

Recent changes in drainage route and outburst magnitude of Russell Glacier ice-dammed lake, West Greenland

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Abstract. Glacial lake outburst floods (GLOFs) or ‘jökulhlaups’ from ice-dammed lakes are frequent in Greenland and can influence local ice dynamics, and cause bedrock displacement and geomorphological changes and as well as pose flooding hazards. Multidecadal time series of lake drainage dates, drainage-volumes and flood outlets are rare, but essential for understanding the impact on, and as well as the interaction with, the surrounding landscapes, identifying drainage mechanisms, and for mitigating downstream flood effects. In this study, we use ultra-high-resolution structure-from-motion (SfM)-digital elevation models (DEM) and orthophotos (0.1 x 0.1 m) from-generated from uncrewed unmanned-aerial vehicle (UAV) field surveys, in combination with optical satellite imagery to reconstruct robust lake volume changes associated with 14 GLOFs between 2007 and 2021 at Russell Glacier, West Greenland. As a result, this is makes it, one of the most comprehensive and longest records of ice-dammed lake drainages in Greenland to date. Importantly, we find a mean difference of ~10 % between the lake drainage volumes when compared with estimates derived from a gauged hydrograph 27 km downstream. Due to ice-dam thinning of the local ice dam, the potential maximum drainage volume in 2021 is c. 60 %-smaller than that estimated to have drained in 2007. Our time series also reveals variations in the drainage dates ranging from late May to mid-September and moreover that drained volumes range between 0.9 - 37.7 M m³. We attribute these fluctuations between short periods of relatively high and low drainage volumes to a weakening of the ice dam and an incomplete sealing of the englacial tunnel following the large GLOFs. The This syphoning drainage mechanism is triggered by a reduction in englacial meltwater, likely driven by late-seasonal drainages and sudden air temperature reductions, as well as annual variations in the glacial drainage system. Furthermore, we provide geomorphological evidence of an additional drainage route first observed following the 2021 GLOF, with a sub- or en-glacial flow pathway, and as well as supraglacial water flow across the ice margin. It seems probable that the new drainage route will become dominant in the future which will drive changes in the downstream geomorphology and raise the risk of flooding-related hazards as the existing buffering outlet lakes will be bypassed.

1 Introduction

Ice-dammed lakes can form either in supraglacial, subglacial or ice-marginal positions (Tweed and Russell, 1999)(Tweed and Russell, 1999). Globally, proglacial lakes (including ice-marginal lakes) contain up to 0.43 mm of sea level equivalent (Shugar et al., 2020)(Shugar et al., 2020) and recent studies show that ice-marginal lakes in Greenland have increased in both number and size (Carrivick and Quincey, 2014; Shugar et al., 2020)(Carrivick and Quincey, 2014; Shugar et al., 2020). More Currently, there are more than 3300 ice-marginal lakes are found in Greenland, with these predominately found estly around peripheral mountain glaciers and ice caps (PGICs), but there is also a relatively high density of ice-dammed lakes along the southwest Greenland ice sheet (GrIS) margin (Carrivick et al., 2022; How et al., 2021)(Carrivick et al., 2022; How et al., 2021). The outflow of ice-dammed lakes can vary substantially from a gradual near-steady discharge to sudden outburst floods called jökulhlaups or Glacial Lake Outburst Floods (GLOFs) (Tweed and Russell, 1999)(Tweed and Russell, 1999). Several mechanisms have been proposed for the rapid drainage of ice-dammed lakes and due to changes in lake inputs and topographic settings, drainages at the same lake may be occur in response to different trigger mechanisms (Tweed and Russell, 1999)(Tweed and Russell, 1999). Sudden drainage of water from ice-dammed lakes in Greenland can have implications on for fjord circulation (Kjeldsen et al., 2014)(Kjeldsen et al., 2014), affect local ice dynamics (e.g. Kjeldsen et al., 2017; Sugiyama et al., 2007)(e.g. Kjeldsen et al., 2017; Sugiyama et al., 2007), cause bedrock displacements (Furuya and Wahr, 2005; Kjeldsen et al., 2017)(Furuya and Wahr, 2005; Kjeldsen et al., 2017), alter downstream geomorphology (Russell et al., 2011)(Russell et al., 2011) as well as have severe societal impacts (Carrivick and Tweed, 2016)(Carrivick and Tweed, 2016). Carrivick and Tweed (2019)Carrivick and Tweed (2019) review the status of knowledge on GLOFs and ice-dammed lake drainages in Greenland and show that continuous multidecadal observations of transient lake water levels (i.e. pre- and post-drainage), lake drainage dates, and released flood volumes are extremely rare. Nevertheless, such time series are important for revealing spatio-temporal patterns in lake drainage and the flood-timings and magnitudes of flood events. Furthermore, long-term data improve our understanding of drainage triggers and mechanisms, provide important context for the scale and frequency of current and future GLOFs andas well as helps aid in the mitigation of downstream effects. The primary aim of this paper is to (re)calculate and analyse the lake water level and lake-drainage volume of 14 historical GLOFs observed from 2007 to 2021. Secondly, we investigate geomorphological changes supporting a shift in the proglacial GLOF drainage route observed following the recent GLOF on 22nd August 22, 2021.

2 Study site

One of the most intensively monitored and widely studiedintensively monitored and studied ice-dammed lakes in Greenland is located on the northern flank of Russell Glacier in West Greenland (Figure 1) (Carrivick et al., 2017; Lamsters et al., 2020; Mikkelsen et al., 2013; Russell, 1989, 2007; Russell et al., 2011)(Carrivick et al., 2017; Lamsters et al., 2020; Mikkelsen et al., 2013; Russell, 1989, 2007; Russell et al., 2011) and so it is a key site for understanding GLOFs behaviour. The lake is ~0.7 km² and drains through a c. 600 to 1000 m glacial tunnel in the southwestern part of the lake transporting water and sediment

into two outlet lakes and further afield into the Watson River (~~Carrivick et al., 2013; Carrivick et al., 2018; Mernild and Hasholt, 2009; Russell, 1989; Russell, 2007; Russell et al., 2011~~)(Carrivick et al., 2013; Carrivick et al., 2018; Mernild and Hasholt, 2009; Russell, 1989; Russell, 2007; Russell et al., 2011). Based on aerial photographs, sedimentary data and refill rates the lake drained every 2 to 3 years from the 1950s and up until 1987 where it entered a 20-year stagnant period of stable water levels (~~Carrivick et al., 2018; Russell et al., 2011~~)(Carrivick et al., 2018; Russell et al., 2011). On the 31st of August 2007 a new GLOF occurred (Russell et al., 2011) and the lake entered a new cycle of almost yearly-annual reoccurring drainage events, with the last documented event happening in 2015 (~~Carrivick et al., 2017~~)(Carrivick et al., 2017). Previous lake drainage events have ~~Drainage parameters of the lake at Russell Glacier have previously~~ been estimated using a variety of different methods such as -downstream gauged hydrographs, pressure transducers within the lake, time lapse cameras and

Global Positioning System (GPS) using differential GPS (dGPS) techniques to monitor water surface elevation (Carrivick et al., 2017; Mernild and Hasholt, 2009; Mikkelsen et al., 2013; Russell et al., 2011)(Carrivick et al., 2017; Mernild and Hasholt, 2009; Mikkelsen et al., 2013; Russell et al., 2011).

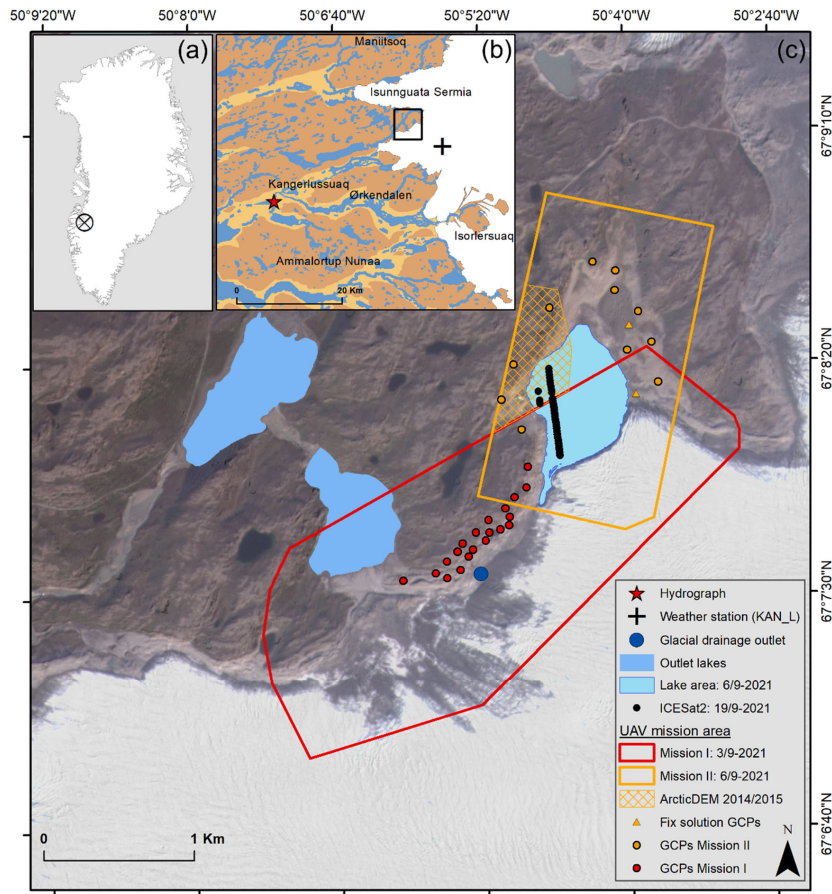
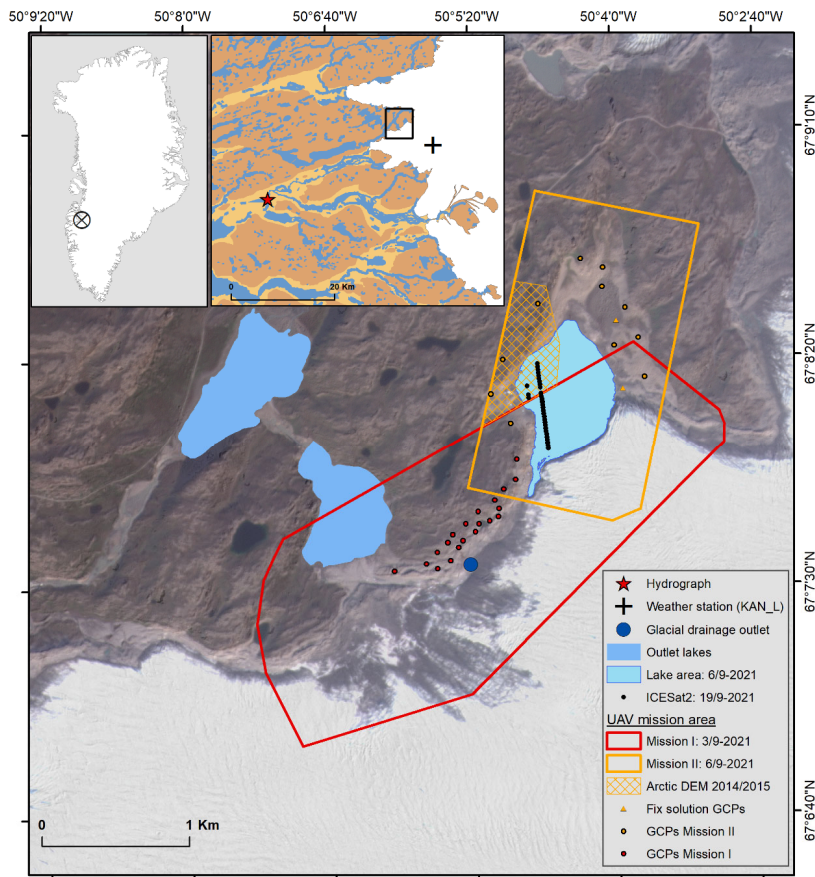


Figure 1. A) Study site location in Greenland. B) Zoom in on study site with location of hydrograph and Promice weather station. C) and UAV mission area I and II with location of GCPs overlaid on a four band Planet (2017) acquisition from 23/8-2021. The yellow triangles illustrate the only two reliable fix solution GCPs. Due to image gaps at the western part of the lake the produced UAV DEM is filled with elevation data from two ArcticDEMs acquired on the 19/9-2014 and 2/8-2015.



3 Methods and data

Fieldwork at Russell Glacier was carried out between the 3rd and 6th of September 2021, two weeks after a GLOF on 22nd August 2021. Two UAV missions were ~~conducted-undertaken~~ to produce DEMs and orthophotos of the drained lake basin topography, ice margin and the outlet and flood drainage route (Figure 1). As the lake did not fully drain we were ~~unet-able~~ to ~~capture-survey~~ the entire ~~drained~~ lake topography, ~~however, a~~ A minimum standing water level of 408.8 m₋ was surveyed

in the lake, which is almost identical to the minimum lake levels observed after other previous GLOF events (Russell et al., 2011). Russell et al. (2011) produced a DEM of the lake basin bathymetry made from interpolation of kinematic dGPS tracks surveyed in February 2008, with finding a minimum elevation of 410 m. In this study, our UAV mission surveys enabled a highly accurate and ultra-high-resolution DEM without surface interpolation. From the refined UAV-derived DEM, we are able to precisely estimate the pre- and post-GLOF water level, the lake area and the likely lake drainage volume of both historical and future events. All elevations are reported as height above the WGS84 ellipsoid, unless otherwise stated.

3.1 Aerial surveys

The UAV flights were conducted on two different dates using two different UAVs, due to the battery capacity and weather conditions (Table 1, Figure 1):

Table 1 Overview of the two UAV mission. *Parentheses indicate the number of GCPs with a fixed GNSS solution.

Both UAVs have an onboard post-processed kinematic (PPK) direct georeferencing capabilities provided by an on-board GNSS receiver (Table 1), which records the logging position-positional data of each image as at the time of image it is captured

UAV Mission	Flight date	UAV type	Flight mode	Images captured	Covered area (km ²)	Camera position accuracy (m)		Resolution (m)		Number of GCPs*	RMSE camera location (m)		
						Vertical	Horizontal	DEM	Ortho		X	Y	Z
Mission I	03-09-2021	Fixed-wing, WingtraOne w. multi-frequency L1/L2 GNSS receiver	Automatic	1106, nadir (60% overlap)	4.3	0.06	0.09	0.1	0.04	20 (0)	0.01	0.01	0.02
Mission II	06-09-2021	Quadcopter, DJI Phantom 4 Pro w. KlauPPK 7700C GNSS receiver	Manual	563, oblique and nadir	2.39	0.06	0.09	0.1	0.1	13 (2)	0.28	0.32	0.14

acquisition. To achieve centimetre-level accuracy in both the vertical and horizontal direction of the camera positions, we kinematically post-processed the positional data from the UAV GNSS receivers. Compared to real-time kinematic (RTK) correction, post-processed kinematic (PPK) positioning is considered more accurate and does not depend on a reliable real-time connection to a GNSS base station (Chudley et al., 2019). The UAV GNSS data was post-processed using WingtraHub (v. 2.2.0) and KlauPPK (v. 7.17) software relative to the fixed Greenland GPS Network (GNET) base station, located in Kangerlussuaq (KLSQ) approx. 30 km from the field site (Bevis et al., 2012). The processed camera position for both UAV surveys had a vertical and horizontal accuracy of c. 0.09 m and 0.06 m, respectively (Table 1).

This gives absolute centimeter-level accuracies in both the vertical and horizontal direction and removes the need for ground control points (GCPs) (Chudley et al., 2019). The UAV PPK data was post-processed using WingtraHub (v. 2.2.0) and KlauPPK (v. 7.17) software. We used base station data from the fixed Greenland GNSS Network (GNET) station located in

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Kangerlussuaq (KLSQ) approx. 30 km from the field site (Bevis et al., 2012). The processed camera position has a vertical and horizontal accuracy of c. 0.09 m and 0.06 m, respectively.

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For the purpose of validating the accuracy of the produced DEMs we placed a combined total of 33, 0.3 x 0.3 m black and white, ground control points (GCPs) in each study area and measured their position using an Emlid Reach RS2 GPS-GNSS receiver (Table 1). We post-processed the log files from the Emlid rover using Emlid Studio (v. 1.3) software and the KLSQ base station data. Due to poor satellite reception and cycle slips we were only able to retrieve reliable fix solution position results for 0/20 and 2/13 GCPs in Mission I and Mission II, respectively (Table 1, Figure 1).

3.2 Development and validation of DEMs and orthophotos

The UAV images were processed using a structure-from-motion (SfM) workflow in Agisoft Metashape Pro. (v. 1.7.4). We follow the general processing workflow described in the official Agisoft guidelines (Agisoft LLC, 2020)(Agisoft LLC, 2020). The camera calibration is was set as 'precalibrated' and the calibration parameters are set according to the calibration report of the used camera. Instead of GCPs, we used the post-processed, geolocated camera positions are used as input instead of GCPs to georeference the point cloud. During the bundle adjustment, we performed a refined camera calibration, which is recommended when other variables are well constrained (Chudley et al., 2019)(Chudley et al., 2019). DEMs and orthomosaics for Mission I were then exported at resolutions of 0.1 and 0.04 m, respectively, while for Mission II both were exported at a resolution of 0.1 m (Table 1). During the bundle adjustment, we perform a refined camera calibration, which is recommended when other variables are well constrained (Chudley et al., 2019). Mission I DEM and orthophoto have a resolution of 0.1 x 0.1 m and 0.036 x 0.036 m, respectively. The Mission II DEM and orthophoto both have a resolution of 0.1 x 0.1 m (table 1). The RMSE of the X, Y and Z camera location, as reported in Agisoft Metashape after model generation, is 0.01, 0.01, and 0.02 m for Mission I and 0.28, 0.32, and 0.14 m for Mission II (Table 1). The large RMSE values of Mission II, likely originate from strong wind conditions at the time of surveying, which may have caused the UAV to tilt or move slightly during image acquisition. In combination with the manual flight mode, this may have resulted in a lowered image quality and a poor image overlap in specific regions, such as at the western part of the lake (Figure 1). Furthermore, the majority of the acquired images have an oblique view angle, which makes them computationally challenging compared to nadir images, due to geometric and photometric deformations caused by varying perspective and illumination (Jiang et al., 2020).

Previous studies, using a similar setup and approach (Chudley et al., 2019; Jouvet et al., 2019), reported horizontal and vertical uncertainties in the range of 0.1 – 0.4 m, without the use of GCPs. Based on the By measuring the horizontal and vertical displacement between the two fix solution -GCPs and their observed location in the Mission II orthomosaic and DEM, we estimated the accuracy to we were only able to estimate the accuracy of the Mission II DEM, which is found to be xy = 0.14 m and z = 0.35 m, respectively. Due to a lack of reliable GCPs, we applied an additional method for determining the uncertainty. Inspired by similar studies (Chudley et al., 2019; Jouvet et al., 2019), we estimated the uncertainty by calculating

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the relative offset between the Mission I and Mission II DEM over stable bedrock, assuming no change in the topography. We applied the python module PyBob (McNabb, 2019) based on the co-registration method developed by Nuth and Kääb (2011), which determines the X,Y and Z offset from elevation difference residuals as well as the terrain's aspect and slope. The co-registration was based on >8 million pixels extracted from two areas of overlapping bedrock located on both the western and eastern part of lake. Using the Mission I DEM as the reference, we found a relative offset of X = -0.43 m, Y = 0.11 m and Z = 0.53 m and adopted this as our main measure of uncertainty. By applying this offset to the Mission II DEM, we were able to reduce the mean elevation difference and RMSE over stable bedrock from 0.39 m to 0.00 m and 0.42 m to 0.17 m, respectively. Following co-registration, we mosaicked the Mission I and Mission II DEM.

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Due to image gaps at the western part of the lake, we were not able to produce a complete UAV-derived DEM of the drained lake topography. Thus, the missing parts-regions were filled with elevation measurements-data from two Arctic-DEM strips captured-acquired on the 19th of September 2014 and the 2nd of August 2015 and 19th of September 2014, respectively (Figure 1). At the time of acquisition, both Arctic DEMs had a water level of approx. 407 m. The Arctic-DEM strips have a resolution of 2 x 2 m and are based on photogrammetric processing of Worldview stereo-image pairs (Noh and Howat, 2015)(Noh and Howat, 2015). At the time of acquisition, both Arctic DEMs had a standing water level of approx. 407 m. We predominately mainly-utilised the 2015 DEM strip as it was produced from using images acquired only five days after the 2015 drainage event, however, the 2015 DEM strip also contained a few areas with no data several data gaps, which we consequently we filled these with values from using the 2014 DEM, which was strip-produced from images using images captured-acquired 47 days after the 2014 drainage event. Prior to mosaicking, all DEMs were resampled to 0.1 m resolution and co-registered over solid bedrock using the python module PyBob (McNabb, 2019).

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-based-on-the-method-developed-by-Nuth-and-Kääb-(2011). Using the co-registered DEM mosaic, as well as the Mission II orthomosaic, we digitised lake area and extracted elevation points every 5 m along the digitised eastern lake margin to estimate a water level of $408.8 \text{ m} \pm 0.35$ on the 6th September 2021. Using the mosaic of Mission II DEM and ArcticDEM as well as the Mission II orthophoto we digitize the lake area and estimate the water level on 6th September 2021 to $408.8 \text{ m} \pm 0.35$, by extracting the elevation of points every 5 m along the digitized waterline at the eastern part of the lake. Finally, all elevation data within the lake area were changed to 408.8 m to avoid erroneous elevation estimates on the water surface. From herein the final mosaicked and lake-burned DEM will be referred to as the 2021 post-drainage DEM. We validated the estimated water level by comparing it to 33 ICESat2 data points from 19th September 2021 measured at the interior of the lake (Figure 1). The ICESat2 points have a mean water level of 408.70 m and a STD of 0.02 m.

3.3 Estimation of water level, lake area and drainage volume

To estimate the lake water level at different ~~timestamps~~ temporal intervals we used satellite images from Planet scope, Landsat 7 and 8 and Sentinel-2. The satellite images were manually georeferenced to the high-resolution UAV orthophotos to adjust for small offsets. Inspired by the approach of previous studies (e.g. Carrivick and Tweed, 2019)(Carrivick and Tweed, 2019) the pre- and post-drainage water level ~~is~~ was determined by manually placing 30 points along the ~~~600 m waterline on the eastern part of the lake's waterline~~ as observed on the satellite images. ~~The points were placed with an approximate spacing of 20 m, however, varying depending on the visibility of the waterline as well as from avoiding areas with apparent morphological changes, and then extracting the elevation at these points from the produced 2021 post-drainage DEM.~~ The eastern part ~~is~~ was chosen as it only contains high-resolution (0.1 x 0.1 m) UAV-derived elevation pixels as well as having a flat slope compared to the steep terrain in the west (Figure A1). ~~For each of the 30 points, we extracted the elevation from the 2021 post-drainage DEM and Based on the 30 elevation points we calculated~~ the mean water level ~~and as well as~~ the standard deviation indicating the uncertainty of the elevation estimate (Table 2). The mean water level ~~is~~ was used to estimate the lake outline and area by masking out pixels above the mean water level as well as removing depressions not linked to the existing lake area. Using the estimated lake area and the 2021 post-drainage DEM we calculated the pre- and post-drainage water volumes using Eq. (1):

$$\sum_{i=1}^n (\mu_{wl} - P_{elev_i}) * P_{width_i} * P_{height_i}, \quad (1)$$

where n denotes all pixels within the lake area, μ_{wl} the mean water level, P_{elev_i} the elevation of the pixel and P_{width_i} and P_{height_i} the pixel resolution, which is 0.1 x 0.1 m. The total lake area change and water volume release of every GLOF ~~is~~ was determined by ~~simply~~ extracting the pre and post-drainage estimates (Table 2). As area and volume estimates ~~are~~ were calculated relative to the 6th of September 2021 when images for the 2021 post-drainage DEM were acquired, they are sensitive to changes in the position of the ice margin. From 2007 to 2011 we ~~have~~ observed a gradual advance of the margin, while ~~after from 2011 onwards the front has been~~ it remained relatively stable with ~~just only~~ slight changes in frontal position observed (Figure A2). ~~To accommodate for the influence of the observed frontal advances from 2007 to 2011 we recalculated the lake area and volume changes of those years. For each year, we manually adjusted the lake area to match with the position of the ice margin, as observed in the respective satellite image, and then recalculated the volume change of the adjusted lake area based to the estimated pre- and post-drainage level. Thus, we adjust both the lake area and drainage volumes from 2007 to 2011 by manually expanding the lake area to match the position of the ice margin and assuming a similar water level change of the entire added area corresponding to the estimated pre- and post-drainage level.~~

All drainage estimates from 2017-2021 are based on Planet scope satellite images, whereas estimates of previous events are based on mainly panchromatic images from Landsat 7 and 8 with a resolution of 15 m as well as RGB images from Sentinel-2 with a resolution of 10 m (Table 2). In contrast to the ~~relatively coarse low~~ (10 and 16 days) temporal coverage of the Landsat and Sentinel images, Planet images not only have a much ~~better~~ finer spatial resolution of 3 m, but also a temporal

205 resolution of approximately 1 day (Planet, 2017), enabling detection of ~~sudden changes~~short-term changes in water level, albeit during clear-sky conditions.

3.4 Drainage routes

210 Based on the Mission I-~~derived~~ DEM we determined~~d~~ the main surface drainage routes for the 2021 GLOF event from the glacial drainage outlet~~the GLOF drainage water running from the glacial drainage outlet~~ to (i) the outlet lakes and (ii) across the ice margin. The drainages routes ~~are-were~~ calculated as the paths of least resistance from the source (drainage outlet) to the locations (i) and (ii)~~destinations (i and ii)~~ assuming that water is flowing to the neighbouring pixel with the lowest elevation. The calculations ~~are-were~~ based on a 2 x 2 m resampled version of the DEM to ~~even-out~~limit locale elevation maxima from small surface features such as rocks and ice blocks that ~~could~~ potentially ~~hinders~~influence the water flow. Finally, we generated points every two meters along both of the estimated drainage routes and extracted the underlying elevations to determine ~~each routes maximum elevation~~the maximum elevation of each route.

3.5 Hydrograph volume estimation

220 We estimated the drainage volume from a hydrograph station deployed in Watson River at Kangerlussuaq, 27 km downstream of the lake (van As et al., 2017)~~(van As et al., 2017)~~. Here pressure transducers record changes in water pressure, which subsequently is corrected for atmospheric pressure before being converted into hourly averages in water ~~stage~~level. Water discharge ~~is-was the~~ obtained using a rating curve, based on discharge measurements at various water levels, and is ~~an~~ associated with a conservative uncertainty value of 15 %. Due to diurnal fluctuation in discharge, ~~induced by melting of the vast ice coverage in the catchment~~, we estimated the daily minima and maxima on the day of the drainage event, by fitting linear trend through the equivalent low and high stage values on the day before and after. This allowed estimates of the baseflow and thus estimates of the volume associated with lake drainage to be made.

3.6 Temperature data

225 ~~The Air~~ temperature ~~data record-was~~is obtained from the KAN_L ~~a~~Automatic Wweather ~~S~~station, ~~which is~~ part of the PROMICE AWS network, ~~and which~~ is located on the ice sheet ~~proper~~ at 670 m asl, 18.5 km from the study site. We use hourly average data that is based on measurements recorded every 10 min (Fausto et al., 2021; GEUS Dataverse n.d.)~~Fausto et al., 2021; GEUS Dataverse n.d.~~; For each of the analysed periods, the air temperature data contained no missing values.

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230 4 Results

4.1 Drainage volumes

Figure 2 shows illustrates how the lake volume and area change with variations in the water level, as calculated based on the 2021 post-drainage DEM. The lake has a theoretical maximum water level of 433 m, after which water overflows the ice dam, hereby indicating the elevation of the damming glacier. The lake has a theoretical maximum water level of 433 m, after which water overflows the ice dam. The 2021 theoretical water level maximum produces a lake surface area of 0.79 km² and a maximum drainage volume of 14.3 M m³, which is a 63 % decrease compared to the actual estimated drainage volume of the 2007 GLOF (Table 2). Moreover, we compared the theoretical maximum water level to the estimated 2007 pre-drainage water level of 453.1 m, and found an ice dam lowering of at least 20.1 m. We were able to determine a theoretical maximum water level of 450 m from the 2015 ArcticDEM, which was 17 m higher than the 2021 level. Based on the present configuration of the lake and ice margin, the lake is not able to reach the 2007 maximum level as it would drain through the

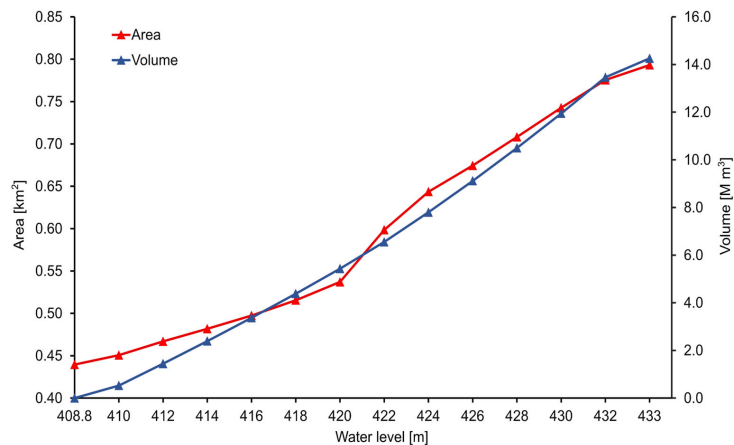
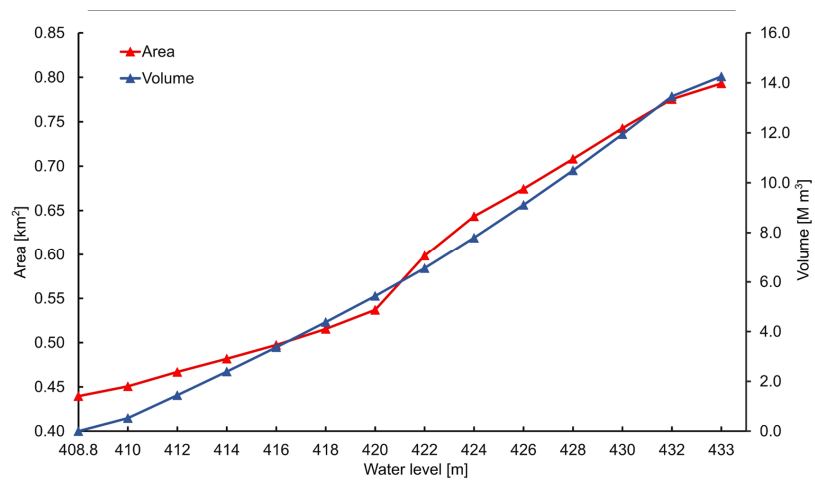


Figure 2. Relationship between water level and area (km²) and lake water level and volume (M m³) with changing water level (m), calculated for every second meter, based on the 2021 post-drainage DEM. The lake has a theoretical maximum water level of 433 m after which it overflows the damming glacier. The sharp increase in lake area from ~420 m to 422 m is due to a plateau at the glacial conduit at a lower level.

To accommodate a higher water level associated with the situation in 2007, we manually adjust the ice margin and thus the resulting volume. Based on the present configuration of the lake and ice margin, the lake would likely never reach the 2007 maximum level as it would drain through the glacial conduit at a lower level. Moreover, we regard the theoretical maximum as a proxy for the thickness of the ice dam. From the 2015 ArcticDEM strip we determine a theoretical maximum water level of 450 m, giving a total lowering of 17 m compared to 2021.



4.2 Drainage cycles

Since the lake entered its new drainage cycle in 2007 we observe yearly-annually reoccurring events, with the exception of 2009. The 2007 GLOF had the largest observed drainage volume, with a release of value of $37.73 \pm 1.08 \text{ M m}^3$ recorded (Table 2 and Figure 3), yet a year later in 2008 the volume release was four times lower, at just $9.4 \pm 1.46 \text{ M m}^3$. No drainage was observed in 2009, but in contrast, in 2010 the release-drainage volume once again returned to a higher level, with was much larger again at $26.08 \pm 2.54 \text{ M m}^3$ recorded. In Over the following three years (2011 to 2013) the drainage volume released was remained relatively stable at between 7 and 9 M m^3 , before decreasing to whereas the 2014 and 2015 outburst volume decreased to $\sim 4 \text{ M m}^3$ in 2014 and 2015, after which a threefold-times-increase occurred to 12.5 M m^3 was observed in 2016. In both 2017 and 2020, we have reconstructed small, partial drainage events of just 2.7 and 0.9 M m^3 , respectively (Table 2 and Figure 3). These two events occurred earlier in the melt season in comparisoned to any previous drainage events, with the 2020 event happening-occurring already by-on the 31st of May. In the years following after the occurrence of these observed partial drainage, i.e. in 2018 and 2021, the observed GLOFs then-occurred relatively late in the melt season, and with volumes of 8.5 and 9 M m^3 recorded, respectively (Table 2 and Figure 3). In general, the lake seems to fluctuate between short periods of relatively high and low drainage volumes, with the low volume GLOFs happening-occurring earlier in the melt season.

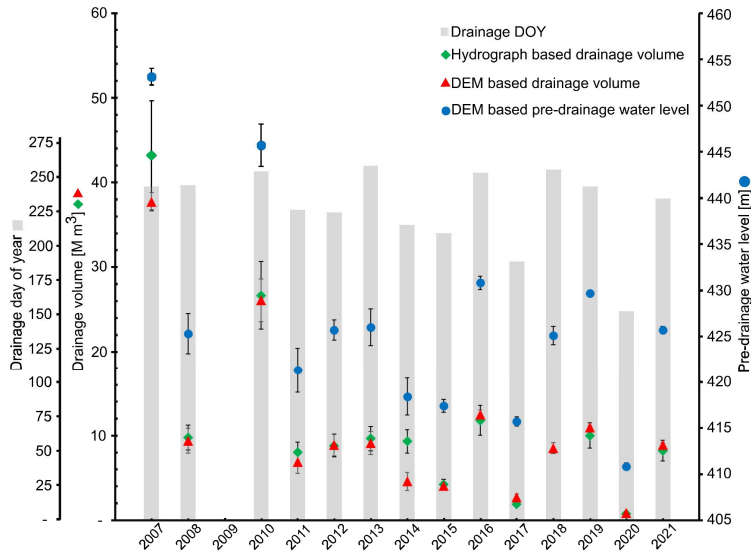


Figure 3. Pre-drainage water level, drainage volume and drainage day of year (DOY) for 14 GLOFs spanning 2007 to 2021. Pre-drainage water levels (blue circles) are and drainage volume is reconstructed/estimated based on the using the 2021 post-drainage DEM. Drainage volumes are estimated using both the 2021 post-drainage DEM (red triangles) and downstream hydrograph observations (green squares). DEM method and drainage volume from hydrograph methods. The grey

However, ~~the~~ a later occurrence of these drainage events~~date~~ is not always equivalent to a larger drainage volume, as evidenced ~~in~~ 2018 and 2019.

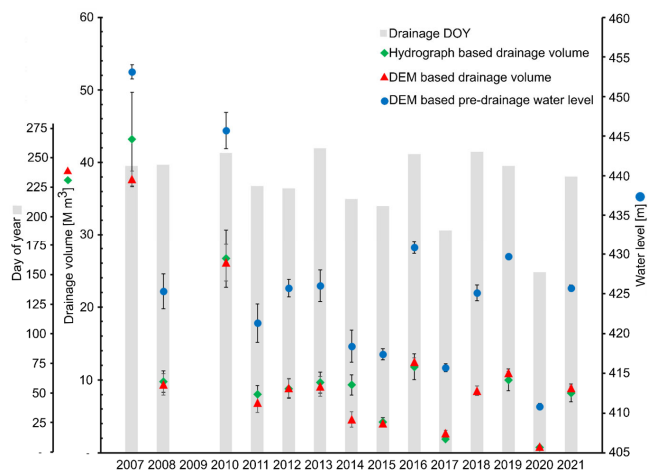
Table 2. Drainage dates, pre- and post-drainage water levels, lake areas, and volumes estimate for 15 GLOFs spanning 1987 to 2021. The 1987 estimates are adopted from Russell et al., 2011. The 2007 to 2021 estimates are reconstructed using from DEM method the 2021 post-drainage DEM in combination with selected optical satellite images as well as –as well as volume estimates from downstream hydrograph method observations. The Table includes references to previous studies of the lake, including estimated drainage volumes.

Drainage dates	Water level (m)		Lake area (km ²)		Area change (km ²)	Volume relative to 6th Sept. 2021 (M m ³)		Lake volume release (M m ³)	Source	Volume from hydrograph (M m ³)	Other references and volume estimates (M m ³)
	Pre drain	Post drain	Pre drain	Post drain		Pre drain	Post drain				
17-19. July 1987	450.8	402.5	-	-	-	-	-	31.3	Russell et al., 2011.	-	Russell 2007; Russell 1989
31. Aug. 2007	453.1 ± 0.9	< 408.8	1.308* ± 0.022	0.475* ± 0.007	0.833 ± 0.023	37.73** ± 1.08	0***	37.73 ± 1.08	This study (Landsat 7)	43.19 ± 6.47	Russell et al. 2011 (39.1 ± 0.8) Mikkelsen et al. 2013 (25.5) Mernild & Hasholt 2009 (11.3)
31. Aug. 2008	425.3 ± 2.2	< 408.8	0.710* ± 0.037	0.435* ± 0.008	0.275 ± 0.038	9.40** ± 1.46	0***	9.40 ± 1.46	This study (Landsat 7)	9.75 ± 1.46	Russell et al 2011 (12.9 ± 0.3) Mikkelsen et al. 2013 (3.6) Mernild & Hasholt 2009 (4.6)
11. Sept. 2010	445.7 ± 2.3	410.4 ± 1.3	1.051* ± 0.092	0.495* ± 0.013	0.556 ± 0.093	27.26** ± 2.33	1.18** ± 1.02	26.08 ± 2.54	This study (Landsat 7)	26.66 ± 4.00	Carrivick 2017 (30.7) Mikkelsen et al. 2013 (8.4)
14. Aug. 2011	421.3 ± 2.4	< 408.8	0.583* ± 0.057	0.413* ± 0.007	0.170 ± 0.057	6.90** ± 1.38	0***	6.90 ± 1.38	This study (Landsat 7)	8.02 ± 1.20	Carrivick et al. 2017 (No vol.)
11. Aug. 2012	425.7 ± 1.1	< 408.8	0.670 ± 0.018	0.404* ± 0.008	0.266 ± 0.020	8.91 ± 1.29	0***	8.91 ± 1.29	This study (Landsat 7)	8.81 ± 1.32	Carrivick et al. 2017 (25.5)
15. Sept. 2013	426.0 ± 2.0	< 408.8	0.674 ± 0.031	0.413* ± 0.007	0.261 ± 0.032	9.12 ± 1.35	0***	9.12 ± 1.35	This study (Landsat 8)	9.65 ± 1.45	-
3. Aug. 2014	418.4 ± 2.0	< 408.8	0.519 ± 0.021	0.410* ± 0.007	0.109 ± 0.028	4.59 ± 1.04	0***	4.59 ± 1.04	This study (Landsat 8)	9.31 ± 1.40	Carrivick et al. 2017 (8.0)
28. July 2015	417.4 ± 0.7	< 408.8	0.510 ± 0.006	0.411* ± 0.007	0.099 ± 0.009	4.07 ± 0.36	0***	4.07 ± 0.36	This study (Landsat 8)	4.22 ± 0.63	Carrivick et al. 2017 (7.5)
8. Sept. 2016	430.8 ± 0.7	408.9 ± 0.3	0.748* ± 0.01	0.441 ± 0.003	0.307 ± 0.010	12.53 ± 0.51	0.04 ± 0.08	12.49 ± 0.52	This study (Sentinel-2)	11.78 ± 1.77	-
7. July 2017	415.7 ± 0.5	410 ± 0.7	0.495 ± 0.004	0.451 ± 0.006	0.044 ± 0.007	3.22 ± 0.25	0.53 ± 0.32	2.69 ± 0.41	This study (Planet)	1.89 ± 0.28	-
12-13. Sept. 2018	425.1 ± 1.0	< 408.8	0.661 ± 0.015	0.440* ± 0.007	0.221 ± 0.017	8.51 ± 0.66	0***	8.51 ± 0.66	This study (Planet)	No data	-
31. Aug. 2019	429.7 ± 0.2	410.5 ± 0.3	0.732* ± 0.002	0.455 ± 0.002	0.277 ± 0.003	11.71 ± 0.15	0.75 ± 0.14	10.96 ± 0.21	This study (Planet)	10.00 ± 1.50	-
31. May 2020	410.8 ± 0.4	< 408.8	0.457 ± 0.003	0.428* ± 0.007	0.029 ± 0.08	0.89 ± 0.18	0***	0.89 ± 0.18	This study (Planet)	0.75 ± 0.11	-
22. Aug. 2021	425.7 ± 0.4	< 408.8	0.670 ± 0.006	0.438* ± 0.007	0.232 ± 0.009	8.91 ± 0.27	0***	8.91 ± 0.27	This study (Planet + UAV ortho)	8.22 ± 1.23	-

* Areas have been manually edited. From 2007 to 2011 to compensate for changes at the ice margin. Pre drain 2016 and 2019, to avoid water extending on the ice margin. Post drain 2012-2015, 2018 and 2020-2021 as the water level was observed to be lower than the reference DEM minimum of 408.8 m

**Volumes adjusted to compensate for changes observed at the ice margin.

***Post drain volume set to 0. As the post drainage lake area in 2007, 2008, 2011-2015, 2018, 2020, 2021 is almost identical to that of the reference area (0.439 km²) the volumes are assumed to be almost identical.



4.3 Geomorphology of glacial surface features of the drainage area

Figure 4A and 4B show-illustrates the two main drainage-routes of drainage for the r-the GLOF event to exit drainage-water exiting the glacial the drainage outlet. Drainage route I channels the water into an ephemeral river channel a proglacial passage and further into into two outlet lakes connected to the downstream river network. In contrast, in D drainage route II leads-the water flows across the ice margin and into an ice-marginal meltwater drainage system before reaching the river network, thus bypassing the two outlet lakes. There is a 0.4 m elevation difference between the drainage threshold of drainage route I (390.2m) and drainage route II (390.6m) (Figure 4B).

The 0.1 m resolution image in Fig. 4B is generated based on the Mission I derived DEM and shows the drainage area following the 2021 GLOF.

The ultra-high-resolution of the orthomosaic and DEM produced from through UAV Mission I hillshade, DEM, and orthophoto have enabled-allows us to observe a number of important geomorphological features across the drainage region which are not visible in the 3m high-resolution Planet satellite-imagesry-(3-m). As evidentFor example, large blocks of ice up to 5-m x 5 m in length are observed scattered along-across both drainage route I and II (Figure 4B, 4C and 4D). On the western part of the ice margin we observe a c. 100 m x 100 m area where the ice surface is fractured and broken (Figure 4F). The ice margin also contains 0.5 m to 3 m wide, parallel, eireular-eracksfractures (Figure 4G and 4H) that run up to several hundred meters in an interrupted, circular pattern (Figure 4B, 4G, 4H), as well as five water-escape-roughly circular and nearly vertical holes with a diameter of c. 10 m (Figure 4E). Finally, Observations of the ice margin and drainage outlet position in both 2015 and 2021 indicate positions-of the ice margin and glacial drainage outlet show a retreat of 30 m and 60 m retreatin this period, respectively (Figure 4B).

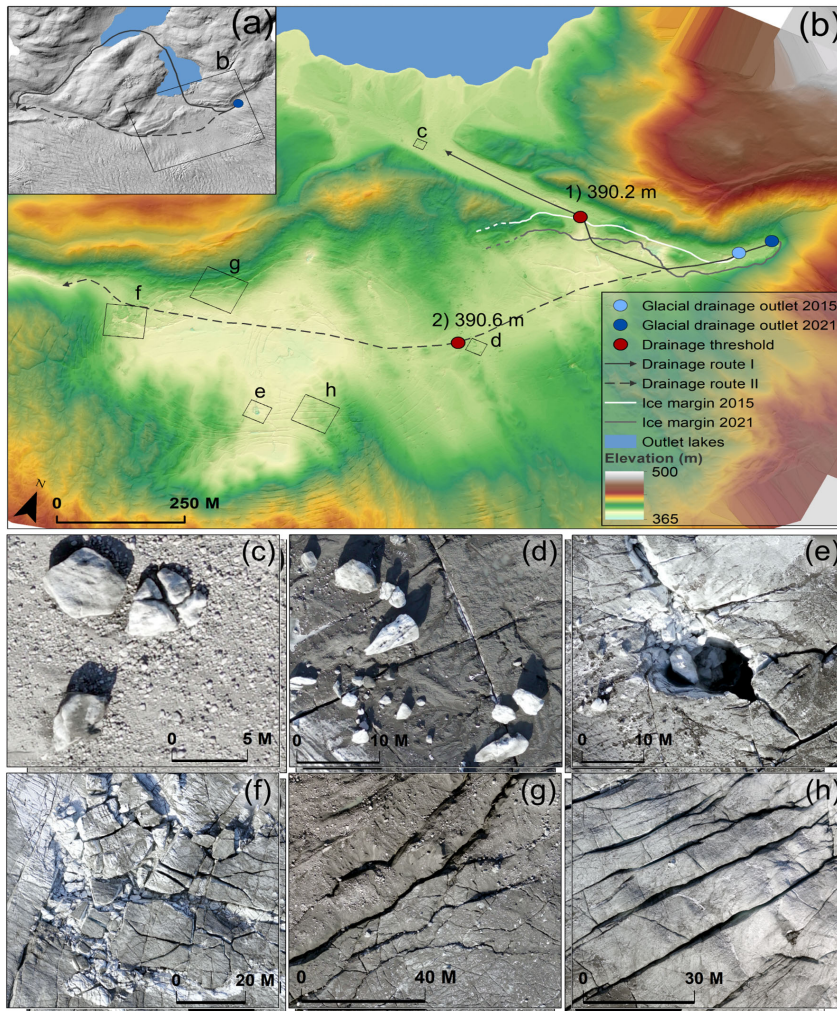


Figure 4. A) Overview of drainage route I and II overlaid on a hillshade based on the ArcticDEM from 2015. Box indicates the region illustrated in panel b) (with a marked zoom-in of area b). B) Color-coded hillshade image of the post drainage terrain where the water exits the glacial drainage outlet, based on the 2021 0.1 x 0.1 m Wingtra DEM, produced from the Mission I DEM, highlighting where the water exits the glacial drainage outlet. The drainage thresholds show indicate the highest elevation points along the drainage routes. The 2015 and 2021 ice margins are digitized based on the ArcticDEM and Mission I derived DEM, respectively. C) and D) Ice blocks deposited along the two drainage routes, up to 5 x 5 m in size/length. E) Roughly circular and nearly vertical holes (water-escape holes), ~10 m in diameter, with. There

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5 Discussion

5.1 Drainage volume estimates

300 For all GLOFs except 2014, the DEM and hydrograph based methods produce volume estimates ~~that are located~~ within each
other's margins of error (Table 2, Figure 3) with a total mean difference of 10-% ~~(excluding the 2014 event)~~. This ~~underlines~~
~~indicates~~ that the two methods ~~used~~ to obtain drain~~aged~~ volumes ~~can~~ serve as independent validation for one another. For the
2014 GLOF the hydrograph estimate is greater; two times as large as the DEM-derived volume. This could partly be ~~due~~
~~because~~ ~~to~~ the cloud-free Landsat 8 images captured closest to the drainage date on ~~3rd August 3 2014 is was acquired from~~
305 ~~July 21 2014~~, 13 days prior to the GLOF, ~~on the 21st July~~. Using the max 2010-inflow rate of $1.3 \text{ m}^3 \text{ s}^{-1}$ ~~(Russell et al.,~~
~~2011)(Russell et al., 2011)~~, the lake volume would increase by approx. 1.5 M m^3 , which is still 3.2 M m^3 lower than the
hydrograph estimate. However, based on a comparison between the 2010 and 2014 July temperature at KAN_L the actual
inflow rate is likely smaller, leaving the discrepancy between the two estimates even larger. It has been suggested that GLOFs
can trigger additional release of meltwater from englacial storages or due to frictional melting ~~(Huss et al., 2007; Mernild and~~
310 ~~Hasholt, 2009)(Huss et al., 2007; Mernild and Hasholt, 2009)~~. This would show as larger hydrograph estimates and could
explain the 2014 volume difference. However, as all remaining GLOFs present no evidence of additional water release, it is
considered unlikely. Moreover, we find no evidence ~~that any of the other proglacial lakes changes in lake area of any of the~~
~~proglacial lakes~~ in the system ~~have undergone a change in their area, which that could would~~ indicate changes in the water
storage, and ~~therefore as such~~ the 2014 event remains ~~unreconciled~~unquantified. In years with an early drainage date and a
315 ~~low drainage volume (2014, 2015, 2017, 2020), we checked for additional late seasonal drainage events by manually going~~
~~through satellite images starting from the observed drainage date to the end of the melt season.~~

When the lake drains below the 2021 post-drainage DEM reference elevation of 408.8 m (2007, 2008, 2011-2015, 2018, 2020,
2021) we underestimate the volume release, as we cannot measure the precise post drainage water level. As annual differences
320 in the post-drainage area are minimal (Table 2), the changes in volume are also expected to be limited. Additionally, the total
lake area during these instances is at its minimum. ~~Russell et al., (2011)Russell et al., (2011)~~ reported the post drainage water
level of the 2007 event to be 404.5 m, which is 3.34 m lower than our 2021 reference minimum. Assuming that the entire 2007
post-drain area (Table 2) is lowered by an additional 3.34 m, it would give an extra volume release of 1.59 M m^3 corresponding
to a 4-% increase from 37.73 M m^3 to 39.32 M m^3 . ~~Russell et al., (2011)Russell et al., (2011)~~ estimated the volume of the 2007
325 event to be 39.1 M m^3 . ~~Mernild & Hasholt (2009) and Mikkelsen et al., (2013)Mernild & Hasholt (2009) and Mikkelsen et al.,~~
~~(2013)~~ find much lower drainage volumes for the 2007 GLOF of 25.5 M m^3 and 11.3 M m^3 , respectively (Table 2), however,
these estimates are based on obsolete stage-discharge relations ~~(van As et al., 2017)(van As et al., 2017)~~. A similar pattern of
matching and conflicting volume estimates is identified for other previous GLOFs (i.e, 2008, 2010, 2012, 2014, 2015 in Table
2), both ~~aeross-in~~ existing studies as well as ~~when~~ compared to the reconstructed volumes ~~presented in~~of this study. This ~~shows~~

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330 ~~highlights~~ the challenges related to reconstructing drainage volumes, and stresses the need for consistent methodological estimates ~~for to allow for~~ better comparisons of ~~yearly annual changes in the drainage parameters~~ variations to be made.

5.2 Drainage trigger mechanisms and controls

With the documentation of seven new, and ~~the~~ re-calculation of seven known GLOFs ~~which show~~ showing variations in timing and magnitude, we are now able to re-evaluate ~~the~~ proposed drainage triggering mechanisms. Previous studies have suggested ~~various several different trigger~~ mechanisms ~~that~~ controlling the GLOFs at Russell Glacier, such as flotation of the ice dam (Carrivick et al., 2017)(Carrivick et al., 2017), fluctuation in subglacial meltwater (Russell & de Jong, 1988; Russell, 1989)(Russell & de Jong, 1988; Russell, 1989), incomplete resealing of the subglacial conduit (Russell et al., 2011), and subglacial drainage through an incised bedrock-walled Nye channel (Russell et al., 2011)(Russell et al., 2011). Recent data from ground penetrating radar ~~surveys, however,~~ revealed no evidence of ~~any~~ Nye channel incised into the bedrock, but instead found evidence of at least one englacial tunnel running parallel to the ice margin (Lamsters et al., 2020)(Lamsters et al., 2020). Had the lake been draining due to flotation of the ice dam we would expect to see a gradual decrease in the release volume and pre-drainage water level as less water is required to float the thinning ice dam. We do observe a lower drainage volume compared to the 2007 and 2010 maximum, but the lake is still able to drain at ~~both~~ similar and higher water levels than observed in 2008 (Figure 3, Table 2). The two largest GLOFs (i.e. 2007 and 2010) both occurred following ~~a~~ years of no drainage, ~~s~~ and indicate that in order for the lake to reach such ~~a~~ high-water level an additional (or multiple) melting season is required. However, due to ~~the~~ thinning of the damming glacier the lake is ~~not-un~~able to reach its previous peak drainage water level and volume ~~that was~~ observed in 2007 or 2010, ~~and can~~. As a result, ~~and~~ based on its current configuration, ~~the lake can~~ only reach a maximum water level of 433 m, at which point ~~the lake it~~ overfills the ice dam.

~~Russell (1989) Russell (1989) pointed to suggested~~ the internal drainage network of Russell Glacier, and a possible reduction ~~of in~~ (sub)glacial meltwater as the main trigger for the 1984~~7~~ and 1984~~7~~ GLOFs. This ~~fits closely well~~ aligns with the majority of the observed GLOFs occurring late in the melt season when sub- and englacial water pressure is lower. However, the partial drainage events of 2014, 2015, 2017, and 2020 occur earlier in the melt season, indicating a different drainage mechanism or ~~an additional means by which to lower another trigger for the lowering of~~ the water pressure. The water pressure can also be lowered as a consequence of a sudden reduction in meltwater production (Tweed and Russell, 1999; Russell et al., 2011)(Tweed and Russell, 1999) and Russell et al. (2011) Russell et al. (2011) suggested a link to an observed drop in air temperature prior to the 2007 and 2008 GLOFs. For 7 of the 12 GLOFs ~~that occurred from between~~ 2010-2021 (2010-2011, and 2015-2019), we observe a similar drop in mean air temperature (MAT) when comparing the MAT of the 10 days prior to the GLOF with the MAT of the month prior (Figure 5). The difference ranges from -1.1 to -4.5 °C, with the largest drop observed in 2019. For the five remaining GLOFs the mean temperature changes are either very moderate (-0.2 - -0.5 °C) or increasing (0.3 - 1.1 °C). However, when comparing the 10-day MAT to the 5-day MAT prior to the drainage in both 2012 and 2013 we observe a 1.7 and 3 °C drop, respectively (Figure 5). A drop in temperature could influence the triggering of the GLOFs as the sub- and englacial water pressure falls in response to the reduced ablation, ~~and~~ thereby permitting the lake water

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to escape via hydraulic connection to the englacial conduit. This syphoning mechanism may be triggered by a reduction in melt, but as the timing and triggering threshold of the GLOF is linked to the water pressure dynamics of the englacial hydrological system it also reflects annual variations in the glacial drainage system (Tweed and Russell, 1999; Russell et al., 2011)(Tweed and Russell, 1999; Russell et al., 2011). As syphoning requires the draining lake to already be connected to the glacial drainage network (Tweed and Russell, 1999)(Tweed and Russell, 1999), a different mechanism must have triggered the 2007 GLOF and caused it to produce the englacial tunnel, which likely still acts as the main drainage passage for the following yearly-annually reoccurring events.

The fluctuation between short periods of relatively high and low drainage volumes (Figure 3, Table 2), points-towards-suggests other factors also-may-influencing the triggering threshold. The partial 0.9 M m³ GLOF in 2020 drained just 0.3 m ± 0.5 above the post drainage water level of the 11 M m³ 2019 GLOF. This suggests that the ice dam did not seal during the 2019-2020 winter, allowing the lake to drain already-earlier at the beginning of the ablation season in late May. We hypothesize, that the large GLOFs potentially weaken the ice dam allowing the following event(s) to occur at much lower water level. A similar theory is suggested by Russell et al. (2011)Russell et al. (2011) as an explanation for the differences between the 2007 and 2008 events. After a number few of such small events the drainage system likely undergoes a changes in configuration, resulting in the closure of-and the drainage outlet properly-closes-and allowing for a-the reoccurrence of a larger GLOF the following year.

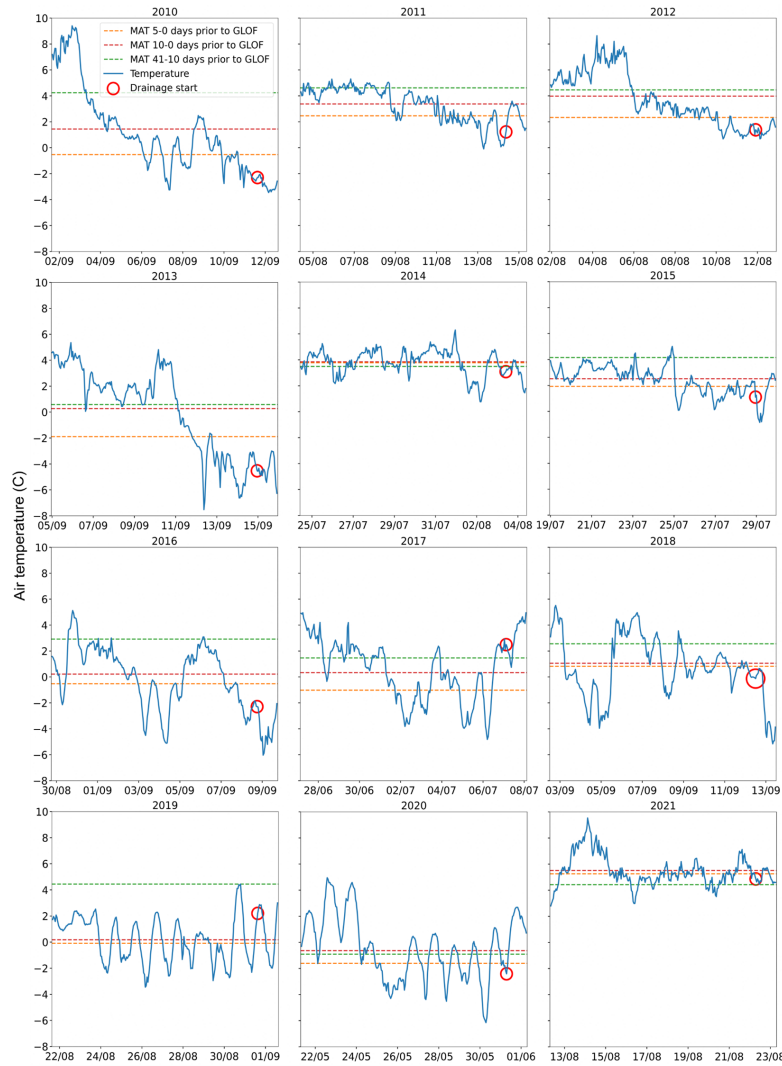


Figure 5. Plot of hourly temperature measurements from 10 days prior to the drainage event from KAN_L. Green line shows the mean air temperature (MAT) 41-10 days prior to the drainage, red line shows MAT 10-0 days prior, and orange line MAT 5-0 days prior to drainage. Red circle denotes the start of the GLOF and for the 2018 event the circle is larger due to uncertainty about the timing. All plots share the same Y axis range.

5.3 Evidence of changing drainage route

Previous observations of the lake drainage system (e.g. Carrivick et al., 2018; Mernild & Hasholt, 2009; Russell, 1989) coincides with the estimated location of drainage route I. In this study, the scattered ice blocks and the fractured ice surface observed in Figure 4(B, 4C, 4D, 4F), indicate a considerable flow of surface water along both drainage route I, and as well as the new route II during the 2021 GLOF. The parallel, circular cracks on the ice margin (Figure 4B, 4G, 4H) were likely caused by a sudden drop in elevation which indicates a substantial amount of sub- or englacial drainage water flowing beneath the margin and thus undermining the surface structure of the glacier. The roughly circular and nearly vertical holes, exemplified in Figure 4E, are likely created by the collapse of the ice surface above an empty en- or subglacial cavity, or they may potentially be a result of pressurised en- or subglacial water flow being forced upwards and breaching the ice surface, causing a localised collapse. The multiple water escape holes observed in figure 4B and 4E are either blowholes created as sub- or englacial pressurized water was forced upwards or they are simply collapsed ice roofs, both likely effects of sub- or englacial water flow. There are multiple potential explanations for the parallel fractures observed on the ice margin (Figure 4G and 4H), such as a propagation of basal crevasses towards the surface, stretching of the ice surface from increased basal sliding, as well as a temporary uplift and/or (subsequent) falling of the ice surface. In combination with the additional observed surface features, we consider the latter hypothesis the most plausible, however, all explanations can be linked to a sub- or englacial flow of drainage water.

From 3m-resolution Planet satellite images (Planet Team, 2017) captured immediately before and after the 2021 GLOF, we also observe geomorphological changes along the ice-marginal meltwater drainage system which channels the GLOF drainage water from drainage route II into the downstream river network. As a results of this This-observation we reanalysed those previous events, caused us to check back through previous events, and whilst although there we found is no evidence of geomorphological changes along the ice-marginal meltwater drainage system after the 2020 and 2019 events, we did observe standing water on the ice margin and changes in the ice colour (black to white) after the 2019 drainage, indicating water flow on the ice surface.

On the basis of these observations, we hypothesize that the new drainage pattern is predominantly caused mainly due to the by the thinning and retreat of the ice margin in the vicinity of the outlet, allowing floodwater to more easily run over and into the ice margin. The 0.4 m elevation difference between drainage route threshold I1 and I2 (Figure 4B) suggest that drainage route I is still the primary path. However, as the ice margin gradually thins the new additional drainage route II will likely become the dominant path taken. This shift is very profound, because it bypasses the two outlet lakes (Figure 1) that currently acts as a buffers and slow the downstream water flow of water. Thus, this shift will affect the downstream geomorphology and potentially cause hazards to local infrastructure. Therefore, we strongly and we suggest that a comprehensive study investigation of the potential downstream consequences of floods GLOFs along the new route is needed undertaken.

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7 Conclusion

415 This study presents one of the longest and continuous known records of GLOF drainage estimates in Greenland. We (re)analyse 14 GLOFs spanning ~~from~~ 2007 to 2021 to provide a new evaluation and ~~better-a~~ greater understanding of ~~the~~ drainage patterns and trigger mechanisms.

Our time series reveal ~~yearly-annually~~ reoccurring GLOFs, with the exception of 2009, and considerable variations in both the ~~drainage-date of drainage~~, ranging from ~~May-31st May to 15th September-15~~, as well ~~asas the overall~~ volume~~s~~ ranging from
420 0.9 to 37.7 M m³. We compare ~~our estimates of~~ lake drained volume ~~produced estimates from-through~~ DEM analyses with flood volumes calculated from a downstream hydrograph and find that the two methods produce comparable results with a mean volume difference of 10 %. That difference is excluding the 2014 GLOF where the hydrograph estimate is double the DEM-derived volume, ~~which which cannot be resolved with the available datafor now remains unresolved~~. In general, we find that our reconstructed time series ~~illustratesdemonstrates~~ the need for consistent methodological estimates when studying year-
425 to-year variations. We ~~show-illustrate~~ that the 2021 theoretical maximum drainage volume is 14.3 M m³, which is a 63 % decrease compared to the 37.7 M m³ volume estimate for the 2007 GLOF. This decrease can likely be explained as ~~due-a result of the continual observed thinning ofo-an observed thinning-of~~ the ice dam.

We hypothesize that when the ice-dammed lake episodically drains suddenly, it does so through an englacial tunnel created by the 2007 GLOF. ~~In contrast, the F~~ ensuing annual sudden drainages are likely caused by a syphoning drainage mechanism
430 within the pre-existing englacial conduit. ~~Thise~~ syphoning is likely triggered by a reduction in melt water, driven by late-season~~al~~ drainages and sudden reductions in mean air temperature, as well as ~~due-to~~ annual variations in the configuration of internalthe drainage system of the damming glacier. The observed fluctuations between short periods of relatively high and low drainages volumes suggest that the large GLOFs potentially weaken the ice dam causing it not to seal during winter and thus allowing the following event(s) to drain at a lower water level.

435 This study also reports geomorphological evidence from UAV and satellite data that reveals an altering of the proglacial drainage route with a new sub- or englacial flow pathway, as well as-and the supraglacial flow of drainage water going across the ice margin. We suggest that the new drainage route has developed ~~due-as a result ofto-a~~ thinning and retreat of the ice margin, and that ~~a-~~ further thinning will cause the new drainage route to eventually become dominant. As the new route bypasses the two buffering outlet lakes the delivery of drainage water to the downstream system will be faster and less
440 attenuated, with large-significant consequences for the surrounding geomorphology and thea potential risk of flooding hazards.

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Appendices

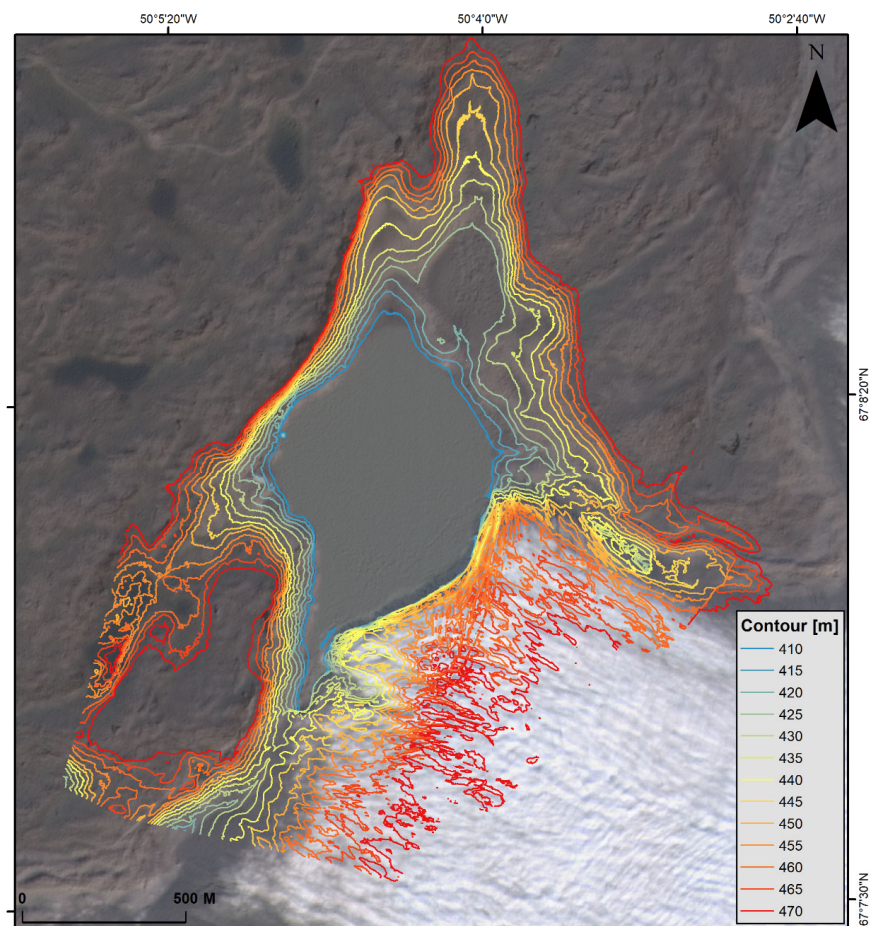


Figure A1. Contour map with 5 m intervals based on the 2021 post-drainage DEM. Background is a four band Planet (2017) acquisition from 23/8-2021, shown on a Planet (2017) images.

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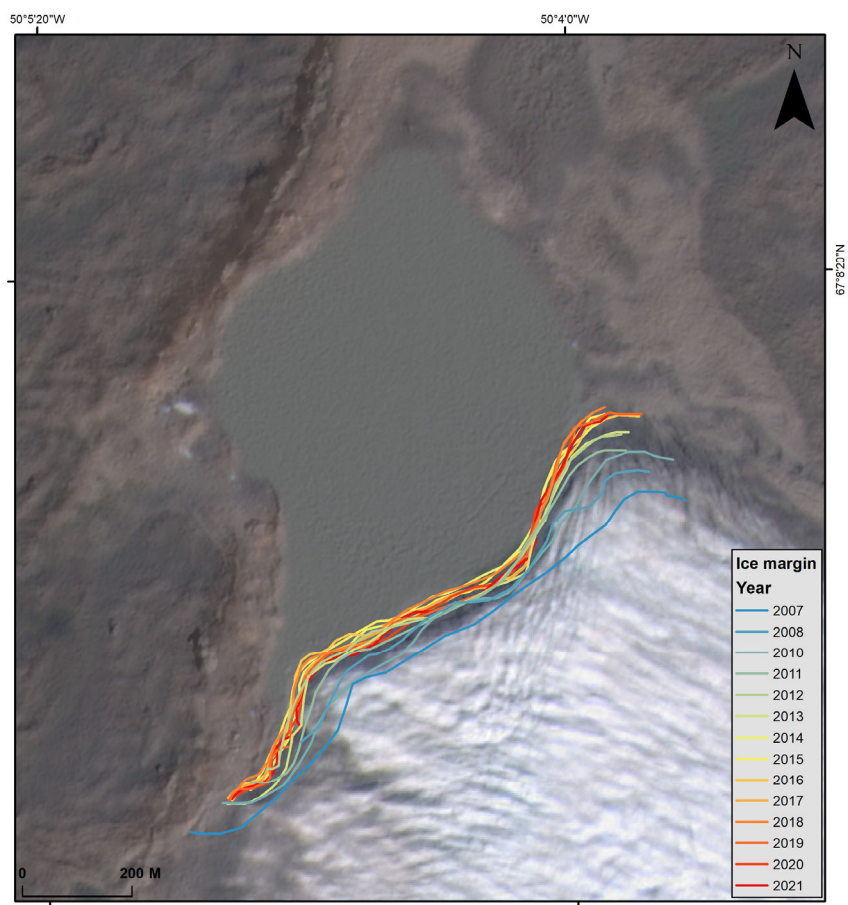


Figure A2. Position of ice margin digitized based from on-satellite images. Background is a four band Planet (2017) acquisition from 23/8-2021, shown on a Planet (2017) images.

Data availability

The UAV DEMs and orthophotos will be made available through Pangaea upon publication. DOI will be inserted here.

Author contributions

MD led the data analysis and wrote the main manuscript. MD, FH, AAB planned the study and carried out the fieldwork. KKK collected the hydrograph data and performed the hydrograph volume estimates. SAK carried out GPS data processing. JLC provided guidance on the interpretations and assessment of the drainage triggers and water rerouting. All authors contributed to the data analysis and interpretation of results and provided inputs for the manuscript.

Competing interests

The authors declare that they have no conflict of interest.

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