Recent changes in drainage route and outburst magnitude of Russell Glacier ice-dammed lake, West Greenland

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Abstract. Glacial lake outburst floods (GLOFs) or 'jökulhlaups' from ice-dammed lakes are frequent in Greenland and can influence local ice dynamics and bedrock motion, cause geomorphological changes, as well as pose flooding hazards. Multidecadal time series of lake drainage dates, volumes, and flood outlets are extremely rare. However, they are essential for determining the scale and frequency of future GLOFs, identifying drainage mechanisms, and for mitigating downstream flood effects. In this study, we use high-resolution digital elevation models (DEM) and orthophotos (0.1 x 0.1 m) generated from uncrewed aerial vehicle (UAV) field surveys, in combination with optical satellite imagery. This allows us to reconstruct robust lake volume changes associated with 14 GLOFs between 2007 and 2021 at Russell Glacier, West Greenland. As a result, this is one of the most comprehensive and longest records of ice-dammed lake drainages in Greenland to date. Importantly, we find a mean difference of ~10 % between our lake drainage volumes when compared with estimates derived from a gauged hydrograph 27 km downstream. Due to thinning of the local ice dam, the potential maximum drainage volume in 2021 is ~60 % smaller than that estimated to have drained in 2007. Our time series also reveals variations in the drainage dates ranging from late May to mid-September and drainage volumes ranging between 0.9 - 37.7 M m^3. We attribute these fluctuations between short periods of relatively high and low drainage volumes to a weakening of the ice dam and an incomplete sealing of the englacial tunnel following the large GLOFs. This syphoning drainage mechanism is triggered by a reduction in englacial meltwater, likely driven by late-seasonal drainage and sudden air temperature reductions, as well as annual variations in the glacial drainage system. Furthermore, we provide geomorphological evidence of an additional drainage route first observed following the 2021 GLOF, with a sub- or en-glacial flow pathway, as well as supraglacial water flow across the ice margin. It seems probable that the new drainage route will become dominant in the future. This will drive changes in the downstream geomorphology and raise the risk of flooding-related hazards as the existing buffering outlet lakes will be bypassed.

1 Introduction

Ice-dammed lakes can form either in supraglacial, subglacial or ice-marginal positions (Tweed and Russell, 1999). Globally, proglacial lakes (including ice-marginal lakes) contain up to 0.43 mm of sea level equivalent (Shugar et al., 2020) and recent studies show that ice-marginal lakes in Greenland have increased in both number and size (Carrivick and Quincey, 2014; Shugar et al., 2020). Currently, there are more than 3300 ice-marginal lakes in Greenland. These are predominately found around peripheral mountain glaciers and ice caps (PGICs) as well as along the southwest Greenland ice sheet (GrIS) margin (Carrivick et al., 2022; How et al., 2021). The outflow of ice-dammed lakes can vary substantially from a gradual near-steady discharge to sudden outburst floods called jökulhlaups or Glacial Lake Outburst Floods (GLOFs) (Tweed and Russell, 1999). Several mechanisms have been proposed for the rapid drainage of ice-dammed lakes and due to changes in lake inputs and topographic settings, drainages at the same lake may occur in response to different trigger mechanisms (Tweed and Russell, 1999). Sudden drainage of water from ice-dammed lakes in Greenland can have implications for fjord circulation (Kjeldsen et al., 2014), affect local ice dynamics (e.g. Kjeldsen et al., 2017; Sugiyama et al., 2007), cause bedrock displacements (Furuya and Wahr, 2005; Kjeldsen et al., 2017), alter downstream geomorphology (Russell et al., 2011) as well as have severe societal impacts (Carrivick and Tweed, 2016).

Carrivick and Tweed (2019) review the status of knowledge on GLOFs and ice-dammed lake drainages in Greenland and show that continuous multidecadal observations of transient lake water levels (i.e. pre- and post-drainage), lake drainage dates, and released flood volumes are extremely rare. Nevertheless, such time series are important for revealing spatio-temporal patterns in lake drainage and the timing and magnitude of flood events. Furthermore, long-term data improve our understanding of drainage triggers and mechanisms, provide important context for the scale and frequency of current and future GLOFs as well as aid in the mitigation of downstream effects. The primary aim of this paper is to (re)calculate and analyse the lake water level and drainage volume of 14 historical GLOFs observed from 2007 to 2021. Secondly, we investigate geomorphological changes supporting a shift in the proglacial GLOF drainage route observed following the recent GLOF on 22nd August 2021.

2 Study site

One of the most intensively monitored and widely studied ice-dammed lakes in Greenland is located on the northern flank of Russell Glacier in West Greenland (Figure 1) (Carrivick et al., 2017; Lamsters et al., 2020; Mikkelsen et al., 2013; Russell, 1989, 2007; Russell et al., 2011) and so it is a key site for understanding GLOF behaviour. The lake is ~0.7 km^2 and drains through a ~600 to 1000 m glacial tunnel in the southwestern part of the lake transporting water and sediment into two outlet lakes and further afield into the Watson River (Carrivick et al., 2013; Carrivick et al., 2018; Mernild and Hasholt, 2009; Russell, 1989; Russell, 2007; Russell et al., 2011). Based on aerial photographs, sedimentary data and refill rates the lake drained every two to three years from the 1950s until 1987 where it entered a 20-year stagnant period of stable water levels (Carrivick et al., 2018; Russell et al., 2011). On the 31st of August 2007 a new GLOF occurred (Russell et al., 2011) and the lake entered a new cycle of almost annual drainage events, with the last documented event happening in 2015 (Carrivick et al.,

2017). Previous lake drainage events have been estimated using a variety of methods such as downstream gauged hydrographs, pressure transducers within the lake, time lapse cameras and dGPS techniques to monitor water surface elevation (Carrivick et al., 2017; Mernild and Hasholt, 2009; Mikkelsen et al., 2013; Russell et al., 2011).
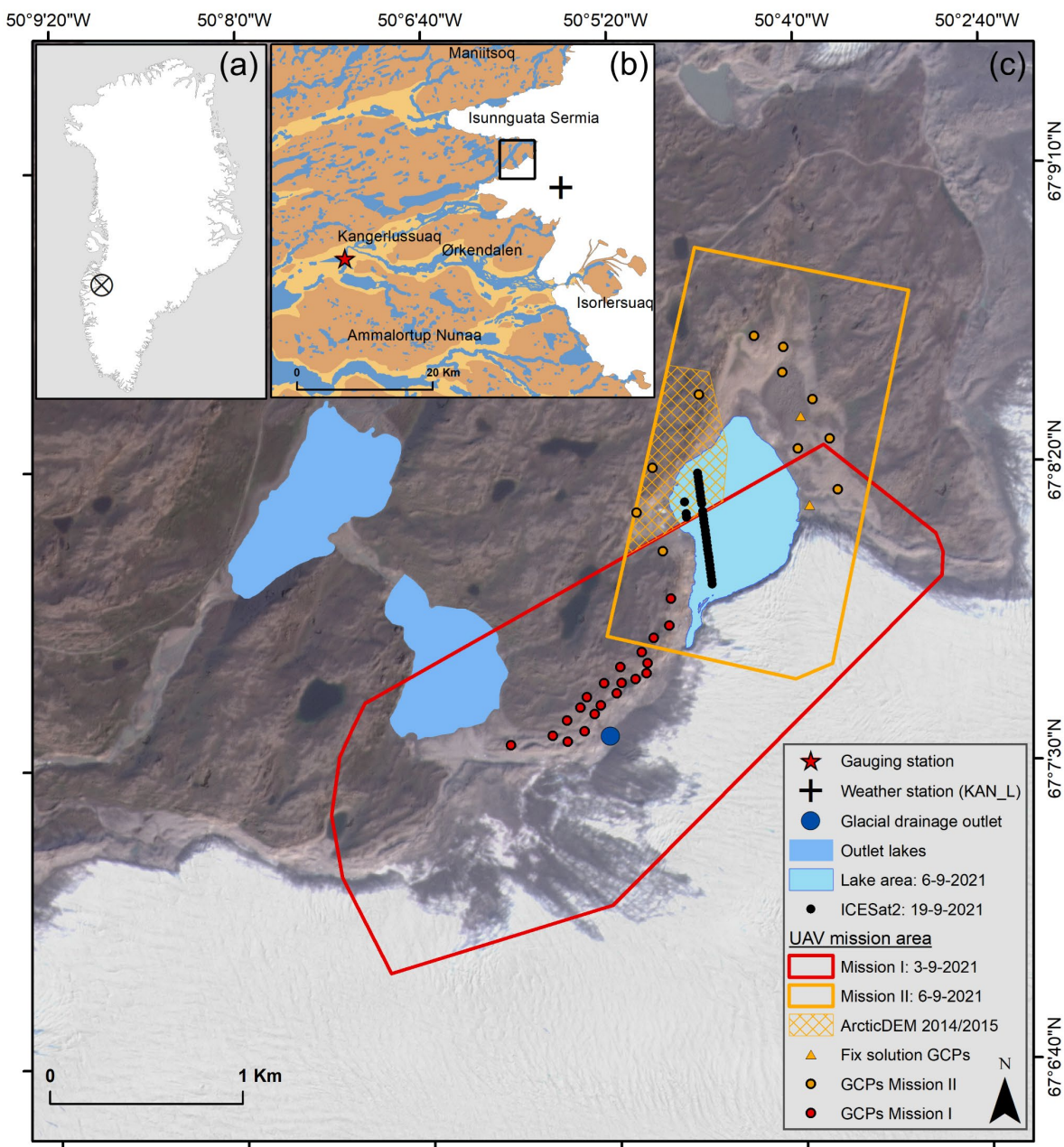
Figure 1. A) Study site location in Greenland. B) Close up of the study site with location of gauging station and Promice weather station. C) UAV mission area I and II with location of GCPs overlaid on a four band Planet (2017) acquisition from 23-8-2021. The yellow triangles illustrate the only two reliable fix solution GCPs. Due to image gaps at the western part of the lake the produced UAV DEM is filled with elevation data from two ArcticDEMs acquired on the 19-9-2014 and 2-8-2015.

3 Methods and data

Fieldwork at Russell Glacier was carried out between the 3rd and 6th of September 2021, two weeks after a GLOF on 22nd August 2021. Two UAV missions were undertaken to produce DEMs and orthophotos of the drained lake basin topography as well as the flood drainage route (Figure 1). As the lake did not fully drain we were unable to survey the entire lake topography, however, a standing water level of 408.8 m was surveyed in the lake, which is almost identical to the minimum lake levels observed after other previous GLOF events (Russell et al., 2011). Russell et al. (2011) produced a DEM of the lake basin bathymetry from interpolation of kinematic dGPS tracks surveyed in February 2008, finding a minimum elevation of 410 m. In this study, our UAV surveys enabled a highly accurate and high-resolution DEM without surface interpolation. From this DEM, we are able to precisely estimate the pre- and post-GLOF water level, the lake area and the likely drainage volume of both historical and future events. All elevations are reported as height above the WGS84 ellipsoid, unless otherwise stated.

3.1 Aerial surveys

The UAV flights were conducted on two different dates using two different UAVs, due to the battery capacity and weather conditions (Table 1, Figure 1):

Table 1 Overview of the two UAV mission. *Parentheses indicate the number of GCPs with a fixed GNSS solution.

UAV Mission	Flight date	UAV type	Flight mode	Images captured	Covered area (km^2)	Camera position accuracy (m)		Resolution (m)		Number of GCPs*	RMSE camera location (m)		
						Vertical	Horizontal	DEM	Ortho		X	Y	Z
Mission I	03-09-2021	Fixed-wing, WingtraOne w. multi-frequency L1/L2 GNSS receiver	Automatic	1106, nadir (60% overlap)	4.3	0.06	0.09	0.1	0.04	20 (0)	0.01	0.01	0.02
Mission II	06-09-2021	Quadcopter, DJI Phantom 4 Pro w. KlauPPK 7700C GNSS receiver	Manual	563, oblique and nadir	2.39	0.06	0.09	0.1	0.1	13 (2)	0.28	0.32	0.14

Both UAVs have direct georeferencing capabilities provided by an on-board GNSS receiver (Table 1), which records the positional data of each image as it is captured. To achieve centimetre-level accuracy in both the vertical and horizontal direction of the camera positions, we kinematically post-processed the positional data from the UAV GNSS receivers. Compared to real-time kinematic (RTK) correction, post-processed kinematic (PPK) positioning is considered more accurate and does not depend on a reliable real-time connection to a GNSS base station (Chudley et al., 2019). The UAV GNSS data was post-processed using WingtraHub (*v. 2.2.0*) and KlauPPK (*v. 7.17*) software relative to the fixed Greenland GPS Network (GNET) base station, located in Kangerlussuaq (KLSQ) approx. 30 km from the field site (Bevis et al., 2012). The processed camera position for both UAV surveys had a vertical and horizontal accuracy of ~0.09 m and 0.06 m, respectively (Table 1).

For the purpose of validating the accuracy of the produced DEMs we placed a combined total of 33, 0.3 x 0.3 m black and white, ground control points (GCPs) and measured their position using an Emlid Reach RS2 GNSS receiver (Table 1). We post-processed the log files from the Emlid rover using Emlid Studio (*v. 1.3*) software and the KLSQ base station data. Due to poor satellite reception and cycle slips we were only able to retrieve reliable fix solution position results for 0/20 and 2/13

95 GCPs in Mission I and Mission II, respectively (Table 1, Figure 1).

3.2 Development and validation of DEMs and orthophotos

The UAV images were processed using a structure-from-motion (SfM) workflow in Agisoft Metashape Pro. (*v. 1.7.4*). We follow the general processing workflow described in the official Agisoft guidelines (Agisoft LLC, 2020). The camera calibration was set as 'precalibrated' and the calibration parameters set according to the calibration report of the used camera.

100 Instead of GCPs, we used the post-processed, geolocated camera positions to georeference the point cloud. During the bundle adjustment, we performed a refined camera calibration, which is recommended when other variables are well constrained (Chudley et al., 2019). DEMs and orthomosaics for Mission I were then exported at resolutions of 0.1 and 0.04 m, respectively, while for Mission II both were exported at a resolution of 0.1 m (Table 1). The RMSE of the X, Y and Z camera location, as reported in Agisoft Metashape after model generation, is 0.01, 0.01, and 0.02 m for Mission I and 0.28, 0.32, and 0.14 m for

105 Mission II (Table 1). The large RMSE values of Mission II likely originate from strong wind conditions at the time of surveying, which may have caused the UAV to tilt or move slightly during image acquisition. In combination with the manual flight mode, this may have resulted in decreased image quality and a poor image overlap in specific regions, such as at the western part of the lake (Figure 1). Furthermore, the majority of the acquired images were captured from an oblique viewing angle, which makes them computationally challenging to process compared to nadir images, due to geometric and photometric

110 deformations caused by varying perspective and illumination conditions (Jiang et al., 2020).

Previous studies, using a similar setup and approach (Chudley et al., 2019; Jouvet et al., 2019), reported horizontal and vertical uncertainties in the range of 0.1 – 0.4 m, without the use of GCPs. By measuring the horizontal and vertical displacement between the two fix solution GCPs and their observed location in the Mission II orthomosaic and DEM, we estimated the

115 accuracy to be 0.14 m and 0.35 m, respectively. Due to a lack of reliable GCPs, we applied an additional method for determining the uncertainty. Inspired by similar studies (Chudley et al., 2019; Jouvet et al., 2019), we estimated the uncertainty by calculating the relative offset between the Mission I and Mission II DEM over stable bedrock, assuming no change in the topography. We applied the python module PyBob (McNabb, 2019) based on the co-registration method developed by Nuth and Kääb (2011), which determines the X,Y and Z offset from elevation difference residuals as well as the terrain's aspect and

120 slope. The co-registration was based on >8 million pixels extracted from two areas of overlapping bedrock located on both the western and eastern part of lake. Using the Mission I DEM as the reference, we found a relative offset of X = -0.43 m, Y = 0.11 m and Z = 0.53 m and adopted this as our main measure of uncertainty. By applying this offset to the Mission II DEM,

we were able to reduce the mean elevation difference and RMSE over stable bedrock from 0.39 m to 0.00 m and 0.42 m to 0.17 m, respectively. Following co-registration, we combined the Mission I and Mission II DEM into a mosaic.

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Due to image gaps at the western part of the lake, we were not able to produce a complete UAV-derived DEM of the drained lake topography. Thus, the missing regions were filled with elevation data from two ArcticDEM strips acquired on the 19th of September 2014 and 2nd of August 2015, respectively (Figure 1). The ArcticDEM strips have a resolution of 2 x 2 m and are based on photogrammetric processing of Worldview stereo-image pairs (Noh and Howat, 2015). At the time of acquisition,

130 both ArcticDEMs had a standing water level of approx. 407 m. We predominately utilised the 2015 DEM as it was produced using images acquired only five days after the 2015 drainage event, however, it also contained several data gaps. Consequently, we filled these using the 2014 DEM, which was produced using images acquired 47 days after the 2014 drainage event. Prior to mosaicking, all DEMs were resampled to 0.1 m resolution and co-registered over solid bedrock using the python module PyBob (McNabb, 2019).

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Using the co-registered DEM mosaic, as well as the Mission II orthomosaic, we digitised lake area and extracted elevation points every 5 m along the digitised eastern lake margin to estimate a water level of 408.8 m ± 0.35 on the 6th September 2021. Finally, all elevation data within the lake area were changed to 408.8 m to avoid erroneous elevation estimates on the water surface. From herein the final mosaicked and lake-burned DEM will be referred to as the 2021 post-drainage DEM. We

140 validated the estimated water level by comparing it to 33 ICESat2 data points from 19th September 2021 measured at the ice-free lake interior (Figure 1). The ICESat2 points have a mean water level of 408.70 m and a STD of 0.02 m.

3.3 Estimation of water level, lake area and drainage volume

To estimate the lake water level at different temporal intervals we used satellite images from Planet scope, Landsat 7 and 8

145 and Sentinel-2. The satellite images were manually georeferenced to the high-resolution UAV orthophotos to adjust for small offsets. Inspired by the approach of previous studies (e.g. Carrivick and Tweed, 2019) the pre- and post-drainage water level was determined by manually placing 30 points along the ~600 m waterline on the eastern part of the lake as observed on the satellite images. The points were placed with an approximate spacing of 20 m, however, this varied depending on the visibility of the waterline as well as to avoid areas with apparent morphological changes. The eastern part was chosen as it only contains

150 high-resolution (0.1 x 0.1 m) UAV-derived elevation pixels as well as having a flat slope compared to the steep terrain in the west (Figure A1). For each of the 30 points, we extracted the elevation from the 2021 post-drainage DEM and calculated the mean water level as well as the standard deviation indicating the uncertainty of the elevation estimate (Table 2). The mean water level was used to estimate the lake outline and area by masking out pixels above the mean water level as well as removing depressions not linked to the existing lake area. Using the estimated lake area and the 2021 post-drainage DEM we calculated

155 the pre- and post-drainage water volumes using Eq. (1):

$$\sum_{i=1}^{n}(\mu_{wl} - P_{elev_i}) * P_{width_i} * P_{height_i}, \qquad\qquad\qquad (1)$$

where n denotes all pixels within the lake area, μ_{wl} the mean water level, P_{elev_i} the elevation of the pixel and P_{width_i} and P_{height_i} the pixel resolution, which is 0.1 x 0.1 m. The total lake area change and water volume release of every GLOF was determined by extracting the pre and post-drainage estimates (Table 2). As area and volume estimates were calculated relative to the 6th of September 2021 when images for the 2021 post-drainage DEM were acquired, they are sensitive to changes in the position of the ice margin. From 2007 to 2011 we observed a gradual advance of the margin, while from 2011 onwards it remained relatively stable with only slight changes in frontal position observed (Figure A2). To accommodate for the influence of the observed frontal advances from 2007 to 2011 we recalculated the lake area and volume changes of those years. For each year, we manually adjusted the lake area to match with the position of the ice margin, as observed in the respective satellite image. Finally, we recalculated the volume change of the adjusted lake area based on the estimated pre- and post-drainage level.

All drainage estimates from 2017-2021 are based on Planet scope satellite images, whereas estimates of previous events are based on mainly panchromatic images from Landsat 7 and 8 with a resolution of 15 m as well as RGB images from Sentinel-2 with a resolution of 10 m (Table 2). In contrast to the relatively coarse (10 and 16 days) temporal coverage of the Landsat and Sentinel images, Planet images have a much finer spatial resolution of 3 m, and a temporal resolution of approximately one day (Planet, 2017). This enables the detection of short-term changes in water level, albeit during clear-sky conditions.

3.4 Drainage routes

Based on the Mission I DEM we determined the main surface drainage routes for the 2021 GLOF event from the glacial drainage outlet to (i) the outlet lakes and (ii) across the ice margin. The drainages routes were calculated as the paths of least resistance from the source (drainage outlet) to the locations (i) and (ii) assuming that water is flowing to the neighbouring pixel with the lowest elevation. The calculations were based on a 2 x 2 m resampled version of the DEM to limit local elevation maxima from small surface features such as rocks and ice blocks that could potentially influence water flow. Finally, we generated points every two meters along both of the estimated drainage routes and extracted the underlying elevations to determine the maximum elevation of each route.

3.5 Hydrograph volume estimation

We estimated the drainage volume from a gauging station deployed in Watson River at Kangerlussuaq, 27 km downstream of the lake (van As et al., 2017). Here pressure transducers record changes in water pressure, which subsequently is corrected for atmospheric pressure before being converted into hourly averages in water level. Water discharge was then obtained using a rating curve, based on discharge measurements at various water levels (van As et al., 2017), and is associated with a conservative uncertainty value of 15 %. Due to diurnal fluctuation in discharge, we estimated the daily minima and maxima on the day of the drainage event by fitting linear trend through the equivalent low and high stage values on the day before and after. This allowed estimates of the baseflow and thus estimates of the volume associated with lake drainage to be made.

3.6 Temperature data

Air temperature data was obtained from the KAN_L automatic weather station, part of the PROMICE AWS network, which is located on the ice sheet at 670 m asl, 18.5 km from the study site. We use hourly average data that is based on measurements recorded every 10 min (Fausto et al., 2021; GEUS Dataverse n.d). For each of the analysed periods, the air temperature data contained no missing values.

4 Results

4.1 Drainage volumes

Figure 2 illustrates how lake volume and area change with variations in water level, as calculated based on the 2021 post-drainage DEM. The lake has a theoretical maximum water level of 433 m, after which water overspills the ice dam, hereby indicating the elevation of the damming glacier. The 2021 theoretical water level maximum produces a lake surface area of 0.79 km^2 and a maximum drainage volume of 14.3 M m^3, which is a 63 % decrease compared to the actual estimated drainage volume of the 2007 GLOF (Table 2). Moreover, we compared the theoretical maximum water level to the estimated 2007 pre-drainage water level of 453.1 m, and found an ice dam lowering of at least 20.1 m. We were able to determine a theoretical maximum water level of 450 m from the 2015 ArcticDEM, which was 17 m higher than the 2021 level. Based on the present configuration of the lake and ice margin, the lake is not able to reach the 2007 maximum level as it would drain through the glacial conduit at a lower level.
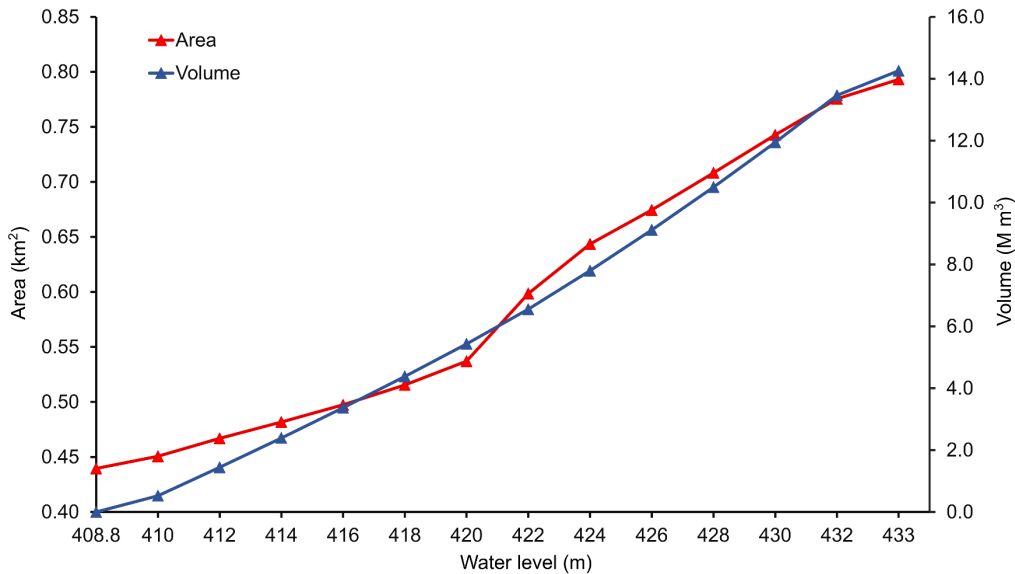
Figure 2. Lake area (km^2) and lake volume (M m^3) with changing water level (m), calculated for every second meter, based on the 2021 post-drainage DEM. The lake has a maximum water level of 433 m after which it overspills the damming glacier. The sharp increase in lake area from ~420 m to 422 m is due to a plateau at the north eastern part of the lake (Figure A1).

4.2 Drainage cycles

Since the lake entered its new drainage cycle in 2007 we observe annually reoccurring events, with the exception of 2009. The
2007 GLOF had the largest observed drainage volume, with a value of 37.73 ± 1.08 M m^3 recorded (Table 2 and Figure 3),
yet a year later in 2008 the volume release was four times lower, at 9.4 ± 1.46 M m^3. In contrast, in 2010 the drainage volume
once again returned to a higher level, with 26.08 ± 2.54 M m^3 recorded. Over the following three years (2011 to 2013) the
drainage volume remained relatively stable at between 7 and 9 M m^3, before decreasing to ~4 M m^3 in 2014 and 2015, after
which a threefold increase to 12.5 M m^3 was observed in 2016. In both 2017 and 2020, we have reconstructed small, partial
drainage events of just 2.7 and 0.9 M m^3, respectively (Table 2 and Figure 3). These two events occurred earlier in the melt
season in comparison to previous drainage events, with the 2020 event occurring by 31st May. In the years following the
occurrence of these partial drainage, i.e. in 2018 and 2021, the observed GLOFs occurred relatively late in the melt season,
with volumes of 8.5 and 9 M m^3 recorded, respectively (Table 2 and Figure 3). In general, the lake seems to fluctuate between
short periods of relatively high and low drainage volumes, with the low volume GLOFs occurring earlier in the melt season.
However, the later occurrence of these drainage events is not always equivalent to a larger drainage volume, as evidenced in
2018 and 2019.
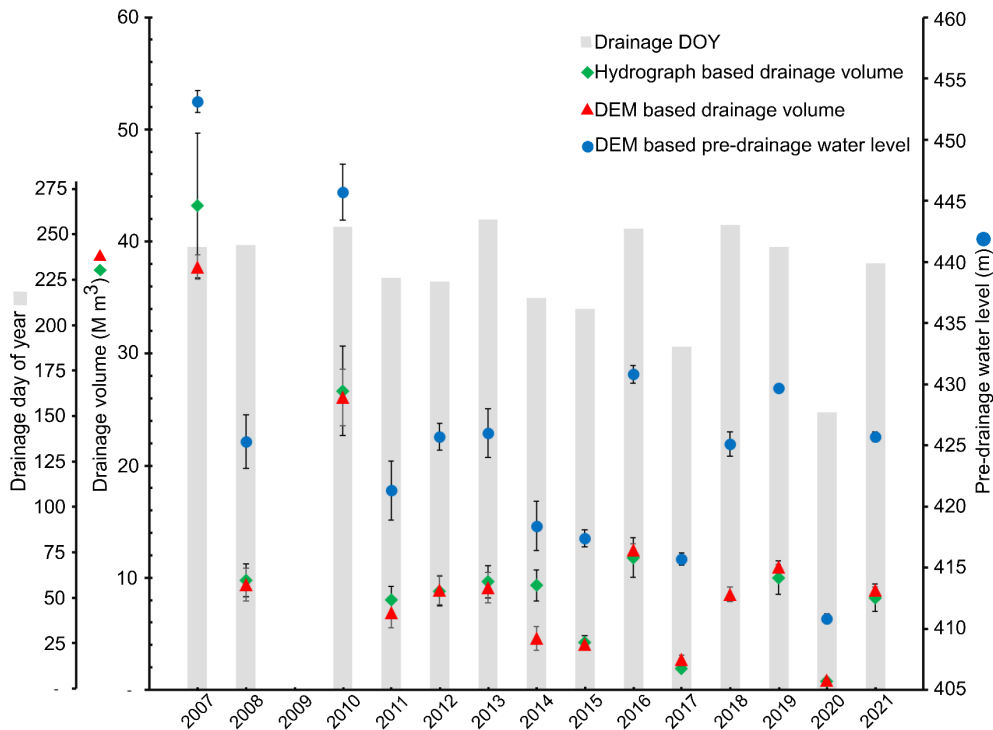
Figure 3. Pre-drainage water level, drainage volume and drainage day of year (DOY) for 14 GLOFs spanning 2007 to 2021. Pre-drainage water levels (blue circles) are estimated using the 2021 post-drainage DEM. Drainage volumes are estimated using both the 2021 post-drainage DEM (red triangles) and downstream hydrograph observations (green squares). The grey bars indicate the day of year (DOY) of the drainage and refers to the leftmost Y-axis. No hydrograph data for the 2018 event.

Table 2. Drainage dates, pre- and post-drainage water levels, lake areas, and volumes for 15 GLOFs spanning 1987 to 2021. The 1987 estimates are adopted from Russell et al., 2011. The 2007 to 2021 estimates are reconstructed using the 2021 post-drainage DEM in combination with selected optical satellite images as well as from downstream hydrograph observations. Table includes references to previous studies of the lake, including estimated drainage volumes.

Drainage dates	Water level (m)		Lake area (km2)		Area change (km2)	Volume relative to 6th Sept. 2021 (M m3)		Lake volume release (M m3)	Source	Volume from hydrograph (M m3)	Other references and volume estimates (M m3)
	Pre drain	Post drain	Pre drain	Post drain		Pre drain	Post drain				
17-19. July 1987	450.8	402.5						31.3	Russell et al., 2011.		Russell 2007; Russell 1989
31. Aug. 2007	453.1 ± 0.9	< 408.8	1.308* ± 0.022	0.475* ± 0.007	0.833 ± 0.023	37.73** ± 1.08	0***	37.73 ± 1.08	This study (Landsat 7)	43.19 ± 6.47	Russell et al. 2011 (39.1 ± 0.8) Mikkelsen et al. 2013 (25.5) Mernild & Hasholt 2009 (11.3)
31. Aug. 2008	425.3 ± 2.2	< 408.8	0.710* ± 0.037	0.435* ± 0.008	0.275 ± 0.038	9.40** ± 1.46	0***	9.40 ± 1.46	This study (Landsat 7)	9.75 ± 1.46	Russell et al 2011 (12.9 ± 0.3) Mikkelsen et al. 2013 (3.6) Mernild & Hasholt 2009 (4.6)
11. Sept. 2010	445.7 ± 2.3	410.4 ± 1.3	1.051* ± 0.092	0.495* ± 0.013	0.556 ± 0.093	27.26** ± 2.33	1.18** ± 1.02	26.08 ± 2.54	This study (Landsat 7)	26.66 ± 4.00	Carrivick 2017 (30.7) Mikkelsen et al. 2013 (8.4)
14. Aug. 2011	421.3 ± 2.4	< 408.8	0.583* ± 0.057	0.413* ± 0.007	0.170 ± 0.057	6.90** ± 1.38	0***	6.90 ± 1.38	This study (Landsat 7)	8.02 ± 1.20	Carrivick et al. 2017 (No vol.)
11. Aug. 2012	425.7 ± 1.1	< 408.8	0.670 ± 0.018	0.404* ± 0.008	0.266 ± 0.020	8.91 ± 1.29	0***	8.91 ± 1.29	This study (Landsat 7)	8.81 ± 1.32	Carrivick et al. 2017 (25.5)
15. Sept. 2013	426.0 ± 2.0	< 408.8	0.674 ± 0.031	0.413* ± 0.007	0.261 ± 0.032	9.12 ± 1.35	0***	9.12 ± 1.35	This study (Landsat 8)	9.65 ± 1.45	
3. Aug. 2014	418.4 ± 2.0	< 408.8	0.519 ± 0.021	0.410* ± 0.007	0.109 ± 0.028	4.59 ± 1.04	0***	4.59 ± 1.04	This study (Landsat 8)	9.31 ± 1.40	Carrivick et al. 2017 (8.0)
28. July 2015	417.4 ± 0.7	< 408.8	0.510 ± 0.006	0.411* ± 0.007	0.099 ± 0.009	4.07 ± 0.36	0***	4.07 ± 0.36	This study (Landsat 8)	4.22 ± 0.63	Carrivick et al. 2017 (7.5)
8. Sept. 2016	430.8 ± 0.7	408.9 ± 0.3	0.748* ± 0.01	0.441 ± 0.003	0.307 ± 0.010	12.53 ± 0.51	0.04 ± 0.08	12.49 ± 0.52	This study (Sentinel-2)	11.78 ± 1.77	
7. July 2017	415.7 ± 0.5	410 ± 0.7	0.495 ± 0.004	0.451 ± 0.006	0.044 ± 0.007	3.22 ± 0.25	0.53 ± 0.32	2.69 ± 0.41	This study (Planet)	1.89 ± 0.28	
12-13. Sept. 2018	425.1 ± 1.0	< 408.8	0.661 ± 0.015	0.440* ± 0.007	0.221 ± 0.017	8.51 ± 0.66	0***	8.51 ± 0.66	This study (Planet)	No data	
31. Aug. 2019	429.7 ± 0.2	410.5 ± 0.3	0.732* ± 0.002	0.455 ± 0.002	0.277 ± 0.003	11.71 ± 0.15	0.75 ± 0.14	10.96 ± 0.21	This study (Planet)	10.00 ± 1.50	
31. May 2020	410.8 ± 0.4	< 408.8	0.457 ± 0.003	0.428* ± 0.007	0.029 ± 0.08	0.89 ± 0.18	0***	0.89 ± 0.18	This study (Planet)	0.75 ± 0.11	
22. Aug. 2021	425.7 ± 0.4	< 408.8	0.670 ± 0.006	0.438* ± 0.007	0.232 ± 0.009	8.91 ± 0.27	0***	8.91 ± 0.27	This study (Planet + UAV ortho)	8.22 ± 1.23	

* Areas have been manually edited. From 2007 to 2011 to compensate for changes at the ice margin. Pre drain 2016 and 2019, to avoid water extending on the ice margin. Post drain 2012-2015, 2018 and 2020-2021 as the water level was observed to be lower than the reference DEM minimum of 408.8 m

**Volumes adjusted to compensate for changes observed at the ice margin.

***Post drain volume set to 0. As the post drainage lake area in 2007, 2008, 2011-2015, 2018, 2020, 2021 is almost identical to that of the reference area (0.439 km2) the volumes are assumed to be almost identical.

4.3 Geomorphology of the drainage area

Figure 4A and 4B illustrate the two main routes of drainage for the GLOF event to exit the drainage outlet. Drainage route I channels the water into an ephemeral river channel and into two outlet lakes connected to the downstream river network. In contrast, in drainage route II the water flows across the ice margin and into an ice-marginal meltwater drainage system before reaching the river network, thus bypassing the two outlet lakes. There is a 0.4 m elevation difference between the drainage threshold of drainage route I (390.2 m) and drainage route II (390.6m) (Figure 4B).

The high resolution of the orthomosaic and DEM produced through UAV Mission I have enabled us to observe a number of important geomorphologic features across the drainage region which are not visible in the 3m resolution Planet imagery. For example, large blocks of ice up to 5 m in length are observed scattered across both drainage route I and II (Figure 4C and 4D). On the western part of the ice margin we observe a ~100 m x 100 m area where the ice surface is fractured and broken (Figure 4F). The ice margin also contains 0.5 m to 3 m wide, parallel fractures (Figure 4G and 4H) that run up to several hundred meters in an interrupted, circular pattern (Figure 4B) as well as five roughly circular and nearly vertical holes with a diameter of ~10 m (Figure 4E). Finally, observations of the ice margin and drainage outlet position in both 2015 and 2021 indicate a retreat of 30 m and 60 m in this period, respectively (Figure 4B).
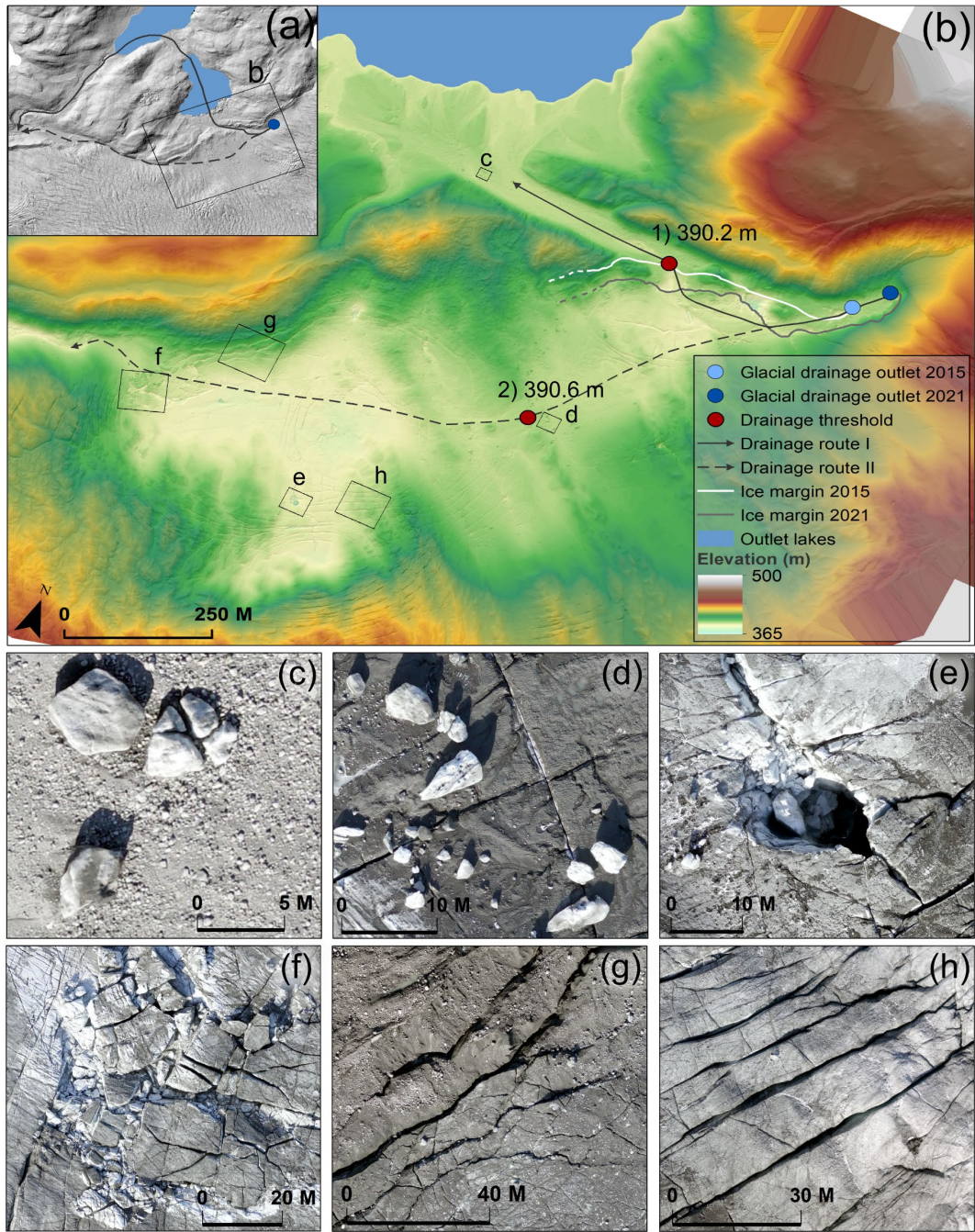
Figure 4. A) Overview of drainage route I and II overlaid on a hillshade of the ArcticDEM from 2-8-2015. Box indicates the region illustrated in panel b). B) Hillshade of the post drainage terrain, produced from the Mission I DEM, highlighting where the water exits the glacial drainage outlet. The drainage thresholds indicate the highest elevation points along the drainage routes. The 2015 and 2021 ice margins are digitized based on the ArcticDEM and Mission I DEM, respectively. C) and D) Ice blocks deposited along the two drainage routes, up to 5 m in length. E) Roughly circular and nearly vertical holes, ~10 m in diameter, with a total of five such features observed at the ice margin. F) Fractured ice due to supraglacial water flow. G) and H) Parallel fractures, reaching several hundred metres in length.

5 Discussion

5.1 Drainage volume estimates

240 For all GLOFs except 2014, the DEM and hydrograph based methods produce volume estimates that are within each other's margins of error (Table 2, Figure 3) with a total mean difference of 10%. This indicates that the two methods used to obtain drainage volumes can serve as independent validation for one another. For the 2014 GLOF the hydrograph estimate is greater; two times as large as the DEM-derived volume. This could partly be because the cloud-free Landsat 8 image captured closest to the drainage date on 3rd August was acquired 13 days prior to the GLOF, on the 21st July. Using the max 2010-inflow rate

245 of 1.3 m^3 s^{-1} (Russell et al., 2011), the lake volume would increase by approx. 1.5 M m^3, which is still 3.2 M m^3 lower than the hydrograph estimate. However, based on a comparison between the 2010 and 2014 July temperature at KAN_L the actual inflow rate is likely smaller, leaving the discrepancy between the two estimates even larger. It has been suggested that GLOFs can trigger additional release of meltwater from englacial storages or due to frictional melting (Huss et al., 2007; Mernild and Hasholt, 2009). This would show as larger hydrograph estimates and could explain the 2014 volume difference. However, as

250 all remaining GLOFs present no evidence of additional water release, it is considered unlikely. Moreover, we find no evidence that any of the other proglacial lakes in the system have undergone a change in their area, which would indicate changes in water storage, and therefore the 2014 event remains unquantified. We observe no notable presence of ice on the lake surface during any of the 14 GLOFs. This is important as ice may limit the lake's water storage capacity and influence the drainage timing and volume (Jenson et al. 2022). In years with an early drainage date and a low drainage volume (2014, 2015, 2017,

255 2020), we checked for additional late seasonal drainage events by manually going through satellite images starting from the observed drainage date to the end of the melt season.

When the lake drains below the 2021 post-drainage DEM reference elevation of 408.8 m (2007, 2008, 2011-2015, 2018, 2020, 2021) we underestimate the volume release, as we cannot measure the precise post drainage water level. As annual differences in the post-drainage area are minimal (Table 2), the changes in volume are also expected to be limited. Additionally, the total

260 lake area during these instances is at its minimum. Russell et al., (2011) reported the post drainage water level of the 2007 event to be 404.5 m, which is 3.34 m lower than our 2021 reference minimum. Assuming that the entire 2007 post-drain area (Table 2) is lowered by an additional 3.34 m, it would give an extra volume release of 1.59 M m^3 corresponding to a 4% increase from 37.73 M m^3 to 39.32 M m^3. Russell et al., (2011) estimated the volume of the 2007 event to be 39.1 M m^3. Mernild & Hasholt (2009) and Mikkelsen et al., (2013) find much lower drainage volumes for the 2007 GLOF of 25.5 M m^3

265 and 11.3 M m^3, respectively (Table 2). However, these estimates are based on obsolete stage-discharge relations (van As et al., 2017). A similar pattern of matching and conflicting volume estimates is identified for other previous GLOFs (i.e, 2008, 2010, 2012, 2014, 2015 in Table 2), both in existing studies as well as when compared to the reconstructed volumes presented in this study. This highlights the challenges related to reconstructing drainage volumes, and stresses the need for consistent methodological estimates to allow for better comparisons of annual variations to be made.

5.2 Drainage trigger mechanisms and controls

With the documentation of seven new, and the re-calculation of seven known GLOFs, we are now able to re-evaluate the proposed drainage triggering mechanisms. Previous studies have suggested several different mechanisms that control GLOFs at Russell Glacier, such as flotation of the ice dam (Carrivick et al., 2017), fluctuation in subglacial meltwater (Russell & de Jong, 1988; Russell, 1989), incomplete resealing of the subglacial conduit (Russell et al., 2011), and subglacial drainage through an incised bedrock-walled Nye channel (Russell et al., 2011). Recent data from ground penetrating radar surveys, however, revealed no evidence of a Nye channel incised into the bedrock, but instead found evidence of at least one englacial tunnel running parallel to the ice margin (Lamsters et al., 2020).

Had the lake been draining due to floatation of the ice dam we would expect to see a gradual decrease in the release volume and pre-drainage water level as less water is required to float the thinning ice dam. We do observe a lower drainage volume compared to the 2007 and 2010 maximum, but the lake is still able to drain at both similar and higher water levels than observed in 2008 (Figure 3, Table 2). The two largest GLOFs (i.e. 2007 and 2010) both occurred following a year of no drainage, and indicate that in order for the lake to reach such a high-water level an additional (or multiple) melt season is required. However, due to thinning of the damming glacier the lake is unable to reach its previous peak drainage water level and volume that was observed in 2007 and 2010. As a result, and based on its current configuration, the lake can only reach a maximum water level of 433 m, at which point it overspills the ice dam.

Russell (1989) suggested the internal drainage network of Russell Glacier, and a possible reduction in (sub)glacial meltwater as the main trigger for the 1984 and 1987 GLOFs. This closely aligns with the majority of the observed GLOFs occurring late in the melt season when sub- and englacial water pressure is lower. However, the partial drainage events of 2014, 2015, 2017, and 2020 occur earlier in the melt season, indicating a different drainage mechanism or an additional means by which to lower the water pressure. The water pressure can also be lowered as a consequence of a sudden reduction in meltwater production (Tweed and Russell, 1999; Russell et al., 2011). Russell et al. (2011) suggested a link to an observed drop in air temperature prior to the 2007 and 2008 GLOFs. For 7 of the 12 GLOFs that occurred between 2010-2021 (2010-2011, and 2015-2019), we observe a similar drop in mean air temperature (MAT) when comparing the MAT of the 10 days prior to the GLOF with the MAT of the month prior (Figure 5). The difference ranges from -1.1 to -4.5 °C, with the largest drop observed in 2019. For the five remaining GLOFs the mean temperature changes are either very moderate (-0.2 - -0.5 °C) or increasing (0.3 - 1.1 °C). However, when comparing the 10-day MAT to the 5-day MAT prior to the drainage in both 2012 and 2013 we observe a 1.7 and 3 °C drop, respectively (Figure 5). A drop in temperature could influence the triggering of the GLOFs as the sub- and englacial water pressure falls in response to the reduced ablation. This permits the lake water to escape via hydraulic connection to the englacial conduit. The syphoning mechanism may be triggered by a reduction in melt, but as the timing and triggering threshold of the GLOF is linked to the water pressure dynamics of the englacial hydrological system it also reflects annual variations in the glacial drainage system (Tweed and Russell, 1999; Russell et al., 2011). As syphoning requires the draining lake to already be connected to the glacial drainage network (Tweed and Russell, 1999), a different mechanism must have

triggered the 2007 GLOF and caused it to produce the englacial tunnel, which likely still acts as the main drainage passage for the following annually reoccurring events.

305 The fluctuation between short periods of relatively high and low drainage volumes (Figure 3, Table 2), suggests other factors may influence the triggering threshold. The partial 0.9 M m^3 GLOF in 2020 drained just 0.3 m $\pm$ 0.5 m above the post drainage water level of the 11 M m^3 2019 GLOF. This suggests that the ice dam did not seal during the 2019-2020 winter, allowing the lake to drain earlier at the beginning of the ablation season in late May. We hypothesize that the large GLOFs potentially weaken the ice dam leading to an incomplete sealing of the englacial tunnel. This allows the following event(s) to occur at

310 much lower water level. A similar theory is suggested by Russell et al. (2011) as an explanation for the differences between the 2007 and 2008 events. After a number of such small events the drainage system likely undergoes a change in configuration, resulting in the closure of the drainage outlet and allowing for the reoccurrence of a larger GLOF the following year.

Figure 5. Plot of hourly temperature measurements from 10 days prior to the drainage event from KAN_L. Green line shows the mean air temperature (MAT) 41-10 days prior to the drainage, red line shows MAT 10-0 days prior, and orange line MAT 5-0 days prior to drainage. Red circle denotes the start of the GLOF and for the 2018 event the circle is larger due to uncertainty about the timing. All plots share the same Y axis range.

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5.3 Evidence of changing drainage route

Previous observations of the lake drainage system (e.g. Carrivick et al., 2018; Mernild & Hasholt, 2009; Russell, 1989) coincides with the estimated location of drainage route I. In this study, the scattered ice blocks and fractured ice surface observed in Figure 4C, 4D, 4F, indicate a considerable flow of surface water along drainage route I, as well as the new route II during the 2021 GLOF. The roughly circular and nearly vertical holes, exemplified in Figure 4E, are likely created by the collapse of the ice surface above an empty en- or subglacial cavity. They may also be a result of pressurised en- or subglacial water flow being forced upwards and breaching the ice surface, causing a localised collapse. There are multiple potential explanations for the parallel fractures observed on the ice margin (Figure 4G and 4H), such as a propagation of basal crevasses towards the surface, stretching of the ice surface from increased basal sliding, as well as a temporary uplift and/or (subsequent) falling of the ice surface. In combination with the additional observed surface features, we consider the latter hypothesis the most plausible, however, all explanations can be linked to a sub- or englacial flow of drainage water.

From 3m-resolution Planet satellite images (Planet, 2017) captured immediately before and after the 2021 GLOF, we also observe geomorphological changes along the ice-marginal meltwater drainage system which channels the GLOF drainage water from drainage route II into the downstream river network. As a results of this observation we reanalysed previous drainage events. The reanalysis showed no evidence of geomorphic change along the ice-marginal meltwater drainage system after the 2020 and 2019 events. However, we did observe standing water on the ice margin and changes in the ice colour (black to white) after the 2019 drainage, indicating water flow on the ice surface.

On the basis of these observations, we hypothesize that the new drainage pattern is predominantly caused by the thinning and retreat of the ice margin in the vicinity of the outlet, allowing floodwater to more easily run over and into the ice margin. The 0.4 m elevation difference between drainage route I and II (Figure 4B) suggest that route I is still the primary path. However, as the ice margin gradually thins drainage route II will likely become the dominant path taken. This shift is very profound, because it bypasses the two outlet lakes (Figure 1) that currently acts as a buffer and slow the downstream flow of water. Thus, this shift will affect downstream geomorphology and potentially cause hazards to local infrastructure. Therefore, we strongly suggest that a comprehensive investigation of the potential downstream consequences of GLOFs along the new route is undertaken.

7 Conclusion

This study presents one of the longest and continuous known records of GLOF drainage estimates in Greenland. We (re)analyse 14 GLOFs spanning 2007 to 2021 to provide a new evaluation and a greater understanding of the drainage patterns and trigger mechanisms. Our time series reveal annually GLOFs, with the exception of 2009, and considerable variations in both the date of drainage, ranging from 31st May to 15th September, as well as the overall volume, ranging from 0.9 to 37.7 M m^3. We compare our estimates of lake drained volume produced through DEM analyses with flood volumes calculated from a

downstream hydrograph. We find that the two methods produce comparable results with a mean volume difference of 10 %. That difference is excluding the 2014 GLOF where the hydrograph estimate is double the DEM-derived volume, which cannot

350   be resolved with the available data. In general, we find that our reconstructed time series demonstrates the need for consistent methodological estimates when studying year-to-year variations. We illustrate that the 2021 theoretical maximum drainage volume is 14.3 M m^3, which is 63 % lower than the 37.7 M m^3 estimated for the 2007 GLOF. This decrease can likely be explained by the observed thinning of the ice dam.

We hypothesize that when the ice-dammed lake episodically drains, it does so through an englacial tunnel created by the 2007

355   GLOF. In contrast, the ensuing annual drainages are likely caused by a syphoning drainage mechanism within the pre-existing englacial conduit. This syphoning is likely triggered by a reduction in melt water, driven by late-seasonal drainage and sudden reductions in mean air temperature, as well as annual variations in the configuration of the drainage system of the damming glacier. The observed fluctuations between short periods of relatively high and low drainage volumes suggest that the large GLOFs potentially weaken the ice dam causing it not to seal during winter and thus allowing the following event(s) to drain

360   at a lower water level.

This study also reports geomorphological evidence from UAV and satellite data that reveals an altering of the proglacial drainage route with a new sub- or englacial flow pathway, as well as the supraglacial flow of drainage water across the ice margin. We suggest that the new drainage route has developed as a result of thinning and retreat of the ice margin, and that further thinning will cause the new drainage route to eventually become dominant. As the new route bypasses the two buffering

365   outlet lakes the delivery of drainage water to the downstream system will be faster and less attenuated, with significant consequences for the surrounding geomorphology and the potential risk of flooding hazards.

Appendices
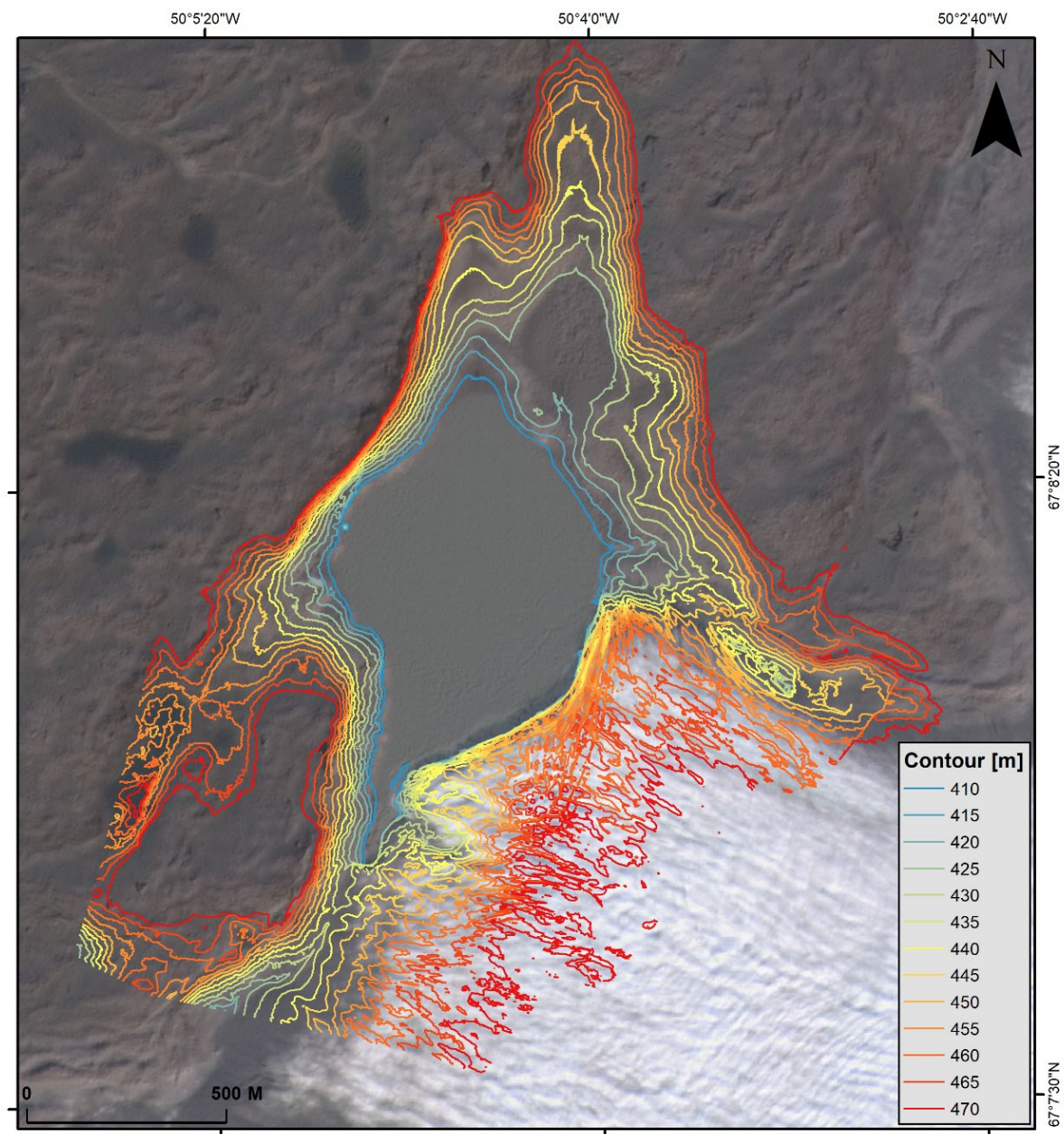
Figure A1. Contour map with 5 m intervals based on the 2021 post-drainage DEM. Background is a four band Planet (2017) acquisition from 23-8-2021.

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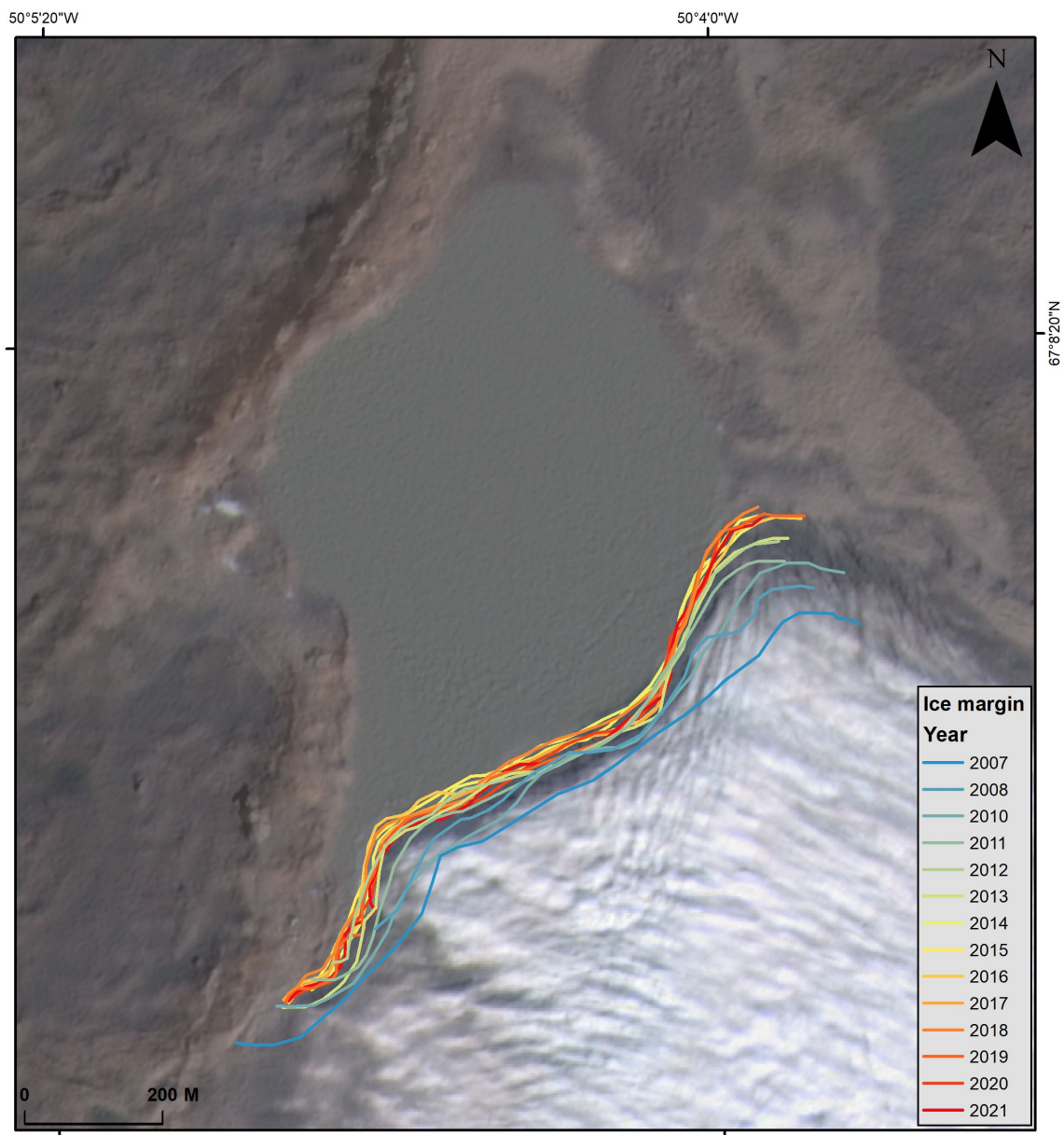
Figure A2. Position of ice margin digitized from satellite images. Background is a four band Planet (2017) acquisition from 23-8-2021.

Data availability

DEMs and orthophotos of the drained lake topography and outlet drainage route are publicly available via figshare (https://doi.org/10.6084/m9.figshare.21981731).

Author contributions

MD led the data analysis and wrote the main manuscript. MD, FH, AAB planned the study and carried out the fieldwork. KKK collected the hydrograph data and performed the hydrograph volume estimates. SAK carried out GPS data processing. JLC provided guidance on the interpretations and assessment of the drainage triggers and water rerouting. All authors contributed to the data analysis and interpretation of results and provided inputs for the manuscript.

Competing interests

The authors declare that they have no conflict of interest.

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