



1 Monitoring European anthropogenic NOx emissions from space

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Abstract

Since the launch of TROPOMI on the S5p satellite, NO_2 observations have become available with a resolution of 3.5x5 km, which makes monitoring NO_x emissions possible at the scale of city districts and industrial facilities. For Europe, emissions are reported on an annual basis for country totals and large industrial facilities and made publicly available via the European Environmental Agency (EEA). Satellite observations can provide independent and more timely information on NOx emissions. A new version of the inversion algorithm DECSO (Daily Emissions Constraint by Satellite Observations) has been developed for deriving NOx emissions for Europe on a daily basis, averaged to monthly mean maps. The estimated precision of these monthly emissions is about 25% for individual grid cells. These satellite-derived emissions from DECSO have been compared to the officially reported European emissions and spatial-temporal disaggregated emission inventories. The country total DECSO NOx emissions are close to the reported emissions and the emissions compiled by the Copernicus Atmospheric Monitoring Service (CAMS). The comparison of the spatial distributed NOx emissions of DECSO and CAMS showed that the satellite-derived emissions are often higher in cities, while similar for large power plants and slightly lower in rural areas.

1. Introduction

Nitrogen oxides (NO_x) concentrations play an important role in air quality, the nitrogen cycle, and as precursor for climate gasses. Knowledge of NO_x emissions is also important for climate studies (Shindell et al., 2005). Because of the importance of NO_x for air quality, both the concentrations in air and emissions to air are regulated in Europe. Country total NO_x emissions

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need to be reported by EU countries as part of the Convention for Long-Range Transboundary Air Pollution (LRTAP, Pinterits et al., 2021) and the National Emission reductions Commitments (NEC) Directive (NEC, 2023) of the European Union. More detailed emission inventories including spatial distribution are compiled based on reported emissions, statistical information (e.g. population density) and activity data. Examples of these inventories on a global scale are the Emissions Database for Global Atmospheric Research (EDGAR, EC-JRC/PBL, 2011, Janssens-Maenhout et al., 2015) and the various global and regional emission inventories developed in the context of the Copernicus Atmosphere Monitoring Service (CAMS, Innes et al, 2019) of the EU Copernicus programme. These gridded emission inventories are widely used for global atmospheric composition and regional air quality modelling. The realism of the air quality model results depends largely on the accuracy of the emission inventory (Thunis et al, 2021). Since the availability of satellites capable of measuring NO2 concentrations in the atmosphere, methods have been developed to derive top-down emissions (Streets et al., 2013). These topdown emissions have the major advantage that they are observation based. This fully independent source of information provides the possibility to check reported emissions, monitor rapid changes (e.g. due to the COVID-19 lockdowns) and has the potential of finding unknown and unreported sources. Polar satellites with a global daily coverage within 1-3 days, allow monitoring of changes in emissions on timescales of days to weeks. Satellites measure total concentrations of trace gases, and the distinction of source sector type must be deduced via the source location. A popular inversion technique for NOx emissions is the divergence method of Beirle et al. (2021, 2023), where the average flux is calculated in grid cells, assuming local mass balance, to find the sources of the emissions. Although no model is needed in this method, the required spatial derivations lead to noisy fields for daily overpasses, and it provides useful emissions when averaged over a longer period. Furthermore, assumptions must be made for the chemical lifetime, and simplifications lead to biases especially in background emissions. A second class of methods is based on plume fitting (Fioletov et al., 2022). This method can be applied to individual overpasses but needs well-defined plume shapes which is not trivial for areas with multiple sources close together. Both these methods simplify atmospheric transport as two-dimensional. For a full three-dimensional description of transport and chemistry, a data assimilation or inverse modelling method is used to match





the model results and observations by adapting the emissions (Miyazaki et al., 2017, Fortems-61 62 Cheiney et al., 2021). A typical application of satellite-derived emissions is the study of the 63 impact of recent events, like for example the effect of COVID regulations (Ding et al., 2020). Top-down emissions are also used for the verification and support to improve current 64 emission inventories (Guevara et al., 2021; Crippa et al., 2023). Interesting aspects to study 65 more closely are the spatial distribution, seasonal time profiles and multi-annual trends of the 66 67 emissions. 68 In this study we present the latest version 6.3 of the Daily Emissions Constrained by Satellite 69 Observations DECSO (DECSO) inversion algorithm. The DECSO algorithm can be applied for 70 the operational monthly (or even daily) monitoring of emissions for any region worldwide 71 based on satellite observations of trace gases such as SO₂, NH₃ or NO₂. In this paper this new 72 DECSO version has been applied to NO₂ observations over Europe from the TROPOMI 73 instrument (Veefkind et al., 2012) on board the Sentinel-5P satellite. The DECSO system is 74 efficient, requires only a single forward run of the chemistry-transport model and takes about 75 12 hours to process one month of data on a 30-core computer. Here, we will evaluate the 76 performance of DECSO on various spatial scales (from national to point sources) by 77 comparison with the various bottom-up emission inventories available for Europe. By 78 comparing satellite derived emissions with bottom-up emissions we gain insight in the 79 accuracy of both derived emission datasets.

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2. Methodology and data

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2.1 DECSO: inversion of TROPOMI observations

The inversion algorithm DECSO (Daily Emissions Constrained by Satellite Observations) has been developed at KNMI for the purpose of deriving emissions for short-lived gases (Mijling and van der A, 2012). DECSO is using a Kalman Filter implementation for assimilating emissions. The emission forecast model is based on persistency from the analysis, while the concentrations are calculated from the emissions by a chemical transfer model (CTM) and compared to satellite observations. The sensitivity of concentrations to emissions is calculated





from multiple forward trajectories to account for the transport of the short-lived gas, but only 91 92 a single CTM forward run is needed. More detailed information on the method can be found 93 in Mijling and Van der A (2012), the validation is described in Ding et al. (2017a) and the previous latest published version, i.e. DECSO v5.2, is described in Ding et al. (2020). Recent 94 95 developments of the algorithm to improve its resolution and quality have led to the release 96 of version 6.3. The most important updates are the use of a recent version of the chemical 97 transport model, improved TROPOMI observations and changes in the sensitivity matrix 98 calculations. 99 The chemical transport model in DECSO has been upgraded to the latest version of the 100 Eulerian regional off-line CTM CHIMERE v2020r3 (Menut et al., 2021). The implementation of 101 CHIMERE in DECSO was described in Ding et al. (2017b). In this study CHIMERE is combined 102 with the Copernicus Landcover 2019 data (Buchhorn et al., 2020) and HTAP v3-2018 for the 103 source sector split of the emissions. The meteorological input data for CHIMERE are the 104 operational ECMWF weather forecasts. 105 The sensitivity matrix, giving the relationship between emissions and concentrations is based 106 on trajectories calculated with a high temporal resolution (maximum 7.5 minutes). In the new 107 version the relationship is limited to a range of maximum 150 km to avoid effects of errors in 108 the trajectories over longer distances. The default settings of DECSO described here are for a 109 grid resolution of 0.2 degree. For higher grid resolutions, the settings for temporal resolution 110 and maximum trajectory distance are increased and reduced respectively. The error parametrizations for the emission model and observations are based on the 111 112 Observation-minus-Forecast (OmF) and the Observation-minus-Analysis (OmA) statistics of previous runs. The latest version of DECSO can also be applied to the simultaneously 113 114 optimisation of emissions of NO_x and NH₃ (Ding et al., 2024). 115 We are using the latest version 2.4 reprocessed and offline TROPOMI NO2 observations (van 116 Geffen et al,2022b) converted to super-observations as described in Ding et al. (2020). The 117 TROPOMI tropospheric column and averaging kernels have been recomputed by combining 118 the TM5-MP retrieval a-priori model output with the data in the level-2 file. This results in a retrieved partial column from about 700 hPa (terrain following) to the surface. The 119 120 corresponding averaging kernels are rescaled using the 700hPa column air-mass factor and 121 are zero above the 700 hPa level. This procedure removes NO₂ in the free troposphere caused





122 by, for example, lightning or long-range transport, which is known to be a significant source of 123 error (Douros et al., 2023). 124 Superobservations (Sekiya et al., 2022) are constructed as the area-weighted mean of cloud-125 free (qa value > 0.75) TROPOMI observations over the CHIMERE model grid cells. For a grid of 0.2x0.2 degree a superobservation contains about 10 to 15 TROPOMI NO2 observations. The 126 127 use of superobservations improves the signal-to-noise ratio and it reduces the calculation time 128 of DECSO. On the other hand, the sampling of transported NO2 from the observations 129 calculated back to the source on the emission grid, based on superobservations, will slightly 130 spread out the derived emissions and reduce their spatial resolution compared to using 131 individual observations. The chosen size of the superobservation grid of 0.2x0.2 degree is 132 therefore a compromise between noise, calculation speed and spatial resolution. Knowing 133 that the smoothing of emissions after averaging can be imagined as a distribution by a pyramid 134 shape weighting function around a point source, a deconvolution is possible for isolated 135 emission sources with a known location. The current version of DECSO makes use of the 136 superobservations software as also used in Sekiya et al. 2022. The software has been further 137 developed focusing on a realistic description of the superobservation uncertainty (Rijsdijk et 138 al, 2024) and this new software will be used in future DECSO studies 139 In a post-processing step, the total monthly NO_x emissions are split into anthropogenic and 140 biogenic contributions. This is based on the assumption that biogenic emissions show a strong 141 seasonal cycle with low emissions in winter, while the anthropogenic emissions are more 142 constant over the year. This splitting method is detailed described in detail in Lin et al. (2023). 143 For the monthly emissions also the precision of the emission in each grid cell has been 144 calculated. Each daily NO_x emission per grid cell derived by DECSO is accompanied by a 145 standard deviation calculated according the Kalman Filter equations. As the starting point of 146 each daily step in the calculation by DECSO is the emissions of the previous day, the resulting 147 emissions will show an autocorrelation in their errors. For each grid cell the autocorrelation 148 function ρ_k (for time lag k) has been calculated for each month. We see typically that the 149 autocorrelation effects in the errors have disappeared completely after about 1 week. 150 When calculating the variance of the monthly mean values, we must take this autocorrelation 151 function into account. The variance S of the monthly mean NO_x emissions per grid cell is 152 calculated following Bayley and Hammersley (1946) or Box et al. (2008) as



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$$S = \frac{\sigma^2}{n} \left[1 + 2 \sum_{k=1}^{n-1} \left(1 - \frac{k}{n} \right) \rho_k \right] ,$$

where σ is the mean standard deviation of the emissions over the month and n is the number of days in the month. We assume here that σ is not varying a lot over the month. This precision σ is calculated in the Kalman equations of the inverse modelling and it depends on the precision of the TROPOMI NO₂ superobservations. The precision depends on the location and emission magnitude, but on average the precision is estimated as 8% for annual emissions, 25% for monthly emissions and between 10 and 60 % for the daily emissions.

In this study we will focus only on NO_x emissions. Although DECSO has been applied to many regions in the world, in this study we will show results for a domain over Europe (35°-55°N, 10° W-30°E) and for 0.2 degree spatial resolution. The temporal resolution of our inversion is daily, usually averaged to monthly or yearly mean values, for the period of 2019 to 2022. Figure 1 show the average annual emissions for 2019 as derived with DECSO version 6.3.

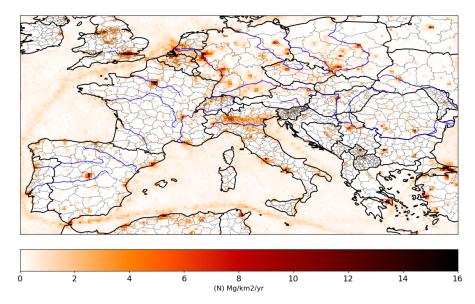


Figure 1 The annual-averaged anthropogenic NO_x emissions for 2019 derived from TROPOMI NO_2 observations using the DECSO algorithm.





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2.2 Databases for validation

For comparison of the emission results in Europe we will use several inventories, all based on official emissions reported to the European Environmental Agency (EEA). The first one is the inventory of national emissions per source category reported under the National Emission reductions Commitments (NEC) Directive of the European Union. Another similar inventory is the Emission inventory reported under the Convention on Long-range Transboundary Air Pollution (LRTAP), which give the country totals of emissions in various source categories. The last one we will use is the European Pollutant Release and Transfer Register (E-PRTR; EPRTR, 2012), which is a database of the individual emissions of the biggest industrial facilities (above 0.1Mg/year) in Europe. From here on we will call those databases simply NEC, LRTAP and E-PRTR. Besides comparison with these officially reported emissions, we will also compare our emissions to the regional anthropogenic emission inventory CAMS-REG-ANT v5.1 for air quality in Europe (Kuenen et al., 2022) developed for the Copernicus Atmospheric Monitoring Service (CAMS), hereafter called CAMS-REG. For these CAMS-REG emissions we use the total emissions regridded from 0.1° x 0.05° to 0.2°x0.2° and exclude the agricultural emissions, which are also excluded in DECSO. Temporal profiles are also derived in CAMS, which allow us to compare timeseries. We will use the Copernicus Atmosphere Monitoring Service TEMPOral profiles (CAMS-GLOB-TEMPO, Guevara et al., 2021,2023) for comparison of monthly variations in anthropogenic NO_x emissions. The global emission data version 5.3, called CAMS-GLOB-TEMPO, on a resolution of 0.1°x0.1° has been regridded to 0.2° x 0.2° resolution and is hereafter referred to as CAMS-TEMPO.

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3. Evaluation of the satellite derived emissions

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3.1 Country scale intercomparison

The NOx emissions derived with DECSO have been summed over the countries (weighted by the land-fraction per grid cell) in our domain and compared to the registered total emissions in NEC and LRTAP. Note that for the national total emissions the spatial resolution or spatial

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smoothing of the derived emissions play hardly any role. In total 21 countries are completely covered by our geographical domain and have reported their emissions. The total anthropogenic emissions (excluding agricultural emissions) for all these 21 countries are 1.44 Tg/year according both LRTAP and NEC. The total calculated anthropogenic emissions by DECSO are 1.54 Tg/year, about 7% higher than the reported emissions. The total anthropogenic emissions of CAMS-REG (excluding agricultural emissions) for the same region are 1.54 Tg/year, in agreement with DECSO. Note that the total soil emissions derived by DECSO are 0.78 Tg/yr for the same region, but this number cannot be compared because soil emissions in LRTAP and NEC are only given for the agricultural sector and not for forestry. The anthropogenic country totals are shown in Figure 2. In general, we see a good agreement per country except for Italy, which has much lower reported emissions. Greece, on the other hand, has higher registered emissions, but the mismatch might be related to the difficult counting over the Greek islands, since these emissions are weighted by the land fraction in the grid cell of DECSO to exclude maritime emissions in our counting. Note that Ireland is only partly in our geographical domain and has therefore lower emissions according to DECSO. Besides the comparison on a national level also on a provincial scale good agreement is found, as has been shown for Catalonia by Mijling et al. (2023).





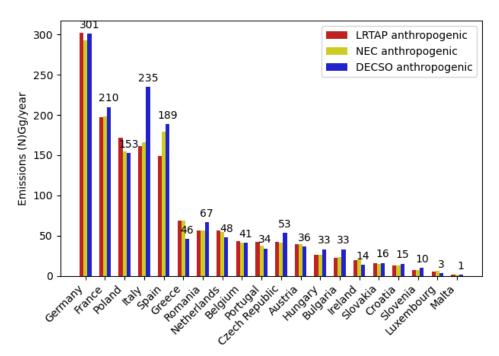


Figure 2 Country totals of anthropogenic NOx emissions (in (N)Gg/year) in the year 2019 according to databases LRTAP and NEC and the DECSO calculations.

3.2 City scale

With our current spatial resolution of 0.2x0.2 degree, we observe emissions per city district for mega cities, but the geographical distribution can be slightly blurred by the 0.2 degree resolution of the TROPOMI superobservations. Figure 3 shows the spatial distribution of the annual emissions of DECSO and CAMS-REG for three of the largest megacities in Europe: Madrid, Paris, and Rome. Although DECSO show similar emissions for the country totals, we see that for megacities DECSO estimates higher emissions in the city center, and more activities are seen in the region surrounding the city, as compared to the CAMS emissions. The industrial complexes at Rouen located north-west of Paris, and at the port of Civitavecchia located west of Rome are similar in DECSO compared to CAMS-REG. The area of Rouen used to have an active oil refinery, but in recent years the industrial emissions are about 0.11 (N)kg/km²/h according to the E-PRTR database, which compares well to CAMS-REG and





DECSO. The spatial extent of high emissions in the Rome area is smaller in CAMS, which follows more the population density. However, the densely populated center of Rome is surrounded by a busy ring road with a 20 km radius and a lot of commercial activities around the city, which are not reflected in the population density map. The two powerplants at Civitavecchia have reported emissions according to the E-PRTR database, which are equivalent to about 0.17 (N)kg/km²/h per grid cell, which is closer to the DECSO derived emissions. Although this study focuses mainly on the land emissions, we see in the map for Rome, that the maritime emissions of CAMS and DECSO disagree a lot, and this is a topic for further studies.

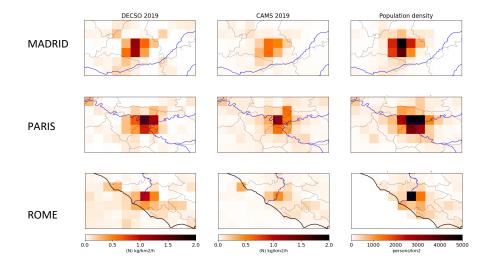


Figure 3 Zoom-in plots for 3 megacities in Europe to illustrate the differences in distribution of emissions of DECSO (first column), CAMS-REG (second column) and the population density (third column) per km².

Figure S1 in the supplement is an example of a timeseries for city emissions, in this case for the city of Paris. The time series show 3 low emission periods: in Nov. 2019 (reason unknown), in April 2020 when COVID hits Europe, and in the winter of 2020-2021 when strict COVID regulations were in place. After the recovery from COVID we see that emissions grow again in 2022 to the level of pre-COVID.





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3.3 Intercomparison for large point sources

To evaluate the performance of monitoring emissions from large point sources (LPS), we compare the DECSO emissions with emissions registered in the E-PRTR data base. The isolated LPS in Europe we selected are all large power plants close to lignite mines. Emissions from DECSO are slightly spread to adjacent grid cells because the spatial resolution of the emission field is less than the sampling of the grid cells as discussed in Sect. 2. To correct for this, we can deconvolute the emissions around the isolated point source, but here we choose to sum the anthropogenic emissions in the 3x3 grid cells including and around the point source to make sure all emissions are accounted for. For the four cases discussed below, no significant other sources exist in these 3x3 grid cell boxes, and biogenic emissions are excluded. The rural anthropogenic emissions in such an area of 3x3 grid cells in Europe we estimate as about 0.13 (N)Gg/year by averaging the emissions of several similar rural 3x3 regions in Europe. We did not correct for this background signal. The first case is that of the Maritsa Iztok facility in Bulgaria located next to an open coal mine. There is no big city or any other industrial facility in the neighborhood, except for the three big power plants of the Maritsa Iztok facility. Figure 4 shows the monthly averaged emissions calculated by the DECSO algorithm, the CAMS-TEMPO inventory, and the annual emissions from the E-PRTR database for the Maritsa facility. For a fair comparison we selected for CAMS-TEMPO also the same 3x3 grid cells around the LPS. For the period 2019-2022 the annual emissions are given in Table 1 according to DECSO, CAMS-TEMPO and E-PRTR. The difference in annual emissions between DECSO, CAMS-TEMPO and E-PRTR of the Maritsa facility are relatively small, although DECSO is the highest. The CAMS-TEMPO emissions show a negative trend, which is not visible in DECSO that shows the highest emissions for 2022. Unfortunately, no E-PRTR data for 2022 is yet publicly available. The second power plant is the Bełchatów power plant with its capacity of 5,053 MW, the biggest power plant of Europe. It is also one of the most polluting power plants in the world and gets its fuel from the adjacent lignite coal mine of Bełchatów (Guevara et al., 2023). For the year 2020 no emission values are reported in the current E-PRTR database. For the years 2019 and 2021 DECSO observes high emissions of about 5.5 Gg per year, but this is lower than

the reported value of more than 7 Gg per year. CAMS-TEMPO also shows lower emissions with





287 a negative trend. Godłowska et al. (2023) showed the stack measurements of this power plant 288 in their Figure 7, which also are in general lower than the E-PRTR values. The next selected isolated power plant is the Šoštanj lignite power plant in the Velenje basin 289 290 in a mountainous area of Slovenia. It is responsible for one third of the electricity need of 291 Slovenia (Boznar et al., 2012). For this LPS both CAMS-TEMPO and DECSO show more than 292 two times higher emissions than E-PRTR, which is too large to be explained by the small cities 293 or other small sources located in the neighborhood. 294 The last case is that of the power plants of the Ptolemais-Amyntheon and Florina coal basins 295 in West Macedonia, Greece, which were also studied by Skoulidou et al. (2021). There are 5 power plants associated with and located at this basin, but only three are still active: Agios 296 297 Dimitrios (1595 MW), Kardia (1200 MW), and Amyntheon (600 MW) (Kostakis, 2009). For 2021 no data was reported for Amynteon in the E-PRTR database. The reported values of the 298 299 E-PRTR database match those of CAMS-TEMPO and DECSO quite well, excep for the year 2020 300 that marks the start of a decrease in emissions in this region. The decreasing trend can be 301 seen in all three emissions time lines, but is strongest in the E-PRTR time series. Most notable 302 in the Figure is the strong seasonal cycle in DECSO NOx emissions for the Greek power plants 303 with the lowest emissions in summer time. This can related to the availabliity of more 304 sustainable energy sources in the summer months.





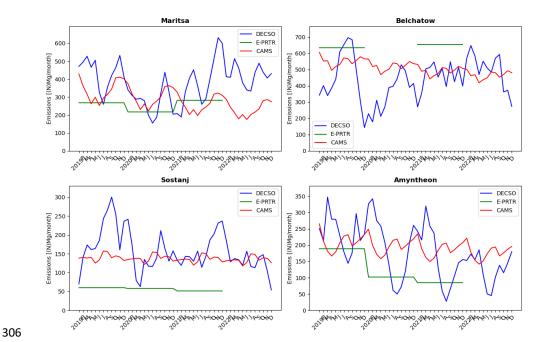


Figure 4 Timeseries of the NOx emissions of the selected LPS in Europe as estimated by DECSO (blue line), E-PRTR (green line) and CAMS-TEMPO (red line).

From this comparison for several large LPS in Europe, we see that CAMS-TEMPO and DECSO are often larger than the reported emissions in E-PRTR. The annual values of CAMS-TEMPO and DECSO are often in reasonable agreement (within 20%), but the variability of DECSO is much higher. The CAMS-TEMPO emissions in the period 2019 to 2022 show for most studied LPS a constant negative trend, which was generally not detected in DECSO. Without additional information it is difficult to draw any conclusions on the performance for LPS, but DECSO supplies additional information on these industrial facilities in Europe and the largest discrepancies may be caused by strong diurnal variability (while TROPOMI observes at about

In all cases we see lower emissions in 2020 during the COVID-19 pandemic. In this period the demand of energy was lower and while renewable energy output remained similar, the energy from lignite-based power plants was in relatively less demand (Quitzow et al., 2021).

13:30) and will be interesting for further investigation.





Table 1 Annual NOx emissions (N)Gg/year of the four lignite power plants.

	2019			2020			2021			2022		
Facility	CAMS	DECSO	E- PRTR									
Maritsa	4.1	5.2	3.2	3.6	3.3	2.6	3.2	4.6	3.4	2.8	5.0	-
Belchatow	6.6	5.5	7.6	6.3	4.3	-	5.9	5.4	7.9	5.6	6.0	-
Sostanj	1.7	2.4	0.69	1.7	1.7	0.66	1.6	1.9	0.62	1.5	1.3	-
Amyntheon	2.5	2.8	2.3	2.4	2.3	1.2	2.3	2.0	1.0	1.6	1.3	-

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4. Discussion

We presented the latest version of the DECSO algorithm, version 6.3. Updates has been made for the superobservations, the chemical transport model, the sensitivity matrix and the error parametrization. The new version includes also an error estimate for the monthly NOx emission data taking into account the autocorrelation in time. The new DECSO version has been applied to the domain of Europe and show more spatial details than before as a result of the higher resolution of TROPOMI observations compared to earlier satellite observations. In the comparison with CAMS-REG over Europe (where emissions are usually well-known) the deviations are small (within 10%) when looking at country scale. For point sources the spread in the differences is much higher, but no systematic effect is yet found. For cities DECSO show higher emissions, while CAMS is higher for rural regions. On a European scale the biggest difference between CAMS-REG and DECSO was found for the region West of Belgrade in Serbia, where the Nicola Tesla power plants are located. While these show up as a strong emission source close to Belgrade in both the DECSO emissions and the E-PRTR database, they are not included or mislocated in the CAMS emissions. This is a prominent example that demonstrates the value of monitoring emissions with satellite observations. The precision of the derived emissions by DECSO are given for each grid cell in the data files. In general, we can say that the precision of NO_x emissions given per grid cell (0.2x0.2 degree)

is about 8% for annual emissions, 25% for monthly emissions and between 10 and 60 % for





the daily emissions. When averaging over a larger domain the precision will of course become 345 346 higher by the square root of the number of grid cells. 347 The comparison between CAMS and DECSO showed that DECSO is very similar on average. 348 While compared to the reported emissions in NEC or LRTAP, DECSO is 7 % higher. Validation of the TROPOMI NO₂ observations showed that, when using averaging kernels, the bias of the 349 350 tropospheric column is estimated as -8% on average by comparison with MAX-DOAS 351 observations (Keppens and Lambert, 2023). This bias of -8% should result in lower emissions 352 by DECSO and the deviation between DECSO and other inventories would be higher in reality. 353 Keppens and Lambert further report that for polluted regions the mean bias of the TROPOMI 354 NO₂ observations is stronger, about -29%, while for clean areas the median bias is positive and 355 about +13% (when using averaging kernels). This would be contradictory to our findings over 356 cities, where DECSO shows higher emissions than CAMS-REG. Another potential cause of 357 biases in our emissions is the CHIMERE model. More research is needed for a better 358 understanding of the validation results of TROPOMI observations, CHIMERE performance, and 359 the comparisons between DECSO and CAMS. 360 This study shows the potential of DECSO for operational emission monitoring for Europe. The 361 monitoring of LPS only gives mainly clear results for isolated sources, thus an easy 362 improvement can be gained by providing the emissions on a higher resolution. DECSO has 363 already demonstrated its performance on a 0.1°x0.1° for the Yangtze River Delta (Zhang et al., 364 2023), West Siberia (van der A et al., 2020), Spain and the Netherland. 365 In this study the focus was on Europe, but in other regions of the world emissions might be 366 less well-known. For these regions DECSO can or has been applied since we have global 367 satellite observations. Recently we have applied DECSO to areas in Africa, where several mines with high NOx emissions were found that were unreported in bottom-up emission inventories 368 like EDGAR or CAMS. This shows the possibilities also for application of DECSO in the Global 369 370 South.

Data availability

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- 373 The TROPOMI NO2 data version 2.4 are available via the Copernicus website
- 374 https://dataspace.copernicus.eu/ and via the TEMIS website
- 375 https://www.temis.nl/airpollution/no2.php. The NOx emissions of DECSO v6.3 are available on the





376 GlobEmission website: https://www.temis.nl/emissions/region_europe/datapage_nox.php. The 377 European emissions data sets for countries NEC, LRTAP and large facilities E-PRTR are available on the 378 website https://www.eea.europa.eu/en/analysis of the EEA. The CAMS databases CAMS-REG-ANT 379 v5.1 and CAMS-GLOB-TEMPO v3.1 are available on the ECCAD website on respectively 380 https://permalink.aeris-data.fr/CAMS-REG-ANT and https://permalink.aeris-data.fr/CAMS-GLOB-381 TEMPO. 382 383 **Author contributions** 384 RA and JD made the improvements to DECSO, HE developed the superobservation code. RA 385 did the processing, visualisations and main writing. JD and HE reviewed and edited the 386 manuscript. 387 388 **Competing interests** 389 The authors declare that they have no conflict of interest. 390 391 Acknowledgments 392 This research was part of the Sentinel EO-based Emission and Deposition Service (SEEDS, 393 Grant ID 101004318) project that has received funding from the European Union's Horizon 394 2020 research and innovation programme. Sentinel-5 Precursor is a European Space Agency 395 (ESA) mission on behalf of the European Commission. The TROPOMI payload is a joint 396 development by ESA and the Netherlands Space Office. The Sentinel-5 Precursor ground segment development has been funded by ESA and with national contributions from the 397 Netherlands, Germany, and Belgium. This work contains modified Copernicus Sentinel-5P 398 399 TROPOMI data (2018–2023), processed locally at KNMI. 400 401 402 403 References





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