The Size Distributions of Faults and Earthquakes: Implications for Orogen-Internal Seismogenic Deformation

Sandro Truttmann[1], Tobias Diehl[2], Marco Herwegh[1], Stefan Wiemer[2]

[1]Institute of Geological Sciences, University of Bern, Bern, 3012, Switzerland

5 [2]Swiss Seismological Service, ETH Zürich, Zürich, 8092, Switzerland

Correspondence to: Sandro Truttmann (sandro.truttmann@gmail.com)

Abstract. Pre-existing geological discontinuities such as faults represent structural and mechanical discontinuities in rocks which influence earthquake processes. As earthquakes occur in the subsurface, seismogenic reactivation of pre-existing fault networks is difficult to investigate in natural settings. However, it is well-known that there exists a physical link between both

10 faults and earthquakes since an earthquake's magnitude is related to the ruptured fault area and therefore fault length. Furthermore, faults and earthquakes exhibit similar statistical properties, as their size distributions follow power laws.

In this study, we exploit the relation between the size distributions of faults and earthquakes to decipher the seismic deformation processes within the exhumation-related orogen-internal setting of the Southwestern Swiss Alps, which due to its well-monitored seismic activity and the excellent outcrop conditions provides an ideal study site. Characterizing the size

15 distribution of exhumed fault networks from different tectonic units based on multi-scale drone-based mapping, we find that power law exponents of 3D fault networks generally range between 3 and 3.6. Comparing these values with the depth-dependent exponents of estimated earthquake rupture lengths, we observe significantly larger values of 5 to 8 for earthquake ruptures at shallow depths (< 3 km below sea level (BSL)). At intermediate crustal depths (~3 to 9 km BSL), the power law exponents of faults and earthquakes appear to be similar. These findings imply depth-dependent differences in the seismogenic

20 reactivation of pre-existing faults in the study region: while partial rupturing is the prevailing deformation mechanism at shallow depths, faults are more likely to rupture along their entire length at intermediate crustal depths. Therefore, the present-day near surface differential stresses are likely insufficient to rupture entire pre-existing faults seismogenically. Our findings have direct implications for seismic hazard considerations, as earthquakes that rupture along entire faults appear to become less likely with decreasing depth.

1 Introduction

Within the Earth's crust, the occurrence of earthquakes is commonly attributed to the reactivation of pre-existing geological discontinuities, commonly referred to as faults. Nevertheless, in regions characterized by extensive faulting and scattered seismic activity, like in collisional orogens such as the Alps, the task of assigning earthquakes to specific fault segments

30 becomes notably complex. This challenge limits our ability to decipher the current deformation processes and discern the significance of such intricate pre-existing fault networks in influencing the underlying seismic events.

Despite their complexity, faults in nature often appear qualitatively self-similar at different scales. This qualitative self-similarity can be quantified by power law distributions, inherently implying scale invariance and thus absence of a characteristic length scale, which is different to any other statistical distribution. Previous studies have shown that a power law

35 is best suited for describing the size (or length) distribution of natural fault traces (Odling, 1997; Bonnet et al., 2001; Torabi and Berg, 2011; Yielding et al., 1996; Davy et al., 2010; Scholz, 2019), even if other types of distributions have been proposed (Cowie et al., 1995, 1993; Ackermann et al., 2001; Nicol et al., 1996). A power law distribution defines the number n of features of a given length l as:

$$n(l) = c\, l^{-\alpha} \tag{1}$$

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where α represents the power law exponent (i.e., the slope of the linear trend in a log-log plot), and c denotes the density constant. The power law exponent α is of main interest herein, since it measures the relative proportion of short and long features (Davy, 1993; Pickering et al., 1995). As fault data is often acquired at a single mapping scale, a major problem for the

45 identification of power law distributions is the limited dynamic length range of the fault traces and the uncertainties related to sampling bias, which can lead to size distributions that appear to deviate from power laws (Odling, 1997; Scholz, 2007, 2019; Torabi and Berg, 2011).

Similar to faults, it is well-known that earthquake magnitudes follow power law distributions, often referred to as the Gutenberg-Richter law (Gutenberg and Richter, 1944) or magnitude-frequency distribution, implying that also earthquakes are

50 scale invariant. As proposed by Hatton et al. (1993), "the observed fractal nature of both fault length distributions and earthquake magnitude-frequency distributions suggests that there may be a relationship between the structure of active fault systems and the resulting seismicity." This is supported by the fact that the statistical properties of micro-fracturing at the laboratory scale are similar to earthquakes (e.g., Scholz, 1968; Mogi, 1962). Furthermore, faults and fractures represent the geometrical anisotropies that provide planes of weakness within the rock masses and are thus most likely to be reactivated

55 seismically if suitably oriented with respect to the local stress field. Faults and earthquakes can thus be regarded as the long- and short-time-scale phenomena of brittle tectonics, and there should exist an inherent relation between the size distributions of faults and earthquakes (Scholz, 2019, 1998; Turcotte, 1997). However, the relationship between these size distributions in natural datasets has yet received little attention, mainly due to the challenging acquisition of reliable quantitative information

of fault networks due to limited outcrop conditions and small dynamic range. The Southwestern Swiss Alps, with (i) a long-lasting exhumation history during several million years (e.g., Egli et al., 2017; Herwegh et al., 2020; Boutoux et al., 2016; Cardello et al., 2024), (ii) well-preserved extensive Neogene faulting in high-Alpine regions with formation depths similar to the present-day earthquakes (Cardello and Mancktelow, 2015; Huggenberger and Aebli, 1989; Cardello et al., 2024), (iii) an increased and exceptionally well-recorded seismic activity (e.g., Diehl et al., 2021a; Lee et al., 2022), and (iv) on-going vertical tectonics (e.g., Ustaszewski and Pfiffner, 2008; Brockmann et al., 2012; Herwegh et al., 2023; Piña-Valdés et al., 2022) implying a similar stress field to the time of fault formation, provide a unique natural laboratory to investigate the link between the size distributions of faults and earthquakes. Owing to the abundant occurrence of thermal springs, the region is also a potential target for the exploitation of geothermal energy, where knowledge of faulting at depth and constraints on the potential risks of induced seismicity are critical.

Herein, we explore the relation between the size distributions of faults and earthquakes and its implications for orogen-internal seismogenic deformation in the exhumation-related (vertical) tectonic setting of the Rawil depression region (Southwestern Swiss Alps). We use field observations and drone-based fault trace mapping on multiple scales to quantitatively characterize the size and orientation distributions of fault networks in different tectonic units. We employ a multi-scale power law fitting approach on the fault network data, which allows to expand the limited dynamic length range of single-scale observations. We then exploit the relationship of the fault orientation and size distributions with similar properties of the recent seismic activity, and discuss the implications for seismogenic fault reactivation processes in the subsurface.

2 Regional Setting

In the framework of a nation-wide seismic hazard assessment, Switzerland was zoned into different seismotectonic domains (Wiemer et al., 2016). We herein focus on the seismotectonic domain z21 in the Southwestern Swiss Alps, mainly due to its well-exposed rock outcrops and the exceptionally well-monitored enhanced seismic activity (Fig. 1). In the study area, several External Crystalline Massifs (ECMs) are exposed: the Aiguilles Rouges massif in the West, and the Aar and Gastern massifs in the East (Fig. 1a). Between their exhumed parts, these basement units form a saddle-like structure, commonly referred to as the Rawil depression, which is overthrusted by the Helvetic limestone nappes (Burkhard, 1988; Dietrich, 1989; Dietrich and Casey, 1989; Ramsay, 1989, 1981). The Helvetic nappe system is composed of different, heavily folded nappes, which have been stacked on top of each other during an early thin-skinned deformation phase of the Alpine orogen (e.g., Musso Piantelli et al., 2022; Escher et al., 1993; Pfiffner 1993; Burkhard, 1988; Ramsay, 1981, 1989). In a late-Alpine stage, dominated by thick-skinned vertical tectonics, both the crystalline basement units and the Helvetic limestones have been heavily affected by late-Alpine deformation, resulting in pervasive and complex faulting that affects all tectonic units (Cardello and Mancktelow, 2015; Gasser and Mancktelow, 2010; Huggenberger and Aebli, 1989; Herwegh et al., 2020, 2023; Cardello et al., 2024). Some of the predominantly subvertical late-Alpine faults have been linked to the regional seismic activity (Cardello and Mancktelow, 2015; Pavoni, 1980a; Ustaszewski et al., 2007; Ustaszewski and Pfiffner, 2008; Pavoni and Mayer-Rosa, 1978; Cardello et al.,

2024). Apart from the Rhône-Simplon Fault Zone (RSF) along the southern margin of the study area (e.g., Campani et al., 2014, 2010; Egli and Mancktelow, 2013; Mancktelow, 1985), regional-scale faults are largely absent at the surface of the study area. The nappes of the Helvetic units are separated by shallow-dipping thrust faults which are arguably not seismically active nowadays (Lee et al., 2022), so we herein do not discuss these thrusts further.

95 The presently dense seismic monitoring network in the region resolves the seismic activity exceptionally well, detecting earthquakes with a magnitude of completeness M_C of about $M_L \approx 1.5$ until 2016 and about $M_L \approx 1.0$ thereafter (Diehl et al., 2021a; Lee et al., 2023). The earthquakes predominantly occur in a NE-SW striking, elongated corridor in the center of the Rawil depression (Fig. 1b), which is referred to as the conceptual Rawil Fault Zone (RFZ) (Lee et al., 2023). The seismicity at depth arguably reactivates a complex system of subvertically oriented faults (Diehl et al., 2021a, 2018; Lee et al., 2023;

100 Truttmann et al., 2023). This is supported by the variety of previously published, predominantly strike-slip-type focal mechanisms shown in Fig. 1b (Baer et al., 2005, 2003, 1997; Deichmann et al., 2012, 2006, 2002, 2000; Delacou et al., 2005; Diehl et al., 2021a, 2018, 2013; Jimenez and Pavoni, 1983; Maurer, 1993; Maurer and Deichmann, 1995; Pavoni et al., 1997; Truttmann et al., 2023), suggesting an overall transtensional regime (Kastrup et al., 2004).

The Southwestern Swiss Alps are further characterized by their long-lasting vertical tectonics. During the latest stage of the

105 Alpine orogeny, thick-skinned tectonics prevailed and led to the exhumation of the ECMs (e.g., Herwegh et al., 2020; 2023; Boutoux et al., 2016). Recent uplift rates in the range of 1 mm per year (Brockmann et al., 2012; Piña-Valdés et al., 2022) and the pronounced seismic activity document the ongoing exhumation (Figs. 1b and c). As a consequence of these long-lasting vertical tectonics, a similar stress field likely prevailed during both the formation of the exhumed fault networks and today's earthquakes.

110 In summary, the investigated seismotectonic domain reveals complex and pervasive fault networks, well-recorded seismic activity, and long-lasting vertical tectonics. In our view, the Rawil depression region in the Southwestern Swiss Alps thus provides a unique natural laboratory to elaborate the statistical link between faults and earthquakes in an orogen-internal setting.

3 Data and Methods

115 ### 3.1 Fault Networks

3.1.1 Fault Data

We selected four sites along the Rawil depression to conduct detailed analysis of the fault networks in the ECM units of (A) the Aiguilles Rouges massif and (D) the Gastern massif, as well as in the Helvetic limestones of (B) the Diablerets and (C) the Wildhorn nappes (Fig. 1). As pronounced glacial and fluvial erosion, vegetation and Quaternary cover greatly limit the outcrop

120 conditions and thus affect reliable sampling of fault networks, we selected sites with little weathering, vegetation, and

Quaternary cover, as well as flat terrain to minimize topographic effects (Baumberger et al., 2022), which were encountered only at high altitude sites.

At each site, we performed detailed characterization of the fault networks (Fig. 2a). We carried out drone-based surveys (DJI Mavic 2 Pro; Hasselblad L1D-20c camera) at two different observation heights to produce orthorectified images (orthophotos) and Digital Elevation Models (DEMs) with Agisoft Metashape (v1.6.6) at mm and cm ground resolutions (see Table 1). Additionally, we used orthophoto and DEM products at dm ground resolution from the Federal Office of Topography swisstopo. We then manually digitized the visible fault traces at fixed mapping scales of 1:10, 1:100, and 1:1'000 within circular mapping areas, preferring circular extents to minimize potential orientation bias (e.g., Bonnet et al., 2001) (Table 1, Fig. 2a). Fault traces are herein defined as curvilinear features that represent the intersections between a fault plane and the Earth's surface (Baumberger et al., 2022; O'Leary et al., 1976), which serve as a proxy for the pre-existing geometrical anisotropies. As such pre-existing anisotropies are likely to be reactivated also in today's stress field if suitably oriented, and the power law exponents are insensitive to the type of fracture (Bonnet et al., 2001; Marrett et al., 1999), we chose to incorporate also mode I fractures but, for the sake of simplicity, generally refer to these geological discontinuities as faults. Unambiguous differentiation of faults from other discontinuities such as bedding structures based on remote sensing alone is often ambiguous, which is why we systematically validated the fault maps in the field to ensure their representativeness of the real fault populations. We also measured both the 3D orientations of the faults and where possible the kinematic indicators (i.e., slickensides) in the field.

Despite thorough data collection, mapping of fault traces includes several limitations. The detectability of fault traces by remote sensing depends on both the fault length, the image resolution, the mapping scale, and the degree of erosion of the related tectonites (i.e., the resulting morphological incision). Furthermore, image artifacts caused by illumination or shadow effects in low contrast domains or by partial coverage of the bedrock by Quaternary debris or vegetation can prohibit the appropriate identification of faults. These factors lead to deviations from the true fault trace length which in terms influences the quantitative analysis (e.g., Cao and Lei, 2018). To minimize such potential artifacts, we carefully selected sites with little Quaternary cover and topographic effects, and acquired the images in similar light conditions. Areas covered by debris or vegetation were excluded as "no data" areas. The influence of the remaining uncertainties is further discussed in section 5.1.

3.1.2 Statistical Analysis of Fault Networks

We used the data from the fault trace maps to quantify both the orientation and size distributions of the fault networks. To describe their 2D orientation distribution, we derived length-weighted rose diagrams from the fault traces for each individual dataset presented in Table 1 (Fig. 2a). Additionally, we used field measurements to characterize the 3D orientation distribution of the fault networks, as well as their kinematics. The 2D and 3D distributions capture different aspects of the fault orientations: while the 3D distribution yields information about the dip range of the fault sets, the 2D orientation distribution from the fault trace maps represents a better-suited quantitative measure of the dominant strike orientations.

In a next step, we evaluated the size (or length) distribution of the fault networks from the four sites. We assume an underlying power law distribution, which is most commonly used to model fault size distributions (e.g., Bonnet et al., 2001; Bour et al.,
155   2002; Odling, 1997; Scholz et al., 1993; Torabi and Berg, 2011; Yielding et al., 1996; Davy et al., 2010; Scholz, 2019). In nature, all power laws must have upper and lower limits (Bonnet et al., 2001; Torabi and Berg, 2011; Turcotte, 1997, 1989). For faults, the upper limit is likely related to the thickness of the crust or the stratigraphic layering, while the lower limit is constrained by a physical length scale (e.g., grain size). Defining these limits is nontrivial, and deviations from a power law in the tails of the size distribution of fault networks commonly occur presumably independent of the physical limits of the system.
160   Instead, sampling bias such as truncation and censoring effects can result in size distributions that appear to be exponential or log-normal (Bonnet et al., 2001; Odling, 1997; Odling et al., 1999; Torabi and Berg, 2011). Due to the underestimation of the frequency of small faults, these structures are systematically underrepresented due to the limited resolution of the orthophotos and DEM's, which is commonly referred to as truncation (Bonnet et al., 2001; Bour et al., 2002; Torabi and Berg, 2011) (Fig. 2b). The truncation length l_{trunc} defines the length above which faults can be reliably detected. Similarly, large faults are more
165   likely to lie partially outside the boundaries of the sampling area, so their lengths and frequencies are often systematically underestimated (Bonnet et al., 2001; Pickering et al., 1995). This leads to a steepening of the curve at the upper tail of the distribution, commonly called censoring effect (Fig. 2b). Note that the fault lengths at which truncation and censoring effects occur do not necessarily correspond to the true physical limits of the power law distribution (Bonnet et al., 2001). Since both truncation and censoring effects in natural fault datasets are often rather pronounced, it is a major challenge to identify the
170   scaling range where the distribution follows a power law. It is therefore crucial to ensure that the power law fitting is based on a large range of fault lengths, ideally spanning values over 2 to 3 orders of magnitude (Bonnet et al., 2001). Practical issues and mapping bias (see previous section), however, prevent the acquisition of high-resolution orthophotos over large areas that would be required for this. On a single observation scale, the length range is thus limited, rendering the identification of power law distributions challenging (Bonnet et al., 2001; Bour et al., 2002; Davy et al., 2006; Pickering et al., 1995; Scholz, 2007).
175   To overcome these limitations, we herein used a multi-scale approach, combining the observations from different mapping scales (Fig. 2b). The basic idea is to normalize the fault density with the fractal area, which allows to greatly extend the length range (e.g., Bonnet et al., 2001; Heffer and Bevan, 1990; Odling, 1997). The normalized density size distribution is given as (Bour et al., 2002; Davy et al., 1990)

$$n(l,L) = c \, l^{-\alpha_F} \, L^D \tag{2}$$

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with l as the fault trace length, c representing the fault density, α_F as the power law exponent of the fault networks, and L^D denotes the area term. The latter is defined by the diameter of the study area L and the fractal dimension D of the fault trace barycenters (i.e., the centroids of the fault traces) and fixes the number of structures of a given length per unit fractal area
185   independently from the observation scale and is thus a scale-independent measure (Davy et al. 1990, Bour et al. 2002). This allows for comparison of the data obtained at different scales.

The fractal dimension D was derived with the two-point correlation function C_2 (Hentschel and Procaccia, 1983; Vicsek, 1992), which describes the spatial correlation of fault trace barycenters and has been suggested as an appropriate measure for D of fault networks (Bonnet et al., 2001; Bour et al., 2002; Bour and Davy, 1999; Davy et al., 1990). It is defined as:

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$$C_2(r) = \frac{1}{N^2} N_d(r) \qquad (3)$$

where N is the total number of fault trace barycenters and N_d is the number of pairs whose barycenter interdistance is less than r (Hentschel and Procaccia, 1983). For fractal populations, $C_2(r)$ scales with r as r^D, with D as the correlation dimension.

195 Following Bonnet et al. (2001), we estimated the fractal dimension by identifying a plateau of the local slopes of D.

To then fit the fault trace data with equation (2), we only extracted the unbiased data from each fault trace map. To account for truncation effects, we determined the truncation length l_{trunc} with the approach of Alstott et al. (2014) and Clauset et al. (2009), using the Kolmogorov-Smirnov (KS) distance as a measure for the goodness of fit between the fitted power law and the data. Hereby, the minimum KS distance defines l_{trunc} (Fig. S1). We then removed all fault traces with lengths smaller than

200 l_{trunc}. We also accounted for censoring effects by removing faults that intersect the sampling window (Lei et al., 2015). The measured fault densities of each mapping scale n(l) were then normalized with the area term L^D. We finally fitted the normalized dataset with a power law using Maximum Likelihood Estimation (MLE). This is commonly preferred over linear regression (Clauset et al., 2009; Goldstein et al., 2004). We finally obtained power law size distributions which, owing to the multi-scale approach, span several magnitudes of fault lengths (Fig. 2b). As the number of fault traces is critical for the reliable

205 extraction of power law exponents (Zeeb et al., 2013), and the number of fault is rather small for non-dominant orientations, we chose to not incorporate orientation-dependent α_F values but rather derived a single bulk value of α_F for the respective site.

3.2 Earthquakes

We analyzed the recent seismicity within four subdomains of the seismotectonic domain z21 of Wiemer et al. (2016), each associated with one of the fault mapping sites A to D (Fig. 1b). In analogy with the fault data, we characterized both the

210 orientation and size distributions of the earthquakes within these subdomains.

The orientation of the rupture plane activated during an earthquake often remains unknown, and the determination of the orientation distribution of seismic ruptures is thus challenging. However, focal mechanisms (e.g., determined by the polarities of the first arriving P waves) give a first-order constraint on the orientation of the ruptured plane for earthquakes with significant energy release. Such first-motion focal mechanisms yield an ambiguous solution with two possible rupture plane

215 orientations. Additional constraints such as the spatial distribution of hypocenters can in some cases be used to decipher the activated ruptured plane (e.g., Truttmann et al., 2023), but this information is often lacking. For this study, we compiled previously published focal mechanism data as shown in Fig. 1b (Baer et al., 2005, 2003, 1997; Deichmann et al., 2012, 2006, 2002, 2000; Delacou et al., 2005; Diehl et al., 2021a, 2018, 2013; Jimenez and Pavoni, 1983; Maurer, 1993; Maurer and

Deichmann, 1995; Pavoni et al., 1997; Truttmann et al., 2023), which partly incorporates information about the active rupture
220 plane. Based on these focal mechanisms, we evaluated the 3D orientation distribution of earthquake ruptures within each
subdomain by plotting the nodal planes in stereographic projections and incorporate, where available, the information about
the effectively ruptured plane.

We consecutively analyzed the size distribution of earthquakes, using the data from the earthquake catalog published by Diehl
et al. (2021b) (Fig. 1b). Indications exists that the M_L magnitudes in the SED bulletin include inconsistencies between earlier
225 and modern epochs due to changes in instrumentation and determination procedures of magnitudes (Staudenmaier et al., 2018).
We therefore only considered events after 2005, for which the M_L magnitudes are derived from digital data in a relatively
consistent manner. As we are interested in a measure that is directly comparable to the size distribution of faults, we herein
derived the size distribution of earthquake ruptures rather than the magnitude or seismic moment, which serves as a proxy for
the recently activated part of the fault network at depth. This approach is justified by the fact that the earthquake magnitude is
230 directly related to the ruptured fault length (e.g., Wells and Coppersmith, 1994). Therefore, we translated the local magnitudes
M_L to the earthquake rupture lengths l_R. After converting the recorded local earthquake magnitude M_L to the moment
magnitude M_W after Goertz-Allmann et al. (2011) using an empirical M_L-M_W scaling relationship, we derived the earthquake
rupture area A_R, given as:

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$$A_R = 10^{\frac{(M_W - a)}{b}} \tag{4}$$

where a and b represent constants derived from empirical scaling relations (e.g., Wells and Coppersmith, 1994). We herein
used three different scaling relations determined for strike-slip earthquakes in stable continental regions with a = 4.18 and b =
1 (Leonard, 2014), a = 3.49 and b = 0.94 (Thingbaijam et al., 2017), and a = 3.98 and b = 1.02 (Wells and Coppersmith, 1994).
240 From A_R, we then calculated the earthquake rupture length l_R under the assumption of a circular rupture plane. Based on this
new dataset containing a rupture length for each earthquake, we then employed the MLE power law fitting procedure of Alstott
et al. (2014) and Clauset et al. (2009) using equation (1) to derive the power law exponent α_R of the earthquake ruptures. α_R
represents a modified b-value that is the commonly used power law exponent in seismology. Similar to the fitting procedure
of the fault data, we used the minimum KS distance as a measure for the optimal truncation length (Fig. S2), which is
245 comparable to M_c often used by seismologists.

4. Results

4.1 Fault Networks

Based on remote sensing, we identified between 1'608 and 10'894 fault traces on each of the 12 different maps (Table 1, Fig.
3). In the following, we use these data to characterize the fault networks in terms of their orientation and size distributions.

4.1.1 Orientation Distribution

Site A is characterized by three main sets of subvertical faults identified in the field (Fig. 4a): a SE dipping (A_I) and a NW dipping set (A_{II}), as well as an almost perpendicular SW dipping set (A_{III}). Set A_I consistently indicates normal movements, while A_{II} faults reveal a reverse shear sense (Fig. 4b). For set A_{III}, we only observed a single kinematic indicator, revealing oblique sinistral movements. The length-weighted rose diagrams for site A suggest that the NW-SE striking A_{III} faults are the dominant set (Fig. 3).

At site B, the measured fault planes reveal a similar 3D orientation distribution with a slight clock-wise rotation compared to site A (Fig. 4c). The SE dipping set B_I strikes parallel to the NW dipping fault set B_{II}, and perpendicular to the SW dipping set B_{III}. Both B_I and B_{II} exhibit dextral strike-slip movements (Fig. 4d), while faults of set B_{III} mostly indicate normal movements. The rose diagrams in Fig. 3 show that the NE-SW striking B_I and B_{II} faults are the most prominent sets at all scales.

Also at site C, steeply SE (C_I) and NW dipping faults (C_{II}) are the dominant sets (Fig. 4e). Set C_I exhibits large variations in strike directions, ranging from NNE-SSW to E-W. Both sets predominantly imply dextral strike-slip movements (Fig. 4f). The rose diagrams indicate that E-W to ENE-WSW are the dominant fault strike orientations, corresponding to both fault sets C_I and C_{II} (Fig. 3).

The fault network at site D is characterized by two main sets, with a diffusely oriented SE dipping set (D_I) and a dominant subvertical, NW-SE striking fault set (D_{II}) (Fig. 4g). For neither set D_I nor D_{II}, the kinematic indicators reveal a clear pattern (Fig. 4h). The rose diagrams in Fig. 3 reveal a bimodal distribution, with both sets D_I and D_{II} equally abundant.

In summary, we document a change in dominant fault orientations, from NW-SE striking in the Aiguilles Rouges massif (site A), to E-W and NE-SW dominated in the limestone nappes in the center of the Rawil depression (sites B and C), to a NE-SW and NW-SE bimodal fault distribution in the Gastern massif (site D).

4.1.2 Size Distribution

To combine the fault trace data from the different scales, we first derive the fractal dimension D for each fault trace map. Using the two-point correlation function C_2, we obtain values of D between 1.64 and 1.83 (Fig. 5), suggesting a relatively homogeneous spatial fault distribution, as D = 2 would imply a perfectly homogeneous spatial distribution. This is in good agreement with the qualitative observation of widespread and pervasive faulting in the area. Since the datasets from different scales reveal consistent values of D, we argue that the fractal dimension is scale-independent.

Using the obtained values of D for the area normalization (see section 3.1.2), we find that the normalized fault length data follows a linear trend in a log-log plot for all study sites, supporting the assumption of an underlying power law distribution (Fig. 6). The power law scaling seems to hold over a length range of three orders of magnitudes for fault lengths between ca. 10^0 to 10^3 m. However, as can be seen for the data of site C, for example, individual datasets slightly deviate from the power law behavior. Such deviations can be caused by sampling bias such as the choice of the sampling area of the consecutive

mapping scale, since subareas with anomalously high or low fault densities can lead to an offset in the multi-scale size distributions. We will further discuss potential uncertainties in section 5.1.

The obtained fault power law exponents α_F, which are of main interest for comparison with the earthquake data, range between 2.43 and 2.73 (Fig. 6), which suggests that little regional variations exist. As the fault networks are sampled in both crystalline
285   basement rocks as well as in the Helvetic limestone units, α_F seems to be relatively insensitive to differences in lithologies. For the dimensionless fault density term c, we observe somewhat larger variations. With a value of $c = 1.57 * 10^{-4}$, site B reveals the lowest fault density term, while sites A, C, and D show larger c values of up to $5.76 * 10^{-4}$. Even though all c values range in the same order of magnitude, the fault density term varies by a factor of three for the different sites, however without any clear regional trends.

290   **4.2 Earthquake Ruptures**

Next, we assess the orientation and size distributions of seismic rupturing at depth, derived from focal mechanism data and earthquake rupture lengths for the different subdomains denoted in Fig. 1b. We therefore use a compilation of 69 previously published focal mechanisms and 4'612 earthquakes of the earthquake catalog of Diehl et al. (2021b) that lie within the seismotectonic domain z21 shown in Fig. 1 (see section 3.2).

295   **4.2.1 Orientation Distribution**

The data from the focal mechanism catalog reveals consistent rupture orientations within the different subdomains, with known earthquake ruptures predominantly occurring along subvertical, E-W to NE-SW striking planes (Fig. 7). While in subdomain A in the Aiguilles Rouges massif, the known active planes dip steeply towards the South (Fig. 7a), steeply north-dipping earthquake ruptures are observed additionally in the central and eastern subdomains C and D (Figs. 7c and d). For the data of
300   subdomain B, currently no active rupture planes are provided in the published focal mechanism data, but ENE-WSW striking nodal planes render similar active rupture orientations possible (Fig. 7b). Together with the observation of the NE-SW directed clustering of the seismicity (Fig. 1b), this implies that the majority of the seismicity in the Rawil region occurs along subvertically oriented, E-W to NE-SW striking faults.

4.2.2 Size Distribution

305   As shown in Fig. 8, the size distribution of earthquake ruptures for the different subdomains all follow power laws at length scales between about 10^2 and 10^3 m. For the data of subdomains A and D, we observe a deviation from power law behavior in the upper tail of the distribution, likely related to individual larger earthquakes. In subdomain A, this can be attributed to the $M_L = 4.9$ Vallorcine earthquake in 2005 (Fréchet et al., 2011), while in subdomain D, it relates to the $M_L = 4.1$ Salgesch earthquake in 2016 (Diehl et al., 2018). In subdomains B and C, we observe well-defined power law distributions for the
310   earthquake rupture lengths. The three used empirical M_w – A_R scaling laws all yield similar values of α_R, which indicates that a significant dependency from the used empirical scaling relations on the obtained power law exponents appears unlikely (Fig.

8). In general, the derived earthquake rupture power law exponents α_R all range between values of 3.88 and 4.81, implying little along-strike variations in the α_R values. As the size distribution of earthquakes often shows variations with depth, we further investigate a possible depth-dependency in section 5.4.

315 Overall, the α_R and α_F exponents exhibit significant differences that are unlikely to be solely attributed to uncertainties. These differences will be further explored in the discussion section.

5. Discussion

5.1 Uncertainties in Fault Size Distributions

In the following, we discuss two of the major uncertainties related to data sampling that can affect the fault size distributions:
320 (i) the finite mapping resolution of fault trace lengths, and (ii) the choice of the subsampling mapping area as well as the potential bias due to manual mapping.

Mapping fault traces on a fixed mapping scale on imagery with a given finite resolution necessarily leads to a bias in the derived fault lengths, as the terminations of the fault traces can only be mapped with a certain accuracy that is dependent on the image resolution. This potentially shifts the data along the horizontal axis of a log-log plot, leading to variations in the
325 derived power law exponent α_F. We here use the rather conservative assumption that the fault trace lengths are mapped with errors ϵ of 0.05 m (1:10), 0.5 m (1:100), and 5 m (1:1000) at the different mapping scales. We then randomly perturb all measured fault traces with length values between [-ϵ, ϵ] with a uniform distribution and calculate the α_F value for 100 Monte Carlo (MC) simulations. As shown in Fig. 9a, the normalized density distributions show relatively little variation. The derived mean power law exponents α_F between 2.14 and 2.80 are similar to the values reported in Fig. 6, and the standard deviations
330 of up to 0.15 suggests that the influence of uncertainties related to fault length estimation on α_F is small (Fig. 9b).

As the multi-scale approach used in this study relies on fault datasets from different scales, it is critical to assess the influence of the choice of different subsampling areas. The derived fractal dimension values below two suggest that the fault density is not a perfectly homogeneous property in the investigated fault networks (Figs. 3 and 5). Therefore, the spatial choice of the subsampling area for the next detailed scale leads to uncertainties in the size distribution, as differences in fault densities shift the data along the vertical axis, affecting the calculation of α_F. Additionally, fault traces may be overlooked or linear features not representing faults may be interpreted as faults during manual mapping of fault traces, leading to a similar effect. When selecting subsampling areas, we tried to avoid specific geometric features (i.e., fault linkages, fault terminations) and focused on minimizing topographic effects and Quaternary cover, since these factors can significantly bias the power law exponent estimates, leading to an overestimation of α_F (Cao and Lei, 2018). To assess the influence of changes in fault densities due to
340 the arbitrary choice of the subsampling area, we randomly altered the number of mapped faults from -25 to +25% and derive α_F for 100 MC simulations. Compared to the fault trace length uncertainties, the effect of the subsampling area uncertainties is more pronounced (Figs. 9c and d). However, the derived α_F values still vary in a small range between 2.44 and 2.86, with standard deviations of up to 0.29.

We conclude from this analysis that both uncertainties related to the fault trace length estimation as well as the choice of the
345   subsampling area and manual mapping have limited influence on the derived power law exponents α_F. We thus expect the true
power law exponents of the fault networks α_F to range between 2.5 and 3, with little regional and lithological variation.

5.2 Fault Network Characteristics

The fault networks from the four different study sites across the Rawil depression illustrate the pervasive but systematic
faulting in the study area (Fig. 3). Interestingly, the 2D orientation distributions for an individual site appear to be consistent
350   across scales (Fig. 3), which is in agreement with the findings of Odling (1997). This implies that the fault orientations are
self-similar, and thus scale-independent, suggesting that a single-scale mapping should be sufficient to capture accurate
information on the orientation distribution within a fault network. Comparing the fault networks of the different sites, however,
we observe variations in the dominant strike orientations (Fig. 3). While in the ECMs, both at site A in the Aiguilles Rouges
massif and site D in the Gastern massif, NW-SE and NE-SW striking faults prevail, the limestone nappes overlying the central
355   part of the Rawil depression are characterized by predominantly E-W to NE-SW striking faults. NE-SW striking faults are
however also present in both sites A and D, implying that these faults are regional features, roughly following the direction of
the RSF and the seismogenic RFZ (Fig. 1a).

The α_F values for the four different study sites are all in the same order and range between 2.5 and 3 (Fig. 6). As shown in

Table 2, these results are in good agreement with previously published values that generally lie between 2 and 3, which suggests

360   that this range can be seen as a first-order universal law of fault size distributions, independent of the host rock lithology. Also

the derived fractal dimension D values of around 1.7 are consistent with values reported in literature (Bonnet et al., 2001 and

references therein).

The multi-scale approach used herein has the benefit to greatly expand the length range of the individual fault trace datasets
compared to single-scale analysis (Figs. 2b and 6). The power law distributions derived in this study cover fault length scales
365   of three orders of magnitudes between about 10^0 and 10^3 m, and it is likely that the power law holds also for smaller and larger
faults. In nature, however, all power laws must have upper and lower physical limits (Bonnet et al., 2001; Torabi and Berg,
2011; Turcotte, 1997, 1989). The detected lower scaling limit of 10^0 m likely does not reflect the actual physical length scale
(e.g., caused by grain size effects), and we thus speculate that our analysis does not incorporate the lower limit of the power
law scaling. Identifying the true limit of the power law would require similar analysis of high-resolution datasets at smaller
370   scales. The derived upper limit of around 10^3 m is way below the assumed thickness of the seismogenic part of the crust of
around 15 kilometers, as well as the thickness of the Helvetic nappe system of a few kilometers (Burkhard, 1988; Levato et
al., 1994; Pfiffner et al., 1997; Steck et al., 1997). However, stratigraphic layering effects within the Helvetic nappes (e.g.,
Pfiffner, 1993) could influence the upper limit of the power law size distributions (Odling, 1997), at least for sites B and C.
Since the upper scaling limits do not significantly differ between the different lithologies, we consider this effect to be of minor
375   importance within the observed length range. We thus assume that our data only covers a limited length range of the actual
fault size distribution, and that the power law scaling holds for smaller and larger faults than studied herein. This interpretation
is supported by the fact that the previously reported α_F values for lengths between 10^{-1} and 10^5 m all lie in a similar range (

Table 2).

5.3 Potential Links to the Seismicity

380 The strong vertical components due to the exhumation-related tectonics during the latest stage of the Alpine orogeny, accompanied by enhanced glacial surface erosion in the past 2 Ma (Häuselmann et al., 2007; Glotzbach et al., 2010; Valla et al. 2012; Fox et al., 2015; Sternai et al., 2019), led to the exposure of the fault networks studied herein (Egli et al., 2017; Herwegh et al., 2020; Cardello et al., 2024). Based on observations of both exhumed fault patterns, earthquake hypocenter locations, and focal mechanisms, previous authors suggested that the exhumed fault networks in the region of the Rawil

385 depression were formed under a similar stress field that prevails today (Cardello and Mancktelow, 2015; Maurer et al., 1997; Pavoni, 1980a, b). As earthquakes and faults are inherently related, they are expected to exhibit similar orientation and size distributions (Bonnet et al., 2001; Scholz, 2007, 1998, 1997). In the following, we attempt to compare these statistical properties of the exhumed fault networks with the same properties of the seismicity in the study region.

Comparing the orientation distributions of the fault networks (Figs. 3 and 4) with the earthquake ruptures (Fig. 7) in a first
390 step, we observe a correlation only in the center of the Rawil depression for study sites and subdomains B and C. The E-W to NE-SW striking fault set C_I (Figs. 4e and f) correlates with the active planes from the respective subdomain C (Fig. 7c). The dextral strike-slip kinematics of the NE-SW striking faults reveals striking similarities with the kinematics of the earthquake ruptures (Figs. 4f and 7c). In subdomain B, where no active nodal planes are deciphered (Fig. 7b), the average orientation of the nodal planes generally renders earthquake rupturing along E-W to NE-SW striking planes possible, which would

395 correspond to reactivation of fault sets B_I and B_{II} (Figs. 4 c and d). However, recent high-precision hypocenter datasets suggest that NW-SE striking fault planes are reactivated at least in the northern part of the Rawil depression (Diehl et al., 2024). In the ECMs on both sides of the Rawil depression, the correlation between the orientation distributions is less clear. In subdomain A, earthquake ruptures strike ENE-WSW (Fig. 7a), likely corresponding to the SE dipping A_I faults (Fig. 4a). It thus seems that the recent earthquakes mainly reactivate prevailing A_I faults as strike-slip faults (Fig. 7a). The E-W striking active rupture

400 planes in subdomain D (Fig. 7d) are not reflected by the bimodal fault network of site D at all (Fig. 4g), which is therefore likely not a good proxy for the E-W directed seismicity in subdomain D. This might be due to the fact that the chosen study site lies slightly outside the main seismic corridor. This difference could be explained by mechanically detached Aar and Gastern massifs, which also exhibit significantly lower seismic activity (Fig. 1b). The mapped NW-SE striking faults could thus represent the eastern lateral boundary of the main E-W to NE-SW striking seismogenic RFZ (e.g., Lee et al., 2022).

405 Overall, earthquake ruptures in the Rawil depression and the RFZ seem to occur mainly along subvertical E-W to NE-SW striking planes, and the exhumed fault networks show similar directivities at least in the central part of the Rawil depression above the main earthquake corridor (Fig. 1b). This implies that the active faults in the basement are consistent with exhumed fault networks in the Helvetic nappes, indicating a link across lithologies. Combined with the observation that α_F values reveal little sensitivity to lithological variations, we argue that the fault networks of sites B and C serve as a good first-order analog

410 of the seismically reactivated fault networks at depth.

5.4 Implications for Orogen-Internal Settings

As earthquakes usually occur several kilometers below the surface where direct information about the prevailing fault networks is sparse, the underlying processes of seismogenic deformation often remain uncovered. However, (i) the good agreement of faults and earthquakes in terms of their orientation distributions, (ii) the insensitivity of α_F to lithological variations, and (iii)
415 the observation that both features arguably formed in a similar stress field (Cardello and Mancktelow, 2015; Maurer et al., 1997; Pavoni, 1980a, b) imply that the exhumed fault networks in our study area might serve as good first-order analog for the fault networks at depth. We therefore attempt to compare the size distributions of the fault networks and earthquake ruptures in a next step. As the power law exponent of fault networks is dependent on the dimensionality of the data (e.g., Bonnet et al., 2001), we have to consider that the power law exponents were obtained from 2D (faults) and 3D (earthquake ruptures)
420 observations, respectively. Stereological considerations have demonstrated that the differing dimensionalities can be corrected for by employing the equation $\alpha_{3D} = 1.28 * \alpha_{2D} - 0.23$ (Bonnet et al., 2001; Borgos et al., 2000; Hatton et al., 1993). Consequently, the 3D power law exponents of the fault networks $\alpha_{F(3D)}$ is ranging somewhere between 3 and 3.6.

The power law exponent of the earthquake size distributions, commonly referred to as b-value by seismologists, has been proposed to decrease with increasing differential stress and thus depth (Mori and Abercrombie, 1997; Spada et al., 2013;
425 Scholz, 2019, 2015). We therefore assess the depth-dependent variations of the frequency and size distribution of earthquake ruptures. As no significant lateral variations in α_R values were observed within the investigated seismotectonic domain (Fig. 8), we calculate α_R values for depth-slices that incorporate the entire seismotectonic domain. To minimize potential bias due to the data selection, we randomly iterate through different combinations of depth thresholds, and only fit a power law for entities with more than 200 data points. Since the majority of vertical uncertainties in the modern era of the earthquake catalog are in the subkilometer range (Diehl et al., 2021b; Lee et. al. 2023), we do not consider hypocenter uncertainties.
430 As shown in Fig. 10a, earthquakes in the study area occur most frequently at depths between 3 and 8 km. The maximum rupture lengths lie, with few exceptions, on the order of 10^2 m for depths shallower than 3 km, with significantly larger ruptures up to 10^3 m occurring at depths between 3 and 9 km (Fig. 10b). At greater depths, the seismicity becomes sparse, and maximum rupture lengths generally decrease, which could be due to the increasing component of temperature-dependent viscous
435 deformation representing the brittle-viscous transition at the lower depth end (e.g., Wehrens et al., 2016). As expected α_R values generally decrease with depth (Fig. 10c), in line with previous studies (e.g., Mori and Abercrombie, 1997; Spada et al., 2013). However, the values for shallow (< 3 km) and intermediate (3 – 9 km depth) crustal earthquakes differ significantly: while shallow earthquakes reveal α_R values around 5 to 8, values for intermediate earthquakes constantly decrease with depth to values of around 3.5. Comparing the α_R values with $\alpha_{F(3D)}$ of the exhumed fault networks, we notice that for shallow
440 earthquake ruptures a significant discrepancy to the $\alpha_{F(3D)}$ values exists (Fig. 10c). For intermediate earthquakes, α_R and $\alpha_{F(3D)}$ values converge towards similar values at around 8 km depth. This observation could potentially be explained by the following two hypotheses.

First, it could be stated that similarly to α_R, also $\alpha_{F(3D)}$ values decrease with depth. This cannot be strictly proven, as fault networks at depth are not directly accessible. The enhanced earthquake frequency at depths > 3 km, however, suggests that the
445 majority of brittle faults are formed at intermediate depth levels (Fig. 10a). Even though faulting certainly occurs at shallow depths < 3 km during exhumation as well, the significantly lower earthquake frequency implies that the majority of faults in the exhumed fault networks were formed at intermediate depth levels. This interpretation is supported by the proposed formation depths of exhumed faults in the surrounding of the Rawil depression derived from geological field observations (Cardello and Mancktelow, 2015; Gasser and Mancktelow, 2010; Ustaszewski et al., 2007; Cardello et al., 2024). Together
450 with the absence of significant lithological variations of α_F and the consistency with previously reported values from a large variety of tectonic settings (

Table 2), we consider this first hypothesis as unlikely.

As a second hypothesis, we thus propose that the $\alpha_{F(3D)}$ values are relatively constant with depth, and $\alpha_{F(3D)}$ and α_R converge towards similar values at intermediate depths. According to this argumentation, the decrease in α_R values therefore records
455 variations in the reactivation potential of pre-existing faults at different depth levels due to increasing differential stresses. As the differential stresses are smaller at shallow depths, rupture initiations are more likely to stop before growing into large earthquakes, which leads to larger α_R values (Mori and Abercrombie, 1997). In contrary, with increasing differential stress, the likelihood of a rupture initiation (i) to grow into a large earthquake that reactivates the full available fault length and (ii) to jump across multiple fault segments is increasing (Manighetti et al., 2007), leading to a convergence of α_R and $\alpha_{F(3D)}$ values at
460 intermediate depths. We propose that the similarities in the power law exponents at depths around 6 to 8 km reveal that earthquakes are more likely to rupture along the entire fault length at these depths.

Apart from the influence of differential stress, previous studies have shown that also other factors such as the faulting type (Gulia and Wiemer, 2010; Petruccelli et al., 2019a, 2019b; Schorlemmer et al., 2005) or material heterogeneities (Mori and Abercrombie, 1997; Mogi, 1962; Goebel et al., 2017) can lead to changes in the earthquake power law exponents. As the
465 dominant orientations of both the fault networks and earthquake ruptures are in good agreement (Figs. 4 and 7), and the focal mechanisms mostly imply transtensional movements (Kastrup et al., 2004), we argue that the faulting style has a minor influence on the observed variations in our case. Material heterogeneities, such as differences in lithologies, could potentially explain the increased α_R values at shallow depths above 3 km, as this depth correlates with the proposed basement-cover contact below the Rawil depression (Burkhard, 1988; Levato et al., 1994; Pfiffner et al., 1997; Steck et al., 1997; Lee et al.
470 2023). Stratigraphic layering effects due to the finite thickness of the Helvetic limestone units may limit the size of earthquake ruptures, increasing the α_R values at this lithological boundary (Ouillon et al., 1996). However, since the derived $\alpha_{F(3D)}$ values of the limestone and crystalline basement units are rather similar, and the discrepancy between the size distributions of exhumed faults and earthquake ruptures occurs at shallow depths, we argue that the elevated α_R values at shallow depths cannot be explained by differences in material heterogeneities alone, in line with the findings of Scholz (1968). As an additional
475 factor, the existence of fluids impacting pore pressure and friction can weaken the strength of the faults in the uppermost crust, preventing accumulation of larger amounts of stresses.

In summary, the depth-dependent comparison of the size distributions of faults and earthquakes suggests that the likelihood of an earthquake rupture to reactivate the entire fault length is higher at intermediate crustal depths, while for shallower earthquakes differential stresses are rather small, rendering earthquakes that rupture the full available fault length less likely,
480 which is similar to the interpretations of Tormann et al. (2014) and Hetényi et al. (2018). As illustrated in Fig. 11, partial seismic rupturing thus seems to be the common seismogenic deformation mode at shallow depth in the Rawil depression region. However, it should be noted that other factors, such as lithological changes and the presence of fluids, can influence fault strength. Consequently, the observed depth-dependent fault reactivation potential may differ in other regions. To assess the universality of this observation, further investigations in different settings are required.

6. Conclusion

The comparison of the statistical properties of faults and earthquakes point towards differences in the seismogenic deformation processes in the investigated orogen-internal setting, characterized by pervasive faulting and distributed seismicity. Our findings show that the potential of pre-existing faults to reactivate seismically seems to vary with depth, likely associated with depth-dependent changes in differential stresses (Fig. 11): while partial seismogenic rupturing of faults is the dominant deformation mode at shallow depths (< 3 km BSL), earthquakes are more likely to reactivate the entire fault length at intermediate depths (ca. 3 to 9 km BSL) in the Rawil depression region. Initiating earthquake ruptures thus reactivate the full available fault length predominantly at intermediate crustal depths.

The earthquake activity at shallow and intermediate depths furthermore documents ongoing brittle deformation in the Rawil depression region. As a consequence, recent faulting processes likely enhance the permeability of pre-existing faults, which could be of great interest for the exploration of the geothermal potential within such orogen-internal settings. In light of potential induced seismicity, our findings indicate that shallow fault systems are less likely to rupture over the entire length than deeper ones. Furthermore, quantitative information about orientation and size distributions of fault networks such as obtained herein are crucial for accurate modelling of recent fluid flow within intricate fault networks. Similar investigations, incorporating the statistical properties of both fault networks and earthquake datasets, could therefore potentially be used for innovative geothermal exploration in orogen-internal settings.

Data Availability

The data that support the findings of this study are openly available in Zenodo at https://zenodo.org/records/13829055 (Truttmann et al., 2024).

505 **Author Contribution**

ST and MH conducted field work. ST performed the formal data analysis with support of all co-authors. ST, TD, MH, and SW wrote, reviewed and edited the manuscript.

Competing Interests

The authors declare that they have no conflict of interest.

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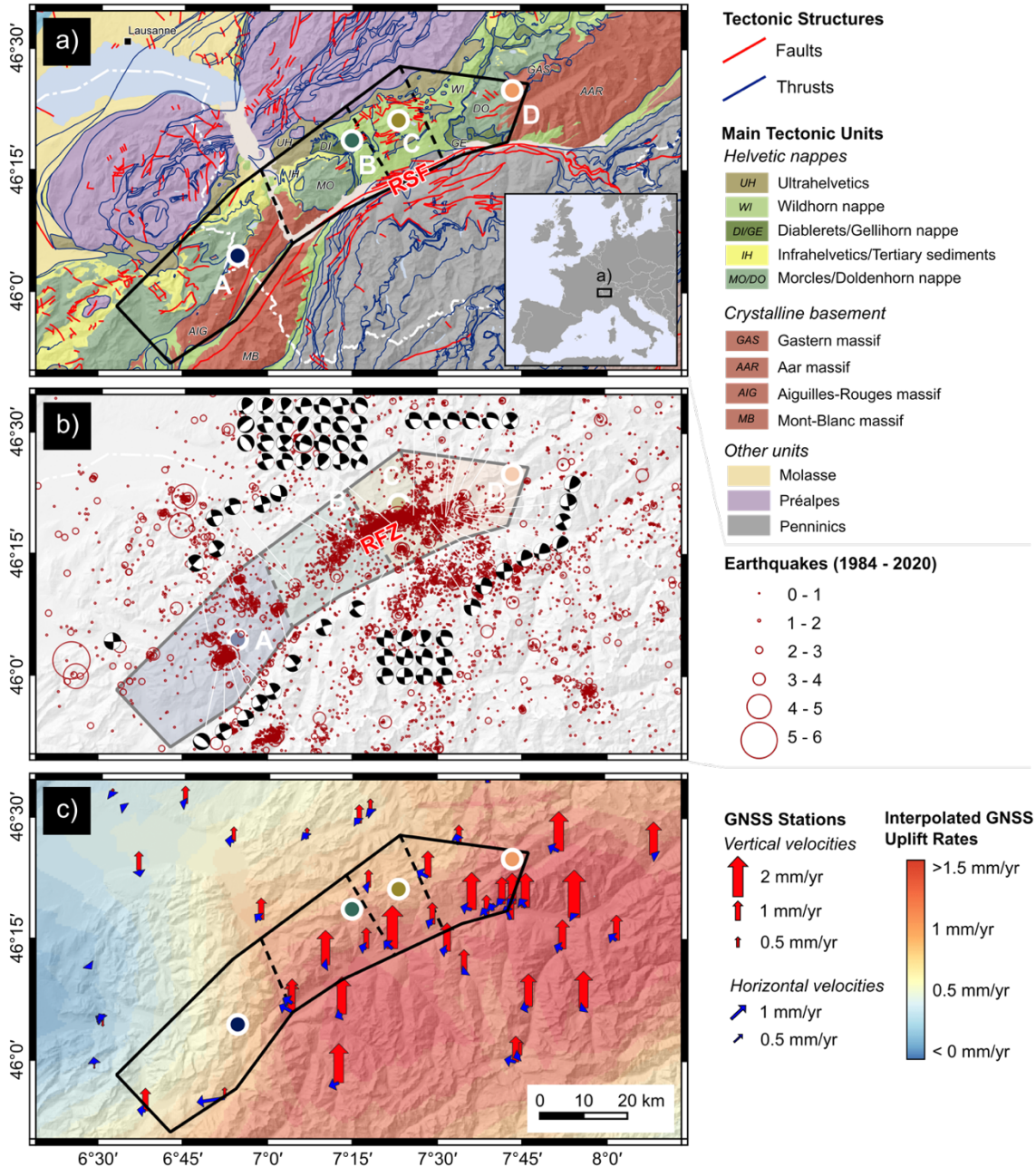
Figure 1: Regional setting of the investigated seismotectonic domain z21 of Wiemer et al. (2016) (black polygon), with the four fault mapping locations (A-D) shown as circles. a) Tectonic map (1:500'000; © swisstopo). RSF: Rhône-Simplon Fault Zone. b) Earthquakes from 1984 to 2020 (Diehl et al. 2021b) and available focal mechanism data (see main text for references). The shaded
830 **colors indicate the different subdomains A-D. RFZ: Conceptual Rawil Fault Zone. c) Recent crustal displacement rates based on GNSS surface velocities in the vicinity of the study area with reference to stable Europe (Data: EUREF Permanent GNSS Network (Bruyninx et al., 2019); swisstopo). Digital elevation model: EU-DEM v1.1 (© European Union, Copernicus Land Monitoring Service 2023, European Environment Agency (EEA)).**

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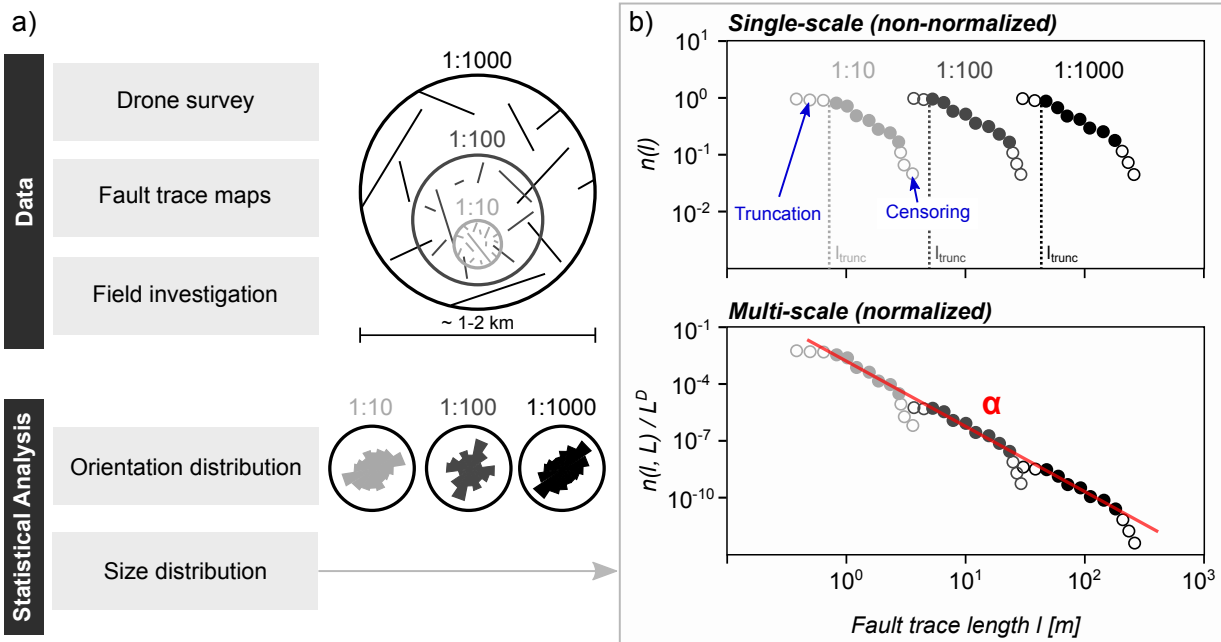
Figure 2: a) Workflow of the fault network analysis conducted separately for each location, combining observations from three different mapping scales of 1:1000, 1:100, and 1:10 (for details see Methods). b) Examples of size distributions of the fault networks, plotted with the non-normalized single-scale approach, treating the data from each mapping scale individually (upper panel), and
840 **the multi-scale approach, combining all information across scales by normalization with the fractal area (lower panel).**

Table 1: Overview of the used orthoimages and digital elevation models (DEM) that serve as a basis for the fault trace maps. Orthoimages and DEM's of the 1:1'000 mapping scale (dm resolution) are publicly available from swisstopo.

Location	Tectonic Unit	Mapping Scale	Image Acquisition	UAV Observation Height [m]	Orthoimage Ground Resolution [m]	DEM Ground Resolution [m]	Nr. of mapped fault traces
A	Aiguilles Rouges	1:10	UAV	10	0.003	0.006	2'440
		1:100	UAV	70	0.029	0.059	5'826
		1:1'000	© swisstopo	-	0.1	2	1'906
B	Diablerets	1:10	UAV	5	0.001	0.002	2'829
		1:100	UAV	50	0.021	0.041	4'654
		1:1'000	© swisstopo	-	0.1	2	3'306
C	Wildhorn	1:10	UAV	5	0.002	0.005	3'519
		1:100	UAV	70	0.024	0.048	10'894
		1:1'000	© swisstopo	-	0.1	2	1'812
D	Gastern	1:10	UAV	10	0.002	0.005	5'213
		1:100	UAV	60	0.024	0.048	3'214
		1:1'000	© swisstopo	-	0.1	2	1'608

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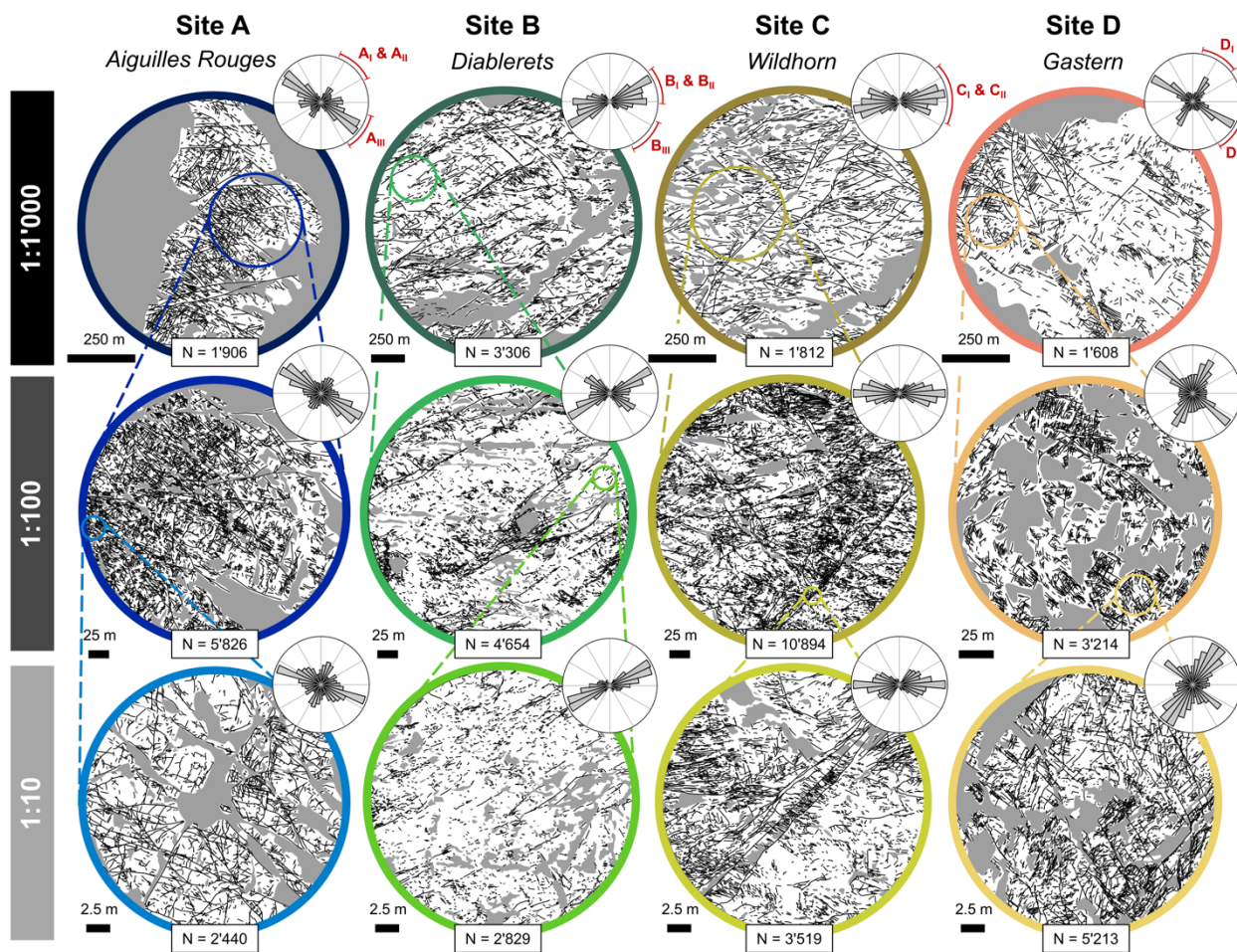
Figure 3: Fault trace maps at different mapping scales (rows) for all four study sites (columns). The maps show both fault traces (black lines) and no data areas (grey areas). The length-weighted rose diagrams to the top right of each map show the 2D orientation distribution of the fault traces. N indicates the number of mapped fault traces.

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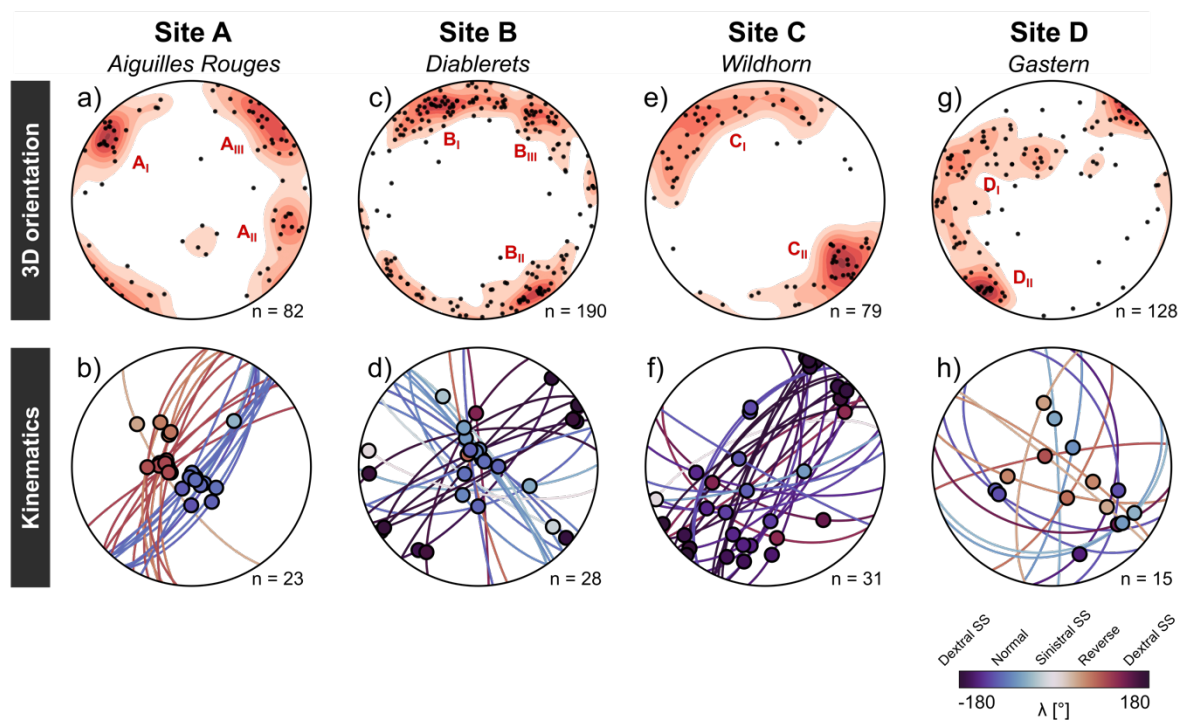
Figure 4: Field-based characterization of the fault populations. The stereoplots in the upper row shows the 3D orientation distributions (black dots: poles to planes on a lower hemisphere projection) with Kamb density contours in red (2σ interval) for all study sites. The lower row shows the respective kinematic indicators from fault observations (lower hemisphere projection). The
855   **dots represent the slip vectors, colored after faulting type and shear sense.**
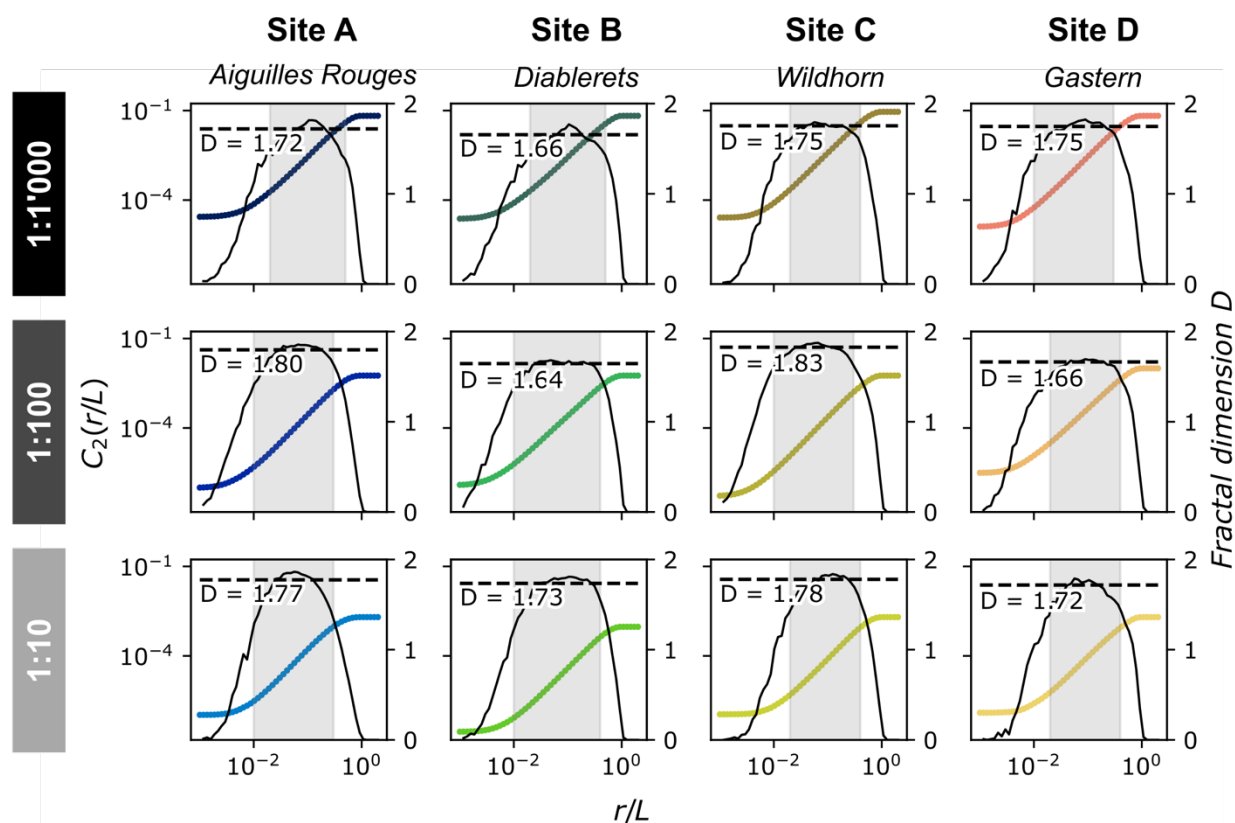
Figure 5: Estimation of the fractal dimension D for each individual fault network based on the two-point correlation function C_2 (colored line). The black line shows the local slopes of C_2 (derivative of C_2; right-hand axis). The plateau in the local slopes within the grey shaded area approximates the fractal dimension D, which is represented by the black dashed lines.

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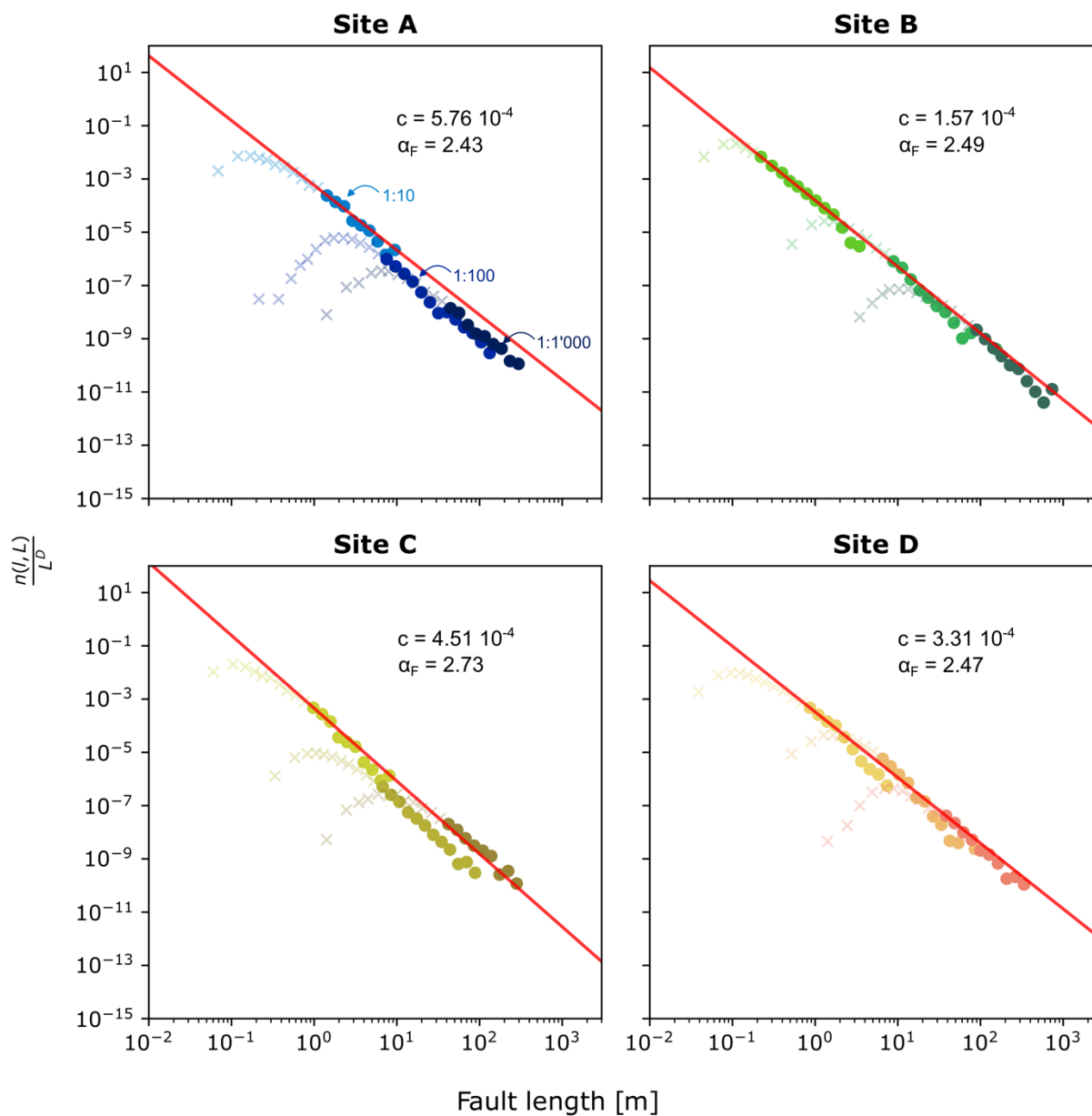
Figure 6: Normalized size distributions of the fault networks for all four study sites, derived from the multi-scale approach. Circles denote the unbiased data, while crosses show the truncated and censored parts of the data. The different color shades represent data from the three mapping scales. The respective fault density term c and the power law exponent α_F are given at the top right.
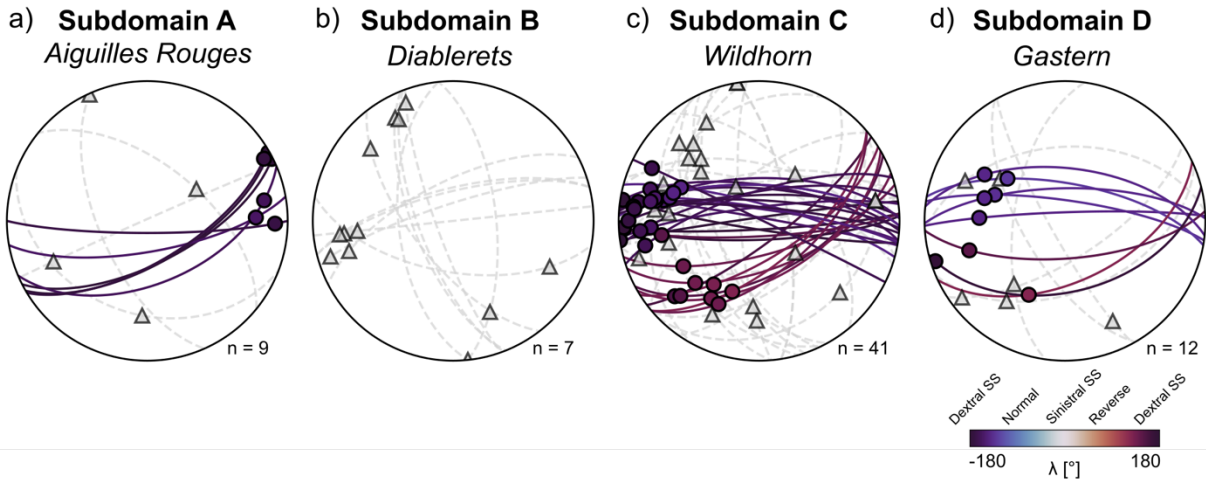
Figure 7: 3D orientation distributions of earthquake ruptures based on the nodal planes from published focal mechanism data (see text for references). Solid colored lines: known active nodal planes with slip vectors plotted as circles. Focal mechanisms without a known active nodal plane are represented by grey dashed lines (planes) and triangles (slip vectors). Secondary nodal planes for focal mechanisms with a known active plane are not shown in the figure.
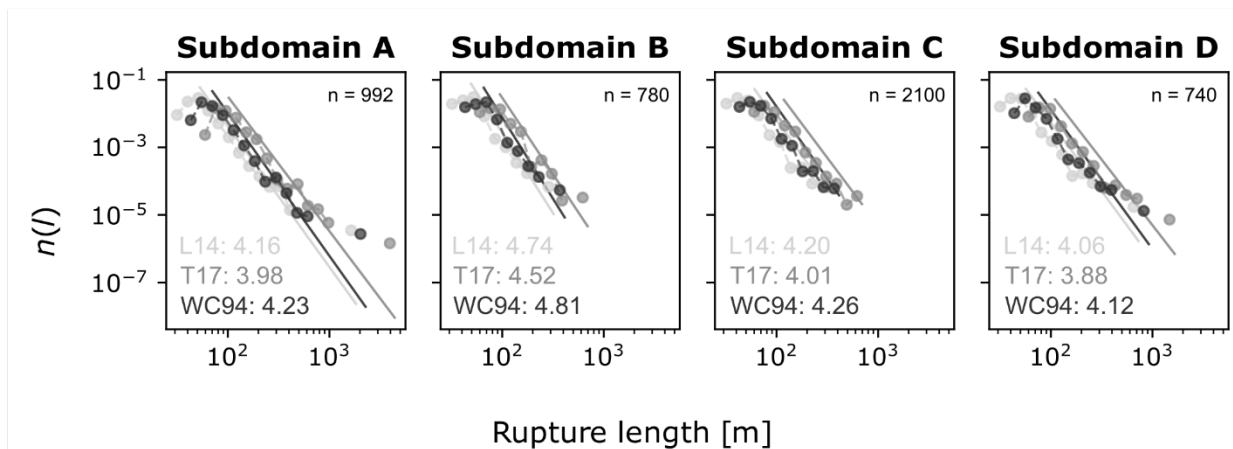
Figure 8: 3D size distribution of earthquake ruptures for the four subdomains. The earthquake magnitudes M_w were converted into rupture lengths L_R with the scaling laws of Leonard (2014) as L14, Thingbaijam et al. (2017) as T17 and Wells and Coppersmith (1994) as WC94 represented by the different grey scales, yielding three slightly different rupture length distributions and α_R values. The values in the bottom left indicate the respective values of α_R.
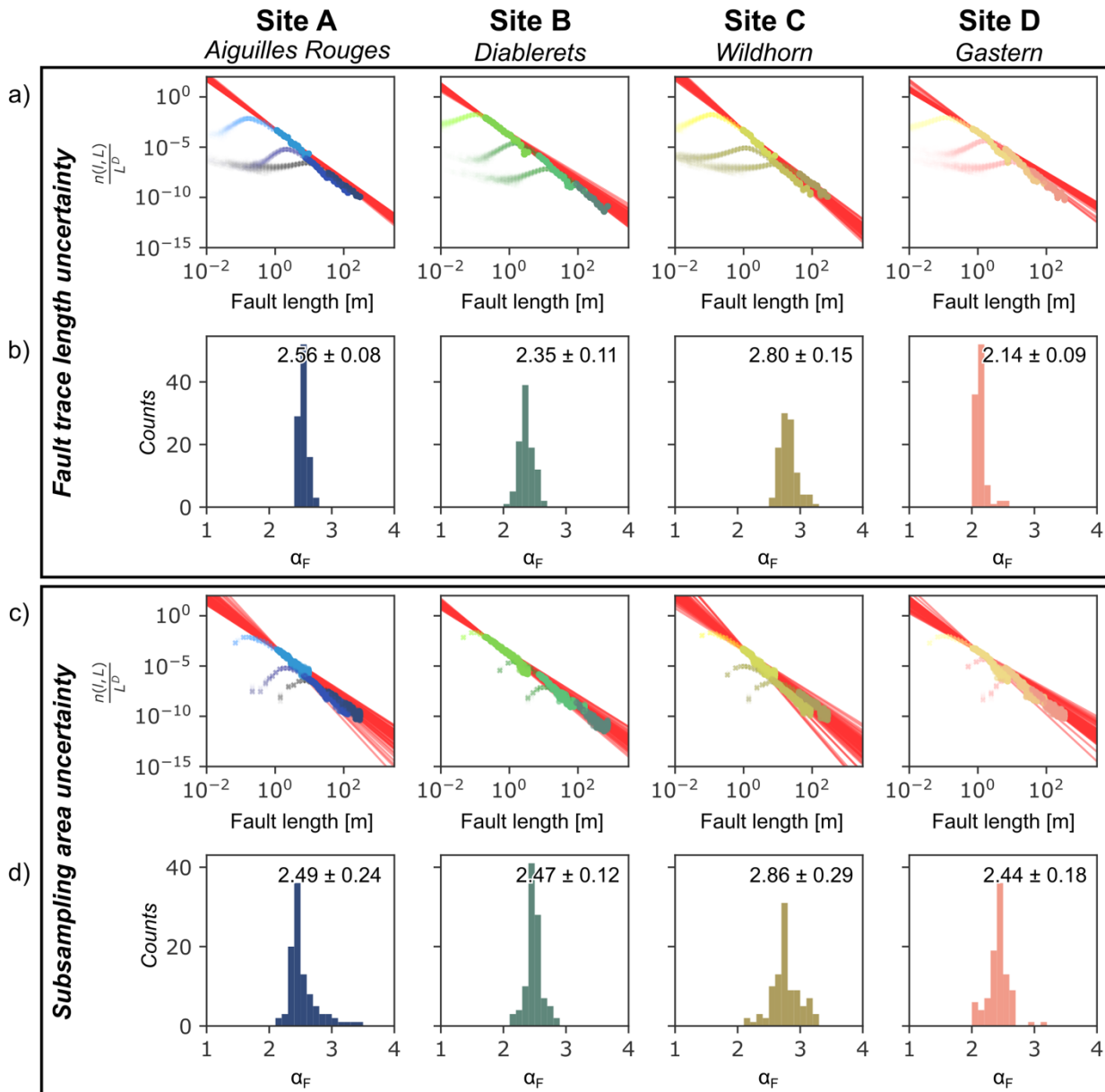
Figure 9: a) Assessment of the fault trace length uncertainties. The plots show the normalized density length distributions with fault trace lengths perturbed with values 0.05, 0.5, and 5 m, respectively. b) Histogram of the derived α_F values. The values report the mean α_F value and the respective standard deviation. c) Assessment of the subsampling area uncertainties, showing the normalized density length distributions with the number of faults in each dataset randomly altered between -25 and +25 %. d) Histogram of the derived α_F values of the sampling area uncertainties. The values report the mean α_F value and the respective standard deviation.

Table 2: Compilation of published power law exponents α_F from fault size distributions sorted by the used analysis approach (single- vs. multi-scale power law fitting), with complementary information deduced where available. As both cumulative (CDF) and probability density functions (PDF) are used for fitting fault length data, we have to make the CDF-based values comparable to our PDF-based α_F values by using $\alpha_{CDF} + 1$ (Bonnet et al., 2001). N: Total number of data; α_F(published): published power law exponent and the used distribution; α_F(PDF): power law exponents converted to PDF values (Bonnet et al., 2001); lower and upper limit: approximate bounds of the power law scaling range.

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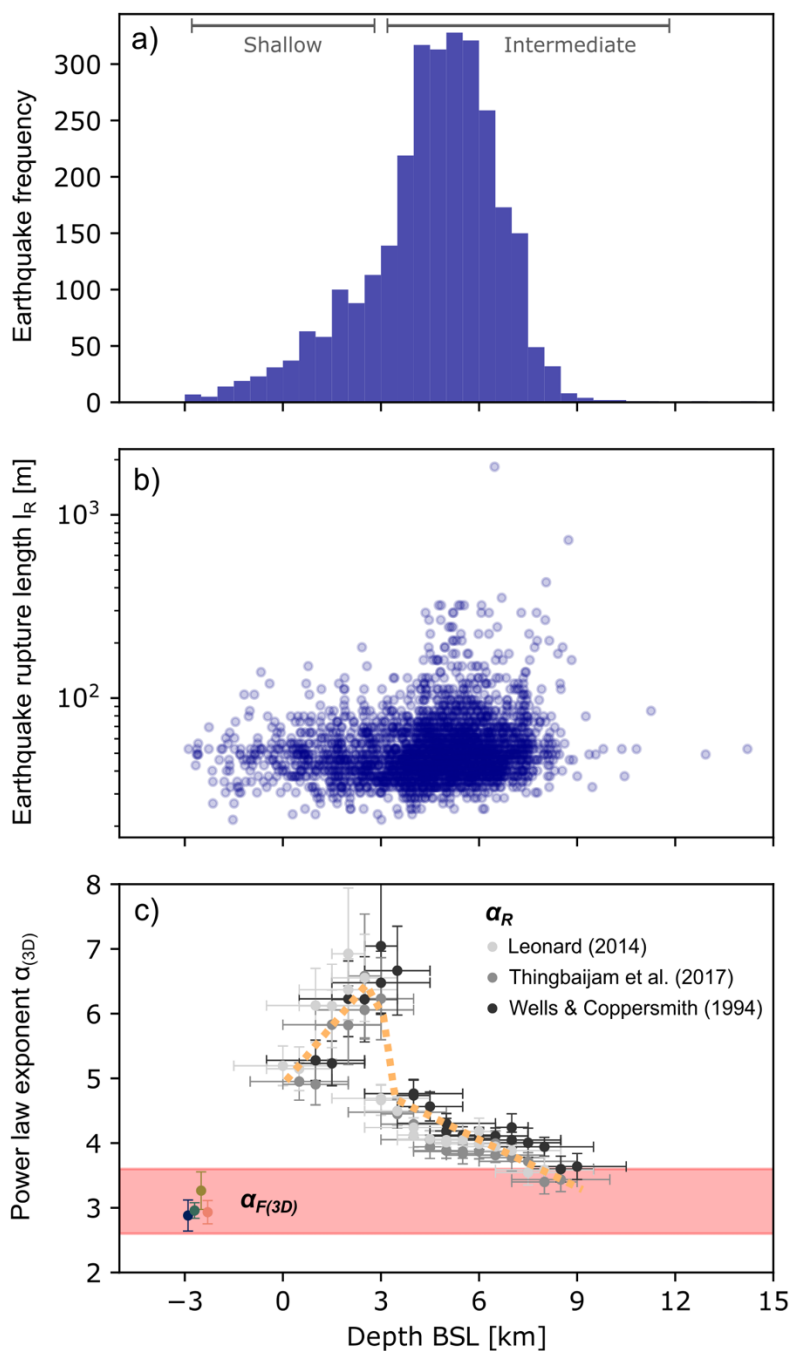
Reference	N	Rock type	α_F(published)	Distribution	α_F(PDF)	Lower limit [m]	Upper limit [m]
Single-scale analysis							
Ackermann and Schlische (1997)	873	Sediments	1.64	CDF	**2.64**	0.04	0.15
Bour and Davy (1999)	3499	-	1.88	PDF	**1.88**	4000	70000
Clark et al. (1999)	1034	-	1.51	CDF	**2.51**	360	4500
Knott et al. (1996)	218	Sediments	1.02	CDF	**2.02**	0.31	0.93
Ouillon et al. (1996)	...	Sediments	1.9	PDF	**1.9**	2	20
Ouillon et al. (1996)	...	Sediments	2.1	PDF	**2.1**	800	8000
Ouillon et al. (1996)	...	Sediments	3.2	PDF	**3.2**	3000	20000
Ouillon et al. (1996)	...	Sediments	2.1	PDF	**2.1**	8000	30000
Schlische et al. (1996)	201	Sediments	1.4	CDF	**2.4**	3	20
Yielding et al. (1996)	~450	-	1.18	CDF	**2.18**	300	10000
Yielding et al. (1996)	~350	-	1.75	CDF	**2.75**	4000	50000
Yielding et al. (1996)	300	-	1.37	CDF	**2.37**	1500	20000
Multi-scale analysis							
This study: Site A	*10172*	*Crystalline basement*	*2.43*	*PDF*	***2.43***	*1*	*300*
This study: Site B	*10789*	*Sediments*	*2.49*	*PDF*	***2.49***	*0.1*	*1000*
This study: Site C	*16225*	*Sediments*	*2.73*	*PDF*	***2.73***	*0.5*	*300*
This study: Site D	*10035*	*Crystalline basement*	*2.47*	*PDF*	***2.47***	*0.5*	*400*
Bossennec et al. (2021)	...	Crystalline basement	2.03	CDF	**3.03**	1	10000
Bour et al. (2002)	21'778	Sediments	2.8	PDF	**2.8**	1	200
Castaing et al. (1996)	...	Crystalline basement & sediments	2.34	CDF	**3.34**	20	10000
Ceccato et al. (2022)	5908	Crystalline basement	1.88	CDF	**2.88**	1	10000
Line et al. (1997)	...	Crystalline basement	1.66	CDF	**2.66**	30	100000
Odling (1997)	...	Sediments	2.1	CDF	**3.1**	1	1000
Odling et al. (1999)	...	Sediments	2.34	CDF	**3.34**	5	100000
Scholz et al. (1993)	...	Volcanic	1.3	CDF	**2.3**	30	3000
Yielding et al. (1992)	...	-	2	CDF	**3**	3000	30000

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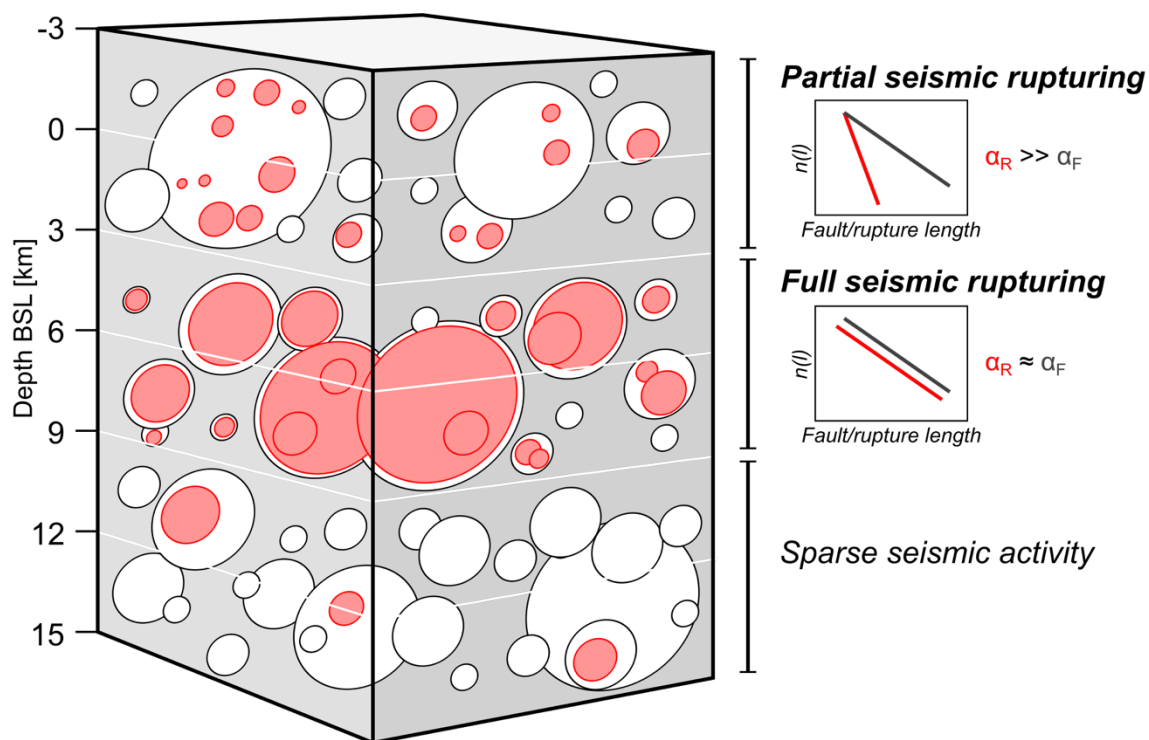
Figure 10: Depth-dependency of the seismicity in terms of a) the number of earthquakes, b) the rupture length l$_R$ of the individual earthquakes, and c) the derived power law exponents α$_{(3D)}$ for both the earthquake ruptures (grayscales) and the fault networks (colored bars and red box). Error bars denote 1σ uncertainties of the power law exponents (vertical bars) and the used depth interval (horizontal bars).

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Figure 11: Schematic block diagram to illustrate the depth-dependent seismogenic fault reactivation patterns observed in this study. Full seismogenic fault reactivation seems only to occur at depths from 3 to 9 km below sea level (BSL).