

# Update of the Seismogenic Potential of the Upper Rhine Graben Southern Region

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## **Abstract.**

The Upper Rhine Graben (URG), located in France and Germany, is bordered by north-south trending faults, some of which are considered active, posing a potential threat to the dense population and infrastructures on the Alsace plain. The largest historical earthquake in the region was the  $M_{6.5\pm 0.5}$  Basel earthquake in 1356. Current seismicity ( $M > 2.5$  since 1960) is mostly diffuse and located within the graben. We build upon previous seismic hazard studies of the URG by exploring uncertainties in greater detail and revisiting a number of assumptions. We first take into account the limited evidence of neotectonic activity, then explore tectonic scenarios that have not been taken into account previously, exploring uncertainties for  $M_{max}$ , its recurrence time, the  $b$ -value, and the moment released aseismically or through aftershocks. Uncertainties on faults' moment deficit rates, on the observed seismic events' magnitude-frequency distribution, and on the moment-area scaling law of earthquakes are also explored. Assuming a purely dip-slip / normal faulting mechanism associated to a simplified 3 main fault model,  $M_{max}$  maximum probability is estimated at  $M_w 6.1$ . Considering this scenario, there would be a 99% probability that  $M_{max}$  is less than 7.3. In contrast, with a strike slip assumption associated to a 4 main fault model, consistent with recent paleoseismological studies and the present-day stress field,  $M_{max}$  is estimated at  $M_w 6.8$ . Based on this scenario, there would be a 99% probability that  $M_{max}$  is less than 7.6.

## 28 1 INTRODUCTION

29 The Upper Rhine Graben (URG), located in France and Germany, is bounded by north-south trending faults, some  
30 of which are considered active, posing a potential threat to the dense population and the industrial and  
31 communication infrastructures of the Alsace plain (Figure 1). The largest historical earthquake in the region was  
32 the 1356 Basel earthquake with a maximum intensity equal to or greater than IX (Mayer-Rosa and Cadiot, 1979;  
33 Fähr et al., 2009), an earthquake presently associated to a magnitude between  $M_{6.5\pm 0.5}$  (Manchuel et al., 2017)  
34 and  $M_{6.9\pm 0.2}$  (Fähr et al., 2009). Current seismicity ( $M > 2.5$  since 1960) is mostly diffuse and located within the  
35 graben (Dobre et al., 2022), hence the difficulty to attribute individual events to a given fault segment. The  
36 bordering faults themselves are relatively quiet except for the south-eastern section of the graben, near Mulhouse-  
37 Basel, where natural seismic sequences (ROULAND et al., 1983; Bonjer, 1997) and induced seismicity (Kraft and  
38 Deichmann, 2014) have been observed. Seismic activity actually varies along the URG with an increasing rate of  
39 events towards the south (Barth et al., 2015). The relative rate between small and large events (b-value from the  
40 Gutenberg-Richter law) also increases towards the south indicating a surplus of small earthquakes or a deficit of  
41 large events roughly south of Strasbourg (Barth et al., 2015). Focal mechanisms of earthquakes suggest that the  
42 region is subject to strike-slip regime with some normal component (Mazzotti et al., 2021), consistent with the  
43 large wavelength strain inferred from geodetic data (Henrion et al., 2020). Characterizing the slip rates of the  
44 graben's faults based on geodetic data remains challenging. Indeed regional glacial isostatic adjustments, local  
45 subsidence and low tectonic strain rates result in a heterogeneous velocity field with values below 0.2 mm/yr and  
46 often within measurement uncertainties (Fuhrmann et al., 2015; Henrion et al., 2020).

47 The seismic hazard of the URG has been evaluated by multiple studies at the national/European scale (Grünthal et  
48 al., 2018; Drouet et al., 2020; Danciu et al., 2021). Furthermore, the seismic hazard of the southern region of the  
49 URG in particular has recently been assessed by Chartier et al. (2017) with a focus on the Fessenheim nuclear  
50 power plant (Figure 1). This study evaluates the seismic hazard using a fault-based approach, taking into account  
51 the network of potentially active faults characterized by Jomard et al. (2017). This fault-based work involves a  
52 moment budget approach, which involves comparing the rate of moment release by seismicity and the rate of  
53 moment deficit (MDR) accumulating along locked portions of faults between large earthquakes (i.e. the tectonic  
54 loading rate of each fault). Since the period of seismological observation (a few centuries) is too short to be  
55 representative of the long-term behavior of seismicity, Chartier et al. (2017) built instead a seismicity model  
56 assumed to be representative of the long-term Magnitude-Frequency Distribution (MFD) of earthquakes, a method  
57 similarly used in former studies (e.g. Molnar, 1979; Anderson and Luco, 1983; Avouac, 2015). Earthquakes below

58  $M_w$ 5 are disregarded (Bommer and Crowley, 2017; Chartier et al., 2017). Earthquakes between  $M_w$ 5 and 6 are  
59 assumed to follow the MFD of the catalog of earthquakes they consider. This catalog integrates several sources of  
60 instrumental and historical earthquakes including sources from the *Laboratoire de Détection et de Géophysique*  
61 of the *Commissariat à l'Énergie Atomique et aux énergies alternatives* (CEA-LDG; <http://www-dase.cea.fr/>) and  
62 from the FPEC (French Parametric Earthquake Catalogue; Baumont and Scotti, 2011), the IRSN contribution to  
63 SHEEC (SHARE European Earthquake Catalogue; Stucchi et al., 2013). MFDs are estimated based on a French  
64 seismotectonic zoning scheme defined by Baize et al. (2013). Earthquakes with magnitude above  $M_w$ 6 are assumed  
65 to occur on the fault planes (Jomard et al., 2017). Chartier et al. (2017) consider two types of model: (1) Each fault  
66 ruptures only as its maximum magnitude event, which is controlled by the surface area of the seismogenic fault  
67 segment (characteristic earthquake model); (2) Events follow the Gutenberg-Richter (GR) law with a b-value equal  
68 to 1, and the maximum magnitude,  $M_{max}$ , is fixed as in the previous model. The recurrence times of the  $M_w > 6$   
69 events are then calibrated so that the rate of moment released by the seismicity models matches the MDR estimated  
70 from neotectonic data (Chartier et al., 2017; Jomard et al., 2017). The authors explore different fault geometries  
71 (e.g. dip and seismogenic depth) using a logic-tree methodology and then proceed to the Probabilistic Seismic  
72 Hazard Assessment (PSHA) of the region, providing a map of the probability of exceedance of Peak Ground  
73 Acceleration (PGA) within a time period.

74 A number of strong assumptions are made within this framework. As mentioned previously, a simplified fault  
75 network is used (Jomard et al., 2017), which constrains the seismogenic area available for ruptures. Expert choices  
76 have also been made to distribute slip rates (i.e. loading rates) originally attributed to faults that have been removed  
77 from the initial fault network (Nivière et al., 2008) on other fault segments. On a number of faults, no estimates of  
78 neotectonic slip rate are available (e.g. West Rhenish Fault) and the authors have chosen to apply slip rates  
79 equivalent to those from other nearby faults (0.01 to 0.05 mm/yr). The neotectonic data are actually only along-  
80 dip slip rate estimates. No along-strike slip rates have yet been published due to the lack of markers to quantify  
81 horizontal offsets along faults and this component has thus been ignored. In addition, Chartier et al. (2017) do not  
82 consider continuous probabilities as they apply a logic-tree method. Chartier et al (2017) fix the b-value to 1,  
83 choose the seismogenic depth to be either 15 or 20 km and do not take into account multi-segment ruptures when  
84 estimating a  $M_{max}$  for each fault segment.

85 In this study, we build upon Chartier et al. (2017) seismic hazard evaluation of the southern URG by exploring  
86 uncertainties in greater detail, revisiting a number of assumptions. We use the methodology from Rollins and

87 Avouac (2019) and Michel et al. (2021), which allows to evaluate the seismogenic potential of faults in a  
88 probabilistic fashion and explore uncertainties for parameters such as the b-value or  $M_{max}$ . We use the fault  
89 network and slip rates taken into account by Nivière et al. (2008), disregarding the Western Rhenish Fault for  
90 which, to our knowledge, no slip rate data is available. We assume faults can rupture simultaneously (i.e. multi-  
91 segment rupture). In the following sections, we start by describing the concepts and methods we use to constrain  
92 the seismogenic potential of the URG, and then describe the data available before discussing the robustness of our  
93 results.

## 94 **2 METHOD**

95 We use the methodology from Michel et al. (2021) in order to estimate the seismogenic potential of the upper  
96 Rhine Graben, including  $M_{max}$  and its recurrence time. As in Chartier et al. (2017), we produce seismicity models  
97 representative of the long-term behavior of earthquakes. We assume that the MFDs of background earthquakes  
98 follow a Gutenberg-Richter power law up to  $M_{max}$ . We define background earthquakes as mainshocks, as opposed  
99 to their subsequent aftershocks. We assume that their timing of occurrence is random, following a Poisson process.  
100 Each model is controlled by three parameters: (1)  $M_{max}$ , (2) the recurrence time of events of a certain  
101 magnitude,  $\tau_c$ , and (3) the b-value. We use two types of model, namely the tapered and truncated models (Rollins  
102 and Avouac, 2019; Michel et al., 2021; Figure S1). The tapered model type assumes a non-cumulative power-law  
103 MFD truncated at  $M_{max}$ , which gives rise to a tapered MFD in the cumulative form (i.e. the traditional display  
104 when representing the Gutenberg-Richter law). The truncated model type assumes instead a MFD with a  
105 distribution truncated at  $M_{max}$  in the cumulative form.

106 The seismicity models are then tested against three constraints: (1) the moment budget, as in Chartier et al. (2017),  
107 which implies that moment released by slip on the fault should match the moment deficit accumulating between  
108 earthquakes over a long period of time; (2) the moment-area scaling law, an empirical scaling law relating rupture  
109 area to slip for each earthquake, and (3) the MFD of observed seismicity. Each of these constraints are described  
110 in more detail in the following sub-sections. The data and associated uncertainties used for the constraints are  
111 discussed in the following section (i.e. Section 3).

### 112 **2.1 Moment budget**

113 A moment budget consists in comparing the rate of moment released from slip events (seismic or aseismic),  
114  $\dot{m}_0^{Total}$ , with the moment deficit rate,  $\dot{m}_0^{def}$ , accumulating between slip events. The moment deficit rate is defined

115 by the equation  $\dot{m}_0^{def} = \int \mu \dot{D}^{def} dA$ , where  $\mu$  is the shear modulus,  $A$  is the area that remains locked during the  
 116 interseismic period (i.e. the potential seismogenic zone), and  $\dot{D}^{def}$  is the rate at which slip deficit builds up. Since  
 117 the distribution of locked segments of faults and their associated loading rates cannot yet be determined for the  
 118 URG from geodetic measurements,  $A$  is assumed to be homogeneous along-strike for each fault, while we consider  
 119 possible the seismogenic width to change from one fault to another. The rate at which slip deficit builds up,  $\dot{D}^{def}$ ,  
 120 is evaluated based on neotectonic information (see Section 3.1). The total moment released,  $\dot{m}_0^{Total}$  is calculated  
 121 based on the rate of moment release of the long-term seismicity model. Since the long-term seismicity model only  
 122 considers mainshocks, we included a fourth parameter,  $\alpha_s$ , that represents the proportion of moment released by  
 123 background seismicity (Avouac, 2015),  $\dot{m}_0^{Bckgrd}$ , relative to the total moment released (including aftershocks and  
 124 aseismic afterslip). If  $\dot{m}_0^{def} = \dot{m}_0^{Total} = \dot{m}_0^{Bckgrd} / \alpha_s$ , then the moment budget is said to be balanced.

125 The cumulative MFD for tapered and truncated seismicity models achieving a balanced moment budget have an  
 126 analytical form and are a function of  $M_{max}$ ,  $b$ ,  $\dot{m}_0^{def}$  and  $\alpha_s$  (see Rollins and Avouac, 2019, and references therein).  
 127 We can therefore estimate the probability of a seismicity model balancing the moment budget,  $P_{Budget}$ , by  
 128 sampling the *a priori* distributions of those parameters.

129

## 130 **2.2 Moment-area scaling law**

131 According to global earthquake statistics, the moment released by an earthquake,  $m_0^{seis}$ , is proportional to the area  
 132 of its rupture,  $A_{eq}$ , such that  $m_0^{seis} \propto A_{eq}^{3/2}$  (Wells and Coppersmith, 1994; Leonard, 2010; Stirling et al., 2013).  
 133 We use this scaling to evaluate whether a seismic event of a given magnitude has a rupture area that fits within the  
 134 seismogenic zone. By considering the spread of the empirical distribution of magnitude vs. area, we assume the  
 135 probability distribution function of an event of magnitude  $M_w$  to be probable considering this scaling,  $P_{scaling}$ . We  
 136 use here the self-consistent scaling law, and related uncertainties, as defined by Leonard (2010) in the dip-slip  
 137 equation (the strike-slip equation is in any case almost the same).

## 138 **2.3 Earthquake catalog**

139 We test whether the observed MFD from earthquake catalogs may be a sample of the distribution of the long-term  
 140 seismicity models we are building. Effectively, we evaluate the likelihood of our observed MFD given the  
 141 distribution of the models. Since we only consider mainshocks, we define the likelihood of the observed seismicity

142 catalog,  $P_{Cat}$ , as  $P_{Cat} = \prod_i P_{poisson}^{M_i}$ , where  $P_{poisson}^{M_i}$  is the probability to observe  $n_{obs}^{M_i}$  events, within the magnitude  
 143 bin  $M_i$ , occurring during the time period  $t_{obs}^{M_i}$ , assuming the long-term mean recurrence of events is  $\tau_{model}^{M_i}$ :

$$144 P_{poisson}^{M_i}(n_{obs}^{M_i}, t_{obs}^{M_i}, \tau_{model}^{M_i}) = \frac{(t_{obs}^{M_i}/\tau_{model}^{M_i})^{n_{obs}^{M_i}}}{(n_{obs}^{M_i})!} e^{-t_{obs}^{M_i}/\tau_{model}^{M_i}}.$$

145 Effectively, for a given seismicity model, we generate randomly 2500 declustered earthquake catalogs. We  
 146 evaluate the likelihood of each catalog and define  $P_{Cat}$  as the average of these likelihood values.

147 Note that we follow the recommendation by Felzer (2008) while exploring magnitude uncertainties and correct  
 148 the magnitudes of each event by  $\Delta M = (b^2 \sigma^2)/(2 \log_{10}(e))$ , where  $b$  is the declustered catalog  $b$ -value,  $\sigma$  is the  
 149 standard deviation for the event's magnitude, and  $e$  is the exponential constant.

## 150 2.4 Seismicity model probability and marginal probabilities

151 Finally, the probability of a seismicity model is defined as  $P_{SM} = P_{Budget} P_{Cat} P_{scaling}$  which depends, among  
 152 others, on  $M_{max}$  and  $b$  (Michel et al., 2021). The evaluation of the parameters to estimate  $P_{SM}$  are discussed in  
 153 Section 3. Marginal probabilities such as  $P_{M_{max}}$ , the probability of  $M_{max}$ , and  $P_b$ , the probability of the  $b$ -value,  
 154 can be estimated based on  $P_{SM}$ . We also define  $P(\tau_{max} | M_{max})$  as the probability of the rate of  $M_{max}$ , and  
 155  $P(\tau | M_w)$  as the probability of the rate of events with magnitude  $M_w$ , which accounts for all earthquakes from all  
 156 of the models (i.e. not only  $M_{max}$ ). Probabilities needed for estimating seismic hazard (e.g. PSHA) such as the  
 157 probability to have an event above magnitude  $M_w$  for a time period  $T$ ,  $P(M > M_w | T)$ , can likewise be evaluated.

## 158 3 DATA AND ASSOCIATED UNCERTAINTIES

159 We present in this section the data and their associated uncertainties used to evaluate each constraint.

### 160 3.1 Neotectonic data, seismogenic along-dip width and moment deficit rate

161 In order to evaluate the MDR for the moment budget constraint (Section 2.1), we must infer estimates of loading  
 162 rate (i.e.  $\dot{D}^{def}$ ) for each fault taken into account. The slip rate on each fault is taken from Nivière et al. (2008) for  
 163 the Rhine River, Black Forest, Weinstetten and Lehen-Schonberg faults (the Landeck or West Renish faults are  
 164 not considered). Their slip rates rely on estimates of the cumulative vertical displacement of the faults based on  
 165 Pliocene-Quaternary sediments thickness variations measured from 451 boreholes, assuming that the  
 166 accommodation space opened by tectonic motion is completely balanced (or over-balanced) by sedimentation.

167 However, potential erosional periods due to the piracy of the Rhine River might bias the measurements, thus the  
168 values are to be interpreted as maximum displacement estimates. Nivière et al. (2008) inferred vertical slip rates  
169 of 0.07 and 0.17 mm/yr from the age of the sediments for the Rhine River and Weinstetten faults respectively. The  
170 Lehen-Schonberg fault slip rate reaches between 0.04 and 0.1 mm/yr. While borehole observations do not allow  
171 to conclude on the Pliocene-Quaternary slip rate of the Black Forest fault, this structure is suggested to be inactive  
172 during this time period, and that the deformation is now accommodated by the other aforementioned faults (Nivière  
173 et al., 2008). Note that these are vertical slip rate estimates and the along-strike component is for the moment  
174 neglected. For the moment rate calculation, we project vertical slip rates on the along-dip direction considering  
175 the dip angles of each fault.

176 The seismogenic down-dip extent of a fault depends on the temperature gradient (e.g. Oleskevich et al., 1999),  
177 among other parameters. Indeed, between the isotherms 350°C and 450°C, quartzo-feldspathic rocks undergo a  
178 transition in frictional properties (Blanpied et al., 1995) from a rate-weakening (<350°C), potentially seismogenic  
179 behavior to a rate-strengthening (>450°C), stable sliding behavior (Dieterich, 1979; Ruina, 1983). The geothermal  
180 gradient below the URG is higher than in the surrounding regions due to its tectonic history (Freymark et al.,  
181 2017). Based on borehole temperature measurements from Guillou-Frottier et al. (2013), we estimate the envelopes  
182 of the geothermal gradient in the southern URG (Figure S2), assuming a linear temperature gradient with depth,  
183 and show that the frictional property transition would occur between depths of 6 (shallowest position of the 350°C  
184 isotherm; Figure S2) and 18 km (deepest position of the 450°C isotherm; Figure S2). In this study, we define the  
185 PDF of the seismogenic down-dip extent as a uniform distribution between 0 and 6 km depth associated with a  
186 linear taper down to 18 km. The linearity of the taper implies that the position of the fault's transition to a fully  
187 rate-strengthening behavior (>350-450°C) has a uniform probability to fall between 6 km (shallowest position of  
188 the 350°C isotherm according to Figure S2) and 18 km depth (deepest position of the 450°C isotherm; Figure S2).

189 Additionally, the southern part of the URG is the site of a potash-salt evaporitic basin (Lutz and Cleintuar, 1999;  
190 Hinsken et al., 2007; Freymark et al., 2017), which reaches a maximum depth of ~2 km. Such formations may not  
191 accumulate any moment deficit as the yield stress of evaporites is very low (Carter and Hansen, 1983). We assume  
192 each fault is potentially impacted by this formation, hence modulating the seismogenic thickness and in turn the  
193 seismogenic area available for a rupture. The resulting PDF for the seismogenic thickness is the convolution of  
194 the PDF of the down-dip extent of the seismogenic zone with the PDF of the evaporitic basin thickness, giving a  
195 uniform distribution between 0 and 2 km. Combining both temperature and salt basin assumptions leads to a PDF

196 of the along-dip seismogenic width, which is uniform down to  $\sim 5$  km and decreases linearly until  $\sim 17$  km (Figures  
197 S3 to S6).

198 The moment deficit is then the product of the length of each fault, their seismogenic width, the neo-tectonic long-  
199 term slip rate, and the shear modulus that we fix to 30 GPa (same as in Chartier et al., 2017). Each fault is assumed  
200 to have its own seismogenic width. The moment deficit rate of each fault is shown in Figure 1. The PDFs for each  
201 of the fault's constitutive parameters are shown in Figure S3 to S6. By considering the range of the fault's  
202 geometrical parameters, which considers also the Black Forest Fault even though it is assumed to be non-active,  
203 we obtain the moment-area constraint shown in Figure 2. Events up to  $M_w 6.5$  are equiprobable while those  
204 above  $M_w 7.7$  are extremely improbable.

### 205 **3.2 Instrumental and historical seismicity catalogs**

206 To constrain the MFD of the long-term seismicity models with an observational seismicity catalog, as described  
207 in Section 2.3, we need to evaluate from the observational catalog the number of events per magnitude bin  $n_{obs}^{M_i}$   
208 over a period of time  $t_{obs}^{M_i}$  (Section 2.3). We use the earthquake catalog from Drouet et al. (2020). This catalog was  
209 built from multiple former catalogs. It relies mostly on the FCAT-17 catalog (Manchuel et al., 2018), which is  
210 itself a combination of the instrumental catalog SiHex (SIsmicit  de l'HEXagone; Cara et al., 2015) for the 1965-  
211 2009 period, and a historical catalog based on the macroseismic database of SISFRANCE (BRGM, IRSN, EDF),  
212 intensity prediction equations from Baumont et al. (2018) and the macroseismic moment magnitude determination  
213 from Traversa et al. (2018) for the 463-1965 period. Events located more than 20 km from the French border, not  
214 provided by the FCAT-17, are based on the SHEEC catalog (Stucchi et al., 2013; Woessner et al., 2015). Finally,  
215 events between 2010 and 2016 come from the CEA-LDG bulletins (<https://www-dase.cea.fr>). All event magnitudes  
216 are given in  $M_w$  and uncertainties are provided. Anthropogenic events are expected to be already removed from the  
217 catalog (Cara et al., 2015; Manchuel et al., 2018).

218 We select events within the coordinates  $[6^\circ, 8.5^\circ]$  longitude and  $[47^\circ, 49.5^\circ]$  latitude, i.e. a broad region covering  
219 the whole URG, and divide the catalog into two time periods, an instrumental period and a historical one taking  
220 events from 1980 onwards and 1850 onwards, respectively. We decluster both catalogs to compare them with the  
221 long-term seismicity models (Section 2.3). Declustering is based on the methodology of Marsan et al. (2017),  
222 which evaluates the probability that an earthquake is a mainshock. Declustering is applied based on a completeness  
223 magnitude,  $M_c$ , of 2.2 and 3.2 for the instrumental and historical catalogs, respectively (Text S1; Figures S7 and  
224 S8). From the resulting catalogs, we keep events from 1994 onwards and 1860 onwards for the instrumental and



225 historical catalogs, respectively (Figures S7 and S8), in order to avoid border effects from declustering. For the  
226 instrumental catalog, 1994 is also the date from which the seismicity rate appears relatively constant (Figure S7).  
227 We then select events in the region of interest (i.e. the southern part of the URG), taking into account only  
228 earthquakes located within a 10 km buffer around the faults considered, including the Black Forest fault (Figure  
229 3). Note that since no events below  $M_c$  are considered, there is a lack of events which falls in the magnitude bins  
230 directly above  $M_c$  while exploring magnitude uncertainties. Thus, when applying the earthquake catalog constraint  
231 (Section 2.3), we take events with  $M_w \geq 2.8$  and  $M_w \geq 4.3$  for the instrumental and historical catalogs,  
232 respectively (Felzer, 2008) (Figure 3).

### 233 3.3 Constitutive parameters of seismicity models

234 As mentioned in Section 2.1, the cumulative MFD for tapered and truncated seismicity models balancing the  
235 moment budget can be defined as a function of  $M_{max}$ ,  $b$ ,  $\dot{m}_0^{def}$  and  $\alpha_s$ . We explore these parameters using a grid  
236 search with  $M_{max}$  and  $b$  sampled uniformly over  $M_{max} \in \mathcal{U}(4.5, 9.9)$  and  $b \in \mathcal{U}(0.1, 1.45)$ , respectively. Based  
237 on global statistics of the post-seismic response following earthquakes (Alwahedi and Hawthorne, 2019; Churchill  
238 et al., 2022), we assume that the PDF of  $\alpha_s$  is a Gaussian distribution with  $\mathcal{N}(0.9, 0.25)$  (Figure S9). Finally, the  
239 PDF of the MDR for each fault is assumed to be uniform between 0 and the estimate based on the maximum slip  
240 rate from Nivière et al. (2008) (Section 3.1). We thus include scenarios for which almost no moment deficit  
241 accumulates on the fault (i.e. the fault slips aseismically or accumulates no strain over long periods of time). This  
242 assumption contrasts with the choice made by Chartier et al. (2017) who assume that each fault is fully locked  
243 over a seismogenic width terminating at either 15 or 20 km. Doing so, we explore a broad range of possible models.

## 244 4 RESULTS

245 The combination of constraints (Section 2) leads to the results shown in Figure 4. For the truncated model, the  
246 marginal probability of  $P_{SM}$  in the  $M_{max}$  and  $\tau_{max}$  space is represented by the gray shaded distribution in Figure  
247 4 (not shown for the tapered model since the models taper at  $M_{max}$ ). The marginal probability of  $M_{max}$  for the  
248 tapered model (in green) peaks at 6.1, while the one for the truncated model (in blue) is bi-modal with peaks at 5.2  
249 and 5.8. For the truncated model (not the tapered model for the same reason as previously indicated), the marginal  
250 probability  $P(\tau_{max} | M_{max} = 5.8)$  (solid blue line in the y-axis) peaks at  $\sim 1000$  yrs. Taking  $M_{max} = 6.6$  or 7.0, a  
251 number close to the estimated magnitude of the 1356 Basel earthquake, the marginal probability would instead  
252 peak at  $\sim 16,000$  and  $\sim 80,000$  yrs, respectively.

253 The marginal probabilities  $P(\tau | M_w = 6.1)$  and  $P(\tau | M_w = 5.8)$  for the tapered and truncated models (green and  
254 blue dotted lines on the y-axis, respectively), which take all events from the seismicity models into account (not  
255 only  $M_{max}$ ), have instead peaks at  $\sim 16,000$  yrs and  $\sim 10,000$  yrs, respectively. The marginal probability  $P_b$  peaks  
256 at  $\sim 0.85$  and  $0.9$  for the tapered and truncated models, respectively.

257 The effect with and without the moment-area scaling law is shown in Figure 5. Adding the scaling law constraint  
258 does not change the mode of  $P_{M_{max}}$  but completely rejects scenarios with  $M_{max} > 7.8$ .

259 Finally, the probabilities  $P(M > M_w | T)$  for  $T = 100$  and  $10,000$  yrs are also shown in Figure 5. As an example,  
260 the probability of occurrence for an event above  $M_w 6.5$  (similar to the 1356 Basel earthquake) for an observational  
261 period of  $100$  yrs is  $\sim 0.1\%$  for both the tapered and truncated models. For an event above  $M_w 6.0$  and for the same  
262 period, this probability is instead  $\sim 1\%$  for both models (see zoom in Figure 5.c).

263 The correlations between  $M_{max}$ , the moment deficit rate, the  $b$ -value, and  $\alpha_s$ , for both the tapered and truncated  
264 models but without the scaling law constraint, are shown in Figures S10 and S11. For both models, probable  $M_{max}$   
265 increases with increasing  $b$ -value (Figure S10.a and S11.a), highlighting strong interdependency between the two  
266 parameters. Raising the moment deficit rate will control the minimum probable  $M_{max}$  (Figures S10.b and S11.b)  
267 but will also tend to exclude scenarios with a high  $b$ -value ( $> 1.25$ ; Figures S10.f and S11.f). While other trends  
268 are expected between parameters, they seem less visible, likely due to the uncertainties of the parameters explored.

269 The results if we combine the PDFs from the tapered and truncated models using a mixture distribution are shown  
270 in Figure S12.  $P_{M_{max}}$  has a main peak at  $5.9$  and a smaller peak at  $5.2$ , which originates from the truncated model.  
271  $P(\tau | M_w = 5.9)$  peaks instead at  $\sim 13,000$  yrs.

## 272 **5 DISCUSSION**

### 273 **5.1 Sensibility to earthquake catalog declustering**

274 The catalog declustering (i.e. removal of aftershocks) may have a significant impact on the results (Section 2.3),  
275 influencing the shape of the observed MFD of earthquakes. In this study, we applied the methodology of Marsan  
276 et al. (2017), which is based on the ETAS framework and intrinsically assumes that background events have  
277 Poisson behavior. Other declustering methodologies are available and we test here the one from Zaliapin and Ben-  
278 Zion (2013) based on the nearest-neighbor distances of events in the space-time-energy domain. The results from

279 this methodology produce background seismicity catalogs with more events than the one from Marsan et al. (2017)  
280 (Text S2 and Figures S13 to S15), but infers larger b-values when combining the instrumental catalog with the  
281 historical one (as inferred by Figure 6.b). The analysis of the seismogenic potential of the URG using Zaliapin and  
282 Ben-Zion (2013) methodology results with  $P_{M_{max}}$  peaking at  $M_{6.3}$  for the tapered model, and is still bi-modal for  
283 the truncated model, with peaks at  $M_{5.2}$  and  $M_{5.9}$  (Figure 6). Unlike with Marsan et al. (2017), the peak at lower  
284 magnitude for the truncated model is more probable than the one at larger magnitude. The most probable  $M_{max}$   
285 for both models are slightly shifted to lower magnitudes than the values estimated using Marsan et al. (2017)  
286 methodology, but the width of the PDFs appears unchanged to first order. The resulting marginal probabilities  
287  $P(\tau | M_w = 5.9)$  and  $P(\tau | M_w = 5.8)$  for the tapered and truncated models both peak at  $\sim 8,000$  yrs.

## 288 **5.2 Source of seismicity**

289 We initially selected earthquakes within a 10 km buffer zone around the faults to reflect the spatial strain pattern  
290 of a vertical fault blocked down to a depth of 10 km. Nevertheless, the locking depth could potentially be deeper,  
291 down to  $\sim 18$  km as suggested in Section 3.1. In this respect, we also provide results if events are selected within  
292 20 km of the faults (Figures S16 and S17). Under these conditions, the seismicity rates of the observational  
293 earthquake catalogs are higher and constrain the long-term seismicity models to cases that produce higher moment  
294 release rate.  $P_{M_{max}}$  thus favours events with a lower magnitude than the one using events within 10 km (Figure 5;  
295 Section 4). The tapered model peaks at  $M_w 5.9$ , instead of 6.1, while the truncated model peaks twice at  $M_w 5.2$   
296 and 5.8, in a similar manner to the reference scenario in Section 4, except that the peak at  $M_w 5.2$  is now the most  
297 probable.

298 However, current seismicity in the URG is seemingly diffuse and it is difficult to associate it with a fault in  
299 particular (Dobre et al., 2022). On the other hand, geodetic data are not yet able to resolve any tectonic  
300 deformation and thus to evaluate the loading rate of faults (Henrion et al., 2020). Even though the Drouet et al.  
301 (2020) catalog, based on FCAT-17 catalog, is supposedly devoid of anthropic seismicity (Cara et al., 2015;  
302 Manchuel et al., 2018), one can then ask whether the current seismicity is totally representative of the undergoing  
303 long-term tectonic processes or presently modulated by surface loads such as the post-glacial rebound (e.g. Craig  
304 et al., 2016), aquifer loads, erosion or incision (e.g. Bettinelli et al., 2008; Steer et al., 2014; Craig et al., 2017). If  
305 so, the assumption that the main driver of seismicity is tectonic loading breaks down and our method used to assess  
306 seismic hazard must be completed by physics-based constraints of such transient stress release (Calais et al., 2016).

307 Distinguishing seismic sources triggered by tectonic loading from other driven forces is an extremely difficult  
308 task. The earthquake catalog contribution (Section 2.3) might then not be appropriate.

309 Additionally, the magnitudes of historical events from the FCAT-17 catalog (before the 1960s), and thus the ones  
310 from Drouet et al. (2020), seem to be overestimated (or the instrumental events have underestimated magnitudes  
311 even though it seems less probable) and a bias of the MFD is thus expected (Beauval and Bard, 2022; Doubre et  
312 al., 2022). For the URG case, 3 bins out of 7 of the observed MFD are estimated from the instrumental period. The  
313 bins estimated from the historical period have thus slightly more weight in the catalog constraint (Section 2.3).

314 We test an alternative constraint inferring that the possible magnitude and frequency of  $M_{max}$  must be consistent  
315 with the observed largest event over the observation period ( $\sim 146$  yrs), meaning that it has to be larger than or  
316 equal to the known largest event while the return period of the largest event cannot be significantly shorter than  
317 the observation period (Approach 2 from Michel et al., 2018). This constraint is equivalent to considering that no  
318 earthquakes with a magnitude greater than the largest event in the observation period occurred during the time  
319 period covered by the observed catalog. Theoretically, this constraint imposes a lower bound on  $M_{max}$  and its  
320 recurrence time. The results obtained using this constraint together with the moment budget and scaling law ones  
321 are shown in Figure 7. Since  $M_{max}$  frequency differs for the tapered and truncated models, the new constraint  
322 imposes different lower bounds for the two models. The truncated model rejects scenarios with  $M_{max}$  below  $M_w 5.5$   
323 more strongly.  $P_b$  is not constrained by the observed seismicity catalog but higher values of the b-value seem  
324 slightly more probable (inset in Figure 7). The marginal probabilities  $P(\tau | M_w = 5.9)$  and  $P(\tau | M_w = 6.3)$  for  
325 the tapered and truncated models have peaks at  $\sim 12,500$  yrs and  $\sim 63,000$  yrs, respectively.

326

### 327 **5.3 Strike slip component**

328 In this study, as well as in Chartier et al. (2017), we assume solely along-dip displacement since it is the only  
329 published neo-tectonic information available. Nevertheless, recent paleo-seismological data on the Black Forest  
330 fault near Karlsruhe (north of our study area) suggest 5.9 m of cumulative strike-slip, in contrast to 1.2 m of  
331 cumulative vertical slip, over the last 5.9 kyrs (Pena-Castellnou et al., 2023). Those displacements seem to be  
332 associated with at least three paleo-earthquakes. This suggests (1) that the Black Forest fault has been active during  
333 the Quaternary period and that (2) strike-slip might be predominant. The ratio between strike- and dip-slip from  
334 the Black Forest event would be then equal to 4.8. We thus test a scenario where the Black Forest fault is associated

335 with a maximum vertical slip deficit rate of 0.18 mm/yr, as proposed by Jomard et al. (2017), and where we  
336 multiply the maximum slip deficit rate of all faults considered by 4.8. The results and the revised MDR for each  
337 fault are shown in Figures 8 and S18.  $P_{M_{max}}$  peaks at  $M_w$ 6.8 and  $M_w$ 6.6 for the tapered and truncated models,  
338 respectively. They are associated with the marginal probabilities  $P(\tau | M_w = 6.8)$  and  $P(\tau | M_w = 6.6)$  that both  
339 peak at ~16,000 yrs for the tapered and truncated models. Note that Pena-Castellnou et al. (2023) suggest that  
340 earthquakes of potentially  $M_w$ 6.5 occurred north of our study area.  $P_b$  peaks at 0.7 for both the tapered and  
341 truncated models, thus at lower values than taking into account the vertical-slip component alone.

342 The previous scenario tested (Figure 8) takes two more faults (i.e. Weinstetten and Lehen-Schonberg faults) into  
343 account than in Chartier et al. (2017), as these two faults are not present within the BDFA (the French database of  
344 potentially active faults; Jomard et al., 2017). The results obtained by selecting faults as defined by Chartier et al.  
345 (2017) and applying the strike slip assumption are provided in Figure S19.  $P_{M_{max}}$  peaks at  $M_w$ 6.7 and  $M_w$ 6.6 for  
346 the tapered and truncated models, respectively, very similar to the scenario taking all four faults, as the moment  
347 deficit rate is dominated by the Rhine River and Black Forest faults. Note that the marginal probabilities  $P(\tau | M_w)$   
348 and  $P(\tau_{max} | M_{max})$  seem to get more noisy, likely due to the shape of the MDR PDF which skews heavily towards  
349 zero (black line in Figure S18.e).

#### 350 **5.4 Multi-segment rupture**

351 In this study we assume that all faults can rupture simultaneously. Nevertheless, the Black Forest Fault is initially  
352 taken as inactive, and the traces of the Weinstetten and Lehen-Schonberg faults are separated by at least 7.9 km.  
353 According to Wesnousky (2006), multi-segment ruptures are associated with low probability when the inter  
354 segment distance exceeds 5 km. Consequently, the seismogenic potential scenario from Section 4 would be an  
355 overestimation. On the other hand, according to Castellnou et al., 2022, the Black Forest Fault is in fact active and  
356 seismogenic, and could be assumed to rupture with other faults. Additional structures might actually link all the  
357 faults together (e.g. Lutz and Cleintuar, 1999; Bertrand et al., 2006; Rotstein and Schaming, 2011). In this case,  
358 the seismogenic potential scenario from Section 4 would be interpreted as an underestimation.

359 Finally, we only consider the faults within a finite zone, which controls the total seismogenic area of the faults (i.e.  
360 the moment-area scaling law effect), whereas the faults continue northwards and southwards to a lesser extent.  
361 According to Weng and Yang (2017), the aspect ratio (width to length ratio of a rupture) of dip-slip events barely  
362 reaches beyond 8. Taking a seismogenic width of 18 km (our maximum estimate), the maximum length of

363 earthquakes would then be 144 km, while the full length of the URG faults considered, including the Black Forest  
364 fault, is ~250 km (~160 km if the Black Forest fault is not included). The rupture of all the faults would then be  
365 unlikely. On the other hand, strike-slip events do not seem to be capped by any aspect ratio (Weng and Yang,  
366 2017), so  $M_w > 7.5$  events cannot be excluded in this context.

## 367 **6 CONCLUSION**

368 In this study, we investigate the seismogenic potential of the south-eastern URG, building on the work by Chartier  
369 et al. (2017). Based on a complex fault network (Nivière et al., 2008), we evaluate scenarios that have not been  
370 accounted for previously, exploring uncertainties on  $M_{max}$ , its recurrence time, the  $b$ -value, and the moment  
371 released aseismically or through aftershocks (see Table 2 for a summary of the results considering the different  
372 scenarios). Uncertainties for the MDR, the observed MFD, and the moment-area scaling law are also explored.  
373 Given the four faults considered, and the scenario in which the Black Forest fault is no longer active but where the  
374 other faults can still rupture simultaneously, the  $M_{max}$  maximum probability is estimated at  $M_w 6.1$  and  $M_w 5.8$   
375 using the tapered or the truncated seismicity models respectively. Nevertheless,  $P_{M_{max}}$  for the truncated model has  
376 a second peak at  $M_w 5.2$  and the recurrence time of events of such magnitude (not only  $M_{max}$ ),  $P(\tau | M_w = 5.2) \sim$   
377 2,000 yrs, is much shorter than the one estimated using the main peak,  $P(\tau | M_w = 5.8) \sim 10,000$  yrs. Again  
378 considering the scenario excluding the Black Forest fault, there is a 99% probability that  $M_{max}$  is less than 7.3  
379 using either the tapered or truncated models. In contrast, when strike-slip kinematics are considered as described  
380 in Section 5.3 and the Black Forest Fault is taken into account, there is a 99% probability that  $M_{max}$  is less than  
381 7.6 and 7.5 for the tapered and truncated models, respectively. This is our preferred scenario as it is based on recent  
382 findings for strike-slip mechanisms, although the assumptions made in this analysis are debatable (i.e. strike-  
383 slip/dip-slip ratio evaluated on a fault just north of our zone of study and applied to all faults; Section 5.3).  
384 It should be noted that seismic hazard studies often place an upper bound on the values of  $M_{max}$  considered. In  
385 the case of the URG, studies that use varying approaches to ours, have yielded values comparable to, or marginally  
386 lower than the 99th percentile of  $P_{M_{max}}$  of our strike-slip scenario (e.g. M7.4, M 7.1 and M7.5 for Grunthal et al.,  
387 2018, Drouet et al., 2020, and Danciu et al., 2021, respectively).

388 In any case, within this study, strong assumptions still had to be made that certainly affected the results. It includes  
389 the methodology used to decluster the earthquake catalogs, determining whether it is wise to compare the loading  
390 rate of each fault with seismicity, opting to only consider the dip-slip component despite the fact that strike-slip is

391 highly probable, covering the possibility of multi-segment ruptures and even the choice of the faults to be  
392 considered. Further work, from paleo-seismology, seismic reflection, geodesy, or earthquake relocation is needed  
393 to obtain more information on the structures tectonically involved and their associated loading rates, and to better  
394 constrain the URG seismic hazard.

395 **7 CODE AVAILABILITY**

396 **8 DATA AVAILABILITY**

397 **9 AUTHOR CONTRUBUTION**

398 **10 COMPETING STATEMENT**

399 The authors acknowledge there are no conflicts of interest recorded.

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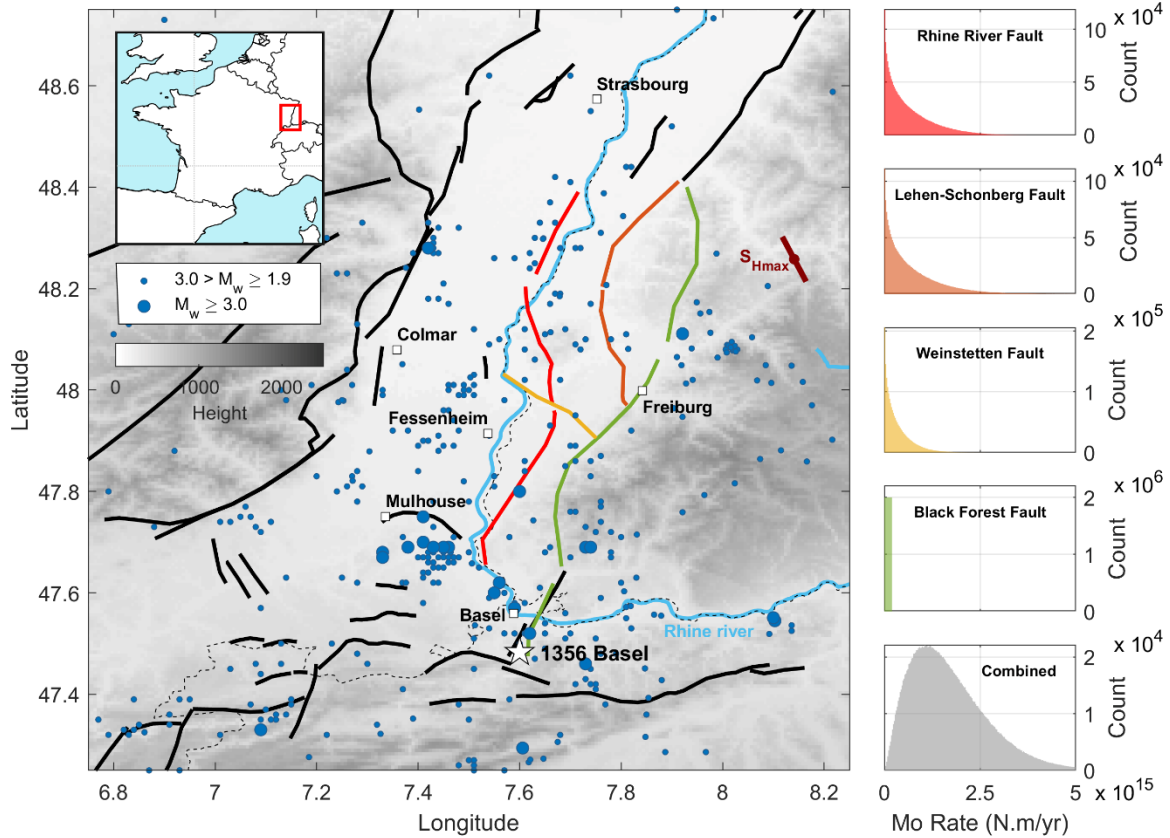
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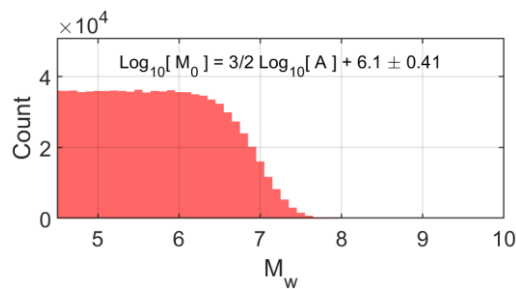
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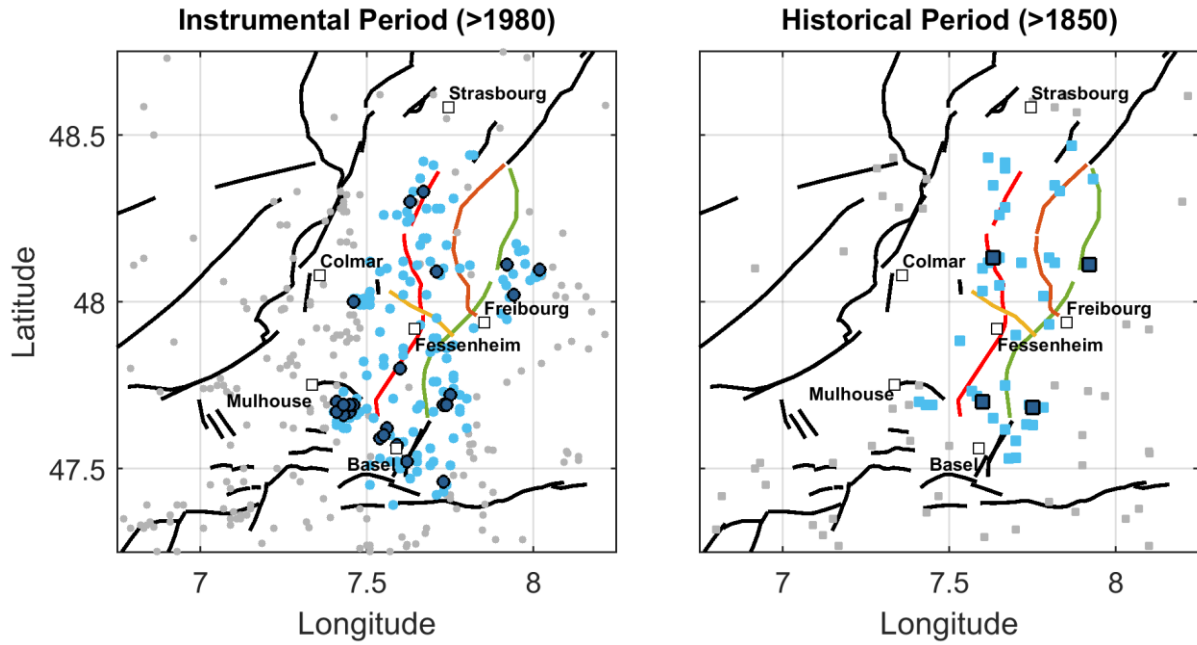
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 561 **Figure 1: (Left panel) Regional setting and seismicity of the Upper Rhine Graben (Drouet et al., 2020). Black lines are**  
 562 **faults while colored ones are the faults taken into account in this study. The fault network geometry is based on the**  
 563 **B DFA database (Jomard et al., 2017) and Nivière et al. (2008). Blue dots are epicenters of  $M_w > 2.2$  earthquakes since**  
 564 **1994. The white star indicates the 1356 Basel earthquake (magnitude ranging from  $M6.5 \pm 0.5$  (Manchuel et al., 2017)**  
 565 **to  $M6.9 \pm 0.2$  (Fäh et al., 2009)). The brown bar indicates the approximate orientation of the maximum horizontal**  
 566 **compressional stress ( $S_{Hmax}$ ) (Heidbach et al., 2016, 2018). The thin dashed black line is the border between France**  
 567 **and Germany. The nuclear powerplant of Fessenheim and the main cities are indicated by white squares. (Right panels)**  
 568 **Moment deficit rate PDFs (expressed in counts) for each of the four faults considered (colors are indicative of the faults**  
 569 **in the left panel), and their combination (in grey).**



570  
 571 **Figure 2: PDF of  $M_w$  considering the along-dip moment-area scaling law of earthquakes from Leonard (2010). Note**  
 572 **that the area from the Black Forest Fault is not included, as its loading rate is assumed equal to 0 mm/yr.**

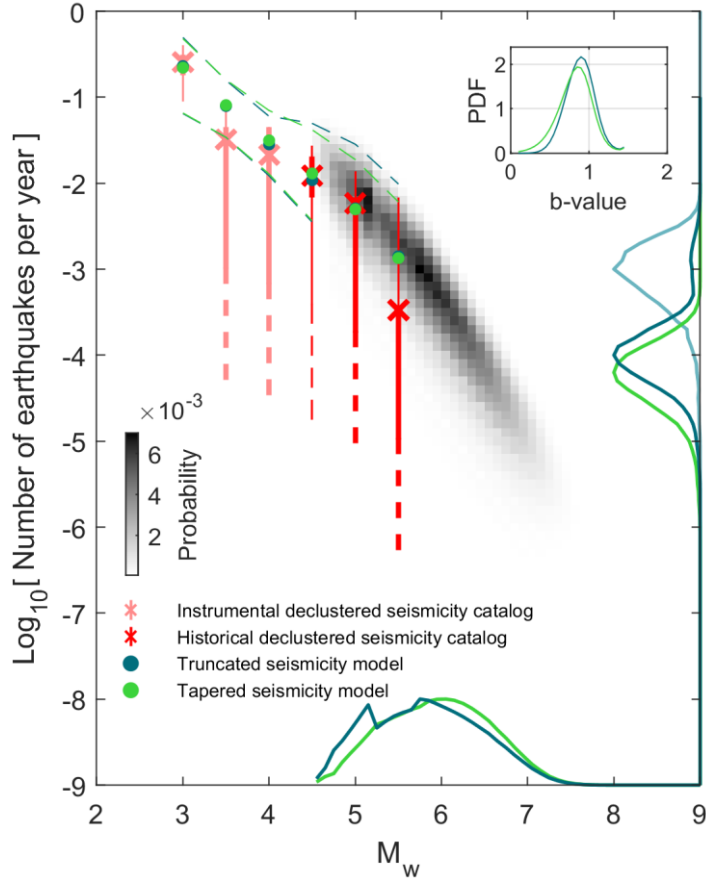


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574 **Figure 3: Earthquake selection for the instrumental (>1994) and historical (>1850) periods. Gray dots and squares**  
 575 **indicate all earthquakes with  $M_c = 2.2$  and  $3.2$  for the instrumental and historical catalogs, respectively. Light blue**  
 576 **dots and squares indicate earthquakes taken into account for the seismogenic potential analysis. Dark blue dots and**  
 577 **squares indicate  $M_w \geq 2.8$  and  $4.3$  earthquakes taken into account for the seismogenic potential analysis.**

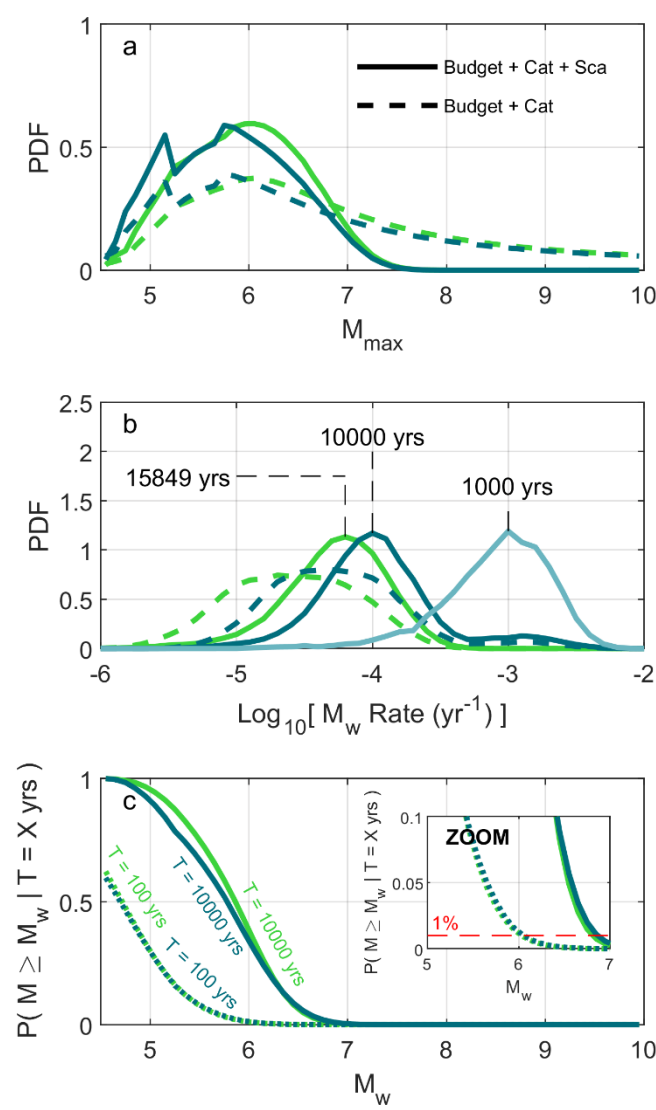
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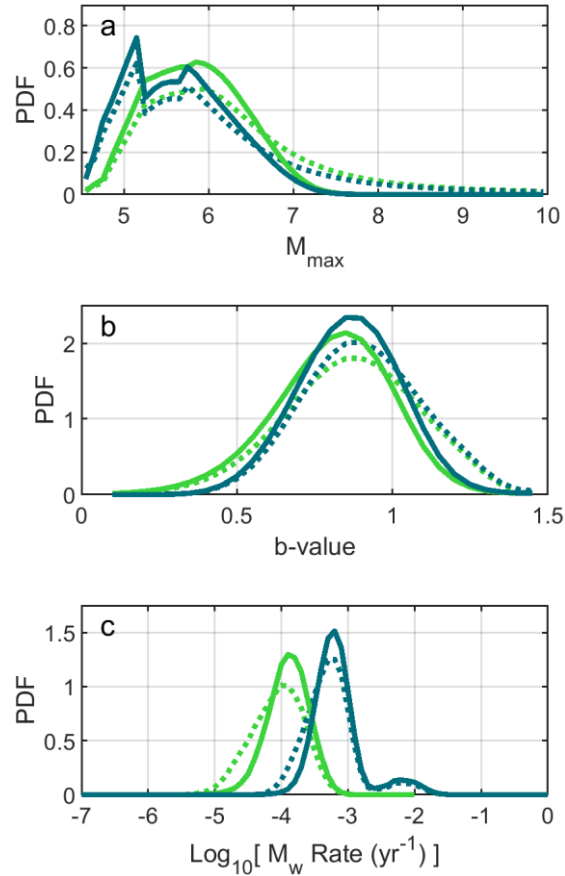
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581 **Figure 4: Seismogenic potential of the URG using all constraints: moment budget, observed magnitude-frequency**  
 582 **distribution, and moment area scaling law. The rate of occurrence of historical and instrumental earthquakes, within**  
 583 **their observation periods, are indicated by red and pink crosses and error bars, respectively. Thick and thin error bars**  
 584 **indicate the 15.9-84.1% (1-sigma) and 2.3-97.7% (2-sigma) quantiles of the MFDs. Dashed lines show the spread of**  
 585 **possible MFDs for the 2500 catalogs randomly generated to explore uncertainties. The green and blue colors are**  
 586 **associated with the tapered and truncated long-term seismicity models. Green and blue dots show the means of the**  
 587 **marginal PDF for the long-term seismicity. Dashed green and blue lines indicate the spread of the best 1% seismicity**  
 588 **models. The marginal probabilities of  $M_{max}$ ,  $P_{M_{max}}$ , are indicated by the solid lines on the  $M_w$  axis. They have been**  
 589 **normalized so that their amplitude is equal to one instead of 0.60 and 0.59 for the tapered and truncated models,**  
 590 **respectively. Green and dark blue lines on the earthquake frequency axis indicate the probability of the rate of events,**  
 591  **$\tau$ , with magnitude  $M_w = M_{Mode}$ , thus  $P(\tau | M_w = M_{Mode})$ , with  $M_{Mode}=6.1$  and  $5.8$  for the tapered and truncated**  
 592 **models, respectively, considering all magnitudes in the seismicity models and not only the recurrence rate of  $M_{max}$ .**  
 593 **They have also been normalized and their peaks were initially at 1.13 and 1.17 for the tapered and truncated models,**  
 594 **respectively. The light blue line on the earthquake frequency axis indicates  $P(\tau_{max} | M_{max} = 5.8)$  (for the truncated**  
 595 **seismicity model only) and is normalized so that its amplitude equals one instead of 1.19. The top-right inset shows the**  
 596 **marginal probability of the b-value. Note that the seismicity MFDs shown in the figure are not in the cumulative form.**



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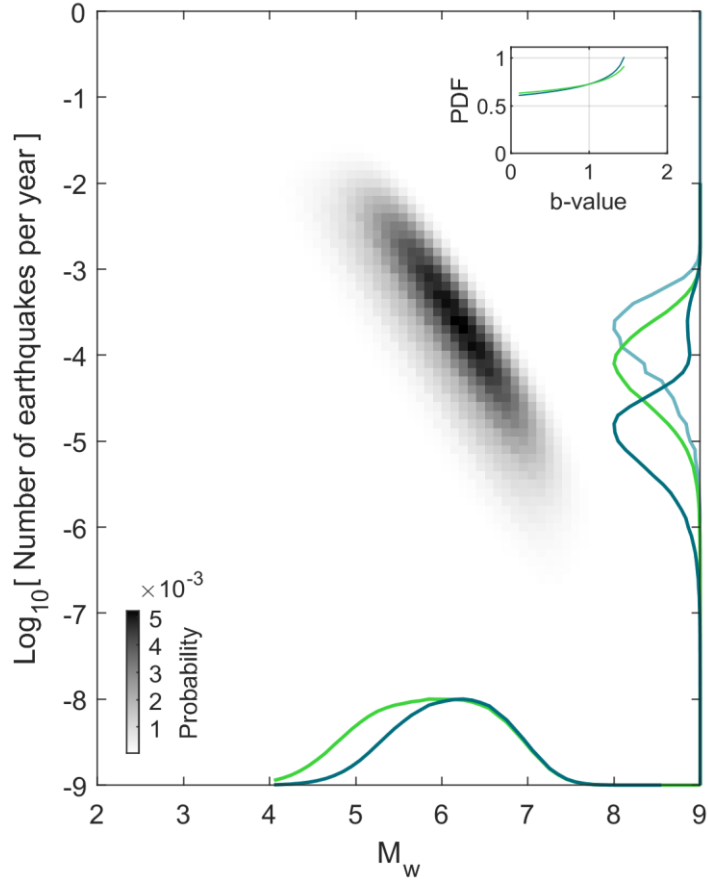
598 **Figure 5:** (a) Evolution of the marginal PDF of  $M_{max}$  when adding the moment-area scaling law constraint. The green  
599 and blue colors in the figure are associated with the tapered and truncated long-term seismicity models. (b) Same as (a)  
600 but for the marginal PDF of the recurrence time of events:  $P(\tau | M_w = 6.1)$  and  $P(\tau | M_w = 5.8)$  for the tapered and  
601 truncated models (dark blue and green lines), respectively, and  $P(\tau_{max} | M_{max} = 5.8)$  shown only for the truncated  
602 model (solid light blue line). (c) Probability of occurrence of earthquakes with a magnitude larger than  $M_w$  over a period  
603 of X yrs. We show the probability of occurrence of such events for the 100 yrs and 10,000 yrs time periods. In (a), (b)  
604 and (c), dotted lines represent the marginal PDFs considering both the moment budget and seismicity catalog constraint,  
605 the dashed lines indicate the PDFs when the earthquake scaling constraint is added. The inset in (c) is a zoom of the  
606 panel. The 1% probability of exceedance over a time period of 100 yrs is a typical order of magnitude for nuclear  
607 applications in France.



608

609 **Figure 6: Results using the declustering method from Zaliapin and Ben-Zion (2013) instead of Marsan et al. (2017)**  
 610 **(Text S2). In this scenario, no probabilities of events to be mainshocks are defined. (a)  $M_{max}$  PDF. (b) b-value PDF. (c)**  
 611  **$P(\tau | M_w = M_{Mode})$  PDF. Solid lines correspond to the results using all constraints while the dotted lines only use the**  
 612 **moment budget and earthquake catalog constraints. Green and blue lines correspond to the tapered and truncated**  
 613 **models, respectively. The results shown here are the ones taking a b-value equal to 1 for Zaliapin and Ben-Zion (2013)**  
 614 **declustering method. The results for b-values of 0.5 and 1.5 are also shown in Figure S15 and are relatively similar to**  
 615 **the ones obtained using a b-value of 1.0.**





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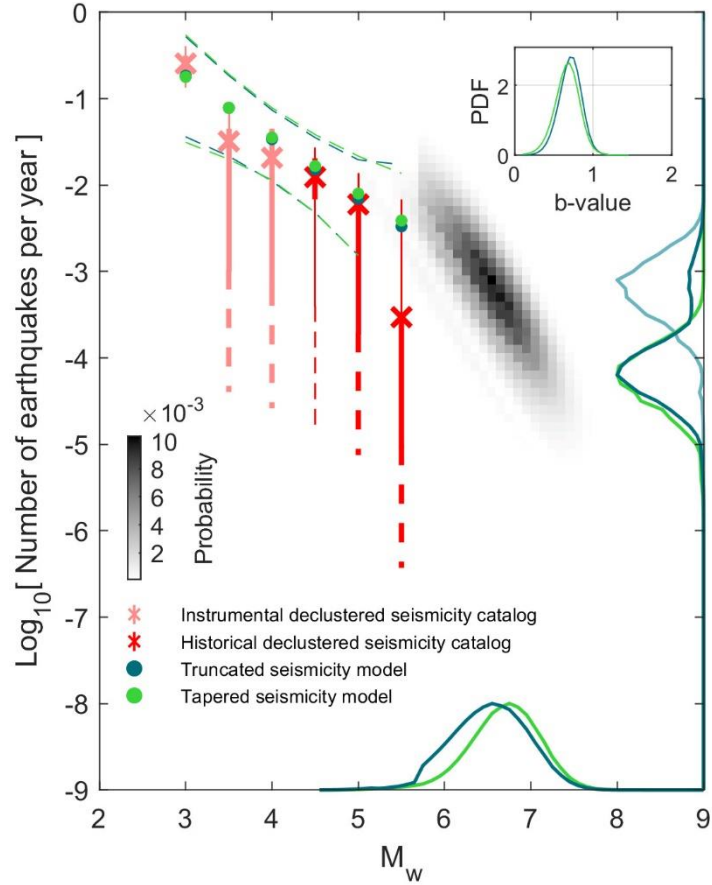
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Figure 7: Same as Figure 4 but only considering the constraints for the moment budget, the moment-area scaling law, and the one on  $M_{max}$  frequency considering the time period of the catalog (which serves as a lower bound constraint for  $M_{max}$ ; Section 5.2; Approach 2 from Michel et al., 2018). The marginal probabilities  $P_{M_{max}}$  have been normalized so that their amplitude is equal to one instead of 0.46 and 0.58 for the tapered and truncated models, respectively. The same is true for  $P(\tau | M_w = M_{Mode})$  which were initially of 0.85 and 0.81 of amplitude, and  $P(\tau_{max} | M_{max} = 6.3)$  (for the truncated seismicity model only) which peaked at an amplitude of 0.85.



623

624 **Figure 8: Same as Figure 2 but considering a strike-slip slip rate component equivalent to 4.8 times the dip-slip estimate,**  
 625 **and assuming the Black Forest Fault maximum long-term vertical slip rate is 0.18 mm/yr (as proposed by Jomard et**  
 626 **al., 2017). Leonard et al.'s (2010) strike-slip moment-area scaling law is used here for the scaling law constraint, even**  
 627 **though it is very similar to the dip-slip version. The marginal probabilities  $P_{M_{max}}$  have been normalized so that their**  
 628 **amplitude is equal to one instead of 1.02 and 0.88 for the tapered and truncated models respectively. The same is true for**  
 629  **$P(\tau | M_w = M_{Mode})$  which were initially of 1.15 and 1.13 of amplitude, and  $P(\tau_{max} | M_{max} = 6.6)$  (for the truncated**  
 630 **seismicity model only) which peaked at an amplitude of 1.17.**

631

632 **Table 1: Fault parameters.  $\mathcal{U}$  and  $\mathcal{N}$  stands for uniform and normal distribution. The PDFs of each of these parameters**  
633 **and the resulting moment deficit rate for each fault are shown in Figure S3 to S6.**

Fault Name	Segment Name (from BDFA)	Dip (°)	Length (km)	Slip-Rate (mm/yr)	Seismogenic zone down-dip extent (km)	Evaporite layer thickness (km)
Rhine River Fault	FRR-1	$\mathcal{U}(50,80)$	$\mathcal{N}(35,2)$	$\mathcal{U}(0,0.07)$	(1) Uniform from 0 to 6 km in depth.  (2) Linearly decreasing	$\mathcal{U}(0,2)$
	FRR-2	$\mathcal{U}(50,80)$	$\mathcal{N}(25,2)$			
	FRR-3	$\mathcal{U}(55,85)$	$\mathcal{N}(20,2)$			
Black Forest Fault	FFN-1	$\mathcal{U}(35,75)$	$\mathcal{N}(20,5)$	0	from 6 to 18 km depth.	
	FFN-2	$\mathcal{U}(40,80)$	$\mathcal{N}(50,2)$			
	FFN-3	$\mathcal{U}(35,75)$	$\mathcal{N}(35,2)$			
Lehen-Schonberg		$\mathcal{U}(40,80)$	$\mathcal{N}(54,2)$	$\mathcal{U}(0,0.1)$	Does not apply to the Black Forest Fault as its loading rate is assumed equal to 0 mm/yr	
Weinstetten		$\mathcal{U}(40,80)$	$\mathcal{N}(15,2)$	$\mathcal{U}(0,0.17)$		

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**Table 2: Summary of the results considering the different scenarios tested from section 4 to 5.3.**

Scenarios	Modes of $M_{max}$	99% probability that $M_{max}$ is below magnitude $M_w$	Mode of $P(\tau   M_w = M_{Mode})$
Rhine River Fault + Lehen-Schonberg Fault + Weinstetten Fault  <i>Dip-Slip Only</i> <i>Marsan et al. (2017) Declus.</i> (Section 4 / Fig. 4 and 5)	<u>Tapered Model</u> $M_w$ 6.1  <u>Truncated Model</u> $M_w$ 5.2 and 5.8	<u>Tapered Model</u> $M_w$ 7.3  <u>Truncated Model</u> $M_w$ 7.3	<u>Tapered Model</u> $\tau = 16,000$ yrs  <u>Truncated Model</u> $\tau = 2,000$ and $10,000$ yrs
Rhine River Fault + Lehen-Schonberg Fault + Weinstetten Fault  <i>Dip-Slip Only</i> <i>Zaliapin and Ben-Zion</i> <i>(2013) Declus.</i> (Section 5.1 / Fig. 6)	<u>Tapered Model</u> $M_w$ 5.9  <u>Truncated Model</u> $M_w$ 5.2 and 5.8	<u>Tapered Model</u> $M_w$ 7.2  <u>Truncated Model</u> $M_w$ 7.1	<u>Tapered Model</u> $\tau = 8,000$ yrs  <u>Truncated Model</u> $\tau = 1,600$ and $8,000$ yrs
Rhine River Fault + Lehen-Schonberg Fault + Weinstetten Fault  <i>Dip-Slip Only</i> <i>Marsan et al. (2017) Declus.</i> <i>Loose catalog constraint</i> <i>(Approach 2 from Michel et</i> <i>al., 2018)</i> (Section 5.2 / Fig. 7)	<u>Tapered Model</u> $M_w$ 5.9  <u>Truncated Model</u> $M_w$ 6.3	<u>Tapered Model</u> $M_w$ 7.4  <u>Truncated Model</u> $M_w$ 7.4	<u>Tapered Model</u> $\tau = 12,500$ yrs  <u>Truncated Model</u> $\tau = 63,000$ yrs
Rhine River Fault + Lehen-Schonberg Fault + Weinstetten Fault + Black Forest Fault  <i>Strike- and Dip-Slip</i> <i>Marsan et al. (2017) Declus.</i> (Section 5.3 / Fig. 8)	<u>Tapered Model</u> $M_w$ 6.8  <u>Truncated Model</u> $M_w$ 6.6	<u>Tapered Model</u> $M_w$ 7.6  <u>Truncated Model</u> $M_w$ 7.5	<u>Tapered Model</u> $\tau = 16,000$ yrs  <u>Truncated Model</u> $\tau = 16,000$ yrs