# Modular approach to near-time data management for multi-city atmospheric environmental observation campaigns

Matthias Zeeman[1], Andreas Christen[1], Sue Grimmond[2], Daniel Fenner[1], William Morrison[1,2], Gregor Feigel[1], Markus Sulzer[1], and Nektarios Chrysoulakis[3]

[1]Albert-Ludwigs-Universität Freiburg, Environmental Meteorology, Freiburg, Germany
[2]University of Reading, Urban Meteorology, Reading, UK
[3]FORTH, Heraklion, Greece

**Correspondence:** Matthias Zeeman (matthias.zeeman@meteo.uni-freiburg.de)

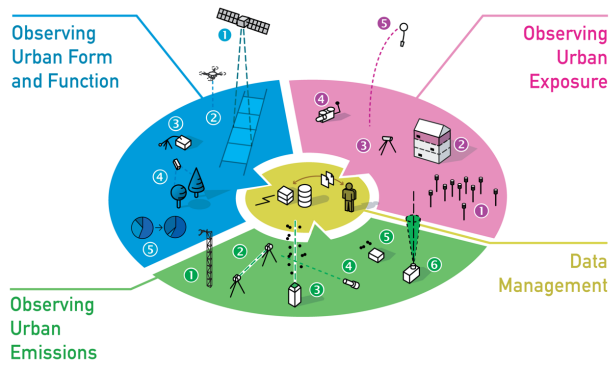
**Abstract.** Urban observation networks are becoming denser, more diverse, and more mobile, while being required to provide results in near-time. The Synergy Grant *urbisphere* funded by the European Research Council (ERC) has multiple simultaneous field campaigns in cities of different sizes collecting data, for improving weather and climate models and services, including assessing the impact of cities on the atmosphere (e.g., heat, moisture, pollutant and aerosol emissions) and people's exposure to
5  extremes (e.g., heat waves, heavy precipitation, air pollution episodes). Here, a solution to this challenge for facilitating diverse data streams, from multiple sources, scales (e.g., indoors, regional-scale atmospheric boundary layer) and cities is presented.

For model development and evaluation in heterogeneous urban environments, we need meshed networks of *in situ* observations with ground-based and airborne (remote-)sensing platforms. In this contribution we describe challenges, approaches and solutions for data management, data infrastructure, and data governance to handle the variety of data streams from primar-
10  ily novel modular observation networks deployed in multiple cities, in combination with existing data collected by partners, ranging in scale from indoor sensor deployments to regional-scale boundary layer observations.

A metadata system documents: (1) sensors/instruments, (2) location and configuration of deployed components, and (3) maintenance and events. This metadata system provides the backbone for converting instrument records to calibrated, location-aware, convention-aligned and quality-assured data products, according to FAIR (Findable, Accessible, Interoperable and
15  Reusable) principles. The data management infrastructure provides services (via, e.g., APIs, Apps, ICEs) for data inspection and subsequent calculations by campaign participants. Some near real-time distributions are made to international networks (e.g., AERONET, Phenocam) or local agencies (e.g., GovDATA) with appropriate attribution. The data documentation conventions, used to ensure structured data sets, in this case are used to improve the delivery of integrated urban services, such as to research and operational agencies, across many cities.

## Summary

Overview of a data system for documenting, processing, managing and publishing data streams from research networks of atmospheric/environmental sensors of varying complexity in urban environments. Our solutions aim to deliver resilient, near-time data using freely-available software.

**Key Figure or Graphical Abstract**

# 1   Introduction

Field observation campaigns are an essential source of information in urban environments, as long-term global climate and weather observation networks often explicitly exclude cities (Grimmond et al., 2020). Urban field campaigns differ in length providing different benefits. For example, short (approximately one year) campaigns offer a cost-effective way to explore seasonal variability in multiple urban areas by relocating instruments, whereas long-term observatories allow changes both from climate and the city itself (e.g., physical, behavioural) to be better understood. Data from both types are needed to support model development for numerical weather and climate predictions and the delivery of integrated urban services (Baklanov et al., 2018) to support current operations, plan management (Chrysoulakis et al., 2023), and adaptation of cities into the future. Such observation campaigns require robust, structured data management. Unlike operational regulatory networks (e.g., air quality), campaigns have limited duration, often employ novel measurement systems often prior to open-source or commercial data management solutions existing.

Urban environments pose challenges because of multiple scales of interest (indoors to city-wide), intra-city and intercity diversity at most scales (e.g., room uses, building types, neighbourhoods), people's activities (e.g., needing to continue undisturbed but impacts observed), and all compounded by city size (Landsberg, 1970; Oke, 2005; Grimmond, 2005; Muller et al., 2013b; WMO, 2019; Yang and Bou-Zeid, 2019; Masson et al., 2020; Grimmond et al., 2020). Existing long-term sensors, enhanced for campaign objectives and applications (e.g., human health, energy infrastructure) allow urban surface-atmosphere dynamics to be captured. However, the multitude of city layouts, topographic settings, and regional climates means there is not one solution to combining field observations, remote sensing and modelling in urban areas. Rather there is need to address this at multiple scales simultaneously, in multiple cities with duplication of combinations to ensure the general pattern is correctly identified (Barlow et al., 2017; Pardyjak and Stoll, 2017; WMO, 2021) in comparisons. Hence, concurrent sensor deployments, mounted on static and mobile platforms, located indoors and outdoors, measuring micro- to mesoscale processes over different length of periods will need to occur.

Research campaigns by definition deviate from operational deployments (e.g., WMO's National Meteorological and Hydrological Services). Urban campaigns have a long tradition of multiple groups combining resources to focus on a city or a specific aspect of the urban environment (e.g., Changnon et al., 1971; Rotach et al., 2005; Allwine et al., 2004; Mestayer et al., 2005; Wood et al., 2013; Bohnenstengel et al., 2015; Scherer et al., 2019; Karl et al., 2020; Caluwaerts et al., 2021; Fenner et al., 2024b), making the homogeneous single-sensor-model network, operated by multiple collaborating partners using identical operating protocols (e.g., same objectives, calibration procedures) unlikely (Scherer et al., 2019; Caluwaerts et al., 2021; Marquès et al., 2022). Although sensors designed for the same observation type may be similar, they are rarely fully interchangeable (de Vos et al., 2020). However, intentionally heterogeneous sensor model networks (e.g., low-cost and high-grade instruments) may complement each-other (Jha et al., 2015; Gubler et al., 2021).

Data collection by a single project in one city should produce comparable data to that collected in other cities, or a later campaign in the same city, to support comparative and longitudinal studies. The large data sets need to be easily ingestible into

model evaluation studies, today and in the future, requiring structured data, attributed metadata, following conventions and

60   standards.

Short-term urban field observation campaigns are highly dynamic (Yang and Bou-Zeid, 2019), capturing processes of interest and responding to near real-time results allowing plans to evolve. ~~This makes~~ The dynamics make data assessments time-sensitive ~~, diagnosing~~ and network operational status ~~critical, to inform models, to make~~ diagnostics a critical task, as intermediate results become indispensable for informing models, making decisions on resource-intensive field deployments

65   (e.g. radiosoundings, tracer releases) ~~, and to make~~ and making dynamic adjustments to network design (Changnon et al., 1971; Rotach et al., 2005). Data management for rapid discovery needs to be both technically and organisationally structured, posing additional challenges (Wilkinson et al., 2016; Middel et al., 2022). In a research community, sharing near real-time data internally and publicly is increasingly expected, as data, software code and products (results) are co-produced. Thus, output becomes "Living Data" given continuous sharing, even before all required metadata are available (Oke, 2005; Stewart, 2011;

70   Muller et al., 2013a; WMO, 2023) including attribution, documentation in peer-reviewed papers, or full scientific scrutiny. However, rapid availability does not remove scientific obligations (e.g., peer-reviewed publications with careful scientific assessment, attribution to researchers, institutions, funding agencies).

Here, we present an approach developed within the European Research Council (ERC) Synergy Grant *urbisphere*. *urbisphere* addresses dynamic feedback between weather, climate and cities through synergistic activities between four disciplines

75   (spatial planning, air- and spaceborne observations, modelling, and ground-based observations). The project involves quantifying aspects of the influence of urban emissions on the atmospheric boundary layer above and downwind of cities; and human exposure in urban environments (e.g., streets, indoors) that vary across a city and with time as both form and function change.

Central to *urbisphere* are both concurrent and consecutive campaigns in multiple cities undertaken in different countries, using a modular observation system. Observations are needed to support empirical assessments and studies, model development

80   and model evaluation. Activities are structured into four Modules (A to D, Figure 1). Module A gathers data on urban form (e.g., morphology, materials) and function (e.g., people's mobility patterns, vegetation phenology), which varies in space and over time. Data from surveys, official sources, imagers and spaceborne sensors are used for geographically and temporally assessing form and function and to derive inputs to models. Module B quantifies how urban form and function affect the urban atmosphere over and downwind of cities through emissions of heat, pollutants, and aerosols and how cities modify the

85   dynamic and thermodynamic state of the overlying atmospheric boundary layer. In Module C, we quantify differential exposure of people in and between cities (e.g., to heat, flooding). The different objectives in Module A to C require targeted and specific observational strategies, but all require consistent data management, documentation and quality control processes ~~.~~ (Module D).

Here we present the integrating data management and infrastructure system (Module D) developed to support the obser-

90   vational sensors and systems in modules A to C (Figure 1). We are excluding spaceborne observations, data from long-term partner data networks (e.g. meteorological agencies and services), and surveys and administrative data as there are existing data management platforms and systems available. Instead we focus on atmospheric and environmental sensing systems in Modules A to C that are deployed during campaigns. The observational sensors and systems deployed in Modules A to C are

diverse (Figure 1)., quantifying many variables, and are operated in diverse settings (e.g., street-light posts, building roof-tops,
indoors) as well as on mobile platforms (e.g., vehicles, balloons, drones). Hence, there are fixed deployments and mobile
measurements, sensors with multiple uses, need for near real-time data (e.g., during intensive observation periods (IOPs)~~,)~~,
and changing configurations, deployments of varying duration (e.g., hours, days, months, years). This is managed by multiple
people with different responsibilities, roles and backgrounds.

The system currently ingests on the order of $10^9$ datapoints per day from about 100+ different stations and approximately
1000 sensors in five different cities. Using automated processes, data are delivered in near-time (minutes to hours) to central
data infrastructure through mobile phone and Internet of Things connectivity. We showcase the technical and organizational
solutions to creating a modular data management system, considering: documentation, acquisition, products, governance, stan-
dardisation, reuse and sharing.

## 2  Data documentation

As data documentation during observation campaigns occurs at pre-, during and post-deployment, it is critical to have a struc-
ture early for capturing all details (e.g., Table 1), especially at busy, time-limited periods. As part of sensor installation prepa-
ration, data to describe a site and sensor-system details need to be captured, as they are essential metadata for processing the
datastream. Standard conventions facilitate data (re)use, enhancing data value both to the general community and the project
(Muller et al., 2013a; WMO, 2021). Critical to this, is it being accessible to team members during a campaign and subsequently
as data are processed (Figure 2).

### 2.1  Metadata

As field observations involve multiple networks (Table 1), metadata are essential to organizing the data collection (e.g., files,
directories), and as the audit trail of modifications. ~~The~~ Because of the latter, the physical, logical, and organisational context
of the field observations are defined early in the data management process (Table 1)~~because of the latter,~~, and amended with
updates from planning to collection to publication. Once data collection begins, the production chain needs to systematically
encode attributes (e.g., location) into a series of searchable databases (DBs; Figure 3).

The *Inventory DB* has all instruments used in the campaigns with links to the maintenance and organisation details (e.g.,
owners of different parts of a deployment, Figure 3). The inventory DB holds the primary calibration, purchasing, maintenance
and software (firmware) history and availability of each instrument. ~~Examples of the~~ The operational relational queries ~~,
using a graphical user interface~~ are supported by graphical user interfaces (GUI) ~~, include finding:~~ with shortcuts for specific
summaries. Those help find, e.g., (1) if an identical instrument model exists in storage or ~~another deployment;~~ in another
deployment, (2) all instruments at a location~~;~~, (3) all mobile-phone SIM cards linked to a data plan ~~;~~ (4) all calibration sheets
and warranty documents for a given sensor ~~, and warranty documents~~ to facilitate sending an instrument back to a manufacturer
for service. The inventory GUI offers dialogue in multiple languages, facilitating international cooperative use by all staff and
incorporates direct access to all instrument manuals.

The *Deployment DB* (Figure 3) has instrument's configuration, including location and relation to other instruments during a deployment, as well as organisation details. This is the primary record of instrument operational status at any time. The *Deployment DB* GUI allows entries to be added or modified. Most instruments are in a hierarchical relation, such as being a "child" connected a "parent" (e.g., internet-attached data logger connected to an instrument). A two-level parent-child hierarchy has instruments on a local network node with a local storage node referred to as a "system" (Table 1 and 2). For the *Deployment DB* consistency, instruments with integrated data recording and autonomous network capabilities are both a "system" and a "sensor".

The hierarchy of spatial information for a "station" (or "site") ~~is from geographic coordinates , to~~ starts with geographic coordinates of a point on a representative surface, which can be determined accurately in advance to assure suitability for sampling by (airborne) remote sensing. The "system" and "sensor" are measured in relation to the "site" in a local Cartesian or polar coordinate system (Figure A3)~~to~~. This helps explain details in a complex setting such as a roof (Figure A1), a street canyon or within a building (Figure A2). The database relationships allow identical sensor replacement~~(e.g., AWS),~~, without needing to modify any of this spatial information. Typically, a duplicate configuration is modified to capture the changes occurring for a period. Given numerous complementary data sources, including space- and airborne (e.g, satellites, drone, aircraft sensors), city GIS, and models (e.g., source areas, numerical weather prediction model output), it is critical that metadata are precisely geo-located and time-stamped. In the deployment DB, start and end time identify the operational periods (Figure 4).

The *Events DB* (Figure 3) captures the field and laboratory notes, normally linked to events, such as on-site maintenance visits, relevant near site changes, remotely identified anomalies, and instrument disturbances (e.g. dirt on sensors). All field visits, instrument malfunctions, disturbances, anomalous weather, unexpected patterns in observed data, and brief ~~datastream~~ data stream outages need to be documented as "events" at the time, and may require subsequent actions. Complete documentation should provide a traceable audit trail of all intended and unexpected conditions related to an observed variable and, to facilitate subsequent data interpretation, measurement and photos of the location, orientation, direction of view and relative position to obstacles, attributed with a timestamp. This information is vital to identifying and explaining unexpected changes or anomalous data. The collected event notes, after evaluation, if needed, are converted into *Deployment DB* entries. Most events are not recorded in the *Events DB* in real-time, because of varied paths, sources requiring decisions about the data consequences, and its appropriate use (Figure 5). Data stream quality control (QC) includes automated assessment of typical meteorological variables (e.g., air temperature, humidity, wind speed, wind direction, pressure, precipitation intensity), following e.g., ~~VDI (VDI 2013, Figure B1 and Figure B2)~~VDI (VDI 2013, see Appendix B). Event detection can include spatial statistics, but this is not operationally implemented. Documentation based on the metadata uses persistent identifiers and versioning in order to accommodate the advancing insights on quality, events and deployment status (e.g., Plein et al., 2024).

## 2.2 Conventions

Building on existing data conventions and standards can enhance data usage. In *urbisphere*, we use the climate and forecast (CF) metadata conventions (cf-conventions-1.10, or CF hereafter; see Hassell et al., 2017) API for NetCDF, with extensions

often used in the urban research community (Scherer et al., 2019)~~and~~. The use is consistent with prior campaigns, model applications, third-party software tools, and common with the campaign's instruments and project-specific production needs.

Most of the production chain in *urbisphere* is based on NetCDF database files. To maximise portability, only features commonly implemented in the various software libraries and platforms are used. A set of unique identifiers creates a relational chain between locations, instruments, events, variables and variable units, and therefore the data recorded and publishable data products. To facilitate this, instruments and data are organised into functional groups (Figure 1, Table 3; see also Appendix B).

Many instruments and data recorders encode sensor data records to proprietary formats, which based on user options may provide calibrated and aggregated data records with sensor diagnostics. To simplify later inquiries, a best practise for output file formats, metadata attributes and file name patterns for each instrument model or instrument group (see, e.g., Appendix B) is adopted. Where possible, identifiers are included as headers in instrument data files, directory names and/or file names. These practises allow programmatic extraction of key identifiers from file names, data and metadata databases with few exceptions. Particularly for observation systems that used APIs for the retrieval of data, a consistent use of identifiers is an essential operational aspect (Feigel et al., in review).

### 2.2.1 Vocabulary

CF forms a robust framework for data and metadata, but does not formally include all variables needed in urban areas (Grimmond et al., 2010; Scherer et al., 2019, 2022; WMO, 2021; Lipson et al., 2022), so extensions are made building on earlier projects that will need further review to be formally brought into the CF (Hassell et al., 2017). The shared vocabulary facilitates efficient queries and ~~multiple benefits~~ benefits for the machine-operability of the data.. The CF conventions defines vocabulary for dimensions and units for many variables, as well as attributes to assure data provenance (Hassell et al., 2017). Existing community software tools work with NetCDF and CF-related vocabulary definitions, including modules to perform programmatic conversion of units ~~of quantities~~ (e.g., the UDUNITS module; Hassell et al., 2017).

### 2.2.2 Outdoor deployment

Site selections in urban deployments depend on research questions, measured variables, and scales of interest (WMO, 2006; Oke, 2017). ~~Measurement of, e.g.,~~ For example, the measurement of near-surface air temperature in an urban area may require different siting requirements than standard WMO regional scale weather ~~, with neither satisfying the other~~ measurements (Stewart, 2011; WMO, 2023).

Most deployments are at fixed locations, but as surroundings change, regular review of deployment configurations are required, and ~~therefore metadataadjustments~~time-specific amendments are needed to the metadata. Some instruments have accurate clocks and sensors to self-determine location and orientation, providing metadata ~~details~~as a separate time-series in the data (e.g., ~~radio-sounding sensors~~ pressure and GPS sensors on radio-sounding systems; motor-drive position and inclinometer on lidar systems). Other deployments may require ~~frequent~~ the sensor viewpoint and orientation as well as time offsets to be ~~determined~~measured regularly or determined continuously relative to a (local) reference. Site documentation requires consistent use of coordinate reference systems, considering various aspects of urban landscapes and linkable to other sources (e.g.,

city GIS systems derived from detailed airborne lidars, numerical models) (Appendix A; Figure A1). Local reference points are needed for all observations to be linked to other (e.g. geospatial) datasets. Some stations are located on surfaces (e.g., roofs) that may not coincide with the deployed platforms or instruments. However, using a representative surface coordinate set (Figure A1b), instead of exact system location (Figure A1a; Figure A2), simplifies immediate reuse of coordinates between sources. Furthermore, some sensor views may not provide usable data for some research objectives, requiring detailed understanding of a site (e.g., glass or shaded areas for thermal imagery; orientation of a roof edge for momentum flux; three-dimensional scan patterns for Doppler wind-lidar). All systems have GPS time or internet reference time services, and all data during *urbisphere* campaigns are ~~generally~~ recorded in UTC or the GMT/UTC+0000 locale without daylight saving for systems with time-zone unaware recording of timestamps (Appendix A1).

### 2.2.3 Indoor deployment

Sensors deployed indoors have multiple purposes including assessing: human exposure (Sulzer et al., 2022), building energy models (Liu et al., 2023), and influences of the indoor micro-climate extremes on human and animal stress (Walikewitz et al., 2015; Marquès et al., 2022; Sulzer et al., 2023), so require many site details. A classification is implemented that includes characteristics and orientation of the building, room, walls, windows, content of the room, space usage type, occupancy, and other factors affecting the indoor climate and human comfort of workers or residents (Appendix A; Figure A2). Whereas basic meteorological observations are recommended to be free of obstacles and heterogeneous influences, indoor observations are, in summary, an opposite. Siting for all sensors need to be representative of what people and room are likely to experience, while still allowing the ~~rooms~~ room to be used in its intended way.

### 2.3 Operational management

Conversations about planning, issues and resolutions are an essential part of a campaign's knowledge base. To make communication related to the deployments accessible for discovery by data users, from any location and at any time, each campaign maintains a repository for issue tracking, source code development and wiki-type documentation (GitHub, GitHub Inc, San Francisco, CA, USA). Similar repositories help maintain overarching subjects, such as data management. Other repositories are maintained on enterprise cloud data storage (Dropbox, Dropbox International Unlimited Company, Dublin, Ireland), to store and share auxiliary data files, such as photos, protocols and calibration records, organised by campaign, location, and time. Additionally, customised forms and shareable spreadsheets are accessible using online services (Google Forms and Google Sheets, Google Ireland Limited, Dublin, Ireland), to gather provisional metadata.

The core database systems, including the inventory and deployment configuration DBs (Figure 3), are designed using open source web-, database- and user-interface tools (the so-called LEMP stack; Linux, Nginx, MariaDB, PHP) and application frameworks (Appendix C3).

## 3   Data acquisition and products

A "data source" may be a sensor, a network node or an organisational unit (Table 1), with different contexts that need to be
retained and clearly identifiable. Typically, a chain of systems and responsibilities are involved, with multiple actors, nodes
and locations (Table 1; Table 3; Figure 5). The source needs to be defined and preserved in order to ensure data governance
agreements, accessibility, responsibilities and effectively respond to issues that occur. For example, if an instrument at a par-
ticular location is not responding, the data and metadata must allow the relevant infrastructure, the responsible people and the
production line processes to be looked up efficiently (Figure 2) for that particular location. Key features of the physical and
logical networks (~~Section 3~~this section) are presented to organisational aspects (Section 4).

### 3.1   Data infrastructure

The data infrastructure combines the interest of data safe-keeping with data accessibility (Figure 6). Keeping data secure is a
primary project deliverable and involves basic protection against unknown malicious actors and protection against accidental
data loss. Within the data architecture, a central operational archive is maintained on a suitably large storage volume (larger
than 50 Tb logical volumes on RAID storage units). A replica of the data is maintained on an identical storage unit in a different
building (geo-redundant backup), with additional daily backups on enterprise storage services (on and off campus). The data
infrastructure uses virtualised computing hardware. Virtualization makes it possible to isolate critical functions without the
need to expand physical hardware, and allows the data infrastructure to scale dynamically as needed. The critical functions
include a remote access node for all uploads from local field stations ("gateway"), a remote access node for metadata databases
and related web-interfaces ("status"), a remote storage node for archival of data and public access nodes ("workstations") for
monitoring, computations and user access to data (Figure 6).

### 3.2   Access

The original data and metadata are kept on different physical servers. However, users with access to a workstation are provided
with immediate access to a read-only view of the original data, as well as a read-only replica of the metadata DBs. Access
to data and metadata is read-only by default, primarily to minimize the risk of accidental data loss. This in turn removes the
need for strict user access guidelines on the public access node workstations, allowing a more liberal use of the workstation
resources. Workstations are used as public access nodes, with a wide selection of services available at the user-level, including
Application Programming Interfaces (APIs), Integrated Computing Interfaces (ICEs) and other interactive websites (Apps) for
users and the public (see also Appendix C).

However, adding new files to the archive, or modifying files on the archive, is more involved, and requires new or renewed
upload. The uploaded data are managed by data managers, using separate accounts for the upload and data management. Users
and groups are managed on a file system level and the credentials are maintained in encrypted key chains for each campaign.
The need for administrator privileges is avoided, where possible, and the directory access for accounts used in automation (e.g.,
FTP credentials are transmitted as text) is restricted in scope. Write access to the remote storage node is restricted by default

255 and limited in scope. Typically, data are uploaded automatically by an instrument, or manually by a user, onto intermediate storage locations on the remote storage node ("upload server"; see Figure 6). Typically, uploads are synchronised immediately to dedicated locations on the archive. The synchronisation uses individual configurations for each of the upload locations, which can be activated or deactivated if needed. Data management accounts are restricted in access scope to the relevant locations on the archive, set by file system permissions of the intermediate storage source and the destination location on the

260 remote storage node. The design allows multiple campaigns to be operated at the same time without cross-interference, and facilitates the transition in instrument deployment from one campaign to the next by either replacement of the user credentials for data upload on the local network node in the field or by re-configuring the redirection destinations on the remote access node. Such a transition between campaigns is helpful, as it allows the write access to original data locations to be revoked by a data manager after completion of one campaign, without the need to modify the individual file attributes of a complex subset

265 of millions of files in file locations shared with subsequent campaigns.

### 3.3 Sources

Instrument groups are based on characteristic instrument features (Table 3). The three-character identifier is sufficient to prevent ambiguity.

Data are stored in the instrument-provided formats, which may be custom text records (encoded information in a proprietary

270 format, e.g., TOA5, or a defined schema, e.g., XML), where new records are appended as lines to a file with a header that contains metadata and a column description. However, we have a preference for standardised delimited text files (e.g., comma separated values) to simplify archival. Binary format files are used only where no text-based alternative exists. Binary formats are introduced where encoding is necessary to save storage space and bandwidth, including image formats for grid data and NetCDF format for trajectory data (Table 3). The data files contain collections of up to daily periods, except for the few cases

275 with single timestamp observations stored in separate files.

### 3.4 Transmission

Network connections for temporarily deployed instruments need to be flexible and modular. As a research network, temporary and long-term network outages must be accounted for in the design, requiring sufficient local data storage on or near the instrument, as well as methods to resume data transmission after an outage. The data recorded since the start of the network

280 outage need to be transferred, ideally automatically. This requires methods that identify what is missing on the remote storage location, and skip redundant uploading to save bandwidth. Although there are no substantial differences between text and binary data storage, the transfer of binary data requires extra caution. File corruption from an incompletely transferred binary file makes data inaccessible, whereas incomplete text files can mostly be read and processed. In both cases, it is critical to assure transfer of an identical copy from the local instrument to the remote archive.

285 As a logical network, the local storage node and local access node have an important role in transmission of data (Table 2). The local storage and local access node are combined, where possible, by selecting instruments with autonomous mobile phone network capabilities (NBIoT network type) or by connecting an instrument directly to: an existing station network (wired or

4G LTE network type), a mobile phone network router (4G LTE network type) or a more capable instrument within the shared local network (see e.g., Raspberry PI model 4 based data logging; Feigel et al., in review). Those capabilities include having redundancy in data storage, network access and data transfer services (e.g., desktop access, file access) and housekeeping software. These capabilities typically help remedy limitations arising from any legacy operating systems and outdated firmware of instruments.

The logical network uses industry-standard protocols for the transmission of data files (i.e., FTP, SFTP and RSYNC through SSH). SFTP adds a secure authentication and encryption layer to the transfer (cf. FTP), whereas RSYNC adds incremental, compressed and validated data transfer (cf. SFTP). RSYNC is preferred, as it allows reliable recovery of incomplete or failed transfers with limited bandwidth overhead on the logical network. Custom software is used to configure the RSYNC client software and set retention periods for data transmission (Morrison, 2022). The synchronisation of data between storage locations also relies on RSYNC (i.e., as transport method for Lsyncd). We find the FTP protocol is no longer fully supported by all mobile phone network carriers. As some data loggers (e.g., model CR1000X, Campbell Scientific, Logan, Utah, USA) use alternative protocols, the upload server is configured to allow legacy authentication methods for SFTP connection. The flexibility to make such server-side adjustment to the configuration underpins why ad-hoc research data collection benefits from a dedicated, custom data infrastructure (Figure 7).

A limitation of the current internet infrastructure is that an assigned network address cannot be reached from outside a private or mobile network without a Virtual Private Network (VPN). By default, the data transfer can only be initiated from the local access node to the remote storage node. VPN is available through some routers (e.g., model RUT240 and Teltonika services, Teltonika Network, Kaunas, Lithuania), or commercial remote desktop software (e.g., AnyDesk Software GmbH, Stuttgart, Germany). On occasions, both remote access solutions are used to diagnose issues, transfer miscellaneous files or reconfigure instruments from a remote office location.

### 3.5 Production levels

Participants and data systems produce many data set and services. Most intermediate results are shared immediately and automatically for different uses. Production processes have production levels (some optional) to help keep track of data from collection to publication, as follows (Figure 8):

- *RAW*: Data recorded by instruments, from multiple sources (e.g., campaign-deployed sensors, partners, third-party APIs).

- *L0* (optional): Transcribed RAW data (i.e., to binary) with metadata attributes and typically aggregated to daily or monthly periods. This structured alternative to RAW data is intended to speed up data ingestion for subsequent data processing tasks, with variable vocabulary identical to the RAW input files.

- *L1* (optional): Curated data sets, with various processing (e.g., quality control, coordinate alignments, metadata standardization, translation of names and units according to conventions) but remaining penultimate to L2.

- *L2*: Published or publication-ready data sets. Metadata attributes, as its absolute minimum, include title, source, keywords, references, authors, contributors, license, comments, history and creation time.

The production levels are collaboratively managed. L0 products are typically scheduled automated routines (e.g., Figure 8, Figure 9, Figure 2), with timing adjusted to recover if brief (2 - 28 h) data transmission delays occur between a local instrument source and the remote destination (Figure 5). Beyond this, further interaction is needed (Appendix A1). L0 data are shared as input for diagnostics and other near real-time analyses. Data products and intermediate results follow naming conventions given in Appendix B.

## 3.6 Services

Web-based interactive computing environments (ICE) on workstations with common libraries and replicate environments are to develop code with immediate access to the data archive. The intent of this centrally-managed ICE is to reduce interoperability issues arising between libraries and versions from individually-maintained code environments. The common ICE has Python and R interfaces (JupyterLab), is modified upon request and documented (i.e., a GitHub repository) and if needed, users can built and use their own ICE (Appendix C2, Figure C1).

Visualisation of data is implemented into internet-accessible applications (Apps), developed and deployed by researchers using ICEs. The main evaluation of data processes, operational status and availability relies on "quick-look" figures, automatically generated from RAW/L0/L1 data. These are integrated into interactive Apps, or dashboards (Appendix C; notably C3). Data flows are monitored with respect to recorded data files and data within. A software tool monitors system status, resource monitoring and alerts ("watchdog") using the NAGIOS protocol and tools.

Application programming interfaces can enhance data access by providing dedicating handling of communication between computer programs and are used for many tasks. For some instrument subgroups, APIs are the main point of access to recorded data (e.g., a street-level automatic weather stations network, Figure C1). In turn, we provide access to curated data in near real-time to researchers and partners using APIs (Appendix C4). The ZENODO research data repository API helps simplify automated data management tasks for publication of data (European Organization For Nuclear Research and OpenAIRE, 2013; Rettberg, 2018). The APIs use REST methods for communication (Appendix C4).

## 3.7 Operational Costs

To help keep operating costs low, logical network design, careful configuration of data transfer tools and automation are used. Semi-automated, central data collection allows multiple people to monitor instrument and network output in near real-time. The efficiency of incremental, compressed data transfer reduces data transfer volumes, allowing many systems (stations) to share one mobile phone data plan. User-level automation on local storage nodes (e.g., scheduled data transfer, local data housekeeping and data transfer recovery after outages) reduce interference of running systems during maintenance (e.g., onsite swapping storage cards). User-level automation on remote access node and public access nodes, allow campaign data managers

350 to control their data flow and allow multiple users to develop solutions for data monitoring, data exploration and computation, independently.

The virtual hardware is provided by the host (approx. EUR 500 to 1000 per year) with a one-time purchase of data storage units (approx. EUR 40.000). The software tools are open source, except for remote access software license (approx. EUR 250 per year). All tools need to be configured and programmed, for which the personnel costs include a data scientist, as well as a 355 researcher, a field technician and research assistants for each campaign.

The benefits of near real-time data access and cost savings must be weighed against costs (e.g., mobile phone network routers, data subscriptions, development time). Other operational costs involve the servers (e.g. configuration, maintenance of local and remote access nodes), storage (e.g. remote nodes, redundant backup systems) and public access node workstations. Typically, local access nodes are not modified during a campaign, so require rigorous testing prior to deployment (Feigel et al., 360 in review). For our system, the remote access, storage and metadata database nodes consisting of ten servers using Windows, Linux and OSX operating systems. All requiring frequent security updates to comply with institutional requirements and industry practise. Virtualization hardware, additional backup systems and encryption certificates are provided institutionally. This data infrastructure can be expanded as required from multiple, concurrent campaigns and projects.

## 4    Data governance

365 Most campaigns use data streams from partners instrumentation either directly or more typically from their data networks (e.g., Weather Service), or from third-party networks they contribute to (e.g., AERONET, Phenocam Network, ICOS, PANAME) (Giles et al., 2019; Richard et al., 2018; Haeffelin et al., 2023). Many of the latter are two-way contributions with campaign sensors also providing data to these networks. Data management is facilitated by assignment of roles and responsibilities. The roles are commonly shared or combined. Examples of different type of roles of users of the system include (Figure 2, Figure 5, 370 Figure 7, Figure 8, Table A2).

- *Principal Investigator*: executive responsibility for all scientific activities, campaigns, data and peer-reviewed publications and priorities;

- *Publication Manager*: responsible for a data publication process;

- *Campaign Manager*: lead for all aspects of a particular campaign (city);

375 - *Data Manager*: lead for data infrastructure supporting campaign teams;

- *Publication Manager*: responsible for a data publication process;

- *Researcher*: responsible for a particular data production line or instrument group;

- *Field Operator*: responsible for deployment and maintenance.

Many people undertake data manager and researcher roles, with most at the end having a responsibility for publishing data.
We should further recognise the responsibilities for (1) data science (i.e., scientific requirements, analysis, products), (2) data management (i.e., logical requirements, policies, workflow design, quality control) and (3) data infrastructure engineering (i.e., software and hardware architecture, software development, operations, performance management, end-to-end user/security/network implementation). There are clear differences between these responsibilities, and having experts focus on each separately can arguably improve data system resilience and longevity. However, setting up teams of data experts is not common in soft-funded academic projects engaged in short-term collaborative observational campaigns, and responsibilities end up being carried by few people (see Section 3.7).

Data governance needs to recognize the multiple participating members (e.g., campaign teams, project partners, land owners, external data providers and data users), their interests (e.g., contribution to outputs, liability limitations, expenses, funding agencies) and to provide open data using FAIR principles (i.e., findable, accessible, interoperable and reusable; Hassell et al., 2017). Thus, data governance covers (Figure 10):

– *Formal agreements* for deploying instruments on a property or institutional platform (e.g., lattice mast) or location (e.g., observatory).

– *Grant agreements* (e.g., *urbisphere* Data Management Policy) covering data ownership and grant compliance laws (e.g., European GDPR (General Data Protection Regulation 2016/679), FAIR, data security and data retention).

– L2 data are releases with a *license* (e.g., Creative Commons Attribution 4.0 International; CC BY 4.0) with terms of use adjusted in compliance with the license (Brettschneider et al., 2021). Various notices are included, e.g., license, creator, copyright, attribution, materials, disclaimer notice and citation. The license notice is a machine readable reference to the license, including a link or URI to the full license text. The creator notice states the data authorship. The attribution notice includes a template to address attribution parties, e.g., to credit the primary funding agency. The disclaimer notice involves legal text regarding the limitation of liability and warranty. The material notice describes exactly what part of the work is covered by the licence, such as data records, images and text, but not the NetCDF database structure. Prior to release, the license and creator notice will not be included and a copyright notice is used instead (Table 6).

The data management agreements set requirements on how data will be stored and accessed, which must be communicated and made understandable to the individuals and associations involved (Figure 11), regardless of their role in the organisation of a campaign (Figure 2, Table 1).

## 5  Conclusions

A resilient modular monitoring system for urban environments has been developed to allow rapid new deployments with changes in infrastructure and network technology with a diverse set of field instruments being deployed during observation campaigns. The implementation primarily uses: freely-available software tools, established services for storing research data, and community adopted conventions.

The system has to date been employed in several cities and different countries simultaneously. Our use cases not only involve research data products but also urban hydrometeorological services that reach the users – government officials, modeling teams and the public – in near real-time through the implementation of FAIR principles.

*Code and data availability.* Datasets are available through the Zenodo community *urbisphere* (zen, 2021).

# List of Tables

# List of Figures

**Table 1.**

| Physical Network | Logical Network | Organisation /Association |
|---|---|---|
| **Instrument**/Sensor * | Local source node * | Owner * |
| Instrument/System * | Local storage node * | Owner * |
| Instrument/System * | Local access node * | Field Operator * |
| Station * | | Station Owner * |
| Server | Remote access node | Data Operator |
| Server | Remote storage node | Data Manager |
| Server | Public access node | **Open Access** |

**Table 2.** Observational network data are organised using a limited set of dimensions, (typically) retrieved from the data itself and their associated metadata. Ingested data (RAW) are completed across the multi-dimensional data stores at level 0 (L0). Although metadata are essential for data analysis, they are not repeated at all levels (L) to improve interoperability.

| Data dimension | Production Level | | | |
| --- | --- | --- | --- | --- |
| | RAW | L0 | L1 | L2 |
| **time** | ☑ | ☑ | ☑ | ☑ |
| **station** | | ☑ | ☑ | ☑ |
| system | ☐ | ☑ | ☐ | ☐ |
| sensor | ☐ | ☑ | | |
| channel | ☐ | ☑ | ☐ | ☐ |
| **cell** | ☑ | ☑ | ☑ | ☑ |
| attributes | ☑ | ☑ | ☐ | |
| attribution | | ☑ | ☑ | ☑ |
| history | | ☑ | ☑ | ☑ |
| license | | ☐ | ☐ | ☑ |

**Table 3.** Instruments are classified into functional groups with sensors measuring at a point, along a path, or pixel area. Many instruments have dynamic source areas either because of meteorological conditions or if the sensor is mounted on a mobile platform.

| Group | Feature | Name |
|-------|---------|------|
| AWS | point | Automatic Weather Station |
| RAD | point | Radiometer System |
| IBS | point | Indoor Biometeorology System |
| ECS | point | Eddy Covariance System[a] |
| GAS | point | Gas Analyser System |
| SRS | point | Spectroradiometer System |
| ALC | path | Automatic Lidar and Ceilometer |
| DWL | path | Doppler Wind Lidar |
| LAS | path | Large Aperture Scintillometer |
| MWR | path | Microwave Radiometer System |
| RSS | path | Radio Sounding System |
| SPS | path | Sun Photometer System |
| HIR | area | Hyper-Spectral Image Recorder |
| MIR | area | Multi-Spectral Image Recorder |
| TIR | area | Thermal Infrared Image Recorder |
| VIR | area | Visible and Thermal Infrared Image Recorder |
| RGB | area | Visible Red-Green-Blue Image Recorder |
| PHE | area | Phenocam |

$a$) Can include a gas analyser instrument.

Table 4: Example production lines used in the data management system.

| Module | Group | Production line | Instrument(s) | Primary products (RAW, L0) | Secondary products (L1, L2) | Example tools used for the production |
|---|---|---|---|---|---|---|
| A | PHE TIR | Phenocams, Cloudcams | | RGB, IR images | Green chromatic coordinate time series | Richardson et al. (2018, Phenocam Network) |
| B | ALC | Automatc lidar and ceilometer | Vaisala CL31, CL61; Lufft CMK15 | Attenuated backscatter; layer detection; diagnostics | Mixed layer heights; PM10 concentration | Kotthaus et al. (2020, STRATfinder) |
| B | DWL | Doppler wind lidar | HaloPhotonics StreamLine | Attenuated backscatter; radial wind velocity; diagnostics | Wind direction; wind speed; velocity variance; layer classification | Manninen et al. (2018) and Vakkari et al. (2019, FMI code); Teschke and Lehmann (2017) and Kayser et al. (2021, DWD code); Zeeman et al. (2022). |
| B | LAS | Scintillometers | Scintec BLS450, BLS2000 | CN2 | Sensible heat flux | Fenner et al. (2024a) |
| B | ECS | Flux towers | CampbellSci IRGASON | Wind components; $H_2O$, $CO_2$ fluctuations | Wind direction; wind speed; velocity variance; latent heat flux; sensible heat flux; $CO_2$ flux; $H_2O$ flux; momentum flux | Eddy Pro |
| C | RSS | Radio Sounding | SparvEmbedded WindSond | Air temperature; Humidity; Pressure; Location | Calibrated values | Fenner et al. (2024b) |
| C | RAD AWS | Sun trackers and radiometers | KippZonen CM21, CG1, CG4, CHP1, Solsys2, CNR4 | Shortwave irradiance (direct, diffuse); Long-wave irradiance; Shortwave out; Long-wave out | Calibrated values; On-site calibration with roving reference system | |

| | | | | | | |
|---|---|---|---|---|---|---|
| C | SPS | Sun Photometers | CIMEL X18-T | Directional irradiance in different wavelengths | Aerosol optical depth | Giles et al. (2019, AERONET) |
| C | AWS | Outdoor street-level sensor network and weather stations | CampbellSci ClimaVUE50, Blackglobe-L; PESSL LoRAIN | Air temperature; humidity; precipitation; wind speed; wind direction; pressure; global radiation; lightning; black globe temperature; diagnostics | Mean radiant temperature; Physiologically equivalent temperature (PET); Universal Thermal Climate Index (UTCI) | Feigel et al. (in review), VDI (2013, automated QC), |
| C | IBS | Indoor sensor network | | Air temperature; humidity; black globe temperature; wind speed; diagnostics | Mean radiant temperature; Physiologically equivalent temperature (PET); Universal Thermal Climate Index (UTCI) | Sulzer et al. (2022, online calibration and calculations) |

Table 5: Glossary.

| Term | Definition | Example |
|---|---|---|
| Data | Collected observations, recorded information. | |
| Metadata | Description of circumstances, configurations, conditions, decisions under which data were collected and/or processed. | |
| Deployment | The installation and operation of an instrument at a given station over a given timeframe. | A ceilometer deployed from April 1 to April 15 at a given station. |
| Deployment Configuration | The details of the deployment, namely the arrangement, alignment and programming of instruments in a deployment | Location, tilt, relative position (see Appendix A). |
| Event | A period in time in which either a sensor, a system, a station is affected by a situation that could affect data quality and/or scientific relevance. | Snow cover on radiometers, weather forecast warnings for storm or heatwave, power outage, damage by vandalism, maintenance such as, e.g., sensor and platform cleaning. |
| Production level | Milestones in the recording, production and publication process of data and metadata. <br><br> – RAW: Data files, as recorded and transmitted by systems and sensors, i.e., the primary measurements; <br><br> – L0: Conversion to a common data structure; <br><br> – L1: Computation, conversion to a common vocabulary; <br><br> – L2: Final attribution for public release. | |
| Production line | A set of consistently applied conversions, computations and other procedures to obtain consolidated, attributed secondary information from original measurements. | Mixed layer height determination, eddy covariance flux calculation, statistics |
| Station | A fixed geographic location where one or several instruments are deployed. | Eddy covariance station, observatory |
| Platform | A structure or mobile device on which one or several instruments are deployed. | Tower, tripod, van, balloon, drone, aircraft |
| Network | A group of stations and/or platforms in a campaign. The grouping can be physical (same city), logical (same instrument model, same production line) and/or organisational (same owner). | Street-level sensor network, indoor sensor network. |
| System (Instrument) | A coherent device that contains one or more sensors and/or records and transmits data. | Radiosonde, datalogger |
| Sensor (Instrument) | A device that records an atmospheric or environmental property over time (and/or space). | Thermometer, barometer, thermal camera |

| | | |
|---|---|---|
| Channel | Data dimension for variables with the same coordinates. | Red-Blue-Green in an image, recordings with diagnostics/computations/statistics separately |
| Cell | Data dimension for a single data point (one unit of observation, at one point in time, at the data collection level or subsequent statistics), defined with spatial and temporal boundaries. | |
| Point | Feature of data, a data point (or a basic volume). | See Table 3 |
| Path | Feature of multi-dimensional data: | See Table 3 |

- – Trajectory: way-points for each cell;

- – Transect: between two locations;

- – Profile: along an axis (i.e., vertical).

| | | |
|---|---|---|
| Area | Feature of multi-dimensional data, e.g, raster, grid, image pixel. | See Table 3 |

**Table 6.** Notices (e.g., disclaimers) accompanying data publications in the *urbisphere* project. Data published in near-time have additional text (bold). Author list is updated at publication with an open licence.

| Notice Type | Production | Publication |
|---|---|---|
| Author | Principal Investigators (PIs) of the project | List of authors in compliance with the (national, institutional) academic code of conduct. |
| Copyright | *"Some rights reserved."* | |
| License | | *"This work is licensed under a <a rel="license" href="http://creativecommons.org/licenses/by/4.0/"> Creative Commons Attribution 4.0 International License</a>."* |
| Creator | *"This work is owned by the PIs of the <a rel="author" href="http://urbipshere.eu">urbisphere project</a>."* | |
| Material | *"The notices cover data in databases, APIs, text and images contained in the work."* | |
| Attribution | *"The [creation and] curation of this work has been funded by the European Research Council (ERC) under the European Union's Horizon 2020 research and innovation programme (grant agreement No 855005)."* | |
| Disclaimer[a] | *"The use of the work is at the user's own risk. The authors, the involved institutions, and/or the European Research Council accept no liability for material or non-material damage arising from the use or non-use or from the use of incorrect or incomplete information in this work. **There is no legal claim to permanent availability of this work.** The authors, the involved institutions, and/or the European Research Council do not guarantee the completeness **and timeliness** of the information provided. The authors, the involved institutions, and/or the European Research Council are not responsible for any use that may be made of the information in this work. The legal provisions remain unaffected."* | |

a) Additional wording is used for near real-time publication (text in bold).

**Module A**
**Observing Urban Form and Function**

❶ Spaceborne sensing
❷ Hyperspectral Image Recorder (HIR)
❸ Spectroradiometer System (SRS)
❹ Phenocam (PHE)
❺ Socioeconomic data and surveys

**Module B**
**Observing Urban Emissions**

❶ Eddy Covariance System (ECS)
❷ Large Aperture Scintillometer (LAS)
❸ Automatic Lidar Ceilometer (ALC)
❹ Sun Photometer System (SPS)
❺ Gas Analyzer System (GAS)
❻ Doppler Wind Lidar (DWL)

**Module C**
**Observing Urban Exposure**

❶ Automatic Weather Stations (AWS)
❷ Indoor Biometeorology System (IBS)
❸ Thermal Infrared systems (TIR, IRT)
❹ Radiometer system (RAD)
❺ Mobile Radiosounding System (RSS)

**Module D**
**Data management**

Near-time transmission and monitoring
Data storage and retention
Documentation and metadata
Data processing and production
Data publication and governance

**Figure 1.** Conceptual diagram of the modular observation system operated in the *urbisphere* project. Modules A to C collect observational data in different cities, Module D integrates them in the unified data management approach.

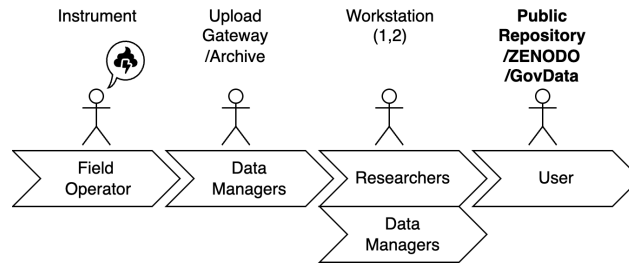



**Figure 2.** Operational connections are entwined between the physical and logical networks and the organisations.

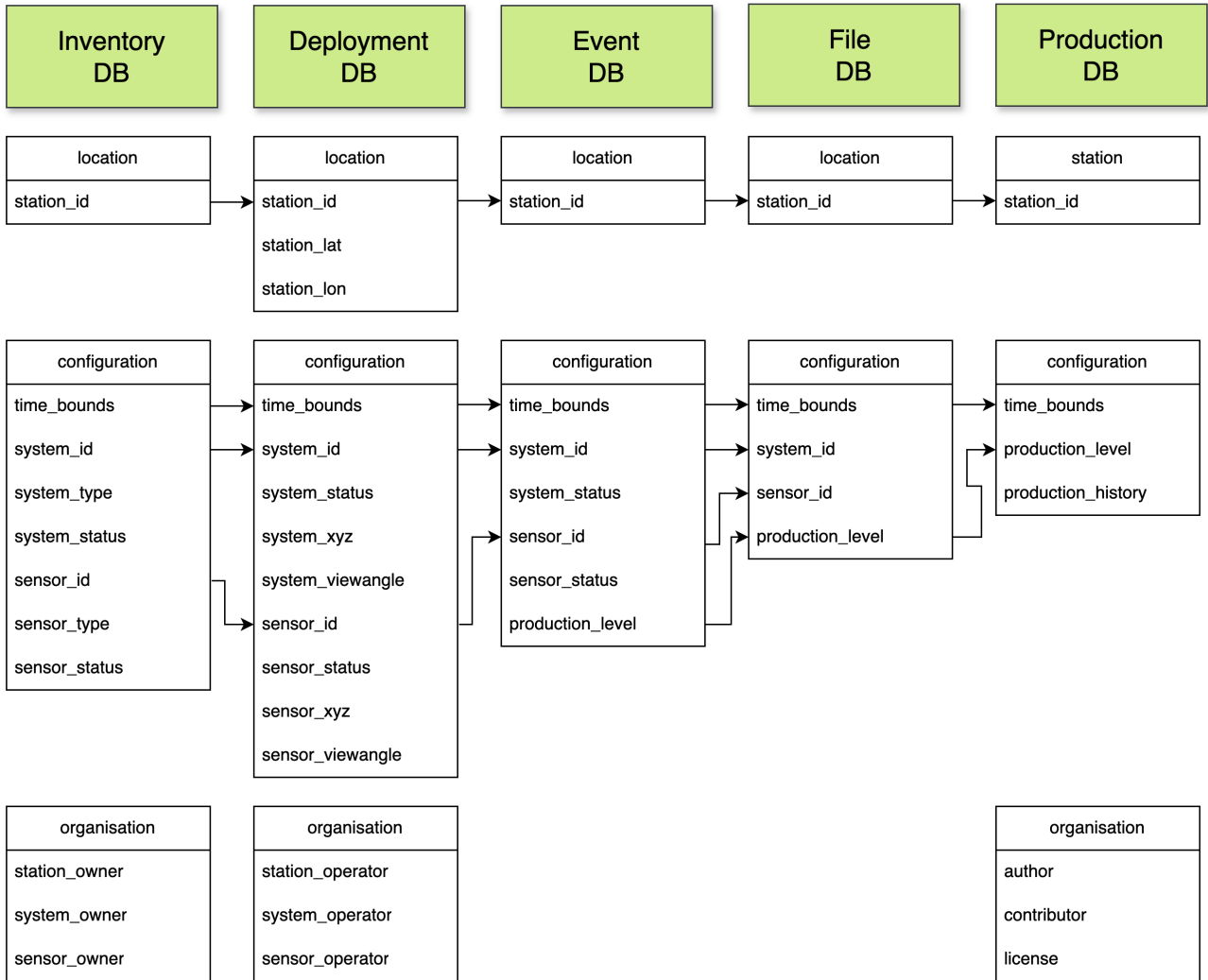



**Figure 3.** Conceptual overview of databases (DBs) that form the metadata, and the primary attributes that connect the DBs.

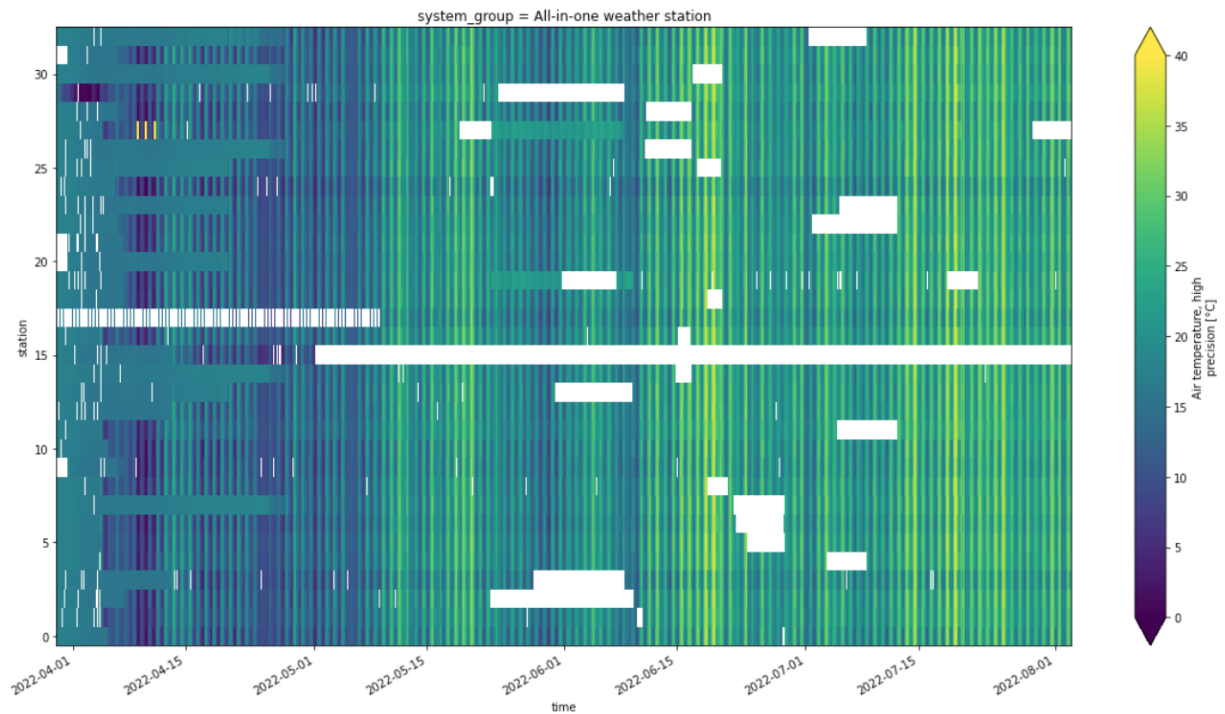
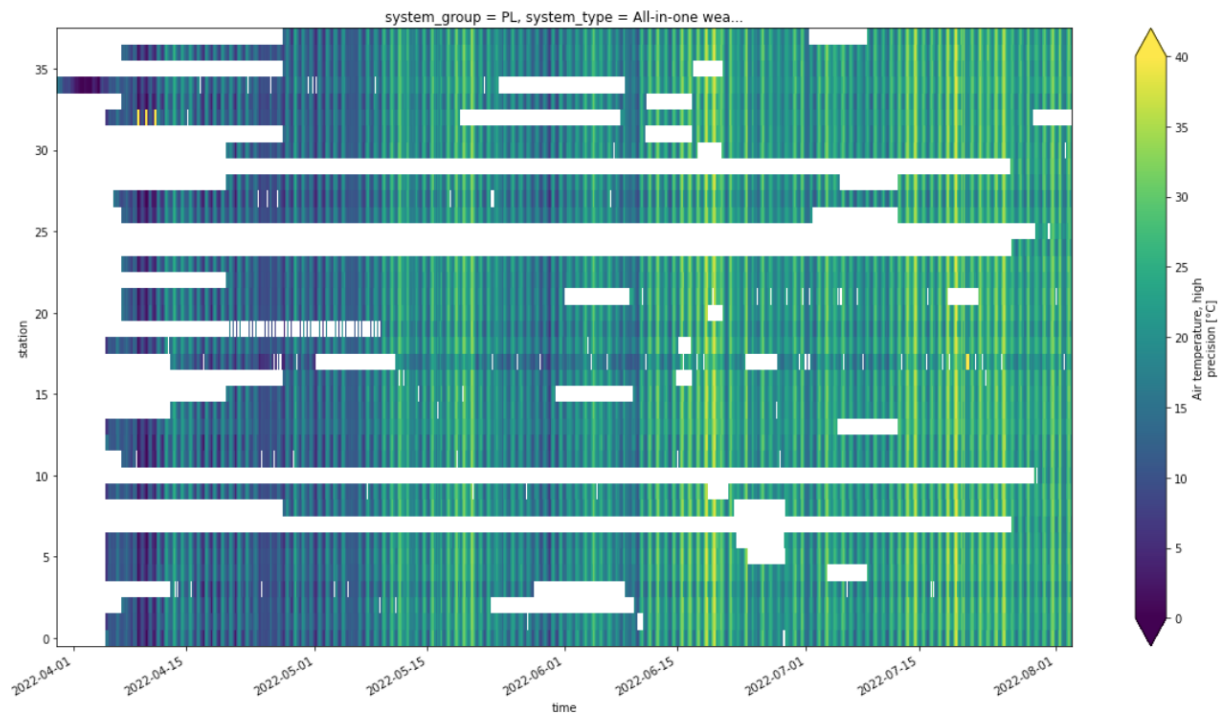



**Figure 4.** Example of data (air temperature) through time per station deployed (Freiburg, Germany): (upper) pre- and (lower) post-metadata application for masking invalid data. In this case, the instruments (Autonomous Automatic Weather Stations) report data if powered, so metadata are needed to define operational deployment periods.

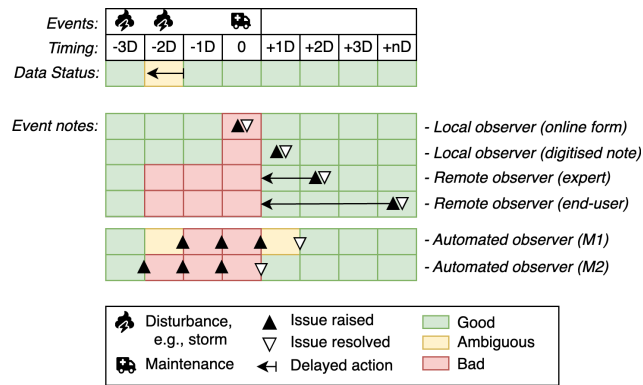



**Figure 5.** Conceptual timeline (days, D) before and after an event is raised and resolved, with different examples of when and who are involved, including two automated methods (M1, M2).

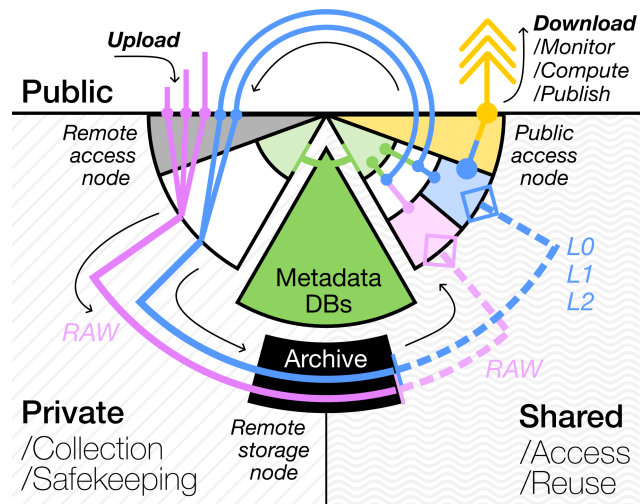



**Figure 6.** Access to data is needed from both public and private domains, using private data infrastructure. Archived data and metadata are read-only accessible (dashed lines, light colors) for shared production (L0, L1, L2), which is redirected to the archive and interfaces for public access and other uses. DB: Database

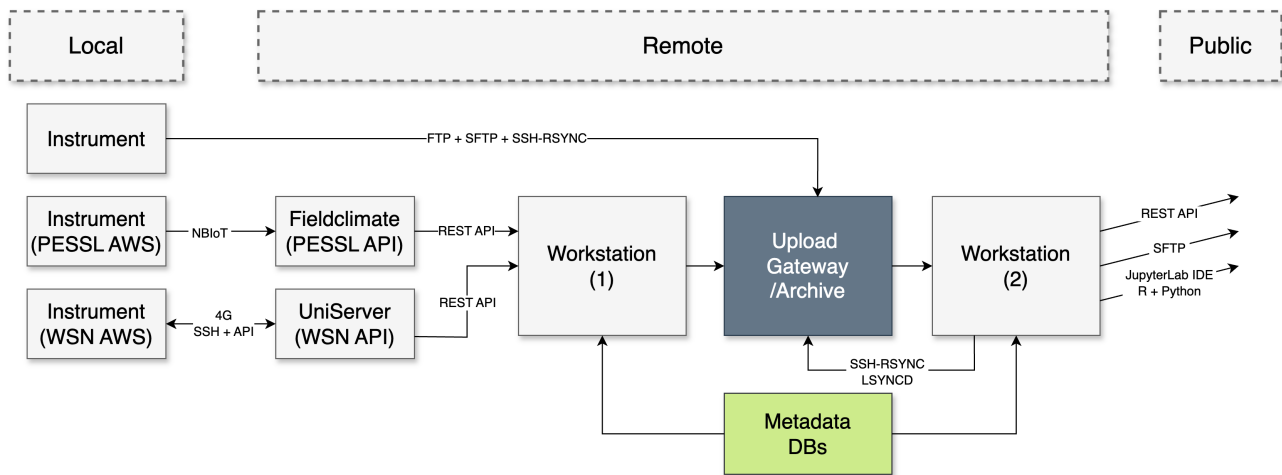



**Figure 7.** Example of a data-stream from multiple networks and various databases (DBs), with the applications used in the production steps and the data store formats (bottom row) using scheduled scripts. The typical data stream is from local instruments to a remote server that provides public access.

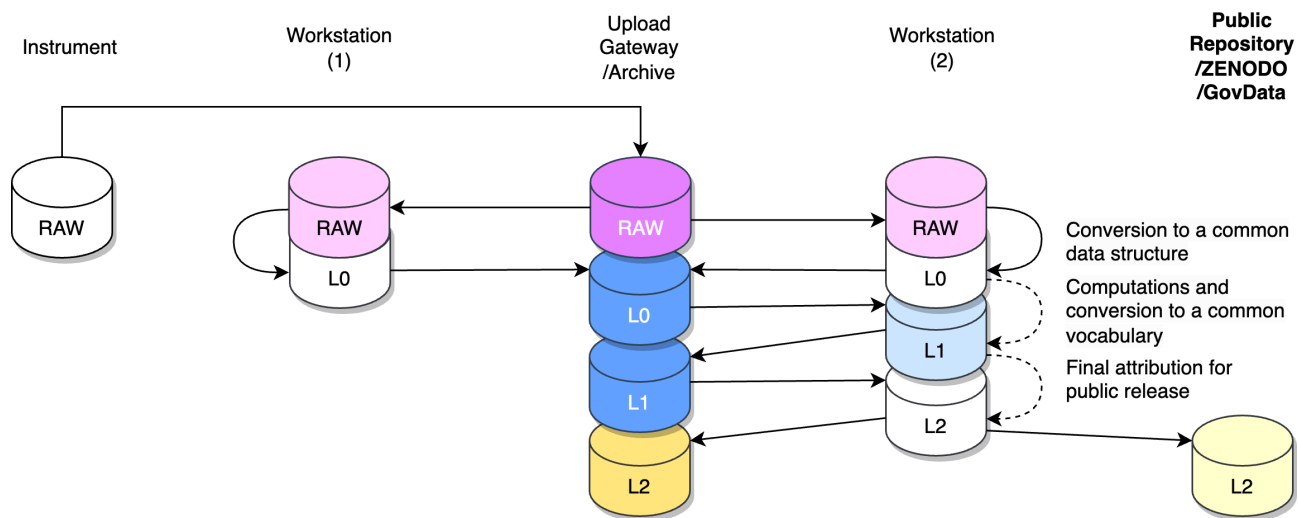



**Figure 8.** Pathways of data (from RAW to intermediate (L0, L1) and publication (L2)) with archiving at multiple stages. Data are shared (dark) and replicated (light).

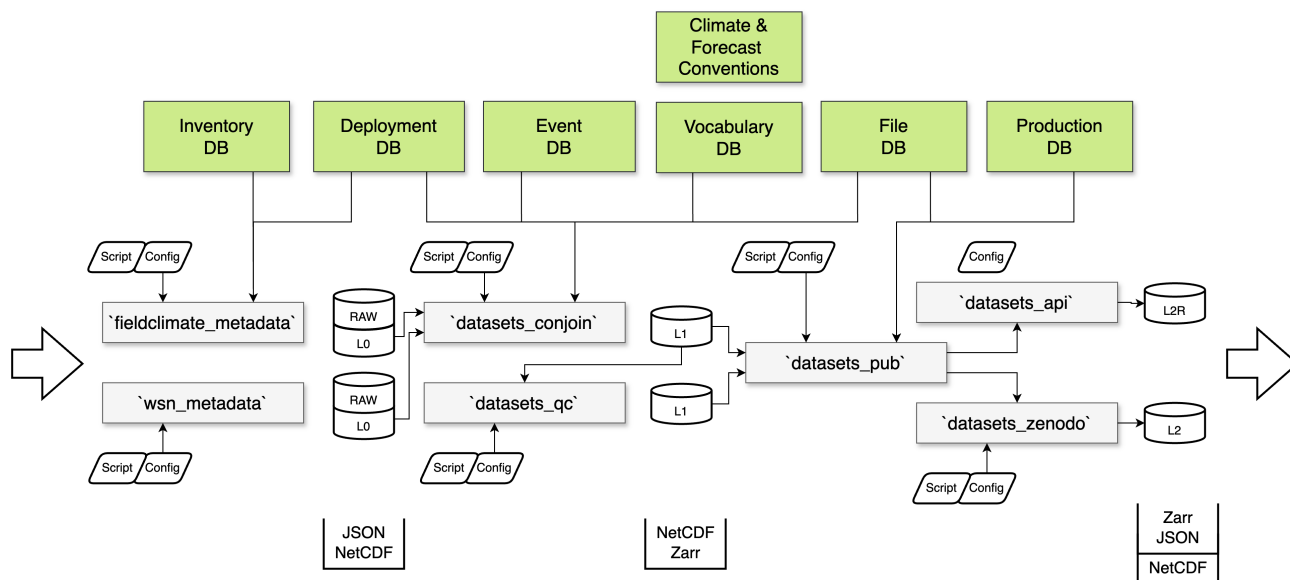



**Figure 9.** An example of a production line, the various databases (DBs) and applications used in the production steps and the (bottom) data formats for data products for multiple uses. Scheduled scripts generate configurations that actuate the production line code during automation.

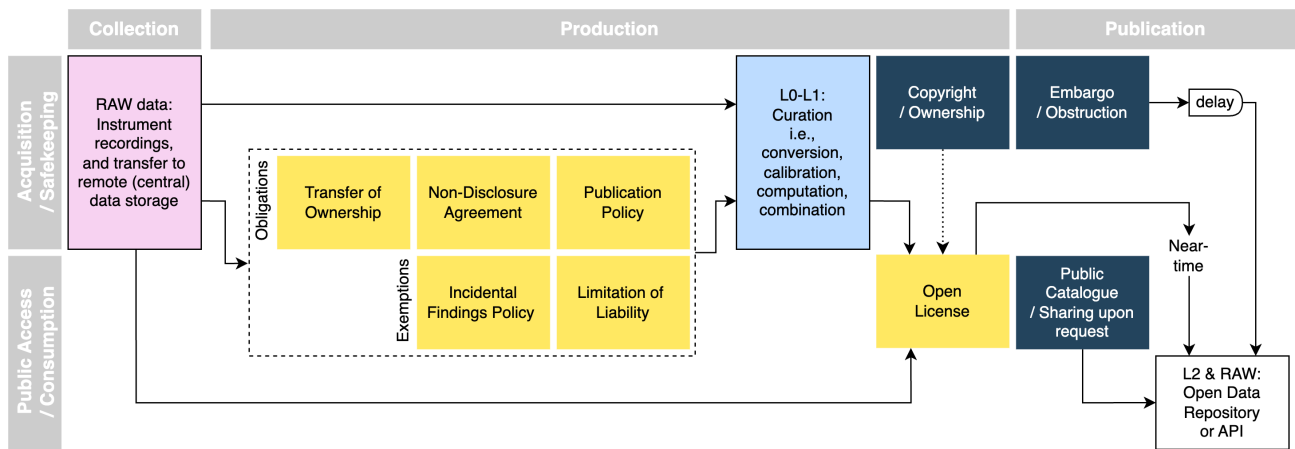



**Figure 10.**

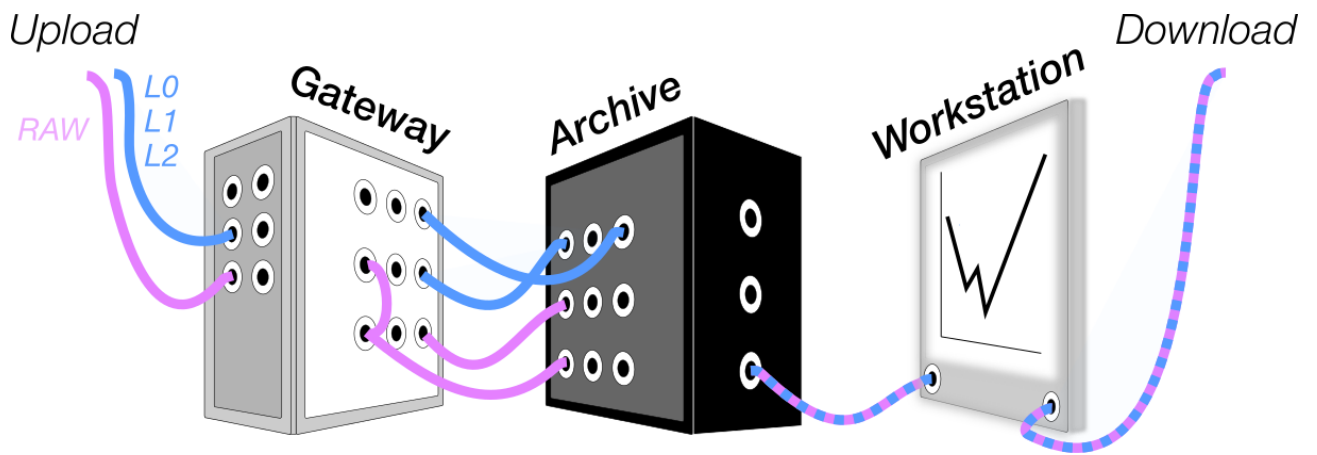



**Figure 11.**

## Appendix A:  Coordinate Systems

In an urban deployment ensuring a "station" is representative of the scale of interest is challenging, as is finding sites to deploy sensors. Often the place a sensor will be mounted will be in a complex location, resulting in a need to a hierarchy of spatial coordinates (Figure A3). For example, providing coordinates for a sensor mounted on a boom that extends off the edge of a roof is challenging, yet required for accurate documentation (Figure A). Similarly, further complications arise with sensors within buildings (Figure A2). Fortunately, high-resolution geographic information systems are extremely common in cities, helping this process (e.g.,  Fenner et al., 2024b; Hertwig et al., in preparation). Here, we use the follow coordinate systems:

- The *Coordinate Reference System* (CRS) is a commonly-used global system, i.e., WGS84 or EPSG:4326. In some cases the UTM or a European reference system (i.e., ETRS89) can be useful alternatives, but their use in reporting must be explicitly specified in metadata.

- The *Vertical Coordinate Reference System* (VRS) by default uses a global or regional system (e.g., European reference EVRS by EUREF; specifically the European Vertical Reference Frame, EVRF2007/EVRF2019, as it is integrated in the Global Navigation Satellite Systems, GNSS, and tied to the level of the Normaal Amsterdams Peil; Bundesamt für Kartographie und Geodäsie, 2023), and must be specified explicitly with a datum and coordinate system otherwise.

- In some cases, National Reference Systems may be used, when *urbisphere* observations need to be combined with local GIS data (e.g., spatial datasets provided by local authorities). In these cases, the respective ellipsoid and datum should also be specified.

- *Urban heights*: in urban deployments, all instrument configurations are linked to an "active surface" for which the height can be ambiguously interpreted as height above the ground (i.e., ground surface, topographic elevation) and height above a structure (e.g., a floor in a building, a roof terrace, a pavement level). Therefore, estimates of the altitude of the observation volume, as well as the altitude/height and properties of the (nearest) urban feature and the surrounding topographic elevation are documented in the metadata (Figure A1b).

- *Local coordinate systems*: to help with the documentation of locations in the physical network, a local reference system was used. A fixed point on the active surface is defined as a station, from which offsets are measured in the field, such as the distance to the platform and any offsets from the platform to the the observed volume (Figure A1a). Any offset in the alignment with zenith and north are recorded as tilt and bearing (elevation and azimuth in CF standards; which typically are also recorded, e.g., by remote sensing systems and mobile platforms (compare Figure A3d and Figure A3e, respectively)).

The information is stored in coordinates that are consistent with conventions and the hierarchical (physical) network (Table A1; see also Table 1). It is helpful to assume defaults, as particularly the vertical coordinates (altitude, topographic elevation of the ground level) take care to be determined and may be revised (Table A2).

Table A1: Coordinate attributes and the relationship between coordinate reference systems (i.e., station, using global CRS and VRS references; system, sensor, channel using local references) and metadata (i.e., conventions, standards, definitions, units).

| Coordinate Name | Standard Name | Optional suffix | Convention | Reference | Units | Comment |
|---|---|---|---|---|---|---|
| station_lat | lat | bounds | CF | CRS | degree | Default CRS "epsg:4326" |
| station_lon | lon | bounds | CF | CRS | degree | Default CRS "epsg:4326" |
| station_height | height | bounds | CF | | m | Vertical distance above the surface. |
| station_altitude | altitude | bounds | CF | VRS | m | Vertical distance above mean sea level. |
| station_ground_level_altitude | ground_level_altitude | bounds | CF | VRS | m | Vertical distance above the named surface "sea_level"; Observed or derived from a Digital Surface Model; a.k.a. surface elevation. |
| station_surface_height _above_ground_level | surface_height _above_ground_level | bounds | | | m | Vertical distance of a surface above the ground level. |
| station_surface_name | | | | | m | Surface name, e.g., roof-top, ground |
| station_surface_type | | lcz; ura; clc; osm | *cf* classification | | | Landcover classification. Optional as Local Climate Zone (lcl), Urban Atlas (ura), CORINE Landcover (clc) or OpenStreetMap object identifier (osm). |
| system_azimuth_angle | platform_azimuth_angle | bounds | CF | station | degree | |
| system_zenith_angle | platform_zenith_angle | bounds | CF | station | degree | |
| system_x | | bounds | | station | m | Cartesian distance to Reference |
| system_y | | bounds | | station | m | Cartesian distance to Reference |
| system_z | | bounds | | station | m | Cartesian distance to Reference |
| sensor_azimuth_angle | sensor_azimuth_angle | bounds | CF | system | degree | |
| sensor_zenith_angle | sensor_zenith_angle | bounds | CF | system | degree | |
| sensor_view_angle | sensor_view_angle | bounds | CF | system | degree | |
| sensor_x | | bounds | | system | m | Cartesian distance to Reference |
| sensor_y | | bounds | | system | m | Cartesian distance to Reference |
| sensor_z | | bounds | | system | m | Cartesian distance to Reference |

| cell_x | bounds | sensor; CRS | m; degree | Cartesian distance to Reference; alternatively as longitude time series |
| cell_y | bounds | sensor; CRS | m; degree | Cartesian distance to Reference; alternatively as latitude time series |
| cell_z | bounds | sensor; VRS | m | Cartesian distance to Reference; alternatively as altitude time series |

**Table A2.** Coordinate attributes and their meaning for metadata that are required, partially required or required but set with a default value.

| Coordinate Name | Data Dimension | Requirement | Default |
|---|---|---|---|
| station_lat | station | ☑ | |
| station_lon | station | ☑ | |
| station_height | station | ☑ [b] | 0 |
| station_altitude | station | ☑ [a,b] | |
| station_ground_level_altitude | station | ☑ [b] | |
| station_surface_height_above_ground_level | station | ☑ [b] | 0 |
| station_surface_name | station | ☐ | ground |
| station_surface_type | station | ☐ | |
| system_azimuth_angle | system | ☑ [b] | 0 |
| system_zenith_angle | system | ☑ [b] | 0 |
| system_x | system | ☑ [b] | 0 |
| system_y | system | ☑ [b] | 0 |
| system_z | system | ☑ [b] | 0 |
| sensor_azimuth_angle | sensor | ☑ [b] | 0 |
| sensor_zenith_angle | sensor | ☑ [b] | 0 |
| sensor_view_angle | sensor | ☑ [b] | 0 |
| sensor_x | sensor | ☑ [b] | 0 |
| sensor_y | sensor | ☑ [b] | 0 |
| sensor_z | sensor | ☑ [b] | 0 |
| cell_x | cell | ☑ [b] | 0 |
| cell_y | cell | ☑ [b] | 0 |
| cell_z | cell | ☑ [b] | 0 |

[a]) Required, but can be derived.    [b]) Required, but a default value can be assumed if omitted.

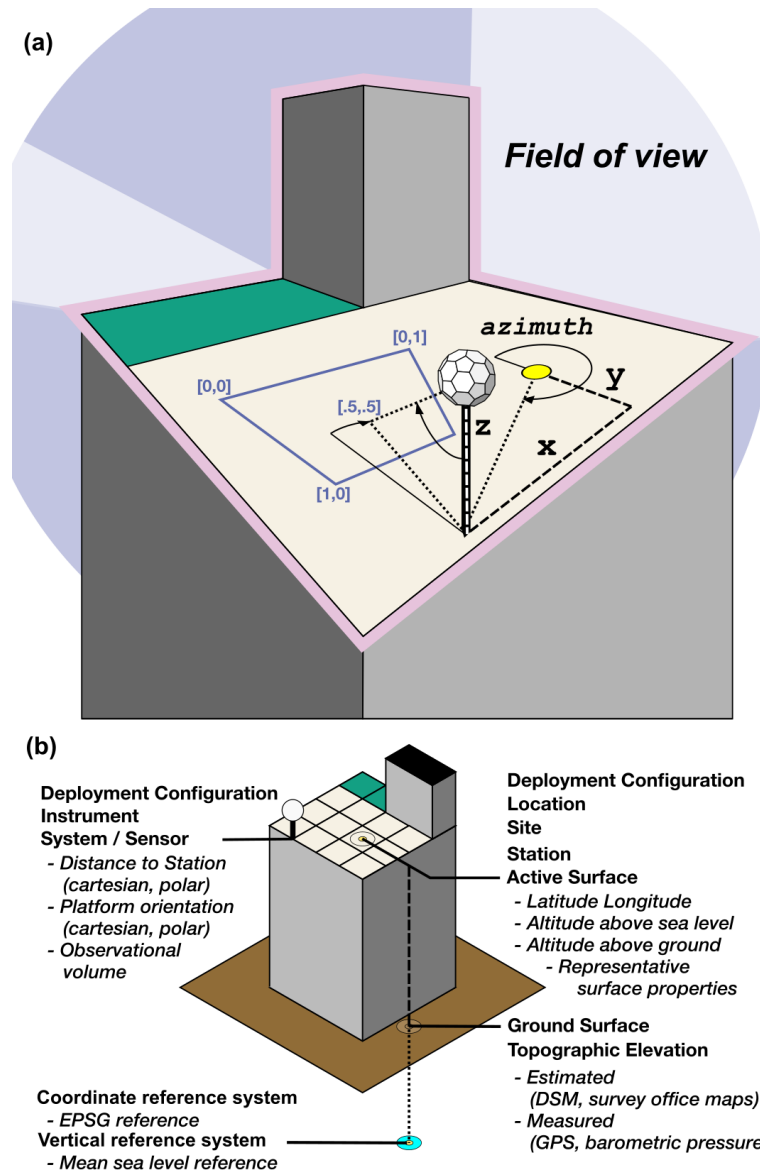



**Figure A1.** Deployment on a building roof with the relations between (a) a local station, platform, instrument, recorded image and related coordinate systems in polar and Cartesian coordinates, and (b) local and global coordinate reference systems as well as features in ordinance inventory and Earth Observation.

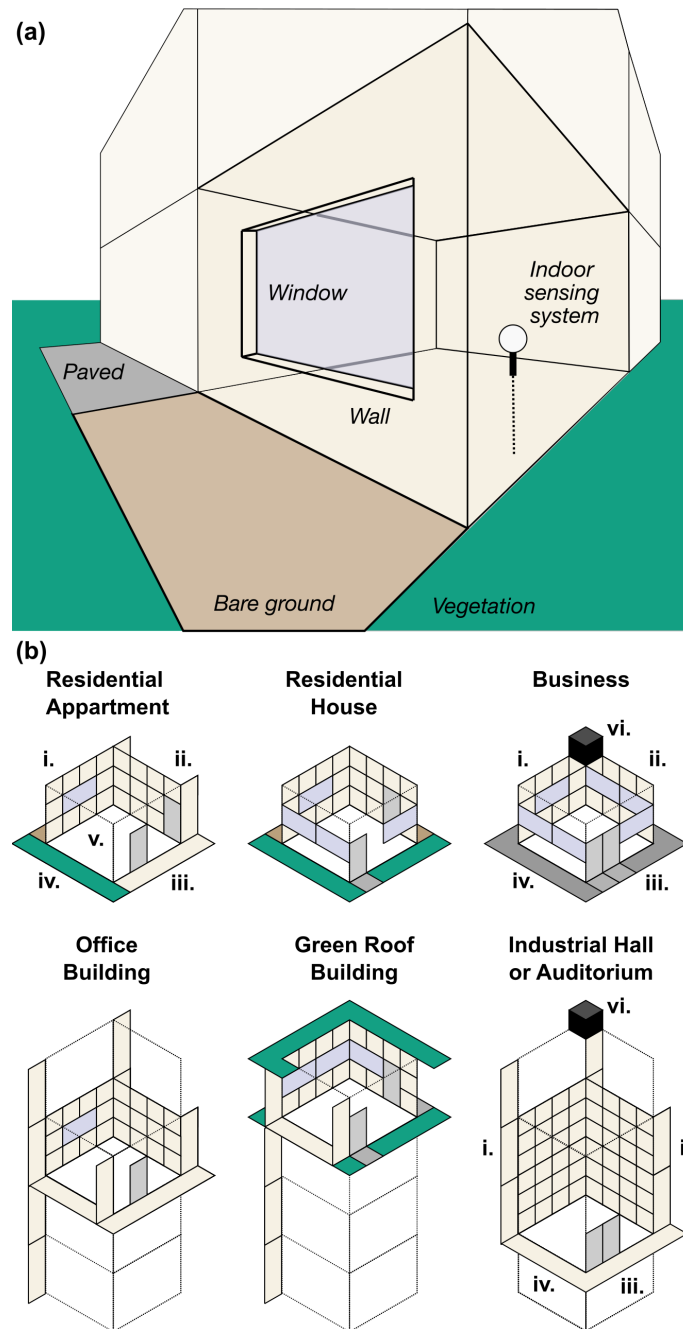



**Figure A2.** Indoor measurements of ambient temperature require uniquely different metadata, compared to classical outdoor measurements, including additional coordinates for the orientation and features of the building, the room, the walls and the adjacent space, as well as of objects that generate, transmit, transport or intercept radiative heat.

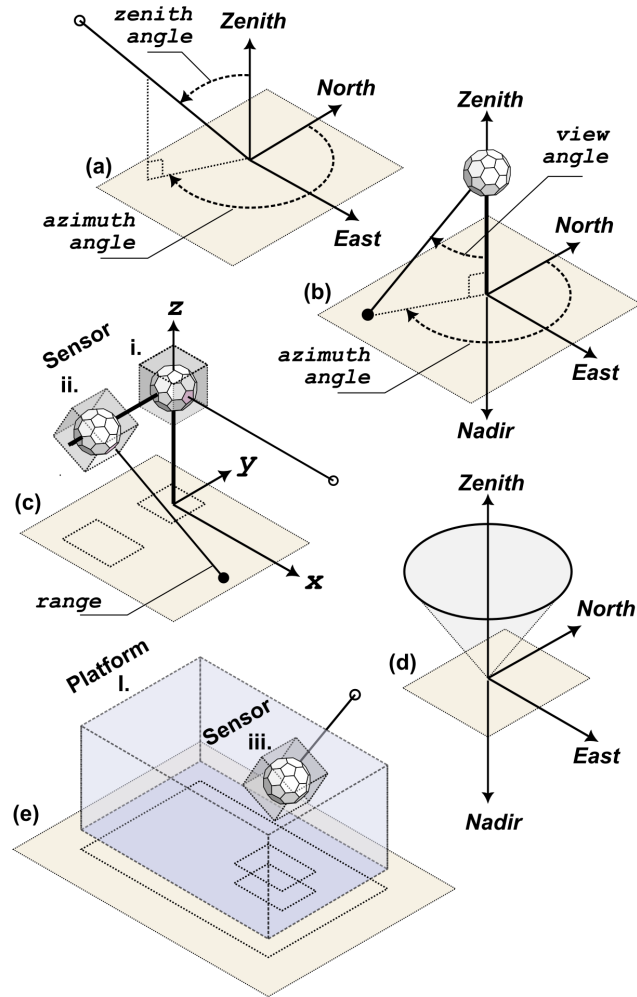



**Figure A3.** Metadata definitions for the relationships between platforms and instruments, and their coordinate systems.

## A1   Time

Data management operates in close to real-time or in short-interval batch acquisition (Figure A4). All system clocks use UTC time (ideally), but if local time (without daylight saving) is locally essential the metadata includes this information.

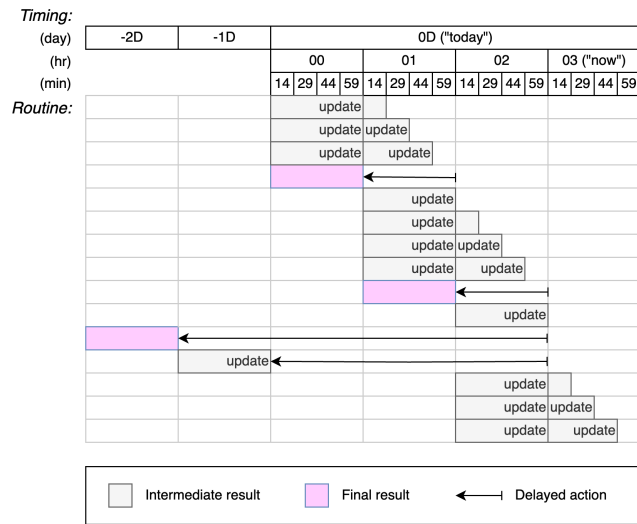



**Figure A4.** Production schedule includes batch routines, sub-hourly and daily overlapping routines to recover data if short-term interruptions in networks occur (e.g., within last 48 h).

## Appendix B: Curation

### B1    File names

To define locations, deployment configurations and production stages, short-hand identifiers are used to structure both the metadata database relational features, and the directories and files for data (Table B1).

– *Project identifier*: the organisational framework in which a data record is collected or computed. Much of the procedures and agreements depend on a formal separation of organisational units within the organisational network (see, e.g., Table 1);

– *Production level* (RAW, L0, L1, L2, see section 3.5): the original source data need to be archived in a different location than subsequent production stages;

– *Instrument identifier vs Location identifier*: the (re-)organisation of data files by location can vastly improve the overview of the network, but a deployed configuration is typically unaware of its location and can only reliably provide instrument serial numbers as identification. The location short code is a `CCNNNN` format, which merges a two-character `CC` city code (optional) and a four-character `NNNN` station identifier. Station names are generally based on geographic neighborhood and not street names or property names, to avoid referring to a company/trademark or disclose exact locations, where privacy is affected. The station codes do not necessarily need to be unique, for example, stations FRCHEM and PACHEM operated simultaneously and are located in Freiburg (FR) and Paris (PA), respectively.

– *Instrument classification*: most instruments can be configured to use a model identifier in their output file path and file header. In some cases, the output file format did not differ between instrument models (e.g., TOA5 data logger files) and the output for a instrument group (e.g., data loggers) could be combined during subsequent production steps.

– *Time*: all file names include a timestamp or time bounds (in UTC), and in case large numbers of daily files are expected, additional sub-folders with year or date information facilitate manual file browsing.

The motivation for the use of definition rules for acronyms is not to be restrictive, but to reserve acronyms for 2- 3- 4- and 6-character uppercase acronyms to, city, system group (Table 3), station identifier and combined city-station identifier reference, respectively. We found the consistent use of those formats in metadata, communication and publication helpful.

**Table B1.** Naming convention for different types by production level with patterns and attributes.

| Production level | Type | Naming convention pattern (example) | Attribute |
|---|---|---|---|
| RAW | folder | `/srv/meteo/archive/./` | base path |
| | folder | `urbisphere/` | project name |
| | folder | `data/RAW/` | production level |
| | folder | `by-source/smurobs/` | network identifier |
| | folder | `by-serialnr/France/Paris/CL61/U4910813/` | campaign and instrument identifiers |
| | file | `U4910813_20231126_090916.nc` | instrument recorded file name |
| L0 | folder | `/srv/meteo/archive/./` | base path |
| | folder | `urbisphere/` | project name |
| | folder | `data/L0/` | production level |
| | folder | `by-source/smurobs/` | network identifier |
| | folder | `by-location/France/Paris/PAAUNA/ALC/U4910813/` | campaign and instrument identifiers |
| | file | `raw2l1` | production name |
| | file (cont'd) | `_set(*,**,***)` | production identifier(s) |
| | * | `fr.paris.PAAUNA` | location identifier(s) |
| | ** | `ALC_U4910813` | system group and serial no. |
| | *** | `20231126T000000_20231127T000000` | time bounds (ISO8601) |
| | file (cont'd) | `_version(****)` | version identifier(s) |
| | **** | `v1.0.1` | semantic version |
| | file (cont'd) | `.nc` | file extension(s) |

## B2   Quality Control

540   An automated assessment of typical meteorological variables was implemented using the Verein Deutscher Ingenieure (VDI) guidelines for meteorological observations (VDI, 2013). The guidelines provide threshold values for the range, rate of change (absolute deviation) and duration of steady-state (stationarity duration) for a number of variables. The threshold values are specified for different averaging times. Testing the data with these threshold values determines for each data point if the quality is good, ambiguous or poor. The procedure for change rate and steady-state calculations require data before and after a data

545   point to be available and the computations involve repeated averaging at different time intervals, which incurs computational costs and complexity. Additional care is needed to assure the units between the data and threshold values match.

    The output of the quality control is a new dataset with the same time dimension as the original data. The result can be summarized into an ensemble quality control indicator for specific variables, which can be useful for evaluation and masking data points before further use. (Figure B1). By combining all quality control output for a network of sensors and multiple

550   variables, outliers and trends can be assessed (Figure B2). The example describes a passing storm on the evening of 11 Jul 2023, registering (1) a rapid humidity change at most locations, (2) high variability in wind speed and/or wind direction at some locations depending on the orientation of the street canyon to the wind (3) a possible malfunction in the precipitation sensor at FRLAND (4) a possible time offset of the system at FRCHEM, and (5) an unspecified technical issue that affects the data delivery at FRTECH. The information should be considered indicative, as it can reveal both natural changes and technical

555   problems, but can be further supported by spatial statistics (not implemented here) and field reports.

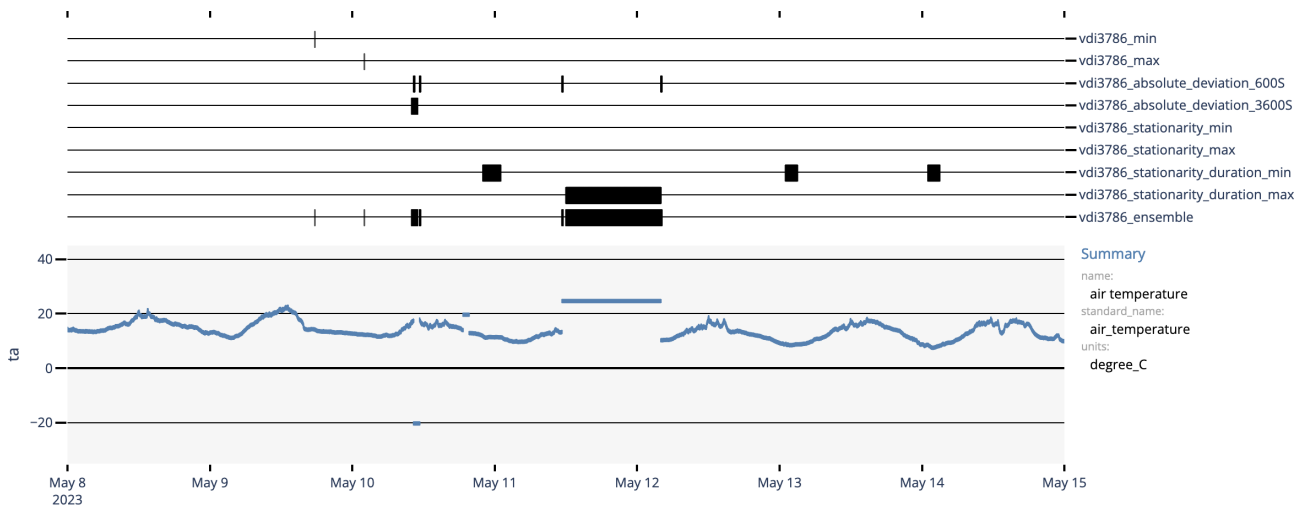



**Figure B1.** Example of automatic quality control for AWS air temperature (ta, bottom panel) data to illustrate VDI 3786 (VDI, 2013) quality control indicators (vertical lines = bad quality, top panel).

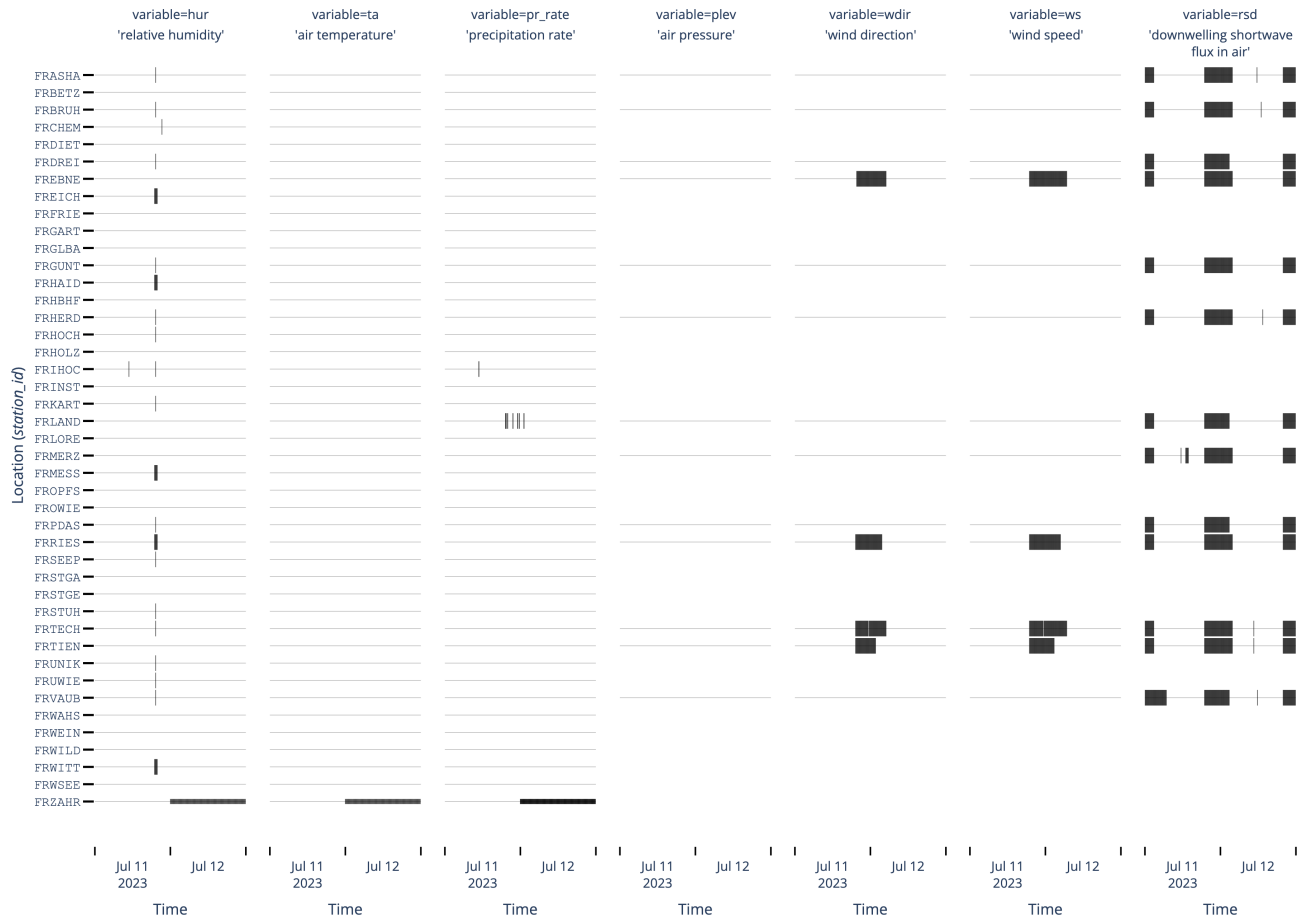



**Figure B2.** VDI 3786 (VDI, 2013) quality control indicators applied to the Freiburg AWS network (rows) during a storm (11 to 12 Jul 2023) for all variables (precipitation *pr_rate*; air temperature *ta*; relative humidity *hur*; wind speed *ws*; wind direction *wd*; station pressure *plev*; incoming short wave (or global) radiation *rds*) with quality flags shown: long = "bad", short = missing.

## Appendix C: Services

### C1 Computing Environment

A system-wide copy of the Anaconda Python distribution (ana, 2023) is installed on Workstations in order to provide users with preconfigured python and R environments. These environments are updated occasionally to introduce new features. The

560 environments contain packages for scientific data analytics (e.g., functions for calculation, access to common data file formats) and access to the metadata DBs. Taking a pragmatic approach, we rely on Python libraries supported by the Numerical Foundation for Open Code and Useable Science (NumFOCUS). Libraries (*xarray*; *pandas*; *numpy*; *scipy* and *dask*), plus useful extensions to NetCDF (e.g., data access: *zarr*, time conversion: *cftime*, unit conversion: *cfunits*) allow the produced NetCDF database files to be used in R and Matlab ICEs and by dedicated NetCDF tools (e.g., NCO, CDO, Panoply), and vice-versa.

565 ### C2 Online access

Each workstation functions as a web server, with certificate-based communication (HTTPS) using the host institution IT services and authentication for security. Web hosting has different domains for public and private access. The private domain have basic authentication with credentials entered in a web browser pop-up.

Apps are not private because of sensitive information, but because of performance cost and operational risks linked to

570 public access. Some experimental services have additional authentication (e.g., JupyterLab; Figure C1). Although setting up web services requires system administrator changes to the workstation web proxy, researchers are free to manage their Apps independently.

### C3 Apps

Web app templates, using open source projects (e.g., shiny, panel), are modified to comply with publication guidelines, host

575 institution policies, project policies, European law (e.g., terms of use statement) and other legal terms. The template header and footer information (e.g., location, contact, creation time, terms of use) identify version status and formal reference if used (e.g., during talks). The templates are prepared using the *plotly* library, as it is available for multiple ICEs (e.g., R, python).

Apps assist field operators, data managers and researchers in diagnostics and early exploration:

– *Diagnostics* to help monitor the network data stream (Figure C2): overview of recently added or modified files, automated

580 tasks status reports, interactive figures showing file count for individual systems in past hour and days.

– *Visualisation* of variables gives operational status of dynamic processes (Figure C3): templates combining metadata and data, give automatic, distributed, provisional data for review of quality and availability (Figure C4, Figure C5, Figure C6 and Figure C7b).

– *Outreach* providing community-available near real-time data (Figure C7c; Feigel et al., in review): can also be usable as

585 a diagnostic tool.

## C4 Data API

Methods to expose NetCDF4 data stores through a Representational State Transfer Application Programming Interface (REST API) are provided by libraries (*zarr*, *xarray*, *fastapi*, *fsspec*, *xpublish*; Figure C7b). JSON output format, a widely supported text-based encoding format for data storage, is added to the API as local governments (e.g., City of Freiburg) require it for applications (e.g., urban planning, civil protection, disaster management, climate adaptation). However, as JSON is unsuitable for streaming large data queries (>10 MB), an alternative format is needed (i.e., Zarr). The JSON data output can be converted back to NetCDF (i.e., using *xarray*), ensuring both Zarr and JSON output of the API can be used, interchangeably.

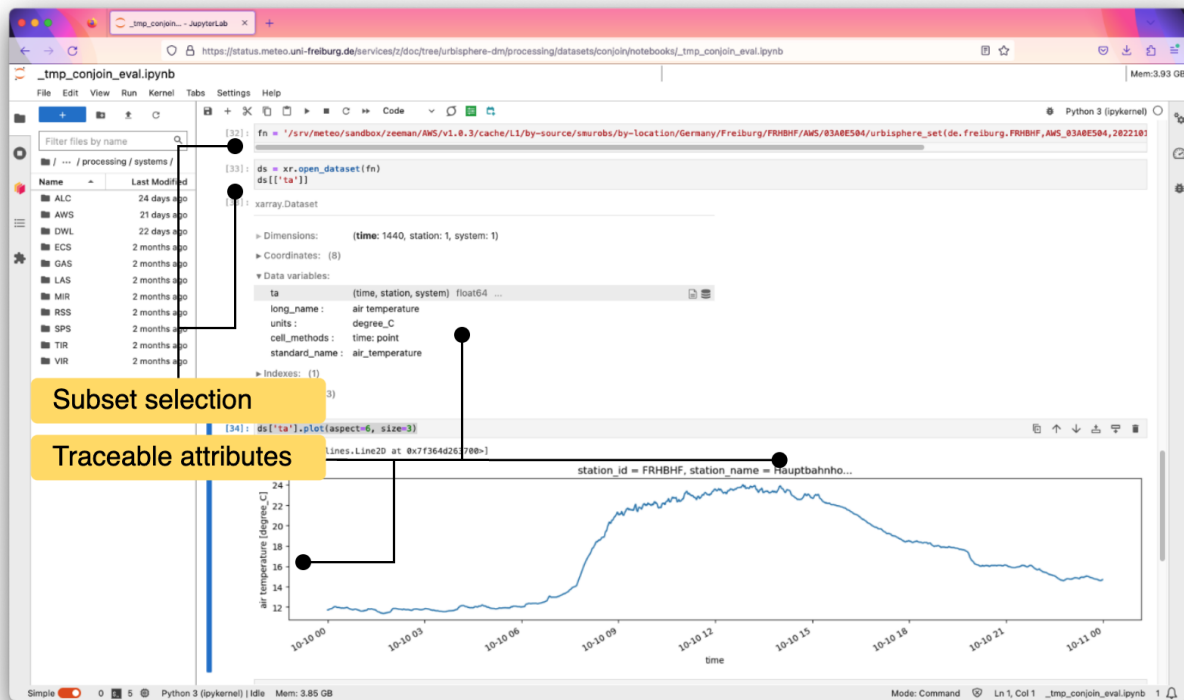



**Figure C1.** An example of web browser data science environment and ICE (JupyterLab) with simple code inspecting data.

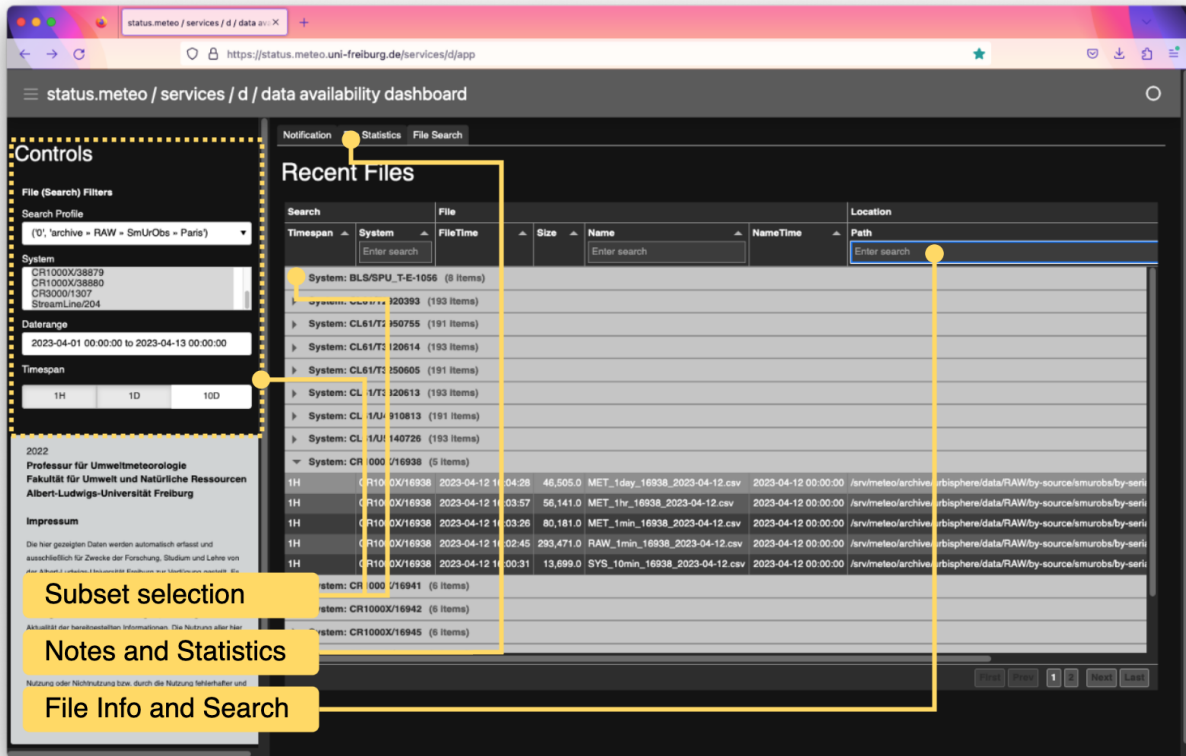



**Figure C2.** As Fig. C3 but, of most recently changed files and folders by campaign (e.g., city).

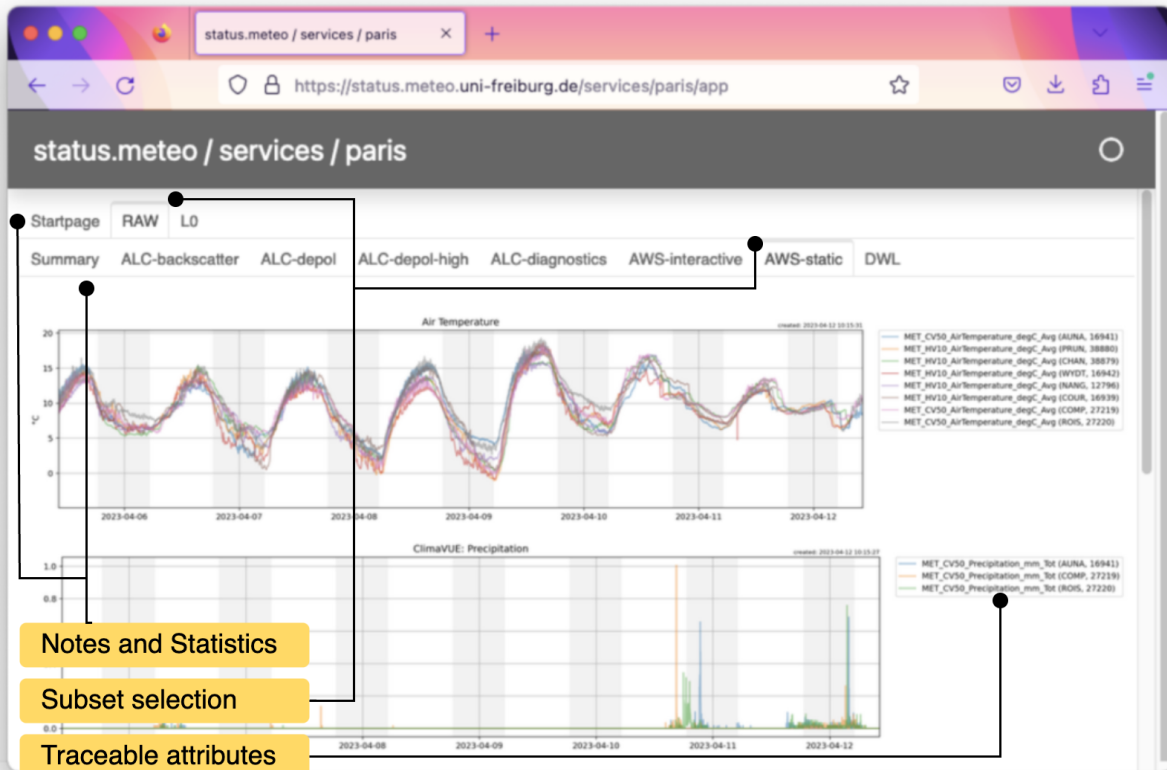



**Figure C3.** Dashboard App used to visualise most recent data for inspection.

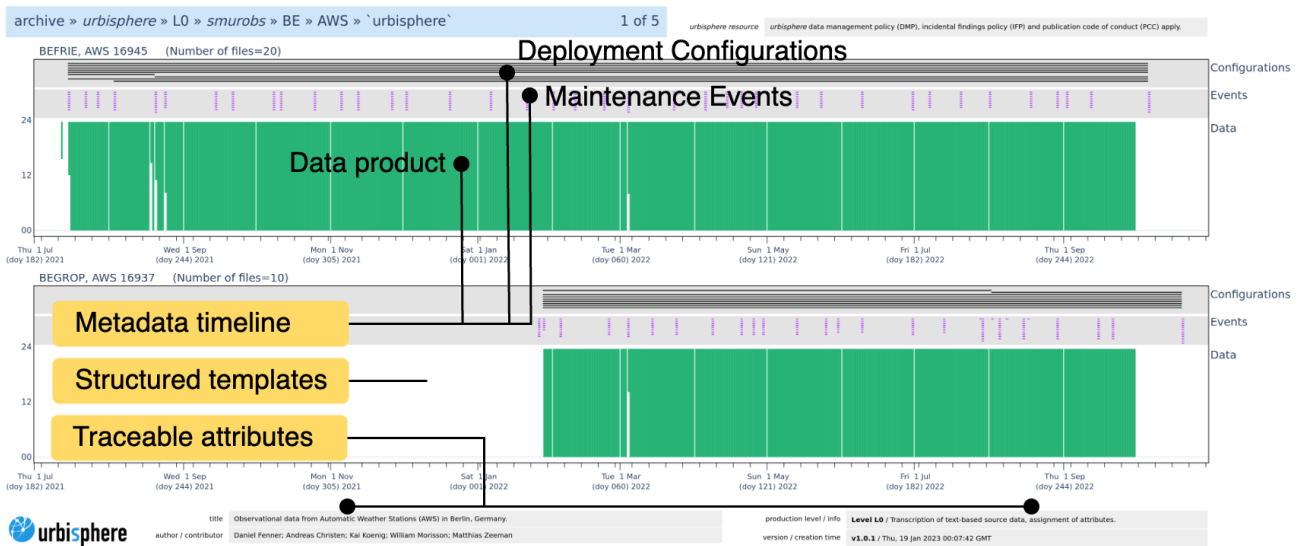



**Figure C4.** Example overview of available data as time against time of day, includes metadata attributes to help identify attribution, location context, production information and a time line of events as known at time of creation.

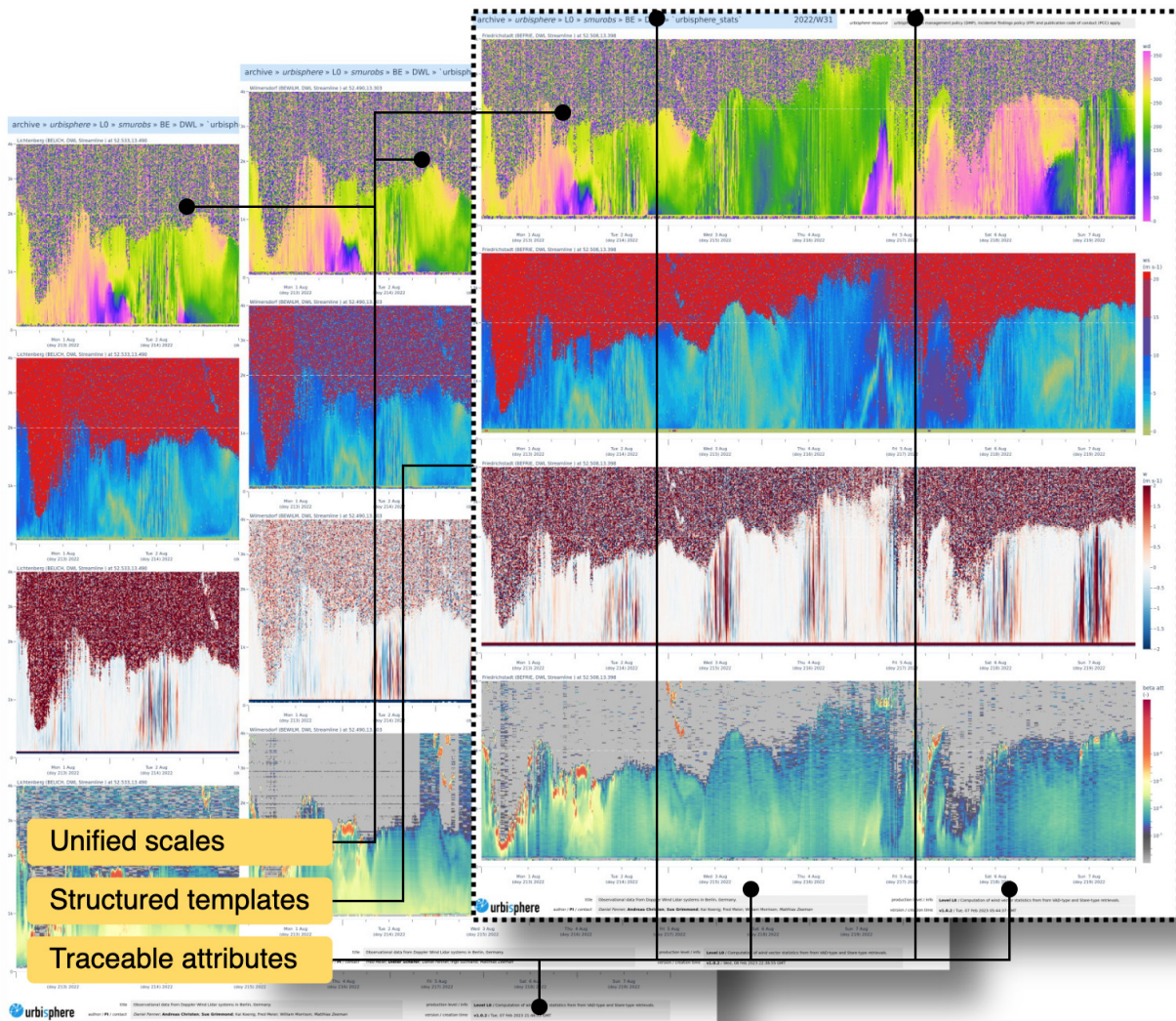



**Figure C5.** Near-time Doppler Wind Lidar (DWL) data used for diagnostics and data exploration.

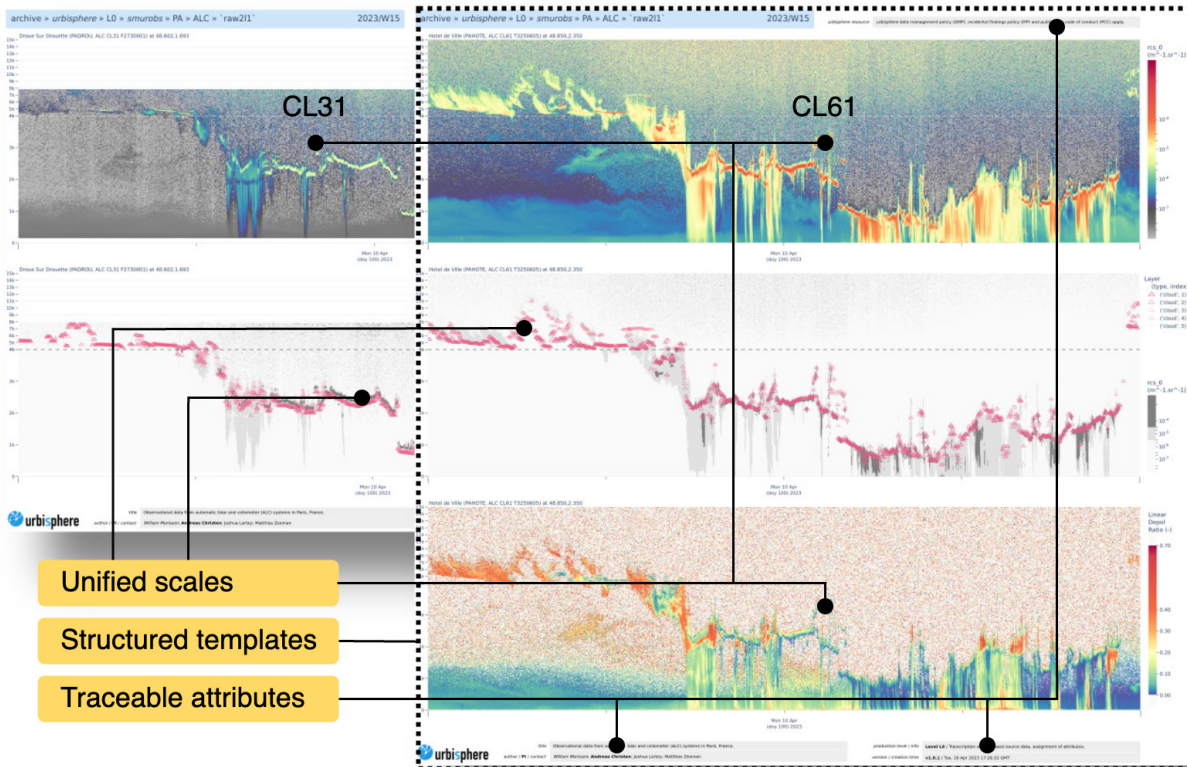



**Figure C6.** As Fig. C5, but for Automatic Lidar and Ceilometer (ALC)

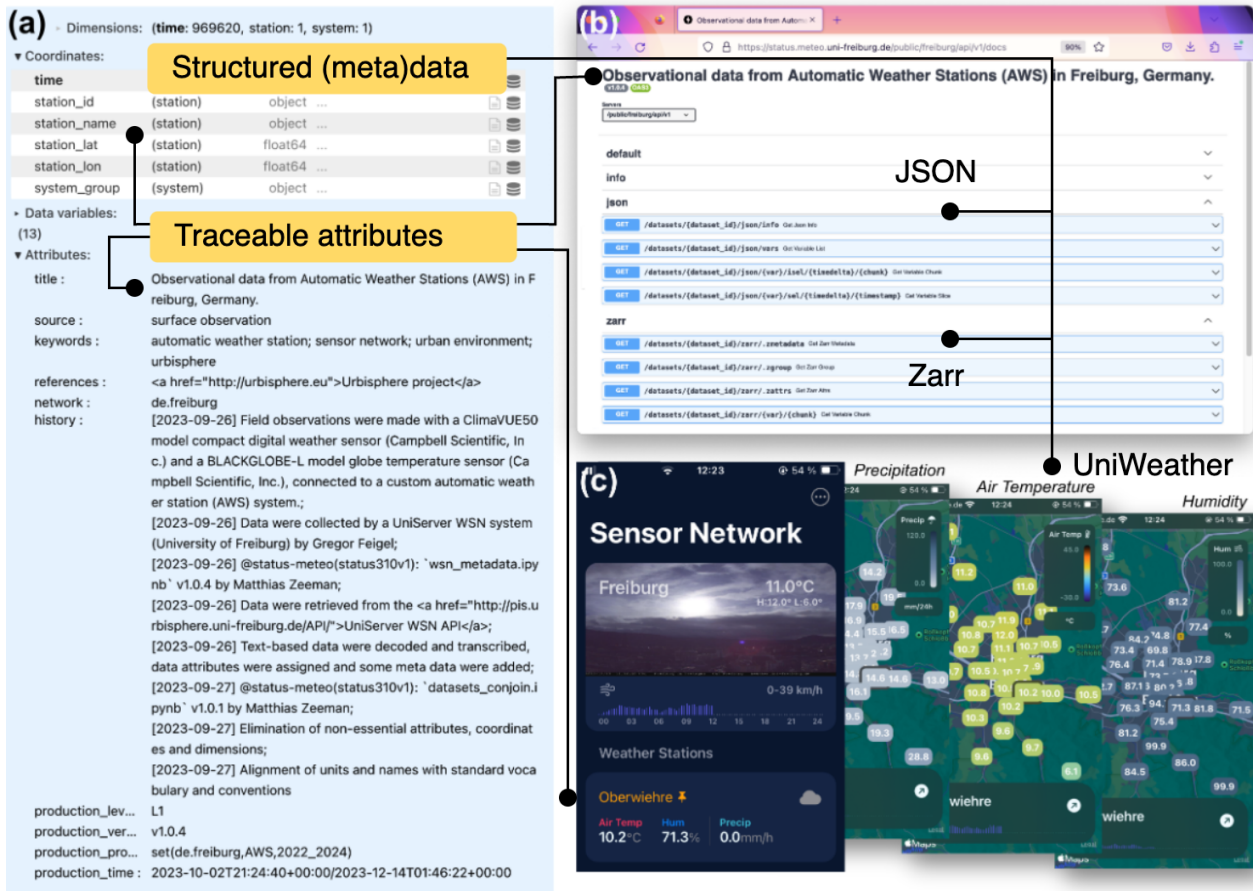



**Figure C7.** An example of (a) an AWS product summary (b) a data API and (c) the uniWeather Phone App (Feigel et al., in review) that use the same (meta-)data dynamically.

*Author contributions.* AC, SG and NC supervised the project; DF, WM, GF and MS performed investigation; MZ performed data management and computations; all authors contributed to the data system; MZ wrote the manuscript draft; AC, SG, NC, DF, WM and GF reviewed and edited the manuscript.

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