Sensitivity of Gyrescale Marine Connectivity Estimates to Fine-scale Circulation

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10 **Abstract.** We investigated the connectivity properties of an idealized western boundary current system separating two ocean gyres, where the flow is characterized by a well-defined mean circulation as well as energetic fine-scale features (i.e., mesoscale and submesoscale currents). We used a time-evolving 3D flow field from a high-resolution (HR-3D) ocean model of this system. In order to evaluate the role of the fine-scales on connectivity estimates, we computed Lagrangian trajectories in three different ways: using the HR-3D flow, using the same flow but filtered on a coarse-resolution grid (CR-3D), and 15 using the surface layer flow only (HR-SL). We examined connectivity between the two gyres, along the western boundary current and across it, using and comparing different metrics, such as minimum and averaged values of transit time between 16 key sites, arrival depths, probability density functions of transit times, and betweenness centrality. We find that when the fine-scale flow is resolved, the numerical particles connect pairs of sites faster (between 100 days to 300 days) than when it is absent. This is particularly true for sites that are along and near the jets separating the two gyres. Moreover, the 20 connectivity is facilitated when 3D instead of surface currents are resolved. Finally, our results suggest that western boundary currents are characterized by high betweenness centrality values, which confirms their key role in controlling the transfer of particles across ocean gyres. Our results emphasize that ocean connectivity is 3D and not 2D, and that assessing connectivity properties using climatologies or low resolution velocity fields yields strongly biased estimates.

1 Introduction

25 Solutions to a number of problems important to the marine environment require knowledge of connectivity, i.e., how distant ocean sites are connected to one other through transport by currents. Connectivity is important, for example, to understand the persistence of isolated populations and the flow of genetic information (Treml et al., 2008; Roughgarden et al., 1988; Gaylord and Gaines, 2000; James et al., 2002; Palumbi, 2003; Trakhtenbrot et al., 2005). This is all the more important that spatial and temporal patterns in the distribution of marine organisms are strongly influenced by differences or changes in 30 population connectivity (Treml et al., 2008; Levin, 1992; Warner, 1997). Quantifying connectivity is therefore essential for managing marine ecosystem protection. But connectivity is also useful for assessing pollutant dispersion from their sources

to other regions, for managing water quality, for planning pollutant release to coastal or offshore waters, and for assessing the evolution of oil spills (Mitarai et al., 2009; Fischer et al., 1979; Grant et al., 2005). In recent years, connectivity analysis has become a dynamic and rapidly evolving field of research in marine science and oceanography, partly because there is an increasing demand to inform effective assessment and management of marine resources (e.g., Hariri et al., 2022; Drouet et al., 2021; Bharti et al., 2022; Ward et al., 2021; Richter et al., 2022). Thus connectivity is usually understood as the exchange of individuals between remote marine populations, or transport of plastic, or more generally as the exchange of water masses and water properties (Froyland et al., 2014; Ser-Giacomi et al., 2015). In this work, we will evaluate connectivity in its most general definition of the exchange of particles between different sites.

Estimating connectivity from Lagrangian analysis requires the knowledge of Eulerian velocity fields. In the ocean, such velocities are either derived from satellite altimetry, from ocean general circulation models, or from ocean reanalyses, which combine the two (e.g., Poulain and Niiler, 1989; Swenson and Niiler, 1996; Dever et al., 1998; Blanke and Raynaud, 1997; LaCasce, 2008; Alberto et al., 2011; Watson et al., 2011; Mora et al., 2012; van Sebille et al., 2012; Hariri et al., 2015; van Sebille et al., 2018; Hariri, 2020; Hariri, 2022). The resolution of such products is often insufficient to fully capture the highly dynamical fine-scale portion of the ocean circulation. Also, many studies have limited the implementation of the Lagrangian approach to the surface layer (e.g., Treml et al., 2008; Mitarai et al., 2009; Jonsson and Watson, 2016; Dever et al., 1998; LaCasce, 2008; van Sebille et al., 2012; Poulain and Hariri, 2013; Drouet et al., 2021; Hariri, 2022). This can potentially induce strong bias in the estimates of connectivity, to the intense horizontal and vertical circulation associated with ocean mesoscale eddies and jets and with submesoscale features such as filaments and fronts.

Recent studies demonstrate the breadth of techniques and applications employed in ocean connectivity analysis and underscore the importance of this field in advancing our understanding of ocean dynamics; a variety of tools has been used, such as ocean circulation models, in-situ measurements, and numerical models, to examine the connectivity of diverse marine populations, identify subpopulations from connectivity matrices, and analyze biogeographical patterns along large-scale oceanic currents (e.g., Wang et al., 2019; Drouet et al., 2021; Novi et al., 2021; Ward et al., 2021; Cotroneo et al., 2022; Ser-Giacomi et al., 2021b; Hariri et al., 2022; Richter et al., 2022; Kot et al., 2022).

In this study, we assess how connectivity properties of typical ocean flows are affected by the fine-scale circulation, and highlight the challenges we face in estimating ocean connectivity due to lack of spatial resolution (both horizontal and vertical) of the flow field. We focus on mid-latitude open ocean gyres, typical of the subtropical and subpolar oceanic gyres of the North Atlantic, separated by the western boundary current Gulf Stream-North Atlantic drift system, or of the North Pacific, separated by the Kuroshio-Oyashu, which are regions where fine scales are particularly intense. Our results highlight the need for high resolution velocity fields to derive reliable connectivity estimates. In order to study the transport of numerical particles in a specific area, we conducted offline Lagrangian transport simulations. The study involved the release of these particles from regularly distributed sites in the region, and the simulations were run for a period of five years. To perform these simulations, we used the ARIANE quantitative Lagrangian approach (Blanke and Raynaud, 1997; Blanke et al. 2012) which integrates all spatial scales of the modelled velocity. In the published litterarure, marine connectivity has

been often assessed by defining relatively simple metrics based on Lagrangian integrations and "connectivity time" (e.g., Cowen et al., 2007; Froyland et al., 2009; Mitarai et al., 2009; Rossi et al., 2014; Jonsson and Watson, 2016; Ser-Giacomi et al., 2021). Furthermore, the theory of graphs has been emerging as a more objective approach to account for connectivity (Treml E.A., et al., 2008; Rossi et al., 2014). In this study we explore different of the more classical metrics based on time, as well as one specific formulation of the graph theory that has been previously applied to map connectivity in marine systems and that seemed particularly appropriate to our case-study (Costa et al., 2017; Ser-Giacomi et al., 2021a). The latter is based on betweenness centrality which allows to focus on areas where a relevant amount of transfers across a graph (a specific location in the domain) passes through.

The paper is organized as follows: the model and methods used to measure connectivity are described in Section 2, the results are presented in Section 3, and the discussion and conclusion are presented in Section 4.

2 Data and methods

The impact of the fine-scale circulation is evaluated by comparing connectivity estimates derived from a full 3D high resolution velocity field, with estimates based on velocity fields where the resolution is degraded, either horizontally or vertically. The high-resolution (HR) velocity fields are derived from a HR ocean circulation model. Using this velocity field, we carry out offline Lagrangian transport of numerical particles released in a set of regularly distributed sites in the study region.

2.1 Data: The ocean circulation model fields

The ocean circulation was generated with the state-of-the-art ocean general circulation model NEMO (Madec et al., 1998). The model domain is a 2000x3000 km rectangle, 4 km deep, rotated 45°, with closed boundaries. The model was forced at its surface by prescribed seasonal buoyancy fluxes and winds (Lévy et al., 2012a). The model equations were solved on a grid with a resolution of 1/54° on the horizontal. This allows the simulation of mesoscale and submesoscale dynamical structures with an effective resolution close to 1/9° (the smallest size of the structures which are captured by the model outside the dissipative range, is less than the grid resolution on which model equations are discretized and solved) (Lévy et al., 2012b). The model grid consists of 30 vertical levels, with thicknesses ranging from 10 m to 20 m in the upper 100 m, increasing to 300 m at the bottom. The model equations were integrated for 50 years. In this study we used the last five years of model outputs, which were saved every two days at the effective model resolution, i.e., on a 1/9° grid.

The time-averaged solution of the model shows two large oceanic gyres, a subtropical gyre in the south with an anticyclonic circulation, and a subpolar gyre in the north with a cyclonic circulation, separated by a strong zonal jet, and a series of secondary zonal jets. This horizontal circulation in the surface layers is characteristic of the North Atlantic or North Pacific, the strong jet being the equivalent of the Gulf Stream or Kuroshio. It should be noted, however, that our domain is smaller than that of these two ocean basins. The model velocities are highly turbulent, and show strong variability at the daily scale,

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and on horizontal scales < 1°. This mesoscale turbulence is characterized by strong jet oscillations, the formation of secondary jets, eddies and filaments between eddies, and is associated with intense vertical movements.

In order to assess the impact of this fine-scale circulation on connectivity, we filtered this velocity field on a 1° grid to remove all variations with scales smaller than 1° and compared the connectivity analyses performed with unfiltered (hereafter high-resolution HR) and filtered (hereafter coarse resolution CR) velocities. Filtering was done according to Lévy et al. (2012b), to preserve averaged velocities, and was applied only in space and not in time to conserve seasonal and higher frequency variations.

Figure 1 shows a snapshot of the surface vorticity and vertical velocity on March 31 of the first year of the simulation. With full resolution of the velocity field (HR), the flow is organized with a large number of eddies covering a wide range of scales, displaying filamentary structures resulting from their nonlinear interaction. The more intense small-scale activity develops in the vicinity of the two jets, the first one located at around 30°N, and the second at 35°N. Fig. 1a illustrates the importance of meso- and submesoscale structures in shaping currents, in setting scales of spatiotemporal variability and dynamical regimes. Importantly, these features are associated with intense vertical currents (Figs. 1c). When these highly turbulent currents are filtered on a coarse resolution grid, the vorticity is smoother and mainly related to the position of the main jets (Fig. 1b), and the vertical velocity is one to two orders of magnitude smaller.

2.2 Methods

2.2.1 Simulation of trajectories

In this paper, the focus is on the analysis of ocean connectivity from Lagrangian numerical particles (Fig. 2 and Fig. 3a) deployed at different defined sites across the double-gyre current configuration, located in key areas of the circulation (Fig. 3b). For this purpose, the positions of the numerical particles at each time step (i.e., every day) were calculated using the Lagrangian tool ARIANE (http://stockage.univ-brest.fr/~grima/Ariane/). ARIANE is an open-source, off-line three-dimensional Lagrangian particle tracking model written in Fortran, and is compatible with many OGCM outputs. It works by interpolating velocity values to a given particle position using an analytical scheme and advects the particle over a user-defined time step. A description of the algorithm is given by Blanke and Raynaud (1997) and Blanke et al. (2001).

Sites were defined as circular regions of 1° radius. This size corresponds to the grid size of the coarse-resolution velocity field. A total of 100,000 particles were deployed in each site. Such a large number of particles and the wide size of each site reduces the sensitivity of the results to the exact location of the initial position and provides statistically more robust estimates. We used 1,600,000 particles for each Lagrangian experiment. Based on the Lagrangian tool, ARIANE, particles reaching domain boundaries continue their movement along the model closed boundaries. The frequency of particle release was specified with random initial times while the minimum duration of trajectory tracking was one year (the maximum

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integration time was five years). Particles were released every 1 m from the surface to the base of the mixed layer, yielding a total of 150 release locations over this depth (667 particles per meter) (Fig. 2).

130 We analyzed and compared the properties of three sets of Lagrangian experiments, one performed using the full resolution of the velocity field in 3D (HR-3D), one performed using the filtered velocity field (CR-3D), and one using the full resolution surface-only velocity field (HR-SL).

2.2.2 Sites specification

Sites were distributed in key regions of the flow, in order to examine and contrast connectivity properties between the two
135 gyres, along the main jets, and across the jets. The exact location of the sites is arbitrary, but in order to have reliable results, we choose more than one site to represent each key region of the domain. More precisely, three sites were located along the main jet (-85°~-68° W and 27°~32° N) on the western side of the basin (sites 10, 11 and 12, Figure 3b) and two sites were located upstream of the secondary jet (-81°~-60° W and 33°~35° N) at locations with lower kinetic energy (sites 5 and 6), in order to study connectivity between different parts of each jet, for example from the tails (ends) of the jets to their heads and
140 back (see Figure 3). In addition, other sites between the jets were selected to calculate connectivity properties between gyres (sites 1 to 4 in the subpolar gyre, sites 7 to 9 in the inter-jet region, sites 13 to 15 in the subpolar gyre). Also, five sites (1, 3, 8, 15, and 16) were aligned along the model diagonal to determine the transfer time from north to south and vice versa (Fig. 3b), but three other sites (2,7,13) can be used for the same purpose.

145 ### 2.2.3 Lagrangian indices

Different approaches, all based on the tracking of passive Lagrangian particles, have been used to quantitatively measure connectivity between different marine sites, e.g., Lagrangian probability density functions (PDFs) (Mitarai et al., 2009; Froyland et al., 2009; Ser-Giacomi et al., 2021), transport networks (Rossi et al., 2014) and characteristic time scales (Jonsson and Watson, 2016). Some of these methods rely on the general definition of "connectivity time," which depends on
150 oceanographic distances and is often estimated as the mean time required for particles to move from one location to another (Cowen et al., 2007; Mitarai et al., 2009). However, in the global ocean, mean and median transit times are not well defined because each particle deployed at a given location will eventually reach all other areas of a defined domain over a sufficiently long time (Jonsson and Watson, 2016). To address this, Jonsson and Watson (2016) proposed to use the "minimum connectivity time" (Min-T), defined as the fastest travel time from source to destination for numerical particles,
155 inferred from a Dijkstra algorithm (1959). This minimum connection time shows good correspondence with genetic dispersal in marine connectivity (Alberto et al., 2011). The benefit of using the minimum connection time rather than the average transit time has been shown in previous empirical work (e.g., Mora et al., 2012; Mitarai et al., 2009; Döös, 1995; Cowen et al., 2007). Following up on these previous advances, in this study, we focus on mean and median values of minimum connectivity time for all particles traveling from one given site to another in order to obtain a clear picture of transit times.
160 Furthermore, dispersion patterns of the numerical trajectories show the main effects of the particle release position and ocean

circulation on the strength and persistence of connections between site pairs. Specifically, we will provide a comprehensive matrix containing analyses of the mean, median and most frequent values of the minimum connection time between each selected area seeded with numerical particles.

2.2.4 Lagrangian PDF

165 The Lagrangian PDF approach is useful to examine the dispersion of particles by turbulent phenomena. It has been widely used in fluid mechanics (e.g., Pope, 1994; Mitarai et al., 2009; Froyland et al., 2009; Ser-Giacomi et al., 2021b). This method relies on the probability that particles have moved from one location to another during a given time interval. Since the PDF values provide an estimate of the mean dispersion properties of the numerical particles, a correct estimation of the PDF values requires a large number of trajectories (Mitarai et al., 2009), For the purpose of our study, 100,000 particles were

170 assigned to each site. This number was set to have a significant number of particles for the connectivity estimates but was, however, limited to remain computationally manageable. The Lagrangian PDF for each site is obtained by: (Mitarai et al., 2009)

$$LagrangianPDF(\xi, t) = \frac{n_\xi(t)}{N * S_\xi} \tag{1}$$

where ξ is the sample space related to the discretion of Lagrangian PDF (here, a sample space of ~ 1 km^2 is applied for

175 the calcutaltion of the PDF fields), S_ξ is the area of the sample space ξ, N is the total number of Lagrangian particles, and $n_\xi(t)$ is the number of particles residing in the sample space ξ at the simulation time t.

2.2.5 Betweenness centrality

180 By representing portions of the sea as nodes and the transfer probabilities between them as edges allows us to apply graph theory to the study of marine connectivity. More specifically, by applying the betweenness centrality in graph theory, it is possible to identify the ocean areas that play a key role in controlling the transport within the connectivity network (Freeman, 1979; Girvan and Newman 2002, Ser-Giacomi et al., 2015; Costa et al., 2017; Lindner and Donner, 2017; Ser-Giacomi et al., 2021a). Indeed, betweenness centrality is a mathematical measure used in network analysis to assess the

185 importance of a node in a network based not only on the "proximity" (in terms of physical or time distance) to all other nodes in the network but it allows also to identify those nodes that act as bridges in connecting the other nodes, measuring their "strength" in terms of "relationship" (then the definition of "shortest" paths retains its simple interpretation). Betweenness centrality has become the subject of recent studies in oceanography, applied to assess the role of different regions in the global ocean in terms of water masses transport, or to evaluate ocean ecosystem connectivity (Gamoyo et al.,

190 2019; Ser-Giacomi et al., 2021a), to identify ocean regions apt to become marine protected areas (MPAs) (Assis et al., 2021, Ospina-Alvarez et al. 2020). Despite its usefulness, it's essential to note that betweenness centrality is one of several

measures that can be used to assess node importance in a network, and its results may depend on the mathematical formulation of the weights associated to the edges (connections among the nodes) and it does not always align with other measures like degree centrality or closeness centrality (Costa et al., 2019).

To identify the sites that controls ocean transport in our study-case, we applied the betweenness centrality formalism and visualized our sites as nodes in a connectivity network (the latter referring to a system of interconnected regional ocean processes that facilitate the exchange of water, nutrients, organisms, and other materials between different regions of the ocean: Freeman, 1977). This formalism accounts for the number of shortest paths between pairs of nodes (sites) that pass through a particular node, allowing us to identify critical links between sites (Treml et al., 2008). We followed the approach of Costa et al. (2017) by applying the betweenness centrality measure to 32 sites, using 20 different connectivity matrices obtained from Lagrangian simulations. The purpose of using "betweenness centrality" is to ensure that the most probable shortest paths (e.g., Ser-Giacomi et al., 2015) between two sites are identified. Such sites are the ones through which a high number of similar water trajectories pass and that are therefore crucial in controlling to the overall network connectivity.

The betweenness value of a node k, $BC(k)$, is defined as the fraction of shortest paths existing in the graph, σ_{ij}, with $i \neq j$, that effectively pass through k, $\sigma_{ij}(k)$, with $i \neq k \neq j$:

$$BC(k) = \sum_{i \neq k \neq j} \frac{\sigma_{ij}(k)}{\sigma_{ij}} \tag{2}$$

It should be mentioned that the betweenness value is normalized by $(N-1)(N-2)$, where N is the number of nodes in the graph, thus $0 \leq BC \leq 1$.

The matrix used for the network analysis to determine the betweenness centrality is based on raw transfer probability. The calculation of betweenness was based on the methods defined by Costa et al. (2017). All of the trajectories deployed from all sites were used together to calculate the betweenness values, instead of using different matrices (1,600,000 trajectories). For each site (node), the betweenness values were determined based on the node/edge measure definition. Initially, raw transfer probabilities (a_{ij}) were used as edge weight, with the weight decreasing as the probability decreases (whereas the transport probability should be defined from the amount of particles that travels from node i to j). However, this method, as noted by Costa et al. (2017), has a drawback in that high betweenness could be associated with nodes through which a high number of improbable trajectories pass. To address this issue, we applied the new metric, suggested by Costa et al. (2017), which transforms transfer probabilities a_{ij} into a distance. This involved reversing the order of the probabilities so that higher values of the old metric correspond to lower values of the new one. Based on this method the the weight of the edge defined between two nodes i and j is given by:

$$d_{ij} = \log\left(\frac{1}{a_{ij}}\right) \tag{3}$$

The raw transfer probabilities a_{ij} were calculated considering the position of the particles only at the beginning and at arrival at the final destination. Additionally, the calculation of transfer probabilities between nodes i and j is independent of the previous node where the particle was before arriving at node i (we only concentrate on two nodes here for sake of simplicity: i and j). The calculation of the shortest paths involves the sum of a variable number of transfer probability values. We used the Dijkstra algorithm, which is one of the most commonly used algorithms.

3 Results

3.1 Transit times

A quantitative assessment requires some degree of simplification due to the multiple spatial and temporal scales involved. In this framework, it is useful to determine the probability distribution of the numerical particles deployed from the different sites for different integration times (see Fig. 4 for the results obtained for site 1). After the first week of deployment, the concentration of numerical particles is larger around the starting positions, as expected. After six months, the particles move a short distance from their initial positions and spread over 5~10 degrees of longitude, depending on the flow velocity. When particles are close to strong jets, they disperse very rapidly (2~6 months), whereas in other parts of the basin, due to slower and less energetic velocities, the dispersion occurs over a longer period (1.5 ~ 2 years).

One and a half years after their release, the particles deployed from the subpolar gyre (site 1) have dispersed in the entire subpolar gyre and have also penetrated in the subtropical gyre, along its eastern edge. Regardless of the initial deployment position, 3.5 years after deployment, almost all particles are concentrated along the two intense jets that separate the two gyres (supplementary Figs. S1-S5). For particles leaving site 1, the probability that they reach sites 2, 3, and 4 after 2 years, along the basin diagonal, is between 0.2% and 0.8%, and for sites 5, 6, and 14, it is about 0.5%. This means that connectivity between these sites and site 1 is achieved in less than 2 years. A uniform PDF distribution after 2.5 years for the particles from site 1 shows that in less than 900 days they have spread across more than 75% of the basin. We also note that with longer particle lifetimes, the PDFs show similar behavior compared with the other sites (Fig.4). After 1.5 years, particles are mostly on the eastern side of the basin, moving slowly southward due to less energetic flow in these areas (Figs. 4c, 4d).

In contrast, particles deployed in the main jet (supplementary Fig. S4) remain mostly close or move slowly to the southern basin during all simulation times. This pattern reveals the strong influence of the jets on particle movement. For this case; the PDF has the highest values in the jet area and in the subtropical gyre. After 5 years, the lowest PDF values for particles reaching the jet and the subtropical gyre are associated with particles initially deployed along the western boundary of the subpolar gyre (e.g., site 2). In conclusion, the PDFs show that particles spend long periods of time in the subtropical gyre, indicating that this regional retention by the highly energetic nonlinear ocean dynamics prevent rapid dispersion in all other regions. This significantly increases the mean particle transit times.

3.2 Comparison of connectivity properties between HR-3D and CR-3D

3.2.1 PDF histogram for HR-3D and CR-3D

Figure 5 shows the PDFs of the transit times of particles traveling between selected sites for HR-3D and CR-3D. The PDFs are not Gaussian and are skewed with a long tail. Fig. 5a shows the PDFs of the particles deployed at site 1, in the centre of the subpolar gyre, arriving at site 15, in the centre of the subtropical gyre, whereas Fig. 5b shows the reverse connection, i.e., for the particles deployed at site 15 traveling to site 1. For HR-3D the first particles reach site 15 after about 200 days, and most particles reach this site after about 600 days and the latest particles continue to arrive at site 15 after 1600 days. The CR-3D PDF is shifted in time with respect to HR-3D, with particles only reaching site 15 after about 300 days. The width of the CR-3D PDF is broader than that of the HR-3D, suggesting a larger but slower spread of particles across the domain before reaching site 15. The median transit time from site 1 to site 15 is 751 days, while the minimum transit time in this direction is 201 days. The Lagrangian connections for particles deployed in site 15 and reaching site1 (i.e., connectivity in the opposite direction as for the previous case) show a longer transit time and a greater spread for both simulations (Fig. 5b). The CR-3D PDF shows an even larger delay in arrival time compared to HR-3D.

For HR-3D, the mean time required for particles to travel along the basin diagonal from the subpolar gyre to the subtropical gyre (i.e., from site 1 to site 15) is about 796 days, and the modal time is 559 days, compared to 989 and 1262 days, respectively, for the reverse connection (i.e., from south to north, site 15 to site 1). This means that the northward movement along the diagonal is faster than the southward movement. The PDFs distributions cover almost the same time range, although the general shape is different. The same transit times (mean and most frequent values) for CR-3D are 891 and 644 from north to south and 1162 days and 1315 from south to north. The minimum time required for particles from south to north (site 15 to site 1) in the HR model is 153 days shorter than in the CR model (201 vs. 355 days).

To compare the Lagrangian connectivity between the most distant sites with the sites closer to each other and within the main jet ([30° N, -85° W], [30° N, -70° W] ,where the mean energy and eddy kinetic energy show the highest values) we computed the transit time statistics between sites 10 and 12. The results are shown in Fig. 5c for the direct connection (site 10 to site 12) and in Fig. 5d for the opposite direction (site 12 to site 10). They suggest that the connection along the eastward jet is faster (as expected): the first and largest number of particles arrive within 10 days in HR-3D, whereas for CR-3D the arrival time of the first particles is longer (40 days) and the PDF distribution is larger.

As foreseen, the intense and highly energetic eastward jet moves the particles very rapidly eastward, although fine-scale circulation (mesoscale eddies and filaments) generated at the edges of the jet disperse the particles that reach site 12 almost continuously (albeit in decreasing numbers) until about 1400 days. The minimum and median transit times for the HR-3D simulation are 11 and 348 days, while these values are larger for CR-3D (64 and 213 days, respectively). The CR-3D velocity field induces slower connections because the peak velocity of the jet is lower and its width larger. The connection time in the coarser velocity field is relatively continuous until about 1300 days. This can be explained by the particles traveling through the larger-scale recirculation cells of the subpolar and subtropical gyres before reaching site 12.

In contrast, the HR-3D and CR-3D PDFs have a more similar shape and distribution for the opposite (westward) connection, with the first particles reaching site 10 from site 12 in less than 50 days and 452 days on average and 546 days in median time (Fig. 5d). The minimum and mean transit times for particles from site 12 to site 10 are longer. The modal value is 260 days, and the median transit time is 398 days. The similarity in connectivity behavior for the opposite (westward) connection for both velocity fields suggests that the particles move through the mean larger-scale recirculation cells and follow the common pathways.

The above PDF results for both simulations (HR-3D and CR-3D) clearly show the impact of the ocean fine-scale dynamics which increase the efficiency of the current advection and accelerates the particle motion; in this case, for the CR-3D simulation, the PDFs of transit times are wider with longer mean and minimum transit times due to insufficient resolved turbulent motions.

3.2.2 Minimum and median transit time as a function of geographical distance

Fig. 6 shows the minimum and median values of transit time as a function of distance computed in HR-3D for sites along the basin diagonal. The results indicate that with increasing distances, the transit times (minimum and median) increase linearly. For the particles initially deployed from site 1, the results show almost the same behavior for median and minimum time, except for connections between site 1 and sites 12 and 15. The shortest minimum transit time in a diagonal direction is from site 8 to site 12 with a value of 2 days. The fastest connection based on median transit times is from site 8 to site 5, with a value of about 95 days. The minimum transit times from south to north and north to south are almost identical (about 200 days). The longest minimum transit time is for the particles moving from site 12 to site 1, 240 days, with a median value of 1109 days. This suggests that the intense fine-scale circulation facilitate connections between site 8 (which is located in the middle of the diagonal transect) and site 12 (at the eastern end of the main jet) and slows those between sites 8 and 5 (a median transit time of 225 days versus 95 days). In general, the Lagrangian transit times (median and minimum) for a site pair located at the same distance along the basin diagonals differ. Such a difference arises from the complex trajectories followed by the numerical particles and induced by the small-scale simulated dynamics. On the other hand, for sites pairs located at shorter distance (less than 6 degrees), the minimum transit time is less than 55 days, regardless the site location.

To assess more quantitatively the differences in connectivity between HR-3D and CR-3D, Fig. 7 shows the comparison of minimum and median transit times computed for a subset of sites for the two Lagrangian simulations. The results clearly indicate that the minimum and median transit times in HR-3D are significantly lower than for the coarse-resolution configuration. In HR-3D, the resolved nonlinear dynamics induce intense currents, and the particles move much faster than in CR-3D, in particular for the sites located along the two main jets. Fig. 7 suggests that for distant sites, CR-3D will not provide realistic information about the connection time between sites. The lack of fine-scale motions in the coarse-resolution simulation leads to significant delays in the advection of numerical particles, especially in areas where mesoscale variability plays an important role in particle displacement. The results obtained for particles deployed from site 15, for short-range connections (distances less than 10 degrees), show a better match for the median transit time for both configurations, HR-3D

and CR-3D. Based on a minimum connection time of less than 50 days, there is some convergence between HR-3D and CR-3D for particles deployed from site 1, whereas large differences arise for distances greater than 6 degrees and for areas that include hotspots of high eddy kinetic energy. In addition, in HR-3D, the particles disperse not only faster but also more uniformly than in CR-3D, which reduces transit times between sites. From south to north along the diagonal, the results of both simulations (median values of transit times) are similar, showing that in this direction particles follow pathways less affected by small-scale ocean instabilities.

3.2.3 Examples of depth arrival PDF for HR-3D and CR-3D

Connectivity studies of marine ecosystems commonly integrate Lagrangian trajectories using 2D surface velocity fields because the focus is on passively drifting biological species (plankton, fish larvae, algae …). We test here the robustness of such a strong assumption by integrating Lagrangian particles in a 3D framework: For each site at the initial integration time step, particles are distributed over the water column extending from the surface to the base of the mixed layer (which can be as deep as 150 m). Then, the particles are advected by the 3D flow, without any depth constraint. In this way, we can test whether particles in the upper ocean remain at the same depth throughout their journey and thus confirm or invalidate the soundness of using 2D and not 3D velocity fields for marine ecosystem connectivity estimates.

Figures 8a and b show the PDFs of the mean arrival depth of particles initially deployed from site 1 and arriving at site 15 (left panel), and in the opposite direction from site 15 to site 1 (right panel). Our analysis indicates that the majority of particles in both simulations remain in the depth range below 165 meters without moving much deeper, although the peak is deeper in the south-to-north motion for HR- 3D and CR-3D and is quite noisy.

The HR-3D and CR-3D PDFs (Figs. 8a, b) indicate that the particles are almost twice as deep in the south-north connection as in the north-south connection. From south to north, a small percentage of the particles reach the bottom layer (more than 450 meters deep) where frictional processes alter the dynamics and thus play an important role in the transit of the numerical particles. These processes do not appear to play a role in the north-south movement.

The PDF of the mean arrival depth of particles deployed from site 10 to site 12 (Fig.8c) shows that for the trajectories simulated by the high-resolution fields there is a tail that extends down to 175 meters, with a slightly higher percentage of particles in the subsurface layer compared to the CR results, and the particles in the upper layer tend to travel faster than those are at greater depths, as velocities decrease with depth.

On the other hand, although the mean PDF of arrival depth for particles moving from site 10 to site 12 shows the same behavior in the HR and CR 3D velocity fields, in the opposite direction (site 12 to site 10) the PDF distributions for the two simulations are completely different, considering that the distribution is overall flatter in CR-3D than in HR-3D with a long tail extending to 380 meters in depth.

A comparison of the mean arrival depth of the numerical particles deployed from site 12 to site 10 (Fig. 8d) in the HR case shows that the majority of the particles remain within 50 meters of the surface layer, while in the opposite direction, some particles move to greater depths, up to 150 meters. Furthermore and as already mentioned, the numerical trajectories

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simulated in CR are relatively uniform across the upper layer where they were initially seeded. Indeed, in CR, more than 70% of the particles deployed from site 12 and arriving at site 10 remain close to the surface mixed layer and the subsurface, where the effects of turbulence at different scales on the numerical particle distribution are more detectable.

Mainly, for all cases examined, in HR-3D, the particles tend to remain in the subsurface layer due to the larger effects of coherent vortices as well as other structures such as filaments and eddies. The PDFs of arrival depth indicate that the differences between HR-3D and CR-3D are not limited to the arrival time, but are also detectable on different 3D pathways for each case, resulting in significant changes on the arrival depth. Thus, we can add that the depth results differ depending on the direction of motion. Also, the peak for all HR-3D cases is at the depth of less than 10 meters except for the south-north motion, which shows that in this direction, the particles move more in the vertical direction due to weaker stratification at depth and less turbulence in the surface layer.

3.2.4 Mean connection time fields for sample sites

The mean connection times from three sites (north, west, and south of the basin) are shown in Figure 9. Fig. 9a shows that the particles from site 1 follow pathways that require the longest time to connect to sites in the subtropical gyre and western boundary current regions, such as sites 10, 11, 12, 13, 15, and 16. The particles reached a depth of 150 meters from the surface layer near the eastern side of the basin between (-60°~-55° W) and (37.5°~42.5° N) near site 4, although the transit time from site 1 to site 4 was less than 300 days (not shown). Particles deployed from site 1, moving from south to north, take almost 500 days, while they take about 400 days to travel the same distance from north to south. The shortest mean transit times are between sites 1 and 4, and between sites 1 and 3, both less than 350 days, while the longest connections (from site 1) are associated with sites 10 and 11 (944 and 915 days respectively). This was expected since these sites are located along the strong jet. Note that the mean arrival depth for the shortest transit time is about 35 meters (not shown), while for the longest transit time, the mean arrival depth is over 100 meters below the surface layer. For site 1, the mean transit time is 1.25 times greater in CR-3D than in HR-3D. Figures 9a and 9d show similar distributions, although the connection times between site 1 and sites between 30° and 40° latitude and -72.5° and -62.5° longitude differ significantly.

Figure 9b shows the mean arrival time from site 10. As shown in the mean transit time map, a large area connecting the southwestern region to the north-eastern region has the lowest values. This clearly shows the direct connection of the particles seeded in the main jet, which travel fast and reach these areas rapidly. For these regions, the mean arrival depth values were less than 70 meters (not presented here). The longest connection times are associated with sites 1 and 16 for particles that initially started from site 10. These particles took over 1200 days to arrive north of site 1 and appear to be in a shadow dynamical region that is not directly connected to the jet. The results are similar in CR-3D for site 10, although the transit time is significantly higher in the coarser simulation than in the finer resolution simulation (Figs. 9b, 9e).

Figures 9c and 9f show the mean transit time of particles initially deployed from site 15 to other sites for HR-3D and CR-3D. The distribution is remarkably different. In the CR-3D simulation, the connection is fast in the southernmost region and does not allow some transit times to be modelled acceptably, such as the motion from site 15 to the areas around site 16, and from

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site 15 to the northern part of the basin (north of site 1). This figure clearly indicates that the particles in CR-3D move in a less dynamical velocity field, especially for trajectories moving from south to north and from south to west. The shortest connection time from site 15 and site 14 in HR-3D is less than 13 days, while it is 50 days for CR-3D.

In all simulated cases, we were able to differentiate the impacts of highly energetic small scales on particle transit times between different sites. As shown in the surface vorticity snapshots in Fig. 1, filamentary structures and small eddies in the jets separating the two gyres and the subpolar region act as transport barriers, for example for particles traveling from site 15 to site 1.

3.3 Betweenness centrality

Figure 10 shows the betweenness centrality values for 16 sites based on Lagrangian simulations for three different cases: HR-3D, CR-3D and HR-SL calculated based on d_{ij} as the edge weight suggested by Costa et al. (2017). It can be observed from Fig. 10a that the betweenness values for the sites in the network vary greatly. Sites 3, 4, 7, and 15, in particular, have the highest betweenness values, suggesting that they play a crucial role in connecting the other sites in the network. This finding highlights the significance of these sites in the network structure, as particles are most likely to pass through them as they traverse from one site to another.

Furthermore, the network matrix generated using the edge weight suggested by Costa et al. (2017) provides a visual representation of the relationships between sites (Fig. 10b). In Fig. 10 b, the direction of the element d_{ij} is shown by the arrows starting from node *i* and ending at node *j*, with the color code of the arrows representing the magnitude of the edge weights. We utilized a site-to-site (node-to-node) metric to calculate the shortest paths, using transfer probabilities obtained from Lagrangian simulations. This matrix provides valuable information for understanding the structure of the network and can be used to inform future simulations and analyses. The network matrix identifies critical nodes and edges in the network, which are crucial for maintaining its connectivity and efficiency. This information can be used to develop strategies for improving the resilience of the network, by strengthening these critical nodes and edges.

Comparing the betweenness values between the three cases, HR-3D, CR-3D, and HR-SL, reveals that the HR-3D case has the highest betweenness values. This difference can be attributed to the highly variable 3D flows that strongly shape connectivity and which is smoothed out in CR-3D and not taken into account by the purely 2D flow case (HR-SL) . This result emphasizes the significance of taking into account the highly nonlinear, three-dimensional ocean dynamics, and highlights the importance of considering these factors in applying network analyses.

Moreover, the differences in betweenness values between the three cases (HR-3D, CR-3D, and HR-SL) can be used to evaluate the impact of various factors on the network structure. The analysis provides a comprehensive understanding of the network structure and functioning, and can inform future simulations and analysis.

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3.4.1 Comparison of transit time between site pairs for HR-3D and CR-3D

To complete the study, we compared the minimum and median transit times for all defined sites in the basin. We evaluate the sensitivity of the transit time matrix to the currents provided by two different cases: HR-3D and CR-3D. Specifically, in this section, we provide a complete matrix containing the analyses of the median and minimum connection time between each selected area seeded with numerical particles.

Figure 11 provides in an overview of the structure and time characteristics of the connectivity between sites. It shows that the connectivity between the northern and the southern sites is the weakest (the connection is the longest in terms of both the minimum and median times) and it is not symmetric. The longest connection is between the northern and southern sites. The fastest connection is along the main jet (site 10 to site 13). This matrix also highlights the difference in the definition of connectivity when applying the minimum or the median time. The latter is three to four times larger than the first. Moreover, the minimum time for CR is slightly larger than for HR, and varies between 10 days and 4 months. The difference increases notably for the median time, including along the principal jet (with a delay in arrival time ranging from 1 to 6 months).

The longest connection is for particles moving from the northern edge of the subpolar gyre (site 1) to the easternmost region between the two zonal jets separating the gyres (site 9), with minimum and median transit times of 516 and 1131 days respectively for HR. For CR and for the same sites, these times increase by an additional 30 and 164.5 days, respectively. On the other hand, the shortest connection is between sites 6 and 5, along the northern zonal jet, where we obtained for HR 1 and 13 days as minimum and median transit times, respectively. Note that this result is related to an increased efficiency of the particle advection due to the resolved small-scale nonlinearities, which seem to be particularly active in this part of the basin. The resolved small scales act as stirring structures that accelerate the movement of particles around, for example, the peripheries of mesoscale eddies and along filaments. In addition, areas with longer transit times show larger differences between HR and CR (for example, departures from sites 14,15 and 16 and arrivals at sites 1, 2, and 3).

3.4.2 Comparison of transit time matrices for HR-3D and HR-SL

To determine whether the Lagrangian properties of oceanic flows can be evaluated in a 2D (limited to the surface layer of the ocean), rather than by including the full 3D framework, we compare connectivity properties between defined sites for 2D and 3D high-resolution simulations (Fig. 12 and supplementary Fig. S6). The results show that the transit times for numerical particles deployed in the surface layer are generally shorter than those for particles that started in deeper layers (3D), although there are some exceptions such as the motion from site 2 to site 6 and 7: in this direction, a high percentage of particles in the surface layer need a longer transit time to reach the final destination than similar particles in deeper layers. This is due to vertical fluxes associated with the displacement of isopycnals by internal dynamics (e.g., eddy pumping or eddy/eddy interaction). Therefore, areas with similar values of connectivity properties in the 2D and 3D simulations suggest that vertical motions for these regions are not strong enough to add complexity to trajectories.

Although, there are many similarities between the median transit time matrices for the HR-3D and HR-SL cases (Fig. 12), the distribution of the betweenness values shows differences (Fig. 10); the main reason is related to vertical movements; in other words, the vertical dimension of the trajectories that exists in HR-3D gives the possibility to establish more pathways between the different areas. This result provides important insight into connectivity properties in the ocean: while 2D

450   simulations provide useful information on transit times, it is necessary to understand the rate of connections using 3D simulations.

In conclusion, both 2D and 3D ocean connectivity are important tools for understanding the movement of water and other properties within the ocean, but 3D connectivity provides a more complete picture by taking into account the full three-dimensional movement of water, and thus life.

4 Discussion and conclusion

Lagrangian connectivity analysis utilizes sets of numerical particle trajectories to identify connecting pathways, as well as time scales and transport between oceanic regions. This is a powerful tool to coherently study the connection between different areas in the ocean. The current study is one of the first large-scale studies to use high-resolution ocean flow data and particle tracking to describe connectivity patterns in a large-scale (although idealized) basin.

460   In this paper, the focus was on analyzing the connectivity of different sites in a double gyre ocean model, using a Lagrangian approach with numerical particles. Sixteen sites were specified and in each site 100,000 particles were used for the numerical analysis. Lagrangian properties such as mean, median and modal transit times were calculated to examine connectivity properties in the North Atlantic. In addition, the probability-density-functions (PDFs) of transit times and mean arrival depths for different simulations were compared. The analysis used high-resolution 3D velocity fields (HR-3D), or surface

465   velocity (HR-SL), or velocity fields averaged over a coarser resolution grid (CR-3D).

The Lagrangian PDF modelling approach was implemented for the sample sites in all the simulations. The particles have different trajectories to reach their final destinations due to the small-scale motions induced by the resolution of the fine-scale dynamics. The results indicate that particles that remain in the surface layer or near the subsurface layer move faster due to intensified velocities resulting from simulating the fine-scale circulation. In the deeper parts of the basin, particles

470   need more time to reach their final site, as at depth, the velocity intensity decreases due to the effect of the nonlinear dynamics. This finding is confirmed by comparing the PDF of the 2D surface layer simulation with other simulations.

Fine-scale movements, especially in the upper 50 meters of the surface layer, play an important role in particle motion. The numerical particles in the two simulations (HR-3D and CR-3D) show significantly different PDF distributions, especially for movement from the western part of the basin to the eastern part (e.g., from site 10 to sites 4 and 2, see supplementary Figure

475   S7). It was also found that the particles transported by the high-resolution velocity fields tend to move to deeper parts of the basin compared to the CR-3D simulation.

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In the 5-year simulation based on HR-3D velocity fields, the longest route was obtained for particles deployed from site 9 (in the eastern part of the Western boundary current extension) to site 1 (in the subpolar gyre), with an average transit time of 1145 days. This is due to less energetic flow in the areas close to these sites. In contrast, transit along the principal zonal jet

480 (site 10 to site 11) are among the shortest and fastest routes, with an average transit time of 179 days.

As expected, the numerical particles remain concentrated around their starting position during the first week after their deployment. But 3 years after their departure and independently of their initial deployment positions, almost all particles concentrate along the two zonal jets. These jets act as attraction hubs that eventually capture most of the particles. Based on the mean arrival depth at the sample sites, we can see that the particles move toward deeper depths in the interior of the

485 ocean, due to the strong nonlinear velocity fields that develop around these jets on the western side of the basin, with a direct impact on the vertical motion of the numerical particles.

Our results emphasize that because ocean circulation is turbulent at horizontal scales 10-100 km, it is not relevant to assess connectivity properties using climatologies or low-resolution (>100 km) velocity fields; moreover we show that connectivity in the ocean is not 2D but 3D, and that assessments based on 2D fields may alter significatively the results.

490 The betweenness values of 16 sites were analyzed in three different cases: HR-3D, CR-3D, and HR-SL. The analysis showed that sites 3, 4, 7, and 15 have the highest betweenness values and play a crucial role in connecting other sites within the network. The network matrix generated using the edge weight suggested by Costa et al. (2017) provides valuable information for understanding the network structure. Comparison of the betweenness values between the three cases revealed that HR-3D has the highest betweenness values due to the impact of the ocean small-scale and flow field resolution on the

495 network structure.

There are several open and unsolved questions related to the impact of small-scale flow variability on Lagrangian connectivity measures (i.e., the need for interdisciplinary approaches, incorporating physical oceanography, ecology, and mathematical modeling, to fully understand the impact of small-scale flow variability on Lagrangian connectivity; the importance of incorporating the impact of small-scale flow variability into ocean circulation models for accurate predictions

500 of particle transport; the relationship between small-scale flow variability and transport pathways of particles in the ocean) Lagrangian trajectories simulated with the coarse resolution velocity fields do not sufficiently show the effect of mesoscale eddies on particle dispersion, which results in unreliable Lagrangian indices (e.g., transit time) compared to estimates based on HR model simulations. The CR ocean flow simulation used in this study, with a spatial resolution of ~100 km, is inadequate to describe the mesoscale circulation. Yet, this fine-scale variability has been shown to significantly shape and

505 change the connectivity of the North Atlantic.

In this context, our results show that the use of high-resolution velocity fields, as opposed to coarse-resolution fields, resulted in a reduction of 39% in mean transit time. This suggests that the use of high-resolution velocity fields allows for a more accurate representation of the complex flow dynamics in the region and results in faster particle transport.

Moreover, the study also found that taking into account the full three-dimensional (3D) velocity instead of just surface fields

510 resulted in an increase of 8.4% in the mean transit time. This suggests that the vertical component of the velocity field

significantly affects the transport behavior of the particles, and that account of this vertical component leads to a more accurate representation of their transport patterns. Overall, these findings highlight the importance of considering the resolution and dimensionality of the velocity fields when studying the transport behavior of particles in the study region.

515 In conclusion, the present study highlights the importance of small-scale variability in determining patterns of connectivity and provides detailed information on Lagrangian connectivity in the North Atlantic. Our results can guide the spatial scales at which future OGCMs should be run for reliable connectivity analysis; moreover, for Lagrangian studies, we advocate refining OGCMs to the appropriate resolution with sufficient spatiotemporal accuracy.

Author contribution

SH and SP contributed to the data analysis and preparing the figures. SH, SP, BBL and ML contributed to the manuscript

520 writing and design of the Lagrangian experiments. All authors reviewed and accepted the final version of the manuscript.

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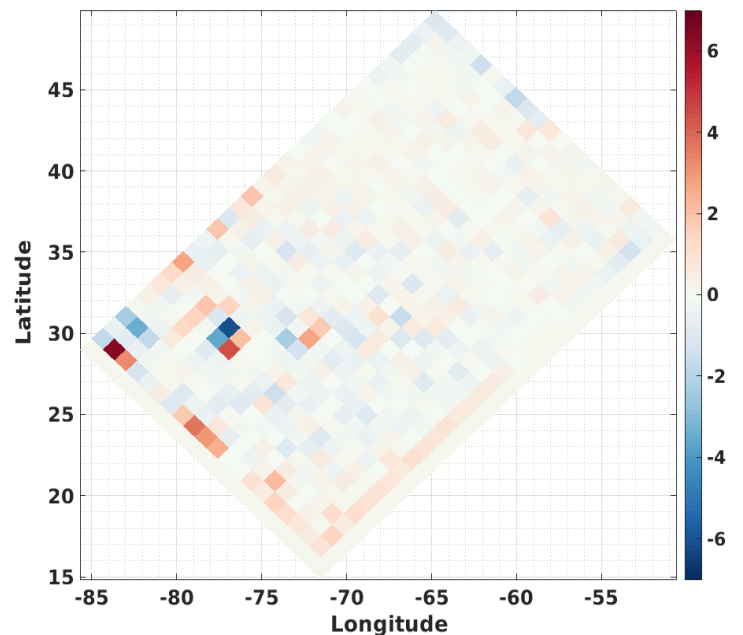
675 **Figure captions**

Figure 1: Snapshots on March 31st of a) Surface vorticity at high resolution (HR), b) Surface vorticity at coarse resolution (CR), c) vertical velocity at 40m at HR, d) and vertical velocity at 40m at CR.

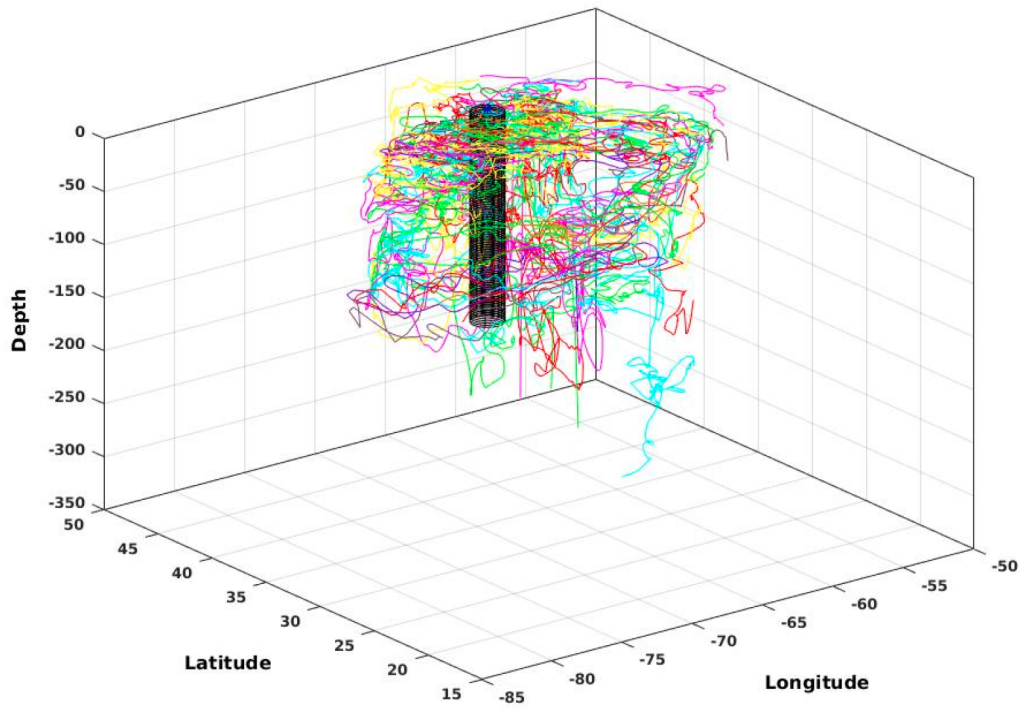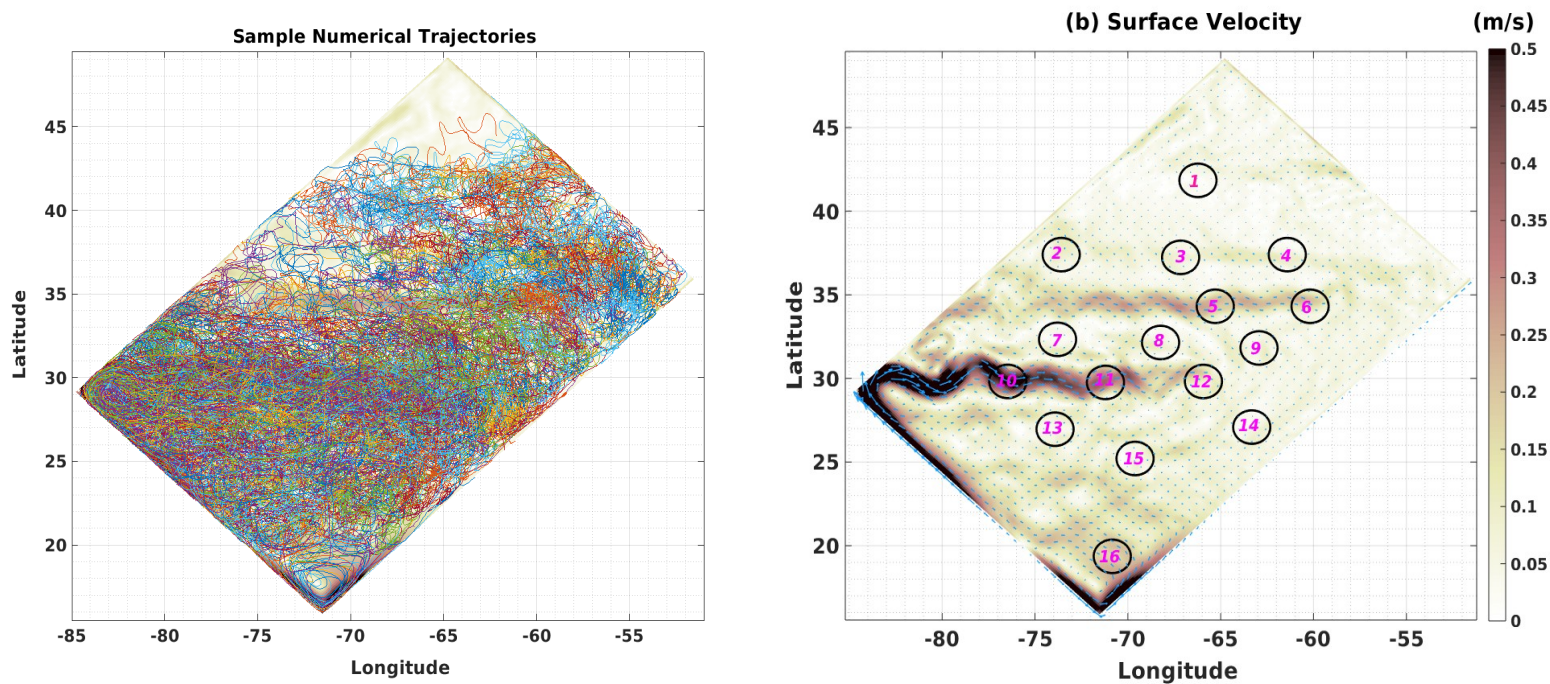**Figure 2:** Sample trajectories deployed from site 1 in HR-3D.

Figure 3: a) Dispersal of sample trajectories on the surface layer in HR-3D from site 13, (b) Annual mean speed and location of the sites.
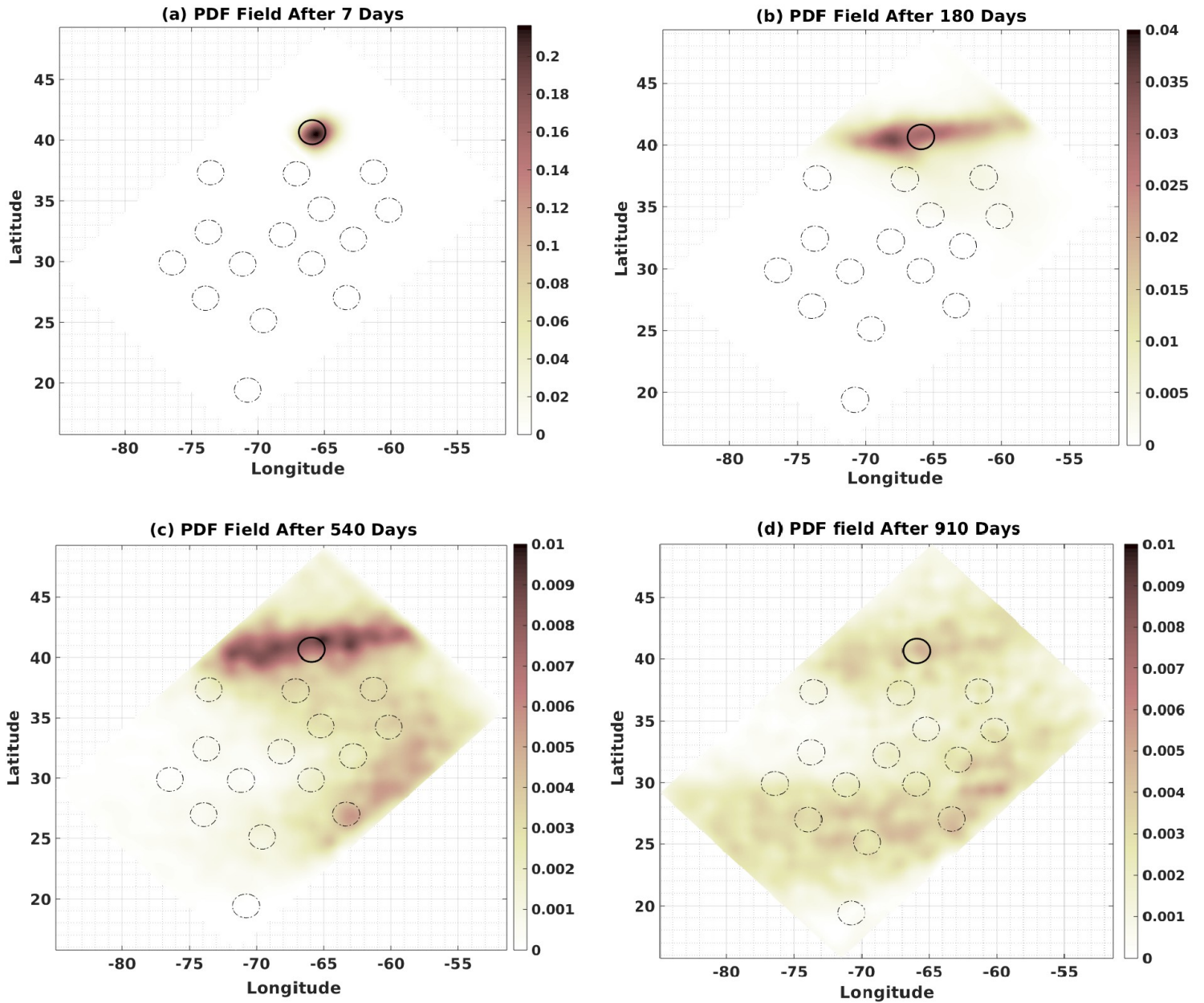
680 **Figure 4:** PDF fields of the position of particles after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), and after 910 days (d).
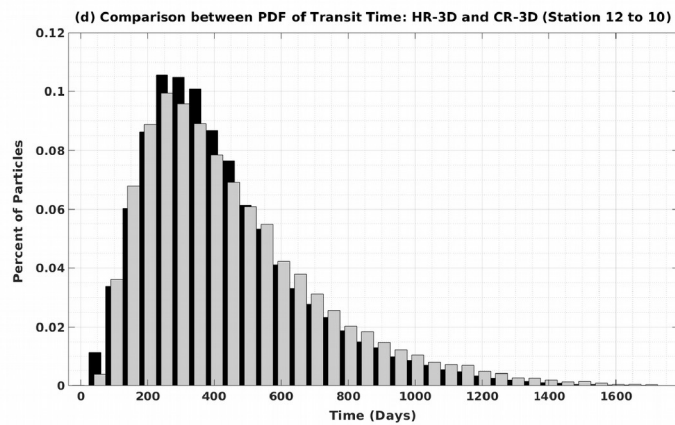
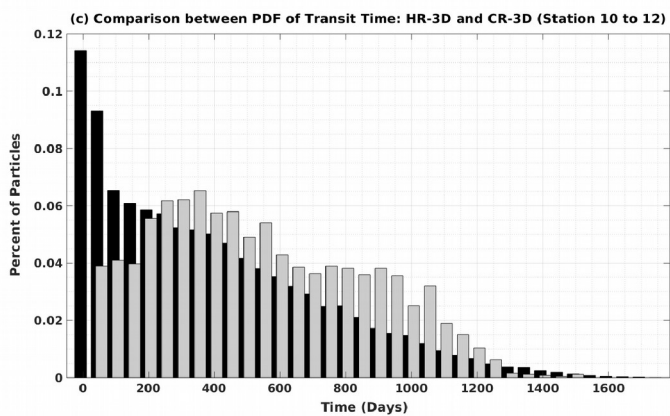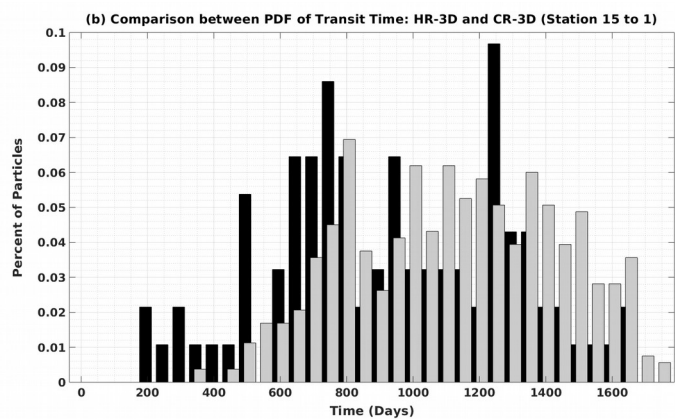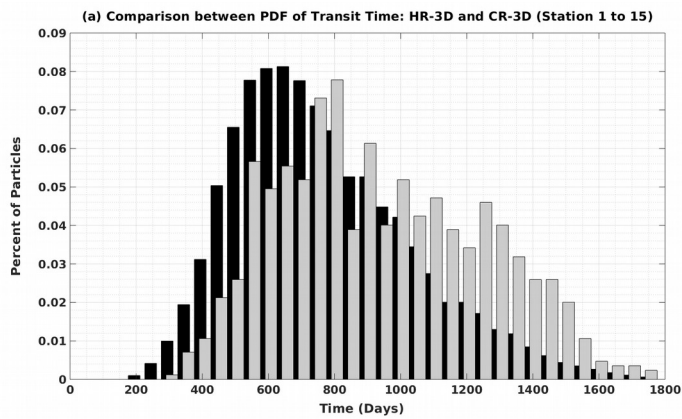**Figure 5:** Comparison of HR-3D (black) and CR-3D (gray) transit time distributions, a) for particles deployed initially from site 1 to site 15, b) from site 15 to site 1, c) from site 10 to site 12, and d) from site 12 to site 10.
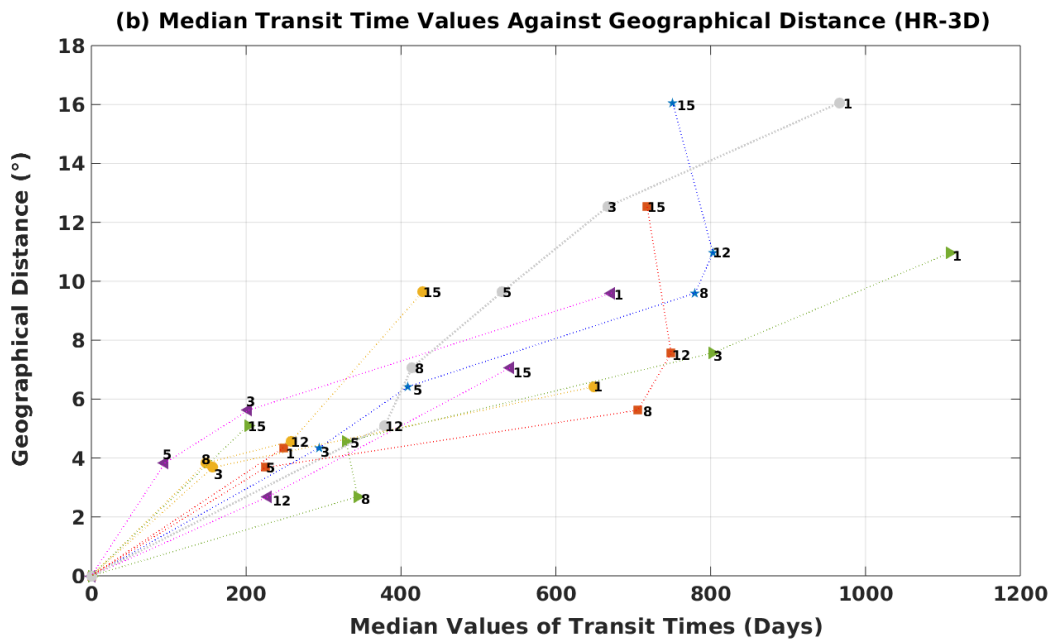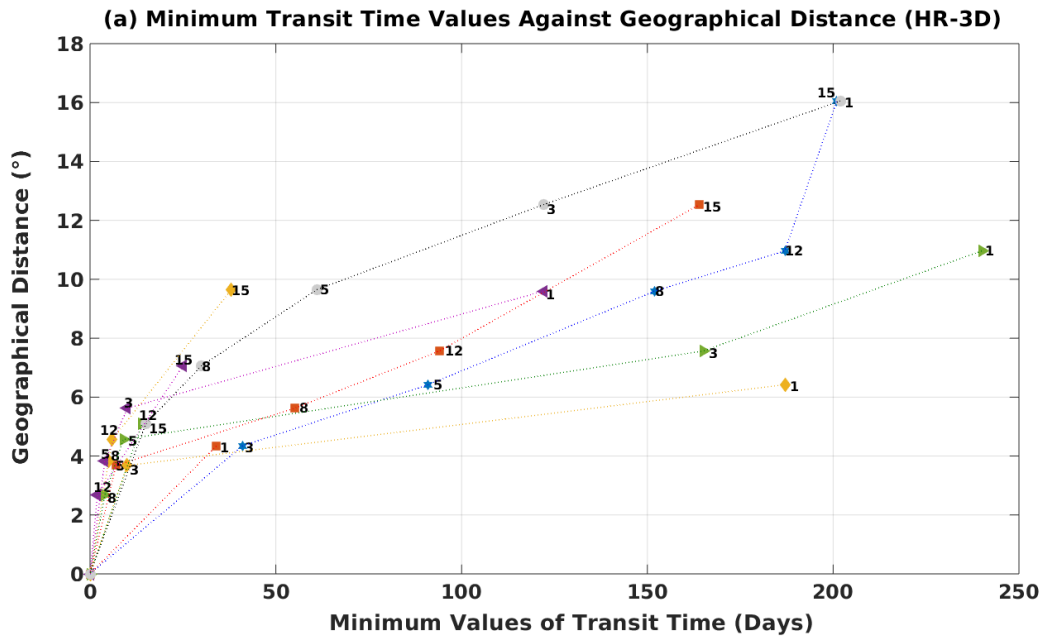
Figure 6: HR-3D minimum (a) and median (b) transit time against geographical distance. Blue: particles initially deployed from site 1;
685 red: particles initially deployed from site 3; yellow: particles initially deployed from site 5; purple: particles initially deployed from site 8; green: particles initially deployed from site 12; grey: particles initially deployed from site 15.
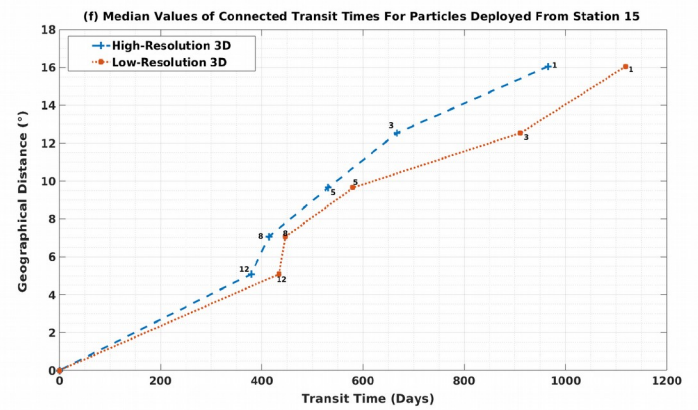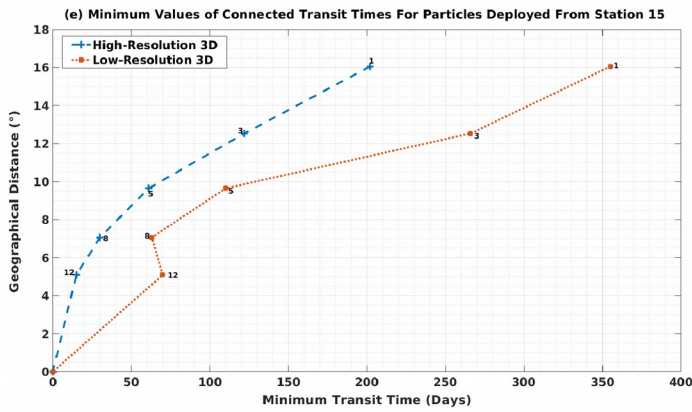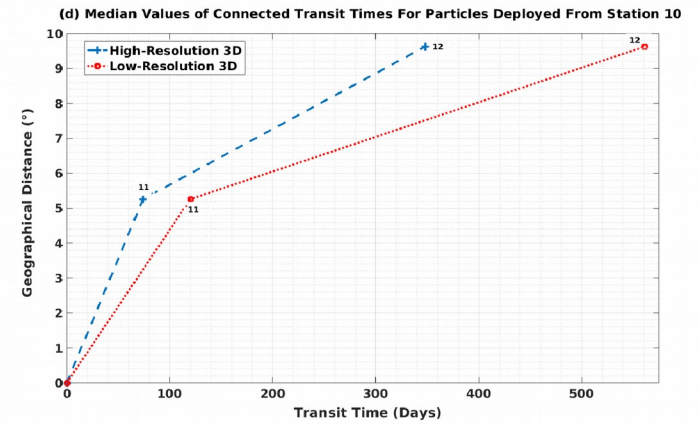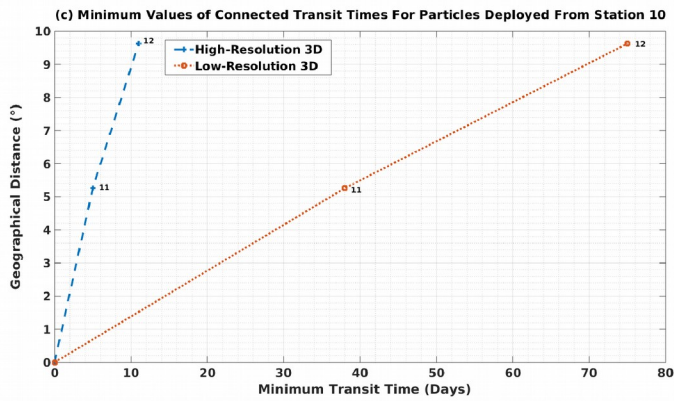
Figure 7: Comparison of HR-3D and CR-3D minimum and median transit times, (a, b) Along diagonal direction for particles deployed initially from site 1. (c,d) Along front for particles deployed initially from site 10. (e,f) Along diagonal direction for particles deployed initially from site 15.

690 **Figure 8:** Comparison of HR-3D (black) et CR-3D (grey) arrival depth distributions, a) for particles deployed initially from site 1 to site 15, b) from site 15 to site 1, c) from site 10 to site 12, and d) from site 12 to site 10.

Figure 9: Comparison of HR-3D and CR-3D mean arrival (transit) time, (a, d) for particles deployed initially from site 1, (b, e) from site 10, (c, f) from site 15.

Figure 10: a) Comparison HR-3D, CR-3D, HR-SL betweenness values (results obtained by using d_{ij}), (b) the connectivity matrix

695 used for network analysis in HR-3D using d_{ij} as edge weight.

Figure 11: Comparison of HR-3D and CR-3D minimum and median transit times between site pairs, a) minimum transit time for HR-3D, b) difference between minimum transit time at CR-3D and HR-3D, c) median transit time for HR-3D, and d) median transit time for CR-3D.

Figure 12: Comparison of HR-3D and HR-SL minimum and median transit times between site pairs, a) minimum transit time for HR-3D, b) difference between minimum transit time at HR-SL and HR-3D, c) median transit time for HR-3D, and d) median transit time for HR-SL.

Supplementary Figure

Figure S1: PDF fields of the position of particles (initially deployed from site 2) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S2: PDF fields of the position of particles (initially deployed from site 6) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S3: PDF fields of the position of particles (initially deployed from site 8) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S4: PDF fields of the position of particles (initially deployed from site 10) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S5: PDF fields of the position of particles (initially deployed from site 16) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).
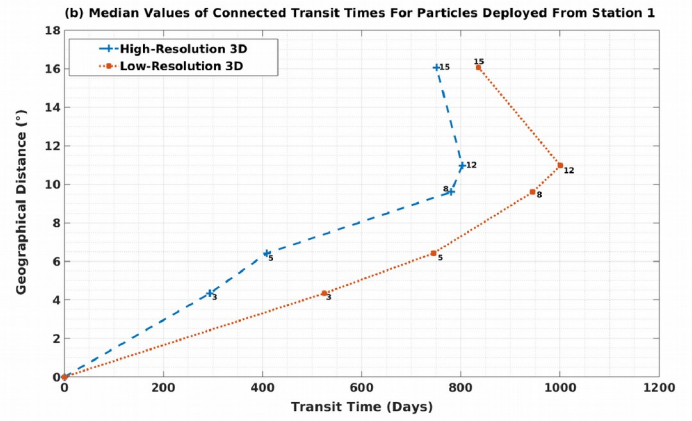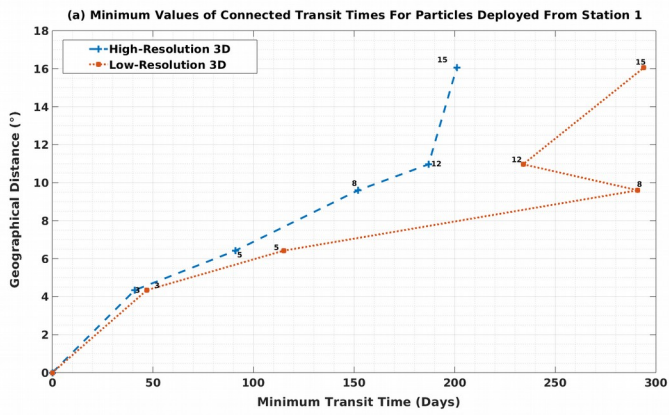
Figure S6: Comparison of HR-3D and HR-SL minimum and median transit times, (a, b) Along diagonal direction for particles deployed initially from site 1. (c,d) Along front for particles deployed initially from site 10. (e,f) Along diagonal direction for particles deployed initially from site 15.

**Figure S7:** PDF plots showing the arrival depth: (up:Left Panel: section 4-10, Right Panel: section 10-4; down: Left Panel: section 10-2, Right Panel: section 2-10). Colors: (3D high resolution: Black, 3D coarse resolution grid: Gray).

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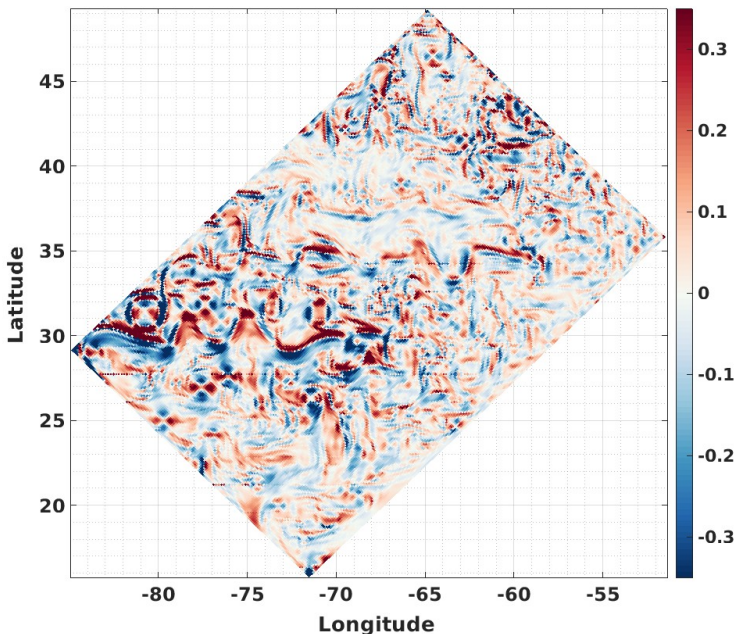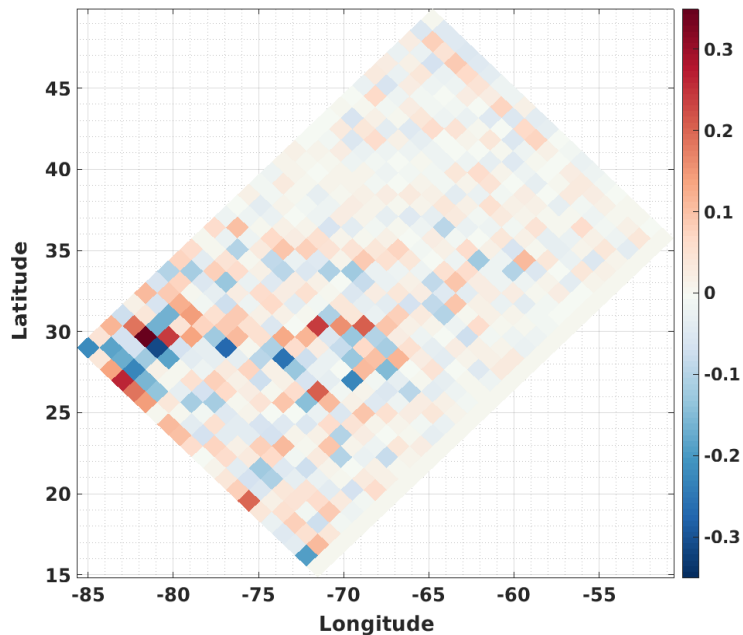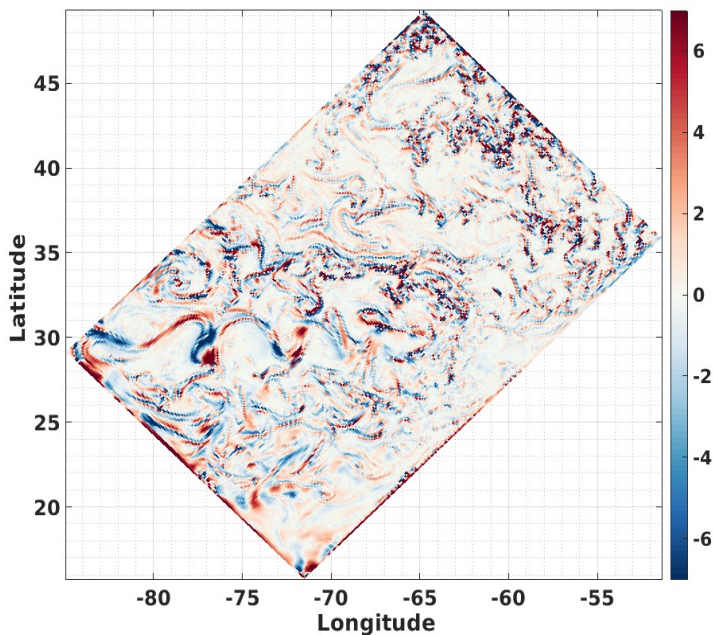
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Figure 6: HR-3D minimum (a) and median (b) transit time against geographical distance. Blue: particles initially deployed from site 1; red: particles initially deployed from site 3; yellow: particles initially deployed from site 5; purple: particles initially deployed from site 8; green: particles initially deployed from site 12; grey: particles initially deployed from site 15.

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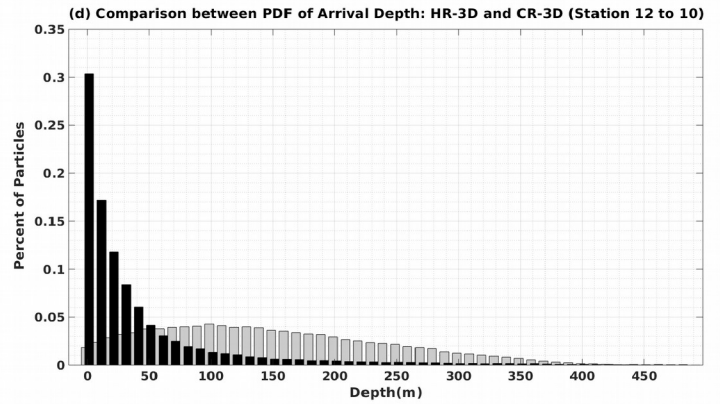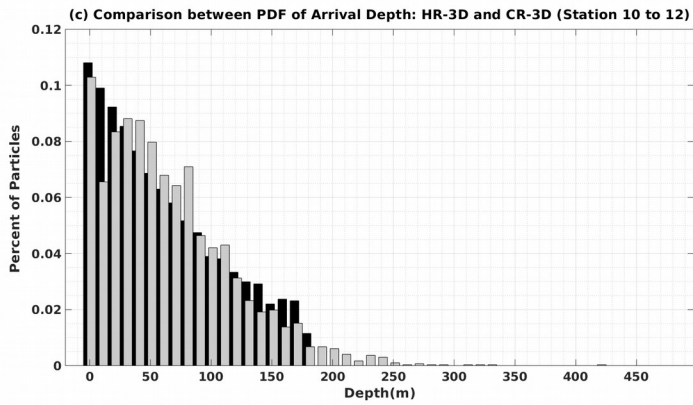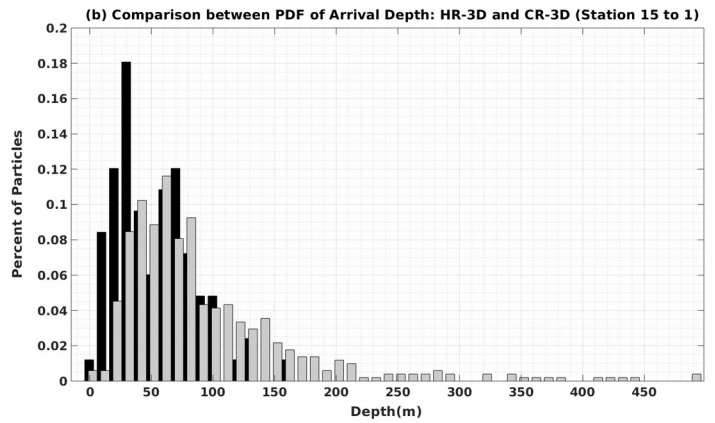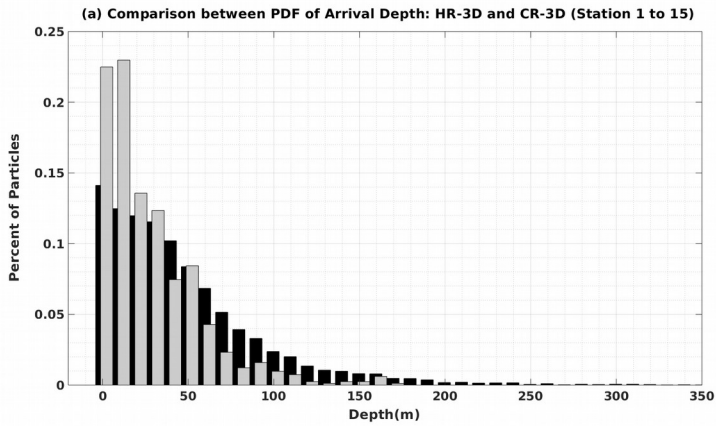
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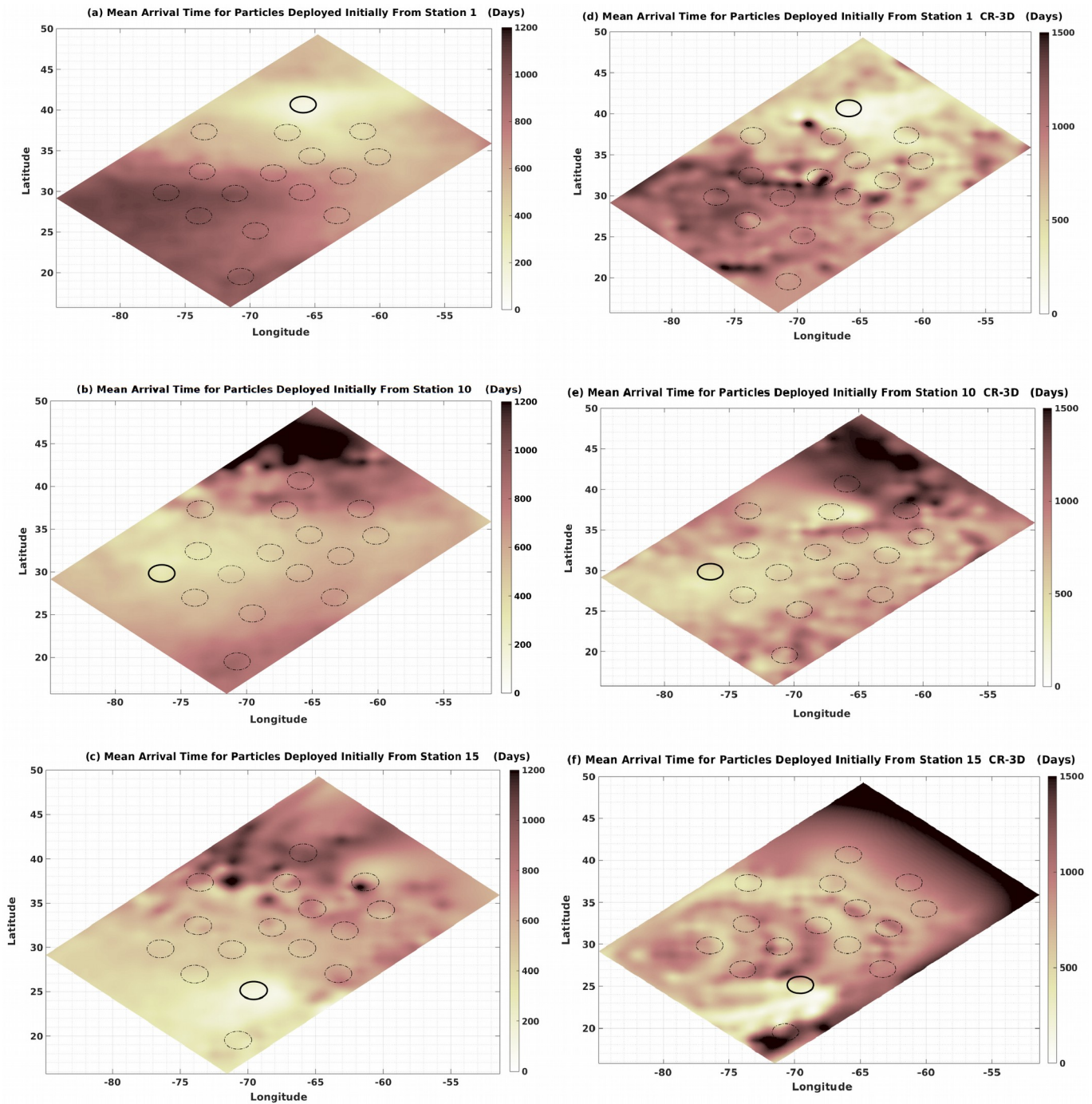
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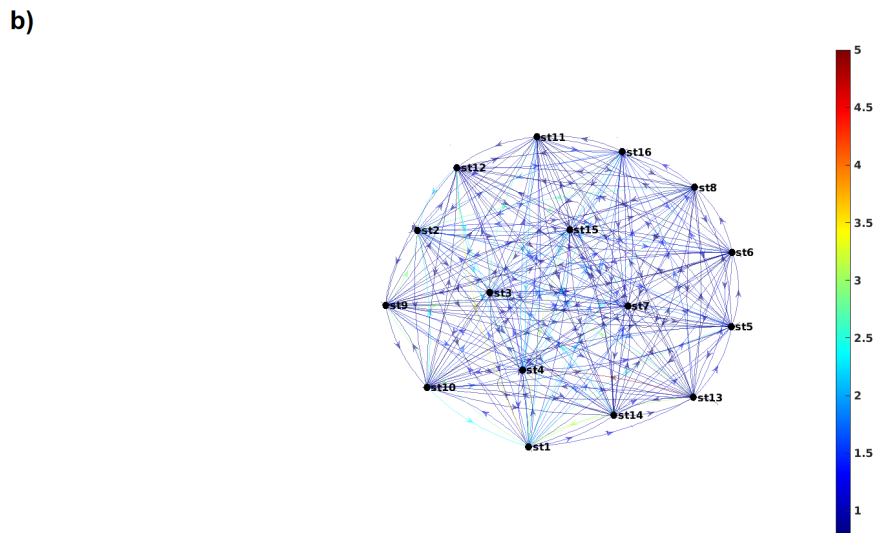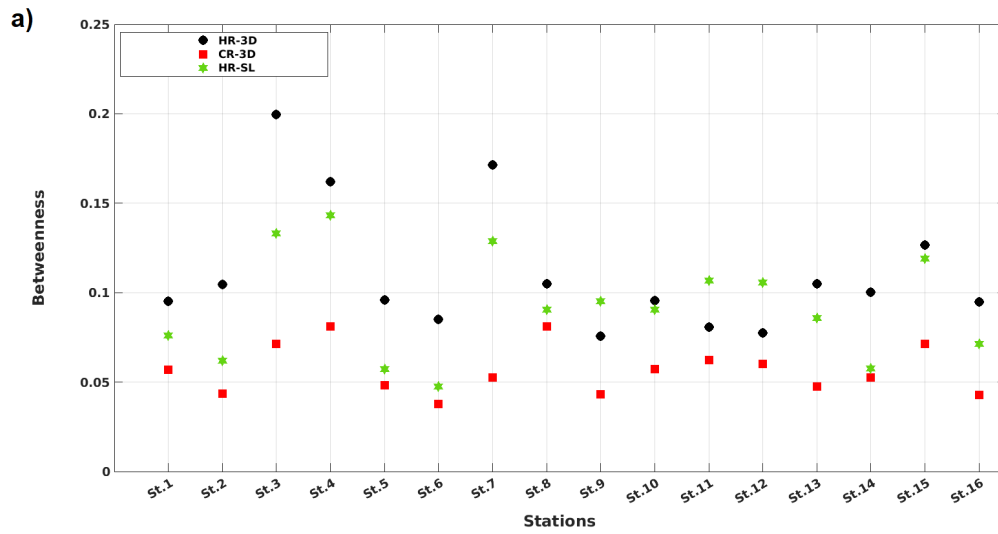
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Figure 12: Comparison of HR-3D and HR-SL minimum and median transit time between site (station) pairs, a) minimum transit time for HR-3D, b) difference between minimum transit time at HR-SL and HR-3D, c) median transit time for HR-3D, and d) median transit time for HR-SL.

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Figure S2: PDF fields of the position of particles (initially deployed from site 6) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S3: PDF fields of the position of particles (initially deployed from site 8) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S4: PDF fields of the position of particles (initially deployed from site 10) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S5: PDF fields of the position of particles (initially deployed from site 16) after increasing time intervals, in HR-3D. After 7 days (a), after 180 days (b), after 540 days (c), after 910 days (d), after 1260 days (e), and after 1440 days (f).

Figure S6: Comparison of HR-3D and HR-SL minimum and median transit time, (a, b) Along diagonal direction for particles deployed initially from site (station) 1. (c,d) Along front for particles

deployed initially from site (station) 10. (e,f) Along diagonal direction for particles deployed initially from site (station) 15.
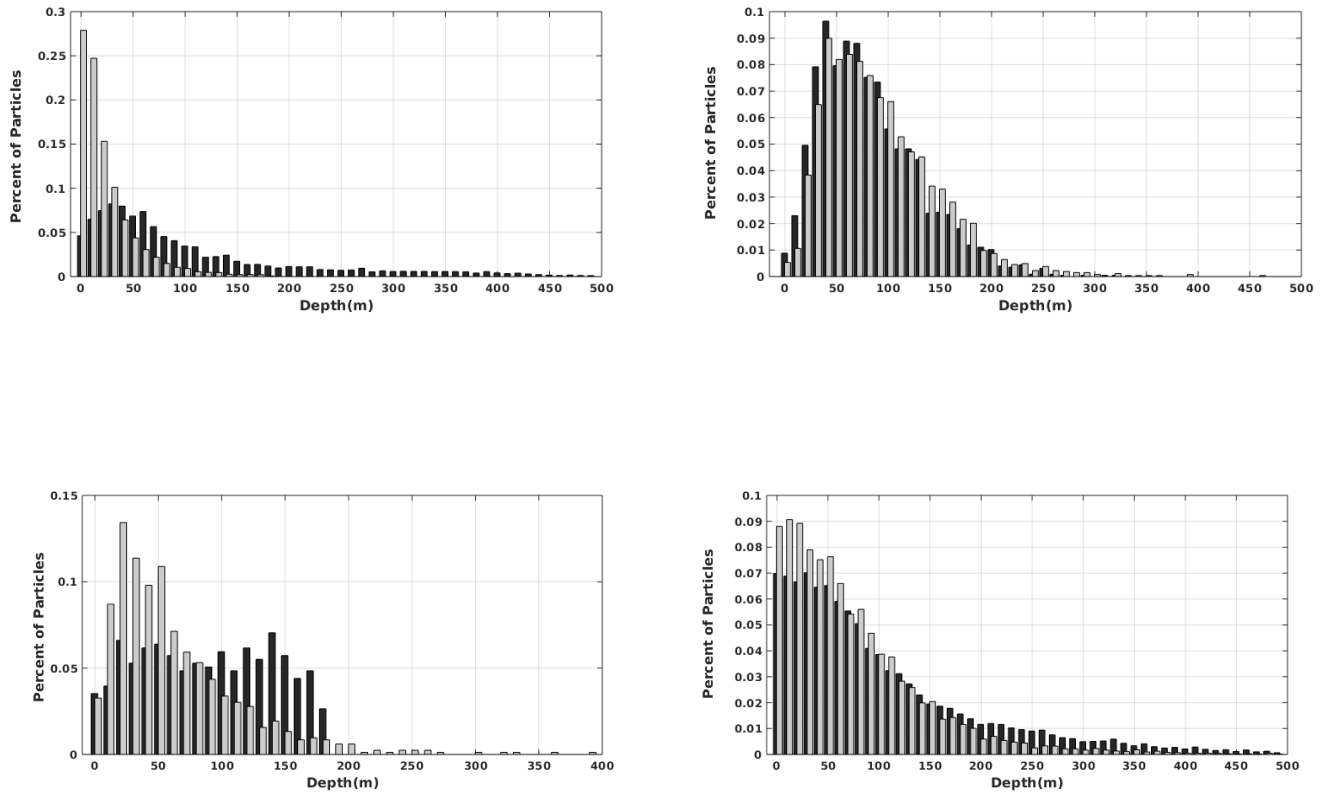
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```
pkgdatadir = $(datadir)/ariane
pkgincludedir = $(includedir)/ariane
pkglibdir = $(libdir)/ariane
pkglibexecdir = $(libexecdir)/ariane
am__cd = CDPATH="$${ZSH_VERSION+.}$(PATH_SEPARATOR)" && cd
install_sh_DATA = $(install_sh) -c -m 644
install_sh_PROGRAM = $(install_sh) -c
install_sh_SCRIPT = $(install_sh) -c
INSTALL_HEADER = $(INSTALL_DATA)
transform = $(program_transform_name)
NORMAL_INSTALL = :
PRE_INSTALL = :
POST_INSTALL = :
NORMAL_UNINSTALL = :
PRE_UNINSTALL = :
POST_UNINSTALL = :
build_triplet = x86_64-unknown-linux-gnu
host_triplet = x86_64-unknown-linux-gnu
subdir = .
DIST_COMMON = README $(am__configure_deps) $(srcdir)/Makefile.am \
        $(srcdir)/Makefile.in $(top_srcdir)/configure \
        ./confdb/config.guess ./confdb/config.sub ./confdb/install-sh \
        ./confdb/missing ./confdb/mkinstalldirs AUTHORS COPYING \
        ChangeLog INSTALL NEWS
ACLOCAL_M4 = $(top_srcdir)/aclocal.m4
am__aclocal_m4_deps = $(top_srcdir)/configure.ac
am__configure_deps = $(am__aclocal_m4_deps) $(CONFIGURE_DEPENDENCIES) \
        $(ACLOCAL_M4)
am__CONFIG_DISTCLEAN_FILES = config.status config.cache config.log \
 configure.lineno config.status.lineno
mkinstalldirs = $(SHELL) $(top_srcdir)/./confdb/mkinstalldirs
CONFIG_CLEAN_FILES =
CONFIG_CLEAN_VPATH_FILES =
SOURCES =
DIST_SOURCES =
RECURSIVE_TARGETS = all-recursive check-recursive dvi-recursive \
        html-recursive info-recursive install-data-recursive \
        install-dvi-recursive install-exec-recursive \
        install-html-recursive install-info-recursive \
        install-pdf-recursive install-ps-recursive install-recursive \
        installcheck-recursive installdirs-recursive pdf-recursive \
        ps-recursive uninstall-recursive
RECURSIVE_CLEAN_TARGETS = mostlyclean-recursive clean-recursive     \
  distclean-recursive maintainer-clean-recursive
AM_RECURSIVE_TARGETS = $(RECURSIVE_TARGETS:-recursive=) \
        $(RECURSIVE_CLEAN_TARGETS:-recursive=) tags TAGS ctags CTAGS \
```

```
		distdir dist dist-all distcheck
ETAGS = etags
CTAGS = ctags
DIST_SUBDIRS = $(SUBDIRS)
DISTFILES = $(DIST_COMMON) $(DIST_SOURCES) $(TEXINFOS) $(EXTRA_DIST)
distdir = $(PACKAGE)-$(VERSION)
top_distdir = $(distdir)
am__remove_distdir = \
  if test -d "$(distdir)"; then \
    find "$(distdir)" -type d ! -perm -200 -exec chmod u+w {} ';' \
      && rm -rf "$(distdir)" \
      || { sleep 5 && rm -rf "$(distdir)"; }; \
  else :; fi
am__relativize = \
  dir0=`pwd`; \
  sed_first='s,^\([^/]*\)/.*$$,\1,'; \
  sed_rest='s,^[^/]*/*,,'; \
  sed_last='s,^.*/\([^/]*\)$$,\1,'; \
  sed_butlast='s,/*[^/]*$$,,'; \
  while test -n "$$dir1"; do \
    first=`echo "$$dir1" | sed -e "$$sed_first"`; \
    if test "$$first" != "."; then \
      if test "$$first" = ".."; then \
        dir2=`echo "$$dir0" | sed -e "$$sed_last"`/"$$dir2"; \
        dir0=`echo "$$dir0" | sed -e "$$sed_butlast"`; \
      else \
        first2=`echo "$$dir2" | sed -e "$$sed_first"`; \
        if test "$$first2" = "$$first"; then \
          dir2=`echo "$$dir2" | sed -e "$$sed_rest"`; \
        else \
          dir2="../$$dir2"; \
        fi; \
        dir0="$$dir0"/"$$first"; \
      fi; \
    fi; \
    dir1=`echo "$$dir1" | sed -e "$$sed_rest"`; \
  done; \
  reldir="$$dir2"
DIST_ARCHIVES = $(distdir).tar.gz
GZIP_ENV = --best
distuninstallcheck_listfiles = find . -type f -print
am__distuninstallcheck_listfiles = $(distuninstallcheck_listfiles) \
  | sed 's|^\./|$(prefix)/|' | grep -v '$(infodir)/dir$$'
distcleancheck_listfiles = find . -type f -print
ACLOCAL = ${SHELL} /home/.../ariane-2.2.8_05/confdb/missing --run aclocal-1.11
AMTAR = $${TAR-tar}
AUTOCONF = ${SHELL} /home/.../ariane-2.2.8_05/confdb/missing --run autoconf
AUTOHEADER = ${SHELL} /home/…./ariane-2.2.8_05/confdb/missing --run autoheader
AUTOMAKE = ${SHELL} /home/.../ariane-2.2.8_05/confdb/missing --run automake-1.11
AWK = mawk
CPPFLAGS =
CYGPATH_W = echo
DEFS = -DPACKAGE_NAME=\"Ariane\" -DPACKAGE_TARNAME=\"ariane\"
-DPACKAGE_VERSION=\"2.2.8_05\" -DPACKAGE_STRING=\"Ariane\ 2.2.8_05\"
-DPACKAGE_BUGREPORT=\"Bruno.Blanke@univ-brest.fr\ or\ Nicolas.Grima@univ-brest.fr\"
-DPACKAGE_URL=\"http://www.univ-brest.fr/lpo/ariane\" -DPACKAGE=\"ariane\" -DVERSION=\"2.2.8_05\"
ECHO_C =
ECHO_N = -n
ECHO_T =
EXEEXT =
F77 = gfortran
FC = gfortran
FCFLAGS = -g -O2 -frecord-marker=4 -I/usr/include
```

```
FCFLAGS_f90 =
HDF5_INC =
HDF5_LIB =
INSTALL = /usr/bin/install -c
INSTALL_DATA = ${INSTALL} -m 644
INSTALL_PROGRAM = ${INSTALL}
INSTALL_SCRIPT = ${INSTALL}
INSTALL_STRIP_PROGRAM = $(install_sh) -c -s
LDFLAGS = -g -O2 -frecord-marker=4
LIBOBJS =
LIBS = -L/usr/lib/x86_64-linux-gnu -lnetcdff -lnetcdf -L/usr/local/lib -lnetcdf
LTLIBOBJS =
MAKEINFO = ${SHELL} /home/.../ariane-2.2.8_05/confdb/missing --run makeinfo
MKDIR_P = /bin/mkdir -p
NETCDF_INC = /usr/include
NETCDF_LIB = /usr/local/lib
OBJEXT = o
PACKAGE = ariane
PACKAGE_BUGREPORT = Bruno.Blanke@univ-brest.fr or Nicolas.Grima@univ-brest.fr
PACKAGE_NAME = Ariane
PACKAGE_STRING = Ariane 2.2.8_05
PACKAGE_TARNAME = ariane
PACKAGE_URL = http://www.univ-brest.fr/lpo/ariane
PACKAGE_VERSION = 2.2.8_05
PATH_SEPARATOR = :
SET_MAKE =
SHELL = /bin/bash
STRIP =
VERSION = 2.2.8_05
abs_builddir = /home/.../ariane-2.2.8_05
abs_srcdir = /home/.../ariane-2.2.8_05
abs_top_builddir = /home/.../ariane-2.2.8_05
abs_top_srcdir = /home/.../ariane-2.2.8_05
ac_ct_FC =
am__leading_dot = .
am__tar = $${TAR-tar} chof - "$$tardir"
am__untar = $${TAR-tar} xf -
bindir = ${exec_prefix}/bin
build = x86_64-unknown-linux-gnu
build_alias =
build_cpu = x86_64
build_os = linux-gnu
build_vendor = unknown
builddir = .
datadir = ${datarootdir}
datarootdir = ${prefix}/share
docdir = ${datarootdir}/doc/${PACKAGE_TARNAME}
dvidir = ${docdir}
exec_prefix = ${prefix}
host = x86_64-unknown-linux-gnu
host_alias =
host_cpu = x86_64
host_os = linux-gnu
host_vendor = unknown
htmldir = ${docdir}
includedir = ${prefix}/include
infodir = ${datarootdir}/info
install_sh = ${SHELL} /home/.../ariane-2.2.8_05/confdb/install-sh
libdir = ${exec_prefix}/lib
libexecdir = ${exec_prefix}/libexec
localedir = ${datarootdir}/locale
localstatedir = ${prefix}/var
mandir = ${datarootdir}/man
```

```
mkdir_p = /bin/mkdir -p
oldincludedir = /usr/include
pdfdir = ${docdir}
prefix = /usr/local
program_transform_name = s,x,x,
psdir = ${docdir}
sbindir = ${exec_prefix}/sbin
sharedstatedir = ${prefix}/com
srcdir = .
sysconfdir = ${prefix}/etc
target_alias =
top_build_prefix =
top_builddir = .
top_srcdir = .
BASE_SUBDIRS = src doc examples
SUBDIRS = $(BASE_SUBDIRS)
all: all-recursive

.SUFFIXES:
am--refresh: Makefile
        @:
$(srcdir)/Makefile.in:  $(srcdir)/Makefile.am  $(am__configure_deps)
        @for dep in $?; do \
          case '$(am__configure_deps)' in \
            *$$dep*) \
              echo ' cd $(srcdir) && $(AUTOMAKE) --gnu'; \
              $(am__cd) $(srcdir) && $(AUTOMAKE) --gnu \
                  && exit 0; \
              exit 1;; \
          esac; \
        done; \
        echo ' cd $(top_srcdir) && $(AUTOMAKE) --gnu Makefile'; \
        $(am__cd) $(top_srcdir) && \
          $(AUTOMAKE) --gnu Makefile
.PRECIOUS: Makefile
Makefile: $(srcdir)/Makefile.in $(top_builddir)/config.status
        @case '$?' in \
          *config.status*) \
            echo ' $(SHELL) ./config.status'; \
            $(SHELL) ./config.status;; \
          *) \
            echo ' cd $(top_builddir) && $(SHELL) ./config.status $@ $(am__depfiles_maybe)'; \
            cd $(top_builddir) && $(SHELL) ./config.status $@ $(am__depfiles_maybe);; \
        esac;

$(top_builddir)/config.status: $(top_srcdir)/configure $(CONFIG_STATUS_DEPENDENCIES)
        $(SHELL) ./config.status --recheck

$(top_srcdir)/configure:  $(am__configure_deps)
        $(am__cd) $(srcdir) && $(AUTOCONF)
$(ACLOCAL_M4):  $(am__aclocal_m4_deps)
        $(am__cd) $(srcdir) && $(ACLOCAL) $(ACLOCAL_AMFLAGS)
$(am__aclocal_m4_deps):

# This directory's subdirectories are mostly independent; you can cd
# into them and run `make' without going through this Makefile.
# To change the values of `make' variables: instead of editing Makefiles,
# (1) if the variable is set in `config.status', edit `config.status'
#     (which will cause the Makefiles to be regenerated when you run `make');
# (2) otherwise, pass the desired values on the `make' command line.
$(RECURSIVE_TARGETS):
        @fail= failcom='exit 1'; \
        for f in x $$MAKEFLAGS; do \
```

```
            case $$f in \
              *=* | --[!k]*);; \
              *k*) failcom='fail=yes';; \
            esac; \
          done; \
          dot_seen=no; \
          target=`echo $@ | sed s/-recursive//`; \
          list='$(SUBDIRS)'; for subdir in $$list; do \
            echo "Making $$target in $$subdir"; \
            if test "$$subdir" = "."; then \
              dot_seen=yes; \
              local_target="$$target-am"; \
            else \
              local_target="$$target"; \
            fi; \
            ($(am__cd) $$subdir && $(MAKE) $(AM_MAKEFLAGS) $$local_target) \
            || eval $$failcom; \
          done; \
          if test "$$dot_seen" = "no"; then \
            $(MAKE) $(AM_MAKEFLAGS) "$$target-am" || exit 1; \
          fi; test -z "$$fail"

$(RECURSIVE_CLEAN_TARGETS):
        @fail= failcom='exit 1'; \
        for f in x $$MAKEFLAGS; do \
          case $$f in \
            *=* | --[!k]*);; \
            *k*) failcom='fail=yes';; \
          esac; \
        done; \
        dot_seen=no; \
        case "$@" in \
          distclean-* | maintainer-clean-*) list='$(DIST_SUBDIRS)' ;; \
          *) list='$(SUBDIRS)' ;; \
        esac; \
        rev=''; for subdir in $$list; do \
          if test "$$subdir" = "."; then :; else \
            rev="$$subdir $$rev"; \
          fi; \
        done; \
        rev="$$rev ."; \
        target=`echo $@ | sed s/-recursive//`; \
        for subdir in $$rev; do \
          echo "Making $$target in $$subdir"; \
          if test "$$subdir" = "."; then \
            local_target="$$target-am"; \
          else \
            local_target="$$target"; \
          fi; \
          ($(am__cd) $$subdir && $(MAKE) $(AM_MAKEFLAGS) $$local_target) \
          || eval $$failcom; \
        done && test -z "$$fail"
tags-recursive:
        list='$(SUBDIRS)'; for subdir in $$list; do \
          test "$$subdir" = . || ($(am__cd) $$subdir && $(MAKE) $(AM_MAKEFLAGS) tags); \
        done
ctags-recursive:
        list='$(SUBDIRS)'; for subdir in $$list; do \
          test "$$subdir" = . || ($(am__cd) $$subdir && $(MAKE) $(AM_MAKEFLAGS) ctags); \
        done

ID: $(HEADERS) $(SOURCES) $(LISP) $(TAGS_FILES)
        list='$(SOURCES) $(HEADERS) $(LISP) $(TAGS_FILES)'; \
```

```
          unique=`for i in $$list; do \
            if test -f "$$i"; then echo $$i; else echo $(srcdir)/$$i; fi; \
          done | \
          $(AWK) '{ files[$$0] = 1; nonempty = 1; } \
              END { if (nonempty) { for (i in files) print i; }; }'`; \
          mkid -fID $$unique
tags: TAGS

TAGS: tags-recursive $(HEADERS) $(SOURCES)  $(TAGS_DEPENDENCIES) \
              $(TAGS_FILES) $(LISP)
          set x; \
          here=`pwd`; \
          if ($(ETAGS) --etags-include --version) >/dev/null 2>&1; then \
            include_option=--etags-include; \
            empty_fix=.; \
          else \
            include_option=--include; \
            empty_fix=; \
          fi; \
          list='$(SUBDIRS)'; for subdir in $$list; do \
            if test "$$subdir" = .; then :; else \
              test ! -f $$subdir/TAGS || \
                set "$$@" "$$include_option=$$here/$$subdir/TAGS"; \
            fi; \
          done; \
          list='$(SOURCES) $(HEADERS)  $(LISP) $(TAGS_FILES)'; \
          unique=`for i in $$list; do \
            if test -f "$$i"; then echo $$i; else echo $(srcdir)/$$i; fi; \
          done | \
          $(AWK) '{ files[$$0] = 1; nonempty = 1; } \
              END { if (nonempty) { for (i in files) print i; }; }'`; \
          shift; \
          if test -z "$(ETAGS_ARGS)$$*$$unique"; then :; else \
            test -n "$$unique" || unique=$$empty_fix; \
            if test $$# -gt 0; then \
              $(ETAGS) $(ETAGSFLAGS) $(AM_ETAGSFLAGS) $(ETAGS_ARGS) \
                "$$@" $$unique; \
            else \
              $(ETAGS) $(ETAGSFLAGS) $(AM_ETAGSFLAGS) $(ETAGS_ARGS) \
                $$unique; \
            fi; \
          fi
ctags: CTAGS
CTAGS: ctags-recursive $(HEADERS) $(SOURCES)  $(TAGS_DEPENDENCIES) \
              $(TAGS_FILES) $(LISP)
          list='$(SOURCES) $(HEADERS)  $(LISP) $(TAGS_FILES)'; \
          unique=`for i in $$list; do \
            if test -f "$$i"; then echo $$i; else echo $(srcdir)/$$i; fi; \
          done | \
          $(AWK) '{ files[$$0] = 1; nonempty = 1; } \
              END { if (nonempty) { for (i in files) print i; }; }'`; \
          test -z "$(CTAGS_ARGS)$$unique" \
           || $(CTAGS) $(CTAGSFLAGS) $(AM_CTAGSFLAGS) $(CTAGS_ARGS) \
             $$unique

GTAGS:
          here=`$(am__cd) $(top_builddir) && pwd` \
           && $(am__cd) $(top_srcdir) \
           && gtags -i $(GTAGS_ARGS) "$$here"

distclean-tags:
          -rm -f TAGS ID GTAGS GRTAGS GSYMS GPATH tags
```

```
distdir: $(DISTFILES)
	$(am__remove_distdir)
	test -d "$(distdir)" || mkdir "$(distdir)"
	@srcdirstrip=`echo "$(srcdir)" | sed 's/[].[^$$\\*]/\\\\&/g'`; \
	topsrcdirstrip=`echo "$(top_srcdir)" | sed 's/[].[^$$\\*]/\\\\&/g'`; \
	list='$(DISTFILES)'; \
	  dist_files=`for file in $$list; do echo $$file; done | \
	  sed -e "s|^$$srcdirstrip/||;t" \
	      -e "s|^$$topsrcdirstrip/|$(top_builddir)/|;t"`; \
	case $$dist_files in \
	  */*) $(MKDIR_P) `echo "$$dist_files" | \
	                   sed '/\//!d;s|^|$(distdir)/|;s,/[^/]*$$,,' | \
	                   sort -u` ;; \
	esac; \
	for file in $$dist_files; do \
	  if test -f $$file || test -d $$file; then d=.; else d=$(srcdir); fi; \
	  if test -d $$d/$$file; then \
	    dir=`echo "/$$file" | sed -e 's,/[^/]*$$,,'`; \
	    if test -d "$(distdir)/$$file"; then \
	      find "$(distdir)/$$file" -type d ! -perm -700 -exec chmod u+rwx {} \;; \
	    fi; \
	    if test -d $(srcdir)/$$file && test $$d != $(srcdir); then \
	      cp -fpR $(srcdir)/$$file "$(distdir)$$dir" || exit 1; \
	      find "$(distdir)/$$file" -type d ! -perm -700 -exec chmod u+rwx {} \;; \
	    fi; \
	    cp -fpR $$d/$$file "$(distdir)$$dir" || exit 1; \
	  else \
	    test -f "$(distdir)/$$file" \
	    || cp -p $$d/$$file "$(distdir)/$$file" \
	    || exit 1; \
	  fi; \
	done
	@list='$(DIST_SUBDIRS)'; for subdir in $$list; do \
	  if test "$$subdir" = .; then :; else \
	    test -d "$(distdir)/$$subdir" \
	    || $(MKDIR_P) "$(distdir)/$$subdir" \
	    || exit 1; \
	  fi; \
	done
	@list='$(DIST_SUBDIRS)'; for subdir in $$list; do \
	  if test "$$subdir" = .; then :; else \
	    dir1=$$subdir; dir2="$(distdir)/$$subdir"; \
	    $(am__relativize); \
	    new_distdir=$$reldir; \
	    dir1=$$subdir; dir2="$(top_distdir)"; \
	    $(am__relativize); \
	    new_top_distdir=$$reldir; \
	    echo " (cd $$subdir && $(MAKE) $(AM_MAKEFLAGS) top_distdir="$$new_top_distdir" distdir="$$new_distdir" \\"; \
	    echo "     am__remove_distdir=: am__skip_length_check=: am__skip_mode_fix=: distdir)"; \
	    ($(am__cd) $$subdir && \
	      $(MAKE) $(AM_MAKEFLAGS) \
	        top_distdir="$$new_top_distdir" \
	        distdir="$$new_distdir" \
	            am__remove_distdir=: \
	            am__skip_length_check=: \
	            am__skip_mode_fix=: \
	        distdir) \
	    || exit 1; \
	  fi; \
	done
	-test -n "$(am__skip_mode_fix)" \
	|| find "$(distdir)" -type d ! -perm -755 \
```

```
              -exec chmod u+rwx,go+rx {} \; -o \
        ! -type d ! -perm -444 -links 1 -exec chmod a+r {} \; -o \
        ! -type d ! -perm -400 -exec chmod a+r {} \; -o \
        ! -type d ! -perm -444 -exec $(install_sh) -c -m a+r {} {} \; \
      || chmod -R a+r "$(distdir)"
dist-gzip: distdir
      tardir=$(distdir) && $(am__tar) | GZIP=$(GZIP_ENV) gzip -c >$(distdir).tar.gz
      $(am__remove_distdir)

dist-bzip2: distdir
      tardir=$(distdir) && $(am__tar) | BZIP2=$${BZIP2--9} bzip2 -c >$(distdir).tar.bz2
      $(am__remove_distdir)

dist-lzip: distdir
      tardir=$(distdir) && $(am__tar) | lzip -c $${LZIP_OPT--9} >$(distdir).tar.lz
      $(am__remove_distdir)

dist-lzma: distdir
      tardir=$(distdir) && $(am__tar) | lzma -9 -c >$(distdir).tar.lzma
      $(am__remove_distdir)

dist-xz: distdir
      tardir=$(distdir) && $(am__tar) | XZ_OPT=$${XZ_OPT--e} xz -c >$(distdir).tar.xz
      $(am__remove_distdir)

dist-tarZ: distdir
      tardir=$(distdir) && $(am__tar) | compress -c >$(distdir).tar.Z
      $(am__remove_distdir)

dist-shar: distdir
      shar $(distdir) | GZIP=$(GZIP_ENV) gzip -c >$(distdir).shar.gz
      $(am__remove_distdir)

dist-zip: distdir
      -rm -f $(distdir).zip
      zip -rq $(distdir).zip $(distdir)
      $(am__remove_distdir)

dist dist-all: distdir
      tardir=$(distdir) && $(am__tar) | GZIP=$(GZIP_ENV) gzip -c >$(distdir).tar.gz
      $(am__remove_distdir)

# This target untars the dist file and tries a VPATH configuration.  Then
# it guarantees that the distribution is self-contained by making another
# tarfile.
distcheck: dist
      case '$(DIST_ARCHIVES)' in \
      *.tar.gz*) \
        GZIP=$(GZIP_ENV) gzip -dc $(distdir).tar.gz | $(am__untar) ;;\
      *.tar.bz2*) \
        bzip2 -dc $(distdir).tar.bz2 | $(am__untar) ;;\
      *.tar.lzma*) \
        lzma -dc $(distdir).tar.lzma | $(am__untar) ;;\
      *.tar.lz*) \
        lzip -dc $(distdir).tar.lz | $(am__untar) ;;\
      *.tar.xz*) \
        xz -dc $(distdir).tar.xz | $(am__untar) ;;\
      *.tar.Z*) \
        uncompress -c $(distdir).tar.Z | $(am__untar) ;;\
      *.shar.gz*) \
        GZIP=$(GZIP_ENV) gzip -dc $(distdir).shar.gz | unshar ;;\
      *.zip*) \
        unzip $(distdir).zip ;;\
```

```
	esac
	chmod -R a-w $(distdir); chmod a+w $(distdir)
	mkdir $(distdir)/_build
	mkdir $(distdir)/_inst
	chmod a-w $(distdir)
	test -d $(distdir)/_build || exit 0; \
	dc_install_base=`$(am__cd) $(distdir)/_inst && pwd | sed -e 's,^[^:\\/]:[\\/],/,'` \
	  && dc_destdir="$${TMPDIR-/tmp}/am-dc-$$$$/" \
	  && am__cwd=`pwd` \
	  && $(am__cd) $(distdir)/_build \
	  && ../configure --srcdir=.. --prefix="$$dc_install_base" \
	    $(AM_DISTCHECK_CONFIGURE_FLAGS) \
	    $(DISTCHECK_CONFIGURE_FLAGS) \
	  && $(MAKE) $(AM_MAKEFLAGS) \
	  && $(MAKE) $(AM_MAKEFLAGS) dvi \
	  && $(MAKE) $(AM_MAKEFLAGS) check \
	  && $(MAKE) $(AM_MAKEFLAGS) install \
	  && $(MAKE) $(AM_MAKEFLAGS) installcheck \
	  && $(MAKE) $(AM_MAKEFLAGS) uninstall \
	  && $(MAKE) $(AM_MAKEFLAGS) distuninstallcheck_dir="$$dc_install_base" \
	        distuninstallcheck \
	  && chmod -R a-w "$$dc_install_base" \
	  && ({ \
	       (cd ../.. && umask 077 && mkdir "$$dc_destdir") \
	       && $(MAKE) $(AM_MAKEFLAGS) DESTDIR="$$dc_destdir" install \
	       && $(MAKE) $(AM_MAKEFLAGS) DESTDIR="$$dc_destdir" uninstall \
	       && $(MAKE) $(AM_MAKEFLAGS) DESTDIR="$$dc_destdir" \
	            distuninstallcheck_dir="$$dc_destdir" distuninstallcheck; \
	      } || { rm -rf "$$dc_destdir"; exit 1; }) \
	  && rm -rf "$$dc_destdir" \
	  && $(MAKE) $(AM_MAKEFLAGS) dist \
	  && rm -rf $(DIST_ARCHIVES) \
	  && $(MAKE) $(AM_MAKEFLAGS) distcleancheck \
	  && cd "$$am__cwd" \
	  || exit 1
	$(am__remove_distdir)
	@(echo "$(distdir) archives ready for distribution: "; \
	  list='$(DIST_ARCHIVES)'; for i in $$list; do echo $$i; done) | \
	  sed -e 1h -e 1s/./=/g -e 1p -e 1x -e '$$p' -e '$$x'
distuninstallcheck:
	@test -n '$(distuninstallcheck_dir)' || { \
	  echo 'ERROR: trying to run $@ with an empty' \
	       '$$(distuninstallcheck_dir)' >&2; \
	  exit 1; \
	}; \
	$(am__cd) '$(distuninstallcheck_dir)' || { \
	  echo 'ERROR: cannot chdir into $(distuninstallcheck_dir)' >&2; \
	  exit 1; \
	}; \
	test `$(am__distuninstallcheck_listfiles) | wc -l` -eq 0 \
	   || { echo "ERROR: files left after uninstall:" ; \
	        if test -n "$(DESTDIR)"; then \
	          echo "  (check DESTDIR support)"; \
	        fi ; \
	        $(distuninstallcheck_listfiles) ; \
	        exit 1; } >&2
distcleancheck: distclean
	@if test '$(srcdir)' = . ; then \
	  echo "ERROR: distcleancheck can only run from a VPATH build" ; \
	  exit 1 ; \
	fi
	@test `$(distcleancheck_listfiles) | wc -l` -eq 0 \
	   || { echo "ERROR: files left in build directory after distclean:" ; \
```

```
                $(distcleancheck_listfiles) ; \
                exit 1; } >&2
check-am: all-am
check: check-recursive
all-am: Makefile
installdirs: installdirs-recursive
installdirs-am:
install: install-recursive
install-exec: install-exec-recursive
install-data: install-data-recursive
uninstall: uninstall-recursive

install-am: all-am
        @$(MAKE) $(AM_MAKEFLAGS) install-exec-am install-data-am

installcheck: installcheck-recursive
install-strip:
        if test -z '$(STRIP)'; then \
          $(MAKE) $(AM_MAKEFLAGS) INSTALL_PROGRAM="$(INSTALL_STRIP_PROGRAM)" \
            install_sh_PROGRAM="$(INSTALL_STRIP_PROGRAM)" INSTALL_STRIP_FLAG=-s \
              install; \
        else \
          $(MAKE) $(AM_MAKEFLAGS) INSTALL_PROGRAM="$(INSTALL_STRIP_PROGRAM)" \
            install_sh_PROGRAM="$(INSTALL_STRIP_PROGRAM)" INSTALL_STRIP_FLAG=-s \
            "INSTALL_PROGRAM_ENV=STRIPPROG='$(STRIP)'" install; \
        fi
mostlyclean-generic:

clean-generic:

distclean-generic:
        -test -z "$(CONFIG_CLEAN_FILES)" || rm -f $(CONFIG_CLEAN_FILES)
        -test . = "$(srcdir)" || test -z "$(CONFIG_CLEAN_VPATH_FILES)" || rm -f $
(CONFIG_CLEAN_VPATH_FILES)

maintainer-clean-generic:
        @echo "This command is intended for maintainers to use"
        @echo "it deletes files that may require special tools to rebuild."
clean: clean-recursive

clean-am: clean-generic mostlyclean-am

distclean: distclean-recursive
        -rm -f $(am__CONFIG_DISTCLEAN_FILES)
        -rm -f Makefile
distclean-am: clean-am distclean-generic distclean-tags

dvi: dvi-recursive

dvi-am:

html: html-recursive

html-am:

info: info-recursive

info-am:

install-data-am:

install-dvi: install-dvi-recursive
```

```
install-dvi-am:

install-exec-am:

install-html: install-html-recursive

install-html-am:

install-info: install-info-recursive

install-info-am:

install-man:

install-pdf: install-pdf-recursive

install-pdf-am:

install-ps: install-ps-recursive

install-ps-am:

installcheck-am:

maintainer-clean: maintainer-clean-recursive
	-rm -f $(am__CONFIG_DISTCLEAN_FILES)
	-rm -rf $(top_srcdir)/autom4te.cache
	-rm -f Makefile
maintainer-clean-am: distclean-am maintainer-clean-generic

mostlyclean: mostlyclean-recursive

mostlyclean-am: mostlyclean-generic

pdf: pdf-recursive

pdf-am:

ps: ps-recursive

ps-am:

uninstall-am:

.MAKE: $(RECURSIVE_CLEAN_TARGETS) $(RECURSIVE_TARGETS) ctags-recursive \
	install-am install-strip tags-recursive

.PHONY: $(RECURSIVE_CLEAN_TARGETS) $(RECURSIVE_TARGETS) CTAGS GTAGS \
	all all-am am--refresh check check-am clean clean-generic \
	ctags ctags-recursive dist dist-all dist-bzip2 dist-gzip \
	dist-lzip dist-lzma dist-shar dist-tarZ dist-xz dist-zip \
	distcheck distclean distclean-generic distclean-tags \
	distcleancheck distdir distuninstallcheck dvi dvi-am html \
	html-am info info-am install install-am install-data \
	install-data-am install-dvi install-dvi-am install-exec \
	install-exec-am install-html install-html-am install-info \
	install-info-am install-man install-pdf install-pdf-am \
	install-ps install-ps-am install-strip installcheck \
	installcheck-am installdirs installdirs-am maintainer-clean \
	maintainer-clean-generic mostlyclean mostlyclean-generic pdf \
	pdf-am ps ps-am tags tags-recursive uninstall uninstall-am
```

```
# Tell versions [3.59,3.63) of GNU make to not export all variables.
# Otherwise a system limit (for SysV at least) may be exceeded.
.NOEXPORT:
```

```
&ARIANE
   key_alltracers =.FALSE.,
   key_sequential =.TRUE.,
   key_ascii_outputs =.TRUE.,
   mode ='qualitative',
   forback ='forward',
   bin ='nobin',
   init_final ='init',
   nmax =9900000,
   tunit =86400.,
   ntfic = 2,
   tcyc =86400.,
   output_netcdf_large_file = .TRUE.,
/

&OPAPARAM
   imt = 270
   jmt = 180,
   kmt =31,
   lmt =900,
   key_periodic =.FALSE.,
   key_jfold =.FALSE.,
   key_computew =.TRUE.,
   key_partialsteps =.FALSE.,
   w_surf_option ='zero',
/

&SEQUENTIAL
   maxcycles =1,
/
&QUANTITATIVE
 key_eco       = .TRUE.,
 key_reducmem   = .TRUE.,
 key_unitm3    = .FALSE.,
```

```
  key_nointerpolstats = .FALSE.,
  max_transport  =  100,
  lmin=1,
  lmax=365,
/

&QUALITATIVE
   delta_t =86400.,
   frequency =1,
   nb_output =1800,
   key_region =.FALSE.,
/

&ZONALCRT
   c_dir_zo ='/home/.../ariane-2.2.8_05/data',
   c_prefix_zo ='U.nc',
   ind0_zo =-1,
   indn_zo =-1,
   maxsize_zo =-1,
   c_suffix_zo ='NONE',
   nc_var_zo ='U',
   nc_var_eivu ='NONE',
   nc_att_mask_zo ='9.96921e+36f'
/

&MERIDCRT
   c_dir_me ='/home/.../ariane-2.2.8_05/data',
   c_prefix_me ='V.nc',
   ind0_me =-1,
   indn_me =-1,
   maxsize_me =-1,
   c_suffix_me ='NONE',
   nc_var_me ='V',
   nc_var_eivv ='NONE',
   nc_att_mask_me ='9.96921e+36f'
/

&VERTICRT
   c_dir_me ='/home/.../ariane-2.2.8_05/data',
   c_prefix_me ='W.nc',
   ind0_me =-1,
   indn_me =-1,
   maxsize_me =-1,
   c_suffix_me ='NONE',
   nc_var_me ='W',
   nc_var_eivv ='NONE',
   nc_att_mask_me ='9.96921e+36f'
/

&MESH
   dir_mesh ='/home/.../ariane-2.2.8_05/data',
   fn_mesh ='meshmask.nc'
   nc_var_xx_tt ='xt',
   nc_var_xx_uu ='xu',
   nc_var_yy_tt ='yt',
   nc_var_yy_vv ='yv',
   nc_var_zz_ww ='zw',
   nc_var_e2u ='e2u',
   nc_var_e1v ='e1v',
   nc_var_e1t ='e1t',
   nc_var_e2t ='e2t',
   nc_var_e3t ='e3t',
   nc_var_tmask ='tmask',
```

```
   nc_mask_val =0.,
/
```