode and five coarse-mode aerosol models same as the MODIS DT algorithm (Remer et al., 2006). The algorithm searches for the AOD and FMF that give the best match between observed and pre-calculated TOA reflectances at seven VIIRS channels (Jackson et al., 2013; Laszlo and Liu, 2022).

Over land, EPS simultaneously retrieves AOD, aerosol optical model, and Lambertian surface reflectances in selected bands, by matching the observed and calculated TOA reflectance over both dark and bright (snow-free) surfaces. EPS considers four candidate aerosol optical models, of which three are spherical, fine-mode dominated aerosols (labeled as generic, urban, and smoke), and one is non-spherical, coarse-mode dominated aerosol (labeled as dust). The dust model is forcibly used for North

Africa and the Arabian Peninsula to account for the dominant dust presence in these regions. The candidate aerosol models are adopted from the MODIS Collection 5 DT algorithm (Remer et al., 2006). Over bright desert surfaces, the surface reflectance is estimated from a static database of spectral reflectance ratios between VIIRS channels (Zhang et al., 2016).

2.2.4 MODIS MAIAC algorithm

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Unlike the single-view approach adopted by DT, DB and EPS algorithms, MAIAC uses a sliding window to accumulate up to 16 days of multi-angle observations from different orbits for the same location to retrieve bidirectional surface reflectance over land (including deserts) simulataneously with aerosol properties (Lyapustin et al., 2018). MAIAC uses a dynamic minimum reflectance method to define the surface reflectance spectral ratios for each 1 km grid cell, which allows AOD retrieval over both dark and bright surfaces. The MODIS Collection 6 MAIAC algorithm uses nine aerosol optical models derived from AERONET climatology to represent the regional background aerosol conditions. For Central Asia, the background aerosol model ("Model 2") is derived from AERONET measurements over the western U.S., which represents a mixture of dust and fine mode aerosols. During the retrieval, a smoke/dust test is first applied to determine whether the background or dust model should be used. If dust is detected, the algorithm uses a spheroidal dust model ("Model 6") derived from AERONET measurements from the Solar Village site in Saudi Arabia (Dubovik et al., 2006).

2.2.5 MISR AOD and particle property algorithms

MISR measures reflected sunlight using nine push-broom cameras with view angles of $\pm 70.5^{\circ}$, $\pm 60.0^{\circ}$, $\pm 45.6^{\circ}$, $\pm 26.1^{\circ}$, and 0° along-track, each in four spectral bands (446, 558, 672, and 866 nm) across a 380 km swath at pixel-resolution between 275 m and 1.1 km, depending on the channel (Diner et al., 1998). The MISR Standard Aerosol retrieval algorithm produces AOD and constraints on column-effective particle type operationally (Garay et al., 2020). The aerosol column is represented by 74 aerosol optical models as mixtures of single-composition components, including 50 mixtures of spherical components, 20 mixtures of spherical and dust components, and 4 mixtures of dust components. The algorithm accounts for the contribution of surface bidirectional reflectance factor (BRF) based on a principal component analysis of TOA radiances (Martonchik et al., 2009).

The MISR Research Aerosol (RA) retrieval algorithm is optimized to provide constraints on particle size, sphericity, and light-absorption under favorable observing conditions on a case-by-case basis (Limbacher et al., 2022). The algorithm considers a broader range of aerosol mixtures to allow more subtle particle property distinction. For the surface reflectance, two different approaches are considered: (a) surface BRF retrieved self-consistently with the atmosphere using only MISR data (similar to the standard algorithm), and (b) surface BRF contribution prescribed from the MODIS MAIAC product to separate the surface contribution. In addition, a XGBoost AI/ML approach has been developed using the retrieved and prescribed RA results, along with an aerosol microphysical property validation dataset developed by Anstett et al. (in prep). The XGBoost models employed here use MISR RA prescribed + retrieved geophysical output as input, training models separately against AERONET AOD, FMF, Ångström Exponent, non-sphericity, and SSA. The training dataset consists of ~50,000 global MISR/AERONET overland coincidences, with each of the coincidences containing potentially >2,000 MISR pixels (retrievals). For the purposes of

developing optimal AI/ML coefficients, each of these quality-assessed pixels was treated as an independent data point, yielding a total of \sim 18 million data points that were used for training.

2.3 Thermal Infrared AOD (AOD₁₀)

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Compared to visible and NIR-based techniques, aerosol retrieval in the thermal-infrared (TIR) offers several advantages, such as nighttime observation and enhanced contrast of dust signals over deserts. In addition, the infrared spectrum is primarily sensitive to coarse particles (diameter>1 μ m), providing better dust detection. Split-window techniques have been used to detect dust from passive radiometers by exploiting the distinct negative brightness temperature difference between two neighboring atmospheric window channels (e.g., 10.8 and 12 μ m) (Legrand et al., 2001; Lensky and Rosenfeld, 2008). Based on this approach, the Dust RGB composite derived from the Spinning Enhanced Visible and InfraRed Imager (SEVIRI) is capable of tracking dust plumes every 15 minutes and mapping the source locations over Central Asia, as demonstrated in Xi (2023).

Hyperspectral infrared spectrometers have offered new potential to infer dust properties, including AOD_{10} and dust layer height. A major challenge in TIR-based retrieval is isolating the aerosol signal from the infrared emissions of the atmosphere and the underlying surface. TIR-based algorithms rely on forward model simulations of TOA radiances or brightness temperatures for a range of atmospheric profiles (e.g., temperature, water vapor), surface properties (e.g., emissivity, temperature), and dust aerosol properties (e.g., AOD_{10} , vertical distribution, size, and refractive index). Below, we describe four different algorithms used for retrieving AOD_{10} from the Infrared Atmospheric Sounding Interferometer (IASI), a Fourier transform spectrometer onboard the European MetOp satellite series that observes the Earth's radiation spectra from 645 to 2760 cm⁻¹ (3.6–15.5 μ m) at a spectral resolution of 0.5 cm⁻¹ and a nadir ground resolution of 12 km. The four algorithms differ in the retrieval methods, the atmosphere and surface input data, and the dust optical models assumed in forward model calculations, among other factors.

2.3.1 LMD algorithm

The Laboratoire de Météorologie Dynamique (LMD) algorithm employs a two-step, LUT-based approach (Capelle et al., 2018). In the first step, the atmospheric state is determined using 18 IASI channels that are insensitive to the surface or aerosols. In the second step, AOD_{10} , mean altitude, and surface temperature are retrieved by fitting observed brightness temperatures against simulations at 8 aerosol-sensitive channels. These simulations incorporate a range of atmospheric profiles, surface properties (emissivity, temperature, and pressure), AOD_{10} , altitudes, and dust microphysical properties. Dust is represented by a spherical, lognormal size distribution (R_{eff} =2.3 μ m, σ_g =0.65) and two refractive indices from Balkanski et al. (2007) and Volz (1973), corresponding to strongly and weakly absorbing dust types, respectively. Surface emissivity is based on the monthly mean IASI retrievals by Capelle et al. (2012).

255 2.3.2 MAPIR algorithm

The Mineral Aerosol Profiling from Infrared Radiances (MAPIR) algorithm retrieves the vertical profiles of dust concentrations using the Rodgers optimal estimation method (Callewaert et al., 2019). The dust concentration profiles are converted to AOD_{10} using Mie-calculated extinction cross section, based on an assumed size distribution and refractive index. A forward model (RTTOV) is used to simulate IASI radiances based on a priori of the state vector (i.e., dust concentration profiles at seven 1-km-thick layers centered at 0.5 to 6.5 km), along with temperature and water vapor profiles derived from IASI. The dust optical model assumes a lognormal size distribution (r_g =0.6 μ m, σ_g =2), and refractive index from Volz (1973). Surface emissivity is based on a monthly climatology derived from IASI clear sky spectra by Zhou et al. (2011).

2.3.3 ULB algorithm

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The Université libre de Bruxelles (ULB) algorithm estimates dust AOD_{10} using a neural network approach (Clarisse et al., 2019). The algorithm first performs dust detection by computing a dust index from a linear discrimination analysis of IASI-observed spectra. The dust index is then converted to dust AOD_{10} via a neural network trained with synthetic spectra generated by a forward model. The forward model incorporates a representative set of atmospheric states from IASI Level-2 data, surface emissivity from Zhou et al. (2011), and a range of dust layer altitudes (from 0 to 7 km). Dust aerosol is represented by a lognormal size distribution (r_q =0.5 μ m, σ_q =2), and refractive index from Volz (1973).

270 2.3.4 IMARS algorithm

The Infrared Mineral Aerosol Retrieval Scheme (IMARS) algorithm performs probabilistic estimates of AOD_{10} , composition, effective radius, and mean layer temperature (a proxy for dust layer height), based on forward model simulations of IASI-observed radiances under various dust and ice cloud conditions (Offenwanger et al., 2024). The algorithm considers 12 possible combinations of four dust mineralogical mixtures (China, Central Sahara, Niger, Iowa Loess) and three size distributions. Each dust mixture is associated with predefined mineral fractions (and hence refractive indices) and particle effective radius. Surface emissivity is based on the MODIS UCSB Emissivity Library.

2.4 ALH

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Aerosol vertical distribution can be retrieved from both active and passive sensors. Active sensors, such as the Cloud-Aerosol Lidar with Orthogonal Polarization (CALIOP) lidar, provide vertically-resolved retrievals of aerosol volume extinction at high vertical resolutions. However, they are limited by narrow swaths and poor spatial coverage. In recent years, substantial progress has been made in retrieving ALH from passive sensors using various techniques, such as stereoscopic retrieval from polar-orbiting multiangle or geostationary imagers (Nelson et al., 2013; Carr et al., 2020), polarimetric observations in the near UV (Wu et al., 2016), differential optical absorption spectroscopy in oxygen absorption bands (Xu et al., 2017, 2019), and hyperspectral infrared measurements (Capelle et al., 2018; Callewaert et al., 2019; Clarisse et al., 2019; Offenwanger et al., 2024). Although passive techniques do not achieve the same level of accuracy as lidars and only estimate an effective height

with limited information on the aerosol layer thickness, they provide much better spatial coverage and revisit frequency (Lu et al., 2021, 2023).

The ALH definition varies by retrieval techniques, and may refer to the top of aerosol layers such as from stereoscopic techniques, or an effective central height corresponding to peak aerosol extinction (Xu et al., 2017). Like AOD, ALH is an optical quantity and varies with the retrieval wavelength. Except for stereoscopic techniques, passive ALH retrievals depend on assumptions about the aerosol vertical distribution. In this study, we compare four ALH products, including the CALIOP aerosol extinction-weighted height, EPIC aerosol optical centroid height (AOCH) product, IASI mean dust layer altitude, and MISR plume height.

2.4.1 CALIOP aerosol extinction-weighted height

CALIOP was a nadir-viewing elastic backscatter lidar onboard the Cloud-Aerosol Lidar and Infrared Pathfinder Satellite Observations (CALIPSO), and measured polarized backscatter at 532 nm and total attenuated backscatter at 532 nm and 1032 nm, with a vertical resolution of 30 m below 8.2 km and 60 m between 8.2 and 20.2 km (Winker et al., 2009). In the CALIOP data processing, calibrated attenuated backscatter coefficient profiles are used to detect the top and base altitudes of atmospheric features. A set of scene classification algorithms (SCA) then classifies these features as either aerosol or cloud, and determine the aerosol type and cloud phase. During this process, aerosol lidar ratios are selected to derive the aerosol extinction and backscatter coefficient profiles (Young et al., 2018). The selection of lidar ratios is based on the aerosol typing algorithm which considers six tropospheric aerosol types—clean marine, dusty marine, dust, polluted continental/smoke, polluted dust, and elevated smoke (Kim et al., 2018). Based on the aerosol extinction profile, the ALH with respect to the mean sea level can be calculated as $\frac{\sum_{i=1}^{n} \beta_{ext,i} Z_i}{\sum_{i=1}^{n} \beta_{ext,i}}$, where $\beta_{ext,i}$ is the 532 or 1064 nm aerosol extinction coefficient (km⁻¹) at level i, and Z_i is the altitude (km) at level i (Koffi et al., 2012).

2.4.2 EPIC AOCH product

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The EPIC AOCH product is derived from the spectral contrast in TOA reflectances between the oxygen (O_2) absorption and continuum bands. The physical principle is that ALH affects the path length of backscattered light and the amount of light absorbed by well-mixed O_2 molecules. Consequently, the spectral contrast between the O_2 absorption bands and the continuum bands depends on the ALH (Xu et al., 2019). The EPIC AOCH algorithm employs pre-computed TOA reflectances for a range of $AOD_{0.68}$, AOCH, surface reflectivity, and surface pressure. Three aerosol optical models are considered: smoke, Saharan dust, and Asian dust. The dust models are derived from AERONET measurements at Cape Verde and over East Asia (Xu et al., 2017). The aerosol vertical distribution assumes a quasi-Gaussian profile characterized by a centroid altitude and a fixed half-width at half maxima of 1 km. Hence, the EPIC-retrieved AOCH represents the altitude of peak volume extinction.

315 2.4.3 IASI dust laver altitude

TIR-based retrieval of dust layer height employs the sensitivity of infrared radiation to the temperature of the aerosol layer, which is intrinsically linked to its mean altitude. The IASI LMD algorithm estimates the dust AOD_{10} and mean altitude by matching IASI observations to forward model simulations assuming eight mean layer altitudes from 750 to 5795 m (Capelle et al., 2018). Dust is assumed to be uniformly distributed within a single atmospheric layer, of which the thickness varies from 500 to 800 m. The retrieved mean altitude represents the height at which half of the AOD_{10} is below and half of the AOD_{10} is above, and considered as an infrared optical equivalent to the centroid of the aerosol vertical profiles.

2.4.4 MISR plume height

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In addition to the radiometrically derived AOD, ALH can be derived geometrically from the parallax in the MISR hyperstereo imagery. The MISR Interactive Explorer (MINX) software performs this task interactively, on a case-by-case basis, and retrieves plume heights at 1.1 km horizontal resolution, and between 250 and 500 m vertical resolution (Nelson et al., 2013). The MISR ALH retrievals identify the layer of maximum spatial contrast in the plume imagery, so the results are often skewed lower than CALIPSO, which is also sensitive to thin, less distinct aerosol layers above dense plume features (Flower and Kahn, 2017).

3 Evaluation of Cross-Sensor and Cross-Algorithm Consistency

Table 1 summarizes the satellite products and parameters considered in this study. These products were chosen based on the data availability and similar overpass times over the Aralkum Desert, ensuring minimal scene differences between the sensors. While some products have duplicated parameters (e.g., the UVAI products report total and absorbing AOD), we focus on the primary and most widely used aerosol parameters from each product. The UVAI and midvisible AOD products report particle property retrievals over desert surfaces, such as Ångström Exponent and single scattering albedo (SSA); however, they are subject to larger uncertainties than AOD retrievals and generally not recommended for scientific studies.

3.1 Horizontal and Vertical Dust Distributions

On 27 May 2018, MODIS/Aqua observed an extensive whitish dust plume originating from Aralkum and moving southeast towards Iran and Afghanistan (Fig. 2(a)). Although CALIOP missed the Aralkum event, it detected a shallow dust layer at an altitude of 0–1 km at the southeastern coast of Caspian Sea (Fig. 2(d)). This dust likely originated from the dry channel of the ancient River Uzboy, a highly active dust source in western Turkmenistan (Nobakht et al., 2021).

On 28 May 2018, a high-pressure system developed just south of Aralkum. As shown in the nighttime SEVIRI Dust RGB composite (Fig. 2(b)), the anticyclonic flow carried the lofted dust across Ustyurt Plateau towards the Caspian Sea, while simultaneously lifting dust from Aralkum that dispersed eastward. CALIOP detected an extensive dust layer stretching from Aralkum to the Kopet-Dag Range (Fig. 2(e)). The Kopet-Dag Range acted as a physical barrier, causing dust to accumulate

Table 1. List of satellite aerosol products considered in this study.

Sensor	Algorithm/Product	Resolution	Data Reference						
UV Aerosol Index (UVAI)									
OMPS/SNPP	NMMIEAI v2	$50\times50 \text{ km}^2$	Torres (2019a)						
EPIC/DSCOVR	AER v3	$12\times12~\mathrm{km}^2$	Torres (2019b)						
TROPOMI/S5P	TROPOMAER v1	7.5×3 km ²	Torres (2021)						
	AER_AI v2	7.5×3 km ²	ESA (2021)						
Midvisible Aerosol Optical Depth (AOD)									
MODIS/Terra, Aqua	DT C6.1	$10\times10~\mathrm{km}^2$	Levy and Hsu (2015a)						
	DT3K C6.1	3×3 km ²	Levy and Hsu (2015b)						
	DB C6.1	$10\times10~\mathrm{km}^2$	Levy and Hsu (2015a)						
	MAIAC C6.1	$1\times1~\mathrm{km}^2$	Lyapustin and Wang (2022)						
VIIRS/SNPP, NOAA20	DT v2	$6\times6~\mathrm{km}^2$	Levy et al. (2023)						
	DB v2	$6\times6~\mathrm{km}^2$	Hsu (2022)						
	EPS v3r0	$0.75 \times 0.75 \text{ km}^2$	Kondragunta et al. (2023)						
MISR/Terra	v23 (operational)	$4.4\times3~\mathrm{km}^2$	ASDC (1999)						
	Research Algorithm		Limbacher et al. (2022)						
	Thermal Infrare	d AOD (AOD ₁₀)							
IASI/METOP-A	LMD v2.2	1°×1°	C3S CDS (2019)						
	MAPIR v5.1	1°×1°	C3S CDS (2019)						
	ULB v9	1°×1°	C3S CDS (2019)						
	IMARS v7	1°×1°	C3S CDS (2019)						
Aerosol Layer Height (ALH)									
CALIOP/CALIPSO	05kmAPro v4.51	5 km	ASDC (2023)						
EPIC/DSCOVR	AOCH v1	$30\times30 \text{ km}^2$	ASDC (2018)						
IASI/METOP-A	LMD v2.2	12 km	C3S CDS (2019)						
MISR/Terra	Plume Height	1.1 km	This Study						

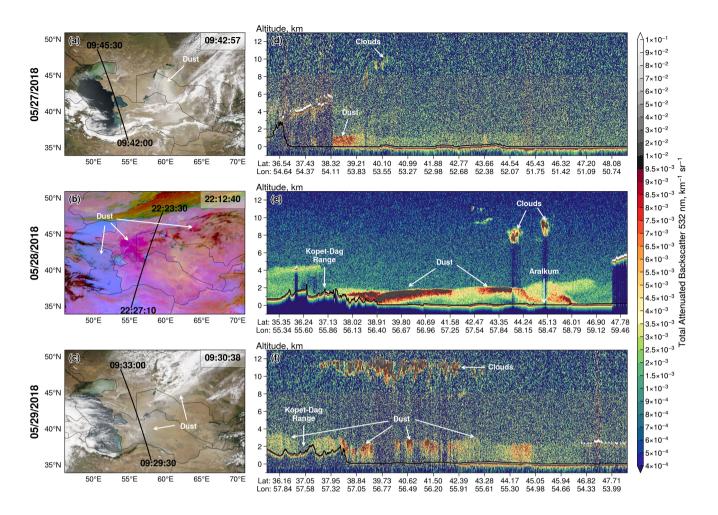


Figure 2. (a–c) CALIPSO ground tracks superimposed on coincident MODIS/Aqua true color (27 and 29 May 2018) and SEVIRI Dust RGB composite (28 May 2018) imagery. The ground track start and end times are labeled. MODIS and SEVIRI scan times over Aralkum (45°N, 60°E) are shown at the top right corner. (d–f) Corresponding CALIOP 532 nm total attenuated backscatter profile. Black lines indicate the ground surface.

along the foothills. Overall, the airborne dust resided below 2 km with a sharp upper boundary, probably due to large-scale subsidence and the shallow nighttime boundary layer (e.g., due to temperature inversion). The lofted dust was concentrated within an elevated layer at 1–2 km altitude near Aralkum, but extended to the ground by the gently sloping foothills. The variation of dust layer height may explain the contrasting color signatures observed in the SEVIRI imagery: the elevated dust near Aralkum displays a rich magenta hue, whereas the low-lying dust near the Kopet-Dag Range is less discernible, possibly due to reduced temperature contrast between the surface and dust aloft.

On 29 May 2018, remnants of the Aralkum dust plume continued to affect western Uzbekistan and Turkmenistan (Fig. 2(c)). The suspended dust was only partially detected by CALIOP due to extensive cloud cover (Fig. 2(f)). The dust layer

extended to an altitude of 3.5 km, likely resulting from the daytime convective mixing and increased vertical motion ahead of an approaching cold front.

355 3.2 Comparison of UVAI Products

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Figure 3 compares multiple UVAI products in detecting the freshly emitted dust plume on 27 May 2018, including the OMPS, TROPOMI and EPIC Mie-based UVAI products developed by NASA, and the TROPOMI LER-based UVAI developed by ESA. The sensor scan times over Aralkum (45°N, 60°E), as shown in each panel, are less than 20 minutes apart. The UVAI products display similar spatial patterns, but with significant differences in the dynamic range and statistical distributions.

Among the three NASA products (Fig. 3(b–d)), OMPS yields markedly lower UVAI (e.g., mean=0.5, maximum=3.2) compared to EPIC (1.1 and 11.4) and TROPOMI (0.6 and 5.2), likely due to its coarser spatial resolution and cloud interference. EPIC exhibits significantly higher values over dusty scenes, partly because the 340/388 nm pair is more sensitive to absorbing aerosols. Nonetheless, cloudy scenes in EPIC appear more noisy, most likely due to EPIC L1 calibration issues (personal communications with Karin Blank). Statistically, both OMPS and TROPOMI reveal a bimodal distribution with a prominent peak near zero and a secondary peak near 1. EPIC displays a unimodal distribution with a larger spread, as indicated by its standard deviation (SD), median absolute deviation (MAD), and interquartile range (IQR).

Compared to the TROPOMI 354/388 nm Mie-based UVAI from NASA, the ESA LER-based product exhibits more negative values over cloudy and dust-free scenes, and consequently greater dispersion, as indicated by a trimodal distribution (Fig. 3(d)). The choice of 354/388 nm versus 340/380 nm wavelength pair in the ESA product has minor effects on the regional means, extremes, and dispersion. In contrast, the 335/367 nm pair produces significantly lower UVAI and less dispersion, indicating reduced sensitivity to aerosol absorption.

Dust detection using UVAI products often employs fixed thresholds to isolate the dust signal. For example, Prospero et al. (2002) used a UVAI threshold of 1 for North Africa and 0.7 elsewhere; Schepanski et al. (2012) used a threshold of 2 to detect major dust plumes over the Sahara. As shown in Fig. 3(g), EPIC yields more than 18% pixels exceeding a threshold of 2—over three times those observed in OMPS and TROPOMI. This disparity suggests that using a fixed UVAI threshold may lead to inconsistent detection of dust plumes. In contrast, adopting a percentile-based threshold can more effectively capture the dynamic range of each product, resulting in more coherent dust detection. As demonstrated in Fig. 3, using the 95th percentile produces a consistent delineation of the plume extent, and captures three clusters of elevated UVAI values separated by clouds (see Fig. 3(a)).

A persistent feature in all UVAI products is the occurrence of large positive values along the eastern coast of Caspian Sea, particularly over the northern Caspian Sea and Garabogazköl Gulf. To determine whether airborne dust was responsible for these anomalies, we compared multiple UVAI products with coincident CALIOP AOD $_{0.53}$ measurements along the CALIPSO overpass shown in Fig. 3. To account for the along-track scan time differences (<30 min apart) between the sensors, we shifted the UVAI products to match the UVAI and AOD $_{0.53}$ maxima observed at the southeastern coast of Caspian Sea (see Fig. 2(d)). Next, we applied a 5-second moving averaging to smooth the co-located data, which are shown in Fig. 4.

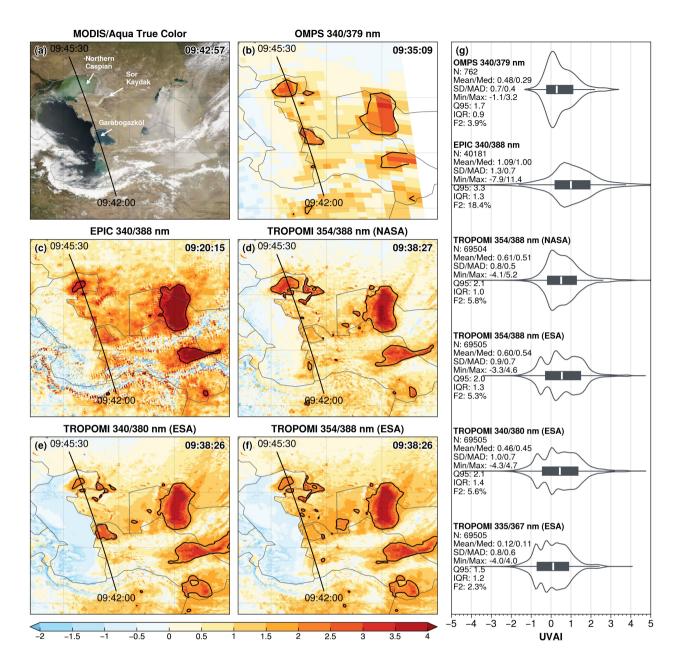


Figure 3. Comparison of UVAI products on 27 May 2018: (a) MODIS/Aqua true color composite; (b−f) Five UVAI products from OMPS, EPIC, and TROPOMI; (g) Violin plots and summary statistics of six UVAI products. The sensor scan time over Aralkum and CALIPSO ground track are indicated on panel (a−f). Black contours in (b−f) indicate the 95% percentile of UVAI values. Summary statistics in panel (g) are pixel count (N), mean, median (Med), standard deviation (SD), median absolute deviation (MAD), minimum (Min), maximum (Max), 95% percentile (Q95), interquartile range (IQR), and proportion of UVAI≥2 pixels (F2).

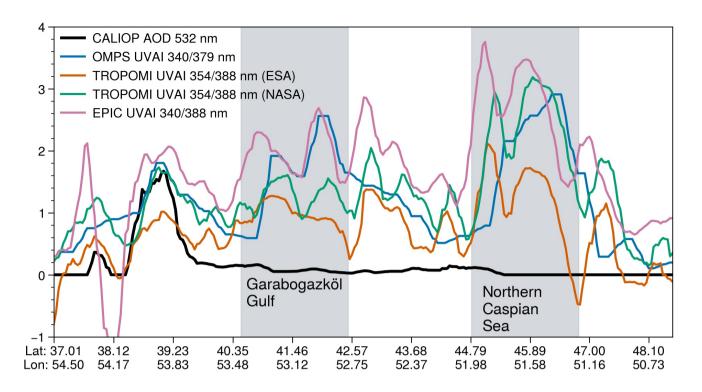


Figure 4. Coincident measurements of CALIOP 532 nm AOD and various UVAI products along the eastern coast of Caspian Sea on 27 May 2018. CALIPSO ground track is shown in Fig. 3. Shaded areas represent the Garabogazköl Gulf and northern Caspian Sea.

Apparently, CALIOP detected only a very thin aerosol layer over the northern Caspian Sea and Garabogazköl Gulf. The large positive UVAI in these regions also remained stationary and persisted on dust-free days, indicating that they were unlikely caused by dust and likely related to time-invariant surface features. Due to influx of sediment-rich water from the Volga and Ural rivers (Modabberi et al., 2019; Moradi, 2022), northern Caspian Sea displays persistent discoloration, as seen in Fig. 3(a). This shallow, sediment-rich water strongly absorbs in the near-UV, producing enhanced absorption at shorter wavelengths that resembles the spectral signature of airborne dust (He et al., 2012; Lee et al., 2013). Similarly, the shallow, saline waters of Garabogazköl Gulf (with a salinity of \sim 35%) cause strong near-UV absorption and yield a dust-like UVAI signal, in contrast to the deep water of the Caspian Sea, which has a much lower salinity (\sim 1.3%) and yields near-zero UVAI. Large positive UVAI values are also observed over the Sor Kaydak salt marsh due to enhanced UV absorption by salt minerals and organisms (Fig. 3). In summary, enhanced UV absorption by turbid and saline waters and salt flats causes the water-leaving UV radiances to deviate from those for a pure scattering atmosphere, thereby generating large positive UVAI that resembles the effects of airborne dust. This surface feature-related UVAI signal may be common over ephemeral and dried lakes, which constitutes a potential source of error in using UVAI products for dust plume detection and source mapping in these regions.

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Table 2. Summary statistics of eight AOD products in observing the Aralkum dust aerosol during 27–29 May 2018, based on best-quality, over-land retrievals. SD, standard deviation. MAD, median absolute deviation. IQR, interquartile range. Sk, skewness. 90th, 90th percentile.

Product	N	Mean	SD	Median	MAD	IQR	Sk	90th	Max
MODIS/Terra DB	21,338	0.49	0.73	0.25	0.17	0.38	3.0	1.0	3.5
MODIS/Aqua DB	21,659	0.46	0.55	0.31	0.18	0.37	3.4	0.9	3.5
MODIS/Terra MAIAC	5,223,130	0.35	0.54	0.18	0.11	0.26	4.7	0.7	6
MODIS/Aqua MAIAC	5,070,926	0.37	0.69	0.17	0.10	0.24	4.3	0.7	6
VIIRS/SNPP DB	110,726	0.44	0.76	0.15	0.10	0.39	3.6	1.0	5
VIIRS/NOAA20 DB	110,286	0.56	0.85	0.26	0.19	0.55	3.2	1.2	5
VIIRS/SNPP EPS	5,295,908	0.49	0.62	0.26	0.19	0.54	2.3	1.2	5
VIIRS/NOAA20 EPS	3,996,574	0.37	0.53	0.19	0.16	0.39	2.8	1.0	5

3.3 Comparison of Midvisible AOD Products

400 3.3.1 AOD retrieval over desert surfaces

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Table 2 summarizes the statistics of eight AOD products, based on best-quality, over-land retrievals between 27 and 29 May 2018. The number of pixels differs greatly among the products, indicating inconsistent sampling due to differences in spatial resolutions, screening of irretrievable scenes (e.g., clouds, snow/ice, sun glint, ocean color), and/or QA definitions. The inconsistent sampling, along with algorithm differences as discussed in Section 2.2, contribute to disparities in the AOD statistics. In addition, the NOAA EPS product uses L1b data from the NOAA VIIRS Calibration/Validation group, while the NASA DT and DB products use the L1b data from the NASA VIIRS Calibration Support Team, which may further contribute to product inconsistency.

The MODIS-retrieved AOD appears more consistent between Terra and Aqua platforms than between DB and MAIAC algorithms. In particular, the mean AOD differs by less than 10% between Terra and Aqua, but exceeds 20% between DB and MAIAC. Compared to MAIAC, DB produces a larger upper tail, as indicated by a higher 90th percentile, and consequently a broader distribution (higher SD, MAD and IQR). MAIAC produces a narrower distribution (lower MAD and IQR) despite more extreme high values (i.e., upper limit of 6 versus 3.5 for DB).

VIIRS DB and EPS algorithms employ the same upper AOD limit (5), but display more complex patterns compared to MODIS. For VIIRS/SNPP, EPS yields a higher mean and median as well as more extreme values, while DB produces a larger SD and skewness, indicating a broader upper tail. For VIIRS/NOAA20, DB yields a larger spread (higher SD and IQR) and a larger upper tail (higher 90th percentile) than EPS, suggesting that DB captures more frequent high AOD values.

Next, we focus on comparing the MODIS/Aqua DB versus MAIAC products, and VIIRS/NOAA20 DB versus EPS products. By comparing AOD retrieved from the same sensor, we can attribute the disparity to the choice of algorithms. The instruments are hereafter referred to simply as MODIS and VIIRS unless otherwise noted. Due to different spatial resolutions, the L2

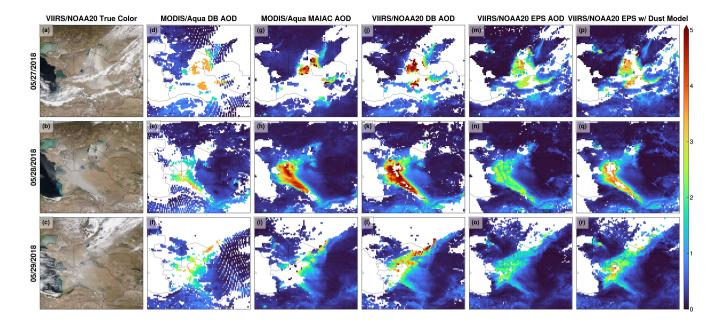


Figure 5. Over-land AOD retrievals on 27–29 May 2018. (a–c) VIIRS/NOAA20 true color images, (d–f) MODIS/Aqua DB product, (g–i) MODIS/Aqua MAIAC product, (j–l) VIIRS/NOAA20 DB product, (m–o) VIIRS/NOAA20 EPS product, and (p–r) VIIRS/NOAA20 EPS product using the dust optical model as a test case.

products are gridded onto a uniform $0.2^{\circ} \times 0.2^{\circ}$ resolution by computing the mean value of all pixels within each grid cell. We only use the best-quality retrievals based on the QA rules recommended in each product.

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Figure 5 displays the daily gridded AODs, along with VIIRS true color composites to help attribute missing retrievals to either clouds or incorrect cloud screening. None of the products captured the full extent of the fresh dust plume on 27 May 2018. The retrieved AOD over the dust scene also reached the upper limit defined in each algorithm. There are several reasons for defining an upper AOD limit. First, setting an upper AOD limit is necessary to minimize the effect of residual cloud contamination. Second, AOD retrieval from reflected sunlight relies on scene brightening by aerosol scattering (primarily the forward scattering of surface reflection) against a relatively dark background. At high aerosol loadings, the TOA reflectance becomes less sensitive to additional AOD increases, hence making AOD retrieval less accurate during heavy aerosol events. Lastly, AOD retrieval is performed by matching observed TOA reflectances against pre-computed values within a specific AOD range. A poor fit may result, if the aerosol burden exceeds the predefined range. Retrievals under such scenarios are often flagged as marginal quality, and consequently excluded from our screening for best quality data. Thus, heavy dust scenes may be either retrieved but with low confidence in clear sky, or classified as clouds and not retrieved.

To check whether the freshly emitted dust on 27 May was erroneously classified as clouds, Fig. 6 displays the cloud fraction or cloud masks reported in selected granules from each product. Fig. 6 reveals that the thick dust plume is mostly flagged as clouds in all products. For MODIS, DB detected parts of the plume fringes, where the retrieved AOD reached the algorithm

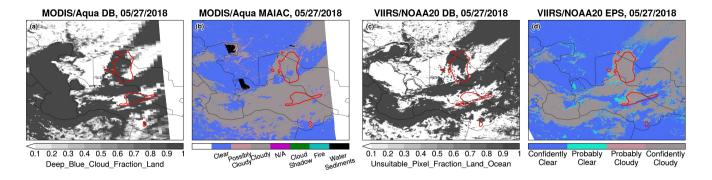


Figure 6. Misclassification of freshly emitted dust as clouds on 27 May 2018. (a) Cloud fraction from MODIS/Aqua DB product; (b) Cloud mask from MODIS/Aqua MAIAC product; (c) Unsuitable pixel fraction from VIIRS/NOAA20 DB product; and (d) Cloud mask from VIIRS/NOAA20 EPS product. Red contours indicate the 95th percentile (2.1) of TROPOMI TropOMAER UVAI product.

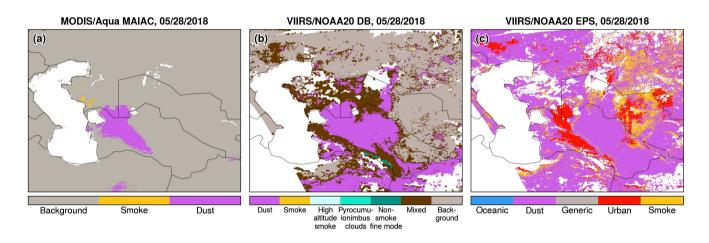


Figure 7. Aerosol optical model used for over-land retrievals on 28 May 2018 in the (a) MODIS/Aqua MAIAC, (b) VIIRS/NOAA20 DB, and (c) VIIRS/NOAA20 EPS products.

limit (3.5). MAIAC classifies the majority of dust scene as "cloudy". For VIIRS, DB does not report cloud masking or fraction; instead it reports an Unsuitable_Pixel_Fraction_Land_Ocean parameter, which indicates that the dust pixels near Aralkum were not retrieved. Similarly, EPS flags the dust scene as "confidently cloudy".

On 28 May 2018, a high-pressure system produced cloud-free conditions, providing an optimal sky condition for aerosol retrieval (Fig. 5(b)). All products successfully captured the extensive dust layer; however, there are large differences in the AOD magnitudes. Notably, VIIRS EPS yields significantly lower (by more than 50%) AOD than other products over dust-affected areas. As described in Section 2, satellite algorithms use predefined aerosol optical models (including coarse-mode dust models) to represent location- and season-dependent aerosol microphysical properties. To determine whether the dust optical model was successfully selected, Fig. 7 displays the aerosol optical model selected for retrieval in each product. MODIS

DB does not report this information and thus is not shown. Both MODIS MAIAC and VIIRS DB successfully selected their respective dust models for the dust scene over western Turkmenistan. VIIRS EPS selected the urban aerosol model, presumably because the urban model produced a closer match between observed and simulated TOA reflectances.

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According to Laszlo and Liu (2022), EPS first retrieves AOD in the blue channel (0.41 μ m), and then scales it to longer wavelengths using the normalized spectral extinction coefficients associated with the aerosol optical model. The normalized extinction coefficient exhibits much stronger wavelength dependence in the urban model than the dust model (see Figure 3-4 in Laszlo and Liu (2022)). For the same $AOD_{0.41}$ value, the dust model would yield more than 40% higher AOD compared to the urban model. In other words, had the dust model be selected, EPS would have retrieved higher AOD that aligns more closely with DB and MAIAC. Indeed, when we forced EPS to use the dust model, its agreement with DB and MAIAC improved, although the retrieved AODs were still lower, and had more marginal-quality retrievals that were excluded from our screening procedure (Fig. 5(p-r)).

Using the gridded AOD products in Fig. 5, we conducted a regression analysis to further examine the consistency between aerosol algorithms. The results are shown in Fig. 8. The choice of algorithms for both MODIS and VIIRS introduces a non-linear response in the retrieved AOD. For MODIS, MAIAC produces lower AOD than DB under low aerosol loadings (e.g., 36% lower for AOD<1), but higher AOD under heavy loadings (22% higher for 2<AOD<3). This nonlinearity may be partly explained by MAIAC's higher spatial resolution, which yields more extreme retrievals (either very clean or heavily polluted). The higher AOD limit in MAIAC (6 vs. 3.5 for DB) may further exacerbate the discrepancies at heavy aerosol loadings, as shown in Fig. 8(a). For VIIRS, EPS produces generally lower AODs than DB under all aerosol loadings, with the EPS–DB difference increasing from 37% for AOD<1 to 51% for 4<AOD<5 (Fig. 8(b)). Indeed, Fig. 5(m–o) show that EPS yields approximately 50% lower AODs than other algorithms over the dust scene.

Figure 9 displays MISR AOD retrievals on 28 May 2018 (orbit 98092) based on the standard operational product and MISR research algorithms. The standard product exhibits several limitations. First, an outdated land/water mask was used and marked the Aral Sea as "shallow water"; As a result, no retrievals were performed over the Aralkum Desert. Second, the lofted dust over the Kopet-Dag foothills was misclassified as clouds. Lastly, the retrieved AOD is substantially lower than those from single-view sensors (Fig. 5). Kahn et al. (2010) noted that MISR tends to underestimate AOD under heavy aerosol loadings, as the weak surface reflection signal leads to poor surface-atmosphere separation and overestimation of the surface contribution to TOA radiances. Additionally, the standard product selected spherical non-absorbing aerosol mixtures for the dust scene, resulting in underestimation of the nonspherical fraction and overestimation of FMF and SSA. A key factor for the biased particle property retrieval is the lack of appropriate aerosol optical models for saline dust in the MISR standard algorithm; Consequently, the particle property retrievals are of low confidence.

To explore the particle-property information content of MISR observations, we ran the MISR research algorithm in three modes: (a) with the surface retrieved self-consistently with the atmosphere using only MISR data, (b) with the surface reflectance prescribed from MODIS MAIAC product (Limbacher et al., 2022), and (c) with a modified algorithm based on an AI/ML approach. Initial statistics indicate that these models do well in the regional means. AOD is retrieved fairly consistently with all three approaches, except in the highest and lowest AOD regions. The agreement with single-view AOD products (Fig.

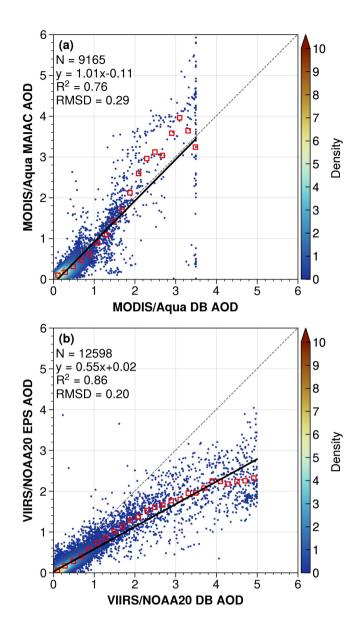


Figure 8. Comparison of over-land AOD retrievals during 27–29 May 2018: (a) MODIS/Aqua MAIAC vs. DB; (b) VIIRS/NOAA20 EPS vs. DB. Black lines indicate the linear model fits. Red squares indicate bin-averaged AODs every 0.1 increments. RMSD, root mean square difference.

5, second row) is improved substantially. The prescribed surface results appear to perform better for extremely high AOD conditions, and capture the increasing AOD gradient towards the Kopet-Dag Range. The retrieved nonspherical fraction and FMF show large discrepancies among the three approaches. The AI/ML approach performs closest to expectation in this case (i.e., NonSph>0.8), whereas the retrieved- and prescribed-surface results may have underestimated the nonspherical fraction.

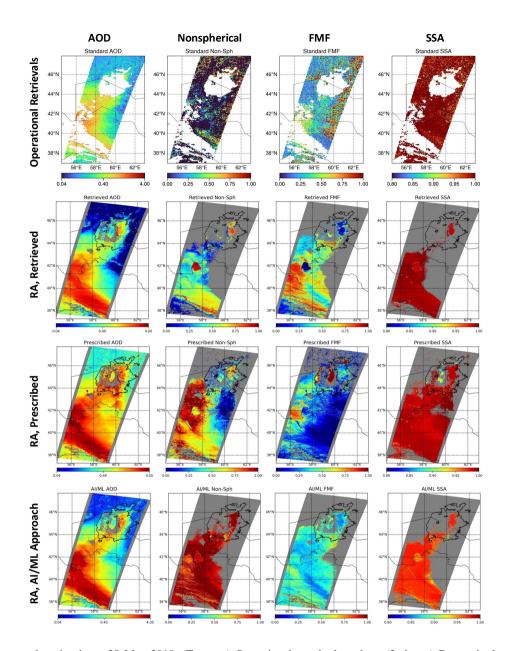


Figure 9. MISR aerosol retrievals on 28 May 2018. (Top row) Operational standard product; (2nd row) Research algorithm (RA) with retrieved surface reflectances from MISR data; (3rd row) Research algorithm with prescribed surface reflectances from MODIS MAIAC product; (Bottom row) Research algorithm using an AI/ML approach.

Results for SSA are generally consistent, with SSA>0.95 for the dust scene, except for low AOD regions where the AI/ML SSA results are probably too low.

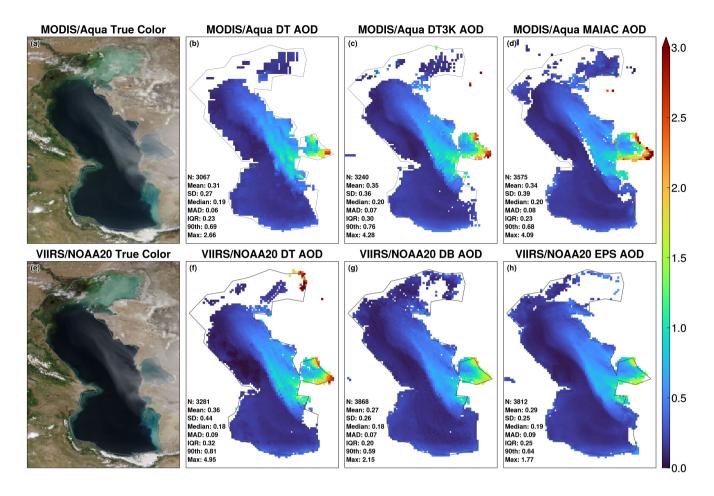


Figure 10. Over-water AOD retrievals over the Caspian Sea on 28 May 2018. Top row panels are MODIS/Aqua (a) true color composite, (b) DT AOD, (c) DT3K AOD, and (d) MAIAC AOD. Bottom row panels are VIIRS/NOAA20 (e) true color composite, (f) DT AOD, (g) DB AOD, and (h) EPS AOD. All products are gridded to a 0.1°×0.1° resolution.

3.3.2 AOD retrieval over the Caspian Sea

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We further compared six AOD products in observing the dust outflow to the Caspian Sea on 28 May 2018, based on best quality retrievals from MODIS/Aqua (DT, DT3K, and MAIAC) and VIIRS/NOAA20 (DT, DB, and EPS). All Level-2 products were gridded to a $0.1^{\circ} \times 0.1^{\circ}$ resolution by averaging the pixels within each grid cell. Bilinear interpolation was applied to MODIS DT product to account for reduced pixel resolutions near sensor swath edges. The gridded AODs are displayed in Fig. 10.

All products capture the enhanced aerosol burden associated with dust outflow to the Garabogazköl Gulf and Caspian Sea. Among the MODIS products, DT3K and MAIAC produce more extreme AOD than DT, resulting in higher means and greater spread (indicated by higher SD and MAD). These spurious AODs create unnatural discontinuities along coastal regions, likely due to inaccurate surface reflectance characterization. VIIRS DT retrieves very high AOD over the shallow waters and salt flats

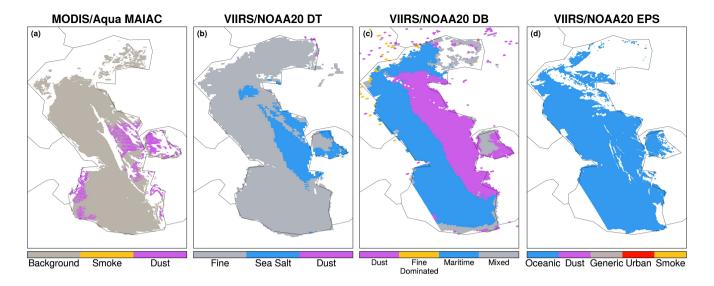


Figure 11. Aerosol optical models used for AOD retrieval over the Caspian Sea on 28 May 2018 in the (a) MODIS/Aqua MAIAC, (b) VIIRS/NOAA20 DT, (c) VIIRS/NOAA20 DB, and (d) VIIRS/NOAA20 EPS products.

over northern Caspian Sea, and to a lesser extent over the coastal region of Garabogazköl Gulf. The non-negligible surface signal from these areas deviated from the dark water surface assumption in the DT algorithm, and was likely misinterpreted as aerosol signal, leading to spurious high AODs. As a result, VIIRS DT produces a higher mean, more extreme upper tail values (indicated by the 90th percentile and maximum), and a larger spread (higher SD and IOR) than DB and EPS.

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We further examined the aerosol optical models selected during the retrieval, as shown in Fig. 11. The MAIAC spheroidal dust model ("Model 6") was applied to only parts of the dust scene, resulting in discontinuous AOD patterns. The VIIRS DT product reports the AOD partitions among nine fine/coarse aerosol models in the "best solution", from which we computed the relative contributions of three aerosol type: fine aerosol, sea salt, and coarse dust. The sea salt type is a dominant contributor to the AOD, suggesting that the sea salt aerosol model provides the closest fit to the dust scene in the "best solution". VIIRS DB successfully applied its spheroidal dust model for the full extent of the dust scene, and maritime aerosol model for dust-free regions. VIIRS EPS selected its oceanic aerosol model for the full scene, again failing to select the dust model similar to the over-land retrieval. In summary, the aerosol algorithms showed varied performance in selecting aerosol optical models for AOD retrieval over the Caspian Sea.

Figure 12 compares the gridded AOD products via linear regression to assess the consistency between algorithms. Overwater retrievals exhibit stronger linear relationships and better agreement than over-land retrievals (Fig. 8), with $R^2 > 0.9$ and RMSD<0.1 in all cases. MODIS DT and DT3K products show excellent agreement with a slope of 0.98 and R^2 of 0.91, while other products show slightly weaker slopes of \sim 0.8. In general, DT yields lower AOD under clean marine conditions (AOD<0.15), but higher AOD in dusty conditions than the MAIAC, DB and EPS algorithms.

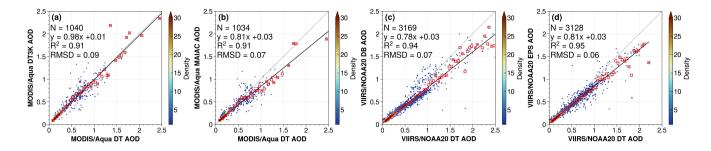


Figure 12. Comparison of AOD retrievals over the Caspian Sea on 28 May 2018: (a) MODIS/Aqua DT3K vs. DT; (b) MODIS/Aqua MAIAC vs. DT, (c) VIIRS/NOAA20 DB vs. DT, (d) VIIRS/NOAA20 EPS vs. DT. Black lines indicate the linear regression fits. Red squares indicate bin-averaged AODs at 0.05 increments. RMSD, root mean square difference.

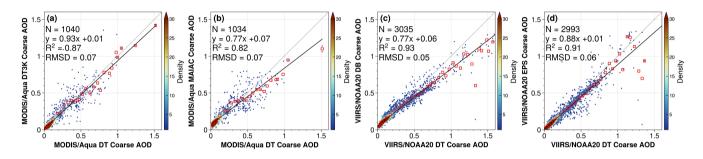


Figure 13. Same as Fig. 12 but for coarse-mode AOD.

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Compared to aerosol retrieval over land, over-water retrieval provides greater information content to constrain particle properties. As described in Section 2.2.1, over-water algorithms represent the aerosol column as a sum of a fine and a coarse mode, and retrieves the total AOD and FMF. Here, we use the total AOD and FMF to compute the coarse-mode AOD from each product, and perform a similar comparison as in Fig. 12. Figure 13 shows that the coarse-mode AODs exhibit strong linear relationships, with $R^2 > 0.8$ and RMSD<0.1, although the agreement is somewhat weaker than for the total AOD. Overall, DT tends to yield higher coarse-mode AOD under dust-laden conditions compared to DT3K, MAIAC, DB and EPS.

Table 3. Summary statistics of four IASI AOD_{10} products in observing the Aralkum dust aerosol during 27–29 May 2018. SD, standard deviation. MAD, median absolute deviation. IQR, interquartile range. Sk, skewness.

Algorithm	N	Mean	SD	Median	MAD	IQR	Sk	Max
LMD	1122	0.13	0.20	0.05	0.05	0.17	2.5	1.2
MAPIR	1380	0.11	0.11	0.08	0.03	0.07	6.0	1.7
ULB	1486	0.06	0.09	0.03	0.04	0.09	2.0	0.6
IMARS	365	0.08	0.07	0.07	0.05	0.10	1.4	0.4

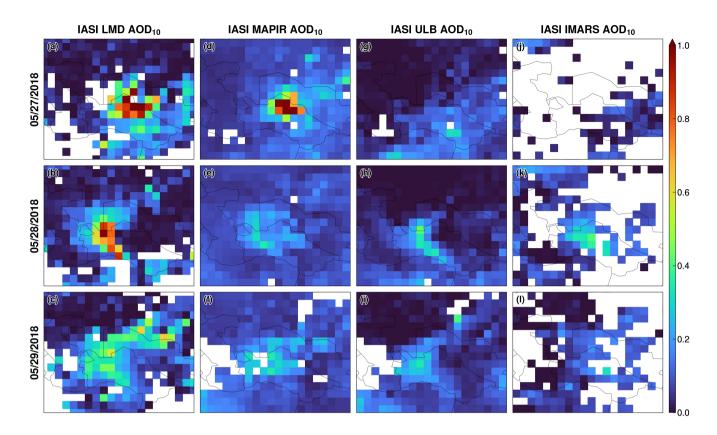


Figure 14. IASI AOD₁₀ retrievals from four algorithms on 27–29 May 2018, (a-c) LMD, (d-f) MAPIR, (g-i) ULB, and (i-l) IMARS.

3.4 Comparison of Infrared AOD (AOD₁₀) Products

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This section compares the IASI AOD₁₀ products from four algorithms: LMD, MAPIR, ULB and IMARS, based on Level-3 daily 1°×1° gridded products. Table 3 summarizes the AOD₁₀ statistics based on separate daytime (descending node) and nighttime (ascending node) retrievals on 27–29 May 2018. Figure 14 displays the daily combined AOD₁₀ by merging the daytime and nighttime observations. The inclusion of both daytime and nighttime data substantially improved the data coverage compared to midvisible AOD products which relies solely on daytime observations (Fig. 5).

Among the four algorithms, LMD has the best performance in detecting the dust plume features both over deserts and the Caspian Sea. On 27 May, LMD captured the extensive plume stretching from the Aralkum Desert to the Kopet-Dag Range (Fig. 14(a)), outperforming midvisible techniques in detecting the fresh dust plume. The highest AOD_{10} (1.2) was observed downwind over Uzbekistan rather than in the immediate vicinity of Aralkum, likely due to difficulty in detecting the heavy dust near the source. Additionally, the retrieved AOD_{10} reached the upper limit of the predefined range in the LMD algorithm (0–1.4), indicating possible underestimation. Unlike midvisible retrievals which include fine aerosol contributions, AOD_{10} is sensitive to coarse particles only. The AOD_{10} -to-AOD ratio depends on the particle size distribution, particularly the relative

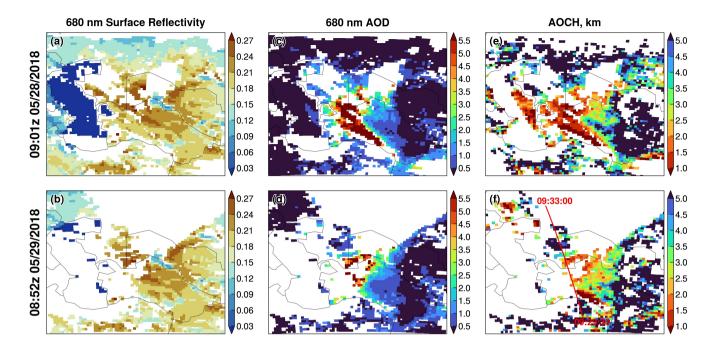


Figure 15. EPIC AOCH retrievals at 09:01z 28 May 2018 (top row) and 08:47z 29 May 2018 (bottom row): (a, b) 680 nm surface reflectivity; (c, d) 680 nm AOD; (e, f) AOCH. The coincident CALIPSO ground track is shown in panel (f).

fraction of fine and coarse modes. Using a AOD_{10} -to-AOD ratio of 0.6 for coarse-dominated dust would imply an AOD_{10} of \sim 3 or more than twice the upper limit, based on the maximum VIIRS DB AOD observed on 27 May (Fig. 5(j)). On 28 May, LMD successfully retrieves the suspended dust by the Kopet-Dag foothills and the dust outflow to the Caspian Sea (Fig. 14(b)), resulting in a spatially continuous AOD_{10} pattern, in contrast to midvisible retrievals which exhibited unnatural discontinuities in coastal regions. The AOD_{10} on 29 May captures both the remnant dust from the previous days and the new emission event from Aralkum, consistent with VIIRS observation shown in Fig. 5(c).

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Compared to LMD, MAPIR yields generally higher background AOD_{10} over aerosol-free areas but lower AOD_{10} over dust-laden scenes, resulting in less distinct plume features (Fig. 5(g–i)). The two products exhibit moderate correlations, with R^2 of 0.6 for daytime retrievals, and 0.4 for nighttime retrievals. MAPIR successfully retrieved the thick dust on 27 May, although with a smaller spatial extent than LMD. MAPIR struggled in detecting dust over the complex terrains of the Ustyurt Plateau and Kopet-Dag foothills on 28–29 May, likely due to increased uncertainty in characterizing the surface properties (e.g., emissivity, temperature), to which infrared retrievals are highly sensitive over elevated terrains (Capelle et al., 2014).

Overall, ULB and IMARS exhibit poorer performance compared to LMD and MAPIR. Specifically, ULB misclassified the fresh dust plume as clouds on 27 May, and retrieves very low AOD_{10} on 28–29 May. IMARS reported substantial missing data for dust-affected areas on all three days, likely due to overly restrictive cloud masking and/or low confidence associated with its probabilistic retrievals.

3.5 Comparison of ALH Products

In this section, we compare four ALH products: CALIOP aerosol extinction-weighted height, EPIC AOCH product, IASI LMD mean dust layer altitude, and MISR stereo-height retrieval. The CALIOP ALH is derived from aerosol extinction vertical profiles at 532 and 1064 nm, while the EPIC and IASI products retrieve an effective ALH using passive techniques that rely on a priori assumptions about aerosol vertical distributions (Section 2.4). Among the IASI products, we focus on the LMD algorithm due to its better performance in detecting the dust plume features (Fig. 14). Below, we first examine the EPIC retrievals on 28 and 29 May 2018, and use co-located CALIOP measurements for validation. The dust plume on 27 May is misclassified as clouds in the EPIC AOCH product and thus not discussed. Next, we compare the coincident retrievals from EPIC and IASI to assess the consistency between passive ALH retrievals. Finally, we present results on MISR plume height retrieval on 28 May 2018.

Figure 15 displays the 0.68 μ m surface reflectivity, AOD_{0.68}, and AOCH retrieved by EPIC. On 28 May, the low surface reflectivity and enhanced aerosol loading (i.e., AOD_{0.68} >0.5) over Caspian Sea provided optimal conditions for AOCH retrieval. The dust outflow was elevated to an altitude of 1.5–2.5 km (Fig. 15(e)), likely enhanced by orographic lifting as the lofted dust was transported over the Ustyurt Plateau.

Bright desert surfaces pose significant challenges for isolating aerosol scattering contributions to EPIC measurements. Radiative transfer simulations indicate that the sensitivity to ALH in the O₂ band spectral contrast diminishes over bright surfaces, requiring high aerosol loadings to generate sufficient signal-to-noise ratios for reliable AOCH retrieval (Xu et al., 2019). As shown in Fig. 15, EPIC-retrieved AOD_{0.68} and AOCH exhibit opposite spatial patterns: AOCH displays unrealistically high values over low AOD_{0.68} areas, and reasonably low values over high AOD_{0.68} (up to 6) areas that form a continuous pattern with the Caspian Sea retrieval. Thus, AOD_{0.68} provides a practical means for screening marginal-quality AOCH retrievals. Focusing on dust scenes where AOD_{0.68} exceeds 2, the AOCH over Turkmenistan increased from 1–1.5 km on 28 May to 2–3 km on 29 May. This temporal evolution can be explained by the evolution of meteorological conditions: a prevailing high-pressure system suppressed vertical aerosol mixing on 28 May, whereas enhanced upward motion ahead of a deepening cold front promoted convective mixing on 29 May.

The EPIC AOCH retrievals are compared against coincident CALIOP extinction-weighted ALH, as shown in Fig. 16. Generally, the CALIOP 532 nm channel is more prone to signal attenuation in the presence of dense absorbing aerosols, resulting in lower ALH than the 1064 nm channel (Torres et al., 2013). Our analysis reveals that the wavelength choice has minor effects on the CALIOP-derived ALH, with a mean difference of 0.05 km between the two channels. EPIC AOCH exhibits significant positive biases under low aerosol loadings. Using the CALIOP 532 nm ALH as a benchmark, EPIC AOCH has a mean bias of 3.6 km and an RMSE of 4.3 km, with only 17% (21%) of co-located retrievals within 0.5 (1.0) km agreement. However, after applying a AOD_{0.68} threshold of 1.5 to isolate dust-laden scenes, the AOCH accuracy significantly improved, with a much lower mean bias (0.4 km) and RMSE (0.8 km), as well as 61% (72%) of co-located retrievals within 0.5 (1.0) km agreement. In general, the higher the AOD_{0.68} threshold, the better the agreement between EPIC and CALIOP. The close agreement between

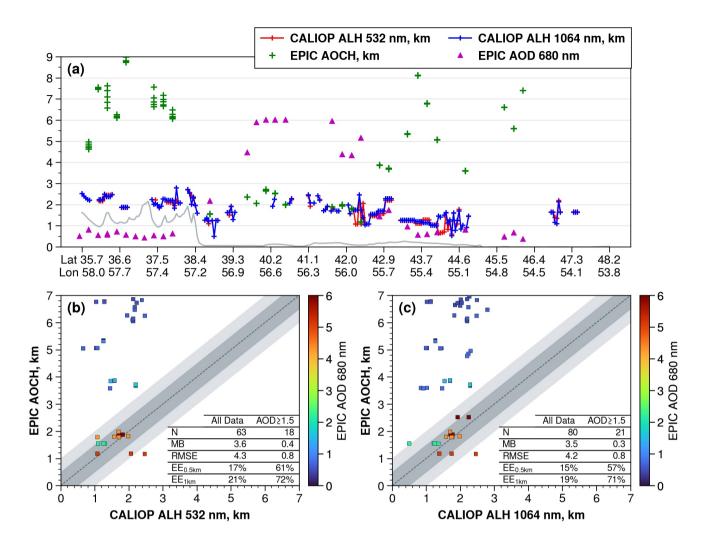


Figure 16. (a) Coincident retrievals of CALIOP extinction-weighted ALH and EPIC AOCH along the CALIPSO overpass on 29 May 2018 (ground track shown in Fig. 15f). Magenta triangles are EPIC-retrieved AOD_{0.68}. Gray line indicates CALIPSO-detected ground surface. (b) Comparison between CALIOP 532 nm ALH and EPIC AOCH. (c) Comparison between CALIOP 1064 nm ALH and EPIC AOCH. N, number of coincident retrievals. MB, mean bias. RMSE, root mean square error. EE, percentage of co-located retrievals within expected errors of 0.5 and 1 km (shaded areas).

EPIC and CALIOP, as well as between the two CALIOP channels, can be attributed to the well-defined upper boundary of the dust layer (as seen in Fig. 2(f)), such that the different techniques detected the strongest signal from the same altitude.

To compare EPIC AOCH with IASI mean dust altitude, we selected the EPIC scans closest in time (06:50z 28 May and 06:41z 29 May) to the daytime IASI overpasses. We applied an $AOD_{0.68}$ threshold of 1.5 to EPIC AOCH over land in order to exclude marginal-quality retrievals and enhance clarity. As shown in Fig. 17(a–b), the $AOD_{0.68}$ threshold removes the majority

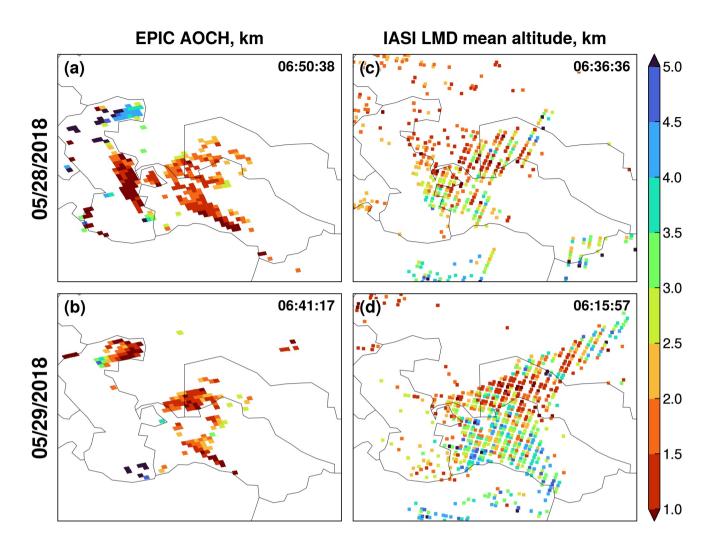


Figure 17. ALH retrievals in the (a, b) EPIC AOCH and (c, d) IASI LMD products on 28–29 May 2018. Only the EPIC AOCH retrievals with $AOD_{0.68} > 1.5$ are shown. The sensor scan times over Aralkum (45°N, 60°E) are shown at the top right corner of each panel.

of unrealistic AOCH values over land. However, EPIC displays unrealistic retrievals over the northern Caspian Sea. This bias resembles the surface-related UVAI signal shown in Fig. 3, indicating that the water-leaving radiance from shallow turbid waters may have been mistreated as aerosol signal in the EPIC algorithm. The EPIC AOCH retrievals at 06:50z and 09:01z 28 May show minor changes over time, likely due to a prevailing cold anticyclone which trapped dust within the boundary layer. In contrast, the AOCH increases by ~ 0.4 km from 06:41z to 08:52z on 29 May, due to the lifting by an approaching cold front.

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Figure 17(c–d) show that IASI generally retrieves higher ALH than EPIC in dust-laden scenes, over both desert surfaces and the Caspian Sea. The EPIC and IASI Level-2 products are gridded onto a $1^{\circ}\times1^{\circ}$ resolution to further assess their consistency as a function of aerosol loading. Figure 18 shows that EPIC and IASI have the poorest agreement under low aerosol loadings,

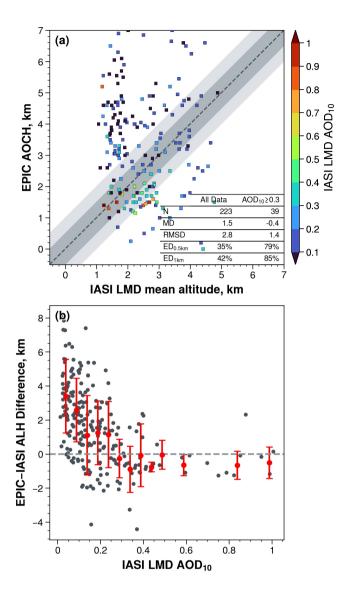


Figure 18. (a) Comparison of co-located ALH retrievals by EPIC and IASI. N, number of coincident retrievals. MD, mean difference. RMSD, root mean square difference. ED, percentage of co-located retrievals within expected differences of 0.5 and 1 km (shaded areas). (b) The EPIC—IASI difference as a function of IASI-retrieved AOD₁₀.

wherein EPIC AOCH tends to be overestimated as discussed earlier. As aerosol loading increases, the ALH difference decreases rapidly and stabilizes at $AOD_{10} \ge 0.3$ (Fig. 18(b)). Retrievals for $AOD_{10} \ge 0.3$ show a mean EPIC–IASI difference of -0.4 km and an RMSD of 1.4 km, with 79% (85%) of co-located retrievals falling within 0.5 (1.0) km differences.

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Finally, Fig. 19 shows the stereo height retrieval from MISR multi-angle images for two polygon regions located near the Kopet-Dag foothills. The digitized pixels in both regions indicate an elevated dust layer extending from ~ 0.8 km above the

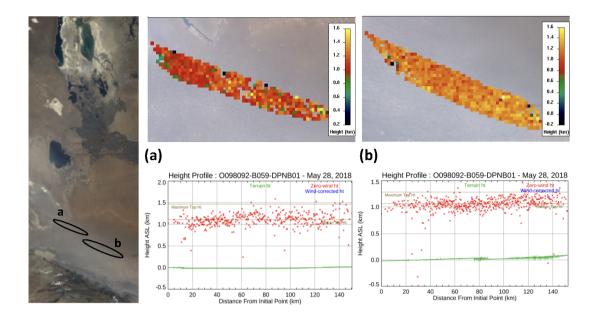


Figure 19. MINX-retrieved plume height profiles (middle and right panels) based on MISR multi-angle images on 28 May 2018 (orbit 98092), for two polygon areas denoted in the nadir-view RGB image (left panel). Surface elevation is represented in green, and retrieved plume heights in red.

ground to a sharp upper boundary at ~ 1.3 km, with a median plume height of 1.1 km. This estimate is ~ 1 km lower than the CALIOP-detected dust layer top (Fig. 2(f)), consistent with expected differences in these two techniques (Section 2.2.5). Overall, the MISR ALH retrieval aligns with CALIOP and EPIC in detecting the dust layer height at the Kopet-Dag foothills (Fig. 16(a)).

4 Conclusions

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The Aralkum Desert has emerged as a prominent source of saline dust aerosol. While satellite-based aerosol retrievals remain the most practical means for monitoring the dust activity from Aralkum, they face considerable challenges due to the absence of local aerosol observational constraint and the region's heterogeneous and highly variable surface characteristics. Although satellite algorithms are optimized for global performance, they may exhibit greater inconsistency and biases for regions with poor algorithm representations of region-specific aerosol and surface properties. To date, the performance and consistency of satellite techniques in characterizing the saline dust from Aralkum remain poorly understood. We address this knowledge gap through two key efforts.

First, we conducted a survey of satellite techniques and algorithms capable of detecting the presence, column burden, and vertical height of airborne dust from the Aralkum Desert, focusing on four families of satellite aerosol products: UVAI, mid-

visible AOD, thermal-infrared AOD, and ALH. The survey identifies the diverse approaches employed by various algorithms and the differing a priori assumptions on surface properties and aerosol optical models (e.g., refractive index, particle shape, particle size distribution). In particular, the dust optical models in these algorithms are primarily derived from AERONET measurements from West Africa and the Middle East. These models may deviate substantially from the microphysical properties of Aralkum-derived aerosols, which has been found to contain distinct chemical and mineralogical compositions compared to typical desert dust, such as abundant sulfate- and carbonate-rich minerals and negligible iron oxide content.

Currently, due to lack of in situ aerosol measurements (e.g., AERONET) near Aralkum, the extent to which these dust optical models deviate from actual conditions has yet to be determined. The impact of inaccurate algorithm assumptions on the aerosol product performance is also under-explored. Addressing these knowledge gaps requires establishing routine aerosol monitoring near Aralkum, e.g., in the downwind Karakalpakstan region. Such measurements are essential not only for validating satellite products but also for developing new or refining existing aerosol optical models for saline dust aerosol.

Second, we performed a case study to assess the cross-sensor and cross-algorithm consistency in observing a saline dust event from the Aralkum Desert during 27–29 May 2018. We compared a broad range of aerosol products, including UVAI from OMPS, TROPOMI and EPIC, midvisible AOD from MODIS, MISR, and VIIRS, thermal-infrared AOD from IASI using four different algorithms, and ALH from EPIC, CALIOP, IASI, and MISR. This synergistic, multisensor analysis allowed us to identify the complementary strengths of different techniques and uncover the product inconsistency and potential limitations. The main findings are as follows.

The UVAI products show similar spatial patterns associated with the fresh dust plume, but exhibit notable differences in magnitude and dynamic range. These discrepancies can be attributed, at least in part, to the choice of wavelength pair and the treatment of cloud scattering effect. Using the 95th percentile as a threshold for dust detection, we find overall agreement in delineating the dust plume extent between the products. All UVAI products show large positive values over the northern Caspian Sea, Garabogazköl Gulf, and Sor Kaydak salt marsh. These dust-like signals are primarily caused by enhanced UV absorption by shallow, turbid and saline waters, which causes the water-leaving UV radiance to deviate from a pure Rayleigh scattering atmosphere, similar to the effect of absorbing aerosols. This presents an important limitation for using UVAI to detect airborne dust and dust sources over Central Asia, due to interferences of turbid/salty waters, salt marshes, and saline deserts. Caution must be used to avoid misinterpreting these surface features as dust signals.

Midvisible AOD retrievals over desert surfaces exhibit considerable inconsistency across different sensors and algorithms. The choice of algorithms causes nonlinear relationships between the retrieved AOD from MODIS and VIIRS. Specifically, MAIAC retrieves lower AOD than DB under low aerosol loadings, but higher AOD under high aerosol loadings. EPS generally produces lower AOD than DB, with their divergence increasing as aerosol loading increases. In the EPS product, an urban aerosol optical model was selected for dust retrieval, leading to significantly lower AOD compared to other algorithms. A test retrieval using the dust optical model, however, shows better agreement between EPS and other algorithms. The MISR operational product exhibits significant missing data and AOD underestimation compared to MODIS and VIIRS. In contrast, the MISR research algorithm produces higher, more consistent AODs as well as improved constraints on particle microphysical properties. Over the Caspian Sea, midvisible AOD retrievals show better agreement between algorithms, despite the DT and

EPS algorithms failing to select their dust optical models during their retrieval. Generally, DT retrieves lower AOD under clean marine conditions but higher AOD under dust-laden conditions compared to MAIAC, DB, and EPS algorithms.

The high reflectivity of desert surfaces and shallow or turbid coastal waters pose a great challenge for passive ALH retrieval. The EPIC AOCH product significantly overestimates aerosol heights under low aerosol loading or background conditions. However, EPIC shows good agreement with CALIOP in detecting the dust layer with a well-defined upper boundary, resulting in a mean bias of 0.4 km and 61% (72%) of co-located retrievals within 0.5 km (1.0 km) differences. EPIC also shows reasonable agreement (with a mean difference of -0.4 km) with IASI infrared-based mean dust layer altitude over dust-laden scenes. The MISR plume height retrieval, derived from parallax of multi-angle images, aligns well with EPIC and CALIOP in detecting dust layer height over the Kopet-Dag foothills.

Data availability. The aerosol products analyzed in the study are publicly available, from the links provided in Table 1. The MISR research algorithm and plume height results are available upon request. The regridded aerosol products are available at https://doi.org/10.5281/zenodo. 13994593.

Author contributions. XX performed conceptualization, data curation, formal analysis, visualization, and writing of the initial draft. HL performed VIIRS EPS test retrieval. JL and RK performed MISR research algorithm and plume height retrievals. All authors contributed to data analysis and edited the manuscript.

Competing interests. The authors declare no competing interests.

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