

Locating and quantifying CH₄ sources within a wastewater treatment plant based on mobile measurements

Junyue Yang¹, Zhengning Xu¹, Zheng Xia^{4,5}, Xiangyu Pei¹, Yunye Yang¹, Botian Qiu^{2,3}, Shuang Zhao^{2,3}, Yuzhong Zhang^{2,3*}, Zhibin Wang^{1,6*}

¹Zhejiang Provincial Key Laboratory of Organic Pollution Process and Control, MOE Key Laboratory of Environment Remediation and Ecological Health, College of Environmental and Resource Sciences, Zhejiang University, Hangzhou 310058, China

²Key Laboratory of Coastal Environment and Resources of Zhejiang Province, School of Engineering, Westlake University, Hangzhou 310030, China

³Institute of Advanced Technology, Westlake Institute for Advanced Study, Hangzhou 310024, China

⁴Ecological and Environmental Monitoring Center of Zhejiang Province, Hangzhou 310012, China

⁵Zhejiang Key Laboratory of modern Ecological and Environmental Monitoring, Hangzhou 310012, China

⁶ZJU-Hangzhou Global Scientific and Technological Innovation Center, Zhejiang University, Hangzhou 311200, China

Correspondence to: Zhibin Wang (wangzhibin@zju.edu.cn) and Yuzhong Zhang (zhangyuzhong@westlake.edu.cn)

Abstract. Wastewater treatment plants (WWTPs) are substantial contributors to greenhouse gas (GHG) emissions because of the high production of methane (CH₄) and nitrous oxide (N₂O). A typical WWTP complex contains multiple functional areas that are potential sources for GHG emissions. Accurately quantifying GHG emissions from

these sources is challenging due to the inaccuracy of ~~activity~~emission data, the ambiguity of emission sources, and the absence of monitoring standards. Locating and quantifying WWTPs emission sources ~~using in combination with~~ measurement-based GHG emission quantification methods ~~is~~are crucial for evaluating and improving traditional emission inventories. In this study, CH₄ mobile measurements were conducted within a WWTP complex in the summer and winter of 2023. We utilized a multi-source Gaussian plume model combined with the genetic algorithm inversion framework, designed to locate major sources within the plant and quantify the corresponding CH₄ emission fluxes. We identified ~~132~~ main ~~point~~ sources in the plant and estimated plant-scale CH₄ emission fluxes of $68.78 \pm 17.40 \text{ kg h}^{-1}$ ($603.33 \pm 152.66 \text{ t a}^{-1}$) for the summer and $47.76 \pm 21.39 \text{ kg h}^{-1}$ ($418.95 \pm 187.59 \text{ t a}^{-1}$) for the winter. The predominant sources of CH₄ emissions were the screen and primary clarifier, contributing 55 % and 67 % to the total emissions in summer and winter, respectively. The comparison revealed that summer CH₄ emissions were 2.8 times higher than inventory estimates, while winter emissions were twice the inventory values.~~The comparison against traditional emission inventories revealed that the CH₄ emission fluxes in the summer were 2.8 times greater than the inventory estimates, and in the winter, emissions were twice the inventory values. Our flux inversion method achieved a good agreement between simulations and observations (correlation > 0.6 and a root mean square error (RMSE) < 0.7 mg m⁻³).~~ This study demonstrated that mobile measurements, combined with the multi-source Gaussian plume inversion framework, are a powerful tool to locate and quantify GHG sources in a complex site, with the potential for further refinement to accommodate different types of factories and gas species.

1 Introduction

~~Greenhouse gas (GHG) emissions exacerbate the greenhouse effect, causing adverse~~

~~impacts on human health, ecosystems, and the environment (IPCC, 2023).~~ Methane (CH₄) is the second-largest contributor to climate change, with the global warming potential 27.9 times that of carbon dioxide (CO₂). Reducing CH₄ emissions is essential for mitigating climate change and progressively achieving the global target of limiting warming to 1.5 °C (IPCC, 2023). ~~The latest observational study from the~~ WMO Global Atmospheric Watch network indicated that the global annual average concentration of CH₄ in 2022 was 1923 ± 2 ppb, representing a 264 % increase from pre-industrial levels (WMO, 2023). The International Energy Agency (IEA)'s 2024 Global Methane Tracker report suggests that global CH₄ emissions reached 580 Mt in 2023, with anthropogenic CH₄ emissions accounting for 60 %. The complexity of CH₄ emission processes, lack of monitoring systems, and limitations of emission estimation models present challenges in accurately estimating anthropogenic CH₄ emissions.

The quantification of CH₄ emission fluxes is typically achieved through a bottom-up inventory method. However, due to the difficulties in obtaining ~~actual emission factors~~ activity data used for actual emission factors, and specific information on different emission sources, there is considerable uncertainty in the assessing of the emission inventory method (Lin et al., 2021). In contrast, a top-down method that estimates CH₄ emissions by monitoring atmospheric concentration has been increasingly applied in recent years (Sun et al., 2019; Cusworth et al., 2024; Han et al., 2024; Maazallahi et al., 2023; Riddick et al., 2017). The monitoring technology mainly includes satellite (Zhang et al., 2021; Liang et al., 2023; Jacob et al., 2022) and airborne (Allen et al., 2019; Abeywickrama et al., 2023; Cui et al., 2017) remote sensing, as well as ground-based monitoring such as vehicle-based mobile monitoring (Albertson et al., 2016; Al-Shalan et al., 2022; Caulton et al., 2018), station monitoring (Dietrich et al., 2021; Hase et al., 2015; Heerah et al., 2021) and tower monitoring (Richardson et al., 2017; Balashov et al., 2020). Emission flux inversion methods also include isotope tracer method (Jackson et al., 2014; Zimnoch et al., 2018), cross-sectional flux method (Luther et al., 2019; Makarova et al., 2021), and atmospheric diffusion model inversion method (Kumar et

al., 2021; Yacovitch et al., 2015). Atmospheric transport models with varied degrees of complexity, including Gaussian diffusion models (Stadler et al., 2021), Lagrangian models (Mckain et al., 2015), and Eulerian models (Bergamaschi et al., 2018), are used in the inversion to relate GHG concentrations with emissions. Optimization methods, such as Bayesian optimization (Karion et al., 2019) and linear regression models (Kumar et al., 2021), are applied to achieve accurate inversion results. Furthermore, some studies incorporate carbon isotope observations to better attribute the contribution of different CH₄ emission sources (Maazallahi et al., 2020). Numerous studies use satellite remote sensing, unmanned aerial vehicle (UAV) monitoring, and vehicle-based mobile monitoring techniques to measure CH₄ emissions (Sun et al., 2023). However, satellite spatiotemporal resolution is limited and UAVs have short endurance, making vehicle-based mobile monitoring a better choice for measuring CH₄ emissions at wastewater treatment plants (WWTPs). Vehicle-based mobile monitoring can perform continuous real-time monitoring and precise identification of emission sources, and hence have been applied to urban (von Fischer et al., 2017; Defratyka et al., 2021) and plant-scale (Zhao et al., 2021; Jin et al., 2010) monitoring of GHG concentrations and emission fluxes. Vogel et al. (2024) used high-precision fast-response GHG analyzers to investigate CH₄ leaks in 12 cities across 8 countries, using high-precision fast-response GHG analyzers combined with the mobile survey methodology (von Fischer et al., 2017). Chen et al. (2020) utilized the multiple-Gaussian-plume model and a forward modeling approach for mobile measurements of CH₄ emissions during the Munich Oktoberfest. Shi et al. (2023) proposed a CO₂/CH₄ emission quantification model (EMISSION PARTITION) and conducted mobile measurements with vehicle-based monitoring system at chemical, coal washing, and waste incineration plants in two cities and one industrial park in China, assuming different numbers of emission sources for quantitative assessment. Wang et al. (2022a; 2022b) employed the Environmental Protection Agency's Other Test Method 33A (OTM 33A) for monitoring downwind of fueling stations to estimate the CH₄ emission fluxes of nine

109 ~~compressed natural gas (CNG) stations and five liquefied natural gas (LNG) stations in~~
110 ~~Eastern China. Emission flux inversion methods also include isotope tracer method~~
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118 ~~regression models (Kumar et al., 2021), are applied to achieve accurate inversion results.~~
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120 ~~the contribution of different CH₄ emission sources (Maazallahi et al., 2020).~~

121 As a significant source of GHG emissions, [wastewater treatment plants \(WWTPs\)](#)
122 generate substantial amounts of CH₄, N₂O, and CO₂ during the collection, treatment,
123 and discharge of sewage and sludge, contributing 3 % of the global total GHG
124 emissions (Bai et al., 2022). The estimation of CH₄ emission fluxes from WWTPs has
125 increasingly attracted widespread attention. Li et al. (2024) developed a plant-level and
126 technology-based CH₄ emission inventory for municipal WWTPs in China, estimating
127 the CH₄ emissions for 2020 to be 150.6 Gg. ~~Wang et al. (2022) systematically~~
128 ~~considered process technological differences in wastewater treatment, constructing a~~
129 ~~high-resolution greenhouse gas emission inventory for Chinese WWTPs from 2006 to~~
130 ~~2019.~~ Delre et al. (2017) measured the CH₄ ~~and N₂O~~ concentrations downwind of five
131 WWTPs in Scandinavia using tracer gas dispersion, which obtained a range of CH₄
132 emission fluxes from 1.1 ± 0.1 to 18.1 ± 6.3 kg h⁻¹. Moore et al. (2023) employed ~~an~~
133 ~~integrated Gaussian plume model with a Bayesian framework for~~ [CH₄](#) mobile
134 measurements ~~of CH₄ emissions~~ from 63 WWTPs in the United States, pointing to a
135 significant underestimation in the CH₄ emission inventories. [However, most studies](#)
136 [lack comparisons between measured and simulated concentrations, resulting in](#)

[significant uncertainty in the results.](#) We present a mobile measurement investigation of a WWTP in Hangzhou 2023. To analyze the mobile data, we construct a multi-source Gaussian plume model combined with the genetic algorithm inversion framework, which assists us to locate and quantify CH₄ emission sources, based on the concentration distribution measured within the WWTP. Additionally, we compare CH₄ emission fluxes from the measurements with the bottom-up estimates of emission inventories. A sensitivity analysis is performed to elucidate the discrepancies arising from variations in emission source locations. Our results provide insight into formulating and evaluating emission reduction measures for WWTPs.

2 Instruments and methods

2.1 Site selection

The monitoring site was chosen at a WWTP in Hangzhou, a megacity in East China. This WWTP is a large-scale plant located in Hangzhou, processing up to 1.5 million tons of domestic wastewater daily. ~~The plant roads were flat and wide, suitable for vehicle-mounted CRDS (Cavity Ring Down Spectrometer Spectroscopy) to conduct monitoring along the internal roads of the plant to monitor various functional areas within the plant.~~ [The chosen](#) WWTPs processes typically encompass mechanical treatment, biological treatment, sedimentation, advanced treatment, disinfection, and sludge treatment. As illustrated in Fig. 1, we divide the WWTP into 14 functional areas according to treatment processes. ~~For instance, a~~ [Areas](#) associated with primary treatment were labeled as coarse screens and primary sedimentation tanks, while those linked to secondary treatment were indicated as aeration tanks and secondary sedimentation tanks. ~~Mobile measurements were conducted by driving around the outer periphery and internal functional areas of the wastewater treatment plant, with each monitoring experiment involving circling the functional areas 1-2 times. 10 days of~~

~~experiments were carried out from June to December 2023. This yielded 8 valid sets of monitoring data, including 3 days of summer data and 5 days of winter data.~~ We performed one monitoring experiment per day, with each experiment entailing 1-2 rounds of mobile measurements along external roads and internal functional areas roads. Additionally, we conducted repeated mobile measurements and fixed measurements on roads with high concentrations to calculate average concentration data. Over 10 days of experiments from June to December 2023, we obtain 8 days of complete monitoring data, including 3 days in summer and 5 days in winter. On the other two experimental days, internal facility maintenance restricted access to certain roads, resulting in incomplete monitoring data.





Figure 1. Distribution of functional areas of the WWTP. [The yellow mark represents the simulated location of the line source. Solid lines show the roads measured by the mobile vehicle.](#) Map data are from ESRI.

2.2 Instrumentation

The monitoring instruments consisted of a vehicle-mounted [Cavity Ring-Down Spectrometer \(CRDS\)](#) monitoring system [\(Zhao et al., 2024\)](#) and a portable meteorological station. The vehicle-mounted CRDS system was anchored by the CRDS analyzer (Picarro G2201-i, [Picarro 2010](#)), accompanied by GPS and meteorological instruments. ~~The CRDS analyzer measures $^{12}\text{CO}_2$, $^{13}\text{CO}_2$, $^{12}\text{CH}_4$, $^{13}\text{CH}_4$ and H_2O , t~~ The volume fraction of CH_4 is measured with an accuracy of $5 \text{ ppb} \pm 0.05 \%$ ~~(Picarro 2010)~~. CRDS measurements have the advantages of strong interference resistance, high sensitivity and accuracy, making them widely employed in research focused on monitoring GHG emissions (Rella et al., 2015; Lopez et al., 2017).

In this study, the CRDS analyzer was ~~securely~~ placed inside the monitoring vehicle, ~~with the sampling probe mounted on the roof to mitigate the effects of vehicular emissions.~~ [to measure \$\text{CH}_4\$ concentrations in the WWTP. The sampling probe was](#)

placed near the roof along the window of the car to avoid interference from vehicle exhaust due to the low position. ~~The system was powered by a battery, drawing in ambient air through a pump, and displaying real-time monitoring data on a screen.~~ The mobile meteorological instrument was placed on the roof of the vehicle to gather meteorological data. In addition, the GPS unit was integrated to record the location of sampling points during the measurement period. Two portable meteorological stations ([Hangzhou Pengpu Technology SWS-500](#)) were positioned adjacent to the main entrance and atop the filter tank at the WWTP. Capable of measuring ~~key~~ meteorological parameters ~~such as~~ (wind speed, direction, temperature, humidity, and atmospheric pressure), ~~this station provided essential climatic data for the monitoring experiments. Mobile measurements were performed by the monitoring vehicle along the entire roads of the WWTP, as well as the internal roads, to pinpoint the locations of emission sources, scrutinize variations in emission concentrations. The concentration data was subsequently integrated with an inversion model to estimate the CH₄ emission fluxes.~~

2.3 Inventory accounting method

We used the methods suggested by the IPCC Guidelines for National Greenhouse Gas Inventories (2006) to calculate the amounts of CH₄ emissions from wastewater. The formula for calculating the amounts of CH₄ emissions from wastewater is described as:

$$E_{CH_4} = (TOW - S \cdot a) \cdot EF_{CH_4} - R_{CH_4} \quad (1)$$

Where E_{CH_4} denotes the direct CH₄ emissions from the wastewater treatment plant, tCH₄ a⁻¹. TOW is defined as the total organic pollutant load in the influent wastewater, tCOD a⁻¹. S refers to the annual production total of dry sludge, t a⁻¹. The parameter a signifies the organic matter content in the dry sludge, tCOD t⁻¹. EF_{CH_4} is the CH₄ emission factor, tCH₄ tCOD⁻¹. R_{CH_4} quantifies the annual recovery of CH₄ from

anaerobic treatment processes, t a^{-1} .

Operational data of the WWTP examined in this study is derived from the Urban Drainage Statistical Yearbook, an annual publication of urban water supply and drainage systems in China. This data set includes details such as the water treatment volume, sludge production, and the concentrations of six pollutants (COD_{Cr} , BOD, SS, $\text{NH}_3\text{-N}$, TN, and TP) in both influent and effluent. The Total Organic Waste (TOW) is ~~deduced from the yearbook's foundational data~~ calculated by the amount of treated water and COD influent concentration of the WWTP provided in the yearbook, while the annual sludge production (S) is extracted directly from ~~the yearbook~~. The organic matter content in dry sludge is estimated at an empirical 40 %, assuming a sludge moisture content of 75 %, leading to a value of 0.1 (Guo et al., 2019). EF_{CH_4} is selected based on the recommended value for Zhejiang province, 0.0046 (Cai et al., 2015). Given the infrequency of anaerobic treatment in wastewater, R_{CH_4} is set to 0.

2.4 Inversion method

We developed an inversion framework for CH_4 -emission fluxes designed for plant-level applications. The framework used ~~CH_4 -concentration~~ mobile measurements data, ~~specific~~ locations of emission sources, and initial emission estimates, alongside wind speed and direction data, as inputs to the ~~multi-point-and-line source~~ multi-source Gaussian diffusion models. The preliminary localization of the emission sources was chiefly contingent upon the concentration distribution along the roads within the internal functional areas. Meanwhile, the initial emission estimates for each source were determined by integrating the concentration data from these areas with an improved empirical equation (Weller et al., 2019⁸). Based on the comparison of measurement and model simulation results (Fig. S1), it is determined that the plant exhibits multiple point sources and line source diffusion patterns. Fig. S1 illustrates that the CH_4 concentration curve presents distinct peak distributions in point source diffusion patterns, while the

CH₄ concentration distribution in line source diffusion patterns consistently maintains higher levels. ~~These inputs were fed into a multi-source Gaussian plume model that simulates the concentration patterns of CH₄ given multiple point and line sources.~~ We then used a genetic algorithm to iteratively optimize source emission fluxes and their locations. The inversion framework simulation dictated the placement of 12 main point sources throughout the WWTP, specifically within Aeration Tank ①②③④⑤, Primary Clarifier ③④⑤, Screen ①, Secondary Clarifier ①②, and the Sludge Treatment ② (Fig. 1). ~~The inclusion of a Gaussian line source model was determined based on the actual emission conditions.~~ Within this study, a uniform line source was established, with the assumed location along the road between the Screen ① and the Primary Clarifier ① (Fig. 1 yellow mark). This assumption was grounded in the CH₄ concentration distribution observed within this road segment and was substantiated through model validation, ~~confirming the existence of a line source emission pattern.~~ The remaining emission flux inversion processes followed the same procedure as the point source simulation. Adjustments to the source locations within the model narrow the gap between simulated and measured concentrations, thus enhancing the accuracy of inversion. This section delineates each model incorporated into the inversion framework.

2.4.1 Empirical equation for estimating initial emissions

We used the improved empirical equation to estimate the initial emissions of emission sources (von Fisher et al., 2017; Weller et al., 2019). This method was primarily utilized for urban CH₄ leakage source emissions estimation (Defratyka et al., 2021; Maazallahi et al., 2020). The empirical equation is as follows:

$$\ln(M_{CH_4}) = -0.988 + 0.817 \times \ln(CH_4 \text{ emission rate}) \quad (2)$$

The M_{CH_4} is the maximum enhancement value of CH₄ concentration, ppm. The

CH₄ emission rate represents the CH₄ emission flux, L min⁻¹.

2.4.21 Multiple-point-source Gaussian plume model

We developed a multiple-point-source Gaussian plume model to relate CH₄ concentration enhancement to CH₄ emissions. This method approximates atmospheric dispersion of CH₄ from an individual source as a Gaussian plume under uniform and stable wind conditions (Nassar et al., 2017), which is usually good for describing average atmospheric transport tens to hundreds of meters downwind the source, making the Gaussian plume model a useful tool to study emissions from industrial and traffic sources.

The mass concentration enhancement (C , mg m⁻³) is computed as superposition of Gaussian plumes from multiple point sources.

$$C(x, y, z) = \sum_{i=1}^n \frac{Q_i}{2\pi\bar{u}\sigma_{i,y}\sigma_{i,z}} \exp\left(-\frac{(y-y_i)^2}{2\sigma_{i,y}^2}\right) \left\{ \exp\left[\frac{-(z-z_i)^2}{2\sigma_{i,z}^2}\right] + \exp\left[\frac{-(z+z_i)^2}{2\sigma_{i,z}^2}\right] \right\} \quad (23)$$

The variables x , y , and z denote the downwind, crosswind distances, and the height above the ground from the source, m. Q_i signifies the emission rate from the i_{th} point source, mg/s mg s⁻¹, for $i = 1, 2, 3, \dots, N$, where N represents the total count of point sources. The average wind speed is indicated by \bar{u} , m s⁻¹. The x_i , y_i and z_i are represented as the spatial position of the i_{th} point source, m. $\sigma_{i,y}$ and $\sigma_{i,z}$ are the horizontal and vertical dispersion parameters of the i_{th} point source, respectively, which are given by the formula below:

$$\sigma_{i,y} = \gamma_1 \cdot (x - x_i)^{\alpha_1}, \text{ when } x > x_i \quad (34)$$

$$\sigma_{i,z} = \gamma_2 \cdot (x - x_i)^{\alpha_2}, \text{ when } x > x_i \quad (45)$$

The power functions, known as the Pasquill's curves, associates with the downwind distance x and the prevailing atmospheric stability (Briggs et al., 1973). Atmospheric stability is determined based on the Pasquill stability classes recommended in the Technical Principles and Methods for Formulating Local Air Pollution Emission Standards (GB3840-83). During the observation, the CH₄ concentrations were obtained

through the vehicle-mounted CRDS monitoring system. The portable meteorological stations collected data on wind speed and direction, while GPS tracked the mobile paths to pinpoint emission source locations.

2.4.3.2 General Finite Line Source Model

Our analysis of measurement at WWTPs indicates that multiple-point-source Gaussian plume model is insufficient to capture the observed CH₄ concentrations. The entire road between the Screen ① and the Primary Clarifier ① shows high distribution of CH₄ concentrations. ~~To match the observations, we further consider a line source based on observed concentration distribution. The line source model is used to confirm that the road concentration distribution is consistent with line source emissions (Fig. S1).~~ The contribution of a line source to CH₄ concentration is given by the General Finite Line Source Model (GFLSM) (Luhar et al., 1989; Venkatram et al., 2006), which represents the line source as an ensemble of point sources:

$$C = \frac{Q}{2\pi\bar{u}\sigma_y\sigma_z} \left\{ \exp\left[\frac{-(z-H)^2}{2\sigma_z^2}\right] + \exp\left[\frac{-(z+H)^2}{2\sigma_z^2}\right] \right\} \cdot \left[\operatorname{erf}\left(\frac{\sin\theta\left(\frac{L}{2}-y\right)-x\cos\theta}{\sqrt{2}\sigma_y}\right) + \operatorname{erf}\left(\frac{\sin\theta\left(\frac{L}{2}+y\right)+x\cos\theta}{\sqrt{2}\sigma_y}\right) \right] \quad (56)$$

x , y , and z correspond to the downwind, crosswind distances, and the altitude above ground level from the source, m. Q_i is the emission fluxes of the unit source, mg s⁻¹. \bar{u} is the average wind speed, m s⁻¹. H_i is the effective emission height of the line source, with the length of the line source represented by L , m. The angle between the line source and the wind direction is given by θ . The horizontal and vertical dispersion parameters are characterized by σ_y and σ_z , respectively.

2.4.4 Genetic algorithm

Genetic algorithms, which mimic the evolutionary process of biological systems, serve as optimization search algorithms. The algorithms encode practical problems into binary genetic coding. Through the simulation of natural selection, crossover, and mutation processes, these algorithms are in a constant state of evolution and iteration, all in the pursuit of the optimal solution (Katoch et al., 2021). We deployed genetic algorithms to enhance the source emission flux outcomes modeled by the Gaussian plume model.

The process of inverting multi-source CH₄ emission fluxes utilizing genetic algorithms involves a series of steps. Initially, the emission flux of each source is treated as a gene, with binary-encoded gene sequences randomly assigned to a set number of individuals within the predefined range of a priori emission fluxes. Subsequently, the formulation of a fitness function is based on the defined optimization goals and constraints. This function serves as a critical tool for assessing the relative merits of each individual within the population. In this study, the objective of the optimization is centered on minimizing the aggregate absolute discrepancy between the values predicted by the model and those obtained from measurements. Ultimately, the population is subjected to the processes of selection, crossover, and mutation. Individuals with elevated fitness values, as determined by the fitness function, are chosen for the generation of new individuals. Through an iterative process, the optimal solution is refined, representing the emission fluxes for each source. Genetic algorithms are distinguished by the parallel computation capabilities, the propensity for identifying global optima, and the commendable stability and reliability (Harada et al., 2020).

2.4.5 Uncertainty analysis

To quantify the uncertainty in the inversion results, we have considered the uncertainties associated with the input parameters of the inversion model, including

wind speed, wind direction, and instrument measurements. The uncertainty in the CH₄ emission fluxes (ε_t) is derived using the error propagation formula as follows:

$$\varepsilon_t = \sqrt{\varepsilon_s^2 + \varepsilon_d^2 + \varepsilon_m^2} \quad (7)$$

ε_s and ε_d denote the uncertainties in wind speed and direction, which are determined by the standard deviation of the wind speed and direction measurements from two fixed meteorological stations during the observation period. ε_m represents the uncertainty in instrumental measurements. This uncertainty is derived from data provided by the manufacturer Picarro, which indicates a concentration measurement uncertainty of approximately 1 ppb for a 10-second integration time (Picarro 2010).

3 Results and discussion

3.1 Concentration mapping

The closed-path mobile measurements were conducted by vehicle-mounted CRDS monitoring system along the external roads encircling the WWTP, with further monitoring conducted along the internal roads. This strategy depicts the distribution of CH₄ concentrations within an WWTP, allowing for identification of specific CH₄ emission sources. Based on 8 days of CH₄ monitoring experimental data, the CH₄ concentration range on the overall roads was determined to be 1.98-17.13 ppm. The CH₄ concentration distribution indicated higher levels downwind, with the highest concentrations consistently recorded at the Screen ① throughout mobile experiments.

Due to the ~~consistency~~similarity of concentration measurement methods, we chose 29th June and 13th December as a typical example ~~for measuring the spatial distribution of CH₄ and evaluating the seasonal variability of WWTP~~. Figure 2 illustrates measured CH₄ concentration enhancement distributions on 29th June (summer) and 13th December (winter) 2023 (other days are shown in Figures S32-S87). The CH₄

concentration enhancements depicted ~~within the figures~~ were calculated by subtracting the background concentrations from the measured values, with the background determined as the mean of the bottom 10 % of the concentration data. Specifically, the background concentrations register at 1.98 ppm on 29th June and at a slightly elevated 2.11 ppm on 13th December. The analysis indicates that the shallower boundary layer in winter causes CH₄ to accumulate near the surface, resulting in a higher background concentration. Moreover, increased concentrations are detected in the regions surrounding the Screen ①, Primary Clarifier ④, and Aeration Tank ③ during these two days. The complete concentration maps, which include the internal roads, reveal that the experiment on 29th June exhibits heightened concentrations at the Screen ①, Secondary Clarifier ②, and Primary Clarifier ②④. The Screen ① exhibits the highest CH₄ concentration, with an enhancement of 14.83 ppm. On 13th December, the concentration enhancements are noted in proximity to the Secondary Clarifier ① and Primary Clarifier ②, with the Primary Clarifier ② showing the highest CH₄ concentration at 4.79 ppm.

CH₄ concentrations in summer surpass those observed in winter, consistent with a previous study on WWTPs (Masuda et al., 2015). The screen, primary clarifier and aeration tank are identified as sources with notably higher concentrations. Analysis of concentration distributions reveals that Screen ① shows a peak concentration reaching 14.83 ppm, which is 7.5 times the background concentration. The four primary clarifiers record high concentrations between 4.79 and 10.88 ppm. The high value measured by aeration tanks is mainly detected in Aeration Tank ③ at 4.60ppm. The screen in this study includes coarse and fine screens and a grit chamber, constituting preliminary wastewater treatment to capture larger suspended solids and particulates. The anaerobic environment of the sewer network promotes the production of CH₄ from organic compounds in municipal wastewater. As this wastewater enters the WWTP, the

397 influent contains dissolved CH₄ that originated in the sewer network. During primary
398 treatment, wastewater is elevated through riser mains, facilitating the release of CH₄
399 into the atmosphere (Guisasola et al., 2008; Bao et al., 2016). Flow velocity, hydraulic
400 design and detention times in these facilities may affect CH₄ production and release
401 (Alshboul et al., 2016; Yin et al., 2024). The primary clarifier physically removes
402 suspended solids from wastewater through sedimentation, while organic matter
403 undergoes anaerobic microbial degradation to the substantial production of CH₄
404 (Masuda et al., 2017). In the aeration tank, operated under anaerobic and anoxic
405 conditions, complex organic compounds are converted to CH₄ by facultative and
406 anaerobic bacteria through biological processes (Yoshida et al., 2014). In contrast,
407 Kupper et al. (2018) identified sludge storage tanks as the primary source of CH₄
408 emissions in Swiss WWTPs, accounting for 70 % or more of the total emissions. Stadler
409 et al. (2022) monitored CH₄ concentrations inside and around wastewater treatment
410 facilities ranging from 2.04-32.78 ppm, with elevated CH₄ levels predominantly
411 measured near sludge treatment tank, the digesters and secondary clarifiers. [CH₄](#)
412 [emissions from various WTPs are affected by a range of factors, including specific](#)
413 [processes, pipeline design, and equipment aging, the mobile monitoring can better](#)
414 [reflect the actual emission distribution.](#)

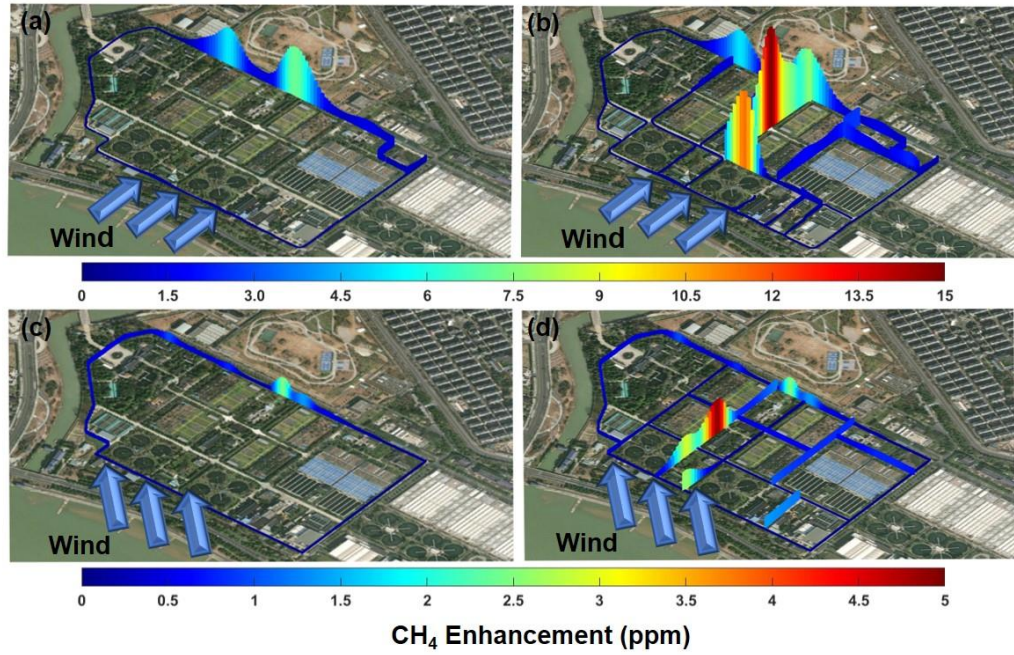


Figure 2. CH₄ concentration maps in the WWTP. The concentration maps for the external roads for 29th June (a) and 13th December (c). The corresponding complete concentration maps that include the internal roads for 29th June (b) and 13th December (d). Map data are from ESRI.

3.2 Emission quantification

The mobile measured CH₄ concentrations were employed in combination with the inversion framework to achieve the quantification of CH₄ emissions and localization of the emission sources within the WWTP. Figures 3 and 4 show the locations of identified point sources and the comparison between ~~measured~~monitored and simulated concentration ~~distributions for the point source locations at the WWTP on the dates of 29th June and 13th December.~~ The experiment conducted on 29th June finds the Screen ① to be the most significant contributor to CH₄ point source emissions at 18.26 kg h⁻¹ ~~160.19 t a⁻¹~~, and the Secondary Clarifier ② as the least significant at 1.23 kg h⁻¹ ~~10.78 t a⁻¹~~. The correlation coefficient R² for the ~~measured~~monitored and simulated

concentrations is 0.63, with an RMSE of 0.70 mg m^{-3} . On 13th December, the Aeration Tank ⑤ is the largest point source of CH_4 emissions at 3.93 kg h^{-1} , and the Primary Clarifier ⑤ is the smallest at 0.55 kg h^{-1} , with a correlation coefficient R^2 of 0.70 and an RMSE of 0.28 mg m^{-3} . The enhanced correlation between winter measurement and simulation data, as well as the improved fit of the measurement and simulation value curves, is attributed to the shorter monitoring cycle and more stable meteorological conditions.

In addition, when employing the multi-source Gaussian diffusion model combined with a genetic algorithm framework for iterative optimization to pinpoint point sources, we were able to locate external sources. As shown in Fig. S2 (a) and (c), external sources are primarily located along the main roadway to the south of the WWTP. Moreover, the estimated emissions vary across different days, which indicates that external source emissions are influenced by traffic vehicles. Fig. S2 (b) and (d) compare measured and simulated CH_4 concentrations before and after accounting for external sources, demonstrating that simulations are significantly closer to the measurements when external sources are included.

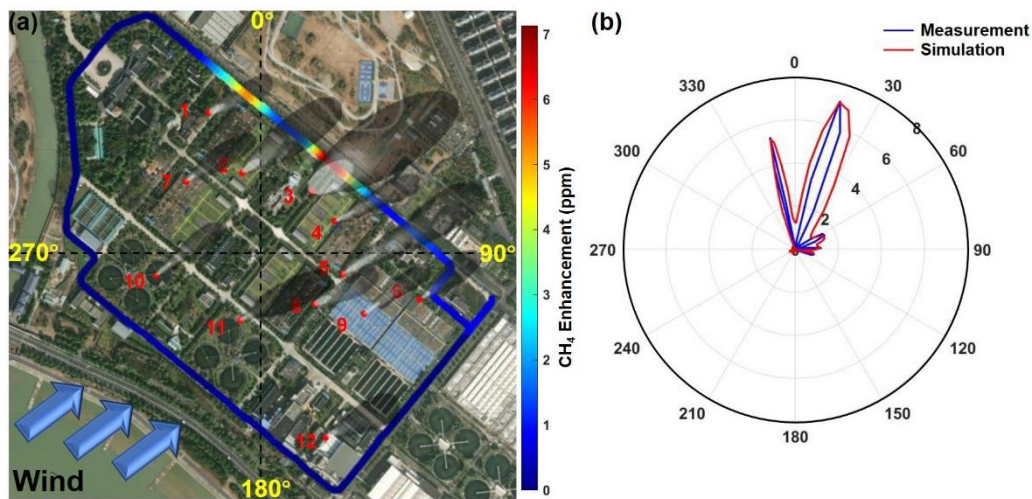
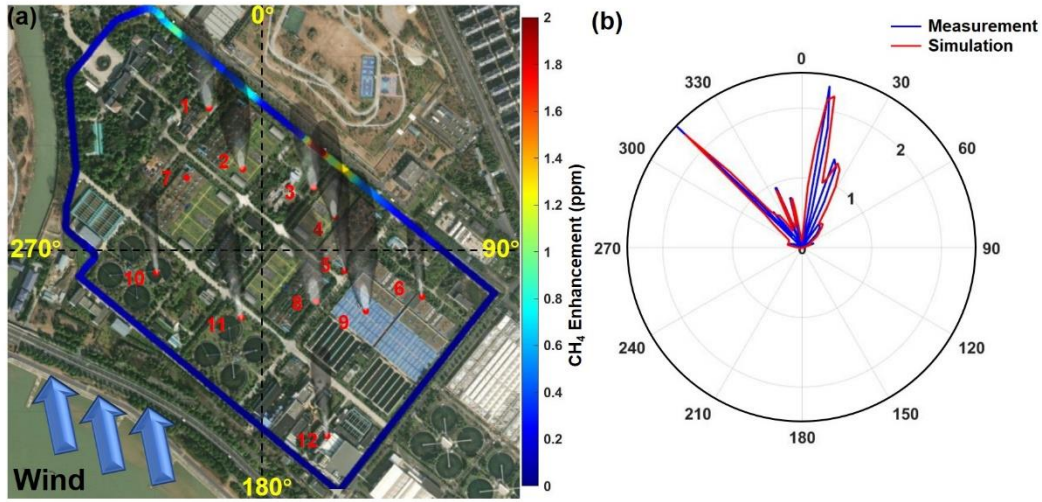


Figure 3. The emission distribution for the source locations (a) and the comparison between measured and simulated CH_4 concentrations (b) at the WWTP on 29th June. Map data are from ESRI.

451



452

453 **Figure 4.** The emission distribution for the source locations (a) and the comparison
 454 between measured~~monitored~~ and simulated CH₄ concentrations (b) at the WWTP on
 455 13th December. Map data are from ESRI.

456

457 Table 1 displays the CH₄ emission fluxes (Q), Wind speed and direction data (W_s ,
 458 W_d), the horizontal diffusion coefficient (γ_1, α_1) and the vertical diffusion coefficient
 459 (γ_2, α_2) from the 8-day monitoring experiment. Wind speed and direction data are the
 460 average wind speed and direction during the monitoring time, and the CH₄ emission
 461 fluxes are obtained by the inversion of the average concentration, wind speed and
 462 direction data as input of the inversion framework.~~Table 1 displays the CH₄ emission~~
 463 ~~fluxes, meteorological data, and the coefficients of the power function expressions for~~
 464 ~~diffusion parameters from the 8-day monitoring experiment.~~ The emission flux values
 465 of CH₄ emission sources (12 point sources and 1 line source) for all experimental days
 466 are detailed in Tables S1 and S2. It is observed that the summer average CH₄ emission
 467 flux ($68.78 \pm 17.40 \text{ kg h}^{-1}$ ~~$603.33 \pm 152.66 \text{ t a}^{-1}$~~) surpasses the winter average CH₄
 468 emission flux ($47.76 \pm 21.39 \text{ kg h}^{-1}$ ~~$418.95 \pm 187.59 \text{ t a}^{-1}$~~). This seasonal disparity in
 469 emissions is primarily attributed to the aeration tank, followed by the screen and
 470 primary clarifier. The activated sludge in the aeration tank contains a higher population

of methanogens, whose CH₄ production capability intensifies with rising temperatures (Vítěz et al., 2020). Notably, the seasonal variance in the aeration tank is predominantly driven by the performance of the Aeration Tank ④. However, the substantial variation in the emissions from the three summer experiments of the Aeration Tank ④ suggests a degree of emission instability. Conversely, the uniformity in the low emissions from the five winter experiments might be associated with the meteorological conditions and the actual operational status of the plant on those days. At lower wind speeds, the CH₄ emissions show only slight differences when compared to emissions on days with higher wind speeds. This suggests that the inversion results are less influenced by wind speed and are primarily associated with seasonal variations.

~~Analysis of emission source data from Tables S1 and S2 reveals that t~~The screen and primary clarifier are the predominant emission sources at the WWTP. Specifically, these sources emit 37.50 kg h⁻¹329 t a⁻¹ in the summer and 31.92 kg h⁻¹280 t a⁻¹ in the winter, accounting for 55 % and 67 % of the total emissions. ~~The study hypothesizes that emissions are boosted by p~~Pipeline leaks near the ~~emission sources in the~~ screen and primary clarifier, leading to ~~the more~~ CH₄ release. Previous research has similarly examined major emission sources at WWTPs. Yin et al. (2024) conducted offline monitoring of WWTPs in Beijing and Guiyang, identifying the primary treatment zone as the primary source of CH₄, accounting for 60.1 % and 35.8 % of the respective total emissions. Masuda et al. (2017) analyzed CH₄ emissions from different processes at three WWTPs in Japan, concluding that primary clarifiers are one of the major sources of CH₄ emissions. He et al. (2023) compiled CH₄ emission proportions for different processes in WWTPs based on reported data, finding percentages of 7 %-12 % for grit chamber, 8.2 %-68.1 % for primary clarifier, and 18.3 %-86.4 % for aeration tank.

Table 1. CH₄ emission fluxes (Q), Wind speed and direction data (W_s, W_d), the horizontal diffusion coefficient (γ₁, α₁) and the vertical diffusion coefficient (γ₂, α₂)

from the 8-day monitoring experiment. ~~CH₄ emission fluxes, meteorological data and diffusion parameter power function expression coefficients from the 8-day monitoring experiment.~~

Date	Q ($\text{kg h}^{-1}\text{t}^{-1}$)	W _s (m s^{-1})	W _d (°)	γ_1	α_1	γ_2	α_2
0601	61.85 ± 20.41	2.3	248.5	0.28	0.91	0.13	0.94
0629	74.92 ± 35.21	1.9	238.3	0.28	0.91	0.13	0.94
0711	69.58 ± 32.70	0.9	225.8	0.28	0.91	0.13	0.94
1213	49.19 ± 21.15	1.6	175.7	0.28	0.91	0.13	0.94
1214	43.29 ± 27.28	1.2	209.9	0.28	0.91	0.13	0.94
1220	49.99 ± 25.00	3.8	342.3	0.18	0.92	0.11	0.92
1221	48.17 ± 17.34	2.7	342.6	0.43	1.10	0.08	1.12
1222	48.15 ± 21.67	3.0	342.5	0.43	1.10	0.08	1.12

[An alternative top-down approach known as the tracer gas dispersion method \(TDM\), which has been applied to estimate CH₄ emissions from city streets \(von Fischer et al., 2017; Weller et al., 2018\), WWTPs \(Yoshida et al., 2014; Delre et al., 2017; Delre et al., 2018\), biogas plants \(Reinelt et al., 2017; Scheutz et al., 2019; Fredenslund et al., 2023\) and landfills \(Rees-White et al., 2019; Kissas et al., 2022\). TDM involves releasing tracer gases like nitrous oxide and acetylene near the source and measuring their concentrations along with CH₄ downwind using a mobile platform. The similar diffusion patterns of CH₄ and the tracer gases result in a stable concentration ratio after atmospheric mixing, enabling the calculation of CH₄ emission rates with a better accuracy \(Mønster et al., 2014\).](#)

[Moreover, the TDM was employed to validate and compare other model inversion methods. Moore et al. \(2023\) proposed that the Gaussian dispersion modeling demands less experimental equipment, site access, and manpower than the TMD, which allows for swifter data gathering. Yacovitch et al. \(2015\) utilized a five-day dataset of tracer gas release in the Barnett shale region to evaluate the Gaussian dispersion flux](#)

quantification method. The results indicated a 95% confidence interval, with a lower bound factor of 0.334 and an upper bound factor of 3.34. von Fischer et al. (2017) performed three controlled release experiments to validate the reliability of leak rate algorithm in Fort Collins, CO, which indicated a very significant correlation between known and estimated leak rates ($p < 0.0001$, $r^2 = 0.43$). Compared to the method employed in the study, the TDM offers advantages such as simpler formula calculations. Nonetheless, it also presents several drawbacks, including complex experimental procedures, safety hazards associated with the release of tracer gases, which require access permits from industrial facilities.

3.3 Comparison with IPCC method

The ~~direct~~ CH₄ emissions ~~from WWTP~~ were also calculated using the IPCC method, with data sourced from the Urban Drainage Statistical Yearbook of 2017. ~~By applying the formula to the basic information of the WWTP outlined in the yearbook, t~~ The emission flux of $213.95 \pm 128.37 \text{ t a}^{-1}$ was determined, with the uncertainty (60%) derived from the data summarized in the research (Lin et al., 2021). Figure 5 shows the contrast between the emission inversion results from the monitoring experiment and the emission inventory. The uncertainty of the inversion results was determined by accounting for the uncertainties in wind speed, wind direction, and instrument measurements, following the method presented in Section 2.4.5. The uncertainties in emission fluxes inversion ranged from 33% to 63% on individual days. Notably, the uncertainty associated with wind speed contributes approximately 44% to 94% of the uncertainty range. The summer average inversion emission flux ($603.33 \pm 152.66 \text{ t a}^{-1}$) was calculated to be 2.8 times that of the inventory, and the winter average ($418.95 \pm 187.59 \text{ t a}^{-1}$) was twice as much. It is posited that the discrepancy may stem from significant uncertainties in the emission factors associated with the WWTPs or the lack of updated activity level data, as the statistical yearbook provided data only up to 2017,

the emission inventory might have underestimated the actual emissions.

Furthermore, other studies have also investigated the comparison between CH₄ emissions obtained from different measurement methods at WWTPs and IPCC inventory estimates. The majority of these studies indicate that the measured values exceed the inventory values. Wang et al. (2021) conducted a measurement-based assessment of CH₄ emissions (46.58 t a⁻¹) in Wuhu City, revealing a 46.71 % higher than those calculated using the IPCC method. Moore et al. (2023) employed mobile monitoring to evaluate CH₄ emissions at 63 WWTPs across the United States. ~~The study showed that the estimates based on the IPCC guidelines underestimated the emissions from most of the measured plants.~~ Specifically, CH₄ emissions from centrally treated domestic wastewater in the U.S. amount to 4.64×10^5 t a⁻¹, which is 1.9 times greater than the EPA inventory. Song et al. (2023) investigated CH₄ emissions from municipal wastewater treatment in the U.S at $(4.36 \pm 2.8) \times 10^5$ t a⁻¹. ~~sewer systems and water resource recovery facilities. Utilizing a collected dataset, they employed the Monte Carlo analysis method to determine the CH₄ emissions from municipal wastewater treatment in the U.S. at $(4.36 \pm 2.8) \times 10^5$ t a⁻¹.~~ This value was approximately twice the estimates provided by the IPCC. Our estimated results are generally consistent with the previous studies. The lower estimated results provided by the IPCC method can be attributed to the neglect of certain potential emission sources from the emission inventories, including emissions from equipment in sludge treatment facilities and leaks from pressure relief valves.

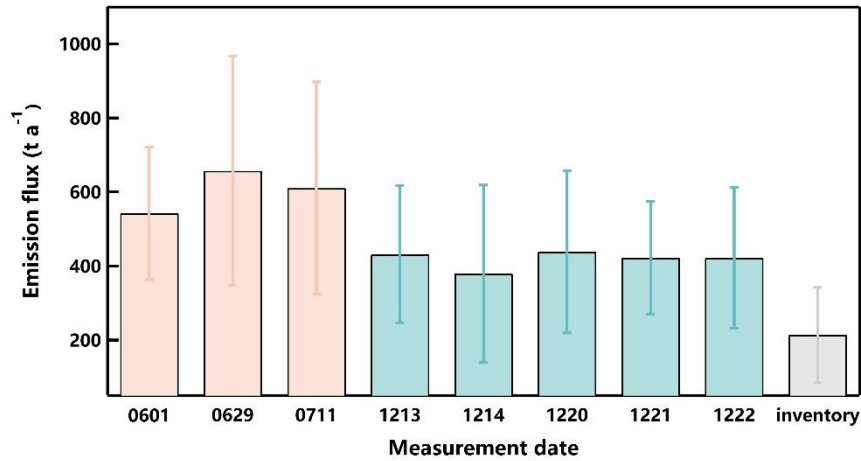


Figure 5. Comparison of CH₄ emission fluxes from the monitoring experiment and emission inventory in the WWTP.

3.4 Sensitivity analysis

In this section, we evaluated the stability of the inversion framework through sensitivity analysis and explored the impact of different point source locations on the inversion of emission concentrations. The precise identification of emission sources can enhance the accuracy of emission flux inversion, making a sensitivity analysis of the source location essential. We applied the method of controlling variables to perform a sensitivity analysis on the location of a single point source. The central position of the plant was taken as the reference origin, the positions of 12 emission sources were determined to analyze the variation in error between measured and simulated concentrations within a 200 m × 200 m range around each emission source. We sequentially modified the source position parameters in the model input to analyze the congruence between the simulated concentrations and the observed measurements, quantifying the fit with RMSE. The change in concentration error serves as an indicator of the accuracy of the emission source localization.

Figures 6 and 7 describe the error variation between monitored and simulated concentrations when the point source location is subject to change within a 200 m × 200 m range from the monitoring experiment on 29th June and 13th December. The error

variation of the remaining days can be seen in Figures S98-S143. The point source locations simulated based on the inversion framework are mostly in areas with minor relative concentration errors, which can be considered to have a high reliability in simulating point source locations. The emission source location errors for the two experiments are within the ranges of 0.7-1.3 mg m^{-3} and 0.2-0.3 mg m^{-3} . The winter emission source locations exhibit greater stability and accuracy in the inversion results than the summer ones.

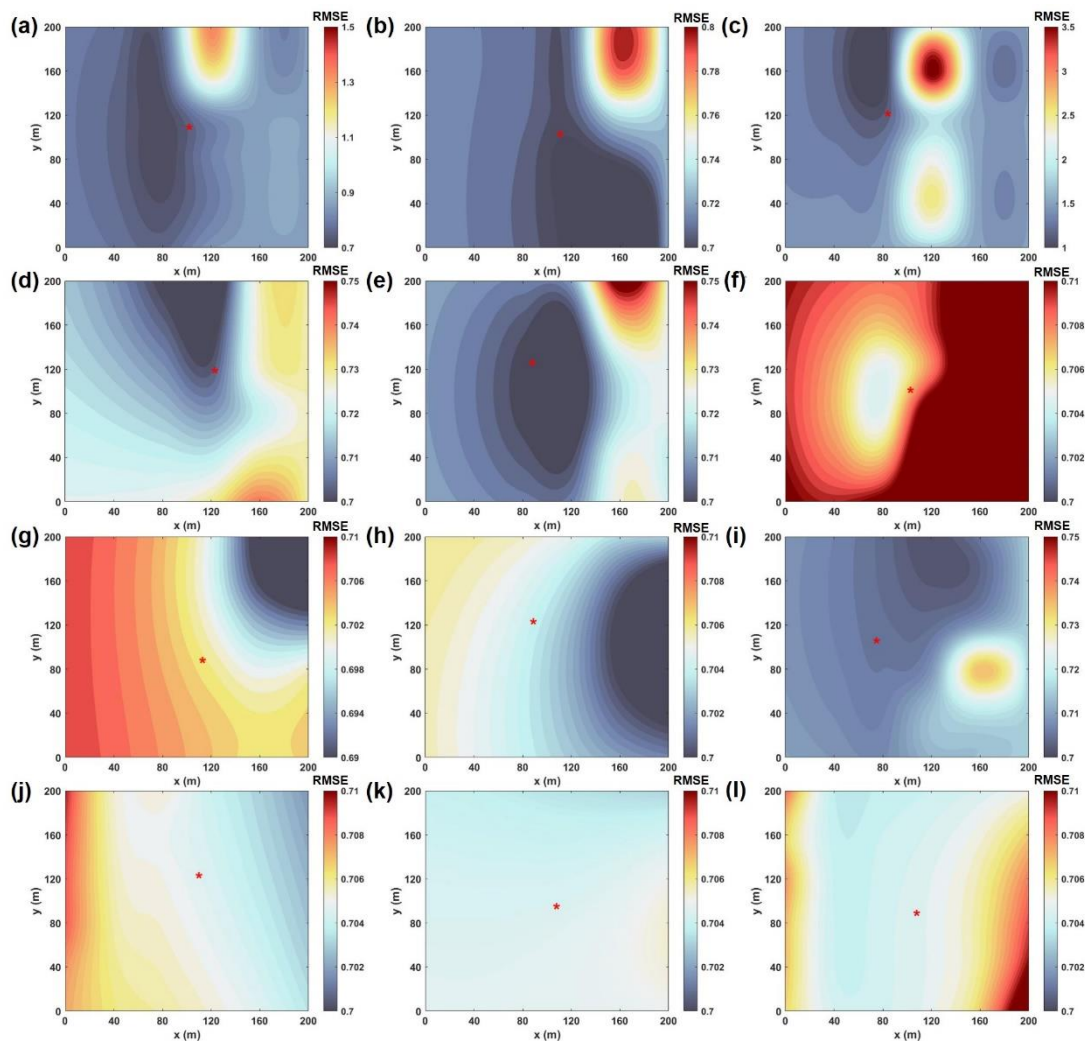


Figure 6. RMSE of monitoring simulated concentration changes with the location of WWTP source on 29th June. The x and y axes denote the horizontal and vertical distances of the simulated point source from the central point of the WWTP. The variation in color signifies the alteration in the root mean square error between the

actual monitored and simulated concentrations, with the red star symbolizing the simulated point source location.

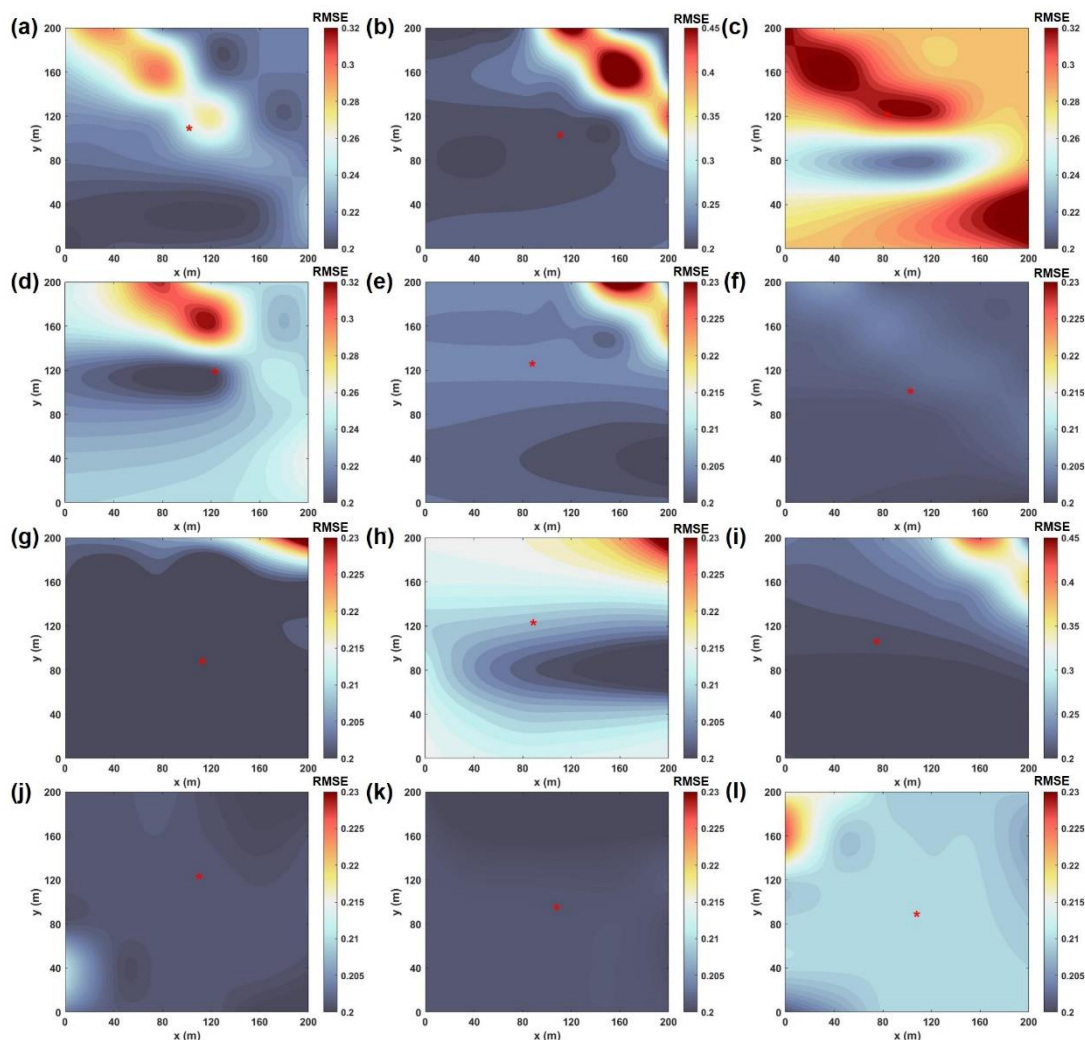


Figure 7. RMSE of monitoring simulated concentration changes with the location of WWTP source on 13th December.

4 Conclusions and outlook

The study carried out ~~CRDS~~-mobile measurements at a WWTP across the summer and winter seasons from Hangzhou 2023. By employing a multi-source Gaussian plume model combined with the genetic algorithm inversion framework, the inversion of CH₄ emission fluxes and their source locations was achieved. ~~A sensitivity analysis of the~~

parameters within the inversion framework was conducted to verify the reliability of the model, offering a strategic approach for the quantification of GHG emissions at the plant scale. The results showed that 12 distinct CH₄ emission sources were pinpointed within the facility through the inversion framework. The average CH₄ emission flux during the summer was $68.78 \pm 17.40 \text{ kg h}^{-1}$ ($603.33 \pm 152.66 \text{ t a}^{-1}$), and $47.76 \pm 21.39 \text{ kg h}^{-1}$ ($418.95 \pm 187.59 \text{ t a}^{-1}$) for the winter. The screen and primary clarifier were the main sources, accounting for 55 % of summer and 67 % of winter emissions. When contrasted with bottom-up emission inventory estimates, the summer CH₄ inversion emissions were found to be 2.8 times higher, and the winter inversion emissions were twice as much as the inventory values based estimation.

The inversion framework is capable of validating emission coefficients in the inventory, identifying emission sources within the plant, and monitoring abnormal emissions. It can be applied to various monitoring systems, such as UAV systems and networks of fixed monitoring stations. We believe that it is an excellent point that collaborative monitoring offers significant improvements in the accuracy of emission fluxes and source inversion. collaborative monitoring by different methods can significantly improve the accuracy of emission fluxes and emission sources inversions. Future efforts should aim to refine It is suggested that future endeavors focus on refining the inversion framework for broader applicability to various pollutant gases, enhancing the inversion efficiency, and extending the validation of the framework through monitoring experiments in a diverse range of industrial facilities.

Data availability. The raw data in this paper can be obtained from the corresponding author upon request.

Author contributions. ZW and YZ administrated the project and determined the main goal of this study. ZX, JY and XP designed the methods and planned the campaign. JY, ZX, YY, SZ and BQ performed the measurements. JY wrote the paper with

contributions from all co-authors.

Competing interests. At least one of the (co-)authors is a member of the editorial board of Atmospheric Chemistry and Physics.

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