



Strength of TROPOMI satellite observations in retrieving hourly resolved sources of volcanic sulfur dioxide by inverse modeling

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Abstract. Volcanic eruptions release sulfur dioxide (SO₂), impacting air quality, ecosystems, and aviation. To comprehensively assess these effects, high-temporal-resolution SO₂ emission data is crucial. In this study, we use an inverse modeling procedure, assimilating SO₂ column measurements from TROPOMI and OMPS low-Earth orbit satellites into an Eulerian chemistry-transport model. This procedure allows us to derive precise hourly SO₂ mass flux and injection heights. TROPOMI, with its exceptional spatial resolution, excels at detecting short-lived, concentrated SO₂ plumes near the source shortly before satellite overpasses. This high-resolution data enables more robust identification and precise characterization of strong SO₂ emissions, surpassing the capabilities of lower-resolution OMPS measurements, which may overlook or underestimate vigorous degassing periods. Notably, this high-resolution data also facilitates the detection of pre-eruptive SO₂ emissions. Cloud cover can obscure SO₂ plumes from satellite observations, but our inverse modeling procedure effectively distinguishes and tracks them by assimilating successive satellite overpass data. Furthermore, this procedure proves less susceptible to ash emissions compared to geostationary Himawari-8/AHI observations. We apply our methodology to study the 2018 Ambrym eruption, a former major volcanic SO₂ emitter. This eruption marked the end of long-lived lava lake activity and initiated a submarine eruption through a massive magma intrusion. Our detailed SO₂ flux time series unveils the evolution of the eruption and identifies distinct SO₂ sources, including lava flows and shallow magma intrusions. In summary, the assimilation of TROPOMI data into inverse modeling procedures offers significant potential for enhancing our understanding of magma transport and environmental impacts during volcanic eruptions.

1 Introduction

Volcanic sulfur dioxide (SO₂) emissions offer insights into subterranean magma and volatile dynamics, as well as interactions with hydrothermal systems (Oppenheimer et al., 2011, 2014; Edmonds et al., 2003). Additionally, these emissions have multifaceted atmospheric impacts, including air quality degradation (Hansell and Oppenheimer, 2004; Boichu et al., 2016, 2019), ecological effects (Delmelle et al., 2002), and health concerns for both humans and animals (Stewart et al., 2021). They can lead to respiratory issues, exacerbate pre-existing conditions, and harm vegetation (Cronin and Sharp, 2002; Allibone et al., 2012;



Mueller et al., 2020; Thorsteinsson et al., 2012). Large quantities of sulfate aerosols resulting from SO₂ oxidation, whether
25 through direct or indirect mechanisms, can influence the climate (Robock, 2000; Kremser et al., 2016; Marshall et al., 2022).
Moreover, volcanic emissions pose a hazard to aviation, impacting aircraft visibility (Guffanti et al., 2010a; Weinzierl et al.,
2012) and causing damage to aircraft engines due to corrosive sulfate deposition (Prata and Tupper, 2009; Prata, 2009; Carn
et al., 2009; Guffanti et al., 2010b).

Monitoring volcanoes, especially SO₂ emissions, is therefore essential for accurate hazard assessment. To achieve this, we
30 must precisely estimate key emission parameters, including SO₂ mass flux and injection height, with high temporal resolution
(e.g., Thomas and Watson, 2010; Boichu et al., 2015). As SO₂ is an unambiguous indicator of volcanic plume, these parameters
become vital inputs for chemistry-transport models (CTM), enabling accurate simulations of volcanic SO₂, ash, and sulfate
aerosol dispersion to assess atmospheric hazards. Additionally, detailed emission data provides valuable insights into magma
dynamics and can potentially reveal precursor signals of impending eruptions (e.g., Sparks, 2003; Oppenheimer, 2010; Kilbride
35 et al., 2016).

Remote sensing methods excel in detecting volcanic SO₂ due to its unique spectral signature and relatively low background
atmospheric concentration. Since 1978, low-Earth polar-orbiting (LEO) ultraviolet (UV) and infrared (IR) hyperspectral sen-
sors have continuously observed global bulk SO₂ levels (Carn et al., 2017), albeit with limited temporal coverage, providing
daily or bi-daily SO₂ column images. Complementing LEO observations, geostationary sensors offer more frequent measure-
40 ments despite lower spectral resolution and sensitivity to SO₂ gas concentration (Prata and Grant, 2001; Prata et al., 2007;
Corradini et al., 2021). Furthermore, ground-based UV DOAS spectrometers have monitored volcanic plumes effectively since
the early 2000s, particularly adept at detecting low-altitude and weak to moderate SO₂ degassing, crucial for pre-eruptive mon-
itoring (Campion et al., 2012; Arellano et al., 2021). Nevertheless, ground-based volcano monitoring poses significant chal-
lenges, encompassing financial constraints, logistical difficulties, installation, equipment upkeep, and local personnel training.
45 The Network for Observation of Volcanic and Atmospheric Change (NOVAC) has coordinated efforts to monitor volcanoes,
but only 37 out of thousands of active volcanoes possess the necessary instruments (Arellano et al., 2021). These instruments
can also malfunction during eruptions or fail to detect degassing amidst heavy ash emissions (e.g., Surono et al., 2012; Boichu
et al., 2015).

Various methods have emerged for sub-daily tracking of volcanic SO₂ emissions from space. The rough Delta-M approach
50 assesses mass flux by calculating the difference in mass burdens between consecutive acquisitions and dividing by the time in-
terval (Theys et al., 2013). A more refined technique, known as the traverse method, estimates SO₂ mass flux by multiplying the
plume's SO₂ amount cross-section by its velocity, derived from external sources and assumed to match the plume altitude wind
speed (Carn and Bluth, 2003; Merucci et al., 2011; Theys et al., 2013). Another set of methods, employed to determine monthly
mean SO₂ lifetime and emission rate, involves fitting an exponentially modified Gaussian function to the monthly mean column
55 amount as a function of distance from the source, as documented by Beirle et al. (2014); Fioletov et al. (2016, 2017, 2020);
Carn et al. (2017). It is important to note that all these techniques rely on assumptions about plume dispersion and wind fields,
rendering them unsuitable for cases involving intricate wind patterns.



Using atmospheric (Lagrangian) trajectory models in a backward mode provides an alternative approach for estimating volcanic SO₂ emission parameters from LEO satellite observations at high temporal resolution. This method initially determines the height of plume parcels and then calculates the time- and height-resolved mass of emissions for each parcel. Notably, this approach, as demonstrated by previous studies (e.g., Hughes et al., 2012; Pardini et al., 2017; Queißer et al., 2019; Cai et al., 2022; Esse et al., 2023), faces challenges related to plume recirculation. For example, Queißer et al. (2019) compare TROPOMI SO₂ column images to ground-based measurements and back-trajectory calculations, and report that they agree well, fairly well, and satisfactorily for monthly, daily, and intra-diurnal averages, respectively. Additionally, assimilating individual LEO satellite images using these methods does not allow for resolving potential trade-offs between injection height and time without a priori assumptions on the eruption timing.

The inverse modeling procedure, while computationally demanding, efficiently addresses these challenges by assimilating multiple successive satellite images of the dispersed SO₂ plume in a single operation (e.g., Boichu et al., 2013, 2015; Theys et al., 2013; Stohl et al., 2011; Eckhardt et al., 2008). This method involves identifying the volcanic ash and/or SO₂ source term that minimizes differences between observed and simulated gas/particle column amounts at each satellite pixel (e.g., Eckhardt et al., 2008; Kristiansen et al., 2010; Stohl et al., 2011; Theys et al., 2013; Boichu et al., 2013, 2014, 2015; Moxnes et al., 2014; Zidikheri and Potts, 2015; Heng et al., 2016). Simulations use either transport or chemistry-transport models to describe atmospheric physico-chemical processes affecting released SO₂ parcels from the volcanic source until satellite acquisition. The hourly retrieval of height-resolved SO₂ mass flux emissions through an inverse modeling procedure, which does not require a priori assumptions of emissions profiles, has been validated against ground-based UV DOAS observations, demonstrating resilience to strong ash emissions (Boichu et al., 2015). In the same vein, 4D-Var data assimilation procedures have been developed (Flemming and Inness, 2013; Vira et al., 2017).

In this study, we illustrate the enhanced accuracy of SO₂ source retrieval using an inverse modeling procedure by assimilating high-spatial-resolution SO₂ observations from the Sentinel-5P/TROPOMI satellite (Theys et al., 2017, 2019), in contrast to coarser SO₂ observations from Suomi-NPP/OMPS (Flynn et al., 2006, 2014) (sect. 2). It is important to clarify that the term "assimilation" in this context refers to a simplified representation of the linear least-squares optimization applied in a retrospective analysis procedure. We improve emissions parameters accuracy and compare results with high-temporal-resolution geostationary measurements from Himawari-8/AHI, which offer qualitative SO₂ flux estimates (sect. 3). Our work demonstrates that sequential data assimilation effectively simulates the presence of SO₂-rich plumes beneath meteorological clouds (sect. 3), opening new avenues for enhancing volcanic plume forecast reliability. As a case study, we examine the 2018 eruption of the Ambrym volcano, which had been a significant continuous SO₂ emitter for the recent decade, ranking it as the world's top SO₂ emitter until 2018 (Carn et al., 2017; Fioletov et al., 2016, 2023). This volcanic eruption disrupted both the decade-long SO₂ degassing and the persistent lava lake activities associated with this basaltic volcano (Hamling et al., 2019; Shreve et al., 2019). Through our analysis of high-resolution SO₂ degassing data, we gain insights into the intricate magma dynamics that occurred during the 2018 eruption (sect. 4). We show how different magma sources contribute to the degassing observed at the surface, a complexity that can result in contrasted volcanic hazards.



2 Data and research methods

2.1 SO₂ columns from low-Earth polar-orbiting UV satellite sensors: TROPOMI and OMPS

LEO satellite sensors provide vertical column density (SO₂ column hereafter) images, which represent the number of SO₂ molecules in an air column per unit area. These images are measured in Dobson Unit (DU), where 1 DU equals 2.69×10^{16} molecules/cm². In 2018, the TROPOMI science team started to provide a daily SO₂ column with a nadir footprint of 7 km × 3.5 km (Veeffkind et al., 2012; Theys et al., 2019). Then from August 2019 onwards, it is available with a nadir footprint of 5.5 km × 3.5 km. This data is obtained using the differential optical absorption spectroscopy (DOAS) algorithm. DOAS algorithm estimates the SO₂ slant column density (SCD) from a measured UV spectrum and subsequently derives the SO₂ column from the SCD (Theys et al., 2015, 2017). To perform this estimation, the algorithm uses the following ancillary inputs: air mass factors, scattering weight functions computed by the radiative transfer model assuming a U.S. standard atmosphere, Lambertian reflecting surface for handling meteorological clouds (Eskes and Boersma, 2003), and a priori SO₂ profile given by the global CTM TM5 (Tracer Model 5, 34 sigma-pressure levels up to 0.1 hPa, Huijnen et al. (2010)). Nevertheless, the operational DOAS algorithm, sensitive to aerosols and clouds, can lead to spectral misfits, introducing systematic errors in SO₂ column retrievals. Recently, Theys et al. (2021) introduced COBRA, a spectral fitting technique similar to the principal component analysis (PCA) technique used in OMI and OMPS retrievals (Yang et al., 2007, 2013; Li et al., 2017, 2020b), which reduces biases for weak SO₂ columns and eliminates the need for post-processing background correction. COBRA uses a measurement error covariance matrix to fully represent SO₂-free radiance variability, focusing solely on retrieving SO₂ SCD. Their study demonstrates that COBRA significantly enhances SO₂ column retrievals compared to the current TROPOMI DOAS operational product. Over a 2.5-year analysis with high-resolution TROPOMI data, this approach unveils numerous new global SO₂ emission sources, highlighting COBRA's superior SO₂ detection capabilities. However, the SO₂ data processed by this algorithm is currently available only from 2022 onwards. The OMPS sensor, on the other hand, captures SO₂ columns at a coarser spatial resolution, with a nadir footprint size of 50 km × 50 km (Flynn et al., 2014; Carn et al., 2015). Unlike the TROPOMI SO₂ retrieval method, the estimation of the SO₂ column from OMPS uses the PCA technique. The a priori SO₂ profile used in this process is derived from the Goddard Earth Observing System global 3D model for atmospheric chemistry (72 sigma-pressure levels up to 0.01 hPa, Bey et al. (2001)). In Theys et al. (2015), the technical details and a comparison of the DOAS and PCA-based SO₂ retrieval methods are presented. They demonstrate a linear relationship between the SO₂ columns derived from DOAS and PCA, based on backscattered UV data obtained from the OMI sensor.

For the 2018 Ambrym case study associated with mid-tropospheric SO₂ degassing, we assimilate the level 2 SO₂ column datasets from TROPOMI and OMPS, namely the 7 km SO₂ product (S5P_OFFL_L2_SO2; Copernicus Sentinel data processed by ESA (2020)) and the TRM SO₂ product (NMSO2_PCA_L2_v2.0; Li et al. (2020a); Zhang et al. (2017)), respectively. We post-process TROPOMI data before assimilation to remove abnormally high SO₂ column values (>1 DU) at the swath edges. These high values are detected even when there are no nearby SO₂ plumes (Fig. S1). We consider the swath edge as extending 25 ground pixels on either side of the swath. To prevent inaccurate retrievals from interfering with the inverse modeling procedure, we set a specific threshold for the SO₂ column values of pixels at the swath edge. This ensures that only



pixels at the swath edge of volcanic origin are considered during the assimilation. We typically adjust the SO₂ threshold for these pixels to be between 1.1 DU to 1.4 DU, depending on the day between December 13 and 18 (Fig. S2). Pixels below this threshold are set to zero SO₂ columns. We do not post-process the OMPS SO₂ data.

2.2 Himawari-8/AHI geostationary satellite data

130 Shreve et al. (2019) use the geostationary Himawari-8 satellite's advanced Himawari imager (AHI) to assess the thermal characteristics of the lava flow during the 2018 Ambrym eruption. AHI captures data in six spectral bands spanning the visible and infrared spectrum. The spatial resolution varies, with the visible and near-infrared bands offering approximately 0.5 km to 1 km resolution across Asia and Oceania, while the infrared bands provide a 2 km spatial resolution (Bessho et al., 2016). The calculation of thermal characteristics of lava flow involves combining brightness temperatures (BT) from the 3.9 μm and
135 10.4 μm channels (Shreve et al., 2019). Then, to estimate the SO₂ flux proxy, Shreve et al. (2019) integrate pixels showing an SO₂ column proxy exceeding 4° K within a 50 km × 35 km region centered at Ambrym. The calculation of the SO₂ column proxy relies on data from the 10.4 μm and 8.5 μm channels, collected at 20-minute intervals.

In addition, SO₂/Ash RGB composites can be derived from these channels to infer qualitative knowledge about the SO₂ emissions, as documented in Ishii et al. (2018). These RGB composites (red: BT_{12.4μm} - BT_{10.4μm}, green: BT_{10.4μm} - BT_{8.6μm},
140 blue: BT_{10.4μm}) are accessible at the AERIS/ICARE data center (Boichu and Mathurin, 2022). They serve to distinguish SO₂ plumes and volcanic ash. It is important to note that SO₂ RGB images can be affected by clouds, aerosols, and other atmospheric species, leading to false positives or negatives and limiting SO₂ signal isolation (e.g., Prata, 1989; Simpson et al., 2000).

2.3 CHIMERE chemistry-transport model simulation

We use the offline Eulerian CTM CHIMERE (Mailler et al., 2017) to simulate the dispersion of the SO₂-rich plume from the
145 Ambrym eruption during 13–18 December 2018. The meteorological fields for CHIMERE are driven hourly by the Advanced Research WRF model (Powers et al., 2017), an external meteorological model that is constrained by the 0.25-degree ERA-5 reanalysis data (Hersbach et al., 2020) at 37 pressure levels to obtain initial and hourly boundary conditions. A two-week spin-up period is computed to accurately simulate with WRF the complex wind fields in the Indonesian-Australian basin because of the Madden-Julian oscillation (e.g., Feng et al., 2020). Additionally, the top layer of the WRF run is set to 50 hPa to correctly
150 simulate deep convection. The horizontal grid for both the CHIMERE and WRF runs is 10 km × 10 km, and the vertical extent of the CHIMERE CTM grid reaches 200 hPa, which is approximately 12.5 km above sea level (ASL).

We simulate SO₂ concentration by injecting each hour passive tracers at multiple altitudes ranging from 2 km to 11 km ASL, as shown in Fig. S3. The tracers are released following a Gaussian profile at each model level, both in time and in altitude. Ambrym's vent is 1.3 km ASL, so we limit our analysis to emissions above 2 km ASL to capture the eruption's gas emissions.
155 Therefore, we do not expect the CTM simulations to generate an SO₂ plume to the northwest of the source, as driven by the low-level southeasterly trade winds. Additionally, UV sensors are less sensitive to SO₂ below 2 km ASL (e.g., Yang et al., 2010; Theys et al., 2017). The CHIMERE run does not account for SO₂ conversion to sulfate aerosol, nevertheless, the passive



tracers followed all the relevant physical processes in the atmosphere, including transport, diffusion, turbulent mixing, dry deposition, and wet scavenging.

160 2.4 Assimilating LEO satellite data to estimate SO₂ emissions

2.4.1 Inverting emission profiles

The CHIMERE CTM provides the forward model Jacobian \mathbf{G} (Eq. 1). The \mathbf{G} matrix ($n \times p$) represents the sensitivity of the observation vector \mathbf{d} ($n \times 1$) to the state vector \mathbf{m} ($p \times 1$), i.e., $G_{ij} = \frac{\partial d_i}{\partial m_j}$. This matrix is determined by simulating tracer transport with the CTM, which incorporates various physical processes and links emissions from the source to LEO satellite-
165 observed SO₂ column data. The satellite observations are compiled in the observation vector \mathbf{d} , which consists of SO₂ columns from several consecutive satellite overpasses during the Ambrym eruption. Each element of the \mathbf{d} vector is associated with a time and spatial coordinate. Inversion of satellite SO₂ columns relies on a large state vector \mathbf{m} to constrain the emission with hourly temporal resolution. However, the size of the state vector is constrained by the resolution of the CTM simulation, which in turn depends on its ability to resolve wind fields. Additionally, it is influenced by factors from the observation perspective,
170 such as the measurement footprint size and accuracy. In our case, the state vector \mathbf{m} comprises 1200 elements. It represents tracers emitted each hour at specific altitudes, portraying the SO₂ emission of the Ambrym eruption in relation to time and injection height.

We adopt the inverse modeling procedure developed by Boichu et al. (2013, 2014, 2015), which uses linear least-squares optimization without using a priori knowledge of SO₂ emissions to minimize the analysis residuals, i.e., the difference between
175 the forward simulation and the observation. This data assimilation procedure is strongly data-driven, relying solely on the data to determine the optimal estimate (\hat{m}). It maximizes the extent to which the data can support the findings as no a priori notions about the SO₂ emissions are used. The optimal estimate \hat{m} is a state vector that minimizes $\|d_i - G_{ij}m_j\|^2$, where d_i and m_j are non-negative and $m_j \in \mathbb{R}^p$ and $d_i \in \mathbb{R}^n$. To account for measurement noise and error in the forward model, we apply the second-order Tikhonov side constraint (Hansen, 1998), which constrains the second derivative of \mathbf{m} . The equation we solve is

$$180 \begin{pmatrix} d \\ 0 \end{pmatrix} = \begin{pmatrix} G \\ 10^\lambda \nabla^2 \end{pmatrix} m. \quad (1)$$

The Laplace operator (∇^2) is a tridiagonal matrix representing the discrete second derivative with respect to time. It has a primary diagonal of -2, and the diagonal components above and below have a value of 1. No smoothing is applied with respect to injection heights. The smoothing factor in the inversion is 10^λ . The optimal solution is determined using the L-curve method (Hansen and O'Leary, 1993) (Fig. S4). The emissions (\hat{m}) are optimized so that the CTM simulation would fit the observations
185 \mathbf{d} while adhering to the restrictions of a non-negative solution (Lawson and Hanson, 1995). Additionally, if the largest element in any row of the \mathbf{G} matrix, $\frac{\partial d_i}{\partial m_j}$, is less than 1×10^{-8} , the entire row and the associated observation in the \mathbf{d} vector are removed to maintain the inversion's numerical stability.



To keep the condition number of the \mathbf{G} matrix low and ensure that the inverse problem is numerically stable (Demmel, 1987; Hansen, 1998), we include all zero data points in the observation vector \mathbf{d} and the corresponding sensitivity elements in the \mathbf{G} matrix. This implies that we treat zero SO_2 column measurements as valid data to constrain the state vector \mathbf{m} . Zero SO_2 column pixels can signify either the absence of a volcanic plume or, in certain cases, an undetected SO_2 plume. For instance, pixels falling below the satellite sensor's detection threshold or obscured by clouds may register as zero data points. Consequently, it is essential not to automatically interpret zero data points as evidence of the absence of a volcanic SO_2 plume. Neglecting them during source estimation could lead to inaccuracies.

195 2.4.2 Post-processing of inverted SO_2 emissions

We use a sifting threshold to eliminate weak SO_2 emissions with a large uncertainty from the optimal emission profile (\hat{m}). The threshold is determined by the mean (μ) and standard deviation (σ) of the SO_2 emissions' (m_i) distribution. To retrieve SO_2 emissions from TROPOMI data assimilation, we use the same threshold as for OMPS data assimilation ($\mu + \sigma$). However, further analysis shows that a higher threshold ($\mu + 2\sigma$) could have been used for OMPS data assimilation (see Fig. S5). This distinction arises from OMPS's lower sensitivity to SO_2 compared to TROPOMI, necessitating a higher threshold to filter out poorly constrained weak emissions. We discuss these uncertainties in sect. 4.2.

3 Results

3.1 Hourly SO_2 emissions obtained by inverse modeling: superiority of TROPOMI compared to OMPS

205 3.1.1 Broad agreement between SO_2 mass-flux time series obtained by assimilating TROPOMI and OMPS column data

The SO_2 mass-flux time series, obtained by assimilating TROPOMI and OMPS SO_2 column data, broadly agree, depicting Ambrym's three-stage eruption between December 13 and 18, 2018 (as shown by the red line for TROPOMI and the blue line for OMPS, see Fig. 1a and 2a). We indicate the three stages of the eruption as follows: first stage – 12:00 UT December 14 to 18:00 UT December 15; second stage – 18:00 UT December 15 to 13:00 UT December 16; third stage – 13:00 UT December 16 to 12:00 UT December 17. This pattern corroborates the findings of Shreve et al. (2019). Both assimilations reveal an intense SO_2 degassing event commencing around 23:00 UT on December 14 and concluding at 18:00 UT on December 15. Within this phase, stage 1, the highest gas flux (3.8 kilotonnes per hour (kt h^{-1}), denoted as #T2 in Fig. 1a), dated 00:00 UT on December 15, emerges from the TROPOMI data assimilation, coinciding with the eruption's onset linked to the emplacement of a lava flow in the caldera (Shreve et al., 2019). This alignment is substantiated by the rise in the thermal index for lava flow pixels, as derived from the analysis of Himawari-8/AHI observations using the $3.9 \mu\text{m}$ channel (illustrated by the green line in Fig. 1a). Shreve et al. (2019) demonstrate that the emission of this lava flow coincided with the drainage of Ambrym's long-lived lava lakes. This event occurred on December 14, between 23:20 and 23:40 UT. The TROPOMI-derived SO_2 flux (hourly resolution) and the SO_2 flux proxy (20-minute resolution), which is a qualitative parameter derived from Himawari-8/AHI



observations (indicated by the gray line in Fig. 1a), both peak at the eruption's onset. However, the OMPS data assimilation
220 reveals a much weaker gas pulse (0.25 kt h^{-1} , labeled as #O1 in Fig. 2a) at 00:00 UT 15 December, despite the #O1 emission
peaking at 04:00 UT 15 December. The #O1 emission, at 1.8 kt h^{-1} , is the second-largest degassing event following #O2,
which records 2.0 kt h^{-1} . These emissions are identified during the initial phase of the eruption when assimilating OMPS
observations. Between 02:00 – 05:00 UT on December 15, TROPOMI-derived SO_2 emissions show another robust degassing
event (#T3, Fig. 1a), with a flux reaching up to 2.75 kt h^{-1} , albeit with a brief interruption and weaker intensity compared to
225 the eruption's onset. On December 15, between 08:00 and 12:00 UT, there is a notable increase in SO_2 emissions, as detected
through the assimilation of TROPOMI (#T4) and OMPS (#O2) data, following a brief interruption. Notably, during the first
stage of the eruption, except for the late hours of December 14 (the eruption's onset) and the period between 12:00 – 18:00
UT on December 15, Himawari-8/AHI's SO_2 flux proxy (indicated by the gray line in Fig. 1a) does not indicate significant
degassing, in contrast to the findings from both TROPOMI and OMPS data assimilations. This disparity can be attributed
230 to the strong emissions of ash particles expelled simultaneously with SO_2 during that period (as depicted in Fig. S6). The
Himawari-8/AHI SO_2 flux proxy is obtained through an analysis of a near-source plume within a roughly $50 \text{ km} \times 35 \text{ km}$
area centered on Ambrym. This analysis uses the $8.5 \mu\text{m}$ and $10.41 \mu\text{m}$ channels (Shreve et al., 2019). Consequently, a high
concentration of ash in the nearby plume can significantly affect these AHI channels, potentially biasing the SO_2 flux proxy by
either underestimating or concealing the presence of SO_2 (e.g., Andres and Schmid, 2001; Suroño et al., 2012). In contrast, the
235 flux obtained by assimilating LEO satellite observations, which capture the plume when it has dispersed farther from the source
and is more diluted, is less affected by these conditions. In the first stage of the eruption, marked by intense degassing, a clear
correlation emerges with high values of the lava flow thermal indices (illustrated by the green line in Fig. 1a). Nevertheless, as
the second stage of the eruption commences, these lava flow thermal indices gradually decrease. This observation implies that
the lava flow has reached its full extent during the first stage of the eruption, consistent with findings from Sentinel-2 optical
240 images (Shreve et al., 2019). In the subsequent stage, the lava flow continues to emit heat without renewed lava emissions.

During the second stage of the eruption, SO_2 degassing is characterized by the largest peak on December 16, as recorded by
TROPOMI-derived flux emissions and Himawari-8/AHI SO_2 flux proxy. From 20:00 UT 15 December to 06:00 UT 16 Decem-
ber, a strong SO_2 flux peaking at 7.1 kt h^{-1} is derived from the TROPOMI data assimilation (#T7 in Fig. 1a), approximately
coinciding with the highest values of the SO_2 flux proxy derived from Himawari-8/AHI observations of the eruption (gray line
245 in Fig. 1a). However, the OMPS data assimilation misses this paroxysmal phase, recording degassing activity with an intensity
similar to the previous day. Sect. 3.1.2 explains why the discrepancy occurs. Furthermore, as reported by Shreve et al. (2019),
a significant earthquake on late December 15 was followed by a sharp rise and lateral migration of seismicity. This suggests
that a large volume of magma moved laterally at a shallow depth from the caldera towards the eastern part of the island. Even
though this dike, which was over 30 km long, did not reach the surface and only fractured it, and caused substantial coastal
250 uplift (Shreve et al., 2019). The concomitant paroxysmal phase of degassing that we highlight in the second stage of degassing
activity is likely due to the degassing of this voluminous extra-caldera dike.

The third stage, lasting until the end of December 17, has minor degassing, with occasional gas pulses of up to 0.4 kt h^{-1}
recorded by TROPOMI and OMPS data assimilations. Himwari-8/AHI-derived proxies show the same degassing pattern.



Ambrym, despite having only three explosive eruptions, was a significant source of passive SO₂ degassing, emitting an estimated 122 kt of SO₂ per year (Carn et al., 2016). Nevertheless, information regarding Ambrym's SO₂ degassing, particularly in terms of high time resolution and passive emissions, remains scarce. Passive degassing from Ambrym's volcano prior to the 2018 eruption shows an annual SO₂ mass flux averaging 2–12 kt d⁻¹ (equivalent to 0.08–0.5 kt h⁻¹). This data is derived from OMI satellite observations spanning from 2005 to 2015, and it has been extended to 2018 using the NASA database (Carn et al., 2017; Shreve et al., 2022). Additionally, ground-based UV-DOAS observations, which are infrequent due to challenging access, estimate Ambrym's substantial SO₂ passive degassing at 5 kt d⁻¹ (equivalent to 0.2 kt h⁻¹), aligning with the satellite-based findings (Bani et al., 2012). Therefore, the SO₂ emissions from Ambrym's passive degassing are significantly lower, by over one order of magnitude, compared to the estimated degassing rate during its 2018 eruption. Bani et al. (2009) report peak SO₂ flux values of 33 kt d⁻¹ (equivalent to 1.4 kt h⁻¹) during intense lava lake degassing in 2005. Our estimation shows that eruptive SO₂ flux reaches 7.1 kt h⁻¹ (emission #T7) during the paroxysmal phase of the 2018 eruption, five times higher than the 2005 lava lake degassing activity. We estimate that the eruption emitted 42 ± 16 kt (OMPS) or 52 ± 13 kt (TROPOMI) of SO₂. The additional 10 kt with TROPOMI corresponds to dense, often young, SO₂ parcels that are more accurately detected, thanks to its higher spatial resolution compared to OMPS. This budget is consistent with the total SO₂ mass burden of 50–60 kt and 30–40 kt previously estimated for the 2015 and 2018 Ambrym eruptions, respectively (Shreve et al., 2019, 2022). Despite its high degassing rate, our estimations show that the 2018 Ambrym eruption released a relatively small amount of SO₂ compared to the global sources of eruptive SO₂ emissions, which are about 2000 kt per year (Carn et al., 2016).

3.1.2 Paroxysmal degassing missed by assimilation of OMPS SO₂ columns

Assimilation of TROPOMI SO₂ columns shows that the highest SO₂ emissions occurred at the end of December 15. This retrieval agrees with the highest values of the SO₂ flux proxy derived from Himawari-8/AHI observations, offering a 20-minute temporal resolution (Fig. 1a). We investigate why the strongest SO₂ degassing associated with #T7 and #T8 emissions (Fig. 1a), spanning three ranges of injection heights (3–5 km, 7–8 km, with a maximum SO₂ mass of approximately 4 kt in 10–12 km, Fig. 3a), is largely underestimated by assimilating OMPS observations, which only records about four times weaker emissions (#O4 in Fig. 2a). In the context of OMPS data assimilation, a perplexing situation emerges. It produces the strongest emission, #O2a (as shown in Fig. 3b and S8b), at approximately 11:00 UT on December 15. In contrast, emissions #O4d and #O4e (as seen in Fig. S9b) represent the SO₂ plume near the volcano's vicinity at the end of December 15, but they are notably weaker when compared to emission #O2a (as indicated in Fig. S9b, where sources are arranged in descending order by amplitude). Both TROPOMI and OMPS acquisitions on December 16 display highly concentrated SO₂ parcels near the source (as revealed in Fig. S12), which pose constraints for retrieving these emissions (#T7e and #T8a in Fig. S9a, #O4d and #O4e in Fig. S9b) through inverse modeling procedures. To address the discrepancies in the retrievals, we examine SO₂ maps obtained simultaneously by OMPS and TROPOMI on December 16. Our aim is to determine if differences in the spatial distribution of the plume, as observed by the two sensors, could explain the differences in the retrievals of mass flux and injection altitude at the source.



On December 16, both OMPS and TROPOMI detect a crescent-shaped SO₂-rich plume emitted by Ambrym that stretches over 1000 km to the east, with a plume core of higher SO₂ density than the periphery (Fig. 4i-1, 4ii-1). TROPOMI detects a highly concentrated SO₂ parcel near the source (#A in Fig. 4ii) and four additional, distinct SO₂-rich parcels at a considerable distance from the source (#B–E in Fig. 4ii). OMPS, by contrast, records no such clear spatial patterns, and only two dense SO₂ parcels near the source are noticeable (Fig. 4i-1). The concentration of these parcels also differs significantly between these two sensors, as shown by plume transects (Fig. 4i-2, 4ii-2). The densest SO₂ parcel identified by TROPOMI (2 pixels) presents a peak column amount value of 664.1 DU (#A in Fig. 4ii-2), while OMPS detects a much less dense parcel, with only one pixel, with a peak value of 30.2 DU (#A in Fig. 4i-2). TROPOMI also indicates another SO₂-rich parcel at a distance of approximately 250 km from the source, with a peak value of 30.5 DU (#B in Fig. 4ii-2), compared to 11.6 DU for OMPS (#B in Fig. 4i-2). TROPOMI measurements also show more pronounced dense SO₂-rich parcels and their fragments with column amounts greater than 10 DU (#C–E in Fig. 4ii-2) than OMPS. TROPOMI's hyperspectral and higher spatial resolution than OMPS explains its ability to detect concentrated areas of SO₂ more effectively (Theys et al., 2019).

To test whether TROPOMI's better spatial resolution explains the differences in the distribution of in-plume SO₂ columns between the two sensors, we apply spatial smoothing to TROPOMI data. We smooth TROPOMI column amount pixel observations within a disk with three different radii: 25 km (Fig. 4iii), 50 km (Fig. 4iv), and 75 km (Fig. 4v). As the disk radius increases, the peak SO₂ columns of dense parcels #A to #E within the plume decreases. With a 50 km smoothing, the SO₂ column of parcel #A, the most concentrated parcel, is reduced by 11 times to 59.5 DU. The SO₂ columns associated with the four other SO₂-rich parcels farther from the source, ranging from 11 DU to 13 DU, are still discernible above a core background of around 7–8 DU. However, with a 75 km smoothing, it becomes difficult to separate these four parcels from the plume core background. Parcel #A is of particular interest because it constrains the strong degassing of the paroxysmal phase (#T7 and #T8, Fig. 1a) in the inverse modeling (see zoomed-in view in Fig. S13). With a 75 km smoothing of TROPOMI data, parcel #A is still discernible, and its concentration peaked at 37.4 DU (Fig. 4v-2), similar to the SO₂ column associated with the same parcel #A in the raw OMPS observations (#A in Fig. 4i-2).

Therefore, TROPOMI data smoothed to a spatial scale of 50 km to 75 km best match raw OMPS data, suggesting that the difference in spatial resolution explains the differences in SO₂ column measurements. TROPOMI's high spatial resolution allows for better characterization of dense SO₂ parcels, especially young highly-concentrated parcels near the source (Fig. S12). This strongly constrains the inverse modeling procedure to retrieve SO₂ mass flux and injection height, resulting in substantially different estimates of flux emissions depending on the satellite measurements. On December 16, emissions #T7e and #T8a (Fig. S9a) clearly indicate a concentrated SO₂ plume near the source. In contrast, emission #O2a (Fig. S9b) does not correspond to the SO₂ plume observed on the same day with a maximum column value of 30.2 DU (Fig. S12). Instead, #O2a is linked to a dense SO₂ parcel situated away from the volcano, injected at an 8 km altitude ASL (Fig. 3b and S9b). This discrepancy raises concerns about the precision of inverse modeling when assimilating low spatial resolution SO₂ images, particularly in capturing dense, localized volcanic SO₂ parcels in the moments leading up to the LEO satellite overpass. Notably, during the paroxysmal phase of the Ambrym eruption at the end of December 15, OMPS data assimilation greatly underestimates SO₂



flux values, with a factor of about 4, as OMPS identifies parcels with concentrations approximately 20 times smaller than those detected by TROPOMI.

3.1.3 A bimodal SO₂ injection at eruption onset

Two consecutive LEO satellite images of Ambrym's eruption plume taken on December 15 and 16 between 00:00 and 03:00 UT
325 constrain the inverse modeling to characterize the SO₂ injection heights at the eruption onset, which took place late December
14 (around 23:40 UT). On December 15 at 00:00 UT, TROPOMI and OMPS SO₂ column assimilations reveal that Ambrym
volcano emitted SO₂ at two distinct altitude ranges, resulting in a bimodal vertical distribution. The most substantial emissions
occurred between 9–11 km ASL, with a secondary emission layer at 4–5 km ASL, corresponding to emissions labeled #T2a–c
and #O1a–c in Fig. 3. Every 20 minutes, SO₂ RGB composites from Himawari-8/AHI observations show the SO₂ plume
330 progressively separating into two distinct branches starting from 01:00 UT on December 15 (left column of Fig. 5, animation
M1, and Fig. S6 for longer time series). This separation affirms that SO₂ is injected at various levels early in the eruption,
ascending to 9–11 km ASL. In contrast, ash remained at lower altitudes due to wind shear. The result is a complex plume
shape with distinct branches dispersing at different altitudes. The HYSPLIT Lagrangian model (Stein et al., 2015), forced by
0.5-degree GDAS reanalysis, shows that releasing ash particles at 00:00 UT on December 15 at an altitude of 5 km ASL (Fig.
335 5-vii) reproduces one branch of the plume moving north-northeast, which is likely the ash branch observed by Himawari-
8/AHI (Fig. 5iv–5vi). Releasing SO₂ at higher altitudes (Fig. 5-viii, 5-ix) fits well with the spatial extent and direction of the
SO₂ plume indicated by the light greenish plume in the SO₂ RGB composites from Himawari-8/AHI observations.

3.1.4 Pre-eruptive degassing

Around 15:00 UT on December 14, TROPOMI data assimilation reveals an above-noise-level SO₂ emission (#T1, as shown
340 in Fig. 1a) at an altitude of 11 km ASL, with a mass-flux of up to 1.0 kt h⁻¹ (Fig. 3a). However, the OMPS data assimilation
fails to detect this emission (Fig. 3b). This emission occurs nearly 12 hours before the satellite overpass and 8 hours before
the release of the strong SO₂ emission (#T2) associated with the eruption onset is expelled. Furthermore, the Himawari-8/AHI
SO₂ RGB images do not indicate the presence of the SO₂ plume near the source at this particular time (see animation M1).

We find that the SO₂ emission #T1 is constrained by the presence of dense SO₂ pixels detected near 175° E on December
345 15, even in the noisy swath edge (Fig. 1b-ii and Fig. S14a-ii for a closer view). This scenario poses challenges as it involves
modeling emission parameters using weak but mostly above-noise SO₂ columns. Such complexities arise when the volcanic
plume is positioned at the swath's edge, where noise levels are higher compared to other pixels. This challenging situation
is encountered on multiple occasions, with the same pixels appearing at the swath's edge on the previous day, December 14
(Fig. S12 and Fig. S14a-i). Notably, emission #T1 remains visible on December 16, forming the forefront of the plume (Fig.
350 S14d-iii), even in the presence of cloud interference (Fig. 7a-iii). Conversely, this pre-eruptive degassing cannot be retrieved
through the assimilation of OMPS data due to increased noise and distortion in the coarser OMPS pixels at the swath's edge
(Fig. S14b). The Himawari-8/AHI SO₂ RGB images, less sensitive to weak emissions, do not show any SO₂ plume near the
source at 15:00 UT on December 14 (see animation M1). Nevertheless, volcano-seismic activity began at Ambrym between



13:00 – 20:00 UT (local nighttime) on December 14, with a small increase in lava flow activity (Shreve et al., 2019), which
355 could have been accompanied by weak degassing. The available SO₂ data do not provide sufficient constraints for the inverse
modeling procedures to determine the injection height of the #T1 emission. This is shown in the gray contour in Fig. 3a, along
with retrievals that have uncertainties concerning injection heights. It is improbable for weak SO₂ degassing (#T1) to reach
11 km ASL. Sect. 4.2 provides more information about the uncertainty of SO₂ injection heights related to weak flux values.

3.2 Locating SO₂ plumes beneath clouds: Performance of inverse modeling in mitigating satellite retrieval limitations

360 Satellites, especially those with LEO sensors, have difficulty detecting SO₂ plumes in cloudy areas (e.g., Carn et al., 2013),
but our inverse modeling procedure overcomes this challenge by assimilating highly sensitive SO₂ data from TROPOMI. Our
procedure successfully simulates the presence of SO₂ plumes in cloudy areas by assimilating successive satellite overpass data
of volcanic SO₂ plumes, even when some images are obscured by clouds.

Figs. 1 and 2 show that initializing the CHIMERE CTM simulation with inverted SO₂ emissions results in an elongated
365 SO₂ plume forming to the north-northeast of Ambrym, mainly on December 17 and 18. Both sensors encounter difficulty
in detecting the plume, yet faint SO₂ signals are visible in TROPOMI observations, as depicted by the red contoured areas
in Fig. 6ii. Using TROPOMI-derived SO₂ emissions to initialize the CTM simulation reduces the presence of the simulated
SO₂ plume, especially to the northeast of Ambrym, with the application of a cloud fraction threshold (set at 0.3 to indicate
significant cloud cover). Similarly, the CTM simulation, initialized with SO₂ emissions from OMPS data assimilation, extends
370 the plume to north-northeastern regions near the source. However, OMPS is unable to detect volcanic SO₂ plumes obscured
by clouds (Fig. 6i), rendering this simulated SO₂ plume extension unreliable. Consequently, this cloud fraction threshold lacks
conclusive applicability in OMPS data assimilation. TROPOMI's improved spatial resolution confirms the plume's presence
in cloudy regions, underscoring the potential for our inverse modeling procedure to assimilate TROPOMI data. This procedure
integrates cloud-free TROPOMI observations of the SO₂ plume from previous days and offers a promising method for modeling
375 concealed SO₂ plumes. However, we must also acknowledge the limits of this procedure. The procedure may be less effective
when the SO₂ plume remains entirely concealed by clouds for an extended duration spanning multiple days during the satellite
overpass.

4 Discussion

4.1 Temporal resolution of SO₂ flux

380 The week-long eruption of Ambrym exhibits distinct patterns in SO₂ emissions in three stages (Fig. 1a). TROPOMI data
assimilation reveals ten discernible peaks labeled as #T1 to #T10 in SO₂ flux time series, while OMPS data assimilation
produces only six peaks, labeled as #O1 to #O6. In Fig. 2a, we observe the absence of two prominent peaks in the SO₂ flux
time series derived from OMPS data assimilation during the early hours of December 16. On December 15, during the initial
stage of the eruption (stage 1), the assimilation of OMPS data produces a visibly smoothed representation of the time evolution



385 of SO₂ emissions, identified as #O1. This stands in contrast to the dynamically varying #T2 and #T3 peaks evident in the TROPOMI-derived SO₂ flux time series. The fluctuation in TROPOMI-derived SO₂ flux indicates its capability to detect short-lived SO₂ emissions, owing to its capability of measuring SO₂ at high spatial resolution. It is important to recognize that the effectiveness of the inverse modeling procedure relies on the accurate simulation of local wind shears by the CTM. Following the paroxysmal phase of the eruption (stage 3), both time series for SO₂ flux eventually converge to exhibit similar behavior
390 during the final stage of quiescent degassing. To establish convergence between these two SO₂ flux time series, we use a simple moving average (SMA) with a 2- to 8-hour window on the TROPOMI-inverted SO₂ flux time series. Our analysis reveals that when using a 7–8 hour SMA window, TROPOMI-derived SO₂ flux closely aligns with OMPS-derived SO₂ flux, exhibiting a strong correlation coefficient of 0.77 (Fig. 7d). Note that the correlation coefficient between OMPS-derived SO₂ flux time series and unsmoothed flux from assimilating TROPOMI observations decreases to 0.55. This decrease in the correlation
395 coefficient is mainly because OMPS cannot accurately measure SO₂ emissions during the initial (stage 1) and paroxysmal (stage 2) eruption phases, as reported in sect. 3.1. As a result, assimilating TROPOMI observations into CHIMERE CTM produces a more dependable time series of SO₂ flux with improved temporal resolution. This procedure effectively captures short-lived and intense pulses of SO₂ emissions. In summary, assimilating high spatial resolution SO₂ column observations leads to the retrieval of high temporal resolution SO₂ emissions.

400 4.2 Limitations of the inverse modeling procedure

4.2.1 Modeling emissions over time

The CTM simulation, initialized with inverted SO₂ sources, closely aligns with LEO satellite observations, maintaining a mean residual close to zero in the normal distribution throughout the entire eruption period (Fig. S15). However, the increased standard deviation of analysis residuals, primarily on December 16 (Fig. S15d, S15g), highlights the limitations of inverse
405 modeling. On December 16, the CTM simulation does not fully replicate the leading forefront of the plume, as shown in Fig. 1c and S16. Additionally, it faces challenges in distinguishing between the two branches of the SO₂ plume over the Fiji and Vanuatu islands on December 17 (Fig. 1d, 2d).

The wind fields in the CTM simulation may lack vertical mixing and horizontal shears. The simulation may have also removed most of the emissions by a false precipitation event, or transport errors may have accumulated over time, adding
410 biases to the aged plume. This deficiency could stem from either the resolution of the forcing WRF meteorological model or the quality of the archived reanalysis data, affecting the trajectory accuracy of plume parcels, particularly for distant or aged tracers (see Boichu et al., 2013). To mitigate this uncertainty, we need to limit the ingestion of excessively distant or aged plume sections into the inversion procedures. Furthermore, the CTM simulation cannot replicate concentrated SO₂ parcels near the source. This is because of a well-known issue in Eulerian CTMs, where there is excessive diffusion, as discussed by Freitas
415 et al. (2012). This discrepancy is the cause of the high standard deviation in analysis residuals observed on December 15 (Fig. S15c-iv) and 16 (Fig. S15d-iv). Specifically, the CTM simulation, initialized with TROPOMI-derived SO₂ emissions, cannot generate the dense SO₂ columns measured by TROPOMI near the source. Notably, this problem does not occur when the CTM



simulation is initialized with OMPS-derived SO₂ sources. In addition, observational data indicates that meteorological clouds have a substantial impact on the detection of satellite SO₂ plumes on December 17 and 18 (Fig. 6). In Fig. S17, we present a schematic depicting such scenarios in which the inversion procedure for SO₂ emission profiles is affected by bias resulting from less observational constraint or inherent bias in the CTM simulation. Despite all these challenges, thanks to the assimilation of multiple successive satellite overpass images of the dispersed SO₂ plume, the CHIMERE CTM simulation could reasonably produce SO₂-rich parcels across this continental-scale domain (sect. 3.1).

4.2.2 Overestimating the altitude of SO₂ emissions linked to weak flux emissions

In our inverse modeling procedure, we employ a sifting threshold, detailed in Fig. S5 and described in section 2.4, to detect and filter out SO₂ emissions obtained through the data assimilation with significant uncertainty. Despite this, we still encounter emissions that exhibit conflicting attributes, notably low flux values and unexpectedly high injection altitudes, occurring in the initial and third stages of the eruption (indicated in gray contours Fig. 3). For example, the pre-eruptive emission #T1 (contoured in gray in Fig. 3a) with an amplitude of 1 kt h⁻¹ is injected at an altitude of 11 km ASL. SO₂ plume linked to this emission aligns with the leading edge of the plume on December 15 (Fig. S14a) but falls within the LEO satellite swath's edge, where both sensors have difficulty in detecting SO₂ plume (sect. 3.1.4). Moreover, on December 16, this emission contributes to the northern segment of the main SO₂ plume (Fig. S14d-iii), remaining undetected by the LEO satellites due to meteorological clouds (red contoured lines in Fig. 6a).

In a broader context, we observe that the low SO₂ emissions with large uncertainty, which are subsequently filtered out during the post-processing of inverse modeling results (sect. 2.4), tend to reach higher injection altitudes (Fig. S5). These emissions typically register at less than 0.5 kt h⁻¹ flux values, considered as the background level, but they tend to be released at an average altitude higher than 6 km ASL. Concerning TROPOMI-derived SO₂ flux, these exclude SO₂ emissions amounting to 13 kt of SO₂ mass, while for OMPS-derived SO₂ flux, the total is 16 kt (Fig. S5). OMPS data assimilation rejects more SO₂ mass than TROPOMI data assimilation, even when the sifting threshold is the same. This is because OMPS is less sensitive to weak emissions.

Stohl et al. (2011) report a tendency for volcanic emission source terms derived from inverse modeling to shift towards higher altitudes when extracting ash injection heights from the 2010 Icelandic eruption. They attribute this behavior to systematic errors in satellite detection and disparities with a priori emission knowledge that do not align with satellite measurements. Their Lagrangian transport model simulation resolution is more than 7 times coarser than ours, and they identify continuous emissions at approximately 10–11 km ASL throughout their study period. There are two key explanations for these types of SO₂ emission retrievals by inverse modeling. Firstly, weak emissions from point sources like volcanoes are challenging to detect via satellites, providing limited constraints for inverse modeling. Additionally, the presence of meteorological clouds can hinder the detection of dense SO₂ plumes, falsely rendering them as weak SO₂ columns in LEO satellite images (see red contoured regions in Fig. 6-ii). TROPOMI's high spatial resolution proves invaluable in addressing this issue, as demonstrated in our pre-eruption SO₂ emission analysis (as shown in gray contours in Fig. 3a). Secondly, the tendency for these retrievals to be associated with higher altitudes can be explained from a modeling perspective. Tracers released at higher altitudes disperse



more quickly due to larger wind fields, particularly within the planetary boundary layer and troposphere (as demonstrated by Stoffelen et al. (2005)). This leads to faster and wider spatial dispersion, resulting in lower SO₂ molecule density per unit area compared to emissions at lower altitudes. In contrast, lower altitudes with weaker wind fields maintain a higher SO₂ molecule
455 density per unit area, which contradicts the satellite observations of weak SO₂ columns. This discrepancy means that the weak SO₂ columns observed by satellites are less likely to correspond to low-altitude tracer emissions, especially in the context of the linear least-squares optimization procedure. This challenge is further exacerbated in OMPS data assimilation due to its coarser spatial resolution.

Inverse modeling of weak SO₂ columns is indeed challenging, but employing higher-resolution satellite observations, such
460 as TROPOMI, greatly aids in accurately capturing emission timing. However, precise determination of the injection height for these uncertain emissions is vital, constrained by sensor sensitivity limitations and daily observations. Therefore, the interpretation of such emissions, highlighted in gray in Fig. 3, requires caution. In such situations, SO₂ height products like IASI SO₂ height products (Clarisse et al., 2014) or TROPOMI SO₂ height products (Hedelt et al., 2019) become crucial in constraining the inverse modeling procedure.

465 4.3 Insights into volcanological processes

Following an initial moderate magma intrusion resulting in surface activity within the caldera and a lava flow, a substantial magma-filled dike was intruded at a shallow depth. This dike caused significant deformation of the island, as documented by Shreve et al. (2019, 2022). The dike's propagation towards the eastern part of the island led to a surface rupture and ultimately triggered a submarine eruption offshore.

470 During the first stage of the eruption, we observe a significant correlation between the thermal activity of the lava flow, indicated by the thermal index of lava flow pixels from Himawari-8/AHI observations (green line in Fig. 1a), and the TROPOMI-inverted SO₂ flux time series (red line in Fig. 1a). Emissions labeled #T2 and #T3 coincide with an increase in lava flow activity on December 15, between 00:30 and 04:30 UT, as documented by Shreve et al. (2019). Emission #T2 reaches altitudes between 9–10 km ASL, discharging approximately 3.5 kt of SO₂. Meanwhile, emission #T3 releases about 3.5 kt of SO₂ at an altitude
475 of 5 km, along with an additional 0.5 kt at 2 km ASL. Emissions labeled #T4 and #T5, preceding a significant seismic event around 20:00 UT on December 15 (Shreve et al., 2019), also coincide with the lava flow, indicating that the primary source of SO₂ degassing during this phase is closely related to the degassing of the spreading lava flow within the caldera.

At the onset of the second stage of the eruption on December 16, there is a notable shift in eruption dynamics. During this period, the thermal activity within the intra-caldera lava flow returns to a pre-eruptive background level, indicating the cessation
480 of lava emission, as confirmed by Sentinel-2 images in Shreve et al. (2019). It suggests that the lava flow has reached its full extent. However, the TROPOMI-derived SO₂ flux reveals a sudden, substantial increase in SO₂ emissions (#T7 and #T8), releasing over 10 kt of SO₂ and reaching heights of approximately 11 km ASL (Fig. 3a). This increase is associated with the most significant paroxysmal degassing event since the onset of the eruption. It occurs shortly after a renewed seismic activity, as reported by Shreve et al. (2019), supporting the intrusion of a substantial dike that propagates towards the eastern part of



485 the island. Consequently, the heightened degassing on December 16 likely results from gases originating from the voluminous dike intrusion, which separated from the magma and reached the surface as the dike propagated at a depth of a few kilometers.

Therefore, the assimilation of TROPOMI observations enables the retrieval of hourly-resolved SO₂ emissions. This procedure not only facilitates the monitoring of changes in eruptive dynamics but also aids in identifying various magma sources of SO₂ emission. Additionally, it offers an advantage over Himawari-8/AHI observations by being less affected by ash co-
490 emission. The high temporal resolution provided by LEO satellite data assimilation serves as an additional resource for supporting local volcanological observatories in their efforts to assess local hazards.

5 Conclusions

Our inverse modeling procedure, applied to the 2018 Ambrym eruption, reveals significant benefits from assimilating TROPOMI's hyperspectral and high-spatial resolution SO₂ column measurements, providing valuable insights into the different phases of
495 magma degassing. The assimilation of TROPOMI data excels at capturing short-lived SO₂ emissions. This capability is attributed to TROPOMI's high spatial resolution, allowing it to detect young and narrow plume fragments. This precision significantly improves the accuracy of estimating high SO₂ flux values, especially during the paroxysmal phase of the eruption. Furthermore, TROPOMI data assimilation demonstrates heightened sensitivity to weak pre-eruptive fluxes, even in areas where measured pixels fall within noisy swath edges. This results in a higher-resolution SO₂ flux time series that remains unimpacted
500 by ash co-emissions. It serves as a valuable complement to geostationary satellite measurements, which can miss the SO₂ flux proxy during ash co-emission phases. Our inverse modeling procedure further demonstrates the feasibility of predicting the presence of SO₂ plumes below meteorological clouds by assimilating successive images of dispersed SO₂ plumes, especially assimilating the more sensitive TROPOMI observations. Lastly, our findings shed light on the origins of the Ambrym eruption's SO₂ degassing, which stems from two distinct magma sources. One is associated with surface-level lava flow activity,
505 while the other involves the substantial degassing of SO₂ during the paroxysmal phase of the eruption, originating from a voluminous magma intrusion at shallow depths. The total SO₂ emission budget of this eruption is 42 ± 16 kt (OMPS) or 52 ± 13 kt (TROPOMI), surprisingly unaffected by the voluminous magma accumulation (>0.4 km³) at shallow depth that fractured the surface until the eastern coast.

To enhance the accuracy of SO₂ mass flux and injection height retrieved through inverse modeling procedure, reducing
510 the time lag between emissions and data acquisition is fundamental. Additionally, assimilating observations with varying sensitivities to SO₂ altitude and coexisting particles in volcanic plumes would enhance the accuracy of the retrieved source emissions. Our future plans involve assimilating hyperspectral SO₂ column observations from both UV and IR satellite sensors, harnessing their respective strengths. IR sensors, such as IASI, provide a distinct sensitivity to ash particles and acquire data bi-daily, encompassing both day and night, unlike UV satellite sensors that offer daily observations. Additionally, the assimilation
515 of SO₂ height data from IR sensors in the inverse modeling procedure is expected to enhance the accuracy of emission profiles.



Code availability. The CHIMERE CTM code (version: 2017r4), used in this study, can be accessed for free at the LMD laboratory repository in Paris, France (<https://www.lmd.polytechnique.fr/chimere/>). Similarly, the WRF-ARW model code used in the simulation (version: 4.1.3) can be found on the Git-Hub platform (<https://github.com/wrf-model>). These simulations were performed on the LOA HPC facilities using INTEL-licensed libraries, including the Intel version 2020.1.217 and the Intel MPI version 2019.7.217. Other software packages used include the HDF5 library (version: 1.12.1), NetCDF4 library from Unidata (version: 4.8.1), and PnetCDF library from Argonne laboratory (version: 1.12.3). The preparation of the Jacobian matrix, a key component in the inverse modeling procedure, was carried out using Python (version 3.10.9) modules, along with CDO (version: 2.1.1) and NCO (version: 5.1.4) python bindings. Most of the figures are created using the Generic Mapping Tool (GMT) libraries (version: 6.3.0), and a few are prepared using Matplotlib (version: 3.6.3). Inkscape version 1.2.2 is used to arrange the individual figures in the panels.

525 *Data availability.* The ERA-5 reanalysis data used to drive the WRF run are available for free on the climate data store of ECMWF (<https://cds.climate.copernicus.eu/cdsapp#!/home>). TROPOMI and OMPS SO₂ columns (level 2) are obtained from the NASA GES DISC platform (<https://disc.gsfc.nasa.gov/>).

Video supplement. Throughout December 13–18, 2018, geostationary Himawari-8's SO₂ RGB composite images are made available for viewing the SO₂ emissions from Ambrym every 20 minutes.

530 *Author contributions.* The original idea was conceived by MB. The inverse modeling setup was developed, and remote sensing data were obtained by MB, AKB, and FT. AKB and FT conducted the numerical calculations. NH and SH prepared and analyzed the Himawari-8/AHI data. The results were examined by AKB, MB, and SH. AKB wrote the manuscript, which was reviewed, commented on, and revised by MB and SH. All authors approved the article.

Competing interests. The authors declare that they have no conflict of interest.

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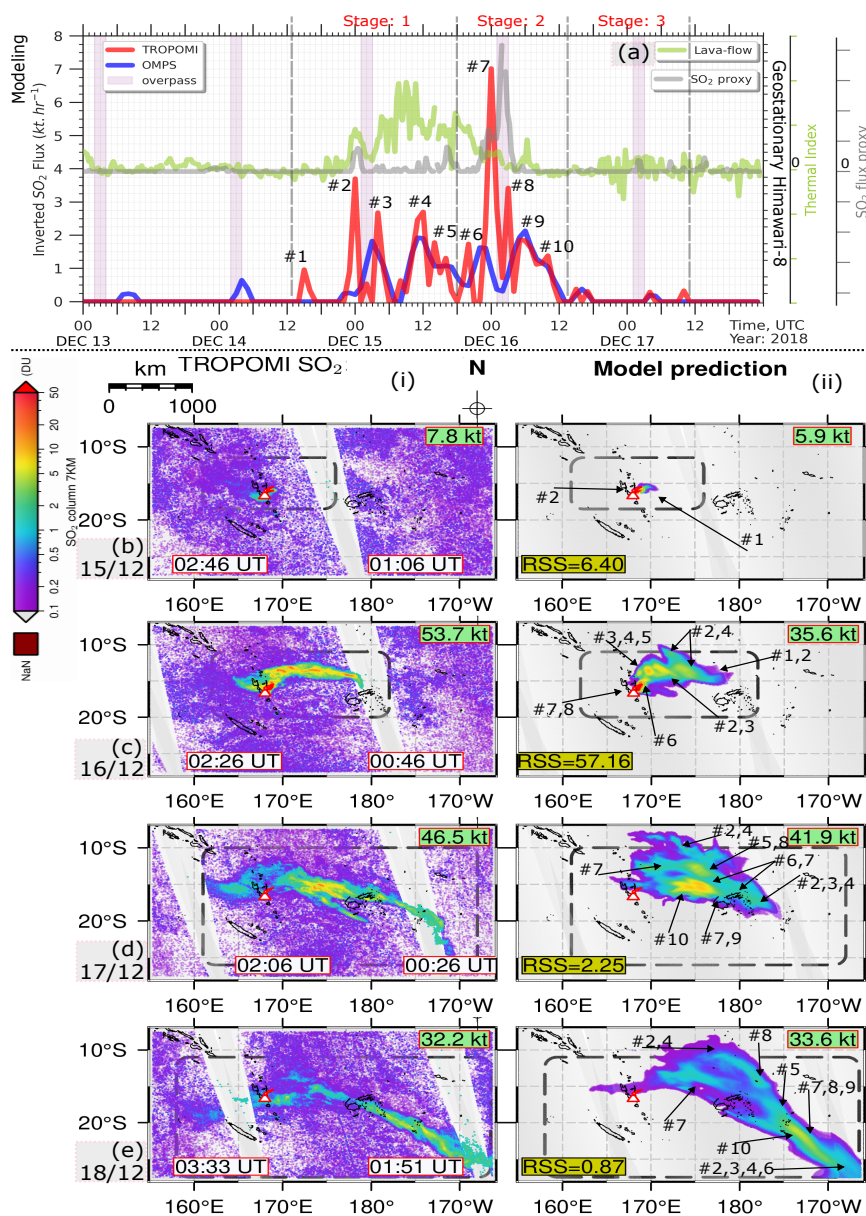


Figure 1. Inverse modeling results: (a) Hourly-resolved SO₂ mass-flux (kt h⁻¹) from Ambrym by assimilating six consecutive images from TROPOMI and OMPS, respectively, taken between December 13–18, 2018. The two satellites’ simultaneous overpass time is indicated with a light pink shade. The TROPOMI-derived time series (red line) produces strong pulses of SO₂ emissions, numbered #T1 through #T10. Time series of the thermal index associated with lava flow pixels (green line) and qualitative SO₂ flux proxy (gray line), both derived from Himawari-8/AHI are also shown. The SO₂ columns for December 15–18 (b–e) are illustrated from TROPOMI (i), together with the associated model simulations, i.e., initializing the CTM simulation with the SO₂ sources acquired through inverse modeling (ii). The inverted SO₂ injection heights are detailed in Fig. 3. The arrows link the emissions noted in the SO₂ mass-flux time series (a) to the corresponding SO₂ parcels (b–e). The analysis residual squared sum (RSS) between observation and CTM simulation, satellite orbit time tags in UT, and SO₂ mass (kt) within the dashed box are provided. SO₂ maps for 13–14 December can be found in Fig. S7.

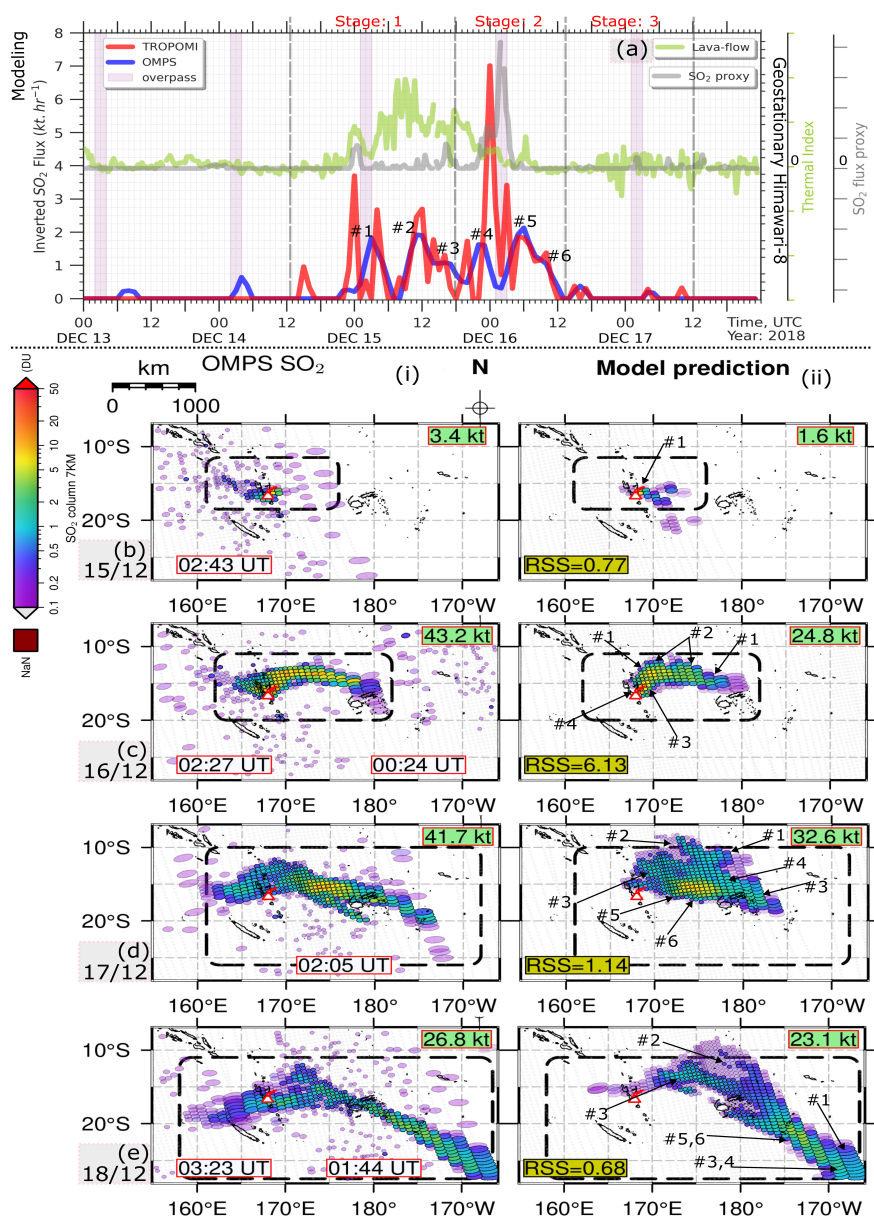


Figure 2. Similar to Fig. 1, but for the inverse modeling of OMPS SO₂ columns (blue line). OMPS has a coarser spatial resolution than TROPOMI, which can cause footprint distortions when the scan lines are near the edge of the swath.

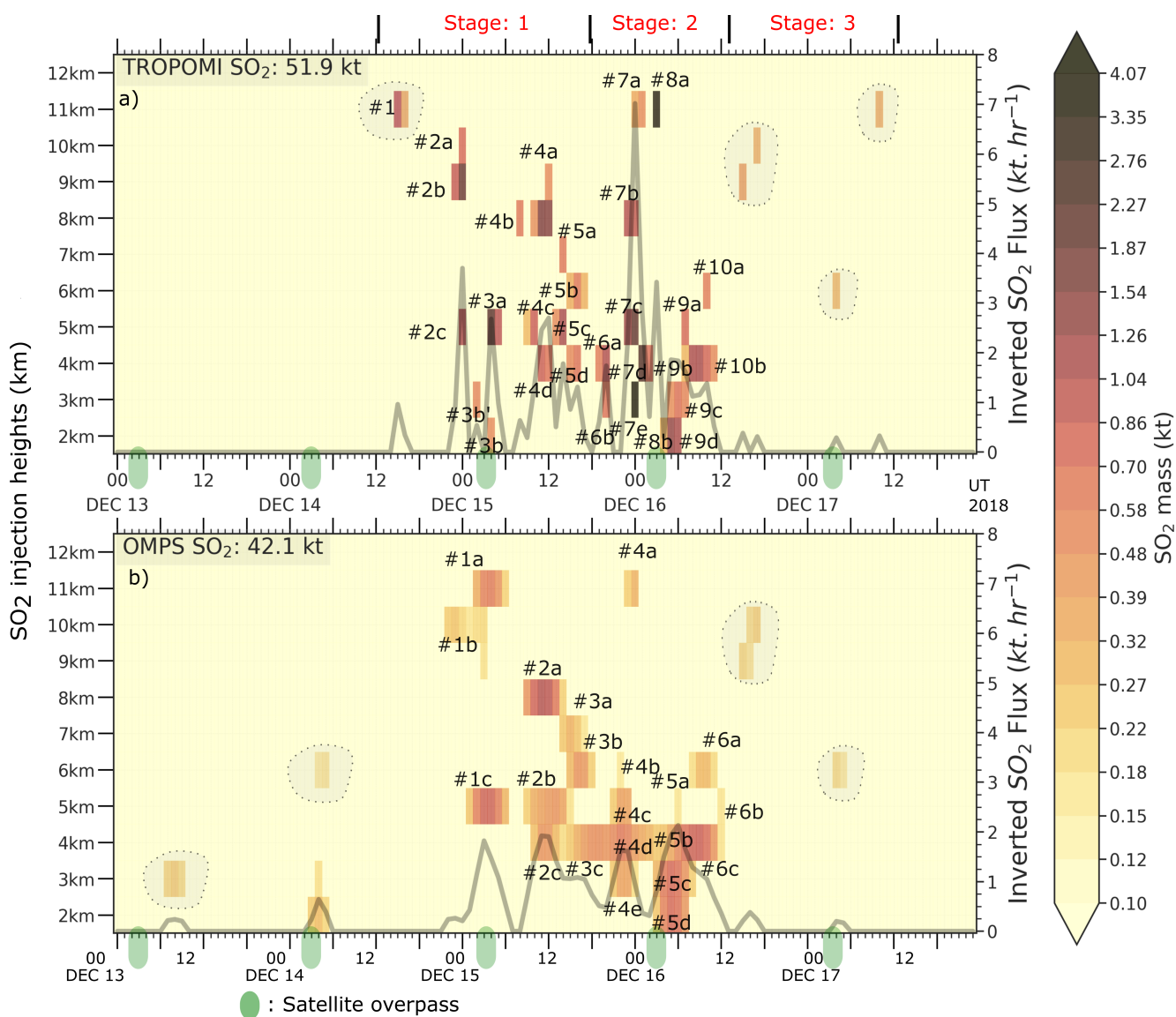


Figure 3. SO₂ emission rates by inverse modeling (identical to Figs. 1a, 2a) for the 2018 Ambrym eruption at hourly temporal resolution, showing SO₂ mass (kt) and corresponding injection heights (km). Numbered emissions (#) are labeled in alphabetical order to indicate multiple SO₂ injection heights. Ambiguous SO₂ injection heights are contoured in gray. Satellite overpass times are also indicated.

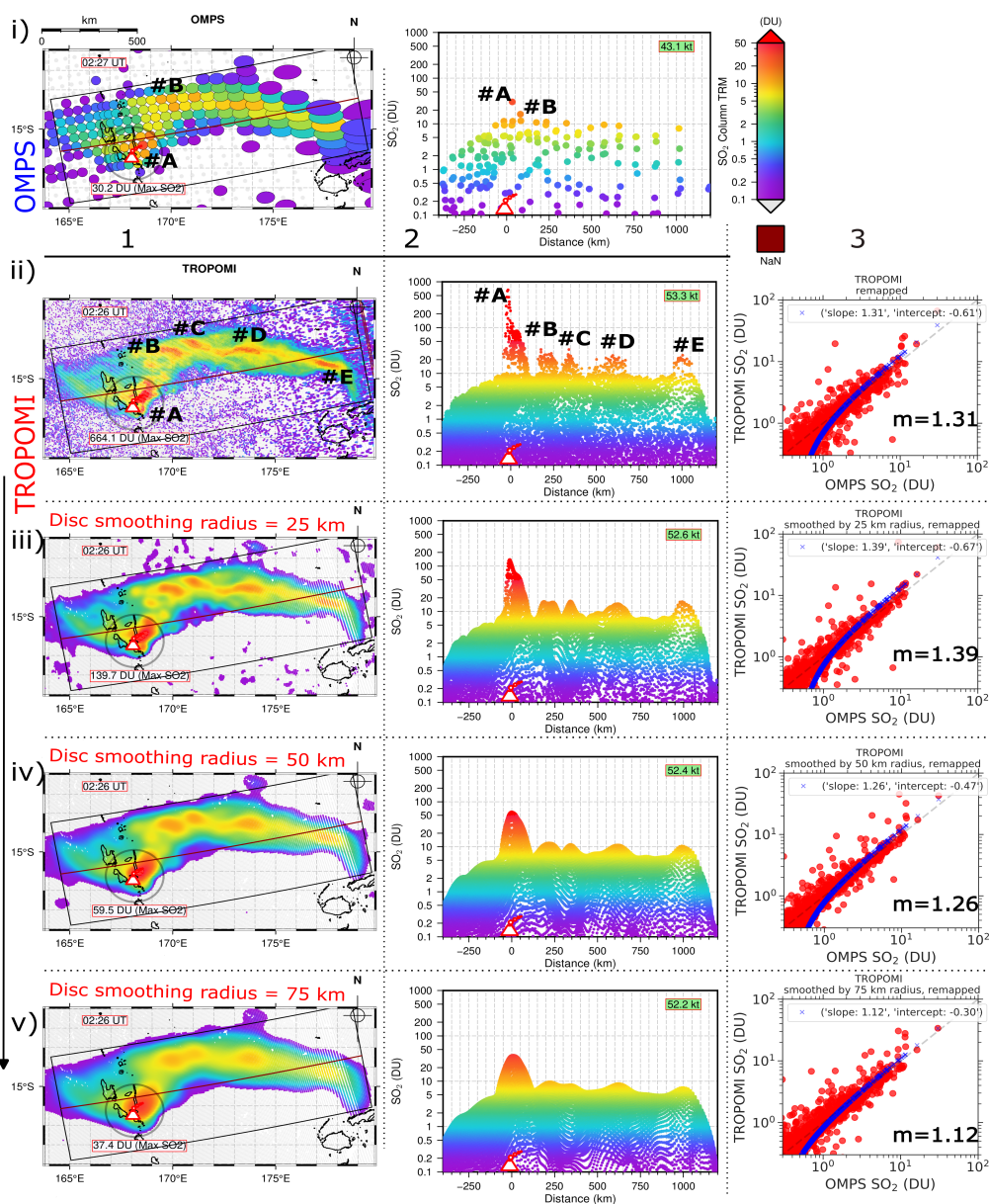


Figure 4. Ambrym dispersed SO_2 -rich plume on December 16, 2018, at about 02:30UT, observed from OMPS (i) and TROPOMI (ii). The maximum SO_2 column within a radius of 150 km around the source is indicated in a rectangular box with a red border. TROPOMI data are smoothed over disks with radii of (iii) 25, (iv) 50, and (v) 75 km, respectively. The first column (1) shows the maps of the SO_2 column. Color-shaded ellipses represent the satellite-measured SO_2 column and the corresponding footprint. The gray dots indicate the center of the footprint for the SO_2 column less than 0.1 DU. The footprint gradually stretches horizontally with increasing longitude because of the large viewing zenith angle and the curvature of the Earth. The second column (2) depicts the eastward plume transect. This transect encompasses pixels within a rectangular box (1200 km \times 600 km). These pixels are projected onto the central axis, positioned in the middle of the box. In the top right corner of each panel, we show the SO_2 mass (kt) contained within this rectangular box. The third column (3) refers to the linear regression between TROPOMI observations, after smoothing and remapping onto the OMPS grid, and OMPS raw SO_2 column data. The linear regression data is based on the measurements on December 13–18, 2018. The slope of the linear fit is denoted by "m".

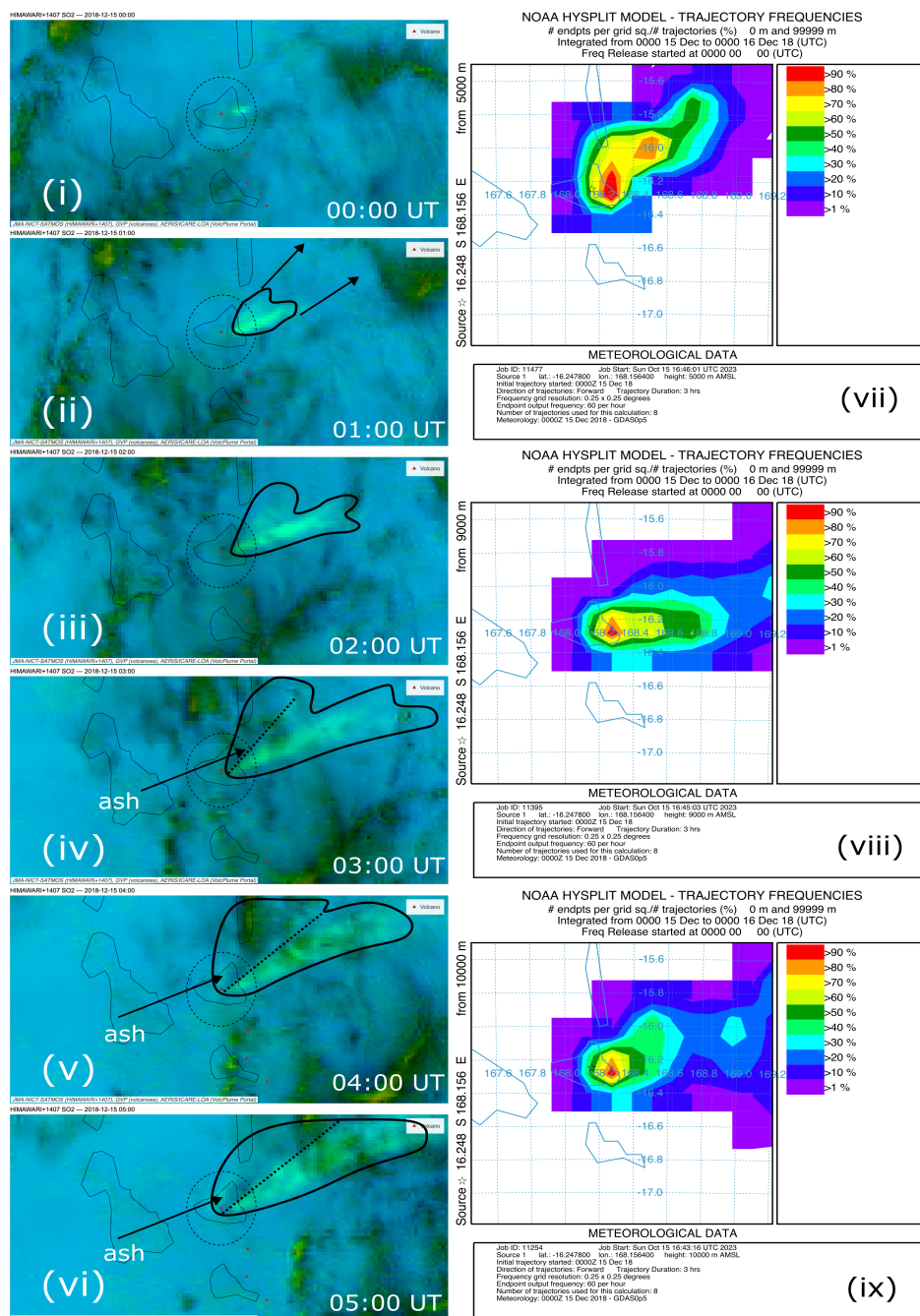


Figure 5. Himawari-8/AHI SO₂ RGB compositions for the Ambrym plume on December 15 show the hourly evolution of the two branches of the SO₂ plume from 00:00 UT until 05:00 UT (left panel, i-vi). The black contour line shows the two strong wind shears at different altitudes that caused the ash and SO₂ to separate, as indicated in iv–vi. The right panel shows the HYSPLIT trajectory frequencies when initialized at 5 km (vii), 9 km (viii), and 10 km (ix) ASL at 00:00 UT on December 15, using 0.5-degree GDAS reanalysis data.

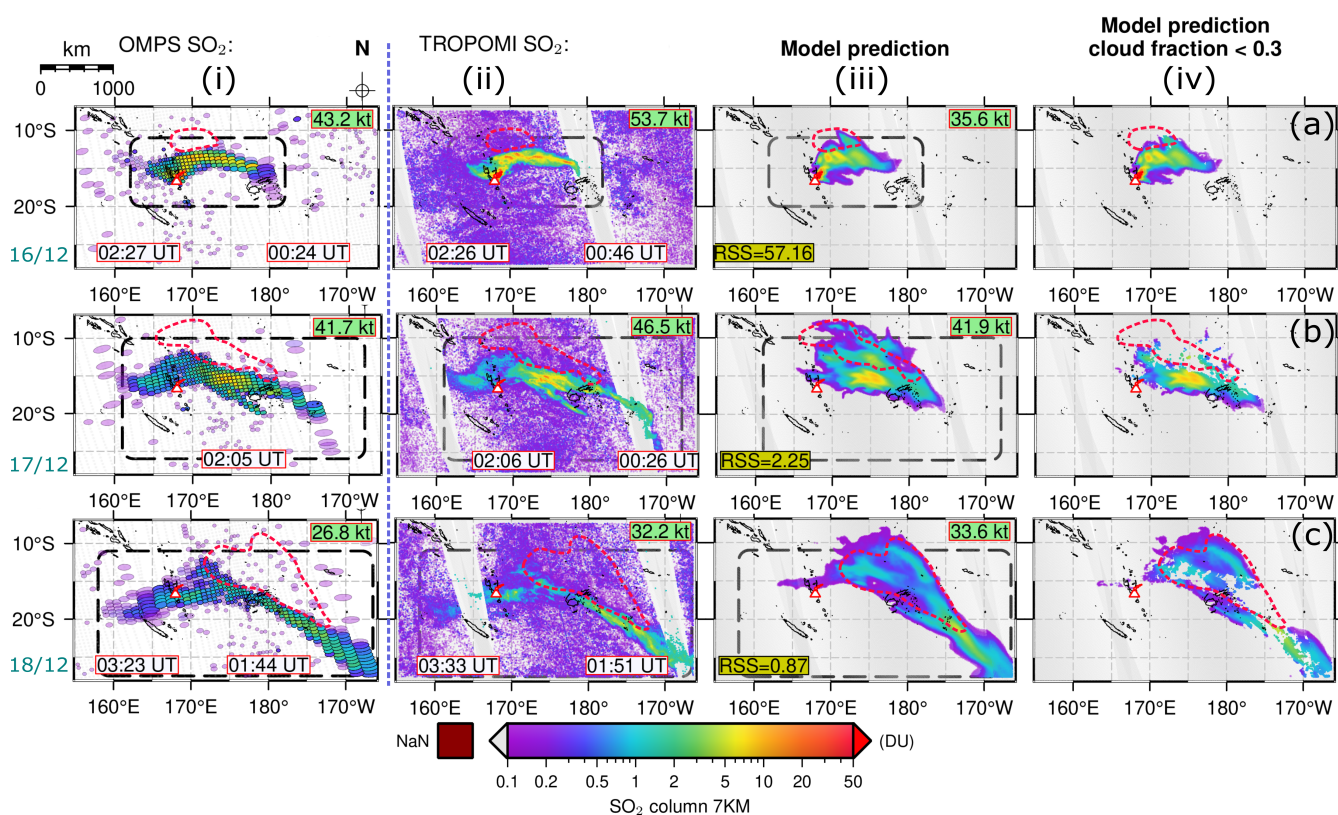


Figure 6. Illustration of the cloud cover over the north and northeast sections of Ambrym’s volcanic SO₂ plume on December 16 (a), 17 (b), and 18 (c), outlined in red. It features SO₂ column measurements from OMPS (i) and TROPOMI (ii), the CHIMERE CTM simulation initialized with TROPOMI-derived SO₂ flux emissions (iii), and the same simulation after implementing a cloud fraction cutoff of 0.3 (iv).

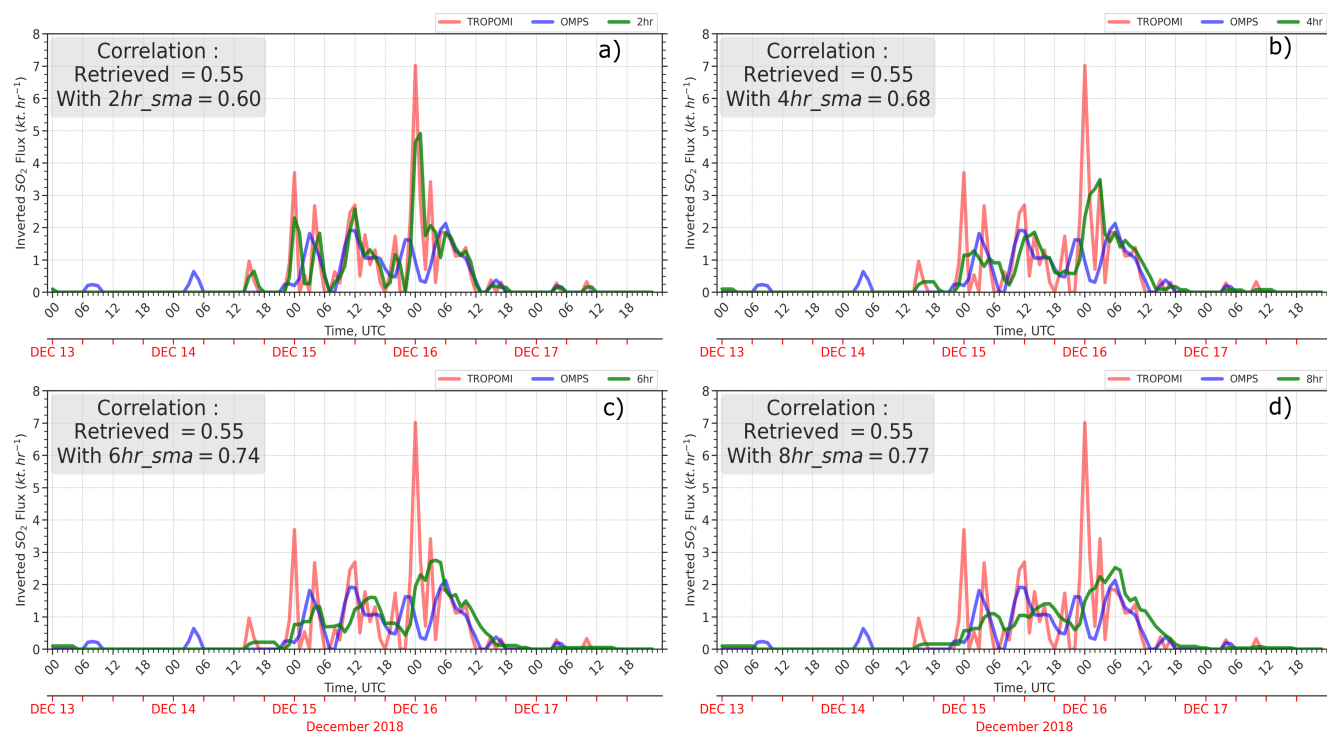


Figure 7. Pearson product-moment correlation coefficients between OMPS-derived SO₂ flux time series and TROPOMI-derived SO₂ flux time series are presented. The TROPOMI-derived SO₂ flux time series is subject to smoothing using a simple moving average (SMA) time window of (a) 2 hours, (b) 4 hours, (c) 6 hours, and (d) 8 hours. The text boxes within each panel show the correlation values both before (retrieved) and after applying the SMA to the TROPOMI-derived SO₂ flux time series.