



Overcoming barriers in long-term, continuous monitoring of soil CO₂ flux: A low-cost sensor system

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Abbreviations

20 CM, chamber method.

 $C_{\text{ref}},$ reference CO_2 concentration measured by Vaisala CO_2 sensor and LI-COR gas analyzer.

 C_{SCD30} , CO_2 concentration measured by low-cost SCD30 CO_2 sensors.

 F_{CM} , soil CO₂ flux measured by chamber method.

 F_{GM} , soil CO₂ flux calculated by gradient method.

- 25 F_s , soil CO₂ flux.
 - GM, gradient method.
 - LC-SS, low-cost sensor system.
 - NDIR, non-dispersive infrared.
 - SD, secure digital.
- 30 SWC, soil water content.





Abstract. Soil CO₂ flux (F_s) is a carbon cycling metric crucial for assessing ecosystem carbon budgets and global warming. However, global F_s datasets often suffer from low temporal-spatial resolution, as well as from spatial bias. F_s observations are severely deficient in tundra and dryland ecosystems due to financial and logistical constraints of current methods for F_s quantification. In this study, we introduce a

- 35 novel, low-cost sensor system (LC-SS) for long-term, continuous monitoring of soil CO₂ concentration and flux. The LC-SS, built from affordable, open-source hardware and software, offers a cost-effective solution (~USD700), accessible to low-budget users, and opens the scope for research with a large number of sensor system replications. The LC-SS was tested over ~6 months in arid soil conditions, where fluxes are small, and accuracy is critical. CO₂ concentration and soil temperature were measured
- 40 at 10-min intervals at depths of 5 and 10 cm. The LC-SS demonstrated high stability and minimal maintenance requirements during the tested period. Both diurnal and seasonal soil CO₂ concentration variabilities were observed, highlighting the system's capability of continuous, long-term, in-situ monitoring of soil CO₂ concentration. In addition, F_s was calculated using the measured CO₂ concentration via the gradient method and validated with F_s measured by the flux chamber method using
- 45 the well-accepted LI-COR gas analyzer system. Gradient method F_s was in good agreement with flux chamber F_s , highlighting the potential for alternative or concurrent use of the LC-SS with current methods for F_s estimation. Leveraging the accuracy and cost-effectiveness of the LC-SS (below 10 % of automated gas analyzer system cost), strategic implementation of LC-SSs could be a promising means to effectively increase the number of measurements, spatially and temporally, ultimately aiding in
- 50 bridging the gap between global F_s uncertainties and current measurement limitations.





1. Introduction

Soil is the largest terrestrial carbon pool (Lal, 2005). Soil carbon can be subdivided into two general pools: organic and inorganic, with the global storage of each pool at approximately 1,530 and 940 PgC, respectively (Monger et al., 2015). Both organic and inorganic soil carbon exchange with the atmosphere through soil CO₂ flux (F_s). F_s is one of the largest carbon fluxes in the Earth system (Bond-Lamberty., 2018; Friedlingstein et al., 2022). Compared with human-caused increases in atmospheric CO₂, annual CO₂ efflux from the soil into the atmosphere is much larger (Oertel et al., 2016). Therefore, F_s is considered a crucial carbon cycling metric, contributing to determining an ecosystem's carbon budget and assessing the current global warming scenarios (Bond-Lamberty et al., 2024; Xiao et al., 2012).

- 60 For decades, there has been a lack of F_s monitoring in different parts of the globe. Various initiatives have been undertaken to integrate dispersed F_s observations worldwide into publicly accessible datasets (Bond-Lamberty et al., 2020; Bond-Lamberty and Thomson, 2010; Jian et al., 2021). However, global F_s datasets often exhibit low temporal-spatial resolution and spatial bias (Stell et al., 2021; Warner et al., 2019). These limitations constrain our understanding of the mechanisms governing soil carbon dynamics
- and bias regional-to-global *F_s* estimation. The largest uncertainties in *F_s* estimates are found in tundra and dryland ecosystems primarily situated at the two poles, across Africa, Central Asia, South America, and Australia (Stell et al., 2021; Warner et al., 2019; Xu and Shang, 2016). These gaps can be primarily attributed to logistical constraints in manual data collection and the high costs of commercial measuring devices (Bouma, 2017; Forbes et al., 2023; Xu and Shang, 2016). Addressing logistical and financial constraints is crucial because critical questions concerning carbon dynamics can only be answered
- 70 constraints is crucial because critical questions concerning carbon dynamics can only be answered through extensive F_s quantification (Kim et al., 2022).

Field methods commonly used worldwide to quantify F_s are the eddy covariance method (Baldocchi et al., 1988; Massman and Lee, 2002), the flux chamber method (CM) (Davidson et al., 2002; Lundegårdh, 1927), and the gradient method (GM) (De Jong and Schappert, 1972; Hirano et al., 2003; Tang et al.,

- 2003). These methods substantially differ in principles, thus deviating in cost and F_s estimation. The eddy covariance method provides F_s from a relatively large surface area (Gu et al., 2012), whereas the CM and GM yield single-point F_s (Bekin & Agam, 2023; Maier and Schack-Kirchner, 2014). The CM allows F_s to be measured directly from the soil surface, while the GM measures subsurface soil CO₂ concentration and estimates F_s using Fick's law (Maier and Schack-Kirchner, 2014).
- 80 Despite the increasing popularity of the eddy covariance and CM, the GM remains a useful, widely used method (Chamizo et al., 2022; Hirano et al., 2003; Tang et al., 2003; Vargas et al., 2010). In comparison to the other two methods, the GM offers several advantages. First, it mitigates issues associated with eddy covariance, such as turbulence insufficiency, and with CM, such as the microclimate alterations from chamber deployment (Bekin and Agam, 2023; Maier and Schack-Kirchner, 2014). Moreover, GM
- 85 offers additional insights into the depth profile of gas production, consumption, and exchange in the soil (Maier and Schack-Kirchner, 2014). The most significant advantage of the GM is its lower purchase and installation costs (1- 2 orders of magnitude less than the CM or eddy covariance method for continuous F_s monitoring).





The development of small, low-cost, low-power, environmental sensors, microcontrollers, and 90 microcomputers has significantly advanced (Chan et al., 2021; Levintal, Suvočarev, et al., 2021). This advancement has led to the extended adoption of low-cost environmental sensing systems in the scientific community (e.g., Helm et al., 2021). Attempts to monitor soil CO₂ concentration using low-cost CO₂ sensors have been made (Blackstock et al., 2019; Hassan et al., 2023; Heger et al., 2020; Osterholt et al., 2022). Others monitored CO₂ fluxes, such as stem, terrestrial, and aquatic fluxes, by implementing the

95 CM using low-cost CO₂ sensors and data loggers (Bastviken et al., 2015; Gagnon et al., 2016; Brändle & Kunert, 2019; Carbone et al., 2019; Forbes et al., 2023; Helm et al., 2021). Implementing the GM using soil CO₂ concentrations measured by underground CO₂ sensors was also reported (Osterholt et al., 2022). However, these studies primarily focused on comparing the precision and accuracy of the low-cost systems with high-end reference systems, typically conducting short-term in-situ examinations lasting from days to weeks, which limits insights into their stability and practicality for long-term use.

To narrow the gap between the uncertainties in the regional-to-global F_s estimations and the capabilities of current measurement methods, in this study, we introduce an open-source, low-cost sensor system (LC-SS) for continuous, long-term monitoring of soil CO₂ concentrations and F_s . The LC-SS was fieldtested over ~6 months in arid soil conditions to examine its stability and accuracy compared to a

105 commercial automated flux chamber. Detailed, step-by-step, do-it-yourself guides describing the design, assembly, and installation are provided to assist non-engineer end-users with easy replication and customization.

2. Materials and methods

2.1. Hardware

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- 110 The LC-SS consists of two units: the control unit and the sensing unit (Fig. 1a & Fig. S1). The control unit includes a microcontroller (Feather M0 Adalogger, Adafruit, USA) accompanied by Secure Digital (SD) card, a latching relay for power control (Latching mini FeatherWing, Adafruit, USA), a clock for accurate time readings (DS3231 RTC, Adafruit, USA), a screen to display real-time results (0.96" 128x64 OLED Graphic Display, Adafruit, USA), and a multiplexer allowing communication to the sensing unit
- (Gravity 1-to-8 I2C Multiplexer, DFRobot, China). For power, the microcontroller uses a 3.7 V lithiumion polymer battery (3.7 V 6000 mAh, Adafruit, USA) charged by solar energy via a solar charger (bq24074, Adafruit, USA), and a 6 W 6 V solar panel (Adafruit, USA). The sensing unit includes seven sensors: six CO₂ sensors (SCD30, Sensirion, Switzerland, 0-10,000 ppm, accuracy between 400 to 10,000 ppm: ±30 ppm + 3 % of full range), and an atmospheric microclimate sensor (pressure, relative
- 120 humidity, and temperature, MS8607, DFRobot, China). The SCD30 CO₂ sensor also measures temperature and relative humidity (accuracy: ±0.4 °C and ±3 %, respectively).

The LC-SS used in this study featured two waterproof designs of CO_2 sensors (**Fig. 1b**): a 50 ml Falcon tube design and a thin coating design. The 50 ml Falcon tube design is an easy-made and long-lasting option, while the thin coating design is suitable for near-surface deployment, effectively reducing errors associated with measurement depths. Both designs included a hydrophobic membrane to keep water from penetrating the sensor while allowing gas exchange with the surrounding soil. Providing two designs

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offers end users the flexibility to adopt the option that best fits their needs and accessibility. The detailed do-it-yourself guide of the LC-SS assembly and sensor waterproof designs can be found on our GitHub page (https://github.com/OpenDigiEnvLab/soil-CO₂-sensor-system). The hardware details are summarized in **Table 1**.

Table 1. Summary of hardware components with examples for potential suppliers (components can be purchased from other suppliers).

Component	Quantity	Cost/item	Sources	Comments
Component	Quantity	(USD)	Sources	comments
Feather M0 Adalogger	1	19.95	Adafruit (https://www.adafruit.com/ product/2796)	A low-cost, low-power data logger
RTC DS3231 with CR1220 battery	1	17.5	Adafruit (https://www.adafruit.com/ product/3013)	Provides accurate time for the data logger; CR1220 battery should be purchased separately
Gravity 1-to-8 I2C Multiplexer	1	6.9	DFRobot (https://www.dfrobot.com/p roduct-1780.html)	Enables the connection of multiple CO ₂ sensors to one data logger
0.96" 128x64 OLED Graphic Display	1	17.5	Adafruit (https://www.adafruit.com/ product/326)	For real-time display of measurement results
Latching relay FeatherWing	1	7.95	Adafruit (https://www.adafruit.com/ product/2923)	For power control: programmed to turn on and turn off the system to optimize power consumption
P2886A feather header kit	1	0.95	Adafruit (https://www.adafruit.com/ product/2886)	To connect Feather M0 Adalogger with Latching relay FeatherWing
Lithium Ion Battery Pack-3.7 V 6600 mAh	1	24.5	Adafruit (https://www.adafruit.com/ product/353)	To provide power for the control and sensor unit
Adafruit Universal USB / DC / Solar Lithium Ion/Polymer charger - bq24074	1	14.95	Adafruit (https://www.adafruit.com/ product/4755)	To charge the battery using the solar energy from solar panel
Medium 6 V-2 W Solar panel	1	29	Adafruit (https://www.adafruit.com/ product/200)	
SD/MicroSD memory card (8GB SDHC)		9.95	Adafruit (https://www.adafruit.com/ product/1294)	
SCD30 CO ₂ sensors	6	61.79	Digikey (https://www.digikey.com/e n/products/detail/sensirion- ag/SCD30/8445334)	4 sensors with thin coating and 2 sensors with 50ml falcon tube
STEMMA QT MS8607 humidity-temperature- pressure sensor	1	14.95	Adafruit (https://www.adafruit.com/ product/4716)	To measure atmospheric humidity, temperature, and pressure
Weather-proof container	1	10	Local suppliers	For the control unit
3D-printed frame	4	2	Printed locally	For thin coating of 4 sensors
Ероху	500 grams	5	Local suppliers	For thin coating of 4 sensors
Plasti Dip	50 ml	5	Local suppliers	For thin coating of 4 sensors





Cables, wires, and	~50	Local suppliers	
general equipment:			
$+7 \times 4$ -wire cable 3 m (6			
for SCD30 sensors and 1			
for MS8607 sensor)			
+ Wires in colors white,			
green, red, black			
$+8 \times 4$ -pin cables with			
Female Dupont			
connectors			
+ 3 × JST PH 2-pin			
cable-male connector			
$+ 1 \times 4$ -pin PH2.0 cable-			
male connector			
+ 2 lever wire connectors			
+ On/off switch			
+ Shrinking sleeves of			
different sizes			
+ Superglue			
- Supergiue			
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The hardware is controlled using open-source Arduino code written in C++ (www.arduino.cc). The complete code uploaded to the LC-SS can be downloaded from our GitHub page. During every measurement cycle, all sensors are activated, and measurement readings are logged onto the SD card with a timestamp and displayed on the user screen. The default measurement interval is 10 minutes and can be easily customized if required.

2.2. Field installation

- 140 The LC-SS was installed at the Wadi Mashash Experimental farm located in the Northern Negev desert of Israel (31°04'14'' N, 34°51'62'' E; 360 meters above sea level). The local climate is arid, with an average annual precipitation of 116 mm, primarily occurring between October and April. The daily average maximum and minimum temperatures in January (winter) are 15.9 °C and 8.0 °C, and in August (summer) are 33.3 °C and 20.7 °C, respectively. Soil is characterized as sandy-loam loess soil (72.5 %)
- sand, 15 % silt, and 12.5 % clay). Soil organic matter content between 0-5 and 5-10 cm is 2.96 and 2.62
 %, respectively. CaCO₃ content between 0-5 and 5-10 cm is 50 and 47 %, respectively.

The LC-SS was installed from 24/05/2023 to 14/11/2023, providing continuous measurements for 175 successive days, spanning both summer and winter. Three CO₂ sensors were installed at each depth (5 and 10 cm) to allow comparison and statistical calibration, as detailed in section 2.3. At each depth, two

- 150 sensors with a thin coating design (labeled as sensor#1_5cm, sensor#2_5cm and sensor#1_10cm, sensor#2_10cm) and one sensor with the 50 ml Falcon tube design (labeled as sensor#3_5cm and sensor#3_10cm) were deployed (Fig. 1c). To enable manual gas sampling during field calibration campaigns, a 60-cm Polyurethane tube (outer diameter × inner diameter = 6×4 mm) was inserted at each depth. One end of the tube was aligned with the CO₂ sensors, while the other end extended above the
- 155 soil surface and was sealed with a valve (Fig. 1d). Additional measurements included soil water content (SWC) using time-domain reflectometers (TDR-315, Acclima, Inc., USA) installed at 3 and 10 cm depths. Air temperature, atmospheric pressure, and precipitation data were taken from a meteorological





station located at the same field where the LC-SS was installed (https://ims.gov.il; Zomet Hanegev station).

160 F_s measured using the CM (F_{CM}) was measured at 1-hour intervals using a non-dispersive infrared (NDIR) gas analyzer (LI-8100A, LI-COR, USA) connected to four automated non-steady-state chambers (104C, LI-COR, USA). F_{CM} was determined as the average readings obtained from the four chambers. The F_{CM} measurements were conducted for the periods 24/05-18/06, 17-23/08, and 5/9-17/10/2023.



165 Figure 1: The design of the low-cost sensor system (LC-SS) (a), two waterproof designs for the SCD30 CO₂ sensors (b), field installation of the CO₂ sensor line at 5 cm (c), and the site after installation (d).

2.3. Two-step calibration of the CO₂ sensors

Calculating F_s based on the GM (F_{GM}) (section 2.4) requires accurate soil CO₂ concentrations. Therefore,
 we developed a two-step calibration process for the underground CO₂ sensors: a field calibration and a statistical calibration.

For the field calibration, CO_2 concentrations from the low-cost SCD30 CO_2 sensors (C_{SCD30}) were calibrated against reference CO_2 concentrations (C_{ref}). C_{ref} were obtained by measuring the CO_2 concentrations sampled from the sampling tube either by a high-end CO_2 sensor (GMP252, Vaisala Inc.,

175 Finland) or by LI-COR gas analyzer (LI-8100A, LI-COR, USA) with three replicates from each depth (depending on field availability). C_{ref} by the Vaisala CO₂ sensor was measured every 5 hours between

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6:00 and 16:00 on two days, 12/06 and 17/07/2023. C_{ref} by the NDIR gas analyzer was measured every 3 hours from 12:00 to 21:00 on 10/9/2023 and from 00:00 to 12:00 on 11/09/2023. In total, the calibration was determined with 21 and 17 measurement points for each sensor at 5 and 10 cm, respectively, over the range of concentrations from ~300 to ~650 ppm.

The statistical calibration consisted of two sequential algorithms. The first algorithm (**Fig. 2a**) addressed abrupt anomalies or jumps of each sensor reading by flagging data points where the difference between measured and smoothed data exceeded 10 % of the measured data point. The smoothed data was executed using the LOESS smoothing algorithm (Jacoby, 2000), which fits multiple locally weighted least squares regressions to estimate a smooth curve through a scatterplot of data points. The second algorithm (**Fig.**)

2b) focused on detecting and correcting gradual drift, utilizing user-defined thresholds to determine when the difference between one sensor and the other two sensors becomes significant enough to require correction. Thresholds of 5 % and 10 % relative to the average for sensors at 5 and 10 cm, respectively, were defined. All calibration algorithms were applied post-data acquisition, ensuring accurate CO₂
190 concentrations essential for calculating *F_{GM}*.



Figure 2: Flowchart of the two statistical calibration algorithms. The algorithm to correct jumps (a) and the algorithm to correct gradual drift (b).

2.4. Calculating the F_{GM} using the LC-SS data





195 To calculate F_{GM} , CO₂ concentrations were first corrected for temperature and pressure (Eq. S1) and then converted to mole density (Eq. S2). The GM is based on Fick's first law, where F_{GM} from depth z to the soil surface is calculated as (De Jong and Schappert, 1972):

$$F_{GM} = -D_s \frac{C_z - C_0}{z} \tag{1}$$

where F_{GM} [µmol m⁻² s⁻¹] is assumed to be equal to F_s from the soil surface (a positive F_{GM} indicates CO₂ efflux and a negative F_{GM} indicates CO₂ influx), D_s [m² s⁻¹] is the CO₂ diffusion coefficient between

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depth z [m] (negative) and the soil surface (0 m), C_z [µmol m⁻³] is the CO₂ mole density at depth z, and C_0 [µmol m⁻³] is the atmospheric CO₂ mole density ($C_0 = 18741.63$ µmol m⁻³ or 420 ppm). The reference value of 420 ppm was based on the average atmospheric CO2 concentrations measured by a LI-COR gas analyzer between 16/05-18/06 and 2/7-13/8/2023. F_{GM} in this study was calculated using CO₂ concentration gradients between 0 and 5 cm depth, as recommended by Chamizo et al. (2022).

205 The relative CO₂ diffusion coefficient in the soil $(D_s/D_a$ where D_a [m² s⁻¹] is the CO₂ diffusion coefficient in free air) is estimated based on soil air content-dependent models $M(\varepsilon)$, with ε being the volumetric air-filled porosity:

$$\frac{D_s}{D_a} = M(\varepsilon)$$
^[2]

 D_a needs to be corrected to in-situ environmental conditions (Jones, 2013) using Eq. S3. Models used in this study to calculate $M(\varepsilon)$, including the most common models, are listed in **Table 2**.

210 Table 2: Classical soil diffusion coefficient models used for the GM. Porosity (φ) values were calculated as described in Eq. S4, and equal to 45%.

Authors	Model	Originally developed for
Buckingham [1904]	$D_s = D_a \varepsilon^2$	Repacked soils
Penman [1940]	$D_s = 0.66D_a \varepsilon$	Dry porous materials
Millington & Quirk [1961]	$D_s = D_a \frac{\varepsilon^{10/3}}{\varphi^2}$	Different porous materials
Millington [1959]	$D_s = D_a \varepsilon^{4/3}$	Comparison of published results
Campell [1985]	$D_s = 0.9 D_a \varepsilon^{2.3}$	Aggregated silt loam
Moldrup [2000]	$D_s = D_a \frac{\varepsilon^{2.5}}{\varphi}$	Unstructured natural soils
Marshall [1959]	$D_s = D_a \varepsilon^{1.5}$	Different porous materials
Currie [1970]	$D_s = D_a (\frac{\varepsilon}{\varphi})^4 \varphi^{1.5}$	Sand
Lai [1976]	$D_s = D_a \varepsilon^{5/3}$	Undisturbed and repacked soils





Sadeghi [1989]	$D_s = 0.18 D_a (\frac{\varepsilon}{\varphi})^{2.98}$	Soils with clay content from 10.3 to 51.1 %

2.5. Validation of F_{GM} using F_{CM}

 F_{GM} values calculated using the gas diffusion models in **Table. 2** were validated using measured F_{CM} . **215** First, we conducted a cross-correlation analysis (Horvatic et al., 2011) between F_{CM} and F_{GM} to systematically assess the lag time between measured F_{CM} and calculated F_{GM} , which reflects the time delay associated with gas transport from the 5 cm depth to the soil surface as previously reported (Sánchez-Cañete et al., 2017). Then, we shifted the F_{GM} using the identified lag time to align with the temporal dynamics of F_{CM} .

220 **3.** Results and discussion

Because this study focuses on the development and field performance of the LC-SS for measuring soil CO₂ concentrations and calculating F_{GM} , our results and discussion will focus mainly on the LC-SS capabilities, such as long-term stability and accuracy.

3.1. CO₂ sensors calibration

- 225 The field calibration curves for the six low-cost CO₂ sensors are presented in Fig. 3a. All sensors show good linearity with high R² > 0.8. The statistical calibration algorithms (Fig. 2) improved both the sudden and permanent drifts (Fig. 3b). At 5 cm, only 6.6, 2.1, and 4.4 % out of 25,200 readings of sensors #1, #2, and #3, respectively, required correction. At 10 cm, 34.5, 1.9, and 1.39 % readings were corrected for sensor #1, #2, and #3, respectively. The results validate the high stability of the CO₂ sensors after ~6
- 230 months. The one exception was sensor#1_10cm, which exhibited significant data requiring correction. However, the observed drift was systematic; therefore, it was easily corrected by referencing the data from the other two sensors at the same depth (i.e., Fig. 3b).







Figure 3: Calibration curves of the SCD30 CO₂ sensors (a) and distribution of CO₂ concentrations collected by six SCD30 CO₂ sensors after each calibration step (b).

3.2. Soil CO₂ concentrations

The 10-min interval time series of CO₂ concentrations at 5 and 10 cm, and precipitation for one month (24/05-24/06/2023) as an example are shown in Fig. 4a-b. The complete dataset for the entire studied period is reported in the supplementary material (Fig. S2 and Fig. S3). The magnitude of CO₂
concentrations at 10 cm was greater than at 5 cm (~340 - ~730 ppm compared to ~320 - ~1000 ppm, respectively). CO₂ concentrations at both depths during daytime (~7:00 - ~21:00 in summer and ~8:00 - ~19:00 in winter) were higher than in the atmosphere, with average daytime concentrations of 545 and 621 ppm at 5 and 10 cm, respectively. However, during nighttime (all hours excluding daytime hours), soil concentrations were lower than in the atmosphere, with average nighttime concentrations of ~380

- 245 ppm at both depths. This indicates an efflux of CO₂ from the soil to the atmosphere during daytime in contrast to an influx of CO₂ from the atmosphere into the soil during nighttime. Daytime efflux and nighttime influx were previously observed in arid soils (Cueva et al., 2019; Hamerlynck et al., 2013; Sagi et al., 2021). The study conducted by Sagi et al. (2021) in the Negev Desert revealed a connection between soil CO₂ influx, cooling soil temperatures, and high soil-to-air temperature gradients,
- 250 specifically occurring when the soil water content (SWC) was below the threshold of ~8%. We observed similar conditions during our study (Fig. 4c-e).

 CO_2 diurnal cycles at 5 cm showed differences between days with and without precipitation (**Fig. 4c-d**) and between summer months (May-September) and winter months (October-November) (**Fig. 4d-e**). On days with precipitation, the average CO_2 concentration increased from 400 ± 20 ppm around 8:00-9:00 to a daily peak of 530 ± 70 ppm at 16:00. On days without precipitation, the morning increase occurred

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earlier around 11:00–13:00, reaching 662±16 ppm. Inter-season patterns were also observed, with a winter daily peak lower than the summer daily peak by 106±22 ppm. The occurrence of diurnal cycles during all seasons is a typical phenomenon previously reported (Spohn and Holzheu, 2021; Chamizo et al., 2022).

260 Our results showcase the ability of the underground CO₂ sensor array to capture CO₂ concentration profiles, typical diurnal changes, and seasonal changes. The results also highlight the capability of the sensor array to capture "hot moments", such as the effect of precipitation events on CO₂ concentration in arid soils, significantly contributing to the understanding of the driving mechanisms underlying these moments.



Figure 4: An example of one month of continuous CO₂ concentration measurements between 24/05-24/06/2023 at 5 cm (a) and 10 cm (b) depths, average daily values at 5 cm of CO₂ concentration, temperature, and soil water content (SWC) during four days with precipitation from May to September (c), 130 days without precipitation between May and September (d), and 44 days without precipitation between October and November (e).

3.3. FGM calculations

The calculated F_S using the GM (F_{GM} , Eq. 1) and the measured F_S using the CM (F_{CM}) are presented in Fig. 5a; for simplicity, continuous results from only three representative days without precipitation are shown. Calculated F_{GM} using different soil gas diffusion models (Table 2) were compared to the F_{CM} . We observed a time lag in all calculated F_{GM} compared to the F_{CM} . Since the F_{GM} was calculated using the CO₂ concentration gradient between 5 cm and the soil surface, F_{GM} can only represent subsurface F_S .

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Cross-correlation analysis was used to evaluate the lag time between the surface F_{CM} and the sub-surface F_{GM} , resulting in a lag time of three hours. To establish temporal alignment between F_{GM} and F_{CM} , F_{GM} was shifted three hours to the past (**Fig. 5a**, dashed lines).

- 280 A delay was also observed in the nocturnal influx F_{GM} compared to the nocturnal influx F_{CM} . Given the direction of nocturnal CO₂ exchange—moving from the atmosphere into the soil—at any given moment, the volume of CO₂ traversing a unit surface area at a given time (CO₂ influx in units of μ m m⁻² s⁻¹) must exceed that passing through the subsurface region at 5 cm depth. This leads to a more negative nocturnal influx F_{CM} than nocturnal influx F_{GM} . Therefore, we used the average daily minimum of nocturnal influx
- 285 F_{CM} as a reference to shift the magnitude of F_{GM} . The time lag between F_{GM} and F_{CM} associated with measurement depth was also reported in previous studies (Sánchez-Cañete et al., 2017); the delay generally increases with sensor depth.

The magnitude and distribution of F_{CM} and F_{GM} are presented in **Fig. 5b** (box plots). The total net flux over 175 days was calculated by determining the total area under the curve of CO₂ efflux minus the total

- 290 area above the curve of CO₂ influx. The average daily flux [g C m⁻² day⁻¹] was obtained by dividing the total net flux by the total number of days (**Fig. 5b**, blue scatters). Except for the F_{GM} by the Buckingham gas diffusion model (Buckingham F_{GM}), a discrepancy between F_{GM} and F_{CM} was observed. Sánchez-Cañete et al., (2017) speculated that ex-situ gas diffusion models yield substantial uncertainties when applied to other soils simply because these models were developed based on soil porosity and SWC of
- 295 specific soil types (**Table 2**). In comparison to F_{CM} , Buckingham F_{GM} was the most comparable, for both magnitude and distribution, as well as average daily net flux. The outliers observed from the boxplot of F_{CM} correspond to CO₂ fluxes induced by precipitation events on 28/05/2023, 13/06-2023, and 9/10/2023.







- Figure 5: Diurnal cycles of F_S measured by the chamber method (F_{CM} , green scatters), by the gradient method (F_{GM} , solid lines), and by the gradient method using a 3-hour lag time (dashed lines) during three representative days without precipitation (a), comparison of F_{CM} (green) and F_{GM} (red; calculated using published gas diffusion models), and average daily flux (blue scatter) (b).
- 305 The linear regression between Buckingham F_{GM} and measured F_{CM} is presented in **Fig. 6a** ($\mathbb{R}^2 = 0.70$). F_S obtained by these two methods correlated mostly on days without precipitation (**Fig. 6b**). In contrast, on days with precipitation such as 13/06/2023 with 2 mm day⁻¹, large variations between the two methods were observed (**Fig. 6c**). The instantaneous increase of F_{CM} due to precipitation was a well-recognized phenomenon when rewetting occurs in water-limited arid soils (Andrews et al., 2023; Barnard et al.,
- 310 2020; Fierer & Schimel, 2003). The observed CO₂ pulse, as measured by CM, agrees with the observed pattern of very high rates right after rewetting and slowly declines over time by Kim et al. (2012). These precipitation-induced CO₂ pulses were underestimated by the GM. Previous studies also reported that the GM did not capture the abrupt CO₂ pulse increases after water application (Jiang et al., 2022; Yang et al., 2018). Therefore, the utility of the GM in general is often accompanied by a validation/calibration
- 315 using a short-term *F_s* measurement for the CM (Chamizo et al., 2022; Sánchez-Cañete et al., 2017).







Figure 6: Linear regression between the Buckingham gradient flux (F_{GM}) and the chamber flux (F_{CM}) (a), the Buckingham F_{GM} and the F_{CM} during two days without precipitation (23-24/07/2023) (b), and during two days with precipitation (13-14/06/2023) (c).

320 3.3. Limitation and modification

We acknowledge that the F_{GM} calculation method has its limitations. F_{GM} calculation requires an accurate diffusion coefficient of CO₂ between 5 cm and the soil surface. This study did not directly measure but used models to estimate the diffusion coefficient, supplemented by F_{CM} measurements for validation. F_{CM} measurements, which require chambers and a LI-COR gas analyzer, may pose a cost constraint for resource-limited research. This limitation is not unique to the LC-SS but applies to GM regardless of the sensor type. Even though using F_{CM} measured by high-end gas analyzers to validate F_{GM} is a recommended practice (Chamizo et al., 2022; Sánchez-Cañete et al., 2017) and applied in this study, it is not inherently obligatory. An alternative is to measure site-specific diffusion coefficient and calculate F_{GM} without using published gas diffusion models. For example, Osterholt et al. (2022) suggested an approach to inject CO₂ as a tracer gas to estimate diffusion coefficient. Furthermore, high-end, expensive

- chambers and gas analyzers can also be replaced with a low-cost, open-source chamber system (e.g., Forbes et al., 2023). When used with the LC-SS, only one chamber-gas analyzer system per several LC-SSs is needed since only a short duration of F_{CM} measurements is required for validation.
- The LC-SS presented here relies exclusively on an SD card for data logging and storage, which requires manual data retrieval and lacks real-time accessibility for monitoring and troubleshooting. Alternatively, we introduce an updated version of LS-SS equipped with a modem for real-time data updates and immediate troubleshooting whenever necessary (e.g., Levintal., et al., 2021). A detailed, step-by-step, do-it-yourself guide for the updated version is also available on our GitHub page.

4. Conclusions

340 This study introduces an innovative LC-SS developed for continuous, long-term monitoring of soil CO_2 concentration and F_s , facilitating in-situ soil-gas-related research. The LC-SS was built from low-cost, readily available hardware and open-source software components. The LC-SS design emphasizes modularity, with publicly available, comprehensive, technical documentation for each module, allowing straightforward replication and customization for non-engineering, low-budget end-users worldwide.





345 The LC-SS was field-tested for ~6 months, showcasing high stability, minimal maintenance requirements, and capabilities to capture the temporal dynamics of soil CO₂ concentrations, including diurnal and seasonal variabilities. Furthermore, the agreement observed between the calculated F_{GM} and measured F_{CM} , both in the short term (i.e., sub-daily fluctuation) and in the long term (i.e., net CO₂ exchange over ~6 months), demonstrate the potential of the LC-SS as a new approach for F_s 350 quantification.

In conclusion, the LC-SS, priced at ~USD700, not only provides high accuracy of F_s but also offers higher temporal resolution and the potential for improved spatial resolution if widely adopted. This, in turn, could contribute to a more comprehensive dataset for regional-to-global estimation of F_s and advancing our understanding of the global soil carbon cycle.

355 Data Availability

The data are available within the above manuscript, the supplementary information, and our GitHub repository.

Author Contributions

TTN and EL conceptualized and conducted the study and wrote the first manuscript draft. EL providedthe resources. All the authors (TTN, NB, AA, MM, NA, and EL) contributed to the final version.

Competing interests

The authors declare that they have no conflict of interest.

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