Characterizing ground ice content and origin to better understand the seasonal surface dynamics of the Gruben rock glacier and the adjacent Gruben debris-covered glacier (southern Swiss Alps)

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Abstract. Over the recent years, there has been focused international efforts to coordinate the development and compilation of rock glacier inventories. Nevertheless, in some contexts, identifying and characterizing rock glaciers can be challenging as complex conditions and interactions, such as glacier-rock glacier interactions, can yield landforms or landform assemblages that are beyond a straightforward interpretation and classification through ordinary visual means alone. To gain a better understanding of the spatial and temporal complexity of the ongoing processes where glacier-permafrost interactions have occurred, the characterization of the subsurface of the Gruben rock glacier and its adjacent complex contact zone is quantitively assessed using a petrophysical joint inversion (PJI) scheme, based on electrical resistivity (ERT) and refraction seismic (RST) data. Surface dynamics are assessed using both in-situ and close-range remote sensing techniques to monitor daily and seasonal displacements and to monitor landform-wide surface changes at high spatial resolution, respectively. Both the geophysical and geodetic surveys allowed to identify two zones: the rock glacier zone and the complex contact zone where both permafrost and embedded surface ice are present. In the complex contact zone extremely high ice contents (estimated up to 85%) were found. Widespread supersaturated permafrost conditions were found in the rock glacier zone. Surface displacement rates in this zone are typical of permafrost creep behaviour, with a gradual acceleration in late spring and a gradual deceleration in winter. Moreover, the coherent nature of the rock glacier zone surface deformation contrasts with the back-creeping and slightly chaotic surface deformation of the complex contact zone. Favouring a multi-method approach allowed a detailed representation of the spatial distribution of ground ice content and origin, which enabled to discriminate glacial from periglacial processes as their spatio-temporal patterns of surface change and geophysical signatures are (mostly) different.
1 Introduction

The high alpine environment is characterized by glacial and periglacial processes and landforms, which express varying degrees of sensitivity to the current warming trend (Mollaret et al., 2019; Kellerer-Pirklbauer et al., 2024; Huss and Fischer, 2016; Carturan et al., 2020). The dynamic response of these phenomena and landforms to this trend is not uniform in space nor in time as the occurrence of ice in high mountain environments can be found under a wide spectrum of possible conditions, processes, materials, origins, landform settings and assemblages (Monnier et al., 2014; Bosson and Lambiel, 2016; Cusicanqui et al., 2023; Navarro et al., 2023). For instance, surface ice not only encompasses landforms of glacial origins such as glaciers, debris-covered glaciers, or dead-ice masses, but also smaller ice occurrences such as perennial ice patches or glacierets, while various forms of ground ice (also termed subsurface ice) relate to long-term thermal aspects of ice formation and preservation in permafrost conditions. In most contexts, there is a clear differentiation between landforms containing surface ice and those that contain ground ice, as their morphologies and kinematic behaviour are distinctive (Haeberli et al., 2024). However, in environments where glacial and periglacial processes occurred or still occur simultaneously, the typology of the ice content and associated processes of the resulting phenomena and landforms can be delicate to assess as they are the product of complex interconnected glacial and periglacial processes (Vivero et al., 2021).

In the Alps, perennially frozen-debris landforms at many sites have coexisted and episodically or continuously interacted with glaciers (Haeberli, 2005; Maisch et al., 2003; Ribolini et al., 2010; Bosson et al., 2015). The Little Ice Age characterized the apogee of the last interaction phase (ca. 1350–1850 in the Alps; (Ivy-Ochs et al., 2009) during which small polythermal cirque glaciers (Etzelmüller and Hagen, 2005) altered the thermal regime of their forefields and the spatial distribution of pre-existing perennially frozen sediments (Kneisel and Kääb, 2007; Seppi et al., 2019; Kunz and Kneisel, 2020; Wee and Delaloye, 2022).

As geomorphological and glaciological systems, environments in which glacier-permafrost interactions have occurred are the result of a wide and interconnected spectrum of glacial, periglacial, nival, hydrological, gravitational, and mass-wasting processes (Etzelmüller and Hagen, 2005; Ballantyne, 2018). Such interactions give rise to the coexistence of a diverse range of landforms, such as glaciogenic debris, glacier ice masses, including debris-covered ice and buried dead glacier ice, but also thermally controlled (permafrost-related), viscous creeping debris-masses (rock glaciers) disturbed and sometimes partly displaced by the loading of glacial-stress (glaciotectonic). Besides geometrical alteration, these glacitectonized frozen landforms may encompass sporadic embedding and burial of glacier ice (sedimentary ice) into frozen debris.

Post-glacial dynamics of these systems and associated landforms comprise spatio-temporally complex and interlaced glacial, periglacial, paraglacial, hydrological and mass-wasting processes whose full understanding requires high-resolution, quantitative, multi-method and interdisciplinary approaches. Recent studies have manifested a growing interest in investigating these systems to achieve a better understanding of processes resulting from glacier-permafrost interactions (Monnier and Kinnard, 2015; Seppi et al., 2015, 2019; Kenner, 2019; Gärtner-Roer and Bast, 2019). New insights on the latter resulted from in-depth geophysical prospections, high-resolution archival and digital photogrammetry, systematic kinematic and ground surface temperature monitoring (Bosson and Lambiel, 2016; Kunz and Kneisel, 2020; Wee and Delaloye, 2022; Gärtner-Roer...
et al., 2022), which enabled the extension of previous studies on the understanding of glacier-permafrost interactions (Reynard et al., 2003; Kneisel and Kääb, 2007; Kääb et al., 1997).

In a context of growing interest and effort to coordinate the development of rock glacier inventories as part of large-scale approaches to quantify the impact of climate change on permafrost, such as the Global Terrestrial Network-Permafrost and IPA Action Group Rock Glacier Inventories and Kinematics (Streletskiy et al., 2021; IPA Action Group RGIK, 2023), especially when automated remote sensing approaches are used (Robson et al., 2020; Sun et al., 2024), confusion and misinterpretations may arise in complex geomorphological settings (Whalley, 2020). This is why there is a necessity for ground truth data to create clarity in order to better interpret and analyse the climatic, hydrological and geomorphological significance of rock glaciers, in particular where complex geomorphological contexts (e.g. glacier-permafrost interactions) hamper simple and straightforward “either-or” classification (Haeberli et al., 2024).

This contribution aims to understand the extent to which ground ice properties influence the surface dynamics of a) a rock glacier partially affected by the advance of a glacier during the Little Ice Age and b) a nearby debris-covered glacier terminus at Gruben (Southern Swiss Alps), on the basis of in-situ geodetic, close-range remote sensing and geophysical measurements. The extent and properties of ground ice is assessed through the analysis of the combination of refraction seismic and geoelectrical resistivity measurements, by applying the petrophysical joint inversion approach (Wagner et al., 2019; Mollaret et al., 2020). The kinematic behaviour of a rock glacier, of a complex contact zone (cf. Haeberli et al., 2024), and of the adjacent debris-covered glacier is investigated, with an emphasis on the contribution of ice melt-induced subsidence to surface elevation changes. This is achieved by combining the analysis of seasonal GNSS and uncrewed aerial vehicle (UAV) surveys, as well as continuous time series of displacements from fixed dGNSS stations. This study underlines the importance of a multi-method and multidisciplinary approach in understanding and discriminating driving processes contributing to the surface dynamics of complex periglacial landforms.

2 Study site

The Gruben site (46°10′22″N 7°58′09″E, Fig. 1) is located in the Saas Valley in the southern Swiss Alps. It is characterized by the rapidly shrinking debris-covered cold tongue of the polythermal Gruben glacier below the western face of the Fletschhorn (3985 m a.s.l.), the continuously advancing, perennially frozen Gruben glacier forefield-connected rock glacier below the south-eastern flank of the Rothorngrat (3104 m a.s.l.), and a complex contact zone of the then more extended Little Ice Age glacier and the rock glacier permafrost (Haeberli et al., 2024). During its LIA maximal extent, the margins of the Gruben polythermal glacier overrode the uppermost zone of the pre-existing Gruben rock glacier (Kääb et al., 1997; Gärtner-Roer et al., 2022), consequently altering the thermal regime, spatial distribution of ground ice, surface morphology of this zone. The morphological signature of this glacier-permafrost contact and interaction is expressed by glaciotectonics (compressive ridges and furrows perpendicular to the stress exerted by the LIA advancing glacier) and thermokarstic features, the latter inferring the presence of buried massive ground ice. Geometrical changes and reoriented stress fields in this zone are
expressed by lateral back-creeping (in the direction of the topographic thalweg formerly occupied by the glacier) and enhanced surface elevation changes mainly due to ice melt-induced subsidence. In contrast to the complex contact zone, the rock glacier displays longitudinal ridges and furrows, parallel to its extending flow field. Its kinematic behaviour is rather constant over time (from 1994 to present-day) with horizontal surface velocities ranging between 0.3 to 1.0 m/y and mean vertical changes are of -0.1 m/y to -0.5 m/y, mainly due to the downslope creep movement and permafrost thaw in summer (Kääb et al., 1997; Gärtner-Roer et al., 2022).

The debris-covered glacier tongue of the polythermal Gruben glacier (south-eastern part in Fig. 1) is characterized by a rather chaotic surface morphology, however, a pattern of somewhat subdued transverse ridges and furrows from compressing flow is discernible. Earlier borehole temperature investigations (Haeberli, 1976) revealed ice temperatures of -1°C to -2°C within the tongue of the glacier, which was frozen to its bed at the margins (i.e. cold-based glacier margins) but was temperate at its upglacier base (cf. (Etzelmüller and Hagen, 2005). Surface elevation changes express strong signs of downwasting: the central zone shows important rates of ice melt-induced subsidence, gradually decreasing towards the margins, inferring the rapid thinning and vanishing of (cold) glacier ice (Gärtner-Roer et al., 2022).

Figure 1: General geomorphological description of the Gruben site. The Gruben rock glacier is highlighted by the yellow dashed lines. The complex contact zone is highlighted by alternating yellow and blue dashed lines. The delineation between the rock glacier...
and the complex contact zone (faded hatched lines) is here not clearly defined but based on geomorphological knowledge and prior studies (Kääb et al., 1997; Gärtner-Roer et al., 2022). The Gruben debris-covered glacier terminus is highlighted in blue. Black dashed lines indicate part of the LIA maximal extent of the Gruben glacier. Red dashed lines indicate a probable former (~1600) LIA glacier advance. Fluted moraines indicate the flow direction of the adjacent Senggchuppa glacier. Background: SWISSIMAGE 2017 (swisstopo).

Winter equilibrium temperature (WEqT) values of the measured ground surface temperature at Gruben between 2015 and 2023 evidence that permafrost is still thermally active, i.e. winter freezing penetrates down to the permafrost table (GärtnervRoer et al., 2022; PERMOS, 2023). However, the mean annual ground surface temperature (MAGST) measured between 2015 and 2023 in this complex contact zone is of 0.39°C, which is significantly (almost fourfold) colder than the MAGST measured in the rock glacier zone (downslope of the complex contact zone, see Fig. 1), which is of 1.27°C (Fig. 2a). This infers that permafrost conditions at depth are in strong thermal disequilibrium with current thermal conditions at the surface (PERMOS, 2023). Moreover, an ongoing warming trend of 1.51°C per decade has been documented on the Gruben rock glacier and complex contact zone, essentially due to summer ground surface warming (Fig. 2b).
3 Methods

To overcome the limitations in interpreting results that can arise when techniques are applied separately, this study favours a multi-method approach using recent and high-resolution datasets (Fig. 3). The characterization of frozen ground is quantitatively assessed in this study using the newly developed petrophysical joint inversion (PJI) approach (Wagner et al., 2019; Mollaret et al., 2020), based on the application of electrical resistivity tomography and refraction seismic tomography.
which have complementary sensitivities to ice-to-water and air phase changes (e.g. Hauck et al., 2011). This novel approach not only allows the quantification of the ice content, but also to quantify supersaturated conditions using non-invasive geophysical methods. Surface dynamics are assessed through a geodetic approach, which relies on differential global navigation satellite system (dGNSS) observations for a high-temporal-resolution, and repeated UAV-based imagery acquisition combined with structure-from-motion (SfM) three-dimensional (3D) reconstruction for high-resolution topographic analysis. Lastly, the combination of geodetics and geophysics allows to link spatially variable ground ice contents with changes over time, for different ice origins.

Figure 3: Overview of the distribution of the geodetic survey points (crosses are the points monitored since 2012 and diamonds are the points monitored since 2021), the location of the four permanent dGNSS and the reference station. The location of the electrical resistivity tomography (ERT) and refraction seismic tomography (RST) profiles is equally presented. The continuous black line indicates ERT profiles with a 5 m electrode spacing and the white lines indicate ERT profiles with a 2.5 m electrode spacing (cf. section 4.1.). The distribution of temperature loggers (UTL-3) is also presented. Background: UAV-derived hillshade (06.10.2022).
3.1 Electrical resistivity tomography (ERT)

ERT is a well-established method to image the two-dimensional distribution of electrical properties of subsurface mountain permafrost and ground ice due to its sensitivity and suitability to distinguish unfrozen material, ice-containing permafrost (excess ice), and massive sedimentary ice due to their contrasting electrical properties (e.g. Haeberli and Vonder Mühll, 1996; Hauck and Kneisel, 2008; Bosson et al., 2015; Halla et al., 2021; Herring et al., 2023).

On the rock glacier and complex contact zone, all ERT profiles were measured between 8–12 August 2022 with a SYSCAL Pro (Iris Instruments), which can connect to 48 stainless-steel electrodes. A longitudinal profile of 955 m (P00) was achieved by aligning 7 consecutive profiles of 235 m (roll-along, with a ½ overlap) with an electrode spacing of 5 m. Along two sections of the profile P00, two co-located profiles P00a and P00b (117.5 m each) with 2.5 m electrode spacing were measured to obtain information at shallower investigation depth. Profiles P00, P00a and P00b were merged in the data management software Prosys II (Iris Instruments) allowing for a single inversion of all quadrupoles measured along the same line (including both 2.5 m and 5 m spacings). On the debris-covered glacier, one profile (P115) with 2.5 m electrode spacing was conducted. All profiles were measured with a Wenner-Schlumberger array configuration. The filtering (i.e. the extermination of bad data points) of the data from all profiles was achieved manually using Res2DInv (Aarhus GeoSoftware). For profiles GRU-P00, GRU-P10, GRU-P23 and GRU-P115, 18%, 2%, 6% and 14% of the data points were filtered, respectively. The inversions were carried out using the pyGIMLi-based code (Rücker et al., 2017).

3.2 Refraction seismic tomography (RST)

RST makes use of the differences in the elastic properties of subsurface materials, such as unfrozen sediments, supersaturated permafrost, and buried surface ice, which are quantified in terms of their different P-wave velocities and their spatial variability. P-waves are refracted when they encounter subsurface layers with velocity contrasts and are especially well suited to delineate quasi-horizontal subsurface layers and to differentiate between air- and ice-filled pores space, which may both exhibit similarly high electrical resistivities (Hauck, 2001; Hilbich, 2010; Draebing, 2016; Halla et al., 2021).

Four RST profiles were measured on co-located lines of the longitudinal ERT profile (P00). A first RST campaign was carried out in mid-August 2022, in the upper glacier-affected zone of the rock glacier (complex contact zone), and a second in mid-August 2023, in the lower glacier-affected zone (complex contact zone) and the rock glacier (cf. Fig. 3). In both campaigns, a 24-channel Geode instrument (Geometrics) with 24 geophones and a sledgehammer source were used. The 2D data analysis (picking of first breaks) and travel-time analysis were performed using ReflexW (Sandmeier geophysical research).

3.3 Petrophysical joint inversion (PJI)

We apply a petrophysical joint inversion (PJI) approach (Wagner et al., 2019; Mollaret et al., 2020) to jointly invert the measured apparent resistivities and seismic travel times to quantify the volumetric fraction of ice, water, air, and rock contents.
Following Mollaret et al., (2020), the PJI approach is based on petrophysical equations that relate bulk electrical resistivities and seismic velocities to the fractions of the four phases in the subsurface, based on the resistivities and P-wave velocities of ice, water, air and the rock matrix. The sum of all fractions has hereby to adhere to:

\[ f_r + f_w + f_a + f_i = 1 \]  

with the indices \( r, w, a, i \) indicating rock, water, air and ice, respectively.

The petrophysical equation for P-wave velocities follows the approach of (Timur, 1968) and (Hauck et al., 2011) linking the slowness and volumetric content of the four fractions to the measured bulk slowness as follows:

\[ \frac{1}{v_p} = \frac{f_r}{v_r} + \frac{f_w}{v_w} + \frac{f_a}{v_a} + \frac{f_i}{v_i} \]  

with the velocities \( v_r, v_w, v_a \) and \( v_i \) for rock, water, air and ice, respectively.

In Wagner et al. (2019) and in many ERT applications on permafrost, Archie’s Law (Archie, 1942) is used to link measured resistivity to material properties such as saturation and porosity (cf. Herring et al., 2023). Archie's law is generally recognized as valid when the electrolytic conduction process is the dominant one. However, this is unlikely to be the case for coarse, blocky materials and supersaturated permafrost conditions, limiting its applicability. Thereby, following Mollaret et al., (2020), the geometric mean model (Eq. 3; Glover, 2010) was applied here instead, as it has the advantage to include all fractions of the four phases (and not only rock and water as in Archie’s Law), and consequently yield realistic and well-constrained ice content estimations also in cases where the water content is potentially low (as in rock glaciers, Mollaret et al., 2020):

\[ \rho = \rho_r^{f_r} \cdot \rho_w^{f_w} \cdot \rho_a^{f_a} \cdot \rho_i^{f_i} \]  

where \( \rho_r, \rho_i, \rho_w \) and \( \rho_a \) are the resistivities for rock, water, air and ice, respectively.

The results of the PJI depend on different sets of parameters in addition to the measured apparent resistivities and seismic traveltimes. A range of resistivity [\( \Omega m \)] and P-wave velocity [m/s] values was attributed to each of the four phases (\( \rho_w, \rho_i, \rho_a, \rho_r \)). These were based on estimated resistivities and velocities obtained from the ERT and RST datasets as well as on standard ranges found in the literature (Hauck and Kneisel, 2008). A physically plausible range (i.e. 0.2-0.8) of initial porosity (\( 1-f_r \)) values was prescribed through an iterative process to define the most adequate initial porosity value of each profile, which influences the distribution of the four phases. Regularisation parameters for the inversion were attributed according to the suggested values by Mollaret et al. (2020) (see Table 1). Because of the varying sensitivity of the model to prescribed resistivities of the four phases and initial porosity, a looping process was used to systematically test different combinations of parameters (\( \rho_w, \rho_i, \rho_a, \rho_r \) and initial porosity) with different sets of prescribed values (Table 2). The goal was to identify the optimal combination that most closely matched the model’s \( \chi^2 \) (where \( \chi^2 = 1 \) indicates a perfect fit to the data, given the data error, following the method outlined by Günther and Rücker (2023) and prior site knowledge.

| Table 1: Summary of the applied parameters for each profile. \( \text{err}_\alpha \) and \( \text{err}_\rho \) are the individual inversion errors of both data types, \( \alpha \) denotes the smoothness regularization parameter, \( \beta \) corresponds to the volumetric conservation regularization parameter, and |
|---|---|---|---|---|---|---|---|
| \( \rho \) | \( \rho \) | \( \rho \) | \( \rho \) | \( \rho \) | \( \rho \) | \( \rho \) | \( \rho \) |
| \( \alpha \) | \( \alpha \) | \( \alpha \) | \( \alpha \) | \( \alpha \) | \( \alpha \) | \( \alpha \) | \( \alpha \) |
| \( \beta \) | \( \beta \) | \( \beta \) | \( \beta \) | \( \beta \) | \( \beta \) | \( \beta \) | \( \beta \) |

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2Weight corresponds to the anisotropic smoothness parameter, used to enhance horizontal or vertical structures (Mollaret et al., 2020).

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<th>Parameters</th>
<th>GRU-S01</th>
<th>GRU-S02</th>
<th>GRU-S03</th>
<th>GRU-S04</th>
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<td>( \text{err}_t ) (m/s)</td>
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<td>15</td>
</tr>
<tr>
<td>( \beta )</td>
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<td>10 000</td>
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<td>10 000</td>
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<tr>
<td>( z_{\text{Weight}} )</td>
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<td>0.25</td>
<td>0.15</td>
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</table>

Table 2: Combination of parameters used for the looping process.

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<thead>
<tr>
<th>( \rho_w ) (( \Omega \text{m} ))</th>
<th>( \rho_i ) (( \Omega \text{m} ))</th>
<th>( \rho_r ) (( \Omega \text{m} ))</th>
<th>( \rho_a ) (( \Omega \text{m} ))</th>
<th>( \phi_{\text{start}} ) (%)</th>
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<td>100</td>
<td>5 000 000</td>
<td>30 000</td>
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<td>40</td>
</tr>
</tbody>
</table>

3.4 Differential global navigation satellite system (dGNSS)

Surface velocities of rock glaciers are measured by bi-annual terrestrial geodetic surveys (TGS) in early and late summer (early-July and early October), as well as hourly by permanently installed dGNSS devices. These two complementary approaches allow to capture the seasonal velocity variations (permanent dGNSS) as well as their spatially distributed annual and intra-annual changes (TGS) (PERMOS, 2022). Moreover, the data derived from these measurements allow to calculate the kinematic response to thermally driven processes such as ice melt-induced subsidence (Wee and Delaloye, 2022).

3.4.1 Bi-annual (seasonal) terrestrial geodetic survey (TGS) acquisitions

Surface displacement changes have been monitored on the Gruben rock glacier and complex contact zone bi-annually (early summer and late summer) since 2012, as well as on the Gruben debris-covered glacier since 2021 by real-time kinematics (RTK) differential GNSS surveys using a Leica Viva GS10 (Leica Geosystems), according to the measurement set-up described by Lambiel and Delaloye (2004). In the scope of this study, measurements from field surveys carried out between 2022 and 2023 in early July and early October are used to distinguish the surface displacements during the longer winter period (approximately 270 ± 5 days) from those occurring during snow-free summer period (90 ± 5 days). A total of 75 monitoring points is distributed throughout the site, including 46 on the rock glacier and complex contact zone, and 24 on the debris-
covered glacier as survey points, and five control points marked on stable bedrock for quality assessment. Horizontal, vertical and 3D displacement vectors are calculated between two geodetic surveys with a relative accuracy of about 2-3 cm horizontally and 4-5 cm vertically. On survey dates 06.10.2022 and 03.07.2023, all monitoring points were measured. However, on 07.10.2023, only the monitoring points located on the rock glacier were measured.

From the TGS, we assess the driving processes contributing to surface elevation changes between early October 2022, early July 2023 and early October 2023. This timeframe allows the seasonal coverage over a year. We hereby assume that the change in elevation ($\Delta z_{\text{meas}}$) over time is attributed to the combination of three main processes (a) elevation change due to the downslope movement, following the topographical slope angle ($\Delta z_{\text{topo}}$); (b) change in elevation due to the melting ($\Delta z_{\text{melt}}$) or aggradation of excess ground ice, i.e., ice in oversaturated conditions or massive ice lenses; and (c) change in elevation caused by extending or compressing flow patterns ($\Delta z_{\text{flow}}$) (Lambiel and Delaloye, 2004; Haeberli et al., 2006; Bosson and Lambiel, 2016; Wee and Delaloye, 2022). Here, following Isaksen et al. (2000) and Bosson and Lambiel (2016) the expected vertical position of each block ($\Delta z_{\text{topo}}$) was calculated from the measured horizontal movement ($\Delta x_{\text{meas}}$) and the mean topographical slope angle around each block (derived from a resampled 5 m resolution DEM) (Eq. 4).

$$\Delta z_{\text{topo}} = \Delta x_{\text{meas}} \times \tan (\alpha)$$  \hspace{1cm} (4)

The difference between the obtained values of the expected vertical displacement ($\Delta z_{\text{topo}}$) and the measured vertical movement ($\Delta z_{\text{meas}}$) provided information related to estimated ice melt-induced surface elevation changes and flow patterns (calculated $\Delta z_{\text{melt-flow}}$; Eq. 5).

$$\Delta z_{\text{melt-flow}} = \Delta z_{\text{meas}} - \Delta z_{\text{topo}}$$  \hspace{1cm} (5)

To assess the seasonality and spatial signature of the driving processes contributing to surface elevation changes, the ratio between the expected summer displacement ($\Delta z_{\text{topo-summer}}$) and the winter displacement ($\Delta z_{\text{topo-winter}}$) was calculated. The ratio between downslope movement and surface lowering ($\Delta z_{\text{topo}}/\Delta z_{\text{melt-flow}}$) was calculated to evaluate the dominant process among the former and the latter. Surface lowering likely due to ice melt is dominant when $\Delta z_{\text{topo}}/\Delta z_{\text{melt-flow}} < 1$ and downslope movement probably enhanced by an extending flow pattern is dominant when $\Delta z_{\text{topo}}/\Delta z_{\text{melt-flow}} > 1$.

### 3.4.2 Continuous automatic dGNSS acquisitions

Three permanent GNSS stations are installed on the Gruben site: two on the complex contact zone and one on the debris-covered glacier, which have been delivering continuous hourly position measurements since early summer 2022. An additional permanent GNSS station has been installed on stable terrain to provide a stable reference for the double-difference GNSS post-processing processing scheme to obtain robust quality controlled daily positions (Beutel et al., 2021; Cicoira et al., 2022). The high temporal resolution provided by permanent GNSS instruments enables the computation of monthly to daily displacements (Wirz et al., 2016; PERMOS, 2022). However, because of the noise observed in the dataset, which can be caused by stochastic movements of the terrain’s surface, the rotation around the axis of the GNSS mast (which depends on the size of the boulder), but also by various environmental factors such as wind, temperature changes, or snow cover (Wirz et al., 2014;
Beutel et al., 2021; Cicoira et al., 2022), we apply a simple 15-day running-mean was applied to the dataset to filter displacement noise from any displacement signal.

### 3.5 UAV-Structure from Motion (SfM) photogrammetry

To obtain high-resolution orthoimages and digital elevation models (DEMs) for the studied area, UAV surveys were conducted on 6 October 2022, 3 July 2023, and 7 October 2023. These surveys enabled high spatial resolution mapping of seasonal (summer and winter) surface displacements at the studied area (Vivero et al., 2022). The UAV surveys employed a Phantom 4 RTK DJI device, equipped with a GNSS L1 and L2 frequencies antenna, providing real-time kinematics (RTK) differential corrections using a virtual reference station (VRS) based on the automated GNSS [reference stations] network for Switzerland (AGNES). Flight missions were planned with the built-in DJI GS RTK application. All missions were designed with the same parameters: side and forward overlap were set to 70% and 80%, respectively and flown at a constant height of 70 m, based on the swissALTI3D DEM loaded in the Terrain Awareness module to cover the entire area of interest. This resulted in approximately 2000 images with a geotagging accuracy between 1-2 cm (horizontally) and 1.5-3 cm (vertically) per survey.

The UAV images were processed using the software PIX4Dmapper Pro version 4.7 to derive digital elevation models (DEMs) and orthomosaics, which were sampled at a resolution of 2.5 cm × 2.5 cm.

Surface elevation changes were quantified by differencing the sequential DEMs from each other to obtain a DEM of difference (DoD) for each time interval, respectively 06.10.2022 – 03.07.2023 and 03.07.2023 – 07.10.2023. The obtained high-resolution DEMs allowed to derive the terrain’s topography, from which the loss in surface elevation due to downslope movement was calculated (Bosson and Lambiel, 2016; Wee and Delaloye, 2022). Horizontal surface displacements were derived from pairs of the above-mentioned multi-temporal orthoimages of 0.25 m pixel size by applying a normalised cross-correlation (NCC) procedure using the image correlation CIAS software (Kääb and Vollmer, 2000; Debella-Gilo and Kääb, 2011). The accuracy and quality of the image correlation was evaluated by applying the Helmert transformation based on points placed on stable terrain in the vicinity of the studied landforms (Kääb, 2023). Despite the difficulty of finding stable terrain outside the studied landforms in the surveyed area, 46 (44) stable points were used for the t1 orthoimage and 44 for the epoch 1 (epoch 2) orthoimage pair. This allowed to assess scale differences, rotations, or translations (x-y shifts) between two orthoimages (Table 3).

<table>
<thead>
<tr>
<th>Orthoimage</th>
<th>Points</th>
<th>Scale [m]</th>
<th>Rotation [°]</th>
<th>Shift x [m]</th>
<th>Shift y [m]</th>
<th>σx [m]</th>
<th>σy [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>06.10.2022 – 03.07.2023</td>
<td>46</td>
<td>1.00</td>
<td>359.99</td>
<td>-0.015</td>
<td>-0.007</td>
<td>0.024</td>
<td>0.032</td>
</tr>
<tr>
<td>03.07.2023 – 07.10.2023</td>
<td>44</td>
<td>1.00</td>
<td>359.99</td>
<td>-0.008</td>
<td>0.004</td>
<td>0.031</td>
<td>0.033</td>
</tr>
</tbody>
</table>

The uncertainties associated with the x and y displacement vectors derived from image matching in CIAS were assessed using the standard deviations (σx and σy) of the residuals of the stable points used to assess the orthorectification of each orthoimage,
and where $\Delta x$ and $\Delta y$ are the individual components of the displacement vector, corrected for any co-registration bias (Redpath et al., 2013):

$$\sigma_d = \sqrt{\frac{(\Delta x)^2}{d} \sigma_x^2 + \frac{(\Delta y)^2}{d} \sigma_y^2}$$

(6)

The variance $\sigma_x$ and $\sigma_y$, which are about equal to the pixel size, indicate the spatial uncertainty that arises from the orthorectification and mosaicking processes, as well as the performance of the automatic imagine matching using the NCC function. A confidence interval of 90% for each displacement vector was calculated (i.e. $1.645 \times \sigma_d$) to define the minimum limit of detection (LoD). The resulting LoD were converted into m/y. A GIS filtering of flawed data points (e.g. vectors located on snow patches, vectors pointing upstream) was established in a final step.

### 3.6 Ground surface temperature

The thermal state of the ground surface and the possible occurrence of ground ice close to the subsurface on the Gruben rock glacier were assessed through the monitoring of ground surface temperature (GST) at a 2-hour frequency since 2013. Three temperature loggers are located in the complex contact zone (Gru-03, Gru-10, Gru-21), and two are located in the rock glacier zone (Gru-29 and Gru-36). From 2013 to 2018, GST data were measured using UTL-1 data loggers (Geotest AG) with an accuracy of $\pm 0.2^\circ$C, and from 2018 onwards, UTL-3 data loggers (Geotest AG) with an accuracy of $\pm 0.02^\circ$C were used.

### 4 Results

#### 4.1 Characterisation of the subsurface: conventional ERT

Figure 4 presents the inverted resistivity tomograms for all profiles. Two main zones can be identified from prior geomorphological analysis and interpretation, but also from the spatial distribution of resistivity values observed in the longitudinal profile GRU-P00: the rock glacier zone and the complex contact zone (Fig.4a). In what is here considered as the permafrost zone of the Gruben rock glacier, resistivity values range between 35 and 50 k$\Omega$m in the uppermost 5-7 m, which likely corresponds to the active layer. Below the active layer, a layer with very high resistivity values ranging between 350 and 500 k$\Omega$m dominates the lower section of the profile, suggesting widespread perennially frozen, ice-supersaturated sediments (excess ice). Resistivity values characterizing perennially frozen ground reach deeper than the penetration depth of the soundings.

In the central part of the profile GRU-P00 (Fig.4a), between roughly 450 m and 650 m, a relatively thin layer of coarse debris of about 2 m, which gradually becomes thinner (supposedly < 1 m), overlays a layer with resistivity values ranging from 350 to 1000 k$\Omega$m, whose thickness exceeds the penetration depth of the sounding. Local distinct patches of resistivity values of around 2500 k$\Omega$m are corroborated by the transversal profile GRU-P23 that crosses the longitudinal profile at around 500 m (Fig. 4a, 4e, 4g). Such extremely high resistivity values suggest the presence of buried surface ice in this zone,
as pure glacier ice has been shown to be significantly less conductive than ground ice produced under permafrost conditions. The latter contains more electrically conductive ions through refreezing of water that has been in contact with rock material (in contrast to glacier ice which forms through precipitation of snow).

In the uppermost section of the complex contact zone, profiles GRU-S01 and GRU-P10 indicate resistivity values ranging between 350 and 1000 kΩm under a shallower layer of more conductive glaciogenic fine sediments between 15 and 30 kΩm (Fig. 4a, 4c, 4f). Resistivity values at the north-eastern end of the longitudinal profile (between 900 m and 955 m) range from 3 to 10 kΩm, pointing to unfrozen and ice-free conditions. Similar to the values observed at the uppermost end of the longitudinal profile, towards the outer margins (south-east) of the Gruben rock glacier, both transversal profiles GRU-P10 (Fig. 4f) and GRU-P23 (Fig. 4g) show resistivity values between 3 and 30 kΩm, which could possibly indicate a high water content.

Profile GRU-P115 is located on the Gruben debris-covered glacier tongue (Fig. 4h). The resistivity values measured in the uppermost 3-4 m of the profile range between 10 and 30 kΩm. Under this layer of very coarse debris, a highly resistive layer of 1000 to likely > 2500 kΩm is observed, indicating glacier ice.
Figure 4: The main longitudinal ERT profile GRU-P00 is presented in the uppermost panel (a). ERT profiles GRU-S01, GRU-S02, GRU-S03 and GRU-S04 are presented in panels (b-e) and represent the profiles where both ERT and RST measurements were carried out. The transversal profiles GRU-P10 and GRU-P23 are presented in panels (f-g). Profile GRU-P115, carried out on the debris-covered glacier is presented in panel (h).
4.2 Estimation of ground ice content

Figure 5 shows the estimated ice, water and rock content distributions along profiles GRU-S01, GRU-S02, GRU-S03 and GRU-S04. Using the full ranges of free parameters (within reasonable physically consistent bounds) shown in Table 2, would yield a wide range of different spatial distributions for the abovementioned three phases. The parameters selected in Table 4 yield a best guess estimate for the porosity (or rock fraction) and ice content distribution, informed by prior geomorphological knowledge of the site, and result in a low $\chi^2$ error, demonstrating a strong agreement with the observed data. A high water-to-ice ratio is observed in the north-eastern section (between 100 and 130 m) of profile GRU-S01 (Fig. 5a), where the terrain surface is characterized by fine-grained glaciogenic sediments (till), where more water capillary action occurs. In contrast, the section between 20 and 75 m, located at the edge of a former thermokarst lake, presents a high ice-to-water ratio. This can be explained by the coarse-blocky terrain surface, which favours the resilience of ground ice (Amschwand et al., 2023). Between 125 and 160 m in profile GRU-S02 (Fig. 5b), where the ice content ranges between 80-90%, almost no water is present, suggesting the presence of embedded cold surface ice. The minimum ice content is encountered in the thermokarst depression, intersecting the 1995 drainage breach (Kääb et al., 1997), suggesting an alteration of the subsurface thermal regime. Both extremities of profile GRU-S03 contain less ice, which is compensated by a relatively high rock fraction. High ice contents reaching up to 84% are locally found in the middle of the profile and are counterbalanced by a relatively porous medium, inferring remnants of massive (surface-?) ice lenses embedded in the frozen sediments (Fig. 5c).

In contrast to the profiles located in the complex contact zone, the uppermost 5-7 m of profile GRU-S04 within the rock glacier zone displays a well-defined porous (about 40-30%) coarse debris layer. Below this layer, the maximum ice content is found under supersaturated conditions (Fig. 5d).
Table 4: Selected parameters corresponding to low $\chi^2$ and RMS error used for the PJI.

<table>
<thead>
<tr>
<th>Parameters</th>
<th>GRU-S01</th>
<th>GRU-S02</th>
<th>GRU-S03</th>
<th>GRU-S04</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\rho_w$ (Ωm)</td>
<td>50</td>
<td>100</td>
<td>50</td>
<td>5</td>
</tr>
<tr>
<td>$\rho_i$ (Ωm)</td>
<td>5000000</td>
<td>2500000</td>
<td>5000000</td>
<td>5000000</td>
</tr>
<tr>
<td>$\rho_r$ (Ωm)</td>
<td>30000</td>
<td>30000</td>
<td>30000</td>
<td>30000</td>
</tr>
<tr>
<td>$\rho_a$ (Ωm)</td>
<td>1000000</td>
<td>1000000</td>
<td>1000000</td>
<td>1000000</td>
</tr>
<tr>
<td>$\phi_{start}$ (%)</td>
<td>60</td>
<td>80</td>
<td>80</td>
<td>80</td>
</tr>
</tbody>
</table>

4.3 Seasonal surface displacements and surface elevation changes

Figure 6 displays seasonal horizontal surface velocity flow fields of the Gruben rock glacier, complex contact zone and debris-covered glacier. A coherent, lengthwise-oriented flow field is documented on the Gruben rock glacier, downslope of the
topographical rupture. Between the latter and the complex contact zone, the measured vector field shows an orientation oblique
This flow trajectory may indicate that the influence of the LIA glacier on the creeping permafrost extended beyond the former ice margin. In the complex contact zone with the LIA glacier, the flow field is considerably more complex and includes a clear south-east oriented back-creeping towards the topographic depression of the forefield, previously occupied by the Gruben glacier during the LIA.

During the winter period (06.10.2022-03.07.2023, Fig. 6a), the mean horizontal surface velocity measured in the lower section of the slightly steeper rock glacier zone (close to the topographical rupture, zone 1) is 0.62 m/y, while in the relatively flat complex contact zone (zone 2), the mean horizontal surface velocity is 0.26 m/y. Horizontal surface velocities are generally faster during the summer period (Fig. 6b) compared to the winter period, particularly in the uppermost complex contact zone (zone 2), where the mean velocity is 0.52 m/y. In the lower section of the rock glacier (zone 1), the mean summer horizontal surface velocity is 0.92 m/y.

The upslope and downslope sections of the debris-covered glacier tongue are strikingly distinguishable in terms of flow field direction and velocity. In the uppermost zone, surface displacements are oriented towards the north-west, whereas in the lowermost zone, after the elbow turn, the flow trajectory is more diffuse and is directed towards the south-west. The upper section is characterized by faster velocities than the flatter and decaying frontal zone. The mean horizontal surface velocity observed in the lower zone (zone 3) during the winter period in the lower section is 0.37 m/y, while in the upper section (zone 4), the mean velocity is 1.74 m/y (Fig. 6a). During the summer period (Fig. 6b), the lower section’s (zone 3) mean velocity is 0.72 m/y, and the mean horizontal velocity is 4.19 m/y in the upper part (zone 4). The latter is characterized by more chaotic flow fields, which is likely due to differential ablation rates of the glacier in this section caused by an uneven distribution of debris-cover thickness.
Figure 6: UAV-derived horizontal surface displacements. The winter period (06.10.2022 to 03.07.2023) is presented in panel (a) and the summer period (03.07.2023 to 07.10.2023) is presented in panel (b). The zones (1-4) from which the mean velocities are derived from are highlighted by the dashed polygons. Background: UAV-derived hillshade (06.10.2022).
Surface elevation changes and horizontal surface velocities presented in Figure 7 reveal a striking seasonal and spatial signal in terms of the kinematic behaviour of the rock glacier. Flow fields, velocity patterns together with elevation changes observed on the rock glacier surface allowed to highlight the distinction between surface processes occurring in the complex contact zone from processes occurring in the rock glacier zone. UAV-derived elevation changes show that during the winter period, elevation changes range from -0.05 m to -0.20 m in the upper section of the complex contact zone, while in its lower section (east of the thermokarst depression) almost no elevation change is observed. The non-glacier-affected part of the rock glacier illustrates a vertical loss of about -0.20 m during winter, which can largely be explained by the continuous longitudinal stretching of the creeping ice-rich permafrost (Kääb et al., 1997). In summer, a higher vertical decrease of about -0.50 m is evidenced in the uppermost section of the complex contact zone, which largely exceeds the horizontal displacement (as shown in Fig. 7b), inferring ice-melt induced subsidence. This elevation loss extends downstream to the lower part of the complex contact zone, where the average elevation change reaches -0.35 m. Elevation changes in the rock glacier zone reach -0.20 m, and the general displacement slope angle of the surveyed points largely exceeds the topographical slope angle, evidencing ice melt but also elevation loss due to thinning (extending flow pattern) and downslope movement along the topographical slope. Elevation changes obtained from in-situ dGNSS surveys are consistent with the above-mentioned observations and are in agreement with the results previously presented by Gärtner-Roer et al. (2022).

Near the ice-cliff section of the debris-covered glacier terminus, the mean winter (06.10.2022-03.07.2023) surface elevation change is about -0.15 m, while in the margins surface elevation changes are < 0.10 m. Summer elevation changes are generally enhanced in this lower section of the debris-covered tongue, ranging from -0.15 to -0.55 m.
Figure 7: Seasonal elevation changes derived from DoD. Vertical changes and horizontal surface displacements derived from TGS. The measured points are identified by their corresponding number (Gru-xx, only in panel (a)). The winter period (06.10.2022 to 03.07.2023) is presented in panel (a) and the summer period (03.07.2023 to 07.10.2023) is presented in panel (b). Background: UAV-derived hillshade (06.10.2022).
The spatio-temporal variation of the surface elevation changes was assessed by calculating the ratio of the expected vertical movement (solely due to the downslope movement) for the summer and winter periods. The results document a strong seasonal and spatial pattern (Figure 8). In the complex contact zone, the mean ratio between the expected summer vertical displacement and the expected winter vertical displacement is of 2.52, which infers that additional processes such as ice melt-induced subsidence and extending flow contribute dominantly to the elevation loss in this zone. Whereas in the rock glacier zone, the mean ratio is of 1.12, which implies that surface elevation changes are relatively constant throughout the year but are likely slightly enhanced by thaw or melt-induced subsidence or due to the extending flow pattern observed in this area. The ratio between the downslope movement and the additional surface lowering over a year was calculated to determine the weight of the processes contributing to surface elevation loss. Surface lowering most likely due to ice melt dominates in the complex contact zone, with a mean ratio of 0.30. The mean ratio of 5.12 obtained in the rock glacier zone illustrates the predominance of the downslope movement, likely combined with thinning effects from extending flow. Points located in the thermokarst depression showed a less coherent behaviour as their values are relatively heterogeneous.

![Figure 8](https://doi.org/10.5194/egusphere-2024-1283)

Figure 8: The seasonal (summer and winter) and annual expected downslope displacement (solely following the slope angle topography) was calculated for the different zones (cf. Fig. 7) of the rock glacier and the complex contact zone. The ratio between the summer and winter expected downslope displacement was calculated (ratio seasonal \( \Delta z_{\text{topo}} \)). Seasonal and annual surface lowering rates (calculated \( \Delta z_{\text{melt-flow}} \)) are presented. The main dynamics are represented by the ratio between the annual expected downslope displacement (\( \Delta z_{\text{topo}} \)) and the calculated annual surface lowering (\( \Delta z_{\text{melt-flow}} \)).

---

\[
\begin{array}{|c|c|c|c|c|c|}
\hline
\text{Location} & \text{Expected } \Delta z_{\text{topo}} [\text{m/yr}] & \text{Ratio seasonal } \Delta z_{\text{topo}} & \text{Calculated } \Delta z_{\text{melt-flow}} [\text{m/yr}] & \text{Ratio } \Delta z_{\text{topo}}/\Delta z_{\text{melt-flow}} \\
\hline
\text{Gru-03-06} & -0.11 & -0.06 & -0.07 & 2.03 & -0.43 & -0.06 & -0.17 & 0.45 \\
\hline
\text{Gru-07-11} & -0.13 & -0.07 & -0.08 & 2.60 & -1.09 & -0.05 & -0.33 & 0.18 \\
\hline
\text{Thermokarst depression} & -0.19 & -0.06 & -0.08 & 3.55 & -0.98 & 0.01 & -0.26 & 0.36 \\
\hline
\text{Gru-23-27} & -0.08 & -0.04 & 0.05 & 1.91 & -0.88 & -0.06 & -0.28 & 0.20 \\
\hline
\text{Rock glacier} & & & & & & & & \\
\hline
\text{Gru-28-31} & -0.11 & -0.11 & -0.11 & 1.02 & -0.26 & -0.06 & -0.11 & 1.79 \\
\hline
\text{Topographical rupture} & -0.43 & -0.36 & -0.38 & 1.18 & 1.12 & -0.31 & 0.06 & -0.04 & 10.86 \\
\hline
\text{Gru-35-44} & -0.23 & -0.20 & -0.21 & 1.17 & -0.23 & -0.02 & -0.08 & 2.71 \\
\hline
\end{array}
\]
4.4 Contribution of ground surface temperatures to seasonal surface changes

The potential direct influence of ground surface temperature changes on ice melt-induced subsidence was assessed through the acquisition of hourly position measurements by permanent dGNSS stations, which were compared to daily GST measurements (Fig 9). At stations Gru-010 and Gru-023, located in the complex contact zone, vertical surface velocities tend to instantly decelerate once ground surface temperatures are below 0°C, and accelerate with a 10-day phase lag following the warming (> 0°C) of ground surface temperatures. Horizontal surface velocities slightly increase as ground temperatures start to increase (Fig. 9a-b). Displacement profiles of Gru-010 and Gru-023 show the sensitivity of the underlying ground ice to surface temperatures, as summer surface temperatures lead to an enhanced vertical displacement (Fig. 10a-b). Moreover, the displacement angle of about 65° largely exceeds the surface topography (10°), suggesting ice melt-induced subsidence. The reactivity of surface displacements to the thermal state of the ground surface can likely be attributed to the presence of embedded surface ice buried under a relatively shallow layer of debris (Fig. 4). In contrast to the kinematic behaviour observed in the complex contact zone, the intra-annual variability of vertical and horizontal surface velocities observed at station Gru-036 in the rock glacier zone, is more constant throughout the year (Fig. 9c). Peak velocities are reached in early summer, coinciding with the zero-curtain period, and in late autumn. This is explained by a phase lag between the seasonal summer peak in the ground surface temperatures and the surface velocities, may be partly attributed to the time for the temperature signal to propagate from the surface to the permafrost table (Wirz et al., 2016; Cicoira et al., 2019). The displacement angle of profile Gru-036 (Fig. 10c) follows the topographical slope of 15°, which is in complete accordance with the observations made Gärtner-Roer et al. (2022). The mere absence of a steeper displacement trajectory during the summer period suggests surface lowering due to downslope movement in a zone where extending flow pattern is dominant.
Figure 9: Ground surface temperature and horizontal and vertical velocity time series in the complex contact zone Gru-010 (a) and Gru-023 (b), and in the rock glacier zone Gru-036 (c).
Figure 10: Displacement profiles measured by permanent dGNSS stations Gru-010 (a) and Gru-023 (b) for the period 19.07.2022 to 22.11.2023. The lower graph (c) shows the displacement profile measured by the permanent dGNSS station Gru-036 for the period 01.04.2016 to 01.12.2017.

5 Discussion

The combination of geophysical datasets with high spatio-temporal resolution geodetic measurements and ground surface temperature monitoring allowed a detailed representation of the spatial distribution of ground ice, its properties, and its influence on the kinematic behaviour of the Gruben rock glacier and debris-covered glacier tongue. Here, the analysis of recent and high-resolution geodetic data together with GST data provides key information regarding the kinematic response to thermally driven processes. Moreover, geoelectrical and refraction seismic data enabled the characterisation of the subsurface, which revealed the influence of ground ice content and properties, and active-layer (or debris-cover) thickness on surface dynamics.
5.1 Evaluation of the geophysical approach

Using several ERT and RST profile lines on the rock glacier and debris-covered glacier, we applied a Petrophysical Joint Inversion (PJI) approach to model the four phase contents of the subsurface, with a focus on the quantification of the ground ice content. Within the PJI, the geometric mean model was employed to link the measured electrical resistivities with the volumetric fractions of each phase, as this approach has yielded well-constrained estimations of ice content and porosity for ice-rich rock glaciers (Mollaret et al., 2020) such as the Gruben rock glacier. As mentioned in chapter 3.3., different parameters, such as the initial porosity and the resistivity values of the four phases were tested to build a plausible range of model estimations. It was found that the ground ice estimation is sensitive to the model initial porosity constraints (Mollaret et al., 2020; Halla et al., 2021; Hilbich et al., 2022), as initial porosities ≥ 60% systematically yielded higher mean ground ice content, which appeared to be the most plausible ice content values according to the model’s χ² and RMS error. The choice of the most plausible tomograms was determined by considering the final model’s best-fit value χ² within the region where the model is characterised by high-complexity and low misfit. A sensitivity analysis was performed to better evaluate the reliability of the prescribed parameters and to estimate the range of possible model results from this parameter uncertainty. Figure 11 shows the dependence of (mean) ground ice contents in the different profiles on two of the major influencing parameters in our PJI models: initial porosity φ_{\text{start}} and ice resistivity ρ_i. Higher initial porosities (φ_{\text{start}} ≥ 0.6) systematically generated lower χ² and RMS values (not shown) (Fig. 11). Moreover, we tested the uncertainty range related to the influence of the prescribed water resistivity values ρ_w (5Ωm, 50 Ωm, 100 Ωm, red circles in Fig. 11) for a fixed set of other parameters. No significant variation in the mean ice content occurs, which reduces the uncertainty in regard to the chosen model. Finally, the choice of the model was also based on geomorphological knowledge and information from geodetic and temperature measurements. In contrast to the strong ambiguity between ice and rock content found in model applications using Archie’s Law (Hauck et al., 2011, Wagner et al. 2019), the application of the geometric mean model reduces the ice and rock ambiguity as all four phases are constrained by both geophysical datasets (Mollaret et al., 2020). Here, the model enabled better and more realistic estimations of the ice content.
The petrophysical joint inversion approach uses the measured apparent resistivities and seismic travel times to image the volumetric fractions of ice, rock, water, and air content. The latter is then re-transformed into P-wave velocity and electrical resistivity tomograms using the same petrophysical equations (1) to (3). Thereby, we additionally assessed the reliability of the model by comparing the conventional, individually inverted ERT and RST tomograms with the PJI-derived (transformed) ERT and RST tomograms (Fig. 12). The same regularisation parameters and mesh sizes were used for the individual inversions.
and for the PJI. All transformed ERT tomograms are qualitatively in good agreement with the conventional ERT tomograms. However, individual information, in particular higher velocities, are not represented in the transformed RST tomograms.

Figure 12: Comparison between the results from the conventional (individual) RST and ERT inversions with the resistivity and P-wave velocity distributions obtained from the PJI using the geometric mean model for resistivity. The electrical resistivity (here in $k\Omega m$) is displayed on a logarithmic colour scale.

5.2 Geodetic approach

The application of dGNSS and UAV surveys enabled an in-depth, of both high-temporal and high-spatial resolution, analysis of the kinematic behaviour of the Gruben rock glacier and debris-covered glacier. The large spatial coverage of the study site
allowed to grasp an overview of the general kinematic behaviour and patterns of both landforms, which are largely comparable to the observations of Kääb et al. (1997) and Gärtner-Roer et al. (2022). The geodetic datasets are quantitatively comparable, providing confidence to their robustness and reliability (Vivero et al., 2022). Despite the large spatial coverage provided by UAV-derived, the selection of ground control points can be a challenging processing step, in particular in high-mountain environments where stable ground surfaces are limited. Furthermore, in this case, the deployment of UAV surveys for kinematic monitoring is limited to snow-free periods. During the early summer survey (03.07.2023), seasonal snow patches were still present on both the rock glacier and the debris-covered glacier and were consequently masked out due to their interference with the image correlation processing applied.

Permanent GNSS stations provided a very high temporal resolution (hourly) of local surface displacements. Here, the use of a reference station mounted on stable ground, allowed to substantially improve the accuracy of the measured coordinates, as each position was corrected in real-time relative to the reference station. Despite the noisy dataset, which was filtered by applying a simple 15-day running mean approach, this dataset allowed to better understand the thermo-mechanical response of the rock glacier and complex contact zone to ground temperature changes in regards to the thickness of the coarse blocky layer above the frozen ground.

5.3 Internal structure and surface dynamics of the Gruben rock glacier and complex contact zone

Despite the lack of a clear surface morphology that would allow a straightforward delineation between the rock glacier and the former glacier-rock glacier contact zone, the observations made in this study provided key information to better understand the extent of the Gruben LIA glacier on the pre-existing perennially frozen sediments.

Geoelectrical soundings performed between 1979 and 1982 revealed ice-rich permafrost conditions in the downslope section of the rock glacier, here considered as the non-glacier-affected rock glacier zone (King et al., 1987). The results from geoelectrical and refraction seismic data of the present study confirmed the occurrence of a layer of ice-rich permafrost at depth in the frontal zone of the rock glacier and demonstrate the resilience of permafrost to the increasing air temperatures in the past four decades. The current conditions infer that the Gruben rock glacier was already under permafrost conditions before the LIA advance of the Gruben glacier. In the upslope section of the rock glacier, geomorphological indicators attest a former contact zone between the permafrost of the Gruben rock glacier and the polythermal Gruben glacier during its LIA maximal extent (Kääb et al., 1997; Gärtner-Roer et al., 2022; Haeberli et al., 2024). During the interaction phase between the polythermal glacier and the permafrost of the rock glacier, debris-covered glacier ice was locally embedded within, and primarily on top of the frozen debris, as evidenced by the geomorphological imprint of thermokarst in the former contact zone, but also by the extremely resistive and widespread ground ice content, likely referring to buried cold surface ice.

The spatial distribution of ground ice and its associated properties (embedded cold glacier ice or supersaturated permafrost) within the rock glacier is reflected by the heterogeneous kinematic behaviour of the latter (Bosson and Lambiel, 2016; Kunz et al., 2022; Cusicanqui et al., 2023). The former glacier-permafrost interaction phase not only altered the spatial distribution of ground ice and ground surface thermal regime of the investigated landform through the direct material contact
with its thermal coupling and mass exchange, but also induced geometrical deformations (changes in the topographic conditions) with related changes in stress transmission and stress fields. It is likely that the pressure – and hence the associated stress field reorientation – exerted by the formerly advancing polythermal glacier onto the pre-existing perennially frozen debris landform was transmitted across extended spatial scales. Deformation may have reached a few tens of meters at depth and over a few hundred of meters horizontally, meaning that the entire width of the rock glacier was probably impacted.

Figure 13: Interpretation of the influence of the LIA glacier-permafrost interaction on the mechanical behaviour of the rock glacier and its adjacent complex contact zone based on the analysis of high-resolution photogrammetry. The dashed grey line represents the topographical rupture. The dark blue arrows represent the stress exerted by the glacier onto the rock glacier. The white dashed arrows show the reoriented flow trajectories of the rock glacier and complex contact zone as a response to the stress exerted by the LIA glacier, while the grey dashed arrows show the unchanged flow trajectory of the rock glacier. The blue dashed line shows the probable extent of a prior stage (~1600) of LIA glacier advance. The dark red dashed line on the orographic right side of the rock glacier and the dashed ellipse show compression ridges likely due to the glacier stress. Background: UAV-derived hillshade (06.10.2022).
Figure 13 shows the general extent to which the mechanical behaviour of the rock glacier was influenced by the stresses exerted by the LIA glacier advances. It is likely that down-valley of the topographical rupture, large-scale stress transmission did not occur and the mechanical behaviour (steady state creep) of the perennially frozen body remained as it was prior to the LIA glacier advance. Coherent flow fields and longitudinal ridges and furrows observed in the downslope section of the rock glacier, indicate the gravity and thermally driven internal permafrost creep deformation and extending flow, respectively. However, up-valley of the topographical rupture up to the western boundary of the thermokarst depression, the stress exerted by the Gruben glacier during its LIA advances probably reached the orographic right side of the rock glacier, causing internal and surface deformation, which could be reflected by the flow trajectories and the compression ridges marked by the dark red dashed lines. Moreover, a glacier advance prior to the latest 1850 advance (Fig. 13) could have contributed to the mechanical deformation in this zone of the rock glacier. Further up-valley in the complex contact zone, less coherent flow fields, diverging from the down-valley direction towards the glacier forefield, indicate geometrical adjustments following the interaction phase between the Gruben rock glacier and the debris-covered glacier. A lateral back-creeping motion dominates this former contact zone. However, in the vicinity of the thermokarst depression, the flow pattern becomes locally much less coherent as the topography is relatively chaotic, favouring the stochastic displacement of the blocky surface. Moreover, where ground ice content is widespread within a rock matrix with excess ice, surface lowering is mainly interpreted as the expression of ice melt and thaw subsidence. The magnitude of the latter is highly dependent of the ground ice properties, the surface debris thickness and coarseness, and the temperature of the ground surface. The results from the geodetic and temperature measurements show direct and high-magnitude responses of subsidence to summer ground surface heating in the complex contact zone, the warmest temperatures are hereby associated with the largest subsidence. In this context, this shows that surface lowering is dominated by ice melt, a thermally driven process occurring at the permafrost or ground ice table (Staub et al., 2016; Wee and Delaloye, 2022). On the rock glacier, the loss in elevation appears to be mainly driven by internal continuous creep deformation, as the magnitude of the displacement is rather constant throughout the year, aside from a slight acceleration in early summer and early autumn, and a slight deceleration in winter. Ice melt-induced subsidence appears to be rather ineffective on surface lowering, however, the seasonal increase in water content due to snowmelt and permafrost thaw, enhances the deformation, suggesting that surface lowering due to a seasonally increased extensive flow pattern cannot be excluded (Cicoira et al., 2019).

5.4 Surface dynamics of the Gruben debris-covered glacier tongue

Surface changes observed on the debris-covered tongue reflects typical processes in response to seasonal variations. However, the magnitude of surface changes observed in the lower section of the Gruben glacier tongue is much smaller than of those observed in the uppermost section of the debris-covered tongue, which is likely due to the thicker debris-cover of the latter. The debris-covered glacier terminus, which is still connected to the debris-free active Gruben glacier, documents drastic signs of down-wasting. The lowermost section of the debris-covered tongue, on the other hand, shows signs of advanced degradation, in particular in its margins where only very slight surface changes occur (Gärtner-Roer et al., 2022). In addition to the low
flow velocities of the tongue’s terminus which impede the removal of the debris from the glacier, an important input of debris is provided from the northwestern flank of the Inner Rothorn (Benn et al., 2001; Mölg et al., 2020). In view of the thickness of the debris-cover, which reaches up to roughly 5 m (Fig. 4), it cannot be excluded that the latter significantly reduces the ablation rate of the terminus part, as near-surface heat transfer is dissipated into the atmosphere before being transferred to the underlying ice surface (Rounce et al., 2015; Nicholson and Benn, 2006). The heterogeneity of the debris-cover thickness causes differential ablation rates, and consequently a rather chaotic debris-surface. These differential ablation rates can also eventually lead to the development of ice-cliffs (Buri et al., 2016), as it is the case at Gruben.

6 Conclusion

The multi-method approach applied in this study provided new insights on ongoing intra-annual and annual dynamics of complex ice-rich landforms systems, such as the Gruben rock glacier and Gruben debris-covered glacier. This study has established the relationship between the internal structure of the investigated landforms with their physical processes and associated surface dynamics. The magnitude of ice melt-induced subsidence was the highest in the complex contact zone where still existing, isolated remnants of buried surface ice were detected by the geophysical investigations. Pronounced surface elevation loss due to extending flow and downslope movement was observed on the glacier forefield-connected rock glacier, which reflects the dominance of permafrost creep deformation. The kinematic signature of these two distinct morphological zones attests of their geomorphological heritage from the Holocene and LIA and highlights the interrelationship between glacial and periglacial processes occurring in the so-called complex contact zone. This underlines the complexity in capturing a complete and thorough understanding of the driving processes contributing to the morphodynamical evolution of such systems. This study also revealed the resilience of the ground ice to a warming atmosphere, in particular in the permafrost of the rock glacier. This was also found for the glacier ice beneath the thickening debris-cover of the Gruben glacier terminus, which is in complete disequilibrium with the current climate.

Data availability. GST and TGS data are partly available on the PERMOS data portal (https://www.permos.ch/data-portal). All other data are available upon request.

Author contributions. JW designed the research, collected the GST and GNSS data since 2016, planned, coordinated, and participated in the geophysical campaigns, processed and analysed the GST, GNSS data, and the geophysical data. SV conducted the UAV campaigns and processed the UAV-derived data with JW. TM and CM contributed to the development of the PJI code. JB provided data of one of the permanent GNSS station. CH and CL supervised and contributed to the study design. WH provided his knowledge from earlier studies. All authors were involved in the discussion and in the preparation of the manuscript.
Competing interests. At least one of the (co-)authors is a member of the editorial board of The Cryosphere.

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