Modelling GNSS-observed seasonal velocity changes of the Ross Ice Shelf, Antarctica, using the Ice-sheet and Sea-level System Model (ISSM)

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Abstract. The flow speed of floating ice shelves around the Antarctic ice sheet exhibit clear intra-annual variability. However, the drivers of this variability remain poorly understood. Here, we present three new velocity datasets from GNSS stations on the Ross Ice Shelf collected between early 2020 and late 2021 and show that they have two distinct peaks observed in austral summer and austral winter. These measurements do not appear to be consistent with the yearly cycle of sea surface height, which has previously been identified as a possible driver. We investigate the potential role of basal melt variability on ice flow speed and use the Ross Ice Shelf as a testbed. First we identify the regions where changes in melt would have the largest influence on ice speed at our GNSS sites using Automatic Differentiation. We then apply idealized sinusoidal perturbations to modeled basal melt rates at these specific locations to identify what magnitude of variability is needed to match the GNSS observed changes in ice speed. We show that, while very local perturbations in basal melt can have a significant impact on ice flow speed, the amplitude of the perturbation required to match observations are significantly higher than expected, which may indicate that these perturbations are not realistic. We suggest that a combination of external forcings and internal mechanics may be needed to reproduce the observed intra-annual velocity variation at all the GNSS sites.

1 Introduction

The Antarctic Ice Sheet (AIS) contains the vast majority of Earth's freshwater and has the potential to raise global sea levels by 58 m (Mottram et al., 2019; Schlegel et al., 2018; Dirscherl et al., 2020). Over recent decades, the AIS has been losing mass at an accelerating rate due to the warming of the atmosphere and ocean (Pattyn et al., 2018; Shepherd et al., 2012, 2018; Jenkins et al., 2018; Rignot et al., 2019; Lipscomb et al., 2021). Ocean-forced basal melting and calving drive the largest mass

losses on the AIS (Pattyn et al., 2018; Rignot et al., 2019; Adusumilli et al., 2020; Joughin et al., 2014). Floating ice shelves, in particular, provide buttressing to grounded ice and thus are vital for controlling AIS mass loss (Schoof, 2007; Gudmundsson, 2013; Dinniman et al., 2016; Joughin et al., 2013; Pattyn and Durand, 2013). Recent observations have shown that some of these ice shelves show clear intra-annual variability in ice flow (e.g., Gwyther et al., 2018; Greene et al., 2018; Holland. et al., 2019; Jenkins et al., 2018). While this flow variability is generally attributed to variability in external environmental forcings, the exact mechanism responsible for speed changes remains unclear. Gwyther et al. (2018), for example, found that there was high interannual variability in the Totten Ice Shelf surface elevation, velocity and grounding line location due to variability in basal melting. Greene et al. (2018) found that seasonal velocity variations observed at Totten Ice Shelf are due to seasonal variations in landfast sea ice concentrations at the calving front. More recently, Mosbeux et al. (2023) attributed the variability in flow speed of the Ross ice shelf to seasonal changes in Sea Surface Height (SSH).

Here, we focus on the Ross Ice Shelf (RIS), which is Antarctica's largest ice shelf by area, and is approximately in balance (Moholdt et al., 2014; Rignot et al., 2013; Depoorter et al., 2013). The RIS has typical flow speeds of several hundred meters per year, with the active Siple Coast Ice Streams and Byrd Glacier displaying velocities of > 300 m/a (Figure 1). Global Navigation Satellite System (GNSS) receivers can record near-continuously at high temporal resolution throughout the year and thus have the ability to measure seasonal variations in ice velocities (Brunt, 2008; King et al., 2011; Brunt and Macayeal, 2014). Typically, GNSS receivers are employed to measure ice velocities over 1–3 months in the austral summer and to highlight short timescale processes such as tidal variability (e.g. Bindschadler et al., 2003). In this study, we present three new long-duration (12 - 24 months) GNSS datasets of intra-annual ice velocity variations on the RIS. We explore three new sites: the shear margin (Site 1) and the calving front near the Ross Island pinning point (Site 2) , and the KIS grounding zone (Site 4; Figure 1). Additionally, the GNSS dataset previously reported in Klein et al. (2020) and Mosbeux et al. (2023) (referred to as DR10 in previous studies and Site 3 here) are explored in this study.

Previous multi-season GNSS observations on the RIS have noted intra-annual (monthly to seasonal) velocity variations, with one distinct peak per year in the austral winter (Klein et al., 2020; Mosbeux et al., 2023). Two mechanisms have been proposed to explain this intra-annual variability. First, Klein et al. (2020) investigated the impact of a seasonal cycle of spatially varying basal melt rates on the RIS using ice sheet modelling. Klein et al. (2020) used monthly basal melt rates from the ocean model described by Tinto et al. (2019). This ocean model was developed using a repeated annual cycle of forcing for the period 2001-2002 and therefore does not account for known inter-annual variability in atmospheric, oceanic and sea-ice conditions in the Ross Sea (Klein et al., 2020). They found that their modelled seasonal flow variations from basal melting were much smaller than the GNSS-observed (Klein et al., 2020). Therefore, Klein et al. (2020) concluded that the GNSS-observed intra-annual velocity variations on the RIS are most likely not driven by seasonal basal melt rates and that some other seasonal forcing must be dominant. Mosbeux et al. (2023) used ice sheet modelling to investigate whether the seasonal variability of SSH would modify ice velocity through a combination of sea surface tilt and changing basal stresses at the grounding zone. Mosbeux et al. (2023) successfully reproduced the GNSS-observed intra-annual velocity variability at their GNSS sites if a sufficiently large cycle of SSH-induced basal shear stress change near the grounding line was parameterized in their ice sheet model. They found that, in order to capture the observed change in flow speed, they had to allow for the model grounding line to

retreat significantly further upstream than what hydrostatic equilibrium would dictate, using a parameterization of viscoelastic processes (Mosbeux et al., 2023). More importantly, Mosbeux et al. (2023) modelled SSH forced velocity variability displays one distinct peak per year, in contrast to our GNSS observations, which all display two distinct peaks per year. This suggests that seasonal variability in SSH may not be the only forcing that explains the observed variability in velocities at our GNSS sites. To address this question, we turn again to the potential role of basal melt variability as it is known to be an important control on ice shelf dynamics.

The RIS basal melt rates are relatively low due to the cold dense water masses formed on the continental shelf blocking the sub-ice-shelf ocean cavity from warm Circumpolar Deep Water (CDW) intrusions (Moholdt et al., 2014; Stevens et al., 2020; Adusumilli et al., 2020). However, basal melt rates of the RIS vary spatially as they are driven by subsurface inflows of cold High Salinity Shelf Water (HSSW) that reach the grounding zone and seasonal inflows of summer-warmed Antarctic Surface Water (AASW) at the calving front (Stewart et al., 2019; Stevens et al., 2020; Klein et al., 2020; Jendersie et al., 2018; Dinniman et al., 2016; Adusumilli et al., 2020). Recently, high basal melt rates have been observed at the calving front near Ross Island due to the seasonal inflow of summer-warmed AASW from the adjacent Ross Sea Polynya downwelling into the ice shelf cavity (Stewart et al., 2019; Malyarenko et al., 2019). Previous studies have suggested that RIS velocities may be modulated at seasonal to intra-annual timescales by basal melting at the calving front (Stewart et al., 2019; Tinto et al., 2019).

Here, we first map the sensitivity of ice flow speed at all available GNSS sites to basal melting to identify the regions of the RIS that are most sensitive to changes in basal melt. We then apply idealized sinusoidal perturbations to weekly MITgcm basal melt rates to identify what magnitude of variability is needed to match the GNSS observed changes in ice speed. We conclude by discussing how realistic these perturbations are, and whether basal melt variability could be the driver of the observed intra-annual changes in flow speed.

2 Locations and Methods

2.1 Global Navigation Satellite Systems locations

We first present results from three new GNSS sites (Sites 1, 2 and 4), and a previously reported GNSS site (Site 3)(Mosbeux et al., 2023; Klein et al., 2020) on the Ross Ice Shelf (Figure 1). The three new GNSS units were installed during the 2019/2020 austral summer and the data were downloaded in December 2021 (Sites 1, 2, and 4 in Figure 1). The geodetic-grade GNSS units were battery-powered and deployed year round on the RIS to provide a long-term continuous observations of intra-annual velocity variability. GNSS observations from Site 3 were previously reported by Klein et al. (2020). Site 3 recorded between November 2015 and December 2016 and is described in more detail in Klein et al. (2020) where it is referred to as DR10 (Figure 1).

Site 1 is located close to Ross Island, which is a major pinning point making it a sensitive region where changes in ice thickness are expected to influence the flow speed of the entire ice shelf (Gudmundsson et al., 2019; Fürst et al., 2016; Baldacchino et al., 2022; Reese et al., 2018) (Figure 1). Pinning points such as Ross Island provide resistance to ice shelf flow by modifying the balance of forces within the floating ice (Still et al., 2019; Cuffey and Paterson, 2010). This modification of forces has

an effect everywhere on the ice shelf due to the balance of forces in floating ice being non-local (Still et al., 2019; Cuffey and Paterson, 2010). High basal melt rates with a seasonal signal have been observed close to the Ross Island pinning point (Stewart et al., 2019). Site 1 GNSS unit recorded every 30 seconds for 1 hour every 6 hours and has 80 days of data missing in July - October 2020, and 70 days in July - September 2021.

Site 2 is located close to the ice front approximately 50km from Ross Island and is expected to be influenced by seasonal changes in basal melting (Figure 1). High basal melt rates have been observed in this region and correlate with declines in sea ice cover and warming of the AASW during the austral summer (Stewart et al., 2019). Site 2 is located within the "passive" region of the ice shelf and thus this region can be removed without reducing the buttressing potential of the ice shelf (Fürst et al., 2016). Site 2 GNSS unit recorded every 30 seconds and has 104 days of data missing in June - November 2020 and 30 days in July - August 2021.

Site 3 is located in the mid-shelf region of the RIS (200km from the calving front) and is the same site (referred to as DR10) previously reported in Klein et al. (2020) and Mosbeux et al. (2023) (Figure 1). Ice flow in the central portion of the RIS is primarily extensional which leads to along-flow thinning (Das et al., 2020). There are no pinning points or ice rises within 300km of Site 3, and no observations of high basal (Adusumilli et al., 2020) or surface (Agosta et al., 2019) melt rates here. The Site 3 GNSS unit recorded every 30 seconds for 1 year (2015 - 2016), with a few days dropped in the austral winter of 2016 (Klein et al., 2020).

Finally, Site 4 is located at the Kamb Ice Stream (KIS) grounding line (Figure 1). The KIS has been inactive for the last 160 years likely due to a change in subglacial hydrology (Retzlaff and Bentley, 1993; Thomas et al., 2013; Hulbe et al., 2016). The KIS used to flow at speeds of 350 m/a but presently flows at speeds of less than 5 m/a (Rignot et al., 2017; Ng and Conway, 2004). Studies have indicated that the KIS could reactivate this century due to its hydrological setting and the length of time it has been inactive (Bougamont et al., 2015; van der Wel et al., 2013). Site 4 GNSS unit recorded every 30 seconds and operated continuously, but was shifted approximately 2.7km upstream in December 2020.

2.2 Global Navigation Satellite Systems processing

GNSS data were processed using the Precise Point Positioning (PPP) methodology (Zumberge et al., 1997; Tétreault et al., 2005) and Natural Resources Canada's Canadian Spatial Reference System Precise Point Positioning (CSRS-PPP) post-processing service[1]. For the 30-second sampled continuous data (Sites 2, 3, and 4), data were divided into 3-hour segments and processed statically to obtain a single position every 3 hours. For Site 1, which has a different sampling frequency, the data were divided into 1-hour segments every 6 hours and a single position was obtained every 6 hours. Data processing was iterated whereby the initial positions were updated with the first processing results and then reprocessed to obtain new position solutions. The position solutions were then projected into polarstereographic coordinates (EPSG:3031) and then used to estimate site velocity by weighted linear regression through x and y coordinates. The position weightings were provided by the reported processing uncertainty. Regression gradients provided velocities in the x and y direction (v_x, v_y) with gradient uncertainties propagated to provide uncertainties in velocity and direction. The linear regression of positions was estimated at every time

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[1]https://webapp.csrs-scrs.nrcan-rncan.gc.ca/geod/tools-outils. Last accessed: 15.08.2023

step (either 3 hourly or 6 hourly) over centered time windows of 8 weeks duration. This provides a low-noise time series with
a high temporal fidelity (albeit smoothed) that shows the seasonal cycle in velocity without aliasing spring-neap tidal velocity
signals. The use of the 8-week duration to estimate velocity means that otherwise rapid changes in velocity are smoothed over
an 8-week period. Other time window lengths were tested and the seasonal signal was found to be largely independent of the
length used. The resulting uncertainties are low with 99% of the 1σ velocity uncertainties less than 0.04 m/a for Sites 1 and 3,
less than 0.06 m/a for Site 2, and less than 0.01 m/a for Site 4. We present all velocities as both absolute velocity (Figure 2)
and as the deviation from the initial velocity to facilitate comparison with the modelling results (Figure 4). We also present
detrended position and direction results for each site (Figures A1-A4).
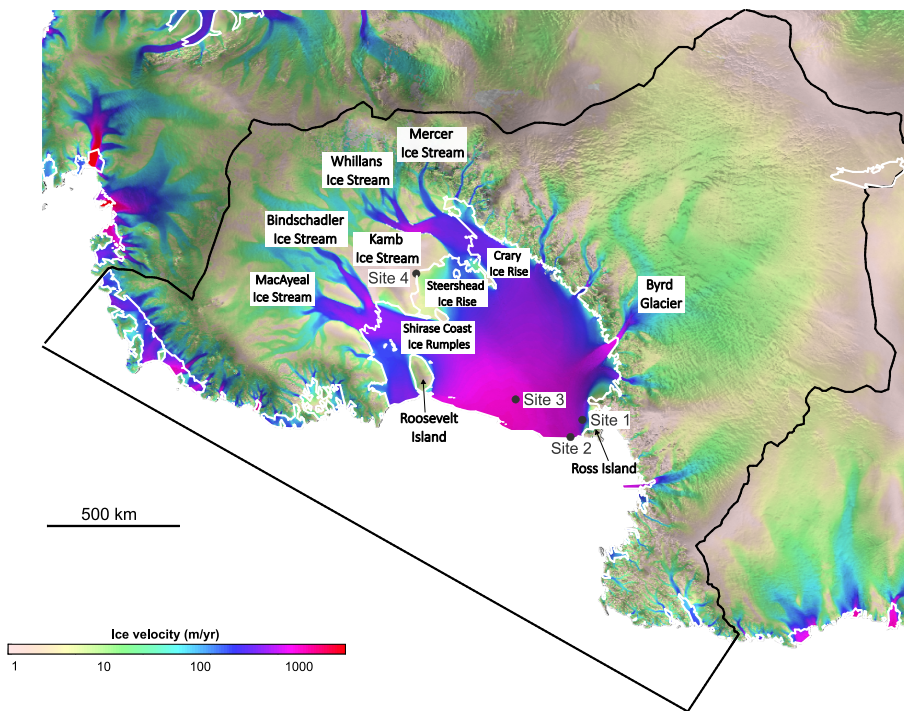
Figure 1. GNSS station locations overlain on modelled Ross Ice Shelf surface velocities. The grounding line is marked in white. GNSS
sites shown are: Site 1 (shear margin region), Site 2 (calving front), Site 3 (mid-shelf region), and Site 4 (KIS grounding zone). Other
locations discussed in this study are also labelled. These include the Siple Coast Ice Streams: Mercer Ice Stream (MIS), Whillans Ice Stream
(WIS), Kamb Ice Stream (KIS), Bindschadler Ice Stream (BIS), and MacAyeal Ice Stream (MacIS). Byrd Glacier (BG) and Ross Island are
also labelled. In addition, the ice rises are labelled on the Siple Coast: Crary Ice Rise (CIR), Steershead Ice Rise (SIR), Shirase Coast Ice
Rumples (SCIR), and Roosevelt Island. The projection of this map and all others presented is polar stereographic with a true scale at -71°
(EPSG:3031).

2.3 Automatic Differentiation

We use Automatic Differentiation (AD, Sagebaum et al., 2019) in the Ice-sheet and Sea-level System Model (ISSM) to explore the influence that changes in basal melt have on the ice velocity at each GNSS site. The complete model description is available in Baldacchino et al. (2022). Here, instead of computing the sensitivity of the model's final volume above flotation, we are interested in the sensitivity of the model velocity at these four GNSS sites. AD allows us to efficiently map by how much the velocity at each site would be affected if we perturb the ocean-induced melt at the scale of the model mesh.

The model domain covers the entire RIS and has a non-uniform mesh with a resolution of 1km at the grounding lines and in the shear margins, 20km in the ice sheet interior, and at most 10km within the ice shelf. The basal friction coefficient over grounded ice and the ice viscosity parameter of the floating ice, B, is inferred through a data assimilation technique (Morlighem et al., 2010, 2013) to reproduce observed InSAR surface velocities from the MEaSURES data-set (Rignot et al., 2017; Baldacchino et al., 2022). Environmental boundary conditions include RACMO2.3p2 Surface Mass Balance (Van Wessem et al., 2018) and Massachusetts Institute of Technology general circulation (MITgcm) basal melt rates (Losch, 2008; Holland and Jenkins, 1999; Davis and Nicholls, 2019; Baldacchino et al., 2022). The ice sheet model is run forward for 20 years to allow the grounding line position and ice geometry to relax.

After relaxation, we run the AD model for 6 months and evaluate the sensitivity of the final velocity at each of the four GNSS sites to perturbations in basal melting rates under floating ice, $\dot{M}_b$. Automatic differentiation provides the gradient of the final velocity at each site, v_i, to basal melt: $\mathcal{D}v_i(\dot{M}_b)$. In other words, the first order response of the velocity to a given perturbation $\epsilon\delta\dot{M}_b$ in $\dot{M}_b$ (where $\epsilon \in \mathbb{R}$, and $\delta\dot{M}_b$ is defined over the entire model domain Ω that can be spatially variable) is given by:

$$v_i(\dot{M}_b + \epsilon\delta\dot{M}_b) = v_i(\dot{M}_b) + \epsilon \int_\Omega \mathcal{D}v_i(\dot{M}_b)\, \delta\dot{M}_b\, d\Omega + \mathcal{O}\left(\epsilon^2\right). \tag{1}$$

The gradient, $\mathcal{D}v_i(\dot{M}_b)$ (in m^{-2}), therefore highlights the regions where the modelled velocity at a given site is most sensitive to changes in $\dot{M}_b$, and the regions where changes in $\dot{M}_b$ would not affect the final velocity at a first order.

This approach provides four sensitivity maps, one for each site. Figure A5 shows the areas where this sensitivity is higher than our threshold value of 2e-11 m^{-2}. The sensitivity threshold value of 2e-11 m^{-2} is chosen to highlight the areas sensitive to basal melt changes. Choosing a lower sensitivity threshold would enlarge the surface area over which the perturbation would need to be applied, and a higher sensitivity threshold would have the opposite effect. We chose a sensitivity value of 2e-11 m^{-2} to highlight areas of high sensitivity over a surface area that is not too restrictive or extensive across the ice shelf (Figure A5). We also include a lower sensitivity value of 0.5e-11 m^{-2} (Figure A6) in our experiments to highlight that the modelled velocity variations are similar for both sensitivity thresholds. These sensitive regions, highlighted in dark red, show where an increase in basal melt rates leads to an increase in ice velocity for each site, and therefore where changes in melt rates would impact ice velocity at these sites the most. Finally, we perform additional experiments where we only perturb the basal melt rates at the identified sensitive regions close to the Ross Island pinning point (Figure A7). These experiments are performed

to understand whether changes in basal melting at the calving front can solely reproduce the intra-annual velocity variations observed at the GNSS sites.

2.4 Modelled perturbed basal melt

We next perform a set of modelling experiments within ISSM to identify what magnitude of basal melt variability is needed to match the GNSS observed changes in ice speed. In these modelling experiments, the MITgcm baseline basal melt rates are perturbed seasonally (using a sine function that includes both melting and refreezing) (Figures A8 and A9) at regions identified as highly sensitive in the final AD map for each GNSS sites:

$$\dot{M}_b(t) = \begin{cases} \mathrm{MITgcm}(t) + p \sin\left(4\pi \times t + \pi\right), & \text{if one or more maps shows a sensitivity} > 2\text{e-}11 \text{ m}^{-2} \\ \mathrm{MITgcm}(t), & \text{otherwise} \end{cases} \tag{2}$$

where $\mathrm{MITgcm}(t)$ is the unperturbed melt rate from the MITgcm (Figure A8), and p is the amplitude of the perturbation, taken here as 0, 20, 40, 60 or 80 m/a. A sine function with two peaks is used to simulate two basal melt peaks per year (Figure A9). These peaks happen in April and October using the $+\pi$ phase shift. Two basal melt peaks per year are needed to reproduce the observed intra-annual velocities at the GNSS sites. The unperturbed MITgcm basal melt rates display a seasonal signal with a clear peak in the austral summer, and multiple smaller peaks throughout the year, highlighting that the basal melt rates already have large intra-annual variability (Figure A8). However, the amplitude of this seasonal variability in the baseline MITgcm basal melt rates is not large enough and the phasing incorrect to reproduce the GNSS observed velocity variability. The model is run forward for an additional 20 years to allow the geometry and grounding line to stabilize using the same model setup as described above (Section 2.3).

2.5 Modelled seasonal sea surface height

As discussed previously, Mosbeux et al. (2023) showed that variability in the RIS velocities can be attributed to seasonal variability in sea surface height (SSH). To explore this potential driver of velocity variability for our new GNSS datasets, we force our model with the SSH perturbations that Mosbeux et al. (2023) used in their study. Mosbeux et al. (2023) interpolated the SSH forcing from the ocean model of Tinto et al. (2019) as a monthly forcing and applied a parameterisation of the friction in the grounding zone (refer to Mosbeux et al. (2023) for further details). We interpolate the SSH forcing onto our ISSM grid for the RIS, following the same model set-up described in Section 2.3. Mosbeux et al. (2023) highlights that there are two main effects of SSH variability on ice shelf velocities: (1) changes in driving stress and (2) changes in basal stress through grounding line migration. Our modelling experiments only accounts for hydrostatic-based grounding line migration and therefore do not account for the potential role of viscoelasticity (similar to modelling experiment ΔLB2 in Mosbeux et al. (2023)).

3 Results

3.1 GNSS Velocities

3.1.1 Site 1

GNSS velocity observations for Site 1 are presented in Figure 2. Site 1's velocities range from a maximum of 447 m/a to a minimum of 441 m/a with a clear decrease in velocities of 4 m/a over the two years (Figure 2). Figure 2 displays an intra-annual signal with two velocity peaks: one in June (austral winter) and one in January (austral summer). These velocity peaks are preceded by periods of acceleration (April - June and November - January) and periods of deceleration (February - April and July - October) (Figure 2). An acceleration of 2 m/a for the peak in June 2020, 1.5 m/a for the peak in January 2021 and 1.5 m/a for the peak in June 2021 highlights the largest seasonal velocity variations at Site 1 (Figure 2).

3.1.2 Site 2

GNSS velocity observations for Site 2 are presented in Figure 2. The velocities range from a maximum of 745 m/a to a minimum of 739 m/a, with a clear intra-annual signal observed at Site 2 (Figure 2). Two distinct velocity peaks are observed at Site 2: one in December (austral summer) and one in July (austral winter). These velocity peaks are preceded by periods of acceleration (April - July and October - December) and periods of deceleration (January - April and July - October) (Figure 2). An acceleration of 5 m/a for the peak in July 2020, an apparent acceleration of 1.5 m/a for the peak in December 2020 (the lower limit was not observed), and an acceleration of 3 m/a for the peak in July 2021 highlights the largest seasonal velocity variations at Site 2 (Figure 2). Site 2 displays a larger maximum velocity of 745 m/a compared to Site 1's maximum velocity of 447 m/a.

3.1.3 Site 3

GNSS velocity observations for Site 3 range from a maximum of 937 m/a to a minimum of 929 m/a and thus display higher maximum velocities compared to Sites 1 and 2 (Figure 2). However, Site 3's intra-annual signal is different to Sites 1 and 2, with a small peak observed in March (austral summer) and a large peak in August (austral winter) (Figure 2). These velocity peaks are preceded by periods of acceleration (January - March and April - August) and periods of deceleration (March - April and September - December) (Figure 2). A small acceleration of 1 m/a for the peak in March 2016 and a much larger acceleration of 8 m/a for the peak in August 2016 is observed (Figure 2). Site 3 was also presented in Klein et al. (2020); Mosbeux et al. (2023) (referred to as DR10), and they display similar results to ours. Both studies display a small velocity peak in January and a large velocity peak in July (Klein et al., 2020; Mosbeux et al., 2023). The velocity variability ranges from -6 m/a in March, and +6 m/a in July, which is a similar range of velocity values found in this study (-7 m/a in April to +1 m/a in August) (Figure 4). However, our velocity peaks (March and August) are offset by 1 - 2 months compared to the findings presented in Klein et al. (2020); Mosbeux et al. (2023). These differences in the phasing of the intra-annual velocity variability
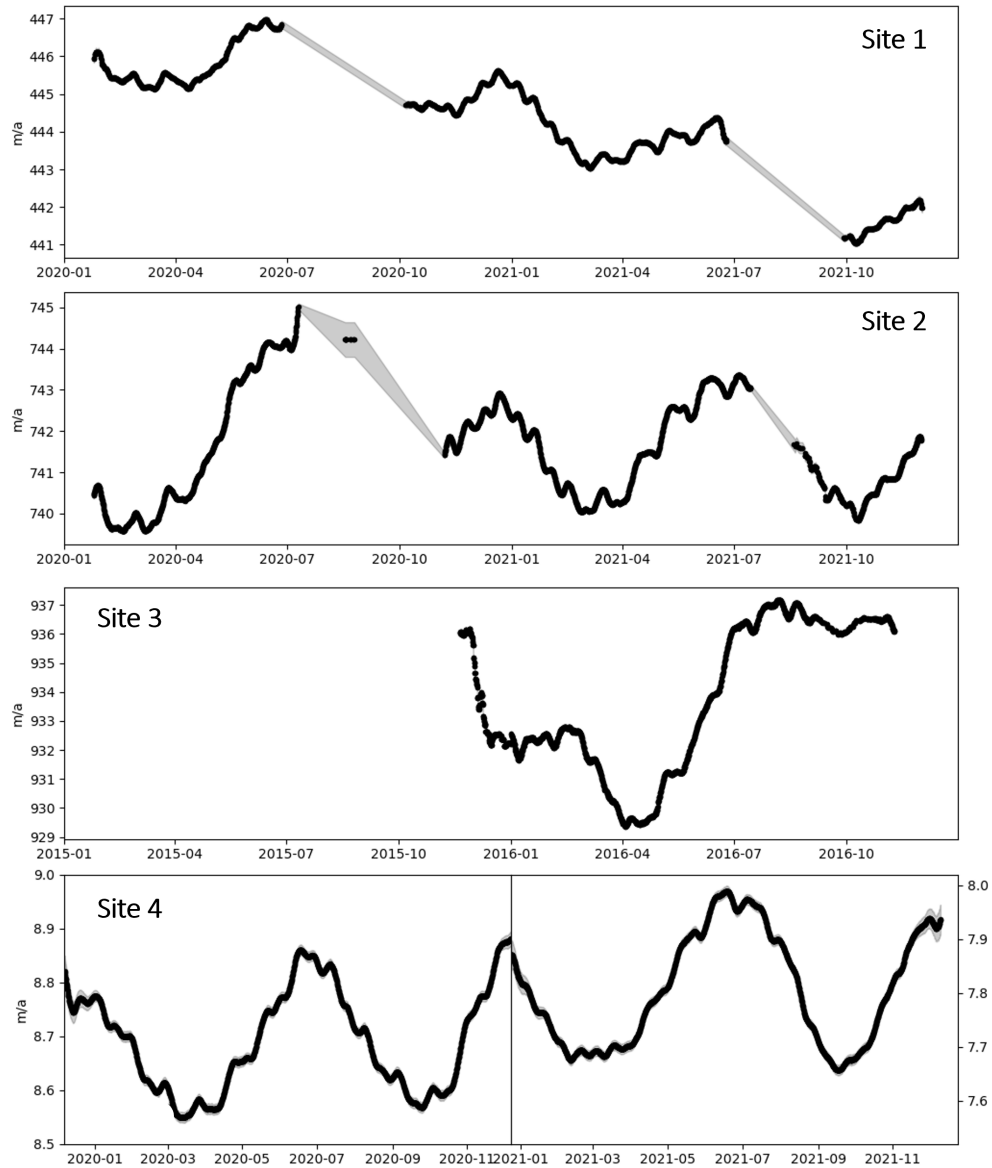
Figure 2. The GNSS velocities (in m/a) at Site 1 (shear margin region), Site 2 (calving front), Site 3 (mid-shelf region), and Site 4 (KIS grounding zone). The uncertainties are provided in the grey windows enclosing the black lines. These uncertainties are not visible in a few places, as they are very small. Detrended position and direction for each site is shown in Figures A1-A4

are likely due to small differences in methodology between the studies, such as the use of T-TIDE analysis (Pawlowicz et al., 2002) and the time window used for smoothing the datasets.

3.1.4 Site 4

The stagnation of KIS results in Site 4's low velocities compared to Sites 1, 2, and 3 (Figure 2). Site 4 displays a clear intra-annual signal which is similar to Sites 1 and 2 (Figure 2). Two velocity peaks are observed at Site 4 for the years 2020 and 2021: one in December (austral summer) and one in June (austral winter) (Figure 2). Site 4 has the most complete record of GNSS velocity measurements for two years and thus highlights the intra-annual velocity variation clearly. These velocity peaks are preceded by periods of acceleration (March - June and October - December) and periods of deceleration (January - March and July - August) (Figure 2). Site 4 displays a small acceleration of 0.4 m/a for the peak in June 2020, 0.3 m/a for the peak in December 2020, 0.3 m/a for the peak in July 2021 and 0.3 m/a for the peak in December 2021 (Figure 2). The magnitude of intra-annual variability at each site scales with distance from the calving front, also observed by Klein et al. (2020).

A fortnightly signal is found in the displacement at all GNSS sites and we attribute this to the response of the ice shelf to spring-neap variability in the tidal cycle (Padman et al., 2003; Ray et al., 2021; Rosier and Gudmundsson, 2020). This fortnightly tide-forced variability is dampened by our use of an 8-week window for our velocity estimates (Mosbeux et al., 2023).

3.2 Sensitivity Maps

The AD model produced sensitivity maps show that high sensitivity is observed at the pinning points and ice rises downstream of the Siple Coast ice streams (i.e., Roosevelt Island, Crary Ice Rise, Steershead Ice Rise, and the Shirase Coast Ice Rumples) for all GNSS sites (Figures 1 and 3). For Sites 1, 2, and 3 we also see high sensitivity to changes in basal melting at the calving front near the Ross Island pinning point. Changes in basal melting can result in detachment from pinning points and ice rises resulting in changes in ice speed (Still et al., 2019; Baldacchino et al., 2022; Reese et al., 2018). Ross Island is a structurally critical region and Gudmundsson et al. (2019) found that melting there influences the flow speed of the entire RIS. Our sensitivity maps confirm this finding, highlighting that changes at and/or near the Ross Island pinning point influence velocities at Sites 1, 2, and 3. It is also important to highlight that Sites 1 and 2 are situated close to the Ross Island pinning point, and thus have high sensitivity to local changes in basal melt.

Additionally, high sensitivity is observed at the Siple Coast Ice Streams and Byrd Glacier grounding lines for Sites 2 and 3 (Figures 1 and 3). The grounding lines show high sensitivity because changes in basal melting there can lead to changes in basal friction and grounding line retreat (Baldacchino et al., 2022). These changes in basal friction can drive changes in the ice streams and outlet glaciers' flow dynamics and discharge (Baldacchino et al., 2022; Pattyn, 2017; Shepherd et al., 2018). We observe high sensitivity at the near-stagnant KIS grounding zone for Site 4, and no sensitivity elsewhere for this GNSS site. This high sensitivity at the KIS grounding zone highlights that local changes in basal melt at the grounding zone can influence the velocities at Site 4 and changes in basal melt elsewhere on the ice shelf do not affect Site 4 velocities.

Finally, high sensitivity within the interior of the ice shelf and directly downstream of active ice streams and outlet glaciers is observed for GNSS Sites 2 and 3 (Figures 1 and 3). Sensitivity to changes in basal melting is also observed at the "passive" region (blue outline in Figure 3 identified by Fürst et al. (2016)) for Sites 2 and 3. This indicates that local changes in basal
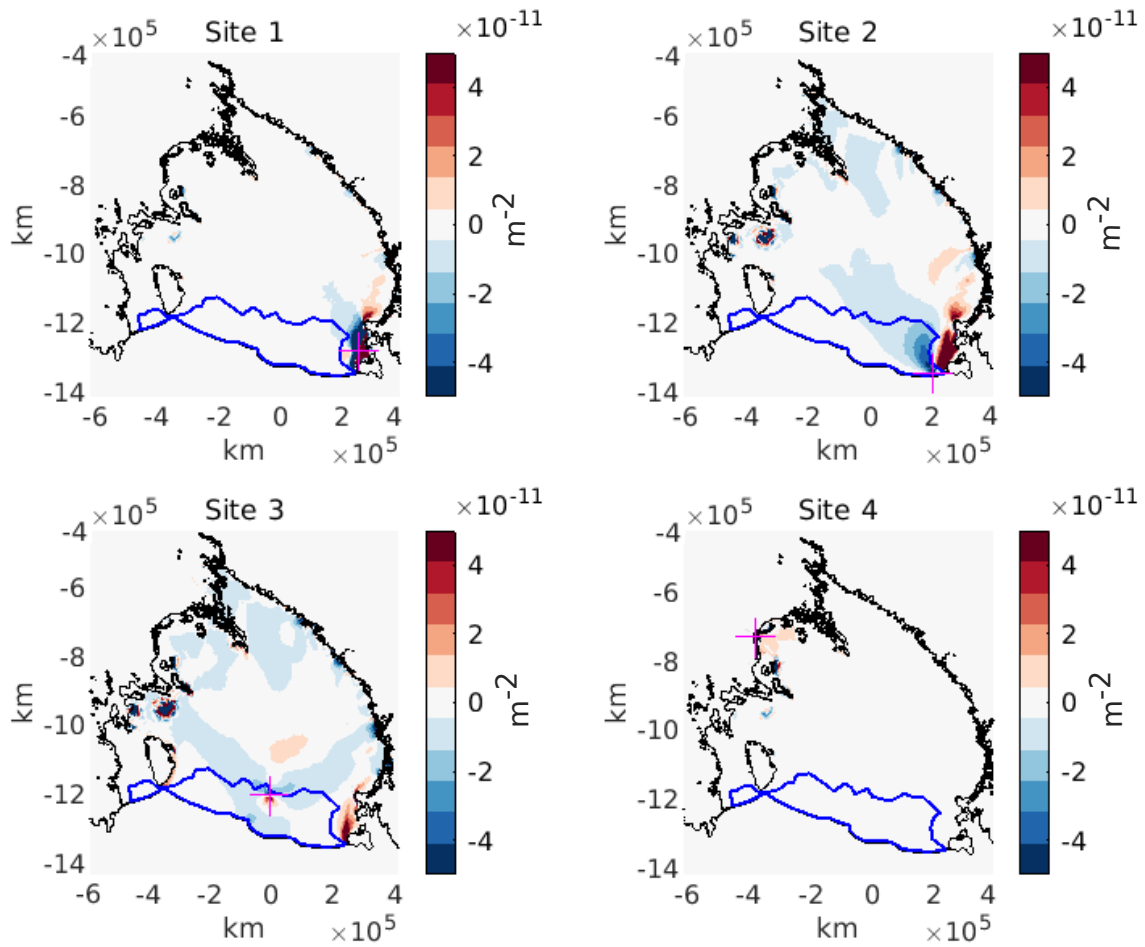
Figure 3. Sensitivity maps of the final velocity at each of the four GNSS sites to basal melt rates under floating ice $\dot{M}_b$ over 20 years (in m^{-2}). The sensitivity maps highlight that an increase (red) or decrease (blue) in basal melt rates at identified sensitive regions increases or decreases the velocities at the GNSS sites. The grounding line (black line) and passive ice (blue line) on the RIS identified by Fürst et al. (2016) are highlighted. The GNSS sites are identified using pink markers.

melt affect the velocities at Sites 2 and 3 as both these sites are located in the "passive" region. Overall, the sensitivity maps show that GNSS Sites 2 and 3 velocities have high sensitivity to basal melting across the majority of the ice shelf, compared to Sites 1 and 4, which have higher sensitivities to local changes in basal melting.

3.3 Modelled Velocities

255   The modelled velocity variations are compared to the GNSS velocity variations (change from the initial velocity) for each site
in Figure 4. We model two distinct velocity peaks: one in January (austral summer) and one in June (austral winter) for the
experiments using our idealized sinusoidal basal melt perturbation at the identified sensitive regions. For all GNSS sites, we
observe that the intra-annual velocity variation is small when we perturb the basal melt rates by a magnitude of 20 m/a, and this
intra-annual velocity variation quadruples when we perturb the basal melt rates by a magnitude of 80 m/a (Figure 4). Figure 4

260   shows that for Sites 1, 2, and 3 the use of the lower sensitivity threshold (dotted black line) did not significantly affect the final
modelled velocity variations. Additionally, Figure 4 shows that for Sites 1, 2, and 3 the perturbation of basal melt rates close
to Ross Island (solid black line) produces similar velocity variations to the other model experiments. However, for Site 4 the
velocity variations are much smaller even when large amplitudes are employed for the perturbation.
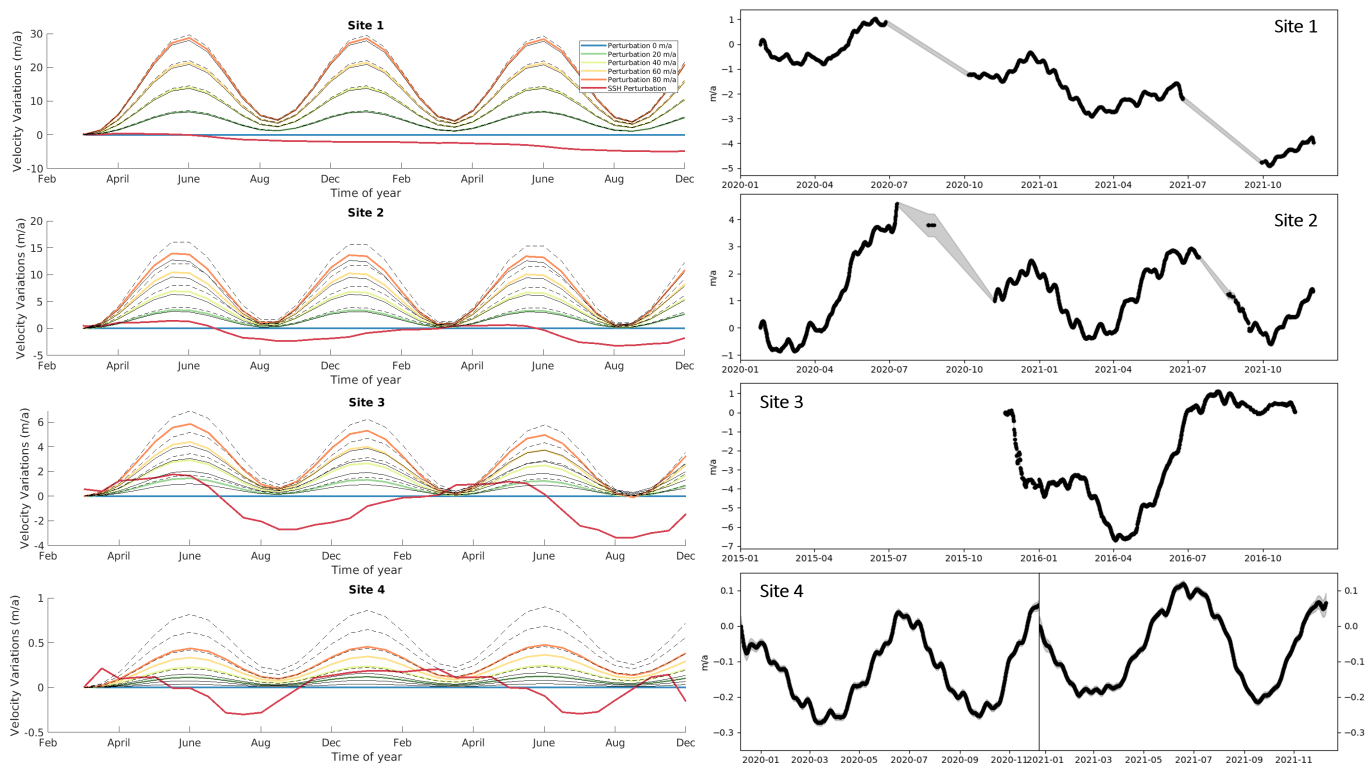
Figure 4. The modelled (left) and GNSS (right) velocity variations (in m/a) at each GNSS site: Site 1 (shear margin region), Site 2 (calving front), Site 3 (mid-shelf region), and Site 4 (KIS grounding zone). The dotted black line represents the additional sensitivity threshold value experiment (lower sensitivity value of 0.5e-11 m^{-2}) and the solid black line represents the additional sensitivity experiment where we only perturbed the basal melt rates close to Ross Island. Note here that we are comparing velocity changes induced by perturbed basal melt rates at identified sensitive regions to velocity changes induced by raw SSH over the entire domain.

Our basal melt perturbed model produces an intra-annual variation in velocity at Site 1 ranging from 1 m/a to 5 m/a for 20 m/a basal melt perturbation and 6 m/a to 28 m/a for the 80 m/a basal melt perturbation (Figure 4). An increase of 4 m/a for the velocity peaks in January and June is observed in the 20 m/a basal melt perturbed model experiments, which is most similar to Site 1's GNSS observed accelerations of 2 m/a for the velocity peak in June 2020, 1.5 m/a for the velocity peak in January 2020 and 1.5 m/a for the velocity peak in June 2021 (Figure 4). The seasonal SSH perturbed model displays little to no intra-annual velocity variability for Site 1 (Figure 4).

The basal melt perturbed modelled intra-annual velocity variations at Site 2 range from 0 m/a to 3 m/a for 20 m/a basal melt perturbation and 2 m/a to 13 m/a for the 80 m/a basal melt perturbation (Figure 4). The phasing of the modelled velocity peaks (January and June) are offset by one month compared to the GNSS observed velocity peaks (December and July) (Figure 4). However, the 20 m/a basal melt perturbed modelled velocity variation is similar in amplitude to the GNSS velocity variations. An increase of 3 m/a for the peaks in January and June is observed in the 20 m/a basal melt perturbed model experiments, which is most similar to Site 2's GNSS observed accelerations of 5 m/a for the peak in July 2020, 1.5 m/a for the peak in December 2020 and 3 m/a for the peak in July 2021 (Figure 4). The seasonal SSH perturbed model displays an intra-annual velocity variability with a different phasing but similar amplitude to the GNSS observations at Site 2 (Figure 4). The SSH forced velocities display one distinct peak per year (late May), with a velocity minimum in August (Figure 4).

For Site 3, the modelled intra-annual velocity variations range from 0 m/a to 1 m/a for 20 m/a basal melt perturbation and 1.5 m/a to 4 m/a for the 80 m/a basal melt perturbation (Figure 4). The phasing of the modelled velocity peaks (January and June) is offset by a couple of months compared to the GNSS observed velocity peaks (March and August) (Figure 4). Additionally, an increase of 1 m/a for the peak in March and 8 m/a for the peak in August is observed by the GNSS receiver at Site 3 (Figure 4). None of the basal melt perturbed modelled velocity variations capture an acceleration of 8 m/a in August (Figure 4). We model two velocity peaks, whereas Klein et al. (2020) modelled one velocity peak in late May, with a smaller velocity range (-0.18 to +0.18 m/a). Furthermore, the seasonal SSH perturbed model displays an intra-annual velocity variability with a different phasing to the GNSS observations (Figure 4), but the amplitude of velocity variations is most similar to the observations. The SSH forced velocities display a velocity maximum in May and a velocity minimum in August. Mosbeux et al. (2023) modelled a velocity peak in August for Site 3, highlighting that our modelled velocity peak is offset by a couple of months. This may be due to our modelling experiments not taking into account the potential role of viscoelasticity.

Finally, the modelled intra-annual velocity variations at Site 4 range from 0.01 m/a to 0.04 m/a for 20 m/a basal melt perturbation and 0.04 m/a to 0.15 m/a for the 80 m/a basal melt perturbation (Figure 4). The phasing of the modelled velocity variations is similar to the GNSS-measured velocity variations with a clear intra-annual signal observed. The modelled velocity peaks occur in January and June which is similar to the GNSS-measured velocity peaks at the end of December and in June (Figure 4). However, none of the modelled velocity variations of the basal melt perturbation experiments could reproduce the amplitudes of the GNSS observed velocity variations. An increase of 0.4 m/a for the peak in June 2020, 0.3 m/a for the peak in December 2020, 0.3 m/a for the peak in July 2021 and 0.3 m/a for the peak in December 2021 (Figure 4). An increase of 0.11 m/a for the peaks in January and June is observed in the 80 m/a basal melt perturbed model experiments and is most similar to the GNSS-measured velocity variations at Site 4. The seasonal SSH perturbed model displays an intra-annual velocity

variability with only one velocity peak per year (February) (Figure 4), but the amplitude of velocity variations is most similar
300   to the GNSS observations, ranging from -0.4 to 0.3 m/a (Figure 4).

4   Discussion

4.1   Local perturbations

In this study, instead of perturbing basal melt rates uniformly everywhere, as has been done previously (Klein et al., 2020),
we only perturb basal melt rates at identified sensitive regions of the ice shelf. Our sensitivity maps highlight that very local
305   perturbations in basal melt can have a significant effect on the ice flow speed, sometimes 1000km away from GNSS sites
(Figure 3). We find that GNSS Sites 1, 2, and 3 are most sensitive to local perturbations in basal melt rates near the Ross
Island pinning point. This can be explained by the loss of buttressing force triggered by ice shelf thinning near the Ross Island
pinning point. This loss of buttressing force is due to reduced ice thickness near the Ross Island pinning point, and a decreased
transmission of stresses from the pinning point to the rest of the ice shelf. Previous studies have shown that Ross Island is
310   an important pinning point for the RIS, with changes in ice thickness here found to significantly impact overall ice shelf
dynamics (Reese et al., 2018; Gudmundsson et al., 2019). Ice shelf thinning can reduce the buttressing force exerted by these
pinning points (Larter, 2022; Arndt et al., 2018; Joughin et al., 2021; Dupont and Alley, 2005; Gudmundsson et al., 2019). Our
sensitivity maps confirm this finding, highlighting that Sites 1, 2 and 3 ice speeds are highly sensitive to local changes in basal
melt at the calving front near the Ross Island pinning point.

315   Furthermore, we find that at GNSS Site 4, ice speed is most sensitive to local perturbations in basal melt rates at the KIS
grounding zone, with changes in basal melt elsewhere on the ice shelf having almost no impact on ice speed at this site. Changes
in basal melting near the grounding zones generally leads to ice thinning and grounding line retreat (Baldacchino et al., 2022;
Ranganathan et al., 2021), which induces an increase in flow speed. Additionally, ice thinning reduces the buttressing effect
from ice rises downstream of the KIS grounding zone, which drive changes in the velocities at Site 4 and elsewhere on the ice
320   shelf.

4.2   Magnitude of variability

We perturb the basal melt rates to peak in April and October to match the observed intra-annual velocity variability on the
ice shelf (Figures 2 and 4). Current basal melt observations display large variability in melt rates throughout the year at the
calving front near Ross Island, with large basal melt peaks in the austral summer (January - March) of > 3 m/a and smaller
325   basal melt peaks in early (April and/or May) and late austral winter (October and/or November) of 1 - 2 m/a (Stewart et al.,
2019; Jendersie et al., 2018; Årthun et al., 2013). These basal melt peaks in the early winter are due to the remnant heat from
the summer AASW inflow and in late winter are due to the inflows of HSSW into the ice shelf cavity when large heat loss
and sea ice production leads to active cross-frontal flow that ventilates the cavity (Stewart et al., 2019; Jendersie et al., 2018;
Årthun et al., 2013). These smaller basal melt peaks in early and late austral winter align with the sinusoidal phasing of our

330 idealized basal melt perturbations. However, we do not capture the variability in basal melt during the rest of the year, and the significantly larger basal melt peaks observed in the austral summer (January - March) (Stewart et al., 2019) (Figures A8 and A9). Therefore, our idealized sinusoidal perturbed basal melt rates do not align with current observations of basal melting on the RIS.

Additionally, we perturb the basal melt rates with a range of magnitudes (20 - 80 m/a) to try and match the observed intra-
335 annual velocity variability on the ice shelf. Our results show that we need to perturb the basal melt rates near the Ross Island shear zone by a magnitude of 20 m/a for Sites 1 and 2 to match the GNSS observations (Figures 3, 2 and 4). Our AD-inferred sensitivity map shows that we do not need 20 m/a of perturbation under the entire ice shelf, but only over 2% of the ice shelf (i.e., identified sensitive regions). The RIS has low annual average basal melt rates across the ice shelf (0 - 1 m/a), with the highest average basal melt rates observed at the ice shelf front (> 3 m/a), near Ross Island pinning point (Stewart et al., 2019;
340 Stevens et al., 2020; Das et al., 2020; Adusumilli et al., 2020; Schodlok et al., 2016; Assmann et al., 2003; Holland et al., 2003; Stern et al., 2013). Recently Stewart et al. (2019) has observed high austral summer basal melt rates of 10 - 50 m/a at the calving front near Ross Island, due to the seasonal inflow of summer-warmed AASW from the adjacent Ross Sea Polynya downwelling into the ice shelf cavity. However, these observed higher basal melt rates occur during the austral summer, and we perturb basal melt rates with magnitudes of $\geq$ 20 m/a in early and late austral winter. For Site 4 we also need to perturb
345 the basal melt rates with significantly high magnitudes (80 m/a) at the KIS grounding zone and Siple Coast ice rises to match the GNSS observations. Observed basal melt rates are low for the interior of the ice shelf (0 - 1 m/a), with localised high basal melt rates of 22.2±0.2m/a observed near grounding lines of the Siple Coast Ice Streams (Marsh et al., 2016; Adusumilli et al., 2020). These studies show that the magnitudes that we use to perturb the basal melt rates on the RIS are significantly higher than observed, which may indicate that our perturbation is not realistic. Additionally, our perturbation represents a sine
350 function, and thus it peaks and troughs at the same magnitudes (i.e., peaks at 25 m/a, and troughs at -25 m/a) to include both melting and refreezing (Figure A9). These negative basal melt rates (i.e., refreezing) are significantly higher than expected for the RIS, especially in the summer (Figures A8 and A9) (Stewart et al., 2019).

Our findings indicate that basal melt rates are only capable of causing the observed velocity variations after we apply our idealized sinusoidal perturbations. As the required perturbations are significantly higher than expected, it is likely that other
355 mechanisms are driving the observed velocity variations. However, we highlight if melt alone was responsible, and it occurred only at sensitive regions of the ice shelf, then a variability in basal melting with peaks of 20 - 80 m/a in April and October would be needed to match the GNSS observations at Sites 1, 2 and 4.

4.3 Other potential drivers of variability

We can match GNSS observations at Sites 1, 2 and 4 when applying our idealized sinusoidal basal melt perturbations at
360 identified sensitive regions. However, we are unable to do so for Site 3, which is consistent with the conclusions of Klein et al. (2020). Here we list some other possible drivers.

Most recently, Mosbeux et al. (2023) has shown that the seasonal variability of sea surface height (SSH) modifies ice velocity by changing (1) the driving stress by locally tilting the ice shelf and (2) the basal condition in the grounding zone.

Our results indicate that seasonal variability in SSH alone cannot reproduce the two velocity peaks per year observed at our
365   new GNSS sites. We suggest that Mosbeux et al. (2023) were able to reproduce the velocity variability recorded at Site 3 due
to implementing additional parameterization of viscoelastic processes in their model. However, we find a closer similarity in
velocity amplitudes at Sites 2, 3 and 4 to the GNSS measurements when forced by changes in SSH compared to basal melt.
Therefore, seasonal variations in SSH are likely contributing to velocity changes on the RIS as indicated by Mosbeux et al.
(2023).

370   Greene et al. (2018) found that changes in buttressing from sea ice can explain the seasonal cycle of Totten Glacier's ice
shelf velocities. Sea ice cover in the Ross Sea decreases in the austral summer and increases in the austral winter, suggesting
that ice shelf velocities would increase in the austral spring and decrease in the austral winter if forced by variations in sea ice
backstress (Greene et al., 2018; Cassotto et al., 2015; Howat et al., 2010). However, we observe an acceleration in ice shelf
velocities in austral summer and austral winter, indicating that the GNSS velocity variations are likely not forced by variations
375   in sea ice backstress.

Seasonal variations in surface air temperatures can also influence the surface melt rates of the ice shelf (Nicolas et al., 2017a;
Trusel et al., 2015; Zou et al., 2021a, b) and drive variations in velocities. For example, it has been shown that surface meltwater
influences ice shelf velocity by percolating through and weakening the ice shelf shear margins (Cavanagh et al., 2017; Vaughan
and Doake, 1996; Greene et al., 2018; Alley et al., 2018). However, the surface melt rates on the RIS are small, and the response
380   of the ice shelf velocities to summer elevated surface melting has been shown to occur over short timescales (hours to weeks)
(Stevens et al., 2022; Chaput et al., 2018; Nicolas et al., 2017a). An El-Niño event occurred in the summer of 2015/2016 when
the GNSS measurements for Site 3 were recorded. This event may have increased surface melt rates on the RIS as well as
modified wind patterns and ocean circulation (Klein et al., 2020; Paolo et al., 2015). Nicolas et al. (2017b) observed 14 days of
enhanced surface melting on the RIS, between the 10th and 21st of January 2016 due to persistent air temperatures higher than
385   -2°C in the region of Site 3 (Klein et al., 2020; Chaput et al., 2018). Klein et al. (2020) suggests that the surface heat fluxes
over the ocean during this surface melt event may have been substantially different than those used to drive the ocean models.
Therefore, the MITgcm basal melt rates likely do not take into account this high surface melt event and this may explain why
we cannot reproduce the intra-annual velocity variability observed at Site 3.

Tides are known to cause substantial variations in velocity over short periods (Anandakrishnan et al., 2003; Gudmundsson,
390   2006; Bindschadler et al., 2003) and longer periods of up to a year (Murray et al., 2007). However, Klein et al. (2020) high-
lighted that the vertical signals of tides are too small to provide a significant forcing to the horizontal movement of the RIS
through non-linear ice-ocean processes along the grounding zone as suggested by Murray et al. (2007). Our GNSS processing
smooths out short-term tidal effects, but daily variability is likely to be large, with the Ross Sea tides being almost diurnal
(Brunt et al., 2010; Padman et al., 2003). Therefore, small, solar-annual, or semi-annual (equinox) tides may drive the remain-
395   ing variability in velocities observed at the GNSS sites that our model perturbations are unable to reproduce. Additionally,
Mosbeux et al. (2023) observed a 6-month signal in their GNSS datasets on the RIS and tentatively attributed this signal to
semiannual changes in tides. This 6-month tidal signal may explain the observed intra-annual velocity variability at Site 4, and
we suggest that it is likely that the tidal signal is playing a role in observed velocity variability at all GNSS sites.

Flow variability in the Siple Coast Ice Streams has also been shown to occur on short timescales due to changes in the distribution and supply of basal meltwater (Catania et al., 2012). Recently, high basal melt rates of 35 m/a have been inferred at the KIS grounding zone within a narrow subglacially sourced basal channel (Whiteford et al., 2022). These high basal melt rates within a subglacial channel suggest that meltwater plumes could be driving changes in the subglacial hydrology system of the KIS. These changes in the subglacial hydrology may be driving variations in the velocities on intra-annual timescales by modifying the basal friction at the KIS grounding line. However, further work is needed to investigate these observed intra-annual velocity variations at Site 4, which is outside the scope of this study.

5 Conclusions

We set out to further understand the drivers of intra-annual velocity variability on the Antarctic ice shelves, using the RIS as a testbed. We present three new GNSS datasets that display an intra-annual velocity variability (two velocity peaks per year) that have not yet been explored in previous studies (Klein et al., 2020; Mosbeux et al., 2023). Notably, our new observations display a consistent periodicity that is different to previous year-round velocity observations from the Ross Ice Shelf. We investigate the potential role of basal melt variability on the RIS ice flow by (1) identifying regions where changes in melt would have the largest impact on ice speed at our GNSS sites and (2) applying idealized sinusoidal basal melt perturbations at these sensitive regions to identify what magnitude of variability is needed to match the GNSS observations. We find that localized changes in basal melt can have a strong impact on the ice shelf flow. Our sensitivity maps highlight that the pinning points and grounding lines of the RIS are highly sensitive to changes in basal melting, and have an impact on ice shelf flow speed. Additionally, we identify the magnitude of variability needed to match the GNSS observations of velocity change at the GNSS sites. We are able to match the GNSS observations at Sites 1, 2 and 4 using our idealized sinusoidal basal melt perturbations with magnitudes of 20 - 80 m/a. However, the required basal melt perturbations are significantly higher than expected for the RIS, which may indicate that these perturbations are not realistic. Therefore isolated regions of periodically-high basal melting are unlikely to be the main factor driving observed GNSS velocity variability. We also show that seasonal variability in SSH alone cannot reproduce the intra-annual velocity variability observed at the new GNSS sites. However, it is likely that changes in SSH and tides in the Ross Sea are contributing to the observed variability in velocities at all GNSS sites. We suggest that a combination of external forcings (e.g. SSH and tides) and internal mechanics (e.g. changes in buttressing forcings and basal friction) may be at play to produce the observed intra-annual velocity variability. We recommend that future work should focus on (1) continuing and expanding the multi-year GNSS records of seasonally resolved ice velocity changes on the RIS, (2) examining ice shelf interactions with basal melt rates on floating and grounded ice through coupled ocean-ice shelf models, and (3) exploring other potential drivers of intra-annual velocity variations.

Appendix A
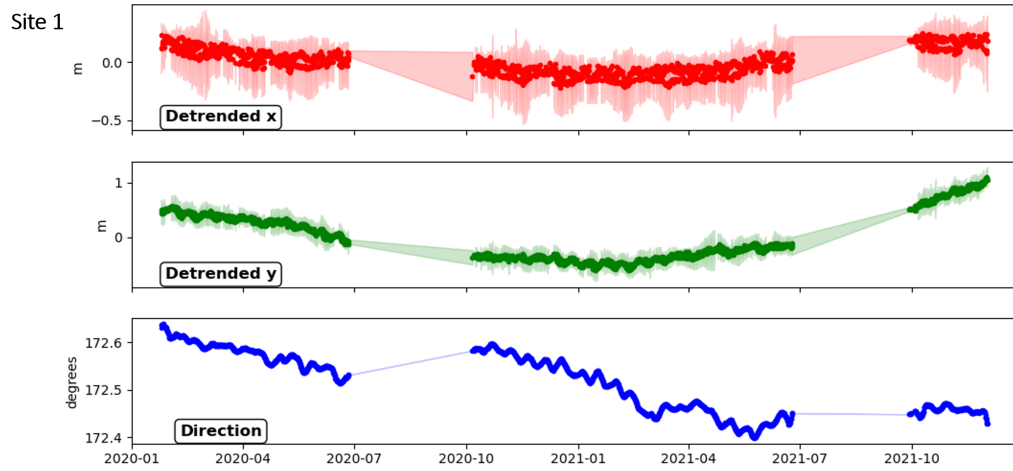
Figure A1. Site 1 GNSS detrended position (x, y) and direction (clockwise from grid north).
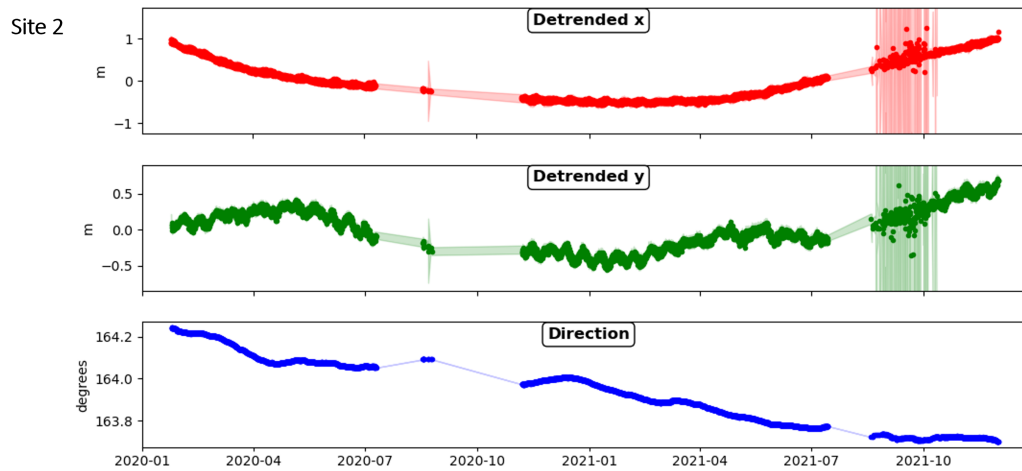
Figure A2. Site 2 GNSS detrended position (x, y) and direction (clockwise from from grid north).
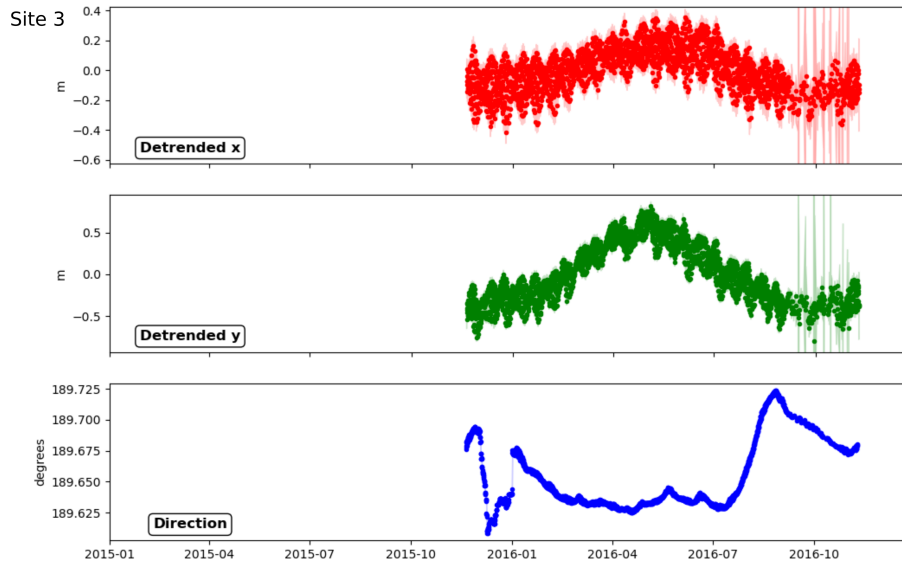
Figure A3. Site 3 GNSS detrended position (x, y) and direction (clockwise from grid north).
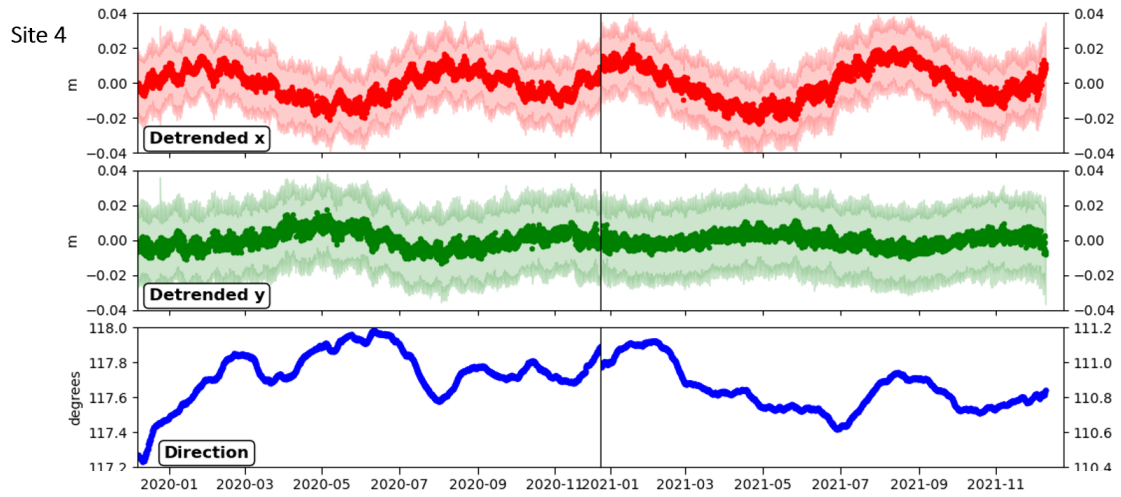
Figure A4. Site 4 GNSS detrended position (x, y) and direction (clockwise from from grid north).
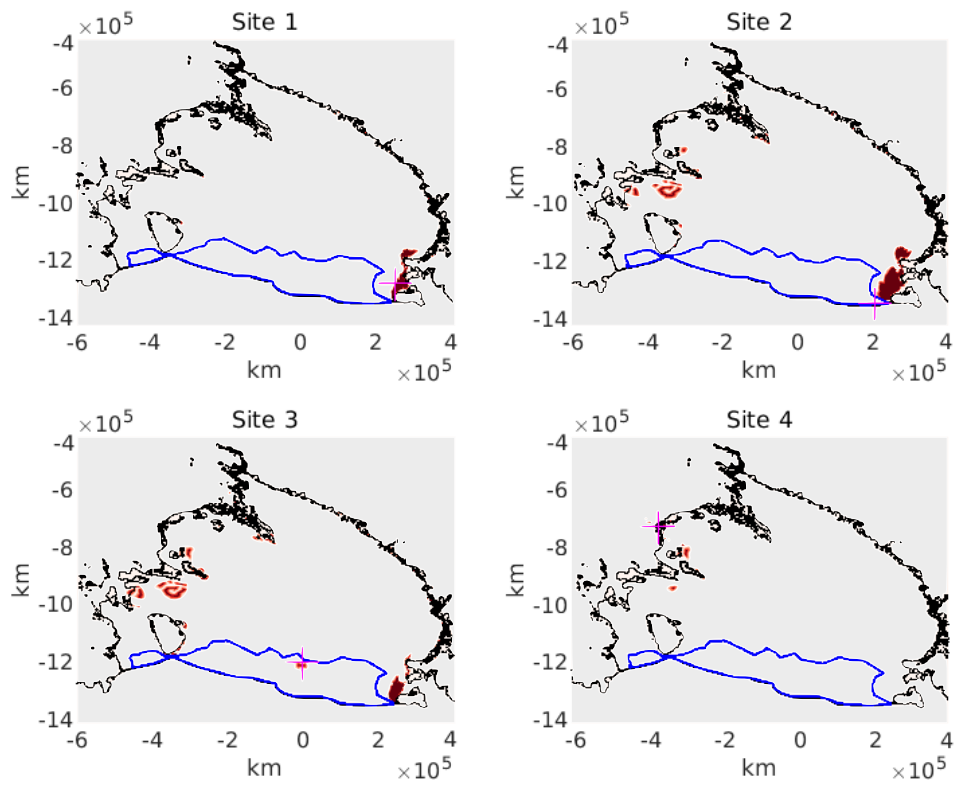
Figure A5. Locations where idealized sinusoidal basal melt perturbations were applied when the the AD mapped sensitivity threshold was set to $2e-11$ m^{-2} (dark red) for each GNSS site (pink markers). The grounding line (black line) and passive ice (blue line) on the RIS identified by Fürst et al. (2016) are highlighted.
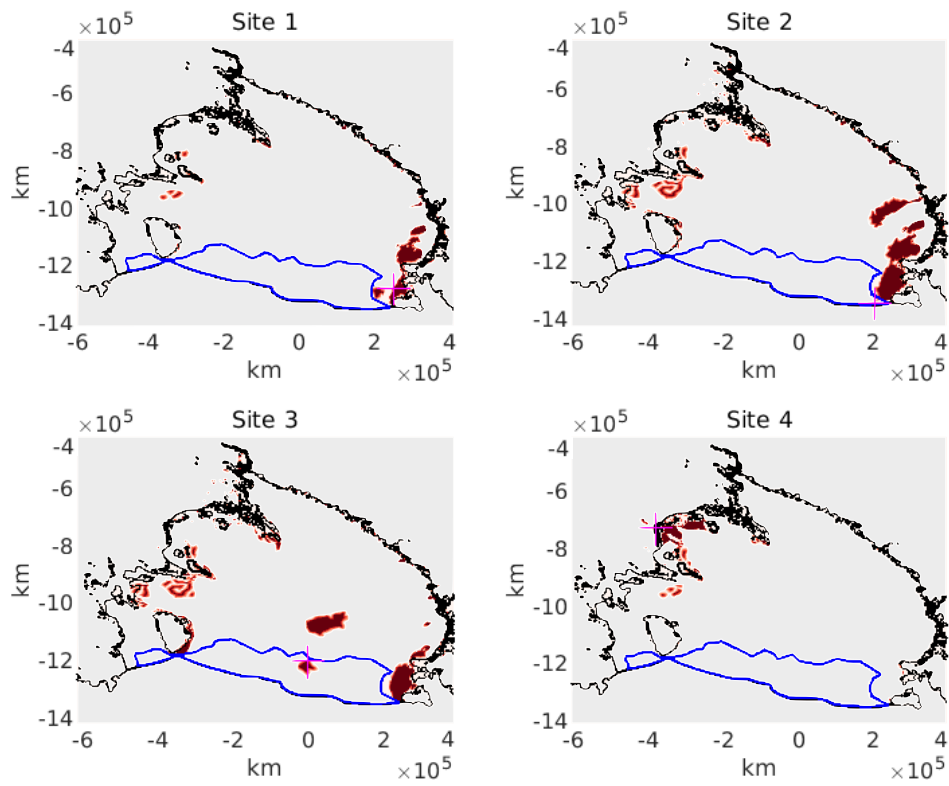
Figure A6. Locations where idealized sinusoidal basal melt perturbations were applied when the the AD mapped sensitivity threshold was set to $0.5e-11 \text{ m}^{-2}$ (highlighted in dark red) for each GNSS site (pink marker). The grounding line (black line) and passive ice (blue line) on the RIS identified by Fürst et al. (2016) are highlighted.
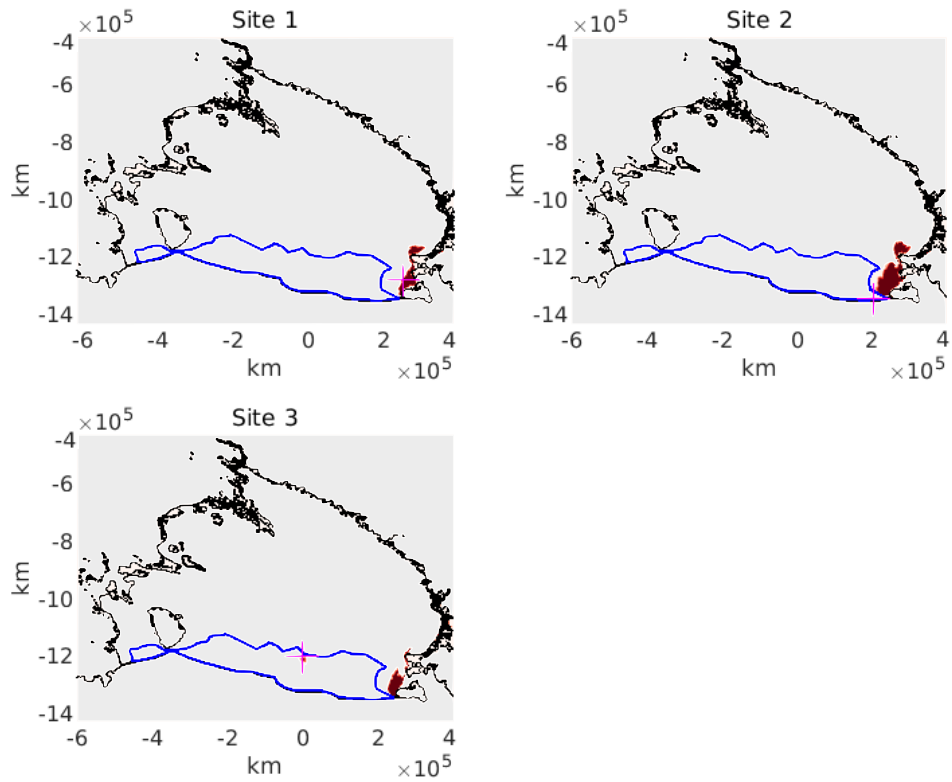
Figure A7. Locations where idealized sinusoidal basal melt perturbations were applied when the the AD mapped sensitivity threshold was set to $2e-11$ m^{-2} and limited to the calving front close to the Ross Island pinning point (highlighted in dark red) for GNSS Sites 1, 2 and 3 (pink marker). The grounding line (black line) and passive ice (blue line) on the RIS identified by Fürst et al. (2016) are highlighted.
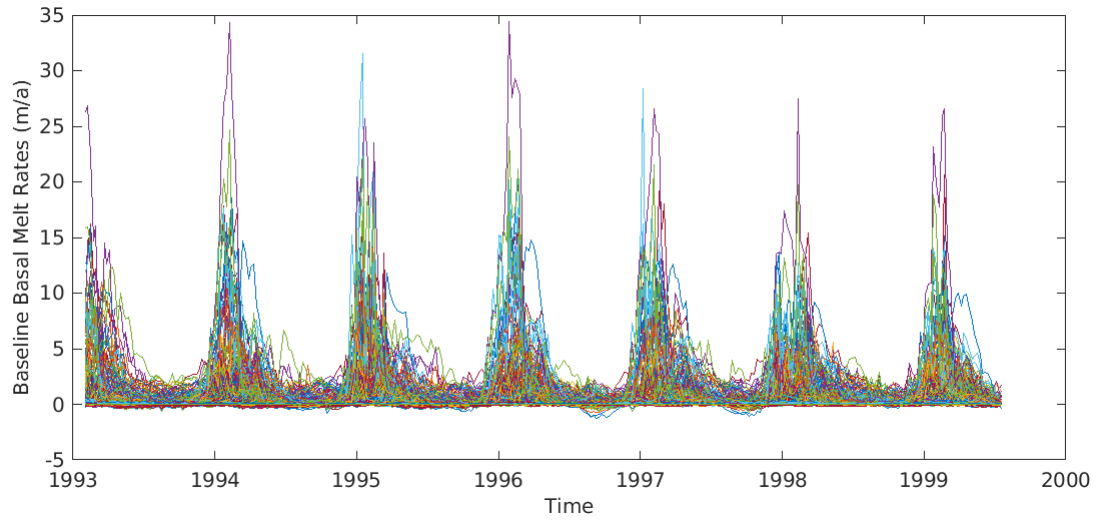
Figure A8. The baseline MITgcm basal melt rates for the identified sensitive regions (greater than $2e-11$ m^{-2}) on the RIS. Each coloured line represents basal melt at different sensitive regions (i.e., different nodes of the mesh).
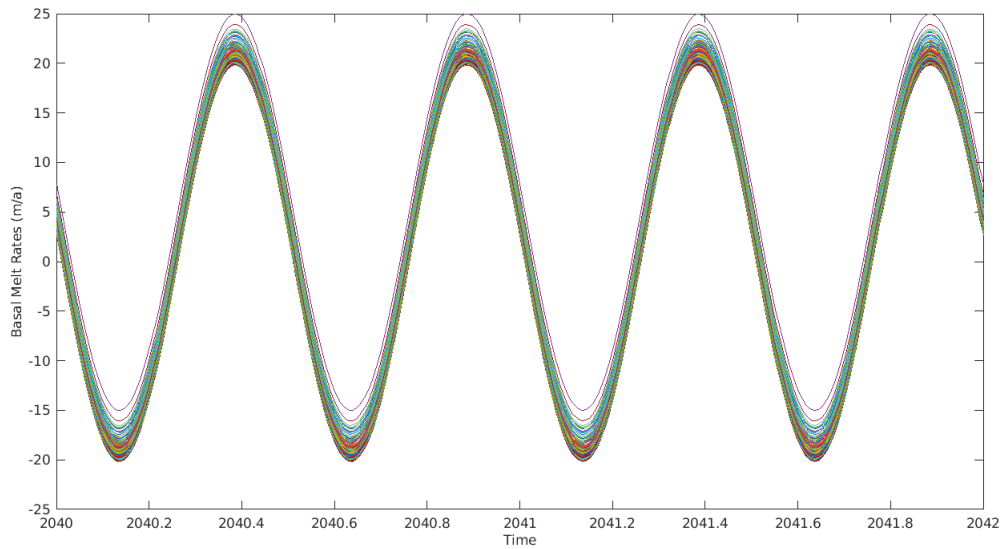
Figure A9. The idealized sinusoidal perturbed MITgcm basal melt rates at the identified sensitive regions (greater than $2e-11$ m^{-2}) on the RIS. Each coloured line represents basal melt at different sensitive regions (i.e., different nodes of the mesh).
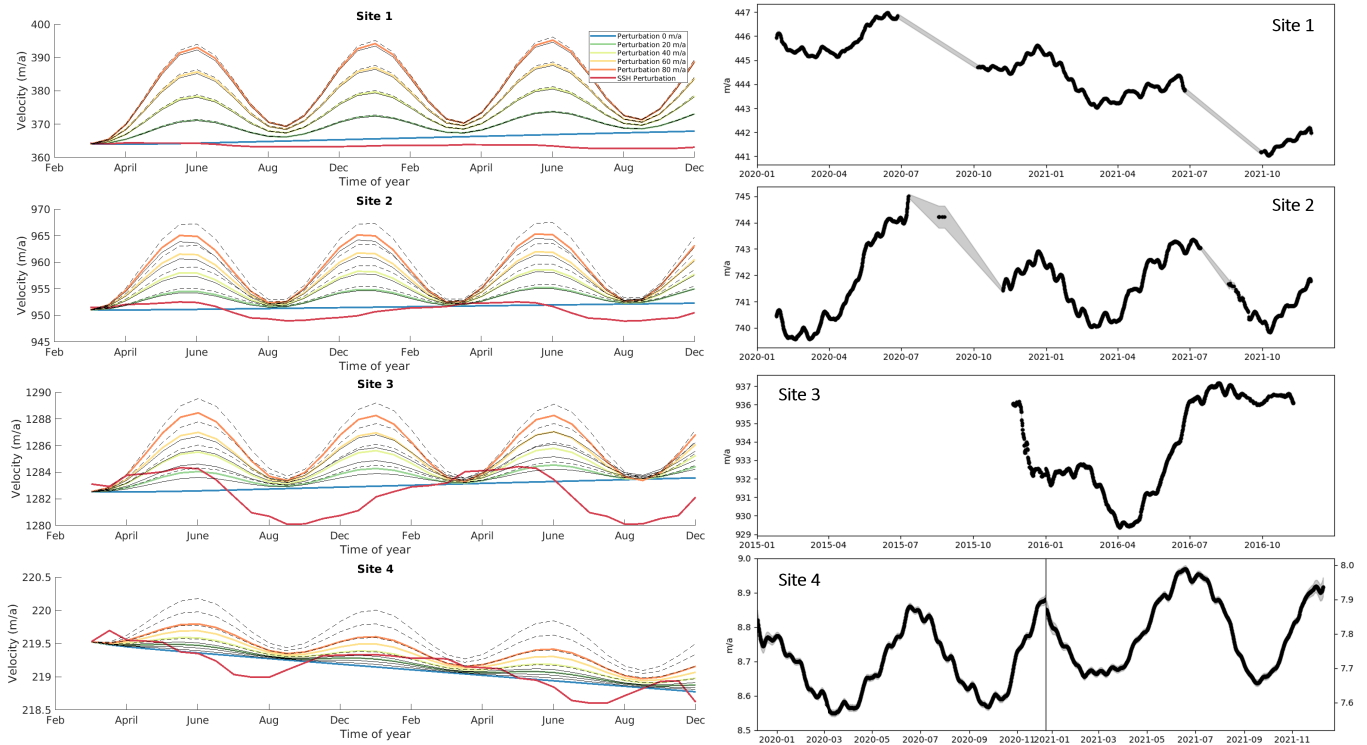
Figure A10. The absolute modelled velocities compared to the absolute GNSS observed velocities for Sites 1, 2, 3, and 4.

Data availability. The model scripts and configuration files can be found here: https://doi.org/10.5281/zenodo.11098089. The Ice-sheet and Sea-level System Model v4.18 can be accessed at https://issm.jpl.nasa.gov. BedMachine Antarctica is available at NSIDC (http//nsidc.org/data/nsidc-0756). InSAR-Based ice velocity is found at NSIDC (https://nsidc.org/data/nsidc-0484/). The Antarctic surface mass balance (RACMO 2.3p2) is available at https://www.projects.science.uu.nl/iceclimate/models/racmo-data.php. The GNSS data can be found here: https://doi.org/10.5281/zenodo.14134876.

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Competing interests. Huw Horgan is an associate editor for The Cryosphere and EGUsphere. The authors declare that they have no other conflicts of interest.

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