## **Decreasing trends of ammonia emissions over Europe seen**

- 2 from remote sensing and inverse modelling
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#### 16 Abstract

17 Ammonia (NH3), a significant precursor of particulate matter, not only affects 18 biodiversity, ecosystems, soil acidification, but also climate and human health. In addition, its 19 concentrations are constantly rising due to increasing feeding needs and the large use of 20 fertilization and animal farming. Despite the significance of ammonia, its emissions are 21 associated with large uncertainties, while its atmospheric abundance is difficult to measure. 22 Nowadays, satellite products can effectively measure ammonia with low uncertainty and a global coverage. Here, we use satellite observations of column ammonia in combination with 23 24 an inversion algorithm to derive ammonia emissions with a high resolution over Europe for the period 2013-2020. Ammonia emissions peak in Northern Europe, due to agricultural 25 26 application and livestock management, in Western Europe (industrial activity) and over Spain 27 (pig farming). Emissions have decreased by -26% since 2013 (from 5431 Gg in 2013 to 3994 28 Gg in 2020) showing that the abatement strategies adopted by the European Union have been 29 very efficient. The slight increase (+4.4%) in 2015 is also reproduced here and is attributed to 30 some European countries exceeding annual emission targets. Ammonia emissions are low in 31 winter (286 Gg) and peak in summer (563 Gg) and are dominated by the temperature dependent 32 volatilization of ammonia from the soil. The largest emission decreases were observed in 33 Central and Eastern Europe (-38%) and in Western Europe (-37%), while smaller decreases 34 were recorded in Northern (-17%) and Southern Europe (-7.6%). When complemented against 35 ground observations, modelled concentrations using the posterior emissions showed improved 36 statistics, also following the observed seasonal trends. The posterior emissions presented here 37 also agree well with respective estimates reported in the literature and inferred from bottom-up 38 and top-down methodologies. These results indicate that satellite measurements combined with 39 inverse algorithms constitute a robust tool for emission estimates and can infer the evolution of 40 ammonia emissions over large timescales.

## 42 **1** Introduction

43 Ammonia (NH<sub>3</sub>), the only alkaline gas in the atmosphere, constitutes one of the most 44 reactive nitrogen species. It is produced from decomposition of urea, which is a rapid process 45 when catalyzed by enzymes (Sigurdarson et al., 2018). The main sectors contributing to its 46 production are livestock management and wild animals (Behera et al., 2013), biomass burning and domestic coal combustion (Fowler et al., 2004; Sutton et al., 2008), volcanic eruptions 47 48 (Sutton et al., 2008), and agriculture (Erisman et al., 2007). Emissions from agricultural activity 49 and livestock management represent over 80% of the total emissions (Crippa et al., 2020), while 50 their regional contribution can reach 94% (Van Damme et al., 2018).

51 Once emitted, it is transported over short distances and deposited to water bodies, soil or 52 vegetation with a typical atmospheric lifetime of a few hours (Evangeliou et al., 2021). It can 53 then lead to eutrophication of water bodies (Stevens et al., 2010), modulate soil pH (Galloway 54 et al., 2003) and «burn» vegetation by pulling water from the leaves (Krupa, 2003). It also reacts 55 with the abundant atmospheric sulfuric and nitric acids (Malm, 2004) forming fine particulate 56 matter (PM2.5) (Tsimpidi et al., 2007). While ammonia has a short atmospheric lifetime, PM2.5 57 resides significantly longer in the atmosphere, on the order of days to weeks (Seinfeld and 58 Pandis, 2000), and hence is transported over longer distances. Accordingly, secondary PM2.5 59 can affect the Earth's radiative balance, both directly by scattering incoming radiation (Henze et al., 2012) and indirectly as cloud condensation nuclei (Abbatt et al., 2006). Its environmental 60 61 effects include visibility problems and contribution to haze formation. Finally, PM2.5 affects 62 human health, as it penetrates the human respiratory system and deposits in the lungs and alveolar regions (Pope and Dockery, 2006; Pope III et al., 2002) contributing to premature 63 64 mortality (Lelieveld et al., 2015).

65 To combat secondary pollution, the European Union established a set of measures focusing on ammonia abatement, similar to the ones introduced by China (Giannakis et al., 66 67 2019). These measures aim at reducing ammonia emissions by 6% in 2020, relative to 2005. 68 However, the lack of spatiotemporal measurements of ammonia over Europe makes any 69 assessment of the efficiency of these measures difficult, as only bottom-up methods are used to 70 calculate emission. These methods still show a slight increase  $(0.6\% \text{ y}^{-1})$  up to 2018 mostly due 71 to increasing agricultural activities (McDuffie et al., 2020). Such bottom-up approaches rely on 72 uncertain land-use data and emission factors that are not always up to date, thus adding large 73 errors to existing inventories.

74 During the last decade, satellite products have also become available to fill the gaps 75 created by spatially disconnected ground-based measurements. Data from satellite sounders 76 such as the Infrared Atmospheric Sounding Interferometer (IASI) (Van Damme et al., 2017), 77 the Atmospheric Infrared Sounder (AIRS) (Warner et al., 2017), the Cross-track Infrared 78 Sounder (CrIS) (Shephard and Cady-Pereira, 2015), the Tropospheric Emission Spectrometer 79 (TES) (Shephard et al., 2015), and Greenhouse Gases Observing Satellite (GOSAT) (Someya 80 et al., 2020) are publicly available. Most of them have been validated against ground-based 81 observations or complemented with other remote sensing products (Van Damme et al., 2015, 82 2018; Dammers et al., 2016, 2017, 2019; Kharol et al., 2018; Shephard et al., 2020; Whitburn 83 et al., 2016).

84 Accordingly, a few studies on ammonia emission calculations have been recently 85 published relying on 4D-Variational inversion schemes such as (Cao et al., 2022; Zhu et al., 86 2013) or process based models (Beaudor et al., 2023; Vira et al., 2020). More recently, Sitwell 87 et al. (2022) proposed an inversion scheme for comparison between model profiles and satellite 88 retrievals using hybrid logarithmic and linear observation operator that attempts to choose the 89 best method according to the particular situation. In the present study, we use direct 90 comparisons between the CrIS ammonia retrievals and model profiles using the Least Squares 91 with Adaptive Prior Covariance (LS-APC) algorithm (Tichý et al., 2016), which reduces the 92 number of tuning parameters in the method significantly using variational Bayesian 93 approximation technique. We constrain ammonia emissions over Europe over the 2013–2020 94 period and validate the results against ground-based observations from EMEP (European 95 Monitoring and Evaluation Programme, https://emep.int/mscw/) (Torseth et al., 2012).

## 96 2 Methods

### 97 **2.1** CrIS observations

98 To constrain ammonia emissions with inverse modelling, satellite measurements were 99 adopted from the Cross-Track Infrared Sounder (CrIS) onboard the NASA Suomi National 100 Polar-orbiting Partnership (S-NPP) satellite, which provides atmospheric soundings with a 101 spectral resolution of 0.625 cm<sup>-1</sup> (Shephard et al., 2015). CrIS presents improved vertical 102 sensitivity for ammonia closer to the surface due to the low spectral noise in the ammonia 103 spectral region (Zavyalov et al., 2013) and the early afternoon overpass that typically coincides 104 with high thermal contrast, which is optimal for thermal infrared sensitivity. The CrIS Fast 105 Physical Retrieval (CFPR) (Shephard and Cady-Pereira, 2015) retrieves ammonia profiles at

106 14 levels using a physics-based optimal estimation retrieval, which also provides the vertical 107 sensitivity (averaging kernels) and an estimate of the retrieval errors (error covariance matrices) 108 for each measurement. As peak sensitivity typically occurs in the boundary layer between 900 109 and 700 hPa (~ 1 to 3 km) (Shephard et al., 2020) and the surface and total column 110 concentrations are both highly correlated with these boundary layer retrieved levels. The total 111 column random measurement error is estimated in the 10-15% range, with total errors to be 112 ~30% (Shephard et al., 2020). The individual profile retrieval levels show an estimated random 113 measurement error of 10-30 %, with total random errors estimates increasing to 60 to 100% 114 due to the limited vertical resolution (1 degree of freedom of signal for CrIS ammonia). These 115 vertical sensitivity and error output parameters are also useful for using CrIS observations in 116 applications (e.g. data fusion, data assimilation; model-based emission inversions; (Cao et al., 117 2020; Li et al., 2019)), as a satellite observational operator can be generated in a robust manner. 118 The detection limit of CrIS measurements has been calculated down to 0.3-0.5 ppbv (Shephard 119 et al., 2020). CrIS ammonia has been evaluated against other observations over North America 120 with the Ammonia Monitoring Network (AMoN) (Kharol et al., 2018) and against ground-121 based Fourier transform infrared (FTIR) spectroscopic observations (Dammers et al., 2017) 122 showing small bias and high correlations.

Daily CrIS ammonia (version 1.6.3) was put on a 0.5°×0.5° grid covering all of Europe 123 124 (10°W-50°E, 25°N-75°N) for the period 2013-2020. Gridding was chosen due to the large 125 number of observations (around 10,000 retrievals per day per vertical level), which made the 126 calculation of source-receptor matrices (SRMs) computationally inefficient. Through gridding 127 we limited the number of observation (and thus the number of SRMs to be calculated) to 2000 128 per day per vertical level. Sitwell et al. (2022) showed that the averaging kernels of CrIS 129 ammonia are significant only for the lowest six levels (the upper eight have no influence onto 130 the satellite observations) and therefore we considered only these six vertical levels (~1018-131 619 hPa). The gridding was performed by averaging the values that fall in each 0.5° resolution grid-cell daily over the 2013 - 2020 period of this study. This type of gridding was selected as 132 133 previous experience with inverse distance weighting interpolation of satellite observations 134 showed overestimated results of up to 100% (Evangeliou et al., 2021). In addition, the quality 135 of gridding with respect to the averaging kernel of CrIS ammonia was evaluated by calculating 136 the standard deviation of the averaged values (Supplementary Figure S 1). The latter shows that 137 the kernel values within each grid-cell were very similar resulting in low gridded standard 138 deviations, and thus low bias caused from the gridding (Supplementary Figure S 1).

#### 139 **2.2** A priori emissions of ammonia

140 We used as a priori emissions for ammonia in the inversion algorithm the ones calculated (i) from the most recent version of ECLIPSEv6 (Evaluating the CLimate and Air Quality 141 142 ImPacts of Short-livEd Pollutants) (Klimont, 2022; Klimont et al., 2017) combined with 143 biomass burning emissions from GFEDv4 (Global Fire Emission Dataset) (Giglio et al., 2013) 144 hereafter "EC6G4", (ii) a more traditional dataset from ECLIPSEv5, GFEDv4 and GEIA 145 (Global Emissions InitiAtive), hereafter "EGG" (Bouwman et al., 1997; Giglio et al., 2013; 146 Klimont et al., 2017), (iii) emissions calculated from IASI (Infrared Atmospheric Sounding 147 Interferometer) and a 1-dimensional box-model and a modelled lifetime (Evangeliou et al., 148 2021), denoted as "NE" and (iv) from the high resolution dataset of Van Damme et al. (2018) 149 after applying a simple 1-dimensional box-model (Evangeliou et al., 2021), hereafter denoted as "VD". Given the large uncertainty in ammonia emissions illustrated in Figure 1, we 150 151 calculated the average of these four priors (hereafter "avgEENV") to establish the a priori 152 emissions used in this study.

## Lagrangian particle dispersion model for the calculation of source-receptor matrices (SRMs) of ammonia

SRMs were calculated for each 0.5°×0.5° grid-cell over Europe (10°W-50°E, 25°N-155 156 75°N) using the Lagrangian particle dispersion model FLEXPART version 10.4 (Pisso et al., 157 2019) adapted to simulate ammonia. The adaptation of the code includes treatment for the loss 158 processes of ammonia adopted from the Eulerian model LMDZ-OR-INCA (horizontal 159 resolution of 2.5°×1.3° and 39 hybrid vertical levels) that includes all atmospheric processes 160 and a state-of-the-art chemical scheme (Hauglustaine et al., 2004). The model accounts for 161 large-scale advection of tracers (Hourdin and Armengaud, 1999), deep convection (Emanuel, 162 1991), while turbulent mixing in the planetary boundary layer (PBL) is based on a local second-163 order closure formalism. The model simulates atmospheric transport of natural and 164 anthropogenic aerosols and accounts for emissions, transport (resolved and sub-grid scale), and 165 dry and wet deposition. LMDZ-OR-INCA includes a simple chemical scheme for the ammonia 166 cycle and nitrate particle formation, as well as a state-of-the-art CH<sub>4</sub>/NO<sub>x</sub>/CO/NMHC/O<sub>3</sub> 167 tropospheric photochemistry (Hauglustaine et al., 2014). To calculate chemical loss of 168 ammonia to PM2.5, after a month of spin-up, global atmospheric transport of ammonia was 169 simulated for 2013–2020 by nudging the winds of the 6-hourly ERA Interim Reanalysis data 170 (Dee et al., 2011) with a relaxation time of 10 days (Hourdin et al., 2006). Using the EGG 171 inventory, we calculated the e-folding lifetime of ammonia in the model, which was adopted in

FLEXPART. We refer the reader to (Tichý et al., 2022) for a detailed description of the
formalism. Atmospheric linearities of the system and a full validation against ground-based
observation are also presented in the same paper.

175 FLEXPART releases computational particles that are tracked backward in time using 176 ERA5 (Hersbach et al., 2020) assimilated meteorological analyses from the European Centre 177 for Medium-Range Weather Forecasts (ECMWF) with 137 vertical layers, a horizontal 178 resolution of 0.5°×0.5° and one hour temporal resolution. FLEXPART simulates turbulence 179 (Cassiani et al., 2014), unresolved mesoscale motions (Stohl et al., 2005) and includes a deep 180 convection scheme (Forster et al., 2007). SRMs were calculated for 7 days backward in time, 181 at temporal intervals that matched satellite measurements and at spatial resolution of 182 0.25°×0.25°. This 7-day backward tracking is sufficiently long to include almost all ammonia 183 sources that contribute to surface concentrations at the receptors given a typical atmospheric 184 lifetime of about half a day (Van Damme et al., 2018; Evangeliou et al., 2021).

#### 185 **2.4** Inverse modeling algorithm

186 The inversion method used in the present study relies on optimization of the difference 187 between the CrIS satellite vertical profile observations, denoted as  $v^{sat}$ , and retrieved vertical 188 profile,  $v^{ret}$ . The latter are obtained by applying an instrument operator applied in logarithm 189 space (Rodgers, 2000) as follows:

$$\ln(v^{ret}) = \ln(v^{a}) + A(\ln(v^{true}) - \ln(v^{a}))$$
(1)

191 where  $v^{ret}$  is the retrieved profile concentration vector,  $v^a$  is a priori profile concentration 192 vector used in the satellite retrievals,  $v^{true}$  is the hypothetical true profile concentration vector 193 supplied by the model ( $v^{true} = v^{mod}$ ), and *A* is the averaging kernel matrix (for each 194  $0.5^{\circ} \times 0.5^{\circ}$  resolution grid-cell). Eq. (1) provides a useful basis for the calculation of the CrIS 195 retrievals if the retrieval algorithm is performing as designed, i.e., it is unbiased and the root 196 mean square error (RMSE) is within the expected variability. The  $v^{mod}$  term can be written as: 197  $v^{mod} = Mx$  (2)

for each grid-cell of the spatial domain, where M is the grid-cell specific SRM calculated with FLEXPART and x is the unknown grid-cell specific emission vector. The SRM matrix M is calculated on circular surroundings around each grid-cell for computational efficiency. We chose circles with a radius of approximately 445 km, equal to 4 degrees, which is shown to be sufficient for reliable emission estimation and low sensitivity has been observed with this choice. Since the vector x is unknown, we replace it by a prior emission  $x^a$  (see section 2.2) in the initial step that is gradually refined iteratively based on the satellite observations. 205 The used inversion setup is based on iterative minimization of mismatch between  $v^{sat}$ 206 and  $v^{ret}$  updating (iteratively) the emission x such as below:

207  $\arg\min_{x^{a} \to x} \left| \left| v^{sat} - v^{ret} \right| \right|_{2}^{2} \qquad (3)$ 

208 for each grid-cell of computational domain. The minimization problem is solved in two steps.

First, we construct the linear inverse problem for each year where  $v^{ret}$  from the given surroundings, denoted here as *S*, forms the block-diagonal matrix  $v_S^{ret}$  while  $v^{sat}$  from the given surroundings form an associated observation vector  $v_S^{sat}$ . This forms the linear inverse problem:

213

 $v^{sat} = v_s^{ret} q_s \tag{4}$ 

where the vector  $q_s$  is a vector with coefficients denoting how  $x^a$  needs to be refined to obtain 214 215 emission estimate vector x. All elements in Eq. 4 are affected by uncertainties originating from 216 both the observations and model, hence, we employ an inverse algorithm to solve Eq. 4 with 217 added regularization in the form of prior distributions with specific covariance models. For one 218 year, 6 vertical profiles, and 4 degrees radius, the size of the the block-diagonal matrix  $v_S^{ret}$  is 219 13896 times 12, hence, the correction coefficient vector  $q_s$  contain 12 values corresponding to each month. We solve Eq. 4 using the least squares with adaptive prior covariance (LS-APC) 220 221 algorithm (Tichý et al., 2016). The algorithm is based on variational Bayesian methodology 222 assuming non-negative solution and favoring solution without abrupt changes and it minimizes 223 the use of manual tuning (Tichý et al., 2020). The method assumes the data model in the form 224 of:

225

$$p(v^{sat}) = N(v_S^{ret}q_S, R)$$
 (5)

where *N* denotes the multivariate normal distribution and *R* the covariance matrix assumed in the form  $R = \omega^{-1}I_p$ , where  $I_p$  is the identity matrix with ones on its diagonal and zeros elsewhere, and  $\omega$  is the unknown precision parameter on its diagonal. Following Bayesian methodology, we assign a prior model to all unknown parameters, i.e.  $\omega$  and  $q_s$ . Their prior models are selected as:

- 231  $p(\omega) = G(\vartheta_0, \rho_0) \quad (6)$
- 232

$$p(q_S) = tN(0, (LVL)^{-1}, [0, +\infty])$$
(7)

where  $G(\vartheta_0, \rho_0)$  is the Gamma distribution (conjugate to the normal distribution) with prior parameters  $\vartheta_0, \rho_0$  selected to  $10^{-10}$  achive non-informative prior. The second term follows truncated normal distribution with positive support and with specific form of a precision matrix. We assume the precision matrix in the form of modified Cholesky decomposition which allows for tractability of estimation of its parameters, matrices *V* and *L*. The matrix *V* is diagonal with 238 unknown diagonal parameters and the matrix *L* is lower bidiagonal with ones on the diagonal 239 and unknown parameters on its sub-diagonal, formalized as vectors *v* and *l*, respectively. 240 These parameters are estimated within the method, while purpose of vector *v* is to allow for 241 abrupt changes in  $q_s$ , and vector *l* to favor smooth estimates (see details in Tichý et al. (2016)). 242 All model parameters ( $\omega$ ,  $q_s$ , *v*, *l*) are estimated using the variational Bayes procedure where 243 we obtain not only point-estimates, but their full posterior distributions.

244 Second, the grid-cell specific coefficient vector  $q_s$  is propagated through Eq. 2 into Eq. 1 to refine a prior emission  $x^a$  and obtain estimated unknown emissions x. To maintain stability 245 of the method, we bound the ratio between prior and posterior emission elements to 0.01 and 246 247 100, respectively. This choice, motivated by Cao et al. (2020), omits unrealistically small or 248 high emissions, however, the bounds are large enough to allow for new sources, as well as for 249 attenuation of old sources. To introduce these boundaries is necessary since the problem in Eq. 250 1 is ill-conditioned and the propagation through the equation may lead to unrealistic values due 251 to numerical instability. For this reason, these boundaries are needed and the sensitivity to the 252 choice of the prior emission are studied in Section 3.3.

Note that CrIS data for some spatiotemporal elements are missing in the dataset. In these cases, we interpolated the missing data following the method proposed by D'Errico (2023), which solves a direct linear system of equations for missing elements, while the extrapolation behavior of the method is linear. Another strategy recently adopted in the literature has been to tackle the missing data using total variation methodology (see details in Fang et al., 2023); however, the method has been limited so far to its use on point-source release, hence we did not use it in this work.

### 260 **3 Results**

#### 261 **3.1** Emissions of ammonia in Europe (2013–2020)

262 We analyze the CrIS ammonia satellite observations for Europe (10°W–50°E, 25°N– 263 75°N) over the 2013-2020 period on monthly basis to derive ammonia emissions using the inverse modelling methodology described in Section 2.4. The inversion algorithm is applied to 264 265 each year of CrIS observations separately with the use of the avgEENV prior emission. Note 266 that since a diurnal cycle is neither assumed in the Chemistry Transport Model, nor exists in 267 the satellite observations from CrIS, daily emissions of ammonia do not represent a daily mean. 268 The overall resulting spatial distribution of the posterior emissions of ammonia (denoted 269 as posterior avgEENV) averaged for the whole period are displayed in Figure 2 (top-left). The 270 highest emissions occur in Northwestern Europe (including Northern Belgium, the Netherlands 271 and northwestern Germany) and to a smaller extent in the Po Valley (Italy), and the Ebro Valley 272 (Spain). Local maxima are also seen over Pulawy (Poland), South Romania and Kutina 273 (Croatia) due to industrial applications (Clarisse et al., 2019; Van Damme et al., 2018). While 274 ammonia emissions were not calculated high in the Po Valley (8 year average), it has been 275 reported that in Lombardy, about 90% of the ammonia emissions there have been reported to 276 originate from manure management (Lonati and Cernuschi, 2020). The Ebro Valley is 277 characterized by intensive agricultural activities (Lassaletta et al., 2012; Lecina et al., 2010) 278 and the Aragon and Catalonia regions by large pig farms (Van Damme et al., 2022). Finally, 279 both Belgium and The Netherlands are countries in which intensive livestock activity is 280 documented. It consists mostly of dairy cow, beef cattle, pig and chicken farming (Gilbert et 281 al., 2018; Lesschen et al., 2011; Velthof et al., 2012).

Figure 2 (top-right) shows the annual posterior emissions discretized monthly for the whole period (solid line) compared to prior ammonia emissions (dashed line), averaged for the domain. Higher emissions than the prior ones were calculated, which is not necessarily attributed to emission increases over Europe, but rather to miscalculation of emissions in the prior bottom-up inventories that were used. A strong seasonal cycle is also observed peaking in the middle of each year (summer) of the study period, but for several of these years, the characteristic bimodal cycle also appears with another peak in spring (Beaudor et al., 2023).

289 To examine more closely the seasonal variability of ammonia emissions in Europe, we 290 present the monthly posterior emissions of ammonia averaged for the whole study period 291 (2013-2020) at the bottom-left panel of Figure 2 together with the prior ones. The total 292 emissions for each month based on the map element size and length of the respective month 293 were averaged for the whole study period. The same was done for each year in the bottom-right 294 panel. The interannual variability over the period between 2013 and 2020, is also apparent in 295 the monthly box and whisker plots of the posterior emissions. In addition, the spatial 296 distribution of monthly ammonia emissions averaged for the eight-year period is given in 297 Supplementary Figure S 2. It appears that ammonia emissions are very low in wintertime (DJF average: 286 Gg) over Europe and increase towards summer (JJA average: 563 Gg), due to 298 299 temperature dependent volatilization of ammonia (Sutton et al., 2013), with the largest 300 emissions occurring in August (601 Gg). Although a clear peak of fertilization in early spring 301 is missing from the plot, emissions start to increase in early spring to peak in late-summer (Van 302 Damme et al., 2022) corresponding to the start and end of the fertilization periods in Europe 303 (Paulot et al., 2014). Fertilization is tightly regulated in Europe (Ge et al., 2020). It is only

allowed from February to mid-September in The Netherlands, while manure application is also
only allowed during the same period depending on the type of manure and the type of land (Van
Damme et al., 2022). In Belgium, nitrogen fertilizers are only allowed from mid-February to
the end of August (Van Damme et al., 2022), so as in Germany (restricted in winter months)
(Kuhn, 2017).

309 Finally, Figure 2 (bottom-right) shows the annual posterior emissions for the whole 310 period with the annual total emissions for each year. We observe a significant decrease in 311 ammonia posterior emissions over Europe during the 2013-2020 period. Emissions were 312 estimated as 5431 Gg for 2013 decreasing to 4890 Gg in 2014. A minor increase can be seen 313 in 2015 (5104 Gg), after which a significant decrease of 534 Gg (more than 10%) was estimated, 314 followed by the nearly constant plateau at the levels between 4383 Gg in 2017, 4323 Gg in 315 2019 and finally to 3994 Gg in 2020. The gradual decrease in ammonia emissions over Europe 316 since 2013 is also plotted spatially in Supplementary Figure S 3. It is evident that the restrictions 317 and measures adopted by the European Union to reduce secondary PM formation were 318 successful, as emissions in the hot-spot regions of Belgium, The Netherlands, Germany and 319 Poland declined drastically over time. However, an increase of +4.4% was observed in 2015. It 320 has been reported that ammonia emissions increased in 2015 and several European Union 321 Member States, as well as the EU as a whole, exceeded their respective ammonia emission 322 ceilings (EEA, 2017). The increase was reported to be +1.8% and was mainly caused by 323 increased emissions in Germany, Spain, France, and the United Kingdom. This was caused by 324 extensive use of inorganic nitrogen fertilizers (including urea application) in Germany, while 325 increased emissions in Spain were driven by an increase in the consumption of synthetic 326 nitrogen fertilizers and in the number of cattle and pigs (EEA, 2017). It should be mentioned 327 that a false decrease of ammonia in 2020 due to the COVID-19 pandemic is calculated by the 328 current methodology, mainly due to bias created by the decrease of  $NO_x$  and  $SO_2$  that are 329 precursor species of the atmospheric acids, with which ammonia reacts (see Tichý et al., 2022).

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#### 3.2 Country-by-country ammonia emissions

Posterior annual emissions of ammonia for 2013–2020 are plotted for four European regions (Western, Central and Eastern, Northern and Southern Europe), accompanied by relative trends calculated as difference between year 2013 and 2020 divided by the average for the whole period, in the left panel of Figure 3, while the estimated seasonal variation of each region is shown on the right panels averaged over the whole eight-year period. Western Europe includes Ireland, Austria, France, Germany, Belgium, Andorra, Luxembourg, The Netherlands, Switzerland, and United Kingdom; Central and Eastern Europe include Albania, Bosnia and
Herzegovina, Bulgaria, Czechia, Croatia, Hungary, Belarus, Slovakia, North Macedonia,
Montenegro, Poland, Romania, Moldova, Slovenia, Ukraine, and Serbia; Northern Europe is
defined by Denmark, Estonia, Finland, Latvia, Lithuania, Faroe Islands, Norway, and Sweden;
finally, Southern Europe includes Cyprus, Greece, Italy, Portugal, Spain.

342 The most significant decreases in ammonia emissions were estimated to be -38% in 343 Central and Eastern Europe and -37% in Western Europe, respectively. Quantitatively, Central 344 and Eastern Europe emissions were estimated to gradually drop from 2190 Gg in 2013 and to 345 1495 Gg in 2020 with a small increase in 2015 (2171 Gg) mainly because Germany, France 346 and the United Kingdom missed their emission targets (EEA, 2017). Western European 347 emissions of ammonia also declined constantly over time from 2041 Gg in 2013 to 1421 Gg in 348 2020. Smaller, yet significant, decreases were calculated over Northern Europe from 398 Gg in 349 2013 to 333 Gg in 2020 (-17%). Finally, Southern Europe exhibited a minor drop between years 350 2013 and 2014 (from 803 Gg in 2013 to 729 Gg in 2014) followed by a small increase until 351 2019 (from 729 to 803 Gg), and then decreased again in 2020 to 743 Gg. Overall, Southern 352 European emissions decreased by -7.62%.

353 The seasonal cycle of ammonia was again characterized by the restrictions applied to the 354 agricultural-related activities by the European Union member states (Figure 3, right panels). As 355 such, emissions in Western, Central and Eastern and Southern Europe were very low in winter 356 and started increasing when fertilization was allowed in early spring, whereas the increasing 357 temperature towards summer increased volatilization and, thus, emissions of ammonia (Van 358 Damme et al., 2022; Ge et al., 2020). Although much less marked than in other European 359 regions due to lower prevailing temperatures and weaker agricultural applications, emissions 360 in Northern Europe show the spring-summer temperature dependence. However, emissions 361 were estimated to be double in winter rather following the cycle of SO2 (Tang et al., 2020). 362 Emission may increase in Northern Europe in winter because OH and O3 concentrations are 363 much lower, and the rate of converting SO2 to sulfate much slower. This means that less sulfate 364 is produced and thus more NH3 stays in the gas form. Supplementary Figure S 4 shows prior 365 emissions in Western, Central and Eastern, Northern and Southern Europe for EC6G4 and NE 366 emission inventories. Both show the aforementioned increase in emissions during winter in 367 Northeastern Europe. Specifically, the NE emissions that dominate the a priori emissions 368 (avgEENV) as the highest inventory show an extreme winter peak in the north (emissions decline from 105 to 13 Gg). Therefore, there is a very strong dependence of the posterior 369

seasonality of ammonia in Northern Europe, which may be also influenced by the used prioremissions, see uncertainty analysis in Section 3.3.

372 Country specific emissions of posterior ammonia on a monthly basis (eight-year average 373 emissions) are shown for 20 countries in Supplementary Figure S 5. For countries such as 374 Portugal, Spain, Italy, United Kingdom, The Netherlands, Belgium, Poland, Hungary, 375 Denmark, Belarus and Romania two peaks can be clearly seen in late spring and end of summer. 376 As discussed before, these peaks coincide with the two main fertilization periods in Europe 377 (Paulot et al., 2014). However, it is expected that ammonia abundance is high throughout the 378 entire spring-summer period (e.g., Greece, France, Germany, Czechia, Ukraine and Bulgaria) 379 due to agricultural activity and temperature dependent volatilization (Sutton et al., 2013). 380 Ammonia emissions in Finland, Sweden and Norway are smaller than in the rest of Europe and 381 show a reverse seasonality.

#### **382 3.3** Uncertainties in ammonia's posterior emissions

For the calculation of uncertainty of the estimated posterior emissions two different approaches were used. The first approach is based on uncertainty arising as a result of the inversion methodology. The standard deviation is calculated from posterior estimate which is in the form of Gaussian distribution such as

(8).

387  $p_{\text{posterior}}(x_i) = N(\mu_i, \sigma_i^2)$ 

388 where *N* denotes normal (Gaussian) distribution and posterior parameters  $\mu_i$  and  $\sigma_i$  are results 389 of inversion for each element of the spatiotemporal domain. The uncertainty associated with 390 any given spatial element is then a property of Gaussian distribution defined with the square 391 root of summed squared standard deviations:

392 
$$\sigma_{\text{location}} = \sqrt{\sum_{t} \sigma_{\text{location},t}^2} \qquad (9)$$

Here,  $\sigma_{\text{location},t}^2$  denotes the estimated variance of the emissions for given coordinates and time period; we consider uncertainty calculated as  $2\sigma$  standard deviations, i.e. 95% of the values lay inside the interval with the center in the reported emissions surrounded by the reported uncertainty.

The second approach is based on ensemble of the used prior emissions as an input for the inversion. The different ensemble members are built from five prior emissions (see Figure 1) while the uncertainty is calculated as the standard deviation of five resulting posterior emissions. 401 The calculated posterior uncertainty for our spatial domain and studied period (2013-402 2020) is shown in Figure 4 for Gaussian posterior (left) and for ensemble of prior emissions 403 (right). The uncertainty associated with Gaussian posterior for each year of the study period are 404 depicted in Supplementary Figure S 6. The absolute uncertainty of Gaussian posterior ammonia emissions reaches a maximum of 23.3 ng m<sup>-2</sup> s<sup>-1</sup> or about 39% (relative value, calculated based 405 406 on related maximum of posterior emissions). The uncertainty based on prior ensemble reaches 407 a maximum of 60.2 ng m<sup>-2</sup> s<sup>-1</sup> which is equal to about 101% based on related maximum of posterior emissions. In general, the pattern of both posterior uncertainties, Gaussian posterior 408 409 and prior ensemble respectively, are in agreement in theirs patterns and follow the one of the 410 posterior emissions, with the highest values over (i) Belgium, the Netherlands, and Germany 411 due to livestock, farming, and agricultural activity; (ii) Poland, South Romania and Croatia due 412 to industrial applications; (iii) Catalonia due to pig farming; (iv) West France due to manure 413 application. Nevertheless, the obtained posterior uncertainty remains low, and this depicts the 414 robustness of the methodology used and the calculated posterior emissions of ammonia.

#### 415

#### 3.4 Validation of posterior emissions

416 As shown in Eq. 3 (Section 2.4), the inversion algorithm minimizes the difference between the satellite observations ( $v^{sat}$ ) and the retrieved ammonia concentrations ( $v^{ret}$ ). The 417 418 latter is a function of different satellite parameters (e.g., averaging kernel sensitivities) and 419 modelled ammonia concentrations using a prior dataset ( $v^{mod}$  or  $v^{true}$ ) as seen in Eq. 1. The 420 overall result is always propagated to  $v^{mod}$  iteratively, each time updating the prior emissions to obtain posterior ammonia. As specified in CrIS guidelines, modelled concentrations ( $v^{mod}$ ) 421 cannot be directly compared with satellite data ( $v^{sat}$ ), while comparing  $v^{sat}$  with  $v^{ret}$  is not a 422 423 proper validation method, because the comparison is performed for satellite observations that 424 were included in the inversion (dependent observations), and the inversion algorithm has been designed to reduce the  $v^{sat}$ - $v^{ret}$  mismatches. This means that the reduction of the posterior 425 retrieved concentration  $(v^{ret})$  mismatches to the observations  $(v^{sat})$  is determined by the 426 weighting that is given to the observations with respect to  $v^{ret}$ . A proper validation of the 427 428 posterior emissions is performed against observations that were not included in the inversion 429 (independent observations).

For these reasons, we compare modelled posterior concentrations of ammonia  $(v^{mod})$  at the surface with ground-based observations over Europe from the EMEP (European Monitoring and Evaluation Programme, <u>https://emep.int/mscw/</u>) network (Torseth et al., 2012). The measurements are open in public and can be retrieved from <u>https://ebas.nilu.no</u>. We used measurements for all years between 2013 and 2020 from an average of 53 stations with 2928
observations for each station covering all Europe (Supplementary Figure S 7). The comparison
is plotted for each of the 53 stations separately on a Taylor diagram in Figure 5. For all stations,
the Pearson's correlation coefficient increased for the posterior ammonia (coloured circles)
increased as compared to the prior one (coloured squares) reaching above 0.6 at several stations,
while the normalized root mean square error (nRMSE) and standard deviation were kept below
2 (unitless) and 2 µg m-3, respectively, in almost all stations (except SI0008 in Slovenia).

441 To further show how posterior emissions of ammonia affect modelled concentrations, we 442 chose six stations (DE0002 in Germany, NO0056 in South Norway, ES0009 in Spain, NL0091 443 in the Netherlands, HU0002 in Hungary and PL0005 in Poland) from the EMEP network 444 (highlighted in red in Supplementary Figure S 7), and we plot prior and posterior concentrations 445 against ground-based ammonia over time for the whole study period (2013-2020) in 446 Supplementary Figure S 8. Given the long period of plotting, we average observations every 447 week and modelled concentrations every month for a more visible representation of the 448 comparison. To evaluate the comparison, we calculate a number of statistic measures, namely 449 nRMSE, the normalized mean absolute error (nMAE) and the root mean squared logarithmic 450 error (RMSLE) as defined below:

451 
$$nRMSE = \frac{\sqrt{\sum_{i=1}^{n} \frac{1}{n} (m_i - o_i)^2}}{\frac{1}{n} \sum_{i=1}^{n} o_i} \qquad nMAE = \frac{\sum_{i=1}^{n} |m_i - o_i|}{\sum_{i=1}^{n} o_i}$$

452 
$$RMSLE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (\log m_i - \log o_i)^2}$$
(10)

453 where n is sample size, m and o the individual sample points for model concentrations and 454 observations of ammonia indexed with *i*. As one can see in Supplementary Figure S 8, all 455 statistics were improved in all six stations and posterior concentrations were closer to the 456 observations. However, individual peaks were in many cases misrepresented in the model. 457 Whether this is a result of the measurement technique or the fact that local sources cannot be 458 resolved at the spatiotemporal resolution of CTM and FLEXPART (given the short lifetime of 459 atmospheric ammonia) needs further research. The best results were obtained at station ES0009 460 (Spain), where model captures the seasonal variation of the observations during the whole study 461 period (2013–2020). In all other stations, the seasonality is maintained albeit steep peaks in the 462 observations are lost.

463 As explained in section 1, ammonia reacts with the available atmospheric acids producing 464 secondary aerosols (Seinfeld and Pandis, 2000). Therefore, its presence and lifetime in the 465 atmosphere is driven by the atmospheric acids and their precursors, SO2 and NO2. Changes in 466 atmospheric levels of these substances have a significant impact on the lifetime of ammonia 467 and its emissions, as highlighted in Tichý et al., (2022). Therefore, it is clear that a wrong 468 representation of trends in modelled SO2 and NO2 will lead to systematic biases in the 469 estimated ammonia emission trends. To further demonstrate that the modelling system correctly 470 represents the trends in SO2 and NO2, we compare ground-based observations of these two 471 species from the EMEP network (https://emep.int/mscw/) against modelled concentrations.

472 The comparison is shown in Supplementary Figure S 9 for six random EMEP stations for 473 different years for each of NO2 and SO2. The full comparison of the two datasets of 474 observations is plotted in scatterplots of modelled versus measured surface concentrations for 475 NO2 and SO2 for all the study period (2013-2020) in Supplementary Figure S 10. A total 476 number of 3,368,660 for SO2 and 4,252,592 for NO2 was used in the validation. It is evident 477 that the seasonal variation of the modelled surface concentrations and their magnitude are both 478 represented very well in the model for NO2 and SO2. nRMSE was 0.12 - 0.19 for NO2 and 479 0.09 - 0.25 for SO2, nMAE 0.39 - 0.94 for NO2 and 0.48 - 1.2 for SO2, RMSLE was 0.25 -480 0.49 for NO2 and 0.11 - 0.33 for SO2 in the six stations (Supplementary Figure S 9). For over 481 4.2 and 3.3 million measurements that were used in this validation of NO2 and SO2 482 concentrations for 2013 - 2020 study period, nRMSE values were 0.05 and 0.02, nMAE 0.74 483 and 1.0 and RMSLE 0.50 and 0.40 for NO2 and SO2, respectively (Supplementary Figure S 484 10).

## 485 4 Discussion

#### 486 **4.1** Comparison with emissions inferred from satellite observations

487 We compared our posterior estimates with two recently published studies on ammonia 488 emission in Europe (Cao et al., 2022; Luo et al., 2022). Luo et al. (2022) used IASI observations 489 for the period 2008 to 2018 to estimate ammonia emissions in a global domain. Their method 490 was based on updating prior emissions with correction terms computed using differences 491 between observed and simulated ammonia columns combined with calculated ammonia 492 lifetimes. The key indicators calculated for the European domain in Luo et al. (2022) are a 493 linear trend for the 2008–2018 period, average annual emissions, and relative trends. Note that 494 we compare our eight-year period with a decade in Luo et al. (2022). The comparison is 495 depicted in Figure 6. Our estimates (Figure 6, left panel) are in good agreement with those 496 calculated by Luo et al. (2022). The linear trend was estimated as -1.27 Tg for the period by 497 Luo et al. (2022), while our estimate is -1.44 Tg. The spatial distribution of the trend is also 498 given in Figure 6 (left panel). The key decrease is observed mainly in France, Germany, and 499 middle Europe, while the increasing trend is observed mostly in Spain, parts of Italy, and 500 Greece. The average annual ammonia emission for the European domain in Luo et al. (2022) 501 was estimated to be 5.05 Tg while our estimate is 4.63 Tg. Our lower estimate (by 502 approximately 8%) might be attributed to use of a more recent period considered in our study, 503 but both methods agree that the trend in Europe is negative. The relative decrease estimated by 504 Luo et al. (2022) is -25.1%, while we calculate -31.02%, which is again in very good agreement. 505 Cao et al. (2022) used CrIS observations for the year 2016 in order to estimate ammonia 506 emissions for 25 European Union members (EU25), namely Austria, Belgium, Bulgaria, 507 Croatia, Republic of Cyprus, Czech Republic, Denmark, Estonia, France, Germany, Greece, 508 Hungary, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Poland, Portugal, 509 Romania, Slovakia, Slovenia, and Spain. The method was tested with uni-directional and bi-510 directional flux schemes. The uni-directional dry deposition scheme assumes only air to surface 511 exchange of ammonia ignoring changes in environmental conditions, while the bi-directional 512 scheme captures dynamics in measured ammonia fluxes. Total estimated ammonia emissions 513 for the EU25 region by the uni-directional scheme (posterior uni) and the bi-directional scheme 514 (posterior bi) were reported as 3534 Gg N y-1 and 2850 Gg N y-1, respectively. The 515 posterior bi estimate is very close to our estimate for EU25 for the year 2016, which is 2712 516 Gg N y-1, while the posterior uni is approximately 30% higher. A uni-directional dry 517 deposition scheme ignores the impacts of changes in environmental conditions (e.g., soil 518 temperature, soil wetness, soil pH, fertilized condition, and vegetation type) on ammonia 519 emissions from fertilized soil and crops (volatilization), which likely lead to high biases in top-520 down estimates. Ammonia in LMDz-OR-INCA model, that was used to capture ammonia's 521 losses, resembles a partially bi-directional treatment, where emissions and deposition are both 522 possible at the same time without any use of a compensation point; this may explain this 30% 523 difference.

524 The detailed EU25 emissions for the year 2016 are displayed in Figure 6 (right panel) for 525 posterior uni (red), posterior bi (yellow), our post avgEENV (blue), and priors used by Cao 526 et al. (2022) and in our study (dashed red and blue, respectively). As seen from Figure 6, our 527 posterior estimates (post avgEENV) have more similar characteristics with posterior bi, with 528 monthly difference to be less than factor of 2 positive or negative from Cao et al. (2022). Note 529 that the posterior uni estimates are always a factor of 3 higher than our posterior estimates for 530 ammonia emissions. The main differences can be observed during February-March and 531 October-November periods where our estimates are generally lower than those from Cao et al. 532 (2022). Finally, Cao et al. (2022) reported more of a springtime peak likely associated with
533 crop fertilization, whereas in this study the peak is towards the warmer season (volatilization)
534 due to livestock sources.

#### 535 **4.2** Assessment of ammonia's atmospheric linearities

Ammonia is a particularly interesting substance due to its affinity to react with atmospheric acids producing secondary aerosols. In most cases, it is depleted by sulfuric and nitric acids. However, when relative humidity is high and particles are aqueous, sulfate reacts with ammonia and decreases, while the equilibrium vapor pressure of ammonia with nitric acid increases shifting the reaction towards production of free ammonia (Seinfeld and Pandis, 2000). The former reaction is a rare event and lots of prerequisites must be fulfilled to take place.

542 Supplementary Figure S 11a shows the frequency distribution of gain (production of free 543 ammonia - negative numbers) or loss (production of sulphate/nitrate - positive numbers) due 544 to all chemical processes in the inversion domain (10°W-50°E, 25°N-75°N), for the study 545 period (2013 – 2020) and the lowest six sigma-p vertical levels (~1018-619 hPa, see averaging 546 kernels in section 2.1) (Sitwell and Shephard, 2021). The figure shows mostly positive numbers 547 indicating that atmospheric ammonia reacts towards secondary aerosol formation. The spatial 548 distribution of gain/loss of ammonia is shown in Supplementary Figure S 11b. The pixels 549 indicating production of gaseous ammonia are located in marine regions, where we chose to 550 not perform inversions, as they are an order of magnitude lower (Bouwman et al., 1997), thus 551 less significant. No continental pixels showing gain of ammonia were detected, which would 552 cause simulated backwards in time to fail with our Lagrangian model (see next paragraph). Our 553 approximation, although simplistic, provides computational efficiency when simulating SRMs 554 in backward mode using FLEXPART (Pisso et al., 2019).

Seibert and Frank (2004) reported that standard Lagrangian particle dispersion models cannot simulate non-linear chemical reactions. First-order chemical reactions, where the reaction rates can be prescribed, are also linear. Non-linear chemistry cannot be calculated because neither the background chemistry is modeled nor is the coupling of the tracked plume (forward or backward) to this background. Technically, the SRM in FLEXPART is calculated for a receptor with a certain mean mixing ratio ( $\chi$ ) and an emitting source ( $q_{i,n}$ ) in a certain discretization of the space (index *i*) and time (index *n*), as:

562 
$$\frac{\chi}{q_{i,n}} = \frac{1}{J} \sum_{j=1}^{J} \Delta t_{i,j,n} \frac{p_{j,n}}{\rho_{i,n}}$$
(11)

563 where J is the total number of backward trajectories (particles index j) originating from the 564 position of the receptor  $\chi$  and ending at a certain discretized time (index n) in certain 565 discretized space position (index i) for a time interval  $\Delta t_{i,j,n}$ , and where the air density is  $\rho_{i,n}$ . 566 The further function  $p_{j,n}$  ( $p_{j,n} \le 1$ ) represents the relative (to the initial receptor state) decay 567 of the mass value in the particle in its travel from the receptor to the discretized space time 568 interval (j, n) due to any linear decay process (e.g. deposition, linear chemical decay) for a perfectly conserved scalar  $p_{j,n} = 1$ . So, for linear decaying species a direct SRM can be 569 570 calculated explicitly among all relevant receptor points and all positions in space and time. The 571 existence of the SRM (H), linking directly mixing ratios at the receptor points with emissions, 572 is the prerequisite to apply simple inversion algorithms, such as the one in the present study.

573 Inversion of observations to obtain emissions for non-linear chemically reactive species 574 entails the need of a chemistry transport model (CTM) forward (and its adjoint backward) in 575 time from time  $t_0$  to time  $t_{\square}$  evolving the full state of the atmosphere, in relation to the emissions and boundary conditions. Subsequently, a cost function is evaluated by an iterative 576 577 descent gradient method that implies running the adjoint of the forward model (Fortems-578 Cheiney et al., 2021). Note that an iterative algorithm means that the forward and adjoint 579 models run several times in sequence until the estimated minimum of the cost function is 580 reached.

581 To overcome these complexities, we examine the linearities of our method and show that 582 FLEXPART simulates ammonia efficiently, we evaluate modelled ammonia against ground-583 based measurements of ammonia from EMEP (https://emep.int/mscw/) in Europe, EANET (East Asia acid deposition NETwork) in Southeastern Asia (https://www.eanet.asia/) and 584 585 AMoN (Ammonia Monitoring Network in the US, AMoN-US; National Air Pollution 586 Surveillance Program (NAPS) sites in Canada) in North America (http://nadp.slh.wisc.edu/data/AMoN/). The SRMs for ammonia express the emission 587 588 sensitivity (in seconds) and yield modelled concentrations at the receptor point when coupled 589 with gridded emissions from EGG (in kg m-2 s-1, see section 2.2) at the lowest model level 590 (100 m). To check the consistency of the proxy used in the SRMs of ammonia, we also 591 simulated surface concentrations of ammonia with FLEXPART in forward mode using the 592 same emissions (EGG). We have chosen two random ground-based stations from each of the 593 three measuring networks (EMEP, EANET, AMoN) to compare modelled concentrations. For 594 consistency, we also plot the resulting surface concentrations from the LMDz-OR-INCA model 595 (Supplementary Figure S 12).

596 Modelled concentrations (forward and backward FLEXPART and the CTM LMDz-OR-597 INCA) at each station have been averaged to the temporal resolution of the observations. 598 Supplementary Figure S 13 shows Taylor diagrams of the comparison between FLEXPART 599 simulated concentration in forward and backward mode. Plotting backward versus forward 600 results is a common procedure to infer whether a Lagrangian model produces reasonable results 601 (Eckhardt et al., 2017; Pisso et al., 2019). In general, the forward and backward simulations 602 show very good agreement for the depicted receptor points. For example, ammonia concentration at stations AL99, CA83, and VNA001 (Supplementary Figure S 12) are 603 604 simulated similarly, and the mean concentrations are almost identical in the forward and 605 backward modes. However, during some episodes there can be notable differences (e.g., at 606 DE0002R) as seen before (Eckhardt et al., 2017). The main reason is that the backward 607 calculations always give more accurate results as the number of particles released at the receptor 608 is much higher in backward mode than in forward mode; the particles are targeted to a very 609 small location in backward, whereas in forward mode the particles are distributed equally on a 610 global scale and therefore less particles represent each receptor location. Another reason is that 611 transport and especially turbulent processes are parametrized by random motion, which are 612 different for each FLEXPART simulation. Finally, the coordinate system for defining the height 613 layer above ground depends on the meteorological field which is read at the start of the 614 simulation, and this can also cause small deviations. The Taylor diagram for the respective 615 comparison (Supplementary Figure S 13) show high Pearson's correlation coefficients (>0.7), 616 low standard deviations (<1 µg N m-3) and root means square errors (RMSEs <0.7 µg N m-3). 617

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#### 618 **4.3** Limitations of the present study

619 The latest Commission Third Clean Air Outlook published in December 2022 (EC, 2022), 620 which is based on data reported by the EEA (https://www.eea.europa.eu/data-and-621 maps/dashboards/necd-directive-data-viewer-7), concluded (p. 2) that emissions of ammonia 622 in recent years remain worryingly flat or may have increased for some member states. The 623 assessment covers the period we investigated in the present manuscript (2013 - 2020) and 624 shows (for the EU27) a reduction in ammonia emissions of only 2% that is far smaller than that 625 we calculated here (26%). The consistency of our results with those calculated with similar 626 methodologies (Cao et al., 2022; Luo et al., 2022) urges us to believe that such differences in 627 ammonia trends are the result of differences between bottom-up and top-down methodologies.

Another reason for the difference in emissions between EC (2022) and this study might be the fact that we used both nigh- and day-time CrIS observations. The night-time observations use the exact same retrieval approach as the day-time ones. Any unknown bias would only be present, if atmospheric conditions are such that it makes the retrievals more challenging during night overpasses (e.g., thermal inversions causing an radiative emission layer at the surface, etc.). Note that CrIS night-time observations have not been validated yet.

634 CrIS ammonia retrievals are performed in the logarithmic space and are expressed by Eq. 635 (1). When solving the cost function in the inverse modelling algorithm, we minimize the modelobservation mismatches, which in the present case is  $v^{ret}$  (calculated using modelled 636 concentrations,  $v^{true} = v^{mod}$ , in Eq. (1) after applying prior emissions) with the CrIS 637 observations,  $v^{sat}$ . Then, iteratively, the algorithm updates  $v^{mod}$  to calculate the posterior 638 639 emissions through Eq.(1). The logarithmic nature of Eq.(1) causes (i) the optimization of the modelled concentrations ( $v^{mod}$ ) to be tiny, and (ii) the trend of the posterior emissions to have 640 641 a very large dependency of the prior column used in CrIS ( $v^a$ ). The latter is shown very clearly 642 in Figure 2 (lower right).

## 643 **5 Conclusions**

644 Today, a large debate takes place about ammonia abatement strategies for Europe, but 645 also for Southeastern Asia, in an effort to reduce secondary formation and, thus, mitigate 646 climate crisis (van Vuuren et al., 2015). These strategies include (a) low nitrogen feed by 647 reducing ammonia emissions at many stages of manure management, from excretion in 648 housing, through storage of manure to application on land, also having positive effects on 649 animal health and indoor climate (Montalvo et al., 2015); (b) low emission livestock housing, 650 which focuses on reducing the surface and time manure is exposed to air by adopting rules and 651 regulations regarding new livestock houses (Poteko et al., 2019); (c) air purification by 652 adopting technologies to clean exhaust air from livestock buildings (Cao et al., 2023) and 653 others. Here we used satellite observations from CrIS and a novel inverse modelling algorithm 654 to study the spatial variability and seasonality of ammonia emissions over Europe. We then 655 evaluated the overall impact of such strategies on the emissions of ammonia for the period 656 2013–2020. The main key messages can be summarized below:

The highest emissions over the 2013–2020 study period occur in North Europe (Belgium,
 the Netherlands and northwestern Germany). At a regional scale, peaks are seen in Western
 Europe (Poland, South Romania and Croatia) due to industrial activities, in Spain (Ebro

Valley, Aragon, Catalonia) due to agricultural activities and farming, in Belgium and The
Netherlands due to livestock activity (dairy cow, beef cattle, pig and chicken farming).

- Ammonia emissions are low in winter (average: 286 Gg) and peak in summer (average:
   563 Gg), due to temperature dependent volatilization of ammonia, while a notable peak
   attributed to fertilization can be seen in early spring during some years.
- Over the 2013–2020 period, European emissions of ammonia decreased from 5431 Gg in
   2013 to 3994 Gg in 2020 or about -26%. Hence, the restrictions adopted by the European
   Union members were effective in reducing secondary PM formation.
- A slight emission increase of +4.4% in 2015 appears for several European Union Member
   States (Germany, Spain, France, and the United Kingdom) who exceeded the respective
   ammonia emission targets. Part of the 2020 ammonia decrease might be attributable to the
   COVID-19 pandemic restrictions.
- The largest decreases in ammonia emissions were observed in Central and Eastern Europe
  (-38%, 2190 Gg in 2013 to 1495 Gg in 2020) and in Western Europe (-37%, 2041 Gg in
  2013 to 1421 Gg in 2020). Smaller decreases were calculated in Northern Europe (-17%,
  398 Gg in 2013 to 333 Gg in 2020) and Southern Europe (-7.6%, from 803 Gg in 2013 to
  to 743 Gg in 2020).
- The maximum calculated absolute uncertainty of Gaussian posterior model was 23.3 ng m<sup>-</sup>
   <sup>2</sup> s<sup>-1</sup>, or about 39% (relative value) and calculated maximum based ensemble of prior
   emissions was 60.2 ng m<sup>-2</sup> s<sup>-1</sup>, or about 101% following the spatial distribution of the
   posterior emissions.
- Comparison of the concentrations calculated with prior and posterior ammonia emissions against independent (not used in the inversion algorithm) observations showed improved correlation coefficients and low nRMSEs and standard deviations. Looking at timeseries of six randomly selected stations in Europe, we also found that posterior surface concentrations of ammonia were in accordance with the ground-based measurement, also following the observed seasonal trends.
- Our results agree very well with those from Luo et al. (2022) (decreasing trend: -1.44 versus -1.27 Tg, annual European emissions: 4.63 versus 5.05 Tg) and those from Cao et al. (2022) following their methodology (their posterior\_bi estimate for EU25 and year 2016 was 2850 Gg N y-1, while we calculate 2712 Gg N y-1).

691 The relatively low posterior uncertainty and improved statistics in the validation of the 692 posterior surface concentrations denote the robustness of the posterior emissions of 693 ammonia calculated with satellite measurements and our adapted inverse framework.

694

695 Data availability. The data generated for the present paper can be downloaded from ZENODO 696 (https://doi.org/10.5281/zenodo.7646462). FLEXPARTv10.4 is open access and can be 697 downloaded from https://www.flexpart.eu/downloads, while use of ERA5 data is free of 698 charge, worldwide, non-exclusive, royalty-free and perpetual. The inversion algorithm LS-APC 699 is open access from https://www.utia.cas.cz/linear inversion methods. CrIS ammonia can be 700 obtained by request to Dr. M. Shephard (Mark.Shephard@ec.gc.ca). EMEP measurements are 701 open in https://ebas.nilu.no. FLEXPART SRMs for 2013-2020 can be obtained from the 702 corresponding author upon request.

703

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705

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715 Author contributions. O.T. adapted the inversion algorithm, performed the calculations, 716 analyses and wrote the paper. S.E. adapted FLEXPARTv10.4 to model ammonia chemical loss. 717 Y.B. and D.H. set up the CTM model and performed the simulation, the output of which was 718 used as input in FLEXPART. N.E. performed the FLEXPART simulations, contributed to 719 analyses, wrote and coordinated the paper. All authors contributed to the final version of the 720 manuscript.

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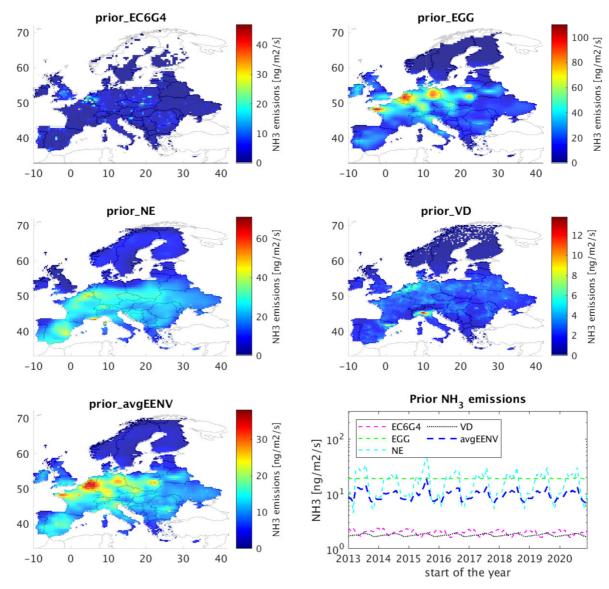
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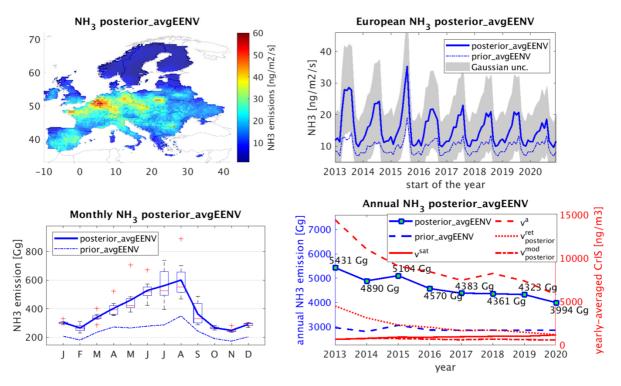
## 1075 FIGURES & LEGENDS



1076

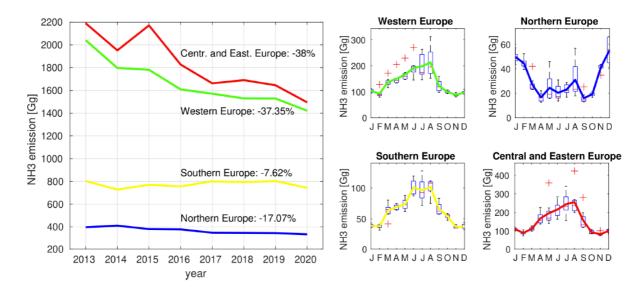
1077 Figure 1. Four ammonia prior emissions (EC6G4, EGG, NE, VD) are displayed in the first two

rows. The combined prior (avgEENV) is displayed in the bottom left. The temporal variabilityof all five prior emissions is given in bottom right.



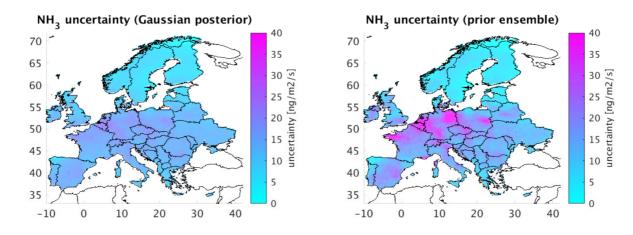


1082 Figure 2. The spatial distribution of posterior ammonia emissions (posterior EENV, top-left) 1083 together with its temporal distribution (top-right). The Gaussian uncertainty of the posterior 1084 emissions is also plotted. Monthly average ammonia emissions are shown in bottom-left graph. 1085 The monthly average posterior emissions over the studied period are accompanied by the box 1086 plot where the red line indicates the median, the bottom and top edges of the Boxes indicating the 25<sup>th</sup> and 75<sup>th</sup> percentiles, respectively, and the whiskers extend to the most extreme data 1087 points not considered as outliers, which are denoted using red crosses. Solid blue lines refer to 1088 1089 the posterior ammonia emissions, while dashed ones to the prior emissions (avgEENV). 1090 Finally, annual average ammonia emissions are also plotted (bottom-right). Except for the 1091 annual average emission dosages that are shown in blue, we also depict the elements that were used to calculate  $v_{posterior}^{ret}$ , namely  $v^a$  and  $v_{posterior}^{mod}$  (see Eq. 1) that were compared with 1092 vsat. 1093



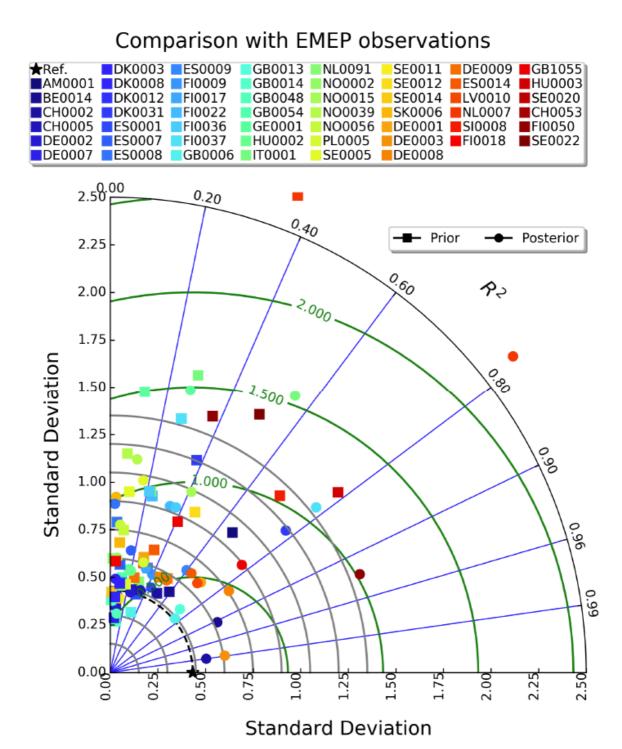
**Figure 3.** Left: Annual posterior emissions of ammonia in Southern (yellow), Western (green), Northern (blue), and Central and Eastern (red) Europe. Right: Monthly average posterior emissions of ammonia accompanied by box plots, where the red line indicates the median, the bottom and top edges of the box indicate the 25<sup>th</sup> and 75<sup>th</sup> percentiles, respectively, and the whiskers extend to the most extreme data points (not considered outliers), which are represented using red crosses.

1102



**Figure 4.** Absolute uncertainty of posterior emissions of ammonia calculated as  $2\sigma$  (left 1105 panel) and from a member ensemble (right panel) comprising posterior emissions calculated

1106 with five different priors (Figure 1) averaged for the whole study period 2013–2020.



1108

**Figure 5.** Modelled concentrations of ammonia with prior and posterior emissions against ground-based observations from 53 EMEP stations for 2013–2020 presented in a Taylor diagram. The diagram shows the Pearson's correlation coefficient (gauging similarity in pattern between the modelled and observed concentrations) that is related to the azimuthal angle (blue contours); the standard deviation of modelled concentrations of ammonia is proportional to the radial distance from the origin (black contours) and the centered normalized RMSE of modelled concentrations is proportional to the distance from the reference standard deviation (green

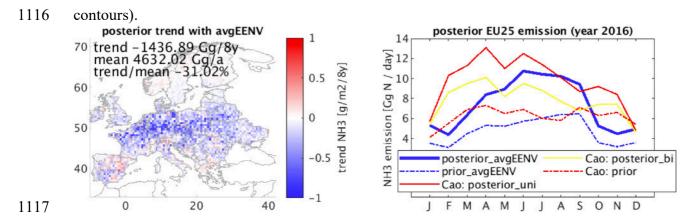


Figure 6. Left: spatial distribution of ammonia emission trends computed for the studied period 2013–2020 in the same way as in (Luo et al., 2022), where also trend, mean, and trend/mean are defined/computed in the same way. Right: comparison of ammonia emissions from the EU25 countries for the year 2016 from our posterior calculations (posterior\_avgEENV, blue) and results from Cao et al. (2022) (posterior uni in red and posterior bi, in yellow).