

# 1 Meteorological modeling sensitivity to parameterizations and 2 satellite-derived surface datasets during the 2017 Lake Michigan 3 Ozone Study

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15 **Abstract.** High-resolution simulations were performed to assess the impact of different parameterization schemes, surface  
16 datasets, and analysis nudging on lower-tropospheric conditions near Lake Michigan. Simulations were performed where  
17 climatological or coarse-resolution surface datasets were replaced by high-resolution, real-time datasets depicting lake surface  
18 temperatures (SST), green vegetation fraction (GVF), and soil moisture and temperature (SOIL). Comparison of two baseline  
19 simulations employing different parameterization schemes (referred to as “AP-XM” and “YNT”, respectively) showed that  
20 the AP-XM simulation produced more accurate analyses on the outermost 12-km resolution domain, but that the YNT  
21 simulation was superior for higher-resolution nests. The diurnal evolution of the surface energy fluxes was similar in both  
22 simulations on the 12-km grid but differed greatly on the 1.3-km grid where the AP-XM simulation had much smaller sensible  
23 heat flux during the daytime and physically unrealistic ground heat flux. Switching to the YNT configuration led to more  
24 accurate 2-m temperature and 2-m water vapor mixing ratio analyses on the 1.3-km grid. Additional improvements occurred  
25 when satellite-derived surface datasets were incorporated into the modeling platform, with the SOIL dataset having the largest  
26 positive impact on temperature and water vapor. The GVF and SST datasets also produced more accurate temperature and  
27 water vapor analyses, but degradations in wind speed, especially when using the GVF dataset. The most accurate simulations  
28 were obtained when using the high-resolution SST and SOIL datasets and analysis nudging above 2 km AGL. These results  
29 demonstrate the value of using high-resolution satellite-derived surface datasets in model simulations.

## 30 1 Introduction

31 Locations along the Lake Michigan shoreline in the United States have a long history of recording surface ozone concentrations  
32 that exceed levels set by the National Ambient Air Quality Standards (NAAQS), especially during the warm season (Stanier  
33 et al. 2021). Since the first ozone NAAQS was released in 1979, most lakeshore counties in the states bordering Lake Michigan  
34 (Wisconsin, Illinois, Indiana, and Michigan) have been designated as being in nonattainment for surface ozone in one or more  
35 of the subsequent NAAQS revisions. These states are required by the Clean Air Act to develop State Implementation Plans

36 (SIPs) to demonstrate strategies to bring affected areas into attainment and to mitigate the impacts of high ozone  
37 concentrations. Large decreases in local emissions of ozone precursors such as nitrogen oxides and volatile organic compounds  
38 have steadily reduced one- and eight-hour maximum ozone concentrations across the region in recent decades (Adelman 2020).  
39 However, the implementation of stricter ozone NAAQS means that additional air quality modeling assessments are necessary  
40 to help states demonstrate that they can reach attainment by the required statutory deadlines.

41  
42 Urban and rural areas near Lake Michigan are susceptible to high ozone events due to the complex interaction between synoptic  
43 and mesoscale circulation patterns with large sources of industrial, transportation, and urban emissions along the southern end  
44 of the lake. High ozone days are most common when synoptic-scale weather patterns characterized by weak southerly winds  
45 transport ozone and its precursors northward from their primary source regions over the Chicago and Milwaukee metropolitan  
46 areas and then interact with the mesoscale lake and land breeze circulations (Lyons and Olsson 1973; Ragland and Samson  
47 1977; Lennartson and Schwartz 2002). At night, the land breeze carries ozone precursors from land-based emissions sources  
48 over the lake where they become confined within a shallow nocturnal boundary layer and are then converted into ozone after  
49 sunrise via photochemical processes (Dye et al. 1995). As the land surface warms during the day, a reversal of the mesoscale  
50 circulation leads to the formation of the lake breeze during the morning that transports the high ozone airmass back onshore,  
51 with elevated ozone concentrations occurring across inland areas during midday and afternoon. On high ozone days, the lowest  
52 ozone concentrations are often found in areas with high nitrogen oxide emissions, such as Chicago and northwestern Indiana,  
53 with the highest ozone levels located downwind in rural and suburban areas to the north of these urban and industrial locations  
54 (Foley et al. 2011; Cleary et al. 2015).

55  
56 When synoptic-scale conditions are favorable for lake and land breeze formation, the horizontal temperature gradient between  
57 adjacent land and water areas influences the strength of the circulation pattern and the distance that the lake breeze penetrates  
58 inland during the daytime. Changes in the location of the lake breeze can have a profound impact on near-surface meteorology,  
59 the depth and vertical structure of the planetary boundary layer (PBL), and ozone concentrations along the Lake Michigan  
60 shoreline (Dye et al. 1995). Among other things, an accurate depiction of near-surface features in numerical weather prediction  
61 models requires an accurate specification of lower boundary conditions at the land and water surface. For example, an accurate  
62 representation of land surface conditions (such as soil moisture, soil temperature, and green vegetation fraction) are necessary  
63 to correctly partition the surface net radiation into sensible, latent, and ground heat fluxes. This partitioning in turn impacts  
64 the growth and depth of the PBL and lower-tropospheric temperature, moisture, and wind profiles (Berg et al. 2014; Dirmeyer  
65 and Halder 2016; Schwingshakl et al. 2017; Welty and Zeng 2018). Soil moisture and vegetation fraction (or leaf area index)  
66 are especially important variables through their influence on land-atmosphere coupling processes that link the surface  
67 hydrologic and atmospheric components of the earth system (Santanello et al. 2018, 2019). Indeed, Huang et al. (2017) showed  
68 that use of improved soil moisture and green vegetation fraction estimates in high-resolution simulations reduced biases in air  
69 temperatures and PBL heights over the Missouri Ozarks and had a large impact on biogenic isoprene emissions.

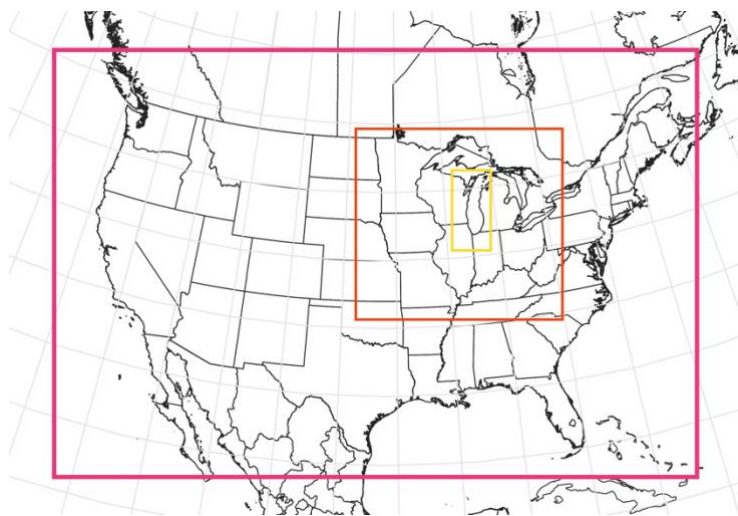
70  
71 Given the important role that boundary layer meteorology and the land-lake breeze circulation have on ozone production and  
72 transport in the Lake Michigan region, it is critical to explore the ability of different parameterization schemes and surface  
73 datasets to improve the accuracy of near-surface meteorological and air quality simulations. For example, ozone production is  
74 highly sensitive to temperature and humidity (Bloomer et al. 2009; Camalier et al. 2007; Coates et al. 2016; Dawson et al.  
75 2007; Jacob and Winner, 2009; Pusede et al. 2015), and production and transport of ozone precursors such as nitrogen oxides  
76 and volatile organic compounds are also dependent on temperature and winds (Dye et al. 1995; Porter and Heald, 2019; Wang  
77 et al. 2022; Wiedinmyer et al. 2006). In this two-part study, we develop and assess the accuracy of a satellite-constrained  
78 modeling platform for the Midwest United States that supports the needs of the Lake Michigan Air Directors Consortium  
79 (LADCO) as they conduct detailed air quality modeling assessments for its member states. The modeling platform uses high-  
80 resolution analyses of soil moisture, green vegetation fraction, and lake surface temperatures derived from satellite  
81 observations and an offline land surface model (LSM) to constrain the evolution of the lower boundary conditions during  
82 multi-week model simulations. In part I, we use results from a large set of Weather Research and Forecasting (WRF) model  
83 simulations to assess the impact of the high-resolution surface datasets, different parameterization schemes, and analysis  
84 nudging on near-surface meteorological conditions and energy fluxes. We will show that a baseline model configuration  
85 employing default surface datasets produces better results for model simulations performed at 12-km horizontal grid spacing,

86 but that more accurate results are obtained at higher resolutions when the satellite-derived surface datasets and alternative  
87 parameterization schemes are used. In part II of this study, we use meteorological analyses from two of the WRF model  
88 configurations as input to Community Multiscale Air Quality (CMAQ) model simulations to assess the impact of these model  
89 changes on ozone forecasts in the Lake Michigan region. The remainder of this paper is organized as follows. Section 2  
90 contains a description of the model configurations and surface datasets. Results are presented in Section 3, with a discussion  
91 and conclusions provided in Section 4.

## 92 2. Methods

### 93 2.1 WRF model configurations

94 Version 3.8.1 of the WRF Preprocessing System (WPS) and WRF model (Powers et al. 2017) was used to perform simulations  
95 containing three one-way nested domains covering the contiguous United States, Midwest United States, and Lake Michigan  
96 regions with 12, 4, and 1.3 km horizontal resolutions, respectively (Fig. 1). Each simulation contained 40 terrain-following  
97 vertical layers, with seven of the layers located below 2 km. The model top was set to 100 hPa. The 0.25-degree resolution  
98 GFS Final reanalyses available at 6-h intervals served as initial and lateral boundary conditions (ICs/BCs) for the WRF model  
99 simulations. All simulations were run from 12 May 2017 – 22 June 2017, with our evaluation focusing on the 22 May – 22  
100 June 2017 time period corresponding to the Lake Michigan Ozone Study field project (Stainer et al. 2021). Except for the two  
101 baseline simulations described below, all of the simulations were performed in daily increments using the standard WRF model  
102 restart files to allow for daily updates of high-resolution surface datasets using the WPS. The 40-category National Land Cover  
103 Dataset (NLCD) 2011 land use dataset (Jin et al. 2013) was used to determine the vegetation type and soil properties for each  
104 model grid point.  
105



106  
107 **Figure 1. Map showing the geographic regions covered by the 12-km (red box), 4-km (orange box), and 1.3-km (yellow box)**  
108 **resolution domains used during the WRF model experiments.**  
109

110 Eight model simulations were performed to assess the impact of different physics options and surface datasets on the model  
111 accuracy in the lower troposphere (Table 1). The first simulation, hereafter referred to as the “AP-XM” baseline configuration,  
112 employed the Morrison microphysics (Morrison et al. 2005), RRTMG longwave and shortwave radiation (Iacono et al. 2008;  
113 Mlawer et al. 1997), and ACM2 PBL (Pleim 2007) parameterization schemes on all three domains, along with the Kain-Fritsch  
114 cumulus scheme (Kain 2004) on the outer two domains. These schemes were chosen for the baseline configuration because  
115 they are often used in simulations performed at the U.S. Environmental Protection Agency (EPA). The ACM2 PBL scheme is

116 a hybrid first-order closure scheme that attempts to capture both local and non-local fluxes (Pleim 2007). When conditions are  
 117 stable, only the local closure portion of the ACM2 scheme is used. Surface energy fluxes (sensible, latent, and ground) and  
 118 changes in soil moisture and soil temperature were simulated using the Pleim-Xiu LSM (Gilliam and Pleim 2010; Xiu and  
 119 Pleim, 2001). In addition, analysis nudging was used to continuously adjust the temperature, water vapor, and winds above  
 120 the PBL toward the 6-h GFS analyses (e.g., Borge et al. 2008; Campbell et al. 2018; Harkey and Holloway 2013; Otte 2008a,  
 121 b; Otte et al. 2012; Pleim and Gilliam 2009). Though additional procedures such as surface observation nudging and indirect  
 122 soil moisture and soil temperature nudging (Pleim and Gilliam 2009; Pleim and Xiu 2003) are sometimes used to constrain  
 123 the evolution of model simulations performed using the ACM2 scheme and Pleim-Xiu LSM, they are not employed during  
 124 this study in order to maintain consistency with the other model simulations.  
 125

126 A second simulation was performed using the YSU PBL (Hong et al. 2006), Noah LSM (Chen and Dudhia, 2001; Ek et al.  
 127 2003), and Thompson microphysics (Thompson et al. 2008, 2016) schemes, which is hereafter referred to as the “YNT”  
 128 configuration. Like the AP-XM simulation, this configuration employed the RRTMG longwave and shortwave radiation and  
 129 Kain-Fritsch cumulus schemes on the outer two domains, along with grid nudging toward the GFS temperature, humidity, and  
 130 wind analyses above the PBL. This particular set of schemes was chosen based on our previous studies showing that they  
 131 performed well during the warm season across the United States (e.g., Harkey and Holloway 2013; Cintineo et al. 2014;  
 132 Greenwald et al. 2016; Griffin et al. 2021; Henderson et al. 2021). Because there are dozens of parameterization schemes to  
 133 choose from in the WRF model, we do not aim to find necessarily the best physics suite but instead to assess the potential of  
 134 using other schemes to improve upon the performance of the baseline AP-XM configuration. The YSU PBL scheme is a first-  
 135 order, non-local closure scheme that allows non-local mixing with explicit entrainment processes at the top of the PBL (Hong  
 136 et al. 2006; Hong 2010). The Noah LSM is a community model that has been widely used within the weather and climate  
 137 modeling communities (Campbell et al. 2019). It contains four soil layers (0-10, 10-40, 40-100, and 100-200 cm depth) along  
 138 with vegetation canopy, soil drainage, and runoff models that allow it to simulate surface hydrological and radiative processes.  
 139 A realistic representation of land surface processes becomes increasingly important when moving towards higher model  
 140 resolutions (e.g., Sutton et al. 2006; Case et al. 2008).  
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142 The remaining six simulations (Table 1) use the YNT configuration as their baseline. These simulations are designed to assess  
 143 the impact of three high-resolution surface datasets and analysis nudging above 2 km (rather than above the PBL) on the model  
 144 accuracy when used individually or in combination. In particular, three simulations were run where the standard climatological  
 145 or coarse-resolution surface datasets were replaced by high-resolution, real-time datasets depicting lake surface temperatures,  
 146 green vegetation fraction (GVF), and soil moisture / soil temperature across the study region. These surface datasets and the  
 147 methods used to incorporate them into the WRF model simulations are described in the next section. Simulations employing  
 148 these datasets are referred to as “YNT\_SST”, “YNT\_GVF”, and “YNT\_SOIL”, respectively. Another experiment was  
 149 performed where analysis nudging was used above 2 km rather than above the PBL, which is referred to as the “YNT\_N2KM”  
 150 simulation. This change in nudging compared to the AP-XM and YNT baseline experiments was motivated by a modeling  
 151 study by Odman et al. (2019) showing that the evolution of the nocturnal low-level jet across the Great Lakes region was more  
 152 accurately simulated when nudging was withheld in the lower troposphere (e.g., below 2 km) when the PBL is shallow.  
 153 Differences in the nocturnal low-level jet could affect the transport of ozone and its precursors from urban regions to Lake  
 154 Michigan during the overnight hours. Finally, two “combination” simulations were performed where the 2-km analysis  
 155 nudging approach was used along with all three of the high-resolution surface datasets (“YNT\_SSNG”) or only with the lake  
 156 surface temperature and soil datasets (“YNT\_SSN”). The latter simulation is included because it was found that this  
 157 combination of surface datasets and analysis nudging generally led to the best results.  
 158

159 **Table 1. List showing the parameterization schemes, model initialization datasets, surface datasets, and nudging approaches used**  
 160 **during each of the eight WRF model experiments. Acronyms are described in the text.**  
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	AP-XM	YNT	YNT_SST	YNT_GVF	YNT_SOIL	YNT_N2KM	YNT_SSNG	YNT_SSN
PBL	ACM2	YSU	YSU	YSU	YSU	YSU	YSU	YSU
LSM	Pleim-Xiu	Noah	Noah	Noah	Noah	Noah	Noah	Noah

Surface Layer	Pleim-Xiu	Monin-Obukhov	Monin-Obukhov	Monin-Obukhov	Monin-Obukhov	Monin-Obukhov	Monin-Obukhov	Monin-Obukhov
Micro.	Morrison	Thompson	Thompson	Thompson	Thompson	Thompson	Thompson	Thompson
Cumulus	Kain-Fritsch	Kain-Fritsch	Kain-Fritsch	Kain-Fritsch	Kain-Fritsch	Kain-Fritsch	Kain-Fritsch	Kain-Fritsch
IC / BC	GFS-FNL	GFS-FNL	GFS-FNL	GFS-FNL	GFS-FNL	GFS-FNL	GFS-FNL	GFS-FNL
SST	<i>default</i>	<i>default</i>	GLSEA	<i>default</i>	<i>default</i>	<i>default</i>	GLSEA	GLSEA
GVF	<i>default</i>	<i>default</i>	<i>default</i>	VIIRS	<i>default</i>	<i>default</i>	VIIRS	<i>default</i>
Soil	<i>default</i>	<i>default</i>	<i>default</i>	<i>default</i>	SPoRT LIS	<i>default</i>	SPoRT LIS	SPoRT LIS
Nudging	analysis above the PBL	analysis, above PBL	analysis, above PBL	analysis, above PBL	analysis, above PBL	analysis, above 2 km	analysis, above 2 km	analysis, above 2 km

## 162 2.2 Surface datasets

### 163 2.2.1 Lake surface temperatures

164 Daily maps of Great Lakes surface temperatures, with a horizontal resolution of ~1.3 km, were obtained from the Great Lakes  
165 Surface Environmental Analysis (GLSEA) produced at the NOAA Great Lakes Environmental Research Laboratory (Schwab  
166 et al. 1992). The lake surface temperatures are estimated using clear-sky infrared brightness temperatures from the Advanced  
167 Very High-Resolution Radiometer onboard multiple polar-orbiting satellites. If a surface retrieval is not possible on a given  
168 day due to cloud cover, a smoothing algorithm is applied to the previous analysis to maintain complete coverage. Only satellite  
169 observations are used to produce the daily lake surface temperature analyses, which Schwab et al. (1992) showed have small  
170 bias and root mean square error (1-1.5° C) when compared to buoys. The daily GLSEA analyses were used to overwrite the  
171 simulated surface temperatures for Great Lakes grid points at 00 UTC each day in the YNT\_SST, YNT\_SSN, and YNT\_SSNG  
172 simulations using the WPS. Replacing the coarse-resolution (0.25°) GFS FNL surface temperatures (Fig. 2a) with the GLSEA  
173 analyses (Fig. 2b) led to warmer lake temperatures near the shoreline, especially along northern parts of Lake Michigan where  
174 temperatures were > 2 K warmer, and cooler temperatures across the rest of the lake, when averaged over the 22 May – 22  
175 June 2017 time period (Fig. 2c). This spatial pattern indicates that the finer horizontal resolution of the GLSEA dataset allows  
176 it to capture warmer temperatures in shallower waters near the shoreline while also depicting the cooler mid-lake temperatures  
177 due to the cooler-than-normal weather conditions that prevailed across the region in May (NCEI 2017).

### 178 2.2.2 VIIRS green vegetation fraction

179 GVF is the photosynthetically active fractional green vegetation cover within a grid cell, with higher values indicating more  
180 extensive actively transpiring vegetation. It is a key parameter in an LSM because vegetation representation is used to partition  
181 the incoming solar radiation into sensible, latent, and ground heat fluxes, where the latent heat flux is largely due to vegetation  
182 transpiration (e.g., Yin et al. 2016). Surface latent heat flux is sensitive to GVF because vegetation roots are able to access  
183 deeper soil moisture that would not otherwise be able to evaporate (Miller et al. 2006). For this study, we used daily global  
184 GVF derived using observations from the Visible Infrared Imaging Radiometer Suite (VIIRS; Vargas et al. 2015) in place of  
185 the default monthly climatology to constrain the evolution of vegetation in the YNT\_GVF and YNT\_SSNG simulations. The  
186 VIIRS GVF composite product is generated daily at 4-km resolution and available from the NOAA Comprehensive Large  
187 Array-data Stewardship System (CLASS). Ding and Zhu (2018) have shown that the VIIRS GVF product has smaller errors  
188 and bias than other satellite derived GVF datasets because of reduced atmospheric influences, improved observing capabilities  
189 in high biomass regions, better representation of vegetation canopies, and reduced bidirectional reflection distribution function  
190 effects. The real-time daily GVF analyses were used to overwrite the default monthly climatological vegetation fraction data

191 used by the WRF model at 00 UTC each day. Using real-time, satellite derived GVF in place of a monthly GVF climatology  
192 has been shown to improve the representation of the surface energy budget and subsequent model forecasts during the warm  
193 season (Case et al. 2014). In Fig. 2f, it is evident that use of the real-time GVF led to lower leaf area index (Fig. 2e; computed  
194 internally by the WRF model) across most of the domain compared to the climatological vegetation data (Fig. 2d), with the  
195 exception of some forested regions in the northern portion of the domain and bands of enhanced leaf area index surrounding  
196 metropolitan areas such as Chicago. The lower leaf area index in agricultural areas is consistent with delayed crop growth due  
197 to the cool spring weather, whereas the bands of higher leaf area index represent the impact of urban sprawl since the  
198 climatological vegetation data shown in Fig. 2d was generated using satellite observations from the late 1980s and early 1990s  
199 (see Gutman et al. 1995).  
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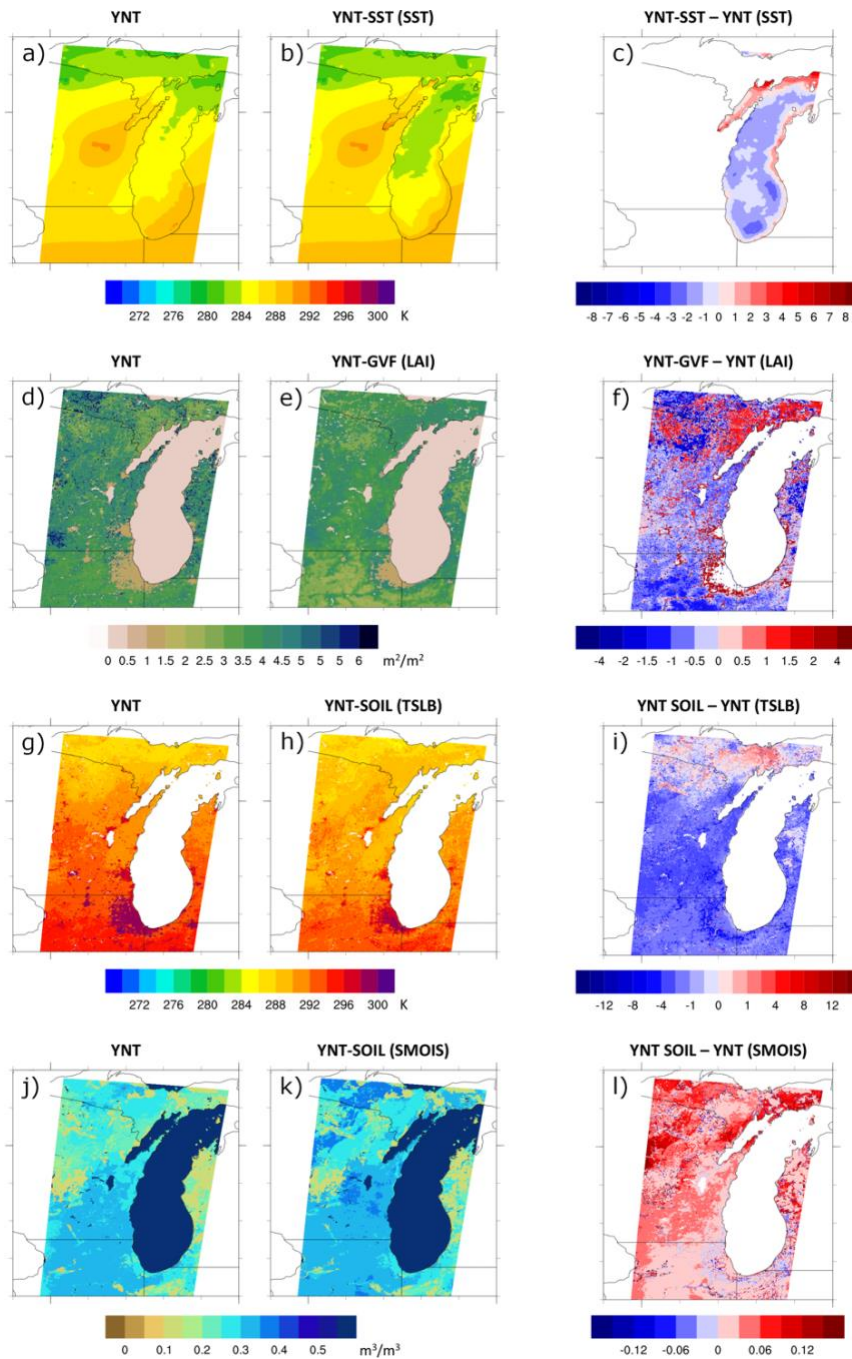


Figure 2. Average lake surface temperatures (K) from the (a) YNT and (b) YNT\_SST simulations, with their differences shown in (c). Average leaf area index (m<sup>2</sup> m<sup>-2</sup>) from the (d) YNT and (e) YNT\_GVF simulations, with their differences shown in (f). Average 0-10 cm soil temperatures (K) from the (g) YNT and (h) YNT\_SOIL simulations, with their differences shown in (i). Average 0-10 cm soil moisture content (m<sup>3</sup> m<sup>-3</sup>) from the (j) YNT and (k) YNT\_SOIL simulations, with their differences shown in (l). The averages for each variable were computed using data valid at 00 UTC each day during the 22 May – 22 June 2017 time period.



## 207 2.2.3 SPoRT LIS soil moisture and temperature analyses

208 A customized version of the Land Information System (LIS; Kumar et al. 2006) run at the Short-term Prediction Research and  
209 Transition Center (SPoRT) was used to generate high-resolution soil moisture and soil temperature analyses. Version 3.6 of  
210 the Noah LSM (Chen and Dudhia 2001) was run on a 1-km resolution domain covering the central and eastern United States  
211 and nearby portions of southern Canada. Required inputs to run the Noah LSM were obtained from hourly analyses of surface  
212 pressure, 2-m temperature, 2-m specific humidity, 10-m wind speed, and downwelling shortwave and longwave radiation from  
213 the North American Land Data Assimilation System – Phase 2 (NLDAS-2; Xia et al. 2012). No observations were assimilated  
214 during the LIS runs. Quantitative precipitation estimates (QPE) were obtained from the Multi-Radar Multi-Sensor (MRMS)  
215 gauge-adjusted radar product (Zhang et al. 2016), the Global Data Assimilation System (GDAS; Wang et al. 2013), and  
216 NLDAS-2. A simple blending methodology was used to incorporate the multiple sources of QPE because evaluation of the  
217 real-time SPoRT-LIS product (Case 2016; Case and Zavodsky 2018; Blankenship et al. 2018) and preliminary LIS experiments  
218 during this study revealed that the NLDAS-2 and MRMS precipitation products have a dry bias across the region. To reduce  
219 this bias, the precipitation forcing used the average of the highest two values of the MRMS, GDAS, and NLDAS-2 QPE  
220 datasets. Inspection of the blended precipitation product showed that the precipitation bias was reduced, while preserving  
221 small-scale spatial details in the MRMS QPE product. Daily VIIRS GVF composites were also used to constrain vegetation  
222 during the offline LIS-Noah simulation.

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224 Following an initial spin-up of LIS using NLDAS-2 forcing data from 2012-2016 to remove memory of the prescribed initial  
225 conditions, the final analysis from this run was used to restart the simulation on 01 January 2012 using NLDAS-2 atmospheric  
226 forcing data, VIIRS GVF, and the merged QPE product. Soil moisture and soil temperature analyses from this LIS simulation  
227 were then used to replace the corresponding variables in the YNT\_SOIL, YNT\_SSN, and YNT\_SSNG simulations at 00 UTC  
228 each day from 12 May – 22 June 2017 using the WPS. Comparison of the 0-10 cm soil temperatures from the GFS (Fig. 2g)  
229 and LIS (Fig. 2h), averaged over the 22 May – 22 June 2017 period, shows that the topsoil temperatures are noticeably cooler  
230 in the LIS data across most of the region, except for northern parts of Wisconsin and Michigan. The cooler temperatures are  
231 most prominent in suburban regions where the largest increases in GVF also occurred (Fig. 2f). For 0-10 cm soil moisture, the  
232 LIS analyses are generally wetter across the domain (Fig. 2i), with the largest increases across forested regions of Wisconsin  
233 and Michigan. Deeper soil layers exhibited similar differences between the GFS FNL and LIS datasets (not shown).

## 234 2.3 Evaluation methods

235 The accuracy of the WRF model simulations was assessed using hourly surface observations of temperature, humidity, and  
236 winds from the Meteorological Assimilation Data Ingest System (MADIS, <https://madis.ncep.noaa.gov/>) during 22 May – 22  
237 June 2017. These observations were chosen because of their widespread availability and their important influence on surface  
238 chemistry processes. The model evaluations are performed on all three domains using observations from stations located on  
239 the innermost domain surrounding Lake Michigan, which allows us to assess the behavior of each configuration as a function  
240 of spatial resolution using the same set of stations. Version 1.4 of the Atmospheric Model Evaluation Tool (AMET; Appel et  
241 al. 2011) from the EPA was used to collocate hourly observed and modeled values in a grid cell where a particular observation  
242 station was located; and to calculate model performance statistics including bias and root mean square error.

## 243 3. Results

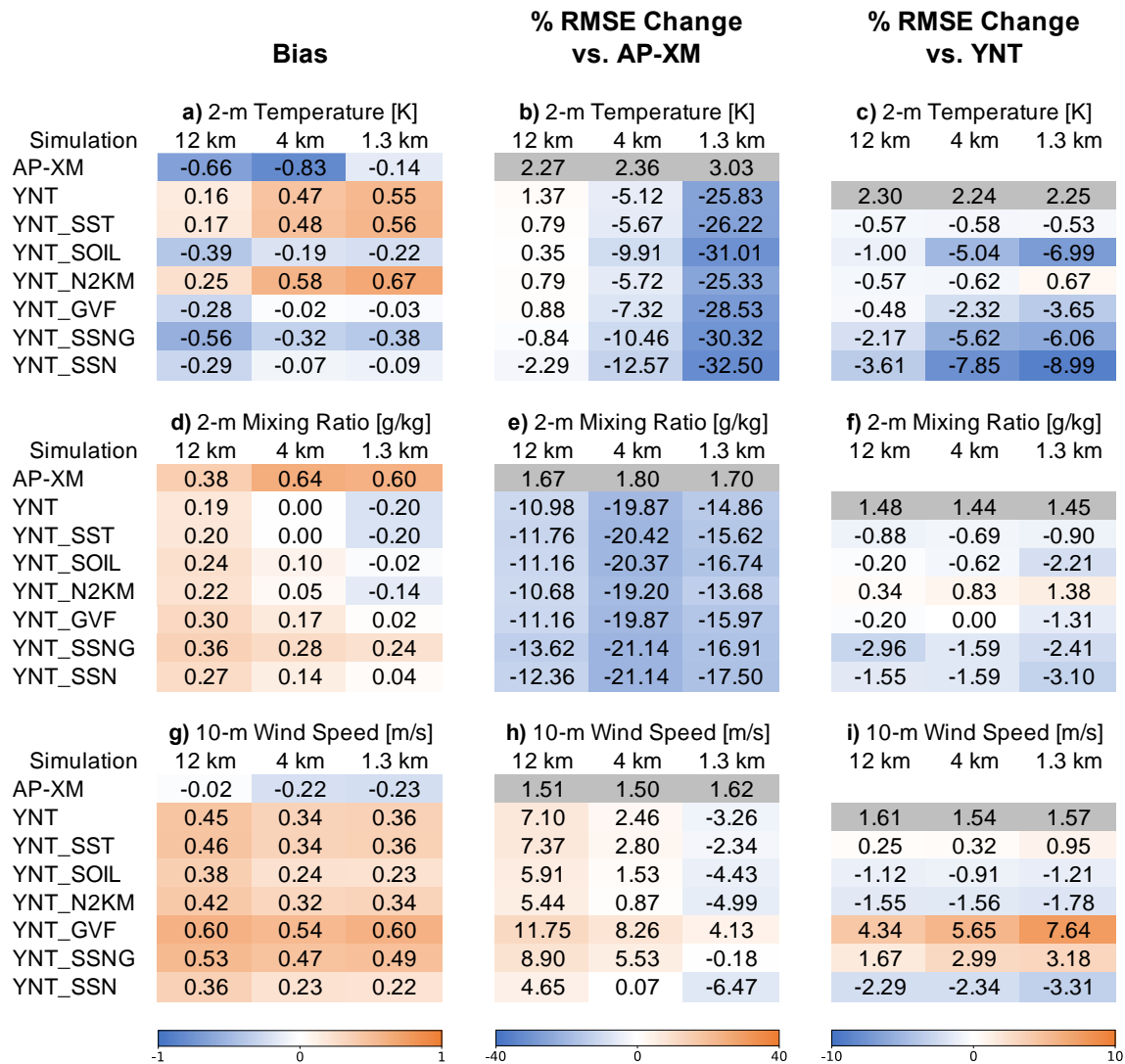
### 244 3.1 Assessment of AP-XM and YNT baseline experiments

245 This section contains a high-level assessment of the accuracy of the AP-XM and YNT baseline experiments on each domain,  
246 with a more detailed evaluation of all experiments on the 1.3-km resolution domain provided in Section 3.2. Figure 3 shows  
247 2-m temperature, 2-m water vapor mixing ratio, and 10-m wind speed errors for each domain computed using hourly surface  
248 observations. The left column shows the bias for each variable and experiment, whereas the center and right columns show  
249 the percentage changes in RMSE for each experiment relative to the AP-XM and YNT baseline experiments, respectively. A



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negative (positive) value for a given variable and domain indicates that the RMSE for that experiment is smaller (larger) than the actual RMSE for the corresponding baseline experiment plotted in the gray box.



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Figure 3. Summary statistics showing the (a) 2-m temperature bias for each experiment, along with the percentage change in the 2-m temperature root mean square error (RMSE) for a subset of experiments relative to the (b) AP-XM baseline and (c) YNT baseline experiments, respectively. Statistics for the 12-km, 4-km, and 1.3-km resolution domains were computed using hourly data from all stations located on the 1.3-km resolution domain during 22 May – 22 June 2017. The actual RMSEs for the baseline experiments (gray boxes) are also shown. Blue (orange) shading indicates a negative (positive) bias for a given experiment in (a), whereas blue (orange) shading depicts smaller (larger) RMSE in a given experiment relative to the AP-XM and YNT baseline experiments in (b) and (c). (d-f) Same as (a-c), except for showing statistics for 2-m mixing ratio. (g-i) Same as (a-c), except for showing statistics for 10-m wind speed.

Inspection of the YNT statistics reveals a consistent pattern in the RMSE where the percentage changes for each variable either switch from positive to negative, or become more strongly negative, as the model resolution increases from 12 km to 1.3 km. For temperature, the RMSE improves from being 1.37% larger than the AP-XM on the 12-km domain to 25.83% smaller on

266 the 1.3-km domain (Fig. 3b). A similar pattern is present for 10-m wind speed where the RMSE is 7.10% larger on the 12-km  
267 domain, but then steadily decreases so that the RMSE becomes 3.26% smaller on the 1.3-km domain (Fig. 3h). The AP-XM  
268 simulation had a smaller wind speed bias on all three domains compared to the YNT baseline. For 2-m mixing ratio (Fig. 3d,  
269 3d), a positive bias on the 12-km domain increased at higher spatial resolutions for the AP-XM simulation but decreased and  
270 turned into a negative bias for the YNT simulation, which also exhibits a large reduction in RMSE on all three domains. These  
271 results indicate that the AP-XM physics suite becomes less accurate at higher resolutions and that the YNT configuration  
272 provides superior performance on the 1.3-km domain when averaged across all stations. In the following sections, we will use  
273 results from this domain to examine the impacts of the surface datasets and analysis nudging on the model accuracy with  
274 respect to the AP-XM and YNT baseline experiments.

## 275 3.2 YNT sensitivity experiments

### 276 3.2.1 2-m temperature evaluation

277 To examine regional differences in model performance, Fig. 4 shows the 2-m temperature bias and RMSE computed separately  
278 for each station using hourly observations from 22 May – 22 June 2017. For the AP-XM simulation, there is a north-south  
279 gradient in the RMSE, with the largest errors across northern Illinois and Indiana (Fig. 4a). Stations near Lake Michigan have  
280 the smallest RMSE due to its moderating influence on local weather conditions. Similar to the RMSE, the smallest biases  
281 occurred in the northern part of the domain and along the eastern shoreline; however, biases along the western shoreline are  
282 larger and of comparable magnitude to those at inland locations across Wisconsin and Illinois. Overall, the AP-XM simulation  
283 had an RMSE of 3.03 K and a bias of -0.14 K when averaged across all stations (Figs. 3a-b). Switching to the YNT  
284 parameterization suite greatly reduced the RMSE by 25.83% across the entire domain (Fig. 3b); however, the bias increased  
285 to 0.55 K (Fig. 3a). The largest RMSE reductions (up to 45%) occurred in rural areas of northern Illinois, with similar RMSEs  
286 found across the entire domain (Fig. 4b). The larger positive temperature bias in the YNT baseline simulation is primarily due  
287 to larger errors in Wisconsin and within densely populated urban areas along the western Lake Michigan shoreline from  
288 Chicago to Milwaukee (Fig. 4f). A mixed pattern of larger and smaller biases occurred elsewhere across the domain.

289 Inspection of the YNT sensitivity experiments shows that the smallest RMSEs occurred during the YNT\_SOIL, YNT\_SSN,  
290 and YNT\_SSNG simulations, with the average RMSE reduced by 30.32% to 32.5% relative to the EPA baseline (Fig. 3b) and  
291 from 6.0% to 9.0% relative to the already greatly improved YNT baseline (Fig. 3c). On an individual basis, the high-resolution  
292 soil dataset (YNT\_SOIL) had the largest positive impact at most stations (Fig. 4d), whereas slightly larger RMSEs were  
293 observed when using nudging (YNT\_N2KM) (Fig. 4j). Comparison of the YNT\_SSN and YNT\_SSNG simulations (Fig. 4l,  
294 4p) shows that inclusion of the VIIRS GVF dataset during the YNT\_SSNG simulation led to slightly larger RMSE for stations  
295 near the lakeshore, but similar or smaller errors for stations located further inland.

296  
297 The bias pattern for the YNT simulations is more complex. Overall, the bias was largest (0.67 K) in the YNT\_N2KM  
298 simulation, with the smallest biases occurring in the YNT\_GVF (-0.03 K) and YNT\_SSN (-0.09 K) simulations (Fig. 3a).  
299 Switching from the AP-XM to YNT baseline configurations led to larger biases across most of the domain, especially along  
300 the southwestern shoreline of Lake Michigan (Fig. 4e-f). The high-resolution SST dataset had a minimal impact on the biases  
301 (Fig. 4g) whereas they were smaller in the YNT\_SOIL (Fig. 4h) and YNT\_GVF (Fig. 4m) simulations relative to the YNT  
302 baseline. Use of these two land datasets however led to much larger negative biases along the eastern shoreline of Lake  
303 Michigan. When 2-km analysis nudging was used (YNT\_N2KM), larger positive biases occurred from Chicago to Milwaukee,  
304 with smaller biases along the eastern shoreline (Fig. 4n). The increased RMSE and bias near the western shoreline compared  
305 to locations further inland during the YNT\_N2KM simulation suggests that the modified nudging routine (applied to heights  
306 above 2 km instead of above the PBL) may not work well for areas near Lake Michigan due to the moderating influence of  
307 the lake on the PBL. Because the PBL tends to be more stable and shallower for locations over and near Lake Michigan due  
308 to the cooler surface temperatures, this means that confining analysis nudging to above 2 km limits its ability to constrain the  
309 evolution of the lower troposphere during the YNT\_N2KM simulation. This behavior could also be due to deficiencies in the  
310 YNT configuration over complex urban-lake transition zones.  
311

### 312 3.2.2 2-m water vapor evaluation

313 For the 2-m water vapor mixing ratio, switching to the YNT physics suite led to nearly a 15% reduction in the station-average  
314 RMSE during the YNT simulation relative to the AP-XM baseline (Fig. 3e), with additional incremental reductions occurring  
315 in all sensitivity experiments except for YNT\_N2KM (Fig. 3f). The lower RMSE in all of the YNT simulations is primarily  
316 due to the large reduction in bias (Fig. 3d). Whereas the AP-XM configuration had a large moist bias ( $0.60 \text{ g kg}^{-1}$ ), the YNT  
317 bias was much smaller and also became negative ( $-0.20 \text{ g kg}^{-1}$ ). The bias was further reduced during most of the sensitivity  
318 experiments, with only a slight increase during the YNT\_SSNG simulation. Overall, the YNT\_SSN simulation had the smallest  
319 RMSE and a bias close to zero when averaged across all of the stations.  
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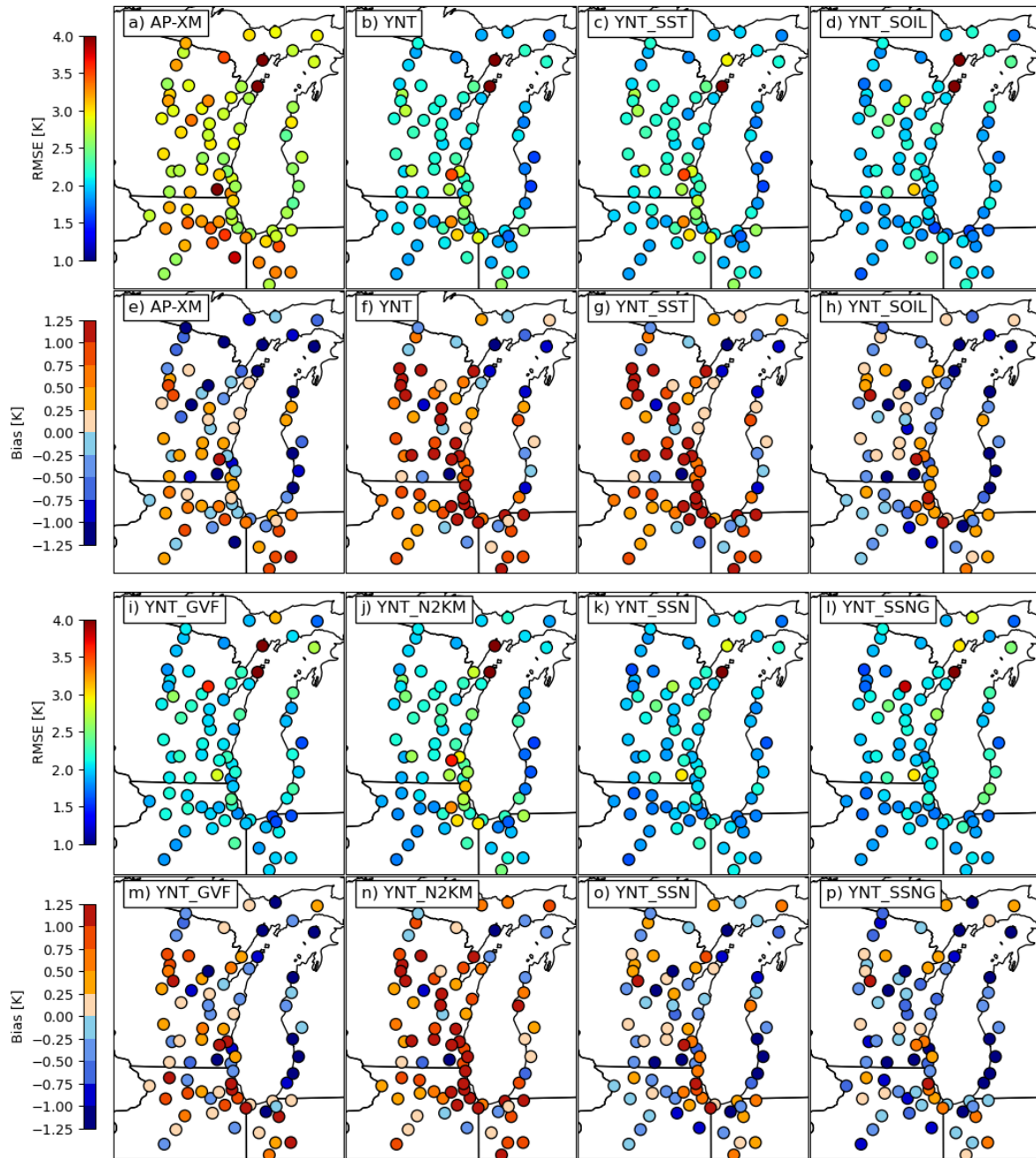
321 Looking more closely at the individual stations (Fig. 5), it is evident that most of them have a positive (e.g., moist) bias when  
322 the AP-XM configuration is used (Fig. 5e). The largest biases are located in the southern portion of the domain, especially for  
323 stations near the lakeshore. In contrast, about two-thirds of the stations exhibit a negative bias during the YNT simulation (Fig.  
324 5f). The spatial pattern of the biases is similar during all of the YNT sensitivity experiments; however, their magnitudes are  
325 generally smaller, which is consistent with the overall statistics (Fig. 3d). For RMSE, the largest errors in the AP-XM  
326 simulation occur primarily along the southern end of Lake Michigan, with generally smaller errors in the northern half of the  
327 domain (Fig. 5a). The RMSE during the YNT simulation is smaller at most locations, especially along the shoreline, though a  
328 few stations near the western shoreline have larger errors (Fig. 5b). Use of the SOIL and GVF datasets reduced the errors at  
329 these nearshore locations (Fig. 5d, 5i), with the smallest errors at most stations occurring during the combination experiments  
330 (YNT\_SSN and YNT\_SSNG). As was the case with 2-m temperature, the most accurate 2-m water vapor analyses were  
331 obtained during the YNT\_SSN simulation.

### 332 3.2.3 10-m wind speed evaluation

333 Compared to the temperature and water vapor fields, changes to the 10-m wind speed statistics were much more modest during  
334 the YNT simulations. Switching from the AP-XM configuration to the YNT configuration led to a 3.26% reduction in the  
335 RMSE, but a larger bias that also changed sign from negative to positive (Fig. 3g). For the YNT experiments, the average  
336 RMSE was slightly smaller during the YNT\_SOIL and YNT\_N2KM simulations ( $-1.21\%$  and  $-1.78\%$ , respectively), but  
337 slightly larger ( $0.95\%$ ) during the YNT\_SST simulation compared to the YNT baseline (Fig. 3i). Use of the GVF surface  
338 dataset led to a 7.64% increase in the RMSE during the YNT\_GVF simulation, primarily due to a larger wind speed bias.  
339 Overall, the most accurate wind speed analyses were achieved during the YNT\_SSN simulation, with an RMSE reduction of  
340 6.47% across all stations.  
341

342 Spatially, there is a latitudinal gradient in wind speed errors during the AP-XM simulation. The largest RMSEs are located  
343 across the southern part of the domain (Fig. 6a), with mostly negative wind speed biases (up to  $2 \text{ m s}^{-1}$ ) in the same region  
344 transitioning to a mix of negative and positive biases in northern Wisconsin and Michigan (Fig. 6e). The RMSE and bias were  
345 much smaller for stations around the southern shoreline of Lake Michigan during the YNT simulation; however, slightly larger  
346 RMSEs are present across inland locations in the northern part of the domain (Fig. 6b). A similar spatial pattern of changes  
347 relative to the AP-XM baseline occurred during the YNT sensitivity experiments, though the errors are generally larger during  
348 the YNT\_GVF simulation (Fig. 6i, 6m) and smaller during the YNT\_SOIL (Fig. 6d, 6h) and YNT\_N2KM (Fig. 6j, 6n)  
349 simulations. The poor performance of the YNT\_GVF and YNT\_SSNG simulations is primarily due to larger errors across  
350 inland areas of Wisconsin where there are large positive wind speed biases (Fig. 6m, 6p), with similar errors elsewhere in the  
351 domain.

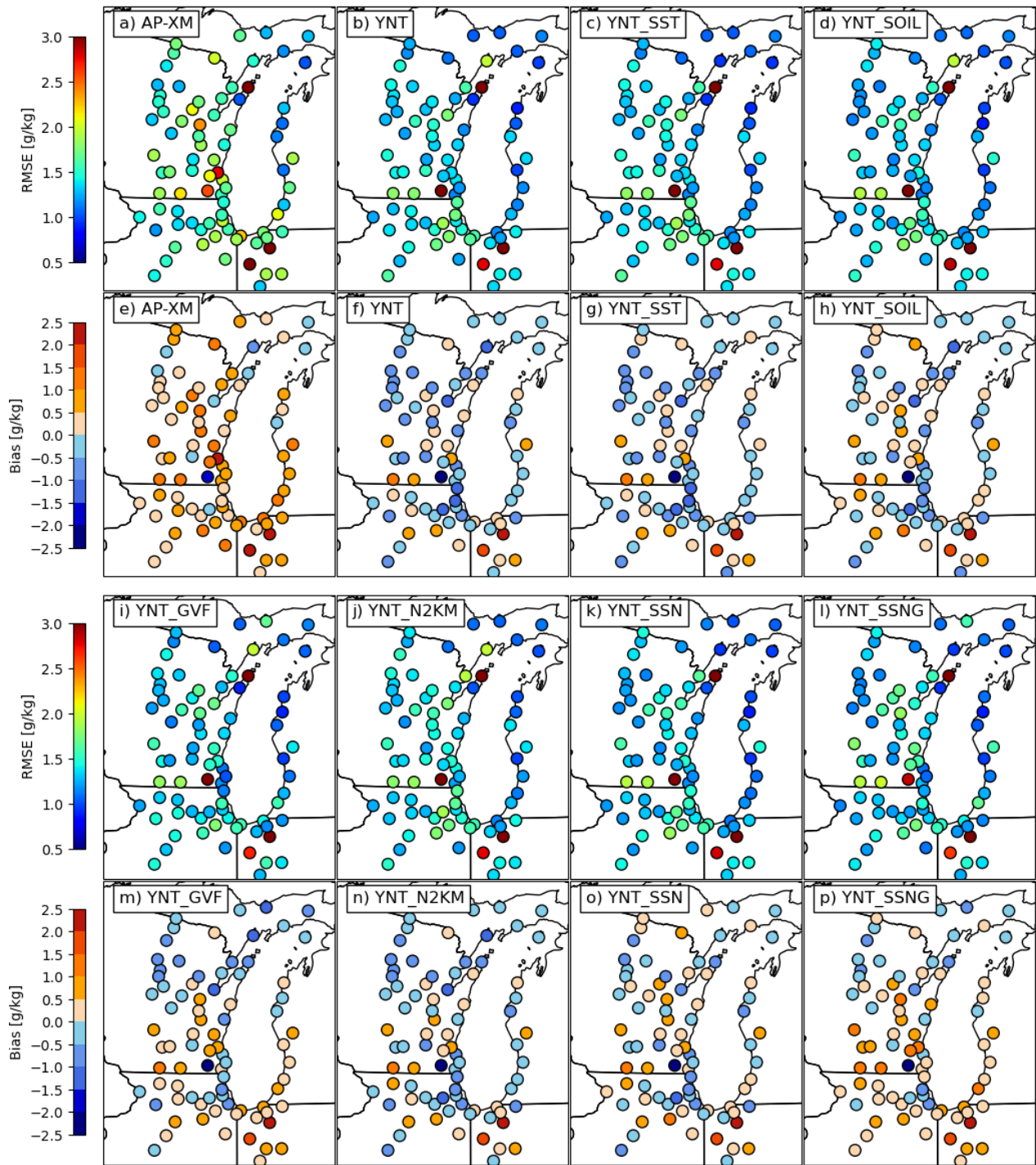
## 2-m Temperature



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Figure 4. Maps showing the 2-m temperature (K) root mean square error (RMSE) and bias for each station on the 1.3-km domain computed using hourly data from 22 May – 22 June 2017. Statistics for the EPA, YNT, YNT\_SST, and YNT\_SOIL experiments are shown in (a)–(h), whereas results for the YNT\_GVF, YNT\_N2KM, YNT\_SSN, and YNT\_SSNG experiments are shown in (i)–(p).

## 2-m Mixing Ratio

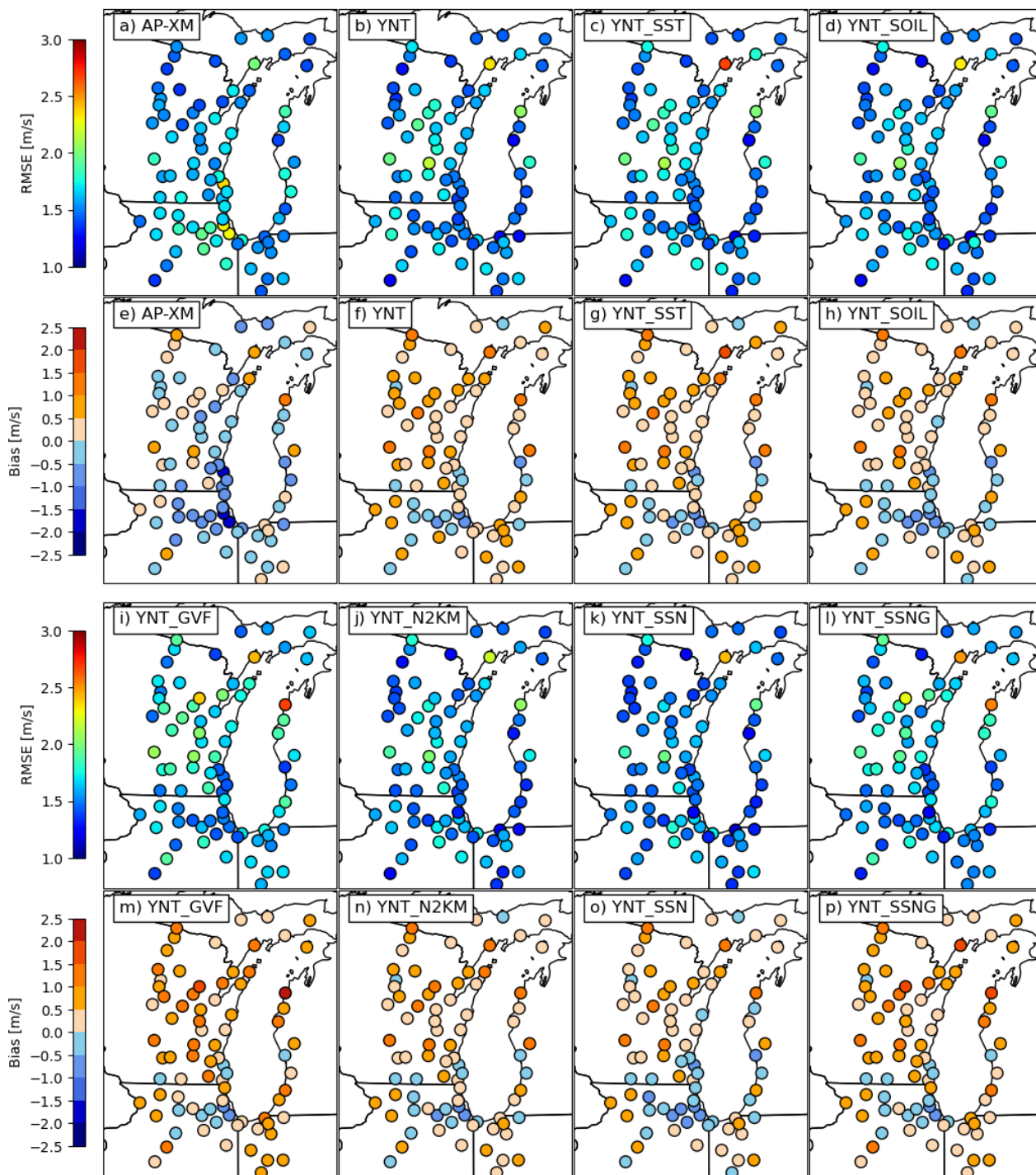


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Figure 5. Same as Fig. 4, except for 2-m water vapor mixing ratio ( $\text{g kg}^{-1}$ ).



# 10-m Wind Speed



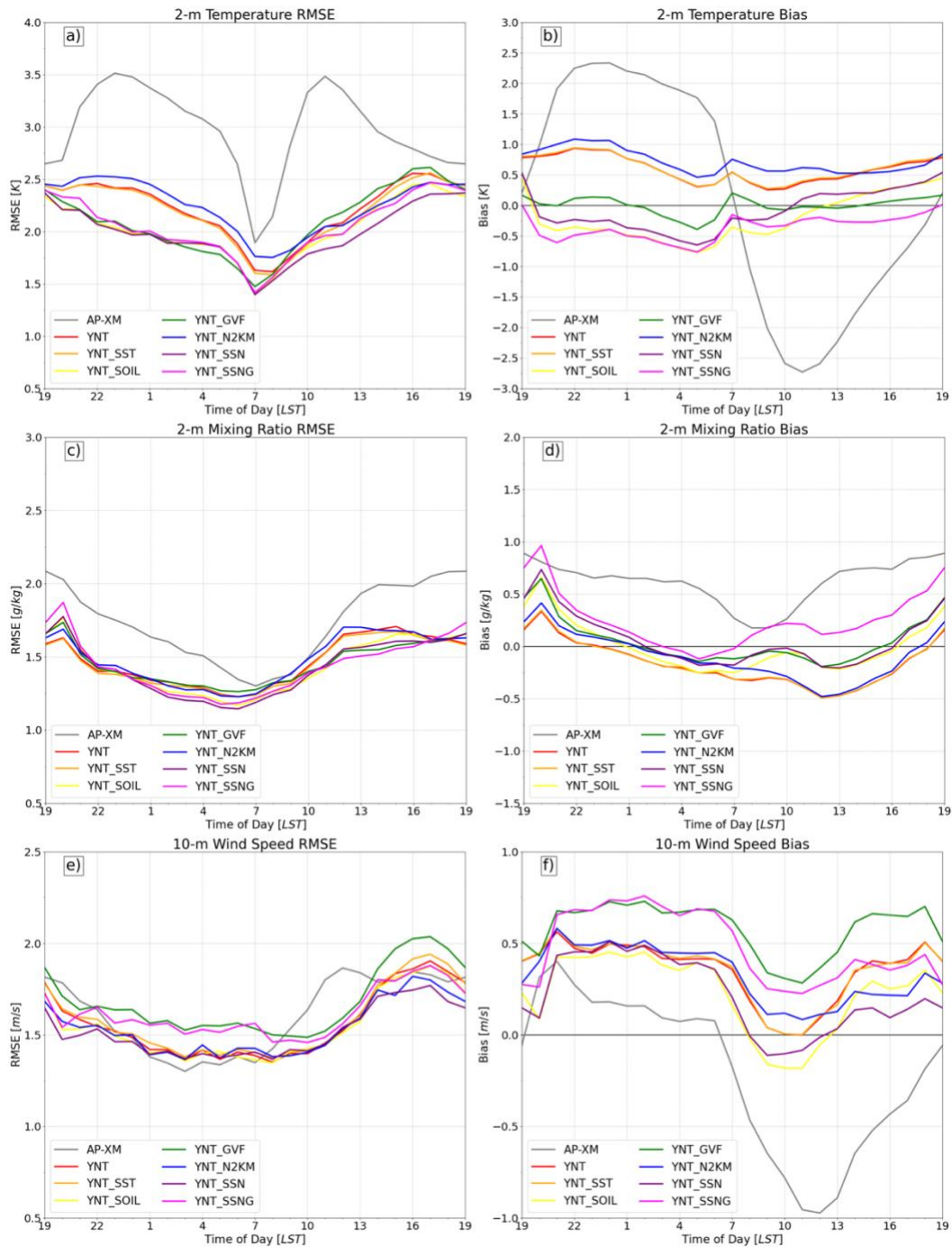
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Figure 6. Same as Fig. 4, except for 10-m wind speed ( $\text{m s}^{-1}$ ).

361 Fig. 7 shows the diurnal evolution of RMSE and bias for 2-m temperature, 2-m water vapor mixing ratio, and 10-m wind speed  
362 at hourly intervals starting at 1900 local standard time (LST). The time series were computed by averaging over data from all  
363 stations on the 1.3-km domain. Overall, it is apparent that the AP-XM simulation contains very different diurnal error patterns  
364 than the YNT simulations. For example, the 2-m temperature bias exhibits a prominent diurnal cycle (Fig. 7b) characterized  
365 by large positive/warm (negative/cool) biases during the night (day), resulting in an overall damping of the diurnal temperature  
366 cycle. The warm biases exceed 2.0 K during most of the night (22 – 03 LST) and the cold biases are  $< -2$  K for several hours  
367 during the daytime (0900–1300 LST). These results indicate that the small temperature bias in the summary statistics for the  
368 AP-XM simulation (Fig. 3a) is misleading because it obscures the presence of substantial biases of opposite signs during the  
369 day and night. The RMSE is also much larger during the AP-XM simulation (Fig. 7a), with local maxima of 3.5 K at 1100 and  
370 2300 LST, respectively, corresponding to peaks in the temperature biases. Switching to the YNT baseline greatly reduces the  
371 temperature RMSE, and the bias time series is no longer characterized by the highly amplified diurnal pattern seen in the AP-  
372 XM simulation. Examination of the YNT sensitivity experiments shows similar error patterns to the YNT baseline. The largest  
373 differences occur at night when use of the GVF and SOIL datasets leads to smaller biases. In contrast, confining the analysis  
374 nudging to above 2 km AGL (YNT\_N2KM) slightly increases the RMSE and bias during the nighttime relative to the YNT  
375 baseline.

376  
377 For water vapor, the AP-XM simulation again exhibits larger bias and RMSE than the other simulations (Fig. 7c, 7d). It has a  
378 large moist bias that ranges from  $0.2 \text{ g kg}^{-1}$  shortly after sunrise to  $0.9 \text{ g kg}^{-1}$  near 1900 LST, before decreasing to a relatively  
379 stable bias of  $0.6 \text{ g kg}^{-1}$  during the night. The RMSE is smaller in the YNT baseline simulation, with a dry bias evident for all  
380 but the evening hours (1900-2200 LST). As is the case for temperature, the RMSE is smallest during the late-night hours and  
381 then steadily increases during the day before reaching its maximum in the evening. All of the YNT sensitivity experiments  
382 have similar RMSE and bias patterns to the YNT baseline, with the smallest (largest) spread between simulations occurring  
383 during the nighttime (daytime) hours, possibly due to differences in the PBL depth and surface energy balance (see Fig. 8).  
384 Comparison of the 10-m wind speed time series reveals that the AP-XM simulation has the smallest bias ( $\sim 0.15 \text{ m s}^{-1}$ ) during  
385 the night, but that the wind speeds are weaker than observed during the daytime, with the largest biases ( $-0.95 \text{ m s}^{-1}$ ) occurring  
386 at noon (Fig. 7f). This diurnal pattern in the AP-XM simulation, characterized by winds that are too strong (weak) during the  
387 night (day), stands in contrast to the mostly positive biases in the YNT simulations. The biases are tightly clustered in all of  
388 the YNT experiments during the nighttime hours (2200–0700 LST), with the exception of the two simulations employing the  
389 GVF dataset (YNT\_GVF and YNT\_SSNG) that are characterized by persistently larger positive biases. These two simulations  
390 also have the largest RMSE (Fig. 7e). Further research is necessary to determine why incorporation of the high-resolution  
391 GVF dataset leads to larger surface wind speed errors.  
392





393  
 394 **Figure 7.** Time series showing the diurnal evolution of (a-b) 2-m temperature (K) root mean square error (RMSE) and bias, (c-d) 2-  
 395 m water vapor mixing ratio ( $\text{g kg}^{-1}$ ) RMSE and bias, and (e-f) 10-m wind speed ( $\text{m s}^{-1}$ ) RMSE and bias at hourly intervals starting  
 396 at 1900 local standard time (LST). Errors were computed for each model simulation using observations from all stations located on  
 397 the 1.3-km resolution domain during 22 May – 22 June 2017.

398 **3.2.5 Surface Energy Budget Considerations**

399 Near-surface atmospheric conditions can be strongly impacted by the partitioning of net surface radiation into sensible, latent,  
400 and ground heat fluxes (Santanello et al. 2018). To examine this more closely, Fig. 8 shows time series depicting the average  
401 diurnal evolution of the PBL height, net surface radiation, and sensible, latent, and ground heat fluxes during 22 May – 22  
402 June 2017 computed using data from stations on the 1.3-km domain to maintain consistency with earlier results. Because in-  
403 situ flux and PBL height observations are not available across the entire domain, the aim is not to examine the accuracy of the  
404 simulated surface energy fluxes and PBL height, but rather to use these variables to help explain differences in the near-surface  
405 temperature, water vapor, and wind speed errors in the model simulations. All of the variables were obtained directly from the  
406 WRF output files. The net surface radiation is defined as the sum of the upward and downward shortwave and longwave  
407 radiation fluxes at the surface.  
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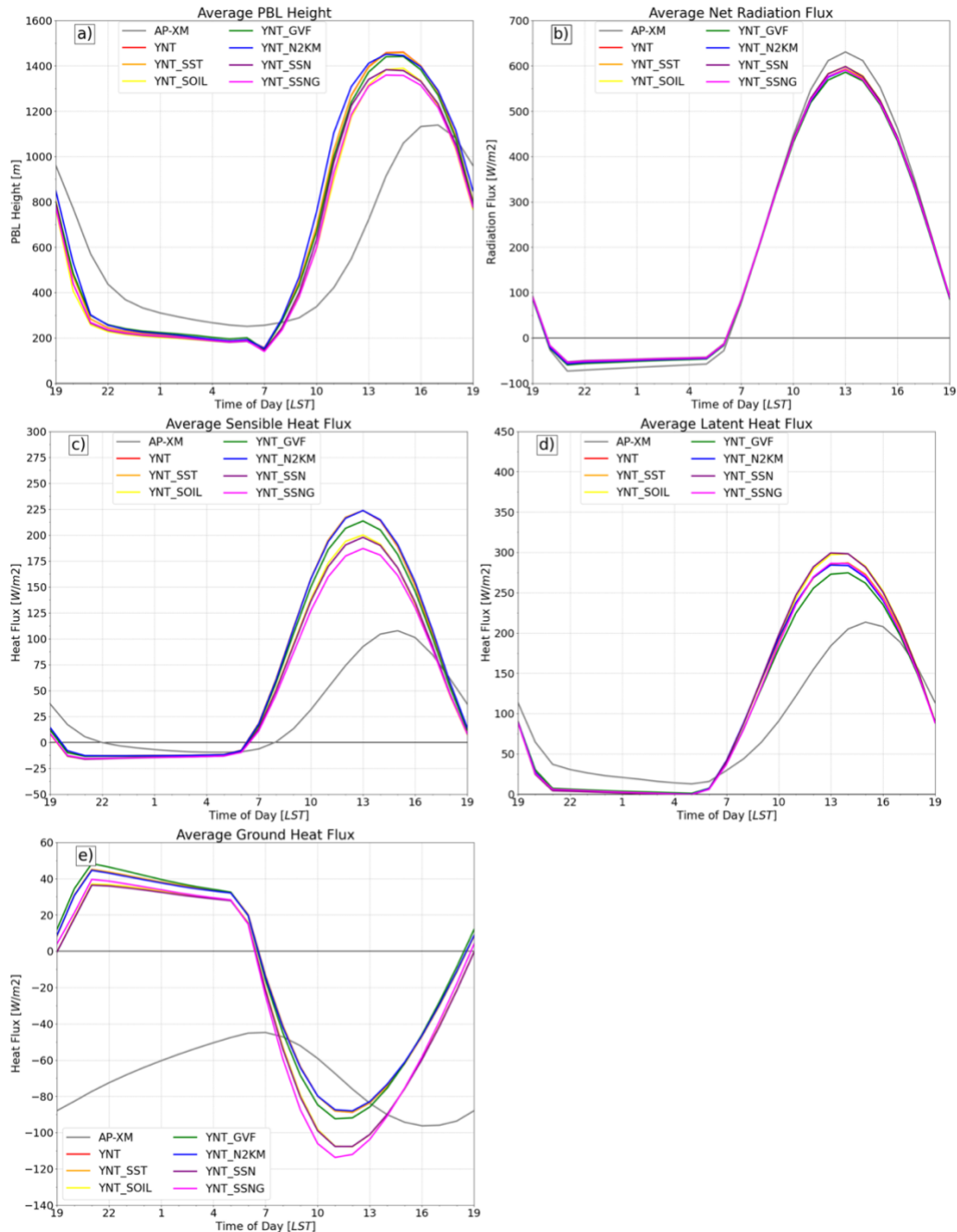
409 Inspection of Fig. 8 reveals large differences between the AP-XM and YNT simulations. The PBL is ~50-150 m deeper in the  
410 AP-XM simulation during the nighttime but then becomes much shallower than the YNT simulations from mid-morning  
411 through the afternoon (1000–1600 LST) with the daytime maximum in PBL height occurring ~2 h later (Fig. 8a). The AP-XM  
412 simulation is also characterized by a smoother and less amplified diurnal evolution. For the YNT simulations, the PBL heights  
413 are tightly clustered during the night (2100 – 0700 LST) but begin to diverge during the morning and reach their largest  
414 differences during the afternoon. In particular, simulations employing the high-resolution soil moisture analyses (YNT\_SOIL,  
415 YNT\_SSN, and YNT\_SSNNG) have average PBL heights that are ~100 m lower than the other YNT simulations. These three  
416 simulations also have slightly lower sensible heat flux (Fig. 8c) and higher latent heat flux during the afternoon (Fig. 8d),  
417 which is consistent with the wetter and cooler topsoil layer in the SPoRT LIS analyses (Fig. 2g-l) and cooler 2-m temperatures  
418 (Figs. 3a, 7b). Using the SST and GVF datasets and confining analysis nudging to above 2 km had minimal impact on the PBL  
419 heights in the YNT\_SST, YNT\_GVF, and YNT\_N2KM simulations; however, sensible and latent heat fluxes are slightly  
420 smaller during the afternoon in the YNT\_GVF simulation.  
421

422 Comparison of the AP-XM and YNT simulations also reveals large differences in the surface energy flux time series. For  
423 example, the AP-XM simulation has much smaller sensible heat flux during the daytime (Fig. 8c) and the latent heat flux  
424 remains relatively large during the night (Fig. 8d). Though the AP-XM and YNT simulations produce similar magnitudes of  
425 latent heat flux during the day, the afternoon maximum is delayed by 2 h in the AP-XM simulation. The combination of a  
426 shallower PBL during the day (Fig. 8a) and higher latent heat flux at night likely contributes to the persistent large moist bias  
427 in the 10-m water vapor mixing ratio (Figs. 3d, 7d) during the AP-XM simulation. Another noteworthy feature of the AP-XM  
428 simulation is that the ground heat flux remains negative at all times. This unphysical behavior stands in sharp contrast to the  
429 more realistic evolution during the YNT simulations where the positive (negative) ground heat flux during the night (day)  
430 indicates that heat is being transferred from (toward) the ground toward (from) the atmosphere due to cooler (warmer) surface  
431 temperatures. These results indicate that the poor performance of the AP-XM simulation on the 1.3-km domain when assessed  
432 using near-surface moisture, temperature, and wind observations is likely due to the presence of vastly different and sometimes  
433 unphysical surface energy fluxes.  
434

435 The lower accuracy of the AP-XM simulation could be due to limitations in the parameterization schemes when used at higher  
436 spatial resolution. This possibility is supported by Fig. 9, which shows the evolution of the PBL height and surface fluxes on  
437 the 12-km domain computed using simulated data from all stations on the 1.3-km domain. Differences between the AP-XM  
438 and YNT simulations are much smaller both in timing and magnitude on the 12-km domain. For example, the time series for  
439 PBL height, sensible heat flux, and latent heat flux are very similar for all of the simulations. Though the ground heat flux  
440 time series for the AP-XM simulation continues to be an outlier at this resolution, it now has the correct diurnal cycle with  
441 positive (negative) values during the night (day). The improved simulation of surface fluxes on the 12-km domain likely  
442 contributes to the more accurate temperature and wind speed analyses in the AP-XM simulation at that resolution (Fig. 3a-b,  
443 3g-h). The presence of persistently higher latent heat flux (Fig. 9d) leads to a positive moisture bias in the AP-XM simulation  
444 (Fig. 3d-e); however, the bias is smaller on the 12-km domain than it was on the 1.3-km domain. Inspection of the surface  
445 energy fluxes and PBL height on the 4-km domain revealed larger differences between the AP-XM and YNT simulations (not  
446 shown), but not as large as those on the 1.3-km domain. Though it is not the focus of this research, differences in PBL height  
447 between the AP-XM and YNT simulations could be due to differences in vertical mixing strength and entrainment flux in the

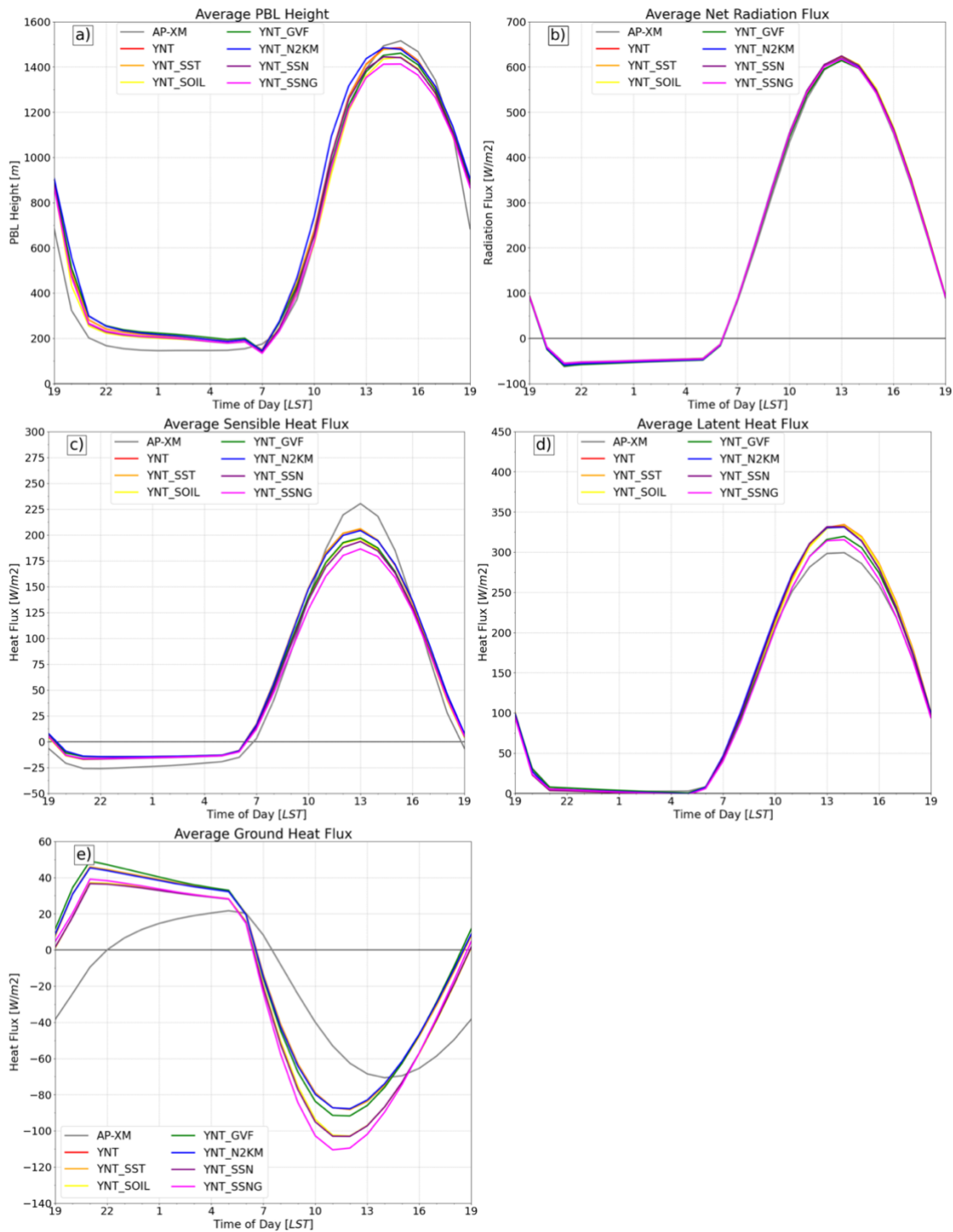
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AMC2 and YSU PBL schemes (e.g., Hu et al. 2010). Together, these results show that the AP-XM simulation performs well at 12-km resolution, but that its accuracy decreases with increasing model resolution.



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**Figure 8.** Time series showing the diurnal evolution of the (a) planetary boundary layer height (m), (b) net radiation ( $\text{W m}^{-2}$ ), (c) sensible heat flux ( $\text{W m}^{-2}$ ), (d) latent heat flux ( $\text{W m}^{-2}$ ), and (e) ground heat flux ( $\text{W m}^{-2}$ ) at hourly intervals starting at 1900 local standard time (LST), averaged over all stations on the 1.3-km domain during 22 May – 22 June 2017. Results are shown individually for each of the model simulations.



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Figure 9. Same as Fig. 8, except for showing results on the 12-km domain. Time series were computed using simulated data from all stations located on the 1.3-km domain.

In this study, eight WRF model simulations were performed to assess the impact of different parameterization schemes, surface datasets, and analysis nudging on the simulation of surface energy fluxes and near-surface atmospheric conditions in the Lake Michigan region during a 1-month period (22 May – 22 June 2017) corresponding to the LMOS field campaign. The simulations employed a triple-nested domain configuration containing 12-, 4-, and 1.3-km resolution grids, respectively. Two baseline simulations (AP-XM and YNT) employing different sets of parameterization schemes were performed to assess the importance of different physics suites. The YNT configuration additionally served as the baseline for six sensitivity simulations that were used to assess the impact of three satellite- and model-derived surface datasets and analysis nudging. Simulations were run where standard climatological or coarse-resolution surface datasets were replaced by high-resolution, real-time datasets depicting lake surface temperatures, GVF, and soil moisture/soil temperature. Near-surface temperature, water vapor, and wind observations were used to assess the accuracy of each model simulation.

The AP-XM configuration generally produced more accurate near-surface analyses on the 12-km domain, with the exception of a moist bias in the 2-m water vapor mixing ratio, but its relative performance decreased with finer model grid resolution. Evaluation of the AP-XM simulation showed that the diurnal evolution of the sensible and latent heat fluxes was similar to the YNT simulation on the 12-km domain but differed greatly on the 1.3-km nested domain where it had much smaller sensible heat flux during the daytime and larger latent heat flux at night. The increased latent heat flux combined with a shallower PBL contributed to the large moist bias in the 2-m water vapor mixing ratio. The evolution of the AP-XM ground heat flux was physically unrealistic on the 1.3-km domain because it remained negative at all times rather than changing signs between day and night as occurred during the YNT simulations. Because the evolution of the surface energy fluxes was more realistic on the 12-km domain, the poorer performance on the 4- and 1.3-km domains suggests that the Pleim-Xiu LSM is unable to adequately represent surface fluxes at higher resolutions. This could be due to its use of two soil layers including a very shallow (1 cm) topsoil layer that make it difficult to fully represent fine-scale features and soil heat fluxes. Increasing the number of soil layers in the Pleim-Xiu LSM could potentially improve its ability to simulate energy fluxes on high-resolution domains. In addition, use of observation nudging and soil moisture and soil temperature nudging as used in Torres-Vazquez et al. (2022) would also help constrain the evolution of this simulation. Though these specialized nudging techniques were not employed in our study due to their added complexity and confounding influence on the model evaluations because the same observations used in the nudging procedure would also be used to assess the accuracy of the simulations, their utility could be assessed in future work.

Inspection of the YNT statistics revealed a pattern where the percentage change in the RMSEs for 2-m temperature, 2-m water vapor mixing ratio, and 10-m wind speed relative to the AP-XM baseline improved as the model resolution increased from 12 km to 1.3 km. Switching to the YNT configuration led to substantial decreases in RMSE for 2-m temperature (25.8%) and 2-m water vapor mixing ratio (14.9%), and a more modest 3.3% reduction in the RMSE for 10-m wind speed, when assessed using all stations on the 1.3-km domain. Despite the already large error reductions when using the YNT parameterization suite, additional improvements occurred in most variables when the high-resolution surface datasets were incorporated into the modeling platform. Evaluation of the YNT sensitivity experiments showed that the high-resolution soil dataset had the largest positive impact on temperature and water vapor errors and the second largest impact on wind speed. Use of the GVF and SST datasets also led to more accurate temperature and water vapor simulations, but some degradations in the wind speed, especially when using the GVF dataset. Only the simulation employing analysis nudging above 2 km produced more accurate 10-m wind speed analyses; however, 2-m temperature errors were larger along the western shoreline of Lake Michigan when the nudging was confined to levels above 2 km instead of above the PBL. This suggests that the modified nudging approach may not work well for areas near Lake Michigan where the PBL tends to be shallower because it reduces its ability to constrain the evolution of the lower troposphere. Despite this limitation, the most accurate near-surface simulations were obtained during the experiment that employed analysis nudging above 2 km combined with the high-resolution SST and soil datasets. Slight degradation occurred when the satellite GVF dataset was included.

With these differences in near-surface temperature, humidity, and winds across model configurations and inputs, we can expect ensuing differences in the accuracy of model simulations of the production and transport of ozone precursors, as well as the

508 production of ozone. In part II of this study (Pierce et al. 2023), we evaluate these impacts on ozone forecasts in the Lake  
509 Michigan region using meteorological analyses obtained from the baseline AP-XM and optimized WRF model configurations  
510 as input to CMAQ model simulations.

#### 511 **Data availability**

512 All raw data can be provided by the corresponding authors upon request.

#### 513 **Author contributions**

514 JAO and RBP planned the study; MH performed the model simulations; JLC provided surface datasets; JAO, LMC, RBP, and  
515 MH analyzed the data; JAO wrote the manuscript; JAO, LMC, JLC, RBP, MH, AL, DSH, ZA, TN, and CRH reviewed and  
516 edited the manuscript.

#### 517 **Competing interests**

518 The authors declare that they have no conflicts of interest.

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