

## **Response to Reviewer 1 (Prof. Keith Beven)**

The edited manuscript has changes highlighted in blue, and all the line numbers referred to in our response correspond to the edited version. Thank you.

Reviewer comment 1: This paper represents a valuable first attempt to provide a practical approach to the probabilistic modeling of meander plan migration, with an application to satellite data for the Ucayali River in the Amazon basin.

As such, it is a bit outside my normal expertise, but I do have more experience in trying to apply probabilistic methods to deterministic knowledge in hydrological and other environmental applications. As such, one of the things that is lacking here is any recognition of the past discussions of epistemic and aleatory uncertainties in environmental applications and their consequences for model testing and uncertainty quantification. The main lesson learned, in fact, is that there is no right answer – what comes out depends on the assumptions made.

Authors' response: We are pleased to read that Prof. Beven considers our manuscript valuable. Thank you very much for reviewing our manuscript and for your suggestions.

To incorporate this comment, we have now further elaborated on and cited previous work done in the field on statistical treatment of uncertainties in landscape evolution and hydrosciences. We added five more references on uncertainty quantification, with one referring to models in earth sciences in general. (L48, L49). We have also rephrased part of the reviewer's comment and incorporated them into the introduction. "Environmental systems, like migrating channels, can be modeled by various types of governing equations - varying in their detail and complexity. These model structure choices dictate the performance of the model as well as the statistical properties of the residual errors. We, therefore, discuss the pros and cons of our statistical assumptions as well." (L67)

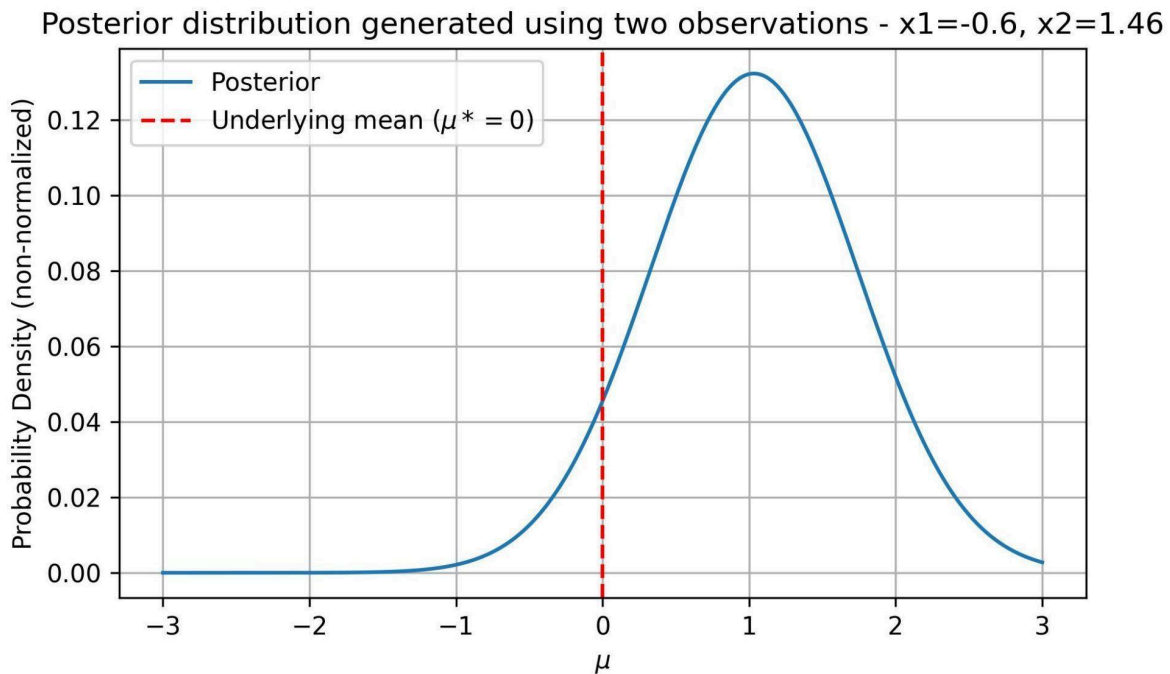
Reviewer comment 2: Here, I suspect that a professional statistician would be reasonably happy with the assumptions made since the problem has been shoehorned into a formal statistical framework (with consequent discussion in the

paper about the possibility of variability of parameters in time and space). But are those assumptions correct? A comment on Figure 6 suggests that “the parameters gravitate towards the same values” (L347). Even in the hypothetical case, where the assumptions are mostly met by definition this is surely not the case – there is a move of the migration coefficient away from the true value. Is the result therefore being biased by the likelihood function? The differences for the actual application are even more marked (the later discussion is more realistic in this respect).

Authors’ response: Thank you for pointing this out. We agree that the likelihood function comes with assumptions about the statistical properties of errors. We mention that explicitly in the paper ( section 4.7: L493 - L521). Now we have added a line in the introduction and conclusions as well (L67 and L545).

“We also suggest further research into the extension of our additive stochastic term, enabling it, for example, to have variable statistical features in space and time.”

Figure 6: Given we only have observations limited in space and time, the posterior will not necessarily have a mode at the underlying parameter value. Even when the assumptions about the distribution are correct - this is because a single trajectory of observed migration is a random sample. But our posterior faithfully captures the parameter value in its spread. To demonstrate this point, we include below a posterior of the mean of a normal distribution of two samples sample from that distribution. Theoretically, it can be shown that the standard deviation of the posterior shrinks with  $\sqrt{n}$ , where  $n$  is the number of samples. And, as the reviewer points out, we have discussed the differences in the posterior distribution using real observations in detail in the discussion section. We now additionally mention this in the caption of the figure.



Reviewer comment 3: So one of the questions (again with much discussion elsewhere but not here) is how far the uncertainty component is actually compensating for the model deficiencies and at what point should the underlying model be considered invalid (see the discussion of model invalidation in Beven and Lane, HP 2022, and references therein). In fact, each model run has its own set of residuals that will not necessarily have common structure or parameters. To assume that they have certainly simplifies the analysis – but it is again an assumption (not “by definition” as stated on L206 – other choices would be possible). So, in conclusion, I suggest that some revision of the paper is needed to reflect some of the issues raised above, both in querying the choice of assumptions as the methods are presented, and in the discussion (especially in how epistemic uncertainties are being formulated as if they are purely aleatory).

Authors' response: We have changed the wording of L213 to explicitly mention that we assume Gaussianity. As mentioned before, we make it explicit that the error description can be made more representative (section 4.7 and L542). We additionally include and cite insights from Beven and Lane, 2022, to drive home the point of rigorously testing and (in)validating environmental models.

I would very much like to see extension to more meanders and longer time scales (surely the data are available) as I suspect that this might reveal more limitations of the assumptions – but I accept that might not be possible. This is already a useful first attempt at uncertainty estimation of such a problem. [As an aside, perhaps for future studies you might consider a limits of acceptability approach to model evaluation?]

Authors' response: We hope to publish another manuscript with details on the application of this method on longer timescales and more rivers. As the reviewer mentioned, for this manuscript, we wish to abstain from including more simulation experiments. We believe limiting ourselves to introducing and explaining the framework will help maintain thematic focus.

Some other comments:

Equation 2. Theta should be included in  $g()$ , even if you then later assume independence.

Authors' response: Resolved. We mention this in L100.

L135. The thing about epistemic errors including model structural errors due to oversimplification is that they are not necessarily systematic – that is what makes strong statistical assumptions often difficult to justify.

Authors' response: We have now made this point more explicit in L143. “Model structure deficits can lead to a combination of systematic (underestimation of the migration rates) as well as random deviations from the real system response.”

L141. The equifinality thesis has quite a long history in hydrology (see e.g., Beven, 2009, Environmental Modelling – An Uncertain Future?)

Authors' response: We have included this citation.

L154. There is a lot of experience with model evaluations and uncertainty estimation of flood risk maps (some mentioned in the Beven and Lane paper)

Authors' response: We have included more citations, including the one mentioned by the reviewer.

L157. Follow some parametric distribution in the limit. You can assume that of course, but this is a nonlinear model subject to epistemic uncertainties so will not necessarily follow in time or space.

Authors' response: As the reviewer had cautioned before in his comments, so we have made this point explicit with various additional lines.

L374/5. Going out in the field. An interesting comment since you are not using a process model and you can get satellite images (and therefore explicitly quantify actual patterns of residuals) relatively frequently – so what would you actually measure? Might you not better suggest allowing data assimilation in updating the forecasts (or will that be the next paper using more up to date images?)?

Authors' response: Thank you for the suggestion. We have now removed the mention of field visits and revised it to include data assimilation.

This could obviously be done in space too, working from bend to bend (L388ff) rather than as a spatially distributed inverse problem with all the interactions between bend parameter sets – since the best prior estimate of the distribution of parameters for each bend should be that of the upstream bend (unless there is information otherwise).

Authors' response: Thank you for this suggestion. We think this spatially sequential updating of parameter values from bend to bend would be an interesting hypothesis to test in future work. For this work, we have assumed that the same parameter values generate the observed migration for the entire domain of the channel.

L438. But in your case the observations are informative in the hypothetical case because the assumptions are consistent. In the real case, they are not, but the observations might still be informative – for example, in showing that your model is wrong (as suggested by Figure 8).

Authors' response: We have now revised our language to mention that we mean "informative" in the context of parameter estimation. And we agree that observation in general always carry information to validate or invalidate a model (L447).

### **Additional references added to the manuscript:**

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