

# Dynamic response and breakage of trees subject to a landslide-induced air blast

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## Abstract

Landslides have been known to generate powerful air blasts capable of causing destruction and casualties far beyond the runout of sliding mass. The extent of tree damage provides valuable information on air blast intensity and impact region. However, little attention has been paid to the air blast-tree interaction. In this study, we proposed a framework to assess the tree destruction caused by powerful air blasts, including the eigenfrequency prediction method, tree motion equations and the breakage conditions. The tree is modeled as a flexible beam with variable cross-sections, and the anchorage stiffness is introduced to describe the tilt of tree base. Large tree deflection is regarded when calculating the air blast loading, and two failure modes (bending and overturning) and the associated failure criteria are defined. Modeling results indicate that although the anchorage properties are of importance to the tree eigenfrequency, tree eigenfrequency is always close to the air blast frequency, causing a dynamic magnification effect for the tree deformation. This magnification effect is significant in cases with a low air blast velocity, while the large tree deflection caused by strong air blast loading would weaken this effect. Furthermore, failure modes of a specific forest subject to a powerful air blast depend heavily on the trunk bending strength

and anchorage characteristics. The large variation of biometric and mechanical properties of trees necessitates the establishment of a regional database of tree parameters. Our work and the proposed method are expected to make people better understand air blast power and be of great utility for air blast risk assessment in mountainous regions worldwide.

**Keywords:** Landslide-induced air blast; Tree eigenfrequency; Dynamic response; Tree breakage

## **1 Introduction**

Long runout landslides involve massive amounts of energy and can be extremely hazardous owing to their long movement distance, high mobility and potential chain disasters (Nicoletti and Sorriso Valvo, 1991; Nicoletti et al., 1993; Johnson and Campbell, 2017; Shugar et al., 2021; Zhang et al., 2022). A moving landslide with high velocity can generate a powerful air blast capable of uprooting trees, lifting people into the air and even flattening buildings (Adams, 1881; Penna et al., 2021). In recent decades, destructive air blasts frequently occurred in mountainous regions worldwide and caused casualties and economic loss far beyond the landslide runout (e.g., Yin, 2014; Bartelt et al., 2016; Kargel et al., 2016). Understanding their force of destruction is of great utility for landslide risk assessment and disaster mitigation, especially in high-altitude regions.

Monitoring equipment has been confirmed to provide great performance in determining the dynamic characteristics of landslide-induced air blasts (Grigoryan et al., 1982; Sukhanov, 1982; Caviezel et al., 2021). However, most case histories occurred in the high-altitude mountainous region without witnesses (Yin and Xing, 2012), and the in-situ equipment can also get damaged because of the near-field destruction of landslides and associated air blasts. Therefore, very few air blast cases were measured in history. Geologists can only evaluate the air blast hazard for most recorded events using historical evidence after the landslide occurred. In-situ information about forest destruction and tree breakage is

often used for the air blast risk assessment (Feistl et al., 2015; Fujita et al., 2017; Zhuang et al., 2019, 2022a) (Fig. 1). Uprooted trees and snapped stems delineate the impact region of air blasts and create a natural vector field indicating the primary movement direction of the landslide, greatly helping analyze the disaster-causing process of the event. In many cases, observations of forest destruction are the only data to quantify air blast danger.



**Fig. 1** Trees breakage caused by a large landslide-induced air blast in Sichuan, China, 2008.

A question remained for air blast mitigation planning using the information of tree damage is how to establish a simple relationship between air blast impact pressure and tree failure. Bending and overturning are two common tree failure modes caused by strong winds. Trees snap when the bending stress exerted by the air blast exceeds the wood strength (Peltola et al., 1999; Gardiner et al., 2000), while the overturning will occur if the applied moment overcomes the anchorage resistance of root systems (Jonsson et al., 2006; Nicoll et al., 2006). The occurrence of these two failure modes depends heavily on both the air blast loading and tree properties. Considering the minor destruction of air blasts relative to the landslide, although long recognized that sliding mass can easily break or uproot trees (Bartelt and

Stöckli, 2001; Šilhán, 2020), little attention has been paid to the tree destruction resulting from air blasts. Furthermore, existing models describing the tree-air blast interaction are mostly static (Feistl et al., 2015) or established based on the small-deflection theory (Bartelt et al., 2018). These methods could aid in a rapid assessment of air blast power, but further research is needed to establish a dynamic model to represent the dynamic response of trees in a strong wind. A mechanical understanding of how trees are damaged by air blasts is therefore essential for quantifying the air blast powers and providing valuable data to verify the possible numerical results.

In this study, we established a simple dynamic model capable of calculating the natural frequency of trees and simulating their dynamic response subject to a powerful air blast. The proposed model regards the tree as a multi-degree-of-freedom beam with variable diameters and accounts for large tree deflections and impacts of root anchorage. Both bending and overturning failure modes are involved in the model. The work conducted in this study is expected to make people better understand the power of landslide-induced air blasts and provide an applicable method to assess the air blast hazard.

## **2. Model description**

Measurements of historical events indicated that the landslide-induced air blast is intermittent and of short duration, lasting only a few seconds and could reach a high velocity (Grigoryan et al., 1982; Sukhanov, 1982; Caviezel et al., 2021). This impulse wave has a propagation distance of hundreds of meters in both horizontal and vertical directions and acts over the entire tree. Thus, the impact of air blasts on trees is similar to extreme wind gusts, producing large bending moments in the stem and root base system, forcing trees to deform or get damaged. Furthermore, fallen trees often point to the movement direction of the landslide, illustrating there is little time for trees to sway and react to air blasts while the inertial effects are greatly important.

To characterize the dynamic response of trees under the impact load of air blasts, we established a mechanical model to predict the eigenfrequency of trees subject to air blasts and developed a dynamic tree-swaying model that accounts for the large tree deflection. In what follows, we present the eigenfrequency prediction method, tree motion equations and the breakage conditions.

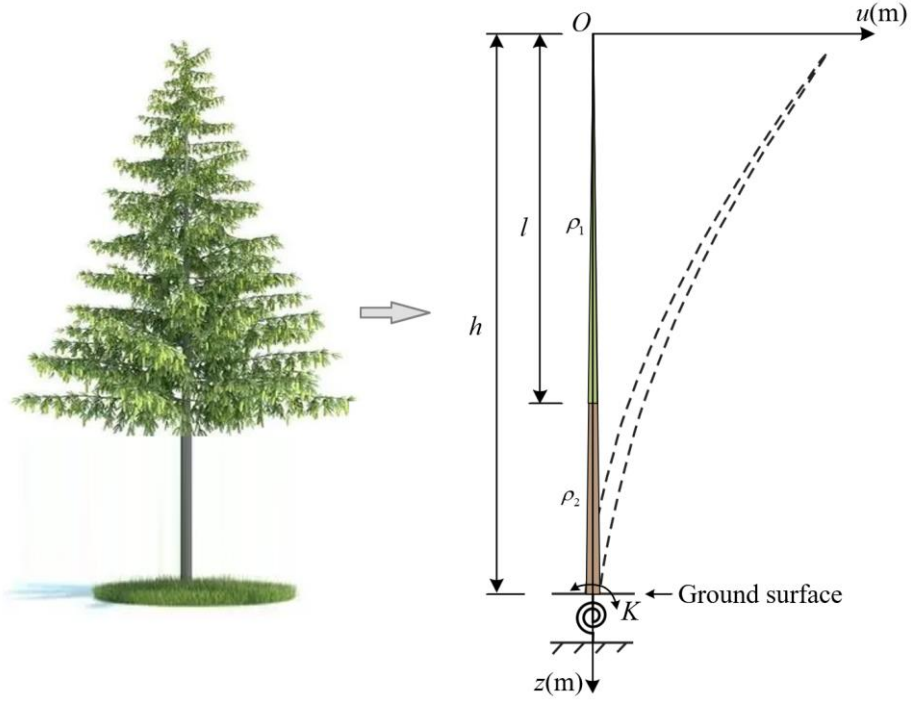
## 2.1 Eigenfrequency prediction

The tree is modeled as a flexible cantilever beam with variable diameters that is hinged at ground level using elastic support. The beam diameter is assumed to continuously linearly decrease with height regarding the decreasing diameters of trunk and crown from bottom to top, while the anchorage stiffness of the root system ( $K$ ) helps to describe the tilt of tree base in response to the moment (Neild and Wood, 1999). In the eigenfrequency prediction mode, the tree beam is divided into two segments with a splitting point located at the starting point of the tree crown (Fig. 2). We assume that the tree crown shows minor impacts on elastic modulus. The tree crown is accounted for through the crown mass, and thus the natural difference between the two segments is the material density.

The governing differential equation for the dynamic bending of a nonuniform Euler-Bernoulli beam is (Keshmiri et al., 2018):

$$\rho A(z) \frac{\partial^2 u}{\partial t^2} + \frac{\partial^2 u}{\partial z^2} \left[ EI(z) \frac{\partial^2 u}{\partial z^2} \right] = 0 \quad (1)$$

where  $z$  is the position variable along the beam length. For ease of calculation, the original point ( $z=0$ ) is set at the treetop and the maximum value of  $z$  is at the tree base, so that the beam diameter  $d(z)$  corresponding to the position  $z$  can be described using a gradient coefficient ( $\mu$ ):  $d(z)=\mu z$ .  $u$  is the beam displacement,  $E$  is the elastic modulus,  $A(z)=\frac{\pi}{4}(dz)^2$  and  $I(z)=\frac{\pi}{64}(dz)^4$  are the cross-sectional area and moment of inertia, respectively.



**Fig. 2** Schematic representation of the eigenfrequency prediction model.

Plugging the expression of  $A(z)$  and  $I(z)$  into Eq. 1 gives:

$$z^2 \frac{\partial^4 u}{\partial z^4} + 8z \frac{\partial^3 u}{\partial z^3} + 12 \frac{\partial^2 u}{\partial z^2} - \frac{16\rho\omega^2 u}{E\mu^2} = 0 \quad (2)$$

where  $\omega$  is known as the eigenfrequency of the beam. The general solution of Eq. 2 can be expressed as:

$$u(z) = \frac{1}{z} \left[ A_1 J_2(2\sqrt{\lambda z}) + A_2 Y_2(2\sqrt{\lambda z}) + A_3 J_2(2i\sqrt{\lambda z}) + A_4 Y_2(2i\sqrt{\lambda z}) \right] \quad (3)$$

where  $\lambda = \sqrt{\frac{16\rho\omega^2}{E\mu^2}}$ ,  $J_2$  and  $Y_2$  are the Bessel functions of the first and second kind (Mocica, 1988),

respectively, and  $A_1$ - $A_4$  are coefficients that need to be determined based on the boundary conditions.

The deflection of the upper segment (crown) and the lower segment (trunk) can be generated in a similar manner:

$$u_1(z) = \frac{1}{z} \left[ A_1 J_2(2\sqrt{\lambda_1 z}) + A_2 Y_2(2\sqrt{\lambda_1 z}) + A_3 J_2(2i\sqrt{\lambda_1 z}) + A_4 Y_2(2i\sqrt{\lambda_1 z}) \right] \quad 0 \leq z < l \quad (4)$$

$$u_2(z) = \frac{1}{z} \left[ B_1 J_2(2\sqrt{\lambda_2 z}) + B_2 Y_2(2\sqrt{\lambda_2 z}) + B_3 J_2(2i\sqrt{\lambda_2 z}) + B_4 Y_2(2i\sqrt{\lambda_2 z}) \right] \quad l \leq z \leq h \quad (5)$$

where  $l$  is the length of crown,  $h$  is the tree height,  $\lambda_1 = \sqrt{\frac{16\rho_1\omega^2}{E\mu^2}}$  and  $\lambda_2 = \sqrt{\frac{16\rho_2\omega^2}{E\mu^2}}$  are the single-valued

function of eigenfrequency.  $\rho_2$  is the wood density and  $\rho_1$  is the equivalent density regarding the contribution of both tree trunk and crown. Same to  $A_1$ - $A_4$ ,  $B_1$ - $B_4$  are also coefficients of the tree deflection equation that need to be determined based on the boundary and continuity conditions.

The boundary condition at the origin ( $z=0$ ) is the free end, and thus Eq. 4 can be simplified as:

$$u_1(z) = \frac{1}{z} \left[ A_1 J_2 \left( 2\sqrt{\lambda_1 z} \right) + A_3 J_2 \left( 2i\sqrt{\lambda_1 z} \right) \right] \quad 0 \leq z < l \quad (6)$$

According to continuity conditions of two segments at the splitting point and the boundary condition at the tree base, following constraints are determined:  $u_1(l) = u_2(l)$  ,  $u_1'(l) = u_2'(l)$  ,  $u_1''(l) = u_2''(l)$  ,  $u_1'''(l) = u_2'''(l)$  ,  $u_2(h) = 0$  , and  $Ku_2'(h) + EI(h)u_2''(h) = 0$  . Introducing the constraints into Eqs. (5-6), a total of six equations are determined here. These six equations can be written in a matrix format:

$$\left[ F(\lambda_1, \lambda_2) \right]_{6 \times 6} \cdot \begin{bmatrix} A_1 & A_3 & B_1 & B_2 & B_3 & B_4 \end{bmatrix}^T = 0 \quad (7)$$

where  $\left[ F(\lambda_1, \lambda_2) \right]_{6 \times 6}$  is a matrix that is composed of  $\lambda_1$  and  $\lambda_2$  . The orders of eigenfrequency and the corresponding vibration mode can be obtained by solving the equation: the determinant of matrix  $|F(\lambda_1, \lambda_2)| = 0$  . Notably, the derivatives of  $u_1(z)$  and  $u_2(z)$  have very complicated expressions but could be easily calculated using Matlab. Therefore, we did not provide the complete expression here.

## 2.2 Tree motion

The mechanical response of trees subject to an air blast is modeled using a modified multi-degree-of-freedom tree swaying model with variable cross-sections (Zhuang et al., 2022b). Different from the simplification in the eigenfrequency prediction method, the size of tree crown here is determined based on real tree data, corresponding to the frontal area distribution of the tree crown (Fig. 3(a)). The model divides the tree beam into a set of segments and calculates the tree motion using linear modal analysis. Specifically, the tree deformation is decomposed into a set of vibration modes so that the total displacement is the combined contribution of each mode. According to preliminary research performed

by Sellier et al. (2008) and Pivato et al. (2014), the contribution of the first vibration model is far ahead of the other modes for trees with a slender shape. Thus, only the first vibration mode and the corresponding eigenfrequency are utilized in this study. The modeling of air blast pressure accounts for the wind-tree relative motion and large tree deflection by regarding the beam velocity and geometric nonlinearities resulting from the inclination of beam segments relative to the wind direction ( $\theta_i$ ) (Fig. 3(b)). With respect to the large tree deflection, we also introduce the impact of eccentric gravity into the model, which significantly contributes during the interaction with a powerful air blast. The gravity and wind load acting on each segment can be easily calculated based on the predetermined diameter and frontal area distribution (Fig. 3(a)). Considering that trees often fall in the direction of landslide motion and have little time to sway, the maximum response of the tree is assumed to be reached before the damping forces act (Bartelt et al., 2018). Only the undamped response to a short-duration blast is considered. The tree motion equations and the expression of air blast force are as follows:

$$m \frac{\partial^2 y}{\partial t^2} + ky = \int_0^h F_i \phi ds + \int_0^h G_i \phi ds \quad (8)$$

$$F_i = 0.5 \rho C_d A_f \left| v \cos \theta_i - \frac{\partial y}{\partial t} \cos \theta_i \right| \left( v \cos \theta_i - \frac{\partial y}{\partial t} \cos \theta_i \right) \cos \theta_i \quad (9)$$

$$G_i = m_i g \cdot \sin \theta_i \cdot \cos \theta_i \quad (10)$$

where  $\phi$ ,  $w$ ,  $m = \int_0^h \bar{m} \phi^2 ds$ ,  $k = 4\pi^2 m \omega^2$  are the first mode shape, the first eigenfrequency, modal mass and stiffness, respectively,  $\bar{m}$  is the mass distribution,  $y$  is the associated generalized displacement,  $F_i$  and  $G_i$  are the air blast loading and eccentric beam gravity act on the  $i$ th segment,  $h$  is the tree height,  $C_d$  is the drag efficient,  $A_f$  is the frontal area,  $\rho$  and  $v$  are the density and velocity of the air blast, respectively.

Our model is applicable of calculating the scenarios for both full-height and part-height air blasts.

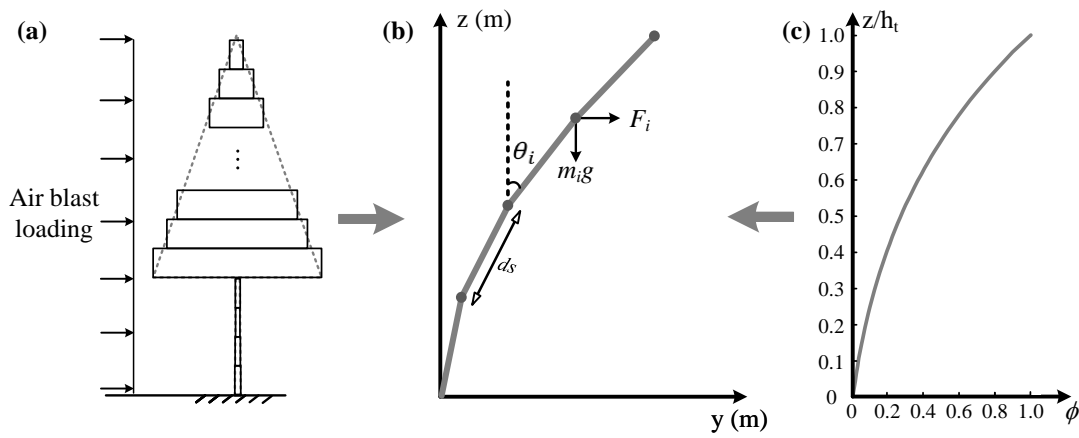
In this study, the air blast velocity is expressed as a sine wave impulse with a short duration time  $t_0$ :

$$v = v_{\max} \sqrt{\sin \omega t} \quad (11)$$



where  $v_{\max}$  is the maximum velocity of the landslide-induced air blast and  $\varpi$  can be regarded as the circular frequency of the wind force  $\varpi = \pi / t_0$  (wind force is related to the square of its velocity).

The mechanical response of trees subject to an air blast is deduced by introducing the calculated wind velocity from Eq. 11 into the tree motion model (Eqs. 8-9), and subsequently solving the equations using the central finite-difference scheme. The validity of this tree motion model has been checked by Pivato et al. (2014) and Zhuang et al. (2022), and thus the validation process is not involved here.



**Fig. 3** a-b Modeling the tree as a multi-degree-of-freedom flexible beam to calculate the dynamic response of trees submitted a powerful air blast. c The first mode shape of the beam helps to model the tree deformation.

### 2.3 Tree breakage

Two failure modes commonly caused by air blasts are involved in the work: bending and overturning (Gardiner et al., 2000).

For the case of tree bending, trees are considered to break when the maximum bending stress  $\sigma_{\max}$  exceeds a critical value  $\sigma_{\text{crit}}$  :

$$\sigma_{\max} = \left[ \frac{M(t, z) \cdot d(z) / 2}{I(z)} \right]_{\max} \geq \sigma_{\text{crit}} \quad (12)$$

where  $\sigma_{\text{crit}}$  is the bending strength of the tree, which depends highly on the material property.  $M(t, z)$  is the bending moment, and its value is calculated at each time step all along the beam:

$$M(t, z) = EI(z) \frac{d\theta}{ds} \quad (13)$$

where  $\frac{d\theta}{ds}$  represents the local beam curvature and  $\theta$  is the angle between the beam segment with the vertical direction.

For the tree overturning case, trees are regarded to break at the basement when the air blast-induced moment reaches the anchorage resistance ( $M_{crit}$ ):

$$M_{base}(t) \geq M_{crit} \quad (14)$$

where  $M_{base}(t)$  is the moment at tree base calculated at each time step, and the anchorage resistance  $M_{crit}$  is often determined based on in-situ tests (e.g. tree pulling tests).

### 3. Application

To demonstrate the power of air blasts and how they damage trees, we consider the problem proposed by Bartelt et al. (2018): a landslide-induced air blast enters a spruce forest at high speed (maximum velocity of 20 m/s). The short-duration air blast lasts a few seconds with a frequency  $\varpi$ . Trees in the forest have a height between 25 and 30 m, which is also the height of the air blast. The sliding mass has stopped before reaching the forest and only the air blast loads on the trees.

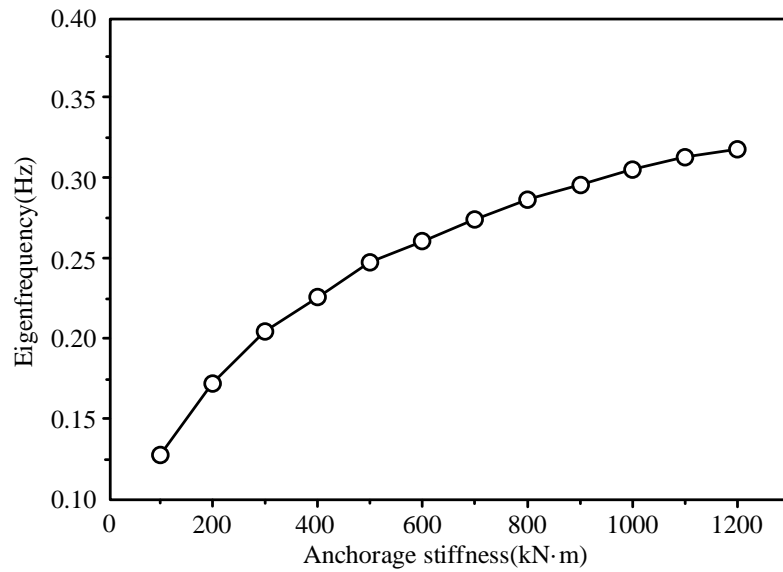
**Table 1** Model parameters used in the numerical simulations of the tree response. Parameters are derived from data contained in Kantola and Mäkelä (2004) and Bartelt et al. (2018).

Height $h(m)$	Crown height $l(m)$	Crown width $w(m)$	Diameter at trunk base $D(m)$	Wood density $\rho_2 (kg/m^3)$	Branch mass $m(kg)$	Drag coefficient $C_d$
27	18	5	0.4	480	540	0.4

Using the measured biomass parameters presented in Table 1, we set the total crown mass of a single tree to be 540 kg. The tree crown is assumed to be a cone with a length of  $18\text{ m} (\frac{2}{3}h)$  and a width of 5 m. The wood density is  $480\text{ kg/m}^3$  and the elastic modulus is 10 GPa. Measurements of root anchorage stiffness ( $K$ ) are very rare and in-situ tests on spruce performed by Neild and Wood (1999) show a value variation of 80-1200 kN·m. This value range indicates a large variation in  $K$  depending on the growth conditions, and the values of 100-1200 kN·m are applied in the prediction of eigenfrequency and

vibration mode in this study.

The eigenfrequency ranging from 0.13 Hz ( $K=100 \text{ kN}\cdot\text{m}$ ) to 0.32 Hz ( $K=1200 \text{ kN}\cdot\text{m}$ ) is calculated based on the above parameters (Fig. 4). The modeled results are in high agreement with measurements performed by Jonsson et al. (2006) (0.16-0.30 Hz), indicating the validity of our proposed eigenfrequency prediction method. Although the tree eigenfrequency varies significantly with the anchorage stiffness, all the calculated values are less than 0.5 Hz. The same order of magnitude between tree eigenfrequency and air blast frequency necessitates a further investigation on the possible impact of resonance. The dynamic magnification effect caused by impulse loading can greatly amplify the static stress state, making the trees easier to be damage.



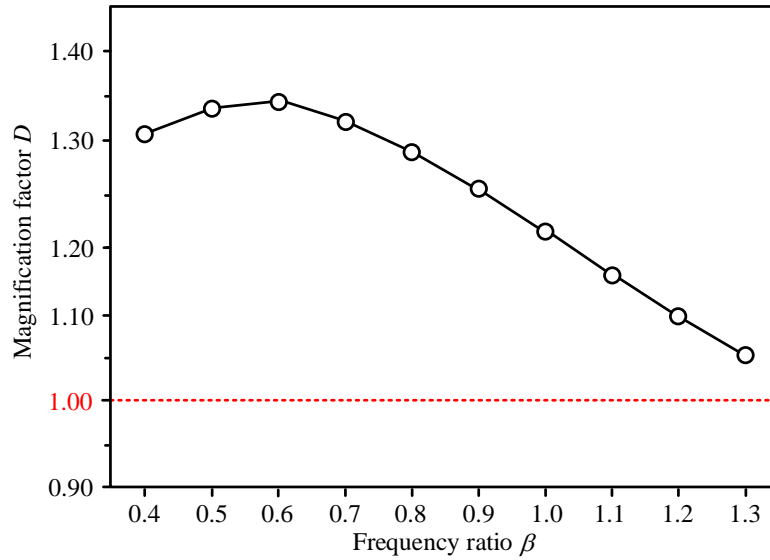
**Fig. 4** Eigenfrequency of trees corresponding to different anchorage stiffness.

To investigate the impact of dynamic magnification, we performed simulations for all the scenarios using the tree eigenfrequency of 0.26 Hz ( $K=600 \text{ kN}\cdot\text{m}$ ) and the associated vibration mode. A magnification factor  $D$  is defined to describe this effect:

$$D = \frac{u_{d,\max}(\beta)}{u_{\text{sta}}} = \frac{u_{d,\max}(\beta)}{\int_0^h F_{s,\max} \phi ds / k} = \frac{u_{d,\max}(\beta)}{\int_0^h \rho C_d A_f v_{\max}^2 \phi ds / k} \quad (15)$$

where  $u_{d,\max}$  and  $u_{\text{sta}}$  are the maximum displacement subject to dynamic load and static load, respectively,

$F_{s,\max}$  is the static wind force corresponding to the maximum air blast velocity and  $\beta = \frac{\varpi}{\omega}$  is the ratio between the air blast frequency ( $\varpi$ ) and the eigenfrequency of the tree ( $\omega$ ). Notably, the air blast is a multi-medium fluid that contains numerous dusts, showing a higher density than air. Measurements and numerical modeling performed by Swiss researchers (Feistl et al., 2015) suggest  $\rho = 5\text{kg/m}^3$ . In this scenario  $u_{\text{sta}}$  is calculated to be 9.8 m.



**Fig. 5** Magnification factor with various frequency ratio.

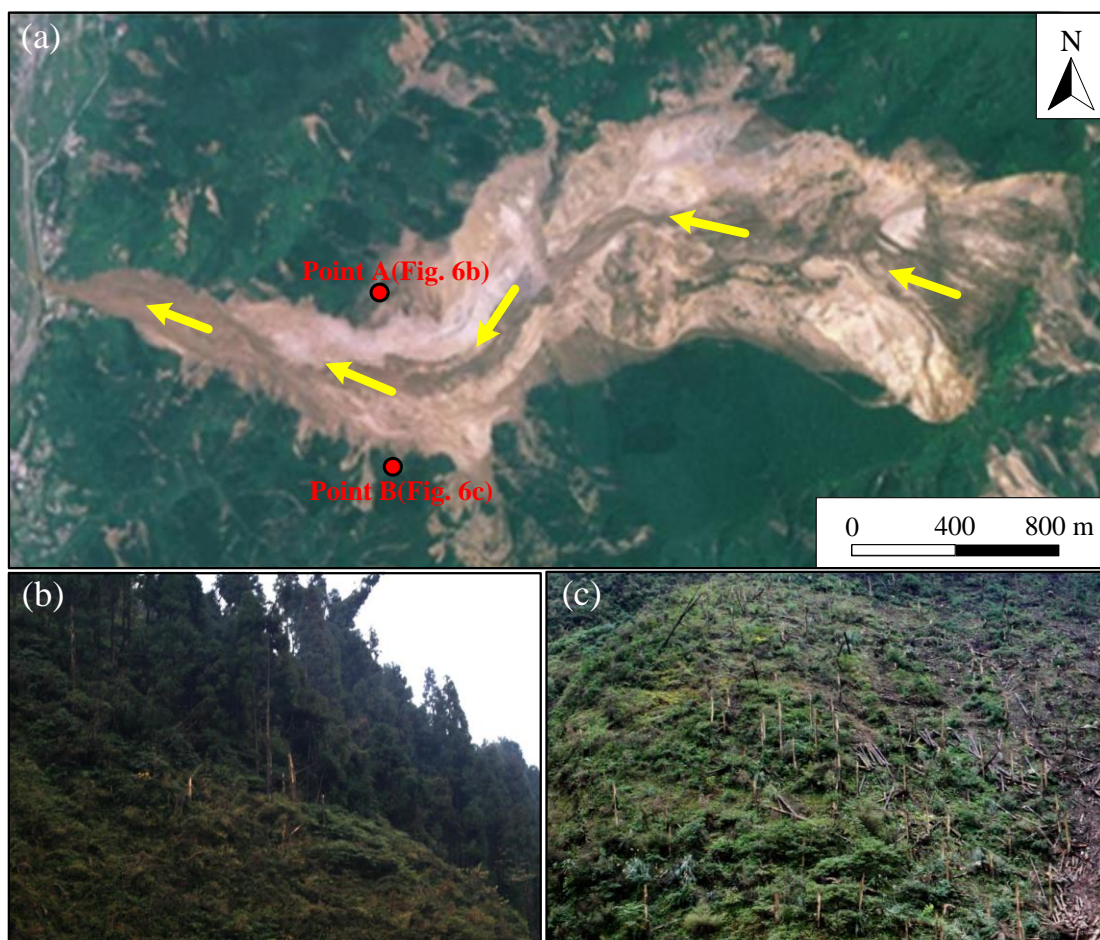
Figure 5 shows the impact of air blast frequency on the dynamic magnification effect. A parabola relationship is identified between the magnification factor and the frequency ratio. Consider first an impulse air blast lasting 1.6 s ( $\beta = 1.2$ ). The air blast frequency is higher than that of the tree, implying the maximum displacement reaches after the loading time. The modeled maximum dynamic deformation  $u_{d,\max}$  reaches 10.7 m, and the magnification factor is 1.09. In this case, the magnification effect of tree deformation seems not significant because of the large tree deflection and short-duration loading, and the modeled result is similar to the static stress state. For a longer air blast duration of 3.2 s ( $\beta = 0.6$ ), we find  $D = 1.34$ , a high value. The maximum tree deformation reaches during the air blast loading. In such a scenario, an air blast travelling at 20 m/s can exert similar destruction as a long-duration wind moves

at 25 m/s. The dynamic magnification effect significantly increases the tree displacement and thus causes such a phenomenon. Measurements of air blast duration reported by Russian and Swiss researchers (Grigoryan et al., 1982; Sukhanov, 1982) are within this range, lasting only a few seconds. Although the large tree deflection decreases the wind loading, the impulse air blast load is prone to damage the trees because of the dynamic magnification effect.

Additional simulations were performed on the air blast induced-tree breakage. The impulse air blast is assumed to have a maximum velocity of 20 m/s and a duration of 3.2 s. For this case, numerical results demonstrate the maximum bending stress and moment of 35 Mpa and 192 kN·m, respectively. The maximum bending stress reaches at 9 m height ( $1/3h$ ), and the maximum bending moment is identified at the tree base. In natural forest areas, the bending strength  $\sigma_{\text{crit}}$  and anchorage resistance  $M_{\text{crit}}$  are highly variable, depending on tree species, soil characteristics and temperatures, etc. Measurements conducted by Peltola et al. (2000) and Lundström et al. (2007) indicate that the bending stress to destroy mature trees needs to exceed a value of 30 MPa while mature spruces with a height of 20-40 m have an anchorage resistance reaches up to 100-400 kN·m. For the case performed in this study, the forest is likely to damage in both bending and overturning failure modes. Reliable values of critical parameters are needed during the assessment of tree destruction, and this will improve the prediction accuracy of the likely failure mode.

A further application was performed on the 2008 Wenjia valley avalanche-induced air blast in Sichuan, China (Fig. 6a). This large avalanche has a volume of over  $40 \times 10^6 \text{ m}^3$  and generated a powerful air blast. According to our previous investigations and numerical modeling (Zhuang et al. 2019), the air blast-damaged trees are mostly tall spruce concentrated near the turning points of the valley (Fig. 6 b-c). The simulated air blast velocity at turning points reaches 30 m/s (point A) and 35 m/s (point B),

respectively. Using the spruce-related parameters indicated in Table 1 and an assumed air blast duration of 3.2 s (a long duration for large avalanches), the maximum displacement of spruces is calculated to be 18.5 m and 22.2 m at points A and B, respectively. In this case, the maximum bending stress of trees at two turning points could reach 51 Mpa and 57 Mpa, respectively, significantly larger than the bending strength suggested by Peltola et al. (2000) (36 Mpa). Therefore, bending failure of tall spruces was widely identified in situ.



**Fig. 6** Wenjia valley avalanche-induced air blast (according to Zhuang et al. 2019). a Overview of the Wenjia valley avalanche. b-c Trees damaged by the generated air blast.

#### 4. Discussion

Risk assessment and disaster mitigation of landslide-induced air blasts are hot issues in mountainous regions. Developing a simple but applicable relationship between air blast pressure and tree failure is of

great utility for scientists to quantify the air blast power. Compared with existing models, one significant improvement of our model is to model the tree as a flexible beam with variable cross-section and involve the impact of anchorage. This improvement allows the tree to move as its natural vibration mode rather than a hypothetical trajectory (e.g. rotate around the tree base as a rigid body (Bartelt et al., 2018)). Moreover, the variable cross-section makes the modeling of tree bending failures more realistic. We can simulate the failure position of trees subjected to a powerful air blast. For the existing model with a constant diameter (Feistl et al., 2015), the rigidity  $EI$  is constant along the beam, and the maximum bending stress is always identified at the tree base. This failure characteristic cannot match the actual situation well.

Our proposed model accounts for the impacts of large tree deflection: eccentric gravity and modeling of air blast force regarding the wind-tree relative motion and geometric nonlinearities. To investigate the impact of these factors and confirm the necessity of considering large deflection, a comparative analysis is needed to make readers have a better understand. Therefore, we designed a comparative analysis by simplifying the tree motion model of Eq. 8 without involving the impact of large tree deflection. The simplified model is similar to that proposed by Bartelt et al. (2018):

$$m \frac{\partial^2 y}{\partial t^2} + ky = \int_0^h 0.5 \rho C_d A_f v_{\max}^2 \phi ds \cdot \sin \varpi t = \int_0^h F_{s, \max} \phi ds \cdot \sin \varpi t \quad (16)$$

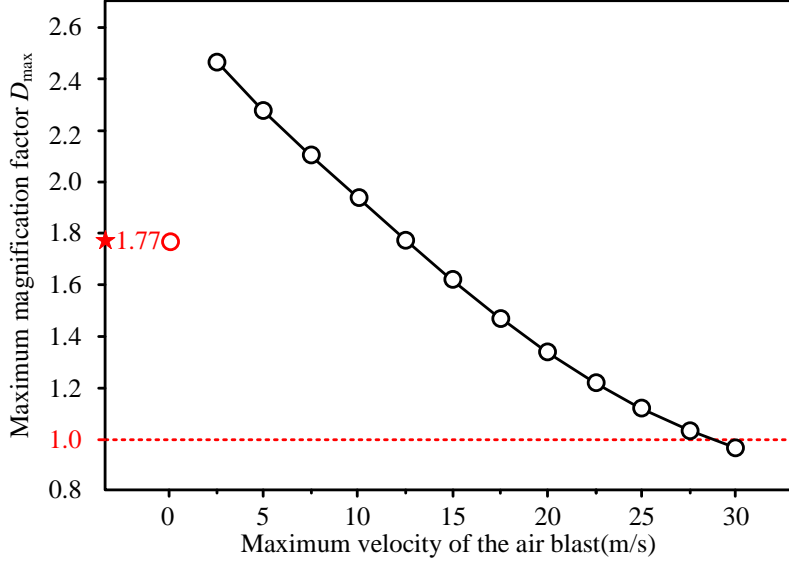
The displacement at the tree top can be written as:

$$\begin{cases} u(t) = \frac{\int_0^h F_{s, \max} \phi ds}{k} \frac{1}{1 - \beta^2} (\sin \varpi t - \beta \sin \omega t) & 0 \leq t \leq t_0 \\ u(t) = \frac{u'(t_0)}{\omega} \sin \omega(t - t_0) + u(t_0) \cos \omega(t - t_0) & t > t_0 \end{cases} \quad (17)$$

The maximum deformation occurs during the loading time when  $\beta \leq 1$ , and after the loading time when  $\beta > 1$ . The magnification factor  $D$  for both scenarios can be expressed as:

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$$\begin{cases} D = \frac{1}{1-\beta^2} [\sin(\frac{2\pi\beta}{\beta+1}) - \beta \sin \frac{2\pi}{\beta+1}] & \beta \leq 1 \\ D = \frac{2\beta}{\beta^2-1} \cos \frac{\pi}{2\beta} & \beta > 1 \end{cases} \quad (18)$$



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288 **Fig. 7** Impact of large tree deflection on the maximum magnification factor  $D_{\max}$ . The red star represents  
 289 the  $D_{\max}$  calculated from Eq. 18. The red circle represents the  $D_{\max}$  corresponding to the scenario with a  
 290 very low air blast velocity (maximum velocity of 0.1m/s) and the eccentric gravity is not considered.

291 Figure 7 presents the impact of large tree deflection on the magnification effect. We first perform  
 292 the simulation using the proposed model without regarding the impact of large tree deflection. A very  
 293 low air blast velocity (maximum velocity of 0.1m/s) is performed and the eccentric gravity is not  
 294 considered. The  $D_{\max}$  value of 1.77 is identified in the scenario, which is consistent with the analytical  
 295 solution from Eq. 18. The tree deformation is small with such a weak air blast loading, and the  
 296 comparison result verifies the validity of our proposed model. Further calculations with higher air blast  
 297 velocities show different results. In the cases of a low air blast velocity, the eccentric gravity contributes  
 298 a lot to the tree deformation, causing a rather large magnification factor ( $>2$ ). However,  $D_{\max}$  greatly  
 299 decreases with the increase of wind velocity. For a high air blast velocity, the dynamic response and  
 300 eccentric gravity amplify the tree deflection, but the inclination of the trees to the wind direction  
 301 significantly reduces the air blast loading. This special mechanism was rarely considered during the



previous assessment of landslide-induced air blasts. We suggest that the modeled tree deformation subjected to a powerful air blast might be overestimated without considering large tree deflection, although this simplified model of Eq. 18 has the advantage of rapid assessment for air blast pressure. The impact of large tree deflection should be accounted for when using forest destruction to quantify the air blast danger.

The dynamic response of trees subject to a landslide-induced air blast is a complex problem, depending heavily on the biometric characteristics of trees. Some biomass variations can be represented by the parameters in the proposed model. For example, for the leafless trees, air blasts pass through the tree crown and only act on the branches, causing a smaller wind load. A reduction of drag efficient  $C_d$  is needed in such a condition. Single trees in the impact region of air blasts are subject to a larger loading than trees in dense forest stands, where tree crowns tend to be narrower and form a shielding effect. We can make a reduction in the frontal area  $A_f$  to simulate this mechanism. Furthermore, although much effort has been paid to the biometric and mechanical characteristics of tree crowns and trunks, less information is available about the anchorage stiffness and resistance. The root anchorage properties significantly influence the tree eigenfrequency and the likely failure mode. A reliable measurement value of tree bending strength and anchorage resistance is of utility to improve the accuracy of tree failure prediction and clarify which failure mode is prone to occur. Overall, biomass-related parameters selected to estimate the air blast pressure are recommended to be determined based on in-situ investigations. In the future, more measurements need to be conducted on the anchorage properties of trees. Regional databases for biometric and mechanical properties of trees are worthwhile to be established. This would help provide reliable parameters for the air blast risk assessment.

In this study, the tree is modeled as a variable cross-section that is hinged at ground level using

elastic support. Root anchorage is complex and sensitive to many factors such as soil mechanical properties, soil water content and root morphology, and we acknowledge that it is difficult to establish a model that accounts for all the factors that affect the anchorage. Most importantly, we developed a simple but practical model that could simulate the dynamic response of trees subject to a powerful air blast and their two possible failure modes. Bartelt and his colleagues (Bartelt et al., 2018) have developed a dynamic model named RAMMS, which could efficiently model the entire movement process of ice/rock/snow avalanches and the associated air blasts. It is anticipated that the combination of our proposed tree model and the RAMMS dynamic model could help the risk assessment of potential air blasts through modeling the air blast impact region and forest destruction.

## **Conclusions**

Air blasts are short-duration impulses and can intensify the potential destruction far beyond the sliding mass. Trees destruction in-situ can provide valuable data to quantify the air blast danger and make us better understand its force of destruction. In this study, we developed a framework for the forest destruction assessment subject to a powerful air blast, including the eigenfrequency prediction method, tree motion equations and breakage conditions. The tree is modeled as a flexible variable cross-section beam hinged at ground using elastic support. The impacts of root anchorage and large tree deflection are regarded during the dynamic response analysis. The framework also involved two failure modes (bending and overturning) and the corresponding failure criteria so that the risk of forest damage could be assessed.

Using the proposed framework, we assumed conditions to investigate the air blast power. Modeling results demonstrate that although the anchorage properties significantly influence the tree eigenfrequency, the latter is always in the same order as air blast frequency. The associated dynamic magnification effect amplifies the tree deformation and thus makes the tree damage easier. In the scenario with a similar

frequency between air blasts and trees, an air blast travelling at 20 m/s causes a similar force of destruction as a long-duration wind load moves at 25 m/s. Notably, this magnification effect caused by the dynamic response and eccentric gravity is significant in the cases of low wind velocity, while the large tree deflection caused by strong air blast loading would weaken this effect. Furthermore, bending and overturning are two likely failure modes for trees subject to a powerful air blast, but exactly what kind of failure will occur for a specific forest depends heavily on the properties of both trees and soil. A case application was further performed on the 2008 Wenjia valley avalanche-induced air blast in China, checking the validity of our proposed model. In the future, more measurements should be conducted on biometric and mechanical properties of trees, and a regional parameter database is worthwhile to be established. This would greatly improve the prediction accuracy of tree damage and air blast pressure.

#### **Data availability**

No data sets were used in this article.

#### **Copyright statement**

All the photos/figures are created by authors and there is no need to add a copyright statement or credit.

#### **Author contribution**

Yu Zhuang did the numerical work and wrote the manuscript with contributions from all co-authors. Aiguo Xing and Perry Bartelt designed the work and modified the manuscript. Bilal Muhammad evaluated the results and proposed various improvements that were incorporated. Zhaowei Ding helped with the eigenfrequency prediction model.

#### **Competing interest**

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

## Acknowledgments

This study was supported by the National Natural Science Foundation of China (No. 41977215).

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