

Response to the Community Comment (CC1)

In-Flight Estimation of Instrument Spectral Response Functions Using Sparse Representations

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We would like to thank the Editor and the referees and community members for their careful and thoughtful comments about our paper. We really appreciate the time and effort that has gone into their reviews. All the comments have been considered as detailed below. A detailed answer to the comments can be found in the following pages.

Response to Community Comment (CC1)

Comment 1

The use of an iterative and dictionary-based based approach for estimating ISRFs is a rather original solution.

Response:

We thank the community member for his/her positive appreciation of our work.

Comment 2

The fact that the most simple method, SVD + OMP, eventually leads to the best performance is a very good, yet somehow surprising, news, and could be further commented: has this to do with a particular choice of the hyper-parameter in (8) or with a lack of discrimination of the L1 norm constraint?

Response:

There is, indeed, no theoretical reason for the method SVD + OMP to lead to superior performance when compared to working with the ℓ_1 norm penalty. In our study, the hyperparameters for the algorithms have been chosen in order to achieve the best results. However, the OMP and LASSO algorithms address two distinct problems. Indeed, when the OMP algorithm provides an approximate solution to the problem with the ℓ_0 penalty, the LASSO algorithm solves the problem using the ℓ_1 penalty, hence gives the solution of an alternative, different problem. Certain limitations of the LASSO algorithm have been highlighted in numerous publications, including [1], and may be at the origin of our observations.

Comment 3

The iterations between dictionary estimates and sparse approximation represent an important aspect of the study, and could be further described.

Response:

Thank you for pointing this out. The following pseudo-codes have been added as an Appendix A in the revision of the manuscript:

- A1. The generation of the matrix of theoretical spectrum.
- A2. The construction of the dictionary.
- A3. The description of the OMP algorithm.
- A4. The description of the LASSO algorithm (for which the MATLAB *lasso* function is used).
- A5. The description of the K-SVD algorithm, which is based on the algorithm defined in [2].

Algorithm 1 Generation of the theoretical spectrum matrix.

Input: Theoretical spectrum r , wavelengths of the theoretical spectrum λ_r , wavelengths associated with the measured spectrum λ , wavelength associated with the ISRF Δ

Output: Theoretical spectrum matrix for all wavelengths R .

```
1: for  $l = 1, \dots, N_\lambda$  do
2:    $\lambda_l = \lambda(l)$ 
3:    $\lambda_{\text{resp}} = \lambda_l + \Delta$ 
4:    $R(l, :) = \text{interp}(\lambda_r, r, \lambda_{\text{resp}})$ 
5: end for
6: return  $R$ 
```

Algorithm 2 Construction of the dictionary.

Input: Matrix of selected ISRFs I , size of the dictionary N_{obs}

Output: Dictionary of ISRFs Φ .

```
1:  $[U, \Gamma, V^*] = \text{SVD}(I)$ 
2:  $\Phi = V(:, 1 : N_{\text{obs}})$ 
3: return  $\Phi$ 
```

Algorithm 3 Orthogonal Matching Pursuit (OMP) algorithm.

Input: Measured spectrum s_l , theoretical spectrum matrix R_l , dictionary of ISRFs Φ , sparsity parameter K

Output: Sparse vector α_l .

```
1:  $\Psi_l = R_l \Phi$ 
2:  $U_1 = s_l$ 
3: for  $k = 1, \dots, K$  do
4:   Find  $\Psi_{\gamma_k} \in \Psi_l$  that maximize the scalar product  $|\langle U_k, \Psi_{\gamma_k} \rangle / \|\Psi_{\gamma_k}\|$ 
5:   Find  $[\alpha_{\gamma_1}, \dots, \alpha_{\gamma_k}] \in \alpha_l$  that solves  $\arg \min_{\alpha} \|U_k - \sum_{k'=1}^k \alpha_{\gamma_{k'}} \Psi_{\gamma_{k'}}\|_2^2$ 
6:    $U_{k+1} = s_l - \sum_{k'=1}^k \alpha_{\gamma_{k'}} \Psi_{\gamma_{k'}}$ 
7: end for
8: return  $\alpha_l$ 
```

Algorithm 4 LASSO algorithm.

Input: Measured spectrum s_l , theoretical spectrum matrix R_l , dictionary of ISRFs Φ , sparsity parameter K , minimum value of the LASSO sparsity parameter μ_{\min} , maximum value of the LASSO sparsity parameter μ_{\max}

Output: Sparse vector α_l .

```
1:  $\Psi_l = R_l \Phi$ 
2:  $\alpha_{\text{resp}} = \text{lasso}(\Psi_l, s_l, \text{'lambda'}, \mu_{\max}, \text{'Alpha'}, 1)$ 
3: while sparsity( $\alpha_{\text{resp}}$ )  $\neq K$  do
4:    $\mu = \frac{\mu_{\min} + \mu_{\max}}{2}$ 
5:    $\alpha_{\text{resp}} = \text{lasso}(\Psi_l, s_l, \text{'lambda'}, \mu, \text{'Alpha'}, 1)$ 
6:   if sparsity( $\alpha_{\text{resp}}$ )  $< K$  then
7:      $\mu_{\max} = \mu$ 
8:   else
9:      $\mu_{\min} = \mu$ 
10:  end if
11: end while
12: Find the non-zero components in  $\alpha_{\text{resp}}$  to form the vector  $[\gamma_1, \dots, \gamma_K]$ 
13: Re-estimate the non-zero sparse coefficients: Find  $[\alpha_{\gamma_1}, \dots, \alpha_{\gamma_k}] \in \alpha_l$  that solves  $\arg \min_{\alpha} \|s_l - \sum_{k'=1}^k \alpha_{\gamma_{k'}} \Psi_{\gamma_{k'}}\|_2^2$ 
14: return  $\alpha_l$ 
```

Algorithm 5 Construction of the dictionary using the K-SVD algorithm.

Input: Matrix of selected ISRFs I , number of selected ISRFs L , size of the dictionary N_{obs} , Dictionary Φ obtained using SVD in Algorithm (2), sparsity parameter K

Output: New dictionary of ISRFs Φ .

```
1: while not convergence do
2:   Sparse coding step:  $x_l = \text{OMP}(I_l, \Phi, K) \forall l = 1, \dots, L$ 
3:   Dictionary update:
4:   for  $j = 1, \dots, N_{\text{obs}}$  do
5:     Define the group of examples that uses the j-th column of the dictionary j,  $w_j = \{l | 1 \leq l \leq N, x_T^j(l) \neq 0\}$ 
6:     Compute the overall representation error matrix,  $E_j = I - \sum_{i \neq j} \phi_i x_T^i$ 
7:     Build  $E_j^R$  from  $E_j$  using the columns corresponding to  $w_j$ 
8:     SVD decomposition  $[U, \Gamma, V^*] = \text{SVD}(E_j^R)$ 
9:     Update the dictionary column  $\phi_j$  as the first column of  $U$  and the vector  $x_R^j$  as the first column of  $V\Gamma(1, 1)$ .
10:  end for
11: end while
12: return  $\Phi$ 
```

Comment 4

The adaptation to calibration errors, and temporal drifts of the feature represent high potential perspectives for this work.

Response:

Thank you for this important suggestion. We are indeed planning to study how our method could be adapted to calibrations errors, and temporal drifts, and will elaborate on this in the Conclusions and Perspectives of the article.

References

- [1] R. Tibshirani, "Regression shrinkage and selection via the lasso," *Journal of the Royal Statistical Society (Series B)*, vol. 58, pp. 267–288, 1996.
- [2] M. Aharon, M. Elad, and A. Bruckstein, "K-SVD: An algorithm for designing overcomplete dictionaries for sparse representation," *IEEE Trans. Signal Process.*, vol. 54, no. 11, pp. 4311–4322, 2006.